

ENHANCED NOISE SENSITIVITY, 2D DIRECTED POLYMERS AND STOCHASTIC HEAT FLOW

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ABSTRACT. We investigate noise sensitivity beyond the classical setting of binary random variables, extending the celebrated result by Benjamini, Kalai, and Schramm to a wide class of functions of general random variables. Our approach yields improved bounds with optimal rates. We also consider an enhanced form of noise sensitivity which yields asymptotic independence, rather than mere decorrelation.

We apply these results to establish enhanced noise sensitivity for the partition functions of 2D directed polymers, in the critical regime where they converge to the critical 2D Stochastic Heat Flow. As a consequence, we prove that the Stochastic Heat Flow is independent of the white noise arising from the disorder.

1. Introduction

Given a function $f(\omega)$ that depends on independent random variables $\omega = (\omega_1, \omega_2, \dots)$, the concept of *noise sensitivity* describes the intriguing phenomenon where a small perturbation of the variables ω_i completely alters the function's output. This phenomenon is particularly relevant in the study of Boolean functions [O'D14], where small changes in input bits can make the output unpredictable, and in statistical physics [GS14], where it describes the sensitivity of systems to random noise, especially in the proximity of a phase transition.

The literature on noise sensitivity has largely focused on binary variables ω_i taking two values, say x_+ and x_- :

$$\mathbb{P}(\omega_i = x_+) = p \quad \text{and} \quad \mathbb{P}(\omega_i = x_-) = 1 - p \quad \text{for some } p \in (0, 1). \quad (1.1)$$

Most results also concern Boolean functions $f(\omega) \in \{0, 1\}$ (see references below). In this paper, we extend the classical BKS criterion for noise sensitivity [BKS99] to a general setting, allowing for a wide class of *non-Boolean functions* $f(\omega) \in \mathbb{R}$ of *general random variables* ω_i (see Theorems 2.9-2.10). When specialised to the binary setting, our results yield *asymptotically optimal rates* (see Theorems 2.17-2.18).

The concept of noise sensitivity is usually formulated in terms of vanishing correlations (see (2.1)) which — for Boolean function $f(\omega) \in \{0, 1\}$ — corresponds to asymptotic independence. For general real functions $f(\omega) \in \mathbb{R}$, however, it is natural to consider an *enhanced form of noise sensitivity* (see (2.24)), where $f(\omega)$ is composed with suitable test functions to ensure asymptotic independence, rather than mere decorrelation. We show that the *BKS criterion implies enhanced noise sensitivity*, at least when the random variables ω_i take finitely many values (see Theorem 2.15).

Date: July 14, 2025.

2010 *Mathematics Subject Classification.* Primary: 05D40; Secondary: 82B44, 60H15.

Key words and phrases. Directed Polymer in Random Environment, Disordered System, Influence, Noise Sensitivity, Stochastic Heat Equation, Stochastic Heat Flow.

Our results on noise sensitivity are presented in Section 2. In the following Section 3, we apply them to a model from statistical mechanics: the two-dimensional directed polymer in random environment. We first establish an instance of *enhanced noise sensitivity for the partition functions* (see Theorem 3.2), in the critical regime where they converge to the Critical 2D Stochastic Heat Flow (SHF) [CSZ23]. Next, we prove the *independence of the SHF from the white noise originating from the environment* (see Theorem 3.6), which indicates that the SHF is not the solution of a stochastic PDE driven by white noise.

In the related setting of the two-dimensional Stochastic Heat Equation with spatially regularised white noise, the convergence of the solution to the SHF was recently established in [Tsa24]. An analogue of our Theorem 3.6 in this context — proving independence of the SHF from the white noise — was obtained independently and simultaneously in [GT25], as a corollary of the main result of the paper, which shows that the SHF is a so-called black noise. We refer the reader to the beginning of Section 3 for a more detailed discussion of the SHF and further references.

The following Sections 4–6 are devoted to the proof of our results, while some technical points are deferred to the appendices.

Acknowledgements. We are very much indebted to Christophe Garban, who introduced one of us (F.C.) to noise sensitivity and suggested to investigate it for directed polymers.

We are also grateful to Malo Hillairet, Giovanni Peccati and Hugo Vanneuville for enlightening discussions and for pointing out relevant references.

We thank Daniel Ahlberg, Malo Hillairet and Ekaterina Toropova for generously sharing a preliminary version of their manuscript [AHT25], in which they independently prove a generalisation of the BKS criterion, using different techniques.

2. Main results for noise sensitivity

In this section, we present our main results concerning noise sensitivity. Let us first recall classical results in the setting of binary random variables ω_i 's, see (1.1).

2.1. Binary setting. Given independent random variables $\omega = (\omega_1, \omega_2, \dots)$, we denote by $\omega^\varepsilon = (\omega_1^\varepsilon, \omega_2^\varepsilon, \dots)$ the configuration obtained by independently resampling each ω_i with probability ε (see Definition 4.1). We focus in this subsection on binary ω_i 's, see (1.1).

A sequence of Boolean functions $f_N(\omega) \in \{0, 1\}$ is called *noise sensitive* if

$$\forall \varepsilon > 0: \quad \lim_{N \rightarrow \infty} \text{Cov}[f_N(\omega^\varepsilon), f_N(\omega)] = 0, \quad (2.1)$$

which implies the asymptotic independence of $f_N(\omega^\varepsilon)$ and $f_N(\omega)$. This notion was introduced by I. Benjamini, G. Kalai and O. Schramm in their seminal paper [BKS99].

It was shown in the same paper that noise sensitivity is closely related to the probability that flipping a single variable ω_k changes the output of the function $f(\omega)$. To formalize this, the *influence* of ω_k on $f(\omega)$ is defined as

$$I_k(f) := \mathbb{P}(f(\omega_+^k) \neq f(\omega_-^k)), \quad (2.2)$$

where ω_\pm^k denotes the configuration $\omega = (\omega_1, \omega_2, \dots)$ with ω_k fixed to x_\pm . The main result of [BKS99] establishes a sufficient “BKS criterion” for noise sensitivity, based on the *sum of squared influences*: for any sequence of Boolean functions $f_N(\omega) \in \{0, 1\}$, we have

$$\sum_k I_k(f_N)^2 \xrightarrow[N \rightarrow \infty]{} 0 \quad \implies \quad (f_N)_{N \in \mathbb{N}} \text{ is noise sensitive.} \quad (2.3)$$

This result was originally proved in the symmetric case $p = \frac{1}{2}$ in [BKS99], but remarked to hold for any $p \in (0, 1)$; a proof was given in [ABGR14].

Intuitively, the sum of squared influences measures how much the function f_N depends on individual variables ω_k . If this sum vanishes as $N \rightarrow \infty$, it indicates that no single variable has a significant impact on the output, which must depend jointly on many variables, making the function highly sensitive to noise.

A quantitative refinement of the BKS criterion (2.3) was provided by N. Keller and G. Kindler [KK13, Theorem 7]: for any $\varepsilon \in (0, 1)$ there is an exponent $\gamma_\varepsilon = \gamma_{\varepsilon, p} > 0$ such that, for all Boolean functions $f(\omega) \in \{0, 1\}$, one can bound

$$\text{Cov}[f(\omega^\varepsilon), f(\omega)] \leq 20 \mathcal{W}[f]^{\gamma_\varepsilon} \quad \text{with} \quad \mathcal{W}[f] := 4p(1-p) \sum_k I_k[f]^2. \quad (2.4)$$

This was improved in [EG22], where it was shown that — always for Boolean functions $f(\omega) \in \{0, 1\}$ — the RHS can be multiplied by $\text{Var}[f]$.

The estimate (2.4) shows that the covariance between $f(\omega^\varepsilon)$ and $f(\omega)$ is controlled by a power of the sum of squared influences $\mathcal{W}[f]$ and, clearly, it implies the BKS criterion (2.3). The exponent γ_ε is asymptotically linear as $\varepsilon \downarrow 0$, namely $\gamma_\varepsilon \sim \alpha \varepsilon$ for a suitable $\alpha = \alpha(p) > 0$ (the asymptotic notation \sim means that the ratio of the two sides converges to 1).

It was already remarked in [KK13, ABGR14] that the BKS criterion (2.3) holds beyond Boolean functions. For instance, the proof of the estimate (2.4) in [KK13] goes through for any function $f(\omega) \in [0, 1]$, provided one extends the definition (2.2) of influence as follows:

$$I_k[f] = \mathbb{E}[|f(\omega_+^k) - f(\omega_-^k)|]. \quad (2.5)$$

More recently, building on ideas from [R06, FS07], it was observed by R. van Handel in a series of lectures (reported in [Ros20]) that a variation of (2.4) holds, in the symmetric case $p = \frac{1}{2}$, for general functions $f(\omega) \in L^2$: for any $\varepsilon \in (0, 1)$, setting $\vartheta_\varepsilon = \frac{\varepsilon}{2-\varepsilon}$, one has

$$\text{Cov}[f(\omega^\varepsilon), f(\omega)] \leq \text{Var}[f]^{1-\vartheta_\varepsilon} \mathcal{W}[f]^{\vartheta_\varepsilon} \quad (2.6)$$

(the exponent ϑ_ε improves on γ_ε from (2.4), since $\gamma_\varepsilon \sim 0.234 \varepsilon$ as $\varepsilon \downarrow 0$, while $\vartheta_\varepsilon > 0.5 \varepsilon$).

The bound (2.6) can also be extended to general binary variables ω_i with $p \in (0, 1)$, for a suitable $\vartheta_{\varepsilon, p} > 0$, as shown in the forthcoming work [AHT25], which studies noise sensitivity with applications to Last Passage Percolation.

All the above results are formulated for binary variables ω_i . Our goal is to go *beyond the binary setting*, extending the BKS criterion (2.3) to general random variables ω_i 's and to a large class of functions $f(\omega) \in L^2$. We establish a quantitative bound like (2.6), with a suitable extension of the “ L^1 notion” (2.5) of influence. We also investigate an enhanced notion of noise sensitivity, which yields asymptotic independence beyond Boolean functions.

In the next Subsection 2.2 we formulate our setting and assumptions. In the following Subsection 2.3 we extend the notion of influence. Subsections 2.4–2.6 are devoted to the presentation of our main results, followed by some concluding remarks in Subsection 2.7.

Remark 2.1. *Even though we focus on the setting of a finite or countable family of random variables $(\omega_i)_{i \in \mathbb{T}}$, we point out that noise sensitivity can also be studied in a continuum setting. We refer to [LPY23, BPY24] for criteria ensuring noise sensitivity for Poisson point processes, with applications to problems involving continuum percolation.*

2.2. Our setting. We consider independent random variables $\omega = (\omega_i)_{i \in \mathbb{T}}$, labeled by a finite or countable set \mathbb{T} , defined on a probability space[†] $(\Omega, \mathcal{A}, \mathbb{P})$ and taking values in measurable spaces (E_i, \mathcal{E}_i) :

$$\omega_i : \Omega \rightarrow E_i \quad \text{with law} \quad \mu_i(\cdot) = \mathbb{P}(\omega_i \in \cdot). \quad (2.7)$$

In many examples the ω_i 's take values in the same space $(E_i, \mathcal{E}_i) = (E, \mathcal{E})$ and they are i.i.d. (independent and identically distributed), but we do not require it.

We are interested in functions $f(\omega) \in L^2$ (where $f : \times_{i \in \mathbb{T}} E_i \rightarrow \mathbb{R}$ is measurable). We anticipate that, *when the ω_i 's are i.i.d. and take finitely many values, we do not need to impose any further constraint on $f(\omega)$* . For general ω_i 's, we need to require a suitable hypercontractivity condition, that we now describe and illustrate by examples.

Given an index $i \in \mathbb{T}$, we can look at $f(\omega)$ as a function of ω_i , denoted by $\omega_i \mapsto f(\omega)$, keeping all other variables $(\omega_j)_{j \neq i}$ fixed. We will single out, for each $i \in \mathbb{T}$, a vector space \mathcal{V}_i of functions of ω_i which a.s. contains $\omega_i \mapsto f(\omega)$, that is

$$\forall i \in \mathbb{T}, \quad \text{for a.e. } (\omega_j)_{j \neq i} : \quad \omega_i \mapsto f(\omega) \text{ belongs to } \mathcal{V}_i \subseteq L^2(E_i, \mu_i). \quad (2.8)$$

Of course, the simplest choice would be to just take $\mathcal{V}_i \equiv L^2(E_i, \mu_i)$, so that (2.8) holds for any $f(\omega) \in L^2$ (by Fubini's theorem). The reason for choosing a smaller $\mathcal{V}_i \subsetneq L^2(E_i, \mu_i)$ is to ensure a *hypercontractivity bound*: we require that centred functions $g \in \mathcal{V}_i$ have L^q norm controlled by the L^2 norm, for some $q > 2$. This is our main assumption.

Assumption 2.2. *The independent random variables $(\omega_i)_{i \in \mathbb{T}}$ and the function $f(\omega) \in L^2$ satisfy the following conditions.*

- (a) *For any $i \in \mathbb{T}$, there is a closed and separable vector space $\mathcal{V}_i \subseteq L^2(E_i, \mu_i)$ containing the constants, i.e. $1 \in \mathcal{V}_i$, such that $\omega_i \mapsto f(\omega) \in \mathcal{V}_i$ a.s. (that is, (2.8) holds).*
- (b) *There exist an exponent $q \in (2, \infty)$ and a constant $M_q < \infty$ such that, for any $i \in \mathbb{T}$,*

$$\|g(\omega_i)\|_q \leq M_q \|g(\omega_i)\|_2 \quad \forall g \in \mathcal{V}_i \quad \text{with} \quad \mathbb{E}[g(\omega_i)] = 0, \quad (2.9)$$

where $\|\cdot\|_q = \mathbb{E}[|\cdot|^q]^{1/q}$ denotes the usual L^q norm.

This assumption is quite general and covers a variety of settings. We present here two relevant examples, deferring a more detailed discussion to Appendix C, where we connect Assumption 2.2 to the notion of *ensembles* from [MOO10, Definition 3.1]. We point out that a similar assumption also appears in [BF08, Proposition 2.1].

The first example concerns binary or, more generally, finite valued random variables ω_i . In this setting, we allow for arbitrary functions $f(\omega) \in L^2$.

Example 2.3 (Finite support). Let the random variables $(\omega_i)_{i \in \mathbb{T}}$ be i.i.d. and take finitely many values, i.e. their law $\mu_i = \mu$ has finite support ($\mu(I) = 1$ with $|I| < \infty$).

Then Assumption 2.2 is satisfied by every function $f(\omega) \in L^2$, for any exponent $q > 2$ (just choose $\mathcal{V}_i = L^2(E, \mu) = L^q(E, \mu)$) and for a suitable $M_q < \infty$ depending only on μ . We refer to Lemma C.1 and Remark C.2 for an elementary proof.

[†]We could work on the canonical space $\Omega = \times_{i \in \mathbb{T}} E_i$, taking ω_i as the coordinate projections, but it is sometimes convenient to allow for extra randomness, e.g. to define ω^ε .

The second example concerns general real valued random variables ω_i 's satisfying a moment condition. In this setting, we can allow for any *polynomial chaos* $f(\omega) \in L^2$. This will be relevant for the application to directed polymers in Section 3.

Example 2.4 (Polynomial chaos). Let the $(\omega_i)_{i \in \mathbb{T}}$ be independent real random variables with zero mean, unit variance and a uniformly bounded moment of some order $q > 2$:

$$\mathbb{E}[\omega_i] = 0, \quad \mathbb{E}[\omega_i^2] = 1, \quad M_q := \sup_{i \in \mathbb{T}} \|\omega_i\|_q < \infty. \quad (2.10)$$

Then Assumption 2.2 is satisfied by all $f(\omega) \in L^2$ that are *polynomial chaos*, i.e. multi-linear polynomials (or power series), where each variable ω_i appears with power 0 or 1:

$$f(\omega) = \mathbb{E}[f] + \sum_{d=1}^{\infty} f^{(d)}(\omega) \quad \text{with} \quad f^{(d)}(\omega) = \sum_{\substack{\{i_1, \dots, i_d\} \subseteq \mathbb{T} \\ i_j \neq i_k \forall j \neq k}} \hat{f}(i_1, \dots, i_d) \omega_{i_1} \cdots \omega_{i_d} \quad (2.11)$$

(for coefficients $\hat{f}(\cdot)$ such that $\sum_{\{i_1, \dots, i_d\}} \hat{f}(i_1, \dots, i_d)^2 < \infty$, so the sum converges in L^2).

Since $\omega_i \mapsto f(\omega)$ is a *linear* map, we see that condition (2.8) holds with the choice $\mathcal{V}_i = \{g(x) = \alpha + \beta x: \alpha, \beta \in \mathbb{R}\}$ and the bound (2.9) holds by assumption (2.10).

Remark 2.5 (Beyond polynomial chaos). Assumption 2.2 is also satisfied by any $f(\omega) \in L^2$ which, as a function of each ω_i for fixed $(\omega_j)_{j \neq i}$, is a polynomial of uniformly bounded degree, provided the ω_i 's have enough finite moments; see Remark C.3 for details.

Remark 2.6 (Binary setting). For binary ω_i 's, see (1.1), every function $f(\omega) \in L^2$ is a polynomial chaos, by the Fourier-Walsh expansion (see Lemma B.1). Thus Examples 2.3 and 2.4 both extend the classical setting of binary ω_i 's, allowing for arbitrary $f(\omega) \in L^2$.

