

KDB 865664 D01 SAR Measurement 100MHz to 6GHz FCC 47 CFR part 2 (2.1093)

SAR EVALUATION REPORT

For

Thinking Remote for Home Automation

Model: The NEEO Thinking Remote (6336-REMOTE)

FCC ID: 2AKK7-RM633601

REPORT NUMBER UL-SAR-RP11456397JD17A V3.0 ISSUE DATE: 13 APRIL 2017

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REVISION HISTORY

Issue Date: 13 April 2017

| Ver. | Issue Date | Revisions | Revised By |
|------|---------------|--|--------------|
| 1.0 | 24 March 2017 | Initial Issue | |
| 2.0 | 29 March 2017 | The following amendments were made in the report: 1. Section 1: Additional information included 2. Section 2: Updated 10g SAR limit 3. Section 5: Measurement uncertainty title updated 4. Section 6.3: Updated the table, 6LowPAN target power corrected 5. Section 8.1: Updated conducted power measurements in section 8.1.1 6. Section 10.2: Updated note and table removed 7. Section 12.2: Updated title of system performance plot 8. Section 12.4: calibration certificate included SN3994 9. Section 12.6: Updated the tissue stimulating liquid | Naseer Mirza |
| 3.0 | 13 April 2017 | The following amendments were made in the report: 1. Section 1: Updated the equipment class for 6LowPAN 2. Section 6.1: Typo corrected | Naseer Mirza |

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1. Attestation of Test Results

| Applicant Name: | Neeo AG | Neeo AG | | | | | |
|---|--|------------------------------|-----------------|-------------------------|-------|-----|--|
| Model: | The NEEO Thinl | king Remote (63 | 36-REMOTE) | | | | |
| Test Device is | A representative | A representative test sample | | | | | |
| Device category | Remote controlle | Remote controller | | | | | |
| Date Tested | 03 March 2017 General Population/Localised SAR (Extremity) – 10g SAR limit 4.0 W/kg | | | | | | |
| ICNIRP Guidelines Limits for SAR Exposure Characteristics | | | | | | | |
| The highest reported | RF Exposure Conditions | | Equipment Class | | | | |
| SAR values for Localized SAR | | | Licensed | DTS | U-NII | DSS | |
| Localized OAIX | Standalone | Extremity | N/A | <mark>0.407</mark> W/kg | N/A | N/A | |
| | Simultaneous Transmission Extremity N/A 0.646 W/kg N/A | | | | | | |
| Applicable Standards | FCC 47 CFR part 2 (2.1093) KDB publications IEEE Std 1528-2013 | | | | | | |
| Test Results | Pass | | | | | | |

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UL VS Ltd. tested the above equipment in accordance with the requirements set forth in the above standards. All indications of Pass/Fail in this report are opinions expressed by UL VS Ltd. based on interpretations and/or observations of test results. Measurement Uncertainties are in accordance with the above standard and are published for informational purposes only. The test results show that the equipment tested is capable of demonstrating compliance with the requirements as documented in this report.

Note: The results documented in this report apply only to the tested sample(s), under the conditions and modes of operation as described herein. This document may not be altered or revised in any way unless done so by UL VS Ltd. and all revisions are duly noted in the revisions section. Any alteration of this document not carried out by UL VS Ltd. will constitute fraud and shall nullify the document. This report must not be used by the client to claim product certification, approval, or endorsement by UKAS. This report is written to support regulatory compliance of the applicable standards stated above.

| Approved & Released By: | Prepared By: |
|-------------------------|---------------------|
| M. Masec | futtal |
| Naseer Mirza | Marc Montserrat |
| Project Lead | Laboratory Engineer |
| UL VS Ltd. | UL VS Ltd. |

2. Test Specification, Methods and Procedures

2.1. Test Specification

| Reference: | KDB Publication Number: 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04 | | | |
|------------------|--|--|--|--|
| Title: | SAR Measurement Requirements for 100 MHz to 6 GHz | | | |
| Introduction: | The SAR Measurement procedures for 100MHz to 6GHz are described in this document. Field probes, tissue dielectric properties, SAR scans, measurement accuracy and variability of the measured results are discussed. The field probe and SAR scan requirements are derived from criteria considered in standard IEEE 1528-2013. The wireless product and technology specific procedures in applicable KDB publications are required to be used unless further guidance has been approved by the FCC. | | | |
| Purpose of Test: | To determine if the Equipment Under Test complies with the Specific Absorption Rate for general population/uncontrolled exposure limit of 4.0 W/kg as specified in FCC 47 CFR part 2 (2.1093). | | | |

2.2. Methods and Procedures Reference Documentation

The methods and procedures used were as detailed in:

IEEE 1528:2013

IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communication Devices: Measurement Techniques.

FCC KDB Publication:

KDB 248227 D01 802 11 Wi-Fi SAR v02r02 KDB 447498 D01 General RF Exposure Guidance v06

KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04

KDB 865664 D02 SAR Reporting v01r02

2.3. Definition of Measurement Equipment

The measurement equipment used complied with the requirements of the standards referenced in the methods & procedures section above. Section 4.3 contains a list of the test equipment used.

