

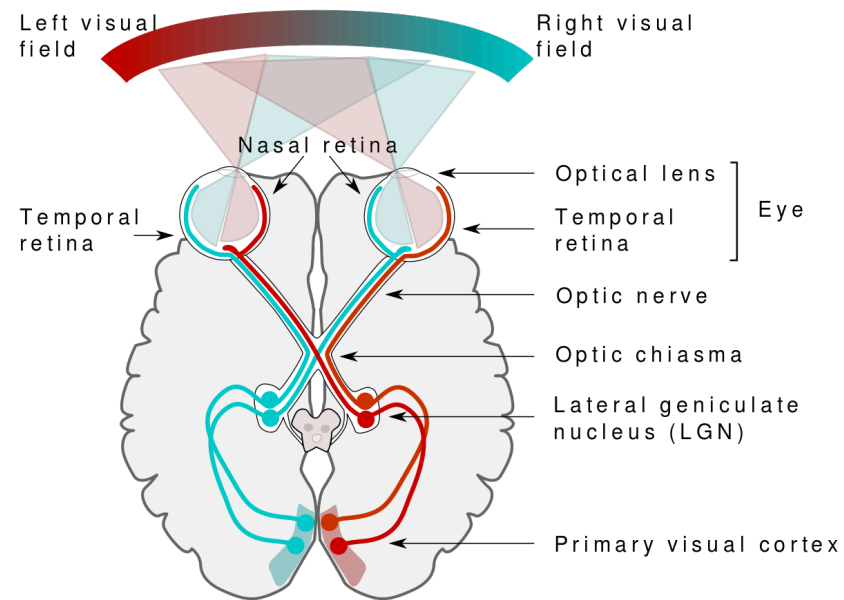
CENG 477

Introduction to Computer Graphics

Human Visual System

Human Visual System

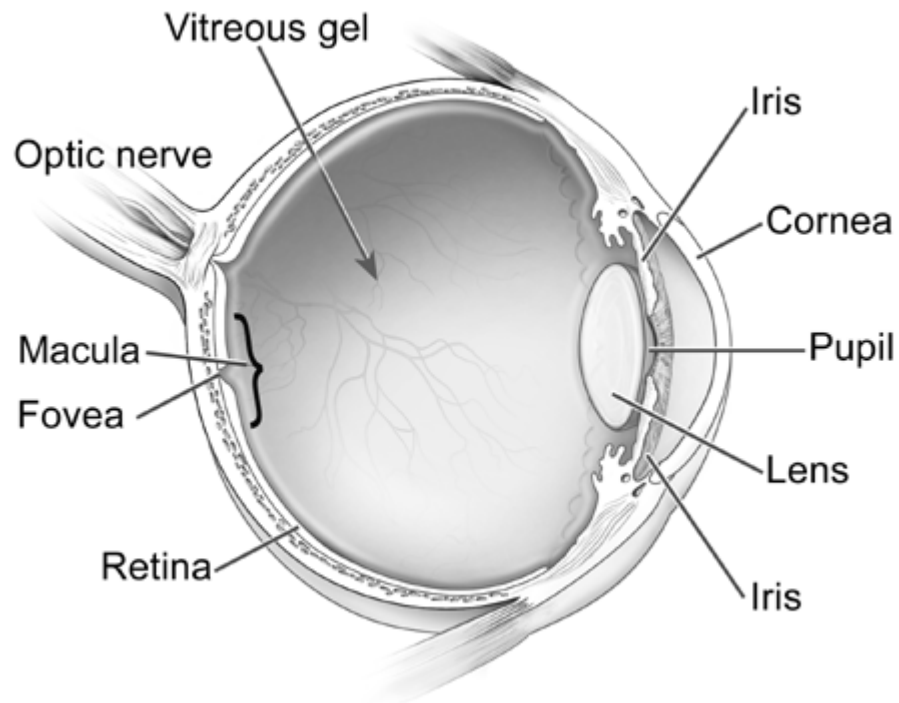
- The HVS consists of the **eyes**, parts of the **brain**, and the connecting **pathways** between the two
- It is a complex system that even today not entirely understood
- We will briefly touch upon its basic working principles