2.3. General influences. We extend the classical notion of influence (2.2) to general functions $f(\omega)$ of general random variables $(\omega_i)_{i \in \mathbb{T}}$.

For $k \in \mathbb{T}$, we introduce the “probabilistic gradient” of f with respect to ω_k :[†]

$$\delta_k f := f - \mathbb{E}_k[f] \quad \text{where we set} \quad \mathbb{E}_k[\cdot] := \mathbb{E}[\cdot | \sigma((\omega_j)_{j \neq k})]. \quad (2.12)$$

We then define the “ L^1 influence” of ω_k on f as the first absolute moment of $\delta_k f$:

$$\text{Inf}_k^{(1)}[f] := \mathbb{E}[|\delta_k f|] \quad (2.13)$$

which is a quantification of “how much f depends on ω_k ”. We finally extend the definition of $\mathcal{W}[f]$, see (2.4), as the sum of squared L^1 influences:

$$\mathcal{W}[f] := \sum_k \text{Inf}_k^{(1)}[f]^2. \quad (2.14)$$

Remark 2.7 (Binary vs. general influences). Definition (2.13) generalises the classical influence (2.2) (see Lemma A.4): for binary variables ω_i 's, see (1.1), one has the following correspondence for Boolean functions $f(\omega) \in \{0, 1\}$

$$\text{Inf}_k^{(1)}[f] = 2p(1-p) I_k[f].$$

In particular, the definition (2.14) of $\mathcal{W}[f]$ extends the classical one from (2.4).

[†]This extends a definition of Talagrand [Tal94] for binary ω_i 's (see Remark A.3). The same notion, denoted $\Delta_k f$, also appears in [BF08].

Remark 2.8 (L^1 vs. L^2 influences). A related notion of “ L^2 influence” is

$$\text{Inf}_k^{(2)}[f] := \mathbb{E}[(\delta_k f)^2]. \quad (2.15)$$

For Boolean functions $f(\omega) \in \{0, 1\}$ one has $\text{Inf}_k^{(1)}[f] = 2 \text{Inf}_k^{(2)}[f]$ (see Lemma A.1), hence L^1 and L^2 influences almost coincide, but for general functions they may differ significantly.

While the L^2 influence is relevant in several contexts, see e.g. [KKL88, Tal94, MOO10], it is the L^1 influence which plays a key role for our goals. This was already understood in [KK13, ABGR14, AHT25], where the influence $I_k[f]$ for non-Boolean functions f is defined as an L^1 norm, see (2.5). However, definition (2.5) still requires binary variables ω_i and, moreover, is based on a discrete gradient which treats the values x_{\pm} equally, even for $p \neq \frac{1}{2}$. This is why a “correction factor” $p(1-p)$ appears in the definition (2.4) of $\mathcal{W}[f]$.

Our general definition of influence (2.13) appears to be more suitable, since it is based on the probabilistic gradient $\delta_k f$ which takes into account the distribution of ω_k .

2.4. General criteria for noise sensitivity. We are ready to state our first main results, extending the Keller-Kindler bound (2.4) to our general setting, in the form (2.6).

We recall that $\omega^\varepsilon = (\omega_i^\varepsilon)_{i \in \mathbb{T}}$ is the configuration obtained from $\omega = (\omega_i)_{i \in \mathbb{T}}$ resampling each ω_i independently with probability ε , see Definition 4.1.

Theorem 2.9 (General noise sensitivity). Let $(\omega_i)_{i \in \mathbb{T}}$ be independent random variables and let $f(\omega) \in L^2$ be a function satisfying Assumption 2.2 for some $q > 2$ and $M_q < \infty$ (see e.g. Examples 2.3 and 2.4).

For any $\varepsilon \in (0, 1)$, there is an exponent $\gamma_{\varepsilon, q} > 0$ such that

$$\frac{\text{Cov}[f(\omega^\varepsilon), f(\omega)]}{\text{Var}[f]} \leq 4 \left(\frac{\mathcal{W}[f]}{\text{Var}[f]} \right)^{\gamma_{\varepsilon, q}}. \quad (2.16)$$

The exponent $\gamma_{\varepsilon, q}$, see (5.11), depends on the hypercontractivity constant η_q defined in Lemma 2.12, and it satisfies $\gamma_{\varepsilon, q} \sim \alpha_q \varepsilon$ as $\varepsilon \downarrow 0$ for an explicit $\alpha_q \in (0, \frac{1}{2})$, see (5.12).

We can give a uniform lower bound on the exponent $\gamma_{\varepsilon, q} \geq \bar{\gamma}_{\varepsilon, q, M_q} > 0$ depending on the constant M_q from Assumption 2.2 (see (5.15) below). As a consequence, we can apply the estimate (2.16) to a sequence of functions $(f_N(\omega))_{N \in \mathbb{N}}$, which yields the announced generalisation of the BKS criterion for noise sensitivity.

Theorem 2.10 (General BKS criterion). Let $(\omega_i)_{i \in \mathbb{T}}$ be independent random variables and let $(f_N(\omega))_{N \in \mathbb{N}}$ be functions satisfying Assumption 2.2 for the same $q > 2$ and $M_q < \infty$ (see e.g. Examples 2.3 and 2.4). Also assume that $\limsup_{N \rightarrow \infty} \text{Var}[f_N] < \infty$.

Then, recalling (2.13)-(2.14), the BKS criterion for noise sensitivity applies:

$$\lim_{N \rightarrow \infty} \mathcal{W}[f_N] = 0 \quad \implies \quad \forall \varepsilon > 0: \quad \lim_{N \rightarrow \infty} \text{Cov}[f_N(\omega^\varepsilon), f_N(\omega)] = 0. \quad (2.17)$$

The proof of Theorems 2.9-2.10 is presented in Section 5. We exploit a *chaos decomposition* known as Efron-Stein or Hoeffding decomposition, see Proposition 4.2, which generalises the notion (2.11) of polynomial chaos: we can write any $f(\omega) \in L^2$ as

$$f(\omega) = \mathbb{E}[f] + \sum_{d=1}^{\infty} f^{(d)}(\omega) \quad \text{with} \quad f^{(d)}(\omega) = \sum_{I \subseteq \mathbb{T}: |I|=d} f_I(\omega),$$

where the functions $f_I(\cdot)$ depend on the variables $(\omega_i)_{i \in I}$ and they are orthogonal to each other. By direct computation, see (4.9) and (4.14), we can write

$$\mathbb{V}\text{ar}[f] = \sum_{d=1}^{\infty} \|f^{(d)}\|_2^2, \quad \mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)] = \sum_{d=1}^{\infty} (1 - \varepsilon)^d \|f^{(d)}\|_2^2. \quad (2.18)$$

The proof of the bound (2.16) is then reduced to the estimate of $\|f^{(d)}\|_2^2$ for $d \in \mathbb{N}$, which we call the *variance spectrum* of f .

Remark 2.11 (Noise sensitivity and variance spectrum). *For functions $(f_N(\omega))_{N \in \mathbb{N}}$ with non-degenerate variances, say $a \leq \mathbb{V}\text{ar}[f_N] \leq b$ for some $0 < a < b < \infty$, it follows by (2.18) that noise sensitivity is equivalent to the variance spectrum drifting to infinity:*

$$\forall \varepsilon > 0: \lim_{N \rightarrow \infty} \mathbb{C}\text{ov}[f_N(\omega^\varepsilon), f_N(\omega)] = 0 \iff \forall d \in \mathbb{N}: \lim_{N \rightarrow \infty} \|f_N^{(d)}\|_2^2 = 0. \quad (2.19)$$

Proving Theorem 2.10 is then reduced to estimating $\|f^{(d)}\|_2^2$. For binary ω_i 's, this was obtained in [KK13] exploiting *exponential large deviations bounds*, which are not available in our setting, since Assumption 2.2 only asks for a finite moment bound, see (2.9). However, *moment bounds turn out to be just as good for our goals*: we show in Theorem 5.2 that

$$\frac{\sum_{\ell=1}^d \|f^{(\ell)}\|_2^2}{\mathbb{V}\text{ar}[f]} \leq \frac{1}{\eta_q^{2d}} \left(\frac{\mathcal{W}[f]}{\mathbb{V}\text{ar}[f]} \right)^{1-\frac{2}{q}} \quad (2.20)$$

where $\eta_q \in (0, 1)$ is the *hypercontractivity constant* defined in the following result, which follows by [MOO10, Proposition 3.16] and by the bound (2.9) from Assumption 2.2.

Lemma 2.12 (Hypercontractivity constant). *If Assumption 2.2 holds with $q > 2$ and $M_q < \infty$, see (2.9), there is a constant $\eta_q \in (0, 1)$ such that*

$$\forall a, b \in \mathbb{R}: \quad \|a + \eta_q b X\|_q \leq \|a + b X\|_2 \quad \begin{aligned} &\text{for any } X = g(\omega_i) \text{ with} \\ &\mathbb{E}[X] = 0, \quad g \in \mathcal{V}_i, \quad i \in \mathbb{T}. \end{aligned} \quad (2.21)$$

We fix $\eta_q \in (0, 1)$ as the largest constant for which (2.21) holds, which satisfies

$$\frac{1}{2M_q \sqrt{q-1}} \leq \eta_q \leq \frac{1}{\sqrt{q-1}}. \quad (2.22)$$

Once the key bound (2.20) is established, we can apply the second relation in (2.18) to deduce Theorem 2.9; see Section 5 for the details.

Remark 2.13. *Random variables X satisfying the bound in (2.21) are called $(2, q, \eta_q)$ -hypercontractive [MOO10, O'D14]. In the case of polynomial chaos, see Example 2.4, since \mathcal{V}_i consists of linear functions, it is enough to check (2.21) for $X = \omega_i - \mathbb{E}[\omega_i]$.*

Remark 2.14. *Even though there is a gap between the bounds in (2.22), one can show that the hypercontractivity constant η_q satisfies $\lim_{q \downarrow 2} \eta_q = 1$, see [CSZ20, Theorem B.1].*

2.5. Enhanced noise sensitivity.

The classical notion of noise sensitivity, namely

$$\forall \varepsilon > 0: \quad \lim_{N \rightarrow \infty} \mathbb{C}\text{ov}[f_N(\omega^\varepsilon), f_N(\omega)] = 0, \quad (2.23)$$

yields the asymptotic independence of $f_N(\omega^\varepsilon)$ and $f_N(\omega)$ for Boolean functions $f_N \in \{0, 1\}$. However, this is no longer true for functions that take more than two values.

For this reason, denoting by C_b^∞ the space of bounded and smooth functions with all bounded derivatives, it is natural to investigate an *enhanced noise sensitivity* condition:

$$\forall \varepsilon > 0: \quad \lim_{N \rightarrow \infty} \mathbb{C}\text{ov}[\varphi(f_N(\omega^\varepsilon)), \psi(f_N(\omega))] = 0 \quad \forall \varphi, \psi \in C_b^\infty \quad (2.24)$$

which yields the asymptotic independence of $f_N(\omega^\varepsilon)$ and $f_N(\omega)$ for general functions f_N (with, say, uniformly bounded variance). Indeed, if $f_N(\omega)$ converges in distribution as $N \rightarrow \infty$ to a random variable Y , then (2.24) implies that, for any $\varepsilon > 0$, the pair $(f_N(\omega), f_N(\omega^\varepsilon))$ converges in distribution to (Y, Y') where Y' is an independent copy of Y .

We now discuss conditions for the enhanced noise sensitivity property (2.24). By an application of Cauchy-Schwarz, see (4.15), it suffices to take $\psi = \varphi$ in (2.24), which reduces to the “classical” noise sensitivity condition (2.23) applied to the function $\varphi(f_N(\omega))$.

It is natural to try and apply the BKS criterion (2.17) from Theorem 2.10 to $\varphi(f_N(\omega))$. We note that influences are stable under compositions by Lipschitz functions, see (5.16):

$$\text{Inf}_k^{(1)}[\varphi(f)] \leq 2 \|\varphi'\|_\infty \text{Inf}_k^{(1)}[f], \quad (2.25)$$

therefore $\mathcal{W}[f_N] \rightarrow 0$ implies $\mathcal{W}[\varphi(f_N)] \rightarrow 0$ for all $\varphi \in C_b^\infty$. However, to apply Theorem 2.10 to $\varphi(f_N(\omega))$, we should first check that $\varphi(f_N(\omega))$ for $\varphi \in C_b^\infty$ satisfies Assumption 2.2. This is not obvious knowing only that $f_N(\omega)$ satisfies Assumption 2.2.

To avoid technicalities, we focus on the case when $(\omega_i)_{i \in \mathbb{T}}$ are i.i.d. random variables which take finitely many values, see Example 2.3. In this setting, Assumption 2.2 holds for any function in L^2 , hence it also applies to $\varphi(f_N(\omega))$. As a corollary of Theorem 2.10, we show that the BKS criterion yields enhanced noise sensitivity.

Theorem 2.15 (Enhanced noise sensitivity). *Let $(\omega_i)_{i \in \mathbb{T}}$ be i.i.d. random variables with finitely many values. Then, for any functions $(f_N(\omega))_{N \in \mathbb{N}}$ we have*

$$\lim_{N \rightarrow \infty} \mathcal{W}[f_N] = 0 \quad \implies \quad \forall \varepsilon > 0, \forall \varphi, \psi \in C_b^\infty: \quad \lim_{N \rightarrow \infty} \mathbb{C}\text{ov}[\varphi(f_N(\omega^\varepsilon)), \psi(f_N(\omega))] = 0. \quad (2.26)$$

This extends, for any $k \in \mathbb{N}$, to vector valued functions $f_N(\omega) = (f_N^{(1)}(\omega), \dots, f_N^{(k)}(\omega))$: the criterion (2.26) still applies with $\mathcal{W}[f_N] := \sum_{i=1}^k \mathcal{W}[f_N^{(i)}]$ (for $\varphi, \psi: \mathbb{R}^k \rightarrow \mathbb{R}$).

The proof of this result is given in Section 5. An interesting application to directed polymers and the SHF is presented in Section 3, where we exploit enhanced noise sensitivity to show *asymptotic independence of f_N from any bounded order chaos*, see Theorem 3.6.

2.6. Optimal BKS. Our generalisation (2.16) of the Keller-Kindler bound contains an exponent $\gamma_{\varepsilon, q} > 0$ which depends on the hypercontractivity constant η_q from Lemma 2.12. We now present a refined bound, obtained by optimising over q , which is especially interesting when the hypercontractivity constant η_q is explicit.

We consider in particular the situation when η_q attains its largest possible value $1/\sqrt{q-1}$, see (2.22). This includes the classical setting (1.1) of binary ω_i 's with $p = \frac{1}{2}$, see [Bon70], where we allow for arbitrary $f(\omega) \in L^2$. More generally, by Remark 2.13, we can consider any polynomial chaos $f(\omega) \in L^2$ if we assume that the centred random variables $X = \omega_i - \mathbb{E}[\omega_i]$ are so-called $(2, q, 1/\sqrt{q-1})$ -hypercontractive for any $q > 2$, that is

$$\forall q > 2, \forall a, b \in \mathbb{R}: \quad \|a + \eta_q b X\|_q \leq \|a + b X\|_2 \quad \text{with} \quad \eta_q = \frac{1}{\sqrt{q-1}}. \quad (2.27)$$

Let us recall some interesting distributions which satisfy (2.27).

Example 2.16 (Optimal hypercontractivity). The random variable $X = \omega_i - \mathbb{E}[\omega_i]$ satisfies the optimal bound (2.27) if ω_i has either of the following distributions:

- a binary distribution (1.1) with $p = \frac{1}{2}$ [Bon70];
- a Gaussian distribution $N(m, \sigma^2)$ for some $m \in \mathbb{R}$, $\sigma^2 > 0$ [Nel73];
- a uniform distribution on some interval $(a, b) \subseteq \mathbb{R}$ [MOO10, Theorem 3.13].

The following refined bound is proved in Section 5.

Theorem 2.17 (Refined bound). *Let the independent random variables $(\omega_i)_{i \in \mathbb{T}}$ and the function $f(\omega) \in L^2$ satisfy Assumption 2.2 for some $q = \bar{q}$. Then we can bound*

$$\forall \varepsilon \in (0, 1): \quad \frac{\text{Cov}[f(\omega^\varepsilon), f(\omega)]}{\text{Var}[f]} \leq \left(\frac{\mathcal{W}[f]}{\text{Var}[f]} \right)^{1 - \frac{2}{q(\varepsilon)}} \quad (2.28)$$

where $q(\varepsilon) > 2$ is defined by (recall $\eta_q \in (0, 1)$ from Lemma 2.12)

$$q(\varepsilon) := \sup \{q \in (2, \bar{q}): \eta_q^2 \geq 1 - \varepsilon\}. \quad (2.29)$$

In the special case when $\eta_q = 1/\sqrt{q-1}$ for any $q > 2$, we obtain the bound

$$\forall \varepsilon \in (0, 1): \quad \frac{\text{Cov}[f(\omega^\varepsilon), f(\omega)]}{\text{Var}[f]} \leq \left(\frac{\mathcal{W}[f]}{\text{Var}[f]} \right)^{\frac{\varepsilon}{2-\varepsilon}} \quad (2.30)$$

which applies, in particular, to any function $f(\omega) \in L^2$ of independent binary random variables $(\omega_i)_{i \in \mathbb{T}}$ with $p = \frac{1}{2}$, see (1.1). More generally, (2.30) holds for any polynomial chaos $f(\omega) \in L^2$ when $X = \omega_i - \mathbb{E}[\omega_i]$ satisfies (2.27) (see Example 2.16).

