

Network Systems Theory and Applications to Synchronous Power Flows

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2nd Colloquium Roberto Tempo on Automatica

CNR and Politecnico di Torino, Turin, Italy, Apr 12, 2019



During his service to CSS



CSS ExCom trip, May 2011, Maynooth and Dublin, Ireland

In Roberto's honor

- Colloquia Roberto Tempo on Automatica, CNR, Turin, Italy, 2018
- PReGio Roberto Tempo Award, IEIIT-CNR, Italy, 2017
- IEEE CDC Roberto Tempo Best Paper Award, IEEE Control Systems Society, 2019
- Plenary session "A Tribute in Memory of Roberto Tempo", IFAC World Congress, Toulouse, France, Jul 2017 (Youtube link)
- "Scaling Heights: Our Times Shared with Roberto Tempo," Plenary special session and technical tutorial session, IEEE Conference in Decision and Control, Melbourne Australia, Dec 2017
- Book: "Uncertainty in Complex Networked Systems: In Honor of Roberto Tempo" editor T. Başar, Springer, 2018
- and many others



Roberto's visits to UCSB

- 08nov10 "Design of Uncertain Complex Systems: A Randomization Viewpoint"
15nov11 "Information-based Complexity for Systems and Control: The Probabilistic Setting"
21oct14 "The PageRank Problem in Google: A Systems and Control Viewpoint"
22oct14 "Distributed Randomized Algorithms in Social and Sensor Networks"
09dec16 "**Belief System Dynamics in Social Networks**"

Center for Control, Dynamical systems and Computation
at University of California, Santa Barbara
presents

Belief System Dynamics in Social Networks
Roberto Tempo

Friday, December 9, 2016 | 1:30 PM | HFH 4164

The recent years have seen substantial activities towards the study of dynamic social networks, which prove useful to explain phenomena such as the propagation of information or the formation of consensus. These models have revealed some common principles regarding coordination and self-organization, including consensus protocols for distributed decision making. This discovery attracted the attention of many research communities to models of social dynamics, and led to the development of new fields of application, such as social robotics, social media, and other irregular behaviors.

The number of dynamic models which describe social group dynamics is currently growing. Their properties are not yet fully understood, and more work is needed to control dynamic viewpoints. In particular, some basic problems concerning identification, stability, convergence and robustness still remain unsolved. Furthermore, how useful are these models to describe the behavior of large groups in real social networks is still a widely open question. This seminar will present some recent and also future results in applications of belief system dynamics under logic constraints. This is joint work with N. Fradkov, A. Proskurnikov and S. Panagiotis.

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journal homepage: www.elsevier.com/locate/arecon

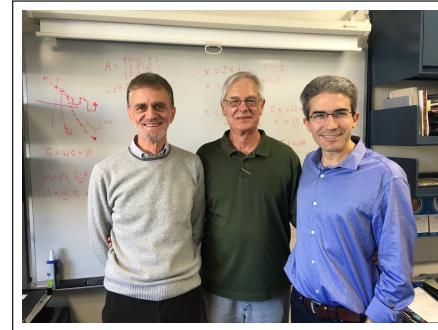
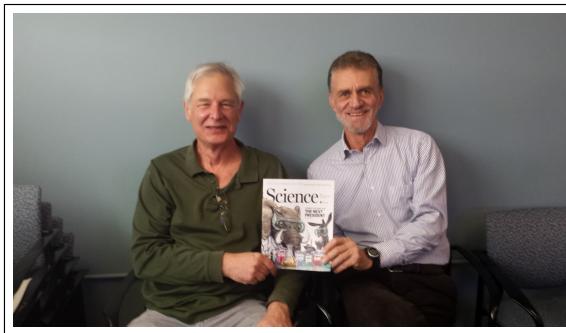
Review
A tutorial on modeling and analysis of dynamic social networks.
Part I^a

Anton V. Proskurnikov^{b,c}, Roberto Tempo^d

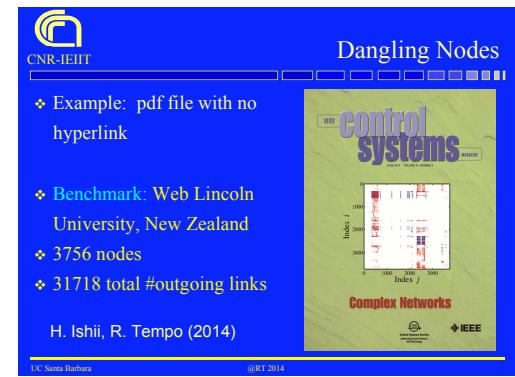
^aSISSA Center for Systems and Control, Dept. University of Technology, Delft, The Netherlands
^bSISSA University, Trieste, Italy
^cSISSA University, SI, Trieste, Italy
^dPolitecnico di Torino, Torino, Italy

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ABSTRACT
In recent years, we have observed a significant trend towards filling the gap between social network theory and its applications. The main idea is to model the dynamics of social groups, the advancement in complex networks theory and multi-agent systems, and the application of control theory to social systems. This review aims to provide a comprehensive overview of a new chapter of control theory, dealing with applications to social systems, in the attention of the recent achievements in the field of social network theory and its applications. We focus on the main concepts of social models of social dynamics and on their relation to the recent achievements in multi-agent systems.



