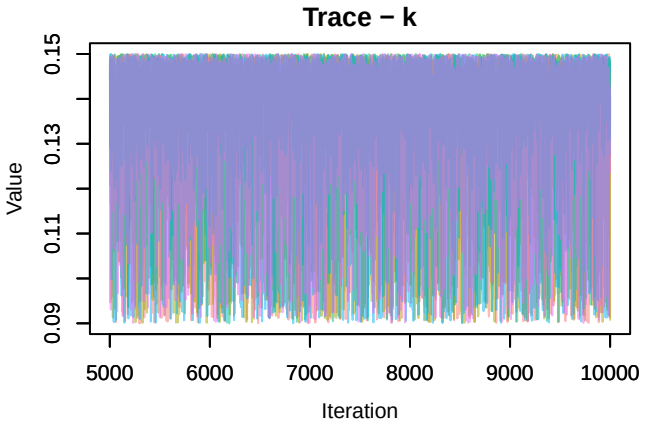
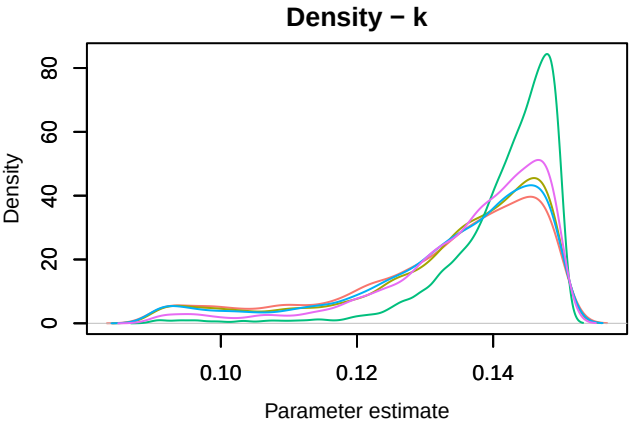
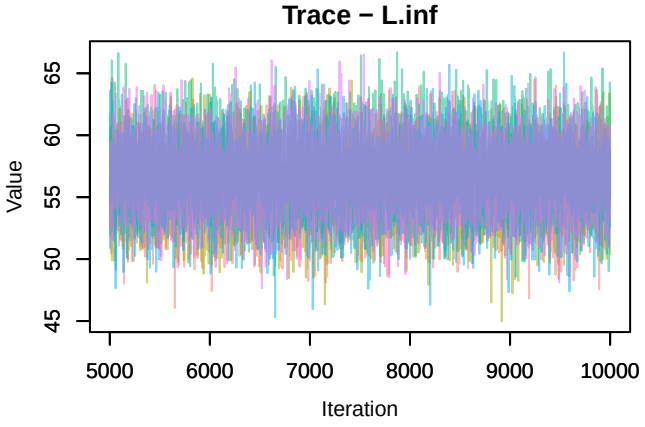
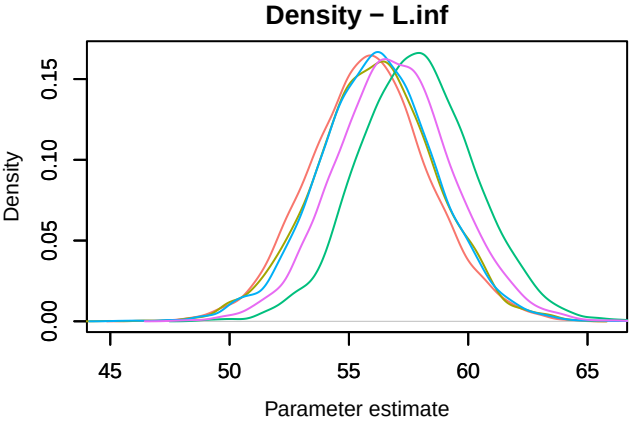
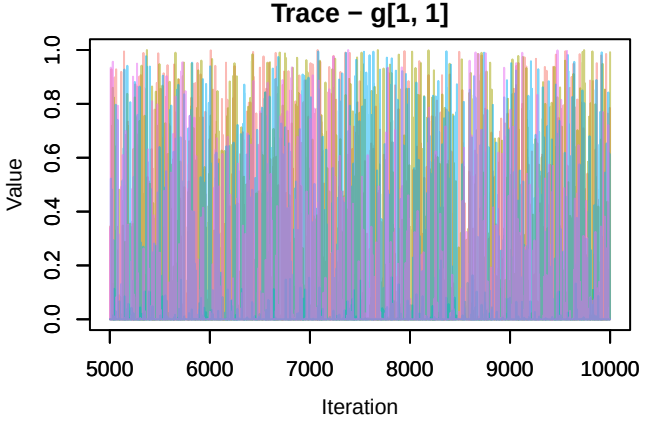
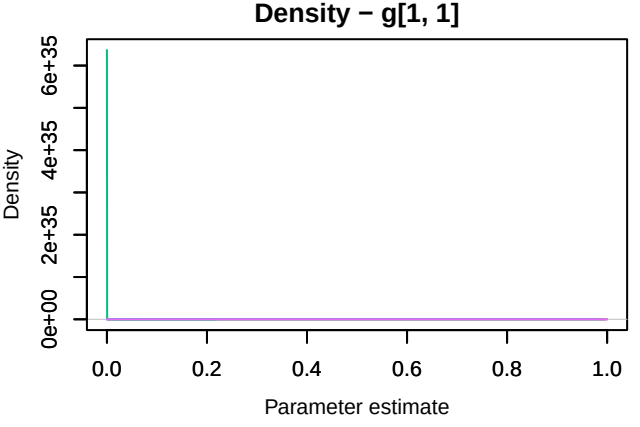

Trace − k
Value
0.09
0.11
0.13
0.15
5000
6000
7000
8000
9000
10000
Iteration

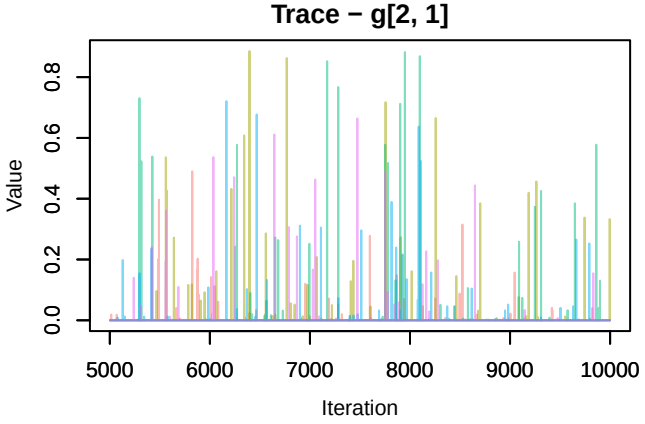

Density − k
Density
0
20
40
60
80
0.10
0.12
0.14
Parameter estimate

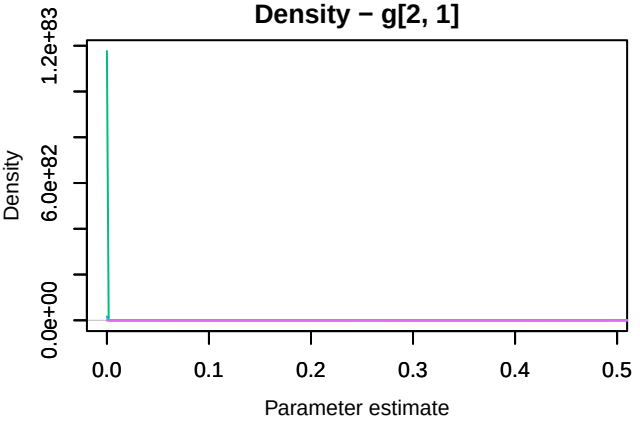

Trace − L.inf
Value
45
50
55
60
65
5000
6000
7000
8000
9000
10000
Iteration

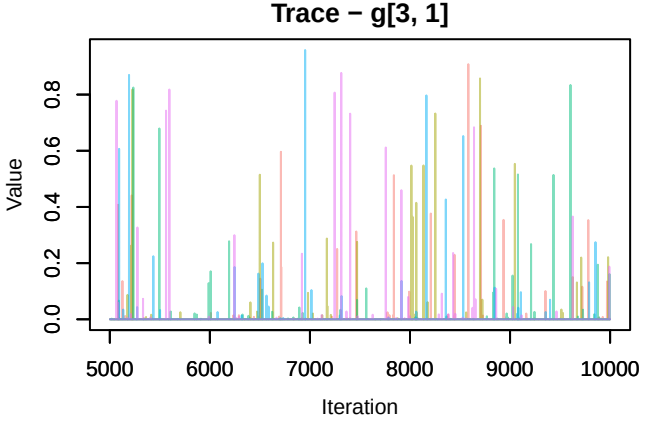

Density − L.inf
Density
0.00
0.05
0.10
0.15
45
50
55
60
65
Parameter estimate

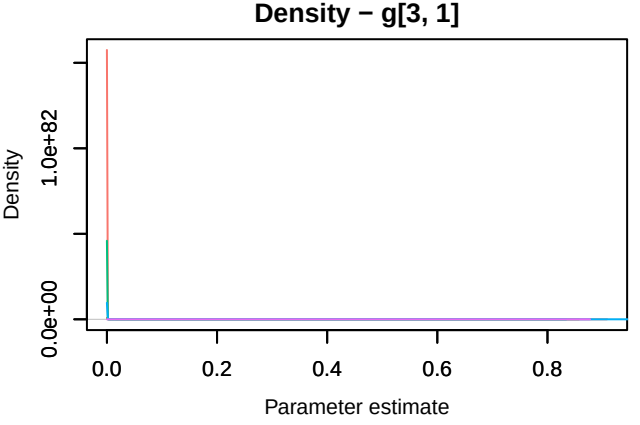

Trace − g[1, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

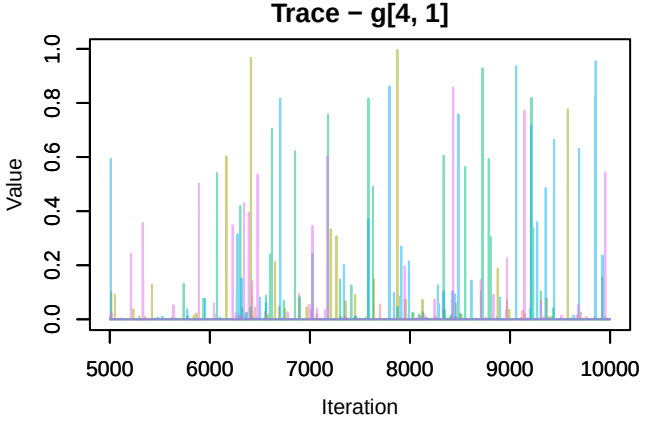

Density − g[1, 1]
Density
0e+00
2e+35
4e+35
6e+35
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

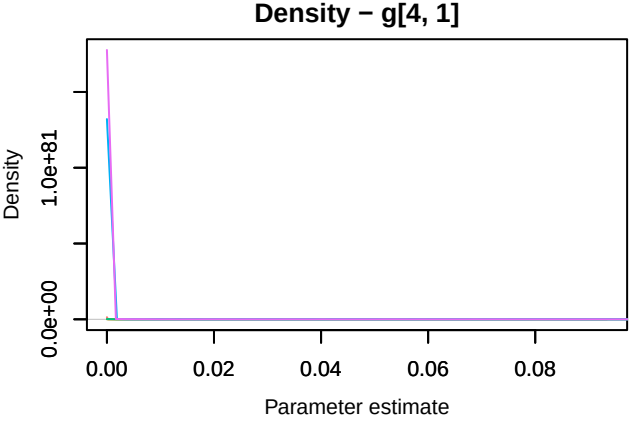

Trace − g[2, 1]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

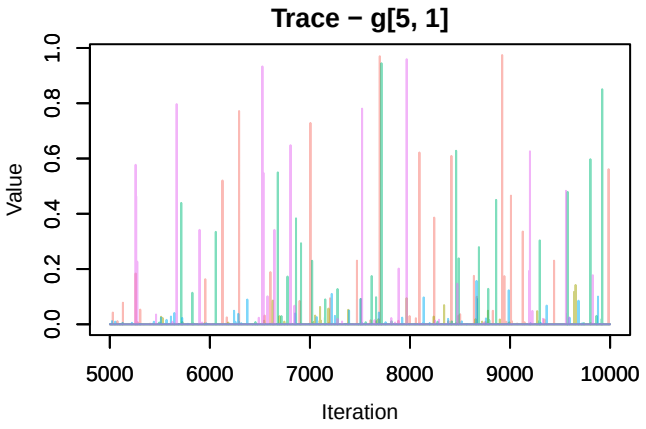

Density − g[2, 1]
Density
0.0e+00
6.0e+82
1.2e+83
0.0
0.1
0.2
0.3
0.4
0.5
Parameter estimate

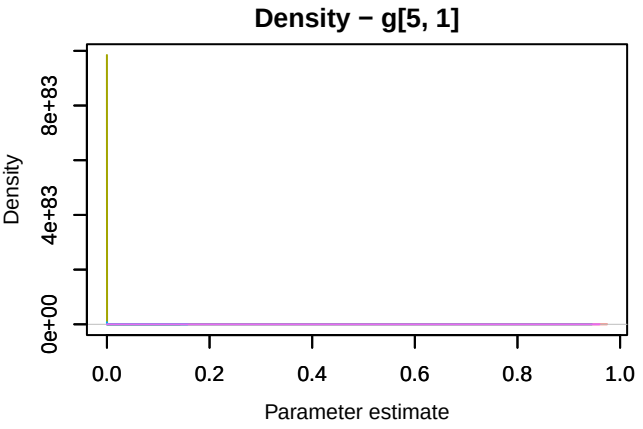

Trace − g[3, 1]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

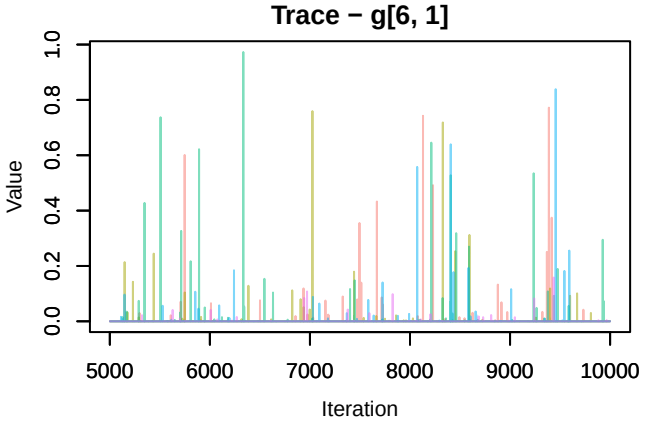

Density − g[3, 1]
Density
0.0e+00
1.0e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

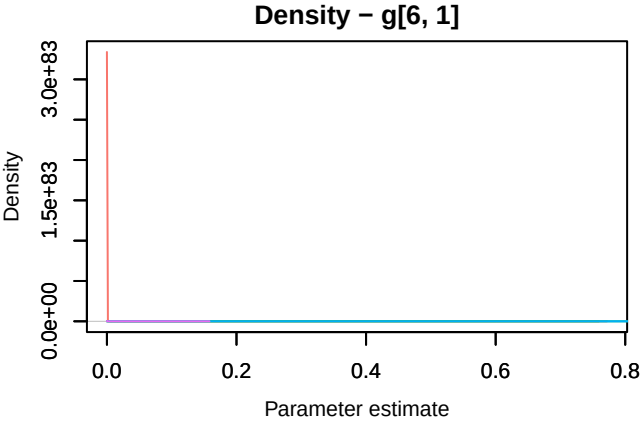

Trace − g[4, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

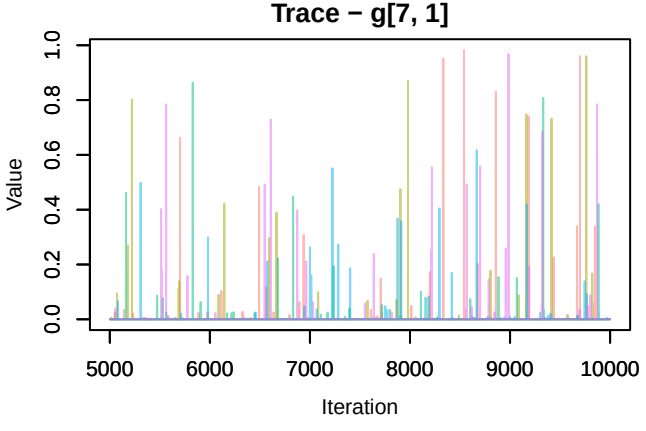

Density − g[4, 1]
Density
0.0e+00
1.0e+81
0.00
0.02
0.04
0.06
0.08
Parameter estimate

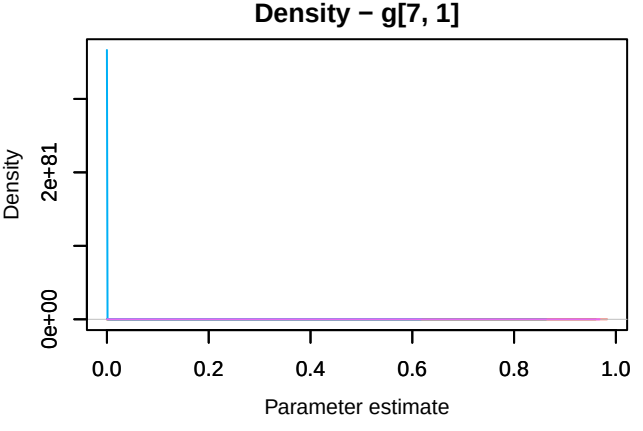

Trace − g[5, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

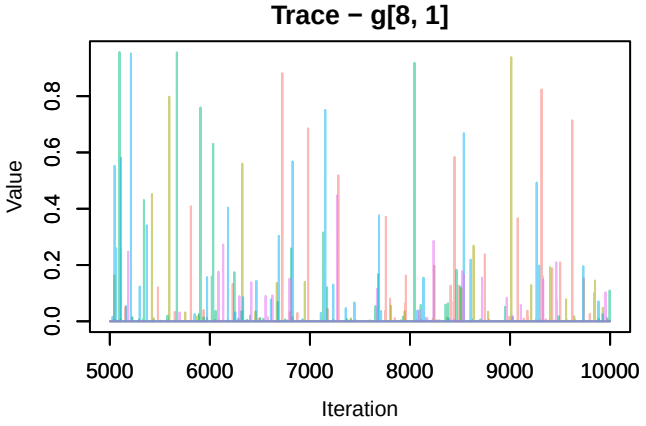

Density − g[5, 1]
Density
0e+00
4e+83
8e+83
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

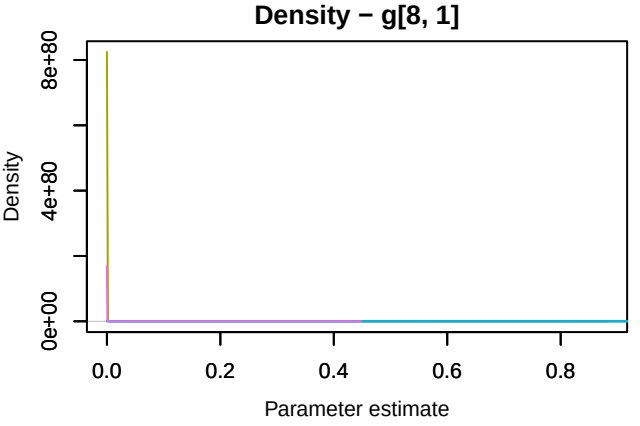

Trace − g[6, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

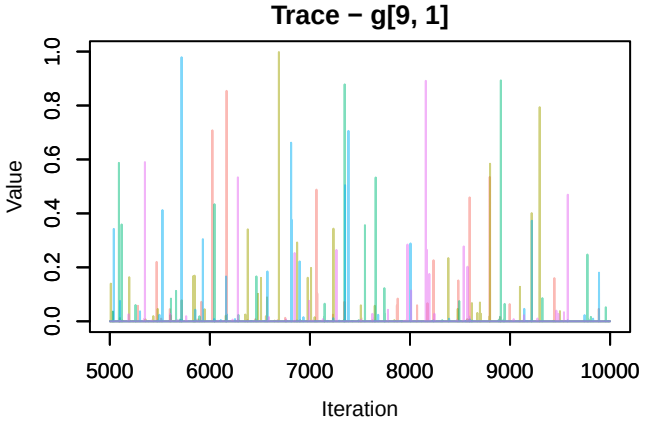

Density − g[6, 1]
Density
0.0e+00
1.5e+83
3.0e+83
0.0
0.2
0.4
0.6
0.8
Parameter estimate

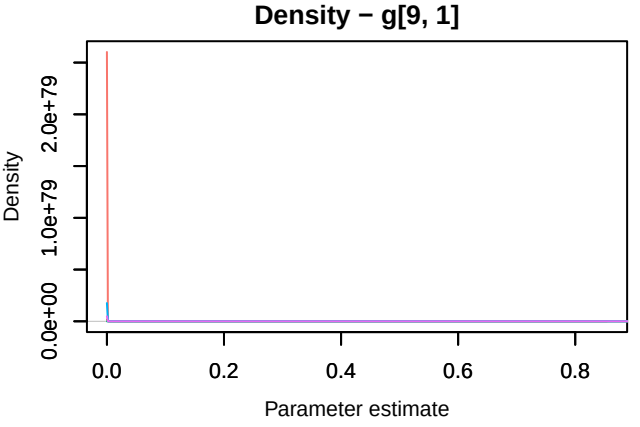

Trace − g[7, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

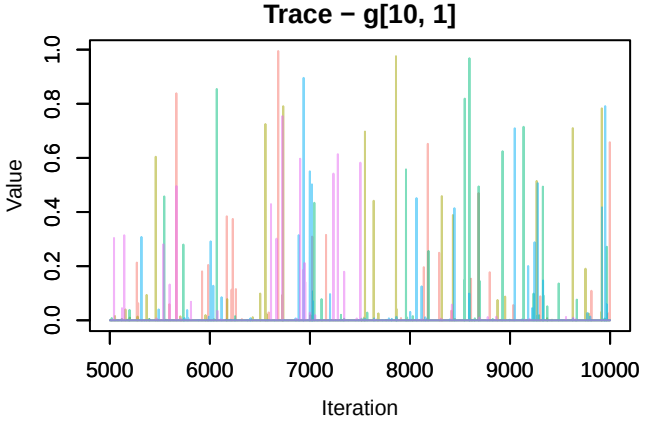

Density − g[7, 1]
Density
0e+00
2e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

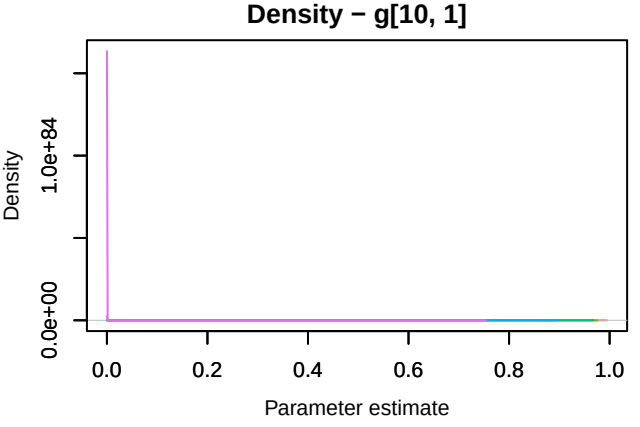

Trace − g[8, 1]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

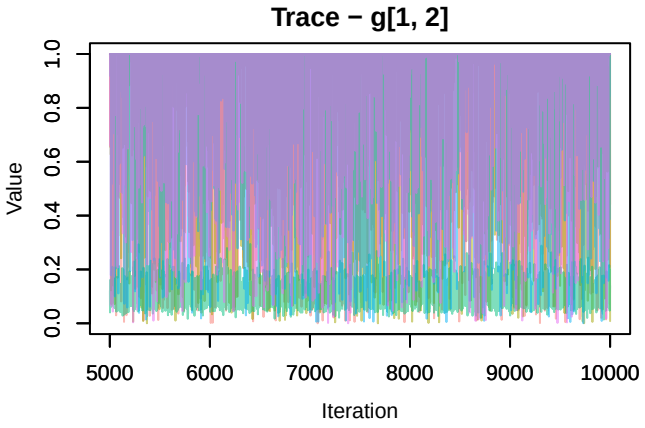

Density − g[8, 1]
Density
0e+00
4e+80
8e+80
0.0
0.2
0.4
0.6
0.8
Parameter estimate

