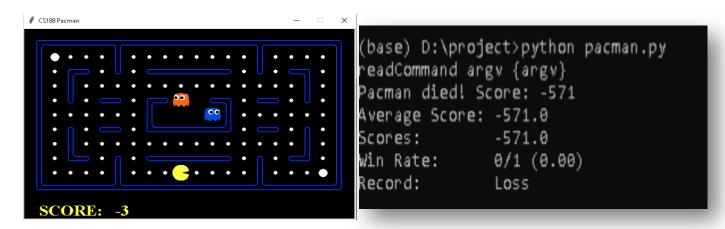
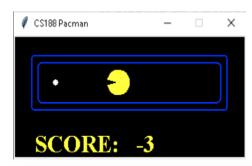
# **Project output**

python pacman.py

## **OUTPUT:**



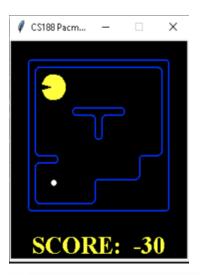
python pacman.py --layout testMaze --pacman GoWestAgent



```
(base) D:\project>python pacman.py --layout testMaze --pacman GoWestAgent
readCommand argv {argv}
Pacman emerges victorious! Score: 503
Average Score: 503.0
Scores: 503.0
Win Rate: 1/1 (1.00)
Record: Win
```

python pacman.py --layout tinyMaze --pacman GoWestAgent

## **OUTPUT:**



```
(base) D:\project>python pacman.py --layout tinyMaze --pacman GoWestAgent readCommand argv {argv}

(base) D:\project>_
```

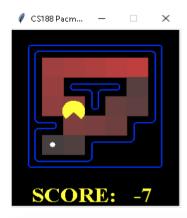
# Question 1: Finding a Fixed Food Dot using Depth First Search

python pacman.py -1 tinyMaze -p SearchAgent -a fn=tinyMazeSearch



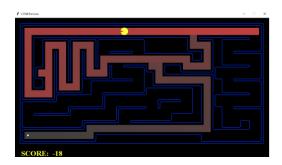
```
(base) D:\project>python pacman.py -l tinyMaze -p SearchAgent -a fn=tinyMazeSearch readCommand argv {argv}
[SearchAgent] using function tinyMazeSearch
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 8 in 0.0 seconds
Search nodes expanded: 0
Pacman emerges victorious! Score: 502
Average Score: 502.0
Scores: 502.0
Win Rate: 1/1 (1.00)
Record: Win
```

python pacman.py -l tinyMaze -p SearchAgent



```
(base) D:\project>python pacman.py -l tinyMaze -p SearchAgent readCommand argv {argv}
[SearchAgent] using function depthFirstSearch
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 10 in 0.0 seconds
Search nodes expanded: 15
Pacman emerges victorious! Score: 500
Average Score: 500.0
Scores: 500.0
Win Rate: 1/1 (1.00)
Record: Win
```

## **OUTPUT:**



```
(base) D:\project>python pacman.py -l mediumMaze -p SearchAgent readCommand argv {argv}
[SearchAgent] using function depthFirstSearch
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 130 in 0.0 seconds
Search nodes expanded: 146
Pacman emerges victorious! Score: 380
Average Score: 380.0
Scores: 380.0
Win Rate: 1/1 (1.00)
Record: Win
```

python pacman.py -1 bigMaze -z .5 -p SearchAgent

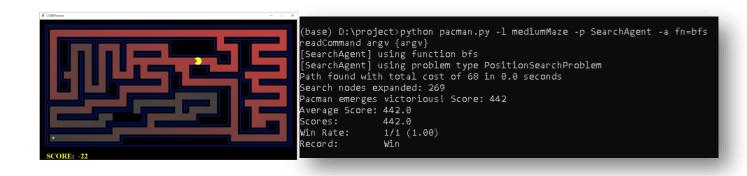


```
(base) D:\project>python pacman.py -l bigMaze -z .5 -p SearchAgent readCommand argv {argv}
[SearchAgent] using function depthFirstSearch
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 210 in 0.0 seconds
Search nodes expanded: 390
Pacman emerges victorious! Score: 300
Average Score: 300.0
Scores: 300.0
Win Rate: 1/1 (1.00)
Record: Win
```

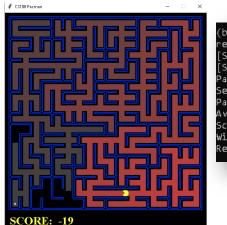
## Question 2: Breadth First Search

python pacman.py -1 mediumMaze -p SearchAgent -a fn=bfs

## **OUTPUT:**



python pacman.py -l bigMaze -p SearchAgent -a fn=bfs -z .5

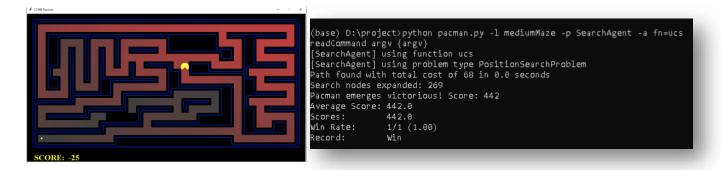


```
(base) D:\project>python pacman.py -l bigMaze -p SearchAgent -a fn=bfs -z .5 readCommand argv {argv}
[SearchAgent] using function bfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 210 in 0.0 seconds
Search nodes expanded: 620
Pacman emerges victorious! Score: 300
Average Score: 300.0
Scores: 300.0
Win Rate: 1/1 (1.00)
Record: Win
```

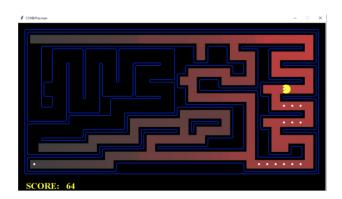
## Question 3: Varying the Cost Function

python pacman.py -1 mediumMaze -p SearchAgent -a fn=ucs

## **OUTPUT:**



python pacman.py -l mediumDottedMaze -p StayEastSearchAgent



```
(base) D:\project>python pacman.py -l mediumDottedMaze -p StayEastSearchAgent readCommand argv {argv}
Path found with total cost of 1 in 0.0 seconds
Search nodes expanded: 186
Pacman emerges victorious! Score: 646
Average Score: 646.0
Scores: 646.0
Win Rate: 1/1 (1.00)
Record: Win
```

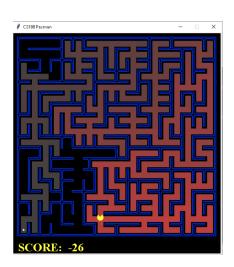
## **OUTPUT:**



```
(base) D:\project>python pacman.py -l mediumScaryMaze -p StayWestSearchAgent readCommand argv {argv}
Path found with total cost of 68719479864 in 0.0 seconds
Search nodes expanded: 108
Pacman emerges victorious! Score: 418
Average Score: 418.0
Scores: 418.0
Win Rate: 1/1 (1.00)
Record: Win
```

## Question 4: A\* search

python pacman.py -l bigMaze -z .5 -p SearchAgent -a fn=astar,heuristic=manhattanHeuristic



```
(base) D:\project>python pacman.py -l bigMaze -z .5 -p SearchAgent -a fn=astar,heuristic=manhattanHeuristic readCommand argv {argv}
[SearchAgent] using function astar and heuristic manhattanHeuristic
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 210 in 0.0 seconds
Search nodes expanded: 549
Pacman emerges victorious! Score: 300
Average Score: 300.0
Scores: 300.0
Win Rate: 1/1 (1.00)
Record: Win
```

فاطمه خدادادي\_97143013