Roberto and network systems



Torino is now a worldwide leading center on network systems, with contributions by Anton Proskurnikov, Chiara Ravazzi, Fabio Fagnani, Fabrizio Dabbene, Francesca Ceragioli, Giacomo Como, Giuseppe Calafiore, Paolo Frasca, ...

I imagine Roberto would be glad to hear us talk about these topics today

Acknowledgments

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Pushkarini Agharkar
Jeff Peters
Wenjun Mei



Saber Jafarpour
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Elizabeth Y. Huang
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Kevin D. Smith
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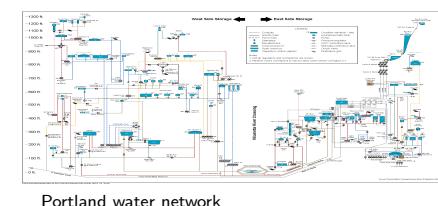
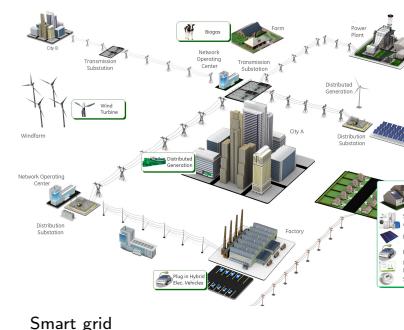
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Synchronization (existence)

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Network systems in sciences

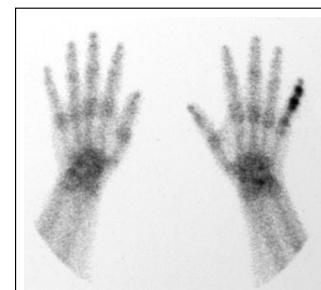
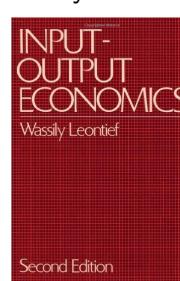
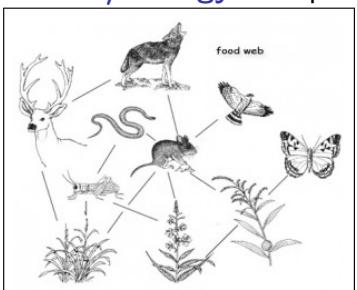
Sociology: opinion dynamics, propagation of information, performance of teams



Ecology: ecosystems and foodwebs

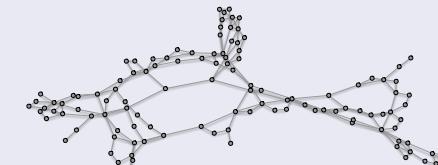
Economics: input-output models

Medicine/Biology: compartmental systems



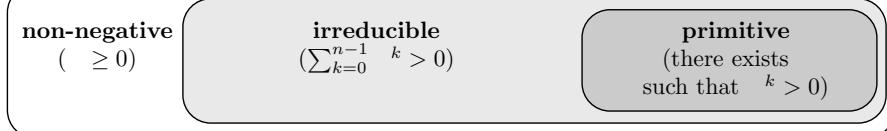
Linear network systems

$$x(k+1) = Ax(k) + b \quad \text{or} \quad \dot{x}(t) = Ax(t) + b$$



network structure \iff function = asymptotic behavior

Perron-Frobenius theory



if A non-negative

- ① eigenvalue $\lambda \geq |\mu|$ for all other eigenvalues μ
- ② right and left eigenvectors $v_{\text{right}} \geq 0$ and $v_{\text{left}} \geq 0$

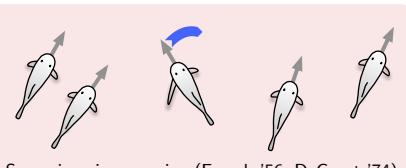
if A irreducible

- ③ $\lambda > 0$ and λ is simple
- ④ $v_{\text{right}} > 0$ and $v_{\text{left}} > 0$ are unique

if A primitive

- ⑤ $\lambda > |\mu|$ for all other eigenvalues μ
- ⑥ $\lim_{k \rightarrow \infty} A^k / \lambda^k = v_{\text{right}} v_{\text{left}}^T$, with normalization $v_{\text{right}}^T v_{\text{left}} = 1$

Averaging systems



Swarming via averaging (French '56, DeGroot '74)

$$x_i^+ := \text{average}(x_i, \{x_j, j \text{ is neighbor of } i\})$$

$$\downarrow$$

$$x(k+1) = Ax(k)$$

A influence matrix:

row-stochastic: non-negative and row-sums equal to 1

For general G with multiple condensed sinks
(assuming each condensed sink is aperiodic)

consensus at sinks
convex combinations elsewhere

consensus: $\lim_{k \rightarrow \infty} x(k) = (v_{\text{left}} \cdot x(0)) \mathbf{1}_n$
where v_{left} = left dominant eigenvector is social power

Algebraic graph theory

Powers of $A \sim$ paths in G :

$$(A^k)_{ij} > 0$$



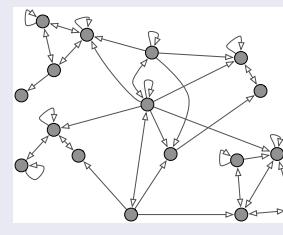
there exists directed path of length k
from i to j in G

