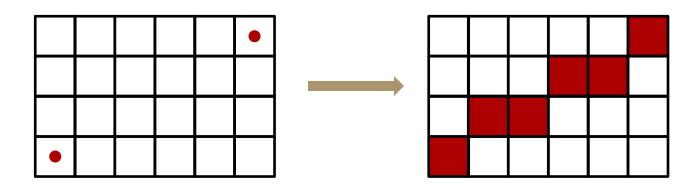
CENG – 477 Introduction to Computer Graphics

Rasterization



Rasterization

- Rasterization is concerned with creating fragments from vertices
- It works in screen coordinates thus it is the next step after the viewport transform
- Goal: Given a set of vertices which fragments must be "turned on" to create the primitive:





Rasterization

Subproblems:

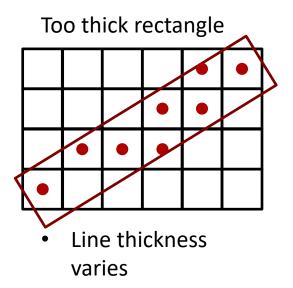
- How to deal with different primitives
- How to make it fast
- How to interpolate color and other attributes
- We'll start with line rasterization



- Several methods exist
- **Option 1:** Treat the line as a thin rectangle and turn on pixels that are inside this rectangle

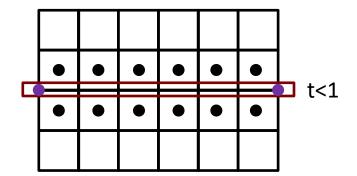
Too thin rectangle

 May cause gaps in the line

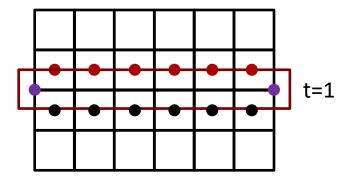




What must be the minimum thickness?



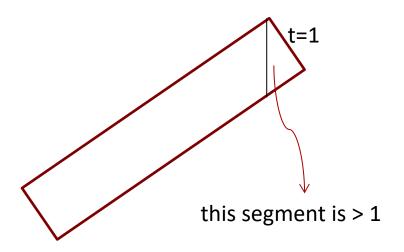
 May not draw anything if it is too thin

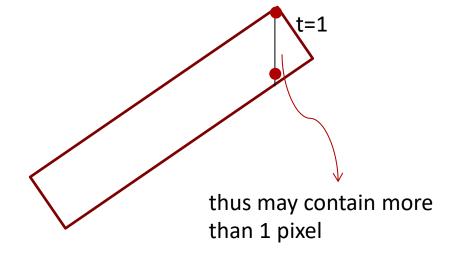


 Must be at least one to draw a horizontal line in some cases



But a thickness of 1 may result in too thick lines



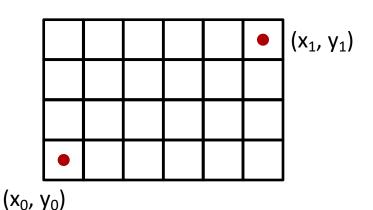




- Therefore we need another solution
- We can use line equations to decide which pixels belong the line
- Assume that we want to draw a line between two screen coordinates: (x_0, y_0) to (x_1, y_1)
- Assume that the slope of the line, m, is in range (0, 1)

$$m = \frac{y_1 - y_0}{x_1 - x_0}$$

Which pixels should we draw?

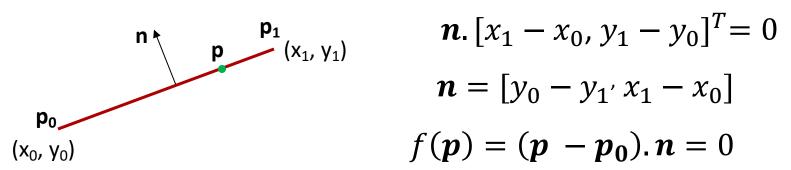


Line Equation

Let's first remember the implicit line equation:

$$f(x,y) = x(y_0 - y_1) + y(x_1 - x_0) + x_0y_1 - y_0x_1$$

• We can derive it from geometry:



What is the meaning of $f(\mathbf{p}) = 0$, $f(\mathbf{p}) > 0$ and $f(\mathbf{p}) < 0$



The Basic Algorithm

The basic algorithm is as follows:

```
y = y_0

for x = x_0 to x_1 do:

draw(x, y)

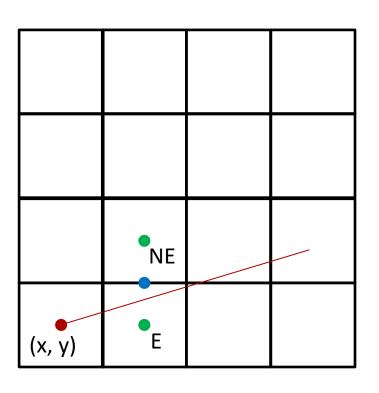
if (some condition) then:

y = y + 1
```

• Because the slope is in (0, 1], we always go right and sometimes go up (assuming that $x_0 < x_1$ and $y_0 < y_1$)



Assume we have just drawn (x, y). Which pixel to draw next?



