

Benchmarking the Robustness of Neural Network-based Partial Differential Equation Solver

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Machine Learning for Science

- ◆ AI shows its power in scientific computing
- ◆ ML can learn how to solve partial differential equations (PDEs)
 - › Neural PDE solver Ψ_{θ}
 - › Learn a mapping from PDE variables \mathcal{A} to PDE solution \mathcal{U}
- ◆ Example models
 - › CNNs, PINN, Fourier neural operators
- ◆ Scientific applications
 - › Physical simulation, flow prediction, weather forecast...

The fundamental driving force is ***High-Quality Data***

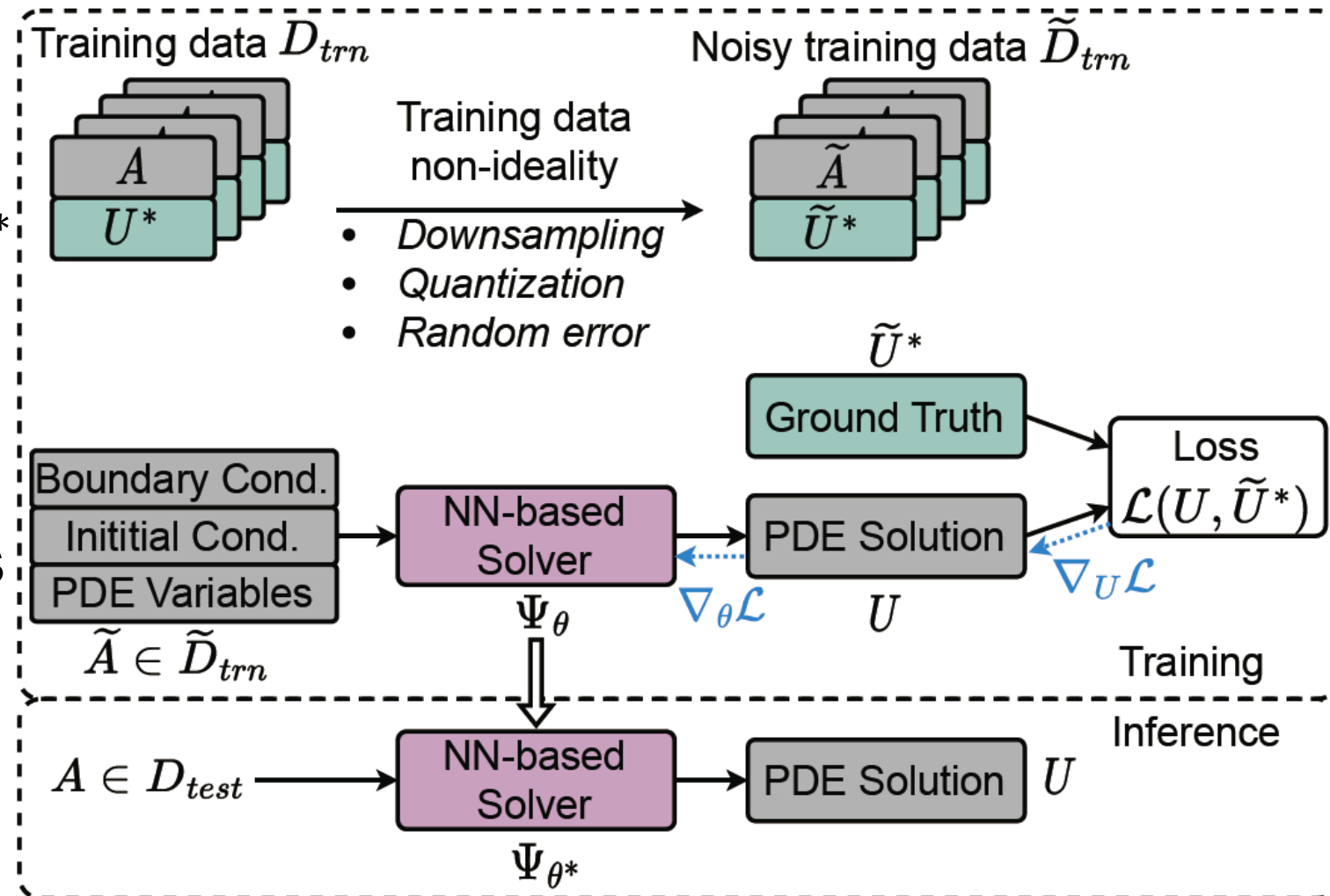
However...

High-resolution, high-fidelity data is hard/costly to collect

Training Data Robustness for Neural PDE Solver

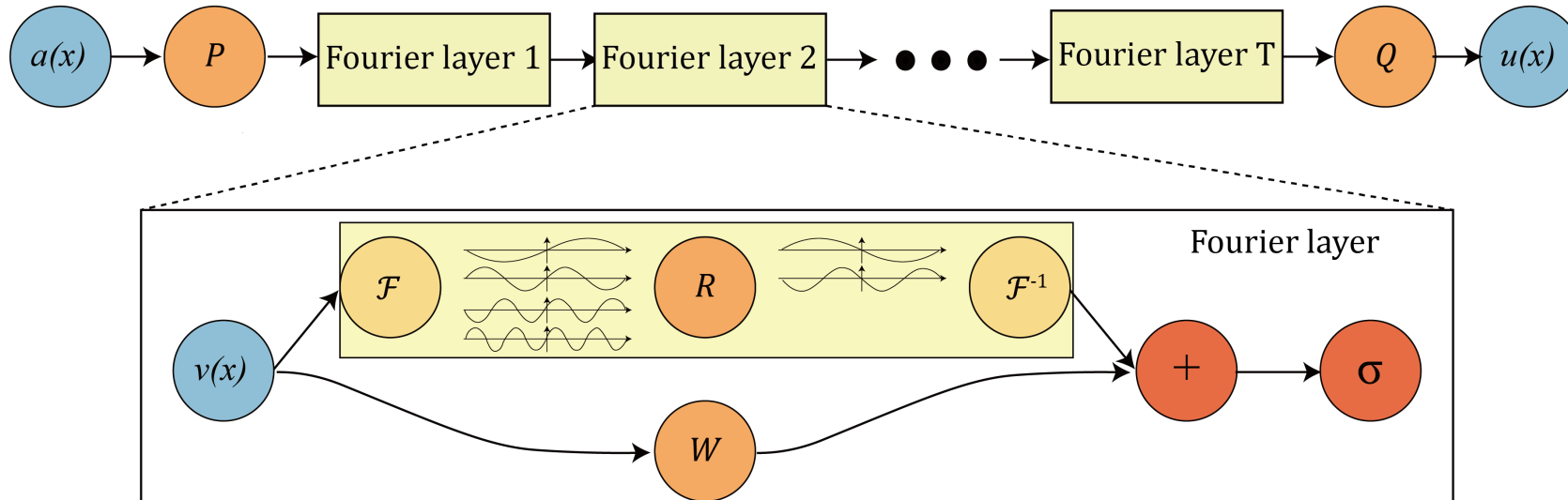
- ◆ What if the train data quality is degraded
- ◆ Train data: $\mathcal{D}_{trn} = A, U^*$
- ◆ Noisy data: $\tilde{\mathcal{D}}_{trn} = \tilde{A}, \tilde{U}^*$
- ◆ Model trained under **perturbed** PDE variables, supervised with **corrupted** solutions

How robust is Neural PDE solver to noisy training data?