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3. Facilities and Accreditation

The measurement facilities used to collect data are located at

| Pavilion A, Ashwood Park, Ashwood Way, Basingstoke, Hampshire, RG23 8BG UK | Facility Type |
|---|--------------------------------|
| SAR Lab 61 | Controlled Environment Chamber |

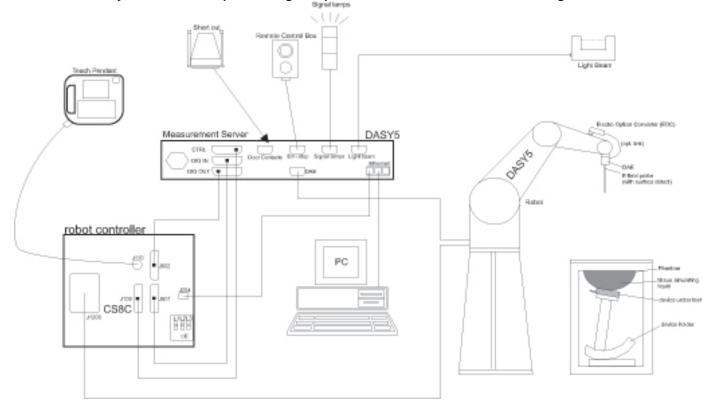
UL VS Limited is accredited by UKAS (United Kingdom Accreditation Service, Accredited to ISO/IEC 17025: 2005), Laboratory UKAS Code 0644.

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4. SAR Measurement System & Test Equipment

4.1. SAR Measurement System

The DASY test systems used for performing compliance tests consists of the following items:



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- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic Field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and Win7 with DASY software installed.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

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4.2. SAR Measurement Procedure

4.2.1. Normal SAR Measurement Procedure

The following procedure shall be performed for each of the test conditions Measure the local SAR at a test point within 8 mm of the phantom inner surface that is closest to the DUT.

- a) Measure the two-dimensional SAR distribution within the phantom (area scan procedure).
- b) The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grid spacing of 20 mm for frequencies below 3 GHz and (60/f [GHz]) mm for frequencies of 3 GHz and greater is recommended. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and δ ln(2)/2 mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and ln(x) is the natural logarithm. The maximum variation of the sensor-phantom surface distance shall be ± 1 mm for frequencies below 3 GHz and ± 0,5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5°. If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional uncertainty evaluation is needed.
- c) From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that will not be within the zoom scan of other peaks; additional peaks shall be measured only when the primary peak is within 2 dB 6 of the SAR compliance limit (e.g., 1 W/kg for 1,6 W /kg 1 g limit, or 1,26 W/kg for 2 W /kg, 10 g limit).
- Measure the three-dimensional SAR distribution at the local maxima locations identified in step c) (zoom scan procedure). The horizontal grid step shall be (24 / f [GHz]) mm or less but not more than 8 mm. The minimum zoom scan size is 30 mm by 30 mm by 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom scan size can be reduced to 22 mm by 22 mm. The grid step in the vertical direction shall be (8-f [GHz]) mm or less but not more than 5 mm, if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be (12/f [GHz]) mm or less but not more than 4 mm, and the spacing between farther points shall increase by an incremental factor not exceeding 1.5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and δ ln(2)/2 mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and $\ln(x)$ is the natural logarithm. Separate grids shall be centred on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved if the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the flat phantom surface shall be less than 5°.
- e) Use post processing (e.g. interpolation and extrapolation) procedures to determine the local SAR values at the spatial resolution needed for mass averaging.
- f) The local SAR should be measured at the same location as in Step a). SAR drift is assessed and reported in the uncertainty budget.
 - In the event that the evaluation of measurement drift exceeds the 5 % tolerance, it is required that SAR be reassessed following guidelines contained within this standard.
 - If the drift is larger than 5 %, then the measurement drift shall be considered a bias, not an uncertainty. A correction shall be applied to the measured SAR value. It is not necessary to record the drift in the uncertainty budget (i.e. ui = 0 %). The uncertainty budget reported in a measurement report should correspond to the highest SAR value reported (after correction, if applicable). Alternatively, the uncertainty budget reported should cover all measurements, i.e., it should report a conservative value.

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Area Scan Parameters:

| | ≤3 GHz | > 3 GHz | | |
|--|---|---|--|--|
| Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface | 5 mm ± 1 mm | $\frac{1}{2} \cdot \delta \cdot \ln(2) \text{ mm} \pm 0.5 \text{ mm}$ | | |
| Maximum probe angle from probe axis to phantom surface normal at the measurement location | 30° ± 1° | 20° ± 1° | | |
| | ≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm | 3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm | | |
| Maximum area scan spatial resolution: Δx _{Area} , Δy _{Area} | When the x or y dimension measurement plane orientat above, the measurement res corresponding x or y dimenat least one measurement po | tion, is smaller than the solution must be \leq the nsion of the test device with | | |

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Zoom Scan Parameters:

| | | | ≤3 GHz | > 3 GHz | |
|---|---|---|--|--|--|
| Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom} | | | \leq 2 GHz: \leq 8 mm 2 – 3 GHz: \leq 5 mm [*] | 3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm* | |
| | uniform grid: $\Delta z_{Zoom}(n)$ | | ≤ 5 mm | 3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm | |
| Maximum zoom scan spatial resolution, normal to phantom surface | hantom $\frac{1}{\text{graded}}$ $\frac{1}{\text{grid}}$ $\frac{1}{\text{dz}_{\text{Zoom}}(n>1)}$: | Δz _{Zoom} (1): between 1 st two points closest to phantom surface | ≤ 4 mm | $3 - 4 \text{ GHz} \le 3 \text{ mm}$ $4 - 5 \text{ GHz} \le 2.5 \text{ mm}$ $5 - 6 \text{ GHz} \le 2 \text{ mm}$ | |
| | | between subsequent | $\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$ | | |
| Minimum zoom scan volume | x, y, z | | ≥ 30 mm | 3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm | |

4.3. Test Equipment

Measuring equipment used to perform the tests is documented in this report and has been calibrated in accordance with UKAS' recommendations, and is traceable to recognized national standards.

