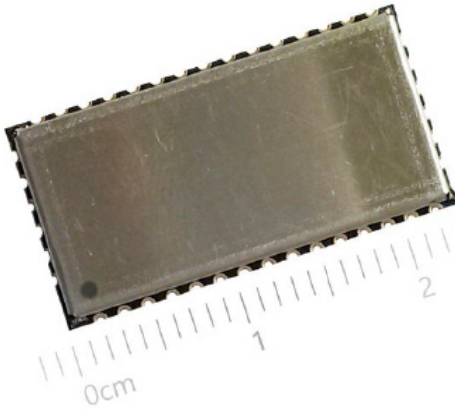


FCC ID:2ACCRMB05

Bluetooth® Technology Audio Module**EH-MB05****• Bluetooth radio**

- Fully embedded Bluetooth® v3.0+EDR
- Class2 module
- 128-bit encryption security
- Range up to 15m
- Multipoint capability(7 transmit data devices connected at the same time)

• Support profiles

- SPP (Master and slave)
- iAP (ipod accessory protocol)
- HFP ,A2DP,AVRCP,HID(Slave)

• User interface

- Send AT command over UART
- Firmware upgrade over USB
- With SPP service active: 560kbps transmission speed (UART)
- PCM interface (I2S, SPDIF)
- I2C interface(Master)

• Audio codec

- 16bit internal stereo codec :95dB SNR for DAC
- 64MIPS Kalimba DSP coprocessor
- Support Apt-X ,AAC, Apt-XLL,SBC codec

• General I/O

- 11 general purpose I/Os
- 2 analogue I/O
- • **FCC and Bluetooth® qualified**
- • **Single voltage supply: 3.3V typical**
- • **Small form factor: 23.24 x 11.93 x 2.2mm**
- • **Operating temperature range: -40 °C to 85 °C**
- • **The operation distance >20cm**

Version 2.0
July 21 2014

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1. Description

The EH-MB05 is an easy to use Bluetooth module, compliant with Bluetooth v3.0+EDR. The module provides complete RF platform in a small form factor.

The EH-MB05 enables electronic devices with wireless connectivity, not requiring any RF experience or expertise for integration into the final product. The EH-MB05 module, being a certified solution, optimizes the time to market of the final application.

The module is designed for maximum performance in a minimal space including fast speed UART and 11 general purpose I/O lines, 1 analogue I/O lines, several serial interface options, and up to 600 kbps transmission speed with SPP service active, 200 kbps with iAP service active.

The module is external antenna, the impedance of the feed line between the RF port and the antenna shall be 50Ω. Embedded Bluetooth AT command firmware is a friendly interface, Support different Bluetooth profiles, such as SPP, A2DP, AVRCP, HFP, HID, iAP and etc. iAP over Bluetooth using apple's authentication coprocessor.

Customers using the Apple authentication IC must register as developers, to become an Apple certified MFI member. License fees may apply, for additional information visit: <http://developer.apple.com/programs/which-program/index.html>.

Certified MFI developers developing electronic accessories that connect to an iPod®, iPhone®, and iPad® can gain access to technical documentation, hardware components, technical support and certification logos.

Customized firmware for peripheral device interaction, power optimization, security, and other proprietary features may be supported and can be ordered pre-loaded and configured.

2. Application

- Home entertainment
- Service diagnostics
- Office and mobile accessories
- Commercial
- Multimedia speaker
- Automotive
- Human interface devices

3. EH-MB05 Product numbering

EH-MB05X

- A. EH ----- Company Name(Ehong)
B. MB05 ----- Module Name

4. Electrical Characteristic

4.1. Recommend operation conditions

Operating Condition	Min	Typical	Max	Unit
Storage Temperature	-40	--	+105	°C
Operating Temperature Range	-40	--	+85	°C
PIO Voltage	+1.7	+3.3	+3.6	V
AIO Voltage	+1.42	+1.5	+1.57	V
VDD Voltage	+2.7	+3.3	+3.6	V
RF frequency	2400	2441	24800	MHz

Table 1: Recommended Operating Conditions

4.2. Absolute Maximum Rating

Rating	Min	Max	Unit
Storage Temperature	-40	+125	°C
Operating Temperature	-40	+85	°C
PIO Voltage	-0.4	+3.6	V
AIO Voltage	-0.4	+1.57	V
VDD Voltage	-0.4	+3.6	V
USB_DP/USB_DN Voltage	-0.4	+3.6	V
Other Terminal Voltages except RF	-0.4	VDD+0.4	V

Table 2: Absolute Maximum Rating Recommended Operating Conditions

4.3. Power consumptions

Operating Condition	Min	Typical	Max	Unit
Standby, without deep sleep	2.1	-	3.1	mA
Standby, with deep sleep	0.11	-	0.7	mA
Inquiry window time ^(b)	-	-	40	mA
Connected (Deep sleep disable, sniff ^(a) enable)	-	3.3	-	mA
Connected (Deep sleep on, sniff ^(a) enable)	-	0.4	-	mA
Connected with data transfer	18	20	22	mA
Connected with audio streaming (A2DP)		35	40	mA

Note :

Power consumption depends on the firmware used. Typical values are shown in the table.

^(a)Sniff mode ----- In Sniff mode, the duty cycle of the slave's activity in the piconet may be reduced. If a slave is in active mode on an ACL logical transport, it shall listen in every ACL slot to the master traffic, unless that link is being treated as a scatter net link or is absent due to hold mode. With sniff mode, the time slots when a slave is listening are reduced, so the master shall only transmit to a slave in specified time slots. The sniff anchor points are spaced regularly with an interval of T_{sniff} .

^(b)Radio on(Inquiry)----Search time is 22 seconds

4.4. Input/output Terminal Characteristics

4.4.1. Digital Terminals

Supply Voltage Levels	Min	Typ	Max	Unit
Input Voltage Levels				
V_{IL} input logic level low	-0.3		+0.25VDD	V
V_{IH} input logic level high	0.625VDD	-	VDD+0.3	V
Output Voltage Levels				
V_{OL} output logic level low, $I_{OL} = 4.0\text{mA}$	-	-	0.125	V
V_{OH} output logic level high, $I_{OH} = -4.0\text{mA}$	0.75xVDD	-	VDD	V
Input and Tri-state Current				
I_i input leakage current at $V_{in}=VDD$ or 0V	-100	0	100	nA
I_{oz} tri-state output leakage current at $V_o=VDD$ or 0V	-100	0	100	nA
With strong pull-up	-100	-40	-10	uA
With strong pull-down	10	40	100	μA
With weak pull-up	-5	-1.0	-0.2	μA
With weak pull-down	-0.2	+1.0	5.0	μA
CI Input Capacitance	1.0	-	5.0	pF
Resistive Strength				
R_{puw} weak pull-up strength at VDD-0.2V	500k	-	2M	Ω
R_{pdw} weak pull-down strength at 0.2V	500k	-	2M	Ω
R_{pus} strong pull-up strength at VDD-0.2V	10k	-	50k	Ω
R_{pds} strong pull-down strength at 0.2V	10k	-	50k	Ω

Table 4: Digital Terminal

4.5. USB

USB Terminals	Min	Typical	Max	Unit
Input Threshold				

V _{IL} input logic level low	-	-	0.3VDD	V
V _{IH} input logic level high	0.7VDD	-	-	V
Input Leakage Current				
GND < V _{IN} < VDD ^(a)	-1	1	5	μA
C _I Input capacitance	2.5	-	10.0	pF
Output Voltage Levels to Correctly Terminated USB Cable				
V _{OL} output logic level low	0.0	-	0.2	V
V _{OH} output logic level high	2.8	-	VDD	V

Table 5: USB Terminal

(a) Internal USB pull-up disable

4.5.1. Internal CODEC Analogue to Digital Converter

Parameter	Conditions	Min	Typ	Max	Unit
Resolution		-	-	16	Bits
Input Sample Rate, F _{sample}		8	-	44.1	kHz
Signal to Noise Ratio, SNR	f _{in} =1kHz B/W=20Hz->20kHz A-Weighted THD+N<1% 150mV V _{pk-pk}	F _{sample}			
		8kHz	-	82	-
		11.025kHz	-	81	-
		16kHz	-	80	-
		22.050kHz	-	79	-
		32kHz	-	79	-
		44.1kHz	-	78	-
Digital Gain	Digital Gain Resolution = 1/32 dB	-24	-	21.5	dB
Analogue Gain	Analogue Gain Resolution = 3dB	-3	-	42	dB
Input full scale at maximum gain (differential)		-	4	-	mV rms
Input full scale at minimum gain (differential)		-	800	-	mV rms
3dB Bandwidth		-	20	-	kHz
Microphone mode input impedance		-	6	-	kΩ
THD+N (microphone input) @ 30mv rms input			0.04		%