Note that (2.30) recovers (2.6), since $\vartheta_\varepsilon = \varepsilon/(2 - \varepsilon)$. Remarkably, *this exponent is optimal*, i.e. there are functions $f(\omega)$ for which $\text{Cov}[f(\omega^\varepsilon), f(\omega)]$ matches the RHS of (2.30) as $\mathcal{W}[f] \downarrow 0$ (up to logarithmic corrections). We show this by building an example which generalises the “Tribes” function by M. Ben-Or and N. Linial [BOL87].

We work in the symmetric binary case (1.1) with $\mathbb{P}(\omega_i = 1) = \mathbb{P}(\omega_i = -1) = 1/2$ for $i \in \mathbb{N}$. Let us fix a sequence $(a_t)_{t \in \mathbb{N}}$ with $a_t \in \mathbb{N}$ such that

$$a_t = t^{\frac{1}{2} + \gamma} + O(1) \quad \text{for some } \gamma \in (0, \frac{1}{2}). \quad (2.31)$$

We also require $t - a_t \in 2\mathbb{N}$ (for periodicity issues) so that $\mathbb{P}(\sum_{i=1}^t \omega_i = a_t) > 0$.

Given $t, m \in \mathbb{N}$, we define a function $f_{t,m}(\omega) = f_{t,m}(\omega_1, \dots, \omega_n)$ for $n = t \cdot m$ as follows.

- We divide the index set $\{1, \dots, n\} = \bigcup_{\ell=1}^m B_\ell$ in m intervals (or “tribes”) of length t :

$$B_\ell := \{(\ell - 1)t + 1, \dots, \ell t\}, \quad \ell = 1, \dots, m. \quad (2.32)$$

- To each interval we associate the random variable

$$Y_\ell(\omega) := \mathbf{1}_{\{\sum_{i \in B_\ell} \omega_i = a_t\}}. \quad (2.33)$$

Note that $(Y_\ell(\omega))_{\ell=1, \dots, m}$ are i.i.d. Bernoulli random variables $\text{Be}(p_t)$ with

$$p_t := \mathbb{P} \left(\sum_{i=1}^t \omega_i = a_t \right) \underset{t \rightarrow \infty}{\sim} 2 \frac{e^{-\frac{t^2 \gamma}{2}}}{\sqrt{2\pi t}}, \quad (2.34)$$

by Gaussian estimates for the simple random walk (the factor 2 is due to periodicity).

- We define the *Modified Tribes* function $f_{t,m}(\omega)$ to be the Boolean function equal to 1 if $Y_\ell(\omega) = 1$ for at least one $\ell = 1, \dots, m$, and 0 otherwise:

$$f_{t,m}(\omega) := \mathbb{1}_{\{\exists \ell=1, \dots, m : Y_\ell(\omega)=1\}} = 1 - \mathbb{1}_{\{Y_\ell(\omega)=0, \forall \ell=1, \dots, m\}}. \quad (2.35)$$

Since $\mathbb{P}(f_{t,m} = 1) = 1 - (1 - p_t)^m$, for $m = m_t := \lfloor 1/p_t \rfloor$ we have the convergence in distribution

$$f_t(\omega) := f_{t,m_t}(\omega) \xrightarrow[t \rightarrow \infty]{d} \text{Be}(1 - e^{-1}).$$

To show the optimality of the exponent $\varepsilon/(2 - \varepsilon)$ in (2.30), we prove a lower bound which matches the RHS of (2.30) up to logarithmic corrections. The proof is given in Section 6.

Theorem 2.18 (Modified Tribes). *For $\gamma \in (0, \frac{1}{2})$, the Modified Tribes function $f_t(\omega)$ satisfies the following: for any $\varepsilon \in (0, 1)$ there is $c_\varepsilon > 0$ such that, as $t \rightarrow \infty$,*

$$\frac{\text{Cov}[f_t(\omega^\varepsilon), f_t(\omega)]}{\text{Var}[f_t]} \sim c_\varepsilon \left(\frac{\mathcal{W}[f_t]}{\text{Var}[f_t]} \right)^{\frac{\varepsilon}{2-\varepsilon}} \left(\log \frac{\text{Var}[f_t]}{\mathcal{W}[f_t]} \right)^{-\frac{1}{2\gamma(2-\varepsilon)}}. \quad (2.36)$$

In particular, the exponent $\varepsilon/(2 - \varepsilon)$ in (2.30) cannot be improved.

Remark 2.19. *Replacing “ $= a_t$ ” by “ $\geq a_t$ ” in the definition (2.33) of Y_ℓ , we would obtain a monotone Boolean function $f_t(\omega)$ which, we believe, still satisfies (2.36) (with a different power of the logarithm). We keep the current definition to make computations simpler.*

2.7. Concluding remarks. We presented extensions of the BKS criterion for noise sensitivity beyond the classical case of binary random variables ω_i . Our setting, formulated in Assumption 2.2, entails a form of hypercontractivity, see Lemma 2.12.

The only result which is formulated under more restrictive conditions is Theorem 2.15, which ensures enhanced noise sensitivity. This is due to the fact that Assumption 2.2 is not obviously stable under composition with smooth functions. It would be interesting to investigate this issue, with the goal of extending the applicability of Theorem 2.15.

It would also be interesting to understand to which extent our key Assumption 2.2 could be relaxed. We point out, however, that *some form of hypercontractivity must be required* for the general BKS criterion (2.17) to hold, as the following example shows.

Example 2.20 (Lack of hypercontractivity). Let $\omega = (\omega_i)_{i \in \mathbb{N}}$ be i.i.d. random variables uniformly distributed in $(0, 1)$. For $N \in \mathbb{N}$ we define

$$f_N(\omega) := \sum_{i=1}^N Y_{i,N}(\omega) \quad \text{with} \quad Y_{i,N}(\omega) := \mathbb{1}_{\{\omega_i > 1 - \frac{1}{N}\}}.$$

Let us show that, even though $\mathcal{W}[f_N] \rightarrow 0$, the family $(f_N)_{N \in \mathbb{N}}$ is *not* noise sensitive.

Plainly $\text{Var}[f_N] = N \frac{1}{N} (1 - \frac{1}{N}) \rightarrow 1$ as $N \rightarrow \infty$. Since $f_N = f_N^{(0)} + f_N^{(1)}$ has only chaos components of degree 0 and 1 (because $\delta_i \delta_j f_N = 0$ for $i \neq j$, see Proposition 4.2), we have

$$\text{Cov}[f_N(\omega^\varepsilon), f_N(\omega)] = (1 - \varepsilon) \|f_N^{(1)}\|_2^2 = (1 - \varepsilon) \text{Var}[f_N] \xrightarrow[N \rightarrow \infty]{} 1 - \varepsilon \neq 0,$$

hence $(f_N)_{N \in \mathbb{N}}$ is not noise sensitive. However, since $\delta_i f_N = Y_{i,N} - \frac{1}{N}$, we have

$$\text{Inf}_i^{(1)}[f_N] = \mathbb{E}[|\delta_i f_N|] = \frac{2}{N}(1 - \frac{1}{N}) \implies \mathcal{W}[f_N] = \sum_{i=1}^N \text{Inf}_i^{(1)}[f_N]^2 \leq \frac{4}{N} \xrightarrow[N \rightarrow \infty]{} 0,$$

which shows that the general BKS criterion (2.17) does not apply.

This is not in contrast with our Theorem 2.10 because the functions f_N fail to satisfy Assumption 2.2 with the same $q > 2$ and $M_q < \infty$: indeed, we must have

$$M_q \geq \frac{\|Y_{i,N} - \mathbb{E}[Y_{i,N}]\|_q}{\|Y_{i,N} - \mathbb{E}[Y_{i,N}]\|_2} \sim N^{\frac{1}{2} - \frac{1}{q}} \xrightarrow[N \rightarrow \infty]{} \infty.$$

We can also consider the monotone Boolean functions $g_N(\omega) := \mathbb{1}_{\{f_N(\omega) \geq 1\}}$. One can show that these functions are also not noise sensitive, even though $\mathcal{W}[g_N] \rightarrow 0$.

3. Application to 2D directed polymers and SHF

We present an application of our noise sensitivity results to the so-called *directed polymer in random environment*. This is a much studied model in statistical mechanics and probability theory, both as a prototype of *disordered system* and because of its link with the (multiplicative) *Stochastic Heat Equation* and *Kardar-Parisi-Zhang (KPZ) equation* and universality class. We refer to [Com17, Zyg24, CSZ24] for more details and references.

We focus here on the case of space dimension 2. In a critical regime of vanishing disorder strength, directed polymer partition functions, averaged over the starting point on the diffusive scale, converge to a universal limit, named in [CSZ23] the *Critical 2D Stochastic Heat Flow (SHF)* (see Theorem 3.1 below). An axiomatic characterisation of the SHF was recently provided by L.-C. Tsai [Tsa24], who also established continuity in time as a measure valued process. It was shown in the same paper that the SHF also arises as the limit of solutions of the 2D Stochastic Heat Equation with space-regularised white noise, as the regularisation is removed and the noise intensity is suitably rescaled.

We prove here the following novel results.

- In Theorem 3.2, we establish *enhanced noise sensitivity* for the directed polymer partition functions converging to the SHF.
- In Theorem 3.6 we deduce the *independence of the SHF from the white noise* arising from the scaling limit of the environment.

In the setting of the Stochastic Heat Equation, a similar result was obtained simultaneously and independently in [GT25], as a corollary of their main result that the SHF is a black noise (see also [HP24] for a related result on the directed landscape).

Many properties related to the SHF have been investigated, including moments [BC95, CSZ20, GQT21, C24, LZ24], comparison to Gaussian multiplicative chaos [CSZ23b, CM24], flow property [CM24], singularity and regularity as a random measure [CSZ25]. See also [N25, C25] for recent progress on a martingale description of the SHF. We refer to the recent lecture notes [CSZ24] for an extended discussion and further references.

3.1. Setting. Let $\mathbb{T} = \mathbb{N} \times \mathbb{Z}^d$ and $\omega = (\omega(n, x))_{(n, x) \in \mathbb{T}}$ be a family of i.i.d. random variables under the law \mathbb{P} , called *environment* or *disorder*, with zero mean, unit variance and finite exponential moments:

$$\mathbb{E}[\omega(n, x)] = 0, \quad \mathbb{E}[\omega(n, x)^2] = 1, \quad \lambda(\beta) := \log \mathbb{E}[e^{\beta \omega(n, x)}] < \infty \quad \forall \beta > 0.$$

Let $(S_n)_{n \in \mathbb{N}}$ be the symmetric simple random walk on \mathbb{Z}^d , with law and expectation P, E .

Given a disorder realisation ω , a system size $N \in \mathbb{N}$, and inverse temperature (or disorder strength) $\beta > 0$, the *directed polymer* is the random probability law for S given by

$$dP_N^{\omega, \beta}(S) := \frac{e^{\sum_{n=1}^N (\beta \omega(n, S_n) - \lambda(\beta))}}{Z_N^{\omega, \beta}} dP(S),$$

where $Z_N^{\omega, \beta}$ is the normalising constant called *partition function*.

For every dimension d there exists a critical value $\beta_c = \beta_c(d) \geq 0$ such that for $\beta \leq \beta_c$ the behaviour of the polymer path is diffusive, while for $\beta > \beta_c$ a localised behavior emerges. The critical value is known to be $\beta_c > 0$ for $d \geq 3$, while $\beta_c = 0$ for $d = 1, 2$. Remarkable progress on the understanding of the the critical point for $d \geq 3$ was only obtained recently, see [J23, HL24, L25] and references therein.

In the recent years, there has been much focus on studying the scaling properties of the model in a finer window around the critical point $\beta_c = 0$ when the dimension equals one or two. To this end, one can rescale the disorder strength as the volume grows by letting $\beta = \beta_N \rightarrow 0$ appropriately, in order to obtain non-degenerate limits for Z_{N, β_N}^ω . The case of spatial dimension one was first treated by Alberts, Khanin and Quastel [AKQ14] who showed that the right scaling is $\beta_N \sim \hat{\beta} N^{-1/4}$.

In dimension $d = 2$ the right scaling is $\beta_N \sim \hat{\beta}/\sqrt{R_N}$, where $R_N = \sum_{n=1}^N P(S_n = S'_n) \sim \frac{1}{\pi} \log N$ (we denote by S' an independent copy of S). It was first shown in [CSZ17] that the model exhibits a phase transition on this finer scale with critical point $\hat{\beta}_c = 1$.

The behaviour at the critical point $\hat{\beta} = 1$ is more subtle: the partition function Z_N starting from a point converges to zero in distribution, while its expectation is one and its second and higher moments diverge. This intermittent behavior suggests to average the partition function in space in order to obtain a meaningful limit.

Let us first state precisely the scaling of β_N around $\hat{\beta}_c = 1$, known as *critical window*:

$$\sigma_N^2 := e^{\lambda(2\beta_N) - 2\lambda(\beta_N)} - 1 = \frac{1}{R_N} \left(1 + \frac{\vartheta + o(1)}{\log N} \right), \quad \vartheta \in \mathbb{R}. \quad (3.1)$$

Given two continuous and compactly supported test functions $g, h \in C_c(\mathbb{R}^2)$ and two times $0 \leq s < t < \infty$, consider the *averaged* partition function

$$Z_{N;s,t}^{\omega, \beta}(g, h) := \frac{1}{N} \sum_{x_0, y_0 \in \mathbb{Z}^2} g\left(\frac{x_0}{\sqrt{N}}\right) E\left[e^{H_{(Ns, Nt)}^{\omega, \beta}(S, \omega)} \mathbb{1}_{\{S_{Nt} = y_0\}} \mid S_{Ns} = x_0\right] h\left(\frac{y_0}{\sqrt{N}}\right), \quad (3.2)$$

where

$$H_{(0,N]}^{\omega, \beta}(S, \omega) = \sum_{n=1}^N \{\beta \omega(n, S_n) - \lambda(\beta)\} = \sum_{(n,x) \in \mathbb{T}} \{\beta \omega(n, x) - \lambda(\beta)\} \mathbb{1}_{S_n=x}.$$

The following is the main result of [CSZ23].

Theorem 3.1 (Directed Polymer and Stochastic Heat Flow [CSZ23]). *Fix β_N in the critical window (3.1) for some $\vartheta \in \mathbb{R}$. For any $g, h \in C_c(\mathbb{R}^2)$ and $0 \leq s < t < \infty$, the partition functions in (3.2) with $\beta = \beta_N$ converge in distribution to a non trivial limit:*

$$Z_{N;s,t}^{\omega, \beta_N}(g, h) \xrightarrow[N \rightarrow \infty]{d} \mathcal{Z}_{s,t}^\vartheta(g, h) := \iint_{\mathbb{R}^2 \times \mathbb{R}^2} g(x) h(y) \mathcal{Z}_{s,t}^\vartheta(dx, dy), \quad (3.3)$$

where $\mathcal{Z}^\vartheta = (\mathcal{Z}_{s,t}^\vartheta(dx, dy))_{0 \leq s < t < \infty}$ is a stochastic process of random measures on $\mathbb{R}^2 \times \mathbb{R}^2$, called the critical 2D Stochastic Heat Flow. The convergence in (3.3) holds jointly over s, t, g, h in the sense of finite-dimensional distributions (f.d.d.).

3.2. Enhanced noise sensitivity for directed polymers. In our first main result for the directed polymer model, we establish enhanced noise sensitivity for the sequence of rescaled partition functions appearing in (3.3).

Theorem 3.2 (Enhanced noise sensitivity for 2D directed polymers). Consider β_N in the critical window (3.1) with $\vartheta \in \mathbb{R}$. Given $g, h \in C_c(\mathbb{R}^2)$ and $0 \leq s < t < \infty$, the partition function $Z_{N;s,t}^{\omega, \beta_N}(g, h)$ in (3.3) is, for every $N \in \mathbb{N}$, a function of the environment:

$$f_N(\omega) := Z_{N;s,t}^{\omega, \beta_N}(g, h). \quad (3.4)$$

This sequence of functions is noise sensitive, namely

$$\forall \varepsilon > 0: \quad \text{Cov}[f_N(\omega^\varepsilon), f_N(\omega)] = \text{Cov}\left[Z_{N;s,t}^{\omega^\varepsilon, \beta_N}(g, h), Z_{N;s,t}^{\omega, \beta_N}(g, h)\right] \xrightarrow[N \rightarrow \infty]{} 0. \quad (3.5)$$

If we further assume that the disorder variables $\omega(n, z)$ take finitely many values, enhanced noise sensitivity holds: for any $k \in \mathbb{N}$, given $g_i, h_i \in C_c(\mathbb{R}^2)$ and $0 \leq s_i < t_i < \infty$ for $i = 1, \dots, k$, defining the vector-valued function $f_N(\omega) \in \mathbb{R}^k$ by

$$f_N(\omega) = (f_N^{(1)}(\omega), \dots, f_N^{(k)}(\omega)) := \left(Z_{N;s_i,t_i}^{\omega, \beta_N}(g_i, h_i)\right)_{i=1,\dots,k},$$

the following asymptotic independence property holds:

$$\forall \varepsilon > 0, \forall \varphi, \psi \in C_b^\infty(\mathbb{R}^k \rightarrow \mathbb{R}): \quad \text{Cov}[\varphi(f_N(\omega^\varepsilon)), \psi(f_N(\omega))] \xrightarrow[N \rightarrow \infty]{} 0. \quad (3.6)$$

Remark 3.3 (Polynomial chaos). The partition function $f_N(\omega)$ in (3.4) satisfies our Assumption 2.2 because, for any $(n, z) \in \mathbb{N} \times \mathbb{Z}^2$, it depends on $\omega(n, z)$ as a linear function of the “tiled” random variables $\zeta(n, z)$ defined by

$$\zeta(n, z) := e^{\beta_N \omega(n, z) - \lambda(\beta_N)} - 1,$$

see (3.13) below, hence (2.8) holds with $\mathcal{V}_{(n,z)} = \{a\zeta(n, z) + b: a, b \in \mathbb{R}\}$. Equivalently, we can view $f_N(\omega)$ as a polynomial chaos in the variables $\zeta(n, z)$, see Example 2.4.