Case Studies for This Topic – Neural PDE Solver

- ◆ Model: State-of-the-art Fourier Neural Operator (FNO)



- ◆ Data-driven
- ◆ N-dimensional FFT + complex matrix multiplication + iFFT

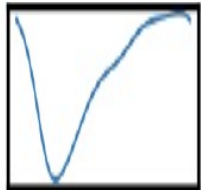
Case Studies for This Topic -- Benchmarks

◆ Tasks



2D Darcy flow: flow of a fluid through a porous medium

$$\begin{aligned} -\nabla \cdot (a(x)\nabla u(x)) &= f(x) & x \in (0, 1)^2 \\ u(x) &= 0 & x \in \partial(0, 1)^2 \end{aligned}$$



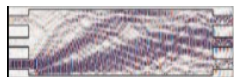
1D Burgers equation: one dimensional flow of a viscous fluid

$$\begin{aligned} \partial_t u(x, t) + \partial_x (u^2(x, t)/2) &= \nu \partial_{xx} u(x, t), \\ u(x, 0) &= u_0(x), \end{aligned}$$



2D Navier-stokes equation: viscous, incompressible fluid in vorticity form

$$\begin{aligned} \partial_t w(x, t) + u(x, t) \cdot \nabla w(x, t) &= \nu \Delta w(x, t) + f(x) \\ \nabla \cdot u(x, t) &= 0, \\ w(x, 0) &= w_0(x), \end{aligned}$$



2D frequency-domain Maxwell equations: photonic device simulation

$$(\nabla \times (\epsilon_r^{-1}(\mathbf{r})\nabla \times) - \omega^2 \mu_0 \epsilon_0) \mathbf{H}(\mathbf{r}) = j\omega \mathbf{J}_m(\mathbf{r})$$

Case Studies for This Topic – Error Settings

◆ Random noises

- › Emulate independent, uniform, high-frequency errors
- › $\tilde{\mathcal{A}} \leftarrow \mathcal{A} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2); \tilde{\mathcal{U}} \leftarrow \mathcal{U} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$

◆ Data down-sampling errors

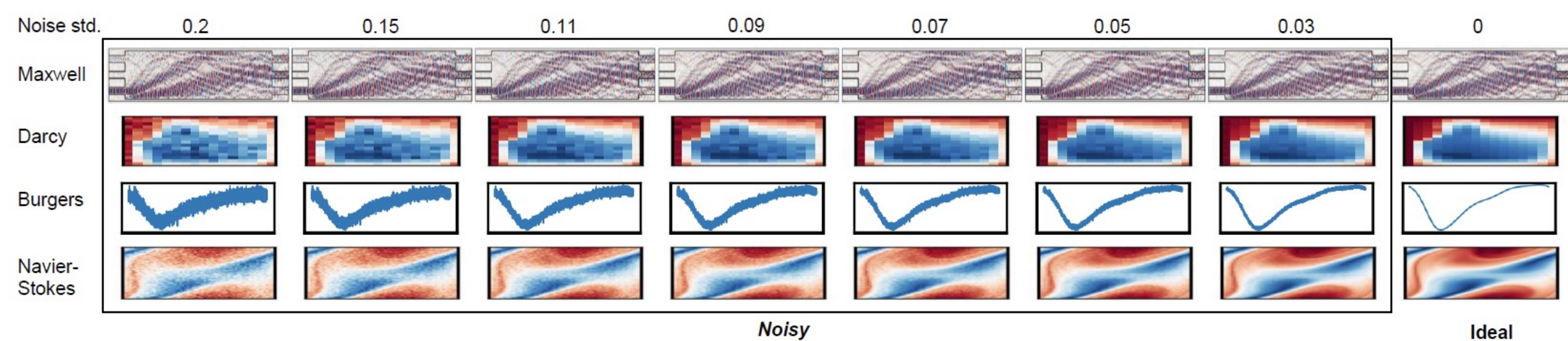
- › Down-sample huge simulation dataset
- › $\tilde{\mathcal{U}} \leftarrow \text{Interp}_{1/s} (\text{Interp}_s (\mathcal{U}))$

◆ Numerical quantization errors

- › Happens in high-precision, high-dynamic range simulation tasks
- › Data compression to low-bit introduces more errors
- › $\tilde{\mathcal{U}} \leftarrow Q(\mathcal{U}; \mathcal{U}_{min}, \mathcal{U}_{max})$

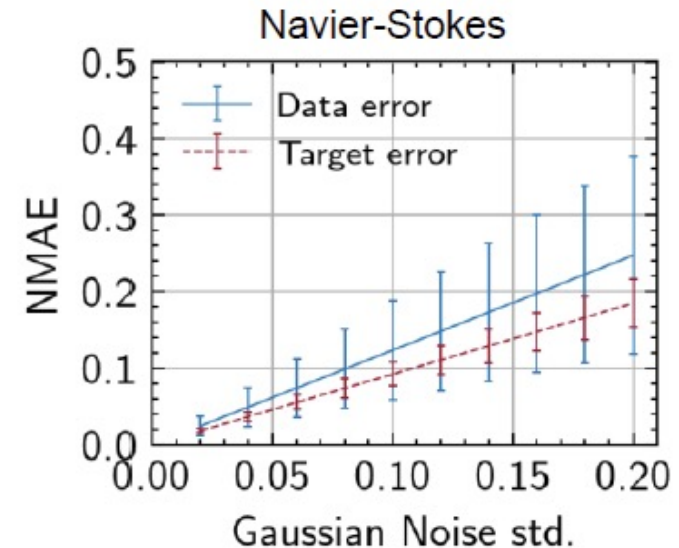
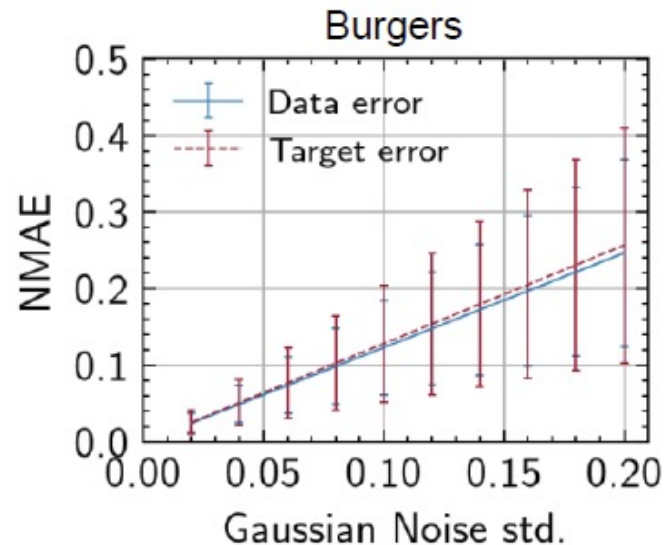
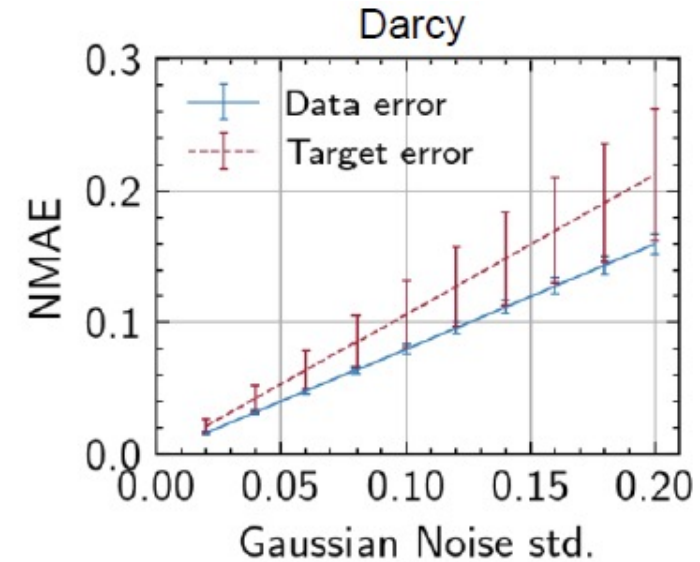
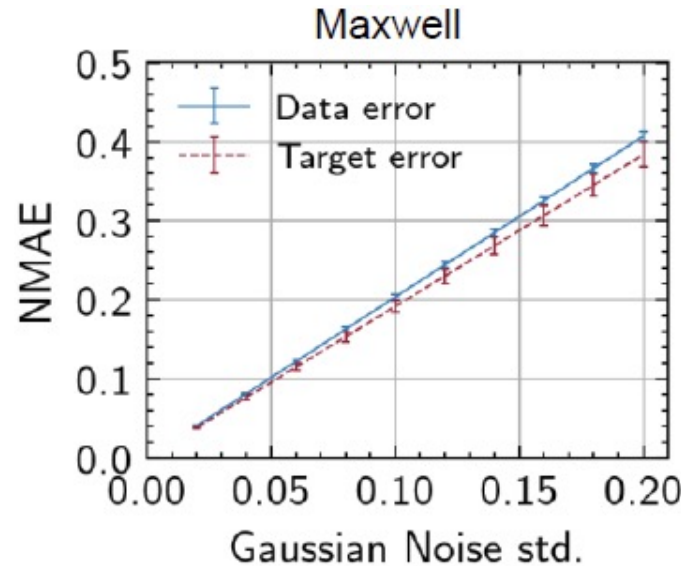
Random Noises on Training Data