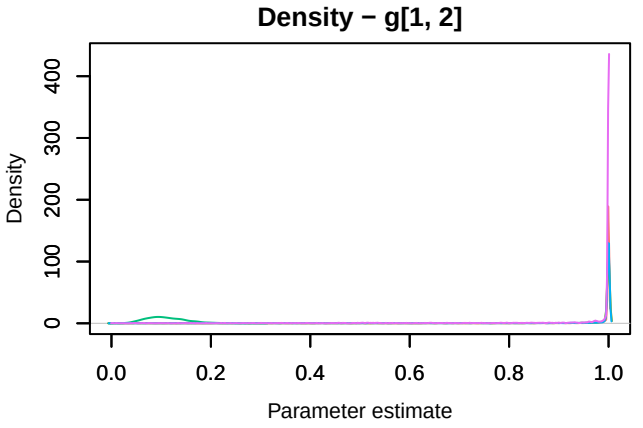

Trace − g[9, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

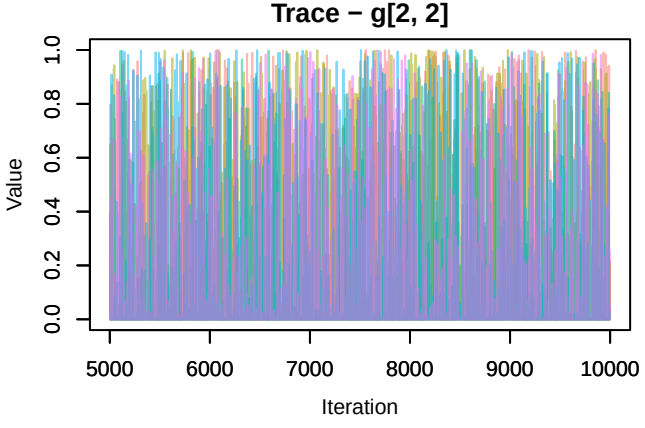

Density − g[9, 1]
Density
0.0e+00
1.0e+79
2.0e+79
0.0
0.2
0.4
0.6
0.8
Parameter estimate

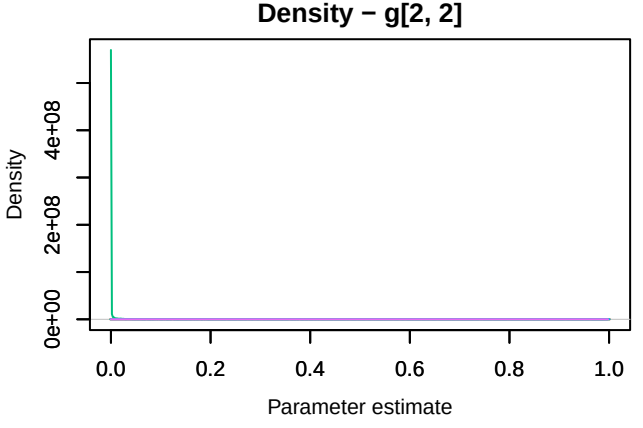

Trace − g[10, 1]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

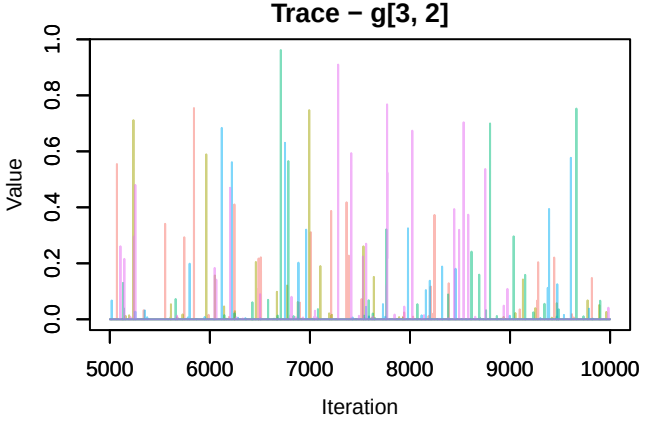

Density − g[10, 1]
Density
0.0e+00
1.0e+84
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

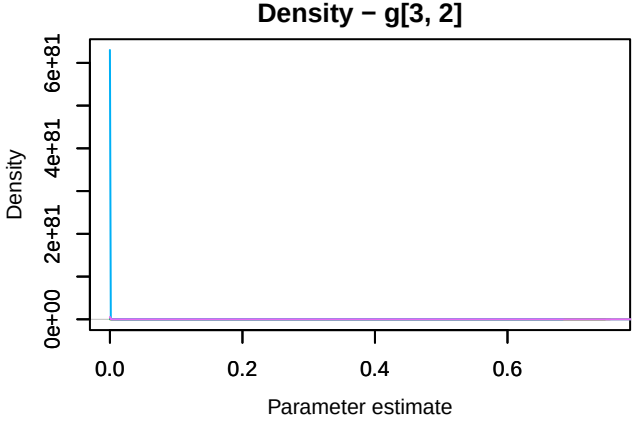

Trace − g[1, 2]
Value
Iteration
5000
6000
7000
8000
9000
10000
0.0
0.2
0.4
0.6
0.8
1.0

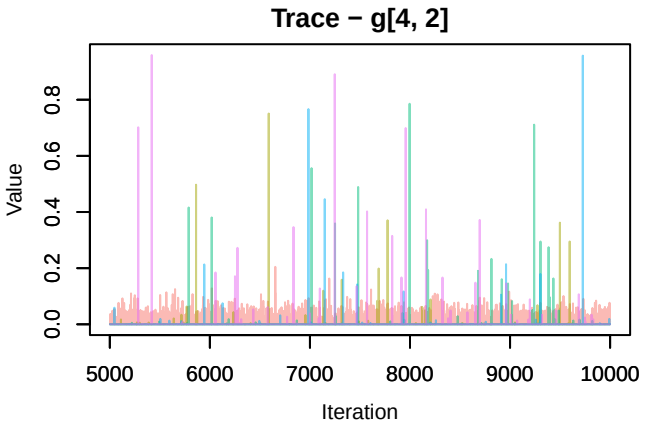

Density − g[1, 2]
Density
Parameter estimate
0
100
200
300
400
0.0
0.2
0.4
0.6
0.8
1.0

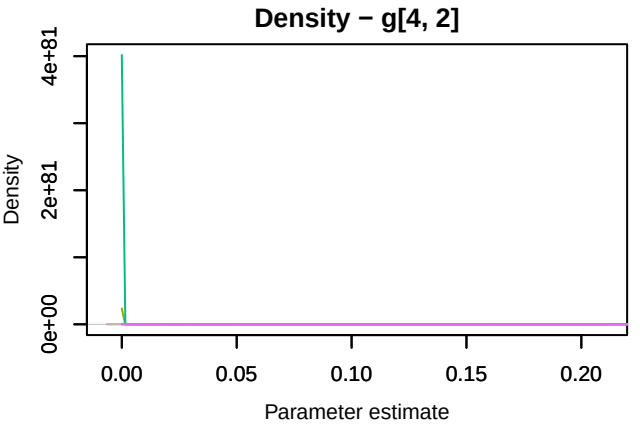

Trace − g[2, 2]
Value
Iteration
5000
6000
7000
8000
9000
10000
0.0
0.2
0.4
0.6
0.8
1.0

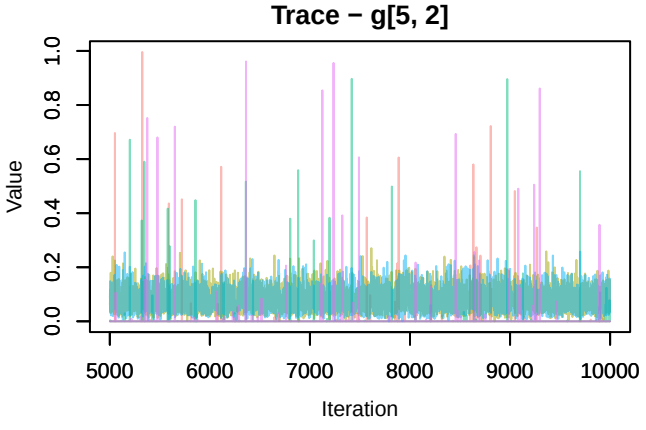

Density − g[2, 2]
Density
Parameter estimate
0e+00
2e+08
4e+08
0.0
0.2
0.4
0.6
0.8
1.0

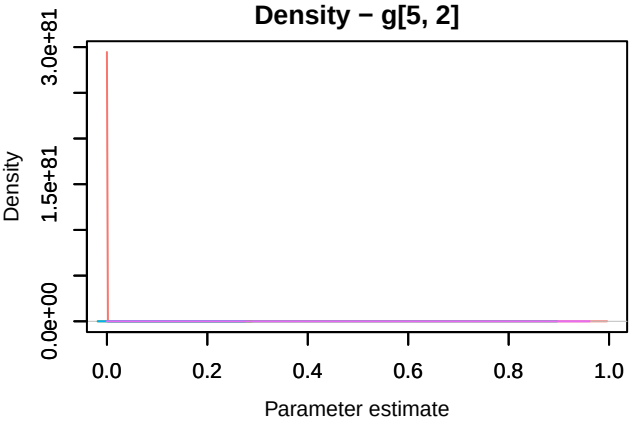

Trace − g[3, 2]
Value
Iteration
5000
6000
7000
8000
9000
10000
0.0
0.2
0.4
0.6
0.8
1.0

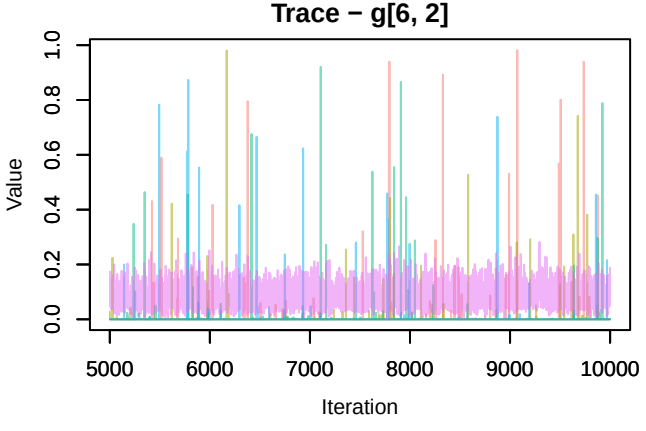

Density − g[3, 2]
Density
Parameter estimate
0e+00
2e+81
4e+81
6e+81
0.0
0.2
0.4
0.6

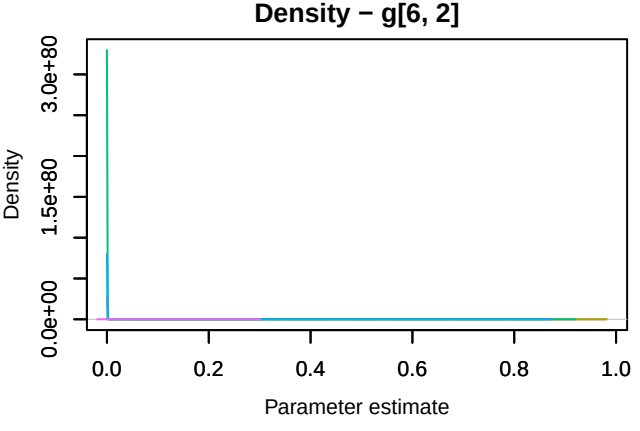

Trace − g[4, 2]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

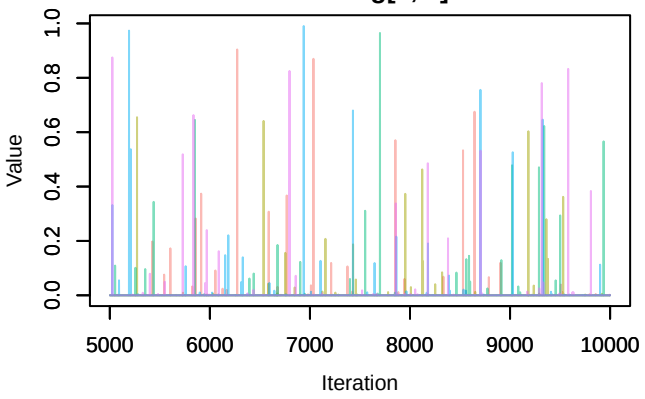

Density − g[4, 2]
Density
0e+00
2e+81
4e+81
0.00
0.05
0.10
0.15
0.20
Parameter estimate

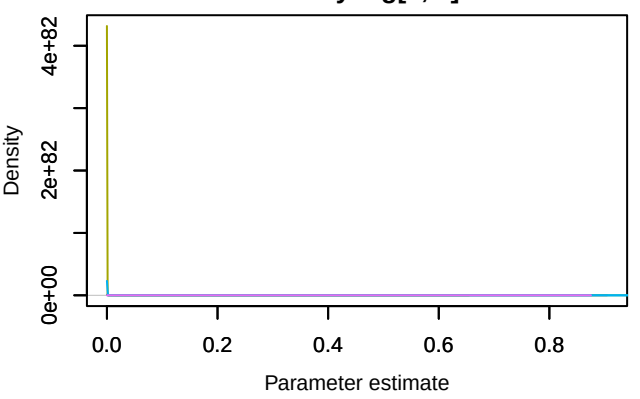

Trace − g[5, 2]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

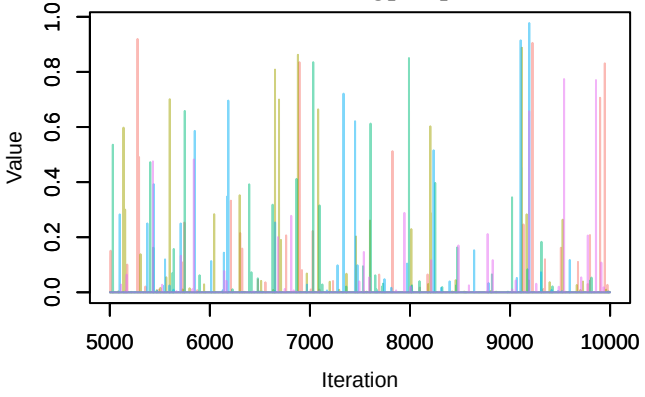

Density − g[5, 2]
Density
0.0e+00
1.5e+81
3.0e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

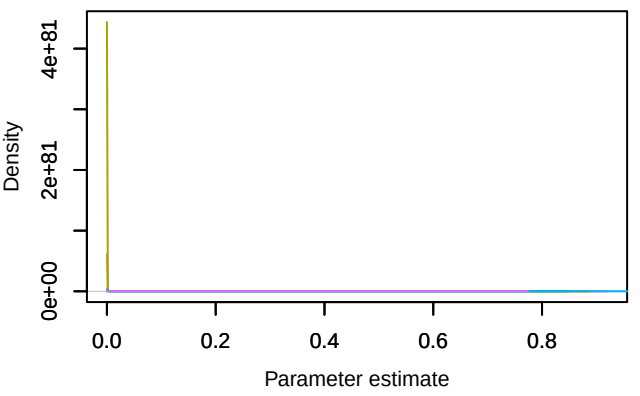

Trace − g[6, 2]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

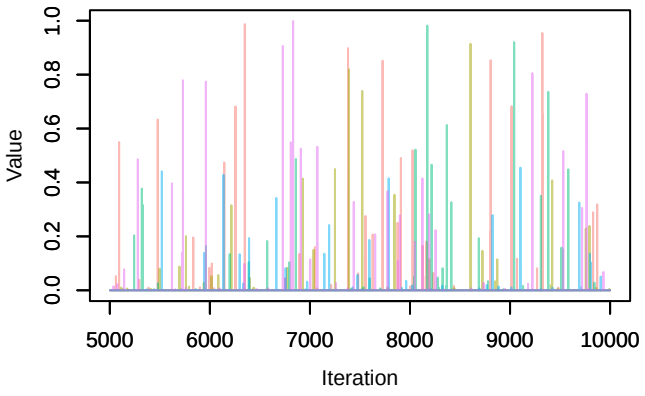

Density − g[6, 2]
Density
0.0e+00
1.5e+80
3.0e+80
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

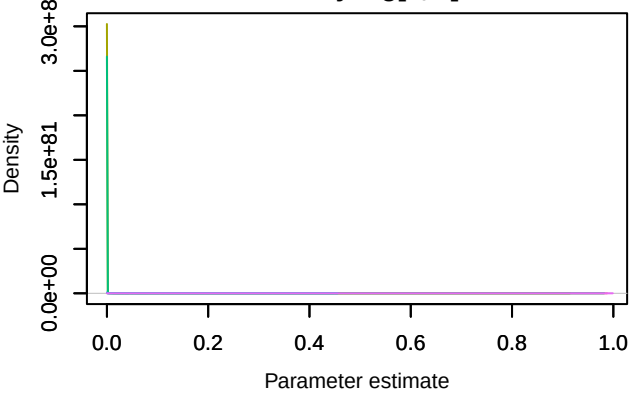

Trace − g[7, 2]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

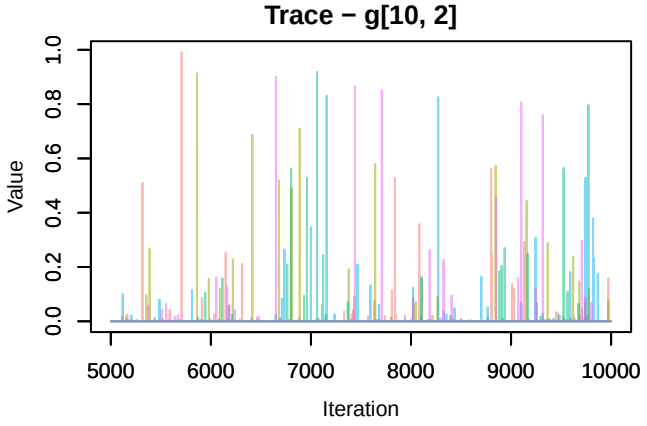

Density − g[7, 2]
Density
0e+00
2e+82
4e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

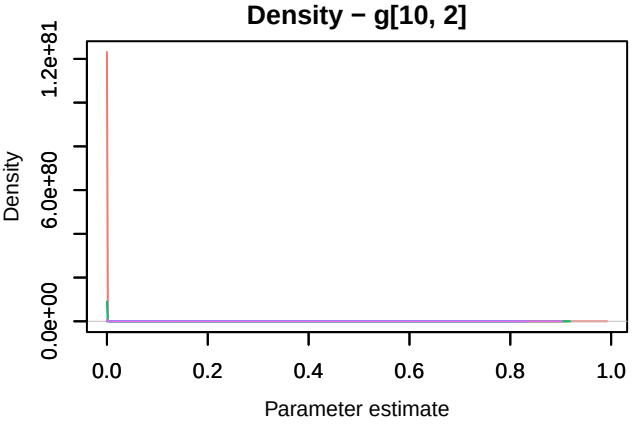

Trace − g[8, 2]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

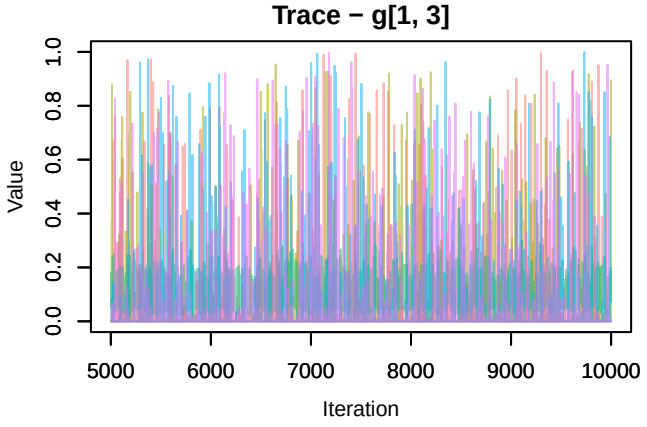

Density − g[8, 2]
Density
0e+00
2e+81
4e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

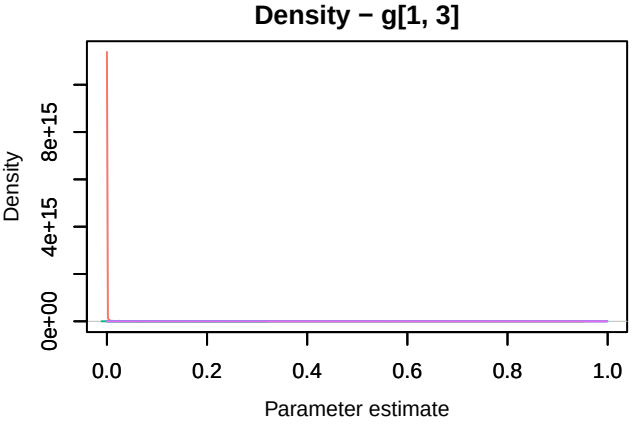

Trace − g[9, 2]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

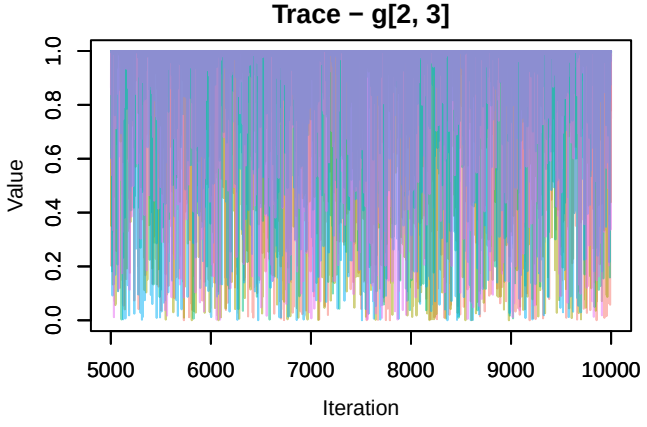

Density − g[9, 2]
Density
0.0e+00
1.5e+81
3.0e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

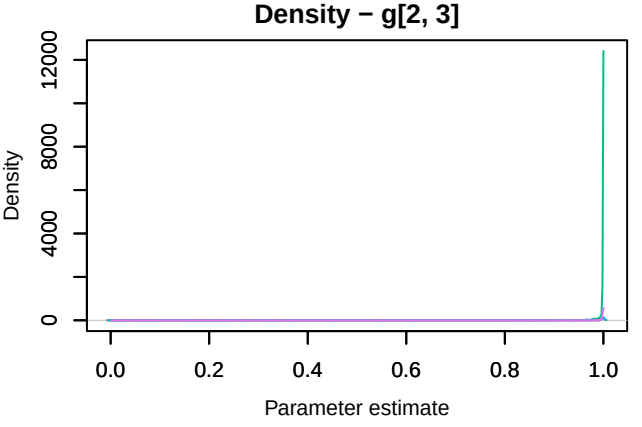

Trace − g[10, 2]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

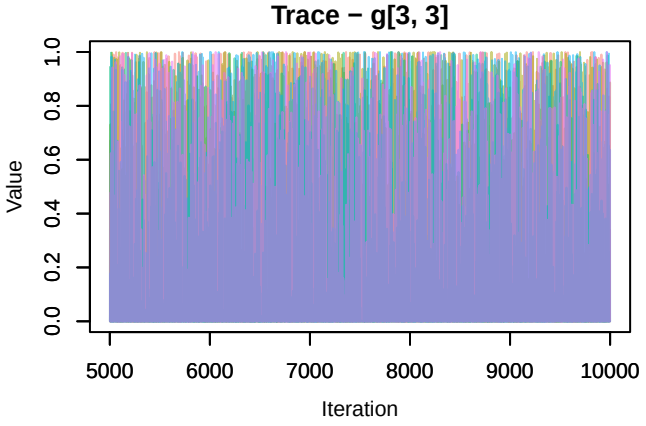

Density − g[10, 2]
Density
0.0e+00
6.0e+80
1.2e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

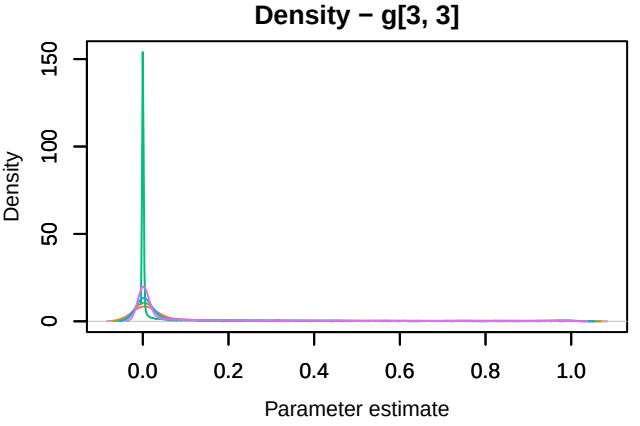

Trace − g[1, 3]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

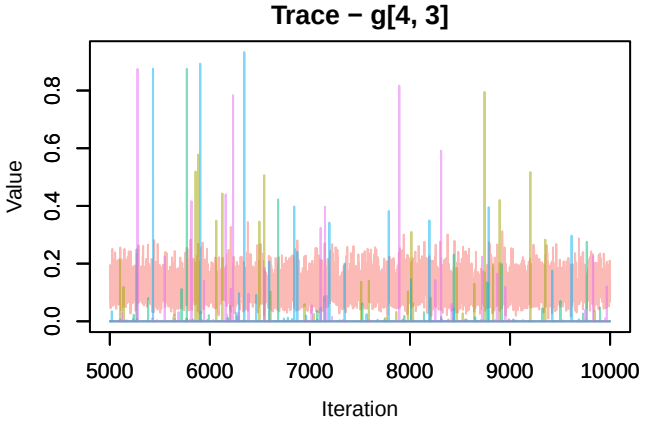

Density − g[1, 3]
Density
0e+00
4e+15
8e+15
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

