Chapter 6.4

- 1. Set $\mathbf{v}_1 = \mathbf{x}_1$ and compute that $\mathbf{v}_2 = \mathbf{x}_2 \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \mathbf{x}_2 3\mathbf{v}_1 = \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix}$. Thus an orthogonal basis for W is $\left\{ \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} \right\}$.
- 3. Set $\mathbf{v}_1 = \mathbf{x}_1$ and compute that $\mathbf{v}_2 = \mathbf{x}_2 \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \mathbf{x}_2 \frac{1}{2} \mathbf{v}_1 = \begin{bmatrix} 3 \\ 3/2 \\ 3/2 \end{bmatrix}$. Thus an orthogonal basis for W is $\left\{ \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 3/2 \\ 3/2 \end{bmatrix} \right\}$.
- 7. Since $\|\mathbf{v}_1\| = \sqrt{30}$ and $\|\mathbf{v}_2\| = \sqrt{27/2} = 3\sqrt{6}/2$, an orthonormal basis for W is $\left\{ \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}, \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|} \right\} = \left\{ \begin{bmatrix} 2/\sqrt{30} \\ -5/\sqrt{30} \\ 1/\sqrt{30} \end{bmatrix}, \begin{bmatrix} 2/\sqrt{6} \\ 1/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix} \right\}.$
- **13.** Since A and Q are given, $R = Q^T A = \begin{bmatrix} 5/6 & 1/6 & -3/6 & 1/6 \\ -1/6 & 5/6 & 1/6 & 3/6 \end{bmatrix} \begin{bmatrix} 5 & 9 \\ 1 & 7 \\ -3 & -5 \\ 1 & 5 \end{bmatrix} = \begin{bmatrix} 6 & 12 \\ 0 & 6 \end{bmatrix}.$
- 17. a. False. Scaling was used in Example 2, but the scale factor was nonzero.
 - **b**. True. See (1) in the statement of Theorem 11.
 - c. True. See the solution of Example 4.

24. [M] Call the columns of the matrix \mathbf{x}_1 , \mathbf{x}_2 , \mathbf{x}_3 , and \mathbf{x}_4 and perform the Gram-Schmidt process on these vectors:

$$\mathbf{v}_1 = \mathbf{x}_1$$

$$\mathbf{v}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \mathbf{x}_2 - (-1)\mathbf{v}_1 = \begin{bmatrix} 3\\3\\-3\\0\\3 \end{bmatrix}$$

$$\mathbf{v}_3 = \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 = \mathbf{x}_3 - \left(-\frac{1}{2}\right) \mathbf{v}_1 - \left(-\frac{4}{3}\right) \mathbf{v}_2 = \begin{bmatrix} 6\\0\\6\\6\\0 \end{bmatrix}$$

$$\mathbf{v}_{4} = \mathbf{x}_{4} - \frac{\mathbf{x}_{4} \cdot \mathbf{v}_{1}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}} \mathbf{v}_{1} - \frac{\mathbf{x}_{4} \cdot \mathbf{v}_{2}}{\mathbf{v}_{2} \cdot \mathbf{v}_{2}} \mathbf{v}_{2} - \frac{\mathbf{x}_{4} \cdot \mathbf{v}_{3}}{\mathbf{v}_{3} \cdot \mathbf{v}_{3}} \mathbf{v}_{3} = \mathbf{x}_{4} - \frac{1}{2} \mathbf{v}_{1} - (-1) \mathbf{v}_{2} - \left(-\frac{1}{2}\right) \mathbf{v}_{3} = \begin{bmatrix} 0 \\ 5 \\ 0 \\ 0 \\ -5 \end{bmatrix}$$

Thus an orthogonal basis for *W* is
$$\left\{ \begin{bmatrix} -10 \\ 2 \\ -6 \\ 16 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 6 \\ -3 \end{bmatrix}, \begin{bmatrix} 6 \\ 0 \\ 5 \\ 0 \\ 0 \\ -5 \end{bmatrix} \right\}$$
.

