The Levi-Civita tensor

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In 3-dimensions, we define the Levi-Civita tensor, ε_{ijk} , to be totally antisymmetric, so we get a minus sign under interchange of any pair of indices. We work throughout in Cartesian coordinate. This means that most of the 27 components are zero, since, for example,

$$\varepsilon_{212} = -\varepsilon_{212}$$

if we imagine interchanging the two 2s. This means that the only nonzero components are the ones for which i, j and k all take different value. There are only six of these, and all of their values are determined once we choose any one of them. Define

$$\varepsilon_{123} \equiv 1$$

Then by antisymmetry it follows that

$$\varepsilon_{123} = \varepsilon_{231} = \varepsilon_{312} = +1$$
 $\varepsilon_{132} = \varepsilon_{213} = \varepsilon_{321} = -1$

All other components are zero.

Using ε_{ijk} we can write index expressions for the cross product and curl. The i^{th} component of the cross product is given by

$$[\mathbf{u} \times \mathbf{v}]_i = \varepsilon_{ijk} u_j v_k$$

as we check by simply writing out the sums for each value of i,

$$\begin{aligned} [\mathbf{u} \times \mathbf{v}]_1 &= & \varepsilon_{1jk} u_j v_k \\ &= & \varepsilon_{123} u_2 v_3 + \varepsilon_{132} u_3 v_2 + (all\ other\ terms\ are\ zero) \\ &= & u_2 v_3 - u_3 v_2 \\ [\mathbf{u} \times \mathbf{v}]_2 &= & \varepsilon_{2jk} u_j v_k \\ &= & \varepsilon_{231} u_3 v_1 + \varepsilon_{213} u_1 v_3 \\ &= & u_3 v_1 - u_1 v_3 \\ [\mathbf{u} \times \mathbf{v}]_3 &= & \varepsilon_{3jk} u_j v_k \\ &= & u_1 v_2 - u_2 v_1 \end{aligned}$$

We get the curl simply by replacing u_i by $\nabla_i = \frac{\partial}{\partial x_i}$,

$$[\nabla \times \mathbf{v}]_i = \varepsilon_{ijk} \nabla_j v_k$$

If we sum these expressions with basis vectors \mathbf{e}_i , where $\mathbf{e}_1 = \mathbf{i}, \mathbf{e}_2 = \mathbf{j}, \mathbf{e}_3 = \mathbf{k}$, we may write these as vectors:

$$\mathbf{u} \times \mathbf{v} = [\mathbf{u} \times \mathbf{v}]_i \mathbf{e}_i$$
$$= \varepsilon_{ijk} u_j v_k \mathbf{e}_i$$
$$\nabla \times \mathbf{v} = \varepsilon_{ijk} \mathbf{e}_i \nabla_j v_k$$

There are useful identities involving pairs of Levi-Civita tensors. The most general is

$$\varepsilon_{ijk}\varepsilon_{lmn} = \delta_{il}\delta_{jm}\delta_{kn} + \delta_{im}\delta_{jn}\delta_{kl} + \delta_{in}\delta_{jl}\delta_{km} - \delta_{il}\delta_{jn}\delta_{km} - \delta_{in}\delta_{jm}\delta_{kl} - \delta_{im}\delta_{jl}\delta_{kn}$$

To check this, first notice that the right side is antisymmetric in i, j, k and antisymmetric in l, m, n. For example, if we interchange i and j, we get

$$\varepsilon_{ijk}\varepsilon_{lmn} = \delta_{il}\delta_{im}\delta_{kn} + \delta_{im}\delta_{in}\delta_{kl} + \delta_{in}\delta_{il}\delta_{km} - \delta_{il}\delta_{in}\delta_{km} - \delta_{in}\delta_{im}\delta_{kl} - \delta_{im}\delta_{il}\delta_{kn}$$

Now interchange the first pair of Kronecker deltas in each term, to get i, j, k in the original order, then rearrange terms, then pull out an overall sign,

$$\varepsilon_{jik}\varepsilon_{lmn} = \delta_{im}\delta_{jl}\delta_{kn} + \delta_{in}\delta_{jm}\delta_{kl} + \delta_{il}\delta_{jn}\delta_{km} - \delta_{in}\delta_{jl}\delta_{km} - \delta_{im}\delta_{jn}\delta_{kl} - \delta_{il}\delta_{jm}\delta_{kn}$$

$$= -\delta_{il}\delta_{jm}\delta_{kn} - \delta_{im}\delta_{jn}\delta_{kl} - \delta_{in}\delta_{jl}\delta_{km} + \delta_{il}\delta_{jn}\delta_{km} + \delta_{in}\delta_{jm}\delta_{kl} + \delta_{im}\delta_{jl}\delta_{kn}$$

