Lecture 10

Torsion and Curvature

Parallel Transport

To do differential calculus with vector fields, we must take derivatives of one vector field along another: ∇_{V} W^{a}

The Lie derivative does not let us do this!

- · L, Wa = [V, w]a
- · [V, W](f) = V(W(f)) W(V(f))
- . v(w(f)) = V ~ dx (W B dB (f))

= Vx dx (WB) dB(f)

+ VX WB DX DB (f)

=> [V, W](f) = [V(WB) - W(VB)] dB(f) +Z V WB d[dB](f)

= 0

Ly Wa requires two vector fields

It does not let us take the

derivative of a vector field

Wa along a single integral

curve of Va.

We need an additional structure $\nabla_{\hat{\sigma}} W^a$ to take the derivative of $W^a(p)$ as we move along $\partial(t)$.

This should take devivatives of wa, but be algebraic in ja.

functionally $\nabla_f v W^a = f \nabla_v W^a$ function linear $\nabla_v (f w^a) = f \nabla_v W^a + W^a \nabla_v f$

Naturally, we define $\nabla_V f := V(f)$.

of curves)

Derivative Operators (covariant Derivative, Affine Connection)

Given: <u>vector</u> Wa and vector field va

- · Tw Va is functionally linear in wb (=> algebraic)
- . Dw va is linear in va
- · Dw + = w(+)
- . Vw T is linear and Leibniz on tensor fields
- . Vw 8 = 0

Example: Coordinate Deravative $\partial w V^{\alpha} = \partial w (v^{\alpha} b_{\alpha}^{\alpha}) := W(v^{\alpha}) b_{\alpha}^{\alpha}$ $\partial_{\alpha}^{\alpha} \text{ (notation)}$

Transport: dw V = 0 (=> Keep the components constant!

The Space of Derivative Operators

Notation: $\nabla_W V^a =: W^b \nabla_b V^a$ emphasizes <u>functional</u>

linearity in W^b

Let $\vec{\nabla}_a$ and $\vec{\nabla}_a$ denote \underline{two} derivative operators:

$$\begin{split} \left(\widetilde{\nabla}_{a} - \nabla_{a}\right) \left(f w_{b}\right) &= \widetilde{\nabla}_{a} \left(f w_{b}\right) - \nabla_{a} \left(f w_{b}\right) \\ &= w_{b} \ \widetilde{\nabla}_{a} f + f \ \widetilde{\nabla}_{a} w_{b} \\ &- w_{b} \ \nabla_{a} f - f \ \nabla_{a} w_{b} \\ &= w_{b} \left[(df)_{a} - (df)_{a} \right] + f \left(\widetilde{\nabla}_{a} - \nabla_{a}\right) w_{b} \end{split}$$

=> (Fa- Va) Wb is functionally linear in Wb (algebraic)

=> $(\tilde{\nabla}_a - \nabla_a) w_b = C_{ab}^c w_c$ tensor! Example: Christoffel Symbols

Va = connection

da = coordinate connection

(Va - da) Wb = Tab Wa

Christoffel tessor

Ja = another coordinate connection

(Va-Ja) Wb = Fab Wc

another Christoffel tensor

 $\tilde{\Gamma}_{ab}^{c} = \Gamma_{ab}^{c} \omega_{c}$ $+ (\partial_{\alpha} - \tilde{\partial}_{a}) \omega_{b}$

"non-tensorial" term

The Christoffel symbols Tab

do not transform like a tensor

because they are different tensors!

The set of all derivative operators on a manifold M is naturally an affine space:

Given ∇a and $\widehat{\nabla} a$, define $[X \nabla a + (1-\alpha)\widehat{\nabla} a] T...$

:= d Va T ... + (1-d) Fa T ... "

• $[\angle \nabla \alpha + (1- \angle) \overrightarrow{\nabla} \alpha] f$ = $\angle \nabla \alpha f + (1- \angle) \overrightarrow{\nabla} \alpha f = (df) \alpha$ $(df) \alpha$

· [x Va + (1-x) Ta] 86 = 0, etc.

We can draw straight lines in the space of derivative operators, but there is no natural origin Va.

The connection is a physical field.

How do the actions of two derivative operators differ on other tensor fields?

Use the Leibniz property:

(Fa- Va) Vb. Wb

= Wb Fa Vb - Wb Va Vb

= Ta (wb Vb) - Vb Ta Wb

d(WbVb) = Va(WbVb) + Vb VaWb

= - Vb (Ta - Va) Wb

= - Vb Cab ~ Wc

= - Vc Cac Wb = - Cac Vc · Wb

(Pa- Va) Vb = - Cacb Vc

Torsion

Let Va be a derivative operator, and define the bracket

[V, W] = = V, W - Vw V

of vector fields.

This bracket is not functionally linear in either argument:

[N, tw] = DN (tw) - Dtm N

= Dr t. M + t Dr M - t Dm N

= V(4) W + f [V, W] V

The ordinary Lie bracket has the same behavior

[V, fW](g) = V(fW(g)) - fW(V(g))= $V(f) \cdot W(g) + fV(W(g)) - fW(V(g))$ $\longrightarrow [V, fW] = V(f) W + f[V, W]$ Neither [v, w] v nor [v, w]

depends algebraically on the

values of v and w at a

point, but their difference does

 $[v,w]_{\nabla}-[v,w]=T(v,w)$

linear map taking two vectors to one wo (¿) tensor field.

my Torsion tensor Tab

The torsion tensor is necessarily anti-symmetric $T(ab)^{c} = 0$ because both brackets are.

$$\widetilde{T}(V, w) - T(V, w)$$

$$= [V, w]_{\widetilde{V}} - [V, w]$$

$$- [V, w]_{V} + [V, w]$$

$$= \widetilde{\nabla}_{V} W - \widetilde{\nabla}_{w} V - \nabla_{v} W + \nabla_{w} V$$

$$\widetilde{T}_{ab} - T_{ab} = -C_{ab} + C_{ba}$$

$$= -Z C_{Eab}$$

$$V^{\alpha}(\widetilde{\nabla}_{\alpha} - \nabla_{\alpha})W^{\mu c} - W^{\alpha}(\widetilde{\nabla}_{\alpha} - \nabla_{\alpha})V^{c}$$

$$= -V^{\alpha} Cab^{c} W^{b} + W^{\alpha} Cab^{c} V^{b}$$

$$= -V^{\alpha} W^{b} (Cab^{c} - Cba^{c})$$

The torsion tensor is also related to the commutator of covariant derivatives of functions.

Vª Wb Tab C Vcf = (Dv W - Dw & - [V, w]) Def = (TV Wc - TW Vc - [V, W] C) Tct = Dr (Act) - M. Dr det - Dw(vc Dcf) + Vc Dw Dcf - W [v, w] (+) = V° Wd Vd Vcf - W° Vd Vd Vcf = -ZVCWd & Vcc Va] f 2 VEa Voj f = - tab C Vcf