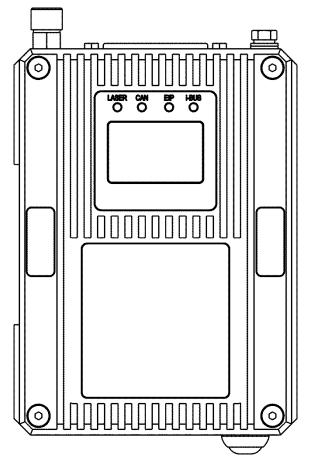
Instruction Manual

SL mini and SLR mini Series Speed and Length Gauges



Issue 1s 5 December 2016

Proton Products International Ltd.

www.protonproducts.com

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DECLARATION OF CONFORMITY (CE)



This is to certify that the following equipment conforms to the requirements of CE including EMC to the heavy industrial standard Class A.

Equipment Covered

| Product name | Description | Part number |
|---------------|---|-------------|
| SL mini 1220 | Unidirectional non-contact speed and length gauge (stand-off distance: 120mm, depth-of field: 20mm) | 00050MC001 |
| SL mini 3060 | Unidirectional non-contact speed and length gauge (stand-off distance: 300mm, depth-of field: 60mm) | 00050MC002 |
| SLR mini 1220 | Bidirectional non-contact speed and length gauge (stand-off distance: 120mm, depth-of field: 20mm) | 00050MC011 |
| SLR mini 3060 | Bidirectional non-contact speed and length gauge (stand-off distance: 300mm, depth-of field: 60mm) | 00050MC012 |

The manufacturer of the above named equipment is:

Proton

Proton Products is an ISO9001:2008 registered company.

The declaration is signed by:

Paul Alexander Sives



DECLARATION OF CONFORMITY (CSA)



This is to certify that the following equipment has been manufactured in compliance with the standards for Machine Safety and Workplace Electrical Safety according to the CSA (Canadian Standards Association).

Equipment Covered

| Product name | Description | Part number |
|---------------|---|-------------|
| SL mini 1220 | Unidirectional non-contact speed and length gauge (stand-off distance: 120mm, depth-of field: 20mm) | 00050MC001 |
| SL mini 3060 | Unidirectional non-contact speed and length gauge (stand-off distance: 300mm, depth-of field: 60mm) | 00050MC002 |
| SLR mini 1220 | Bidirectional non-contact speed and length gauge (stand-off distance: 120mm, depth-of field: 20mm) | 00050MC011 |
| SLR mini 3060 | Bidirectional non-contact speed and length gauge (stand-off distance: 300mm, depth-of field: 60mm) | 00050MC012 |

The manufacturer of the above named equipment is:

Proton

Proton Products is an ISO9001:2008 registered company.

The declaration is signed by:

Paul Alexander Sives



LASER SAFETY PARAMETERS



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Proton Products SL mini and SLR mini series laser speed and length gauges emit laser radiation with the following parameters:

| Parameter | Model | Minimum | Typical | Maximum | Units |
|---|----------|-----------|---------|---------|--------------------|
| Wavelength | All | 650 | 658 | 670 | nm |
| Beam diameter | All | | | 3 | mm |
| Spot size at standoff distance | All | | | 3 | mm |
| Beam divergence | All | | | 1.5 | mrad |
| Total emitted power | SL mini | | | 40 | mW |
| Total effilted power | SLR mini | | | 80 | mW |
| Emitted power per beam | SL mini | | | 20 | mW |
| (2 beams are emitted) | SLR mini | | | 40 | mW |
| Power density at gauge window | SL mini | | | 280 | mW/cm ² |
| (normal operation) | SLR mini | | | 560 | mW/cm ² |
| Power density at gauge window | SL mini | | | 560 | mW/cm ² |
| (absolute maximum) | SLR mini | | | 1120 | mW/cm ² |
| Power density at standoff distance | SL mini | | | 560 | mW/cm ² |
| Fower density at standon distance | SLR mini | | | 1120 | mW/cm ² |
| Nominal hazard zone (NHZ) distance (diffuse surface reflection)* | All | 20 to 100 | | | mm |
| Nominal hazard zone (NHZ) distance (specular / reflective surface reflection) | All | 150 | | | m |

^{*}this distance is highly dependent on the nature and type of diffuse surface.

