

# Toward A Reinforcement Learning-based Rectilinear Macro Placement under Human Constraints

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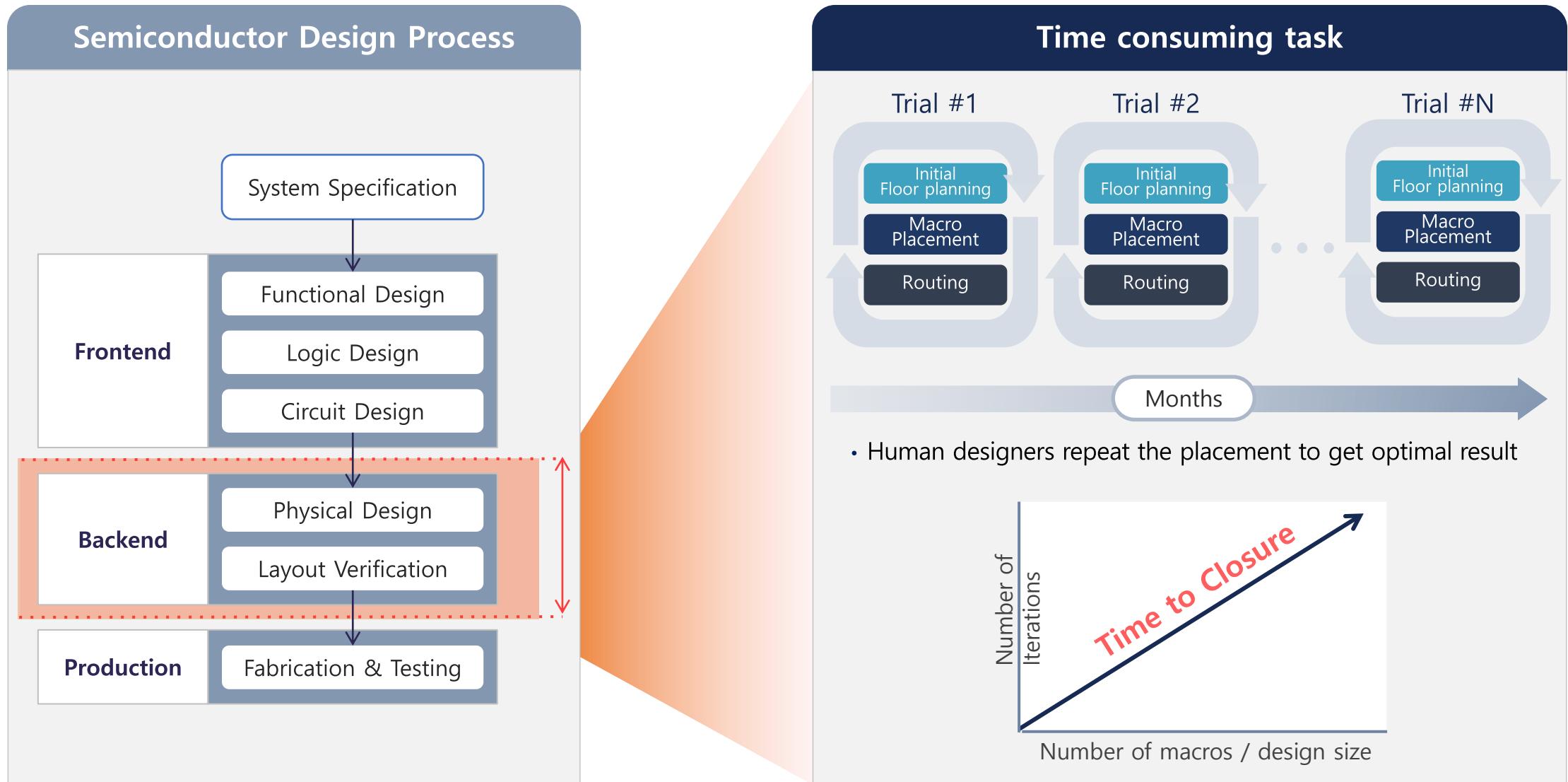
03

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Conclusions

# Macro placement is a critical phase in chip design



# Google's Nature Paper: Deep Reinforcement Learning-based Macro Placement

This method is a chip placement approach that has the **ability to generalize**, meaning that it can leverage what it has learned while placing previous netlists to generate better placements for new unseen netlists.



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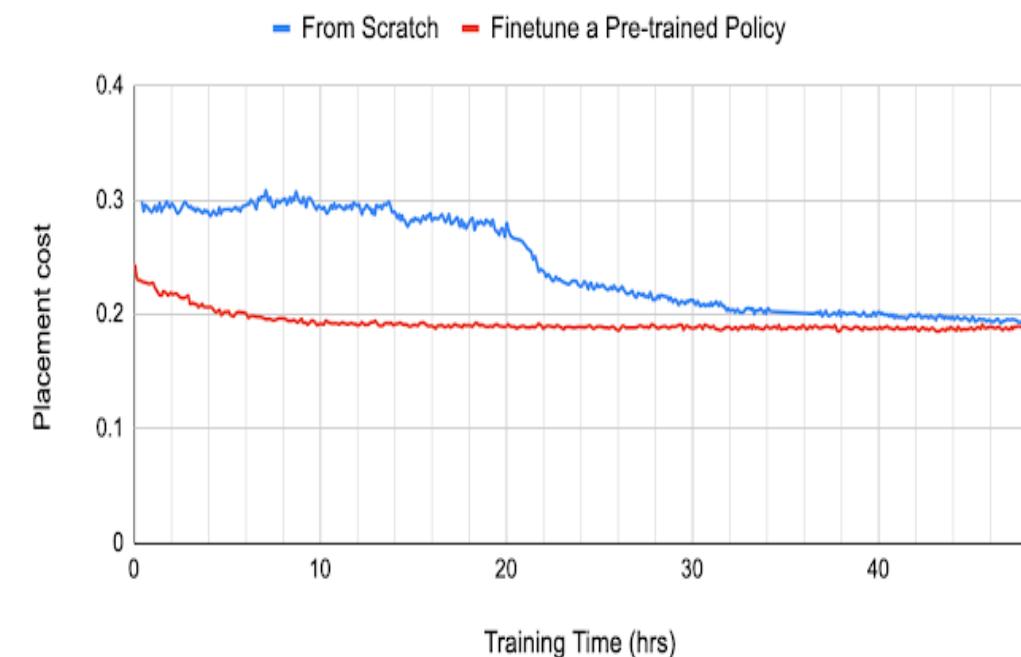
Article | Published: 09 June 2021

## A graph placement methodology for fast chip design

Azalia Mirhoseini , Anna Goldie , Mustafa Yazgan, Joe Wenjie Jiang, Ebrahim Songhori, Shen Wang, Young-Joon Lee, Eric Johnson, Omkar Pathak, Azade Nazi, Jiwoo Pak, Andy Tong, Kavya Srinivasa, William Hang, Emre Tuncer, Quoc V. Le, James Laudon, Richard Ho, Roger Carpenter & Jeff Dean

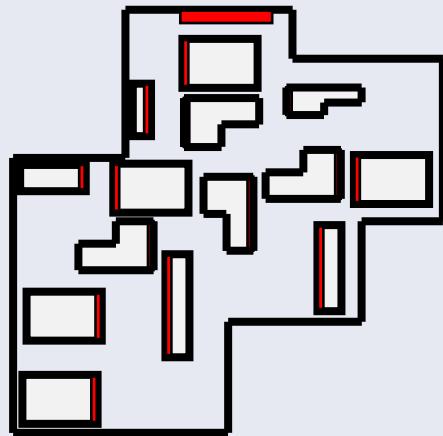
[Nature](#) 594, 207–212 (2021) | [Cite this article](#)