$$= -(\delta_{il}\delta_{jm}\delta_{kn} + \delta_{im}\delta_{jn}\delta_{kl} + \delta_{in}\delta_{jl}\delta_{km} - \delta_{il}\delta_{jn}\delta_{km} - \delta_{in}\delta_{jm}\delta_{kl} - \delta_{im}\delta_{jl}\delta_{kn})$$

$$= -\varepsilon_{ijk}\varepsilon_{lmn}$$

Total antisymmetry means that if we know one component, the others are all determined uniquely. Therefore, set i = l = 1, j = m = 2, k = n = 3, to see that

$$\varepsilon_{123}\varepsilon_{123} = \delta_{11}\delta_{22}\delta_{33} + \delta_{12}\delta_{23}\delta_{31} + \delta_{13}\delta_{21}\delta_{32} - \delta_{11}\delta_{23}\delta_{32} - \delta_{13}\delta_{22}\delta_{31} - \delta_{12}\delta_{21}\delta_{33}
= \delta_{11}\delta_{22}\delta_{33}
= 1$$

Check one more case. Let i = 1, j = 2, k = 3 again, but take l = 3, m = 2, n = 1. Then we have

$$\begin{array}{lll} \varepsilon_{123}\varepsilon_{321} & = & \delta_{13}\delta_{22}\delta_{31} + \delta_{12}\delta_{21}\delta_{33} + \delta_{11}\delta_{23}\delta_{32} - \delta_{13}\delta_{21}\delta_{32} - \delta_{11}\delta_{22}\delta_{33} - \delta_{12}\delta_{23}\delta_{31} \\ & = & -\delta_{11}\delta_{22}\delta_{33} \\ & = & -1 \end{array}$$

as expected.

We get a second identity by setting n = k and summing,

$$\begin{split} \varepsilon_{ijk}\varepsilon_{lmk} &= \delta_{il}\delta_{jm}\delta_{kk} + \delta_{im}\delta_{jk}\delta_{kl} + \delta_{ik}\delta_{jl}\delta_{km} - \delta_{il}\delta_{jk}\delta_{km} - \delta_{ik}\delta_{jm}\delta_{kl} - \delta_{im}\delta_{jl}\delta_{kk} \\ &= 3\delta_{il}\delta_{jm} + \delta_{im}\delta_{jl} + \delta_{im}\delta_{jl} - \delta_{il}\delta_{jm} - \delta_{il}\delta_{jm} - 3\delta_{im}\delta_{jl} \\ &= (3-1-1)\delta_{il}\delta_{jm} - (3-1-1)\delta_{im}\delta_{jl} \\ &= \delta_{il}\delta_{im} - \delta_{im}\delta_{il} \end{split}$$

so we have a much simpler, and very useful, relation

$$\varepsilon_{ijk}\varepsilon_{lmk} = \delta_{il}\delta_{im} - \delta_{im}\delta_{il}$$

A second sum gives another identity. Setting m = j and summing again,

$$\begin{array}{rcl} \varepsilon_{ijk}\varepsilon_{ljk} & = & \delta_{il}\delta_{mm} - \delta_{im}\delta_{ml} \\ & = & 3\delta_{il} - \delta_{il} \\ & = & 2\delta_{il} \end{array}$$

Setting the last two indices equal and summing provides a check on our normalization,

$$\varepsilon_{ijk}\varepsilon_{ijk} = 2\delta_{ii} = 6$$

This is correct, since there are only six nonzero components and we are summing their squares.

Collecting these results,

$$\varepsilon_{ijk}\varepsilon_{lmn} = \delta_{il}\delta_{jm}\delta_{kn} + \delta_{im}\delta_{jn}\delta_{kl} + \delta_{in}\delta_{jl}\delta_{km} - \delta_{il}\delta_{jn}\delta_{km} - \delta_{in}\delta_{jm}\delta_{kl} - \delta_{im}\delta_{jl}\delta_{kn} \\
\varepsilon_{ijk}\varepsilon_{lmk} = \delta_{il}\delta_{jm} - \delta_{im}\delta_{jl} \\
\varepsilon_{ijk}\varepsilon_{ljk} = 2\delta_{il} \\
\varepsilon_{ijk}\varepsilon_{ijk} = 6$$

Now we use these properties to prove some vector identities. First, consider the triple product,

$$\begin{array}{rcl} \mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) & = & u_i \left[\mathbf{v} \times \mathbf{w} \right]_i \\ & = & u_i \varepsilon_{ijk} v_j w_k \\ & = & \varepsilon_{ijk} u_i v_j w_k \end{array}$$