We prove Theorem 3.2 exploiting our general noise sensitivity results, more precisely we deduce (3.5) from Theorem 2.10 and (3.6) from Theorem 2.15. To this purpose, it suffices to show that the function $f_N(\omega)$ defined in (3.4) satisfies the general BKS criterion

$$\mathcal{W}[f_N] = \sum_{(n,z) \in \mathbb{N} \times \mathbb{Z}^2} \text{Inf}_{(n,z)}^{(1)}[f_N]^2 \xrightarrow[N \rightarrow \infty]{} 0, \quad (3.7)$$

for any fixed $g, h \in C_c(\mathbb{R}^2)$ and $0 \leq s < t < \infty$ (we recall that the influence $\text{Inf}_k^{(1)}[f]$ was defined in (2.13)). This follows from the following computation, proved in Subsection 3.4. For ease of notation, we focus on the simple case when $s = 0, t = 1$.

Proposition 3.4 (Influences for directed polymer). For β_N in (3.1), consider the partition function $f_N(\omega) := Z_{N;0,1}^{\omega, \beta_N}(g, h)$ in (3.2) with $s = 0, t = 1$ and $g, h \in C_c(\mathbb{R}^2)$.

For any $(n, z) \in \mathbb{N} \times \mathbb{Z}^2$ we have

$$\text{Inf}_{(n,z)}^{(1)}[f_N] \leq \mathbb{1}_{\{1, \dots, N\}}(n) \frac{\sigma_N}{N} \sum_{x_0, y_0 \in \mathbb{Z}^2} |g(\frac{x_0}{\sqrt{N}})| q_n(z - x_0) q_{N-n}(y_0 - z) |h(\frac{y_0}{\sqrt{N}})| \quad (3.8)$$

with σ_N from (3.1), where $q_n(z - x) = \mathbb{P}(S_n = z \mid S_0 = x)$ is the random walk kernel.

Proof of Theorem 3.2. It suffices to show that (3.7) holds. We will prove that

$$\mathcal{W}[f_N] = O\left(\frac{1}{\log N}\right). \quad (3.9)$$

We recall that $g, h \in C_c(\mathbb{R}^2)$. For simplicity, let g be supported in the unit ball $\{|\cdot| \leq 1\}$. We can bound $|h(\cdot)| \leq \|h\|_\infty$ in (3.8), after which the sum over $y_0 \in \mathbb{Z}^2$ gives 1. We can also restrict the sum to $|x_0| \leq \sqrt{N}$ and bound $|g(\cdot)| \leq \|g\|_\infty$. We then obtain

$$\begin{aligned} \mathcal{W}[f_N] &= \sum_{(n,z) \in \mathbb{N} \times \mathbb{Z}^2} \text{Inf}_{(n,z)}^{(1)}[f_N]^2 \\ &\leq \|g\|_\infty^2 \|h\|_\infty^2 \frac{\sigma_N^2}{N^2} \sum_{n=1}^N \sum_{z \in \mathbb{Z}^2} \sum_{\substack{x_0, x'_0 \in \mathbb{Z}^2 \\ |x_0|, |x'_0| \leq \sqrt{N}}} q_n(z - x_0) q_n(z - x'_0) \\ &= \|g\|_\infty^2 \|h\|_\infty^2 \frac{\sigma_N^2}{N^2} \sum_{n=1}^N \sum_{\substack{x_0, x'_0 \in \mathbb{Z}^2 \\ |x_0|, |x'_0| \leq \sqrt{N}}} q_{2n}(x_0 - x'_0) = O(\sigma_N^2), \end{aligned}$$

where the last equality holds because $\sum_{x_0 \in \mathbb{Z}^2} q_{2n}(x_0 - x'_0) = 1$ and the sums over x'_0 and n give $O(N^2)$. Since $\sigma_N^2 = O(1/R_N) = O(1/\log N)$, see (3.1), we have proved (3.9). \square

Remark 3.5. In the recent work by Y. Gu and T. Komorowski [GK25], a proof of classical (non enhanced) noise sensitivity for the SHE and the Schrödinger equation is given, either in one dimension with white noise, or in higher dimensions with space-colored noise.

3.3. Asymptotic independence of SHF and white noise. By the central limit theorem, the disorder field $\omega = (\omega(n, z))$, suitably rescaled, converges in distribution to (space-time) white noise $\xi = \xi(t, x)$ on $[0, \infty) \times \mathbb{R}^2$. The latter is defined as the centred Gaussian generalised field with covariance $\mathbb{C}\text{ov}[\xi(s, y), \xi(t, x)] = \delta(t - s) \delta(x - y)$.

For a precise statement, let us consider test functions $\varrho \in C_c([0, \infty) \times \mathbb{R}^2)$. Evaluating the white noise $\xi(\varrho)$ on ϱ , which formally corresponds to $\int_{[0, \infty) \times \mathbb{R}^2} \xi(t, x) \varrho(t, x) dt dx$, one gets a genuine centred Gaussian process $(\xi(\varrho))_{\varrho \in C_c}$ with $\mathbb{C}\text{ov}[\xi(\varrho), \xi(\tilde{\varrho})] = \langle \varrho, \tilde{\varrho} \rangle_{L^2}$.

For $N \in \mathbb{N}$, define an approximation ξ_N of the white noise by the rescaled disorder ω :

$$\xi_N(\varrho) := \frac{1}{N} \sum_{(n,z) \in \mathbb{N} \times \mathbb{Z}^2} \varrho\left(\frac{n}{N}, \frac{z}{\sqrt{N}}\right) \omega(n, z).$$

It is easy to check that, as $N \rightarrow \infty$, one has the convergence in distribution $\xi_N(\varrho) \rightarrow \xi(\varrho)$ jointly over $\varrho \in C_c([0, \infty) \times \mathbb{R}^2)$ in the finite-dimensional distributions sense.

Summarising, we have the two convergences

$$\mathcal{Z}_N := (Z_{N;s,t}^{\omega,\beta_N}(g,h))_{s \leq t, g,h \in C_c(\mathbb{R}^2)} \xrightarrow[N \rightarrow \infty]{d} \mathcal{Z}^\vartheta = (\mathcal{Z}_{s,t}^\vartheta(f,g))_{s \leq t, g,h \in C_c(\mathbb{R}^2)}, \quad (3.10)$$

$$\xi_N = (\xi_N(\varrho))_{\varrho \in C_c([0,\infty) \times \mathbb{R}^2)} \xrightarrow[N \rightarrow \infty]{d} \xi = (\xi(\varrho))_{\varrho \in C_c([0,\infty) \times \mathbb{R}^2)}, \quad (3.11)$$

both in the finite-dimensional distributions sense (for simplicity: see Remark 3.7 below). It is then natural to ask for the *joint convergence of the pair* (\mathcal{Z}_N, ξ_N) .

For each $N \in \mathbb{N}$, we remark that \mathcal{Z}_N is a *function of ω* , hence it is also a *function of ξ_N* . Nevertheless, remarkably, *this dependence is fully lost as $N \rightarrow \infty$* : our next result shows that the SHF \mathcal{Z}^ϑ which arises as the limit of \mathcal{Z}_N is *independent* of the white noise ξ which arises as the limit of ξ_N .

Theorem 3.6 (Independence of SHF and white noise). *Assume that the disorder variables $\omega(n, z)$ take finitely many values. As $N \rightarrow \infty$, we have the joint convergence in distribution $(\mathcal{Z}_N, \xi_N) \rightarrow (\mathcal{Z}^\vartheta, \xi)$, in the f.d.d. sense, where \mathcal{Z}^ϑ and ξ are independent.*

Proof. We use the shorthand $\chi = (s, t; g, h)$ so that we may view \mathcal{Z}_N and \mathcal{Z}^ϑ as processes indexed by χ . It suffices to show the following: for any $k, \ell \in \mathbb{N}$, given any $\vec{\chi} = (\chi_1, \dots, \chi_k)$ and $\vec{\varrho} = (\varrho_1, \dots, \varrho_\ell)$, we have the asymptotic independence of the random vectors

$$\mathcal{Z}_N(\vec{\chi}) := (\mathcal{Z}_N(\chi_i))_{1 \leq i \leq k} \quad \text{and} \quad \xi_N(\vec{\varrho}) := (\xi_N(\varrho_i))_{1 \leq i \leq \ell},$$

that is for a suitable class of test functions $\varphi : \mathbb{R}^k \rightarrow \mathbb{R}$ and $\psi : \mathbb{R}^\ell \rightarrow \mathbb{R}$ we have

$$\lim_{N \rightarrow \infty} \mathbb{C}\text{ov} [\varphi(\mathcal{Z}_N(\vec{\chi})), \psi(\xi_N(\vec{\varrho}))] = 0. \quad (3.12)$$

We are going to take $\varphi \in C_b^\infty$, while for ψ we take arbitrary polynomials (they are enough to determine convergence in distribution to Gaussian random variables).

Each random variable $\xi_N(\varrho_i)$ is a linear function of ω , hence its chaos decomposition (4.3) only contains terms of degree 1. Since ψ is a polynomial, say of degree d , it follows that *the chaos decomposition of $\psi(\xi_N(\vec{\varrho}))$ only contains terms of degree $\leq d$* .

On the other hand, by the enhanced noise sensitivity property (3.6), it follows that *the variance spectrum of $\varphi(\mathcal{Z}_N(\vec{\chi}))$ drifts to infinity* for any $\varphi \in C_b^\infty$, see Remark 2.11, namely the contribution to $\text{Var}[\varphi(\mathcal{Z}_N(\vec{\chi}))]$ given by chaos of degree $\leq d$ vanishes as $N \rightarrow \infty$.

Looking back at (3.12), we can replace $\varphi(\mathcal{Z}_N(\vec{\chi}))$ by

$$\varphi(\mathcal{Z}_N(\vec{\chi}))^{(>d)} := \varphi(\mathcal{Z}_N(\vec{\chi})) - \varphi(\mathcal{Z}_N(\vec{\chi}))^{(\leq d)},$$

see (4.11), i.e. we can remove the terms of degree $\leq d$, up to a negligible error in L^2 . After this modification, the covariance vanishes because $\varphi(\mathcal{Z}_N(\vec{\chi}))^{(>d)}$ is orthogonal to $\psi(\xi_N(\vec{\varrho}))$, which only contains terms of degree $\leq d$. The proof is complete. \square

Remark 3.7 (Stronger topologies). *Both convergences (3.10) and (3.11) are known to hold beyond f.d.d., under stronger topologies (e.g. in the space of continuous measure-valued processes for $\mathcal{Z}_N \rightarrow \mathcal{Z}^\vartheta$, see [Tsa24], and in a negative Hölder space for $\xi_N \rightarrow \xi$).*

Since tightness for the pair (\mathcal{Z}_N, ξ_N) follows by tightness for the marginals — and since f.d.d.'s determine the law — Theorem 3.6 yields the joint convergence $(\mathcal{Z}_N, \xi_N) \rightarrow (\mathcal{Z}^\vartheta, \xi)$ under the corresponding product topology, with \mathcal{Z}^ϑ and ξ independent.

3.4. Proof of Theorem 3.4. Let us decompose the expectation appearing in (3.2) on the event $\{S_n = z\}$ and on its complement $\{S_n \neq z\}$. Writing E_{x_0} for $E[\cdot | S_0 = x_0]$, using the Markov property of the random walk as well as the additivity of the Hamiltonian, we obtain

$$\begin{aligned} E_{x_0} \left[e^{H_{(0,N]}^{\omega, \beta_N}(S, \omega)} \mathbb{1}_{\{S_N = y_0\}} \right] &= a_1 e^{\beta_N \omega(n, z) - \lambda(\beta_N)} a_2 + b \\ \text{with } a_1 &:= E_{x_0} \left[e^{H_{(0,n-1]}^{\omega, \beta_N}(S, \omega)} \mathbb{1}_{\{S_n = z\}} \right], \\ a_2 &:= E \left[e^{H_{(n+1,N]}^{\omega, \beta_N}(S, \omega)} \mathbb{1}_{\{S_N = y_0\}} \mid S_n = z \right], \\ b &:= E_{x_0} \left[e^{H_{(0,N]}^{\omega, \beta_N}(S, \omega)} \mathbb{1}_{\{S_n \neq z\}} \mathbb{1}_{\{S_N = y_0\}} \right]. \end{aligned} \tag{3.13}$$

Note that the terms a_1, a_2, b do not depend on $\omega(n, z)$. In particular, the term b vanishes when we apply the operator $\delta_{(n,z)} f = f - \mathbb{E}_{(n,z)} f$. It follows that

$$\delta_{(n,z)} E_{x_0} \left[e^{H_{(0,N]}^{\omega, \beta_N}(S, \omega)} \mathbb{1}_{\{S_N = y_0\}} \right] = a_1 (e^{\beta_N \omega(n, z) - \lambda(\beta_N)} - 1) a_2.$$

We next observe that, by (3.1),

$$\mathbb{E}[|e^{\beta_N \omega(n, z) - \lambda(\beta_N)} - 1|] \leq \sqrt{\mathbb{E}[(e^{\beta_N \omega(n, z) - \lambda(\beta_N)} - 1)^2]} = \sqrt{e^{\lambda(2\beta_N) - 2\lambda(\beta_N)} - 1} = \sigma_N,$$

while by Fubini, since $\mathbb{E}[e^{H_{(a,b]}^{\omega, \beta}}] = 1$, we have

$$\mathbb{E}[a_1] = E_{x_0} [\mathbb{1}_{\{S_n = z\}}] = q_n(z - x_0), \quad \mathbb{E}[a_2] = E[\mathbb{1}_{\{S_N = y_0\}} \mid S_n = z] = q_{N-n}(y_0 - z).$$

Plugging these computations into (3.2), since $\text{Inf}_{(n,z)}^{(1)}[f_N] = \mathbb{E}[|\delta_{(n,z)} f_N|]$, we obtain (3.8).

4. General setting

We give in this section the definition of the objects of our interest.

4.1. Random variables. We recall that $\omega = (\omega_i)_{i \in \mathbb{T}}$ denote independent random variables, defined on a probability space $(\Omega, \mathcal{A}, \mathbb{P})$ and with values in measurable spaces (E_i, \mathcal{E}_i) , with laws μ_i , see (2.7). Whenever we write $f(\omega)$ we imply that $f : \times_{i \in \mathbb{T}} E_i \rightarrow \mathbb{R}$ is measurable with respect to $\otimes_{i \in \mathbb{T}} \mathcal{E}_i$, so that $f(\omega)$ is a random variable defined on Ω .

It is convenient to work on a general probability space —rather than on the canonical space $(\Omega, \mathcal{A}, \mathbb{P}) = (\times_{i \in \mathbb{T}} E_i, \otimes_{i \in \mathbb{T}} \mathcal{E}_i, \otimes_{i \in \mathbb{T}} \mu_i)$ — to allow for extra randomness.

Definition 4.1 (ε -randomisation). For $\varepsilon \in [0, 1]$, we denote by $\omega^\varepsilon = (\omega_i^\varepsilon)_{i \in \mathbb{T}}$ the modified family where $\omega_i^\varepsilon = \omega_i$ with probability $1 - \varepsilon$, while ω_i^ε is independently resampled with probability ε . More explicitly, we define

$$\omega_i^\varepsilon := \omega_i \mathbb{1}_{\{U_i > \varepsilon\}} + \tilde{\omega}_i \mathbb{1}_{\{U_i \leq \varepsilon\}}, \tag{4.1}$$

where $\tilde{\omega} = (\tilde{\omega}_i)_{i \in \mathbb{T}}$ is an independent copy of $\omega = (\omega_i)_{i \in \mathbb{T}}$ and $U = (U_i)_{i \in \mathbb{T}}$ are independent random variables (also independent of $\omega, \tilde{\omega}$) uniformly distributed in $(0, 1)$.

We often omit ω and write $\mathbb{E}[f]$, $\text{Var}[f]$, etc. We denote by $\langle \cdot, \cdot \rangle$ the L^2 scalar product:

$$\langle f, g \rangle := \mathbb{E}[f(\omega) g(\omega)].$$

We denote by \mathcal{F}_I the σ -algebra generated by the random variables ω_i for $i \in I \subseteq \mathbb{T}$:

$$\mathcal{F}_I := \sigma(\omega_i : i \in I). \tag{4.2}$$

We denote by $L^2(\mathcal{F}_I)$ the subspace of L^2 random variables which are \mathcal{F}_I -measurable, i.e. functions of $(\omega_i)_{i \in I}$. We recall that $\mathbb{E}_i[\cdot] = \mathbb{E}[\cdot | \mathcal{F}_{\mathbb{T} \setminus \{i\}}]$, see (2.12).