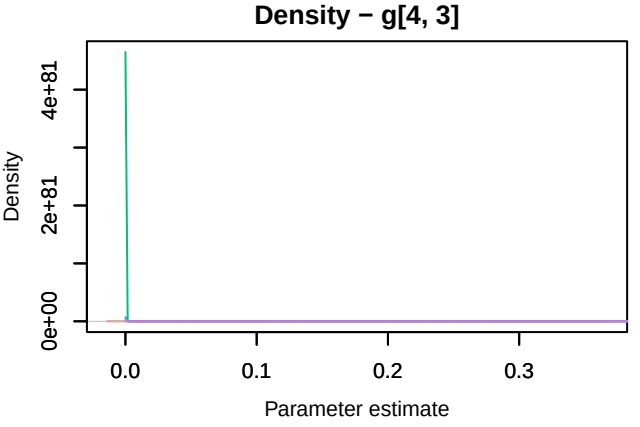

Trace − g[2, 3]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

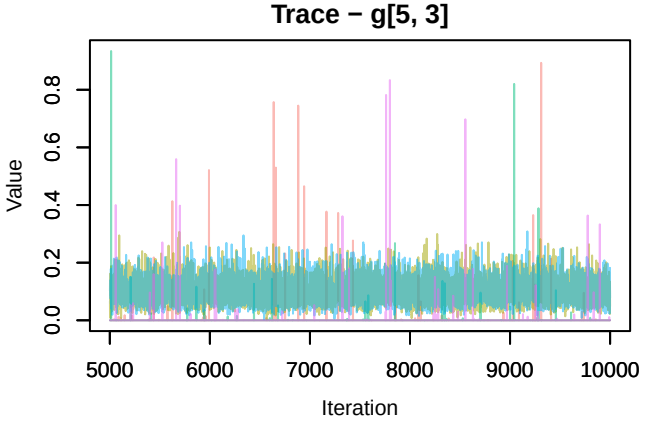

Density − g[2, 3]
Density
0
4000
8000
12000
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

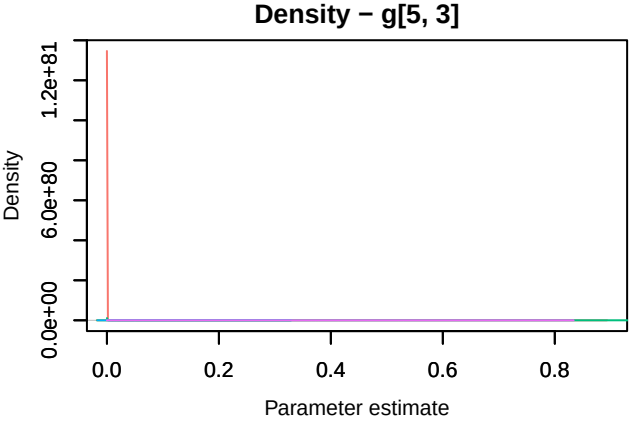

Trace − g[3, 3]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

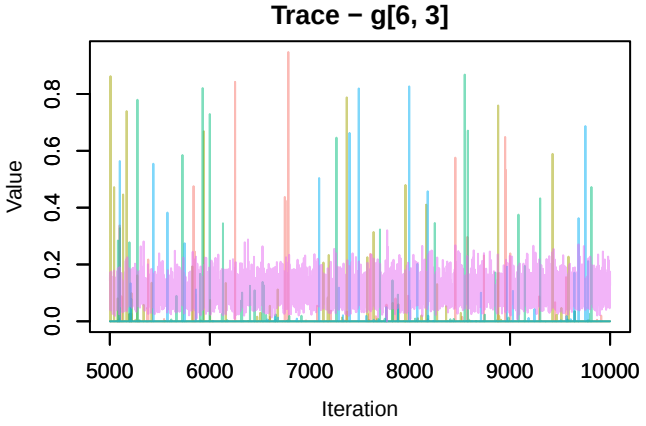

Density − g[3, 3]
Density
0
50
100
150
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

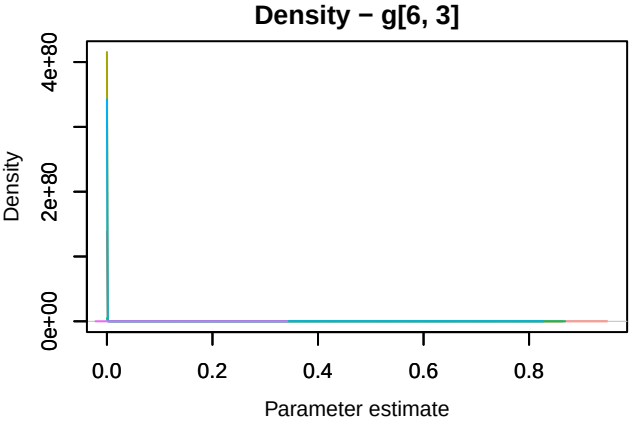

Trace − g[4, 3]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

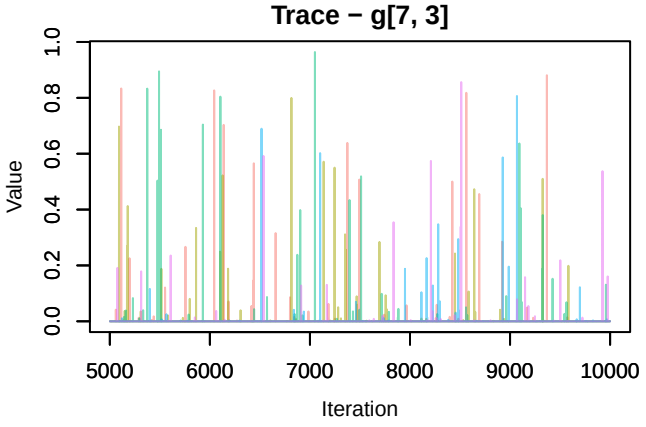

Density − g[4, 3]
Density
0e+00
2e+81
4e+81
0.0
0.1
0.2
0.3
Parameter estimate

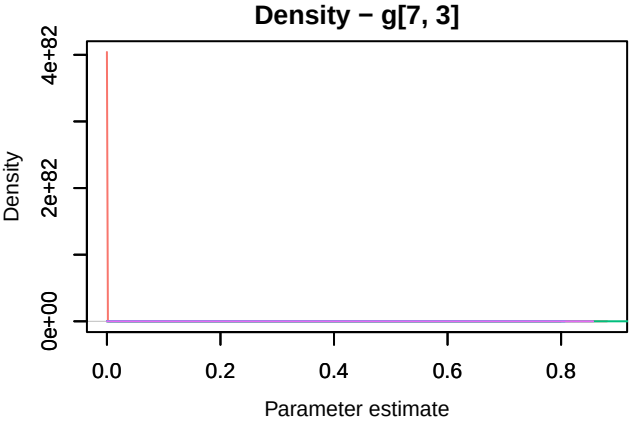

Trace − g[5, 3]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

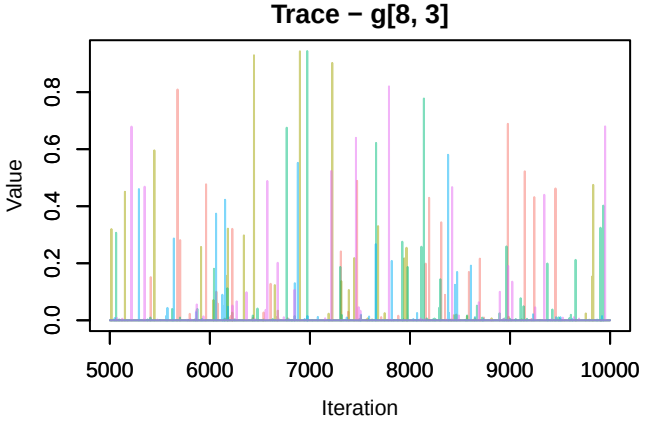

Density − g[5, 3]
Density
0.0e+00
6.0e+80
1.2e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

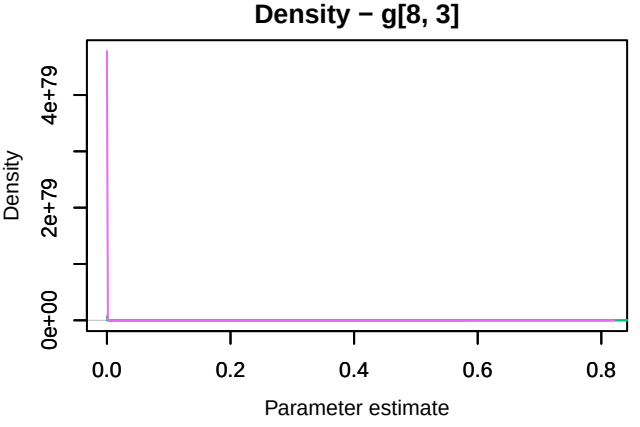

Trace − g[6, 3]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

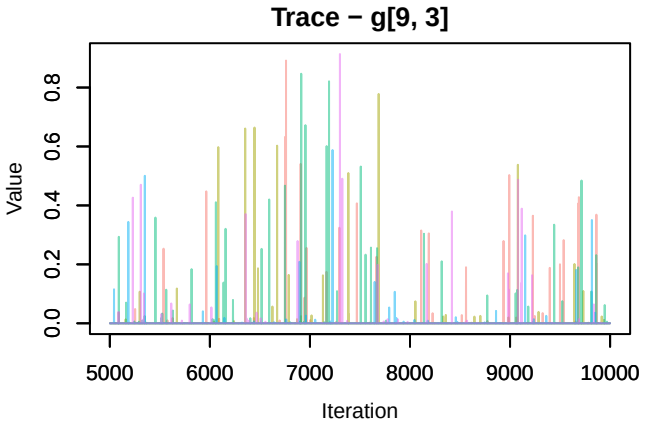

Density − g[6, 3]
Density
0e+00
2e+80
4e+80
0.0
0.2
0.4
0.6
0.8
Parameter estimate

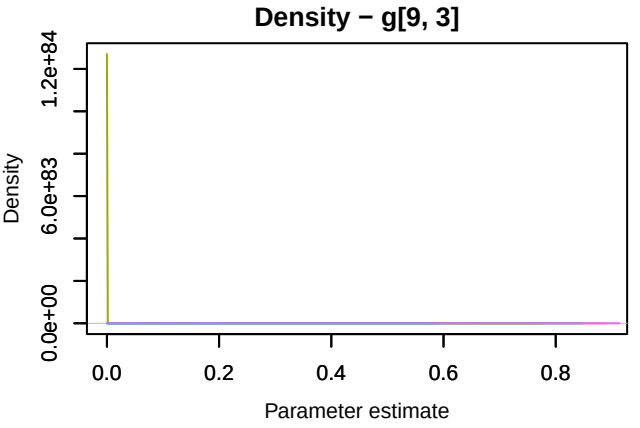

Trace − g[7, 3]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

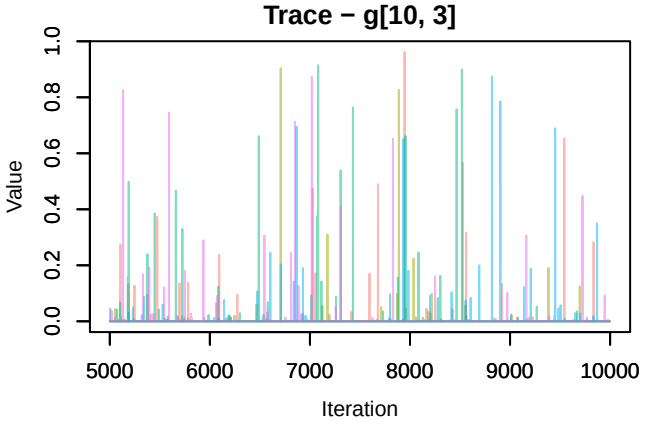

Density − g[7, 3]
Density
0e+00
2e+82
4e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

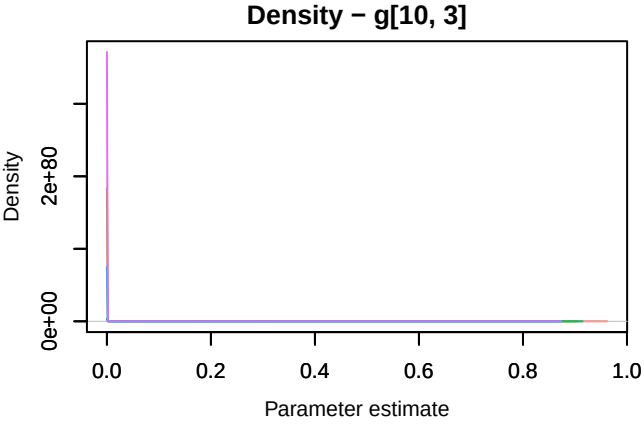

Trace − g[8, 3]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

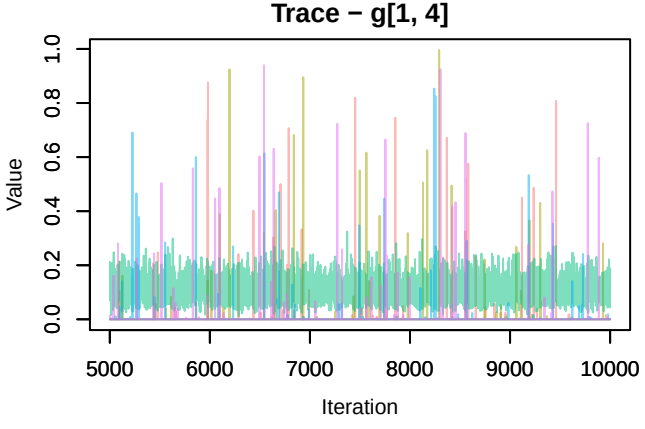

Density − g[8, 3]
Density
0e+00
2e+79
4e+79
0.0
0.2
0.4
0.6
0.8
Parameter estimate

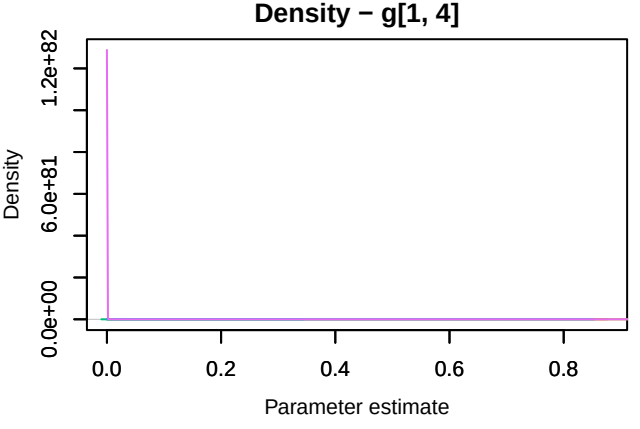

Trace − g[9, 3]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

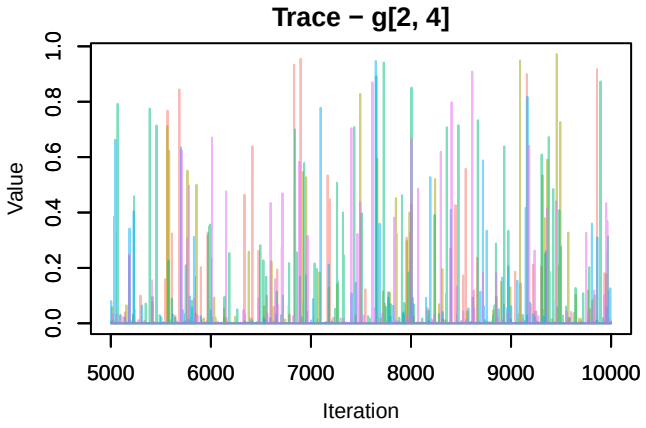

Density − g[9, 3]
Density
0.0e+00
6.0e+83
1.2e+84
0.0
0.2
0.4
0.6
0.8
Parameter estimate

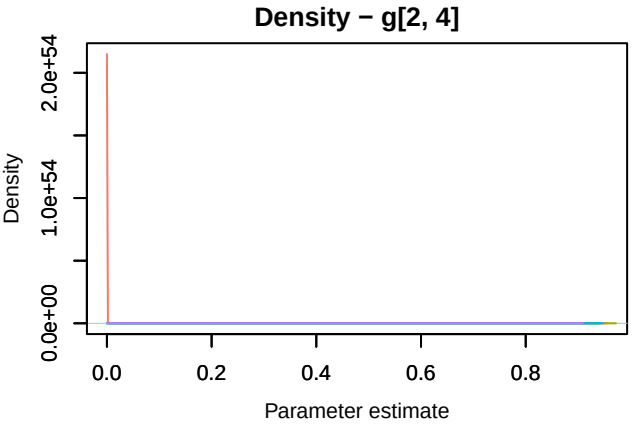

Trace − g[10, 3]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

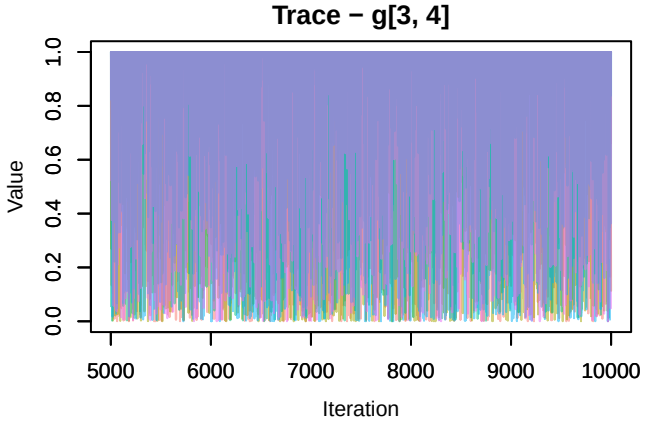

Density − g[10, 3]
Density
0e+00
2e+80
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

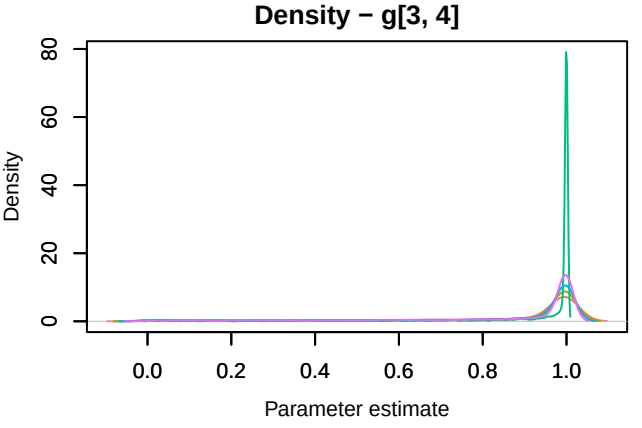

Trace − g[1, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

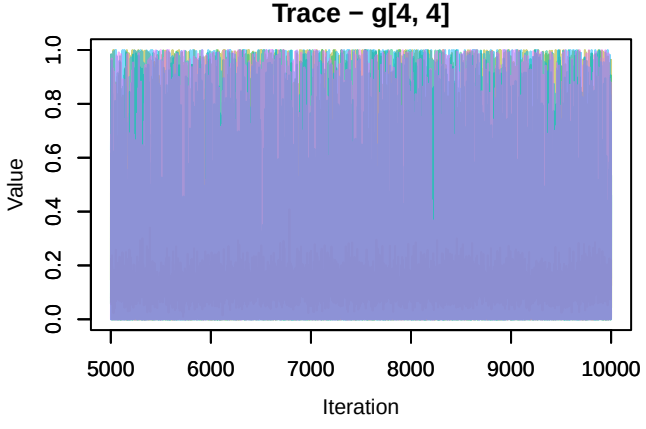

Density − g[1, 4]
Density
0.0e+00
6.0e+81
1.2e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

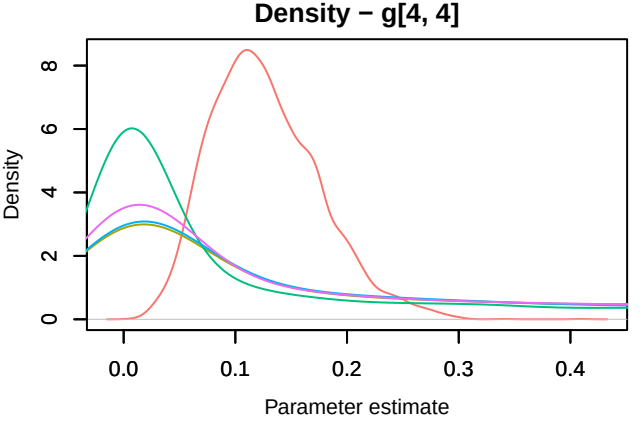

Trace − g[2, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

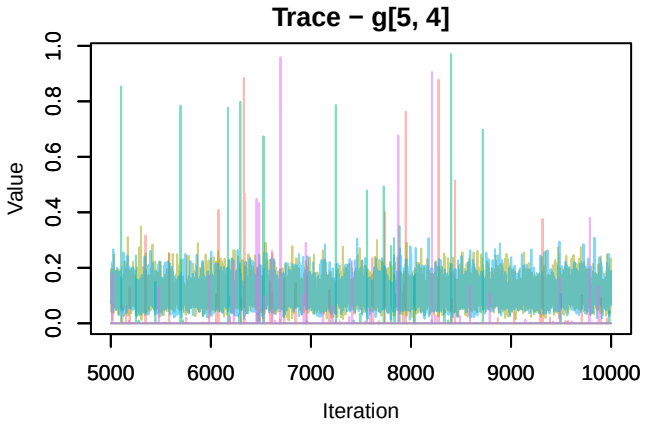

Density − g[2, 4]
Density
0.0e+00
1.0e+54
2.0e+54
0.0
0.2
0.4
0.6
0.8
Parameter estimate

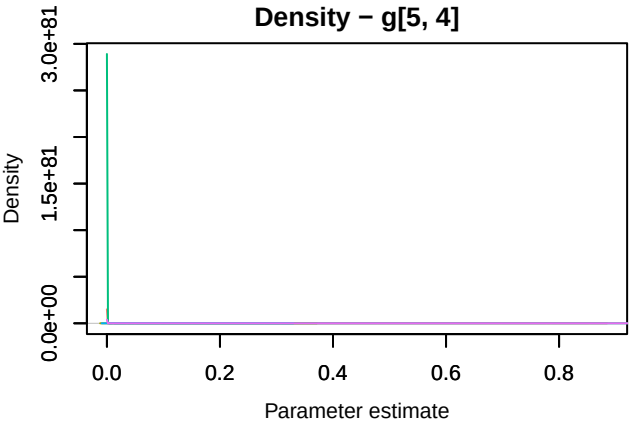

Trace − g[3, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

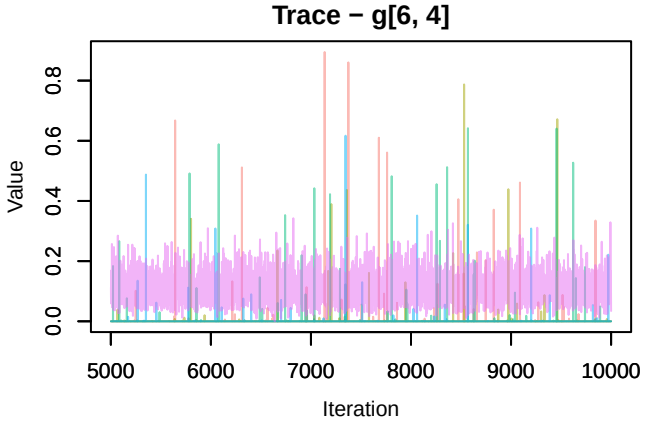

Density − g[3, 4]
Density
0
20
40
60
80
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

