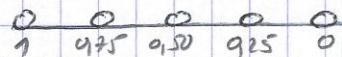


14.6
1) $\lambda = 1 \text{ m}$

$m = 1 \text{ kg}$

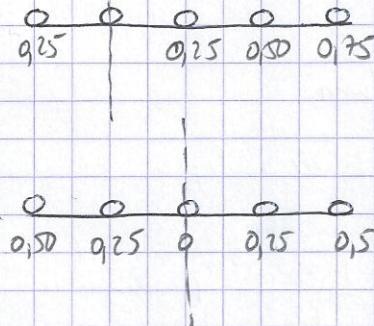
~~mass~~



a) $I = \sum_{i=1}^5 m_i r_i^2$

$$= 1 \times 0 + 1 \times 0,25^2 + 1 \times 0,50^2 + 1 \times 0,75^2 + 1 \times 1^2 = 1,88 \text{ kg} \cdot \text{m}^2$$

b) $I = 0,25^2 + 0,25^2 + 0,50^2 + 0,75^2$
 $= 0,94 \text{ kg} \cdot \text{m}^2$



c) $I = 0,25^2 \times 2 + 0,50^2 \times 2$
 $= 0,63 \text{ kg} \cdot \text{m}^2$

d) $I = m \kappa^2$

a) $1,88 = 5 \times \kappa^2 \Rightarrow \kappa = 0,61 \text{ m}$

b) $0,94 = 5 \times \kappa^2 \Rightarrow \kappa = 0,43 \text{ m}$

c) $0,63 = 5 \times \kappa^2 \Rightarrow \kappa = 0,35 \text{ m}$

2) Theoreme des Steiners: $I = I_{\text{cm}} + M \cdot L^2$

a) $1,88 = 0,63 + 5 \times 0,50^2 \quad \checkmark$

b) $0,94 = 0,63 + 5 \times 0,25^2 \quad \checkmark$

$$\begin{aligned} I_{\text{cm}} &= \int x^2 dm = \int x^2 dm = \\ &= \frac{\pi}{L} \int_{-\frac{L}{2}}^{\frac{L}{2}} x^2 dx = \frac{\pi}{L} \left[2 \times \frac{\frac{L^3}{8}}{3} \right] = \frac{\pi L^2}{12} \end{aligned}$$

2) Masse = $0,20 \text{ kg}$ $I_{\text{entfernt}} = \frac{1}{12} M L^2 = 0,017 \text{ kg} \cdot \text{m}^2$

a) $I_{\text{handk}} = 0,017 + 0,20 \times 0,50^2 = 0,067 \text{ kg} \cdot \text{m}^2$

$I = 1,88 + 0,067 = 1,95 \text{ kg} \cdot \text{m}^2$

b) $I_{\text{handk}} = 0,017 + 0,20 \times 0,25^2 = 0,0295 \text{ kg} \cdot \text{m}^2$

$I = 0,94 + 0,0295 = 0,9695 \text{ kg} \cdot \text{m}^2$

c) $I_{\text{handk}} = 0,017$

$I = 0,63 + 0,017 = 0,647 \text{ kg} \cdot \text{m}^2$

3)



$$m_e = 12 \text{ kg} = 12 \times 1,66 \times 10^{-27}$$

$$m_o = 16 \text{ kg} = 16 \times 1,66 \times 10^{-27}$$

$$r = 1,13 \times 10^{-10} \text{ m}$$

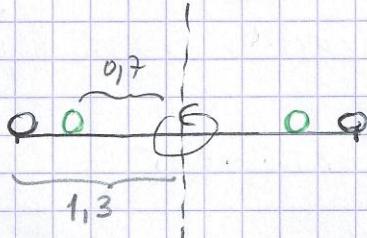
$$I = 16 \times 1,66 \times 10^{-27} \times (1,13 \times 10^{-10})^2 \times 2 = 6,78 \times 10^{-46} \text{ kg} \cdot \text{m}^2$$

4) $m = 25 \text{ kg}$

$$l = 2,6 \text{ m}$$

$$r = 10 \text{ kg}$$

$$\omega = 5 \text{ rev/min}$$



$$I_{\text{bárm}} = \frac{\pi L^2}{12}$$

a) Movimento de inércia mantém-se: $I_i w_i = I_f w_f$

$$I_i = \frac{10 \times 2,6^2}{12} + 25 \times 1,3^2 \times 2 = 90,13 \text{ kg} \cdot \text{m}^2$$

$$I_f = \frac{10 \times 2,6^2}{12} + 25 \times 0,7^2 \times 2 = 30,13 \text{ kg} \cdot \text{m}^2$$

