

Johnathan J. Nielsen

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EXPERIENCE	<i>Firmware Engineer 3</i>	March 2014 - September 2016
	<i>Firmware Engineer 2</i>	August 2010 - February 2014
	Derive Systems (formerly Bully Dog Technologies)	American Falls, ID
	<ul style="list-style-type: none">• Automotive performance electronics• Product support software	
	<i>Undergraduate Researcher</i>	Summer 2010
	MAS-net REU-CSOIS, Utah State University	Logan, UT
	<ul style="list-style-type: none">• Wind profiling using multiple unmanned aerial vehicles	
	<i>Undergraduate Research Assistant</i>	August 2009 - December 2010
	CSOIS, Utah State University	Logan, UT
	<ul style="list-style-type: none">• AUVSI Competition Team Captain• Development of unmanned aerial vehicles for various civilian applications	
	<i>Undergraduate Researcher</i>	Summer 2009
	MAS-net REU-CSOIS, Utah State University	Logan, UT
	<ul style="list-style-type: none">• Tactical coordination of multi-agent autonomous systems.	
SKILLS	<i>Programming Languages:</i> C, C++, C#, Python, PHP, Qt, Assembly	
	<i>Hardware Platforms:</i> dsPIC/PIC, ARM, 8088, 8051, Atmel	
	<i>Software:</i> MS Office, MATLAB, Eagle, Visual Studio, Qt Creator, git	
EDUCATION	Bachelor of Science, Electrical Engineering	December 2010
	Utah State University, Logan, UT	
	Minors: Mathematics, French	
AWARDS	<i>1st Place Utah State University Senior Design Competition</i>	Spring 2010
	<ul style="list-style-type: none">• Real-Time Target Recognition System for Unmanned Aerial Vehicles	
	<i>Undergraduate Research and Creative Opportunities Grant</i>	Spring 2010
	<ul style="list-style-type: none">• Real-Time Target Recognition System	
	<i>Utah Engineering and Computer Science Program Scholarship</i>	Spring 2010
	<i>Engineering Undergraduate Research Program Grant</i>	Fall 2009
	<ul style="list-style-type: none">• Wind Profiling Using Multiple Unmanned Aerial Vehicles	
	<i>Utah State University Dean's Scholarship</i>	2003-2010
PUBLICATIONS	<i>Automated Social Coordination of Cyber-Physical Systems with Mobile Actuator and Sensor Networks</i>	July 2010
	International Conference on Mechatronics and Embedded Systems and Applications	