For further information, please contact your Proton Products representative or Proton Products

Manufacturer signature:

Paul Alexander Sives:

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INTRODUCTION

The Proton Products SL mini and SLR mini series of laser speed and length gauges provide highly-accurate, non-contact speed and length measurement.

SL mini series gauges offer speed and length measurement for unidirectional production lines.

SLR mini series gauges offer speed and length measurement for bidirectional production lines. The gauge senses the direction of motion and will automatically increment or decrement the length accordingly. SLR mini gauges are thus suitable for production lines that undergo direction reversals or stationary (zero speed) periods.

Compared to traditional contact wheel encoders, SL mini / SLR mini non-contact speed and length gauges offer the following advantages:

- Capable of measurement at much higher speeds and accelerations
- No slippage
- Greater accuracy
- No wear or damage to the measured object
- Solid state design results in higher reliability and MTBF

RS-232 and Ethernet communication interfaces are installed as standard for straightforward connection to computers or PLCs. One optional industrial standard communication interface (PROFIBUS, EtherNet/IP or DeviceNET; replaces the standard Ethernet interface) may also be installed in the gauge.

User configurable digital inputs are provided as standard to reset gauge measurements and trigger printing. User configurable digital outputs are provided as standard to signal gauge status and preset length reached.

PRINCIPLE OF OPERATION

SL mini series unidirectional speed and length gauges illuminate the measured surface with a precisely pitched interference pattern created by the intersection of two laser beams. The alternating bright and dark interference fringes modulate the light scattered by the object with a frequency proportional to the object speed. This scattered light is detected by a photodiode and the electrical signal digitally processed to determine the frequency and hence the speed. Object length is then calculated by integrating the speed measurement over time.

SLR mini series bidirectional speed and length gauges extend this principle by using a high-frequency Bragg cell modulator to illuminate the measured surface with a scanning interference pattern, which generates an oscillating light signal even when the object is stationary. Direction of motion is determined by whether the scattered light frequency is higher or lower than the stationary frequency.

PRINCIPLE OF OPERATION

LASER BEAMS: SIDE VIEW

LASER DOPPLER PATTERN



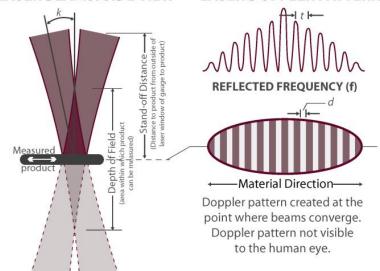
 $d = \frac{\lambda}{2\sin\kappa}$ • Fringe spacing is a function of laser function of laser wavelength and beam angle.



 Doppler frequency is proportional to speed and inversely proportional to fringe spacing.

$$L = \int_0^T dvt$$

 $L = \int_0^T dvt$ • Speed is integrated to measure length.



SPECIFICATIONS

MODEL-SPECIFIC SPECIFICATIONS

| Specification | Unidirectional – SL mini | | Bidirectiona | Units | |
|----------------------------|--------------------------|------|--------------|-------|--------|
| Specification | 1220 | 3060 | 1220 | 3060 | Ullits |
| Minimum speed | 0.1 | 0.25 | 0 | 0 | m/min |
| Maximum speed | 2000 | 5000 | ±2000 | ±5000 | m/min |
| Nominal stand-off distance | 120 | 300 | 120 | 300 | mm |
| Depth of field | 20 | 60 | 20 | 60 | mm |

COMMON SPECIFICATIONS

| Specification | Minimum | Typical | Maximum | Units |
|--------------------------|---------|---------|---------|------------------|
| Accuracy | -0.05 | | 0.05 | % |
| Repeatability | -0.02 | | 0.02 | % |
| Acceleration | | | 1000 | m/s ² |
| Measurement update time | | | 20 | μs |
| Laser beam diameter | | | 3 | mm |
| Laser classification | | | 3B | - |
| Operating temperature | +5 | | +40 | °C |
| Environmental protection | | | IP67 | - |
| Power supply voltage | 15 | 24 | 28 | VDC |
| Power consumption | | | 15 | W |
| | | | | |
| Length | | | 140 | mm |
| Width | | | 105 | mm |
| Height | | | 50 | mm |

