

Machine Learning for Large-Scale Data Analysis and Decision Making (MATH80629A) Fall 2021

Week #4 - Summary



Announcement

Hybrid classroom: Mondays 8:30 am - 11:30 am
 Class room: Manuvie. This classroom is located on the 1st
 floor of Côte-Sainte-Catherine building.
 Zoom: Zoom link.

• Hybrid office hour: Mondays 11:30 am - 1 pm

Office:4.834

Zoom: Zoom link.

• Lab session on week #5 (September 27)

Lab room: Laboratoire Lachute



Today

- Second Quiz on Gradescope!
- Summary of Machine learning fundamental
- Q&A
- Hands-on session





Quiz 1

Login to your Gradescope account



Models for supervised learning

- (Mostly) linear models
- Focus on classification
- 1. Non-Probabilistic Models
 - Nearest Neighbor, Support Vector Machines (SVMs)
- 2. Probabilistic Models
 - Naive Bayes



Supervised learning

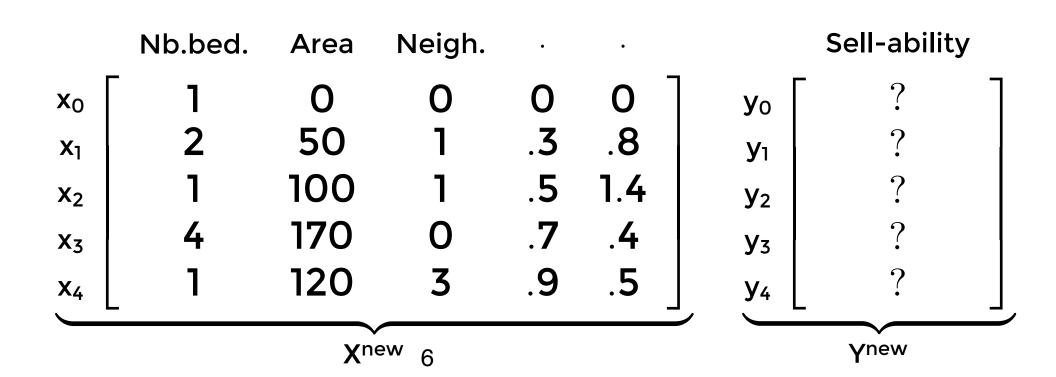
Train Data

| | Nb.bed. | Area | Neigh. | • | • | | Sell-ability | |
|-----------------------|---------|------|--------|----|-----|-----------------------|--------------|---|
| x ₀ | 1 | 0 | 0 | 0 | 0 | y _o [| 1 | 7 |
| x ₁ | 1 | 100 | 1 | .2 | .5 | y 1 | 2 | |
| X ₂ | 3 | 200 | 0 | .1 | .2 | y ₂ | 0 | |
| X3 | 1 | 150 | 1 | .4 | .1 | y 3 | 2 | |
| X4 | 2 | 210 | 2 | .5 | 1.1 | У4 | 1 | |
| | - | X | | | _ | | Y | |

Task

$$f:\mathbb{R}^n \to \{0,1,2\}$$

Test Data



Laurent Charlin & Golnoosh Farnadi — 80-629



Supervised learning

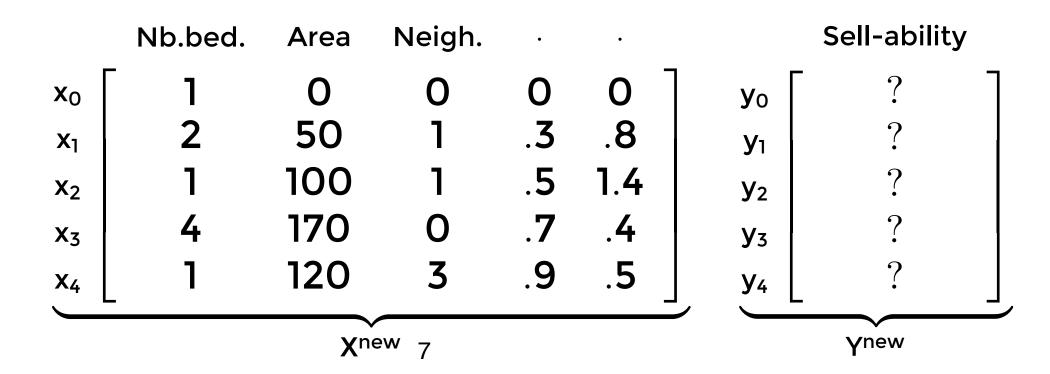
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| | | X | | | | | Y |