| UL No. | Instrument | Manufacturer | Туре No. | Serial No. | Date Last Calibrated | Cal. Interval (Months) |
|------------|---------------------------------|-------------------------|------------------------|-----------------|------------------------------|------------------------------|
| A2547 | Data Acquisition Electronics | SPEAG | DAE4 | 1438 | 25 Apr 2016 | 12 |
| A2544 | Probe | SPEAG | EX3 DV4 | 3994 | 21 Mar 2016 | 12 |
| A1322 | 2450 MHz Dipole | SPEAG | D2450V2 | 725 | 29 Sep 2016 | 12 |
| G0612 | Robot Power Supply | SPEAG | DASY52 | F14/5T5ZA1/C/01 | Calibrated as part of system | - |
| M1877 | Robot Arm | Staubli | TX60 L | F14/5T5ZA1/A/01 | Calibrated as part of system | - |
| A2440 | Body Handset Positioner | SPEAG | MD4HACV5 | None | Calibrated before use | - |
| M1755 | DAK Fluid Probe | SPEAG | SM DAK 040 CA | 1089 | Calibrated before use | - |
| M1015 | Network Analyser | Agilent Technologies | 8753ES | US39172406 | 26 Sept 2016 | 12 |
| M1855 | Power Sensor | R&S | NRP-Z51 | 103246 | 08 Nov 2016 | 12 |
| A2621 | Digital Camera | Nikon | S3600 | 41010357 | N/A | - |
| M1838 | Signal Generator | R&S | SME06 | 1038.6002.06 | 07 Apr 2016 | 12 |
| M1023 | Dual Channel Power Meter | R&S | NRVD | 863715/030 | 13 Apr 2016 | 12 |
| M1635 | Power Sensor | R&S | NRV-Z1 | 826515/015 | 13 Apr 2016 | 12 |
| M1634 | Power Sensor | R&S | NRV-Z1 | 860462/016 | 13 Apr 2016 | 12 |
| A2100 | Directional Coupler | RF-Lambda | 11101300748 | None | Calibrated before use | - |
| A2689 | Amplifier | Mini-Circuits | ZVE-8G | 910401427 | Calibrated before use | - |
| A2549 | Phantom | SPEAG | Eli Phantom | 1252 | Calibrated as part of system | - |
| PRE0141350 | Phantom Support Structure | SPEAG | DASY6 Phantom Table | - | Calibrated as part of system | - |
| M1270 | RS Hygrometer | RS Components | N/A | N/A | 18 March 2016 | 12 |
| PRE0140104 | RF Coax Cable | RM Coax | FB311A1020003 030 | - | Calibrated before use | - |

4.3.1. SAR System Specifications

| Robot System Specifications | |
|--|---|
| Positioner: | Stäubli Unimation Corp. Robot Model: TX60L |
| Repeatability: | ±0.030 mm |
| No. of Axis: | 6 |
| Serial Number: | F14/5T5ZA1/A/01 |
| Reach: | 920 mm |
| Payload: | 2.0 kg |
| Control Unit: | CS8C |
| Programming Language: | V+ |
| Data Acquisition Electronic (DAE) System | V+ |
| Serial Number: | DAE4 SN: 1438 |
| PC Controller | |
| PC: | Dell Precision 340 |
| Operating System: | Windows 2000 |
| Data Card: | DASY5 Measurement Servers |
| Serial Number: | 1080 |
| Data Converter | |
| Features: | Signal Amplifier, multiplexer, A/D converted and control logic. |
| Software: | DASY5 PRO Software |
| Connecting Lines: | Optical downlink for data and status info. Optical uplink for commands and clock. |
| PC Interface Card | |
| Function: | 24 bit (64 MHz) DSP for real time processing Link to DAE3 and DAE4 16 bit A/D converter for surface detection system serial link to robot direct emergency stop output for robot. |
| Phantom | |
| Phantom: | Eli Phantom |
| Shell Material: | Fibreglass |
| Thickness: | 2.0 ±0.1 mm |
| E-Field Probe | |
| Model: | EX3DV4 |
| Serial No: | 3994 |
| Construction: | Triangular core |
| Frequency: | 10 MHz to >6 GHz |
| Linearity: | ±0.2 dB (30 MHz to 6 GHz) |
| Probe Length (mm): | 337 |
| Probe Diameter (mm): | 10 |
| Tip Length (mm): | 9 |
| Tip Diameter (mm): | 2.5 |
| Sensor X Offset (mm): | 1 |
| Sensor Y Offset (mm): | 1 |
| Sensor Z Offset (mm): | 1 |
| | |

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5. Measurement Uncertainty

No measurement or test can ever be perfect and the imperfections give rise to error of measurement in the results. Consequently, the result of a measurement is only an approximation to the value of the measurand (the specific quantity subject to measurement) and is only complete when accompanied by a statement of the uncertainty of the approximation.

The expression of uncertainty of a measurement result allows realistic comparison of results with reference values and limits given in specifications and standards.

The uncertainty of the result may need to be taken into account when interpreting the measurement results.

The reported expanded uncertainties below are based on a standard uncertainty multiplied by an appropriate coverage factor, such that a confidence level of approximately 95% is maintained. For the purposes of this document "approximately" is interpreted as meaning "effectively" or "for most practical purposes".

| Test Name | Confidence Level | Calculated Uncertainty |
|--|---------------------|---------------------------|
| Uncertainty- Freq. < 3 GHz Body Configuration 10 g | 95% | ±19.67% |
| Uncertainty- Freq. > 3 GHz Body Configuration 10 g | 95% | ±16.84% |

The methods used to calculate the above uncertainties are in line with those recommended within the various measurement specifications. Where measurement specifications do not include guidelines for the evaluation of measurement uncertainty, the published guidance of the appropriate accreditation body is followed.