4.2. General chaos decomposition. Every function $f(\omega) \in L^2$ admits an orthogonal *chaos decomposition* similar to the definition of a polynomial chaos, see (2.11), where monomials $\hat{f}(i_1, \dots, i_d) \omega_{i_1} \cdots \omega_{i_d}$ are replaced by suitable orthogonal functions $f_I(\omega)$. This is also called *Hoeffding or Efron-Stein decomposition*.

Proposition 4.2 (Chaos decomposition). *If $\omega = (\omega_i)_{i \in \mathbb{T}}$ are independent random variables, any function $f(\omega) \in L^2$ can be written as the L^2 convergent series*

$$f(\omega) = f^{(0)} + \sum_{d=1}^{\infty} f^{(d)}(\omega) \quad \text{with} \quad \begin{cases} f^{(0)} = f_{\emptyset} = \mathbb{E}[f], \\ f^{(d)}(\omega) = \sum_{I \subseteq \mathbb{T}: |I|=d} f_I(\omega), \end{cases} \quad (4.3)$$

for a unique choice of functions $f_I(\omega) \in L^2$, labelled by finite subsets $I \subseteq \mathbb{T}$, such that

$$f_I \in L^2(\mathcal{F}_I) \quad \text{and} \quad \mathbb{E}_k[f_I] = 0 \quad \forall k \in I. \quad (4.4)$$

Explicitly, recalling the operator $\delta_i g := g - \mathbb{E}_i[g]$ from (2.12), we can write

$$\text{for } I = \{i_1, \dots, i_d\}: \quad f_I = \delta_{i_1} \cdots \delta_{i_d} \tilde{f}_I \quad \text{with} \quad \tilde{f}_I := \mathbb{E}[f | \mathcal{F}_I]. \quad (4.5)$$

We refer to [O'D14, Section 8.3] for a discussion (where f_I, \tilde{f}_I are denoted by $f^{=I}, f^{\leq I}$). We provide a compact proof of Proposition 4.2 in Appendix B. One can also give a hands-on construction of the functions f_I 's by fixing a basis of L^2 , see Lemma C.5 and Remark C.7.

Remark 4.3. *The first property in (4.4) means that f_I is a function of $\omega_I = (\omega_i)_{i \in I}$. The second property in (4.4) means that, if f_I is non zero, then “ f_I depends on every ω_k for $k \in I$ ” (if f_I does not depend on some ω_k , i.e. if it is constant w.r.t. ω_k , then $f_I = \mathbb{E}_k[f_I] = 0$).*

The properties (4.4) imply that, for all $k \in \mathbb{T}$ and $I \subseteq \mathbb{T}$,

$$\delta_k f_I := f_I - \mathbb{E}_k[f_I] = \begin{cases} f_I & \text{if } k \in I, \\ 0 & \text{if } k \notin I, \end{cases} \quad \mathbb{E}[f_I | \mathcal{F}_J] = \begin{cases} f_I & \text{if } I \subseteq J, \\ 0 & \text{if } I \not\subseteq J. \end{cases} \quad (4.6)$$

Then it follows by the chaos decomposition (4.3) that

$$\delta_k f = \sum_{I \supseteq \{k\}} f_I, \quad \mathbb{E}[f | \mathcal{F}_J] = \sum_{I \subseteq J} f_I. \quad (4.7)$$

The second property in (4.6) implies that the functions f_I 's are orthogonal:

$$\langle f_I, f_J \rangle = 0 \quad \text{for any } I \neq J, \quad (4.8)$$

therefore by (4.3) we obtain

$$\text{Var}[f] = \sum_{d=1}^{\infty} \|f^{(d)}\|_2^2 = \sum_{d=1}^{\infty} \sum_{I \subseteq \mathbb{T}: |I|=d} \|f_I\|_2^2. \quad (4.9)$$

Similarly, for any functions $f(\omega), g(\omega) \in L^2$,

$$\text{Cov}[f, g] = \sum_{d=1}^{\infty} \langle f^{(d)}, g^{(d)} \rangle = \sum_{d=1}^{\infty} \sum_{I \subseteq \mathbb{T}: |I|=d} \langle f_I, g_I \rangle. \quad (4.10)$$

Given $f(\omega) \in L^2$ with chaos decomposition (4.3), we define its projection $f^{(\leq d)}(\omega)$ on chaos of order up to d by

$$f^{(\leq d)}(\omega) := \sum_{\ell=0}^d f^{(\ell)}(\omega) = \sum_{I \subseteq \mathbb{T}: |I| \leq d} f_I(\omega). \quad (4.11)$$

(An important result by Bourgain [Bou79, Proposition 6], see also [O'D14, Theorem 10.39], ensures that such projections are bounded in L^q for $1 < q < \infty$.)

4.3. Noise operator. Given $\eta \in [0, 1]$, we define a *noise operator* $T^\eta : L^2 \rightarrow L^2$ acting on functions $f(\omega) \in L^2$ with chaos decomposition (4.3)-(4.4) as follows:

$$T^\eta f(\omega) := \mathbb{E}[f] + \sum_{d=1}^{\infty} \eta^d f^{(d)}(\omega) = \mathbb{E}[f] + \sum_{d=1}^{\infty} \eta^d \sum_{I \subseteq \mathbb{T}: |I|=d} f_I(\omega). \quad (4.12)$$

Recalling the definition (4.1) of $\omega^\varepsilon = (\omega_i^\varepsilon)_{i \in \mathbb{T}}$, we introduce the conditional expectation

$$\mathbb{E}[\cdot | \omega] := \mathbb{E}[\cdot | \sigma(\omega_i)_{i \in \mathbb{T}}],$$

i.e. we integrate out the U_i 's and $\tilde{\omega}_i$'s in (4.1). In the next result, we compute the covariance between $f(\omega^\varepsilon)$ and $f(\omega)$ explicitly in terms of the operator T^η .

Lemma 4.4. *For any $\varepsilon \in (0, 1)$ we have*

$$\mathbb{E}[f(\omega^\varepsilon) | \omega] = T^{1-\varepsilon} f(\omega), \quad (4.13)$$

hence, recalling the chaos decomposition (4.3)-(4.4), for any $f(\omega), g(\omega) \in L^2$ we can write

$$\begin{aligned} \text{Cov}[f(\omega^\varepsilon), g(\omega)] &= \sum_{d=1}^{\infty} (1-\varepsilon)^d \langle f^{(d)}, g^{(d)} \rangle \\ &= \sum_{d=1}^{\infty} \varepsilon (1-\varepsilon)^d \text{Cov}[f^{(\leq d)}, g^{(\leq d)}], \end{aligned} \quad (4.14)$$

where we note that $\text{Cov}[f^{(\leq d)}, g^{(\leq d)}] = \sum_{\ell=1}^d \langle f^{(\ell)}, g^{(\ell)} \rangle$ (see (4.10) and (4.11)). Moreover,

$$\text{Cov}[f(\omega^\varepsilon), g(\omega)] \leq \sqrt{\text{Cov}[f(\omega^\varepsilon), f(\omega)] \cdot \text{Cov}[g(\omega^\varepsilon), g(\omega)]}. \quad (4.15)$$

Proof. The first equality in (4.14) follows by (4.13) and (4.3) since

$$\mathbb{E}[f(\omega^\varepsilon) g(\omega)] = \mathbb{E}[\mathbb{E}[f(\omega^\varepsilon) | \omega] g(\omega)] = \langle T^{1-\varepsilon} f, g \rangle,$$

while the second equality in (4.14) holds by summation by parts. The inequality (4.15) follows by (4.14) applying Cauchy-Schwarz.

It remains to prove (4.13), for which it suffices to show that

$$\mathbb{E}[f_I(\omega^\varepsilon) | \omega] = (1-\varepsilon)^{|I|} f_I(\omega) \quad \forall I \subseteq \mathbb{T}. \quad (4.16)$$

For any fixed $k \in I$, writing $\omega^\varepsilon = (\omega_j^\varepsilon)_{j \neq k} \cup \{\omega_k^\varepsilon\}$, we note that the event $\{U_k \leq \varepsilon\}$ gives a null contribution to (4.16), because the variable $\omega_k^\varepsilon = \tilde{\omega}_k$ can be integrated out:

$$\begin{aligned} \mathbb{E}[f_I(\omega^\varepsilon) \mathbf{1}_{\{U_k \leq \varepsilon\}} | \omega] &= \mathbb{E}[f_I((\omega_j^\varepsilon)_{j \neq k} \cup \{\tilde{\omega}_k\}) \mathbf{1}_{\{U_k \leq \varepsilon\}} | \omega] \\ &= \mathbb{E}[\mathbb{E}_k[f_I]((\omega_j^\varepsilon)_{j \neq k}) \mathbf{1}_{\{U_k \leq \varepsilon\}} | \omega] = 0, \end{aligned}$$

by the second property in (4.4). We then restrict the LHS of (4.16) to the event $\bigcap_{k \in I} \{U_k > \varepsilon\}$, on which we have $f_I(\omega^\varepsilon) = f_I(\omega)$ by the first property in (4.4). This proves (4.16). \square

4.4. Hypercontractivity. The noise operator T^η enjoys a fundamental *hypercontractivity property* when applied to functions $f(\omega) \in L^2$ which satisfy Assumption 2.2. We recall that the hypercontractivity constant $\eta_q \in (0, 1)$ is defined in Lemma 2.12.

Theorem 4.5 (General hypercontractivity). *Let the independent random variables $(\omega_i)_{i \in \mathbb{T}}$ and the function $f(\omega) \in L^2$ satisfy Assumption 2.2 for some $q > 2$.*

Let $f'(\omega)$ be any linear combination f' of components f_I from (4.3):

$$f'(\omega) = \sum_{I \subseteq \mathbb{T}} \alpha_I f_I(\omega) \quad \text{with} \quad \|f'\|_2^2 = \sum_{I \subseteq \mathbb{T}} \alpha_I^2 \|f_I\|_2^2 < \infty. \quad (4.17)$$

Defining $\eta_q \in (0, 1)$ as in Lemma 2.12, the noise operator T^{η_q} from (4.12) satisfies

$$\|T^{\eta_q} f'\|_q \leq \|f'\|_2. \quad (4.18)$$

In particular, if $f' = f'_d$ only contains terms of degree up to d , we can bound

$$\|f'_d\|_q \leq \frac{1}{\eta_q^d} \|f'_d\|_2 \quad \text{for } f'_d = \sum_{I \subseteq \mathbb{T}: |I| \leq d} \alpha_I f_I. \quad (4.19)$$

We show in Appendix C that Theorem 4.5 is a slight extension of results from [MOO10] (which focus on finite \mathbb{T} and finite dimensional \mathcal{V}_i). To this purpose, we show in Lemma C.5 that functions $f(\omega) \in L^2$ which satisfy Assumption 2.2 (a) can be characterised as multi-linear polynomials with respect to suitable *ensembles* [MOO10, Definition 3.1].

5. Proof of noise sensitivity criteria

In this section we prove Theorem 2.17 and Theorem 2.9, from which we then deduce Theorems 2.10, 2.15. We fix a family $(\omega_i)_{i \in \mathbb{T}}$ of independent random variables as in (2.7).

5.1. Preparation. We first state a basic interpolation bound.

Remark 5.1 (Interpolation bound). *For any $g \in L^2$ we can bound*

$$\forall p \in (1, 2), \quad q \in (2, \infty) \quad \text{with} \quad \frac{1}{p} + \frac{1}{q} = 1: \quad \|g\|_p \leq \|g\|_1^{1-\frac{2}{q}} \|g\|_2^{\frac{2}{q}} \quad (5.1)$$

(just write $p = \alpha 1 + (1 - \alpha) 2$ for $\alpha = 2 - p = \frac{q-2}{q-1} \in (0, 1)$ and apply Hölder).

We recall the chaos decomposition (4.3) of a function $f(\omega) \in L^2$, which yields the expansion (4.9) for $\mathbb{V}\text{ar}[f]$, and the projection $f^{(\leq d)}$ on chaos of order $\leq d$, see (4.11).

The core of our proof is the next result which bounds the contribution of $\|f^{(\leq d)}\|_2^2$ in terms of the sum of squared L^1 influences $\mathcal{W}[f]$, see (2.14). This is close in spirit to [KK13, Lemma 6], but we use moment bounds rather than large deviations. A key tool is the hypercontractivity estimate (4.19) from Theorem 4.5.

Theorem 5.2 (Key bound). *Let $(\omega_i)_{i \in \mathbb{T}}$ be independent random variables and let $f(\omega) \in L^2$ satisfy Assumption 2.2 for some $q > 2$. Define $\eta_q \in (0, 1)$ as in Lemma 2.12.*

Then we can bound

$$\text{for } \varepsilon \geq 1 - \eta_q^2: \quad \frac{\mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)]}{\mathbb{V}\text{ar}[f]} \leq \left(\frac{\mathcal{W}[f]}{\mathbb{V}\text{ar}[f]} \right)^{1-\frac{2}{q}} \quad (5.2)$$

which yields

$$\forall d \in \mathbb{N}: \quad \frac{\|f^{(\leq d)}\|_2^2}{\text{Var}[f]} = \frac{\sum_{\ell=1}^d \|f^{(\ell)}\|_2^2}{\text{Var}[f]} \leq \frac{1}{\eta_q^{2d}} \left(\frac{\mathcal{W}[f]}{\text{Var}[f]} \right)^{1-\frac{2}{q}}. \quad (5.3)$$

Proof. Without loss of generality, we assume that the index set \mathbb{T} is totally ordered (e.g. via a correspondence with \mathbb{N}). For finite $I \subseteq \mathbb{T}$ we can thus consider $\max(I) \in \mathbb{T}$ and we note that $\max(I) = k$ if and only if $I = \{k\} \cup J$ with $J < k$ (i.e. $j < k$ for all $j \in J$).

Fix $q > 2$ from Assumption 2.2 and $\varepsilon \geq 1 - \eta_q^2$. We can write, by the first line of (4.14),

$$\text{Cov}[f(\omega^\varepsilon), f(\omega)] \leq \sum_{I \subseteq \mathbb{T}} \eta_q^{2|I|} \|f_I\|_2^2 = \sum_{k \in \mathbb{T}} \left\{ \sum_{I \subseteq \mathbb{T}: \max(I)=k} \eta_q^{2|I|} \|f_I\|_2^2 \right\}. \quad (5.4)$$

The term in bracket can be identified with $\|T^{\eta_q} g_k\|_2^2$ (recall (4.12)) where we define the function

$$g_k(\omega) := \sum_{I \subseteq \mathbb{T}: \max(I)=k} f_I(\omega), \quad (5.5)$$

hence we can rewrite (5.4) as

$$\text{Cov}[f(\omega^\varepsilon), f(\omega)] = \sum_{k \in \mathbb{T}} \|T^{\eta_q} g_k\|_2^2. \quad (5.6)$$

The function g_k is connected to the influence $\text{Inf}_k^{(1)}[f]$, see (2.13): indeed, introducing the σ -algebra $\mathcal{F}_{\leq k} := \sigma(\omega(i): i \leq k)$, we can write by (4.6)-(4.7)

$$g_k(\omega) = \mathbb{E} \left[\sum_{I \subseteq \mathbb{T}: I \ni k} f_I \mid \mathcal{F}_{\leq k} \right] = \mathbb{E}[\delta_k f \mid \mathcal{F}_{\leq k}]. \quad (5.7)$$

It follows by (5.5) that

$$\|T^{\eta_q} g_k\|_2^2 = \langle T^{\eta_q} g_k, T^{\eta_q} g_k \rangle = \langle g_k, T^{\eta_q} (T^{\eta_q} g_k) \rangle.$$

Let $p = \frac{q}{q-1}$ be the conjugate exponent of q . Applying Hölder, the interpolation bound (5.1) and the hypercontractivity bound (4.18) (note that g_k satisfies condition (4.17)), we get

$$\|T^{\eta_q} g_k\|_2^2 \leq \|g_k\|_p \|T^{\eta_q} (T^{\eta_q} g_k)\|_q \leq \|g_k\|_1^{1-\frac{2}{q}} \|g_k\|_2^{\frac{2}{q}} \|T^{\eta_q} g_k\|_2.$$

After simplifying the last factor $\|T^{\eta_q} g_k\|_2$ with one power from the LHS, we can plug this estimate into (5.6). Applying Hölder again, we arrive at

$$\text{Cov}[f(\omega^\varepsilon), f(\omega)] \leq \left(\sum_{k \in \mathbb{T}} \|g_k\|_1^2 \right)^{1-\frac{2}{q}} \left(\sum_{k \in \mathbb{T}} \|g_k\|_2^2 \right)^{\frac{2}{q}}. \quad (5.8)$$

To complete the proof of (5.2), it suffices to show that

$$\sum_{k \in \mathbb{T}} \|g_k\|_1^2 \leq \mathcal{W}[f], \quad \sum_{k \in \mathbb{T}} \|g_k\|_2^2 \leq \text{Var}[f]. \quad (5.9)$$

The first relation in (5.9) is a consequence of (5.7) and (2.13), since

$$\|g_k\|_1 = \mathbb{E}[\|\mathbb{E}[\delta_k f \mid \mathcal{F}_{\leq k}]\|] \leq \mathbb{E}[\mathbb{E}[\|\delta_k f\| \mid \mathcal{F}_{\leq k}]] = \mathbb{E}[\|\delta_k f\|].$$

The second relation in (5.9) follows directly by (5.7) and (4.9), since

$$\sum_{k \in \mathbb{T}} \|g_k\|_2^2 = \sum_{k \in \mathbb{T}} \sum_{I \subseteq \mathbb{T}: \max(I)=k} \|f_I\|_2^2 \leq \sum_{I \subseteq \mathbb{T}: |I| \geq 1} \|f_I\|_2^2 = \mathbb{V}\text{ar}[f].$$

The proof is completed. \square

5.2. Proof of Theorem 2.17. The first bound (2.28) follows directly from Theorem 5.2, because the constraint $\varepsilon \geq 1 - \eta_q^2$ in (5.2) is the same as $\eta_q^2 \geq 1 - \varepsilon$ appearing in the definition (2.29) of $q(\varepsilon)$. Then (2.28) is recovered from (5.2) with $q = q(\varepsilon)$.