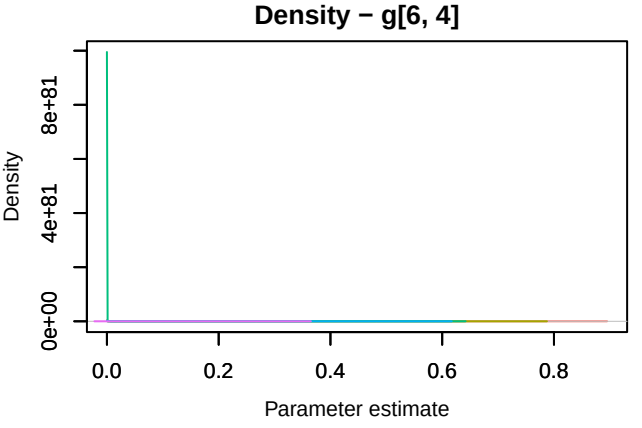

Trace − g[4, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

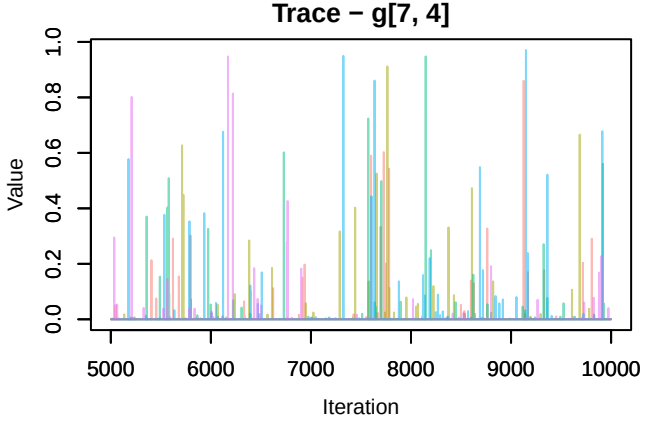

Density − g[4, 4]
Density
0
2
4
6
8
0.0
0.1
0.2
0.3
0.4
Parameter estimate

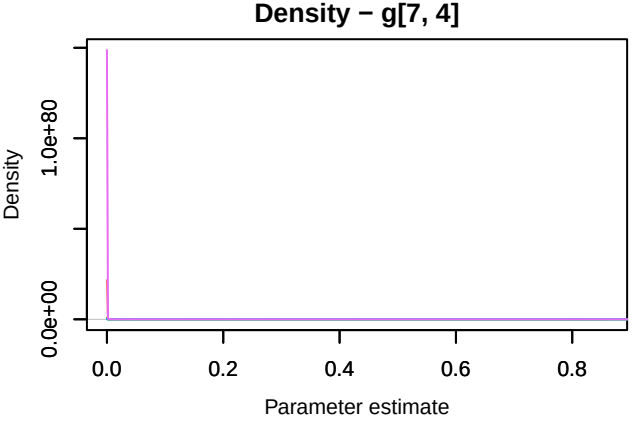

Trace − g[5, 4]
Value
Iteration
5000
6000
7000
8000
9000
10000
0.0
0.2
0.4
0.6
0.8
1.0

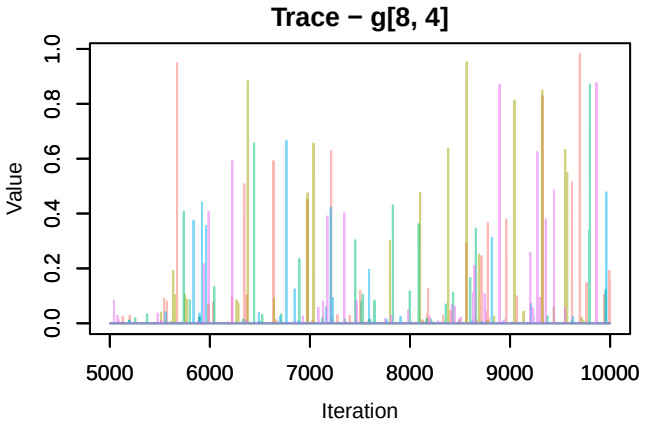

Density − g[5, 4]
Density
Parameter estimate
0.0e+00
1.5e+81
3.0e+81
0.0
0.2
0.4
0.6
0.8

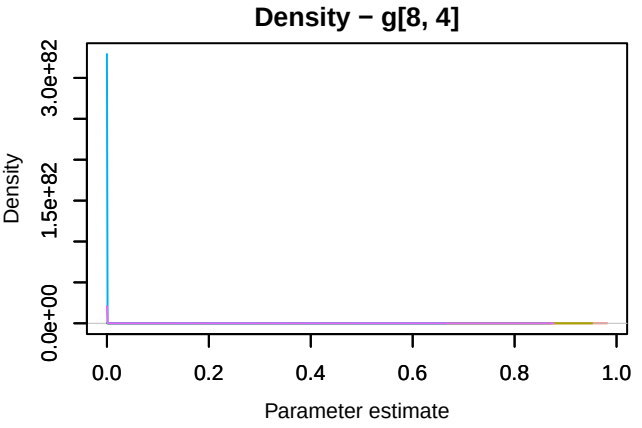

Trace − g[6, 4]
Value
Iteration
5000
6000
7000
8000
9000
10000
0.0
0.2
0.4
0.6
0.8

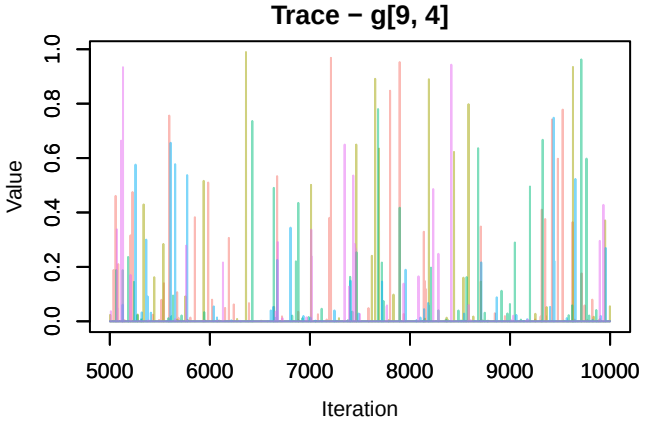

Density − g[6, 4]
Density
Parameter estimate
0e+00
4e+81
8e+81
0.0
0.2
0.4
0.6
0.8

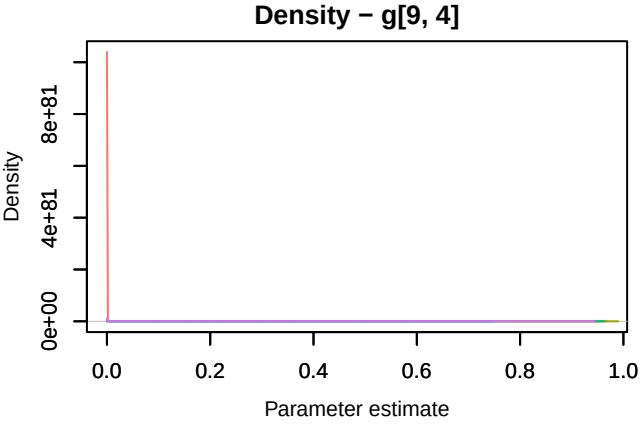

Trace − g[7, 4]
Value
Iteration
5000
6000
7000
8000
9000
10000
0.0
0.2
0.4
0.6
0.8
1.0

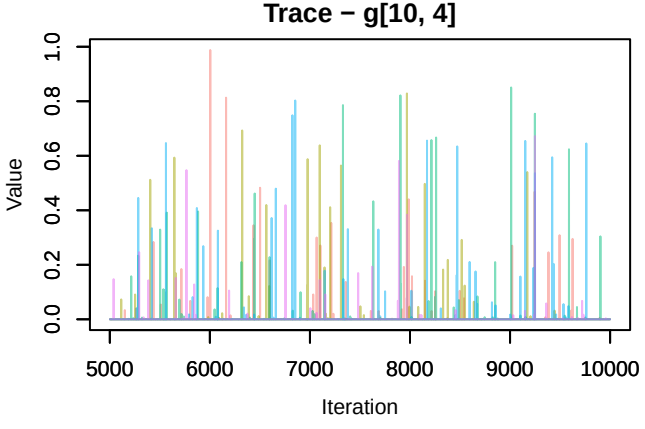

Density − g[7, 4]
Density
Parameter estimate
0.0e+00
1.0e+80
0.0
0.2
0.4
0.6
0.8

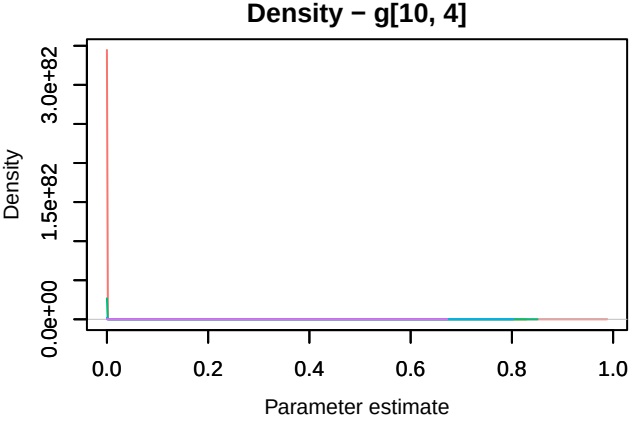

Trace − g[8, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

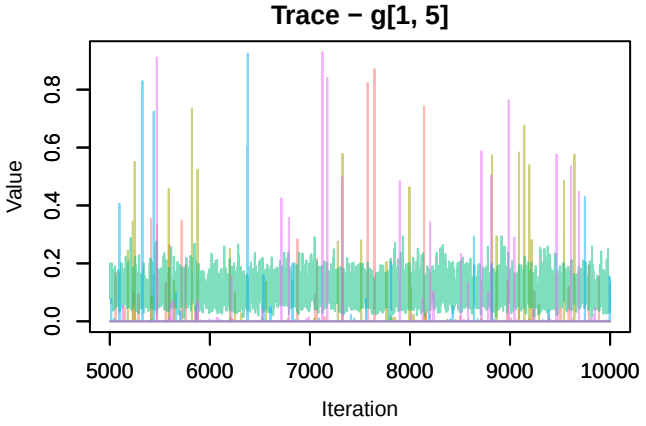

Density − g[8, 4]
Density
0.0e+00
1.5e+82
3.0e+82
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

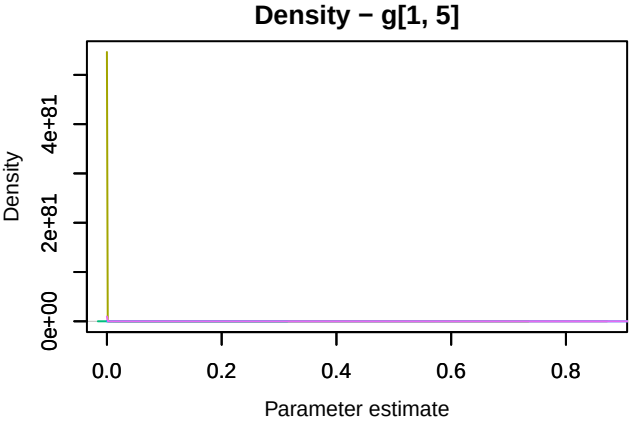

Trace − g[9, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

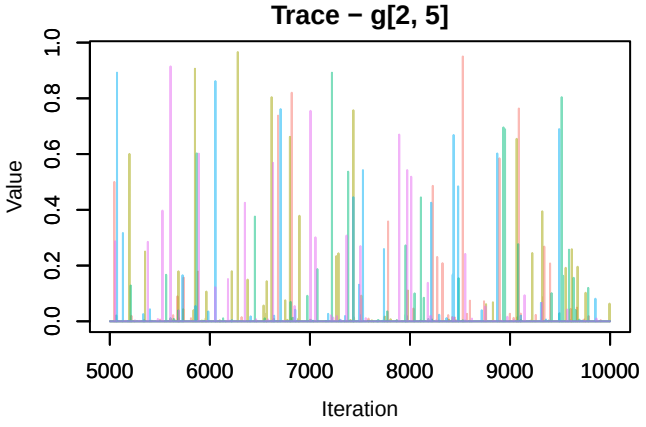

Density − g[9, 4]
Density
0e+00
4e+81
8e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

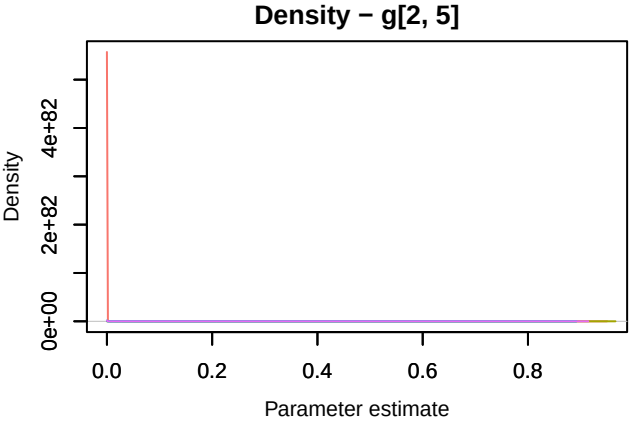

Trace − g[10, 4]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

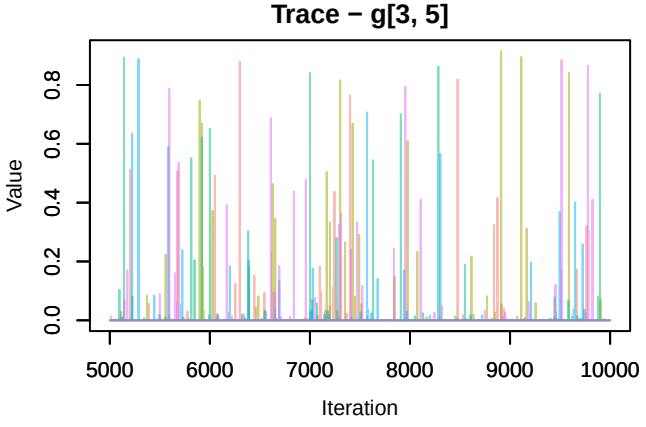

Density − g[10, 4]
Density
0.0e+00
1.5e+82
3.0e+82
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

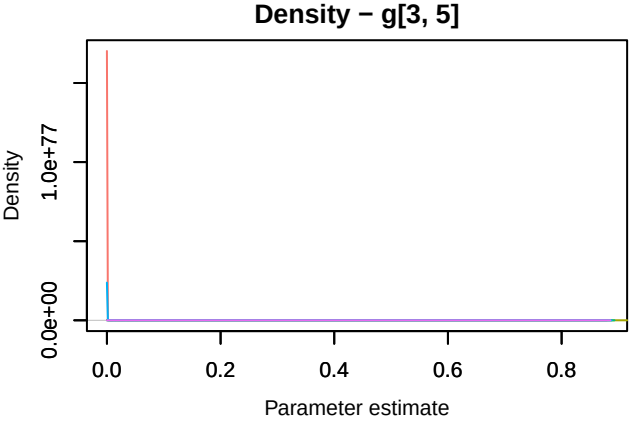

Trace − g[1, 5]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

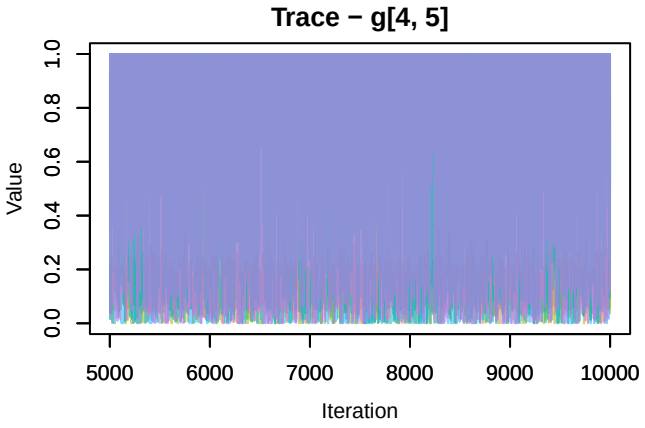

Density − g[1, 5]
Density
0e+00
2e+81
4e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

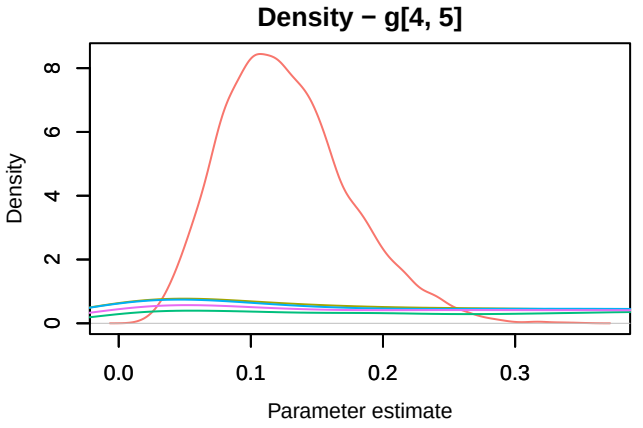

Trace − g[2, 5]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

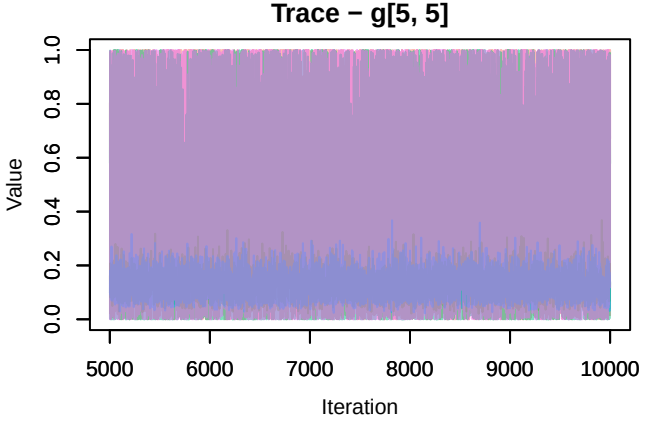

Density − g[2, 5]
Density
0e+00
2e+82
4e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

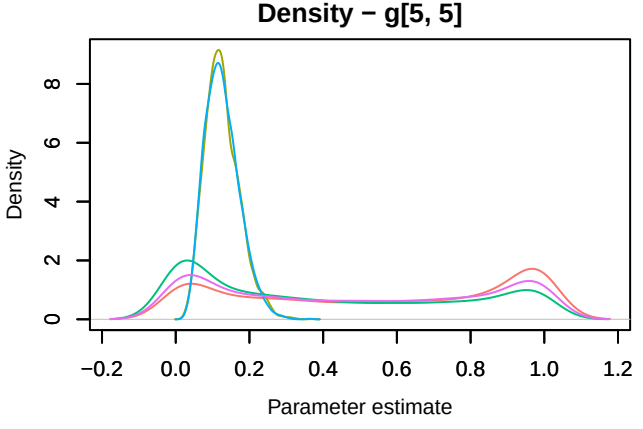

Trace − g[3, 5]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

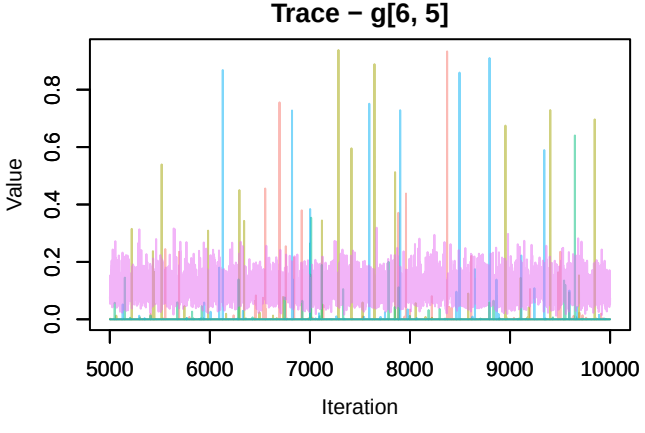

Density − g[3, 5]
Density
0.0e+00
1.0e+77
0.0
0.2
0.4
0.6
0.8
Parameter estimate

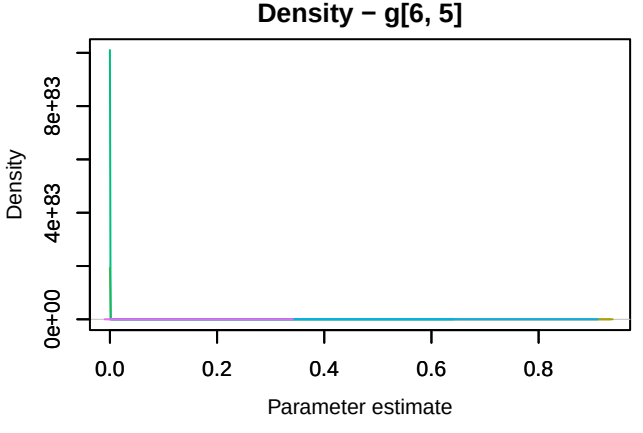

Trace − g[4, 5]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

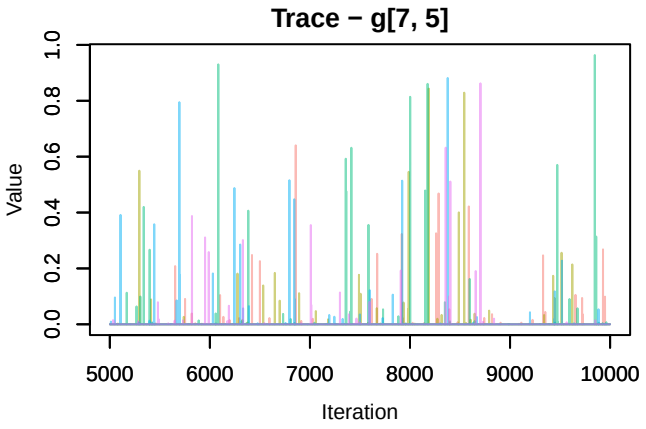

Density − g[4, 5]
Density
0
2
4
6
8
0.0
0.1
0.2
0.3
Parameter estimate

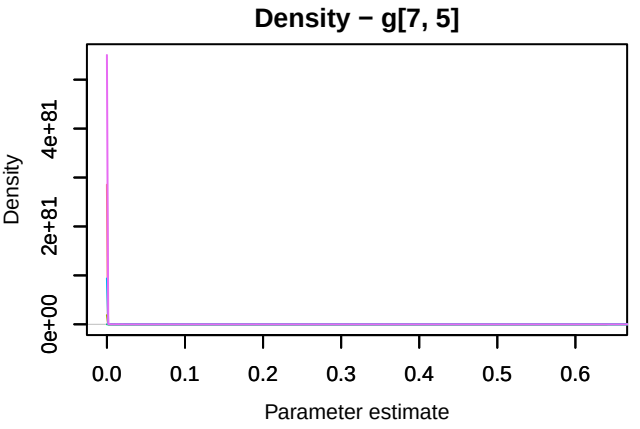

Trace − g[5, 5]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

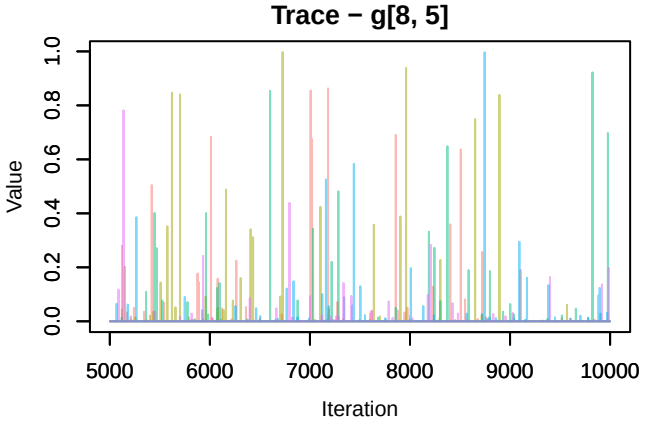

Density − g[5, 5]
Density
0
2
4
6
8
−0.2
0.0
0.2
0.4
0.6
0.8
1.0
1.2
Parameter estimate

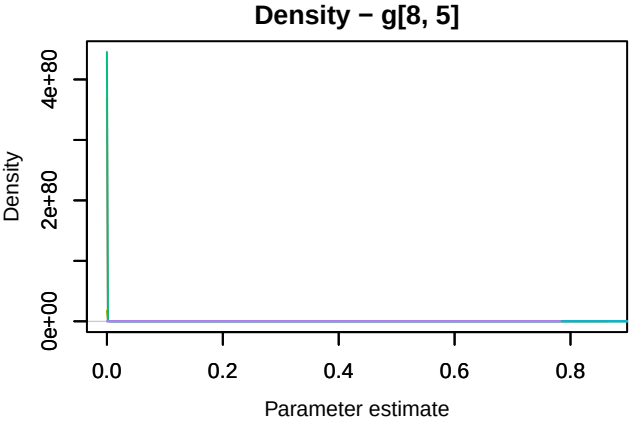

Trace − g[6, 5]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

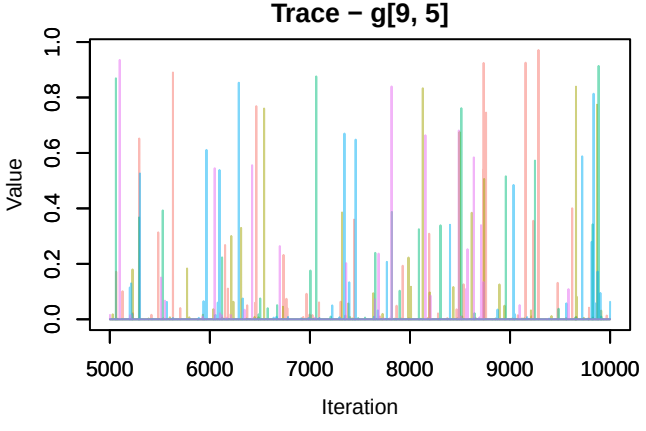

Density − g[6, 5]
Density
0e+00
4e+83
8e+83
0.0
0.2
0.4
0.6
0.8
Parameter estimate

