

WaRP7: The IoT and Wearable Development Platform

Hardware UserManual

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1. Introduction

1.1 PlatformPurpose

The WaRP7 is the next generation Internet of Things (IoT) and Wearable's Reference Platform. WaRP7 is a powerful, low-cost platform designed for rapid prototyping and reduces time to market. WaRP7 is optimized, comes in a tiny form factor and yet flexible enough to offer all the advantages of traditional development tools. It has been architected and designed from the ground up to address key challenges in the IoT and wearables markets, such as battery life, connectivity, user experience and miniaturization. WaRP7 is based on the NXP i.MX 7Solo applications processor that features an advanced implementation of the ARM® Cortex®-A7 core, as well as the ARM® Cortex®-M4 core. It comes with features such as on-board sensors, connectivity including NFC, Bluetooth®, Bluetooth Smart and Wi-Fi® and on-board external LPDDR3 memory.

This document is intended as an introduction to the WaRP7 CPU Board and IO Board hardware and focuses primarily on its initial setup and basic usage.

1.2 Kit Contents

In the box you will find the following items as shown in **Figure1**.

- WaRP7 CPU Board
- WaRP7 IO Board
- Lithium Polymer Battery
- Quick StartGuide.

The display for the kit can be purchased separately (*details coming soon*). Check for availability at www.element14.com/warp7



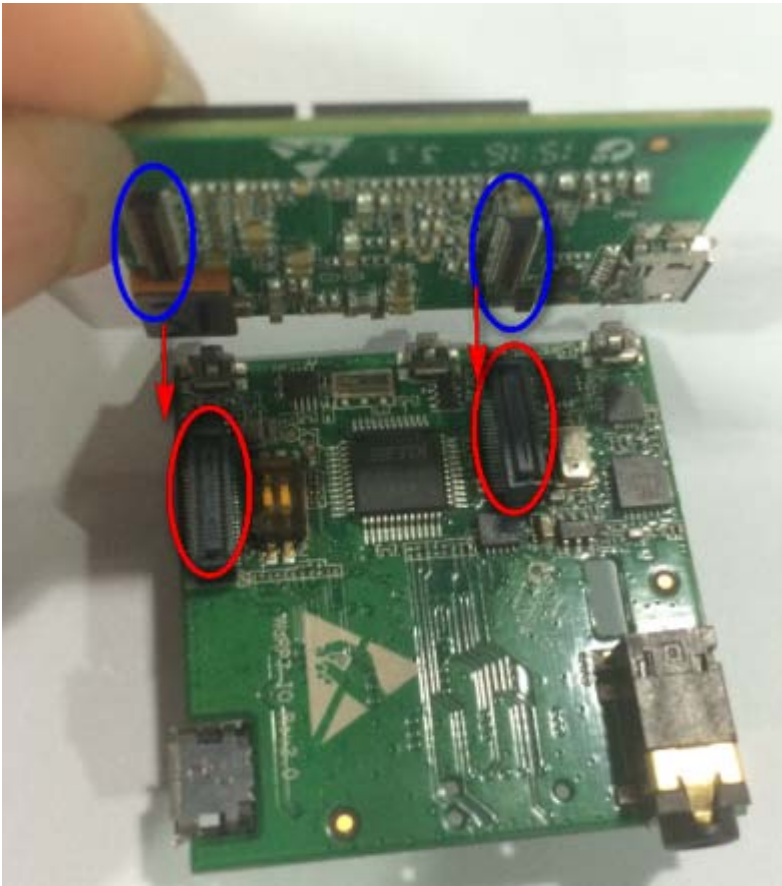
Figure 1 WaRP7

1.2.1 Getting Started with Hardware

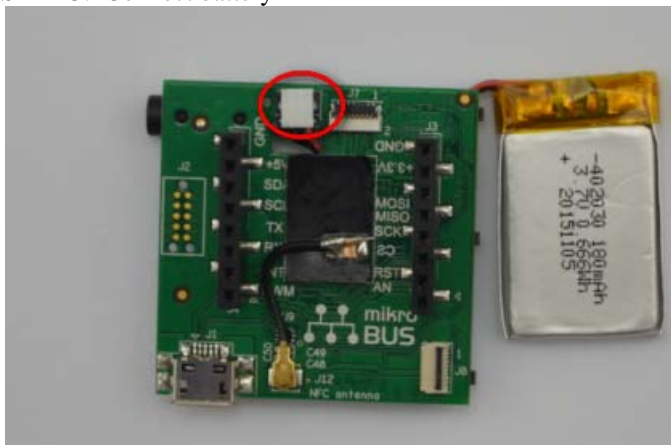
- STEP 1: Connect NFC cables to IO board