Task

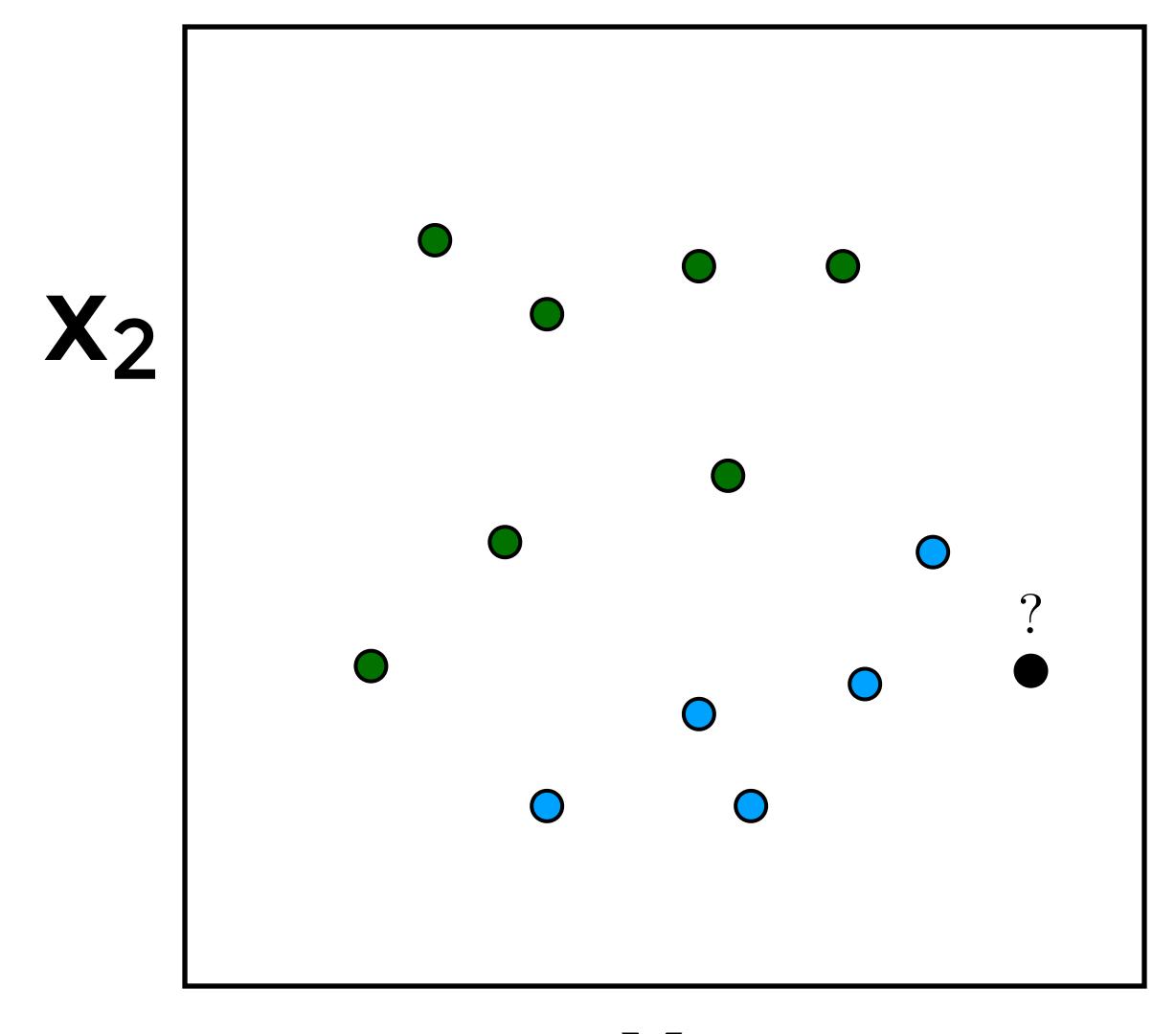
Models
$$f \mathbb{R}^n \to \{0,1,2\}$$

Test Data



Laurent Charlin & Golnoosh Farnadi — 80-629

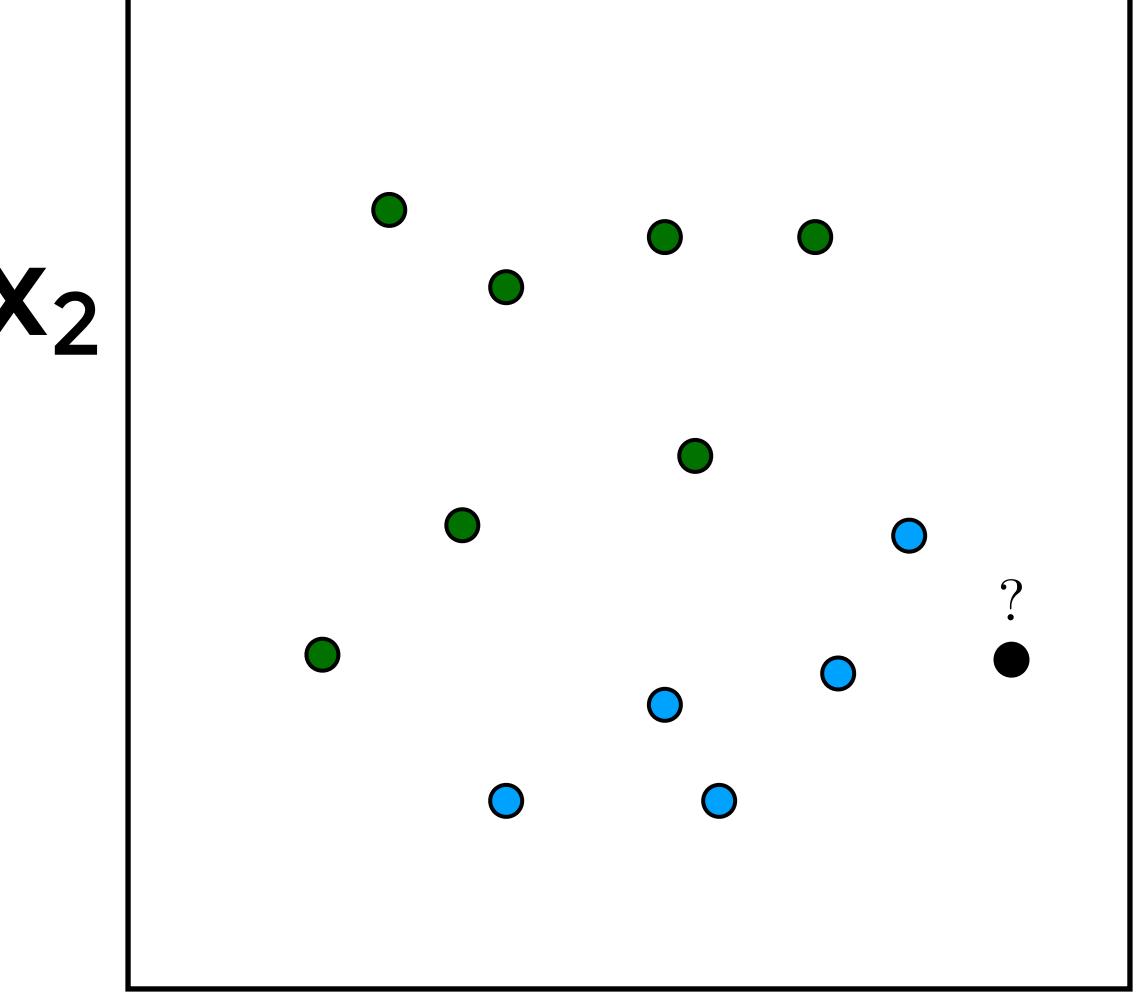








$$\begin{aligned} i' &= \arg\min_{i} dist(x_i, x_j) \\ y_j &= y_{i'} \end{aligned}$$



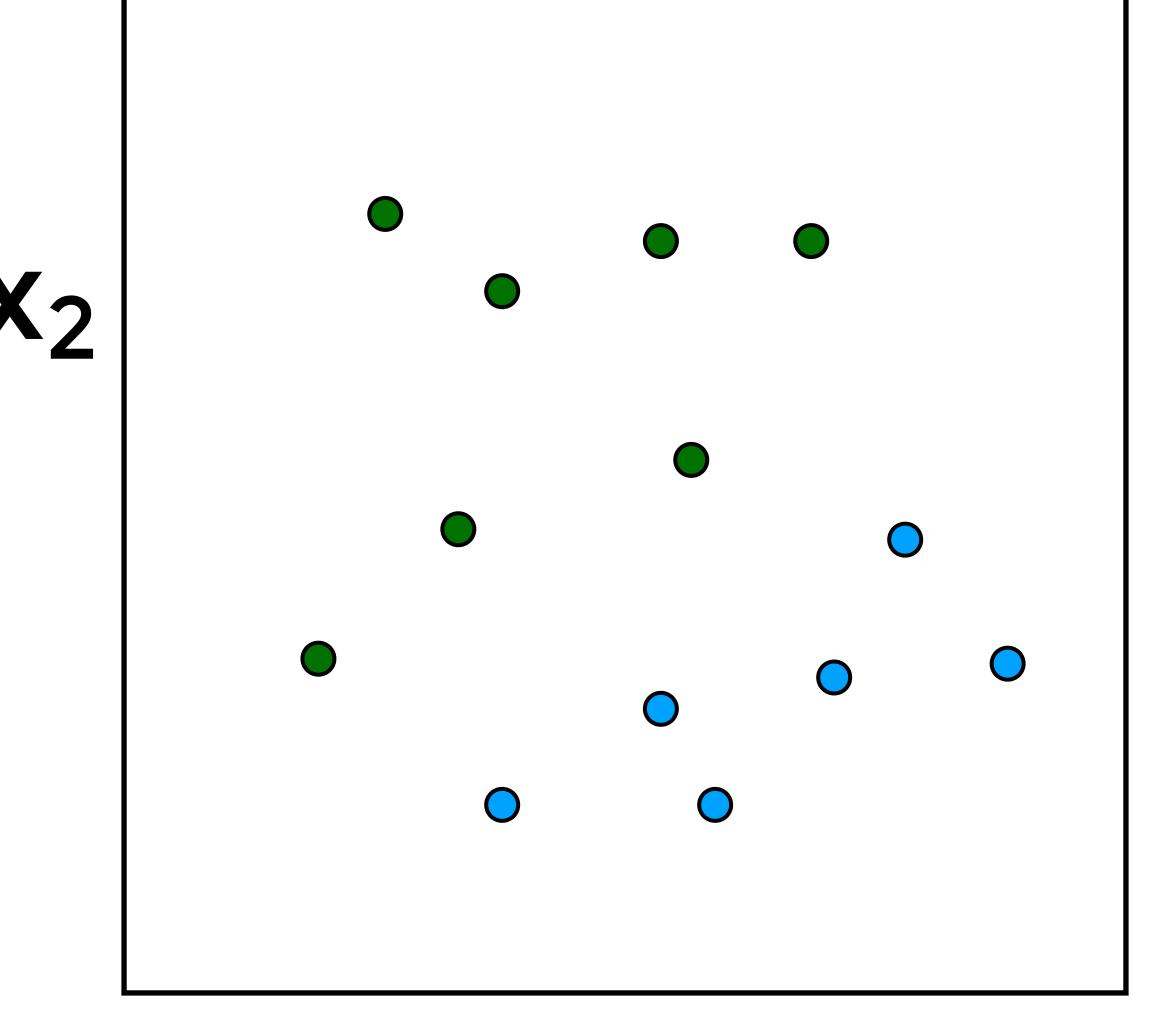
• 1-NN

Instance classified according to its nearest neighbor





$$\begin{aligned} i' &= \arg\min_{i} dist(x_i, x_j) \\ y_j &= y_{i'} \end{aligned}$$



