In the grading of the exercises special attention will be paid to check that answers are substantiated and that the procedure of calculations is well documented. When results are achieved using a calculator or a pc it should be noted in the paper. All 6 problems are weighted equally in the grading. Your solution to the problem set can be written in Danish or English as you prefer.

# PROBLEM 1.

Let the matrix A and the vector  $\mathbf{b}$  be given by

$$A = \begin{bmatrix} 4 & 2 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & q \end{bmatrix} \text{ and } \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}.$$

1. Determine the values of q for which the equation  $A\mathbf{x} = \mathbf{b}$  is consistent.

Let B, C and D be invertible  $n \times n$  matrices.

2. Solve the following three equations for X.

(I) 
$$XBCD = I$$
, (II)  $CXB^{-1} = D$ , (III)  $XB - X = 2D$ .

### PROBLEM 2.

Assume it is requested to find the solution to the homogenous matrix equation  $A\mathbf{x} = \mathbf{0}$  for some unknown  $4 \times 4$  matrix. The augmented matrix has been row reduced and the result is

1. Find the solution of  $A\mathbf{x} = \mathbf{0}$ .

## PROBLEM 3.

Let the matrix A be given as

$$A = \left[ \begin{array}{ccc} 0 & -1 & -1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{array} \right].$$

1. Compute the characteristic equation.

The eigenvalues of A are  $\lambda_1 = \lambda_2 = 1$  and  $\lambda_3 = 2$ .

- 2. By hand, calculate the eigenvectors and find orthogonal bases for the eigenspaces.
- 3. Write the vector  $\mathbf{y} = \begin{bmatrix} 1 & 1 & 2 \end{bmatrix}^T$  as a linear combination of the eigenvectors for A.

#### PROBLEM 4.

For the statements given below, state whether they are true or false and justify your answer for each statement.

- 1.  $\mathbb{R}^2$  is a subspace of  $\mathbb{R}^3$ .
- 2. Every  $m \times n$  matrix has exactly m pivots.
- 3. An  $n \times n$  matrix with only real elements can have both real and complex eigenvalues.

## PROBLEM 5.

Consider the system  $\mathbf{x}_{k+1} = A\mathbf{x}_k + B\mathbf{u}_k$  with matrices

$$A = \begin{bmatrix} 1 & 2 & 2 \\ 1 & 2 & 1 \\ 2 & 1 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$$

and let  $\mathbf{x}_0 = \mathbf{0}$ .

- 1. Find the controllability matrix for the system and show that the system  $\mathbf{x}_{k+1} = A\mathbf{x}_k + B\mathbf{u}_k$ , is controllable.
- 2. Find control vectors  $\mathbf{u}_0$ ,  $\mathbf{u}_1$ ,  $\mathbf{u}_2$  that will force the system to  $\mathbf{y} = \begin{bmatrix} 66 \\ 56 \\ 41 \end{bmatrix}$ .

## PROBLEM 6.

Consider the following set of three equations with two unknowns.

$$\begin{array}{rcl}
 x_1 - 3x_2 &=& 2 \\
 2x_1 - & x_2 &=& -1 \\
 x_1 + & x_2 &=& 0
 \end{array}$$

- 1. Justify that the set of equations do not possess a solution.
- 2. Find a least squares solution of the system using a pseudoinverse.