

gravitación

#1

- 1) la acción puede considerarse como el camino λ que toma, específicamente el largo de ese camino.

$$A(r) = \left(1 - \frac{r_s}{r}\right)$$

$$S = \int \sqrt{ds^2} = \int ds = \int \frac{ds}{d\lambda} d\lambda$$

donde

$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu = A(r) dt^2 - \frac{dr^2}{A(r)} - r^2 d\Omega^2$$

y del punto de vista relativo al cuerpo que toma el camino λ

$$ds^2 = c^2 d\tau^2 \rightarrow \frac{d\tau}{d\lambda} = \frac{1}{c} \frac{ds}{d\lambda} \quad \text{chain rule}$$

$$\left(\frac{d\tau}{d\lambda}\right)^2 = \frac{1}{2} g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda}$$

ya que la partícula está libre, seguirá el camino más corto en el espacio tiempo curvado; siendo $\lambda = \tau$ (tiempo propio)

$$S = \frac{E_0}{c} \int \left[g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \right]^{1/2} d\tau = \frac{E_0}{c} \int \left[g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu \right]^{1/2} d\tau$$

Podemos multiplicar la acción por E de manera que sea una constante que añada las unidades correctas (energía · tiempo)

así $S = \int L dt \Rightarrow$ el Lagrangiano

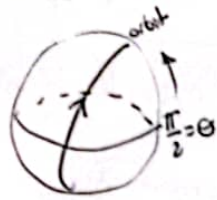
$$L = \frac{E_0}{c} \left[\left(1 - \frac{r_s}{r}\right) c^2 (\dot{t})^2 - \frac{(\dot{r})^2}{\left(1 - \frac{r_s}{r}\right)} - r^2 (\dot{\theta})^2 - r^2 \sin^2 \theta (\dot{\phi})^2 \right]^{1/2}$$

$$L = \frac{E_0}{c} \left[g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu \right]^{1/2}$$

explorando las cantidades conservadas.

#2

ya que la métrica de Schwarzschild viene de simetría esférica
al M no rota



siempre será posible rotar nuestro
sistema de coord. para que el mov.
ocurra en el plano $\theta = \frac{\pi}{2}$.

$$\therefore (\dot{\theta})^2 = \left(\frac{d\theta}{dz}\right)^2 = 0 \quad ; \quad \sin^2 \theta = \left(\sin \frac{\pi}{2}\right)^2 = 1$$

así el Lagrangiano

$$h = \frac{\epsilon_0}{c} \left[(1 - \frac{r_s}{r}) c^2 (\dot{t})^2 - \frac{(\dot{r})^2}{1 - \frac{r_s}{r}} - r^2 (\dot{\phi})^2 \right]^{1/2} = \frac{\epsilon_0}{c} \left[\underbrace{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu}_T \right]^{1/2}$$

$$h = \frac{\epsilon_0}{c} T^{1/2} \quad ; \quad \text{asea que} \quad \frac{\partial h}{\partial q} = \frac{\epsilon_0}{c} \frac{1}{2\sqrt{T}} \frac{\partial T}{\partial q}$$

$$\text{y usando un truco} \quad \sqrt{T} = \sqrt{g_{\mu\nu} \frac{dx^\mu}{dz} \frac{dx^\nu}{dz}} = \sqrt{c^2 \frac{dz}{dz} \frac{dz}{dz}} = c \left(\text{objetos masivos} \right)$$

por tanto para
particular sin masa
el Lagrangiano y acción

$$\rightarrow = \sqrt{0} \quad \left(\text{particular sin masa} \right)$$

$$S = \frac{\epsilon_0}{c} \int \left[g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \right]^{1/2} d\lambda$$

$$; \quad h = \frac{\epsilon_0}{c} \left[g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \right]^{1/2}$$

caso partícula masiva.

#3

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) - \frac{\partial L}{\partial q} = 0$$

las cantidades conservadas son aquellas q
son $\frac{\partial L}{\partial q} = 0 \rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0 \rightarrow \frac{\partial L}{\partial \dot{q}} = \text{cte}$

$$\text{siendo } L = \frac{e_0}{c} \left[A(r) c^2 \dot{t}^2 - \frac{\dot{r}^2}{A(r)} - r^2 \dot{\phi}^2 \right]^{\frac{1}{2}} = f[r, \dot{t}, \dot{r}, \dot{\phi}]$$

no hay t o ϕ

$$\rightarrow \therefore \frac{\partial L}{\partial t} = 0 \Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{t}} \right) = 0 \rightarrow \frac{\partial L}{\partial \dot{t}} = \frac{e_0}{c} \left[A(r) c^2 \dot{t} \right]^{\frac{1}{2}} \frac{1}{\sqrt{T}}$$

$$\frac{\partial L}{\partial \dot{t}} = \frac{e_0 c A(r) \dot{t}}{\sqrt{T}} \quad | \quad \sqrt{T} = \sqrt{c^2} = c \Rightarrow \frac{\partial L}{\partial \dot{t}} = \frac{e_0 c}{c} \left(1 - \frac{v^2}{c^2} \right)^{\frac{1}{2}} \dot{t} = \text{cte.}$$

$$\frac{e_0}{c} \text{ estab en } \text{onkel} \text{ asi que ignorables} \therefore \boxed{c \left(1 - \frac{v^2}{c^2} \right)^{\frac{1}{2}} \dot{t} = E} \quad | \quad \text{ya que } \dot{t} = \frac{dt}{d\tau} = \gamma$$

$$\lim_{v \rightarrow 0} c \gamma \left(1 - \frac{v^2}{c^2} \right) = c \gamma = \frac{mc \gamma}{m} = \frac{E}{m} = E$$

$$\rightarrow \text{otra cantidad conservada } \frac{\partial L}{\partial \phi} = 0 \rightarrow \frac{\partial L}{\partial \dot{\phi}} = \text{cte} = \frac{e_0}{c} \frac{1}{2c} \frac{\partial T}{\partial \dot{\phi}} = \frac{e_0}{c} \frac{1}{2c} (-2r^2 \dot{\phi}) = \text{cte.}$$

$$-\frac{e_0}{c^2} (r^2 \dot{\phi}) = \text{cte} \Rightarrow \boxed{r^2 \dot{\phi} = L} \quad \text{igual que el momento angular clasico.}$$

caso sin masa

para partículas sin masa; considerar $\dot{q} = \frac{dq}{d\lambda}$ y
estos resultados de cantidades conservadas aplican igual.

ecuaciones de movimiento.

#9

$$\left(\frac{ds}{d\lambda}\right)^2 = \left(1 - \frac{r_s}{r}\right) \left(\frac{dct}{d\lambda}\right)^2 - \frac{1}{\left(1 - \frac{r_s}{r}\right)} \left(\frac{dr}{d\lambda}\right)^2 - r^2 \left(\frac{d\phi}{d\lambda}\right)^2$$

$$\text{con } \mathcal{E} = \left(1 - \frac{r_s}{r}\right) \frac{dct}{d\lambda} = c \left(1 - \frac{r_s}{r}\right) \frac{dt}{d\lambda} \rightarrow \frac{d(ct)}{d\lambda} = \mathcal{E} \frac{1}{\left(1 - \frac{r_s}{r}\right)}$$

$$L = r^2 \frac{d\phi}{d\lambda} \rightarrow \frac{d\phi}{d\lambda} = \frac{L}{r^2}$$

$$\left(\frac{ds}{d\lambda}\right)^2 = \left(1 - \frac{r_s}{r}\right) \frac{\mathcal{E}^2}{\left(1 - \frac{r_s}{r}\right)^2} - \frac{1}{\left(1 - \frac{r_s}{r}\right)} \left(\frac{dr}{d\lambda}\right)^2 - r^2 \left(\frac{L^2}{r^4}\right)$$

$$\left(\frac{ds}{d\lambda}\right)^2 = \frac{\mathcal{E}^2}{\left(1 - \frac{r_s}{r}\right)} - \frac{\left(\frac{dr}{d\lambda}\right)^2}{\left(1 - \frac{r_s}{r}\right)} - \frac{L^2}{r^2} \quad (*) \quad / \cdot \left(1 - \frac{r_s}{r}\right)$$

para partículas masivas $\lambda \rightarrow \tau$; $ds^2 = c^2 d\tau^2 \rightarrow \left(\frac{ds}{d\tau}\right)^2 = c^2$

$$c^2 \left(1 - \frac{r_s}{r}\right) = \mathcal{E}^2 - \left(\frac{dr}{d\tau}\right)^2 - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right)$$

$$\left(\frac{dr}{d\tau}\right)^2 = \mathcal{E}^2 - c^2 + \frac{c^2 r_s}{r} - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right)$$

es
movimiento
part. masiva

Partículas sin masa $ds^2 = 0$

$$0 = \mathcal{E}^2 - \left(\frac{dr}{d\lambda}\right)^2 - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right)$$

$$\left(\frac{dr}{d\lambda}\right)^2 = \mathcal{E}^2 - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right)$$

es movimiento
partículo sin masa

ahora a reducirlo al problema unidimensional equivalente para dlo

(#5)

$$\frac{dr}{d\lambda} = \frac{dr}{d\phi} \frac{d\phi}{d\lambda} \quad \text{con} \quad \frac{d\phi}{d\lambda} = \frac{L}{r^2}$$

$$\rightarrow \left(\frac{dr}{d\phi}\right)^2 \left(\frac{d\phi}{d\lambda}\right)^2 = \left(\frac{dr}{d\phi}\right)^2 \left(\frac{L}{r^2}\right)^2 = (\varepsilon^2 - c^2) + \frac{c^2 r_s}{r} - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right)$$

$$\left(\frac{dr}{d\phi}\right)^2 = \frac{r^4}{L^2} (\varepsilon^2 - c^2) + \frac{r^3 c^2 r_s}{L^2} - r^2 \left(1 - \frac{r_s}{r}\right)$$