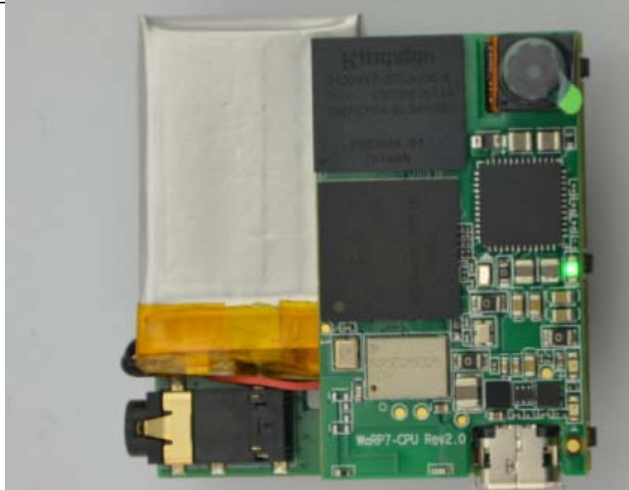


- STEP 2: Connect CPU board

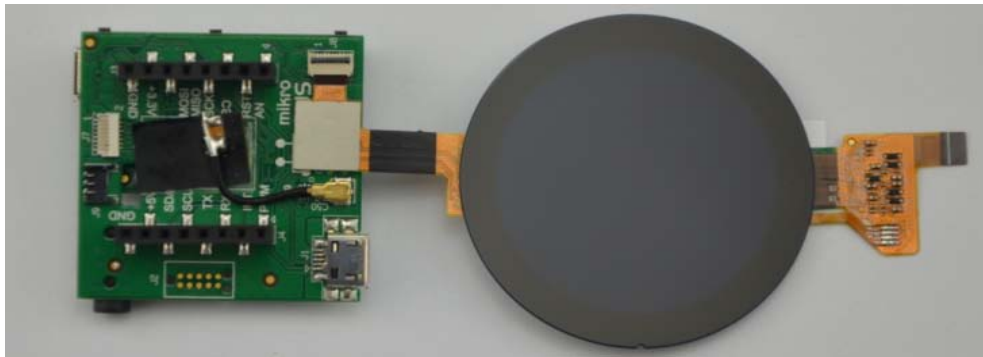


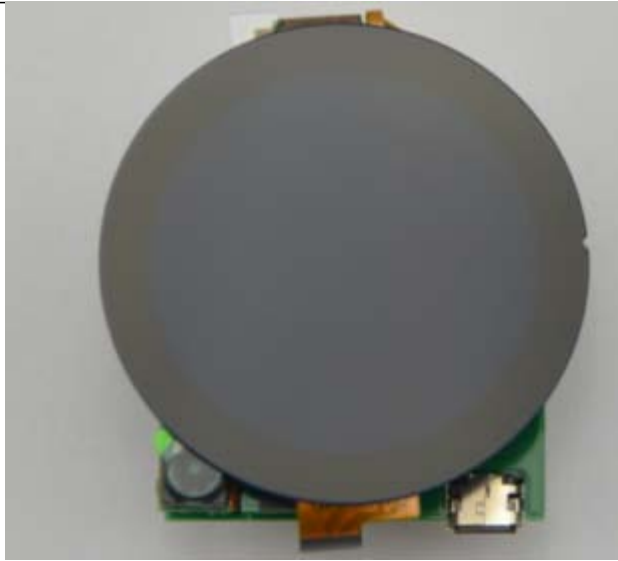
- STEP 3: Connect battery





- STEP 4: Connect LCD





Connect USB



Figure 2 WaRP7 connected

2 WaRP7 Hardware Overview

The WaRP7 is the next generation Wearable's Reference Platform based on the NXP iMX7 Solo applications processor.

The kit consists of 2 boards

- A **CPU board** featuring the ARM Cortex-A7 based iMX7 processor, memory, power management and a combo WiFi/BLE module.
- An **IO board** which provides interface to variety of sensors, expansion and debugging capabilities.

2.1 Features/Specifications

Features		
CPUBoard		
Processor Memory PMIC Wireless Display/Camera interface	NXP iMX7S ARM Cortex-A7/Cortex-M4	
	8GB, 8bit Embedded MMC/512MB LPDDR3	
	PF3000 PMIC and BC3770 battery charger.	
	Combo WiFi/BLE	
	MIPI-DSI connector MIPI-CSI connector	
Power Source	USB/Battery	
PCB	38mm x 23mm	10 layers
Indicators	1-Power, 1-User	
IOBoard		
Debug Support	JTAG, Serial Header	
Sensors	Accelerometer, Magnetometer Pressure Sensor Gyroscope	
Audio	Stereo codec-Mic In/Line Out	
Expansion	MikroE Click header	