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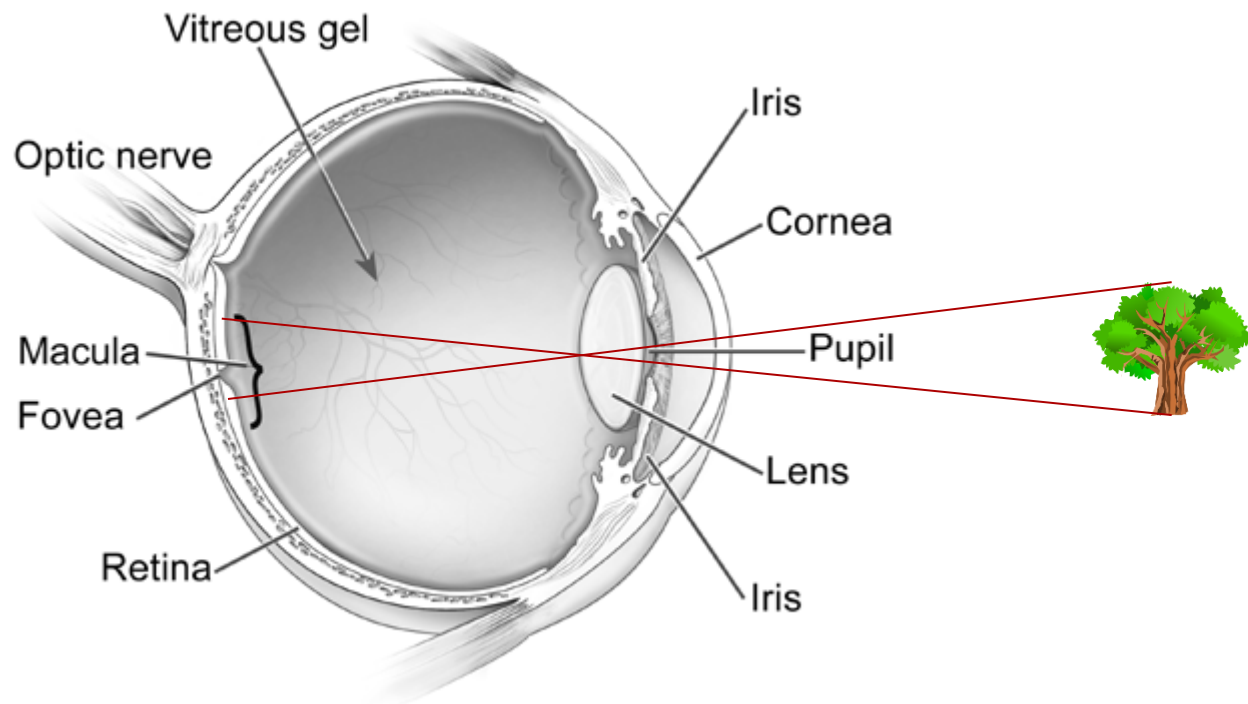
The Eye

- Vision starts at the eyes



The Eye

- Light entering the eye is focused on the fovea (inside retina) by the lens



Retina

- This light is absorbed by two types of photosensitive cells on the retina
 - Rods
 - Cones

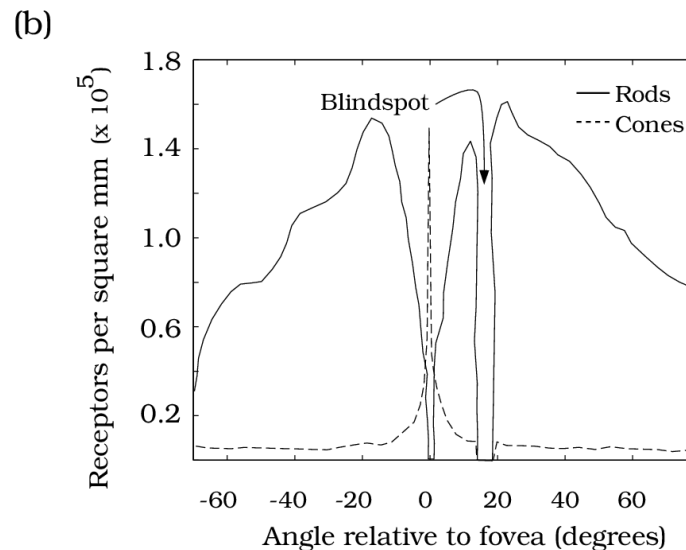
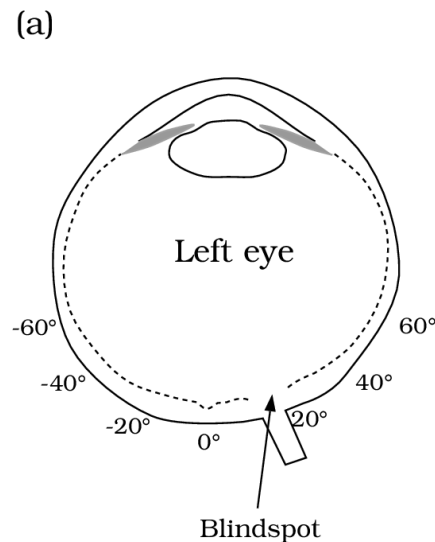
Rods and Cones

- While being more numerous than cones, rods do not exist in the fovea and there is only a single type of rods
 - That is why our night vision is not sharp and colorful
- Rods are active under low light conditions