- ◆ Emulate independent, uniform, high-frequency errors
- ◆ $\tilde{A} \leftarrow \mathcal{A} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2); \tilde{U} \leftarrow \mathcal{U} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$
- ◆ Global pattern does not change significantly
- ◆ Local fine-grained features are corrupted



Random Noises: Training Data Error

- ◆ As the first-order effect, let's look at how much errors on the data
- ◆ $\text{NMAE} = |U - \tilde{U}|_1 / |U|_1$
- ◆ In general it leads to 2%-30% errors on input and target
- ◆ Much higher errors on sparse fields, e.g., optical fields with low light intensities



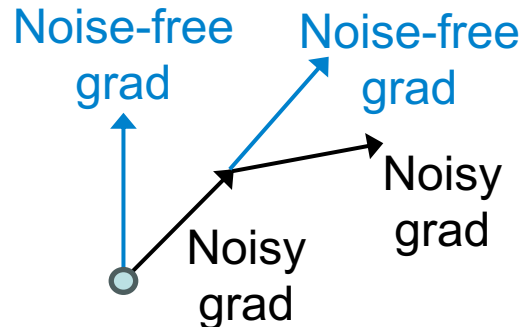
Random Noises: Training Dynamics

- ◆ Evaluate alignment between ideal gradients and noisy gradients

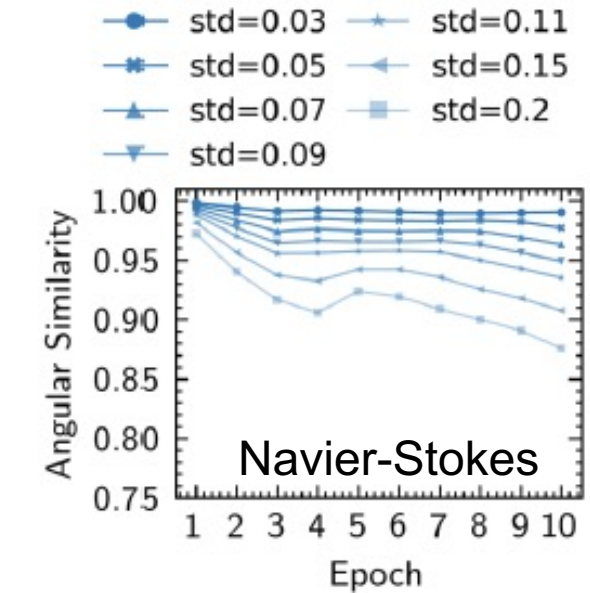
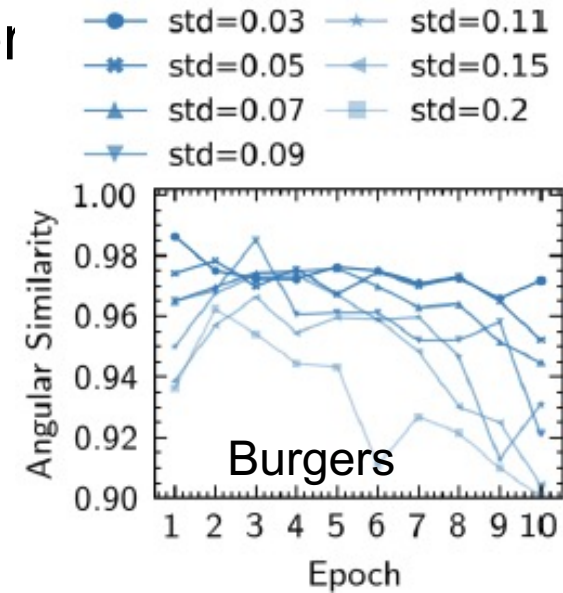
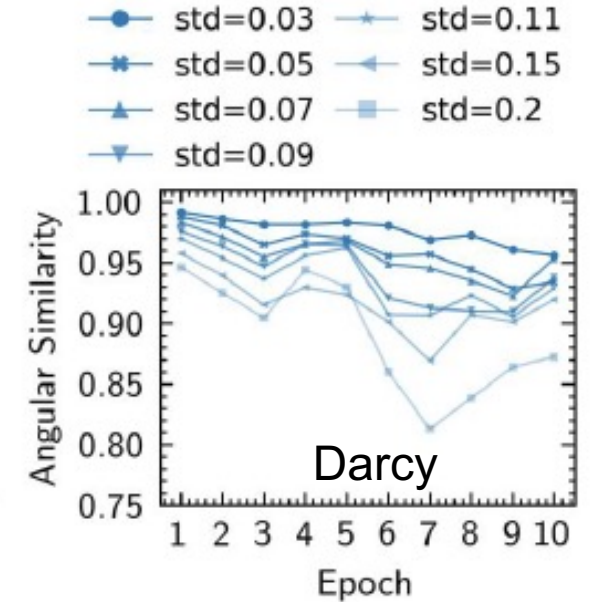
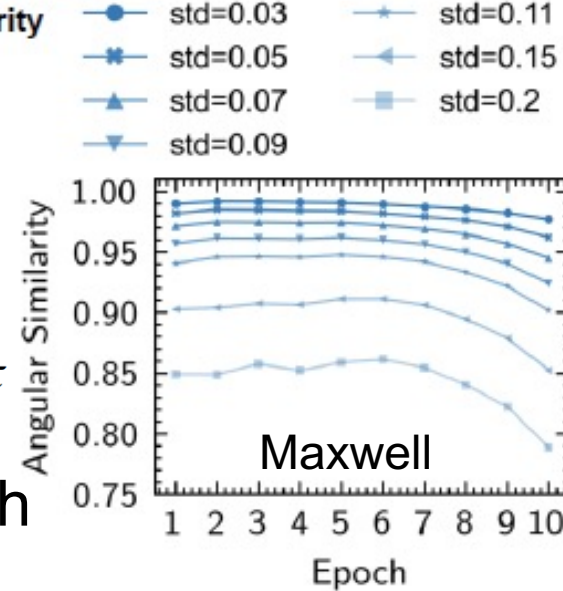
- ◆ Angular similarity across epochs

$$\text{Similarity} = 1 - \arccos\left(\frac{\nabla_{\theta}\mathcal{L}(\mathcal{D}_{trn}) \cdot \nabla_{\theta}\mathcal{L}(\tilde{\mathcal{D}}_{trn})}{\|\nabla_{\theta}\mathcal{L}(\mathcal{D}_{trn})\| \cdot \|\nabla_{\theta}\mathcal{L}(\tilde{\mathcal{D}}_{trn})\|}\right)/\pi$$

- ◆ Align at the beginning, more mismatch later
- ◆ Smooth functions (Burgers) are easier to learn, more tolerant to data noise.
- ◆ High-frequency Maxwell Eq. is more sensitive to noises

