

# nav\_msgs/OccupancyGrid Message

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**File:** `nav_msgs/OccupancyGrid.msg`

## Raw Message Definition

```
# This represents a 2-  
D grid map, in which each cell represents the probability of  
# occupancy.  
  
Header header  
  
#MetaData for the map  
MapMetaData info  
  
# The map data, in row-  
major order, starting with (0,0).  Occupancy  
# probabilities are in the range [0,100].  Unknown is -1.  
int8[] data
```

## Compact Message Definition

```
std_msgs/Header header  
nav_msgs/MapMetaData info  
int8[] data
```

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