25. [M] The columns of Q will be normalized versions of the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 found in Exercise 24. Thus

$$Q = \begin{bmatrix} -1/2 & 1/2 & 1/\sqrt{3} & 0 \\ 1/10 & 1/2 & 0 & 1/\sqrt{2} \\ -3/10 & -1/2 & 1/\sqrt{3} & 0 \\ 4/5 & 0 & 1/\sqrt{3} & 0 \\ 1/10 & 1/2 & 0 & -1/\sqrt{2} \end{bmatrix}, R = Q^{T}A = \begin{bmatrix} 20 & -20 & -10 & 10 \\ 0 & 6 & -8 & -6 \\ 0 & 0 & 6\sqrt{3} & -3\sqrt{3} \\ 0 & 0 & 0 & 5\sqrt{2} \end{bmatrix}$$

Chapter 6.5

1. To find the normal equations and to find \hat{x} , compute

$$A^{T} A = \begin{bmatrix} -1 & 2 & -1 \\ 2 & -3 & 3 \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 6 & -11 \\ -11 & 22 \end{bmatrix}; A^{T} \mathbf{b} = \begin{bmatrix} -1 & 2 & -1 \\ 2 & -3 & 3 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -4 \\ 11 \end{bmatrix}.$$

- **a.** The normal equations are $(A^T A)\mathbf{x} = A^T \mathbf{b} : \begin{bmatrix} 6 & -11 \\ -11 & 22 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -4 \\ 11 \end{bmatrix}$.
- **b.** Compute $\hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b} = \begin{bmatrix} 6 & -11 \\ -11 & 22 \end{bmatrix}^{-1} \begin{bmatrix} -4 \\ 11 \end{bmatrix} = \frac{1}{11} \begin{bmatrix} 22 & 11 \\ 11 & 6 \end{bmatrix} \begin{bmatrix} -4 \\ 11 \end{bmatrix} = \frac{1}{11} \begin{bmatrix} 33 \\ 22 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}.$
- 3. To find the normal equations and to find \hat{x} compute.

$$= \begin{bmatrix} 6 \\ -6 \end{bmatrix}. \qquad A^{T} A = \begin{bmatrix} 1 & -1 & 0 & 2 \\ -2 & 2 & 3 & 5 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 2 \\ 0 & 3 \\ 2 & 5 \end{bmatrix} = \begin{bmatrix} 6 & 6 \\ 6 & 42 \end{bmatrix}; A^{T} \mathbf{b} = \begin{bmatrix} 1 & -1 & 0 & 2 \\ -2 & 2 & 3 & 5 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ -4 \\ 2 \end{bmatrix}.$$

- **a**. The normal equations are $(A^T A)\mathbf{x} = A^T \mathbf{b} : \begin{bmatrix} 6 & 6 \\ 6 & 42 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6 \\ -6 \end{bmatrix}$.
- **b.** Compute $\hat{\mathbf{x}} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{b} = \begin{bmatrix} 6 & 6 \\ 6 & 42 \end{bmatrix}^{-1} \begin{bmatrix} 6 \\ -6 \end{bmatrix} = \frac{1}{216} \begin{bmatrix} 42 & -6 \\ -6 & 6 \end{bmatrix} \begin{bmatrix} 6 \\ -6 \end{bmatrix}.$ $= \frac{1}{216} \begin{bmatrix} 288 \\ -72 \end{bmatrix} = \begin{bmatrix} 4/3 \\ -1/3 \end{bmatrix}$
- 9. a. Because the columns \mathbf{a}_1 and \mathbf{a}_2 of A are orthogonal, the method of Example 4 may be used to find $\hat{\mathbf{b}}$, the orthogonal projection of \mathbf{b} onto Col A:

$$\hat{\mathbf{b}} = \frac{\mathbf{b} \cdot \mathbf{a}_1}{\mathbf{a}_1 \cdot \mathbf{a}_1} \mathbf{a}_1 + \frac{\mathbf{b} \cdot \mathbf{a}_2}{\mathbf{a}_2 \cdot \mathbf{a}_2} \mathbf{a}_2 = \frac{2}{7} \mathbf{a}_1 + \frac{1}{7} \mathbf{a}_2 = \frac{2}{7} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} + \frac{1}{7} \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

- b. The vector $\hat{\mathbf{x}}$ contains the weights which must be placed on \mathbf{a}_1 and \mathbf{a}_2 to produce $\hat{\mathbf{b}}$. These weights are easily read from the above equation, so $\hat{\mathbf{x}} = \begin{bmatrix} 2/7 \\ 1/7 \end{bmatrix}$.
- 17. **a.** True. See the beginning of the section. The distance from $A\mathbf{x}$ to \mathbf{b} is $||A\mathbf{x} \mathbf{b}||$.
 - **b**. True. See the comments about equation (1).
 - c. False. The inequality points in the wrong direction. See the definition of a least-squares solution.
 - d. True. See Theorem 13.
 - e. True. See Theorem 14.