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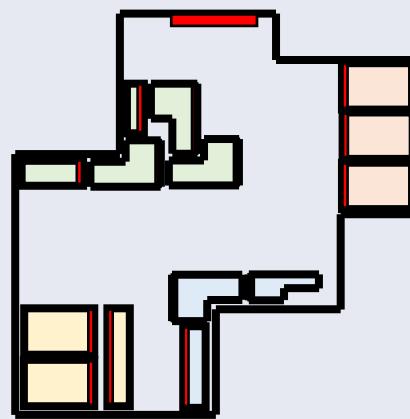
# Motivation

## Dealing with rectilinear macros and layout areas.



- ✓ Macro placement becomes more intricate when involving general **rectilinear macros and layout areas**

## Human-like constraints



- ✓ Macro placement that incorporates human-like constraints, such as **design hierarchy** and **peripheral bias**, has the potential to significantly reduce the amount of additional manual labor required from designers.

## Reduce training resources

Training resources from Google Circuit Training

For the training we utilized the following servers and jobs:

- 1 Replay Buffer(Reverb)/Eval server 32vCPUs (n1-standard-32)
  - 1 Replay Buffer(Reverb) job
  - 1 Eval job
- 20 Collect servers 96vCPUs (n1-standard-96)
  - Each server running 25 collect jobs for a total of 500.
- 1 Training server: 8xV100s (n1-standard-96)
  - 1 Training job

- ✓ We want to constrain training resource utilization to typical configurations
  - 01 x A5000 GPU (24GB)
  - 01 x 64vCPUs

# Our Efforts

## Enhancements on Google's CT

- We propose enhancements to CT-based macro placement including fine-tuning placement to account for human-like constraints
  - Placing macros based on design hierarchy
  - Placing macros at the periphery

## Rectilinear macros and layout areas

- We present methods to unify macro placement using macros and layout areas for general rectilinear shapes
- To the best of our knowledge, this is the **first** work dealing with rectilinear layout areas and macro shapes using RL.

## RL model Enhancement

- We propose an enhanced RL model and demonstrate that our RL-based placer can use fewer resources
- RL model still achieves competitive PPA metrics