Table 6: Analogue to Digital Converter

4.5.2. Internal CODEC Digital to Analogue Converter

Parameter	Conditions	Min	Typ	Max	Unit
Resolution		-	-	16	Bits
Output Sample Rate, F_{sample}		8	-	48	kHz
Signal to Noise Ratio, SNR	$f_{\text{in}}=1\text{kHz}$ $B/W=20\text{Hz}\rightarrow 20\text{kHz}$ A-Weighted $\text{THD}+\text{N}<0.01\%$ 0dBFS signal Load = 100k Ω	F_{sample}			
		8kHz	-	95	-
		11.025kHz	-	95	-
		16kHz	-	95	-
		22.050kHz	-	95	-
		32kHz	-	95	-
		44.1kHz	-	95	-
		48kHz	-	95	-
Digital Gain	Digital Gain Resolution = 1/32 dB	-24	-	21.5	dB
Analogue Gain	Analogue Gain Resolution = 3dB	0	-	-21	dB
Output voltage full swing (differential)		-	750	-	mV rms
Allowed Load	Resistive	16	-	OC	Ω
	Capacitive	-	-	500	pF
THD+N 100k Ω load		-	-	0.01	%
THD+N 16 Ω load		-	-	0.1	%
SNR (Load=16 Ω , 0dBFS input relative to digital silence)		-	95	-	dB

Table 7: Digital to Analogue Converter

5. Pinout and Terminal Description

5.1. Pin assignment

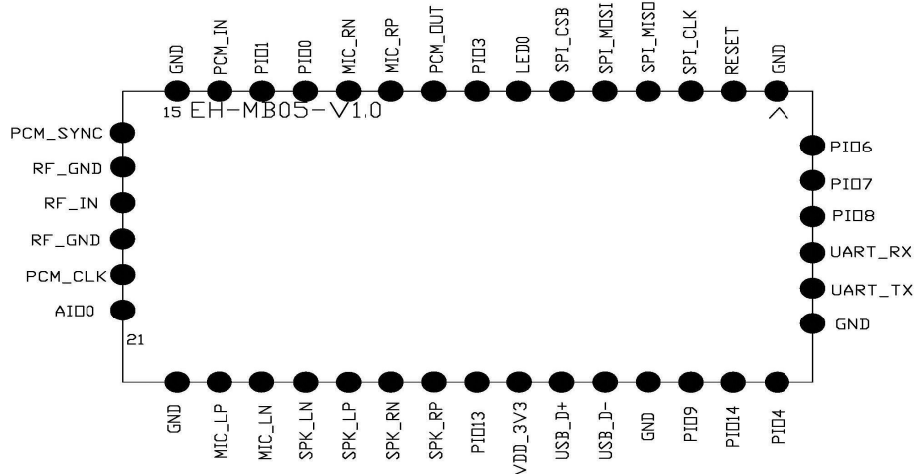


Figure 1: Pinout of EH-MB05

Pin	Symbol	I/O Type	Description
1	GND	Ground	Ground
2	RESETB	CMOS input with weak internal pull-up	Active LOW RESETB, input debounced so must be low for >5ms to cause a RESETB
3	SPI_CLK	Input with weak internal pull-down	Serial Peripheral interface clock for programming only
4	SPI_MISO	CMOS output, tri-state, with weak internal pull-down	Serial Peripheral Interface output for programming only
5	SPI_MOSI	CMOS input, with weak internal pull-down	Serial Peripheral Interface input for programming only
6	SPI_CSB	Input with weak internal pull-up	Chip select for Synchronous Serial Interface for programming only, active low
7	LED0	Open drain output	LED Driver
8	PIO3	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
9	PCM_OUT	CMOS output, tri-state, with weak internal pull-down	Synchronous Data Output
10	MIC_RP	Analogue	Microphone input positive, right
11	MIC_RN	Analogue	Microphone input negative, right

12	PIO0	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
13	PIO1	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
14	PCM_IN	CMOS Input, with weak internal pull-down	Synchronous Data Input
15	GND	Ground	Ground
16	PCM_SYNC	Bi-directional with weak internal pull-down	Synchronous Data Sync
17	RF_GND	RF Ground	RF ground
18	RF_IN	RF	RF Transceiver input/output line
19	RF_GND	RF Ground	RF ground
20	PCM_CLK	Bi-directional with weak internal pull-down	Synchronous Data Clock
21	AIO0	Bi-directional	Analogue programmable input/output line
22	GND	Ground	Ground
23	MIC_LP	Analogue	Microphone input positive, left
24	MIC_LN	Analogue	Microphone input negative, right
25	SPK_LN	Analogue	Speaker output negative, left
26	SPK_LP	Analogue	Speaker output positive, left
27	SPK_RN	Analogue	Speaker output negative, right
28	SPK_RP	Analogue	Speaker output positive, right
29	PIO13	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
30	VDD	3V3 power input	3V3 power input
31	USB_DP	Bi-directional	USB data plus with selectable internal 1.5K pull up resistor
32	USB_DN	Bi-directional	USB data minus
33	GND	Ground	Ground
34	PIO9	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
35	PIO14	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line

36	PIO4	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
37	GND	Ground	Ground
38	UART_TX	Bi-directional CMOS output, tri-state, with weak internal pull-up	UART data output
39	UART_RX	CMOS input with weak internal pull-down	UART data input
40	PIO8	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
41	PIO7	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line
42	PIO6	Bi-directional with programmable strength internal pull-up/down	Programmable input/output line

Table 8: PIN Terminal Description

6. Physical Interfaces

6.1. Power Supply

- The module DC3.3V power input.
- Power supply pin connection capacitor to chip and pin as far as possible close
- Capacitor decouples power to the chip
- Capacitor prevents noise coupling back to power plane.

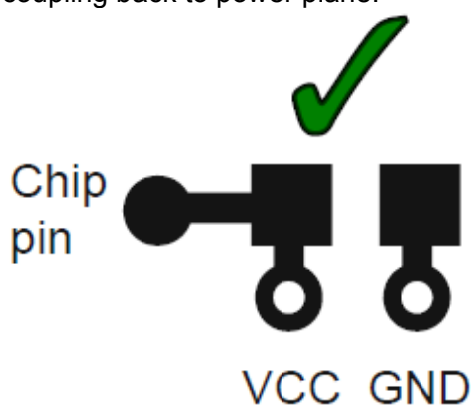


Figure 2: Power Supply PCB Design

6.2. Reset

The module may be reset from several sources: RESETB pin, power-on reset, a UART break character or via software configured watchdog timer.

The RESETB pin is an active low RESETB and is internally filtered using the internal low frequency clock oscillator. A RESETB will be performed between 1.5 and 4.0ms following RESETB being active. It is recommended that RESETB be applied for a period greater than 5ms.

At RESETB the digital I/O pins are set to inputs for bi-directional pins and outputs are tri-state. The pull-down state is shown below.

Pin Name / Group	Pin Status on RESETB
USB_DP	N/a
USB_DN	N/a
UART_RX	PD
UART_TX	PU
SPI_MOSI	PD
SPI_CLK	PD
SPI_CSB	PU
SPI_MISO	PD
RESETB	PU
PIOs	PD
PCM_IN	PD
PCM_CLK	PD
PCM_SYNC	PD
PCM_OUT	PD

Table 9: Pin Status on Reset

6.3. PIO

EH-MB05 has a total of 11 digital programmable I/O terminals. They are powered from VDD (3.3V). Their functions depend on firmware running on the device. PIO lines can be configured through software to have either weak or strong pull-ups or pull-downs.

Note:

All PIO lines are configured as inputs with weak pull-downs at reset.

Any of the PIO lines can be configured as interrupt request lines or as wake-up lines from sleep modes.