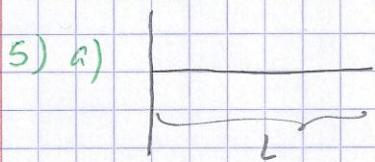
$$w_i = \frac{5 \times 2\pi}{60} = 0,52 \text{ rad/s}$$

$$\text{Logo, } 90,13 \times 0,52 = 30,13 \times w_f$$

$$w_f = 1,56 \text{ rad/s}$$

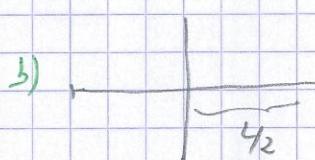
b) $\Delta E_C = E_{Cf} - E_{Ci}$

$$= \frac{1}{2} I w_f^2 - \frac{1}{2} I w_i^2 = \frac{1}{2} \times 30,13 \times 1,56^2 - \frac{1}{2} \times 90,13 \times 0,52^2 \\ = 24,48 \text{ J}$$



$$I = \int x^2 dm = \frac{M}{L} \int_0^L x^2 dx = \frac{M}{L} \left[\frac{x^3}{3} \right]_0^L =$$

$$= \frac{M}{L} \frac{L^3}{3} = \frac{ML^2}{3}$$



$$I = \frac{M}{L} \int_{-L/2}^{L/2} x^2 dx = \frac{M}{L} \left[\frac{x^3}{3} \right]_{-L/2}^{L/2} =$$

$$= \frac{M}{L} \left[\frac{\frac{L^3}{8}}{3} + \frac{\frac{L^3}{8}}{3} \right] = M \left[\frac{L^2}{24} + \frac{L^2}{24} \right] = \frac{ML^2}{12}$$

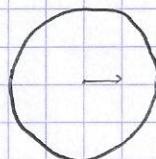
(2)

6)



$$I = \int r^2 dm = \frac{2\pi}{R^2} \int_0^R x^2 \times \pi x^2 dx = \frac{2\pi}{R^2} \left[\frac{x^4}{4} \right]_0^R = \frac{2\pi}{R^2} \frac{R^4}{4} = \frac{\pi R^2}{2}$$

7)



$$J = 10 \text{ Nm}$$

$$R = 0,6 \text{ m}$$

$$I = 100 \text{ kg}$$

$$\omega = 175 \text{ rad/s}$$

$$J = I\alpha$$

$$I = \frac{\pi R^2}{2} = \frac{100 \times 0,6^2}{2} = 18 \text{ kg} \cdot \text{m}^2$$

$$J = 10 \Leftrightarrow 18 \cdot \alpha = 10 \Leftrightarrow \alpha = 0,56 \text{ rad/s}^2$$

$$\text{max } \omega_f = 0 \text{ rad/s}$$

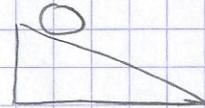
$$\alpha = \frac{\omega_f - \omega_i}{t} \Leftrightarrow 0,56 = \frac{|\theta - 175|}{t}$$

$$\Leftrightarrow t = 312,5 \text{ s} \rightarrow \frac{312,5}{60} = 5,21 \text{ min}$$

$$8) R = 1 \text{ cm} = 0,01 \text{ m}$$

$$m = 5 \text{ g} = 0,005 \text{ kg}$$

$$\omega = 6 \text{ rad/s} = 6 \times 2\pi = 12\pi \text{ rad/s}$$

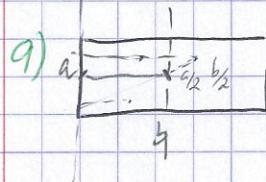


$$a) E_{cr} = \frac{1}{2} I \omega^2 = \frac{1}{2} \times \frac{\pi R^2}{2} \times (12\pi)^2 = 1,78 \times 10^{-4} \text{ J}$$

$$b) E_{cr} = \frac{1}{2} m v^2 = \frac{1}{2} \times 0,005 \times (0,12\pi)^2 = 3,55 \times 10^{-4} \text{ J}$$

$$v = \omega R = 12\pi \times 0,01 = 0,12\pi \text{ m/s}$$

$$c) E_e = E_{cr} + E_{cm} = 5,33 \times 10^{-4} \text{ J}$$

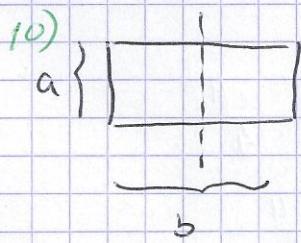


~~$$I_{cm} = \frac{1}{2} M b^2$$~~

$$I_{cm} = \frac{b^2 M}{12} \quad (\text{viel num. lösbar})$$

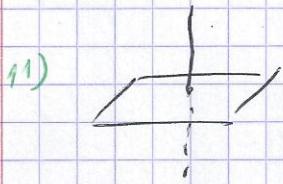
$$I_c = I_{cm} + M d^2$$

$$= \frac{b^2 M}{12} + M \left(\frac{b}{2} \right)^2 = \frac{b^2}{12} M + \frac{3b^2}{12} M = \frac{4b^2}{12} M = \frac{M b^2}{3}$$