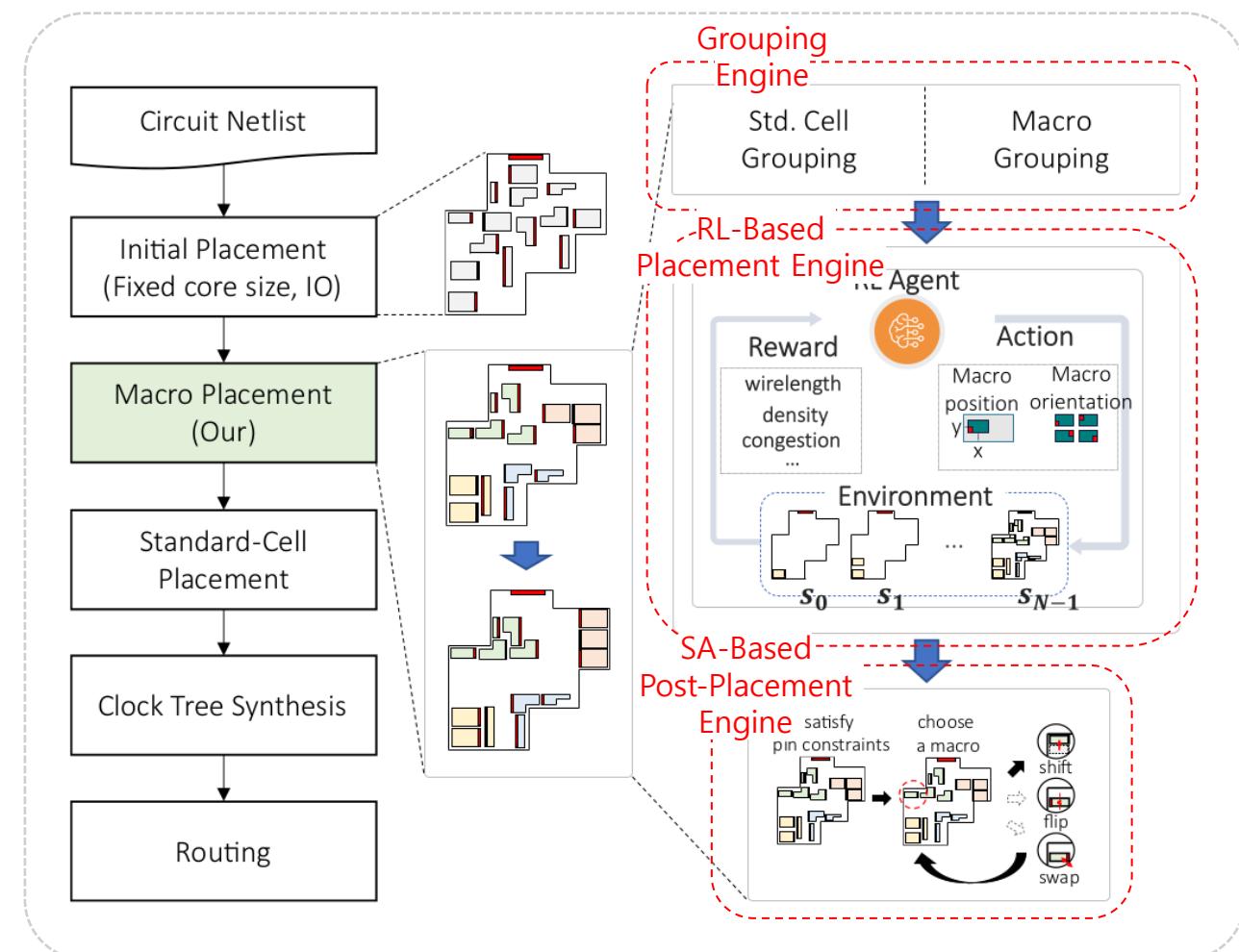


# Our Methodology

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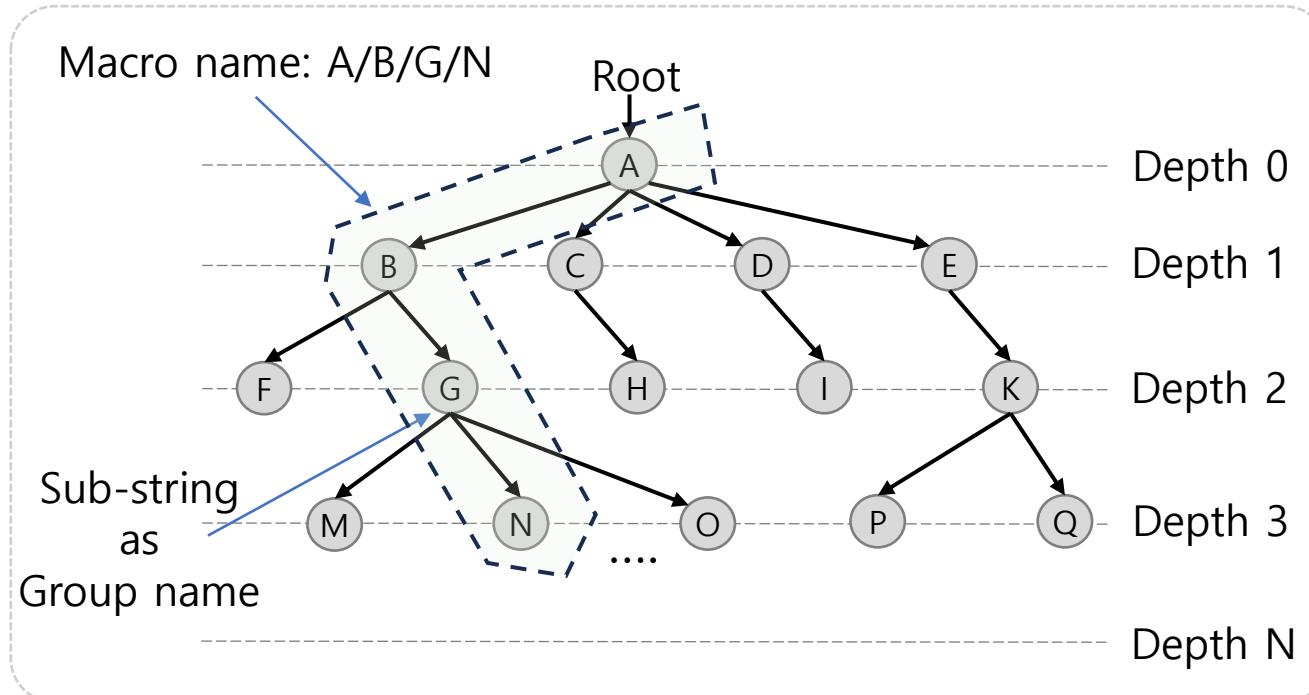
# Methodology

- Our framework consists of three distinct engines designed to optimize the processes of standard cell and macro grouping, macro placement, and post-processing placement:
  - The grouping engine** groups millions of standard cells into several clusters and classifies all the macros into groups based on the design hierarchy
  - The RL-based placement engine** receives input from the grouping engine and produces near-final placements. This engine uses methods to handle rectilinear macros and layout areas, and to satisfy constraints about the design hierarchy, and peripheral bias
  - The SA-based post-placement engine** fine tunes the results generated by the RL placement engine for better pin accessibility, and dead-space minimization.



# Grouping Macros

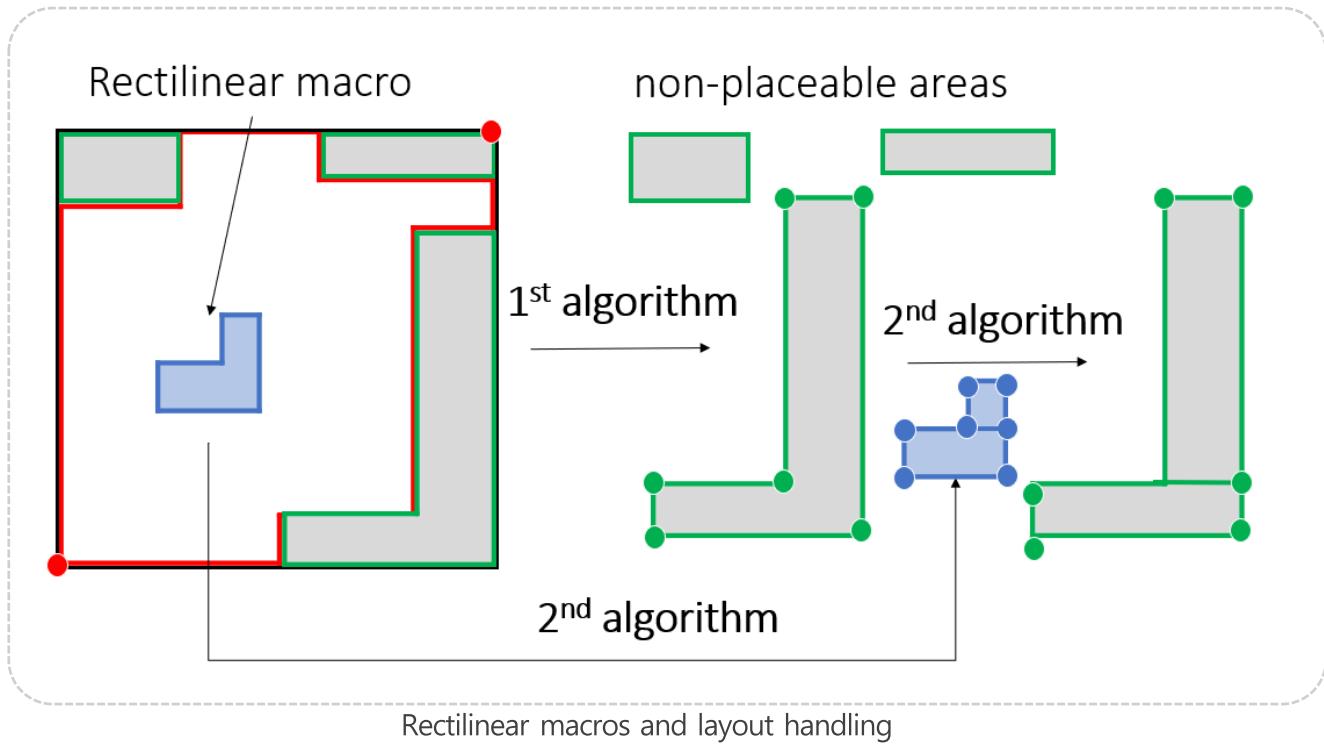
Grouping macros can be guided by human or automatically inferred from the netlist (as we did not have access to the original RTL).



- Grouping macros based on human when human guidance is possible.
- When human guidance is not possible, we propose an alternative method which analyzes the names of all macros in the netlist
  - Recursive search procedure is implemented at each depth level of the tree.
  - If a node at a given depth level has more than one child, it is considered a group
  - Otherwise, the search continues to deeper depth levels

