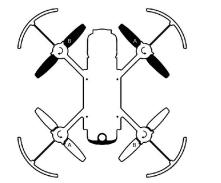
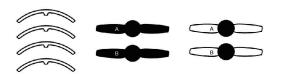
PARTS LIST









# FCC COMPLIANCE STATEMENT

For the product, under normal use condition is at least 20 cm away from the body of the user.

This device complies with Part 15 of the FCC Rules. Its operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

Note: This product has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This product generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this product does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

NOTE: THE GRANTEE IS NOT RESPONSIBLE FOR ANY CHANGES OR MODIFICATIONS NOT EXPRESSLY APPROVED BY THE PARTY RESPONSIBLE FOR COMPLIANCE. SUCH MODIFICATIONS COULD VOID THE USER'S AUTHORITY TO OPERATE THE EQUIPMENT.

# NOTICES AND WARNINGS

Welcome to the world of Cicada. Please read the ENTIRE quick start guide to become familiar with all the features . For the most up-to-date information please visit the corresponding product page at www.elanview.com.

Wish you an amazing flying experience!

# GENERAL PRECAUTION

Do not attempt to operate your aircraft nearby buildings or other obstructions that do not offer a clear view of the sky and thus restrict GPS reception.

### Flight Interference

Do not attempt to operate your aircraft in areas with potential electro magnetic interference including areas nearby (at least 200m) broadcast towers, power transmission stations, high voltage power lines, etc. Otherwise, it may cause failure to take-off and even collisions.

### Flight Restricted-Zone

Do not try to operate your aircraft near airport or military restricted areas: otherwise. you need to take all consequences which may result in.

Do not fly over crowds or dense vehicles in case accidents happen.

### Flight Weather

Flying at high temperatures, snow, wind, rain and other inclement weather is not

## SAFETY WARNING

- Before take-off, you must start the motors with the aircraft in a position that has at least 10 feet (approximately 3 meters) of clear and open space around it, be away from obstructions, crowds or high voltage power lines, etc.
- Always keep the aircraft within to avoid any unexpected situations.
- In case of accidental damage caused by GPS location error, please make sure that when plane returns, no obstacle is around, nor lakes are
- Please make sure children are operating under professionals' supervision or guidance.

Operations towards Cicada are realized by mobile control. Please first download Elan View APP.

DOWNLOADING APP

1. Downloading APP by Computer

Please visit http://www.elanview.com. download 'ElanView' under SUPPORT tab and install it on your computer.

2. Downloading APP by mobile/PAD

## ANDROID SYSTEM

- Search 'Elan View' in BAIDU MOBILE APP, find 'ElanView' download and install it into your mobile.
- Search 'Elan View' in Google Play, download and install it into your mobile.

## IOS SYSTEM

Search 'Elan View' in APP Store, find 'ElanView' download and install it into your mobile.

### SCAN QR CODE

Scan the following QR code, download and install the APP.



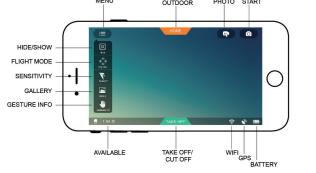








## APP INTERFACE



## TAKE OFF/CUT OFF

TAKE OFF ----- To take off, press 'TAKE OFF' button and hold for 2-3 seconds



----- To cut-off, press 'CUT OFF' button and hold for 2-3 seconds

### HOME/OUTDOOR



- Press 'HOME' button and hold for 2-3 seconds, the plane will land near the take-off position.



Press 'OUTDOOR', the plane will stop to fly home, and switch

HIDE/SHOW: Hide or show the information column

FLIGHT MODE: Switch KevPad. Stick.Gesture or Gravity Mode.

• SENSITIVITY: Choose Speed 1 (slow), Speed 2 (mid-speed), or Speed 3 (fast).

• GALLERY: Enter Gallery and scan the photographs or videos.

GESTURE INFO: Browse the gestures introduction.

## FLIGHT OPERATING

- 1. Install battery, power on the copter, and LED will be on.
- 2. After powering on the copter, place it in horizontal place, wait until it completes
- 3. Swith on WiFi of your mobile or pad, find WiFi name "Cicada XXXXXXXX connect input the password (the password is the last 8 digitals).
- 4. Enter APP, and choose flight scene.



- Outdoor Mode: Suitable for open places with strong GPS signal and less obstacles, such as parks, squares.
- Indoor Mode: Suitable for windless environment, no GPS location, or Go-

### 5. Choose Flight Scene, and enter the operation interface.



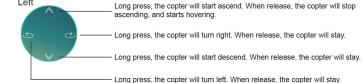
Outdoor Mode

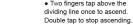


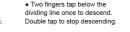




7. Key Pad Mode (Default Mode)







. Tap left side of the screen once: the copter will start to turn left. Double tap to stop turning.



7-3. Gesture Mode (Optional in Menu)



• Only one flight control is available at one time, e.g. to ascend or turn left.





Long press, the copter will move forward, when release, the copter will stop Long press, the copter will move forward in right direction. When release, the

Long press, the copter will move backward, when release, the copter will stop

Long press, the copter will move forward in left direction. When release, the

Slide to upper side, the copter will start to ascend.

Slide to right side, the copter will start to turn right.

Slide to down side, the copter will start to descend.

Slide to left side, the copter will start to turn left.

Slide to upper side, the copter will start to move forward.

Slide to down side, the copter will start to move backward.

- Slide to right side, the copter will start to move forward in the right direction

- Slide to left side, the copter will start to move forward in the left direction.

copter will stop moving.

7-2. Stick Mode (Optional in Menu)

The operation sensitivity has no effects on stick outcome

 Slide your finger to bottom side of the screen, the copter will start move backward. Double tap to stop moving.





the screen, the copter will start the screen, the copter will start screen, the copter will start hovering.

• Slide your finger to left side of • Slide your finger to right side of • Double tap any place of the

## 7-4. Gravity Sensor Mode (Optional in Menu)

move forward in the left direction. move forward in the right direction

Double tap to stop moving. Double tap to stop moving.

Long press, the copter will start ascend. When release, the copter will stop ascending, and starts hovering. Long press, the copter will turn right. When release, the copter will stay.

> Long press, the copter will start descend. When release, the copter will stay Long press, the copter will turn left. When release, the copter will stay.





. Press any place on the right side of the . Press any place on the right side of the screen screen; tilt the mobile forward, the copter will tilt the mobile backward, the copter will move move forward.



move forward in the right direction.







• Outdoor Mode: Press and hold "HOME" button, the copter will fly back near its

Indoor Mode: Operate manually to fly the copter back.

# Landing

off throttle).

• Force landing: When emergency occurs, press and hold 'CUT OFF' button, the motors will stop immediately (Volume key of Android phones can be pressed to cut

 Landing: Descend manually the copter until it lands safely on the ground. Long press 'CUT OFF' button to stop the motors.