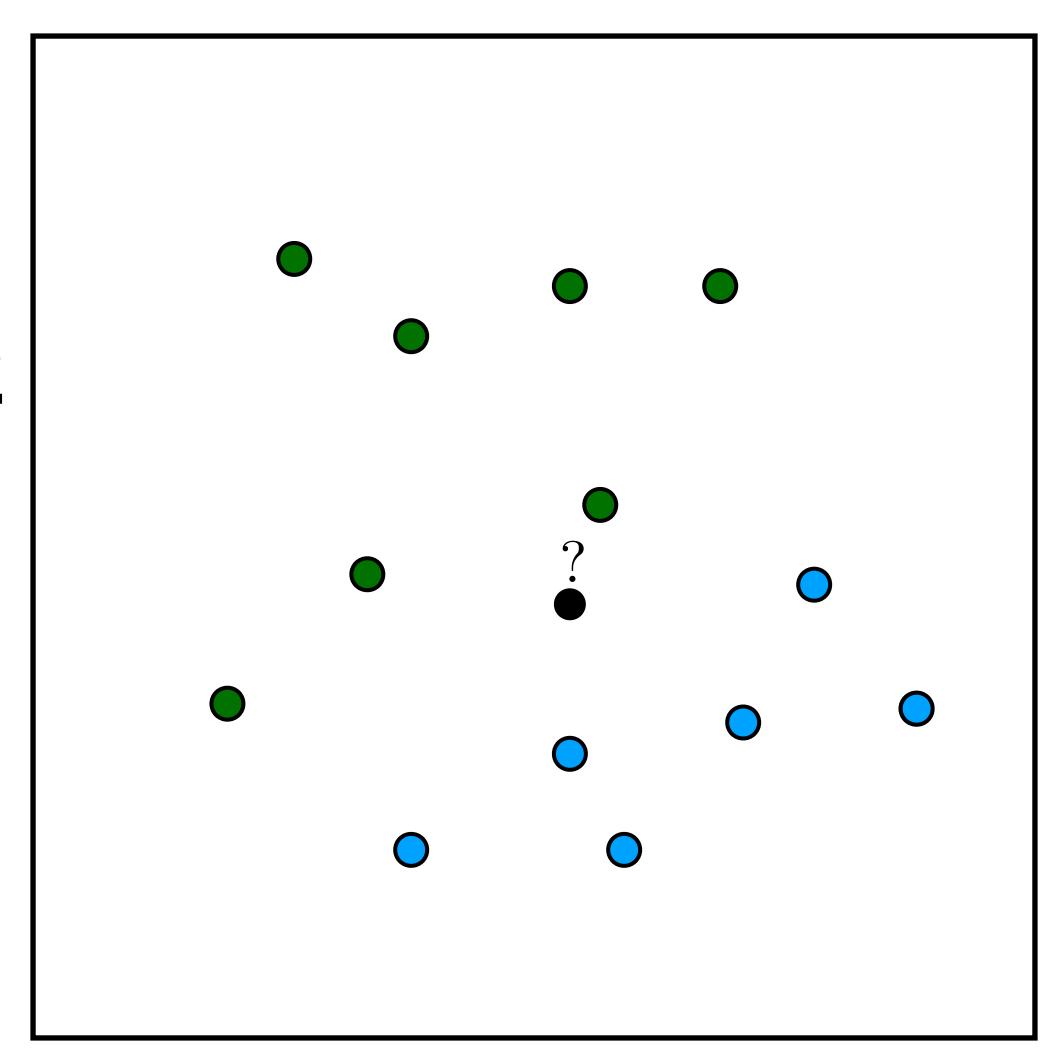
• 1-NN

Instance classified according to its nearest neighbor



$$\begin{aligned} \textbf{i}' &= \arg\min_{\textbf{i}} \textbf{dist}(\textbf{x}_{\textbf{i}},\textbf{x}_{\textbf{j}}) \\ \textbf{y}_{\textbf{j}} &= \textbf{y}_{\textbf{i}'} \end{aligned}$$





• 1-NN

Instance classified according to its nearest neighbor

K-NN

Instance classified according to the majority of its K nearest neighbors





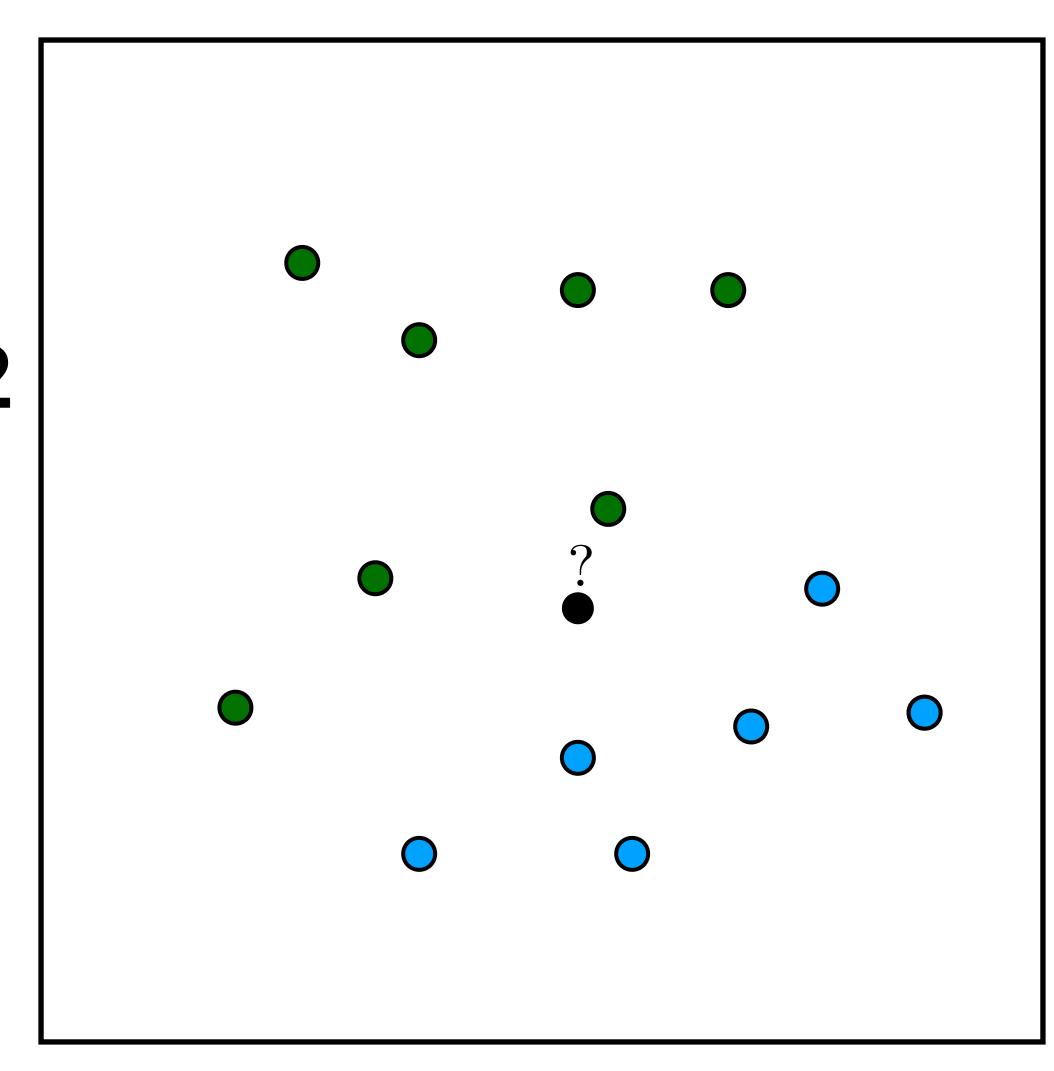
$$\begin{aligned} i' &= \arg\min_{i} dist(x_i, x_j) \\ y_j &= y_{i'} \end{aligned}$$