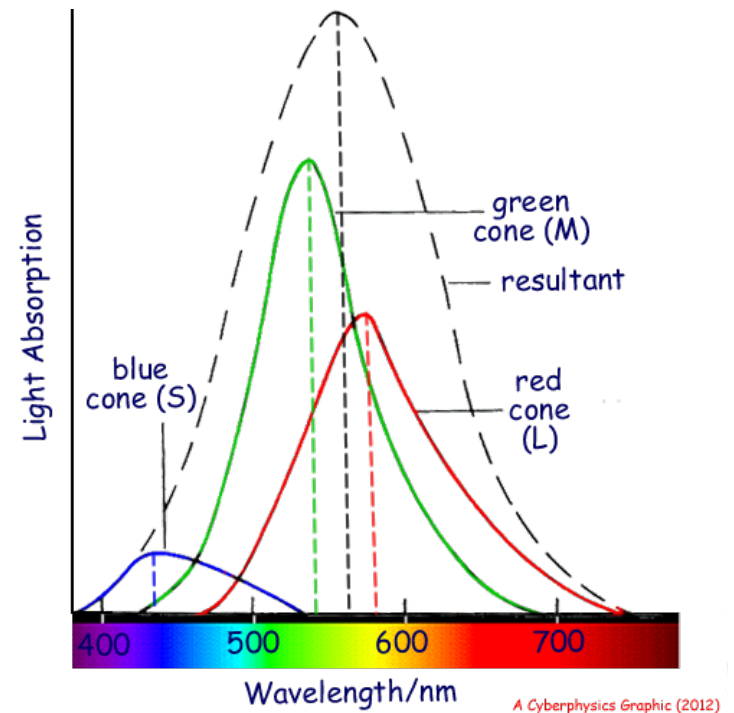
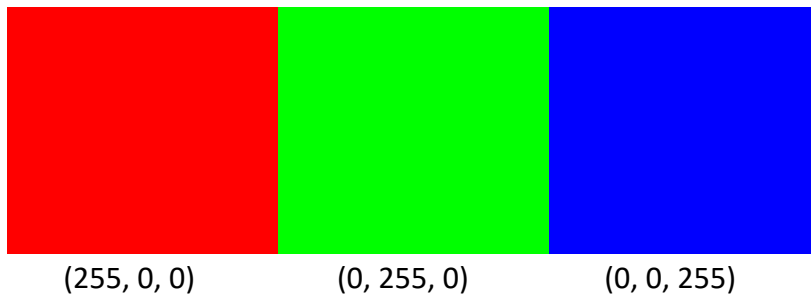
Cones

- Cones are very dense in the fovea
- There are three types of cones: long, medium, short
- Cones are active at normal light conditions



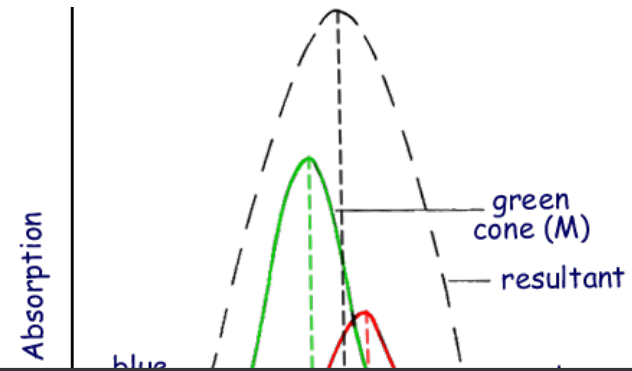
Cones

- Each cone type is responsive to a different color
- Their **relative** contribution determines the perceived color of an object
- Their **combined** contribution determines the perceived brightness of an object

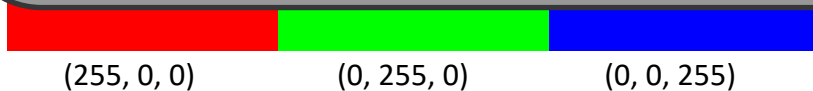


Cones

- Each cone type is responsive to a different color
- Their **relative** contribution determines the perceived color of an object

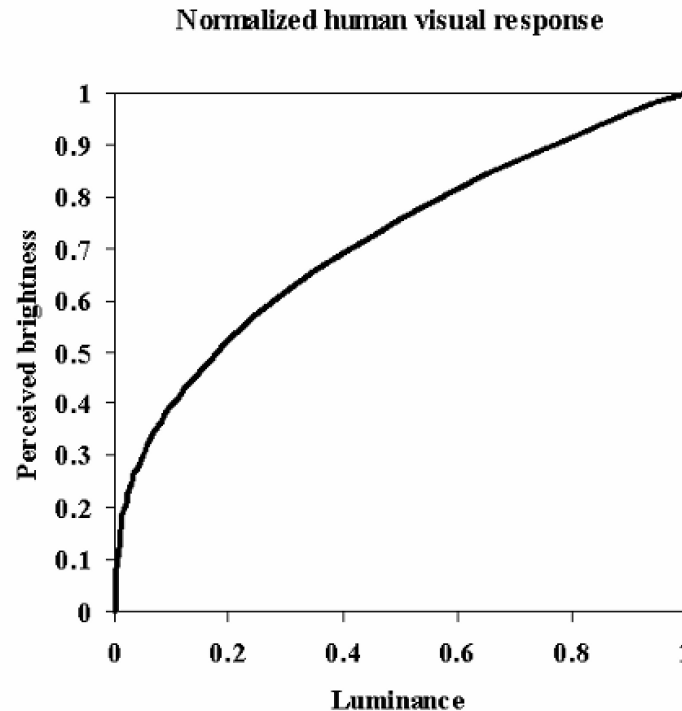


The primary reason that color is typically represented as an **RGB triplet** is because we also have three types of cones