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5.1. Uncertainty – Freq. < 3 GHz Body Configuration 10 g

| Type | Source of uncertainty | + Value | - Value | Probability | Divisor | | Standard U | ncertainty | ບ _i or |
|------|--|---------|---------|----------------|---------|----------------------|------------|------------|-------------------|
| Type | Source of uncertainty | + value | - value | Distribution | Divisor | C _{i (10g)} | + u (%) | - u (%) | v_{eff} |
| В | Probe calibration | 5.050 | 5.050 | normal (k=1) | 1.0000 | 1.0000 | 5.050 | 5.050 | ∞ |
| В | Axial Isotropy | 0.250 | 0.250 | normal (k=1) | 1.0000 | 1.0000 | 0.250 | 0.250 | ∞ |
| В | Hemispherical Isotropy | 1.300 | 1.300 | normal (k=1) | 1.0000 | 1.0000 | 1.300 | 1.300 | ∞ |
| В | Spatial Resolution | 0.500 | 0.500 | Rectangular | 1.7321 | 1.0000 | 0.289 | 0.289 | ∞ |
| В | Boundary Effect | 0.769 | 0.769 | Rectangular | 1.7321 | 1.0000 | 0.444 | 0.444 | ∞ |
| В | Linearity | 0.300 | 0.300 | Rectangular | 1.7321 | 1.0000 | 0.173 | 0.173 | ∞ |
| В | Detection Limits | 0.200 | 0.200 | Rectangular | 1.7321 | 1.0000 | 0.115 | 0.115 | ∞ |
| В | Readout Electronics | 0.160 | 0.160 | normal (k=1) | 1.0000 | 1.0000 | 0.160 | 0.160 | ∞ |
| В | Response Time | 0.000 | 0.000 | Rectangular | 1.7321 | 1.0000 | 0.000 | 0.000 | ∞ |
| В | Integration Time | 8.520 | 8.520 | Rectangular | 1.7321 | 1.0000 | 4.919 | 4.919 | ∞ |
| В | RF Ambient conditions | 3.000 | 3.000 | Rectangular | 1.7321 | 1.0000 | 1.732 | 1.732 | ∞ |
| В | Probe Positioner Mechanical Restrictions | 4.000 | 4.000 | Rectangular | 1.7321 | 1.0000 | 2.309 | 2.309 | × |
| В | Probe Positioning with regard to Phantom Shell | 2.850 | 2.850 | Rectangular | 1.7321 | 1.0000 | 1.645 | 1.645 | × |
| В | Extrapolation and integration / Maximum SAR evaluation | 5.080 | 5.080 | Rectangular | 1.7321 | 1.0000 | 2.933 | 2.933 | ∞ |
| Α | Test Sample Positioning | 3.080 | 3.080 | normal (k=1) | 1.0000 | 1.0000 | 3.080 | 3.080 | 10 |
| Α | Device Holder uncertainty | 0.154 | 0.154 | normal (k=1) | 1.0000 | 1.0000 | 0.154 | 0.154 | 10 |
| В | Phantom Uncertainty | 4.000 | 4.000 | Rectangular | 1.7321 | 1.0000 | 2.309 | 2.309 | ∞ |
| В | Drift of output power | 5.000 | 5.000 | Rectangular | 1.7321 | 1.0000 | 2.887 | 2.887 | ∞ |
| В | Liquid Conductivity (target value) | 5.000 | 5.000 | Rectangular | 1.7321 | 0.4300 | 1.241 | 1.241 | × |
| Α | Liquid Conductivity (measured value) | 2.470 | 2.470 | normal (k=1) | 1.0000 | 0.4300 | 1.062 | 1.062 | 5 |
| В | Liquid Permittivity (target value) | 5.000 | 5.000 | Rectangular | 1.7321 | 0.4900 | 1.415 | 1.415 | ∞ |
| Α | Liquid Permittivity (measured value) | 2.430 | 2.430 | normal (k=1) | 1.0000 | 0.4900 | 1.191 | 1.191 | 5 |
| | Combined standard uncertainty | | | t-distribution | | | 10.04 | 10.04 | >500 |
| | Expanded uncertainty | | | k = 1.96 | | | 19.67 | 19.67 | >500 |