Probl 1D
part. masiva.

esta ecuación ya es útil para resolver el problema.

si se gusta es posible derivar 1 vez extra, $\therefore \frac{d}{d\phi}()$

$$2 \left(\frac{dr}{d\phi}\right) \frac{d^2 r}{d\phi^2} = \left(\frac{4r^3}{L^2} (\varepsilon^2 - c^2) + 3 \frac{r^2 c^2 r_s}{L^2} - 2r + r_s\right) \left(\frac{dr}{d\phi}\right)$$

$$\frac{d^2 r}{d\phi^2} = \frac{2r^3}{L^2} (\varepsilon^2 - c^2) + \frac{3}{2} \frac{r^2 c^2 r_s}{L^2} - r + \frac{r_s}{2}$$

este es útil
para simulaciones
y considerese
un extra.

caso sin masa

$$\left(\frac{dr}{d\phi}\right)^2 = \frac{r^4}{L^2} \left(\varepsilon^2 - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right)\right) = \frac{r^4 \varepsilon^2}{L^2} - r^2 \left(1 - \frac{r_s}{r}\right)$$

$$\left(\frac{dr}{d\phi}\right)^2 = \frac{r^4}{L^2} \varepsilon^2 - r^2 \left(1 - \frac{r_s}{r}\right)$$

Probl 1D
part. sin masa.

y como extra. derivando

$$2 \left(\frac{dr}{d\phi}\right) \frac{d^2 r}{d\phi^2} = \left(4 \frac{r^3 \varepsilon^2}{L^2} - 2r + r_s\right) \left(\frac{dr}{d\phi}\right) \Rightarrow \left(\frac{d^2 r}{d\phi^2}\right) = \frac{2r^3 \varepsilon^2}{L^2} - r + \frac{r_s}{2}$$

1b) Partícula Masiva

(A6)

c) encuentre y grafique el potencial efectivo.

$$\left(\frac{dr}{d\tau}\right)^2 = \varepsilon^2 - c^2 + c^2 \frac{r_s}{r} - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right) \quad / \cdot \frac{1}{2} m$$

$$\frac{1}{2} m \left(\frac{dr}{d\tau}\right)^2 = \frac{1}{2} m \dot{r}^2 = \frac{1}{2} m (\varepsilon^2 - c^2) + \frac{1}{2} m \frac{c^2 r_s}{r} - \frac{1}{2} \frac{L^2 m}{r^2} \left(1 - \frac{r_s}{r}\right)$$

$$m\varepsilon^2 = m\left(\frac{E}{m}\right)^2 = \frac{E^2}{m} \quad ; \quad mc^2 \text{ unidades de energía también} \quad ; \quad \frac{1}{2} m (\varepsilon^2 - c^2) = (\tilde{E})$$

$$\frac{1}{2} m \dot{r}^2 + m \left(\underbrace{-\frac{c^2 r_s}{2r} + \frac{L^2}{2r^2} \left(1 - \frac{r_s}{r}\right)}_{\text{Potencial efectivo relativista}} \right) = (\tilde{E})$$

interpreta como una const. ~ energía

energía cinética

$$\left\{ r_s = \frac{2GM}{c^2} \right\}$$

$$\boxed{V_{eff}[r] = -\frac{GM}{r} + \frac{L^2}{2r^2} - \frac{L^2 GM}{c^2 r^3}}$$

relativistic

$$\boxed{V_{eff}[r] = -\frac{c^2 r_s}{2r} + \frac{L^2}{2r^2} \left(1 - \frac{r_s}{r}\right)}$$

$$\left\{ L = r^2 \dot{\phi} = \frac{d}{dt} \right.$$

momento angular por unidad de masa

donde el Newt. $\Rightarrow V_{eff}[r] = -\frac{GM}{r} + \frac{L^2}{2r^2}$ comparandolo

si $\lim_{c \rightarrow \infty} V_{eff}[r] = \lim_{c \rightarrow \infty} \left(-\frac{GM}{r} + \frac{L^2}{2r^2} - \frac{L^2 GM}{c^2 r^3} \right) = -\frac{GM}{r} + \frac{L^2}{2r^2} = V_{eff}^{Newt}[r]$

// $\lim_{c \rightarrow \infty} \frac{1}{c} = 0$; o sea $-\frac{L^2 GM}{c^2 r^3}$ es la corrección relativista y es importante a r pequeños (mercurio o j)

gráfica del potencial efectivo relativista.

#7

veamos los puntos de estabilidad e inestabilidad, donde $\left. \frac{dV_{\text{eff}}}{dr} \right|_{r=r^*} = 0$

$$\frac{d}{dr} V_{\text{eff}} = \frac{GM}{r^2} - \frac{2}{2} \frac{L^2}{r^3} + \frac{3L^2 GM}{c^2 r^4} = \frac{GM}{r^2} - \frac{L^2}{r^3} + \frac{3L^2 GM}{c^2 r^4} = 0 \quad / \cdot r^4$$

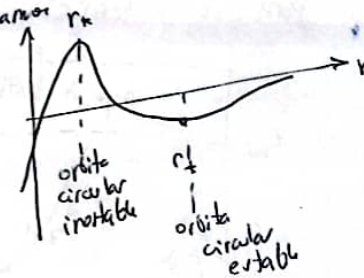
$$r^2 GM - r L^2 + \frac{3L^2 GM}{c^2} = 0 \quad \text{es cuadrática}$$

$$r_* = \left(L^2 \pm \sqrt{L^4 - 4GM \cdot \frac{3L^2 GM}{c^2}} \right) \frac{1}{2GM} = \frac{L^2}{2GM} \pm \frac{L^2}{2GM} \sqrt{1 - \frac{12GM^2}{L^2 c^2}}$$

$$r_* = \frac{L^2}{2GM} \left(1 \pm \sqrt{1 - \frac{12GM^2}{L^2 c^2}} \right) ;$$

si graficamos

V_{eff}

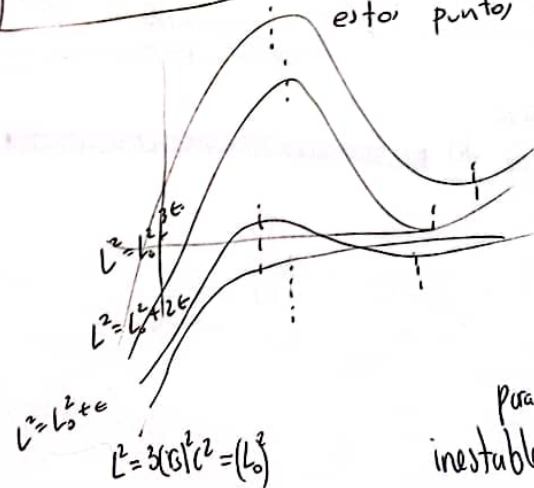


ocurre que los dos r_* se juntan

$$\text{si: } 1 - \frac{12GM^2}{L^2 c^2} = 0 \Rightarrow L^2 = \frac{12GM^2}{c^2} = 3 \left(\frac{GM}{c^2} \right)^2 c^2$$

$$L^2 = 3(r_s)^2 c^2$$

por tanto para $L^2 > 3(r_s)^2 c^2$ tendríamos estos puntos separados.



boceto de distintos potenciales efectivos variando el momento angular.

para $L^2 = 3(r_s)^2 c^2$ es altamente inestable y si $r \neq \frac{L^2}{2GM}$ la partícula caerá.