$$I = \frac{1}{12} r b^2 \quad (\text{limo})$$

$$dI = \frac{\pi}{12} \times r dI$$



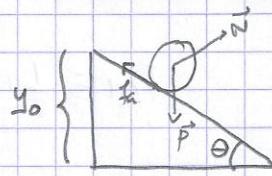
$$I = \frac{\pi (a^2 + b^2)}{12}$$

12)

13)

③

14) esfera: $I = \frac{2}{5} MR^2$



solo
cuadros!
Está bien
con los
Slides

$$E_{H_i} = E_{H_f}$$

$$E_{pg_i} + E_{e_{\text{r},i}} + E_{e_{T,i}} = E_{pg_f} + E_{e_{\text{r},f}} + E_{e_{T,f}}$$

$$\cancel{Mgy_0} + \frac{1}{2} I w_i^2 + \frac{1}{2} m v_i^2 = \cancel{Mgy_0} + \frac{1}{2} I w_f^2 + \frac{1}{2} m v_f^2 \quad v_f = v$$

$$\cancel{Mgy_0} = \frac{1}{2} \times \frac{2}{3} M(\alpha^2) \times \frac{v^2}{R^2} + \frac{1}{2} M v^2$$

$$gy_0 = \frac{\cancel{v^2}}{5} + \frac{\cancel{v^2}}{2} \quad (\Rightarrow) \quad gy_0 = \frac{7v^2}{10}$$

$$(\Rightarrow) v = \sqrt{\frac{10}{7} gy_0}$$

cilindro: $I = \frac{MR^2}{2}$

$$\cancel{Mgy_0} = \frac{1}{2} \times \frac{MR^2}{2} \times \frac{v^2}{R^2} + \frac{Mv^2}{2}$$

$$gy_0 = \frac{v^2}{4} + \frac{v^2}{2} \quad (\Rightarrow)$$

$$4gy_0 = 3v^2 \quad (\Rightarrow) \quad v = \sqrt{\frac{4}{3} gy_0}$$

Anel: $I = MR^2$

$$\cancel{Mgy_0} = \frac{1}{2} MR^2 \times \frac{v^2}{R^2} + M \frac{v^2}{2}$$

$$gy = \frac{v^2}{2} + \frac{v^2}{2}$$

$$v = \sqrt{gy}$$

$$15) R = 0,5 \text{ m}$$

$$I_{CM} = \frac{1}{2} MR^2$$

$$F = 9,8 \text{ N}$$

$$M = 20 \text{ kg}$$

$$t = 2 \text{ s} \quad \alpha = ? \quad \omega = ?$$

$$\vec{\tau} = \vec{\omega} \times \vec{F}$$

$$\vec{\tau} = \vec{\omega} \times \vec{F} \times \operatorname{sen} \theta$$

$$\tau = 0,5 \times 9,8 \times \operatorname{sen} 90^\circ$$

$$J = 4,9 \text{ N.m}$$

$$\text{Mas por el otro lado} \quad J = I\alpha$$

$$4,9 = \frac{1}{2} \times 20 \times 0,5^2 \times \alpha$$

$$\alpha = 1,96 \text{ rad/s}^2$$

Considerando $\omega_i = 0$

$$\alpha = \frac{\omega_f - \omega_i}{t} \Rightarrow 1,96 \times 2 = \omega_f \Rightarrow \omega_f = 3,92 \text{ rad/s}$$