# Rectilinear Macros and Layout Handling

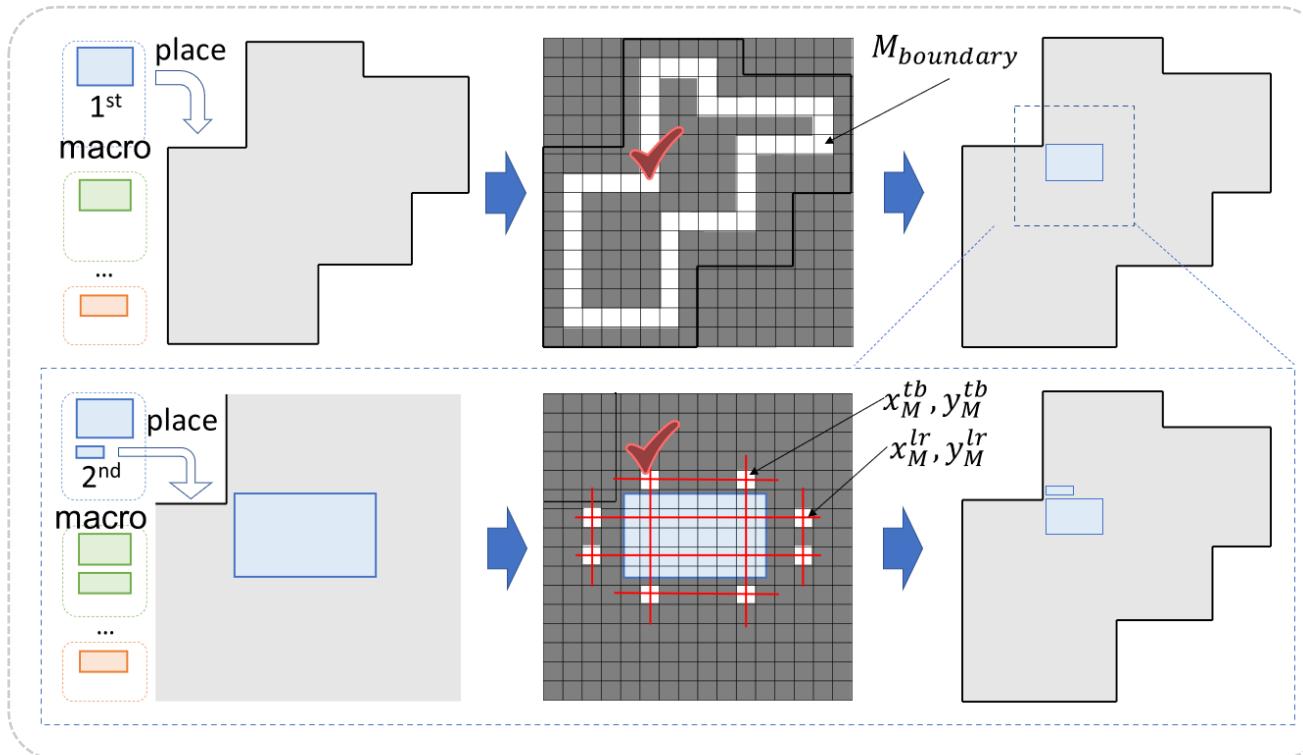
We propose two algorithms for handling the placement of rectilinear macros, allowing the use of a grid-based masking algorithm (next slide) to work with “primitive”, i.e. rectangular, blocks and maximize the use of the layout area.



- The **first** algorithm identifies non-placeable areas
- The **second** algorithm decomposes each rectilinear shape (non-placeable areas and rectilinear macros) into multiple rectangles

# Masking Control Algorithm

We control the position mask to ensure that the currently placed macro adheres to the design hierarchy and periphery bias

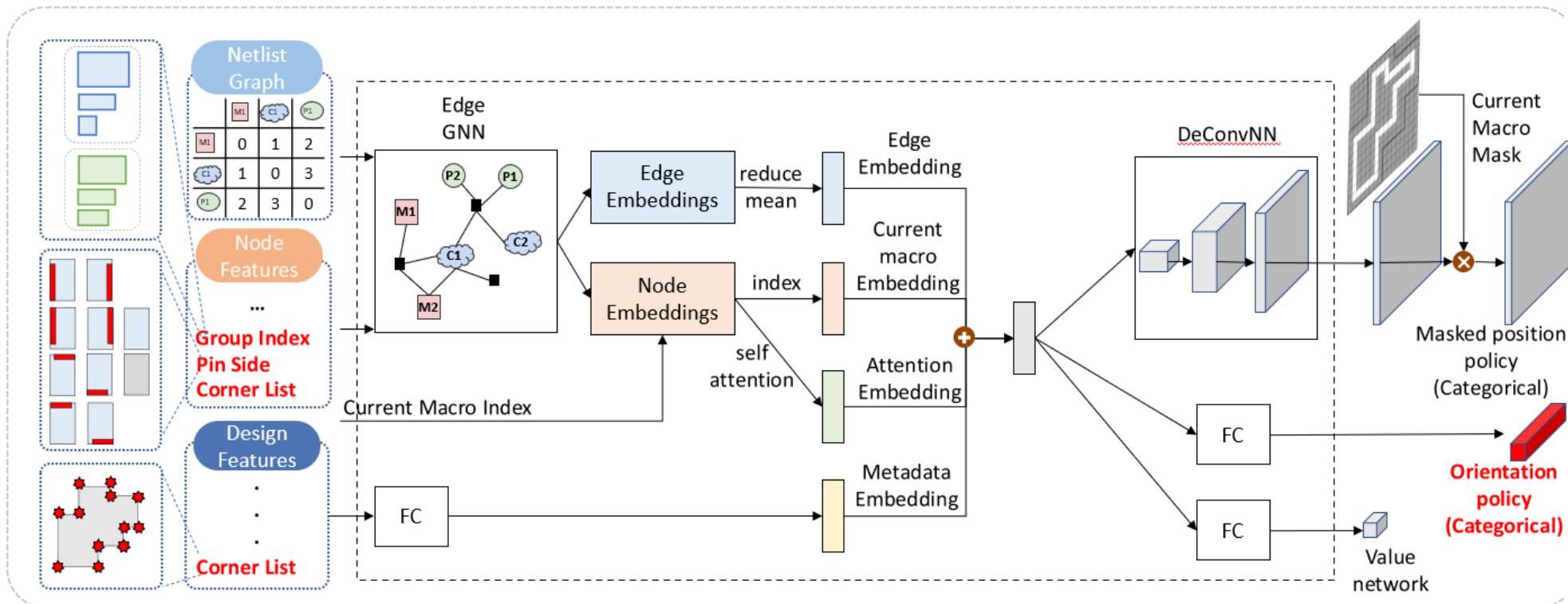


An illustration of the masking control algorithm.

- If the macro is the **first** from its group:
  - the position mask is the boundary mask ( $M_{boundary}$ ), which allows the macro to be placed only by the closest peripheral grid cells.
- Beginning with the **second** macro of a group:
  - The algorithm restricts the placeable grid cells to be in close proximity to macros from the same group that have already been placed

# Neural network model

Our proposal incorporates additional information that significantly enriches the macro and design features. Furthermore, as an additional advancement, we upgrade our model to a two-head policy.



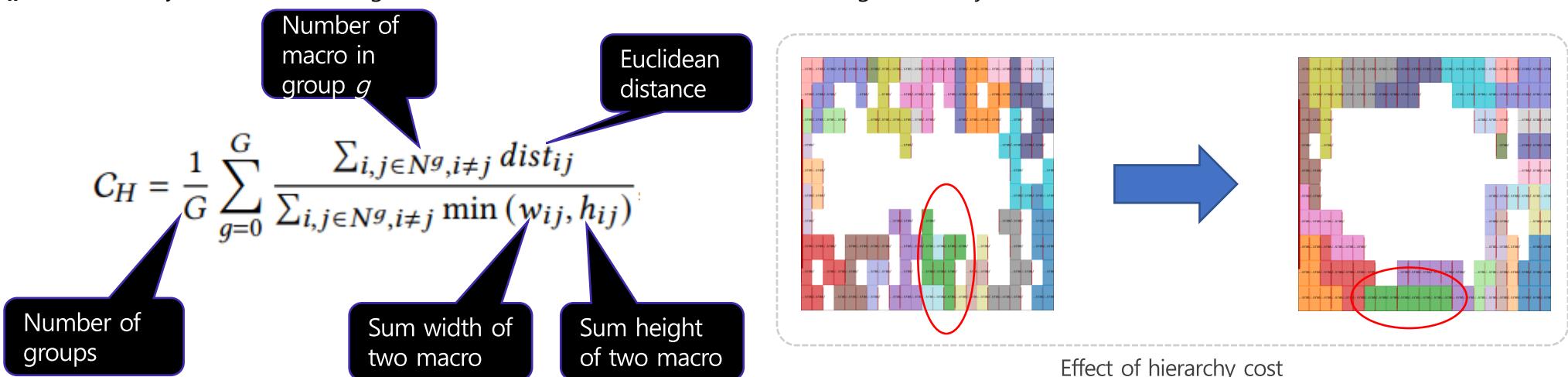
- Additional information:
  - group index
  - pin side
  - corner list
- Two-head policy:
  - macro position
  - macro orientation