6.4. AIO

EH-MB05 has 2 analogue I/O terminals. Their functions depend on software. Typically ADC functions can be configured to battery voltage measurement. They can also be used as a digital PIO.

6.5. UART

This is a standard UART interface for communicating with other serial devices. The UART interface provides a simple mechanism for communicating with other serial devices using the RS232 protocol.

The UART CTS and RTS signals can be used to implement RS232 hardware flow control where both are active low indicators.

Parameter		Possible Values
Baud Rate	Minimum	1200 baud ($\leq 2\%$ Error)
		9600 baud ($\leq 1\%$ Error)
	Maximum	3M baud ($\leq 1\%$ Error)
Flow Control		RTS/CTS or None
Parity		None, Odd or Even
Number of Stop Bits		1 or 2
Bits per Byte		8

Table 10: Possible UART Settings

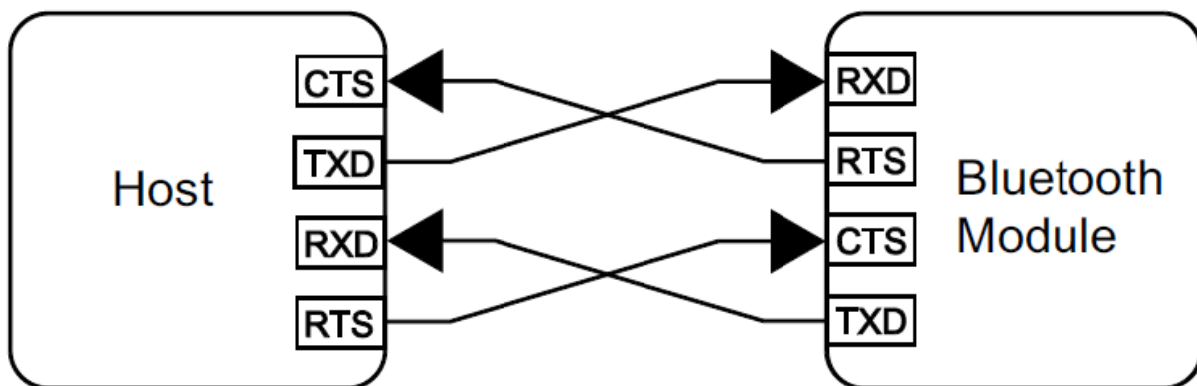


Figure 3: Connection To Host device

6.6. I2C Master

PIO6, PIO7 and PIO8 can be used to form a master I²C interface. The interface is formed using software to drive these lines. It is suited only to relatively slow functions such as driving a LCD, keyboard scanner or EEPROM. In the case, PIO lines need to be pulled up through 2.2K Ω resistors.

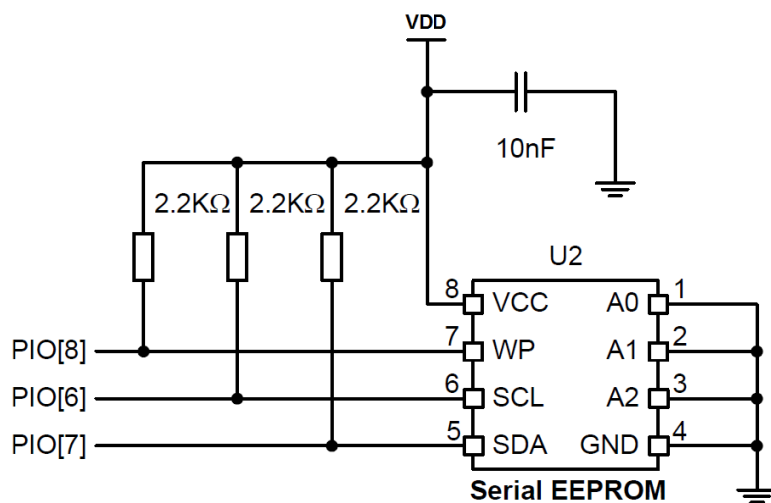


Figure 4: Example EEPROM Connection with I2C Interface

6.6.1. Apple iOS CP reference design

The figures below give an indicative overview of what the hardware concept looks like. A specific MFI co-processor layout is available for licensed MFI developers from the MFI program.

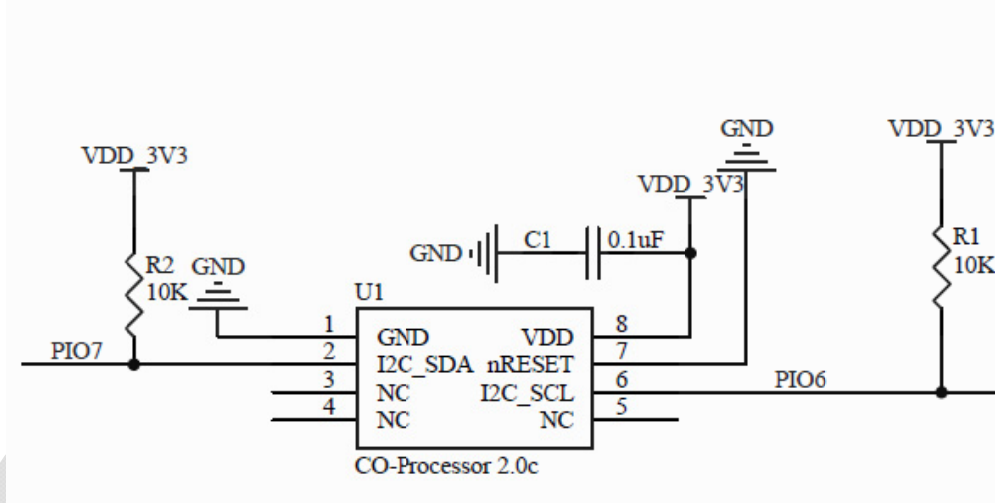


Figure 5: Apple Co-processor 2.0C

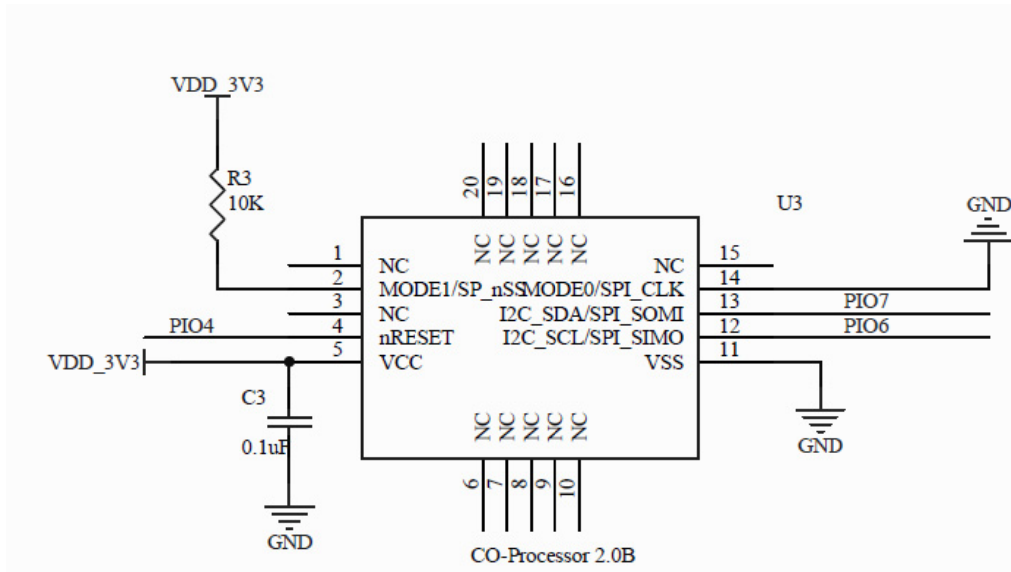


Figure 6: Apple Co-processor 2.0B

6.7. Digital Audio Interfaces

The audio interface circuit consists of:

- Stereo audio codec
- Dual audio inputs and outputs
- A configurable PCM, I²S or SPDIF interface

Figure 2 outlines the functional blocks of the interface. The codec supports stereo playback and recording of audio signals at multiple sample rates with a resolution of 16-bit. The ADC and the DAC of the codec each contain 2 independent channels. Any ADC or DAC channel can be run at its own independent sample rate.

