```
In [183... import cv2
    from matplotlib import pyplot as plt
    import numpy as np
    import imutils
    import easyocr
```

1. Read in Image, Grayscale

```
img = cv2.imread('../data/poor4.jpg')
gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
plt.imshow(cv2.cvtColor(gray,cv2.COLOR_BGR2RGB))
```

Out[184]. <matplotlib.image.AxesImage at 0x2bdcaf8f0>



2. Apply filter and find edges for localization

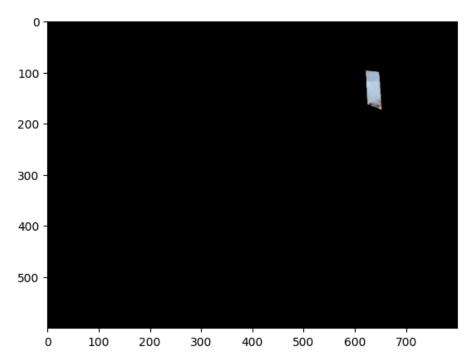
```
In [185...
bfilter = cv2.bilateralFilter(gray, 11, 17, 17) #Noise reduction
edged = cv2.Canny(bfilter, 10, 200) #Edge detection
plt.imshow(cv2.cvtColor(edged, cv2.COLOR_BGR2RGB))
```

Out[185]: <matplotlib.image.AxesImage at 0x30c4be060>

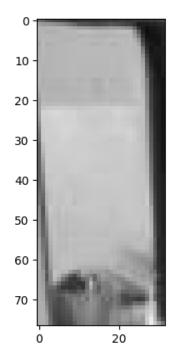


3. Find contours and apply masks

```
In [186...
         keypoints = cv2.findContours(edged.copy(), cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)
          contours = imutils.grab_contours(keypoints)
         contours = sorted(contours, key=cv2.contourArea, reverse=True)[:10]
In [187...
         location = None
          for contour in contours:
              approx = cv2.approxPolyDP(contour, 10, True)
              if len(approx) == 4:
                  location = approx
                  break
         location
In [188...
          array([[[622, 97]],
Out[188]:
                 [[625, 163]],
                 [[653, 173]],
                 [[647, 100]]], dtype=int32)
In [189... mask = np.zeros(gray.shape, np.uint8)
         new_image = cv2.drawContours(mask, [location], 0, 255, -1)
         new_image = cv2.bitwise_and(img, img, mask=mask)
         plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_BGR2RGB))
          <matplotlib.image.AxesImage at 0x3090696a0>
Out[189]:
```



Out[191]: <matplotlib.image.AxesImage at 0x29e223320>



4. Use Easy OCR to Read Text

```
In [192... reader = easyocr.Reader(['en'])
    result = reader.readtext(cropped_image)
    result

Out[192]: []
```

5. Render Result