## 3D計算機圖學期末考 / 3D Computer Graphics Final Exam

姓名:	陳錕詮	交卷時間 ( IP ):	2022-01-13 14:18	分數:	0 / 142			
≪ Soι	≪ Some questions are out of contents of course as bonus!!!							
題組	(共7題)							
	1. 3D Rendering Pipeli	ne:						
1	(1) (4%) Please draw a	a diagram describing	each stage of 3D rendering pipel	ine.				
	transform -> illuminat	tion -> flatten shadov	v -> Z buffer algorithm & rgb					
			分數: 尚未評分			4 /		
2	(2) (4%) Please indicat	re in which stage(s) t	he "rasterization" is involved?			4分		
	projection transform							
			分數: 尚未評分			4分		
3	(3) (4%) Please indicat	e in which stage(s) t	he "clipping" is involved?					
	view transform projection transform							
			分數: 尚未評分					
						4分		
4	(4) (4%) Please indicat	e in which stage(s) t	he "lighting/illumination" is involve	ed?				
	projection transform							

分數: 尚未評分

5 (5) (4%) Please indicate in which stage(s) the "z-buffer HSR algorithm" is involved?

Z buffer algorithm & rgb

分數: 尚未評分

4分

6 (6) (4%) Please indicate in which stage(s) the "Gouraud shading" is involved?

projection

分數: 尚未評分

4分

7 (7) (4%) Please indicate in which stage(s) the "Phong shading" is involved?

projection

分數: 尚未評分

4分

8

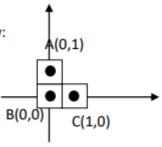
2. (12%) An object with three points (in 2D space) are given as below:

A(0,1) B(0,0) C(1,0)

A series of transformation are applied to this object as below:

Rotate (30 degree)  $\rightarrow$  Translate (2,4)  $\rightarrow$  Scale (2,1)

Please show the final results of points A, B & C.



https://imgur.com/gallery/Jd8Qilp

分數: 尚未評分

12分

題組 (共 3 題)

- 3. Considering two projection methods:
- A. Perpendicular Parallel Projection
- B. Perspective Projection

Please indicate which method is applied in each case below:

9	(1) (4%) Camera				
	B. Perspective Projection				
	分數: 尚未評分				
		4分			
10	(2) (4%) Human eye				
	A. Perpendicular Parallel Projection				
	分數: 尚未評分				
		4分			
11	(3) (4%) Computer Aided Engineering (CAD)				
	A. Perpendicular Parallel Projection				
	分數: 尚未評分				
		4分			
	组 (共 3 題)				
AZS I	5. Considering illumination methods:  A. Ambient Lighting  B. Diffuse Lighting  C. Specular Lighting				
12	(1) (4%)Which method(s) is "position of light source" dependent?				
	B. Diffuse Lighting C. Specular Lighting				
	分數: 尚未評分				
		4分			
13	(2) (4%)Which method(s) is "position of viewer" dependent?				
	C. Specular Lighting				

14 (3) (4%)Which method(s) is "position of illuminated spot" dependent?

A. Ambient Lighting

B. Diffuse Lighting

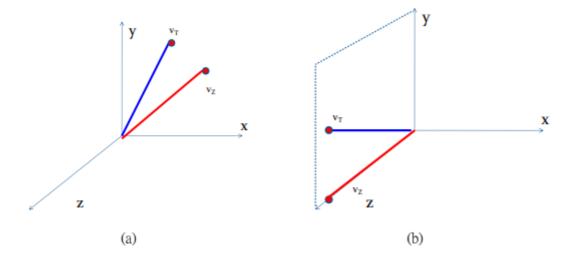
分數: 尚未評分

4分

- 15 6.(10%) In figure
  - (a), there are two vectors VT and VZ. Please transform both vectors in order to align VZ A(0,1) B(0,0) C(1,0) with Z axis and locate VT at Y-Z plane, as shown in fig
  - b). Please derive the GRM (General Rotation Matrix) with information below:

$$V_T = (a, b, c)$$
 ,  $||V_T|| = 1$ 

$$V_Z = (d, e, f)$$
 ,  $||V_Z|| = 1$ 



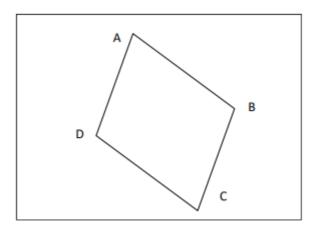
沒圖

分數: 尚未評分

10分

16 7. (10%) Considering the information provided below, please calculate the color(r, g, b) of pixel at (600, 200) with Gouraud Shading algorithm.