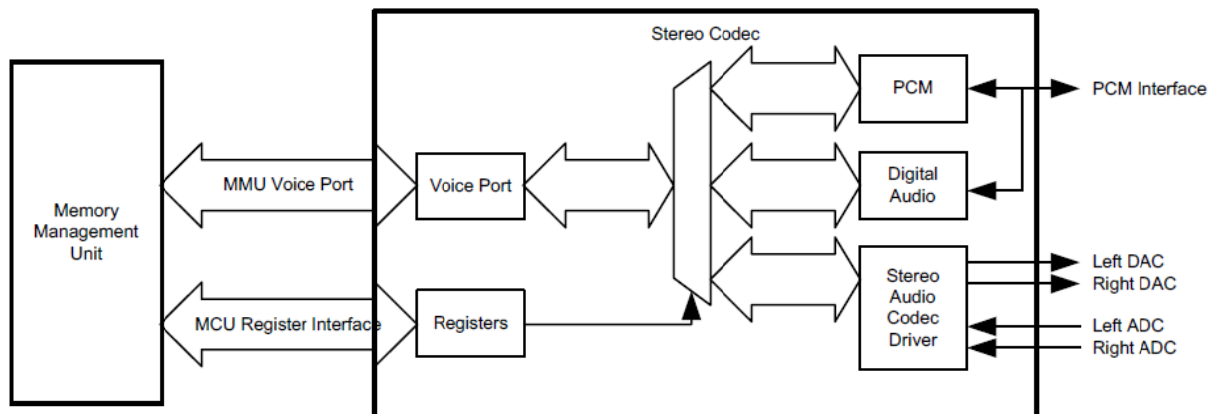


Figure 7: Audio Interface

The interface for the digital audio bus shares the same pins as the PCM codec interface described in Table 11, which means each of the audio buses are mutually exclusive in their usage. Table 11 lists these alternative functions.

PCM Interface	SPDIF Interface	I ² S Interface
PCM_OUT	SPDIF_OUT	SD_OUT
PCM_IN	SPDIF_IN	SD_IN
PCM_SYNC	-	WS
PCM_CLK	-	SCK

Table 11: Alternative Functions of the Digital Audio Bus Interface on the PCM Interface

The audio input circuitry consists of a dual audio input that can be configured to be either single-ended or fully differential and programmed for either microphone or line input. It has an analogue and digital programmable gain stage for optimization of different microphones. The audio output circuitry consists of a dual differential class A-B output stage.

6.7.1. PCM

The audio pulse code modulation (PCM) interface supports continuous transmission and reception of PCM encoded audio data over Bluetooth.

Hardware on EH-MB05 allows the data to be sent to and received from a SCO connection. Up to three SCO connections can be supported by the PCM interface at any one time.

EH-MB05 can operate as the PCM interface master generating PCM_SYNC and PCM_CLK or as a PCM interface slave accepting externally generated PCM_SYNC and PCM_CLK.

EH-MB05 is compatible with a variety of clock formats, including Long Frame Sync, Short Frame Sync and GCI timing environments.

It supports 13-bit or 16-bit linear, 8-bit u-law or A-law companded sample formats and can receive and transmit on any selection of three of the first four slots following PCM_SYNC.

EH-MB05 interfaces directly to PCM audio devices including the following:

- Qualcomm MSM 3000 series and MSM 5000 series CDMA baseband devices
- OKI MSM7705 four channel A-law and μ -law CODEC
- Motorola MC145481 8-bit A-law and μ -law CODEC
- Motorola MC145483 13-bit linear CODEC
- STW 5093 and 5094 14-bit linear CODECs(8)
- EH-MB05 is also compatible with the Motorola SSI interface

6.7.2. Digital Audio Interface (I2S)

The digital audio interface supports the industry standard formats for I2S, left-justified or right-justified. The interface shares the same pins of the PCM interface as Table 11.

The I2S interface can be enabled by using AT+ commands. The module is an I2S slave device with the default firmware. Contact with EHong for special firmware when use the module as an I2S master. The I2S support following formats:

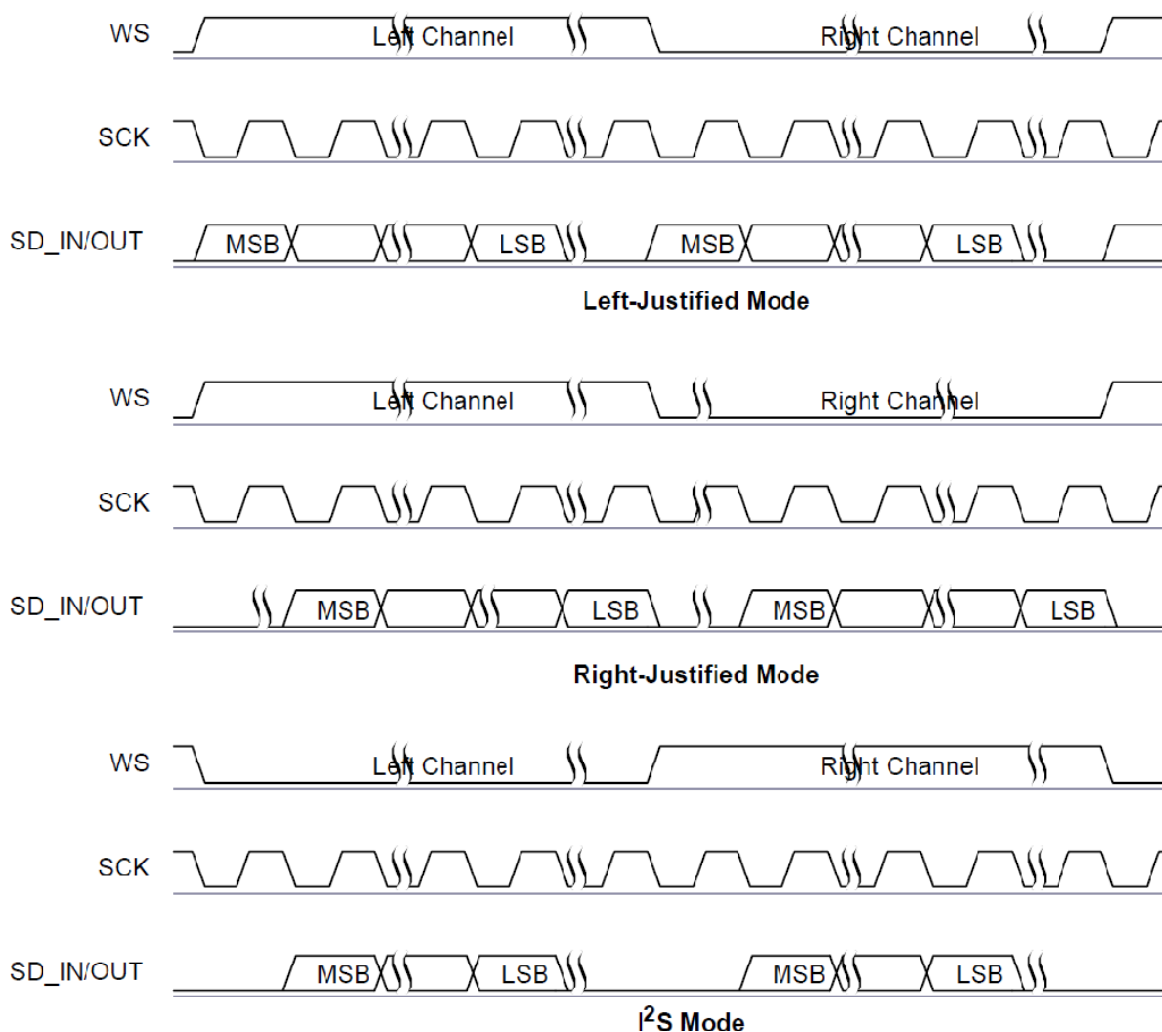
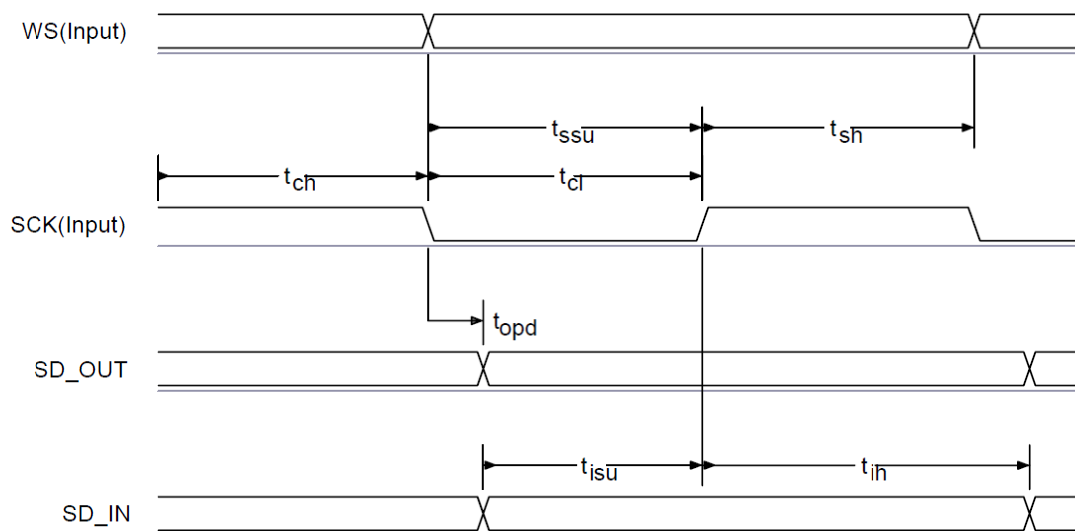