Because $\varepsilon_{ijk} = \varepsilon_{kij} = \varepsilon_{jki}$, we may write this in two other ways,

$$\begin{array}{rcl} \mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) & = & \varepsilon_{ijk} u_i v_j w_k \\ & = & \varepsilon_{kij} u_i v_j w_k \\ & = & w_k \varepsilon_{kij} u_i v_j \\ & = & w_i \left[\mathbf{u} \times \mathbf{v} \right]_i \\ & = & \mathbf{w} \cdot (\mathbf{u} \times \mathbf{v}) \end{array}$$

and

$$\begin{array}{rcl} \mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) & = & \varepsilon_{ijk} u_i v_j w_k \\ & = & \varepsilon_{jki} u_i v_j w_k \\ & = & v_j \left[\mathbf{w} \times \mathbf{u} \right]_j \\ & = & \mathbf{v} \cdot (\mathbf{w} \times \mathbf{u}) \end{array}$$

so that we have established

$$\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = \mathbf{w} \cdot (\mathbf{u} \times \mathbf{v}) = \mathbf{v} \cdot (\mathbf{w} \times \mathbf{u})$$

and we get the negative permutations by interchanging the order of the vectors in the cross products. Next, consider a double cross product:

$$\begin{split} \left[\mathbf{u}\times(\mathbf{v}\times\mathbf{w})\right]_{i} &= \varepsilon_{ijk}u_{j}\left[\mathbf{v}\times\mathbf{w}\right]_{k} \\ &= \varepsilon_{ijk}u_{j}\varepsilon_{klm}v_{l}w_{m} \\ &= \varepsilon_{ijk}\varepsilon_{klm}u_{j}v_{l}w_{m} \\ &= \varepsilon_{ijk}\varepsilon_{lmk}u_{j}v_{l}w_{m} \\ &= \left(\delta_{il}\delta_{jm} - \delta_{im}\delta_{jl}\right)u_{j}v_{l}w_{m} \\ &= \delta_{il}\delta_{jm}u_{j}v_{l}w_{m} - \delta_{im}\delta_{jl}u_{j}v_{l}w_{m} \\ &= \left(\delta_{il}v_{l}\right)\left(\delta_{jm}u_{j}w_{m}\right) - \left(\delta_{jl}u_{j}v_{l}\right)\left(\delta_{im}w_{m}\right) \\ &= v_{i}\left(u_{m}w_{m}\right) - \left(u_{i}v_{j}\right)w_{i} \end{split}$$

Returning to vector notation, this is the BAC - CAB rule,

$$\mathbf{u} \times (\mathbf{v} \times \mathbf{w}) = (\mathbf{u} \cdot \mathbf{w}) \mathbf{v} - (\mathbf{u} \cdot \mathbf{v}) \mathbf{w}$$

Finally, look at the curl of a cross product,

$$[\nabla \times (\mathbf{v} \times \mathbf{w})]_i = \varepsilon_{ijk} \nabla_j [\mathbf{v} \times \mathbf{w}]_k$$

$$\begin{split} &= & \varepsilon_{ijk} \nabla_{j} \left(\varepsilon_{klm} v_{l} w_{m} \right) \\ &= & \varepsilon_{ijk} \varepsilon_{klm} \left(\left(\nabla_{j} v_{l} \right) w_{m} + v_{l} \nabla_{j} w_{m} \right) \\ &= & \left(\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl} \right) \left(\left(\nabla_{j} v_{l} \right) w_{m} + v_{l} \nabla_{j} w_{m} \right) \\ &= & \delta_{il} \delta_{jm} \left(\left(\nabla_{j} v_{l} \right) w_{m} + v_{l} \nabla_{j} w_{m} \right) - \delta_{im} \delta_{jl} \left(\left(\nabla_{j} v_{l} \right) w_{m} + v_{l} \nabla_{j} w_{m} \right) \\ &= & \left(\nabla_{m} v_{i} \right) w_{m} + v_{i} \nabla_{m} w_{m} - \left(\nabla_{j} v_{j} \right) w_{i} - v_{j} \nabla_{j} w_{i} \end{split}$$

Restoring the vector notation, we have

$$\nabla \times (\mathbf{v} \times \mathbf{w}) = (\mathbf{w} \cdot \nabla) \, \mathbf{v} + (\nabla \cdot \mathbf{w}) \, \mathbf{v} - (\nabla \cdot \mathbf{v}) \, \mathbf{w} - (\mathbf{v} \cdot \nabla) \, \mathbf{w}$$

If you doubt the advantages here, try to prove these identities by explicitly writing out all of the components!