## Reward function

Our reward function R is defined as a negative weighted sum of four proxy costs:

$$\mathcal{R} = -(\alpha C_W + \beta C_C + \gamma C_D + \omega C_H)$$

- $C_W$ : the wirelength cost is approximated as the normalized half-perimeter wirelength (HPWL)
- $C_D$  : the density cost is approximated as the average density of the densest 10% of grid cells
- $C_C$  : the congestion cost is approximated as the average of the top 5% most congested grid cells
- $C_H$  : the hierarchy cost is to encourage closeness between macros in the same design hierarchy

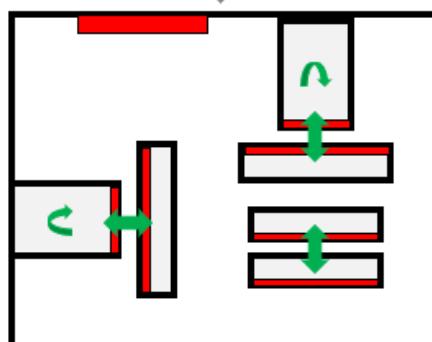
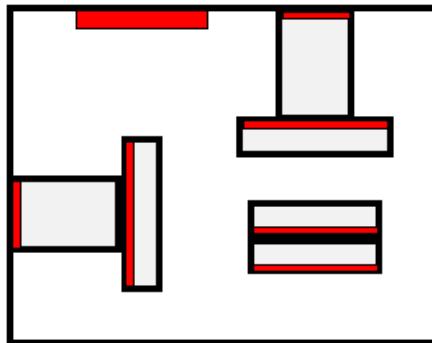


# Simulated Annealing-based Post Placement Engine

SA-based post placement is aim to achieve human-quality placement in terms of pin accessibility and dead-space minimization.

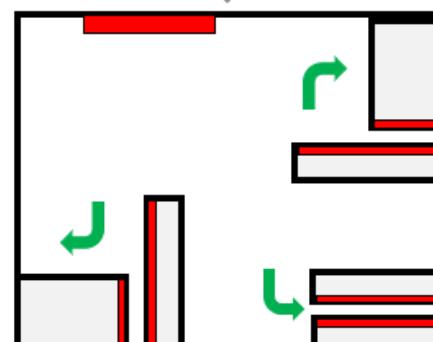
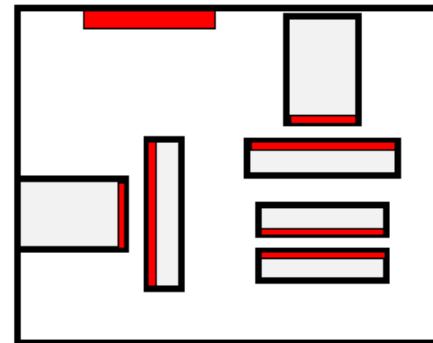
- **Pin Constraints**

- Orient the pins of edge macros inward.
- Maintain spacing between pins and other macros.



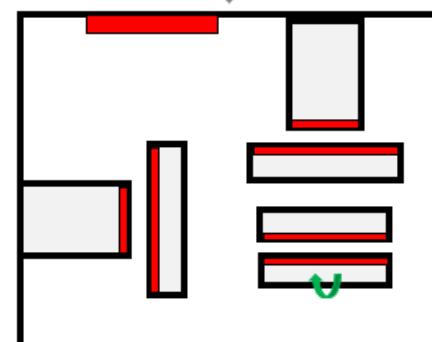
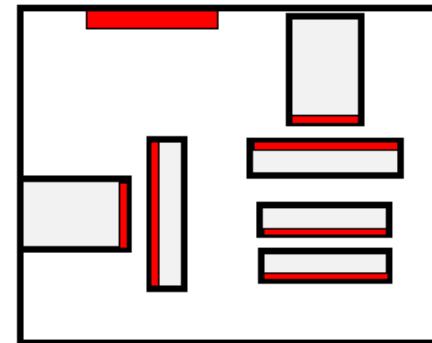
- Macro Action : **Shift**

- Push macros towards the edge to reduce dead space.



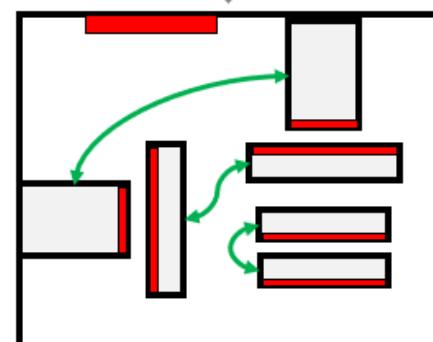
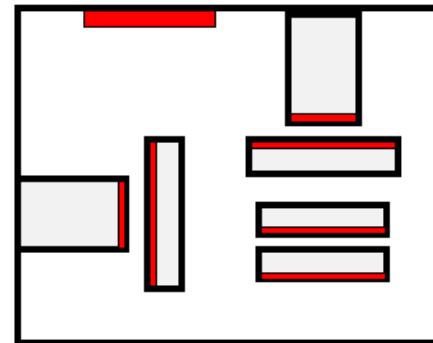
- Macro Action : **Flip**

- Flip or rotate macros to minimize wirelength.



- Macro Action : **Swap**

- Modify macros of the same shape within the same group to reduce costs.



