Cleaning and Mapping Robotics Project

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Introduction

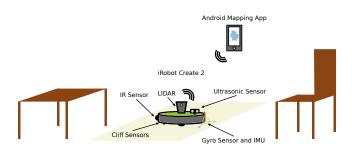


Figure: Diagram representing the working principle of the cleaning and mapping robot

Implemented SBC discovery feature in the Android App using UDP multicasting

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Figure: Screenshot of app with Discovery and Map tabs



```
Select pi@raspberrypi: ~/PyMulti
:\Users\lauer>ssh pi@192.168.0.18
i@192.168.0.18's password:
Linux raspberrypi 4.19.118-v7+ #1311 SMP Mon Apr 27 14:21:24 BST 2020 armv7l
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Wed Jun 24 16:51:53 2020
oi@raspberrypi:~ $ cd P
bash: cd: P: No such file or directory
oi@raspberrypi:~ $ cd PyMulti/
i@raspberrypi:~/PyMulti $ ls
receiver.py sender.py
oi@raspberrypi:~/PyMulti $ python3 receiver.py
data: b'Hello'
address: ('192.168.0.19', 42234)
data: b'Hello'
address: ('192.168.0.19', 35683)
data: b'Hello'
address: ('192.168.0.19', 38314)
data: b'Hello'
address: ('192.168.0.19', 55172)
data: b'Hello'
address: ('192.168.0.19', 60146)
data: b'Hello'
address: ('192.168.0.19', 49428)
```

Figure: Screenshot of the multicast receiver program running

Further app details

- Multicast group: (224.3.29.71, 10000)
- Raspberry Pi sends message ("iRobot Create 2") to app
- Upon pressing the refresh button the app will send out another message to the multicast group
- ListView does not clear when refreshed and detects the same device multiple times

Plans

- Continue adding to the python receiver program to send data from lidar, add separate receiving thread for clients
- Create database using SQLite in app for storing SBC information
- Update refresh button to prevent connecting to redundant remote hosts
- Possibly add spinner animation to refresh button

References I



Python Module of the Week

https://pymotw.com/2/socket/multicast.html

Any Questions?