5.2. Uncertainty - Freq. > 3 GHz Body Configuration 10 g

| Time | Saura of unasatointu | + Value - Valu | Value | Probability | Divisor | | Standard Uncertainty | | |
|------|--|----------------|---------|----------------|---------|----------------------|-------------------------|---------|------------------------------------|
| Type | Source of uncertainty | + value | - Value | Distribution | Divisor | C _{i (10g)} | + u (%) | - u (%) | ບ _i Or ບ _{eff} |
| В | Probe calibration | 5.050 | 5.050 | normal (k=1) | 1.0000 | 1.0000 | 5.050 | 5.050 | ∞ |
| В | B Axial Isotropy | | 0.250 | normal (k=1) | 1.0000 | 1.0000 | 0.250 | 0.250 | ∞ |
| В | , | | 1.300 | normal (k=1) | 1.0000 | 1.0000 | 1.300 | 1.300 | ∞ |
| В | Spatial Resolution | 0.500 | 0.500 | Rectangular | 1.7321 | 1.0000 | 0.289 | 0.289 | ∞ |
| В | Boundary Effect | 0.769 | 0.769 | Rectangular | 1.7321 | 1.0000 | 0.444 | 0.444 | ∞ |
| В | Linearity | 0.300 | 0.300 | Rectangular | 1.7321 | 1.0000 | 0.173 | 0.173 | ∞ |
| В | Detection Limits | 0.200 | 0.200 | Rectangular | 1.7321 | 1.0000 | 0.115 | 0.115 | ∞ |
| В | Readout Electronics | 0.160 | 0.160 | normal (k=1) | 1.0000 | 1.0000 | 0.160 | 0.160 | ∞ |
| В | Response Time | 0.000 | 0.000 | Rectangular | 1.7321 | 1.0000 | 0.000 | 0.000 | ∞ |
| В | Integration Time | 0.000 | 0.000 | Rectangular | 1.7321 | 1.0000 | 0.000 | 0.000 | ∞ |
| В | RF Ambient conditions | 3.000 | 3.000 | Rectangular | 1.7321 | 1.0000 | 1.732 | 1.732 | ∞ |
| В | Probe Positioner Mechanical Restrictions | 4.000 | 4.000 | Rectangular | 1.7321 | 1.0000 | 2.309 | 2.309 | ∞ |
| В | Probe Positioning with regard to Phantom Shell | 2.850 | 2.850 | Rectangular | 1.7321 | 1.0000 | 1.645 | 1.645 | ∞ |
| В | Extrapolation and integration / Maximum SAR evaluation | 5.080 | 5.080 | Rectangular | 1.7321 | 1.0000 | 2.933 | 2.933 | ∞ |
| Α | Test Sample Positioning | 2.430 | 2.430 | normal (k=1) | 1.0000 | 1.0000 | 2.430 | 2.430 | 10 |
| Α | Device Holder uncertainty | 0.154 | 0.154 | normal (k=1) | 1.0000 | 1.0000 | 0.154 | 0.154 | 10 |
| В | Phantom Uncertainty | 4.000 | 4.000 | Rectangular | 1.7321 | 1.0000 | 2.309 | 2.309 | ∞ |
| В | Drift of output power | 5.000 | 5.000 | Rectangular | 1.7321 | 1.0000 | 2.887 | 2.887 | 8 |
| В | Liquid Conductivity (target value) | 5.000 | 5.000 | Rectangular | 1.7321 | 0.6400 | 1.848 | 1.848 | 8 |
| Α | Liquid Conductivity (measured value) | 0.770 | 0.770 | normal (k=1) | 1.0000 | 0.6400 | 0.493 | 0.493 | 5 |
| В | Liquid Permittivity (target value) | 5.000 | 5.000 | Rectangular | 1.7321 | 0.6000 | 1.732 | 1.732 | ∞ |
| Α | Liquid Permittivity (measured value) | 0.990 | 0.990 | normal (k=1) | 1.0000 | 0.6000 | 0.594 | 0.594 | 5 |
| | Combined standard uncertainty | | | t-distribution | | | 8.59 | 8.59 | >500 |
| | Expanded uncertainty | | | k = 1.96 | | | 16.84 | 16.84 | >500 |

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6. Device Under Test (DUT)

6.1. DUT Description

| DUT Description: | The DUT is a remote controller for home automation and it supports Wi-Fi 2.4 GHz (802.11 b/g 6LoWPAN (IEEE 802.15.4). | /n) and | | | |
|-------------------------------------|--|--------------------|--|--|--|
| Serial Number: | The following samples were used to perform SAR measurements: - SN: MBA09: Wi-Fi 2.4 GHz / IEEE 802.15.4 (6LoWPAN 2.4 GHz) The following sample was used to perform conducted power measurements: - SN: MBA22: Wi-Fi 2.4 GHz / IEEE 802.15.4 (6LoWPAN 2.4 GHz) | | | | |
| Hardware Version Number: | Hardware Rev. 10 | | | | |
| Software Version Number: 0.21.4 | | | | | |
| Country of Manufacture: Switzerland | | | | | |
| Device dimension | Overall (Height x Width x Depth): 181.65 mm x 48.50 mm x 10.79 mm | | | | |
| Date of Receipt: | 27 February 2017 | | | | |
| Back Cover | Back Cover ☐ Normal Battery Cover with NFC ☐ Wireless Charger Battery Cover ☐ Wireless Charger Battery Cover with NFC | | | | |
| Accessory | Headset | | | | |
| Battery Options | Battery Options Standard – Lithium-ion battery Extended (large capacity) | | | | |
| Antenna Type: | Internal integral | | | | |
| Antenna Length: | None Stated | | | | |
| Number of Antenna Positions: | Antenna A ~ Wi-Fi Antenna Antenna B ~ 6LoWPAN Antenna | 1 fixed 1 fixed | | | |

6.2. Wireless Technologies

| Wireless technologies | Frequency bands | Operating mode | Duty Cycle |
|-----------------------|-----------------|----------------|------------|
| Wi-Fi | 2.4 GHz | 802.11b | 15% |
| | | 802.11g | |
| | | 802.11n (HT20) | |
| 6LoWPAN | 2.4 GHz | 802.15.4 | 100% |

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Additional Information Related to Testing:

| Wi-Fi | | | | | | | | | | |
|--------------------------------|----------------|---------------|----------------|---------------|----------------|---------------|--|--|--|--|
| | Description | | | | | | | | | |
| Band | 20 MHz BW Ch.# | Frq. (MHz) | 40 MHz BW Ch.# | Frq. (MHz) | 80 MHz BW Ch.# | Frq. (MHz) | | | | |
| | 1 | 2412.0 | | | • | | | | | |
| | 2 | 2417.0 | N/A | | | | | | | |
| | 3 | 2422.0 | | | | | | | | |
| | 4 | 2427.0 | | | | | | | | |
| W. E. O. 4 O. 1 | 5 | 2432.0 | | | | | | | | |
| Wi-Fi 2.4 GHz (802.11b/g/n) | 6 | 2437.0 | | | | | | | | |
| (002.110/9/11) | 7 | 2442.0 | | | | | | | | |
| | 8 | 2447.0 | | | | | | | | |
| | 9 | 2452.0 | | | | | | | | |
| | 10 | 2457.0 | | | | | | | | |
| | 11 | 2462.0 | | | | | | | | |

IEEE 802.15.4 - 6LoWPAN

| | Description | | |
|------------------|-------------|-------|--|
| Band | Ch.# | Frq. | |
| | O.I.I. | (MHz) | |
| | 11 | 2405 | |
| | 12 | 2410 | |
| | 13 | 2415 | |
| | 14 | 2420 | |
| | 15 | 2425 | |
| | 16 | 2430 | |
| | 17 | 2435 | |
| 6LoWPAN 2.4 GHz | 18 | 2440 | |
| OLOWFAIN 2.4 GHZ | 19 | 2445 | |
| | 20 | 2450 | |
| | 21 | 2455 | |
| | 22 | 2460 | |
| | 23 | 2465 | |
| | 24 | 2470 | |
| | 25 | 2475 | |
| | 26 | 2480 | |