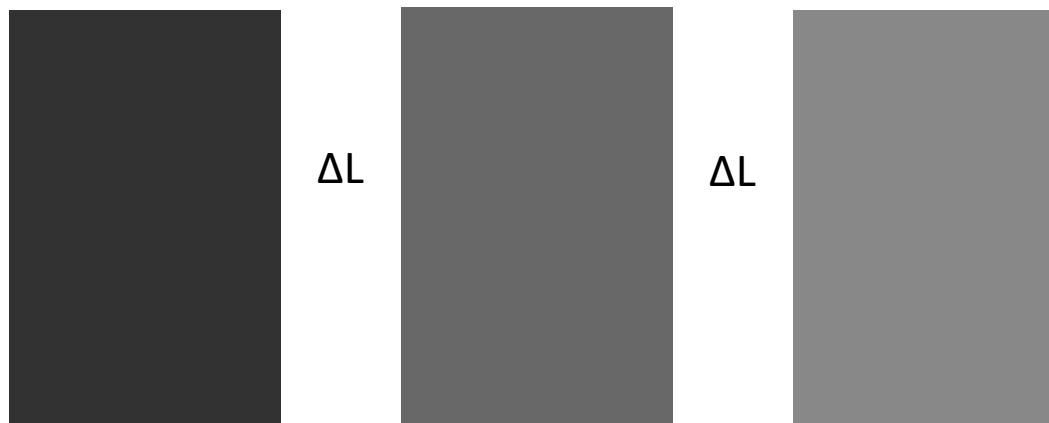
Non-linearity

- The human response to light is non-linear (logarithmic)
- In other words, cameras and the eye has a somewhat similar non-linearity



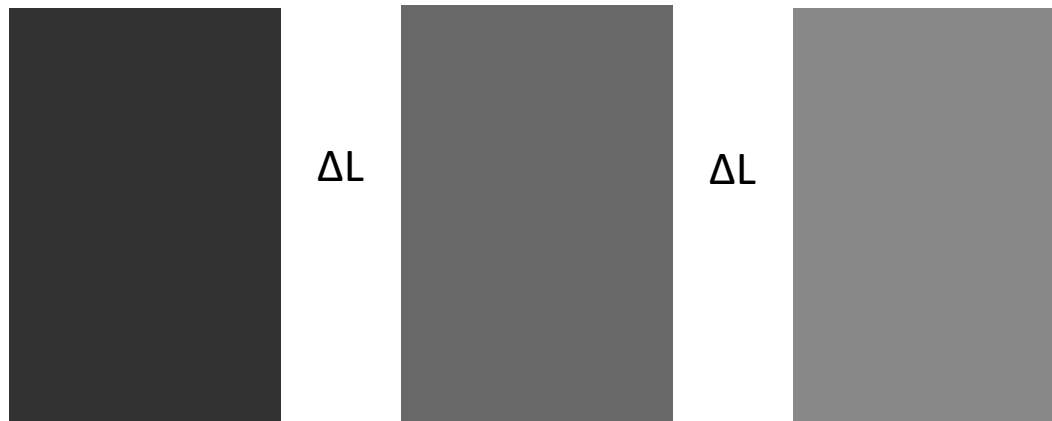
Non-linearity

- Therefore, equal **change in luminance** **does not map** to **equal change in perceived brightness**
- We can verify this experimentally
- The following three patches are separated by about the same amount of luminance difference



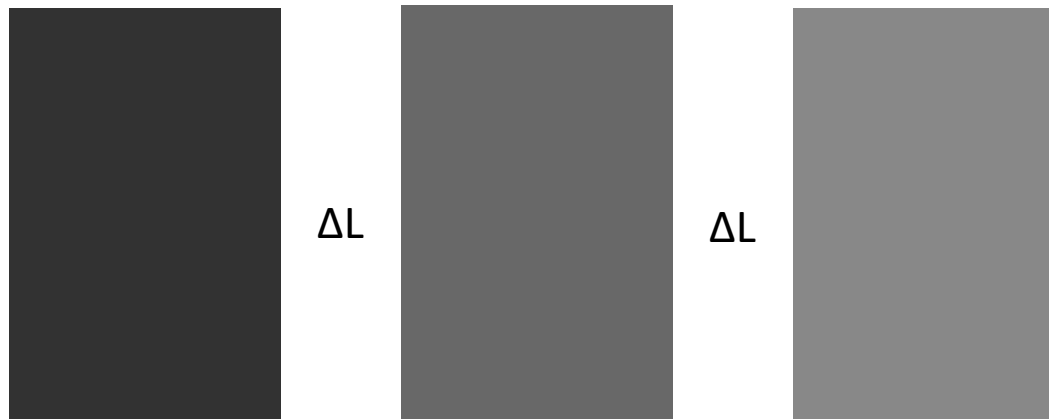
Non-linearity

- Therefore, equal **change in luminance** **does not map** to **equal change in perceived brightness**
- We can verify this experimentally
- But the perceived step size between them is different