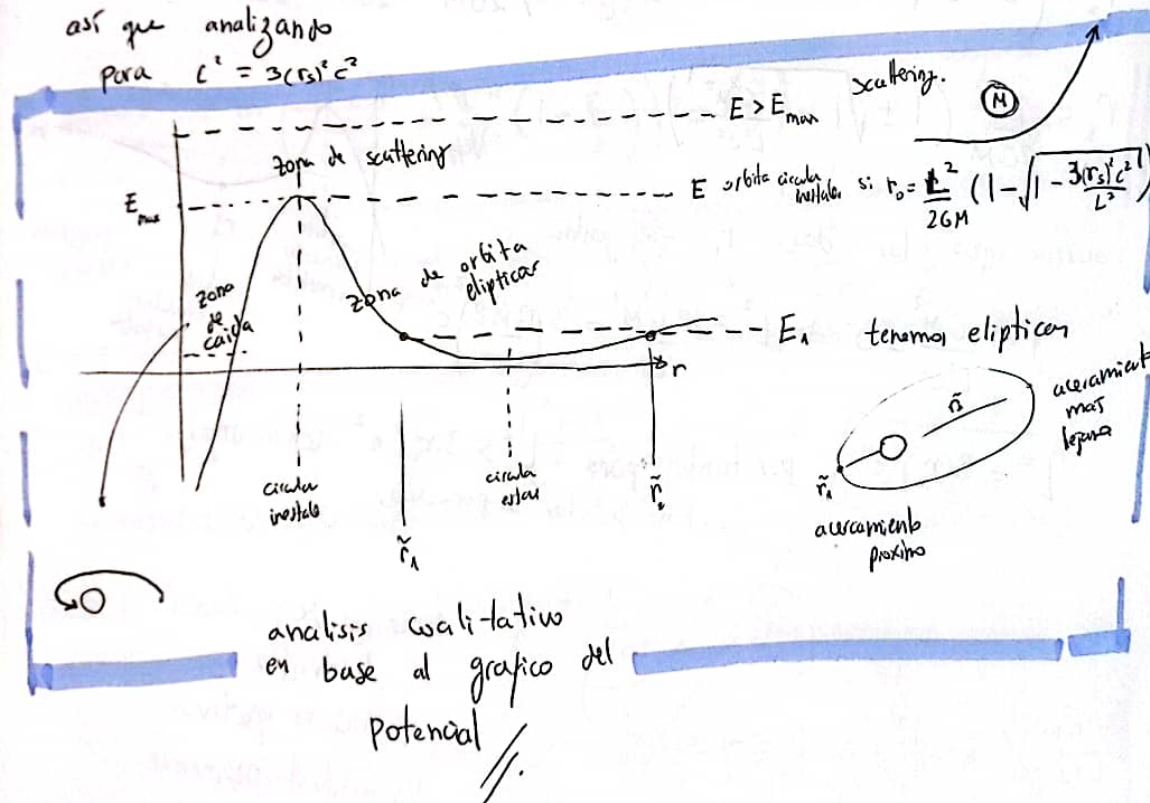
la órbita ~~estable~~ con $L^2 = 3(r_s)^2 c^2$ el radio de la órbita
 circular es $r_* = \frac{L^2}{2GM} (1 + \sqrt{1}) = \frac{3(r_s)^2 c^2}{2GM} = \frac{3(r_s)^2}{r_s} = 3r_s$

#8

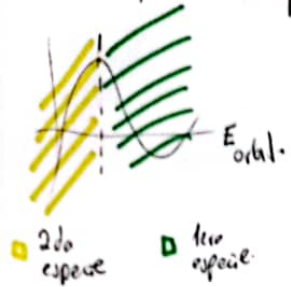
esta es la órbita circular más pequeña, pues mayores
 valores de $L^2 > 3(r_s)^2 c^2$ producen mayor r_* .

$r_* = 3r_s$ es llamada la órbita estable más cercana
 o "inner most stable orbit" $r_h = r_{isco} = 3r_s$.

así que analizando
 para $L^2 = 3(r_s)^2 c^2$



Ab)-II) determinar y graficar orbitas de primera y 2da especie. (#9)
 Para orbitas planetarias, para ello comenzando con



$$E^2 = \varepsilon^2 - c^2$$

$$\left(\frac{dr}{d\phi}\right)^2 = \frac{r^4}{L^2} (\varepsilon^2 - c^2) + \frac{r^3 c^2 r_s}{L^2} - r^2 \left(1 - \frac{r_s}{r}\right)$$

$$= \frac{r^4}{L^2} \left\{ E^2 + \frac{c^2 r_s}{r} - \frac{L^2}{r^2} \left(1 - \frac{r_s}{r}\right) \right\}$$

$$= r^4 \left\{ \left(\frac{E}{L}\right)^2 + \frac{c^2 r_s}{L^2 r} - \frac{1}{r^2} \left(1 - \frac{r_s}{r}\right) \right\}$$

$b = \frac{L}{E}$ parametro de impacto. $\left\{ \left(\frac{dr}{d\phi}\right)^2 = r^4 \left\{ \frac{1}{b^2} + \frac{c^2 r_s}{L^2 r} - \frac{1}{r^2} + \frac{r_s}{r^3} \right\} \right.$

luego hacemos aparecer un polinomio $= \frac{r^4}{b^2} \left\{ 1 + \frac{b^2 c^2 r_s}{L^2 r} - \frac{b^2}{r^2} + \frac{b^2 r_s}{r^3} \right\}$
 $\left\{ \frac{b^2}{L^2} = \frac{1}{E^2} \right.$

$$\left(\frac{dr}{d\phi}\right)^2 = \frac{r^4}{b^2} \left(\frac{1}{r^3}\right) \left\{ r^3 + r^2 \frac{c^2 r_s}{E^2} - b^2 r^2 + b^2 r_s \right\}$$

$$r^3 + r^2 \beta - b^2 r + b^2 r_s = P_3[r].$$

las raices del polinomio representan puntos donde $\frac{dr^2}{d\phi^2} = 0$
 sea orbitas circulares,

podemos usar el metodo de Cardano $P_3(r) = (r-r_0)(r-r_1)(r-r_2)$

$$r^3 + \beta r^2 - b^2 r + b^2 r_s = 0 \quad / \text{buscamos las raíces usando método Cardano}$$

#10

substituyendo $z = \frac{r}{3} = \frac{r}{3}$ $\left\{ \begin{aligned} \left(z - \frac{\beta}{3}\right)^3 + \beta \left(z - \frac{\beta}{3}\right)^2 - b^2 \left(z - \frac{\beta}{3}\right) + b^2 r_s = 0 \end{aligned} \right.$

$\Rightarrow z^3 - z \left(b^2 + \frac{\beta^2}{3}\right) + \left(b^2 r_s + \frac{b^2 \beta}{3} + \frac{2\beta^3}{27}\right) = 0 \quad \Rightarrow z^3 + zp + q = 0$ forma canónica

$$p = -\frac{3b^2 + \beta^2}{3} \quad ; \quad q = \frac{27b^2 r_s + 9b^2 \beta + 2\beta^3}{27}$$

$$4z^3 - \frac{4}{3}(3b^2 + \beta^2)z + \frac{4}{27}[b^2(27r_s + 9\beta) + 2\beta^3] = 0 \quad | \text{forma canónica}$$

$$4z^3 - g_2 z + g_3 = 0 \quad \neq \text{Identidad} \quad 4\sin^3\theta - 3\sin\theta + \sin 3\theta = 0 \quad (*)$$

$\therefore z = w \sin\theta$ e incluyendo un multiplicador de Lagrange.

$$\lambda 4w^3 \sin^3\theta - g_2 \lambda w \sin\theta + \lambda g_3 = 0 \quad \text{comparando a } (*)$$

$$\lambda w^3 = 1 \rightarrow \boxed{\lambda = \frac{1}{w^3}} ; \quad g_2 \lambda w = 3 \rightarrow g_2 \frac{w}{w^3} = g_2 \frac{1}{w^2} = 3 \Rightarrow \boxed{w = \sqrt{\frac{g_2}{3}}}$$

$$\lambda g_3 = \sin 3\theta \rightarrow \frac{1}{w^3} g_3 = \left(\frac{3}{g_2}\right)^{\frac{3}{2}} g_3 = \sin 3\theta$$

$$\lambda g_3 = \sin 3\theta \rightarrow \frac{1}{W^3} g_3 = \left[\left(\frac{3}{g_2} \right)^{\frac{3}{2}} g_3 = \sin 3\theta \right]$$

en general $\sin(3\theta \pm 2n\pi) = g_3 \left(\frac{3}{g_2} \right)^{\frac{3}{2}} \Rightarrow 3\theta = \text{ArcSin} \sqrt{\frac{27(g_3)^2}{(g_2)^3}} + 2n\pi$

$$\theta = \frac{1}{3} \text{ArcSin} \sqrt{\frac{27(g_3)^2}{(g_2)^3}} + \frac{2n\pi}{3} = \theta_0 + \frac{2n\pi}{3} \quad \left| \text{luego. } g_2 = \frac{4}{3} (3b^2 + \beta^2) \right.$$

$$g_3 = \frac{4}{27} [b^2(27r_s + 9\beta) + 2\beta^2]$$

$$W = \sqrt{\frac{4}{9} (3b^2 + \beta^2)} = \frac{2}{3} \sqrt{3b^2 + \beta^2} //$$

$$\theta_0 = \frac{1}{3} \text{ArcSin} \sqrt{\frac{27 \cdot (g_3)^2}{(g_2)^3}} = \frac{1}{3} \text{ArcSin} \left[\frac{1}{2} \sqrt{\frac{(2\beta^2 + 9b^2(3r_s + \beta))^2}{(3b^2 + \beta^2)^3}} \right] = \frac{1}{3} \text{ArcSin} \left[\frac{(2\beta^2 + 9b^2(3r_s + \beta))}{2(3b^2 + \beta^2)^{\frac{3}{2}}} \right]$$

y usando $\sin \left[\alpha + n\frac{2\pi}{3} \right] = \sin \alpha \cos \left[n\frac{2\pi}{3} \right] + \sin \left[n\frac{2\pi}{3} \right] \cos \alpha$

$$\cos \left[\frac{2\pi}{3} \right] = -\frac{1}{2} \quad ; \quad \sin \left[\frac{2\pi}{3} \right] = \frac{\sqrt{3}}{2} \quad ; \quad \sin \left[\frac{4\pi}{3} \right] = -\frac{\sqrt{3}}{2}$$