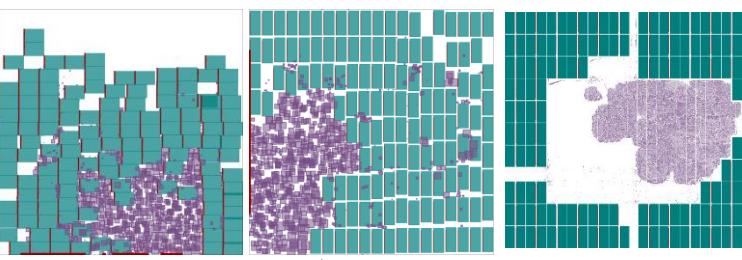


# Experiments

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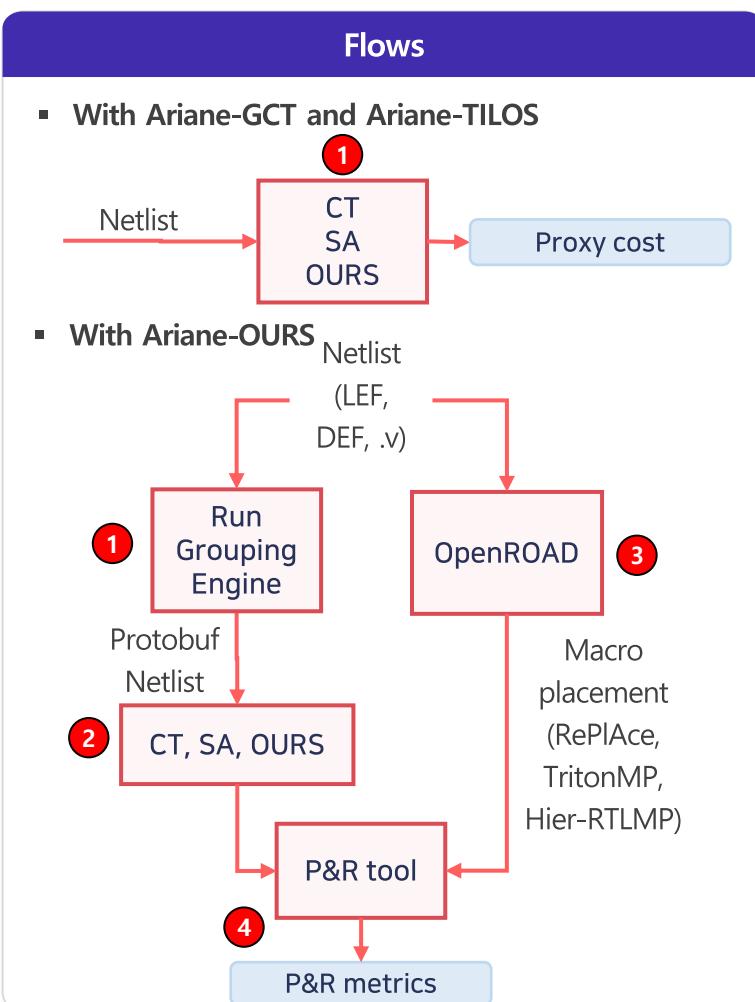
# Evaluation designs, flows, and settings

Designs					
Designs	Netlist information				# Clusters
	Core Size	# Macros	# IOs	# Clusters	
Ariane (GCT)	356.592 356.640	133	1231	799	
Ariane (TILOS)	1347.1 1346.8	133	495	810	
Ariane (OURS)	1445.9 1444.8	133	495	41	



Ariane-GCT      Ariane-TILOS      Ariane-OURS

- We evaluate the framework using three netlists of Ariane CPU provided by [2] (Ariane-GCT), [10] (Ariane-TILOS), and a version we generated using NanGate45 standard-cell library (NG45)



**Settings**

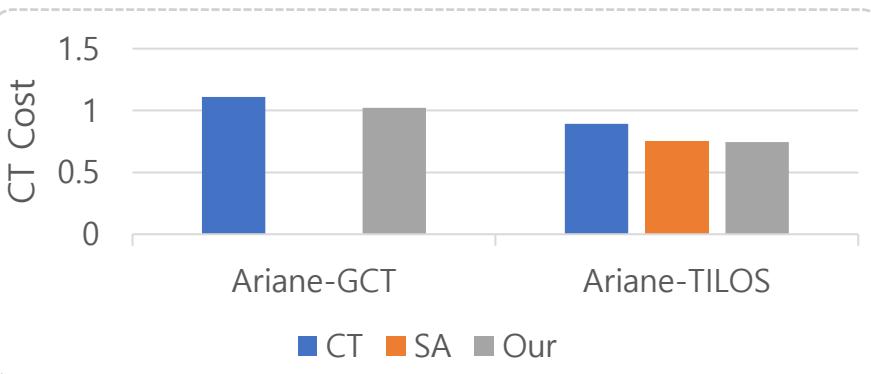
Designs	Model Configuration			
	Ori. Grid	Our Grid	# Nodes	# Edges
Ariane (GCT)	35x33	12x18	1200	10000
Ariane (TILOS)	23x28	23x10	1200	12000
Ariane (OURS)	-	25x10	200	1100

- Infrastructure:**
  - A server with a 64-thread CPU, and an A5000 GPU with 24 GB of memory
  - Each run uses 25 collectors
- Settings:**
  - We keep almost all training settings the same as the settings from [2] and [10].
  - The cost weights  $\alpha$ ,  $\beta$ ,  $\gamma$ , and  $\omega$  were set to 5.0, 1.0, 0.5, and 0.1
  - We select the grid size ( $N_r$  and  $N_c$ ) relative to the chip canvas so that the smallest macro can fit inside a grid cell

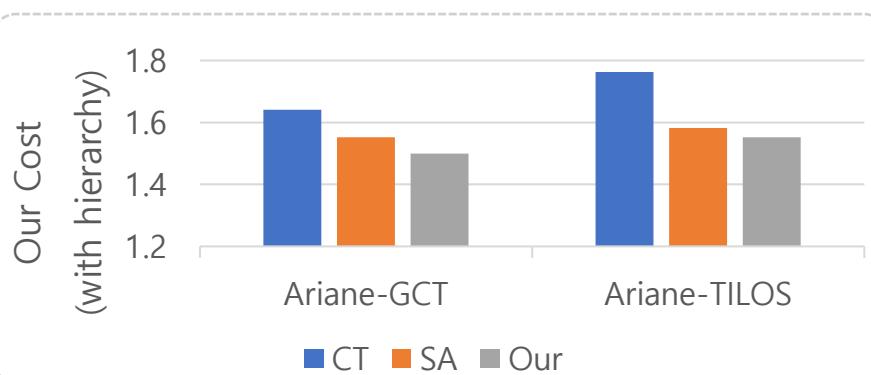
[2] Circuit Training. [https://github.com/google\\_research/circuit\\_training](https://github.com/google_research/circuit_training)

[10] C. Cheng, A. Kahng, S. Kundu, et al. 2023. Assessment of Reinforcement Learning for Macro Placement. In Proc. ISPD. 158–166.

## 1.1 Evaluations Using Ariane-GCT and Ariane-TILOS netlist



① Comparison with published results in [2][10]



② Comparison by adding hierarchy cost

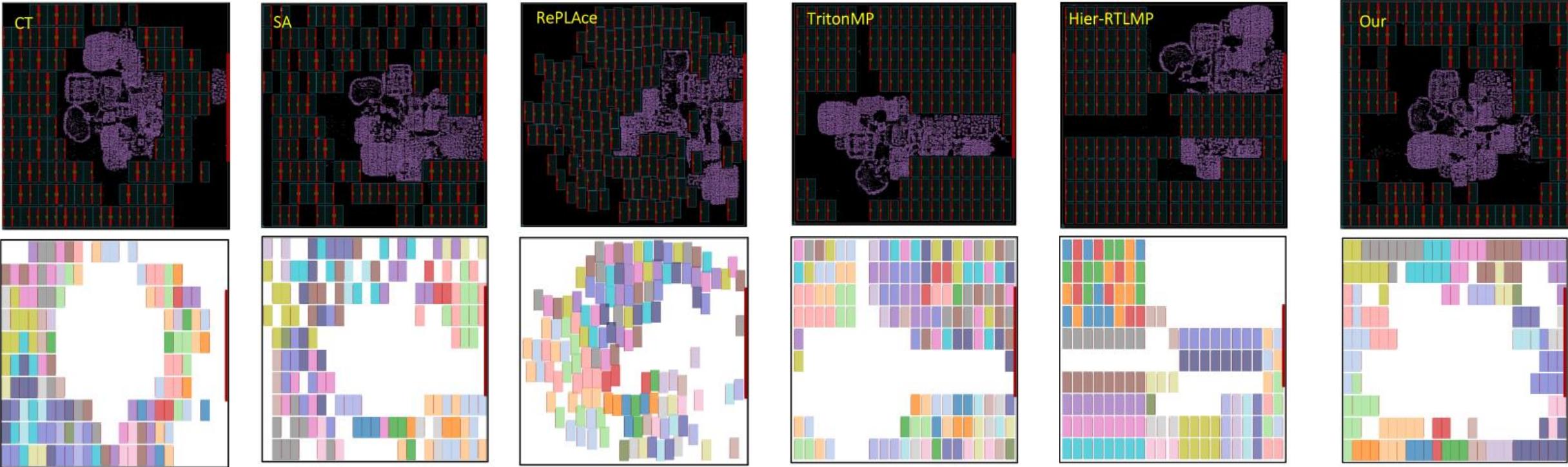
- ① Our method can produce placements that show better proxy cost than those published in [2] and [10]
  - Our method has 8% and 16.7% improvement (compared to CT) on Ariane-GCT and Ariane-TILOS, respectively
- ② By adding hierarchy cost to the reward function:
  - Our method has 8.6% and 12% improvement (compared to CT) on Ariane-GCT and Ariane-TILOS, respectively