Figure 8: Digital Audio Interface Modes

Symbol	Parameter	Min	Typical	Max	Unit
-	SCK Frequency	-	-	6.2	MHz
-	WS Frequency	-	-	96	kHz
t_{ch}	SCK high time	80	-	-	ns
t_{cl}	SCK low time	80	-	-	ns
t_{opd}	SCK to SD_OUT delay	-	-	20	ns
t_{ssu}	WS to SCK set up time	20	-	-	ns
t_{sh}	WS to SCK hold time	20	-	-	ns
t_{isu}	SD_IN to SCK set-up time	20	-	-	ns
t_{ih}	SD_IN to SCK hold time	20	-	-	ns

Table 12 : Digital Audio Interface Slave Timing

Figure 9: Digital Audio Interface Slave Timing

Symbol	Parameter	Min	Typical	Max	Unit
-	SCK Frequency	-	-	6.2	MHz
-	WS Frequency	-	-	96	kHz
t_{opd}	SCK to SD_OUT delay	-	-	20	ns
t_{spd}	SCK to WS delay	-	-	20	ns
t_{isu}	SD_IN to SCK set-up time	20	-	-	ns
t_{ih}	SD_IN to SCK hold time	10	-	-	ns

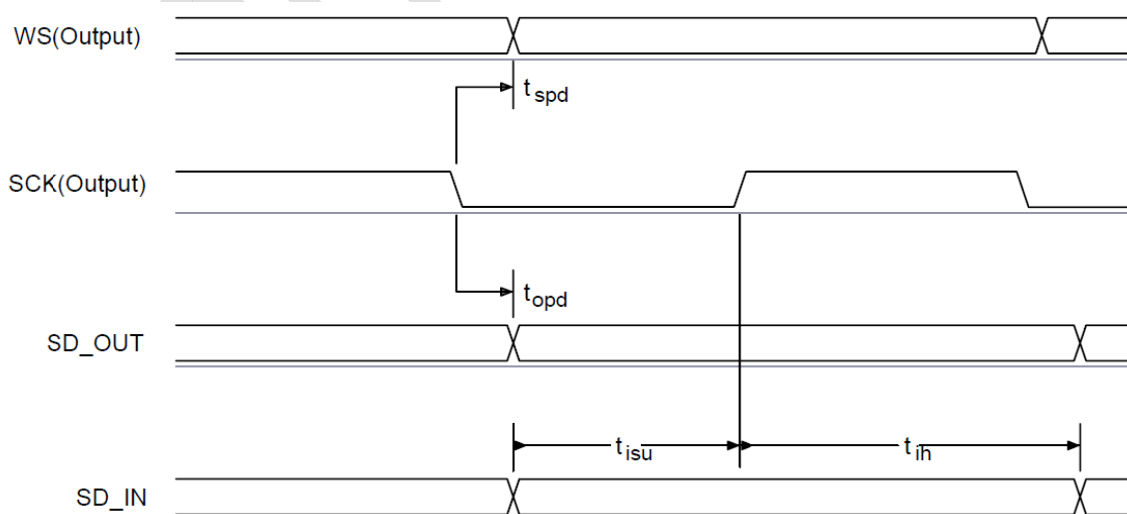
Table 13: Digital Audio Interface Master Timing


Figure 10: Digital Audio Interface Master Timing

6.7.3. IEC 60958 Interface (SPDIF)

Through AT+ command to switch if SPDIF is used. The IEC 60958 interface is a digital audio interface that uses bi-phase coding to minimise the DC content of the transmitted signal and allows the receiver to decode the clock information from the transmitted signal. The IEC 60958 specification is based on the 2 industry standards:

- AES/EBU
- Sony and Philips interface specification SPDIF

The interface is compatible with IEC 60958-1, IEC 60958-3 and IEC 60958-4.

The SPDIF interface signals are SPDIF_IN and SPDIF_OUT and are shared on the PCM interface pins. The input and output stages of the SPDIF pins can interface to:

- A 75Ω coaxial cable with an RCA connector, see Figure 11.
- An optical link that uses Toslink optical components, see Figure 12.

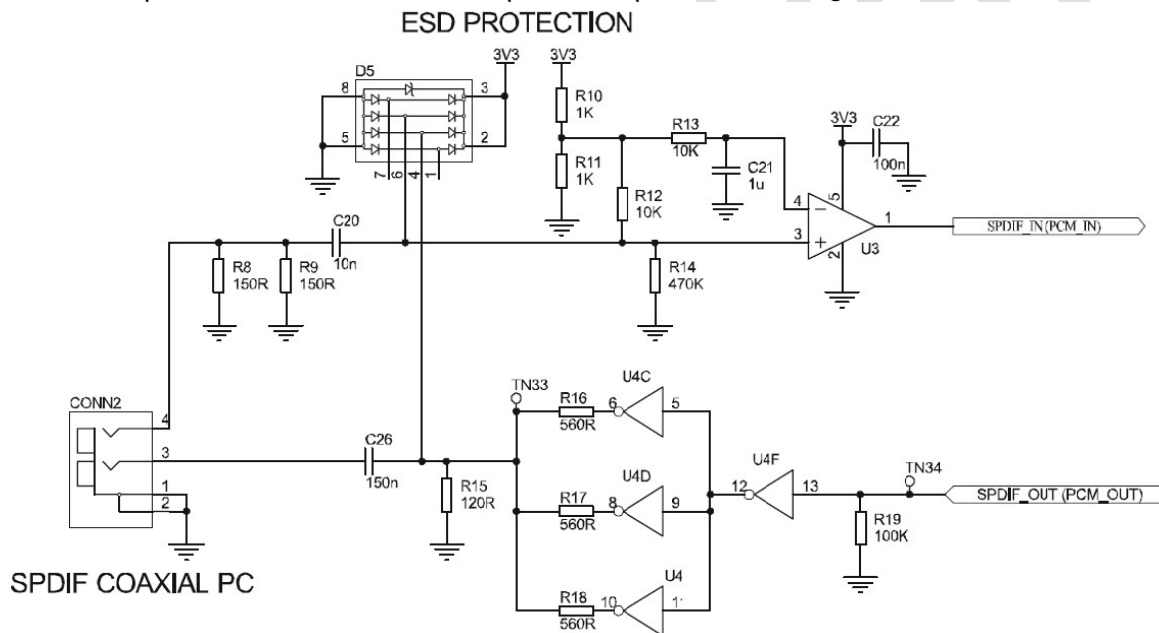


Figure 11: Example Circuit for SPDIF Interface (Co-Axial)