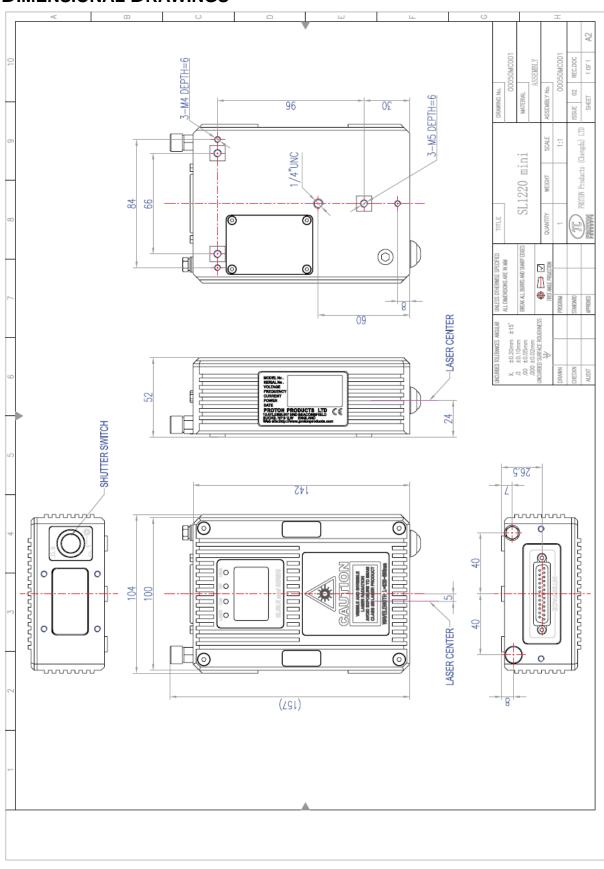
| Measurement display | Integrated backlit LCD | Integrated backlit LCD | | |
|---------------------|---|------------------------|--|--|
| Pulse outputs | 2x RS-422 compliant differential maximum pulse rate < 2 MHz (called end-user configurable as: | | | |
| | 2x independent pulse outputs | 1x quadrature output | | |
| Laser safety | Laser enable input | Open shutter input | | |

| | Shutter status output | | |
|---|--|-----------------|--|
| 2. Logic inputs (and upor configurable | Reverse Direction | Length Hold | |
| 3x Logic inputs (end-user configurable functions) | Reset | Speed Hold | |
| Turictions) | End of Reel | Display Hold | |
| | Gauge OK | Gauge too hot | |
| 2. Logic outputs (and upor configurable | Good reading | Object detected | |
| 2× Logic outputs (end-user configurable | Preset length 1 / Batch length reached | | |
| functions) | Preset length 2 / Batch number reached | | |
| | Gauge measuring speed | | |
| Standard communications interfaces | RS-232* | CANbus** | |
| Standard Communications interfaces | Ethernet TCP/IP (Modbus protocol) | | |
| Optional communications interface (select | ect PROFIBUS PROFINET | | |
| one; replaces the Ethernet interface) | DeviceNet | EtherNet/IP | |

^{*}An optional RS-232-to-USB converter cable is available for connection to USB equipped computers.

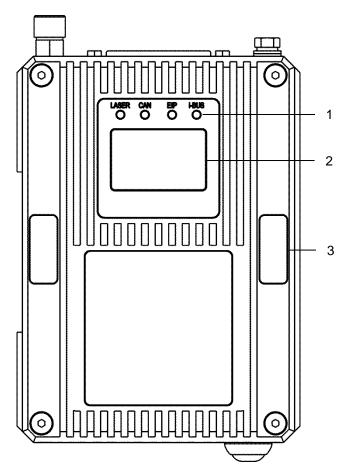
**CAN-bus protocol is proprietary and reserved for connection to other Proton Products equipment such as a CDI interface display unit.

DIMENSIONAL DRAWINGS



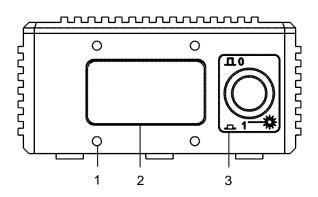
ANNOTATED DRAWINGS

TOP VIEW



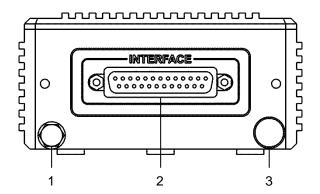
| Label | Description |
|-------|---|
| 1 | LED indicators |
| 2 | LCD display |
| 3 | Tamper-evident seal (x2; damage to or removal will invalidate the product warranty) |