 X_2

k = 5 (assumption)

 $i = \arg \operatorname{sort}_i \operatorname{dist}(x_i, x_j)$

 $y_j = majority(i_{:5})$



• 1-NN

Instance classified according to its nearest neighbor

K-NN

Instance classified according to the majority of its K nearest neighbors





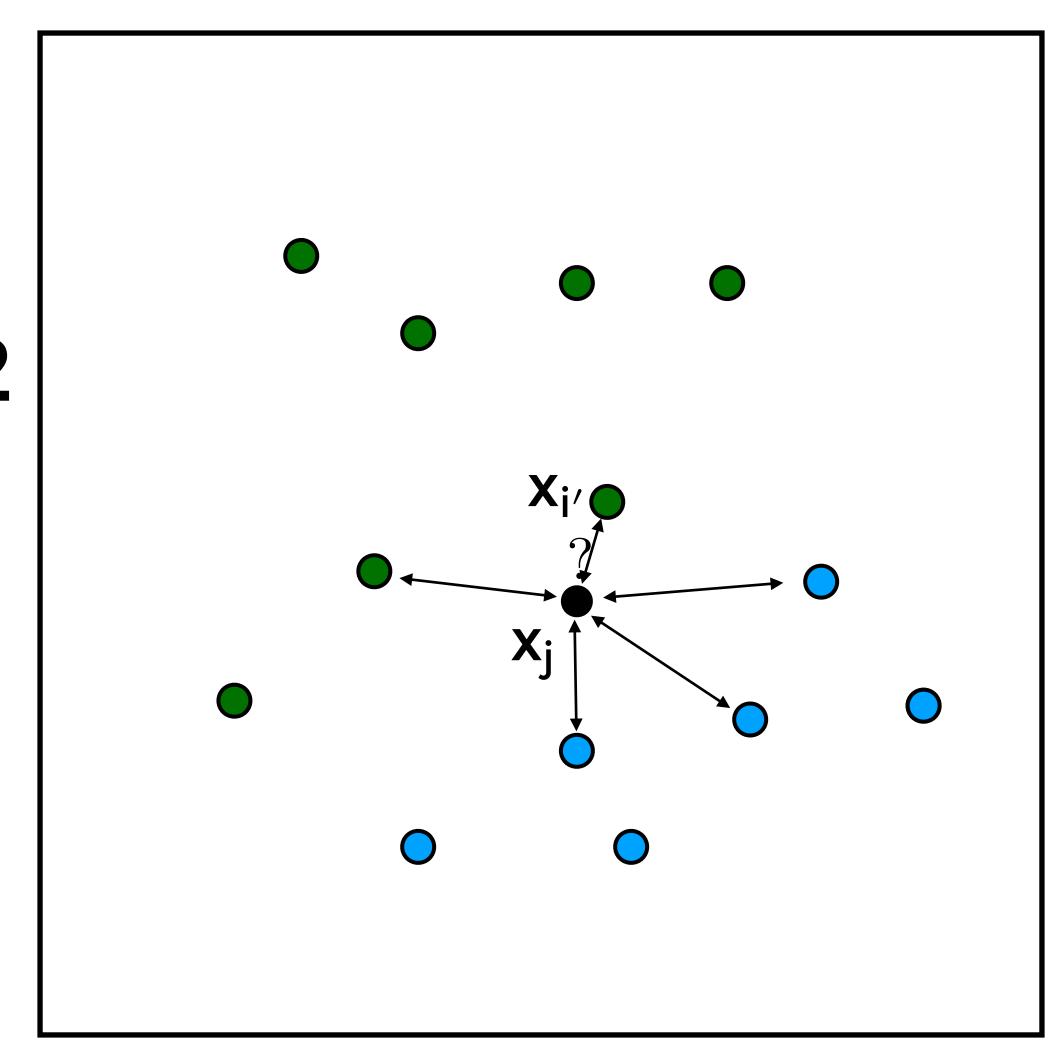
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• 1-NN

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K-NN

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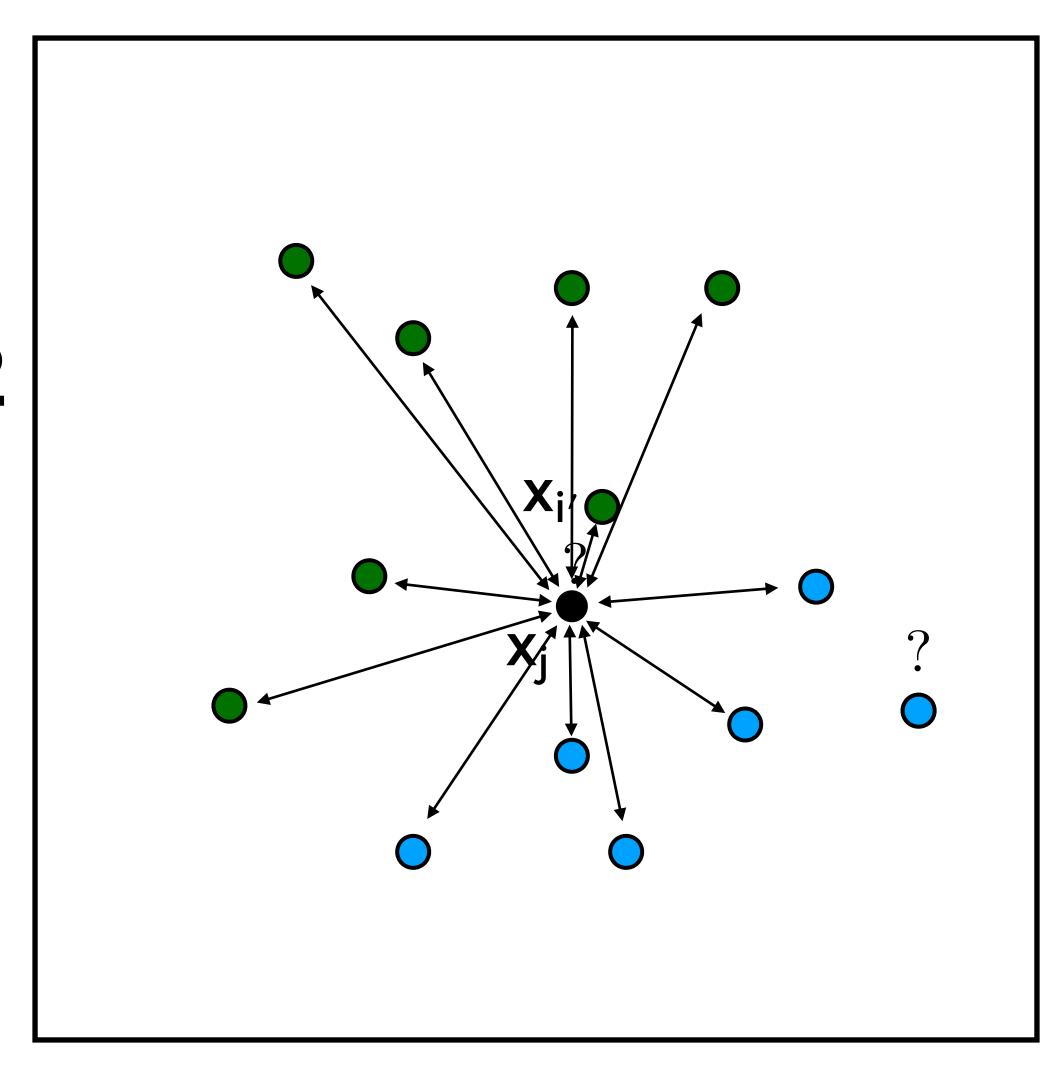
$$i' = \underset{i}{\operatorname{arg\,min}\,dist}(x_i, x_j)$$
 $y_j = y_{i'}$