Let us now consider the special case of $\eta_q = 1/\sqrt{q-1}$. A direct computation gives

$$\eta_q^2 \geq 1 - \varepsilon \quad \text{if and only if} \quad q \leq q(\varepsilon) := \frac{2-\varepsilon}{1-\varepsilon}.$$

Applying (2.28) with $q(\varepsilon)$ as above leads to (2.30) and lets us conclude. \square

5.3. Proof of Theorem 2.9. We fix $q \in (2, \infty)$ as in Assumption 2.2 and $\eta_q \in (0, 1)$ as in Lemma 2.12. Let us define

$$\bar{\varepsilon}_q := 1 - \eta_q^2 > 0, \quad (5.10)$$

We will prove (2.16) for the following exponent $\gamma_{\varepsilon,q}$:

$$\gamma_{\varepsilon,q} := \begin{cases} \left(1 - \frac{2}{q}\right) \frac{\log \frac{1-\varepsilon}{1-\bar{\varepsilon}_q}}{\log \eta_q^{-2}} & \text{if } \varepsilon \leq \frac{1}{2}\bar{\varepsilon}_q, \\ \gamma_{\frac{1}{2}\bar{\varepsilon}_q,q} & \text{if } \varepsilon > \frac{1}{2}\bar{\varepsilon}_q. \end{cases} \quad (5.11)$$

It suffices to show that (2.16) holds for $\varepsilon \in (0, \frac{1}{2}\bar{\varepsilon}_q]$: indeed $\mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)]$ is decreasing in ε , see (4.14), hence the bound extends to $\varepsilon > \frac{1}{2}\bar{\varepsilon}_q$ since we set $\gamma_{\varepsilon,q} := \gamma_{\bar{\varepsilon}_q/2,q}$.

Remark 5.3. One could obtain a sharper bound for $\varepsilon > \bar{\varepsilon}_q/2$ refining the proof below, but we omit the details, since we are mostly interested in small ε .

Remark 5.4. Note that as $\varepsilon \downarrow 0$

$$\gamma_{\varepsilon,q} \sim \alpha_q \varepsilon \quad \text{with} \quad \alpha_q := \frac{1 - \frac{2}{q}}{\log \eta_q^{-2}} \in \left(0, \frac{1}{2}\right). \quad (5.12)$$

To prove that $\alpha_q < \frac{1}{2}$, note that hypercontractivity constant satisfies $\eta_q \leq \frac{1}{\sqrt{q-1}}$, see (2.22), hence

$$\alpha_q \leq f(q) := \frac{1 - \frac{2}{q}}{\log(q-1)}.$$

Since $\lim_{q \downarrow 2} f(q) = \frac{1}{2}$, it suffices to show that $f(\cdot)$ is strictly decreasing for $q > 2$. We have

$$f'(q) = \frac{2(q-1) \log(q-1) - q(q-2)}{q^2 (q-1) (\log(q-1))^2}$$

and we note that the numerator is strictly negative for $q > 2$, as it vanishes for $q = 2$ and its derivative equals $2 \log(q-1) + 4 - 2q < 0$ (by $\log x < x-1$ for $x > 1$).

Henceforth we assume that $0 < \varepsilon \leq \frac{1}{2}\bar{\varepsilon}_q$. We introduce the shorthand

$$\delta := \left(\frac{\mathcal{W}[f]}{\mathbb{V}\text{ar}[f]} \right)^{1-\frac{2}{q}}. \quad (5.13)$$

Since $\eta_q^2 = 1 - \bar{\varepsilon}_q$, we can bound $\sum_{\ell=1}^d \|f^{(\ell)}\|_2^2 \leq (1 - \bar{\varepsilon}_q)^{-d} \delta \operatorname{Var}[f]$ by Theorem 5.2, see (5.3). We use (4.14) to estimate $\mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)]$: for any $\bar{d} \in \mathbb{N}$, recalling (4.9), we get

$$\begin{aligned} \mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)] &\leq \sum_{d=1}^{\bar{d}} \varepsilon (1 - \varepsilon)^d \left(\sum_{\ell=1}^d \|f^{(\ell)}\|_2^2 \right) + (1 - \varepsilon)^{\bar{d}+1} \operatorname{Var}[f] \\ &\leq \left\{ \delta \varepsilon \sum_{d=1}^{\bar{d}} \left(\frac{1 - \varepsilon}{1 - \bar{\varepsilon}_q} \right)^d + (1 - \varepsilon)^{\bar{d}+1} \right\} \operatorname{Var}[f], \end{aligned} \quad (5.14)$$

For $\varepsilon \leq \frac{1}{2}\bar{\varepsilon}_q$ we have $\varrho := \frac{1-\varepsilon}{1-\bar{\varepsilon}_q} \geq \frac{1-\varepsilon}{1-2\varepsilon} \geq 1 + \varepsilon > 1$, hence $\sum_{\ell=1}^{\bar{d}} \varrho^\ell \leq \frac{\varrho^{\bar{d}+1}}{\varrho-1} \leq \frac{1}{\varepsilon} \frac{(1-\varepsilon)^{\bar{d}+1}}{(1-\bar{\varepsilon}_q)^{\bar{d}+1}}$ which yields

$$\frac{\mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)]}{\operatorname{Var}[f]} \leq (1 - \varepsilon)^{\bar{d}+1} \left\{ \frac{\delta}{(1 - \bar{\varepsilon}_q)^{\bar{d}+1}} + 1 \right\}.$$

Plainly, this estimate holds also for $\bar{d} = 0$ (since the LHS is at most $1 - \varepsilon$, see (4.14)).

We first assume that $\frac{\delta}{1-\bar{\varepsilon}_q} \leq 1$. Let $\bar{d} \in \mathbb{N}_0 = \{0, 1, \dots\}$ be the largest integer for which

$$(1 - \bar{\varepsilon}_q)^{\bar{d}} \geq \frac{\delta}{1 - \bar{\varepsilon}_q},$$

that is

$$\bar{d} = \left\lfloor \frac{\log \frac{1-\bar{\varepsilon}_q}{\delta}}{\log \frac{1}{1-\bar{\varepsilon}_q}} \right\rfloor \geq 0.$$

For such \bar{d} we can estimate

$$\frac{\mathbb{C}\text{ov}[f(\omega^\varepsilon), f(\omega)]}{\operatorname{Var}[f]} \leq 2(1 - \varepsilon)^{\bar{d}+1} \leq 2(1 - \varepsilon)^{\frac{\log \frac{1-\bar{\varepsilon}_q}{\delta}}{\log \frac{1}{1-\bar{\varepsilon}_q}}} = 2 \left(\frac{\delta}{1 - \bar{\varepsilon}_q} \right)^{\frac{\log \frac{1}{1-\varepsilon}}{\log \frac{1}{1-\bar{\varepsilon}_q}}},$$

and this bound holds also if $\frac{\delta}{1-\bar{\varepsilon}_q} > 1$ (the LHS is always at most 1). We finally note that

$$2 \left(\frac{\delta}{1 - \bar{\varepsilon}_q} \right)^{\frac{\log \frac{1}{1-\varepsilon}}{\log \frac{1}{1-\bar{\varepsilon}_q}}} = \frac{2}{1 - \varepsilon} (\delta)^{\frac{\log \frac{1}{1-\varepsilon}}{\log \frac{1}{1-\bar{\varepsilon}_q}}} \leq 4 \left(\frac{\mathcal{W}[f]}{\operatorname{Var}[f]} \right)^{\gamma_{\varepsilon,q}},$$

for $\varepsilon \leq \frac{1}{2}\bar{\varepsilon}_q \leq \frac{1}{2}$, by definition of δ and $\gamma_{\varepsilon,q}$, see (5.13) and (5.11). The proof of (2.16) is complete. \square

5.4. Proof of Theorem 2.10. The exponent $\gamma_{\varepsilon,q}$ appearing in (2.16), defined in (5.11), contains the hypercontractive constant η_q from Lemma 2.12, which depends on the vector spaces \mathcal{V}_i in Assumption 2.2. However, by (5.11) and (2.22), we can bound

$$\gamma_{\varepsilon,q} \geq \bar{\gamma}_{\varepsilon,q} := \left(1 - \frac{2}{q}\right) \frac{\log \frac{1}{1-\varepsilon}}{\log(4M_q^2(q-1))}, \quad (5.15)$$

and note that $\bar{\gamma}_{\varepsilon,q}$ only depends on ε, q and M_q . In particular, given functions $(f_N(\omega))_{N \in \mathbb{N}}$ which satisfy Assumption 2.2 for the same $q > 2$ and $M_q < \infty$, we can apply the bound (2.16) with $\gamma_{\varepsilon,q}$ replaced by $\bar{\gamma}_{\varepsilon,q}$, which proves the general BKS criterion (2.17). \square

5.5. Proof of Theorem 2.15. We follow the arguments sketched in the discussion before Theorem 2.15. Let us first prove the bound (2.25), recalling (2.13): for $\varphi \in C_b^\infty$

$$\begin{aligned} \text{Inf}_k^{(1)}[\varphi(f)] &= \mathbb{E}[|\varphi(f) - \mathbb{E}_k[\varphi(f)]|] \\ &\leq \mathbb{E}[|\varphi(f) - \varphi(\mathbb{E}_k[f])|] + \mathbb{E}[|\mathbb{E}_k[\varphi(\mathbb{E}_k[f]) - \varphi(f)]|] \\ &\leq 2\|\varphi'\|_\infty \mathbb{E}[|f - \mathbb{E}_k[f]|] = 2\|\varphi'\|_\infty \text{Inf}_k^{(1)}[f]. \end{aligned} \quad (5.16)$$

This easily extends to a vector of functions $f(\omega) = (f^{(1)}(\omega), \dots, f^{(k)}(\omega))$ with $\varphi : \mathbb{R}^k \rightarrow \mathbb{R}$:

$$\text{Inf}_k^{(1)}[\varphi(f)] \leq 2\|\varphi'\|_\infty \sum_{i=1}^k \text{Inf}_k^{(1)}[f^{(i)}] \quad \text{with } \|\varphi'\|_\infty := \max_{1 \leq i \leq k} \|\partial_i \varphi\|_\infty.$$

In particular, by (2.14), condition $\mathcal{W}[f] := \sum_{i=1}^k \mathcal{W}[f_N^{(i)}] \rightarrow 0$ implies $\mathcal{W}[\varphi(f_N)] \rightarrow 0$.

For i.i.d. random variables $(\omega_i)_{i \in \mathbb{T}}$ with finitely many values, we can apply Theorem 2.10 to any functions in L^2 with bounded variance, in particular to $\varphi(f_N)$ for $\varphi \in C_b^\infty$. Then condition $\mathcal{W}[f_N] \rightarrow 0$ — which implies $\mathcal{W}[\varphi(f_N)] \rightarrow 0$ — yields $\text{Cov}[\varphi(f_N(\omega^\varepsilon)), \varphi(f_N(\omega))] \rightarrow 0$ for any $\varepsilon > 0$ and $\varphi \in C_b^\infty$, see (2.17). Finally, by an application of Cauchy-Schwarz, see (4.15), we obtain $\text{Cov}[\varphi(f_N(\omega^\varepsilon)), \psi(f_N(\omega))] \rightarrow 0$ for any $\varphi, \psi \in C_b^\infty$, which proves (2.26). \square

6. Modified Tribes function

In this section we prove Theorem 2.18. We first consider a general class of “tribes”-like functions, for which computations are more transparent. We will then specialise to the specific function from (2.35) to reach the optimal exponent $\varepsilon/(2 - \varepsilon)$ in (2.30).

6.1. Tribes-like functions. For $t \in \mathbb{N}$ let $A_t = A_t(\omega_1, \dots, \omega_t)$ be an event depending on t variables, that is invariant under permutations of the ω_i 's and has probability

$$p_t := \mathbb{P}(A_t) \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

We set

$$m_t := \lfloor 1/p_t \rfloor$$

and consider the intervals $(B_\ell)_{\ell=1, \dots, m_t}$ in (2.32). Denoting by ω_{B_ℓ} the collection $(\omega_i)_{i \in B_\ell}$, we define

$$Y_\ell(\omega) := \mathbb{1}_{A_t(\omega_{B_\ell})} \quad \text{and} \quad f_t(\omega) := \mathbb{1}_{\{\exists \ell=1, \dots, m_t : Y_\ell(\omega)=1\}}. \quad (6.1)$$

Note that $(Y_\ell(\omega))_\ell$ are i.i.d. Bernoulli random variables of parameter p_t , hence

$$\mathbb{E}[f_t] = 1 - (1 - p_t)^{m_t} \xrightarrow[t \rightarrow \infty]{} 1 - e^{-1} \quad \text{and} \quad \mathbb{V}\text{ar}[f_t] \xrightarrow[t \rightarrow \infty]{} e^{-1}(1 - e^{-1}). \quad (6.2)$$

Remark 6.1. The definition of f_t is coherent with (2.33) when $A_t = \{\sum_{i=1}^t \omega_i = a_t\}$. The original Tribes function [BL85] corresponds to $A_t = \{\omega_i = 1 \ \forall i = 1, \dots, t\}$.

We recall that ω^ε denotes the ε -randomisation of ω , see Definition 4.1. Let us define

$$q_{t,\varepsilon} := \mathbb{P}(Y_1(\omega^\varepsilon) = 1 \mid Y_1(\omega) = 1) = \mathbb{P}(A_t(\omega^\varepsilon) \mid A_t(\omega)). \quad (6.3)$$

The covariance between $f_t(\omega^\varepsilon)$ and $f_t(\omega)$ has an explicit asymptotic behavior described in the following Lemma, whose proof is given in Subsection 6.2.

Lemma 6.2. Suppose that $p_t = o(q_{t,\varepsilon})$ as $t \rightarrow \infty$, for any $\varepsilon \in (0, 1)$. Then, as $t \rightarrow \infty$,

$$\text{Cov}[f_t(\omega^\varepsilon), f_t(\omega)] \sim e^{-2} q_{t,\varepsilon}. \quad (6.4)$$

We next consider the influence of ω_k on $Y_\ell(\omega)$ (recall the classical definition (2.2) of influence). Since $Y_\ell(\omega)$ is invariant under permutations of the ω_k 's, it is enough to focus on

$$r_t := I_1[Y_1] = \mathbb{P}(Y_1(\omega_+^1) \neq Y_1(\omega_-^1)) = \mathbb{P}(A_t(\omega_+^1) \cap A_t(\omega_-^1) = \emptyset), \quad (6.5)$$

where we recall that ω_\pm^1 is the configuration ω where we fix $\omega_1 = \pm 1$. We use r_t to express the influence of ω_k on f_t : recalling (2.35), a direct computation shows that as $t \rightarrow \infty$

$$I_1[f_t] = \mathbb{P}(f_t(\omega_+^1) \neq f_t(\omega_-^1)) = r_t (1 - p_t)^{m_t - 1} \sim r_t e^{-1}. \quad (6.6)$$

Recalling the definition (2.4) of $\mathcal{W}[f]$, we then obtain

$$\mathcal{W}[f_t] \sim t m_t I_1[f_t]^2 \sim e^{-2} t \frac{r_t^2}{p_t}. \quad (6.7)$$

Comparing (6.4) and (6.7), we see that to reach the optimal exponent $\varepsilon/(2 - \varepsilon)$ in (2.30), the quantities $p_t, r_t, q_{t,\varepsilon}$ need to satisfy, as $t \rightarrow \infty$,

$$\text{Cov}[f(\omega^\varepsilon), f(\omega)] \geq \mathcal{W}[f]^{\frac{\varepsilon}{2-\varepsilon} + o(1)} \iff q_{t,\varepsilon} \geq \left(t \frac{r_t^2}{p_t}\right)^{\frac{\varepsilon}{2-\varepsilon} + o(1)}, \quad (6.8)$$

where the term $o(1)$ in the exponent allows for possible logarithmic corrections.