Designs	Placer	CT metrics				CT Cost	Our Cost	Inference time(h)
		WL Cost	Den. Cost	Cont. Cost	Hier. Cost			
Ariane (GCT)	CT[2]	0.1013	0.5502	0.9174	-	1.1102	-	-
	CT <sub>(12×18)</sub>	<b>0.0886</b>	0.5345	0.8852	2.2115	-	1.6411	0.02
	SA <sub>(12×18)</sub>	0.0963	<b>0.5057</b>	0.8446	1.4281	-	1.5523	14
	Our <sub>RL</sub>	0.0973	0.5088	0.8507	1.0571	1.0315	1.5264	0.02
	Our <sub>POST</sub>	0.0933	0.5070	<b>0.8414</b>	<b>1.0565</b>	<b>1.0209</b>	<b>1.4997</b>	0.1
Ariane (TILOS)	CT[10]	0.1060	0.5280	1.0470	-	0.8932	-	-
	SA[10]	0.0860	0.4990	0.8350	-	0.7533	-	12.5
	CT <sub>(23×10)</sub>	<b>0.0975</b>	0.5860	0.7881	2.9580	-	1.7635	0.02
	SA <sub>(23×10)</sub>	0.1061	<b>0.5038</b>	0.7761	1.5988	-	1.5820	10
	Our <sub>RL</sub>	0.1092	0.5121	0.7701	<b>1.3207</b>	0.7503	1.5752	0.02
	Our <sub>POST</sub>	0.1045	0.5156	<b>0.7643</b>	1.3211	<b>0.7444</b>	<b>1.5522</b>	0.1

[2] Circuit Training. [https://github.com/google\\_research/circuit\\_training](https://github.com/google_research/circuit_training)

[10] C. Cheng, A. Kahng, S. Kundu, et al. 2023. Assessment of Reinforcement Learning for Macro Placement. In Proc. ISPD. 158–166.

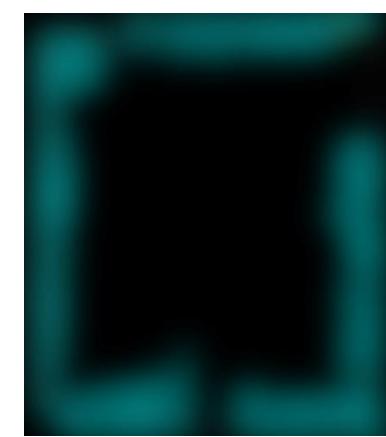
## 1.2 Evaluation using Our Generated Ariane Netlist



- In three out of four metrics, our framework has the **best or second-best** results compared to other placers.
- Our placer shows similarities to HierRTLMP in term of placing macros based on the design hierarchy, as well as **similarities** to both Hier-RTLMP and TritonMP in placing macros on the periphery

P&R Metrics (post-route)								
Designs	Placer	Area (mm <sup>2</sup> )	WNS (ns)	TNS (ns)	# DRC	Power (mW)	Proxy cost	Inference time (h)
Ariane (OURS)	CT <sub>(25×10)</sub>	1.2806	-0.91	-4833.9	9	585	1.8570	0.02
	SA <sub>(25×10)</sub>	1.2850	-0.93	-5320.6	9	586	1.7879	14
	RePLAce	1.2812	-1.04	-5423.7	9	584	1.7244	1
	TritonMP	1.2839	-0.89	-5068.2	9	586	1.9621	1
	Hier-RTLMP	1.2823	-0.84	-4632.2	7	586	1.6482	8
	Our	1.2803	-0.86	-4731.0	6	586	1.5807	0.1