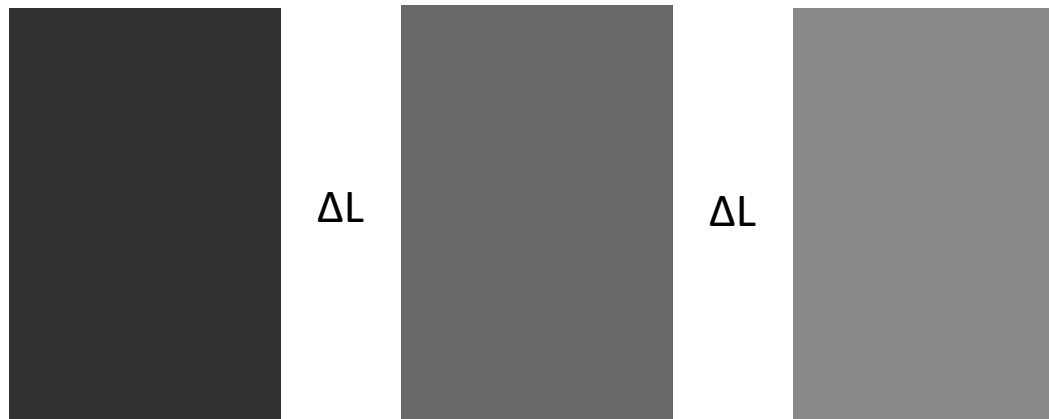
Non-linearity

- Note that to prepare these patches, we must take into account the gamma behavior of display devices:
 - **You cannot simply make the pixel value difference equal!**
- Imagine you want these patches to have luminance values L , $5L$, and $9L$ (so $\Delta L = 4L$)



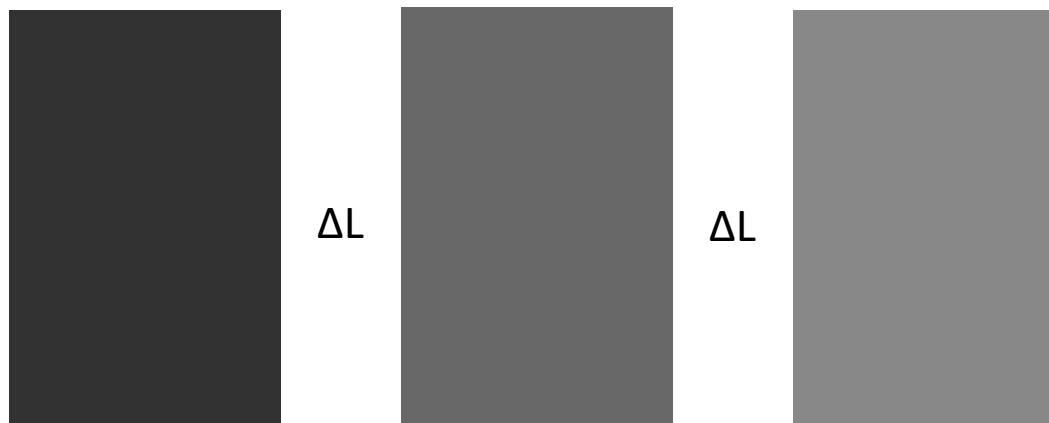
Non-linearity

- Note that to prepare these patches, we must take into account the gamma behavior of display devices:
 - **You cannot simply make the pixel value difference equal!**
- Assume that pixel value of 50 results in a luminance of L
- Also assume that the gamma (γ) of your display device is 2.2



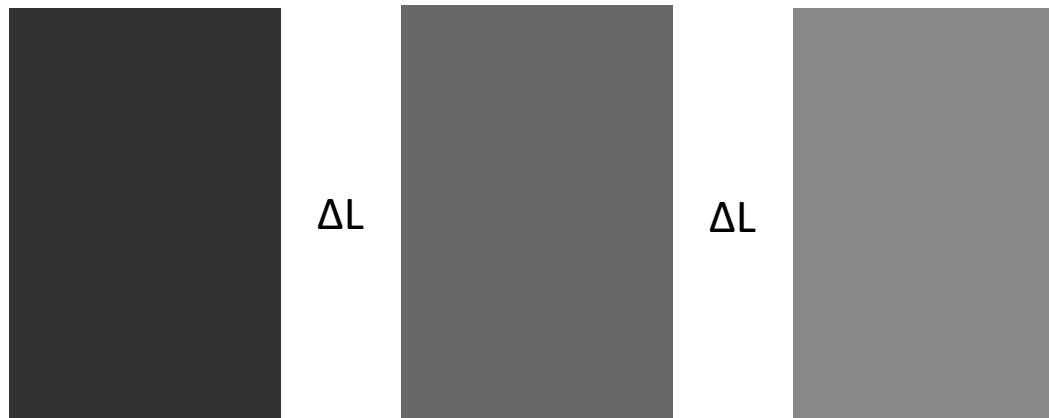
Non-linearity

- What should be the pixel value of the second patch in order to have a luminance of 5L?
- Remember our display model: $L_{out} = cV^\gamma + b$
- Assuming $c = 1$ and $b = 0$, we can say: $L = \left(\frac{50}{255}\right)^{2.2}$