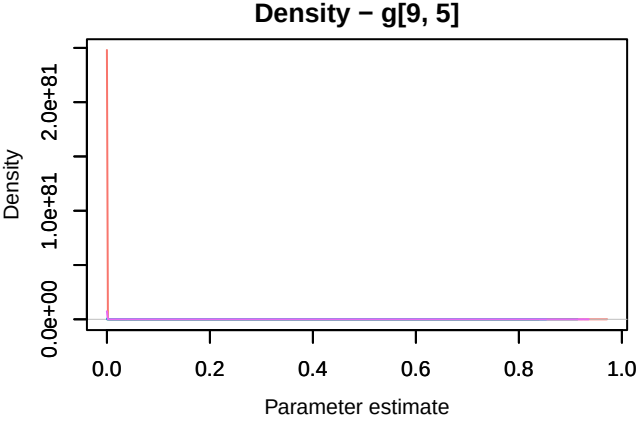

Trace − g[7, 5]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

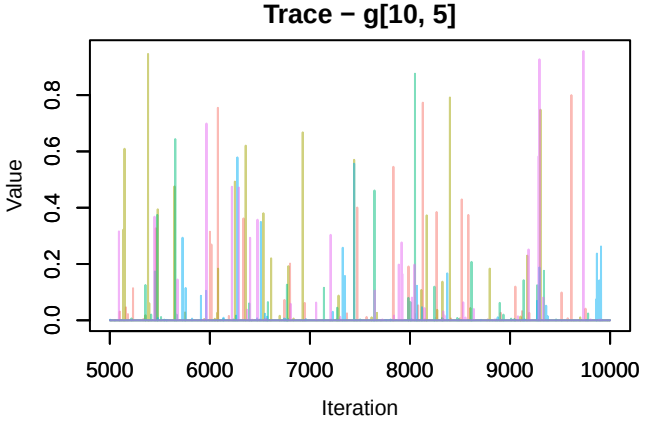

Density − g[7, 5]
Density
Parameter estimate
0e+00
2e+81
4e+81
0.0
0.1
0.2
0.3
0.4
0.5
0.6

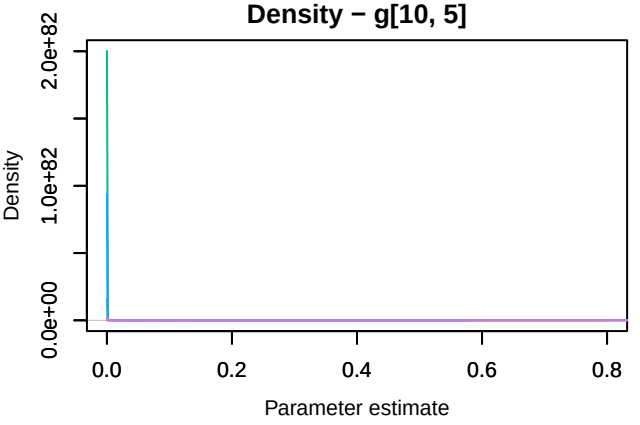

Trace − g[8, 5]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

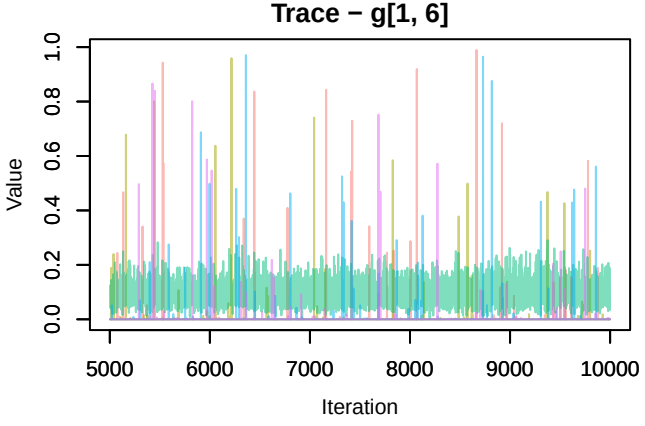

Density − g[8, 5]
Density
Parameter estimate
0e+00
2e+80
4e+80
0.0
0.2
0.4
0.6
0.8

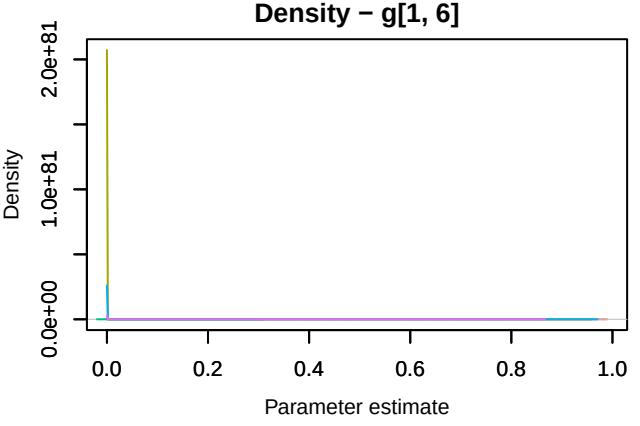

Trace − g[9, 5]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

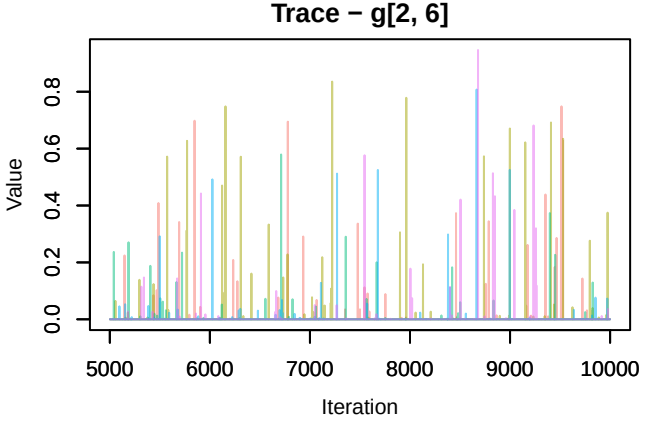

Density − g[9, 5]
Density
Parameter estimate
0.0e+00
1.0e+81
2.0e+81
0.0
0.2
0.4
0.6
0.8
1.0

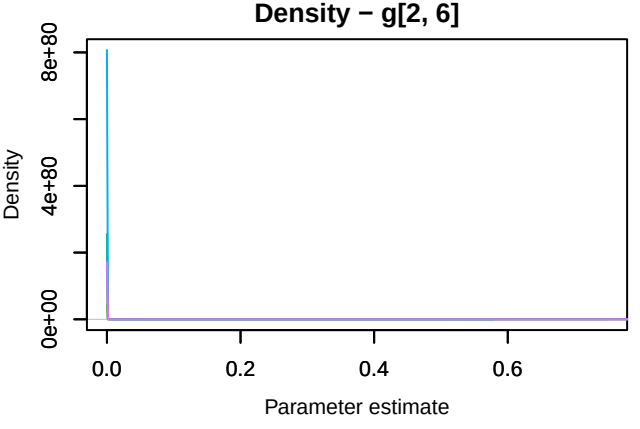

Trace − g[10, 5]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

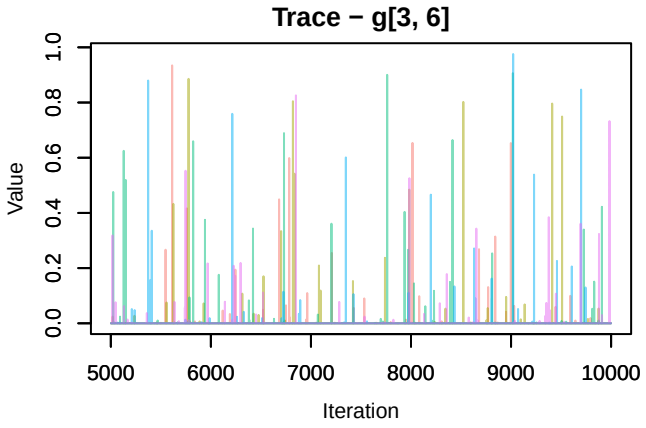

Density − g[10, 5]
Density
0.0e+00
1.0e+82
2.0e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

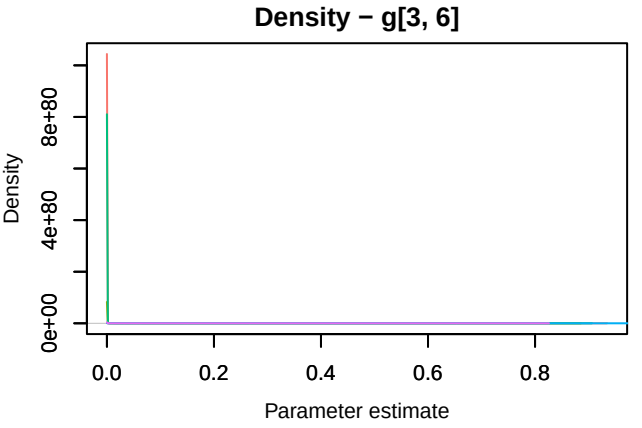

Trace − g[1, 6]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

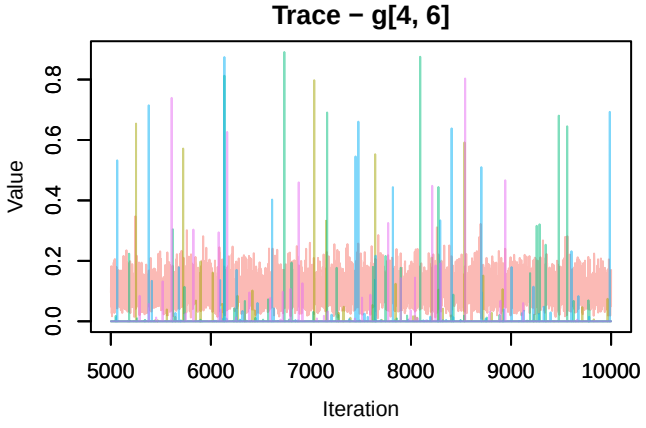

Density − g[1, 6]
Density
0.0e+00
1.0e+81
2.0e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

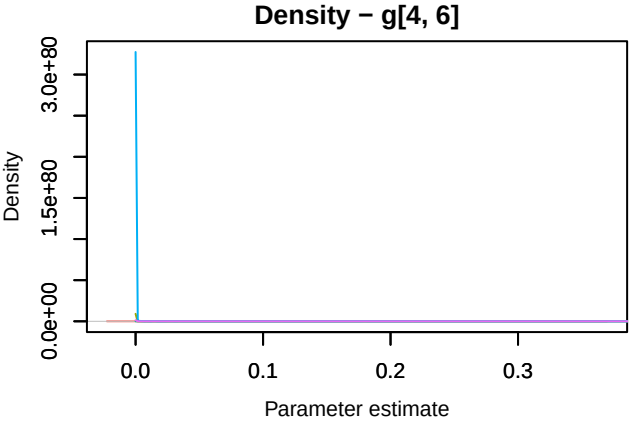

Trace − g[2, 6]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

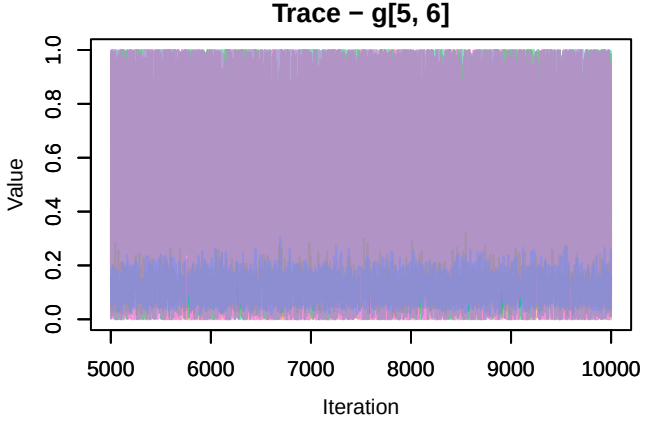

Density − g[2, 6]
Density
0e+00
4e+80
8e+80
0.0
0.2
0.4
0.6
Parameter estimate

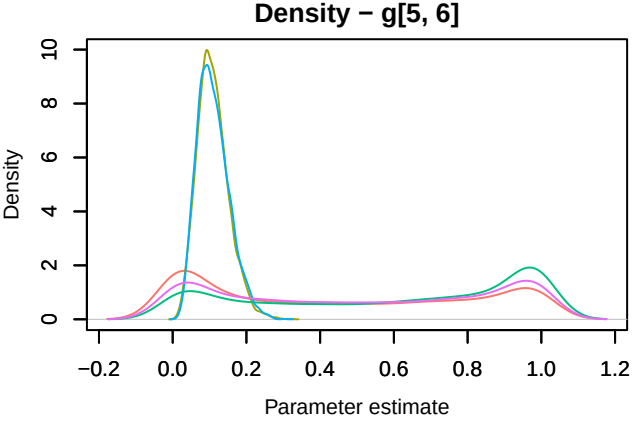

Trace − g[3, 6]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

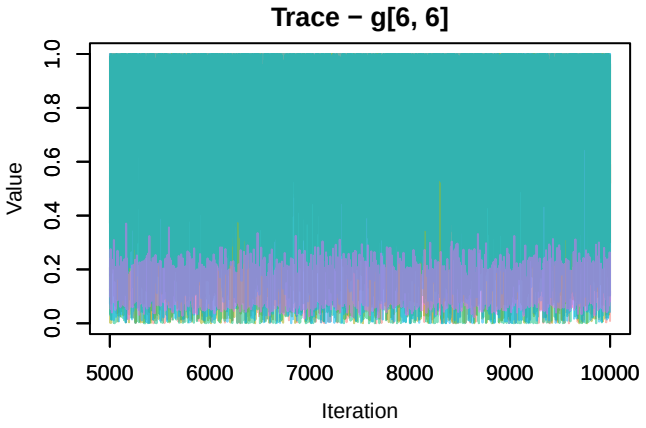

Density − g[3, 6]
Density
Parameter estimate
0e+00
4e+80
8e+80
0.0
0.2
0.4
0.6
0.8

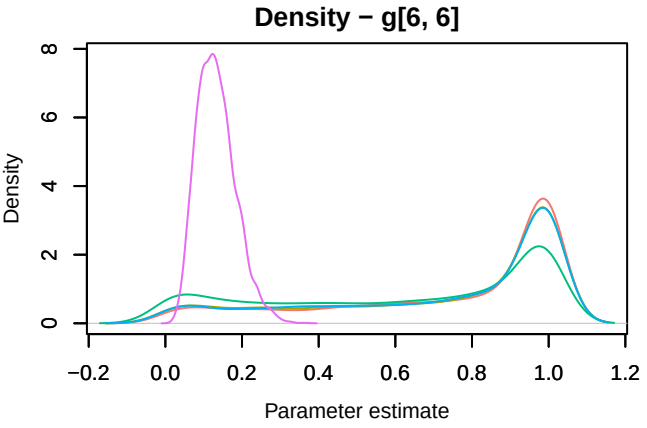

Trace − g[4, 6]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000

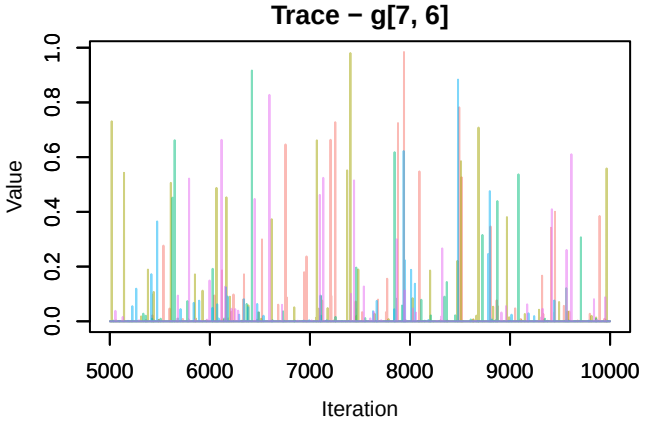

Density − g[4, 6]
Density
Parameter estimate
0.0e+00
1.5e+80
3.0e+80
0.0
0.1
0.2
0.3

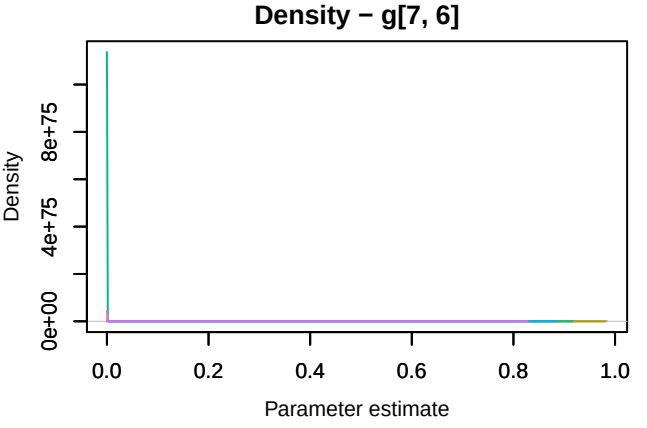

Trace − g[5, 6]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

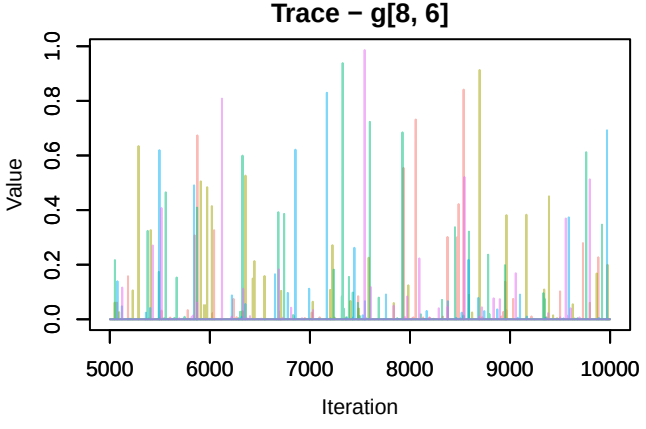

Density − g[5, 6]
Density
Parameter estimate
0
2
4
6
8
10
−0.2
0.0
0.2
0.4
0.6
0.8
1.0
1.2

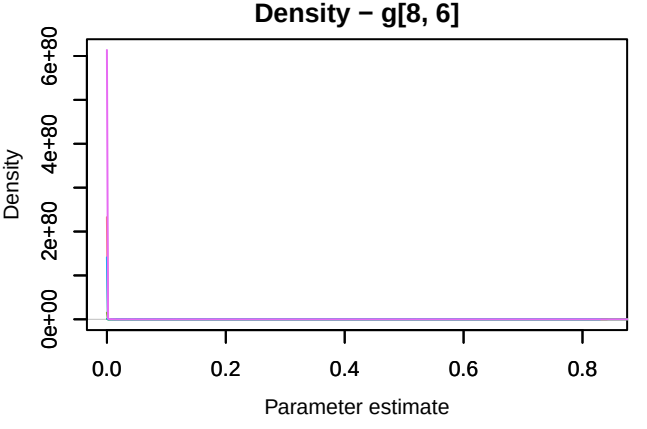

Trace − g[6, 6]
Value
Iteration

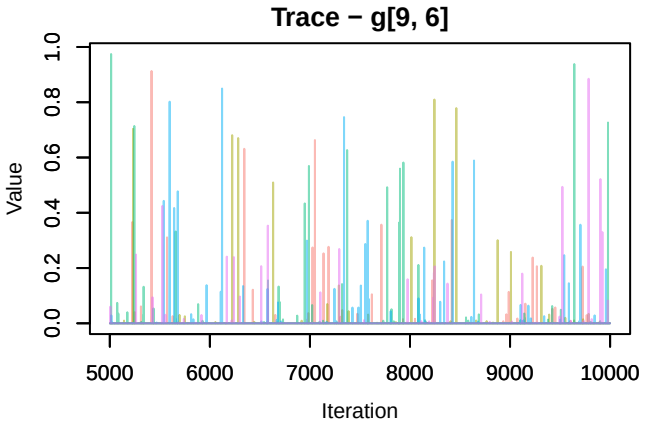

Density − g[6, 6]
Density
Parameter estimate

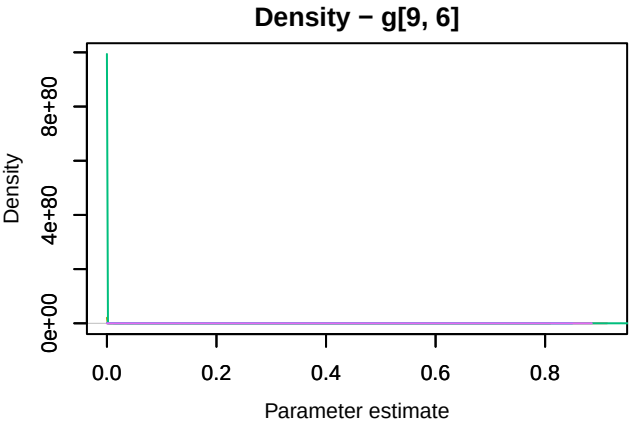

Trace − g[7, 6]
Value
Iteration

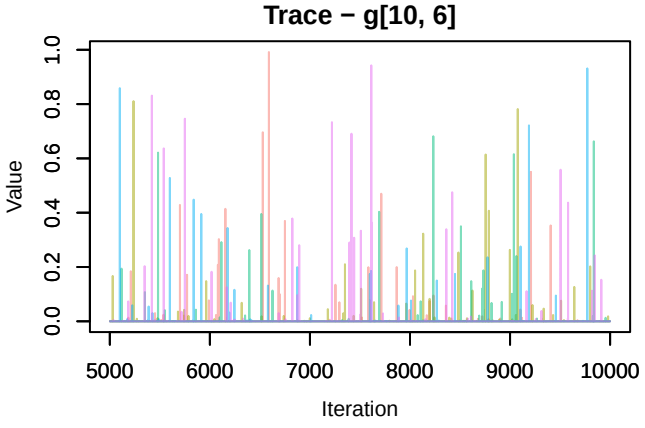

Density − g[7, 6]
Density
Parameter estimate

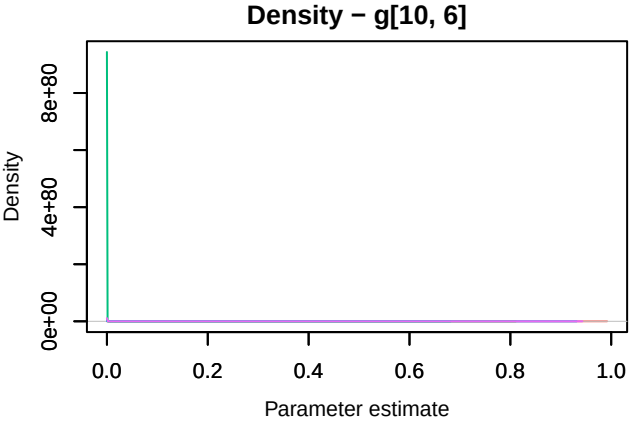

Trace − g[8, 6]
Value
Iteration

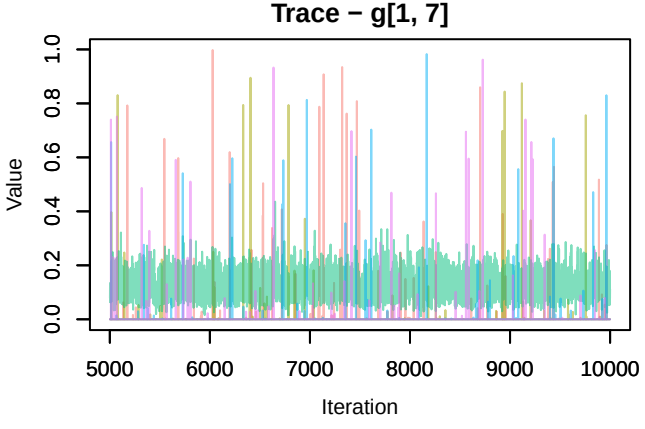

Density − g[8, 6]
Density
Parameter estimate

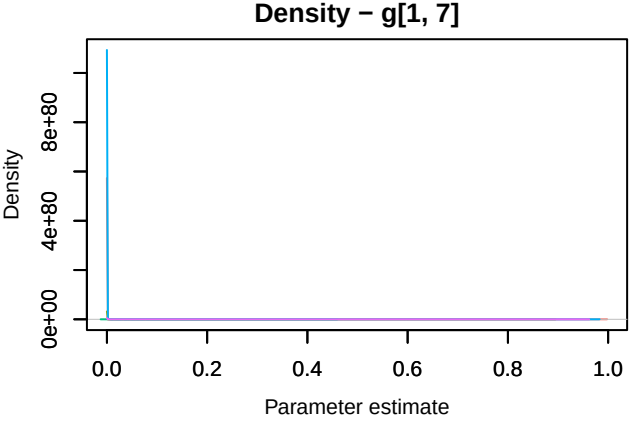

Trace − g[9, 6]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

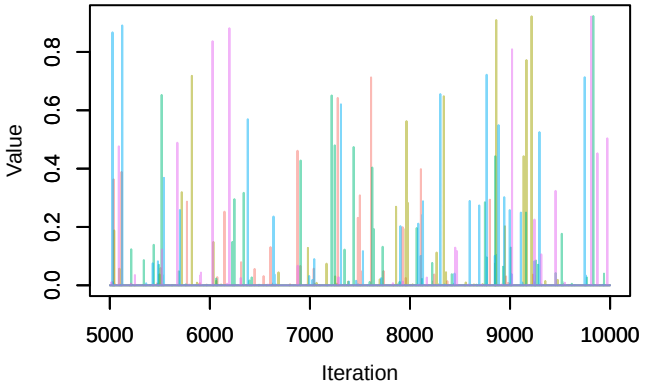

Density − g[9, 6]
Density
Parameter estimate
0e+00
4e+80
8e+80
0.0
0.2
0.4
0.6
0.8

