

AGES UP
14+

6-Axis Gyro Remote Control Series

X33 / X33B

4 Channel Folding Drone

2.4GHZ



OPERATING MANUAL

MAIN CHARACTER

- Using specially-made plastic fuselage, good toughness, high shock resistance, stable flight, it suited to play on indoor or outdoor.
- Built-in 6-axis gyro stabilizer, to ensure precise localization in the air.
- Using modularly structure, easy to install and maintain.
- Disassembly structure, various functionality. It can rotate and aerial shots.

The material, specification, component packing inside of the manual are for your information. Our company is not be responsible for manual body of the print. And we are not taking the initiative to inform consumers of any updates or changes.

Safety cautions

1 Important announcement

(1)The product is a sophisticated equipment integrates the expertise of mechanics, electronics, aeromechanics, high frequency transmitter, etc. It should be assemble and debug exactly to avoid the accidents. The owner of this product should operate it in safety way. If operate improperly, it may cause serious bodily injury and property damage. We do not assume responsibility, because we could not control the process of their assembling, using and operating.

(2)The product apply to the crowd have experience of operating model and above the age of 14.

(3)The place for flight should be legal of location to handle remote control model, such as air line, high-voltage wire etc.

(4)Product once sold, we are not responsible for safety duty cause byoperation, using, handling, etc.

(5)If you have questions of using, operating or maintaining, please contact to local authorized dealer, they will provide technical assistance and service.

2 Safety Caution

RC quad copter model is a high-risk of goods, you must be sure to keep away from crowd when in flight. Artificial assemble improper or body damaged, poor electronic equipment, and unfamiliar operation, it possible to cause unpredictable accident of quad copter damaged or personal injury, etc. Please pay attention to safety, and take responsibility of your negligence.

(1)Keep away from barrier and crowd. It has uncertain flight speed and state when the RC quad copter is flying. When in flight, please keep away from crowd, high building, high-tension wire. At the same time, avoid to flight in the storm and thunder. To make sure the safety of pilot, crowd and property.

(2)Keep away from humid conditions. The quad copter is consist of many precision electronic components and mechanical parts, so it must prevent moisture into the quad copter body. In case of an accident cause by malfunction of the body or electronic components.

(3)Safety operate. According your status and flight skill to control the quad copter. Fatigue, mental poor or improper operation, will increase the probability of an accident risk. When you tired and out of sorts or improper handling, it will increase the risk of accidents.

(4)Keep away from high-speed rotary parts. When the propeller at high speed rotating, the pilot, crowd or other object should keep away from the rotating part for fear of causing the risk and damage.

(5)Keep away from heat. The RC quad copter is be made up of metal, fiber, plastic and electronic components. Therefore, it should be keep away from heat and keep off the sun for longtime, avoid the heat set off deformation of the shape even damage.

3: Preflight notice

(1)Flying environment should be an open space. The recommendation of the space is more than 8M(width) x 8M(length) x 5M(high).

(2)Make sure the power state of batteries for transmitter and receiver is full.

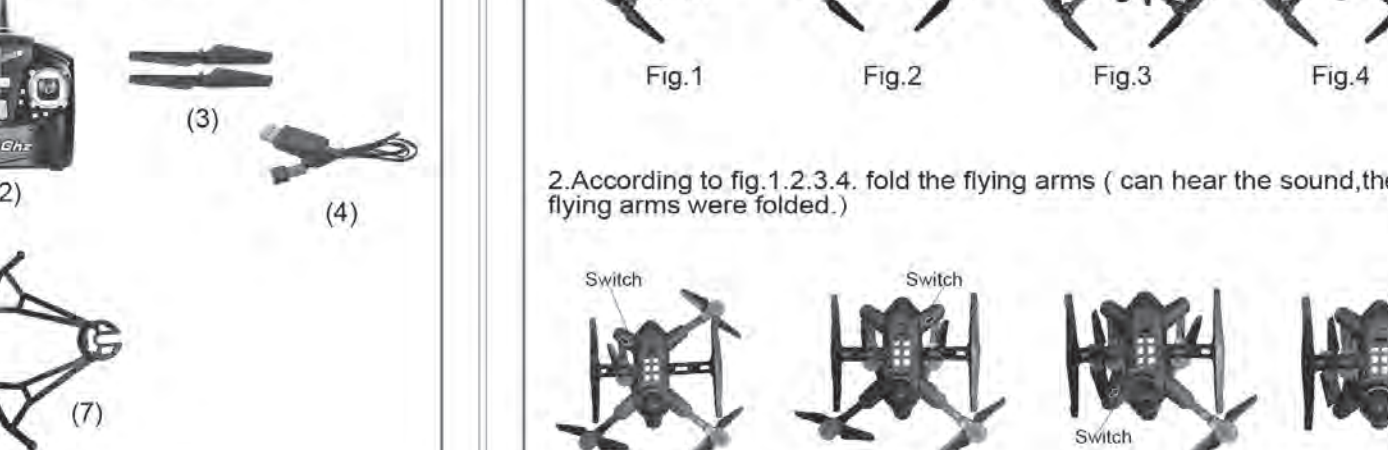
(3)To ensure the throttle stick and throttle trim of the transmitter is on the lowest position.