FRONT VIEW



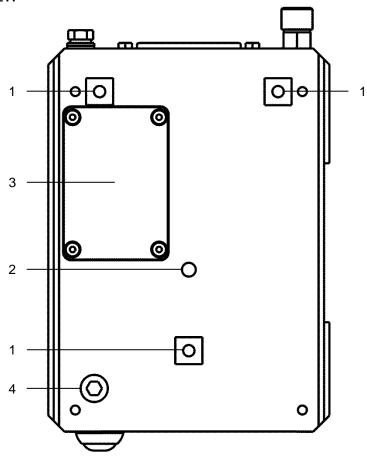
| Label | Description | | | | |
|-------|---|----------------------|-------------------|--|--|
| 1 | Optional air wipe / beam enclosure tube mounting holes (x4) | | | | |
| 2 | Optical window | | | | |
| | Laser shutter control switch | | | | |
| 3 | Switch status | Laser shutter status | Laser beam status | | |
| 3 | Out | Closed | Blocked | | |
| | In | Open | Emitting | | |

REAR VIEW



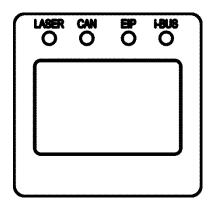
| Label | Description |
|-------|--|
| 1 | Earthing bolt |
| 2 | "INTERFACE" connector port |
| 3 | Nitrogen gas purge port (for factory use only; any attempt to open or connect to this port will invalidate the product warranty) |

UNDERSIDE VIEW



| Label | Description |
|-------|--|
| 1 | M5 threaded mounting hole (x3) |
| 2 | 1/4"-20 UNC threaded tripod mounting hole |
| 3 | Communications module compartment cover |
| 4 | Nitrogen gas purge port (for factory use only; any attempt to open or connect to this port will invalidate the product warranty) |

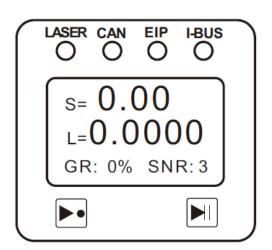
LED INDICATORS



| Label | Condition | Description |
|-------|--------------|--|
| LASER | Extinguished | No laser emission |
| LASER | Yellow | Laser emission |
| CAN | Extinguished | No CANbus connection |
| CAN | Green | CANbus connected |
| | Extinguished | No Ethernet connection |
| EIP | Green | Ethernet connected |
| | Flashing red | Ethernet data transmission |
| i-BUS | Extinguished | Optional DeviceNET / PROFIBUS / PROFINET / EtherNet/IP not connected |
| 1-003 | Green | Optional DeviceNET / PROFIBUS / PROFINET / EtherNet/IP connected |

ON-GAUGE LCD DISPLAY

The SL mini and SLR mini gauges are fitted with a backlit, on-gauge LCD which displays the following information:

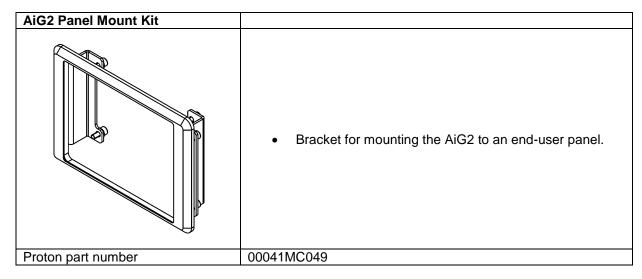


| Label | Description | |
|-------|--------------------------|---------------------------------------|
| S | Measured spee | d |
| L | Measured lengt | h |
| GR | Good Readings percentage | |
| SNR | Signal-to-Noise Ratio | |
| • | Reset button | Press to reset the length to zero. |
| M | Pause button | Press to pause the speed measurement. |

OPTIONAL ACCESSORIES

DISPLAY

| AiG2-SL/SLR | Display module |
|------------------------|---|
| 698.116. 261.427 mm | Connects via the CAN-bus port. Displays measured speed and length. Provides menu-based setting of all parameters. Bright VFD dot matrix display. |
| Proton part number | 00041MC045 |



| CAN-bus cable | | | |
|---------------|--------------|------------|--------------------|
| | Name | Length / m | Proton part number |
| | CAN 9DD_001M | 1 | 00041CB001 |
| | CAN 9DD_005M | 5 | 00041CB005 |
| | CAN 9DD_010M | 10 | 00041CB010 |
| | CAN 9DD_020M | 20 | 00041CB020 |
| L A | CAN 9DD_040M | 40 | 00041CB040 |
| | CAN 9DD_060M | 60 | 00041CB060 |
| | CAN 9DD_100M | 100 | 00041CB100 |
| 7 7 | | | |
| | | | |
| 110-275 | | | |
| | | | |