Primitivity of $A \sim$ paths in G :

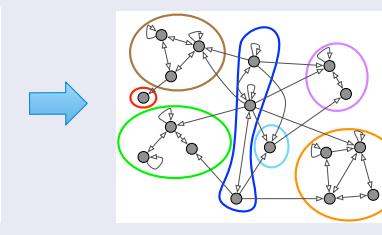
$$A \text{ is primitive} \\ (A \geq 0 \text{ and } A^k > 0)$$



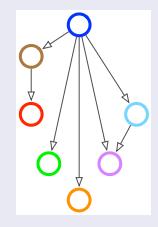
G strongly connected and aperiodic
(exists path between any two nodes) and
(exists no k dividing each cycle length)



digraph

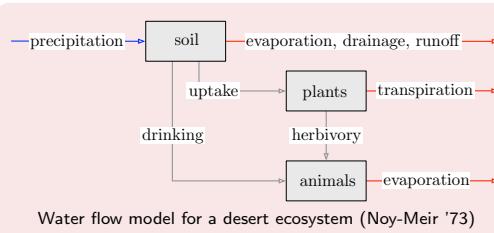


strongly connected components



condensation

Network flow systems



Water flow model for a desert ecosystem (Noy-Meir '73)

$$\dot{q}_i = \sum_j (F_{j \rightarrow i} - F_{i \rightarrow j}) - F_{i \rightarrow 0} + u_i$$

$$F_{i \rightarrow j} = f_{ij} q_i, \quad F = [f_{ij}]$$

$$\dot{q} = \underbrace{(F^T - \text{diag}(F \mathbf{1}_n + f_0))}_{=: C} q + u$$

C compartmental matrix:

quasi-positive (off-diag ≥ 0) and non-positive column sums ($f_0 \geq 0$)
analysis tools: *PF for quasi-positive, inverse positivity, algebraic graph*

system (= each condensed sink)
is outflow-connected



C is Hurwitz

$$\rightarrow \lim_{t \rightarrow \infty} q(t) = -C^{-1}u \geq 0$$

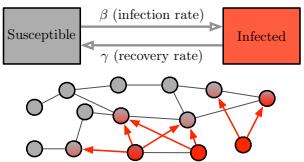
$(-C^{-1}u)_i > 0 \iff$ i th compartment is inflow-connected

Rich variety of emerging behaviors

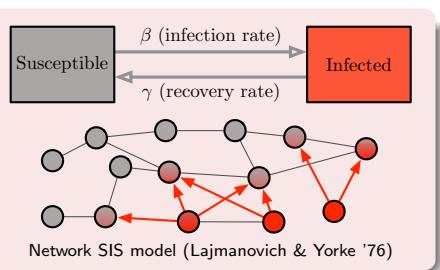
- ① equilibria / limit cycles / extinction in populations dynamics
- ② epidemic outbreaks in spreading processes
- ③ **synchrony and multi-stability in coupled oscillators**

Rich variety of analysis tools

- ① nonlinear stability theory
- ② passivity and dissipativity
- ③ contractivity and monotonicity



Network propagation in epidemiology



Network SIS: ($x_i = \text{infected fraction}$)

$$\dot{x}_i = \beta \sum_j a_{ij} (1 - x_j) x_j - \gamma x_i$$

(rescaling)

$$\dot{x} = (I_n - \text{diag}(x)) A x - x$$

contact matrix A: irreducible with dominant pair $(\lambda, v_{\text{right}})$

below the epidemic threshold: $\lambda < 1$

0 is unique stable equilibrium
 $v_{\text{right}}^T x(t) \rightarrow 0$ monotonically & exponentially

above the epidemic threshold: $\lambda > 1$

0 is unstable equilibrium
unique other equilibrium $x^* > 0$
 $\lim_{t \rightarrow \infty} x(t) = x^*$



Mutualism clownfish / anemones (Takeuchi et al '78)

Lotka-Volterra: $x_i = \text{quantity/density}$

$$\frac{\dot{x}_i}{x_i} = b_i + \sum_j a_{ij} x_j$$

$$\dot{x} = \text{diag}(x)(Ax + b)$$

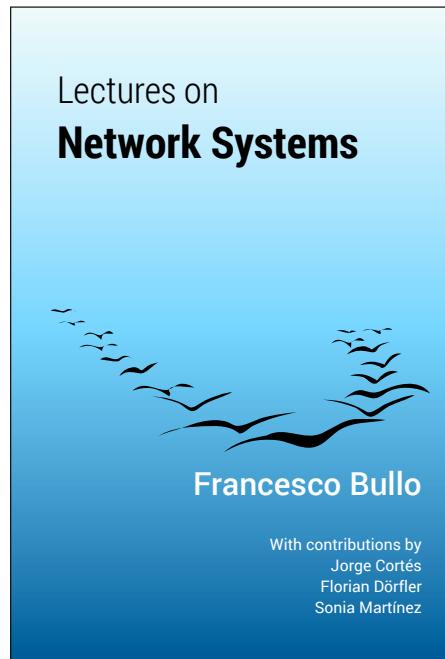
interaction matrix A:

(+, +) mutualism, (+, -) predation, (-, -) competition
rich behavior: persistence, extinction, equilibria, periodic orbits, ...