(4)In starting up, you must be comply with order of power on and off. When starting up, you should be open the power of the quad copter first, then open the power of transmitter. When power off, you should be cut off the power of the quad copter, then turn down the transmitter. Incorrect order of power on and off may cause the quad copter out of control, and affect the safety of others. Please make a habit for correct turn on or shut off.

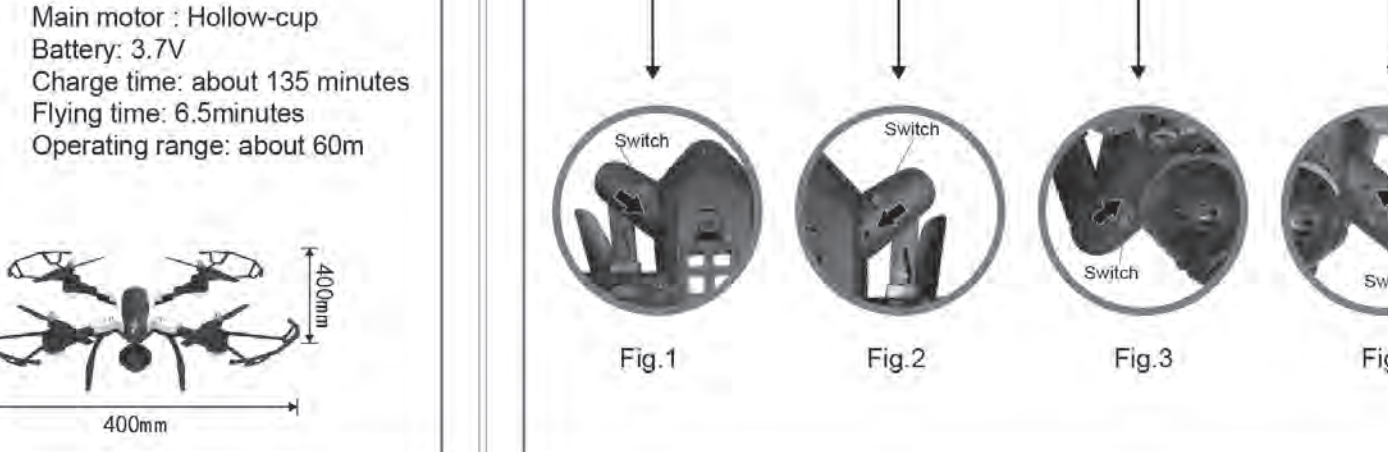
(5)To confirm the junctions of the battery and motor or other components are tight. The shock in flying will make the junction of power loose, then cause the quad copter out of control.

Packing instruction

Production packing included as follow:(1)Quad copter (2)Controller (3)Main blade (4)USB line (5)Screw driver (6)Stand (7)Blade cove



Main parameter

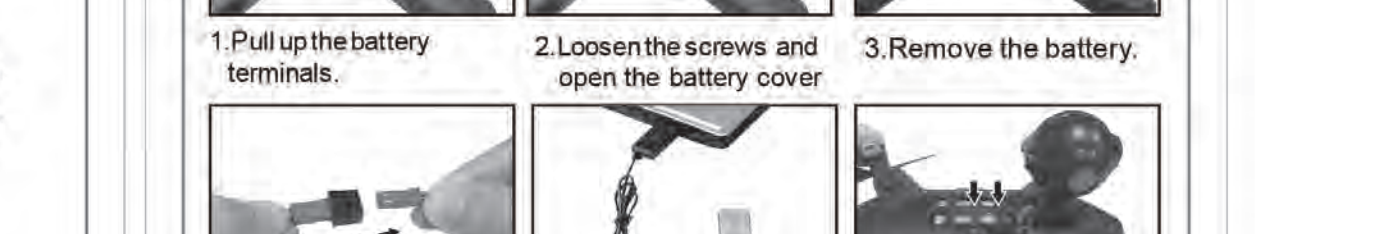


Tips for low tension

When the copter is flying to 6 minutes, and all the lights of the fuselage are glistering. It means the copter is in low tension. (In low tension, prohibit flipping)