PCis_sl/slr mini PC Interface Software PC-based software package. User-friendly graphical user interface. Displays all measurements. Provides menu-based setting of all parameters. Provides trending, data logging, presets and alarms. Gauge to PC connection via RS-232. Proton part number 00050SW001

| 7"Touch Screen PC | Industrial PC |
|--------------------|--|
| | For running the above PCiS_SL/SLR mini software User-friendly graphical user interface. Displays all measurements. Provides menu-based setting of all parameters. Provides trending, data logging, presets and alarms. Gauge to PC connection via RS-232 or optional RS-232-to-USB interface cable (RSCon). |
| Proton part number | 00043MC029 |
| USB-RS232 Cable | |
| | For connecting the RS232 port of the PSU-BOB mini to the 7" Touch Screen PC. Length: 1.8m. |
| Proton part number | GP00000624 |

Power

PSU-BOB mini

Power supply and mini break out box

- Connects via the DB25 "INTERFACE" connector.
- Supplies 24VDC electrical power to the gauge.
- Provides screw terminal access to all electrical interfaces.
- Provides DB9 connectors for access to the CANbus, RS232 and industrial bus communications interfaces.
- Provides a RJ45 socket for the Ethernet interface.
- End user cables are sealed with three cable glands.
- Input voltage range: 90 260 VAC @ 45 65 Hz.
- Select the required length of DB25 cable from below.

Proton part number

Terminal Expander

00050MC039

| DB25 "INTERFACE" port to PSU-BOB mini cable | | | |
|---|---------------|------------|--------------------|
| | Name | Length / m | Proton part number |
| | BOB 25DD_001M | 1 | 00041CT001 |
| | BOB 25DD_003M | 3 | 00041CT003 |
| | BOB 25DD_005M | 5 | 00041CT005 |
| | BOB 25DD_010M | 10 | 00041CT010 |
| | BOB 25DD_020M | 20 | 00041CT020 |
| | BOB 25DD_030M | 30 | 00041CT030 |

Gauge-mounted break-out box

- Connects via the DB25 "INTERFACE" connector.
- Provides DB9 connector access to the RS-232, CANbus, Ethernet or optional industrial bus communications ports.
- Provides screw terminal access to all electrical input and output pins.
- End user cables are sealed with cable glands.

Proton part number

00050MC039

COMMUNICATIONS

Industrial Bus Module For connecting the gauge to industrial communications buses, such as used with PLCs. May be field retrofitted. Protocol Proton part number DeviceNET 00043MC006 PROFIBUS 00043MC022 PROFINET 00043MC031 EtherNet/IP 00043MC005

STANDS AND GUARDS

| Base Plate | | | |
|--------------------|---|--|--|
| | For securing a SL/SLR mini gauge to a mounting surface. | | |
| Proton part number | 00050MC042 | | |

| Vibration reducing kit | | | |
|------------------------|--|--|--|
| \$ | For use with the above Base Plate (00050MC042) in high-vibration environments. | | |
| Proton part number | 00050MC043 | | |

| 3D Adjuster Plate | |
|--------------------|---|
| | For use with the above Base Plate (00050MC042) for precision alignment of the SL/SLR mini gauge to the measured object. Provides ±3° of roll and yaw adjustment. |
| Proton part number | 00050MC044 |

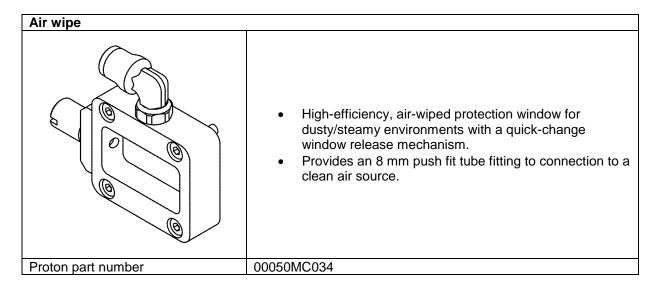
Enclosure of the laser beam to within 10mm of the object for laser safety and harsh environments.

