

# Design and Analysis of Algorithms

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## 1 Fundamentals

**Definition 1.1.** *An algorithm is a well defined computational procedure. It takes an input, does some computation and terminates with output*

To check the correctness of an algorithm, we must check the following characteristics:

- Initialization: The algorithm is correct at the beginning
- Maintenance : The algorithm remains correct as it runs
- Termination : The algorithm terminates in finite time, correctly

For this entire course, we must always prove these characteristics when defining any algorithm.

Algorithms are generally defined by a complexity - the time taken to complete the computation on a given input size. There are three ways we could consider this - best case, worst case, or average case.

Complexity is discussed a lot in DSA, so I'm not going to rewrite it here. A quick roundup is:

- $O(g(n)) = \{f(n) : \text{there exists } c, n_0 : 0 \leq f(n) \leq c \cdot g(n) \forall n \geq n_0\}$
- $\Omega(g(n)) = \{f(n) : \text{there exists } c, n_0 : 0 \leq c \cdot g(n) \leq f(n) \forall n \geq n_0\}$
- $\Theta(g(n)) = \{f(n) : \text{there exists } c, n_0 : 0 \leq c_2 \cdot g(n) \leq f(n) \leq c_1 \cdot g(n) \forall n \geq n_0\}$

To find complexities in the case of recurrences, we use the **master method**. Let the recurrence be given by:

$$T(n) = aT\left(\frac{n}{b}\right) + f(n)$$

Here,  $a, b \geq 1$ . Let  $\epsilon$  be a constant. Then:

1. If  $f(n) = O(n^{\log_b a - \epsilon})$  then  $T(n) = \Theta(n^{\log_b a})$
2. If  $f(n) = O(n^{\log_b a})$  then  $T(n) = \Theta(n^{\log_b a} \log n)$
3. If  $f(n) = O(n^{\log_b a + \epsilon})$  then  $T(n) = \Theta(f(n))$  provided if  $af(n/b) \leq cf(n)$  for some constant  $c < 1$  and all sufficiently large  $n$ .

Here, we redo DSA despite it being a prerequisite of the course. This recap has lasted 3 lectures (so far). You should probably just read CLRS, this is a waste. The topics covered are:

- Quicksort (and it's average case analysis)
- The  $\Omega(n \log n)$  lower bound of comparison sorting
- Non-comparison sorting like counting sort, radix sort, etc.
- Average case analysis of bucket sort

## 2 Matrix Multiplication

Naive Matrix multiplication is  $\Theta(N^3)$ , since we can express the result  $A \cdot B = C$  as:

$$C_{ij} = \sum_{k=1}^r A_{ik} \times B_{kj}$$

We can improve this using a divide-and-conquer approach with **Strassen's Multiplication**. It has four steps:

1. Divide the input matrices  $A$  and  $B$  and the output matrix  $C$  into four  $n/2 \times n/2$  submatrices. This takes  $\Theta(1)$  time.
2. Create 10 matrices  $S_1, S_2, \dots, S_{10}$ , each of which is of size  $n/2 \times n/2$  and is the sum or difference of two matrices created in step 1.
3. Using these submatrices, we can recursively compute seven matrix products  $P_1, P_2, \dots, P_7$ , each of which is  $n/2$ .
4. Compute the desired submatrices  $C_{11}, C_{12}, C_{21}, C_{22}$  by adding and subtracting various combinations of the  $P_i$  matrices. We can compute all four in  $\Theta(N^2)$  time.

The details of this can be seen on page 80 of CLRS, but the running time recurrence will be given by:

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 7T(n/2) + \Theta(n^2) & \text{if } n > 1 \end{cases}$$

By master method, this is  $T(n) = \Theta(n^{\log 7})$

### 3 Polynomial Multiplication

Polynomials are functions of the form:

$$f(x) = a_0 + a_1x + a_2x^2 + \dots a_{n-1}x^{n-1}$$

One way to express this is as a vector of coefficients - this is called the **Coefficient form**. This form also allows us to evaluate  $f(x)$  in  $O(n)$  using Horner's rule, where we express the polynomial as:

$$a_0 + x(a_1 + x(a_2 + \dots x(a_{n-1} - 1) \dots))$$

Another way to express this is using the **point value form**, where we express it as  $n$  point of the form  $(x_i, f(x_i))$ . This point value form uniquely identifies a polynomial. Generally this would take  $\Theta(N^2)$  time, but with FFT we can do it in  $O(N \log N)$ .

The process of getting the coefficient form from the point value form is known as **interpolation**. We can do this in  $O(n^3)$  using Gaussian Elimination, or in  $O(n^2)$  with Lagrange Interpolation.

Generally, the multiplication of polynomials takes  $\Theta(N^2)$ . However, we can do this much faster using **Fast Fourier Transform**.

#### 3.1 Fourier Transform

##### 3.1.1 Discrete Fourier Transform

From now on,  $w_n^k$  will denote the  $k^{th}$  solution of  $x^n = 1$ , i.e. the  $n^{th}$  root of unity.  $w_n$  will denote the principal  $n^{th}$  root of unity. Remember the following properties:

1.  $w_n^k = e^{\frac{2k\pi i}{n}}$
2.  $w_{dn}^{dk} = w_n^k$

3.  $w_n^{n/2} = w_2 = -1$
4. If  $n > 0$  is even, then the squares of the  $n$  complex  $n^{th}$  roots of unity are the  $n/2$  complex  $n/2$ th roots of unity. (Halving Lemma)
5.  $\sum_{j=0}^{n-1} (w_n^k)^j = 0$  (Summation Property)

We call the vector  $y = (y_0, y_1, \dots, y_{n-1})$  the **discrete Fourier Transform** of the polynomial  $A$  if  $y_k = A(w_n^k)$ .

### 3.1.2 Fast Fourier Transform

FFT consists of three parts:

1. Evaluation, where we find the DFT in  $O(n \log n)$
2. Pointwise Multiplication of the two DFTs
3. Interpolation or the inverse FFT, where we find the coefficient form in  $O(n \log n)$ .

Consider the following polynomials:

$$\begin{aligned} A(x) &= a_0x^0 + a_1x^1 + \dots + a_{n-1}x^{n-1} \\ A_0(x) &= a_0x^0 + a_2x^1 + \dots + a_{n-2}x^{n/2-1} \\ A_1(x) &= a_1x^0 + a_3x^1 + \dots + a_{n-1}x^{n/2-1} \end{aligned}$$

It is easy to see that:

$$A(x) = A_0(x^2) + xA_1(x^2)$$

These polynomials have only half as many coefficients as the polynomial  $A$ . So, if we can compute  $DFT(A)$  from  $DFT(A_1)$  and  $DFT(A_0)$  in linear time, we would be able to do this in  $O(n \log n)$  (direct from master method).

We find that do this with the equations:

$$\begin{aligned} y_k &= y_k^0 + w_n^k y_k^1 \\ y_{k+n/2} &= y_k^0 - w_n^k y_k^1 \end{aligned}$$

Here,  $k \in [0, n/2 - 1]$ . The proof of this can be seen on cp-algorithms.

As such, we have found the DFT of the polynomial in  $O(n \log n)$  time.

After performing the pointwise multiplication of the DFT of our polynomials  $A$  and  $B$ , we have to interpolate to find the coefficient form of our resulting polynomial  $C$ .

*TODO: Add interpolation with Vandermonde matrix, can be seen on cp-algorithms*