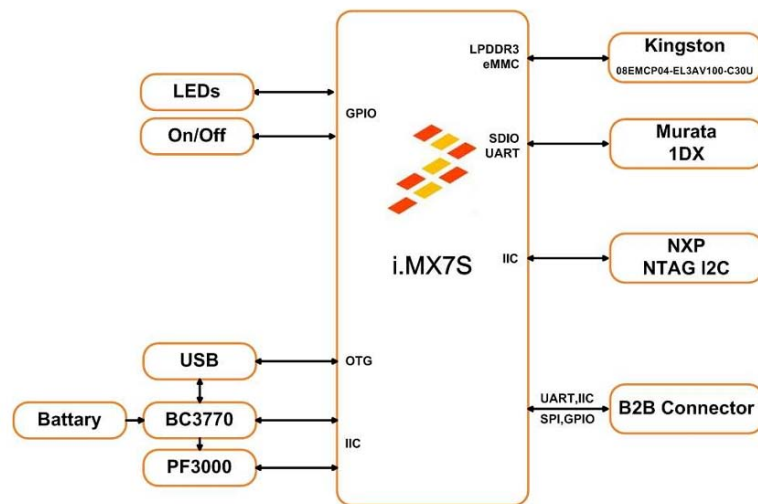


Figure 3 CPU Board

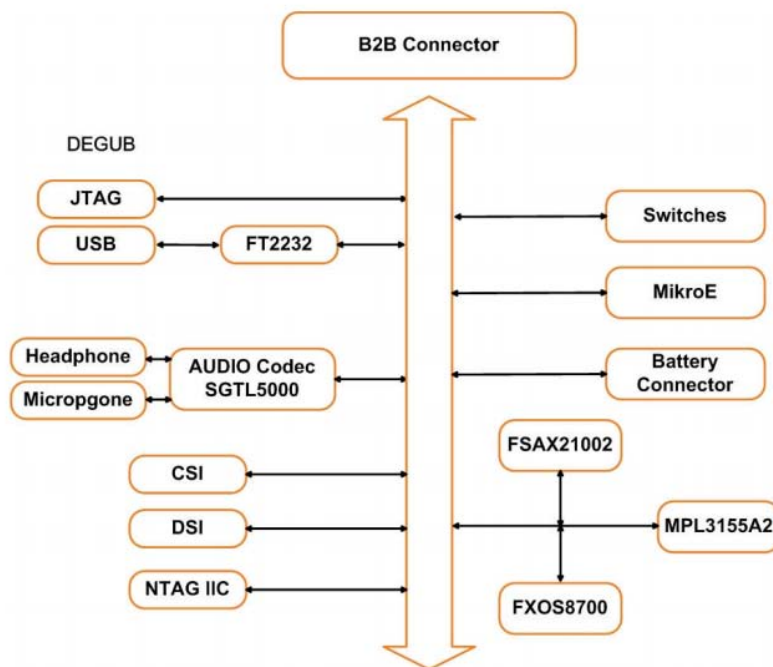
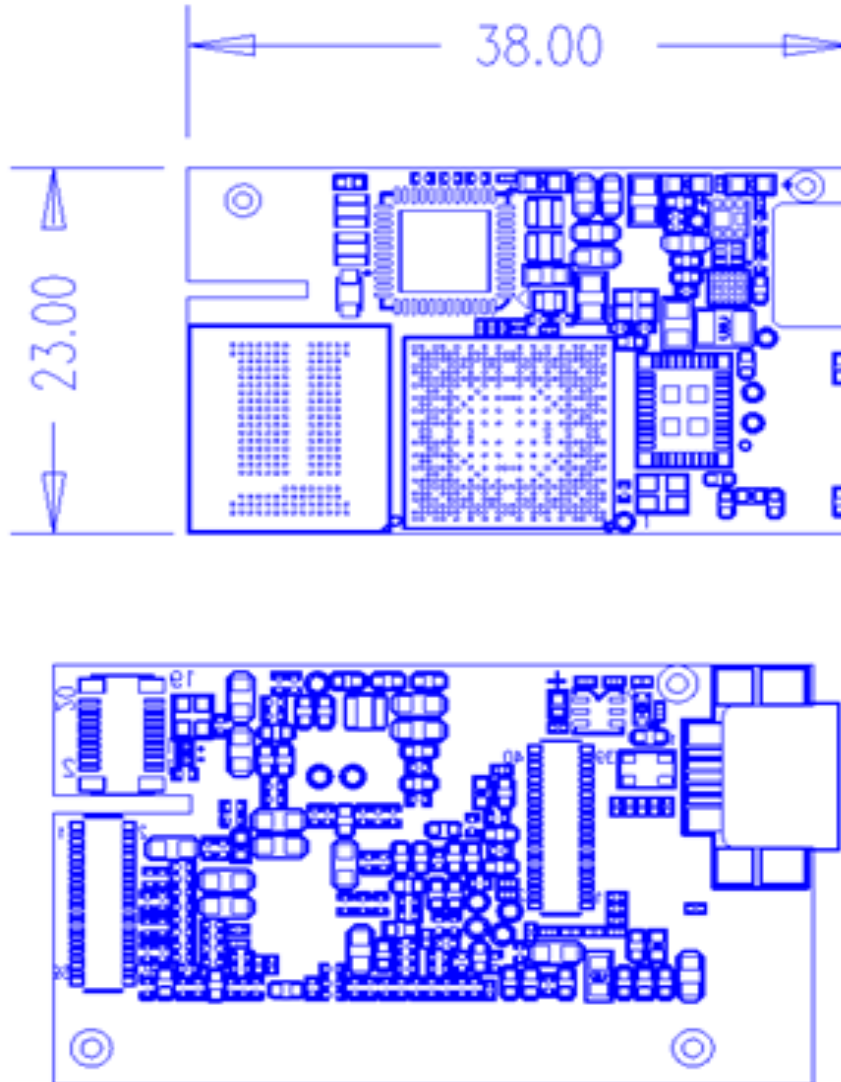


Figure 4 IO Board

2.2 BoardDimensionandOperatingEnvironment

Table1WaRP7CPU BoardDimensions

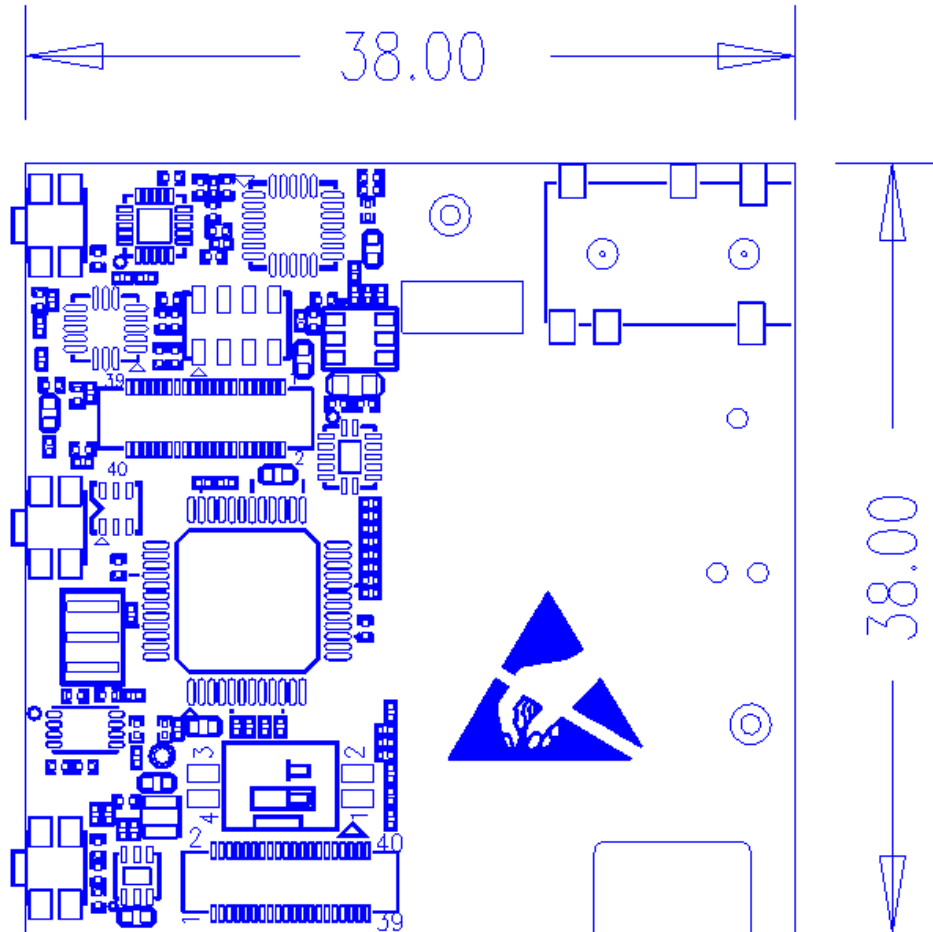
Length	38mm
Width	23mm
PCBThickness	1.0mm



The board operates in the commercial temperature range, 0°C~85°C

Table2 WaRP7 IO Board Dimensions

Length	38mm
Width	38mm
PCBThickness	1.0mm



3 Hardware Overview

3.1 CPUBoard

3.1.1 CPU

Main Processor: NXP MCIMX7S3DVK08SA -i.MX7S with 12mmx12mm MAPBGA, 0.4mm

The i.MX7S applications processor houses an ARM Cortex-A7 core and an ARM Cortex-M4. The device is targeted for IoT, Wearable and general embedded markets.

