

$$\begin{cases} \dot{w} = -\frac{b_m}{J} w + \frac{k_N}{J} i_a \\ \dot{i} = -\frac{k_N}{L} w - \frac{R_a}{L} i_a + \frac{M}{L} \end{cases}$$

No estado estacionário, $\dot{w} = \dot{i} = 0$:

$$+\frac{b_m \Delta \bar{w}}{J} + \frac{k_N \Delta \bar{i}_a}{J} = 0 \Rightarrow \varphi = \frac{\Delta \bar{i}_a}{\Delta \bar{w}} = \frac{b_m}{k_N} \text{ (constante)}$$

$$\frac{k_N \Delta \bar{w}}{L} + \frac{R_a \Delta \bar{i}_a}{L} = \frac{\Delta \bar{M}}{L} \Rightarrow \begin{cases} k_N \Delta \bar{w}_1 + R_a \Delta \bar{i}_a = \Delta \bar{M}_1 & (\text{step } 40 \rightarrow 50) \\ k_N \Delta \bar{w}_2 + R_a \Delta \bar{i}_a = \Delta \bar{M}_2 & (\text{step } 40 \rightarrow 60) \\ k_N \Delta \bar{w}_3 + R_a \Delta \bar{i}_a = \Delta \bar{M}_3 & (\text{step } 40 \rightarrow 70) \end{cases}$$

$$\Delta \bar{w}_i = \bar{w}_i - \bar{w}_{40\%}, i \in \{50; 60; 70\}$$

$$\Delta \bar{i}_a = \bar{i}_a - \bar{i}_{a40\%}$$

$$\Delta \bar{M}_i = \bar{M}_i - \bar{M}_{40\%}$$

Quando $\Delta \bar{M}_1$ e $\Delta \bar{M}_2$, temos:

$$\varphi_{k_N} = \frac{R_a \Delta \bar{i}_a \frac{\Delta \bar{M}_1}{\Delta \bar{M}_2} - R_a \Delta \bar{i}_a}{\Delta \bar{w}_1 - \frac{\Delta \bar{M}_1}{\Delta \bar{M}_2} \Delta \bar{w}_2} \Rightarrow \varphi_{b_m} = k_N \varphi$$

Supondo $i_a \rightarrow 0$ (Corrente varia pouco e varia rápida)

$$\dot{w}_a = -\frac{b_m}{J} w + \frac{k_N}{J} i_a; \quad \dot{i}_a = -\frac{k_N}{L} w - \frac{R_a}{L} i_a + \frac{M}{L} \Rightarrow i_a = \frac{M}{R_a} - \frac{k_N}{R_a} w$$

$$\dot{w}_a = -w \left(\frac{b_m}{J} + \frac{k_N^2}{J R_a} \right) + \frac{k_N M}{J R_a} \therefore w(t) = \frac{k_N}{J R_a} \cdot \frac{1}{p} (1 - e^{-pt}) M(t)$$

Laplace

$$p = \frac{b_m}{\bar{J}} + \frac{K_N^2}{\pi_a \bar{J}} \Rightarrow \bar{J} = \frac{b_m}{p} + \frac{K_N^2}{\pi_a p}$$

$$* \tau_{99} = 5 \bar{\sigma}_2 = \frac{5}{p}$$

Tempo de 99% do Valor
Estacionário (no olho)

Resumo:

$\pi_a, \lambda_a \Rightarrow$ medidas

$$\frac{K_N}{K_N} = \frac{\pi_a \bar{\sigma}_{i2} \frac{\partial \bar{u}_1}{\partial \bar{u}_2} - \pi_a \bar{\sigma}_{i1}}{\bar{\sigma}_{u1} - \frac{\partial \bar{u}_1}{\partial \bar{u}_2} \bar{\sigma}_{u2}}$$

onde $\bar{\sigma}_{i1}$ e $\bar{\sigma}_{u1}$ são medidas
obtidas das grandezas indireta-
mente.

$$\bar{b}_m = K_N \cdot \left(\frac{\partial \bar{u}_1}{\partial \bar{u}_2} \right) ; \quad \bar{J} = \frac{b_m}{p} + \frac{K_N^2}{\pi_a p} \quad * p = \frac{5}{\tau_{99}} \text{ medida}$$