- ① **bounded resources:** A Hurwitz (e.g., irreducible and neg diag dom)
- ② **logistic growth:** $b_i > 0$ and $a_{ii} < 0$
- ③ **mutualism:** $a_{ij} \geq 0$

exists unique steady state $-A^{-1}b > 0$
 $\lim_{t \rightarrow \infty} x(t) = -A^{-1}b$ from all $x(0) > 0$

New text "Lectures on Network Systems"



[Lectures on Network Systems](#), Francesco Bullo, Createspace, 1 edition, 2018, ISBN 978-1-986425-64-3

1. Self-Published and Print-on-Demand at:
<https://www.amazon.com/dp/1986425649>
2. PDF Freely available at
<http://motion.me.ucsb.edu/book-lns>:
For students: free PDF for download
For instructors: slides, classnotes, and answer keys
3. incorporates lessons from 2 decades of research:
robotic multi-agent, social networks, power grids
4. now v1.2
v2.0 will expand nonlinear coverage

300 pages
200 pages solution manual
4K downloads since Jun 2016
150 exercises with solutions
31 instructors in 14 countries

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- ① problem statement
- ② solution

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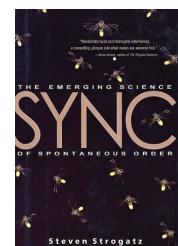
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Motivation

1 Pendulum clocks & “*an odd kind of sympathy*”

[Christiaan Huygens, *Horologium Oscillatorium*, 1673]



2 Local canonical model for weakly-coupled limit-cycle oscillators

[Hoppensteadt et al. '97, Brown et al. '04]

3 Simplest “*network system on manifold*” with rich phenomenology

1 Countless sync phenomena in sciences/engineering
scholar.google: Winfree '67 1.5K, Kuramoto '75 6.8K,
surveys by Strogatz, Acebron, Arenas: 2K citations each

Applications in sciences: biology: pacemaker cells in the heart, circadian cells in the brain, coupled cortical neurons, Hodgkin-Huxley neurons, brain networks, yeast cells, flashing fireflies, chirping crickets, central pattern generators for animal locomotion, particle models mimicking animal flocking behavior, and fish schools

physics and chemistry: spin glass models,

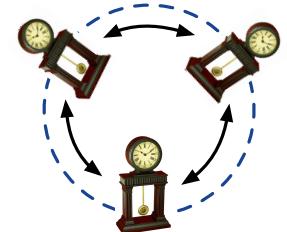
Applications in engineering: deep brain stimulation, locking in solid-state circuit oscillators, planar vehicle coordination, carrier synchronization without phase-locked loops, semiconductor laser arrays, and microwave oscillator arrays

electric applications: structure-preserving and network-reduced power system models, and droop-controlled inverters in microgrids

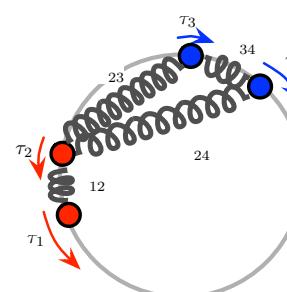
Kuramoto model

- **n oscillators** with angle $\theta_i \in \mathbb{S}^1$
- **non-identical** natural frequencies $\omega_i \in \mathbb{R}^1$
- **coupling** with strength $a_{ij} = a_{ji}$

$$\dot{\theta}_i = \omega_i - \sum_{j=1}^n a_{ij} \sin(\theta_i - \theta_j)$$



Model #1: Spring network analog and applications



Coupled swing equations

Euler-Lagrange eq for spring network on ring:

$$m_i \ddot{\theta}_i + d_i \dot{\theta}_i = \tau_i - \sum_j k_{ij} \sin(\theta_i - \theta_j)$$

Kuramoto coupled oscillators

$$\dot{\theta}_i = \omega_i - \sum_j a_{ij} \sin(\theta_i - \theta_j)$$

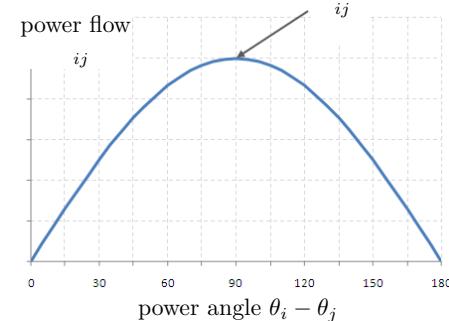
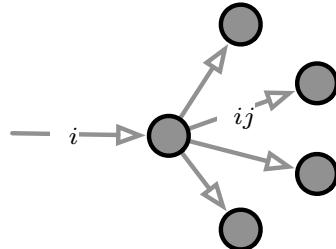
Kuramoto equilibrium equation

$$0 = \omega_i - \sum_j a_{ij} \sin(\theta_i - \theta_j)$$

Model #2: Active Power Flow Problem

AC, Kirckhoff and Ohm, quasi-sync, lossless lines, constant voltages.
supply/demand p_i , max power coeff a_{ij} , voltage phase θ_i

$$p_i = \sum_{j=1}^n f_{ij}, \quad f_{ij} = a_{ij} \sin(\theta_i - \theta_j)$$

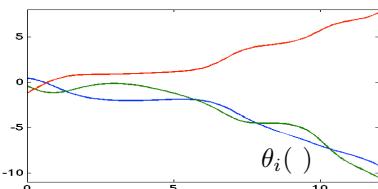


Given: network parameters & topology, load & generation profile,

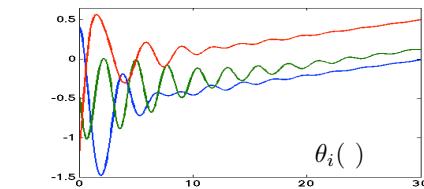
Phenomenon #1: Transition from incoherence to sync