6.3.Nominal and Maximum Output Power

+/-1.85

+/-1.85

(From customer)

WiFi 2.4 GHz - Tolerance (dB)

| Band Cha | hannel | Center Frequency (MHz) | 1DSSS | 802.11b 2DSSS | | | | 902 114 | | | 802.11n |
|----------|--------|------------------------------|-------|------------------|-------|-------|-------|---------|--------|--------|---------|
| | 1 | / | | 20666 | | | | 802.11g | | | HT20 |
| | 1 | 2412 | | 20333 | 11CCK | 6OFDM | 9OFDM | 18OFDM | 36OFDM | 54OFDM | MCS7 |
| | 0 | | 15.56 | 15.56 | 15.66 | 13.01 | 13.01 | 12.76 | 11.26 | 10.91 | 10.06 |
| | 2 | 2417 | 15.54 | 15.54 | 15.71 | 14.76 | 14.76 | 14.76 | 13.26 | 11.36 | 10.06 |
| | 3 | 2422 | 16.01 | 16.01 | 16.26 | 15.31 | 15.31 | 15.36 | 13.86 | 11.76 | 10.56 |
| | 4 | 2427 | 15.96 | 15.96 | 16.21 | 15.36 | 15.36 | 15.41 | 13.91 | 11.91 | 10.56 |
| | 5 | 2432 | 15.91 | 15.91 | 16.21 | 15.41 | 15.41 | 15.41 | 13.91 | 11.91 | 10.66 |
| Wi-Fi | 6 | 2437 | 16.41 | 16.41 | 16.71 | 16.27 | 16.27 | 16.36 | 14.86 | 12.96 | 11.71 |
| 2.4 | 7 | 2442 | 16.86 | 16.86 | 17.06 | 16.06 | 16.06 | 16.16 | 14.66 | 12.66 | 11.31 |
| GHz | 8 | 2447 | 16.26 | 16.26 | 16.56 | 16.06 | 16.06 | 16.16 | 14.66 | 12.66 | 11.46 |
| | 9 | 2452 | 15.81 | 15.81 | 16.06 | 15.26 | 15.26 | 15.26 | 13.76 | 11.81 | 10.46 |
| | 10 | 2457 | 15.86 | 15.86 | 16.16 | 15.26 | 15.26 | 15.26 | 13.76 | 11.81 | 10.56 |
| | 11 | 2462 | 15.96 | 15.96 | 16.21 | 13.26 | 13.26 | 12.76 | 11.26 | 10.96 | 10.66 |
| | 12 | 2467 | | Not Supported | | | | | | | |
| | 13 | 2472 | | | | | | | | | |

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| | | Target (dBm) applicable to antenna B only |
|---------|---------|---|
| Band | Channel | approace to untermade only |
| 6LoWPAN | ALL | 11.50 |

+/-1.85

+/-1.85

+/-1.85

+/-2.10

+/-2.10

+/-2.10

+/-1.85

| 6LoWPAN - Tolerance (dB) | +/-2.08 |
|--------------------------|---------|

Note:

1. The nominal and maximum average source based rated powers declared and supplied by manufacturer are shown in the above tables.

7. RF Exposure Conditions (Test Configurations)

7.1. RF Exposure Conditions (Test Configurations)

| Technology Antenna | Configuration | Antenna-to- User Separation | Position | Antenna-to- Edge Separation (mm) | Evaluation Considered |
|-----------------------|---------------------|-----------------------------------|----------------------|--|--------------------------|
| | | | Front | <25mm | Yes |
| | | | Back | <25mm | Yes |
| Antenna A ~ WLAN ~ | Extremity (Body) | 0mm | Edge 1 (Top Edge) | <25mm | Yes |
| Wi-Fi Antenna | | | Edge 2 (Right Edge) | >25mm | No |
| | | | Edge 3 (Bottom Edge) | >25mm | No |
| | | | Edge 4 (Left Edge) | <25mm | Yes |
| | | 0mm | Front | <25mm | Yes |
| | | | Back | <25mm | Yes |
| Antenna B ~ WPAN ~ | Extremity (Body) | | Edge 1 (Top Edge) | <25mm | Yes |
| 6LoWPAN Antenna | | | Edge 2 (Right Edge) | <25mm | Yes |
| | | | Edge 3 (Bottom Edge) | >25mm | No |
| | | | Edge 4 (Left Edge) | >25mm | No |

7.2. SAR Test Exclusion Consideration

| | Configuration(s) | | | |
|----------------|------------------|------------------|--|--|
| Frequency Band | Extremity | | | |
| | Antenna A - WLAN | Antenna B - WPAN | | |
| WLAN 2.4 GHz | No | N/A | | |
| 6LoWPAN 2.4GHz | N/A | No | | |

Note:

- 1. As per KDB publication 447498 D01, The Frequency Bands with Rated Power including Upper tolerance, which qualify for **Standalone SAR Test Exclusion**, are as per the above table.
- 2. The details for the Maximum Rated Power and tolerance(s) can be found in section 6.3

8. Conducted output power measurements

8.1. RF Output Average Power Measurement: Wi-Fi

8.1.1. Wi-Fi 802.11b/g/n (2.4 GHz)

| | <u> </u> | Avg Power (dBm) | |
|----------------|-----------------|-----------------|-----------------|
| | | Antenna A | |
| Channel Number | Frequency (MHz) | 11 Mbps | Operating Mode |
| 1 | 2412 | 15.55 | |
| 2 | 2417 | 15.56 | |
| 3 | 2422 | 16.17 | |
| 4 | 2427 | 16.23 | |
| 5 | 2432 | 16.28 | |
| 6 | 2437 | 16.85 | |
| 7 | 2442 | 17.38 | 802.11b (11CCK) |
| 8 | 2447 | 16.88 | |
| 9 | 2452 | 16.41 | |
| 10 | 2457 | 16.45 | |
| 11 | 2462 | 16.48 | |
| 12 | 2467 | Not Supported | |
| 13 | 2472 | Not Supported | |

Note:

Conducted power measurements were not performed for mode 802.11g and 802.11n HT20 due to max. rated power being equal or lower to mode 802.11b.