 X_2

k = 5 (assumption)

 $i = arg sort_i dist(x_i, x_j)$

 $y_j = majority(i_{:5})$



X₁

• 1-NN

Instance classified according to its nearest neighbor

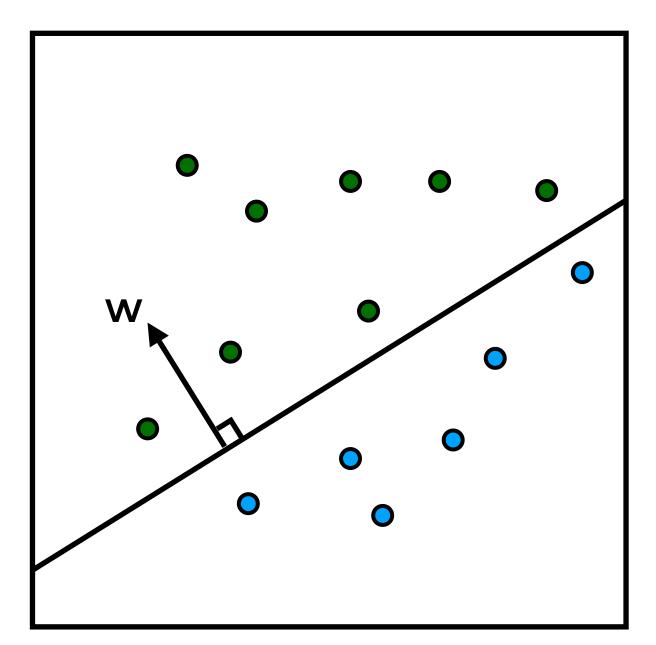
K-NN

Instance classified according to the majority of its K nearest neighbors

weighted-NN
Instance classified
according to all neighbors.
The contribution of each
neighbor is weighted by its
distance.



Linear Classification



decision boundary: y(x) = 0 take two points on the boundary: x_a, x_b

then:
$$\mathbf{w}^{\top}\mathbf{x}_{a} + \mathbf{w}_{0} = \mathbf{w}^{\top}\mathbf{x}_{b} + \mathbf{w}_{0}$$

$$\implies \mathbf{w}^{\top}(\mathbf{x}_{a} - \mathbf{x}_{b}) = \mathbf{0}$$

w is perpendicular to the decision boundary w represents the orientation of the decision boundary

$$\mathbf{y}(\mathbf{x}) = \mathbf{w}^{\mathsf{T}}\mathbf{x} + \mathbf{w}_{\mathbf{0}}$$

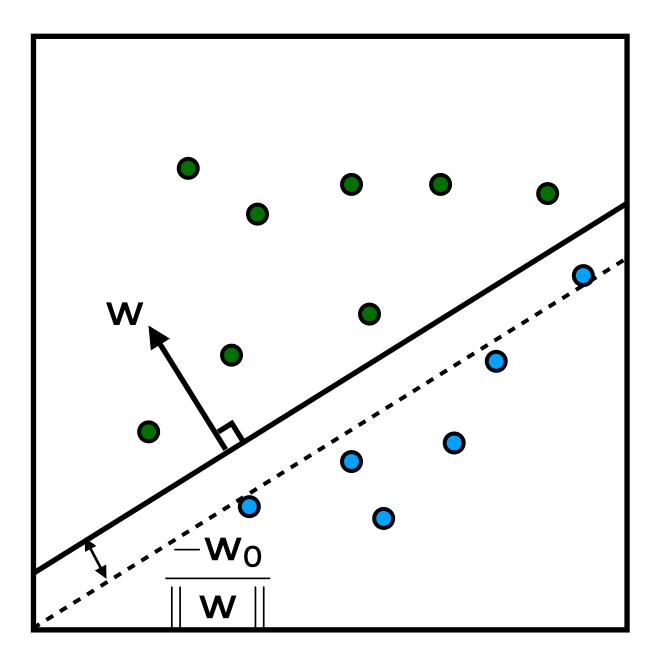
Decision

$$(\mathbf{w}^{\mathsf{T}}\mathbf{x} + \mathbf{w}_{\mathbf{0}}) > \mathbf{0} \implies \mathbf{0}$$

$$(\mathbf{w}^{\mathsf{T}}\mathbf{x} + \mathbf{w_0}) < \mathbf{0} \implies \mathbf{0}$$



Linear Classification



$$\mathbf{y}(\mathbf{x}) = \mathbf{w}^{\mathsf{T}}\mathbf{x} + \mathbf{w}_{\mathbf{0}}$$

Decision

$$(\mathbf{w}^{\top}\mathbf{x} + \mathbf{w}_{0}) > \mathbf{0} \implies \mathbf{0}$$

 $(\mathbf{w}^{\top}\mathbf{x} + \mathbf{w}_{0}) < \mathbf{0} \implies \mathbf{0}$

w₀ is a scalar

you can think of it like an intercept

take x' as the closest point on the decision boundary to the origin

$$\mathbf{x}' = \beta \mathbf{w}$$

$$\implies \mathbf{y}(\mathbf{x}') = \mathbf{w}^{\top}\mathbf{x}' + \mathbf{w_0}$$

$$\implies \mathbf{y}(\mathbf{x}') = \mathbf{w}^{\top}(\beta \mathbf{w}) + \mathbf{w_0}$$

$$\implies$$
 0 = $\beta \parallel \mathbf{w} \parallel^2 + \mathbf{w_0}$

$$\implies \beta = \frac{-\mathsf{W_0}}{\parallel \mathsf{w} \parallel^2}$$

Then you know that the distance from the origin to x' is:

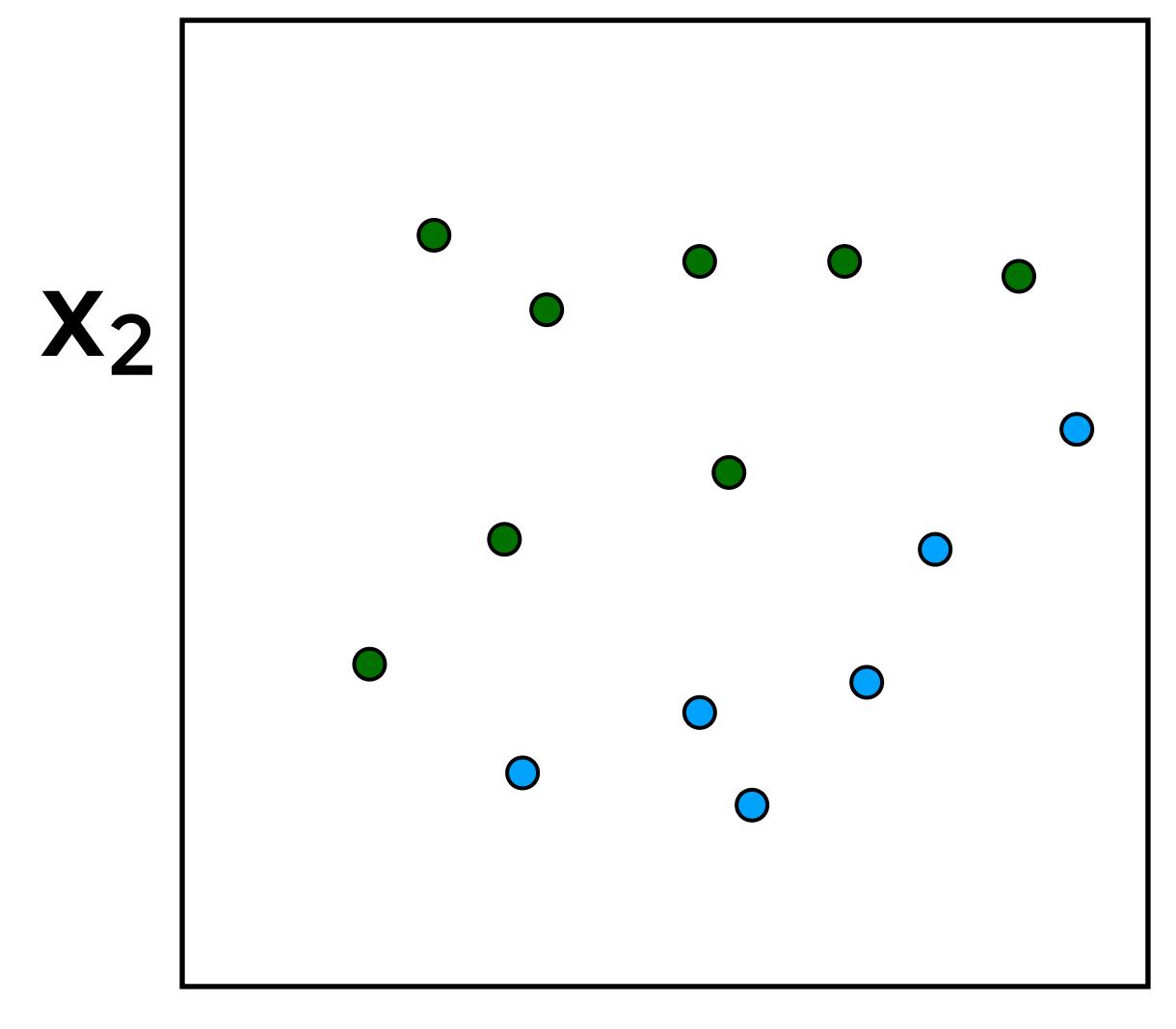
$$\| \mathbf{x}' \| = \| \beta \mathbf{w} \|$$

$$\Rightarrow \| \mathbf{x}' \| = \beta \| \mathbf{w} \|$$

$$\Rightarrow \| \mathbf{x}' \| = \frac{-\mathbf{W}_0}{\| \mathbf{w} \|^2} \| \mathbf{w} \|$$

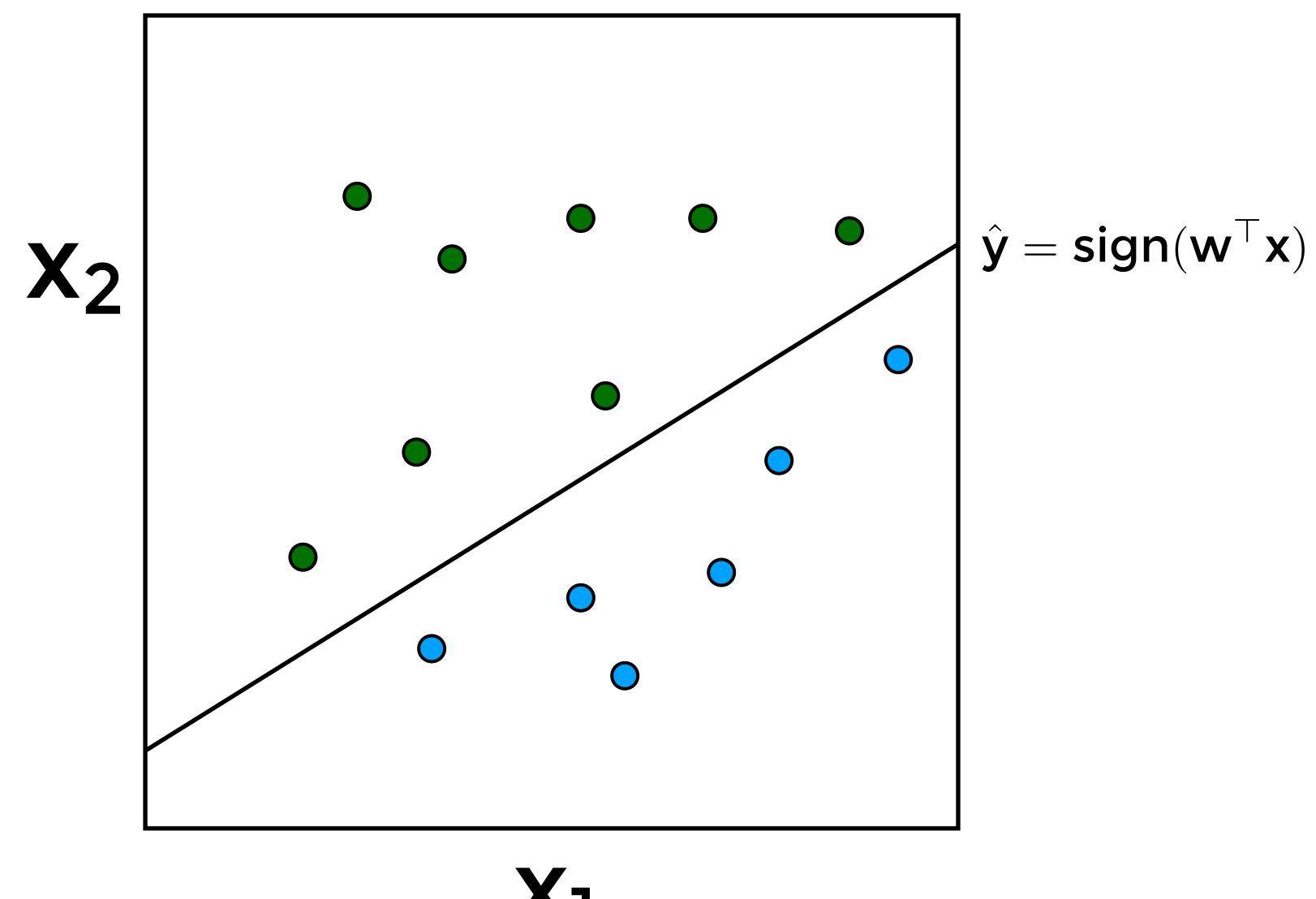
$$\Rightarrow \| \mathbf{x}' \| = \frac{-\mathbf{W}_0}{\| \mathbf{w} \|^2}$$