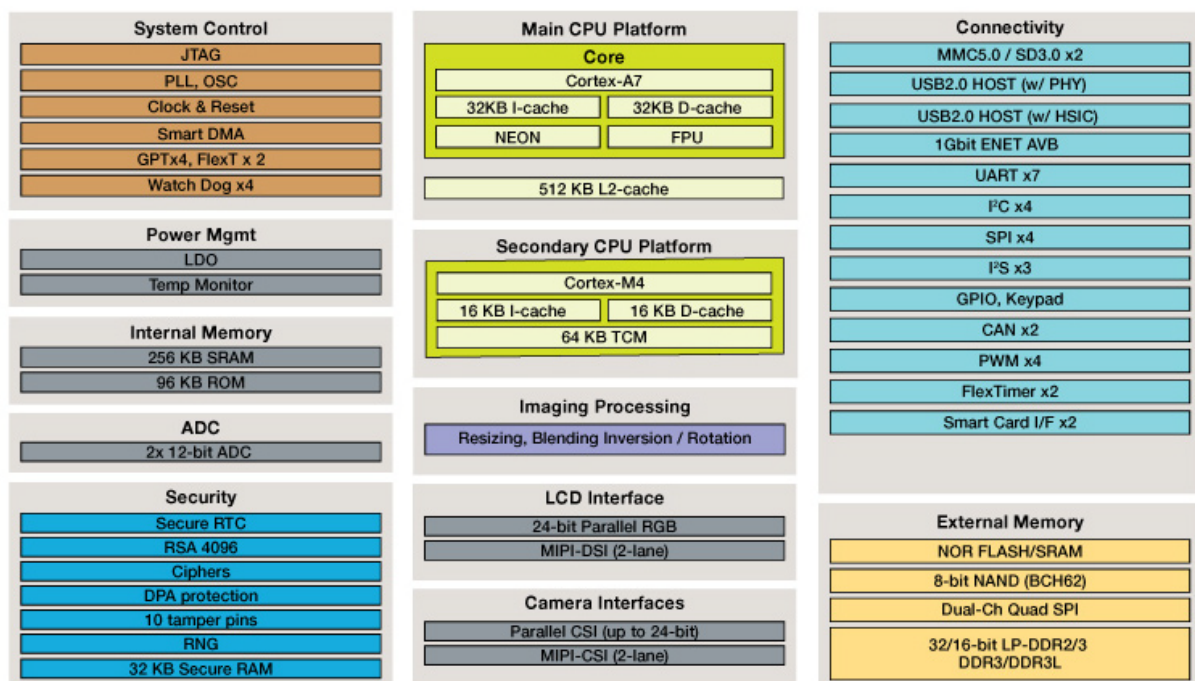


Figure 5 iMX7S SoC Diagram

3.1.2 MemoryeMCP-LPDDR3andMMC

The CPU Board features a Multi-Chip Package Memory08EMCP04-EL3AV100-C30U from Kingston which combines 8GBeMMC and 512MB Low Power DDR3 synchronous dynamic RAM. This comes in 221-ballFBGA package.

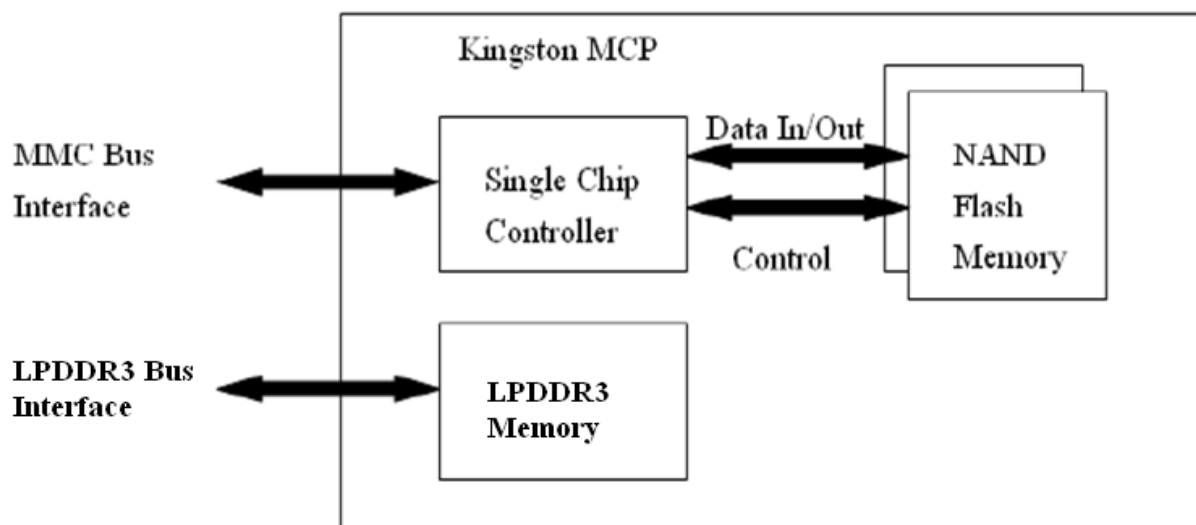


Figure 6KingStoneMCP Block Diagram

3.1.3 Video and Display

The WaRP7 CPU board provides output video from MIPI-DSI and accepts input through MIPI-CSI

3.1.3.1 MIPI-DSI

The CPU board includes a MIPI-DSI connector for outputting output the video from the i.MX7SMIPI-DSIPHY via the MIPI-DSI interface.