Function = synchronization

$$\dot{\theta}_i = \omega_i - \sum_{j=1}^n a_{ij} \sin(\theta_i - \theta_j)$$



large $|\omega_i - \omega_j|$ & small coupling
 \Rightarrow incoherence = no sync



small $|\omega_i - \omega_j|$ & large coupling
 \Rightarrow coherence = frequency sync

- threshold: “heterogeneity” vs. “coupling”
- quantify: “heterogeneity” < “coupling”
- as function of network parameters

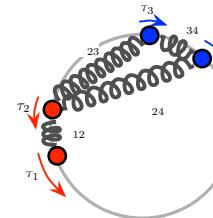
Flow / spring analogy

Active power flow problem

$$p_i = \sum_{j=1}^n a_{ij} \sin(\theta_i - \theta_j)$$

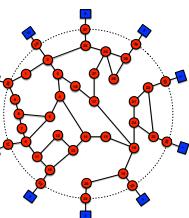
Spring network

- $p_i = \tau_i$: torque at i
- $a_{ij} = k_{ij}$: spring stiffness i,j
- $\sin(\theta_i - \theta_j)$: modulation



Power network

- p_i : injected power
- a_{ij} : max power flow i,j
- $\sin(\theta_i - \theta_j)$: modulation

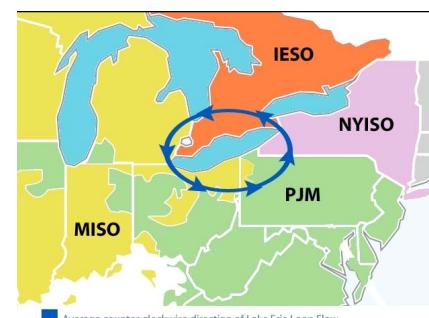


Phenomenon #2: Multiple power flows

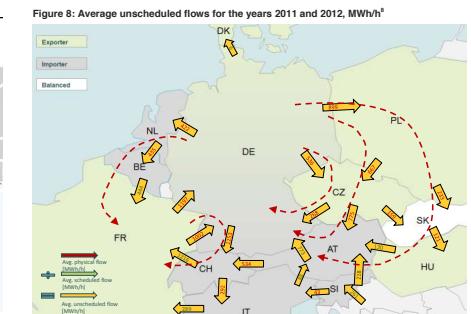
Theoretical observation: multiple solutions exist

Practical observations:

sometimes undesirable power flows around loops
 sometimes sizable difference between predicted and actual power flows



New York Independent System Operator, [Lake Erie Loop Flow Mitigation](#), Technical Report, 2008



Source: THEMA Consulting Group, based on data from 16 TSOs
 THEMA Consulting Group, [Loop-flows - Final advice](#), Technical Report prepared for the European Commission, 2013

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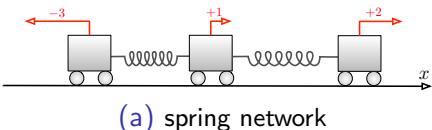
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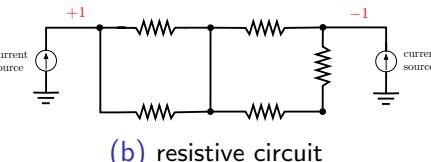
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Laplacian linear balance equation

Linear spring and resistive networks



$$L_{\text{stiffness}} X = f_{\text{load}}$$



and

$$L_{\text{conductance}} V = C_{\text{injected}}$$

Laplacian linear balance equation: $p_{\text{active}} = L\theta$

if $\sum_i p_i = 0$ in $p_{\text{active}} = L\theta$, then equilibrium exists : $\theta = L^\dagger p_{\text{active}}$
pairwise displacements : $B^\top \theta = B^\top L^\dagger p_{\text{active}}$

Weighted undirected graph with n nodes and m edges:

Incidence matrix: $n \times m$ matrix B s.t. $(B^\top p_{\text{active}})_{(ij)} = p_i - p_j$

Weight matrix: $m \times m$ diagonal matrix A

Laplacian stiffness: $L = BAB^\top \geq 0$

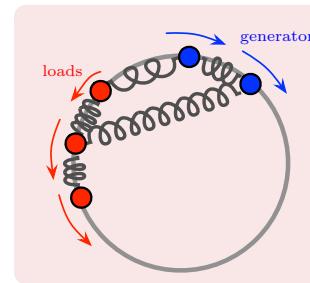
Linearization of Kuramoto equilibrium equation:

$$p_{\text{active}} = B\mathcal{A} \sin(B^\top \theta) \implies p_{\text{active}} \approx B\mathcal{A}(B^\top \theta) = L\theta$$

Algebraic connectivity:

$$\lambda_2(L) = \text{second smallest eig of } L \\ = \text{notion of connectivity and coupling}$$