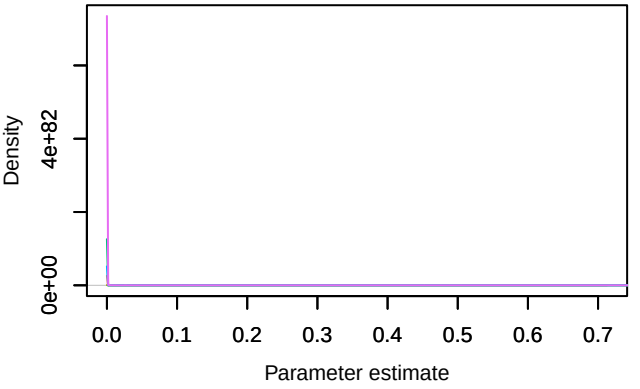

Trace − g[10, 6]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

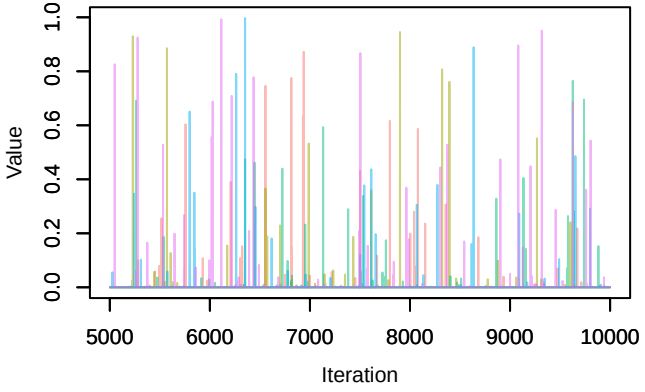

Density − g[10, 6]
Density
Parameter estimate
0e+00
4e+80
8e+80
0.0
0.2
0.4
0.6
0.8
1.0

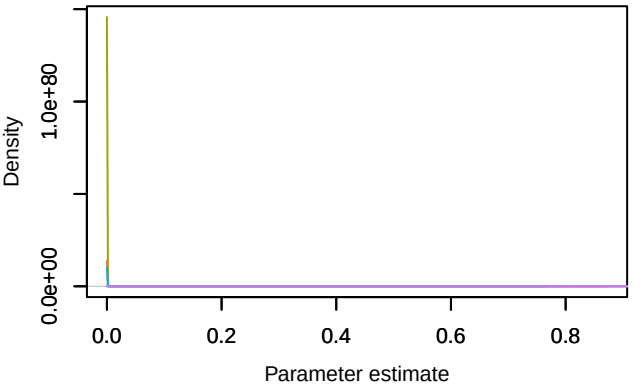

Trace − g[1, 7]
Value
Iteration
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000

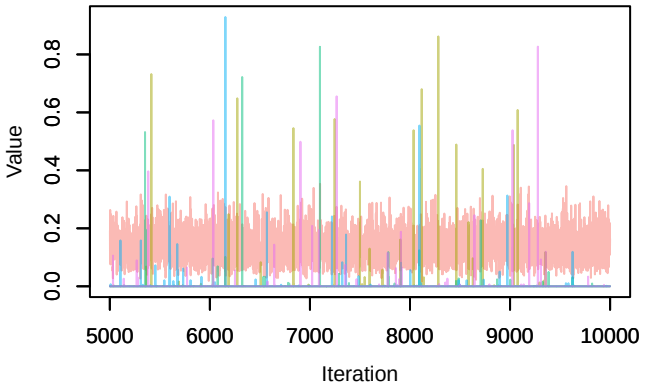

Density − g[1, 7]
Density
Parameter estimate
0e+00
4e+80
8e+80
0.0
0.2
0.4
0.6
0.8
1.0

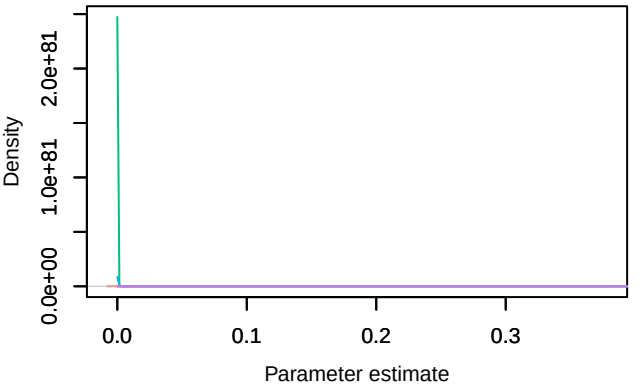

Trace − g[2, 7]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

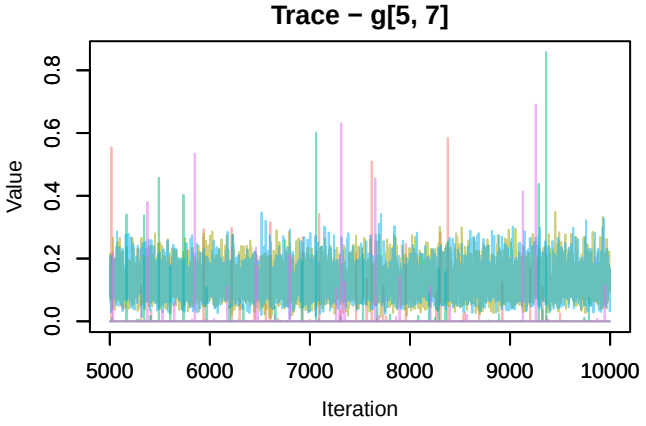

Density − g[2, 7]
Density
0e+00
4e+82
0.0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
Parameter estimate

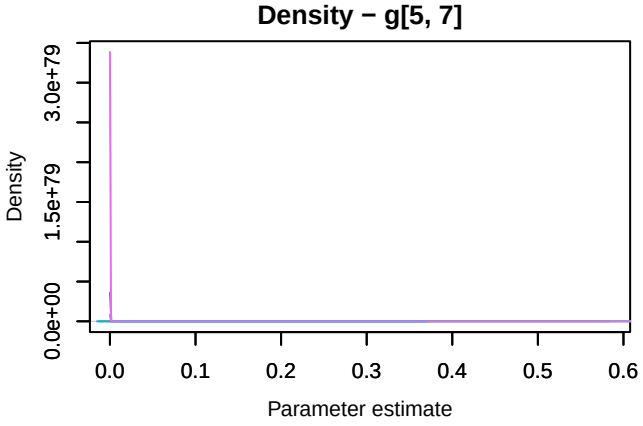

Trace − g[3, 7]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

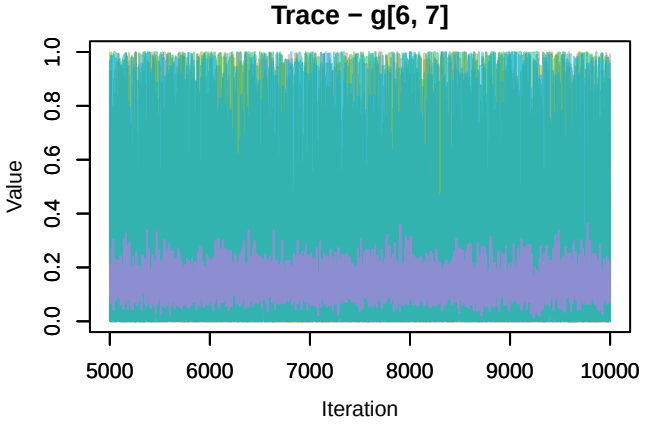

Density − g[3, 7]
Density
0.0e+00
1.0e+80
0.0
0.2
0.4
0.6
0.8
Parameter estimate

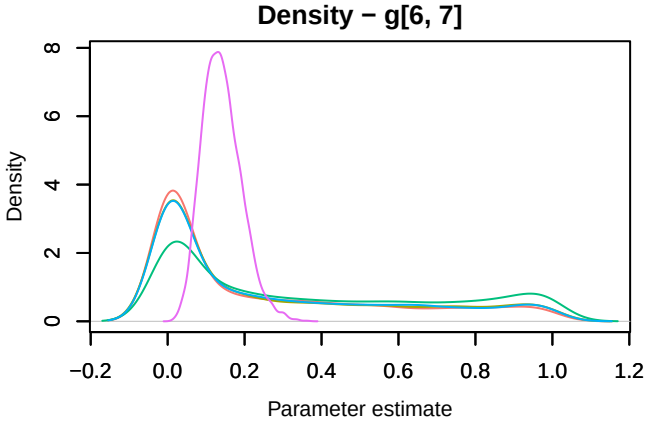

Trace − g[4, 7]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

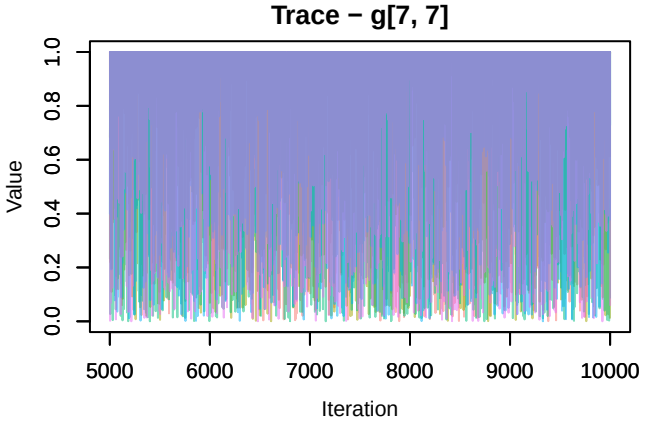

Density − g[4, 7]
Density
0.0e+00
1.0e+81
2.0e+81
0.0
0.1
0.2
0.3
Parameter estimate

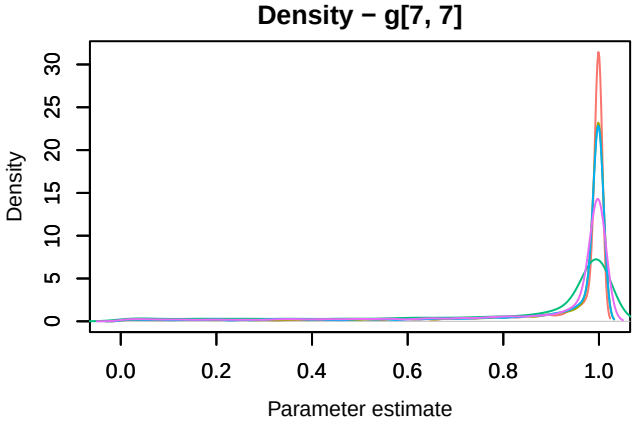

Trace − g[5, 7]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

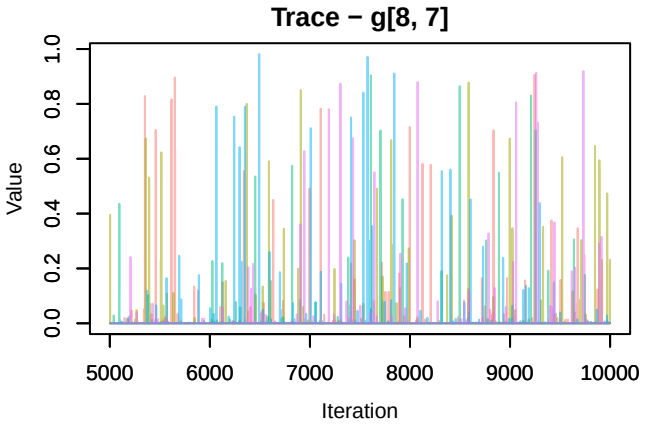

Density − g[5, 7]
Density
0.0e+00
1.5e+79
3.0e+79
0.0
0.1
0.2
0.3
0.4
0.5
0.6
Parameter estimate

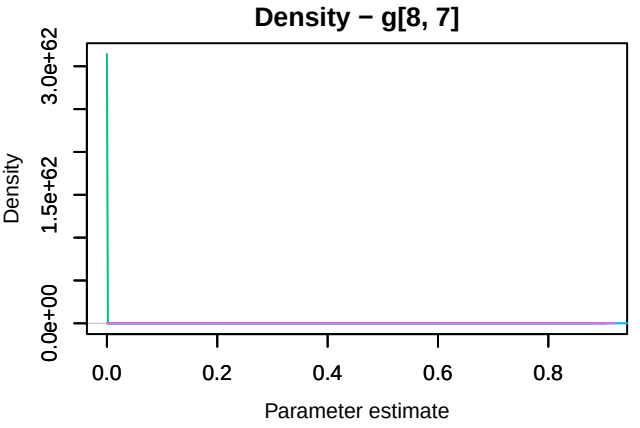

Trace − g[6, 7]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

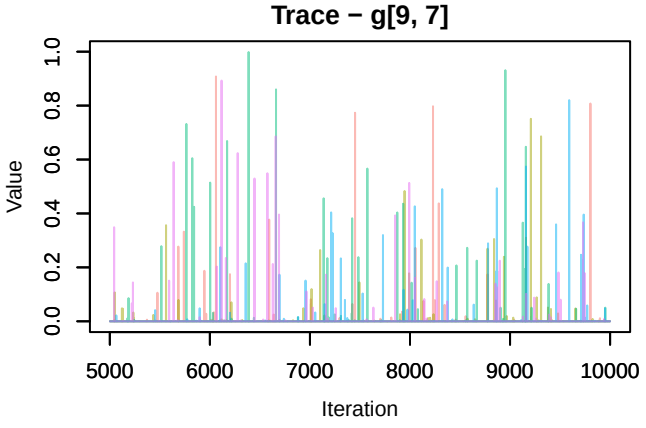

Density − g[6, 7]
Density
0
2
4
6
8
−0.2
0.0
0.2
0.4
0.6
0.8
1.0
1.2
Parameter estimate

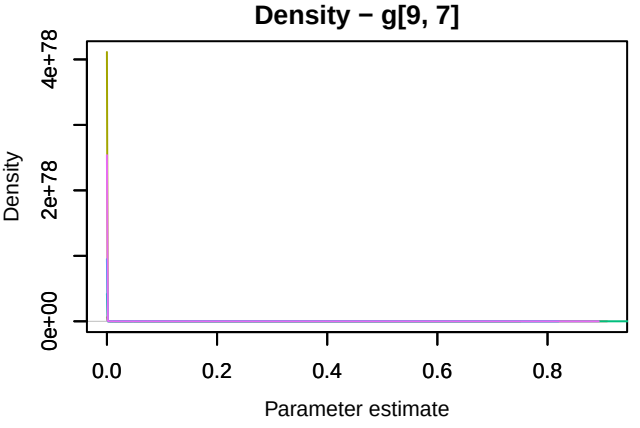

Trace − g[7, 7]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

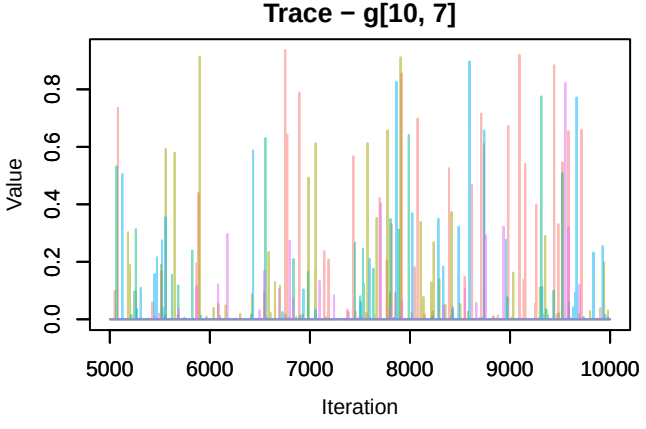

Density − g[7, 7]
Density
0
5
10
15
20
25
30
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

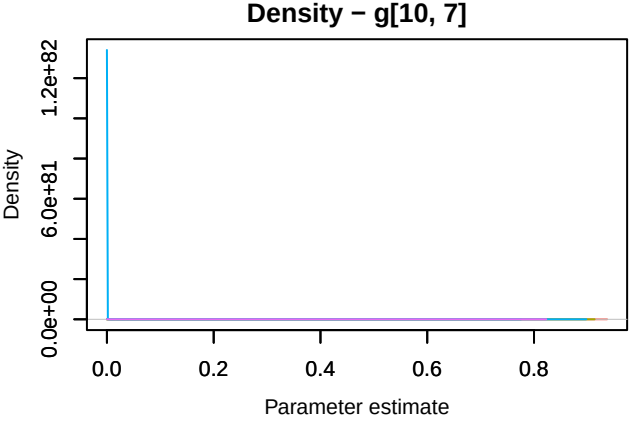

Trace − g[8, 7]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

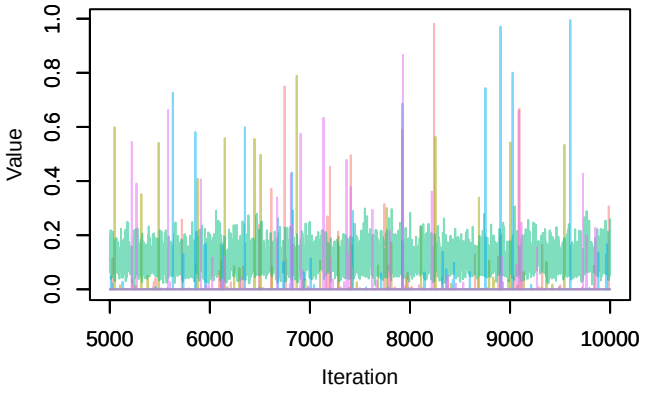

Density − g[8, 7]
Density
0.0e+00
1.5e+62
3.0e+62
0.0
0.2
0.4
0.6
0.8
Parameter estimate

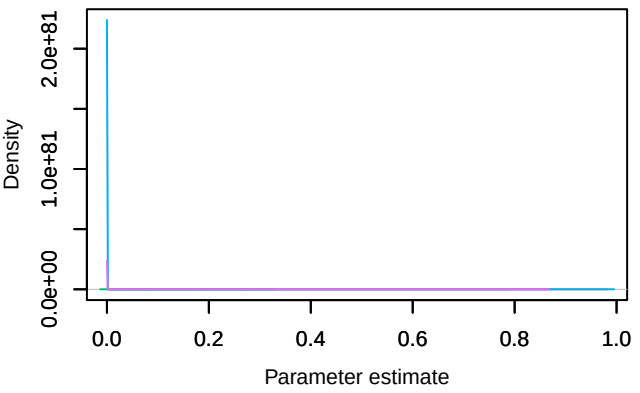

Trace − g[9, 7]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

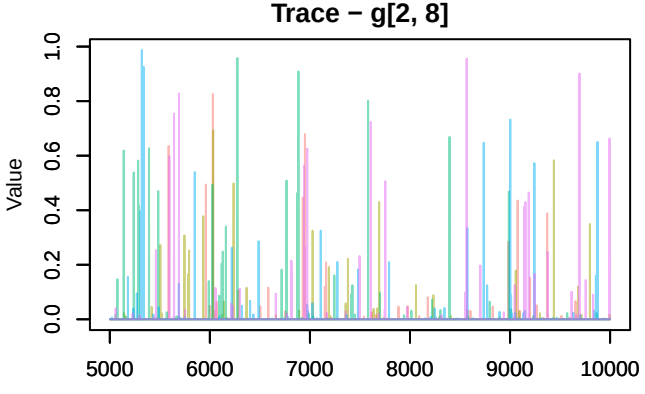

Density − g[9, 7]
Density
0e+00
2e+78
4e+78
0.0
0.2
0.4
0.6
0.8
Parameter estimate

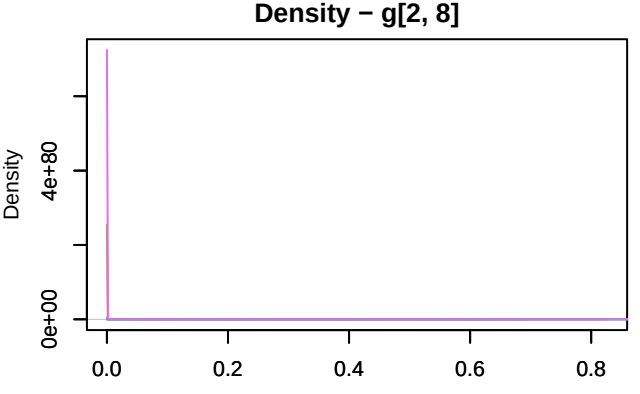

Trace − g[10, 7]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

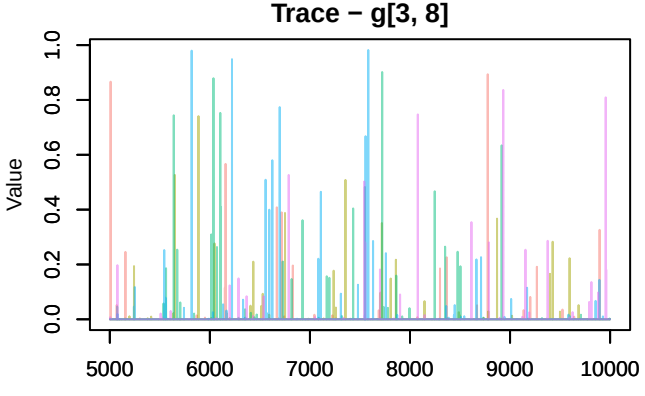

Density − g[10, 7]
Density
0.0e+00
6.0e+81
1.2e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

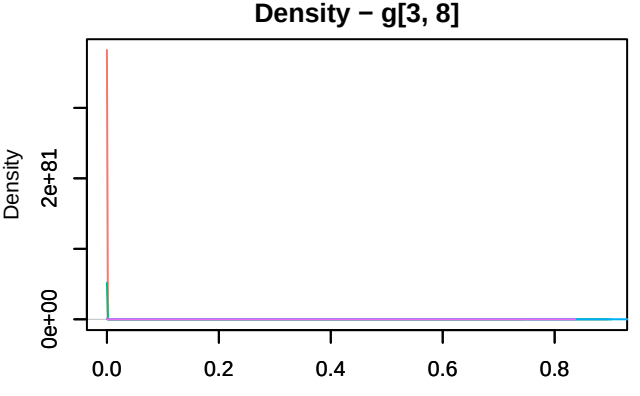

Trace − g[1, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

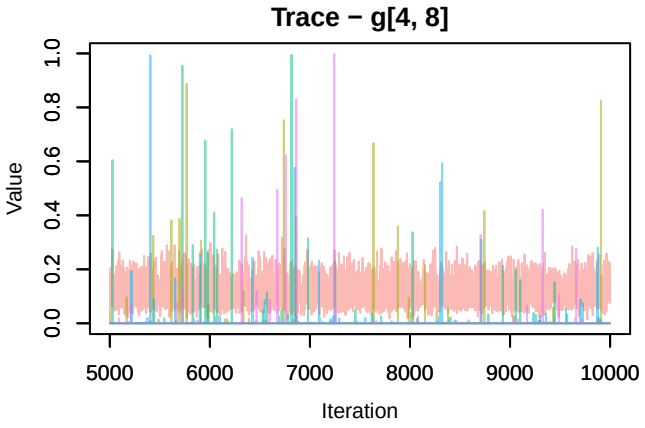

Density − g[1, 8]
Density
0.0e+00
1.0e+81
2.0e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