Folding version operation

1. According to 1.2.3.4. open the flying arm (can hear the sound, then the flying arms were opened.)



2. According to fig.1.2.3.4. fold the flying arms (can hear the sound, then the flying arms were folded.)



Method for changing and charging battery of quad copter

1. Pull up the battery terminals.

2. Loosen the screws and open the battery cover

3. Remove the battery.

4. The USB plunge plug to the power connector.

5. Insert the USB charging port into the computer for charging. (The light is off when charging. After charge full, the light is on)

6. Close the battery cover and lock screw

7. The USB plunge plug to the power connector.

8. The USB plunge plug to the power connector.

9. The USB plunge plug to the power connector.

10. The USB plunge plug to the power connector.

Level calibration and trim reset

1. Quad copter level calibration

When the quad copter after take-off can not be corrected by fine-tuning, lead to the quad copter hovering is operating difficultly, follow these steps to calibrate the quad copter:

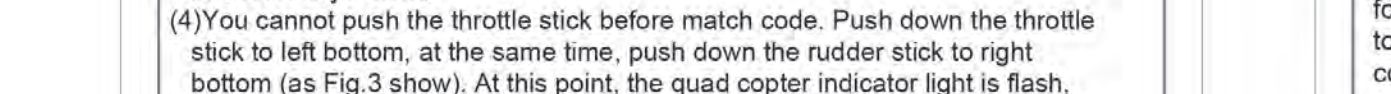
(1)Pull out the power of quad copter firstly, then tune off the switch of the transmitter.

(2)Connect to the quad copter power supply, open the power switch, and put it on the horizontal plane, the lights of fuselage flashing.

(3)To open the transmitter power switch, push up the throttle stick to the peak position, then push down to the lowest position (as Fig1 & Fig2).

you will hear a sound "di", it means the quad copter succeed to match code, and the lights of the fuselage will always on. At this time the transmitter get into level adjustment.

(4)You cannot push the throttle stick before match code. Push down the throttle stick to left bottom, at the same time, push down the rudder stick to right bottom (as Fig.3 show). At this point, the quad copter indicator light is flash, it is calibrating. Till the indicator light is always on, it completed. It will at normal flight.

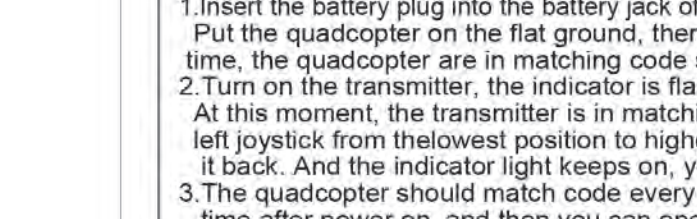


Operating direction

Ascent/Descend control



Turn left/right control



Forward/Backward control



Left or Right side flight control

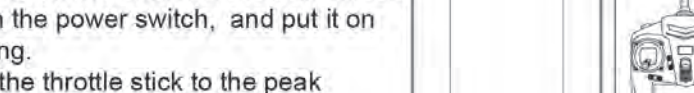


Headless mode

Headless mode

Once the quad-copter is paired with the transmitter, press the headless mode button to enter headless mode. The transmitter will beep continuously.

Pressing the headless mode button again will turn off headless mode. (Headless mode can only be entered prior to take off. If you attempt to enter after take off, the copter will be misdirected or unable to fly.)



Prepare for take off

1. Insert the battery plug into the battery jack of the quadcopter, open the power switch, Put the quadcopter on the flat ground, then the indicator light is flash fast. In this time, the quadcopter are in matching code status.

2. Turn on the transmitter, the indicator is flash with "di" sound. At this moment, the transmitter is in matching code status. Pull up the left joystick from the lowest position to highest position, then pull it back. And the indicator light keeps on, you can operate.

3. The quadcopter should match code every time after power on, and then you can operate.

4. Every time you turn on or off the transmitter, the quadcopter need to re-open, and they should match code again.

5. The quadcopter should match code every time after power on, and then you can operate.

6. The quadcopter should match code every time after power on, and then you can operate.

7. The quadcopter should match code every time after power on, and then you can operate.

8. The quadcopter should match code every time after power on, and then you can operate.

9. The quadcopter should match code every time after power on, and then you can operate.

10. The quadcopter should match code every time after power on, and then you can operate.

Fine-tuning operation

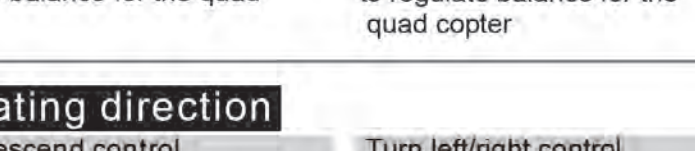
forward/backward fine tuning control

When the quad copter in forward or backward flight, multitouch the forward backward fine-tune key, to regulate balance for the quad copter