$$16) r_1 = 1 \text{ kg}$$

$$r_1 g - T = F$$

$$a_t = r\alpha$$

$$M_1 g - T = r_1 \alpha$$

o empujado sugiere

que F aplicada con el signo
a T

$$T = M_1 g - M_2 \alpha \text{ N.m.}$$

$$\vec{\tau} = \vec{\omega} \cdot \vec{T} \cdot \operatorname{cos} 90^\circ$$

$$\vec{\tau} = 0,5 (M_1 g - M_2 \alpha) \cdot \operatorname{sen} 90^\circ$$

$$\vec{\tau} = 4,9 - 0,25 \alpha \text{ N.m}$$

Mas

$$\vec{\tau} = I\alpha$$

$$4,9 - 0,25 \alpha = \frac{1}{2} \times 20 \times 0,5^2 \alpha$$

$$4,9 - 0,25 \alpha = 2,5 \alpha$$

$$2,75 \alpha = 4,9$$

$$\alpha = 1,8 \text{ rad/s}^2$$

4

$$M_{\text{disco}} = 20 \text{ kg}$$

$$R = 0,5 \text{ m}$$

$$F = Mg$$

$$F = 20 \times 9,8 = 196 \text{ N}$$

$$J = 0,5 \times 196 \times \sin 90^\circ$$

$$J = 98 \text{ Nm}$$

Mas

$$J = I\alpha$$

$$I = I_{\text{cm}} + Md^2$$

$$98 = 7,5 \alpha$$

$$I = \frac{1}{2}MR^2 + M \times R^2 = \frac{3}{2}MR^2$$

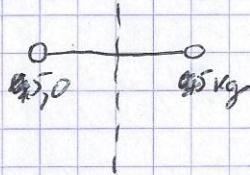
$$\alpha = 13,07 \text{ rad/s}^2$$

$$I = \frac{3}{2} \times 20 \times 0,5^2 = 7,5 \text{ kgm}^2$$

$$a = R\alpha \quad (\Rightarrow) \quad a = 0,5 \times 13,07$$

$$\Rightarrow a = 6,54 \text{ rad/s}^2$$

18)



verfertig

1 rot $\rightarrow 2,0 \Delta$

$$I = 5,0 \text{ kgm}^2$$

OTG
a), b)
c)
d)



$$w = ?$$

$$l_i = 0,90 \text{ m} \quad l_f = 0,15 \text{ m}$$

$$w_i = \frac{1}{2} \omega t/s = \frac{1}{2} \times 2\pi \text{ rad/s} = \pi \text{ rad/s}$$

O momento angular mantém-se: $I_i w_i = I_f w_f$

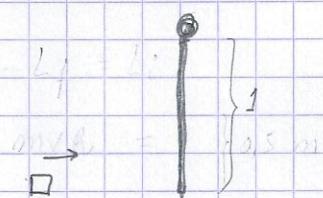
$$I_i = 5 + 5 \times 0,9^2 \times 2 = 13,1 \text{ kgm}^2$$

$$I_f = 5 + 5 \times 0,15^2 \times 2 = 5,225 \text{ kgm}^2$$

$$\text{subst.:} \quad 13,1 \times \pi = 5,225 w_f$$

$$w_f = 7,88 \text{ rad/s}$$

24)



$$m = m_1 = m_2$$

O Ponto de rotação é o centro de massa

$$L_f = L_i$$

$$I_{wf} = m \sqrt{\omega}$$

$$\left(\frac{mL^2}{12} + \frac{mL^2}{4} + mL^2 \right) \times w_f = m \sqrt{\omega L}$$

$$\frac{16}{12} L^2 w_f = \sqrt{\omega L}$$

$$w_f = \sqrt{\frac{12}{16} \omega L}$$

$$w_f = \frac{3}{4} \sqrt{\omega L}$$

25) a) $J = I\alpha$

$$I = \frac{4}{3} ml^2$$

$$\alpha = \frac{J}{I}$$

$$\alpha = \frac{J}{\frac{4}{3} ml^2} = \frac{3J}{4ml^2}$$

b) $v a_t = \alpha R = \frac{3J}{4ml}$

$$v_f^2 = v_i^2 - 2aS$$

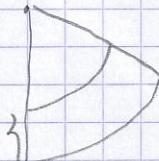
$$S = \frac{v^2}{2a}$$

$$S = \frac{v^2}{\frac{6J}{4ml}}$$

$$S = \frac{4mlv^2}{6J}$$

$$S = \frac{2mlv^2}{3J}$$

c)



$$y_{CM} = \frac{m_1 \frac{l}{2}}{m_1 + m_2} = \frac{1}{2} \times \frac{1}{2} = \frac{l}{4}$$

$$l = l - \frac{l}{4} = \frac{3}{4} l$$

Logo

$$S_1 = \frac{2m \left(\frac{3}{4}l\right)v^2}{3J} = \frac{3}{4} S$$

6) 24) a) $L_i = L_f$

$$m v R = I \omega_f \quad \text{Supondo que o horimeteiro é fixo}$$

$$- m_H v_H R = - \frac{I_m R^2}{2} \omega_f$$

$$- \frac{2 m_H v_H}{m_m R} = \omega_f$$

b) $W_H = \Delta E_C = \frac{1}{2} m_H v_H^2 + \frac{1}{2} I \omega_m^2$

$$= \frac{1}{2} m_H v_H^2 + \frac{1}{2} \times \frac{I_m}{2} \times R^2 \omega^2$$

$$= \frac{1}{2} m_H v_H^2 - \frac{1}{4} I_m R^2 \omega^2$$