	Position (x,y)	Color (r, g, b)
A	(600, 50)	(0.8, 0, 0.2)
В	(900, 300)	(0.2, 0.8, 0)
C	(800, 700)	(0.6, 0.2, 0.4)
D	(300,500)	(0, 0.8, 0.4)



沒圖

分數: 尚未評分

10分

題組 (共 4 題)

- 8. Considering the illumination equation below:
- $I = KaIaOd + KdIp(NL)*Od + KsIp(RV)^n + KrIr + KtIt$
- $(a) \ KaIa \qquad (b) \ Od \quad (c) \ KdIp \quad (d) \ N \qquad (e) \ L \qquad (f) \ KsIp \quad (g) \ R \quad (h) \ V \quad (i) \ n \quad (j) \ KrIr \quad (k) \ KtIt$
- 17 1) (2%) Which part(s) is "Texture Mapping" involved?

a, b

分數: 尚未評分

2分

18 2) (2%)Which part(s) is "Bumping Mapping" involved?

c, f, j

分數: 尚未評分

19 3) (2%) Which part(s) is "Displacement Mapping" involved?

d, g

分數: 尚未評分

2分

4) (2%) Which part(s) is "Reflection Mapping" involved?

d, e, i

分數: 尚未評分

2分

21 9. (10%) What is the purpose of "Bounding Box" and how to utilize it?

A bounding box is an imaginary rectangle that serves as a point of reference for object detection and creates a collision box for that object

分數: 尚未評分

10分

- 22 10. (10%) Please describe two methods about how to tell if a point is inside a polygon or not.
  - A: Planner polygon

polygon as a plane

calculate the equation of polygon plane, check the point is equal to equation.

B: Non - Planner polygon (curvef surface)

Draw a horizontal line to the right of each point and extend it to infinity

Count the number of times the line intersects with polygon edges.

A point is inside the polygon if either count of intersections is odd or point lies on an edge of polygon. If none of the conditions is true, then point lies outside.

分數: 尚未評分

10分

題組 (共 2 題)

11. Please describe the attenuation of Light Intensity by:

## 23 1) Distance (5%)

a reduction in the intensity of a light beam as the beam propagates in matter owing to the joint action of the absorption and scattering of light.

分數: 尚未評分

5分

## 24 2) Atmosphere (5%)

a reduction in the intensity of a light beam as the beam propagates in matter owing to the joint action of the absorption and scattering of light.

分數: 尚未評分

5分

題組 (共 3 題)

- 12. Please describe the disadvantages of:
- 25 1) Z-Buffer Algorithm (at least three points) (6%)
  - 1. 在象素上以z座標決定顯示順序(近物取代遠物),與物體在螢幕的出現順序無關,是在象素級上的消隱算法。
  - 2. 沒有利用圖形的相關性與連續性去做運算。
  - 3. 使用大量的記憶體作為緩衝區·而由於它是以像素為處理的單位·所以需耗用相當大量的運算資源。

分數: 尚未評分

6分

## 26 2) Displacement Mapping (at least one point) (2%)

當物體上面的節點不多時,displacement mapping 能的到的效果就相當有限,是一個看情況的算法。

分數: 尚未評分

2分

著色時需要很多計算,需耗用相當大量的運算資源。

分數: 尚未評分

13. Please explain why clipping at screen space or at image space is not a good idea. (10%)

在著色時會有不正確的過度曝光問題。

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分數: 尚未評分

10分

2分

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