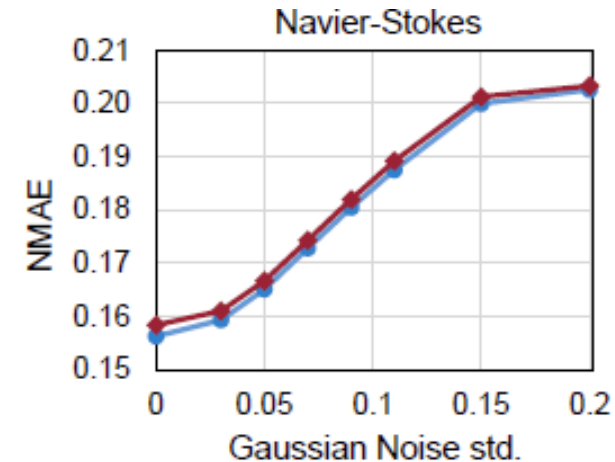
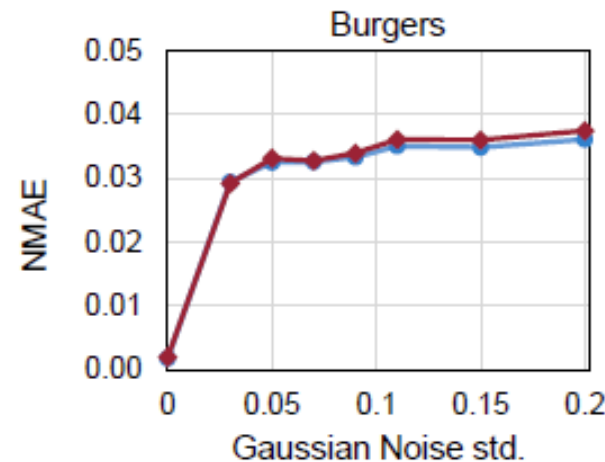
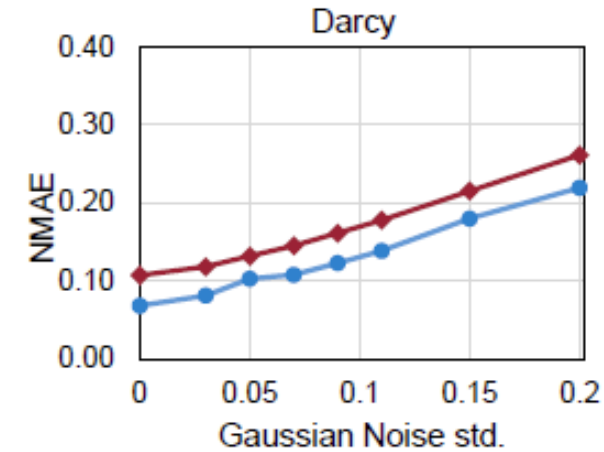
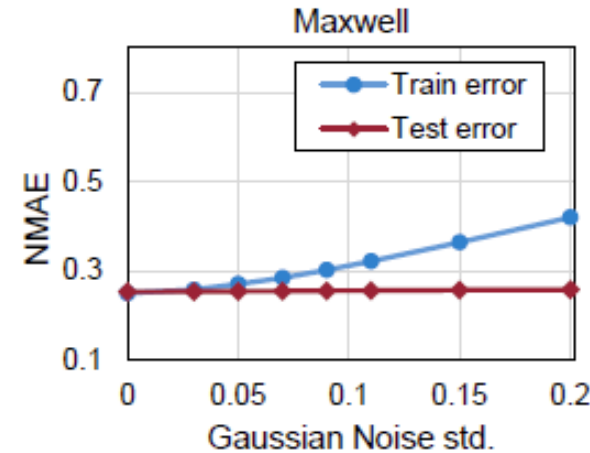


Grad Similarity



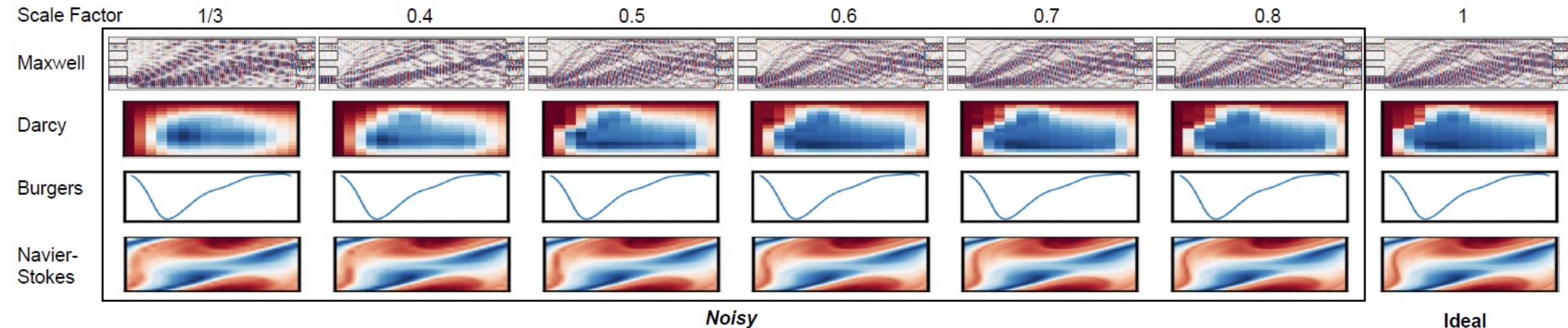
Random Noises: Model Robustness

- ◆ Training/Test NMAE
- ◆ Train/Test error increase simultaneously with larger noise
- ◆ Burgers equation significantly degrades with even small noise
- ◆ Maxwell equation shows the same test error immune to train noises
 - › *Extra regularization and data augmentation helps improve noise tolerance even with large gradient mismatch*