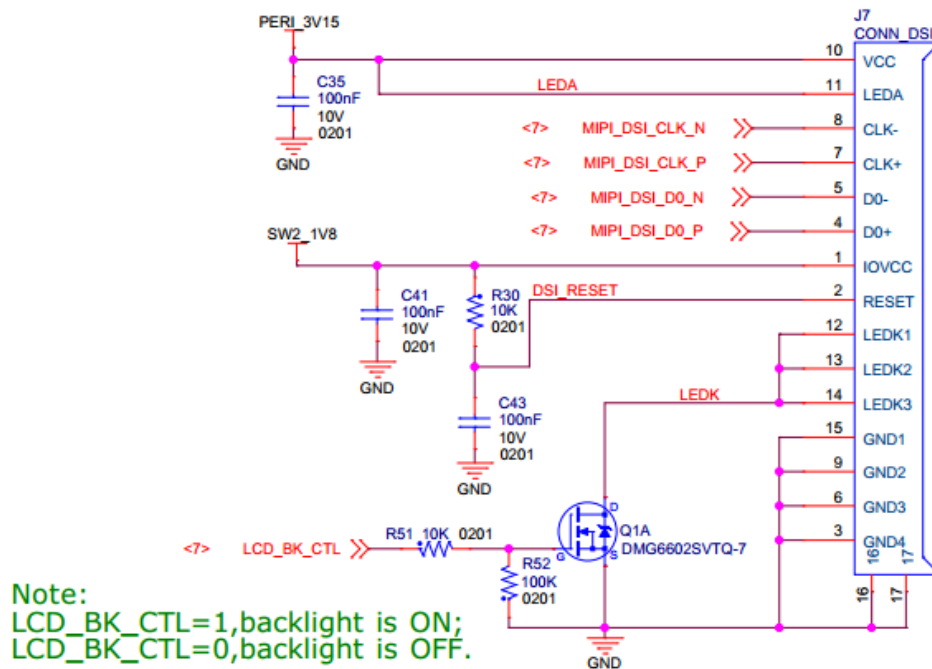


Figure 7MIPI-DSI connector

3.1.3.2 Capacitive Touch Screen

Capacitive touch screen is supported by I2C via touch screen port.

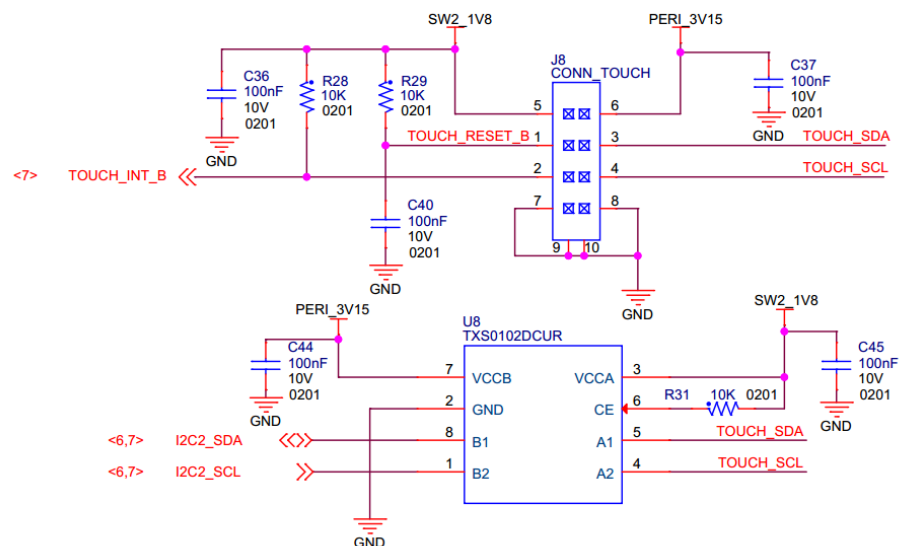
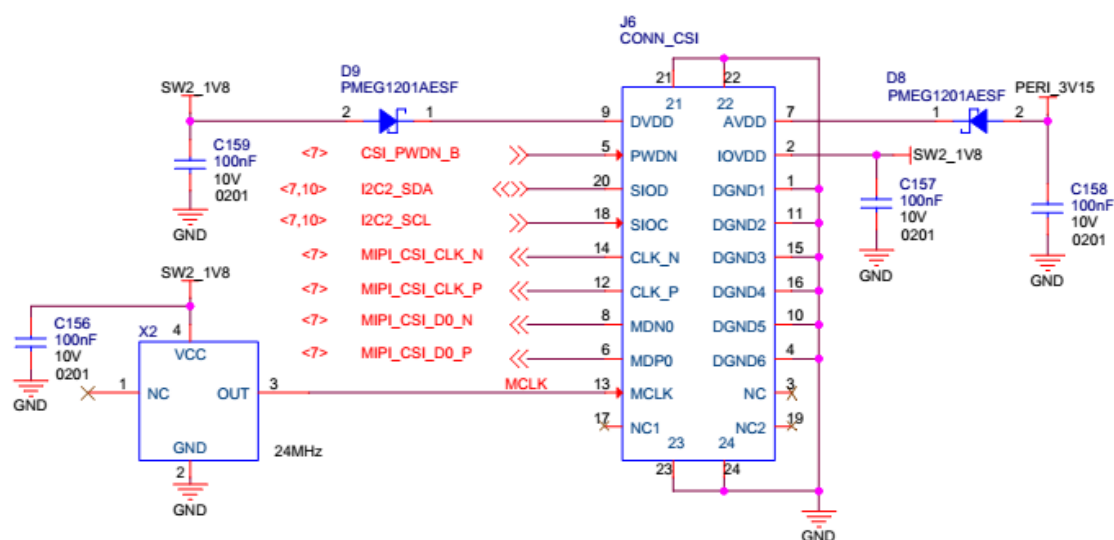


Figure 8 Touch Screen Interface

3.1.3.3 MIPI-CSI

The CPU board includes a MIPI-CSI camera connector for connecting a CSI camera module.



