

rod

*Ainstall blades: Hold the head to aim at the motor axis and press down to lock. Be careful not to damage or deform the blades.

10.SAFETY PRECAUTIONS

advoiding demage due to impact person or things.

@Leave away from mostute or thest source
The interior of an aircraft is made up of a number of sophisticated electronic
components, so it must be protected from moisture or moisture as well as high
temperature storms. Dying and so on.

easy he e as ess ction

(a)Lithium battery safety It is strictly prohibited to use the lithium battery outside the factory to filly, the It is strictly prohibited to use the lithium battery used by different manufacturers is very different as one to cause damage to the aircraft electronic components and personal safety and other dangerous. It is strictly prohibited to use the original battery charger for charging, so as to avoid short circuit, expansion, deformation, or even fire, explosion and other

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ngerous. Explosion and other dangerous

11.TROUBLE SHOOTING

Unable to take off	Failed flips	The quadcopter did not respond	Problem
The blade is assembled wrong. Blade impact deformation Quadcopter LED flashes	Improper operation Quadcopter LED flashes	Singal matching failed. Quadcopter or transmitter low voltage	Reason
Checking the instruction manual of installing blades Righting blades or replace blades The low-voltage protection, re-charge to quadcopter	Checking the instruction manual again The battery of quadcopter is power off. Charging again.	Re-matching again. Replace the transmitter batteries Re-charge to quadcopter	Solution

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**Please keep the battery with 50% power for extending the operating life of the battery if do no use the product for a long time. Half of the battery fully charge time could keep the battery with 50% power.

4.START/OFF STEPS

4.1 Start Steps

When the quadcopter flies defected from crash, and could not fly well by all calibration, please reset it as below:

①Press down the button at controller's top right corner,

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controller with a beep.

5.2 Reset Step

**A*After tuning, press down the button at the top right corner on the controller, with a beep, to quit tunning mode. Or do not move the right rod for three seconds to quit tuning mode automatically.

STurn on the quadcopter (the white indicator under protection frame light on, other four LED indicatos will flash), put quadcopter on a flat place.

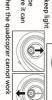
©Turn on controller (controller with beeps and wait the red LED indicator change from flashing to keep light on).

@Push the left rod completely forward and the controller will a beep, then pull it back completely and controller with a beep again. The flour indicators of quadcopter will keep light on. Now quadcopter and controller are paired.

@Upon pairing, place the quadcopter on the ground plane, rotate the control rod of direction one circle clockwise. The red LED indicators of quadcopter shall be flashing, means the gyro is calibrated and scanned for locking the location.



**Before flying, the quadcopter must be calibrated on the ground plane to ensure it can LED lights stop flashing and change to keep light on means calibration finished. ★★The same operation can be made when the quadcopter cannot work



5.OPERATING AND CONTROL A2 Stop Fly Step Pull the accelerator to the lowest position and keep seconds to landing quadcopter on the ground, then blades stop rotating. Then turn off the power both controller and quadcopter.

5.1 Trimming

Press down the key at top right corner with a beep into the fine-tuning mode

* If the quadcopter stews forward, it shall be adjusted by pulling backward the right rod on the transmitter, the quadcopter's back two LED indicators are flashing, it shall be adjusted by # If the quadcopter stews backward, it shall be adjusted by pushing forward the right rod on the transmitter, the quadcopter's forward LED indicators are flashing.

*If the quadcopter stews influenced, it shall be adjusted by pulling influenced the right rod on the transmitter, the quadcopter's right two LED indicators are flashing, wiff the quadcopter stews influenced it shall be adjusted by pulling leftward the right rod on the transmitter, the quadcopter's left two LED indicators are flashing.

During flying time, press the button in upper left corner, controller with a beep, quadcopter start high-speed top spinning then spin as tornado. It's better to adjust the height during spinning.

5.5 Top Spinning

accordingly.

5.3 Speed Switch ©Than turn the right rod a round clockwise. Quadcopter's four red LED indicators change from flashing to light on, means gyro calibration and controller reset are finished. Now the quadcopter also finish reset.

for the beginners, it is better to move the acceleration very slow in case the drone out of control and cause damage. 5.4 Basic Motion Operations as 100% speed 0 Ascend







Push the right lever (direction), up and down. Push the right lever (direction),leftward the quadcopter will go forward and backward and rightward, the quadcopter will go accordingly.







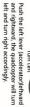




6.2 Rightward flip Press down the right lever, with a beep, push the lever rightward, the quadcopter















6.1 Leftward flip







When press the same button again, after a beep, quadcopter stop high-speed top spinning. Then press one time, quadcopter do high-speed top spinning one time.

6.FLIPS



on the head or the

Press down the right lever, with a beep, into flip mode. Than keep press it down and pull to forward, backward, leftward or rightward to flip the quadcopter to the same direction.

will be easy to keep the height after flips.

In order to get better playing, please keep 1.5m height and ascend, this

Press down the right lever, with a beep, push the lever leftward, the quadcopter will flip one circle leftward. •









Press down the right lever, with a beep, pull the lever backward, the quadcopter will flip one circle backward.

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6.4 Backward flip

circle forward

Press down the right lever, with a beep, push the lever forward, the quadcopter will flip one

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6.3 Forward flip will flip one circle rightward





This device compiles with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.