A <u>vector space</u> is a set in which one can form <u>linear</u> combinations:

(subject to natural axioms.)

Example: Bessel Functions

$$B(z) = B_1 J_{\nu}(z) + B_2 N_{\nu}(z)$$

$$B(z) = B_{H+} H_{\nu}^{+}(z) + B_{-} H_{\nu}^{-}(z)$$

$$B(z) \iff \begin{pmatrix} B_1 \\ B_2 \end{pmatrix} \iff \begin{pmatrix} B_+ \\ B_- \end{pmatrix}$$

The set of Bessel functions of order v is naturally an abstract vector space.

A subset BCV is called a basis if it is

(a) linearly independent: $\alpha' b_1 + \cdots + \alpha'' b_n = 0$ $= \lambda' = \alpha^2 = \cdots = \alpha'' = 0$

(b) spans V:

every veV can be written
as a finite linear combination
of the vectors in B.

Thm: If V admits a finite basis B, then any other basis B' contains the same number of vectors as B.

Example: $\{J_{\nu}(z), N_{\nu}(z)\}$ and $\{H_{\nu}^{\pm}(z)\}$ are both bases for the Bessel functions of order ν .

The number of elements in a basis B is called the <u>dimension</u> of a vector space V.

Change of Basis

Let B and B be two buses for a vector space V.

=> bB = \(\gamma \alpha \B = \basis

ba = \(\bar{B} \bar{A} \bar{B} \arprox \bar{B} = basis

We can write this in matrix form:

$$(\overline{b}_1 \cdots \overline{b}_n) = (b_1 \cdots b_n) \begin{pmatrix} \lambda'_1 \cdots \lambda'_n \\ \vdots & \vdots \\ \lambda''_1 \cdots \lambda''_n \end{pmatrix}$$

1 = change-of-basis matrix

Example:

$$\left(H_{\nu}^{+} H_{\nu}^{-}\right) = \left(\mathcal{J}_{\nu} N_{\nu}\right) \begin{pmatrix} 1 & 1 \\ \vdots & -i \end{pmatrix}$$

$$(J_{\nu} N_{\nu}) = (H_{\nu}^{+} H_{\nu}) \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

Note:
$$\tilde{\Lambda} = \Lambda^{-1}$$
 (why?)

A map 4: V > W is called linear if it commutes with the formation of linear combinations:

$$9(x_1V_1+x_2V_2)=x_19(v_1)+x_29(v_2)$$

sum in V sum in W

If we choose bases B on V and c on W, we can write g(v) = g(Evxba) expansion of g(ba) EW = E V x y (bx) / = I vd [I y B a CB]

matrix

= I y B a V CB representation $= (c_1 \cdots c_m) \begin{pmatrix} g'_1 \cdots g'_n \\ \vdots \\ g''_n \cdots g''_n \end{pmatrix} \begin{pmatrix} v' \\ \vdots \\ v'' \end{pmatrix}$

Dual Basis

V, basis $B = \{b_{\alpha}\}$ $A = \{b_{\alpha}\}$

Given bases B for V

and W C for W, we

naturally get a basis

for vector space Hom(V, W)

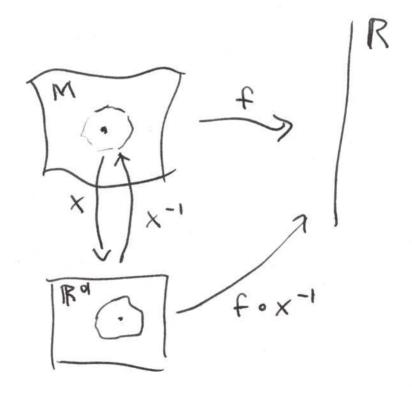
of linear & **: V > W

 $g(v) = \sum_{AB} g^{B}_{A} v^{A} C_{B}$ $\chi^{A}(v)$

ZyBa(compa)(v)= I csyBana(V)

Manifolds

A differentiable manifold is a set on which one can identify the smooth functions.



Adjoint Map

Suppose 9:V > W is linear.

Define 9*:W* > V*

9*(5)(V):=5(9(V))

1
6W*

Riemann tenson E V*&V*&V*&V

Rabo

Space of linear maps V >W is itself a vector space. (x, 9, + xz 92) (V) := x, 8, (V) + 22 82(V) my Dual Space V* = linear maps w: V > F $\omega(v_1) = 0 = \omega(v_2)$ W(X, V, +xzV2) = d, w(v,) + xz w(vz) = 0 Au:= {v|w(v)=1} AZW := {V | ZW(V)=13 = {V | w(v)=== }