8.2.RF Output Average Power Measurement: IEEE 804.15.4

8.2.1. IEEE 804.15.4 - 6LoWPAN (2.4 GHz)

| | | Avg Power (dBm) | |
|----------------|-----------------|-----------------|----------------|
| Channel Number | Frequency (MHZ) | Antenna B | Operating Mode |
| 11 | 2405.0 | 12.90 | |
| 18 | 2440.0 | 12.81 | 6LoWPAN |
| 26 | 2480.0 | 12.64 | |

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9. Dielectric Property Measurements & System Check

9.1. Tissue Dielectric Parameters

The temperature of the tissue-equivalent medium used during measurement must also be within 18° C to 25° C and within $\pm 2^{\circ}$ C of the temperature when the tissue parameters are characterized.

The dielectric parameters must be measured before the tissue-equivalent medium is used in a series of SAR measurements. The parameters should be re-measured after each 3-4 days of use; or earlier if the dielectric parameters can become out of tolerance; for example, when the parameters are marginal at the beginning of the measurement series.

Tissue dielectric parameters were measured at the low, middle and high frequency of each operating frequency range of the test device.

IEEE 1528:2013

| Target Frequency (MHz) | Body | | | | |
|------------------------|----------------|---------|--|--|--|
| | ϵ_{r} | σ (S/m) | | | |
| 150 | 61.9 | 0.80 | | | |
| 300 | 58.2 | 0.92 | | | |
| 450 | 56.7 | 0.94 | | | |
| 750 | - | - | | | |
| 835 | 55.2 | 0.97 | | | |
| 900 | 55.0 | 1.05 | | | |
| 915 | 55.0 | 1.06 | | | |
| 1450 | 54.0 | 1.30 | | | |
| 1500 | - | - | | | |
| 1610 | 53.8 | 1.40 | | | |
| 1640 | - | - | | | |
| 1750 | - | - | | | |
| 1800 | 53.3 | 1.52 | | | |
| 1900 | 53.3 | 1.52 | | | |
| 2000 | 53.3 | 1.52 | | | |
| 2100 | - | - | | | |
| 2300 | - | - | | | |
| 2450 | 52.7 | 1.95 | | | |
| 2600 | - | - | | | |
| 3000 | 52.0 | 2.73 | | | |
| 3500 | - | - | | | |
| 4000 | - | - | | | |
| 4500 | - | - | | | |
| 5000 | 49.3 | 5.07 | | | |
| 5100 | 49.1 | 5.18 | | | |
| 5200 | 49.0 | 5.30 | | | |
| 5250 | 48.9 | 5.36 | | | |
| 5300 | 48.9 | 5.42 | | | |
| 5400 | 48.7 | 5.53 | | | |
| 5500 | 48.6 | 5.65 | | | |
| 5600 | 48.5 | 5.77 | | | |
| 5700 | 48.3 | 5.88 | | | |
| 5750 | 48.3 | 5.94 | | | |
| 5800 | 48.2 | 6.00 | | | |
| 6000 | - | - | | | |

NOTE: For convenience, permittivity and conductivity values at some frequencies that are not part of the original data from Drossos et al. [B60] or the extension to 5800 MHz are provided (i.e., the values shown in italics). These values were linearly interpolated between the values in this table that are immediately above and below these values, except the values at 6000 MHz that were linearly extrapolated from the values at 3000 MHz and 5800 MHz.

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9.2. System Check

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are re-measured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

9.3. Reference Target SAR Values

The reference SAR values are obtained from the calibration certificate of system validation dipoles. The measured values are normalised to 1.00 Watt.

| System Dipole | Serial No. | Cal. Date | Freq. (MHz) | Target SAR Values (mW/g) | | |
|---------------|------------|-------------|-------------|--------------------------|-------|--|
| | | | | 1g/10g | Body | |
| D2450V2 | 725 | 29 Sep 2016 | 2450 | 1g | 50.30 | |
| | | | | 10g | 23.80 | |

9.4. Dielectric Property Measurements & System Check Results

The 1-g SAR and 10-g SAR measured with a reference dipole, using the required tissue-equivalent medium at the test frequency, must be within $\pm 5\%$ of the manufacturer calibrated dipole SAR target. The internal limit is set to $\pm 5\%$.

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System check 2450 Body

Date: 28/02/2017

Validation dipole and Serial Number: D2450V2 / SN: 725

| Simulant | Frequency (MHz) | Room Temp (°C) | Liquid Temp (℃) | Parameters | Target Value | Measured Value | Deviation (%) | Limit (%) |
|-----------|--------------------|----------------|-----------------|------------|-----------------|-------------------|------------------|--------------|
| Body 2450 | | 23.0 | 21.0 | εr | 52.70 | 53.48 | 1.48 | 5.00 |
| | 2450 | | | Σ | 1.95 | 2.03 | 4.00 | 5.00 |
| | 2450 | | | 1g (W/kg) | 50.30 | 51.60 | 2.58 | 5.00 |
| | | | | 10g (W/kg) | 23.80 | 24.04 | 1.01 | 5.00 |

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10. Measurements, Examinations and Derived Result