Note: The camera module's IIC address is 0x6C(write), 0x6D(read).

Figure 9 MIPI CSI connector

3.1.4 Connectivity

The WaRP7 board will provide a number of connectivity include Wi-Fi, Bluetooth, Bluetooth(BLE), and USB-OTG. There will be provision for NFC as a passive tag primarily for Bluetooth pairing.

3.1.4.1 Wi-Fi/Bluetooth

The MurataType1DX module is an ultra-small module that includes 2.4GHz WLAN IEEE 802.11b/g/n and Bluetooth Version 4.0 plus EDR functionality. Based on Broadcom BCM4343W, the module provide high-efficiency RF front-end circuits.

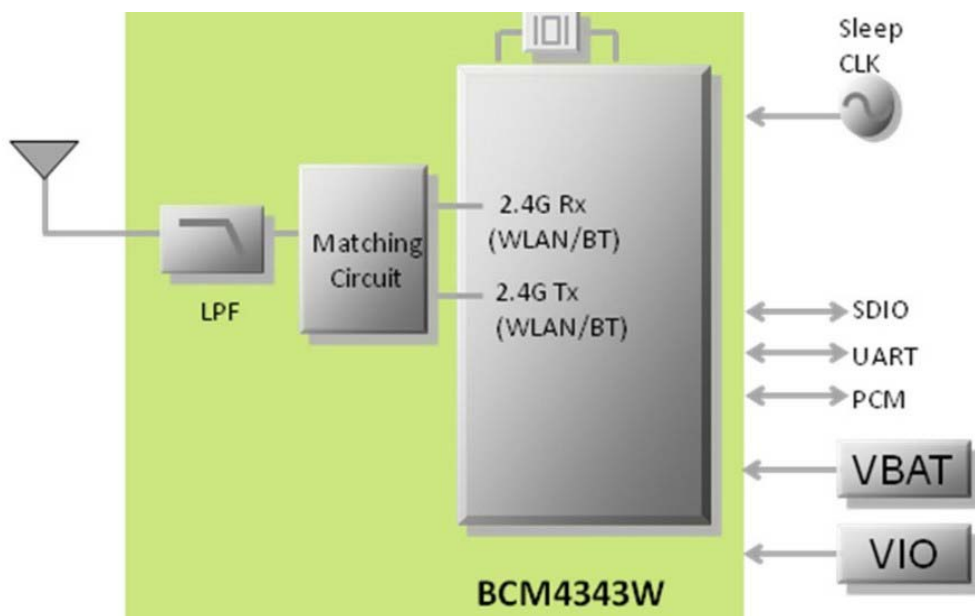


Figure 10 Murata 1DX module

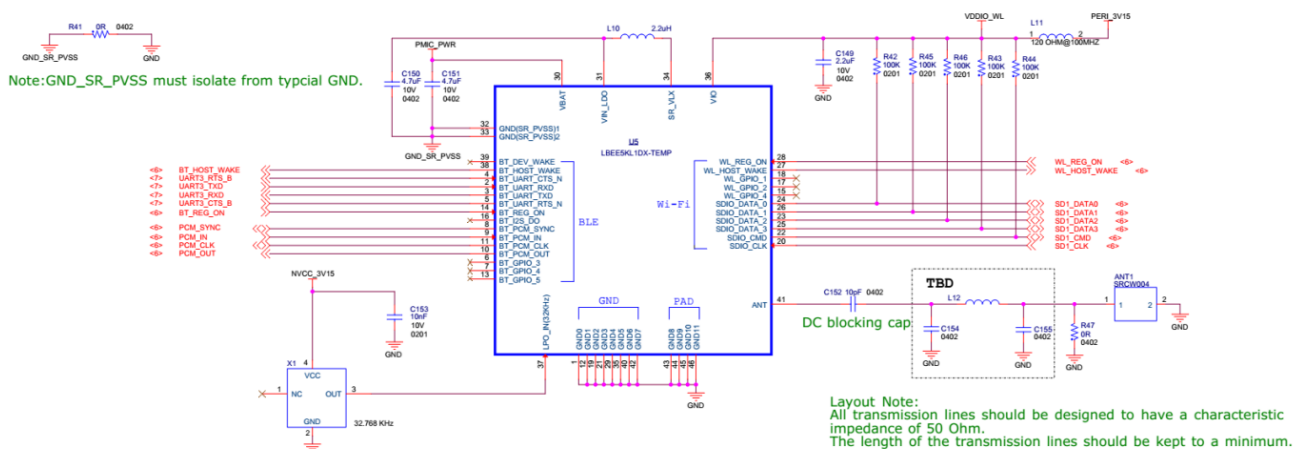


Figure 11 Design implementation of 1DX

3.1.4.2 USB-OTG

The CPU board provides a USB micro-AB connector to support USB-OTG function powered by the USBOTG1 module on i.MX7S.

3.1.4.3 NFC

The board provides support for NFC using the NXPNT3H1101W0FHK. In addition to the passive NFC Forum compliant contact less interface, the IC features an I2C contact interface, which can communicate with i.mx7 ifNTAGI2C is powered from an external power supply. An additional externally powered SRAM mapped into the memory allow safest data transfer between the RF and I2C interfaces and vice versa, without the write cycle limit a tions of the EEPROM memory.