00050MC033

| Laser Protection Tube for SL/SLR mini 3060 | | | | |
|--|---|--|--|--|
| | Enclosure of the laser beam to within 10mm of the object for laser safety and harsh environments. | | | |
| Proton part number | 00050MC037 | | | |

PROTECTION

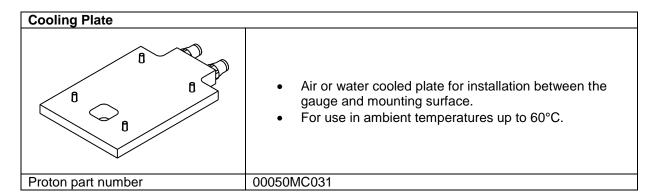
Proton part number



Air quality must meet or exceed ISO 8573.1:2001 Class 1.3.1 (solids.water.oil):

| Specification | Maximum | Units | Class |
|-----------------------------------|---------|-------------------|-------|
| 0.1 - 0.5 µm solid particle count | 100 | / m ³ | |
| 0.5 - 1 µm solid particle count | 1 | / m ³ | 1 |
| 1 - 5 µm solid particle count | 0 | / m ³ | |
| Water vapour pressure dew point | -20 | °C | 3 |
| Oil aerosol and vapour | 0.01 | mg/m ³ | 1 |

COOLING



INSTALLATION

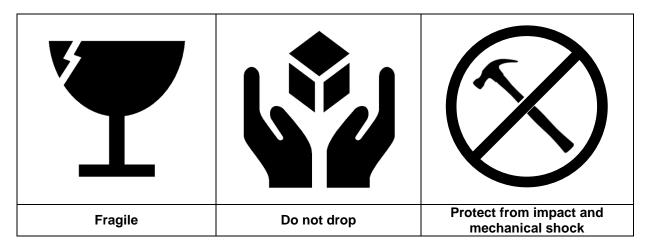
PRECAUTIONS

Operating and storage temperature

| Specification | Minimum | Typical | Maximum | Units |
|-----------------------|---------|---------|---------|-------|
| Operating temperature | +5 | | +45 | °C |
| Storage temperature | 0 | | +45 | Ç |

- Do not store or operate the gauge in temperatures outside of the specified ranges.
- Do not install the gauge near high temperature surfaces or objects which may cause it to overheat.
- Storage or operation of the gauge outside the specified temperature range may result in degraded measurement accuracy, malfunction or damage to the gauge.
- All gauges are fitted with internal temperature sensors which will permanently log any overtemperature condition that invalidates the warranty.

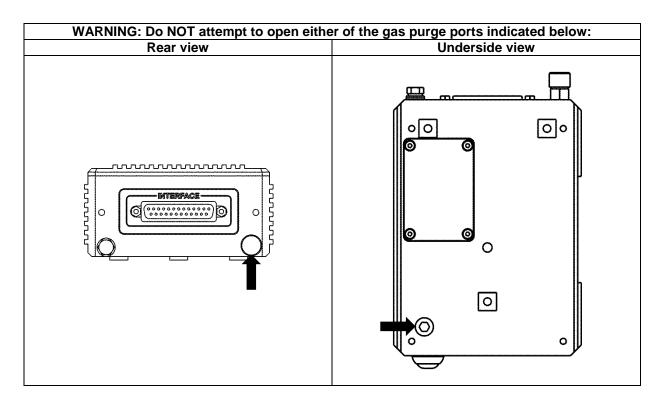
Protect from impact



- The gauge contains delicate optical and electronic assemblies and must never be dropped or struck by other objects.
- Only install the gauge on its mounting/stand when all machining, assembly and transportation
 of the mounting/stand has been completed.
- Do NOT strike, move or perform machining operations on the mounting/stand with the gauge installed.
- Damage incurred by the gauge as a result of impact, mechanical shock or rough handling is NOT covered by the manufacturer's warranty.

Do not open or disassemble

- The gauge contains no user serviceable components.
- Loosening the gauge screws or removing its cover will invalidate the gauge warranty.
- Damage to or removal of any of the anti-tamper stickers will invalidate the gauge warranty.
- The gauge is factory-purged with dry nitrogen gas to prevent condensation on the internal optics; opening of the gas purge ports (indicated below) will invalidate the gauge warranty.



Periodic maintenance

 The physical condition of the gauge, optional accessories and connecting cables should be checked periodically; if any damage is suspected, then the unit should be taken out of service for inspection and repair or replacement of damaged parts.