Remark 6.3 (Tribes is not optimal for (2.30)). *A natural candidate to verify optimality of (2.30) is the original Tribes function [BL85] corresponding to $A_t = \{\omega_i = 1 \ \forall i = 1, \dots, t\}$. However, in this case one has $p_t = 1/2^t = e^{-t \log 2}$, $r_t = 1/2^{t-1} \sim 2 p_t$ and $q_{t,\varepsilon} = (1 - \frac{\varepsilon}{2})^t = e^{t \log(1 - \frac{\varepsilon}{2})}$, so $q_{t,\varepsilon} = p_t^{\gamma_\varepsilon} = (t \frac{r_t^2}{p_t})^{\gamma_\varepsilon + o(1)}$ with $\gamma_\varepsilon = \frac{-\log(1 - \varepsilon/2)}{\log 2}$. Note that $\gamma_\varepsilon \neq \frac{\varepsilon}{2-\varepsilon}$, and even as $\varepsilon \downarrow 0$ we have $\gamma_\varepsilon \sim \frac{\varepsilon}{2 \log 2} \simeq 0.721 \varepsilon$, hence (6.8) is not satisfied.*

6.2. Proof of Lemma 6.2. We set for short $Y_1 := Y_1(\omega)$ and $Y_1^\varepsilon := Y_1(\omega^\varepsilon)$. Observe that

$$\begin{aligned} \mathbb{E}[(1 - f_t(\omega^\varepsilon))(1 - f_t(\omega))] &= \mathbb{P}(f_t(\omega^\varepsilon) = 0, f_t(\omega) = 0) = \mathbb{P}(Y_1 = 0, Y_1^\varepsilon = 0)^{m_t} \\ &= \mathbb{P}(Y_1 = 0)^{m_t} \mathbb{P}(Y_1^\varepsilon = 0 | Y_1 = 0)^{m_t} \\ &= (1 - p_t)^{m_t} (1 - \mathbb{P}(Y_1^\varepsilon = 1 | Y_1 = 0))^{m_t}. \end{aligned}$$

We can write, recalling $q_{t,\varepsilon}$ from (6.3),

$$\begin{aligned} \mathbb{P}(Y_1^\varepsilon = 1 | Y_1 = 0) &= \frac{\mathbb{P}(Y_1^\varepsilon = 1) \{1 - \mathbb{P}(Y_1^\varepsilon = 1 | Y_1 = 1)\}}{\mathbb{P}(Y_1 = 0)} = \frac{p_t(1 - q_{t,\varepsilon})}{1 - p_t} \\ &= p_t(1 - q_{t,\varepsilon}) + O(p_t^2) \quad \text{as } t \rightarrow \infty. \end{aligned}$$

Finally, since $m_t = \lfloor 1/p_t \rfloor$, we have that $p_t m_t = 1 + O(p_t)$ and

$$\begin{aligned} \text{Cov}[f_t(\omega^\varepsilon), f_t(\omega)] &= \text{Cov}[(1 - f_t(\omega^\varepsilon))(1 - f_t(\omega))] \\ &= (1 - p_t)^{m_t} (1 - p_t + p_t q_{t,\varepsilon} + O(p_t^2))^{m_t} - (1 - p_t)^{2m_t} \\ &= (1 - p_t)^{m_t} [e^{-1 + q_{t,\varepsilon} + O(p_t)} - e^{-1 + O(p_t)}] \\ &= (1 - p_t)^{m_t} e^{-1} [q_{t,\varepsilon} + O(p_t) + O(q_{t,\varepsilon}^2)]. \end{aligned}$$

Assuming $p_t = o(q_{t,\varepsilon})$, we obtain (6.4). □

6.3. Proof of Theorem 2.18. We need to check that the *Modified Tribes* function, corresponding to $A_t = \{\sum_{i=1}^t \omega_i = a_t\}$ with a_t from (2.31), satisfies (6.8).

We recall that $p_t = \mathbb{P}(A_t)$ is given in (2.34). Note that the event A_t means that the difference between the number of “+” and the number of “-” signs in $\omega_1, \dots, \omega_t$ equals a_t .

Let us now fix $\varepsilon \in (0, 1)$ and estimate

$$q_{t,\varepsilon} = \mathbb{P}(A_t(\omega^\varepsilon) | A_t(\omega)),$$

which is the probability that the difference between the number of “+” and the number of “-” signs is still equal to a_t after resampling. Assuming that $\sum_{i=1}^t \omega_i = a_t$, set

$$N_t^+ := \frac{t + a_t}{2} \quad \text{number of "+",} \quad N_t^- := t - N_t^+ = \frac{t - a_t}{2} \quad \text{number of "-".} \quad (6.9)$$

Conditionally on $A_t(\omega)$, we can write $A_t(\omega^\varepsilon) = \{B_\varepsilon^+ - B_\varepsilon^- = 0\}$, where B_ε^+ and B_ε^- are respectively the number of changed “+” and “-” signs after rerandomising:

$$B_\varepsilon^+ := |\{i = 1, \dots, t : \omega_i = 1, \omega_i^\varepsilon = -1\}|, \quad B_\varepsilon^- := |\{i = 1, \dots, t : \omega_i = -1, \omega_i^\varepsilon = 1\}|.$$

Under $\mathbb{P}(\cdot | A_t(\omega))$, B_ε^+ and B_ε^- are independent binomial random variables, with respective laws $\text{Bin}(N_t^+, \varepsilon/2)$ and $\text{Bin}(N_t^-, \varepsilon/2)$ with N_t^+, N_t^- as in (6.9). Therefore

$$\begin{aligned} \mu_{t,\varepsilon} &:= \mathbb{E}[B_\varepsilon^+ - B_\varepsilon^- | A_t(\omega)] = (N_t^+ - N_t^-)\frac{\varepsilon}{2} = a_t \frac{\varepsilon}{2}, \\ \sigma_{t,\varepsilon}^2 &:= \text{Var}[B_\varepsilon^+ - B_\varepsilon^- | A_t(\omega)] = (N_t^+ + N_t^-)\frac{\varepsilon}{2}(1 - \frac{\varepsilon}{2}) = t \frac{\varepsilon}{2}(1 - \frac{\varepsilon}{2}). \end{aligned}$$

Local Gaussian estimates for the simple random walk then give

$$q_{t,\varepsilon} = \mathbb{P}(B_\varepsilon^+ - B_\varepsilon^- = 0) \sim \mathbb{P}\left(\mathcal{N}(\mu_{t,\varepsilon}, \sigma_{t,\varepsilon}^2) \in [0, 1]\right) \sim \frac{e^{-\frac{\mu_{t,\varepsilon}^2}{2\sigma_{t,\varepsilon}^2}}}{\sqrt{2\pi\sigma_{t,\varepsilon}^2}} = \frac{e^{-\frac{a_t^2}{2t}\frac{\varepsilon}{2-\varepsilon}}}{\sqrt{2\pi t \frac{\varepsilon}{2}(1 - \frac{\varepsilon}{2})}}. \quad (6.10)$$

We observe, recalling (2.31) and (2.34), that $p_t = o(q_{t,\varepsilon})$ as $t \rightarrow \infty$ (since $\varepsilon/(2 - \varepsilon) < 1$), so the assumption of Lemma 6.2 is satisfied. More precisely,

$$q_{t,\varepsilon} \sim \frac{(\sqrt{\frac{\pi}{2}} t p_t)^{\frac{\varepsilon}{2-\varepsilon}}}{\sqrt{\frac{\pi}{2} t \varepsilon(2 - \varepsilon)}} \sim c_\varepsilon \frac{(t p_t)^{\frac{\varepsilon}{2-\varepsilon}}}{t^{\frac{1}{2-\varepsilon}}} \quad \text{with} \quad c_\varepsilon \underset{\varepsilon \downarrow 0}{\sim} \frac{1}{\sqrt{2\pi\varepsilon}}. \quad (6.11)$$

Finally, we compute r_t (see (6.5)):

$$r_t = \frac{\mathbb{P}(\sum_{i=1}^{t-1} \omega_i = a_t + 1)}{2} + \frac{\mathbb{P}(\sum_{i=1}^{t-1} \omega_i = a_t - 1)}{2} \sim \mathbb{P}\left(\sum_{i=1}^{t-1} \omega_i = a_t\right) \sim p_t. \quad (6.12)$$

The bound in (6.8) follows by gathering (6.11) and (6.12), which shows the optimality of the exponent $\varepsilon/(2 - \varepsilon)$. More precisely, by (6.2), (6.4) and (6.7),

$$\frac{\text{Cov}[f_t(\omega^\varepsilon), f_t(\omega)]}{\text{Var}[f_t]} \sim \frac{e^{-1}}{1-e^{-1}} q_{t,\varepsilon}, \quad \frac{\mathcal{W}[f_t]}{\text{Var}[f_t]} \sim \frac{e^{-1}}{1-e^{-1}} t p_t, \quad (6.13)$$

hence by (6.11) we get, for a suitable c'_ε ,

$$\frac{\text{Cov}[f_t(\omega^\varepsilon), f_t(\omega)]}{\text{Var}[f_t]} \sim \frac{c'_\varepsilon}{t^{\frac{1}{2-\varepsilon}}} \left(\frac{\mathcal{W}[f_t]}{\text{Var}[f_t]} \right)^{\frac{\varepsilon}{2-\varepsilon}}.$$

At last, from the second relation in (6.13) we obtain, recalling (2.34),

$$t \sim \left(2 \log \frac{\text{Var}[f_t]}{\mathcal{W}[f_t]}\right)^{\frac{1}{2\gamma}},$$

which plugged into (6.13) concludes the proof of (2.36). \square

Appendix A. Influences for Boolean functions and binary variables

We recall the definition of L^1 and L^2 influences for a function $f(\omega) \in L^2$:

$$\text{Inf}_k^{(1)}[f] := \mathbb{E}[|\delta_k f|], \quad \text{Inf}_k^{(2)}[f] := \mathbb{E}[(\delta_k f)^2]. \quad (\text{A.1})$$

We first show that, for a Boolean function f , these notions coincide up to a factor 2.

Lemma A.1 (Influences for Boolean functions). *For a Boolean function $f(\omega) \in \{0, 1\}$*

$$\text{Inf}_k^{(1)}[f] = 2 \text{Inf}_k^{(2)}[f] = \mathbb{P}(f(\omega) \neq f(\omega_{\text{ind}}^k)) \quad (\text{A.2})$$

where ω_{ind}^k denotes the family $\omega = (\omega_i)_{i \in \mathbb{T}}$ with ω_k replaced by an independent copy ω'_k .

Proof. For a Bernoulli variable X with mean q we have $\mathbb{E}[|X - q|] = 2q(1 - q) = 2\text{Var}[X]$. Conditionally on $(\omega_j)_{j \neq k}$, the distribution of $f(\omega)$ is Bernoulli with mean $\mathbb{E}_k[f]$, hence

$$\text{Inf}_k^{(1)}[f] = 2 \text{Inf}_k^{(2)}[f] = 2 \mathbb{E}[\mathbb{E}_k[f](1 - \mathbb{E}_k[f])].$$

Using the modified family ω_{ind}^k , we can write $\mathbb{E}_k[f](1 - \mathbb{E}_k[f]) = \mathbb{E}_k[f(\omega)(1 - f(\omega_{\text{ind}}^k))]$, and recalling that $f \in \{0, 1\}$ is Boolean we obtain (with $\mathbb{P}_k(\cdot) := \mathbb{E}_k[\mathbf{1}_{\{\cdot\}}]$)

$$\mathbb{E}_k[f](1 - \mathbb{E}_k[f]) = \mathbb{P}_k(f(\omega) = 1, f(\omega_{\text{ind}}^k) = 0) = \frac{1}{2} \mathbb{P}_k(f(\omega) \neq f(\omega_{\text{ind}}^k)).$$

This completes the proof of (A.2). \square

We next compute the influences in the special case of binary ω_i 's.

Lemma A.2 (Influences for binary variables). *If $\omega_i \in \{x_-, x_+\}$ are binary variables, see (1.1), for any function $f(\omega)$ we have*

$$\text{Inf}_k^{(1)}[f] = 2p(1-p) \mathbb{E}[|f(\omega_+^k) - f(\omega_-^k)|], \quad (\text{A.3})$$

$$\text{Inf}_k^{(2)}[f] = p(1-p) \mathbb{E}[(f(\omega_+^k) - f(\omega_-^k))^2], \quad (\text{A.4})$$

where ω_{\pm}^k denotes the family $\omega = (\omega_i)$ in which we fix $\omega_k = x_{\pm}$.

Proof. By (1.1) we compute $\mathbb{E}_k[f] = p f(\omega_+^k) + (1-p) f(\omega_-^k)$, hence

$$\delta_k f = f - \mathbb{E}_k[f] = \begin{cases} (1-p) \{f(\omega_+^k) - f(\omega_-^k)\} & \text{if } \omega_k = x_+, \\ -p \{f(\omega_+^k) - f(\omega_-^k)\} & \text{if } \omega_k = x_-, \end{cases} \quad (\text{A.5})$$

from which (A.3) and (A.4) readily follow. \square

Remark A.3. Relation (A.5) shows that, for binary ω_i 's, our definition of $\delta_k f = f - \mathbb{E}_k[f]$ coincides with $\Delta_k f$ from [Tal94].

Combining Lemmas A.1 and A.2, we finally obtain the following result.

Lemma A.4 (Influences for Boolean functions of binary variables). *For a Boolean function $f(\omega) \in \{0, 1\}$ of binary variables $\omega_i \in \{x_-, x_+\}$, see (1.1), we have*

$$\text{Inf}_k^{(1)}[f] = 2 \text{Inf}_k^{(2)}[f] = 2p(1-p) \mathbb{P}(f(\omega_+^k) \neq f(\omega_-^k)). \quad (\text{A.6})$$

Proof. We apply (A.2) and note that

$$\{f(\omega) \neq f(\omega_{\text{ind}}^k)\} = \{f(\omega_+^k) \neq f(\omega_-^k)\} \cap \{\omega_k \neq \omega'_k\},$$

where we recall that ω'_k denotes an independent copy of ω_k . Since $\mathbb{P}(\omega_k \neq \omega'_k) = 2p(1-p)$ and the event $\{f(\omega_+^k) \neq f(\omega_-^k)\}$ is independent of ω_k, ω'_k , the proof is completed. \square

Appendix B. Orthogonal decomposition

We first prove the Efron-Stein decomposition in Proposition 4.2, which shows that any function $f(\omega) \in L^2$ admits the chaos expansion (4.3) with f_I given by (4.5).

Proof of Proposition 4.2. The necessity of (4.5) is easy: if we assume that (4.3) holds for some functions f_I 's satisfying (4.4), we already observed that the properties in (4.7) must hold, from which we can directly deduce (4.5).

It remains to show that (4.5) holds with f_I given by (4.5). We first assume that \mathbb{T} is finite, say $\mathbb{T} = \{1, \dots, n\}$. Since $\mathbb{E}_i + \delta_i$ is the identity operator, see (2.12), we can write

$$f = (\mathbb{E}_1 + \delta_1) \cdots (\mathbb{E}_n + \delta_n) f = \mathbb{E}[f] + \sum_{d=1}^n \sum_{I \subseteq \mathbb{T}: |I|=d} f_I,$$

where we expanded the product of *commuting* operators δ_i and \mathbb{E}_j (by Fubini's theorem) and we denoted by f_I the function obtained from f applying δ_i for $i \in I$ and \mathbb{E}_j for $j \in I^c$. If we write $I = \{i_1, \dots, i_d\}$ and, for convenience, $I^c = \{j_1, \dots, j_{n-d}\}$, we obtain (4.5):

$$f_I = \delta_{i_1} \cdots \delta_{i_d} \tilde{f}_I \quad \text{with} \quad \tilde{f}_I := \mathbb{E}_{j_1} \cdots \mathbb{E}_{j_{n-d}} f = \mathbb{E}[f | \mathcal{F}_I].$$

We next consider the case $|\mathbb{T}| = \infty$. We write $\mathbb{T} = \bigcup_{n \in \mathbb{N}} \mathbb{T}_n$ for increasing sets $\mathbb{T}_n \subseteq \mathbb{T}_{n+1}$ with $|\mathbb{T}_n| = n$ and we define

$$f_n := \mathbb{E}[f | \mathcal{F}_n] \quad \text{where} \quad \mathcal{F}_n := \sigma(\omega_i: i \in \mathbb{T}_n). \quad (\text{B.1})$$

Since $|\mathbb{T}_n| < \infty$, we already know that f_n admits the decomposition (4.3). Crucially $(f_n)_I = f_I$ for $I \subseteq \mathbb{T}_n$ because $\mathbb{E}[f_n | \mathcal{F}_I] = \mathbb{E}[\mathbb{E}[f | \mathcal{F}_n] | \mathcal{F}_I] = \mathbb{E}[f | \mathcal{F}_I]$, see (4.5), hence

$$f_n = \mathbb{E}[f] + \sum_{d=1}^{\infty} \sum_{I \subseteq \mathbb{T}_n: |I|=d} f_I. \quad (\text{B.2})$$

Note that $f_n = \mathbb{E}[f | \mathcal{F}_n]$ is a martingale bounded in L^2 , hence $f_n \rightarrow \mathbb{E}[f | \mathcal{F}_\infty] = f$ in L^2 because $\mathcal{F}_\infty = \sigma(\bigcup_{n \in \mathbb{N}} \mathcal{F}_n) = \sigma(\omega = (\omega_i)_{i \in \mathbb{T}})$. Letting $n \rightarrow \infty$ in (B.2), we obtain (4.3). \square

We deduce that any function $f(\omega) \in L^2$ of binary variables ω_i 's is a polynomial chaos.

Lemma B.1 (Completeness for binary ω_i 's). *Let the ω_i be independent and centred real random variables which take two values. Then every function $f(\omega) \in L^2$ is a polynomial chaos, i.e. it is of the form (2.11).*

Proof. When $|\mathbb{T}| = n < \infty$, functions $f(\omega)$ with binary ω_i 's can be identified with functions $f: \{x_-, x_+\}^n \rightarrow \mathbb{R}$, which form a vector space of dimension 2^n . The monomials $(\omega_I)_{I \subseteq \mathbb{T}}$ are precisely 2^n (orthogonal, hence) linearly independent functions, which are then a basis. It follows that any function $f(\omega)$ is a (finite) sum $\sum_I \hat{f}(I) \omega_I$, i.e. a polynomial chaos.