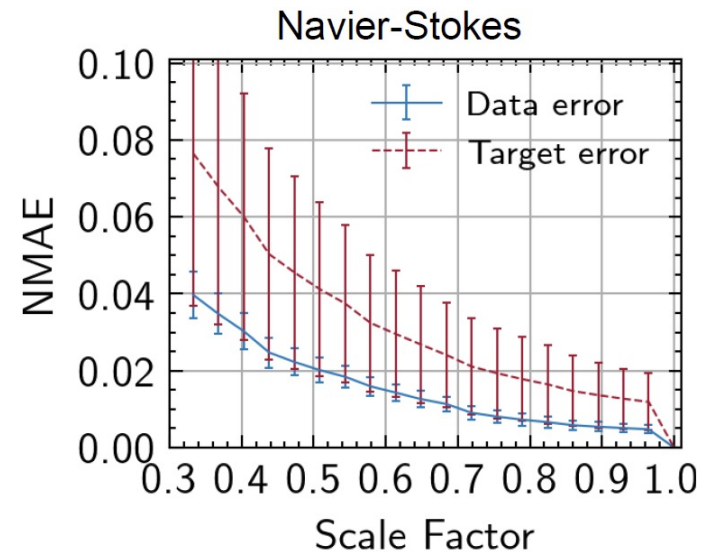
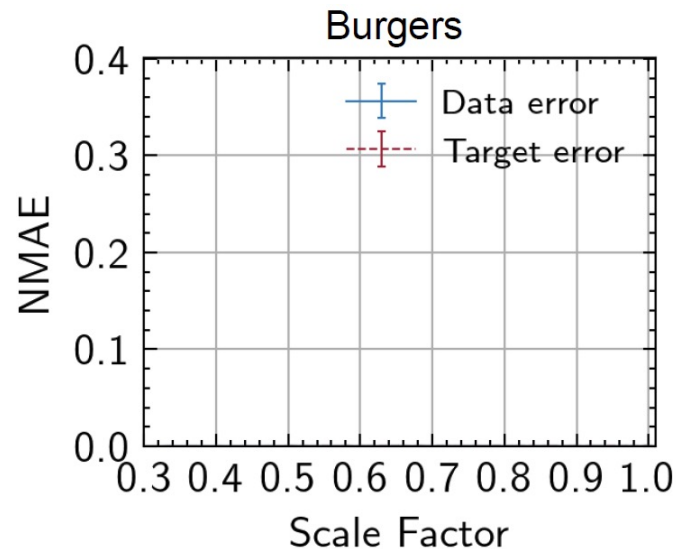
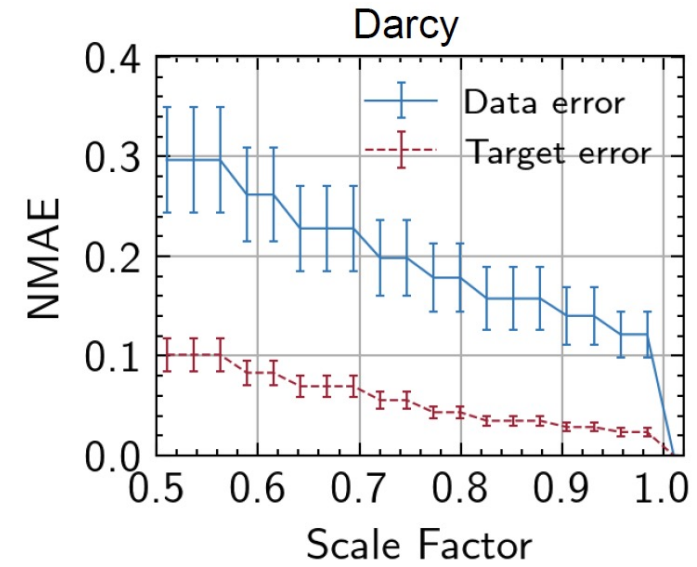
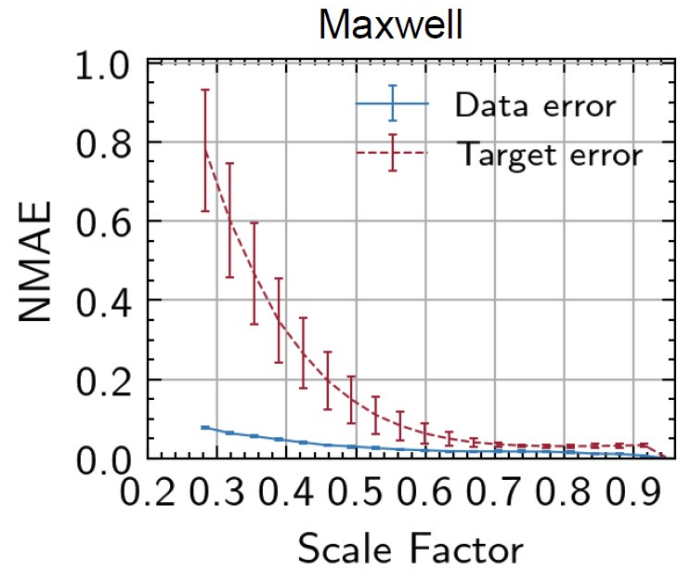
Data Downsampling on Training Data

- ◆ Compress high-res raw data with downsampling to save cost
- ◆ $\tilde{\mathcal{U}} \leftarrow \text{Interp}_{1/s} (\text{Interp}_s (\mathcal{U}))$
- ◆ We inject bicubic/linear resizing errors to input/target
- ◆ Structural errors and related to local field/flow patterns
 - › E.g., Light waves in Maxwell is severely distorted



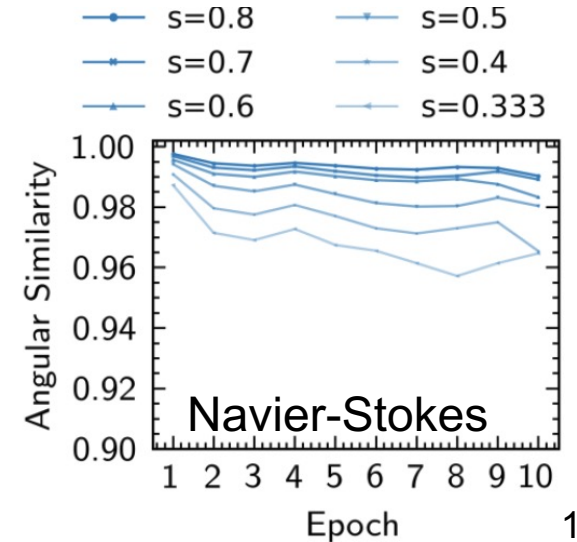
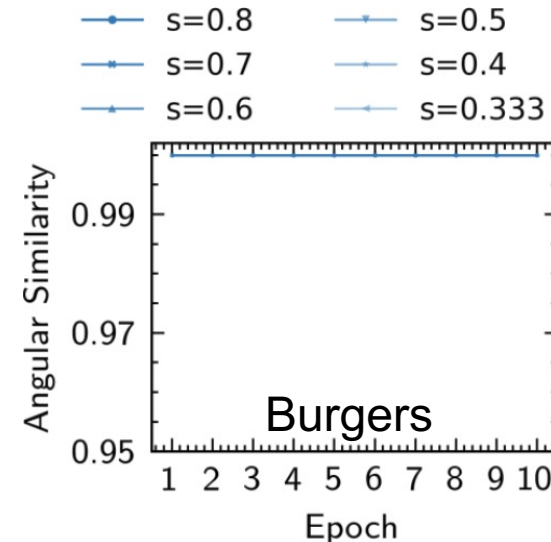
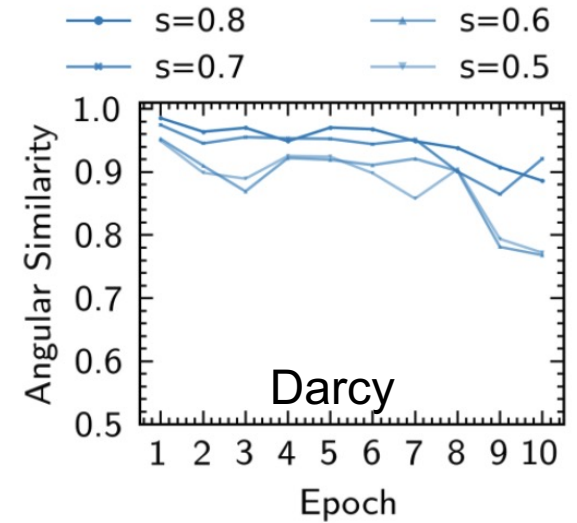
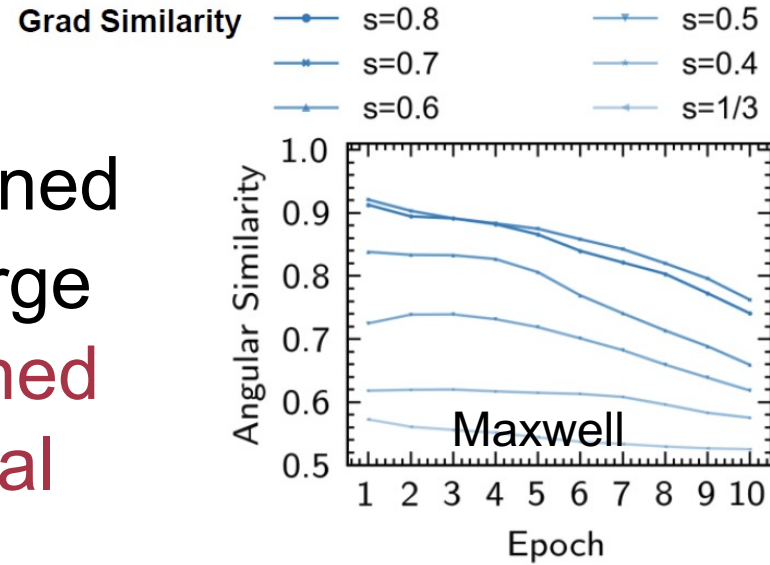
Data Downsampling: Training Data Error

- ◆ Downsampling is disastrous for Maxwell, with 0.2 (5x) downsampling, almost 80% error on waves
- ◆ No errors on Burgers with very smooth patterns
- ◆ Navier-stokes: relatively smooth flow, robust to downsampling (4%-8% error)