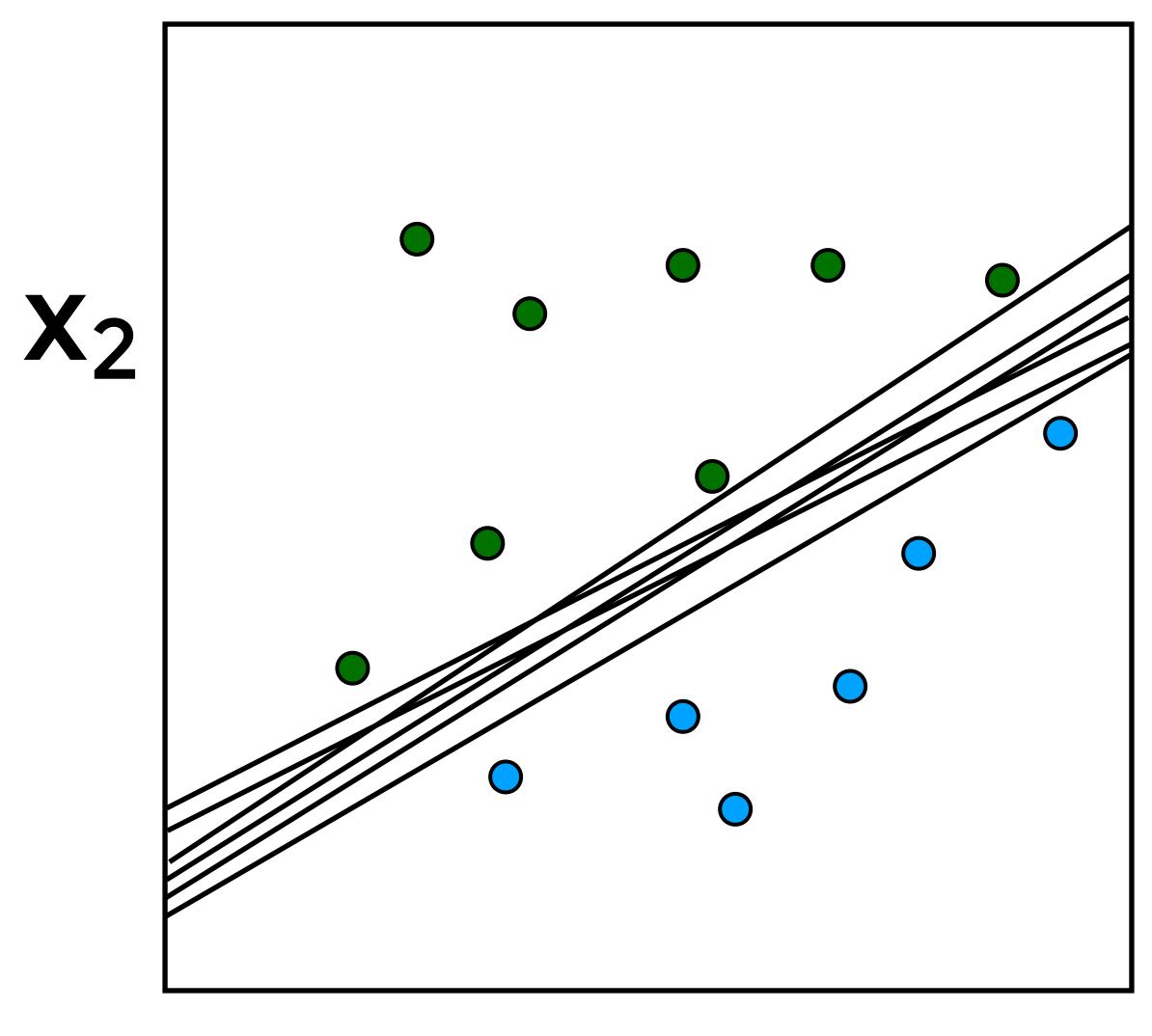


X

HEC MONTREAL





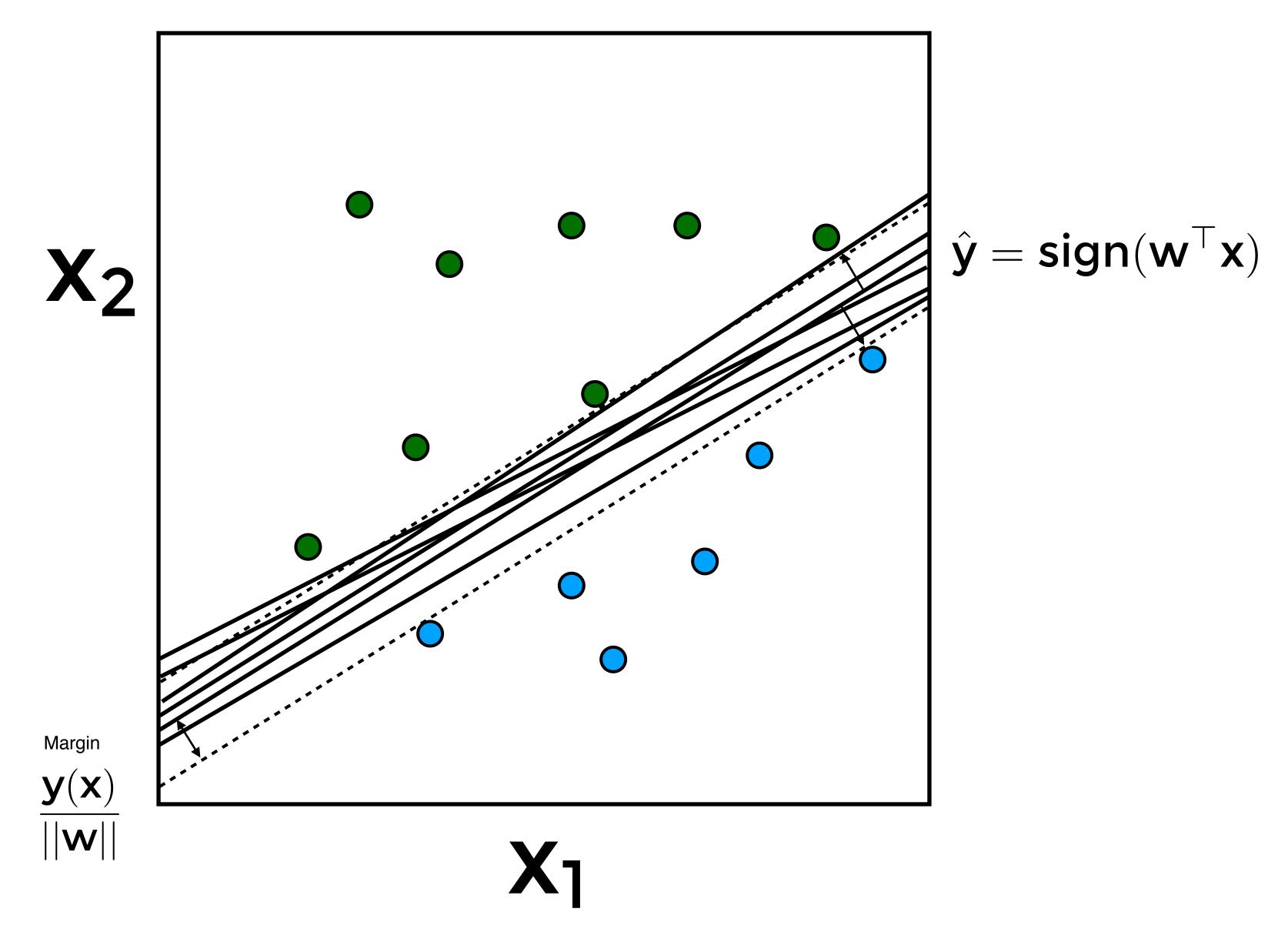


$$\hat{\mathbf{y}} = \operatorname{sign}(\mathbf{w}^{\top}\mathbf{x})$$

X

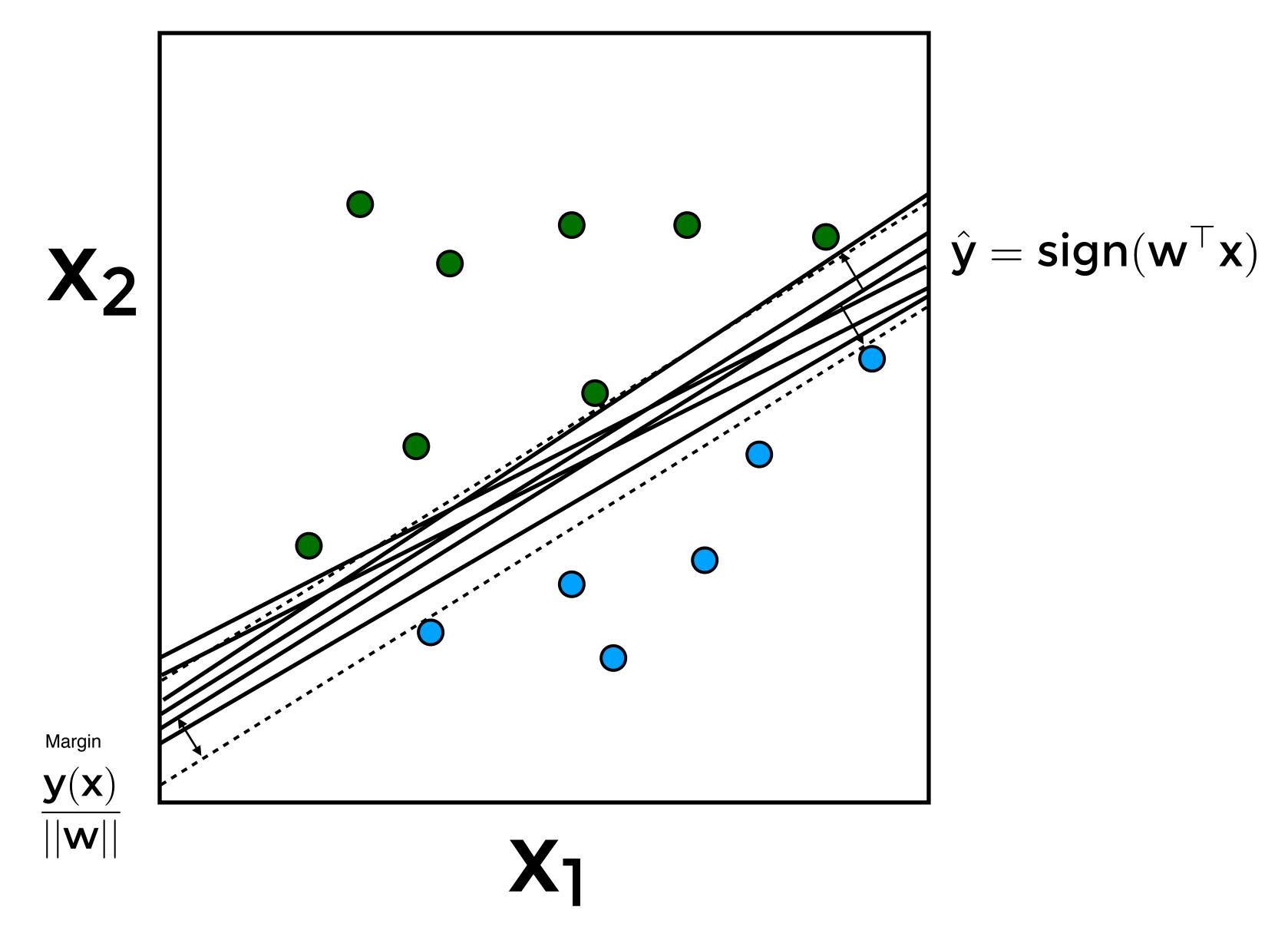


The objective is to find the separating boundary that maximizes the margin



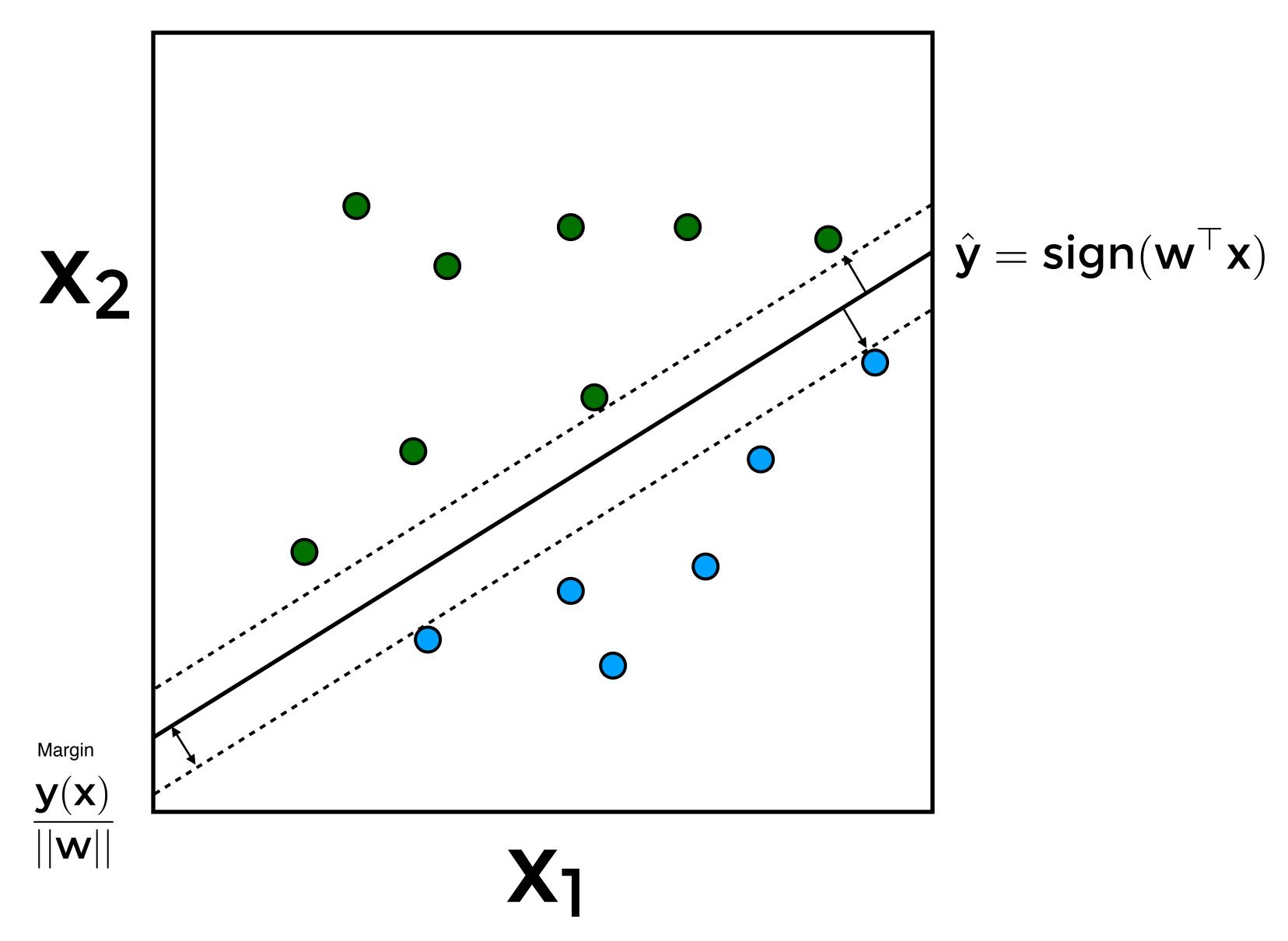


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The objective is to find the separating boundary that maximizes the margin





Probabilistic Models for Classification



Probabilistic Models separate Decision and Inference

Non-Probabilistic Modelling



Probabilistic Modelling

Probabilistic Model

$$\longrightarrow$$
 P(y = k|x) \longrightarrow

Decision Rule



Probabilistic models