From Old to New Tests



Given balanced p_{active} , do angles exist?

$$p_{\text{active}} = B\mathcal{A} \sin(B^\top \theta)$$

synchronization arises if
heterogeneity < coupling
power transmission < connectivity strength

Old Tests: Equilibrium angles (neighbors within $\pi/2$ arc) exist if

$$\|B^\top p_{\text{active}}\|_2 < \lambda_2(L) \quad \text{for unweighted graphs} \quad (\text{Old 2-norm T})$$

$$\|B^\top L^\dagger p_{\text{active}}\|_\infty < 1 \quad \text{for trees, complete} \quad (\text{Old } \infty\text{-norm T})$$

From Old to New Tests

Old Tests: Equilibrium angles (neighbors within $\pi/2$ arc) exist if

$$\begin{aligned} \|B^\top p_{\text{active}}\|_2 &< \lambda_2(L) & \text{for unweighted graphs} & \quad (\text{Old 2-norm T}) \\ \|B^\top L^\dagger p_{\text{active}}\|_\infty &< 1 & \text{for trees, complete} & \quad (\text{Old } \infty\text{-norm T}) \end{aligned}$$

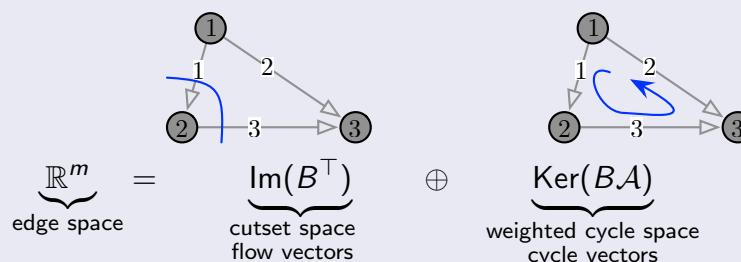


New Tests: Equilibrium angles (neighbors within $\pi/2$ arc) exist if

$$\begin{aligned} \|B^\top L^\dagger p_{\text{active}}\|_2 &< 1 & \text{for unweighted graphs} & \quad (\text{New 2-norm T}) \\ \|B^\top L^\dagger p_{\text{active}}\|_\infty &< g(\|\mathcal{P}\|_\infty) & \text{for all graphs} & \quad (\text{New } \infty\text{-norm T}) \end{aligned}$$

and where \mathcal{P} is a projection matrix

$\mathcal{P} = B^\top L^\dagger B A$ = oblique projection onto $\text{Im}(B^\top)$ parallel to $\text{Ker}(BA)$

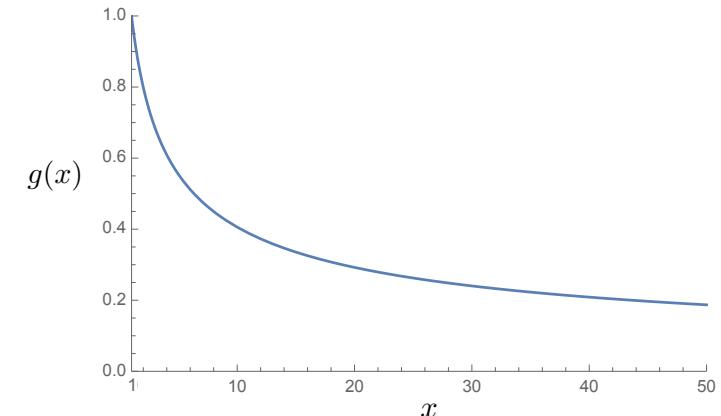


- ① if G unweighted, then \mathcal{P} is orthogonal and $\|\mathcal{P}\|_2 = 1$
- ② if G acyclic, then $\mathcal{P} = I_m$ and $\|\mathcal{P}\|_p = 1$
- ③ if G uniform complete or ring, then $\|\mathcal{P}\|_\infty = 2(n-1)/n \leq 2$

where g is monotonically decreasing

$$g : [1, \infty) \rightarrow [0, 1]$$

$$x \mapsto \frac{y(x) + \sin(y(x))}{2} - x \frac{y(x) - \sin(y(x))}{2} \Big|_{y(x) = \arccos\left(\frac{x-1}{x+1}\right)}$$



New Tests: Equilibrium angles (neighbors within $\pi/2$ arc) exist if

$$\begin{aligned} \|B^\top L^\dagger p_{\text{active}}\|_2 &< 1 & \text{for unweighted graphs} & \quad (\text{New 2-norm T}) \\ \|B^\top L^\dagger p_{\text{active}}\|_\infty &< g(\|\mathcal{P}\|_\infty) & \text{for all graphs} & \quad (\text{New } \infty\text{-norm T}) \end{aligned}$$



Unifying theorem with a family of tests

Equilibrium angles (neighbors within γ arc) exist if, in some p -norm,

$$\|B^\top L^\dagger p_{\text{active}}\|_p \leq \gamma \alpha_p(\gamma) \quad \text{for all graphs} \quad (\text{New } \alpha_p \text{ T})$$

where nonconvex optimization problem:

$$\alpha_p(\gamma) := \min \text{ amplification factor of } \mathcal{P} \text{ diag}[\text{sinc}(x)]$$

Comparison of sufficient and approximate sync tests

Any test predicts max transmittable power (before bifurcation).
Compare with numerically computed.