$$\cos[0] = 1 \quad ; \quad \sin[0] = 0 \quad ; \quad \cos \left[\frac{4\pi}{3} \right] = -\frac{1}{2}$$

$$\left(\frac{dr}{d\phi}\right)^2 = \frac{r^4}{b^2} \left(\frac{1}{r^3} P_3(r)\right)$$

ecuación
de movimiento

#11
#10.6

$$P_3(r) = r^3 + r^2\beta + b^2r + b^2r_3$$

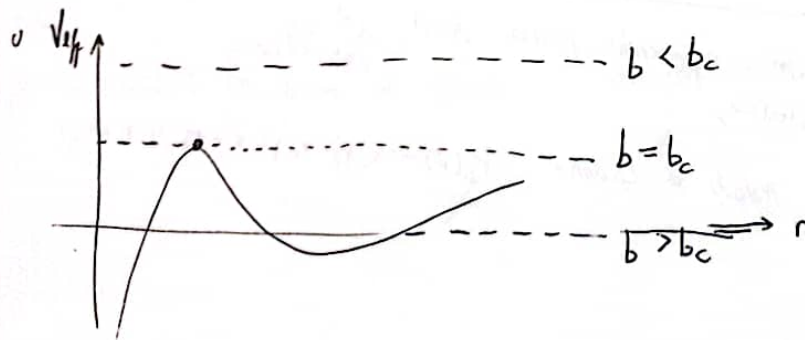
$$= (r - r_0)(r - r_1)(r - r_2)$$

donde $b = \frac{L}{E}$ o sea a menor energía mayor b
y a mayor energía menor b . ; $\beta = \frac{c^2 r_s}{E^2}$

Podemos entonces ; donde $\frac{\beta}{b} = \frac{c^2 r_s}{E^2} \frac{E}{L} = \frac{c^2 r_s}{EL} = \alpha^2$

$$\Theta_0 = \frac{1}{3} \text{ArcSin} \left[\frac{2\beta^2 + 9b^2(3r_s + \beta)}{2(3b^2 + \beta^2)^{3/2}} \right] = \frac{1}{3} \text{ArcSin} \left[\frac{2\beta^2 + 9b^2(3r_s + \beta)}{2b^3 \left(3 + \frac{\beta^2}{b^2}\right)^{3/2}} \right]$$

$$= \frac{1}{3} \text{ArcSin} \left[\frac{b^2}{b^3} \cdot \frac{2\frac{\beta^2}{b^2} + 9(3r_s + \beta)}{2\left(3 + \frac{\beta^2}{b^2}\right)^{3/2}} \right] = \frac{1}{3} \text{ArcSin} \left[\frac{1}{b} \cdot \underbrace{\frac{2\alpha^2 + 9(3r_s + \beta)}{2(3 + \alpha^2)^{3/2}}}_{b_c} \right]$$



soluciones
 $n \in \mathbb{Z}$
 $n \in \{0, 1, 2\}$

$$Z_n = W \sin\left[\theta + n\frac{2\pi}{3}\right] = \frac{2}{3} \sqrt{3b^2 + \beta^2} \left(\sin\theta_0 \cos\left(\frac{2n\pi}{3}\right) + \sin\left(\frac{2n\pi}{3}\right) \cos\theta_0 \right) \quad \#(1)$$

devolviendo el cambio: $r_n = Z_n - \frac{\beta}{3}$; $\beta = \frac{c^2 r_3}{E^2}$; $b = \frac{L}{E}$

con $\theta_0 = \frac{1}{3} \text{ArcSin}\left[\frac{2\beta^2 + 9b^2(3\beta + \beta)}{2(3b^2 + \beta^2)^{3/2}}\right] = \frac{1}{3} \text{ArcSin}\left[\frac{1}{b} \frac{2\beta^2 + 9(3\beta + \beta)}{2(3 + \frac{\beta^2}{b^2})^{3/2}}\right]$

$$r_0 = \frac{2}{3} \sqrt{3b^2 + \beta^2} \sin\theta_0 - \frac{\beta}{3}$$

$$r_1 = \frac{2}{3} \sqrt{3b^2 + \beta^2} \left(-\frac{1}{2} \sin\theta_0 + \frac{\sqrt{3}}{2} \cos\theta_0\right) - \frac{\beta}{3}$$

$$r_2 = \frac{2}{3} \sqrt{3b^2 + \beta^2} \left(-\frac{1}{2} \sin\theta_0 - \frac{\sqrt{3}}{2} \cos\theta_0\right) - \frac{\beta}{3}$$

raíces del polinomio.

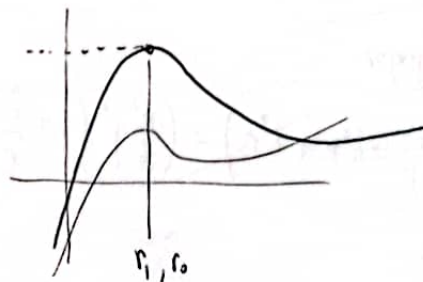
en el caso especial donde $b = b_c \rightarrow \theta_0 = \frac{1}{3} \text{ArcSin}(1) = \frac{1}{3} \frac{\pi}{2} = \frac{\pi}{6}$

$$r_0 = \frac{2}{3} \sqrt{3b_c^2 + \beta^2} \cdot \sin\frac{\pi}{6} - \frac{\beta}{3} = \frac{1}{3} \sqrt{3b_c^2 + \beta^2} - \frac{\beta}{3}$$

$$r_1 = \frac{2}{3} \sqrt{3b_c^2 + \beta^2} \left(-\frac{1}{4} + \frac{\sqrt{3}}{2} \cdot \frac{\sqrt{3}}{2}\right) - \frac{\beta}{3} = \frac{2}{3} \sqrt{3b_c^2 + \beta^2} \left(\frac{1}{2}\right) - \frac{\beta}{3} = r_0$$

solución repetida.

$$r_2 = \frac{2}{3} \sqrt{3b_c^2 + \beta^2} \left(-\frac{1}{4} - \frac{3}{4}\right) - \frac{\beta}{3} = -\frac{2}{3} \sqrt{3b_c^2 + \beta^2} - \frac{\beta}{3} < 0$$



solución o raíz negativa.
 sin significado físico en este caso.

$$\left(\frac{dr}{d\phi}\right)^2 = \left(\frac{r^2}{b}\right)^2 \left(\frac{(r-r_0)(r-r_1)(r-r_2)}{r^3} \right) \quad \begin{array}{l} \text{eq de} \\ \text{movimiento} \end{array} \quad \#12$$

entonces con el cambio y raíz.

$$u = \frac{1}{r} \quad ; \quad du = -\frac{dr}{r^2} \quad dr = -du \cdot r^2 = -\frac{du}{u^2} \quad \rightarrow \quad \frac{dr}{d\phi} = -\frac{1}{u^2} \frac{du}{d\phi}$$

$$\frac{dr}{d\phi} = \pm \frac{r^2}{b} \sqrt{\frac{(r-r_0)(r-r_1)(r-r_2)}{r^3}} \quad \rightarrow \quad -\frac{1}{u^2} \frac{du}{d\phi} = \pm \frac{1}{u^2} \frac{1}{b} \sqrt{u^3 \left(\frac{1}{u} - \frac{1}{u_0}\right) \left(\frac{1}{u} - \frac{1}{u_1}\right) \left(\frac{1}{u} - \frac{1}{u_2}\right)}$$

$$\rightarrow \frac{du}{d\phi} = \mp \frac{1}{b} \sqrt{u^3 \left(\frac{1}{u} - \frac{1}{u_0}\right) \left(\frac{1}{u} - \frac{1}{u_1}\right) \left(\frac{1}{u} - \frac{1}{u_2}\right)}$$

raíz negativa
ligado a r_2 .

$$\frac{du}{d\phi} = \mp \frac{1}{b} \sqrt{u^3 \frac{(u_0 - u)}{u u_0} \frac{(u_1 - u)}{u u_1} \frac{(u_2 + u)}{u |u_2|}}$$

$$\frac{du}{d\phi} = \mp \frac{1}{b} \sqrt{\frac{(u_0 - u)}{u_0} \frac{(u_1 - u)}{u_1} \frac{(u_2 + u)}{|u_2|}}$$

ecuación de todas
las orbitas posibles

es más útil como comenté previamente volver a diferenciar.
comenzamos de:

$$\left(\frac{1}{u^2}\right)^2 \left(\frac{du}{d\phi}\right)^2 = \left(\frac{1}{u^2}\right)^2 \left(\frac{1}{b}\right)^2 \left(\frac{(u_0 - u)(u_1 - u)(u_2 + u)}{u_0 u_1 |u_2|} \right) \quad / \frac{d}{d\phi}$$

$$2 \left(\frac{du}{d\phi}\right) \frac{d^2u}{d\phi^2} = \frac{1}{b^2} \frac{1}{u_0 u_1 |u_2|} \left\{ -(u_0 - u)(u_1 - u)(u_2 + u) \right\} \dots \quad \otimes$$

o usar la eq original mejor

$$\left(\frac{dr}{d\phi}\right)^2 = \left(\frac{r^2}{b}\right)^2 \frac{1}{r^3} (r^3 + r^2\beta - b^2 r + b^2 r_s) = \left(\frac{r^2}{b}\right)^2 \left(1 + \frac{\beta}{r} - \frac{b^2}{r^2} + \frac{b^2 r_s}{r^3}\right)$$