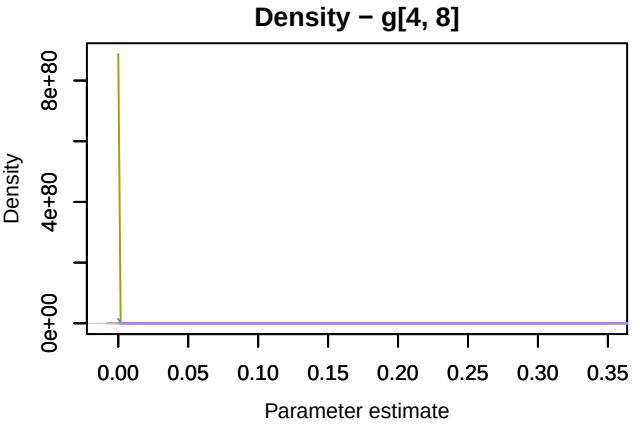

Trace − g[2, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

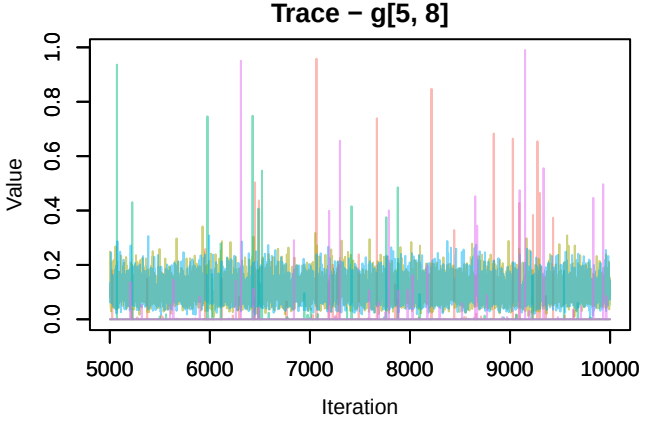

Density − g[2, 8]
Density
0e+00
4e+80
0.0
0.2
0.4
0.6
0.8
Parameter estimate

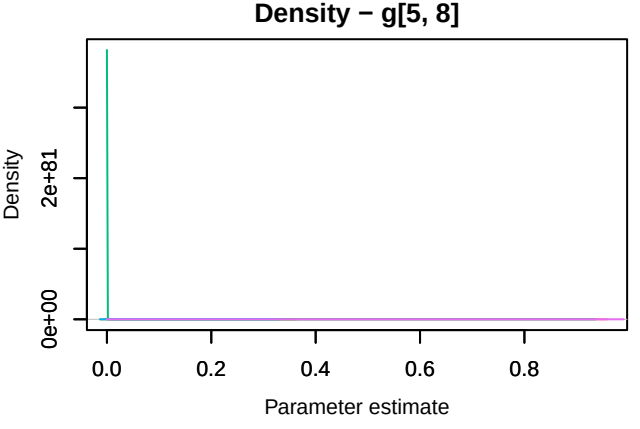

Trace − g[3, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

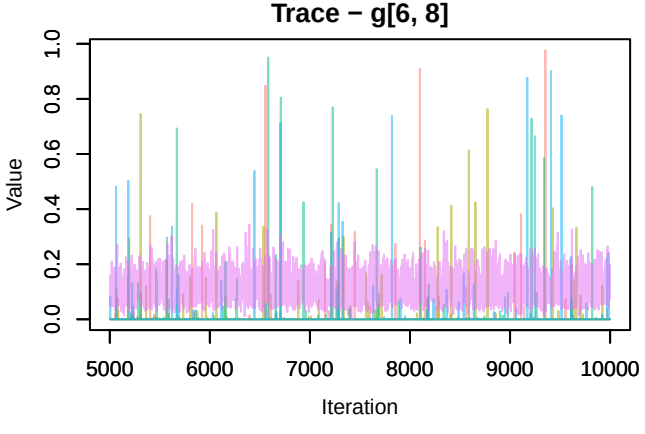

Density − g[3, 8]
Density
0e+00
2e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

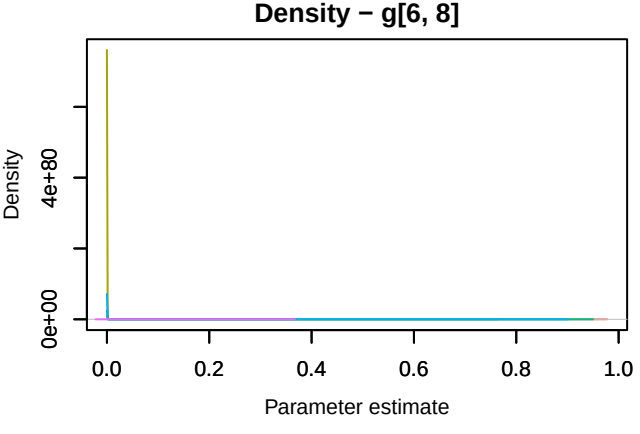

Trace − g[4, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

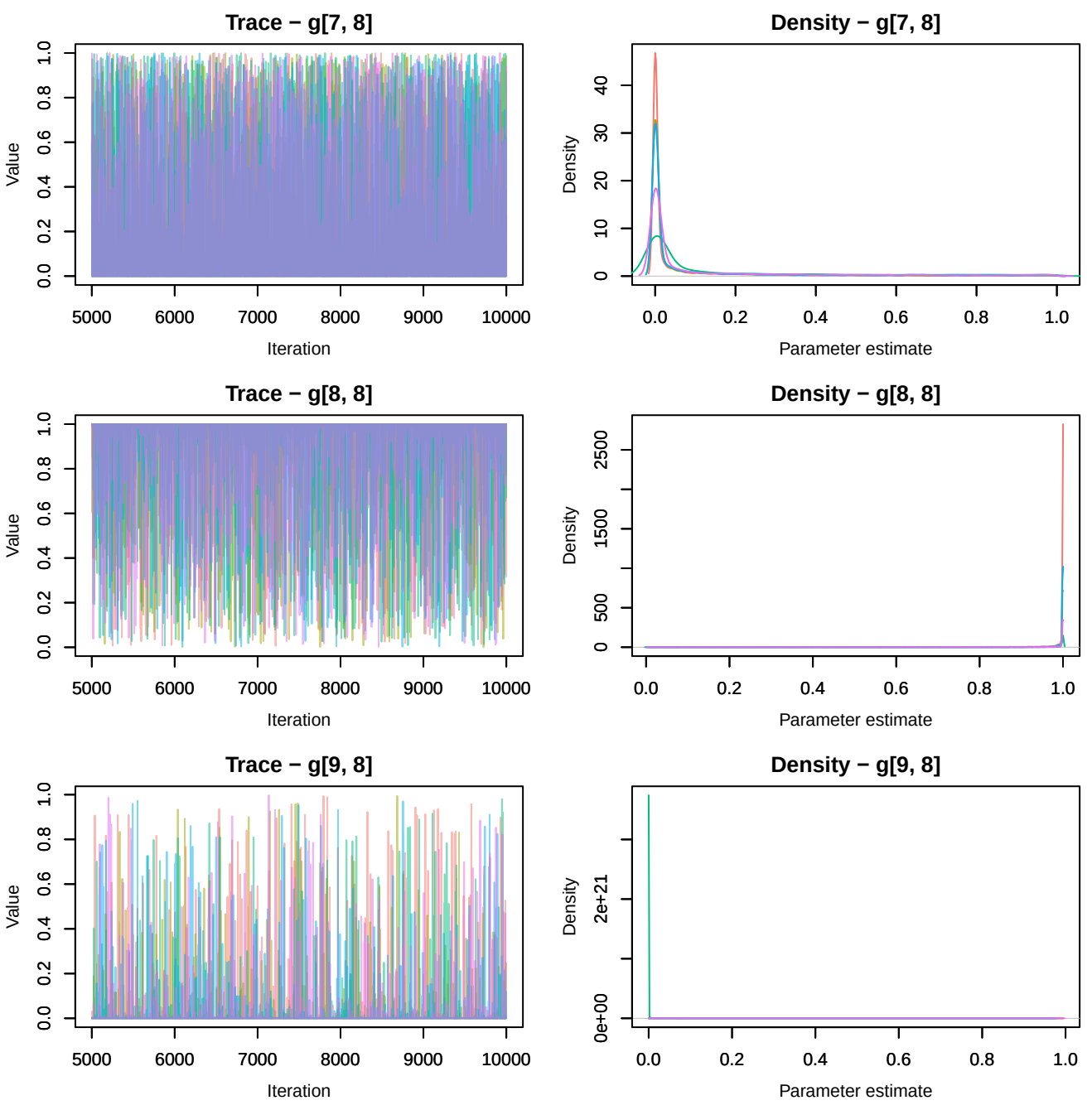

Density − g[4, 8]
Density
0e+00
4e+80
8e+80
0.00
0.05
0.10
0.15
0.20
0.25
0.30
0.35
Parameter estimate

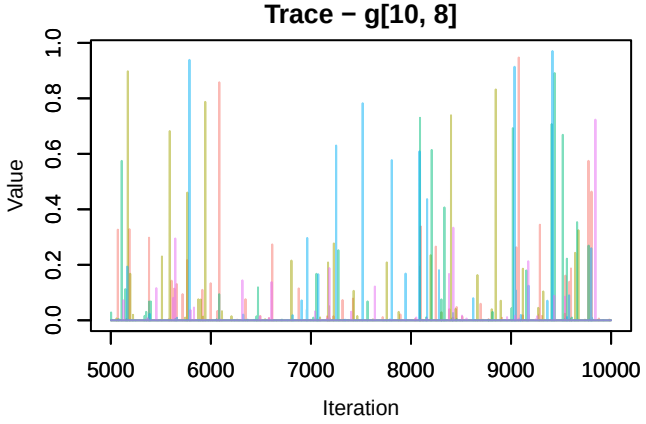

Trace − g[5, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

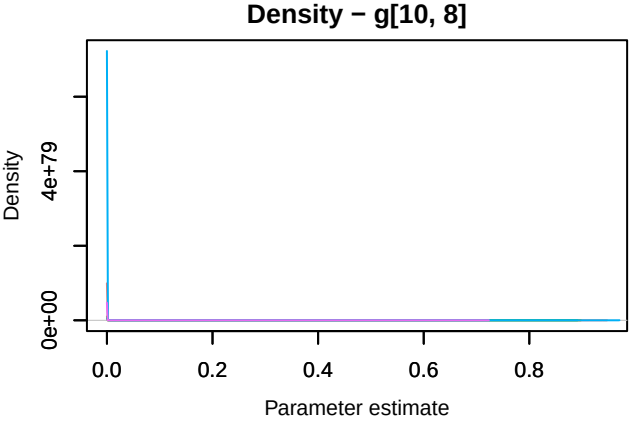

Density − g[5, 8]
Density
0e+00
2e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

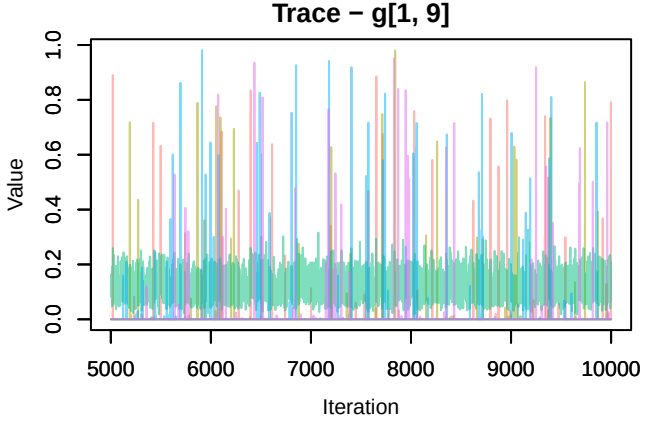

Trace − g[6, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

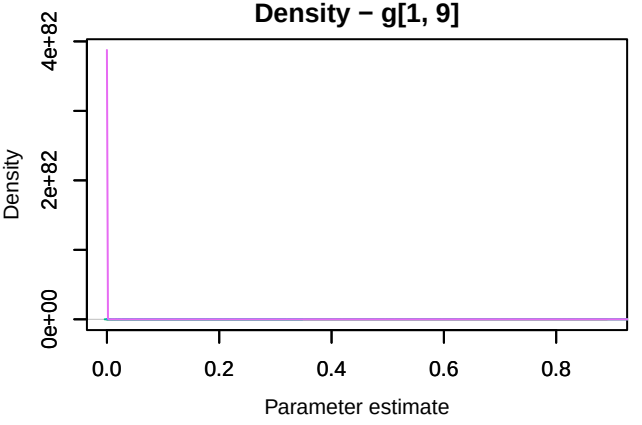

Density − g[6, 8]
Density
0e+00
4e+80
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

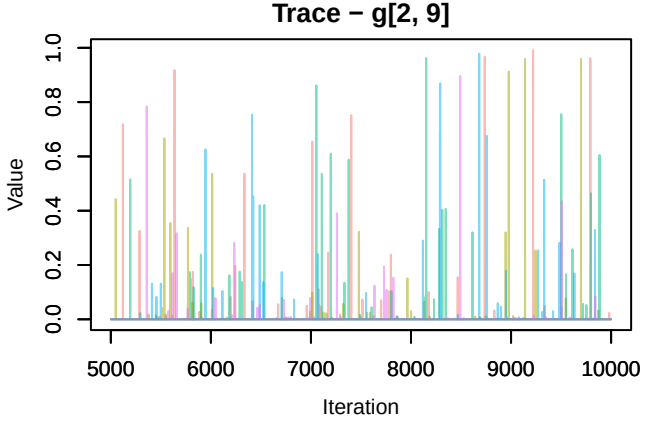

Trace − g[7, 8]
Value
Iteration
Density − g[7, 8]
Density
Parameter estimate
Trace − g[8, 8]
Value
Iteration
Density − g[8, 8]
Density
Parameter estimate
Trace − g[9, 8]
Value
Iteration
Density − g[9, 8]
Density
Parameter estimate

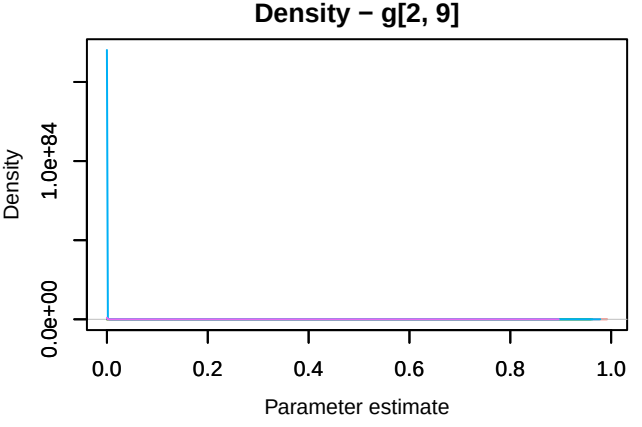

Trace − g[10, 8]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

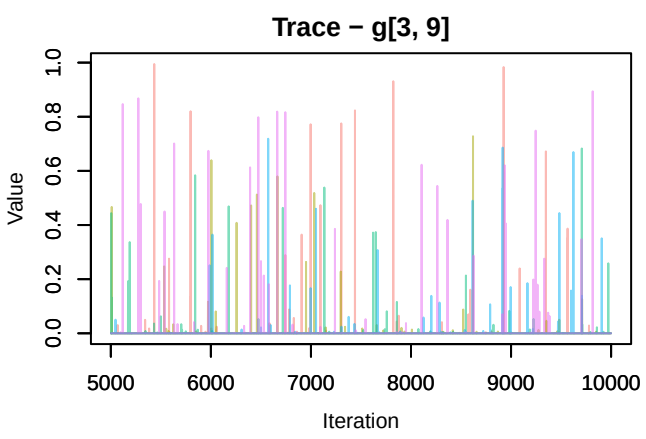

Density − g[10, 8]
Density
0e+00
4e+79
0.0
0.2
0.4
0.6
0.8
Parameter estimate

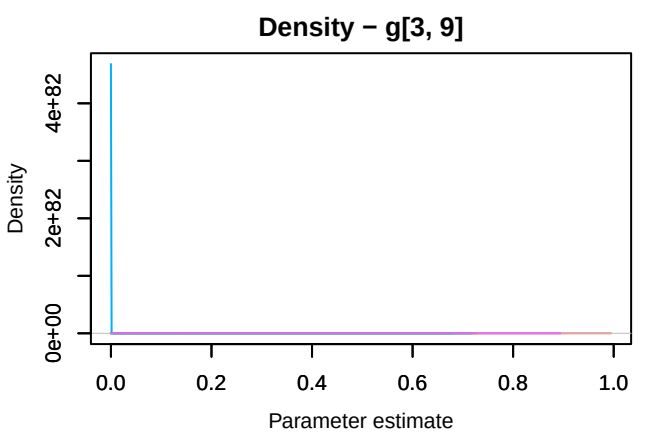

Trace − g[1, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

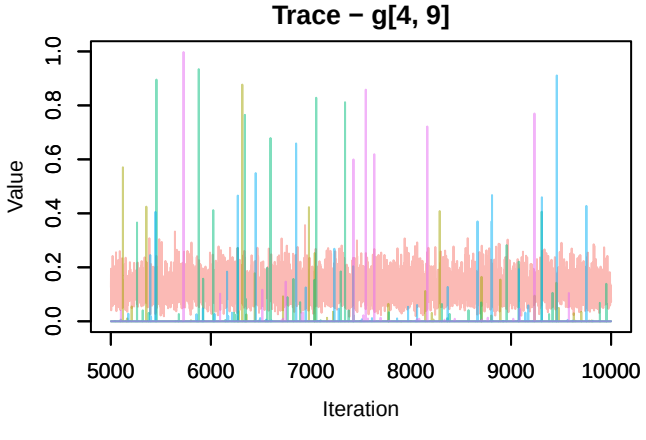

Density − g[1, 9]
Density
0e+00
2e+82
4e+82
0.0
0.2
0.4
0.6
0.8
Parameter estimate

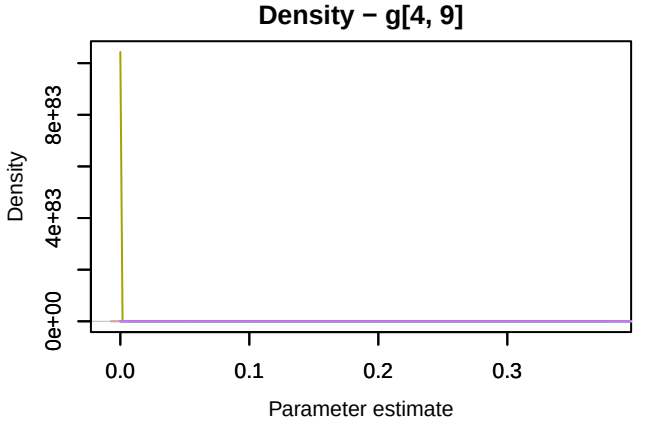

Trace − g[2, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

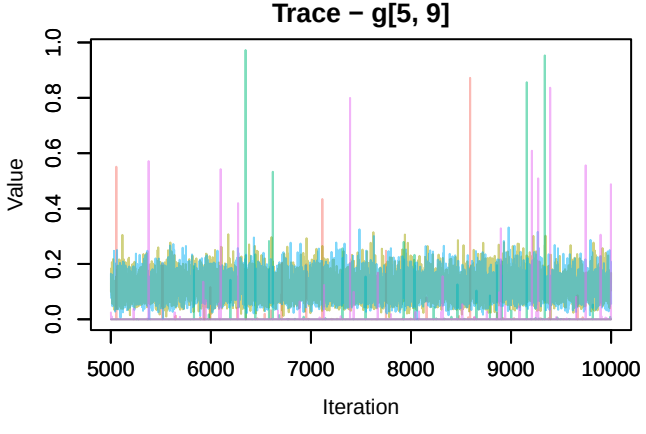

Density − g[2, 9]
Density
0.0e+00
1.0e+84
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

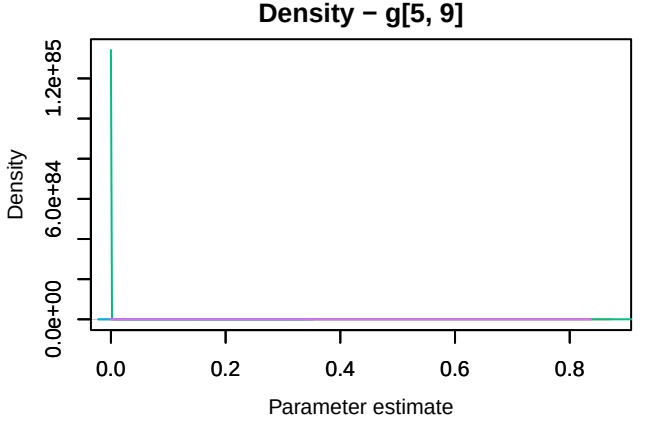

Trace − g[3, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

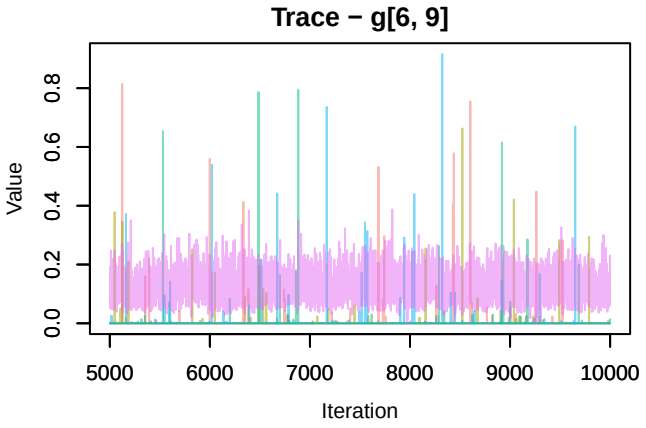

Density − g[3, 9]
Density
0e+00
2e+82
4e+82
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

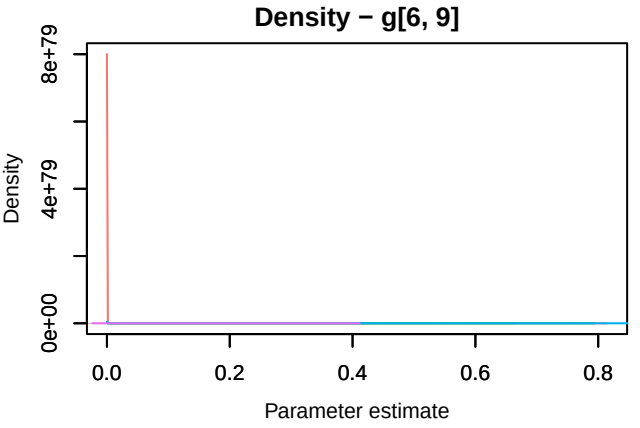

Trace − g[4, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

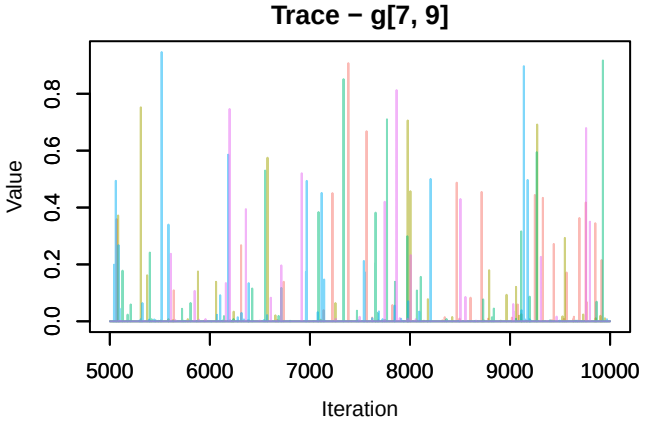

Density − g[4, 9]
Density
0e+00
4e+83
8e+83
0.0
0.1
0.2
0.3
Parameter estimate

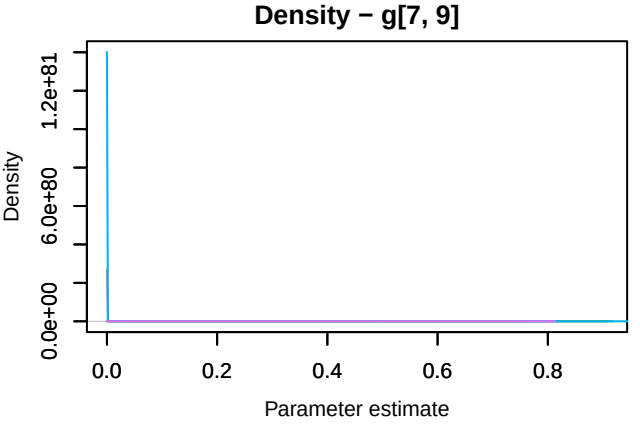

Trace − g[5, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

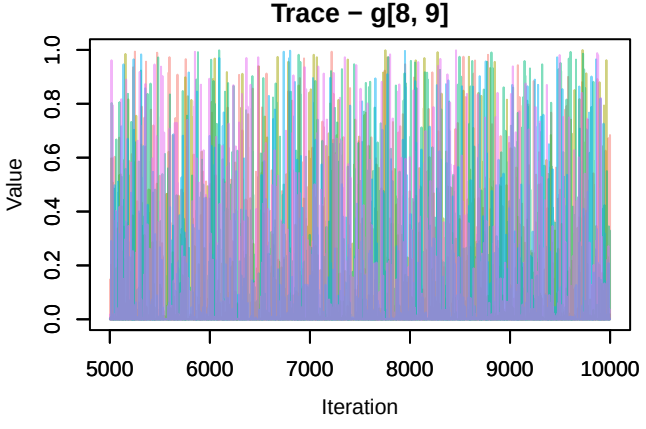

Density − g[5, 9]
Density
0.0e+00
6.0e+84
1.2e+85
0.0
0.2
0.4
0.6
0.8
Parameter estimate