## 2. Evaluation of Industrial Designs

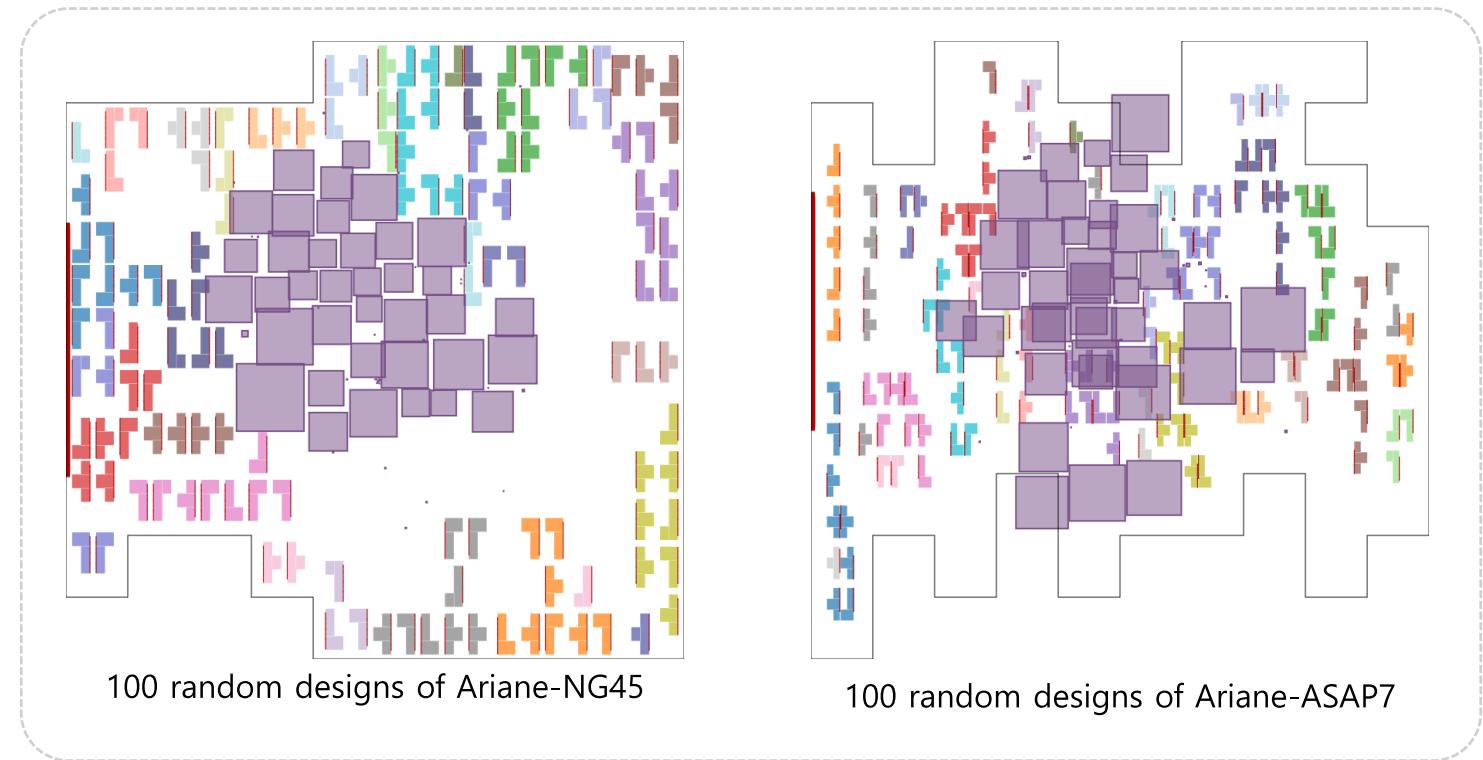


Designs	# Macro	# Types	# IOs	# Cells	# Nets	Recti. Layout	Recti. Macros
ic1	89	59	1125	1.5M	1.7M	✓	
ic2	169	97	630	3.8M	4.3M	✓	
ic3	94	21	2207	1.8M	1.8M	✓	✓
<b>Layout Metrics</b>							
Designs	Placer	Area (mm <sup>2</sup> )	WNS (ns)	TNS (ns)	# DRC	Power (mW)	Run time(h)
ic1	Human	0.4550	-0.6201	-0.6201	2559	44.6	weeks
	Comm	<b>0.4495</b>	<b>-0.6044</b>	<b>-0.6044</b>	<b>2491</b>	46.8	0.5
	Our	0.4548	-0.6178	-0.6178	2695	<b>43.7</b>	14
ic2	Human	1.0331	-0.0709	-376.68	<b>6619</b>	62.6	weeks
	Comm	1.0256	-0.0739	-302.11	23088	<b>58.5</b>	12
	Our	<b>1.0206</b>	<b>-0.0698</b>	<b>-288.59</b>	23542	59.8	28
ic3	Human	5.7972	-0.4193	-1.4651	<b>3924</b>	284	weeks
	Comm	5.7965	-0.4544	-15.5075	5038	274	1.7
	Our	<b>5.7961</b>	<b>-0.1402</b>	<b>-0.5792</b>	4313	<b>269</b>	14

- We only applied reasonable efforts (**no “benchmarking”**), meaning we wanted to see if results were comparable, and not to try to prove if any such approach could “beat” the others.
- Our placer achieved PPA results that are better than those obtained by the designers within a few evaluations and are **quite comparable** to those achieved by the timing-driven placer from the P&R tool

### 3. Evaluation of Shape Generalization (#1)

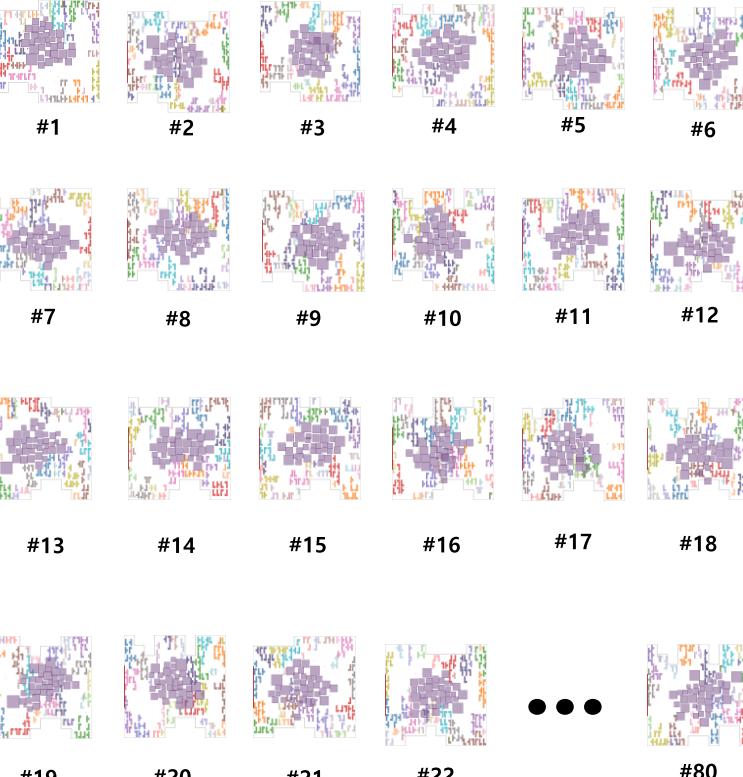
- We create 100 random synthesized designs of Ariane-NG45 (80 for training and 20 for testing)
- We create 100 random synthesized designs of ASAP7 (for testing)
- We restricted the macro shapes to L, J and T patterns
- We avoided modifying macro shapes on their IO sides



### 3. Evaluation of Shape Generalization (#2)

The last experiment assessed the possible generalization of our model to designs containing rectilinear macros and areas.

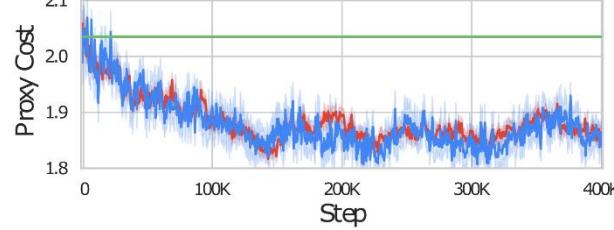
**Training on 80 synthesized Ariane-NG45**



**Testing**

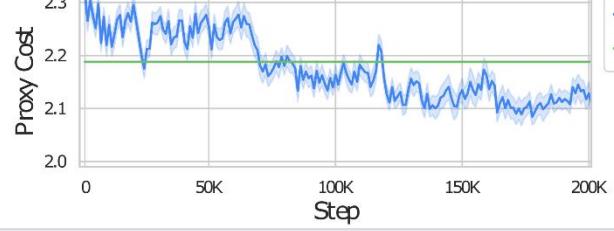
**01 Testing on 20 synthesized Ariane-NG45**

- The model is well trained to fit rectilinear designs from NG45



**02 Testing on 100 synthesized Ariane-ASAP7**

- The model-generated placements improved outperforming the random placements after 100K policy updates



**03 Adaptation**

- Adapting from a pre-trained model enabled the model to converge **faster** than training the model on that design from scratch



## 4. Runtime Analysis

Designs	Inference Time (h)	Training Time (h)
A-GCT	0.1	14
A-TILOS	0.1	10
A-OURS	0.1	14

Runtime

Resource	GPU	CPU
GCT	08 x A100s	20 x 96vCPUs
TILOS	08 x A100s	02 x 96vCPUs
OURS	01 x A5000	01 x 64vCPUs

Training Resources

- Our learning-based placer only needs a few minutes to obtain a good placement (Inference Time)
- To generate a well-trained agent, we need a few hours of training

- It's worth noting that with the same amount of training time, our placer consumes fewer computing resources than other placers

# Conclusions

## Respects crucial human-like constraints

- Placement solution respects crucial human-like constraints
  - Design hierarchy
  - Peripheral bias

## Generalization

- This approach has the potential to generalize a learned model to various designs with rectilinear macros and areas.

## Reduce Training Resources

- We conducted on standard training machines.
- This can drive the research in RL-based placement towards efficiency and affordability.



# Demo page

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<https://anonymous.4open.science/r/rI4cad-AE0F>



# Q & A

# Thank you!