



4th March 2024

## Dear (young)ESAO members and friends of the ESAO community,

We would like to extend to you and your colleagues the special invitation by Prof. Andrea Remuzzi to submit an article for possible publication in an upcoming youngESAO Special Issue of the International Journal for Artificial Organs (IJAO, IF=1.7). The yESAO Special Issue will be published next August and will reach a wide audience within the academic community. If you are interested to submit a manuscript for publication in this Special Issue, we kindly ask you to send an email message to the Editorial Secretary (nollisilvia@gmail.com) with a suggested title of the contribution. We ask you to send us this message by Mach 15th.

The deadline for the **manuscript submissions will be April 30th**, which allows time for preparation and review. The Authors will have the **possibility to apply for the SAGE award and the winning authors can present their work at the ESAO 2024** conference, providing a platform for networking and recognition.

What are the **main benefits** of publishing on IJAO in the context of **yESAO Special Issue**?

- You can apply for the SAGE Award 2024 (awarded with 2500€)
- You will have the unique opportunity to engage directly with the Section Editors to discuss your article and receive valuable feedback
- No costs associated with the submission process
- Rapid publication in the August IJAO issue

## What are the key facts?

- Title submission by Mach 15th (non-binding)
- Article submission by April 30th
- Acceptance by June 30th and publication in the yESAO Special Issue in August

We believe that your expertise and research would be a valuable addition to our journal and we sincerely hope that you will consider submitting an article for consideration. Should you have any questions or require further information, please do not hesitate to contact us at yesao@esao.org.

Thank you for considering this invitation, and we look forward to read your contribution.

Tom Bode, Isabell Esslinger and Jana Korte