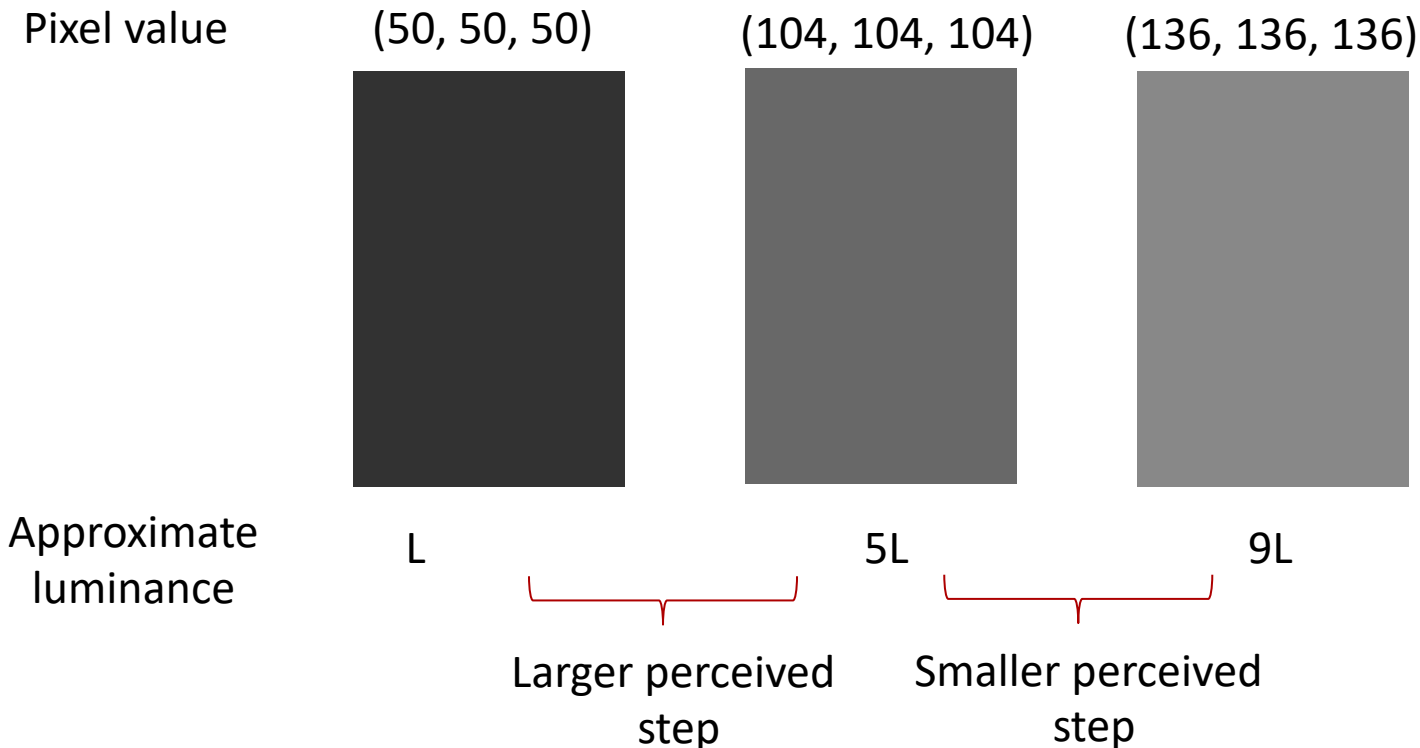
Non-linearity

- If $L = \left(\frac{50}{255}\right)^{2.2}$ then what is x such that $5L = \left(\frac{x}{255}\right)^{2.2}$
- $5 = \left(\frac{x}{50}\right)^{2.2}$ therefore $x \cong 104$
- For the brightest patch ($9L$), $9 = \left(\frac{y}{50}\right)^{2.2}$ therefore $y \cong 136$