- Compute the midpoint of the next pixel
- If the midpoint is on or above the line choose the right pixel (E: east)
- If the midpoint is below the line, choose the top right pixel (NE: north-east)

```
y = y_0

for x = x_0 to x_1 do:

draw(x, y)

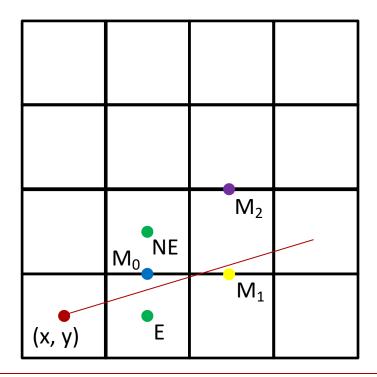
if f(x+1, y+0.5) < 0 then:

y = y + 1
```

We call these pixels E and NE



- This algorithm works well but requires evaluating the line equation at every iteration
- Can be optimized with an incremental algorithm:



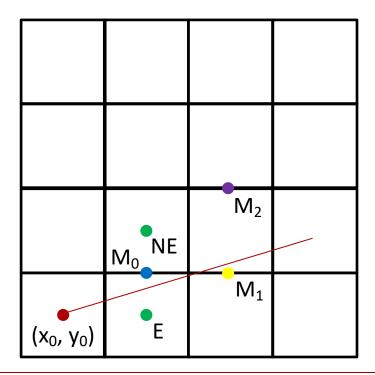
- If we selected E, in the next iteration we need the value of f(M₁)
- If we selected NE, in the next iteration we need f(M₂)
- Both can be computed from $f(\mathbf{M_0})$

$$f(M_1) - f(M_0) = y_0 - y_1$$

$$f(M_2) - f(M_0) = (y_0 - y_1) + (x_1 - x_0)$$



- This algorithm works well but requires evaluating the line equation at every iteration
- Can be optimized with an incremental algorithm:



- In other words, if we know f(M), we can compute the next f(M) by simple integer arithmetic
- What is the first f(**M**)?
- Note that $f(x_0, y_0) = 0$ as it is the starting point of the line

$$f(M_0) = f(x_0 + 1, y_0 + 0.5)$$
$$= (y_0 - y_1) + 0.5(x_1 - x_0)$$



So the overall algorithm is:

```
y = y_0

d = (y_0 - y_1) + 0.5(x_1 - x_0)

for x = x_0 to x_1 do:

draw(x, y)

if d < 0 then: // choose NE

y = y + 1

d += (y_0 - y_1) + (x_1 - x_0)

else: // choose E

d += (y_0 - y_1)
```



• For max efficiency, f(x, y) = 0 is written as 2f(x, y) = 0. This entirely eliminates floating point operations:

```
y = y_0

d = 2(y_0 - y_1) + (x_1 - x_0)

for x = x_0 to x_1 do:

draw(x, y)

if d < 0 then: // choose NE

y = y + 1

d += 2[(y_0 - y_1) + (x_1 - x_0)]

else: // choose E

d += 2(y_0 - y_1)
```



- The presented algorithm works when the slope of the line, m, is in range (0, 1]
- For other slope ranges, minor modifications to the algorithm is required
- For instance if m ∈ (1, ∞), we need to swap the roles of x and
- Other cases must be adapted similarly



Float vs Integer

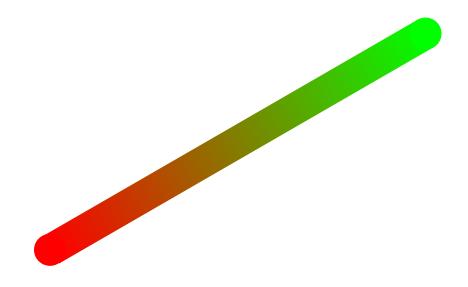
- The midpoint algorithm was originally developed by Pitteway in 1967
- Floating point arithmetic was very expensive at the time
- Does it still matter?
- We implemented both algorithms and drew one million lines each between 1000 and 1400 pixels long:
 - Test run on Intel Core i7 CPU at 3.2 GHz
 - Compiled with g++ and –O2 option
 - Basic algorithm: 7.2 seconds
 - Optimized algorithm: 3 seconds
 - So it still makes a difference!