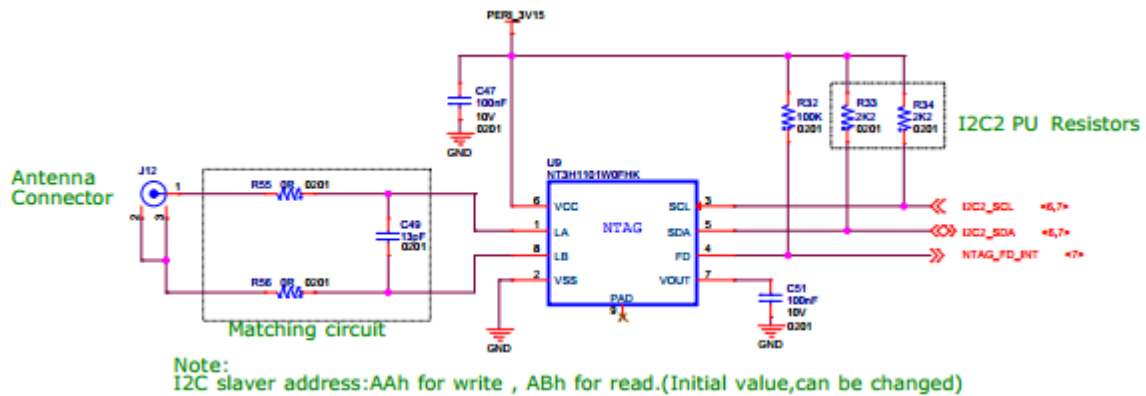


Figure 12NFC circuitry

3.1.5 PowerManagement

3.1.5.1 Power Management IC

The NXPPF3000 power management integrated circuit(PMIC)features a configurable architecture that supports numerous outputs with various current ratings as well as programmable voltage and sequencing. This enables the PF3000 to power the core processor, external memory and peripherals to provide a single-chip system power solution.

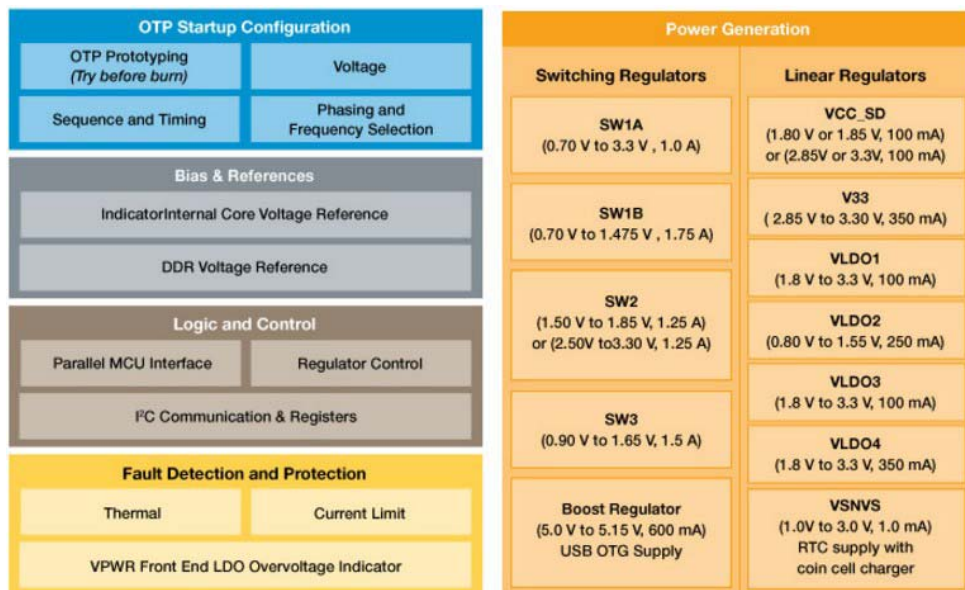


Figure 13PF3000 Functional Block diagram

3.1.5.2 PowerTreeDesign

The usage of PF3000 output is as shown in Table6 below.

Table2PF3000OutputPowerUpSequenceandUsage

PF0300 Channel	Voltage	Powerup sequence	Output Current	i.MX7PowerRail
SW1A	1.15V	1	1000mA	VDD_ARM
SW1B	1.15V	1	1750mA	VDD_SOC
SW2	1.8V	2	1250mA	VDDA_1P8_IN FUSE_FSOURCE VDD_XTAL_1P8 VDD_ADC1_1P8 VDD_ADC2_1P8 VDD_TEMPSENOR_1P8
SW3	1.5V	3	1500mA	NVCC_DRAM NVCC_DRAM_CKE
VSNVS	3.0V	0	1mA	VDD_SNVS_IN
SWBST		-	600mA	
VREFDDR		3	10mA	DRAM_VREF

VLDO1	1.8V	2	100mA	VDD_LPSR_IN
VLDO2	1.2V	-	250mA	
VLDO3	1.8V	2	100mA	NVCC_GPIO1/2
VLDO4	1.8V	-	350mA	
V33	3.15V	2	350mA	NVCC_33VDD_USB_OTG1_3P3_IN VDD_USB_OTG2_3P3_IN
VCC_SD	3.15V	3	100mA	NVCC_SD2

The following i.MX7S power rails must use the internal LDO outputs.

Table3 iMX7S Power Rails–Internal LDO

i.MX7SinternalLDOoutput	i.MX7SPowerRail
VDDD_1P0_CAP	VDD_MIPI_1P0 PCIE_VP PCIE_VP_RX PCIE_VP_TX
VDDA_PHY_1P8	VDDA_MIPI_1P8 PCIE_VPH PCIE_VPH_RX PCIE_VPH_TX
VDD_1P2_CAP	USB_VDD_H_1P2

3.1.5.3 Battery Charger

The NXPBC3770 is a fully programmable switching charger with dual-path output for single-cell Li-Ion and Li-Polymer battery. The dual-path output allows mobile applications with a fully discharged battery to boot up the system.