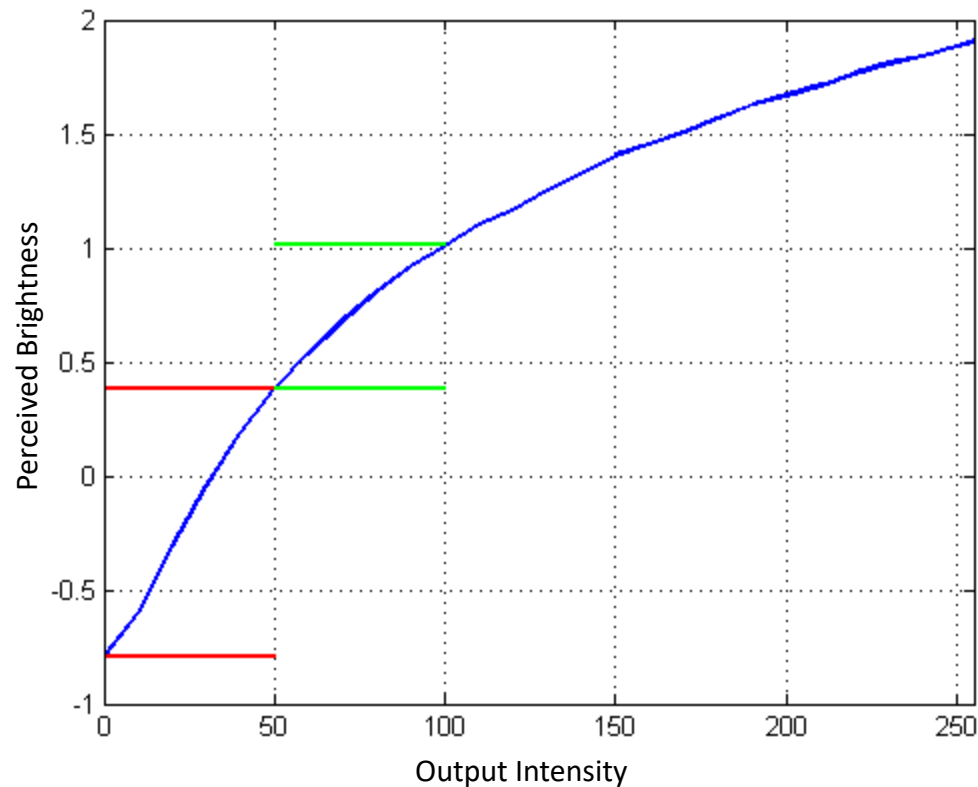
Non-linearity

- Equal **change in luminance** **does not map** to **equal change in perceived brightness**



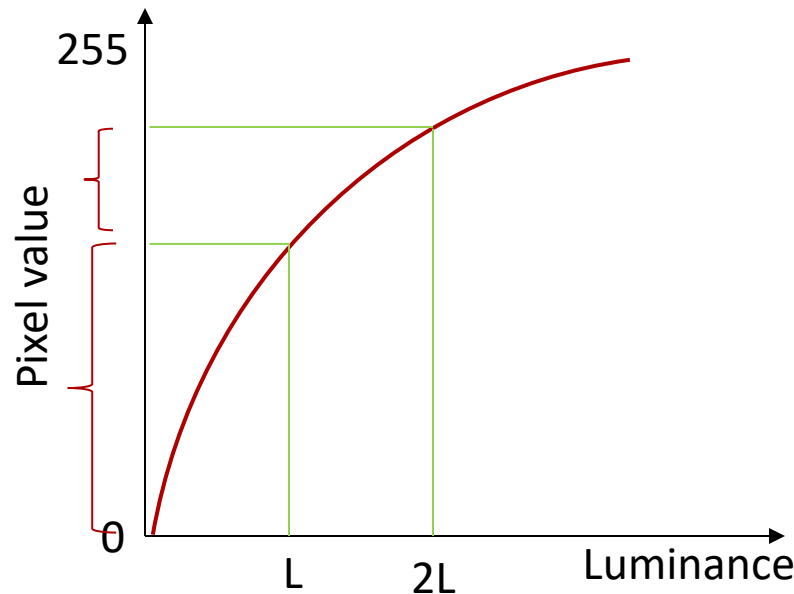
Non-linearity

- This can be explained by the perceived brightness curve:



Back to Gamma Correction

- When apply gamma correction to an image, we are somewhat mimicking the human non-linear response
- We are using more bits to represent luminances to which we are more sensitive