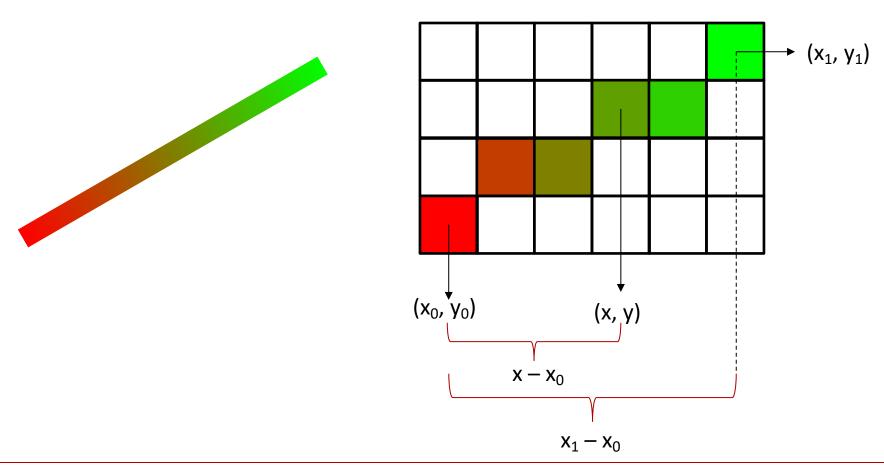
- What if the two end points of the line have a different color?
- The color across the line must smoothly change:



- What if the two end points of the line have a different color?
- The color across the line must smoothly change:









- Assume that the color of the endpoints are c₀ and c₁
- The color of an intermediate point should be:

$$c = (1 - \alpha)c_0 + \alpha c_1$$

where α is the interpolation variable

• At any pixel (x, y), we can compute it based on the horizontal or vertical distance of the pixel to the first endpoint:

$$\alpha = \frac{x - x_0}{x_1 - x_0}$$

For $m \in [0,1]$ it is better to interpolate in the x direction as as it will produce a smoother variation



- Assume that the color of the endpoints are c₀ and c₁
- The color of an intermediate point should be:

$$c = (1 - \alpha)c_0 + \alpha c_1$$

where α is the interpolation variable

It can also be computed incrementally

$$\alpha(x_0 + 1) = \alpha_1 = \frac{1}{x_1 - x_0}$$
$$\alpha(x_0 + 2) = \alpha_2 = \alpha_1 + \frac{1}{x_1 - x_0}$$



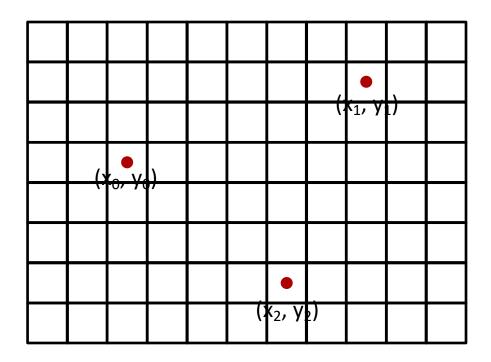
Algorithm with Interpolation

Algorithm with color interpolation:

```
y = y_0
d = (y_0 - y_1) + 0.5(x_1 - x_0)
c = c_0
dc = (c_1 - c_0) / (x_1 - x_0) // skip \alpha; directly compute color increment
for x = x_0 to x_1 do:
  draw(x, y, round(c))
  if d < 0 then: // choose NE
     y = y + 1
     d += (y_0 - y_1) + (x_1 - x_0)
  else: // choose E
     d += (y_0 - y_1)
  c += dc
```

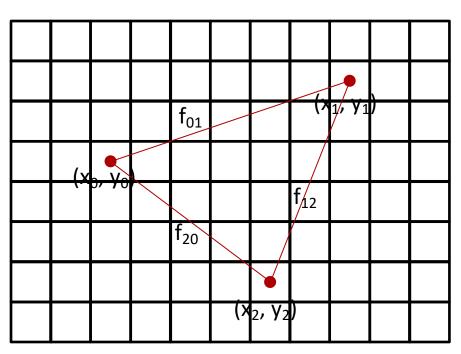


Initially all we have is the screen coordinates of three vertices





• From them we compute line equations for the edges:



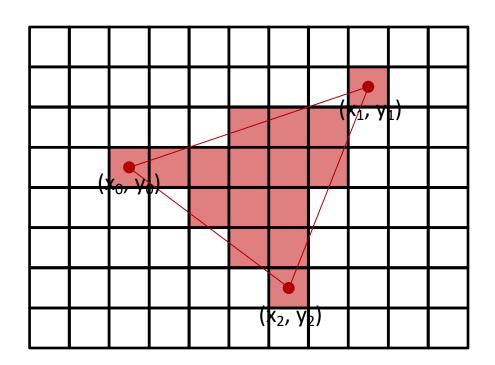
$$f_{01}(x,y) = x(y_0 - y_1) + y(x_1 - x_0) + x_0y_1 - y_0x_1$$

$$f_{12}(x,y) = x(y_1 - y_2) + y(x_2 - x_1) + x_1y_2 - y_1x_2$$

$$f_{20}(x,y) = x(y_2 - y_0) + y(x_0 - x_2) + x_2y_0 - y_2x_0$$

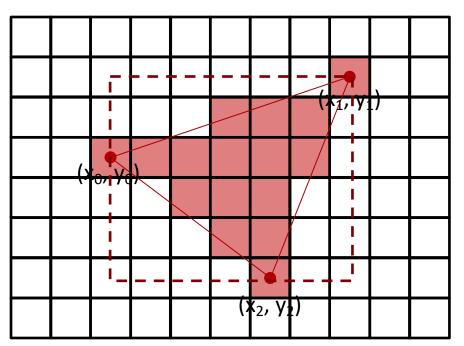


We then walk across the viewport to determine inside pixels:





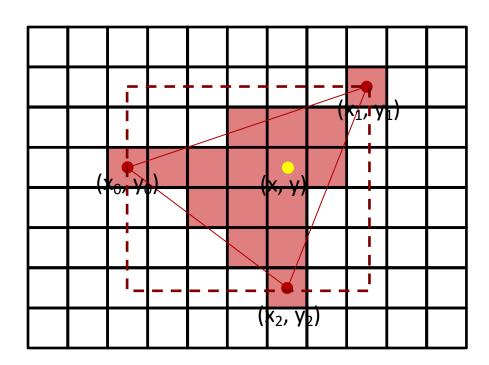
 For efficiency we may only walk within the bounding box of the triangle:



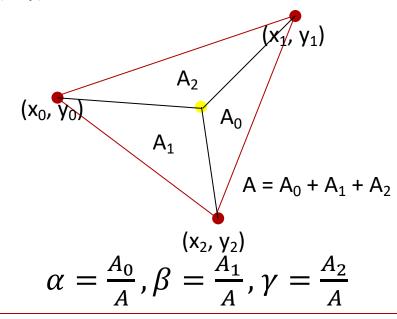
- For each pixel we visit, we must make an inside test with respect to all three edges
- We can simply plug-in the (x, y) value of the visited pixel to each line equation
- If all are negative, the pixel is inside the triangle



 However, using barycentric coordinates will help us with interpolation of attributes



What are the barycentric coordinates of (x, y)?





 We don't actually need to compute the areas as the bases are shared and will cancel out

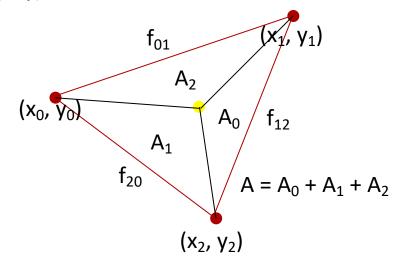
$$\alpha = \frac{A_0}{A}$$
 , $\beta = \frac{A_1}{A}$, $\gamma = \frac{A_2}{A}$

$$\alpha = \frac{f_{12}(x, y)}{f_{12}(x_0, y_0)}$$

$$\beta = \frac{f_{20}(x, y)}{f_{20}(x_1, y_1)}$$

$$\gamma = \frac{f_{01}(x, y)}{f_{01}(x_2, y_2)}$$

What are the barycentric coordinates of (x, y)?





Overall Algorithm

```
for y = y<sub>min</sub> to y<sub>max</sub> do:

for x = x<sub>min</sub> to x<sub>max</sub> do:

\alpha = f_{12}(x,y)/f_{12}(x_0,y_0)

\beta = f_{20}(x,y)/f_{20}(x_1,y_1)

\gamma = f_{01}(x,y)/f_{01}(x_2,y_2)

if \alpha \geq 0 and \beta \geq 0 and \gamma \geq 0 then:

c = \alpha c_0 + \beta c_1 + \gamma c_2

draw(x, y, round(c))
```

 Note that the computation of the barycentric coordinates can also be made incremental for greater efficiency



Summary

- The result of rasterization is a set of fragments (pixel-to-be) for each primitive
- Each fragment has interpolated values of attributes:
 - Color values
 - Texture coordinates
 - Depth value
 - Normals
 - Or any user-defined attribute for vertices
- The next stage in the life of a fragment is to go through the fragment pipeline