$$\left(\frac{dr}{d\phi}\right)^2 = \left(\frac{r^2}{b}\right)^2 \left(1 + \frac{\beta}{r} - \frac{b^2}{r^2} + \frac{b^2 r_s}{r^3}\right) \quad / u = \frac{1}{r} \quad du = -\frac{dr}{r^2} \rightarrow \frac{dr}{d\phi} = -\frac{1}{u^2} \frac{du}{d\phi} \quad (13)$$

$$\left(\frac{du}{d\phi}\right)^2 \left(\frac{1}{u^2}\right)^2 = \left(\frac{1}{u^2}\right)^2 \left(\frac{1}{b}\right)^2 \left(1 + \beta u - b^2 u^2 + b^2 r_s u^3\right) \quad \frac{dr}{d\phi} = -\frac{1}{u^2} \frac{du}{d\phi}$$

$$\left(\frac{du}{d\phi}\right)^2 = \left(\frac{1}{b}\right)^2 \left(1 + \beta u - b^2 u^2 + b^2 r_s u^3\right) \quad / \frac{d}{d\phi}$$

$$2 \left(\frac{du}{d\phi}\right) \frac{d^2 u}{d\phi^2} = \frac{1}{b^2} \left(0 + \beta - 2b^2 u + 3b^2 r_s u^2\right) \left(\frac{du}{d\phi}\right)$$

$$\frac{d^2 u}{d\phi^2} = \frac{1}{b^2} \left(\frac{\beta}{2} - b^2 u + \frac{3}{2} b^2 r_s u^2\right) = \frac{\beta}{2b^2} - u + \frac{3}{2} r_s u^2$$

$$\boxed{\frac{d^2 u}{d\phi^2} + u = \frac{\beta}{2b^2} + \frac{3}{2} r_s u^2} \quad / \cdot \frac{2b^2}{\beta} \quad \left\{ \begin{array}{l} y = \frac{2b^2}{\beta} u \rightarrow u = \frac{y\beta}{2b^2} \end{array} \right.$$

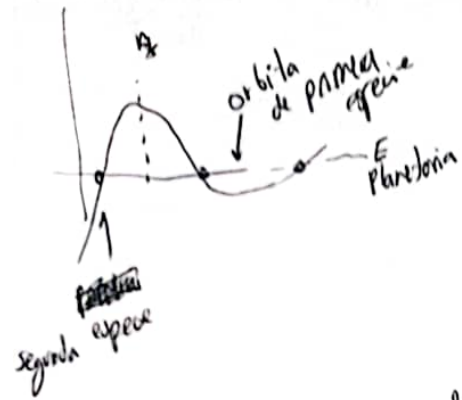
$$\frac{d^2}{d\phi^2} \left(\frac{2b^2}{\beta} u\right) + \frac{2b^2}{\beta} u = 1 + \frac{3}{2} r_s \left(\frac{2b^2}{\beta} u\right) u \quad \left\{ \begin{array}{l} b = \frac{L}{E} ; \beta = \frac{c^2 r_s}{E} \end{array} \right.$$

$$\frac{d^2 y}{d\phi^2} y + y = 1 + \frac{3}{2} r_s y \cdot y \frac{\beta}{2b^2} = 1 + y^2 \frac{3}{4} \frac{r_s \beta}{b^2} = 1 + y^2 \frac{3}{4} \frac{r_s c^2 r_s}{E^2 L^2} E^2$$

$$\frac{d^2 y}{d\phi^2} + y = 1 + y^2 \frac{3}{4} \frac{c^2 (r_s)^2}{L^2} = 1 + y^2 d^2 \Rightarrow \boxed{\frac{d^2 y}{d\phi^2} + y = 1 + y^2 d^2}$$

$$\text{con } y = \frac{2b^2}{\beta} u = \frac{2L^2}{E^2} \frac{E^2}{c^2 r_s} = \frac{2L^2}{c^2 r_s} \frac{1}{r}$$

entonces resolviendo numericamente
para ser capaz de utilizar:



en una orbita de primera especie se tiene el avance del perihelio

y las de 2da especie rapidamente impactan
a la que para orbitas se requiere que
sean mayor a r_*

$$\text{usando } L^2 > 3r_*^2 c^2 ; M=1$$

ver orbita en orbita - masive.ipynb

1c) la ecuación de movimiento para la luz (geodésica nula) #15

$$\left[\left(\frac{dr}{d\phi} \right)^2 = \frac{r^4}{L^2} \varepsilon^2 - r^2 \left(1 - \frac{r_s}{r} \right) \right] \quad \left| \begin{array}{l} u = \frac{1}{r} \\ \rightarrow dr = -\frac{du}{u^2} \end{array} \right.$$

$$\frac{dr}{d\phi} d\phi = -\frac{du}{d\phi} d\phi \frac{1}{u^2}$$

$$\left(-\frac{du}{d\phi} \right)^2 \left(\frac{1}{u^2} \right)^2 = \frac{1}{u^4} \frac{\varepsilon^2}{L^2} - \frac{1}{u^2} \left(1 - \frac{r_s}{r} \right) \quad \cdot u^4$$

$$\left(\frac{du}{d\phi} \right)^2 = \frac{\varepsilon^2}{L^2} - u^2 \left(1 - u r_s \right) \quad \left| \begin{array}{l} \text{usando} \\ y = u \left(1 - \frac{r_s u}{2} \right) \\ b^{-1} = \frac{\varepsilon}{L} \end{array} \right.$$

$$dy = \left(\left(1 - \frac{r_s u}{2} \right) - u \frac{r_s}{2} \right) du = \frac{du}{2} (2 - r_s u - u r_s) = \frac{du}{2} (2 - 2u r_s)$$

$$dy = du (1 - u r_s) \rightarrow \text{el cambio } u(y).$$

$$u(y) = y \left(1 + y \frac{r_s}{2} \right) + \mathcal{O}(r_s^2 u^2)$$

$$\left(\frac{du}{d\phi} \right) = \frac{1}{(1 - u r_s)} \left(\frac{dy}{d\phi} \right)$$

$$\left(\frac{dy}{d\phi} \right)^2 = (1 - u r_s)^2 \left(b^{-2} - u^2 (1 - u r_s) \right) = (1 - 2u r_s + u^2 r_s^2) (b^{-2} - u^2 (1 - u r_s))$$

$$\left(\frac{dy}{d\phi} \right)^2 = (1 - u r_s)^2 b^{-2} - u^2 (1 - u r_s)^2 = (1 - u r_s)^2 (b^{-2} - u^2)$$

$$\triangle \text{ donde } (1 - u r_s)^2 = \left(1 - r_s y \left(1 + y \frac{r_s}{2} \right) + \mathcal{O}(r_s^2 u^2) \right)^2$$

$$\left(\frac{du}{d\phi}\right)^2 = b^{-2} - u^2(1 - u r_s)$$

$$\text{con } y = u(1 - \frac{r_s u}{2})$$

(#15. a)

$$dy = du(1 - u r_s)$$

$$\text{donde: } y = u - \frac{r_s u^2}{2} \Rightarrow u^2 \frac{r_s}{2} - u + y = 0$$

$$u^2 = (y - u) \frac{2}{r_s} \quad / \times$$

$$\left(\frac{dy}{d\phi}\right)^2 \left(\frac{1}{1 - u r_s}\right)^2 = b^{-2} - \frac{2}{r_s} (y - u) (1 - u r_s)$$

$$= b^{-2} - \frac{2}{r_s} [y - y u r_s - u + u^2 r_s]$$

$$= b^{-2} - \frac{2}{r_s} [y - u (y r_s + 1) + \frac{2}{r_s} (y - u)]$$

$$= b^{-2} - \frac{2}{r_s} \left[y \left(1 + \frac{2}{r_s}\right) - u \left(y r_s + 1 + \frac{2}{r_s}\right) \right] \quad // u = y \left(1 + \frac{r_s y}{2}\right) + O(y^2)$$

$$= b^{-2} - \frac{2}{r_s} \left[y \left(1 + \frac{2}{r_s}\right) - \left[y \left(1 + \frac{r_s y}{2}\right) + O^2 \right] \left(y r_s + 1 + \frac{2}{r_s}\right) \right]$$

$$= b^{-2} - \frac{2}{r_s} \left\{ y \left(1 + \frac{2}{r_s}\right) - y^2 r_s \left(1 + \frac{r_s y}{2}\right) + y \left(1 + \frac{r_s y}{2}\right) + \frac{2}{r_s} y \left(1 + \frac{r_s y}{2}\right) + O^2 \left(y r_s + 1 + \frac{2}{r_s}\right) \right\}$$

$$= b^{-2} - \frac{2}{r_s} \left\{ y \left[\left(1 + \frac{2}{r_s}\right) - y r_s \left(1 + \frac{r_s y}{2}\right) + \left(1 + \frac{2}{r_s}\right) \left(1 + \frac{y r_s}{2}\right) \right] + O^2 \left(y r_s + 1 + \frac{2}{r_s}\right) \right\}$$

$$= b^{-2} - \frac{2}{r_s} \left\{ y \left[\left(1 + \frac{2}{r_s}\right) \left(2 + \frac{y r_s}{2}\right) - y r_s \left(1 + \frac{y r_s}{2}\right) \right] + O^2 \left(y r_s + 1 + \frac{2}{r_s}\right) \right\}$$