When $|\mathbb{T}| = \infty$ we argue as in the proof of Proposition 4.2: we write $\mathbb{T} = \bigcup_{n \in \mathbb{N}} \mathbb{T}_n$ for finite increasing sets \mathbb{T}_n and define f_n by (B.1). We already know that $f_n(\omega) = \sum_{I \subseteq \mathbb{T}_n} \hat{f}_n(I) \omega_I$ is

a polynomial chaos with coefficients $\hat{f}_n(I) = \hat{f}(I)$ independent of n , since $\langle f_n, \omega_I \rangle = \langle f, \omega_I \rangle$ for $I \subseteq \mathbb{T}_n$. Then (2.11) holds because $f_n \rightarrow f$ in L^2 by martingale convergence. \square

Appendix C. Assumption 2.2, ensembles, and hypercontractivity

In this section, we discuss Assumption 2.2, connecting it to the notion of *ensembles* from [MOO10]. We then prove Theorem 4.5, deducing it from results in [MOO10].

C.1. Rephrasing Assumption 2.2. Let us look more closely at our key Assumption 2.2. We start from part (a), discussing property (2.8) relative to the vector spaces $\mathcal{V}_i \subseteq L^2(E_i, \mu_i)$, which are by assumption separable Hilbert spaces with $1 \in \mathcal{V}_i$.

Let us fix an *orthonormal basis* of \mathcal{V}_i starting with the constant function 1:

$$h_i^{(0)} := 1, \quad h_i^{(1)}, \quad h_i^{(2)}, \quad \dots \in \mathcal{V}_i \subseteq L^2(E_i, \mu_i); \quad \langle h_i^{(\ell)}, h_i^{(\ell')} \rangle_{E_i} = \delta_{\ell, \ell'}. \quad (\text{C.1})$$

If \mathcal{V}_i has finite dimension $M_i < \infty$ the sequence is finite: $h_i^{(\ell)}$ for $\ell = 0, 1, \dots, M_i - 1$ (otherwise it is an infinite sequence). We can then rephrase condition (2.8) as follows: for any given index $i \in \mathbb{T}$ we can write, for a.e. $(\omega_j)_{j \neq i}$,

$$f(\omega) = \sum_{\ell=0,1,\dots} \alpha_\ell h_i^{(\ell)}(\omega_i) \quad \text{for coefficients } \alpha_\ell = \alpha_\ell((\omega_j)_{j \neq i}). \quad (\text{C.2})$$

This means that $f(\omega)$, as a function of ω_i , is a linear combination of the functions $h_i^{(\ell)}$'s.

We next discuss Assumption (2.2) (b), focusing on the bound (2.9). The next simple result covers many cases, including Examples 2.3 and 2.4 (and beyond).

Lemma C.1 (Finite-dimensional vector space). *Let the random variables $(\omega_i)_{i \in \mathbb{T}}$ be i.i.d. with law μ on (E, \mathcal{E}) . Fix $q > 2$ and a finite dimensional vector space $\mathcal{V} \subseteq L^q(E, \mu)$.*

Any function $f(\omega) \in L^2$ which satisfies Assumption 2.2 (a) with $\mathcal{V}_i = \mathcal{V}$ also satisfies Assumption 2.2 (b), for a suitable $M_q < \infty$.

Proof. We need to show that condition (2.9) holds for some $M_q < \infty$. Fix an orthonormal basis $h^{(0)}, h^{(1)}, \dots, h^{(k)}$ of \mathcal{V} with $h^{(0)} = 1$. Any $g \in \mathcal{V}$ with $\mathbb{E}[g(\omega_i)] = \langle g, h^{(0)} \rangle = 0$ can be written as $g(\cdot) = \sum_{\ell=1}^k \alpha_\ell h^{(\ell)}(\cdot)$ with $\alpha_\ell \in \mathbb{R}$. By the triangle inequality and Cauchy-Schwarz

$$\|g(\omega_i)\|_q \leq \sum_{\ell=1}^k |\alpha_\ell| \|h^{(\ell)}(\omega_i)\|_q \leq M_q \left(\sum_{\ell=1}^k \alpha_\ell^2 \right)^{\frac{1}{2}} \quad \text{with } M_q := \left(\sum_{\ell=1}^k \|h^{(\ell)}(\omega_i)\|_q^2 \right)^{\frac{1}{2}} < \infty.$$

Since $\|g(\omega_i)\|_2^2 = \sum_{\ell=1}^k \alpha_\ell^2$, we have shown that (2.9) holds. \square

Remark C.2. Lemma C.1 covers Example 2.3, because for μ with finite support the space $\mathcal{V} = L^2(E, \mu)$ is finite dimensional (and it coincides with $L^q(E, \mu)$ for any q).

It also includes Example 2.4, since the space of linear functions $\mathcal{V} = \{\alpha + \beta x : \alpha, \beta \in \mathbb{R}\}$ has dimension 2 and $\mathcal{V} \subseteq L^q(\mathbb{R}, \mu)$ under assumption (2.10).

Remark C.3. We can invoke Lemma C.1 also for Remark 2.5, namely when $f(\omega) \in L^2$ depends on any given ω_i as a polynomial of uniformly bounded degree, say at most h (for $h = 1$ we recover polynomial chaos from Example 2.4).

Indeed, Assumption 2.2 (a) is satisfied with $\mathcal{V}_i = \mathcal{V} = \{\alpha_0 + \alpha_1 x + \dots + \alpha_h x^h : \alpha_i \in \mathbb{R}\}$ which has finite dimension $h+1$. In order to have $\mathcal{V} \subseteq L^q(\mathbb{R}, \mu)$ for some given $q > 2$, we only need to require that the ω_i 's have uniformly bounded moments of order qh .

C.2. Ensembles and multi-linear polynomials. Recall the orthonormal basis (C.1) in the space \mathcal{V}_i . Defining the families of random variables

$$\mathcal{X}_i := \{X_{i,0} := 1, X_{i,1}, X_{i,2}, \dots\} \subseteq L^2(\Omega): \quad X_{i,\ell} := h_i^{(\ell)}(\omega_i), \quad (\text{C.3})$$

we obtain a so-called *sequence of ensembles* $(\mathcal{X}_i)_{i \in \mathbb{T}}$ according to [MOO10, Definition 3.1]:

- random variables $X_{i,\ell}$ within each family \mathcal{X}_i are *orthonormal*;
- different families \mathcal{X}_i 's are *independent*.

Let us call *multi-index* any sequence $\ell = (\ell_i)_{i \in \mathbb{T}}$ with $\ell_i \in \{0, 1, \dots\}$ such that $\ell_i \neq 0$ only for finitely many $i \in \mathbb{T}$ (if \mathcal{V}_i has finite dimension $M_i < \infty$ we also require $\ell_i < M_i$). For each multi-index ℓ we define a *multi-linear monomial* X_ℓ in the ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$:

$$X_\ell := \prod_{i \in \mathbb{T}} X_{i,\ell_i} = \prod_{i \in \mathbb{T}} h_i^{(\ell_i)}(\omega_i), \quad (\text{C.4})$$

(the product is finite since $X_{i,\ell_i} = 1$ when $\ell_i = 0$). These random variables are orthonormal:

$$\langle X_\ell, X_{\ell'} \rangle = \delta_{\ell,\ell'} \quad \text{for all multi-indexes } \ell, \ell'.$$

Definition C.4 ([MOO10]). We call *multi-linear polynomial* in the ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$ any random variable $f(\omega)$ in the linear subspace of $L^2(\Omega)$ generated by the X_ℓ 's:

$$f(\omega) = \sum_{\ell} \hat{f}(\ell) X_\ell \quad \text{for real coefficients } (\hat{f}(\ell))_{\ell} \text{ with } \sum_{\ell} \hat{f}(\ell)^2 < \infty \quad (\text{C.5})$$

where the series converges in L^2 (hence we must have $\hat{f}(\ell) = \langle f(\omega), X_\ell \rangle$).

We are ready to give an equivalent characterisation of Assumption 2.2 (a).

Lemma C.5. A function $f(\omega) \in L^2$ satisfies Assumption 2.2 (a) if and only if it is a multi-linear polynomial in the ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$, i.e. (C.5) holds. In this case, the functions $f_I(\omega)$ appearing in the chaos decomposition (4.3) of $f(\omega)$ are

$$f_I(\omega) = \sum_{\ell: \ell_i \geq 1 \forall i \in I \atop \ell_j = 0 \forall j \notin I} \hat{f}(\ell) X_\ell \quad \text{with } \hat{f}(\ell) = \langle f(\omega), X_\ell \rangle. \quad (\text{C.6})$$

Before giving the proof, let us make two observations.

Remark C.6 (Ensembles and polynomial chaos). For real valued ω_i 's with $\mathbb{E}[\omega_i] = 0$ and $\mathbb{E}[\omega_i^2] = 1$, if we take the space of linear functions $\mathcal{V}_i = \{x \mapsto \alpha + \beta x : \alpha, \beta \in \mathbb{R}\}$ with canonical basis $h_i^{(0)} = 1$ and $h_i^{(1)}(x) = x$, we obtain the ensembles $\mathcal{X}_i = \{1, \omega_i\}$. In this setting, multi-indexes ℓ have components $\ell_i \in \{0, 1\}$ and $X_\ell = \omega_{i_1} \cdots \omega_{i_d}$ is nothing but the multi-linear monomial in (2.11) with $\{i_1, \dots, i_d\} = \{i \in \mathbb{T} : \ell_i = 1\}$. Definition (C.5) then gives the polynomial chaos in (2.11).

Remark C.7 (Ensembles and chaos decomposition). If we take $\mathcal{V}_i = L^2(E_i, \mu_i)$ — assumed to be separable — Assumption 2.2 (a) is satisfied by every $f(\omega) \in L^2$ (by Fubini's

theorem). Then it follows by Lemma C.5 that every $f(\omega) \in L^2$ is a multi-linear polynomial, i.e. multi-linear monomials X_ℓ are a basis of $L^2(\Omega, \sigma((\omega_i)_{i \in \mathbb{T}}), \mathbb{P})$. Formula (C.6) then provides a hands-on construction of the chaos decomposition in Proposition 4.2.

Proof of Lemma C.5. It is clear that any multi-linear polynomial (C.5) in the ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$ satisfies Assumption 2.2 (a), since by construction $X_{i,\ell} = h_i^{(\ell)}(\omega_i)$ with $h_i^{(\ell)} \in \mathcal{V}_i$.

We now prove that any $f(\omega) \in L^2$ satisfying Assumption 2.2 (a) is of the form (C.5). We fix an index $i \in \mathbb{T}$ and note that, by (2.8), $\omega_i \mapsto f(\omega)$ belongs to \mathcal{V}_i conditionally on $(\omega_j)_{j \neq i}$. Since $h_i^{(0)}, h_i^{(1)}, \dots$ is an orthonormal basis of \mathcal{V}_i , we write $f(\omega)$ as the L^2 convergent series

$$f(\omega) = \sum_{\ell_i=0,1,\dots} \langle f(\omega), h_i^{(\ell_i)}(\omega_i) \rangle_{E_i} h_i^{(\ell_i)}(\omega_i) = \sum_{\ell_i=0,1,\dots} \mathbb{E}_i[f(\omega) X_{i,\ell_i}] X_{i,\ell_i}. \quad (\text{C.7})$$

If $i' \in \mathbb{T}$ is another index, using again Assumption 2.2 (a) and recalling (C.4), we obtain

$$\begin{aligned} f(\omega) &= \sum_{\ell_i'=0,1,\dots} \sum_{\ell_i=0,1,\dots} \mathbb{E}_{i'}[\mathbb{E}_i[f(\omega) X_{i,\ell_i}] X_{i',\ell_i'}] X_{i,\ell_i} X_{i',\ell_i'} \\ &= \sum_{\substack{\ell \text{ multi-indexes} \\ \ell_k=0 \forall k \notin \{i,i'\}}} \mathbb{E}_{i'} \mathbb{E}_i[f(\omega) X_\ell] X_\ell. \end{aligned}$$

Iterating the same argument for all indexes in a given finite set $\mathbb{T}_n = \{i_1, \dots, i_n\} \subseteq \mathbb{T}$, since $\mathbb{E}_{i_1} \mathbb{E}_{i_2} \cdots \mathbb{E}_{i_n} [\cdot] = \mathbb{E}[\cdot | \mathcal{F}_{\mathbb{T} \setminus \mathbb{T}_n}]$ by Fubini's theorem, we obtain

$$f(\omega) = \sum_{\substack{\ell \text{ multi-indexes} \\ \text{supported in } \mathbb{T}_n}} \mathbb{E}[f(\omega) X_\ell | \mathcal{F}_{\mathbb{T} \setminus \mathbb{T}_n}] X_\ell. \quad (\text{C.8})$$

If \mathbb{T} is finite, we can take $\mathbb{T}_n = \mathbb{T}$ and we obtain our goal (C.5), since $\mathbb{E}[\cdot | \mathcal{F}_{\mathbb{T} \setminus \mathbb{T}_n}] = \mathbb{E}[\cdot]$.

When \mathbb{T} is infinite, writing $\mathbb{T} = \bigcup_{n \in \mathbb{N}} \mathbb{T}_n$ for finite increasing sets \mathbb{T}_n , we have by (C.8)

$$\mathbb{E}[f(\omega) | \mathcal{F}_{\mathbb{T}_n}] = \sum_{\substack{\ell \text{ multi-indexes} \\ \text{supported in } \mathbb{T}_n}} \mathbb{E}[f(\omega) X_\ell] X_\ell \quad (\text{C.9})$$

because $\mathbb{E}[\mathbb{E}[\cdot | \mathcal{F}_{\mathbb{T} \setminus \mathbb{T}_n}] | \mathcal{F}_{\mathbb{T}_n}] = \mathbb{E}[\cdot]$ by Fubini's theorem. Since $\mathbb{E}[f(\omega) | \mathcal{F}_{\mathbb{T}_n}] \rightarrow f(\omega)$ in L^2 as $n \rightarrow \infty$, by martingale convergence, our goal (C.5) follows by (C.9). \square

C.3. Proof of Theorem 4.5. Let us prove (4.18). By Lemma C.5, any $f(\omega) \in L^2$ satisfying Assumption-2.2 is a multi-linear polynomial in the sequence of ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$. As a consequence, in the language of [MOO10, Definition 3.9], proving the bound (4.18) amounts to showing that *the sequence of ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$ is $(2, q, \eta_q)$ -hypercontractive*.

We first consider the case when \mathbb{T} is finite and all \mathcal{V}_i 's have finite dimension, so each ensemble \mathcal{X}_i consists of finitely many random variables. This is the setting considered in [MOO10, Proposition 3.11], by which it suffices to show that *each individual family \mathcal{X}_i is $(2, q, \eta_q)$ -hypercontractive*, i.e. the bound (2.21) holds (the proof is similar to [Jan97, Lemma 5.3]). But this is precisely the way we have fixed $\eta_q \in (0, 1)$, see Lemma 2.12, hence (4.18) is proved in this case.

We next consider the case when either \mathbb{T} is infinite or some \mathcal{V}_i has infinite dimension. Let us write $\mathbb{T} = \bigcup_{n \in \mathbb{N}} \mathbb{T}_n$ as the increasing union of finite sets \mathbb{T}_n . For each $n \in \mathbb{N}$, we define $f_n(\omega) \in L^2$ by restricting the sum in (C.5) to multi-indexes $\ell = (\ell_i)_{i \in \mathbb{T}}$ supported in \mathbb{T}_n and

with all components satisfying $\ell_i \leq n$. We already proved that (4.18) holds for f_n :

$$\|T^{\eta_q} f_n\|_q \leq \|f_n\|_2 \quad \forall n \in \mathbb{N}, \quad (\text{C.10})$$

and it remains to let $n \rightarrow \infty$. By construction $f_n \rightarrow f$ in L^2 , and since T^η is a bounded operator, we also have $T^{\eta_q} f_n \rightarrow T^{\eta_q} f$ in L^2 , in particular $|T^{\eta_q} f_n|^q \rightarrow |T^{\eta_q} f|^q$ in probability. Taking the limit $n \rightarrow \infty$ in (C.10) we then obtain, by Fatou,

$$\|T^{\eta_q} f\|_q \leq \liminf_{n \rightarrow \infty} \|T^{\eta_q} f_n\|_q \leq \lim_{n \rightarrow \infty} \|f_n\|_2 = \|f\|_2,$$

which completes the proof of (4.18).

The proof just given shows that the bound (4.18) holds not just for f but for any multi-linear polynomial in the sequence of ensembles $(\mathcal{X}_i)_{i \in \mathbb{T}}$, which includes any linear combination of components f_I such as f' in (4.17).

If we now consider $f'_d = \sum_{|I| \leq d} \alpha_I f_I$ with degree at most d , we can define $T^{1/\eta_q} f'_d$ even though $1/\eta_q > 1$, see (4.12), and we have the identity $f'_d = T^{\eta_q} (T^{1/\eta_q} f'_d)$. Applying (4.18) with f replaced by $T^{1/\eta_q} f'_d$, which is still a linear combination of f_I 's, we get

$$\|f'_d\|_q^2 \leq \|T^{1/\eta_q} f'_d\|_2^2 = \sum_{I \subseteq \mathbb{T}: |I| \leq d} \frac{1}{\eta_q^{2|I|}} \alpha_I^2 \|f_I\|_2^2 \leq \frac{1}{\eta_q^{2d}} \sum_{I \subseteq \mathbb{T}: |I| \leq d} \alpha_I^2 \|f_I\|_2^2 = \frac{1}{\eta_q^{2d}} \|f'\|_2^2,$$

which is precisely (4.19). \square

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