Test Case	ratio of test prediction to numerical computation			
	old 2-norm	new ∞ -norm	$g(\ \mathcal{P}\ _\infty) \approx 1$	α_∞ test <i>fmincon</i>
IEEE 9	16.54 %	73.74 %	92.13 %	85.06 % [†]
IEEE 14	8.33 %	59.42 %	83.09 %	81.32 % [†]
IEEE RTS 24	3.86 %	53.44 %	89.48 %	89.48 % [†]
IEEE 30	2.70 %	55.70 %	85.54 %	85.54 % [†]
IEEE 118	0.29 %	43.70 %	85.95 %	—*
IEEE 300	0.20 %	40.33 %	99.80 %	—*
Polish 2383	0.11 %	29.08 %	82.85 %	—*

[†] *fmincon* with 100 randomized initial conditions

* *fmincon* does not converge

Outline

Introduction to Network Systems

- 1 F. Bullo. *Lectures on Network Systems*.
CreateSpace, 1 edition, 2018.
With contributions by J. Cortés, F. Dörfler, and S. Martínez.
URL: <http://motion.me.ucsb.edu/book-lns>

Synchronization (existence)

- ② S. Jafarpour and F. Bullo. *Synchronization of Kuramoto oscillators via cutset projections*. *IEEE Transactions on Automatic Control*, 2018.
doi:10.1109/TAC.2018.2876786

Multi-Stability (lack of uniqueness)

- ③ S. Jafarpour, E. Y. Huang, K. D. Smith, and F. Bullo. Multistable synchronous power flows: From geometry to analysis and computation. January 2019.
URL: <https://arxiv.org/pdf/1901.11189.pdf>

Summary: Kuramoto equilibrium and active power flow

Given topology (incidence B), admittances (Laplacian L), injections p_{active} ,

$$p_i = \sum_{j=1}^n a_{ij} \sin(\theta_i - \theta_j)$$

Equilibrium angles exist if, in some p -norm,

$$\|B^\top L^\dagger p_{\text{active}}\|_p \leq \gamma \alpha_p(\gamma) \quad \text{for all graphs} \quad (\text{New } \alpha_p \text{ T})$$

For $p = \infty$, after bounding,

$$\|B^\top L^\dagger p_{\text{active}}\|_\infty \leq g(\|\mathcal{P}\|_\infty) \quad (\text{New } \infty\text{-norm T})$$

Q1: \exists a **stable operating point** (with pairwise angles $\leq \gamma$)?

Q2: what is the **network capacity** to transmit active power?

Q3: how to quantify **robustness** as distance from loss of feasibility?

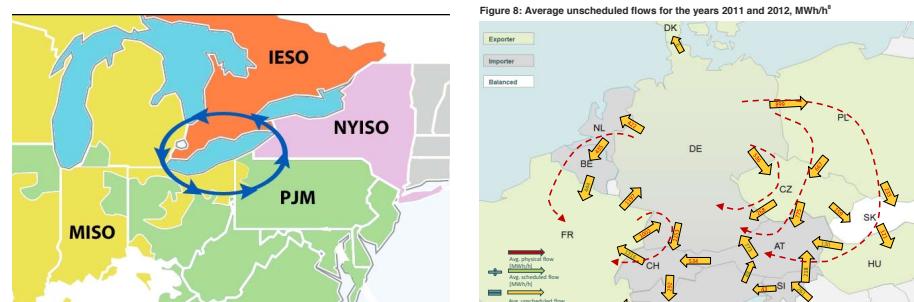
Phenomenon #2: Multiple power flows

Theoretical observation: multiple solutions exist

Practical observations:

sometimes undesirable power flows around loops

sometimes sizable difference between predicted and actual power flows



New York Independent System Operator, Lake Erie
Load Flow Mitigation, Technical Report, 2008

THEMA Consulting Group, **Loop-flows - Final advice**, Technical Report prepared for the European Commission, 2013.

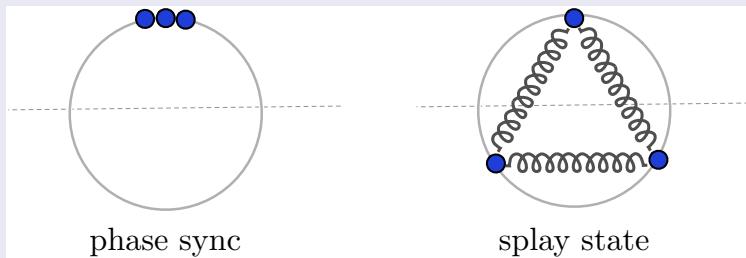
Lack of uniqueness and winding solutions

Given topology (incidence B), admittances (Laplacian L), injections p_{active} ,

$$p_i = \sum_{j=1}^n a_{ij} \sin(\theta_i - \theta_j)$$

- ➊ is solution unique?
- ➋ how to localize/classify solutions?

triangle graph, homogeneous weights ($a_{ij} = 1$), $p_{\text{active}} = 0$



"Kirckhoff Angle Law" and partition of the n -torus

Theorem: Kirchhoff angle law on \mathbb{T}^n

$$\begin{aligned} w_\sigma(\theta) &= 0, \pm 1, \dots, \pm \lfloor n_\sigma / 2 \rfloor \\ \implies w(\theta) &\text{ is piecewise constant} \\ \implies w(\theta) &\text{ takes value in a finite set} \end{aligned}$$