Laser radiation hazard

- This product emits class 3B laser radiation; do not view the laser beams emitted by the gauge either directly or by specular reflection.
- For all class 3B laser devices, the safety measures below MUST be provided. Some
 measures are the responsibility of the device manufacturer (Proton Products), whilst other
 measures are the responsibility of the end-user.
- For further information on laser safety, please refer to European standard BS EN 60825-1:2007 "Safety of laser products; Part 1: Equipment classification, requirements and user's guide".

| Safety Measure | Description | Provided by |
|---------------------------------|--|-------------|
| Laser Safety Officer | A Laser Safety Officer (LSO) must be appointed by the end-user organisation and is responsible for ensuring that both the equipment and staff comply with laser safety regulations. | End-user |
| Laser safety training | The end-user organisation must provide appropriate laser safety training for all operators and maintenance personnel working in close proximity to the gauge. | End-user |
| Laser enable key-switch | A key-switch to disable the laser diode should be wired to the LSR_EN input. The laser safety officer should be responsible for the key and must withhold it during system maintenance or it the system fails to comply with laser safety regulations. | End-user |
| | A laser enable key-switch is provided on the optional PSU-BOB-mini. | Proton |
| Contain and terminate beam path | Terminate the laser beams at the end of their useful length (behind the measured object) with a beam block. Contain laser beam paths with laser guards which have closure switches wired to the SHUT EN input so that the laser shutter is closed | End-user |

| Safety Measure | Description | Provided by | |
|--|---|----------------|--|
| | if any guard is opened. | | |
| | Do NOT permit the laser beams to be directed into open space. | | |
| Prevent | Never direct the laser beams at specular (mirror-like) reflectors. | | |
| specular (mirror-like) reflections | Remove all reflective objects such as jewellery or wristwatches before working near the laser beams. | End-user | |
| Emission | Illumination of the "LASER" LED on the gauge indicates laser emission. | Proton | |
| indicator | An external laser emission warning light may be triggered by the SHUT_ST output. | End-user | |
| Laser shutter | The switch to the side of the laser window opens or closes the laser shutter which blocks laser emission. | Proton | |
| switch | If the gauge is to be mounted in an inaccessible location, then this switch should be set to the open position and a remote, external laser shutter switch wired to the SHUT_EN input. | End-user | |
| Laser protection eyewear | Laser protection eyewear rated with the Optical Density (OD) rated for Class 3B lasers must be worn whenever there is a risk of eye exposure to the laser, for example during gauge alignment (see the "Laser Safety Parameters" section for information on laser wavelength, power and power densities). | End-user | |
| Laser warning signs | Class 3B laser warning signs must displayed in the working area; precautions on the warning signs must be followed. Example class 3B laser warning signage: US standard European standard CAUTION S5mW max. WAVELENGTH λ=620~690nm | | |
| | AVOID DIRECT EXPOSURE TO BEAM CLASS 3B LASER PRODUCT WAVELENGTH λ=620~690nm | | |

Optical windows

- Do not allow smoke, water, steam, dust or other debris to come into contact with any of the optical window.
- Obstruction of the optical window may degrade measurement accuracy or inhibit measurement.
- If the optical window appears to be damaged or misaligned, then the unit should be sent to a Proton Products authorised service agent for repair.
- If the optical window requires cleaning, then refer to the cleaning procedure detailed below to minimise the risk of scratching the windows.

OPTICAL WINDOW CLEANING PROCEDURE

- The optical window is manufactured from anti-reflection coated optical glass; it must be treated with the same level of care as a high-performance camera lens.
- Before inspecting or cleaning the optical window, ensure that the gauge is powered
 off, the LSR_EN key-switch is locked out and no laser light is emitted.

| Required items | Notes |
|--|---|
| Small blower brush | Such as the type used to remove dust from camera lenses. |
| Lens cleaning tissues or micro-fibre lens cleaning cloth | Do NOT use facial tissues as these can scratch delicate optics. |
| Lens cleaning solution | Such as the type specified for cleaning camera lenses. |

- 1. Use the small blower brush to remove any visible dust on the optical window.
- 2. Apply a few drops of lens cleaning solution to a fresh lens cleaning tissue or a clean microfibre lens cleaning cloth.
- 3. Gently wipe the optical window from the centre outwards; apply only light pressure to the tissue or cloth when wiping the optical window.
- 4. Repeat as necessary with fresh tissues or a clean section of cloth until the optical window is clean and free of all smears and smudges.