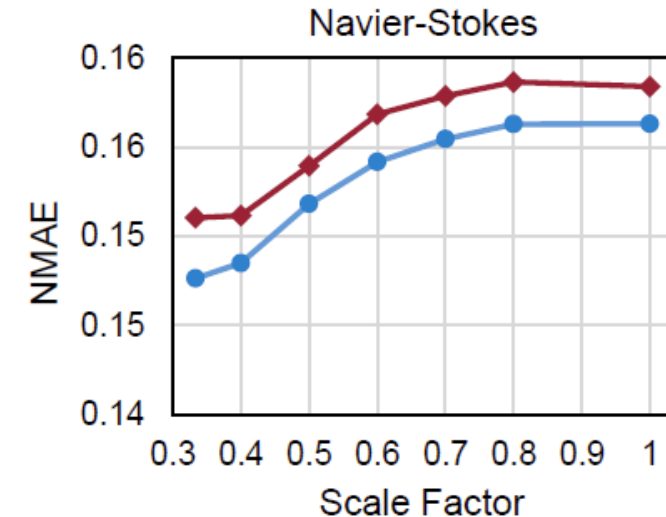
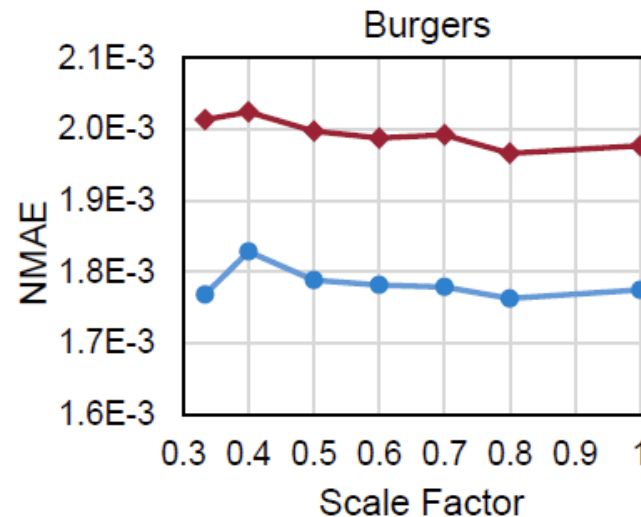
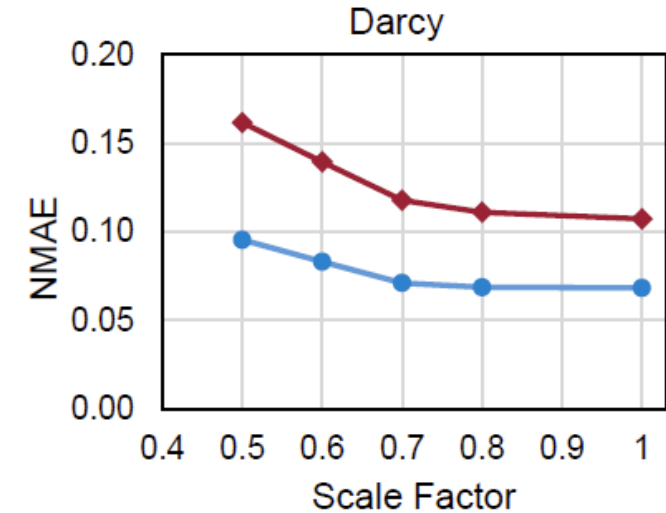
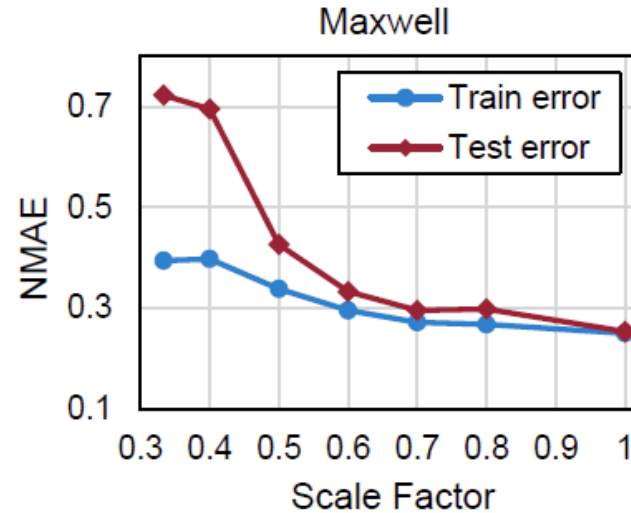
Data Downsampling: Training Dynamics

- ◆ Gradients for Burgers and Navier-Stokes are well-aligned
- ◆ Maxwell equations have large distortion, **severe mismatched gradients (almost orthogonal with 3x resizing)**
- ◆ For smooth patterns, the gradients are insensitive to data compression error.



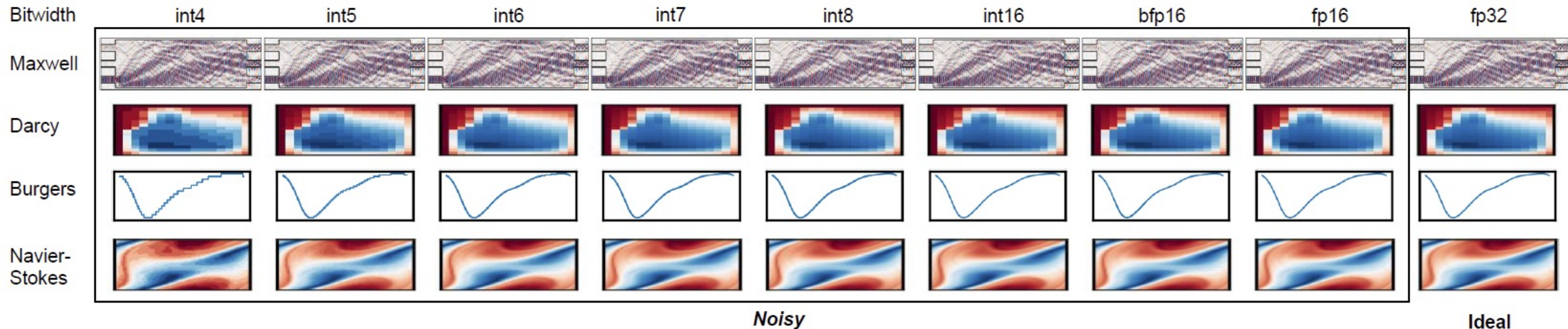
Data Downsampling: Model Robustness

- ◆ Rapid degradation on Maxwell equation
- ◆ Regional correlated errors cause a **systematic bias** on data distribution. **Regularization cannot counter it.**
- ◆ Navier-Stokes: both train/test errors are improved with small errors (**smoothing effects help better converge**)