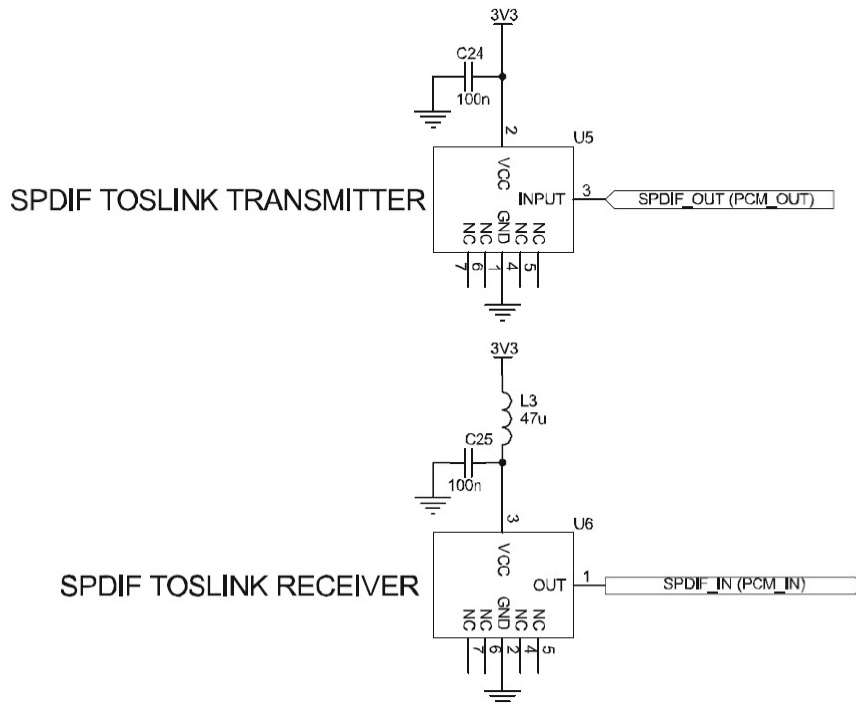


Figure 12: Example Circuit for SPDIF Interface (Optional)

6.8. Microphone input

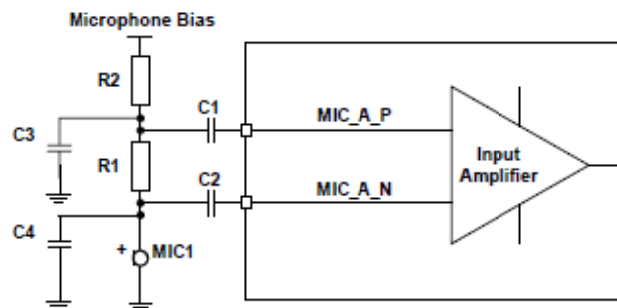


Figure 13: Microphone Biasing (Single Channel Shown)

The audio input is intended for use in the range from $1\mu\text{A}$ @ 94dB SPL to about $10\mu\text{A}$ @ 94dB SPL. With biasing resistors R1 and R2 equal to $1\text{k}\Omega$, this requires microphones with sensitivity between about -40dBV and -60dBV . The microphone for each channel should be biased as shown in Figure 14.

6.9. Analog Output stage

The output stage digital circuitry converts the signal from 16-bit per sample, linear PCM of variable sampling frequency to a 2Mbits/s 5-bit multi-bit bit stream, which is fed into the analogue output circuitry.

The output stage circuit is comprised a DAC with gain setting and class AB amplifier. The output is available as a differential signal between SPKR_LN and SPKR_LP for the right channel, as Figure 14 shows, and between SPKL_RN and SPKL_RP for the left channel.

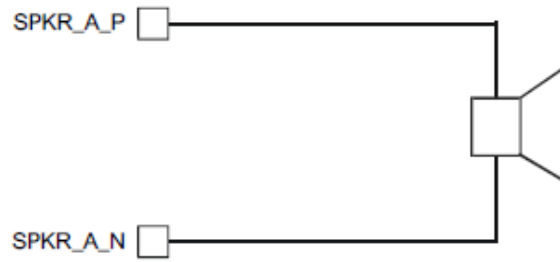


Figure 15: Speaker output

6.10. USB

This is a full speed (12M bits/s) USB interface for communicating with other compatible digital devices. The module acts as a USB peripheral, responding to request from a master host controller, such as a PC.

The USB interface is capable of driving a USB cable directly. No external USB transceiver is required. The device operates as a USB peripheral, responding to requests from a master host controller such as a PC. Both the OHCI and the UHCI standards are supported. The set of USB endpoints implemented can behave as specified in the USB section of the Bluetooth specification v2.1+EDR or alternatively can appear as a set of endpoints appropriate to USB audio devices such as speakers.

The module has an internal USB pull-up resistor. This pulls the USB_DP pin weakly high when module is ready to enumerate. It signals to the USB master that it is a full speed (12Mbit/s) USB device.

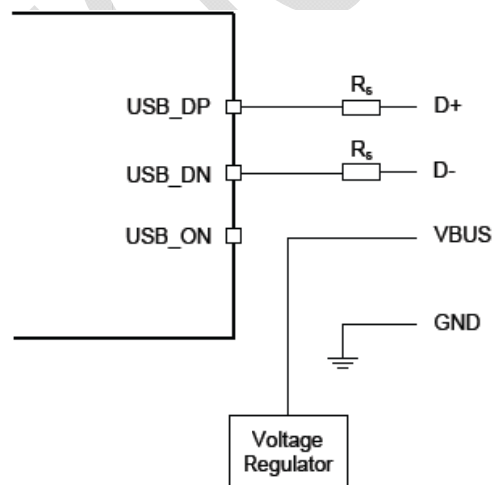


Figure 16: USB Connections

Identifier	Value	Function
R_s	27Ω Nominal	Impedance matching to USB cable

Table 14: USB Interface Component Values

Note:

USB_ON is only used when the firmware need an input to detect if USB is connected and the USB function shall be enabled. In such case it is shared with the module PIO terminals. If detection is not needed (firmware already runs with USB, such as USB DFU or USB CDC), USB_ON is not needed.