10.1. Specific Absorption Rate - Test Results For All SAR measurement in this report the 10g-SAR limit tested to is 4.0 W/Kg

2412.0

2462.0

1

11

10.1.1. Wi-Fi 2.4 GHz – Extremity 10g

Max. Reported SAR = 0.407 (W/kg) 10g: SAR Results (W/kg) -Power (dBm) - ANT ANT A Reported Scale Dist CH Freq Tune up Meas. Scan Mod. **EUT Position** Meas. **Before** Reported (MHz) Limit **Factor** No. **Power** (mm) Scaling 7 2442.0 0.0 Front 18.91 17.38 0.000 0.000 6.67 0.000 1 0.0 Back 7 2442.0 18.91 17.38 0.039 0.055 0.367 2 6.67 11CCK 0.0 7 2442.0 18.91 17.38 0.000 0.000 Top 0.000 6.67 3 (802.11b Left Hand Side 7 2442.0 0.000 0.000 0.000 0.0 18.91 17.38 4 11Mbps) 6.67

15.55

16.48

0.039

0.025

0.061

0.036

6.67

6.67

0.407

0.240

5

6

Note:

As per KDB publication 248227 D01, since continuous transmission is restricted by the device and only a duty cycle of 15% can be achieved, reported SAR has been scaled to 100% transmission duty factor to determine compliance at the maximum tune-up tolerance.

17.51

18.06

Scale-up has been performed using a linear scale factor of:

Back

Back

$$\frac{100 \% [Desired Duty Cycle]}{15 \% [Actual Highest Duty Cycle]} = 6.67$$

10.1.2. IEEE 802.15.4 - 6LoWPAN 2.4 GHz - Extremity 10g

Max. Reported SAR: 0.239 (W/kg)

0.0

0.0

| _ | | | U, | | Power (dBm) - ANT B | | 10g: SAR Results (W/kg) - ANT B | | |
|---------|--------------|-----------------|---------|---------------|---------------------|-------------|------------------------------------|----------|-------------|
| Mod. | Dist (mm) | EUT Position | CH # | Freq (MHz) | Tune up Limit | Meas. Power | Meas. | Reported | Scan No. |
| 6LoWPAN | 0.0 | Front | 11 | 2405.0 | 13.58 | 12.90 | 0.002 | 0.002 | 7 |
| | 0.0 | Back | 11 | 2405.0 | 13.58 | 12.90 | 0.204 | 0.239 | 8 |
| | 0.0 | Тор | 11 | 2405.0 | 13.58 | 12.90 | 0.017 | 0.020 | 9 |
| | 0.0 | Right Hand Side | 11 | 2405.0 | 13.58 | 12.90 | 0.022 | 0.026 | 10 |
| | 0.0 | Back | 18 | 2440.0 | 13.58 | 12.81 | 0.141 | 0.168 | 11 |
| | 0.0 | Back | 26 | 2480.0 | 13.58 | 12.64 | 0.092 | 0.114 | 12 |

10.2. SAR Measurement Variability

In accordance with published RF Exposure KDB procedure 865664 D01 SAR measurement 100 MHz to 6 GHz. These additional measurements are repeated after the completion of all measurements requiring the same head or body tissue-equivalent medium in a frequency band. The test device should be returned to ambient conditions (normal room temperature) with the battery fully charged before it is re-mounted on the device holder for the repeated measurement(s) to minimize any unexpected variations in the repeated results.

- 1) Repeated measurement is not required when the original highest measured SAR is < 2.00 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 2.00 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 3.60 W/kg (~ 10% from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥3.75 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

Note: Measure 10g-SAR levels < 2.000 W/Kg, repeat measurements are not required.

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11. Highest Standalone SAR and Simultaneous Transmission

11.1. Highest Standalone Reported SAR

KDB 447498 D01 General RF Exposure Guidance, introduces a new formula for calculating the SAR to Peak Location Ratio (SPLSR) between pairs of simultaneously transmitting antennas:

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$$SPLSR = (SAR_1 + SAR_2)^{1.5} / Ri$$

Where:

SAR₁ is the highest reported or estimated SAR for the first of a pair of simultaneous transmitting antennas, in a specific test operating mode and exposure condition

SAR₂ is the highest reported or estimated SAR for the second of a pair of simultaneous transmitting antennas, in the same test operating mode and exposure condition as the first

Ri is the separation distance between the pair of simultaneous transmitting antennas. When the SAR is measured for both antennas in the pair, it is determined by the actual x, y, and z coordinates in the 1-g SAR for each SAR Peak Location; based on the extrapolated and interpolated result in the zoom scan measurement using the formula:

$$[(x_1-x_2)^2+(y_1-y_2)^2+(z_1-z_2)^2]$$

A new threshold of 0.10 when 10g SAR applies is also introduced in the KDB 447498. Thus, in order for a pair of simultaneously transmitting antennas, with the sum of 10g SAR > 4.0 W/kg for (Extremity Test Condition only), to qualify for exemption from Simultaneous Transmission SAR measurements, it has to satisfy the condition of:

$$(SAR_1 + SAR_2)^{1.5} / Ri < 0.10$$

The worst case simultaneous transmission analysis is considered for the following cases:

1. WLAN + 6LoWPAN

Worst Case Simultaneous Transmission SAR Analysis:

| Exposure Combinations | Technology Band | Configuration | Highest Reported 10g SAR (W/kg) | Max Rated Source base Avg Power + Max Tolerance [dBm] | Highest Reported Sum-SAR 10g-SAR (W/kg) | SPLSR Ratio |
|-----------------------|-----------------|---------------|------------------------------------|--|---|----------------|
| WWAN + 6LoWPAN | WLAN 2.4 GHz | Extremity | 0.407 | 17.51 | 0.646 | N/A |
| | 6LoWPAN 2.4 GHz | Latienity | 0.239 | 13.58 | 0.040 | IN/A |