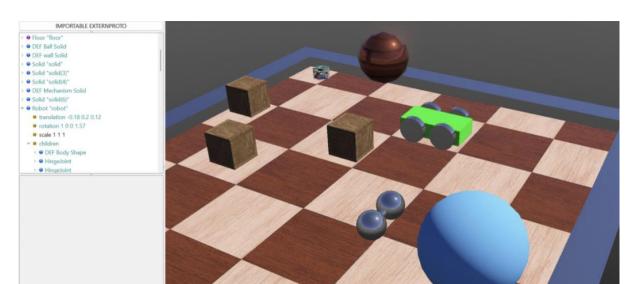


IMPORTABLE EXTERNPROTO

IMPORTABLE EXTERNPROTO

jointParameters NULL
device
device
RotationalMotor "rotational motor"
endPoint Solid
translation 0.06 0 0.05
rotation 0.358 0.863 0.357 1.72
scale 1 1 1
children
outpart of the scale of the



- IMPORTABLE EXTERNPROTO

 * Robot "robot"

 * translation -0.18 0.2 0.12

 * rotation 1 0 0 1.57

 * scale 1 1 1

 * children

 * DEF Body Shape

 * Hingeloint

 * Hingeloint

 * Hingeloint

 * Hingeloint

 * JointParameters HingelointParameters

 * device

 * RotationalMotor "rotational motor"

 * endPoint Solid

 * translation -0.06 0.00366 -0.0463

 * rotation 0.654 -0.378 0.655 -2.42