Chapter 6.6

- 5. If two data points have different x-coordinates, then the two columns of the design matrix X cannot be multiples of each other and hence are linearly independent. By Theorem 14 in Section 6.5, the normal equations have a unique solution.
- **8**. **a**. The model that produces the correct least-squares fit is $\mathbf{y} = X\beta + \epsilon$ where

$$X = \begin{bmatrix} x_1 & x_1^2 & x_1^3 \\ \vdots & \vdots & \vdots \\ x_n & x_n^2 & x_n^3 \end{bmatrix}, \mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}, \boldsymbol{\beta} = \begin{bmatrix} \boldsymbol{\beta}_1 \\ \boldsymbol{\beta}_2 \\ \boldsymbol{\beta}_3 \end{bmatrix}, \text{ and } \boldsymbol{\epsilon} = \begin{bmatrix} \boldsymbol{\epsilon}_1 \\ \vdots \\ \boldsymbol{\epsilon}_n \end{bmatrix}$$

$$\begin{bmatrix} x_n & x_n^2 & x_n^3 \end{bmatrix} \quad \begin{bmatrix} y_n \end{bmatrix} \quad \begin{bmatrix} \beta_3 \end{bmatrix} \quad \begin{bmatrix} \epsilon_n \end{bmatrix}$$
b. [M] For the given data, $X = \begin{bmatrix} 4 & 16 & 64 \\ 6 & 36 & 216 \\ 8 & 64 & 512 \\ 10 & 100 & 1000 \\ 12 & 144 & 1728 \\ 14 & 196 & 2744 \\ 16 & 256 & 4096 \\ 18 & 324 & 5832 \end{bmatrix} \quad \begin{bmatrix} 1.58 \\ 2.08 \\ 2.5 \\ 3.1 \\ 3.4 \\ 3.8 \\ 4.32 \end{bmatrix}$, so
$$\hat{\boldsymbol{\beta}} = (X^T X)^{-1} X^T \mathbf{y} = \begin{bmatrix} .5132 \\ -.03348 \\ .001016 \end{bmatrix}$$
, and the least-squares curve is
$$y = .5132x - .03348x^2 + .001016x^3.$$

$$\hat{\boldsymbol{\beta}} = (X^T X)^{-1} X^T \mathbf{y} = \begin{bmatrix} .5132 \\ -.03348 \\ .001016 \end{bmatrix}, \text{ and the least-squares curve is}$$

$$y = .5132x - .03348x^2 + .001016x^3$$

10. a. The model that produces the correct least-squares fit is $y = X\beta + \epsilon$ where

$$X = \begin{bmatrix} e^{-.02(10)} & e^{-.07(10)} \\ e^{-.02(11)} & e^{-.07(11)} \\ e^{-.02(12)} & e^{-.07(12)} \\ e^{-.02(14)} & e^{-.07(14)} \\ e^{-.02(15)} & e^{-.07(15)} \end{bmatrix}, \mathbf{y} = \begin{bmatrix} 21.34 \\ 20.68 \\ 20.05 \\ 18.87 \\ 18.30 \end{bmatrix}, \beta = \begin{bmatrix} M_A \\ M_B \end{bmatrix}, \text{ and } \epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \end{bmatrix},$$

- **b.** [M] One computes that (to two decimal places) $\hat{\beta} = \begin{bmatrix} 19.94 \\ 10.10 \end{bmatrix}$, so the desired least-squares equation is $v = 19.94e^{-.02t} + 10.10e^{-.07t}$.
- 11. [M] The model that produces the correct least-squares fit is $y = X\beta + \epsilon$ where

[M] The model that produces the correct least-squares fit is
$$\mathbf{y} = X\beta + \epsilon$$
 where
$$X = \begin{bmatrix} 1 & 3\cos .88 \\ 1 & 2.3\cos 1.1 \\ 1 & 1.65\cos 1.42 \\ 1 & 1.25\cos 1.77 \\ 1 & 1.01\cos 2.14 \end{bmatrix}, \mathbf{y} = \begin{bmatrix} 3 \\ 2.3 \\ 1.65 \\ 1.25 \\ 1.01 \end{bmatrix}, \beta = \begin{bmatrix} \beta \\ e \end{bmatrix}, \text{ and } \epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \end{bmatrix}. \text{ One computes that (to two decimal } \epsilon_4 = \epsilon_5$$

places) $\hat{\beta} = \begin{bmatrix} 1.45 \\ .811 \end{bmatrix}$. Since e = .811 < 1 the orbit is an ellipse. The equation $r = \beta / (1 - e \cos \theta)$ produces r = 1.33 when $\vartheta = 4.6$.