$$\left(\frac{du}{d\phi}\right)^2 = b^{-2} - u^2\left(1 - \frac{ur_s}{2} - \frac{ur_s}{2}\right) = b^{-2} - u^2\left(1 - \frac{ur_s}{2}\right) + u^2\left(\frac{ur_s}{2}\right) \quad \text{#156}$$

$$\left(\frac{dy}{d\phi}\right)^2 \frac{1}{(1-ur_s)^2} = b^{-2} - u^2(1-ur_s)$$

$$\left(\frac{d\phi}{dy}\right)^2 = \left[(1-ur_s)^2 (b^{-2} - u^2(1-ur_s)) \right]^{-1} = \frac{1}{\varphi}$$

$$\varphi = (1-ur_s)^2 b^{-2} - u^2(1-ur_s)^3 = b^{-2} - \frac{2r_s u}{b^2} + \left(\frac{r_s^2}{b^2} - 1\right)u^2 + 3r_s u^3 - 3r_s^2 u^4 + r_s^3 u^5$$

$$= \cancel{(b^{-2} - u^2(1-ur_s))} (1-ur_s)^2$$

$$\Rightarrow \sqrt{\frac{1}{\varphi}} = \frac{1}{1-ur_s} \frac{1}{\sqrt{b^{-2} - u^2(1-ur_s)}} \quad \text{colectando por } ur_s$$

$$\varphi = \frac{1}{b^2} - \frac{2(r_s u)}{b^2} - u^2 + \frac{r_s^2 u^2}{b^2} + 3(r_s u)u^2 - 3(r_s u)^2 u^2 + (r_s u)^3 u^2$$

$$\varphi = \frac{1}{b^2} - \frac{2(r_s u)}{b^2} + u^2 \left[-1 + 3(r_s u) - 3(r_s u)^2 + (r_s u)^3 \right] + \frac{(r_s u)^2}{b^2}$$

$$\varphi = b^{-2} \left[1 - 2(r_s u) + (r_s u)^2 \right] + u^2 \left[-1 + 3(r_s u) - 3(r_s u)^2 + (r_s u)^3 \right]$$

ahora si tenemos: $\varphi \left(\frac{r_s}{r_s}\right)^2 = \frac{1}{r_s^2} (r_s u)^2 \left[-1 + 3(r_s u) - 3(r_s u)^2 + (r_s u)^3 \right] + b^{-2}$

we then $\alpha = (r_s u)$

$$\left[1 - 2(r_s u) + (r_s u)^2 \right]$$

$$\varphi = \frac{1}{r_s^2} \alpha^2 \left[-1 + 3\alpha - 3\alpha^2 + \alpha^3 \right] + \frac{1}{b^2} \left[1 - 2\alpha + \alpha^2 \right]$$

Comenzar la expansión de Taylor de.

#15c



$$\psi = \frac{\alpha^2}{r_s^2} [-1 + 3\alpha] + \frac{1}{b^2} [(1-\alpha)^2] + \mathcal{O}[\alpha^3]$$

$$\psi = \frac{\alpha^2 [3\alpha - 1] b^2 + r_s^2 [(1-\alpha)^2]}{b^2 r_s^2}$$

or 1/10
K

$$ii) \frac{d\phi}{dy} = \frac{1 + r_s y}{\sqrt{\frac{1}{b^2} - y^2}} = \frac{1 + r_s y}{\frac{1}{b} \sqrt{1 - b^2 y^2}} = b \frac{1 + r_s y}{\sqrt{1 - b^2 y^2}}$$

$$= b \cdot \frac{1}{\sqrt{1 - b^2 y^2}} + b r_s \frac{y}{\sqrt{1 - b^2 y^2}} \quad \left| \begin{array}{l} 1 - \sinh^2 \theta = \cosh^2 \theta \\ by = \sinh \theta \\ b dy = \cosh \theta d\theta \end{array} \right.$$

$$\int d\phi = b \int \frac{dy}{\sqrt{1 - b^2 y^2}} + b r_s \int \frac{y dy}{\sqrt{1 - b^2 y^2}}$$

$$= b \int \frac{\cosh \theta d\theta \frac{1}{b}}{\cosh \theta} + b r_s \int \frac{\frac{\sinh \theta}{b} \frac{\cosh \theta d\theta}{b}}{\cosh \theta} = \int d\theta + \frac{r_s}{b} \int \sinh \theta d\theta$$

$$= \text{ArcSin}[by] + \phi_0 + \frac{r_s}{b} (-\cosh \theta)$$

$$\begin{aligned} \sinh^2 \theta + \cosh^2 \theta &= 1 \\ \cosh^2 \theta &= 1 - \sinh^2 \theta \\ \cosh \theta &= \sqrt{1 - \sinh^2 \theta} \\ \cosh \theta &= \sqrt{1 - (by)^2} \end{aligned}$$

$$= \phi_0 + \text{ArcSin}[by] - \frac{r_s}{b} \sqrt{1 - b^2 y^2}$$

$$\phi = \phi_0 + \text{ArcSin}[by] - r_s \sqrt{\frac{1}{b^2} - y^2}$$

y teniendo en cuenta el factor extra $\mathcal{O}(r_s^2 u^2)$

$$\text{usando } u^2 = y^2 \left(1 + \frac{r_s y}{2}\right)^2 + \mathcal{O}(r_s^2 u^4) \quad ; \quad y = u \left(1 - \frac{r_s u}{2}\right) = u - \frac{r_s u^2}{2}$$

$$\int \mathcal{O}(r_s^2 u^2) dy = \int r_s^2 y^2 \left(1 + \frac{r_s y}{2}\right)^2 dy = \frac{r_s^2 y^3}{3} + \frac{r_s^3 y^4}{8} + C =$$

↑ incluío
en ϕ

$$\int \mathcal{O}(r_s^2 u) dy = \frac{r_s^2 y^2 y}{3} + \frac{r_s^3 y^3 y}{8} \quad \left| \begin{array}{l} y = u - \frac{r_s u^2}{2} \\ y^2 = u^2 - u^3 r_s + \frac{1}{4} r_s^2 u^4 \end{array} \right. \quad \begin{array}{l} (\#6) \\ \text{con } \underline{r_s u = a} \end{array}$$

$$\begin{aligned} &= \frac{r_s^2}{3} (u^2 - u^3 r_s + \frac{1}{4} r_s^2 u^4) (u - \frac{r_s u^2}{2}) + \frac{r_s^3}{8} (u^2 - u^3 r_s + \frac{1}{4} r_s^2 u^4)^2 \\ &= \left(\frac{a^2 - a^3 + \frac{1}{4} a^4}{3} \right) \left(\frac{a}{r_s} - \frac{a^2}{2 r_s} \right) + \frac{r_s^2}{8} \left(a^2 - a^3 + \frac{1}{4} a^4 \right)^2 \\ &= \mathcal{O}(r_s^2 u^2) \end{aligned}$$

por tanto el resultado de integrar

$$\phi = \phi_0 + \text{ArcSin}[by] - r_s \sqrt{\frac{1}{b^2} - y^2} + \mathcal{O}(r_s^2 u^2)$$

comparando a la solución que demuestra

$\mathcal{O}(r_s^2 u^2)$ debe de tener una forma distinta de $(r_s u)^2$ especificada, para integrar a $\frac{r_s}{b}$.

iii) mostrar que (3) puede ser resuelta con (*) (#17.

$$(3) \left(\frac{d\phi}{du} \right)^2 = \frac{1}{b^2 - u^2(1 - ur_s)} \quad \text{or} \quad \left(\frac{du}{d\phi} \right)^2 = b^2 - u^2(1 - ur_s)$$

derivando el
cambio a u ↑

$$*2) bu = \sin[\phi - \phi_0] + \frac{r_s}{2b} (1 - \cos[\phi - \phi_0])^2 + O\left[\frac{r_s^2}{b^2}\right]$$

$$\begin{aligned} \frac{du}{d\phi} &= \frac{d}{d\phi} \left\{ \frac{1}{b} \sin[\phi - \phi_0] + \frac{r_s}{2b^2} (1 - \cos[\phi - \phi_0])^2 + \cancel{\frac{1}{b} O\left[\frac{r_s^2}{b^2}\right]} \right\} \\ &= \frac{\cos[\phi - \phi_0]}{b} + \frac{r_s}{b^2} 2(1 - \cos[\phi - \phi_0]) \left(-(-\sin[\phi - \phi_0]) \right) \end{aligned}$$

derivado de constante.