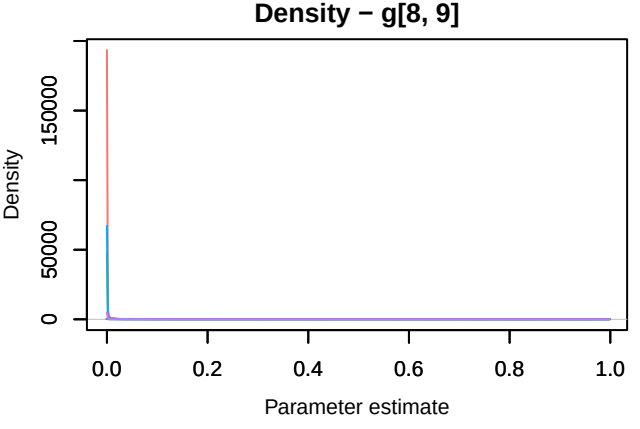

Trace − g[6, 9]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

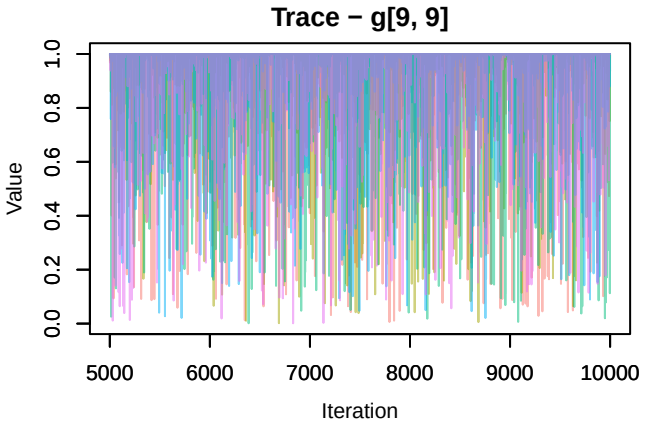

Density − g[6, 9]
Density
0e+00
4e+79
8e+79
0.0
0.2
0.4
0.6
0.8
Parameter estimate

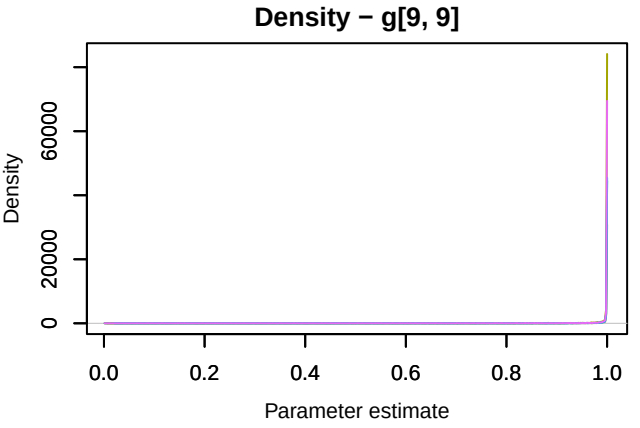

Trace − g[7, 9]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

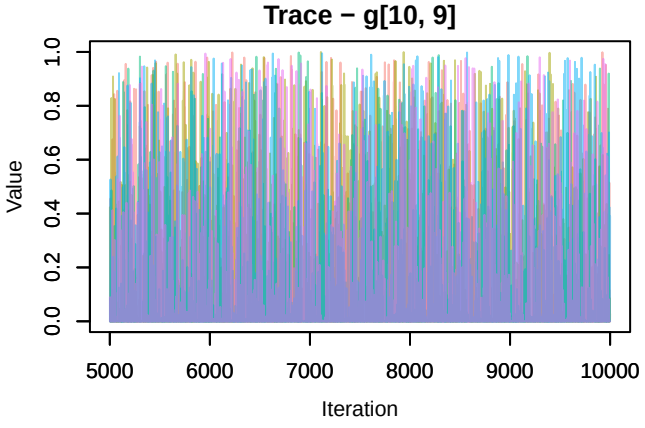

Density − g[7, 9]
Density
0.0e+00
6.0e+80
1.2e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

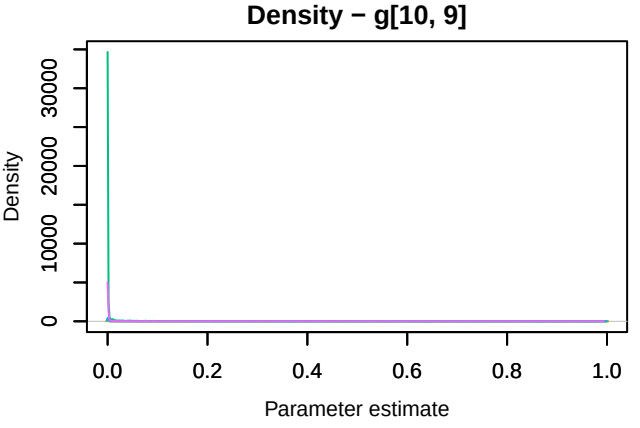

Trace − g[8, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

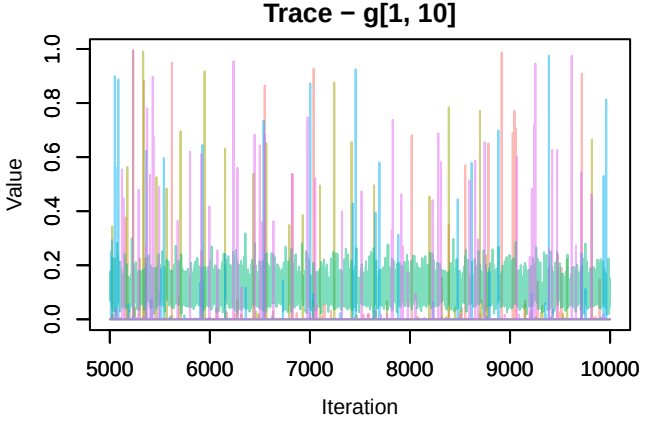

Density − g[8, 9]
Density
0
50000
150000
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

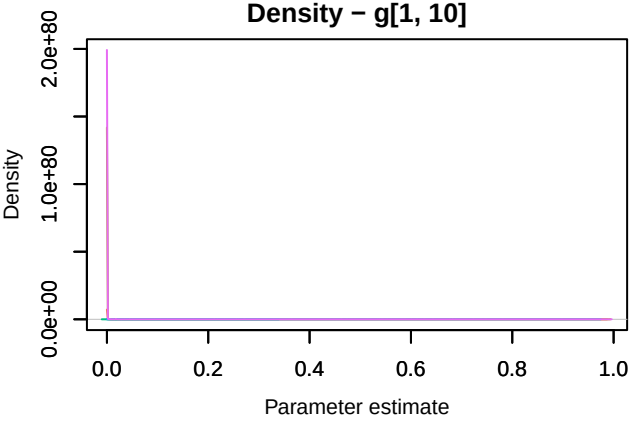

Trace − g[9, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

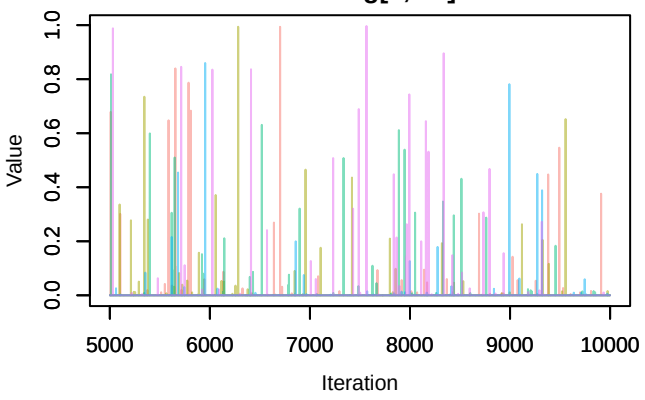

Density − g[9, 9]
Density
0
20000
60000
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

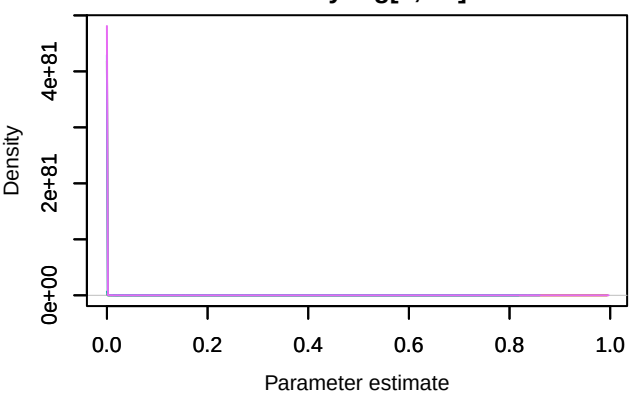

Trace − g[10, 9]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

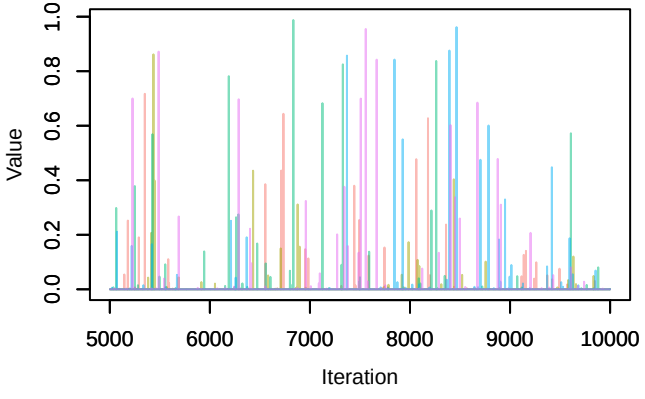

Density − g[10, 9]
Density
0
10000
20000
30000
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

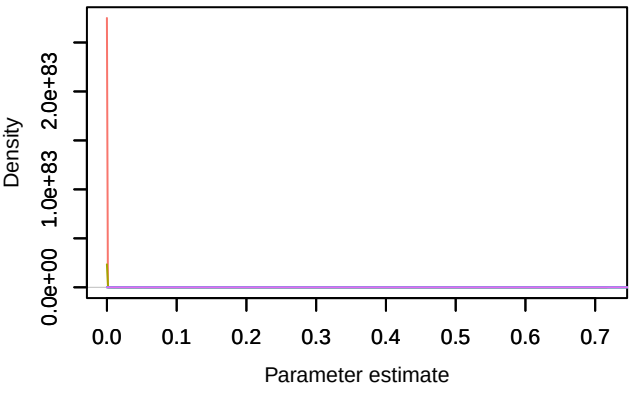

Trace − g[1, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

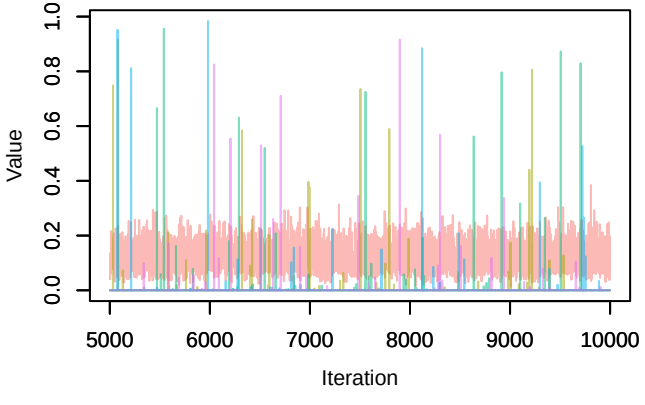

Density − g[1, 10]
Density
0.0e+00
1.0e+80
2.0e+80
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

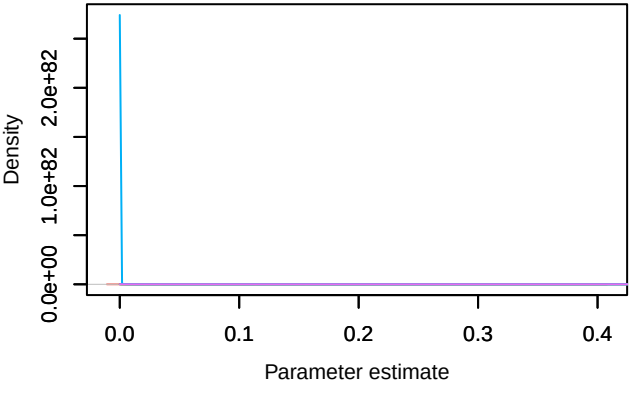

Trace − g[2, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

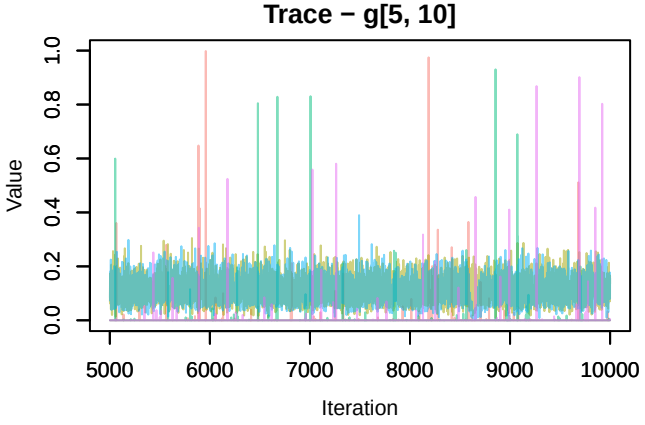

Density − g[2, 10]
Density
0e+00
2e+81
4e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

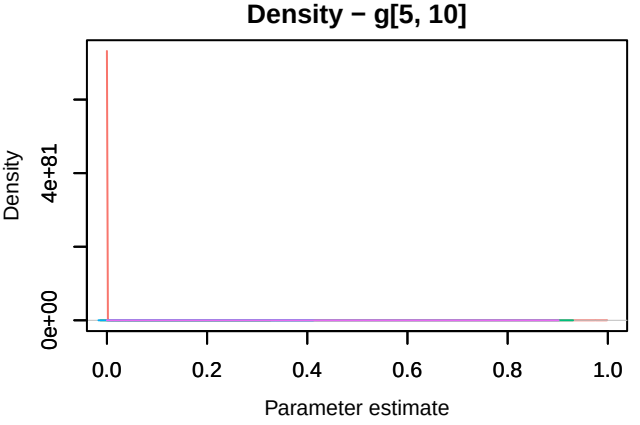

Trace − g[3, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

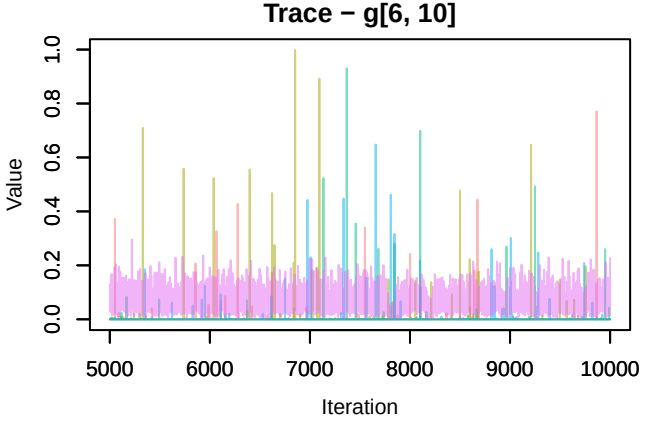

Density − g[3, 10]
Density
0.0e+00
1.0e+83
2.0e+83
0.0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
Parameter estimate

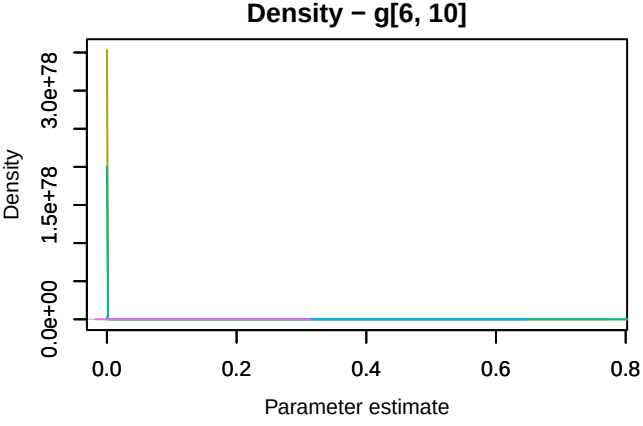

Trace − g[4, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

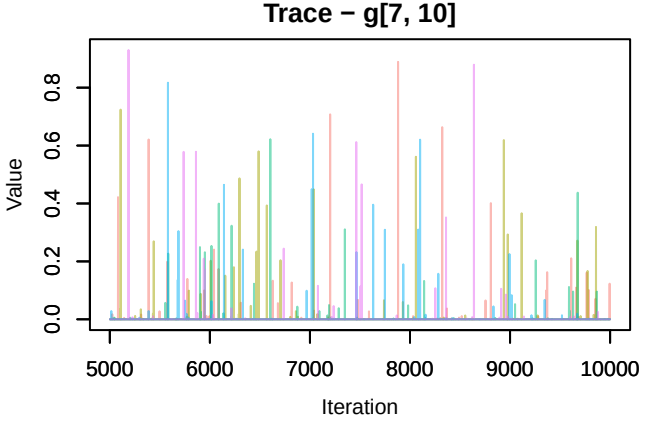

Density − g[4, 10]
Density
0.0e+00
1.0e+82
2.0e+82
0.0
0.1
0.2
0.3
0.4
Parameter estimate

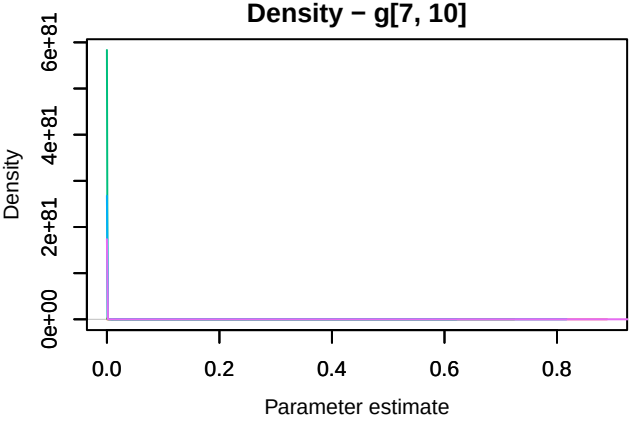

Trace − g[5, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

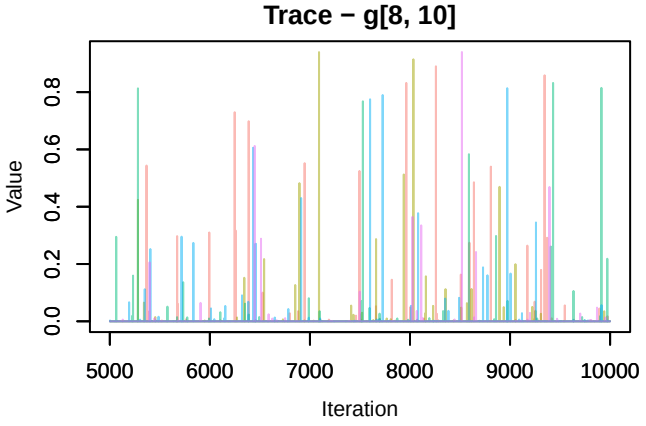

Density − g[5, 10]
Density
0e+00
4e+81
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate

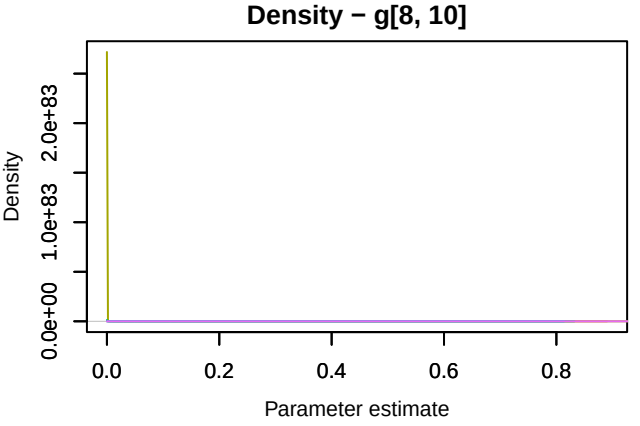

Trace − g[6, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration

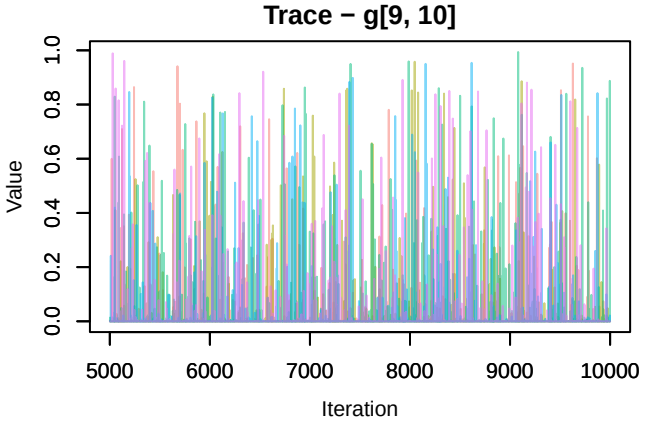

Density − g[6, 10]
Density
0.0e+00
1.5e+78
3.0e+78
0.0
0.2
0.4
0.6
0.8
Parameter estimate

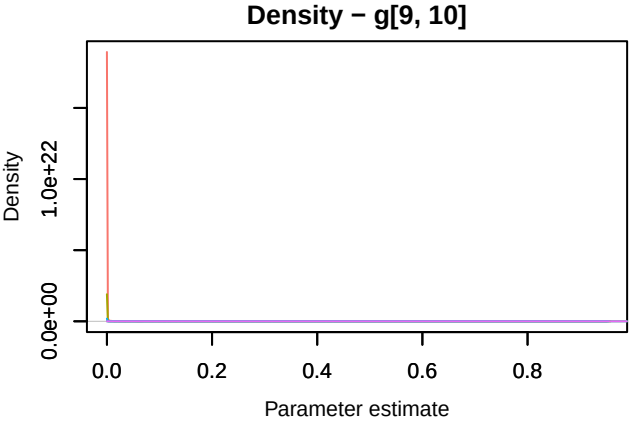

Trace − g[7, 10]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration

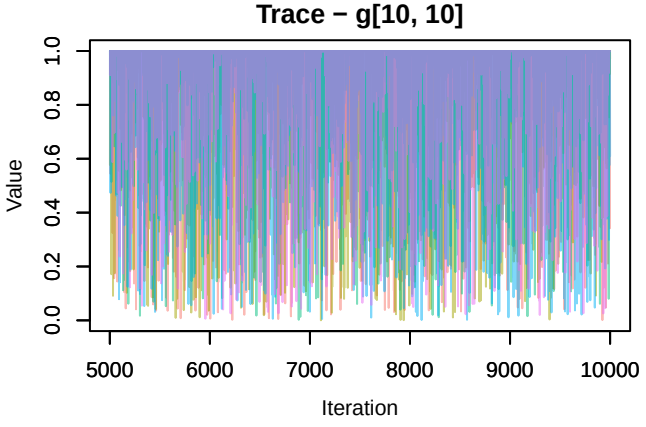

Density − g[7, 10]
Density
0e+00
2e+81
4e+81
6e+81
0.0
0.2
0.4
0.6
0.8
Parameter estimate

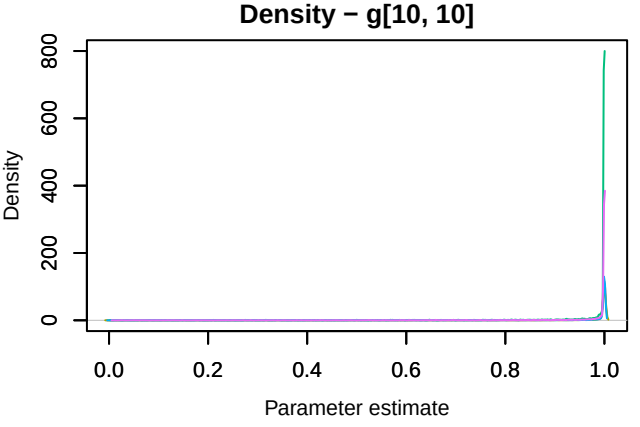

Trace − g[8, 10]
Value
0.0
0.2
0.4
0.6
0.8
5000
6000
7000
8000
9000
10000
Iteration


Density − g[8, 10]
Density
0.0e+00
1.0e+83
2.0e+83
0.0
0.2
0.4
0.6
0.8
Parameter estimate


Trace − g[9, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration


Density − g[9, 10]
Density
0.0e+00
1.0e+22
0.0
0.2
0.4
0.6
0.8
Parameter estimate


Trace − g[10, 10]
Value
0.0
0.2
0.4
0.6
0.8
1.0
5000
6000
7000
8000
9000
10000
Iteration


Density − g[10, 10]
Density
0
200
400
600
800
0.0
0.2
0.4
0.6
0.8
1.0
Parameter estimate