- High efficiency and switch-mode operation reduces heat dissipation and allows for higher current capability for a given package size
- Single input with a 20V with standing input and charges the battery with an input current up to 2A
- Charging parameters and operating modes are fully programmable over an I2C Interface that operates up to 400kHz
- Highly integrated featuring OVP and Power FETs
- Supports 1.5MHz switching capabilities

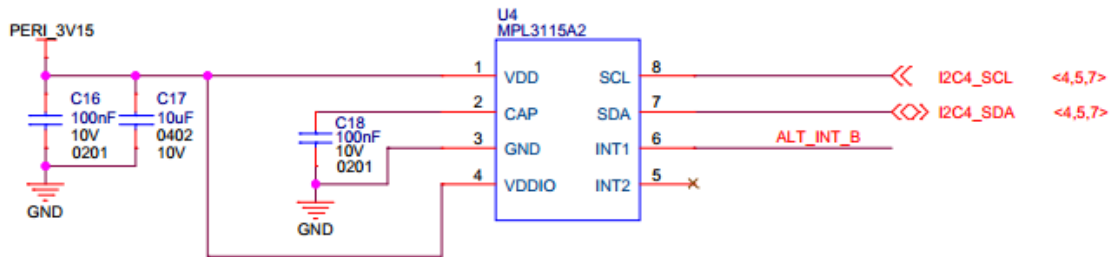


Figure 16 Altimeter schematics

3.2.2.2 Accelerometer and Magnetometer

The board also features FXOS8700CQ 6-axis sensor combines industry-leading 14-bit accelerometer and 16-bit magnetometer sensors in a small 3x3x1.2mm QFN plastic package.

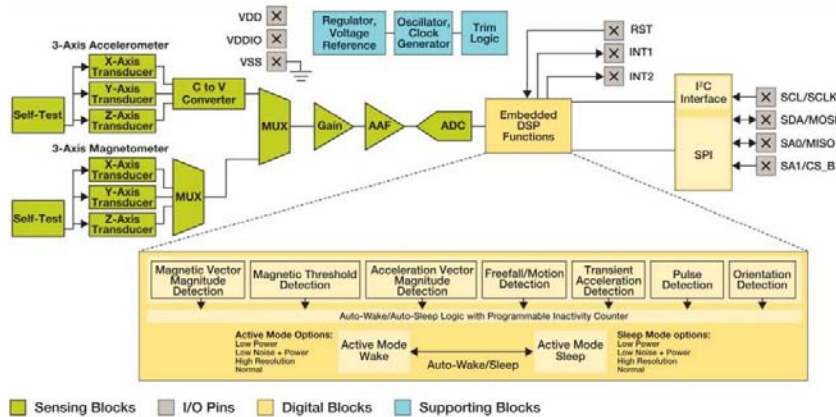


Figure 17 FXOS8700CQ – Accelerometer/Magnetometer Block Diagram

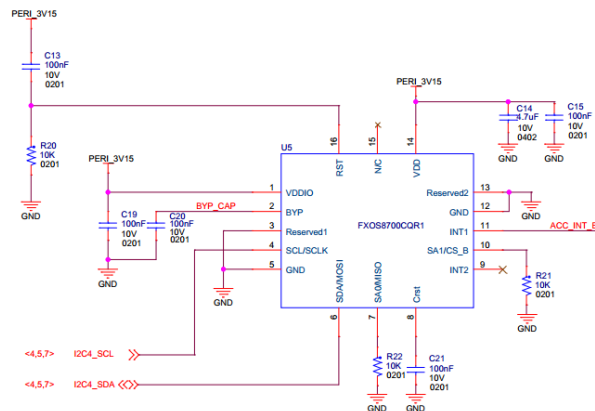


Figure 18 Accelerometer/ Magnetometer schematics

3.2.2.3 Gyroscope

The IO board also features the NXP's 3-axis digital gyroscope- FXAS21002.

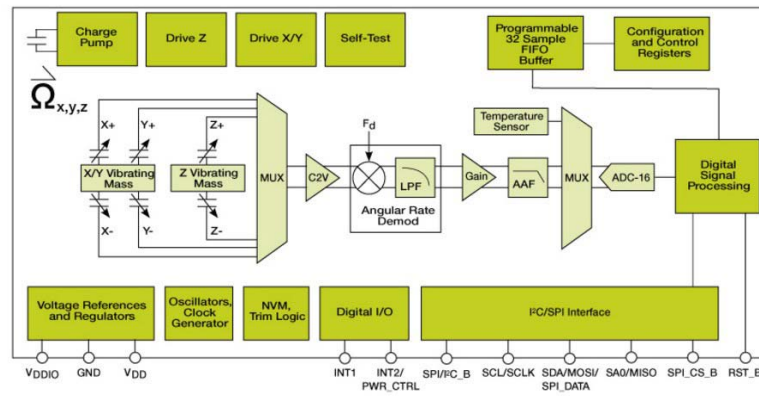


Figure 19 FXAS21002 Gyroscope Block Diagram

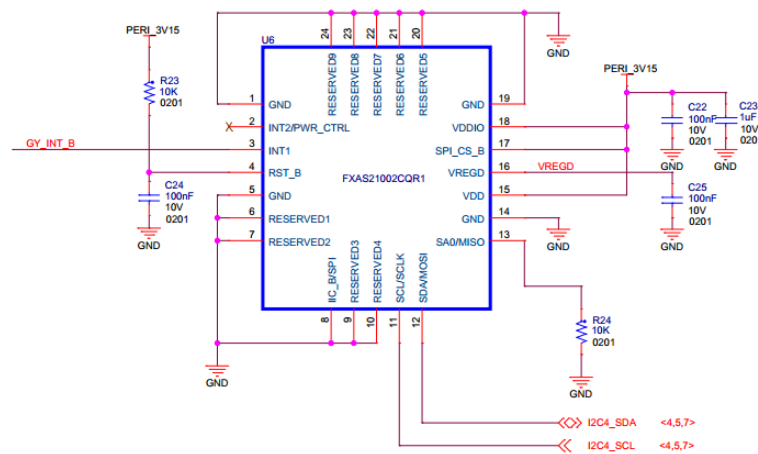


Figure 20 Gyroscope schematics

3.2.3 Peripheral Expansion Port

The board provides expansion headers compatible with the **mikroBUS™** socket connection standard for accessing the following communication modules on i.MX7S:

- I2C
- SPI
- PWM
- UART
- GPIO

FCC Statement

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions: 1) this device may not cause harmful interference, and 2) this device must accept any interference received, including interference that may cause undesired operation.

Note: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. User should avoid un-intended operation of usage when it is collocated with other transmitters or antenna.