$$\frac{du}{d\phi} = \frac{\cos[\phi - \phi_0]}{b} + \frac{r_s}{b^2} (1 - \cos[\phi - \phi_0]) (\sin[\phi - \phi_0])$$

$$\left(\frac{du}{d\phi} \right)^2 = \frac{\cos^2[\phi - \phi_0]}{b^2} + \left(\frac{r_s}{b^2} \right)^2 (1 - \cos[\phi - \phi_0])^2 \sin^2[\phi - \phi_0]$$

$$\text{y el lado derecho: } = b^2 - u^2(1 - ur_s) \quad ; \quad \epsilon = O\left[\frac{r_s^2}{b^2}\right]$$

$$u^2 = \left(\frac{\sin[\phi - \phi_0]}{b} + \frac{r_s}{2b} (1 - \cos[\phi - \phi_0])^2 + \epsilon \right)^2$$

$$u^2 = \left(\frac{\sin[\phi - \phi_0]}{b} + \epsilon \right)^2 + \left(\epsilon + \frac{\sin[\phi - \phi_0]}{b} \right) \left(\frac{r_s}{b} (1 - \cos[\phi - \phi_0])^2 + \frac{r_s^2}{4b^2} (1 - \cos[\phi - \phi_0])^4 \right)$$

$$\left(\frac{du}{d\phi}\right)^2 = b^{-2} - u^2(1 - ur_s)$$

$$// \omega = \phi - \phi_0$$

(#18)

$$(1 - ur_s) = 1 - \frac{\sin[\phi - \phi_0]}{b} r_s + \frac{(r_s)^2}{2b} (1 - \cos[\phi - \phi_0])^2 + \epsilon$$

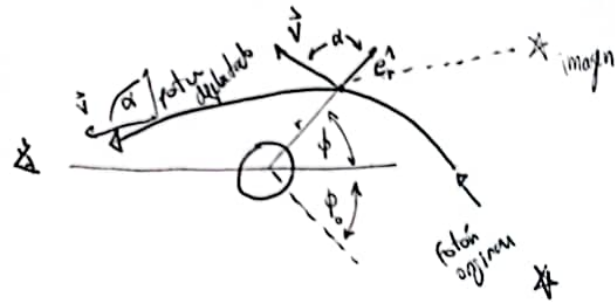
$$\frac{1}{b^2} - u^2(1 - ur_s) = \frac{1}{b^2} - \left(\epsilon + \frac{r_s(1 - \cos w)^2}{2b} + \frac{\sin w}{b} \right)^2 \left(1 - \epsilon \left(\epsilon + \frac{r_s(1 - \cos w)^2}{2b} + \frac{\sin w}{b} \right) \right)$$

Compare las expresiones no hora mucho debido a la enorme cantidad de terminos;

así que dejare este problema hasta aqui para seguir con otros. //

iv) tenemos el vector: $\vec{V} = (0, -1, 0, \frac{d\phi}{dr})$

19



$$\vec{e}_r = (0, 1, 0, 0) = \delta_{\mu 1}$$

$$g_{11} = -\frac{1}{(1 - \frac{r_s}{r})}$$

$$\vec{V} \cdot \vec{e}_r = g_{\mu\nu} V^\mu e_r^\nu = g_{\mu 1} V^\mu \delta_1^\nu = g_{11} V^1 = \frac{-1}{(1 - \frac{r_s}{r})} (-1) = \frac{1}{(1 - \frac{r_s}{r})}$$

Para un observador
 \vec{V} y \vec{e}_r son paralelos
ya que

$$\lim_{r \rightarrow \infty} \vec{V} \cdot \vec{e}_r = \lim_{r \rightarrow \infty} \frac{1}{(1 - \frac{r_s}{r})} = 1$$

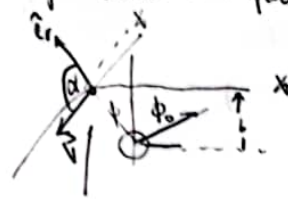
Podemos comparar
en el observador $\hat{e}_\phi = (0, 0, 0, 1)$

$$\vec{V} \cdot \hat{e}_\phi = g_{\mu\phi} \left(\frac{d\phi}{dr} \right) = -r^2 \left(\frac{d\phi}{dr} \right) = r^2 \frac{d\phi}{dr}$$

$$\text{donde } \left(\frac{dr}{d\phi} \right)^2 = r^4 b^{-2} - r^2 \left(1 - \frac{r_s}{r} \right) \rightarrow \left(\frac{d\phi}{dr} \right) = \frac{\pm 1}{r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2} \left(1 - \frac{r_s}{r} \right)}}$$

$$\vec{V} \cdot \hat{e}_\phi = r^2 \frac{d\phi}{dr} = \frac{\pm 1}{\sqrt{\frac{1}{b^2} - \frac{1}{r^2} \left(1 - \frac{r_s}{r} \right)}}$$

el parámetro de impacto.



phi punto de acercamiento más cercano

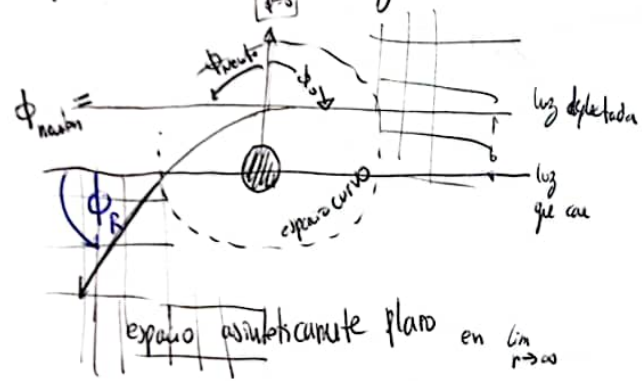
$$\vec{v} \cdot \vec{e}_\phi = \frac{\pm 1}{\sqrt{\frac{1}{b^2} - \frac{1}{r^2}(1 - \frac{r_s}{r})}} = r^2 \frac{d\phi}{dr}$$

#20

en el cas

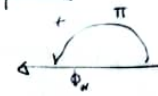
$$\lim_{r \rightarrow \infty} \vec{v} \cdot \vec{e}_\phi = \frac{\pm 1}{\sqrt{\frac{1}{b^2}}} = \pm b = r^2 \frac{d\phi}{dr}$$

para el estudio de angulo



caso Newton

$$\phi_0 + \pi = \phi_N$$



o si vemos phi=0 en phi_0

phi_0=0

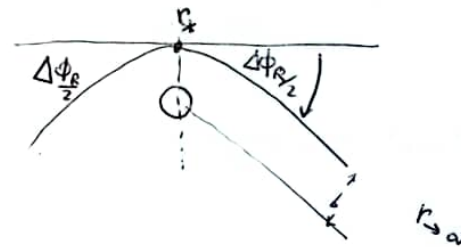
$$\phi_N = \pi$$

$\phi_R[b]$ el angulo de deflexión relativista dependera de b

el problema es simetrico
pues es una hipérbola

es posible calcular

$$\Delta\phi_R = \int_{\phi(r=\infty)}^{\phi(r^*)} d\phi = \int_{r=\infty}^{r^*} \frac{\pm dr}{r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2}(1 - \frac{r_s}{r})}}$$



/ ± el angulo aumenta al disminuir r

$$\Delta\phi_R = - \int_{\infty}^{r^*} \frac{dr}{r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2}(1 - \frac{r_s}{r})}} = \int_{r^*}^{\infty} \frac{dr}{r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2}(1 - \frac{r_s}{r})}} \rightarrow \frac{d\phi}{dr} \leq 0 \quad (\text{signo negativo})$$

a partir de la expresión en ii)

#21

$$\phi - \phi_0 = \frac{r_s}{b} + \text{Arcsin}[by] - r_s \sqrt{\frac{1}{b^2} - y^2} = \Delta\phi \quad (*)$$

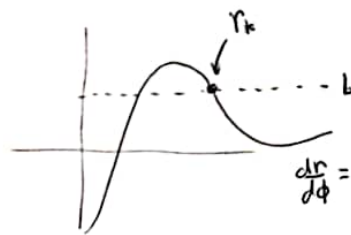
con $y = u(1 - \frac{r_s u}{2}) = \frac{1}{r}(1 - \frac{r_s}{2r})$

evaluamos la integral $\frac{\Delta\phi}{2} = \int_{r_*}^{\infty} \frac{dr}{r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2}(1 - \frac{r_s}{r})}}$ usando $*$ como solución

$$\Delta\phi = \lim_{r \rightarrow \infty} \left(\frac{r_s}{b} + \text{ArcSh}\left[\frac{1}{r}\left(1 - \frac{r_s}{2r}\right)b\right] - r_s \sqrt{\frac{1}{b^2} - \frac{1}{r^2}\left(1 - \frac{r_s}{2r}\right)^2} \right) - \left(\frac{r_s}{b} + \text{ArcSin}\left[\frac{1}{r_*}\left(1 - \frac{r_s}{2r_*}\right)b\right] - r_s \sqrt{\frac{1}{b^2} - \frac{1}{(r_*)^2}\left(1 - \frac{r_s}{2r_*}\right)^2} \right)$$

// r_* es la distancia de máximo acercamiento;
o sea la raíz más pequeña para la energía y L dados por b .

asumiendo $r_s/r \ll 1$.