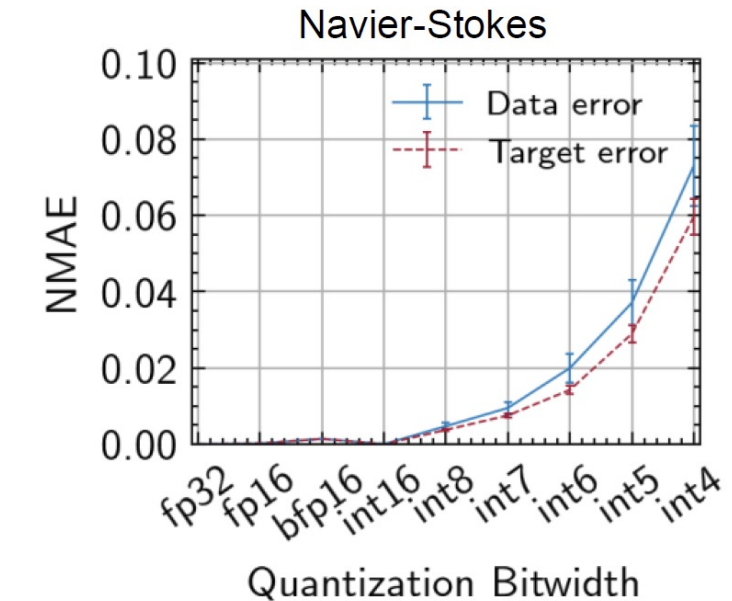
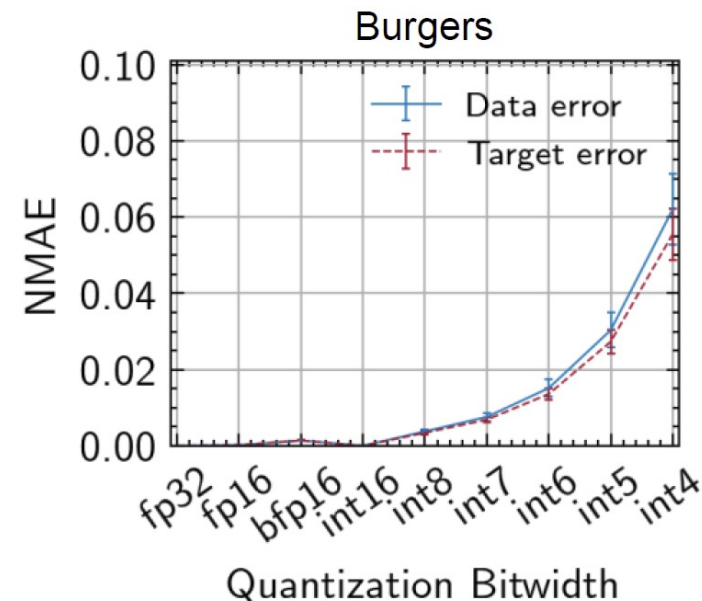
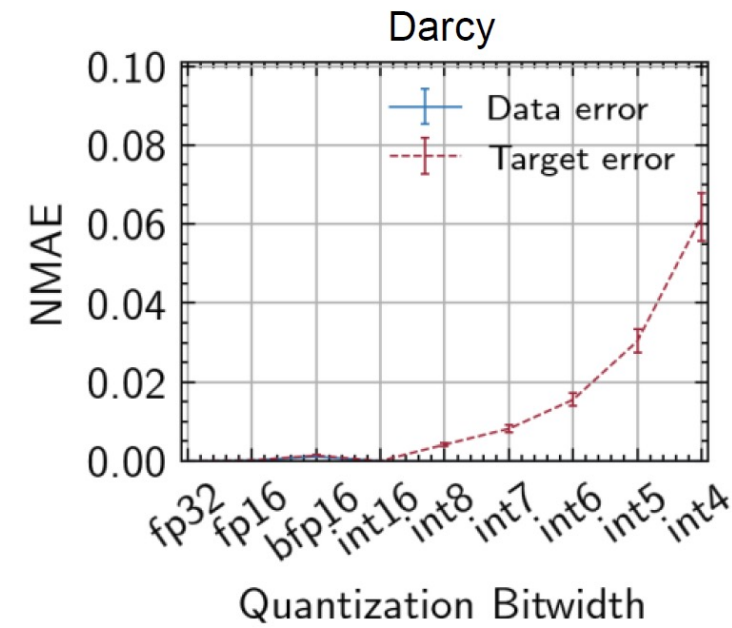
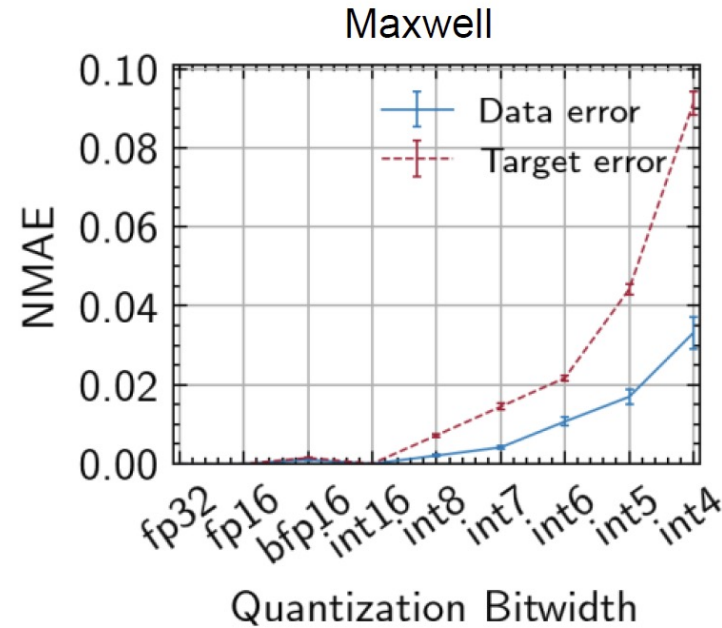
Numerical Quantization on Training Data

- ◆ Compress double/complex128 to low-bit data (INT4-16, BFP16, FP16) to save cost
- ◆ $\tilde{U} \leftarrow Q(U; \mathcal{U}_{min}, \mathcal{U}_{max})$ quantize after min max scaling
- ◆ Still good visualization quality
- ◆ Subtle impact on global patterns, maintains relative magnitude ordering for local data



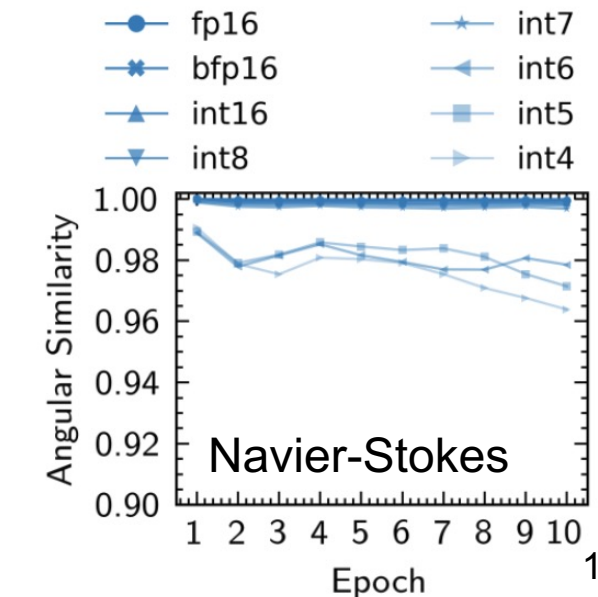
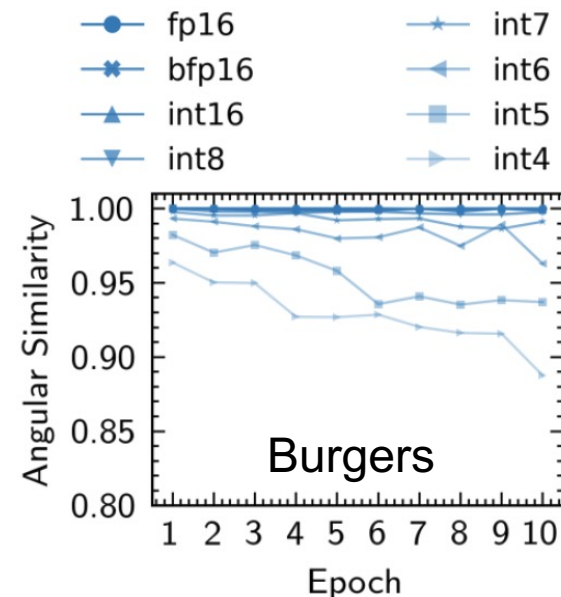
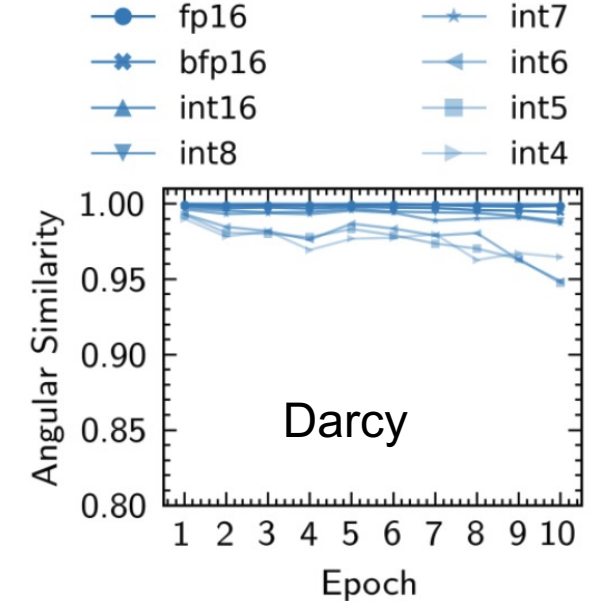
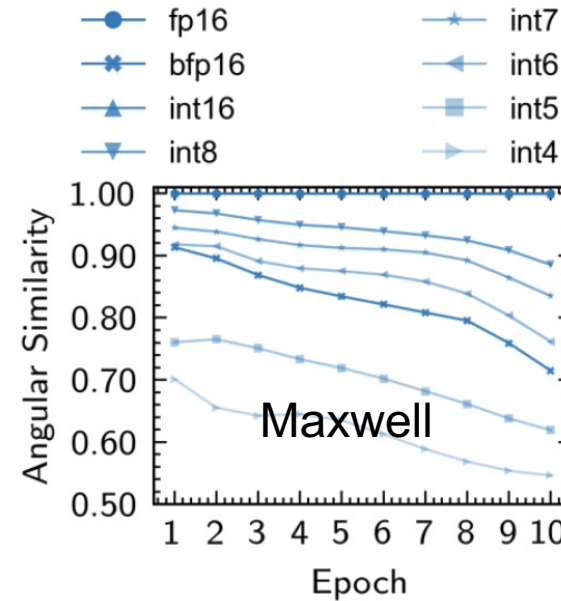
Numerical Quantization: Training Data Error