7. EH-MB05 Reference Design

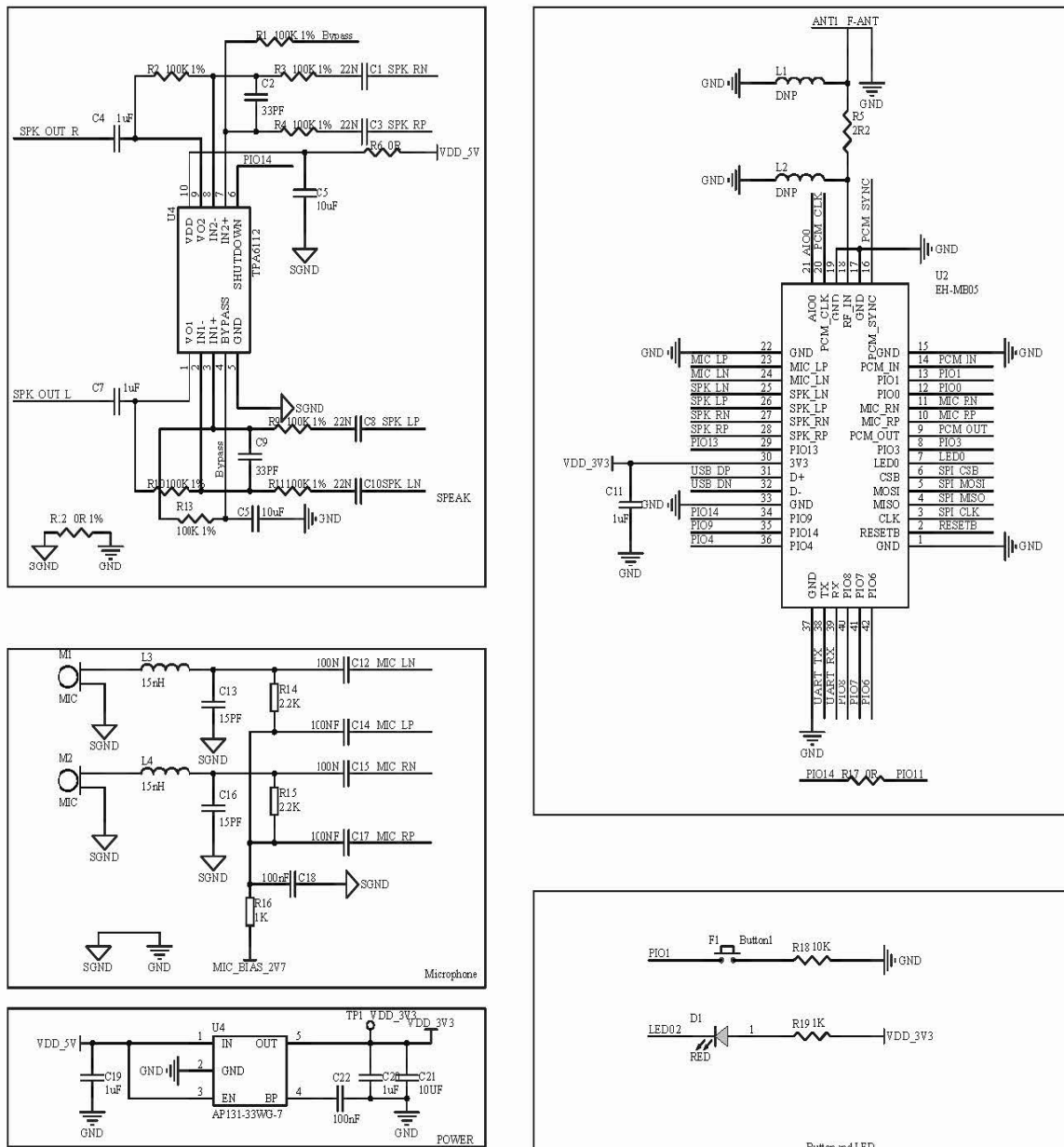


Figure 17: Reference Design

8. Mechanical and PCB Footprint Characteristics

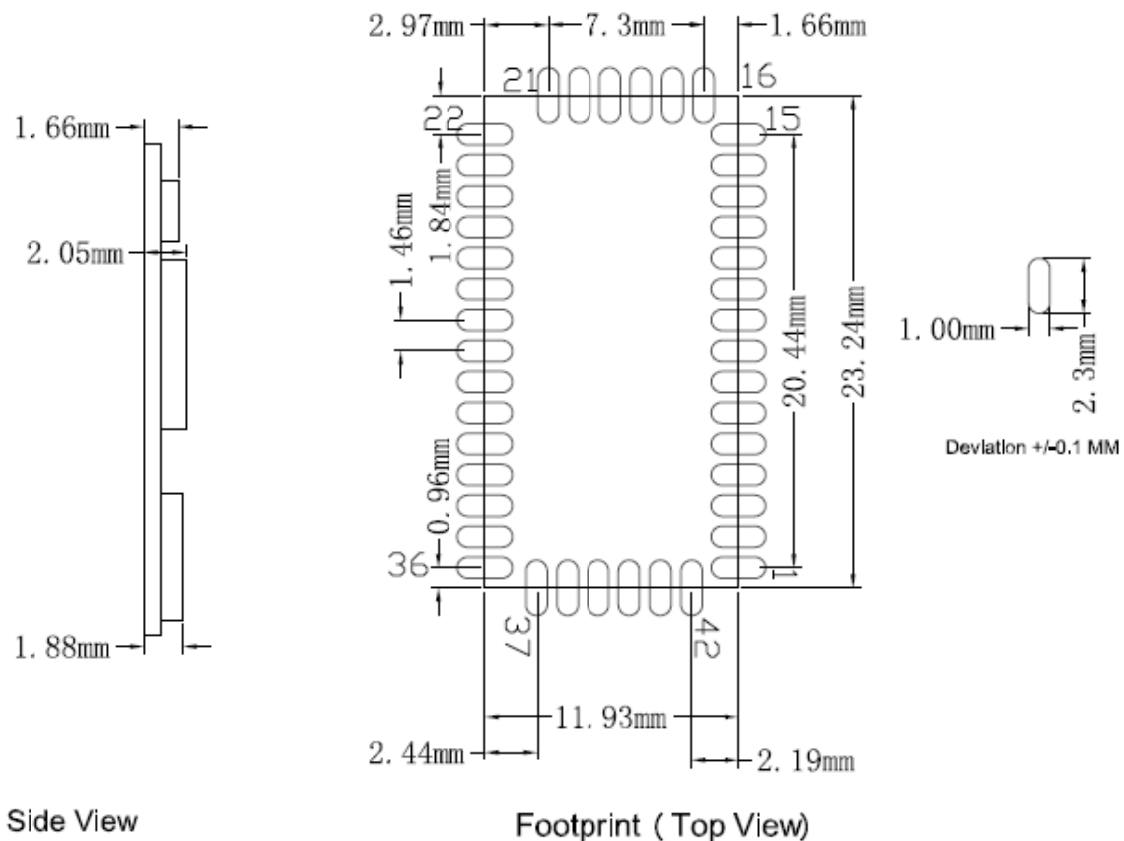


Figure 18: Recommended PCB Mounting Pattern (Unit: mm, Deviation:0.02mm)TOP View

9. RF Layout Guidelines

EH-MB05 has an on-board PCB antenna. PCB design to ensure enough clearance area of antenna, area length is 1.6 times of antenna length, area width is 4 times of antenna width, the bigger the better if the space allows. The specific size as shown figure below.

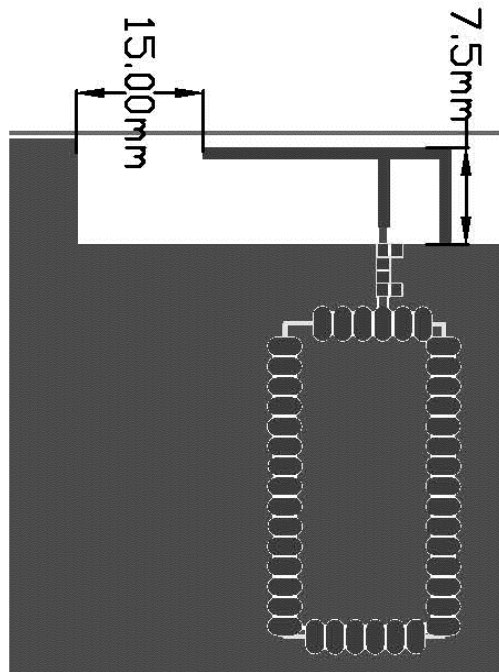


Figure 19: Clearance area of antenna

9.1. Feed Line and Antenna

The impedance of the feed line between the RF port and the antenna shall be 50Ω .

- A good ground directly under the feed line is always needed for impedance control.
- Route the feed line as curve lines when needed, avoid 90 or even less degree angles style.
- The width of the feed line, the distance of the feed line to the ground plane are keys to the impedance. Ask your PCB supplier to control the impedance of the feed line.

For the antenna,

- When PCB antenna is used, matching networks shall be used to optimize the antenna's signal strength.
- Use as many vias as possible to connect the ground planes nearby the antenna.

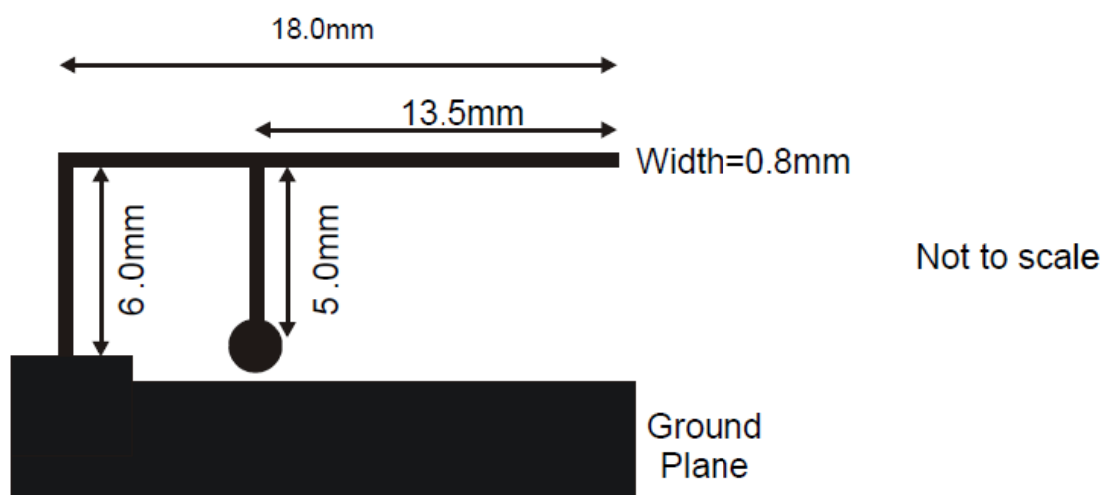


Figure 20: Antenna reference design

9.2. Matching network in free space

The specs of a Fractus standard antenna are measured in their evaluation board (in free space), which is an ideal case. In a real design, components nearby the antenna, semiconductors, LCD's, batteries, covers, connectors, etc affect the antenna performance. This is the reason why it is highly recommended to place 0402 pads for a PI matching network as close as possible to the antenna feeding point. Do it in the ground plane area, not in the clearance area. This is a degree of freedom to tune the antenna once the design is finished and taking into account all elements of the system (batteries, displays, covers, etc).