1. Model the conditional directly:

$$P(y = k|x)$$

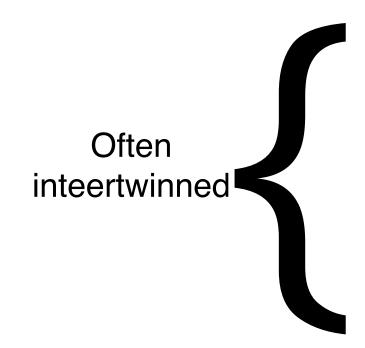
2. Model the joint (or the prior and the class conditionals):

Bayes' Theorem

$$\begin{array}{cccc} \underline{P(y=k|x)} \propto \underline{P(y=k,x)} \\ & \text{posterior} & \text{joint} \\ & = & \underline{P(x\mid y=k)} & \underline{P(y=k)} \\ & \text{class conditional densities class prior} \end{array}$$



Probabilistic Modelling



- 1. Posit a model: P(X, Y)
 - How the data is generated
- 2. Parametrize the distributions: P(X, Y I Parameters)
- 3. Set the objective (e.g., MLE)
- 4. Learn the parameters of the model:
 - E.g., Naive Bayes: learn the parameters of the class conditional P(XIV) and of the prior P(Y)
- 5. Use the model (e.g., for predictions)