This creates the appearance of more smooth transition between intensity values

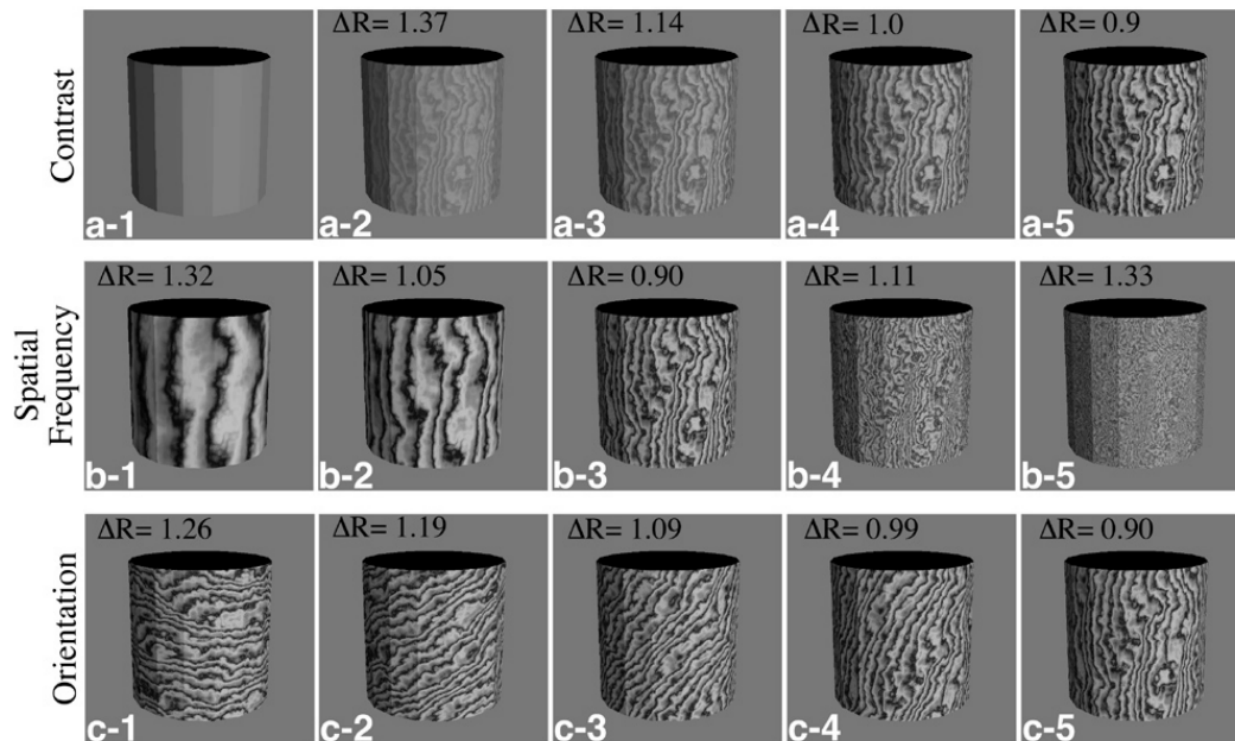
Perception and Graphics

- Understanding visual perception allows for various optimizations in computer graphics
- For example, we can use lower polygon count if the visual system cannot understand it due to presence of a texture

Ferwerda et al. 1997: A Model of Visual Masking for Computer Graphics

Perception and Graphics

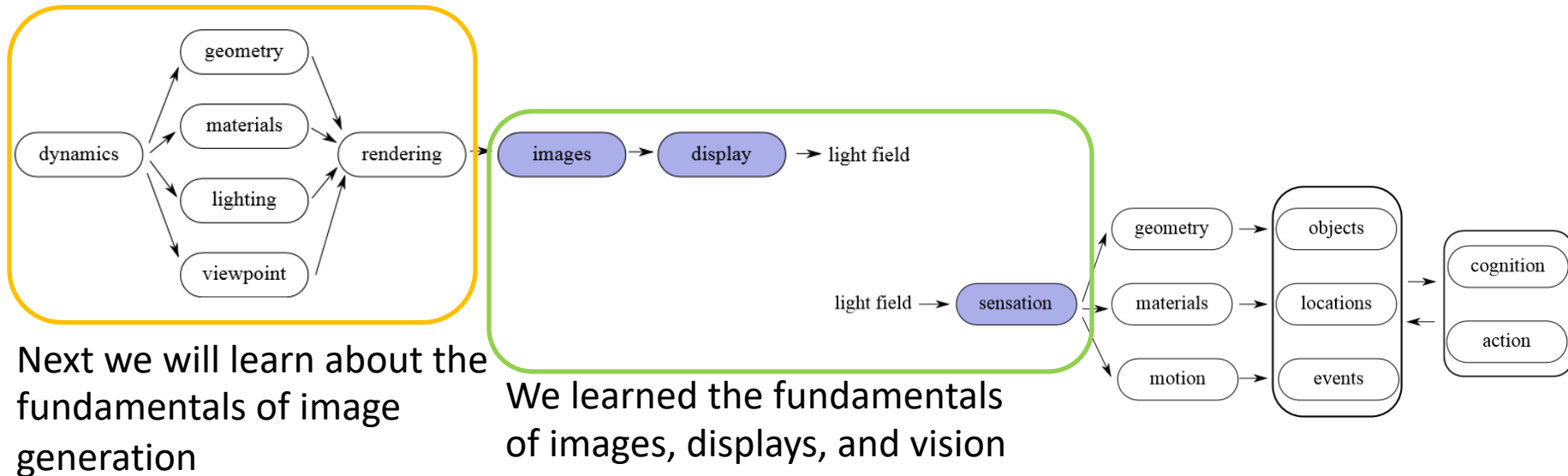
- All cylinders have the same number of polygons but this is masked under textures with different properties



Ferwerda et al. 1997: A Model of Visual Masking for Computer Graphics

Summary

- In CG, images (frames) are rendered and then are either written to a file or directly sent to a display device to be perceived by an observer



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