Theorem: Winding partition

For each possible winding vector u , define

$$\text{WindingCell}(u) := \{\theta \in \mathbb{T}^n \mid w(\theta) = u\}$$

Then

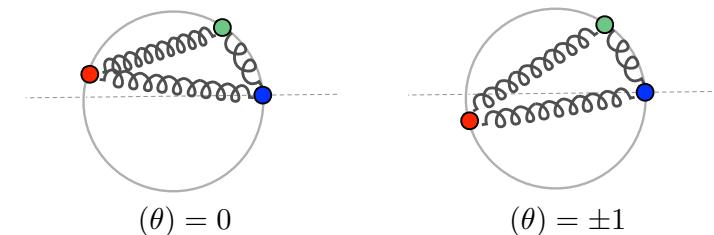
$$\mathbb{T}^n = \bigcup_u \text{WindingCell}(u)$$

Winding number of n angles

Given undirected graph with a cycle $\sigma = (1, \dots, n_\sigma)$ and orientation

- ➊ winding number of $\theta \in \mathbb{T}^n$ along σ is:

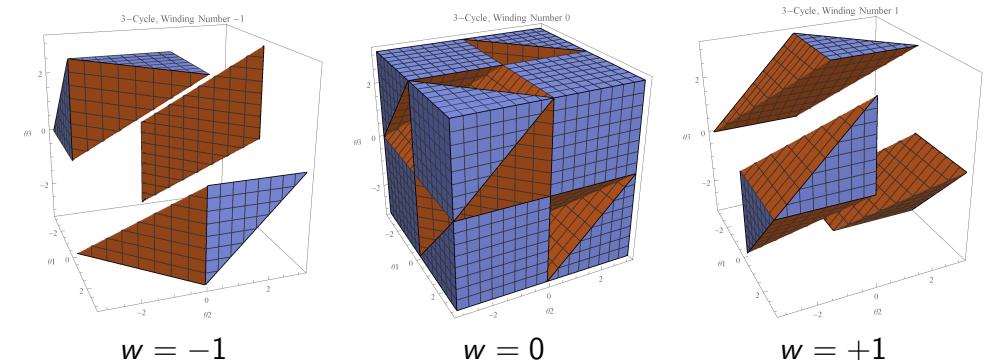
$$w_\sigma(\theta) = \frac{1}{2\pi} \sum_{i=1}^{n_\sigma} d_{cc}(\theta_i, \theta_{i+1})$$



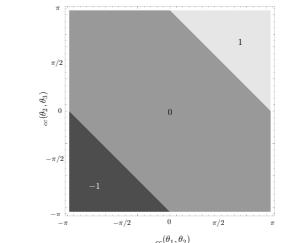
- ➋ given basis $\sigma_1, \dots, \sigma_r$ for cycles, winding vector of θ is

$$w(\theta) = (w_{\sigma_1}(\theta), \dots, w_{\sigma_r}(\theta))$$

Winding partition of triangle graph



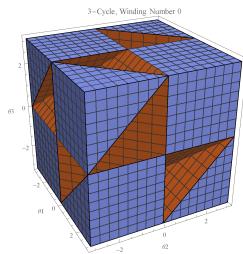
- each winding cell is connected
- each winding cell is invariant under rotation
- bijection:
reduced winding cell \longleftrightarrow open convex polytope



The Kuramoto model and the winding partition

Given topology (incidence B), admittances (Laplacian L), injections p_{active} ,

$$\dot{\theta}_i = p_i - \sum_j a_{ij} \sin(\theta_i - \theta_j)$$



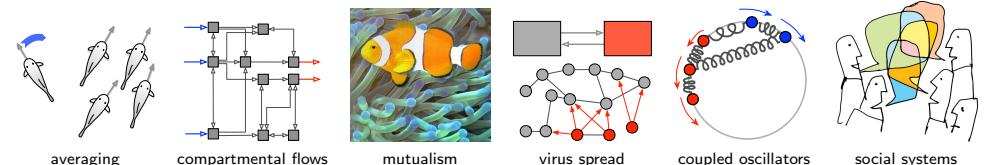
Theorem: At-most-uniqueness and extensions

- ① each WindingCell has at-most-unique equilibrium with $\Delta\theta < \pi/2$
- ② equilibrium loop flow increases monotonically wrt winding number
- ③ existence + uniqueness in $\text{WindingCell}(u)$ with $\Delta\theta < \pi/2$ if

$$\|B^\top L^\dagger p_{\text{active}} + Cu\|_\infty \leq g(\|\mathcal{P}\|_\infty), \text{ or} \quad (\text{Static T})$$

\exists a trajectory inside $\text{WindingCell}(u)$ with $\Delta\theta < \pi/2$ (Dynamic T)

Summary and Future Work



Contributions

- ① an emergent theory of network systems
- ② trade-off between coupling strength and oscillator heterogeneity
- ③ algebraic graph theory of the torus

Future research

- ① close the gap between sufficient and necessary conditions
- ② more realistic power flow equations
- ③ applications to other dynamic flow networks
- ④ **outreach/collaboration opportunities for our community with sociologists, biologists, economists, physicists ...**