- ◆ No significant difference across 4 benchmarks
- ◆ 4-8% relative absolute errors
- ◆ INT4 have relatively large errors



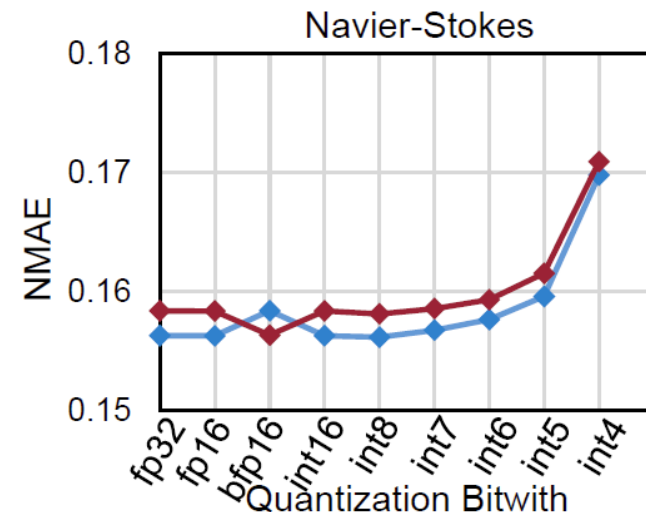
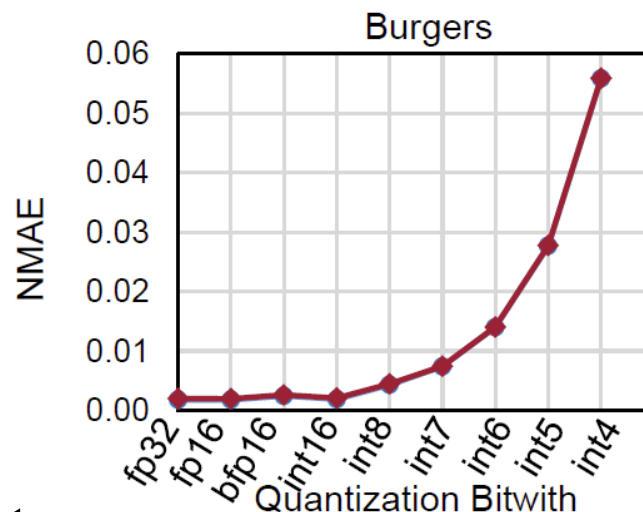
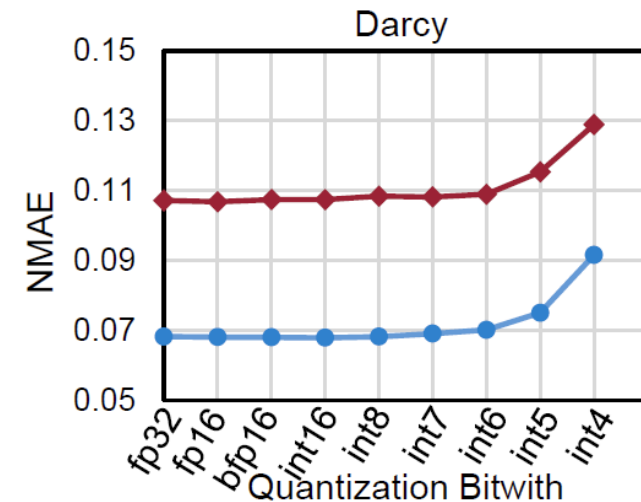
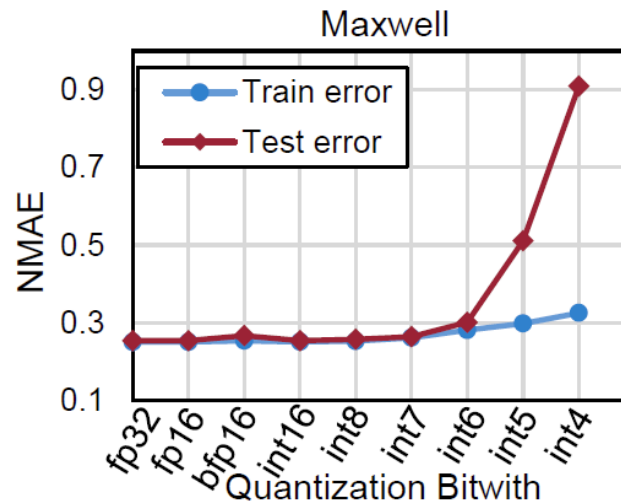
Numerical Quantization: Training Dynamics

- ◆ Only Maxwell benchmarks shows high sensitivity to quantization errors on gradients.
 - › Quantizing Real/Imaginary part separately lead to significant phase rotation -> large angles in gradient mismatch
- ◆ BFloat16 [E8M7] has larger range and fewer fraction bits, shows more errors than FP16 [E5M10]



Numerical Quantization: Model Robustness

- ◆ Significant impacts on training error on Maxwell with 4-bit.
 - › Gradient misalignment
 - › **Intrinsic sensitivity** to input permittivity ϵ
 - › Large quant error makes it hard to learn.
- ◆ Maxwell maintains **high inference fidelity**
 - › Good robustness from regularization
- ◆ >8-bit has negligible impacts



Conclusion & Future Directions

- ◆ We evaluate the training data robustness of Neural PDE solver (FNO) on Burgers equation, Darcy flow, Navier-Stokes equations, and Maxwell equations
- ◆ We benchmark random errors, data downsampling, and numerical quantization and investigate data error, training dynamics (gradients), and generalization
- ◆ Conclusion
- ◆ High-res data with low-freq field/flow patterns demonstrate better tolerance, especially for downsampling errors
- ◆ Regularization helps enhance the resilience, but cannot counter systematic bias from regional errors
- ◆ Future: Compare data-driven/physics-informed, explore more equations, propose data quality metrics