es posible resolver raíces de

$$\frac{dr}{d\phi} = -r^2 \sqrt{\underbrace{\frac{1}{b^2} - \frac{1}{r^2}\left(1 - \frac{r_s}{r}\right)}_{P_3[r]}} \quad \left| = -r^2 \sqrt{\left(1 - \frac{r_s}{r}\right) \left\{ \frac{(1 - \frac{r_s}{r})^{-1}}{b^2} - \frac{1}{r^2} \right\}} \right.$$

$$P_3[r] = \left(1 - \frac{r_s}{r}\right) \left\{ \frac{1}{b^2} \left(1 + \frac{r_s}{r} + \mathcal{O}\left(\frac{r_s^2}{r^2}\right)\right) - \frac{1}{r^2} \right\} = \left(1 - \frac{r_s}{r}\right) \left\{ \frac{1}{b^2} + \frac{1}{r} \frac{r_s}{b^2} - \frac{1}{r^2} \right\}$$

como variable auxiliar $u = \frac{1}{r}$

$$P_3[u] = (1 - ur_s) \left\{ \frac{1}{b^2} + u \frac{r_s}{b^2} - u^2 \right\}$$

$$P_3(u) = (1 - ur_s) \left\{ \frac{1}{b^2} + u \frac{r_s}{b^2} - u^2 \right\} \quad \text{es cuadrática} \quad (u - u_1)(u - u_2) \quad \text{#22}$$

$$= \left(\frac{1}{r} - \frac{1}{r_1} \right) \left(\frac{1}{r} - \frac{1}{r_2} \right)$$

$$u = \frac{-\frac{r_s}{b^2} \pm \sqrt{\frac{r_s^2}{b^4} + 4 \frac{1}{b^2}}}{-2} = \frac{r_s}{2b^2} \pm \sqrt{\left(\frac{r_s}{2b^2} \right)^2 + \frac{1}{b^2}}$$

$$u = \frac{1}{r} = \frac{r_s}{2b^2} \left(1 \pm \sqrt{1 + \frac{4b^4}{r_s^2}} \right) = \frac{r_s}{2b^2} \left(1 \pm \sqrt{1 + \frac{4b^2}{r_s^2}} \right) = \left\{ \frac{1}{r_1}, \frac{1}{r_2} \right\}$$

2 soluciones

entonces

$$P_3(r) = \left(1 - \frac{r_s}{r} \right) \left(\frac{1}{r} - \frac{1}{r_1} \right) \left(\frac{1}{r} - \frac{1}{r_2} \right)$$

∴ esta raíz
esta conectada
al r_s

esta es
la raíz del
acero máximo

la raíz
negativa
por

$$\frac{1}{r_2} = \frac{r_s}{2b^2} \left(1 - \sqrt{1 + \frac{4b^2}{r_s^2}} \right)$$

$\sqrt{1 + \frac{4b^2}{r_s^2}} > 1$

$$r_1 = r_* = \frac{r_s}{2b^2} \left(1 + \sqrt{1 + \frac{4b^2}{r_s^2}} \right)$$

$$P_3(r) = \left(1 - \frac{r_s}{r} \right) \left(\frac{1}{r} - \frac{1}{r_1} \right) \left(\frac{1}{r_2} - \frac{1}{r} \right)$$

$$r_k = \frac{r_s}{2b^2} \left(1 + \sqrt{1 + \left(\frac{4b^2}{r_s^2} \right)} \right)$$

#23

o

$$\Delta\phi = \left(\text{ArcSh}[0] - \frac{r_s}{b} + \frac{0}{b} \right)$$

en el punto $r \rightarrow \infty$
algo así como de

$$- \left(\frac{r_s}{b} + \text{ArcSh} \left[\frac{1}{r_k} \left(1 - \frac{r_s}{2r_k} \right) b \right] - r_s \sqrt{\frac{1}{b^2} - \frac{1}{(r_k)^2} \left(1 - \frac{r_s}{2r_k} \right)^2} \right)$$

$$\Delta\phi = 0 - \left(\frac{r_s}{b} - \text{ArcSh} \left[\frac{2b^2}{r_s} \left(1 + \sqrt{1 + \left(\frac{4b^2}{r_s^2} \right)} \right)^{-1} \left(1 - \frac{r_s}{2r_k} \right) \right] \right)$$

ya que me queda poco tiempo la ecuación exacta tendrá que quedarse para un software matemático

es necesario expresar r_k teniendo en cuenta que r_s puede ser una cantidad pequeña. pues $\alpha \frac{G}{c^2} = \frac{10^{-11}}{10^{16}} = 10^{-26}$

$$r_k = \frac{r_s}{2b^2} \left(1 + \frac{2b}{r_s} \sqrt{\frac{r_s^2}{4b^2} + 1} \right) = \frac{r_s}{2b^2} + \frac{1}{b} \sqrt{\frac{r_s^2}{4b^2} + 1}$$

$$r_k = \frac{r_s}{2b^2} + \frac{1}{b} \sqrt{\frac{r_s^2}{4b^2} + 1} \quad ; \text{ y necesitamos } \frac{1}{r_k} =$$

entonces ~~la~~ $(1+x)^{\alpha} = 1 + \alpha x + \mathcal{O}(x^2)$ $\Rightarrow \left(\frac{r_s^2}{4b^2} + 1 \right)^{\frac{1}{2}} = 1 + \frac{r_s^2}{8b^2} + \mathcal{O}\left(\frac{r_s^4}{4b^4}\right)$

$$\frac{1}{r_k} = \left(\frac{r_s}{2b^2} + \frac{1}{b} + \frac{r_s^2}{8b^3} \right)^{-1} = \left[\frac{1}{b} \left(\frac{r_s}{2b} + 1 + \frac{r_s^2}{8b^2} \right) \right]^{-1} = b \left(\frac{4br_s + 8b^2 + r_s^2}{8b^2} \right)^{-1}$$

$$= \cancel{\frac{1}{b}} = b \left(\frac{r_s^2 + 4br_s + 4b^2 + 4b^2}{8b^2} \right)^{-1} = b \left(\frac{8b^2}{(r_s + 2b)^2 + 4b^2} \right) = \frac{1}{r_k}$$

$$\therefore \Delta\phi = 0 - \left(\frac{r_s}{b} + \text{ArcSin} \left[\frac{1}{r_k} \left(1 - \frac{r_s}{2r_k} \right) b \right] - r_s \sqrt{\frac{1}{b^2} - \frac{1}{r_k^2} \left(1 - \frac{r_s}{2r_k} \right)^2} \right) \cdot \#(24)$$

$$\frac{1}{r_k} = \frac{(2b)^3}{(r_s + 2b)^2 + 4b^2} = \frac{(2b)^2 / 2b}{\left(\frac{r_s}{2b} + 1 \right)^2 + (2b)^2} = \frac{2b}{\left(1 + \frac{r_s}{2b} \right)^2 + 1}$$

$$\left(\frac{1}{r_k} \left(1 - \frac{r_s}{2r_k} \right) \right) = \frac{2b}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \left(1 - \frac{b r_s}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \right)$$

$$\Delta\phi = -\frac{r_s}{b} - \text{ArcSin} \left[\frac{2b^2}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \left(1 - \frac{b r_s}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \right) \right] + \frac{r_s}{b} \sqrt{1 - \frac{b^2}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \left[\frac{2b}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \left(1 - \frac{b r_s}{\left(1 + \frac{r_s}{2b} \right)^2 + 1} \right) \right]^2}$$

no parece muy útil
la aproximación de la solución
prevista; así que la construiremos nosotros mismos.

$$\frac{\Delta\phi_R}{2} = \int_{r_k}^{\infty} \frac{dr}{r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2} \left(1 - \frac{r_s}{r} \right)}} \quad (\text{int}^*)$$

donde previamente resolvimos para $r^2 \sqrt{\frac{1}{b^2} - \frac{1}{r^2} \left(1 - \frac{r_s}{r} \right)}$

$$r^2 \sqrt{\left(1 - \frac{r_s}{r} \right) \left(\frac{1}{r} - \frac{1}{r_k} \right) \left(\frac{1}{r} + \frac{1}{r_2} \right)}$$

luego en (int*) $\left(\frac{r_s}{r} \ll 1 \right)$

$$\text{para } \frac{1}{\sqrt{1 - \frac{r_s}{r}}} \approx 1 - \frac{1}{2} \left(-\frac{r_s}{r} \right) = 1 + \frac{r_s}{2r}$$

$$\frac{\Delta\phi_R}{2} = \int_{r_k}^{\infty} \frac{dr \left(1 + \frac{r_s}{2r} \right)}{r^2 \sqrt{\left(\frac{1}{r} - \frac{1}{r_k} \right) \left(\frac{1}{r} + \frac{1}{r_2} \right)}}$$

realizamos el cambio $u = \frac{1}{r} \rightarrow du = -\frac{dr}{r^2}$

#25

$$\frac{\Delta\phi_R}{2} = - \int_{1/r_k}^0 \frac{du (1 + \frac{r_s}{2} u)}{\sqrt{(u - \frac{1}{r_k})(u - \frac{1}{|r_2|})}} \quad \left| \begin{array}{l} a = \frac{1}{r_k} \\ b = \frac{1}{|r_2|} \end{array} \right. \quad m = \frac{r_s}{2}$$

$$= -\sqrt{ab} - (a-b) m \text{ArcTan}\sqrt{\frac{a}{b}} - 2 \text{ArcTan}\sqrt{\frac{a}{b}}$$

$$= - \left\{ \sqrt{ab} + \left(\text{ArcTan}\sqrt{\frac{a}{b}} \right) ((a-b)m + 2) \right\}$$

$$= - \left\{ \sqrt{\frac{1}{r_k} \frac{1}{|r_2|}} + \left(\left(\frac{1}{r_k} - \frac{1}{|r_2|} \right) \frac{r_s}{2} + 2 \right) \text{ArcTan}\sqrt{\frac{|r_2|}{r_k}} \right\}$$

¡ aquí se me acabó el tiempo.

Fin