## Robot remote control transmitter line description

First, turn the power switch, power—supply lights powered. The rem—ote controller blade swit ch K1 or K2 trigger, the [SCM]] MCU by internal shocks after the transmission of a high clock frequency for the first stage of shock, while single chip MCU sec ond feet—output signal for second level encoding signal amplifier. The amplified signal is transmitted to the corresponding frequency of the robot receiver.