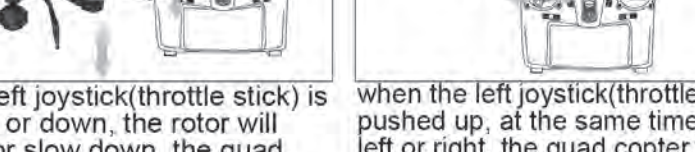
left/right side flight fine tuning control

When the quad copter side fight to left or right, multitouch the left/right side flight fine-tune key, to regulate balance for the quad copter



3D rotate operation

When the quad copter flying, press rotate key, it have the "di" "di" sound. Push right joystick, the quad copter will rotate around (forward/backward/ left/ right). Press rotate key again to exit rotate operation.



The way to install the camera for X33B

1. Put the camera on it. Fig 1

2. Use screwdriver to screw loose and open the battery cover. Fig 2

3. Insert the 3 wire plug into the main socket. Fig3

4. Cover on the battery cover, screw tight. Fig4

5. Turn on the power of the quad copter, the blue light of the camera is always on and red light is out. It show that the camera is in normal working state. When the blue light is always on and the red light is flash, it meant that the SD card does not access.

6. Photograph: When the camera is in normal working state, press photograph key, "Di" is heard and the red light of the camera is flashed. It meant the photograph is completed.

7. Video :When the camera is in normal operating state, press the Video key, "Di" is heard and the red light is always is heard and the red light is out, it is finished.

8. The quadcopter should match code every time after power on, and then you can operate.

9. The quadcopter should match code every time after power on, and then you can operate.

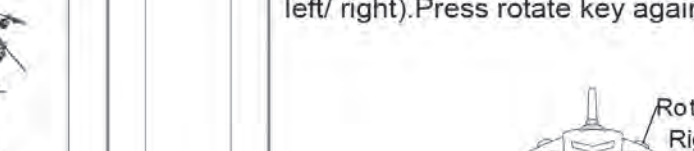
10. The quadcopter should match code every time after power on, and then you can operate.

11. The quadcopter should match code every time after power on, and then you can operate.

Tossing action instructions

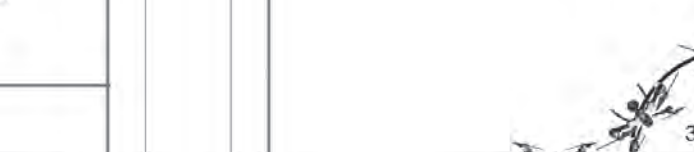
Aircraft using six-axis gyroscope, play ability stronger. The aircraft throw out or turned upward while pushing the operating lever, the aircraft can be smooth blanket the sky.

(Tossing function works only for the quad copter after matching code, and stop operating)



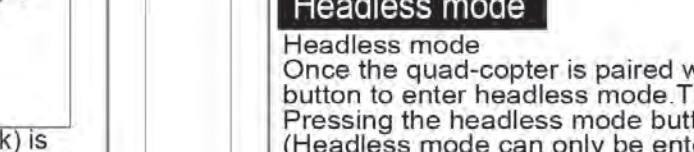
Aircraft stand installation step

Put the stand into body as Fig 1 showed.



Aircraft blade cover installation step

1. Pull up the blade cover.



Troubleshooting guide

Problem: The indicator of transmitter doesn't works

Cause: Install the batteries but doesn't follow the right polarity. Batteries are drained.

Solution: Check and make sure that the batteries are installed by the right polarity. Install new batteries.

Problem: No control

Cause: Transmitter's antenna is not screwed in place and/or is not fully extended.

Solution: Ensure that the antenna is screwed into the controller and fully extended.

Problem: Copter is not flying high enough

Cause: Rotor speed is too slow. Copter is not fully charged.

Solution: Pushing up the left stick(throttle stick). Fully charge your Copter.

Accessories

X33-01 Main cover parts

X33-02 Bottom cover parts

X33-03 Land gear

X33-04 Blade cover

X33-05 AB Blade

X33-06 Motor seat cover

X33-07 Principal axis Wind blade tooth

X33-08 Lampshade

X33-09 Blade cap

X33-10 Gear cover

X33-11 Positive rotate motor

X33-12 Reversal Rotate motor

X33-13 Head light of body

X33-14 Rail light of body

X33-15 Receiver board

X33-16 3.7V battery

X33-17 USB charger

X33-18 Camera parts (Additional purchase)

X33-19 Transmitter

X33-20 Emitter board

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