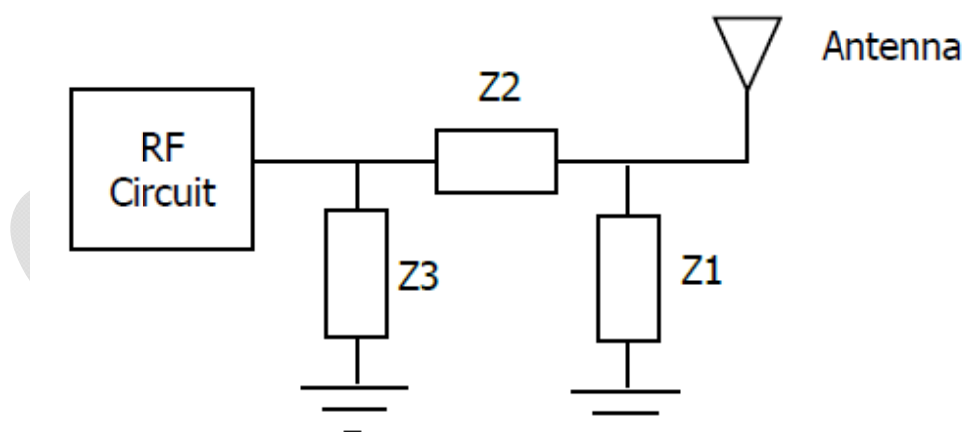


Figure 21: PI match network example

10. Reflow Profile

The soldering profile depends on various parameters necessitating a set up for each application. The data here is given only for guidance on solder reflow.

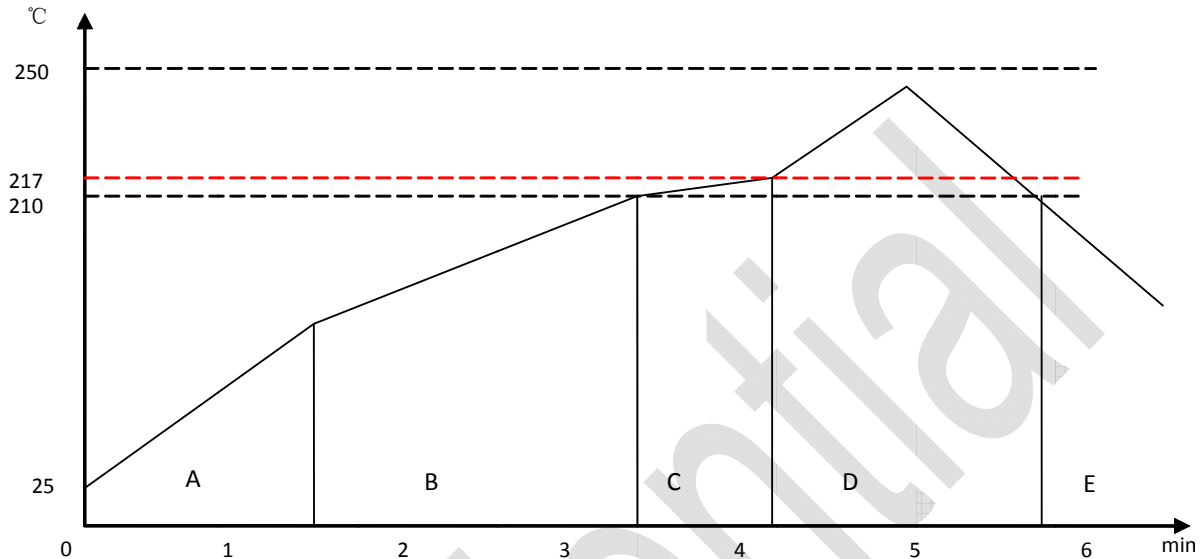


Figure 22: Recommended Reflow Profile

Pre-heat zone (A) — This zone raises the temperature at a controlled rate, **typically 0.5 – 2 °C/s**. The purpose of this zone is to preheat the PCB board and components to 120 ~ 150 °C. This stage is required to distribute the heat uniformly to the PCB board and completely remove solvent to reduce the heat shock to components.

Equilibrium Zone 1 (B) — In this stage the flux becomes soft and uniformly encapsulates solder particles and spread over PCB board, preventing them from being re-oxidized. Also with elevation of temperature and liquefaction of flux, each activator and rosin get activated and start eliminating oxide film formed on the surface of each solder particle and PCB board. **The temperature is recommended to be 150° to 210° for 60 to 120 second for this zone.**

Equilibrium Zone 2 (c) (optional) — In order to resolve the upright component issue, it is recommended to keep the temperature in 210 – 217 ° for about 20 to 30 second.

Reflow Zone (D) — The profile in the figure is designed for Sn/Ag3.0/Cu0.5. It can be a reference for other lead-free solder. The peak temperature should be high enough to achieve good wetting but not so high as to cause component discoloration or damage. Excessive soldering time can lead to intermetallic growth which can result in a brittle joint. The recommended peak temperature (Tp) is 230 ~ 250 °C. The soldering time should be 30 to 90 second when the temperature is above 217 °C.

Cooling Zone (E) — The cooling ate should be fast, to keep the solder grains small which will give a longerlasting joint. **Typical cooling rate should be 4 °C.**

11. Contact Information

Sales: sales@ehlink.com.cn

Technical support: support@ehlink.com.cn

Phone: +86 21 64769993

Fax: +86 21 64765833

Street address: Rom1505, Blk 1st ,No.833 South Hong mei Rd ,Ming hang district shanghai

Note: FCC RF exposure requirements

1. Radiated transmit power must be equal to or lower than that specified in the FCC Grant of Equipment Authorization for FCC ID:2ACCRMB05.

2. To comply with FCC regulations limiting both maximum RF output power and human exposure to RF radiation, maximum antenna gain (including cable loss) must not exceed: .

Bluetooth <4.0 dBi

3. This module must not transmit simultaneously with any other antenna or transmitter.

4. This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

5. The host end product must include a user manual that clearly defines operating requirements and conditions that must be observed to ensure compliance with current FCC RF exposure guidelines.

For portable devices, in addition to the conditions 1 through 5 described above, a separate approval is required to satisfy the SAR requirements of FCC Part 2.1093

If the device is used for other equipment that separate approval is required for all other operating configurations, including portable configurations with respect to 2.1093 and different antenna configurations.

For this device, OEM integrators must be provided with labeling instructions of finished products. Please refer to KDB784748 D01 v07, section 8. Page 6/7 last two paragraphs:

A certified modular has the option to use a permanently affixed label, or an electronic label. For a permanently affixed label, the module must be labelled with an FCC ID - Section 2.926 (see 2.2 Certification (labelling requirements) above). The OEM manual must provide clear instructions explaining to the OEM the labelling requirements, options and OEM user manual instructions that are required (see next paragraph).

For a host using a certified modular with a standard fixed label, if (1) the module's FCC ID is not visible when installed in the host, or (2) if the host is marketed so that end users do not have straight forward commonly used methods for access to remove the module so that the FCC ID of the module is visible; then an additional permanent label referring to the enclosed module: "Contains Transmitter Module FCC ID: 2ACCRMB05" or "Contains FCC ID: 2ACCRMB05" must be used. The host OEM user manual must also contain clear instructions on how end users can find and/or access the module and the FCC ID.

The final host / module combination may also need to be evaluated against the FCC Part 15B criteria for unintentional radiators in order to be properly authorized for operation as a Part 15 digital device.

The users manual or instruction manual for an intentional or unintentional radiator shall caution the user that changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment. In cases where the manual is provided only in a form other than paper, such as on a computer disk or over the Internet, the information required by this section may be included in the manual in that alternative form, provided the user can reasonably be expected to have the capability to access information in that form.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning

the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.