INSTALLATION SEQUENCE

Unpack the gauge and check for missing accessories and shipping damage.

Mechanical installation:

1. Mount the gauge securely either on a user supplied mount or on an optional Proton Products mounting plate.

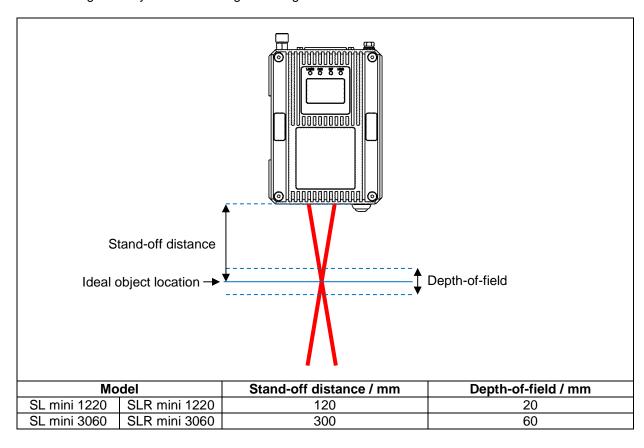
Electrical installation:

- 1. Install earth connections.
- 2. Connect the gauge to an optional Proton Products PSU-BOB mini power supply and breakout box.
- 3. Install laser safety connections (laser enable, shutter enable and shutter status).
- 4. Install communications interface connections (RS-232, Ethernet or optional PROFIBUS, PROFINET, EtherNet/IP or DeviceNET).
- 5. Install electrical interface connections (logic inputs, logic outputs, pulse outputs) using the optional Proton Products PSU-BOB mini breakout box or terminal strip.
- 6. Connect a PC installed with the PCiS_SLmini software to the gauge via the RS-232, Ethernet or optional PROFINET or EtherNet/IP communications interface.
- 7. Configure the gauge using the PCiS_SLmini software.

MECHANICAL INSTALLATION

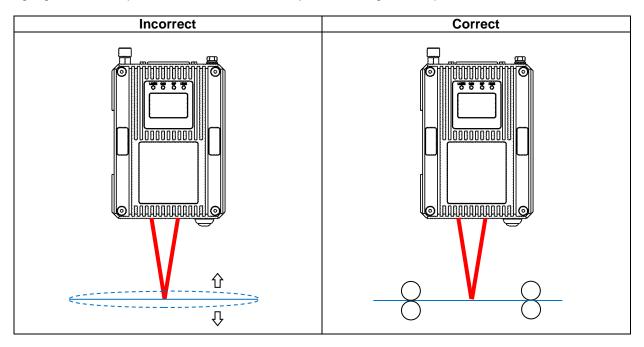
Stand-off distance and depth-of-field

- For best accuracy, locate the measured object at the specified stand-off distance to the gauge.
- Speed and length measurement is possible for objects located away from the specified standoff distance but still within the depth-of-field; however the measurement accuracy may be degraded by the reduced signal strength.



Object stabilisation

For accurate speed and length measurements, the distance between the measured object and the gauge must be kept constant; the measured object must be guided to prevent flutter:

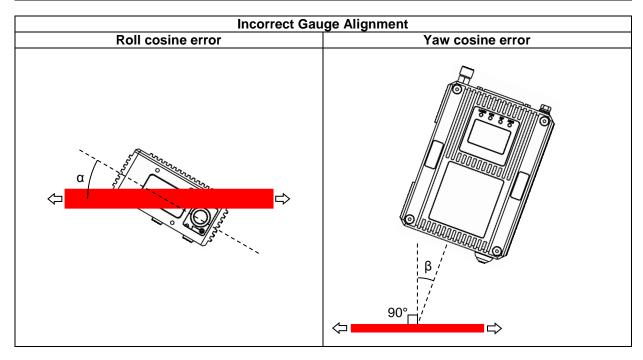


The end-user must provide suitable mechanisms for guiding and stabilising the motion of the measured object.

Optical alignment

Non-perpendicular alignment of the speed and length gauge to the measured object will degrade measurement accuracy; it is recommended the gauge is installed and aligned by technicians with metrology experience who understand the implications of even a small angular misalignment.

| Correct Gauge Alignment | | | | | | | |
|-------------------------|---------------|-----------------|--|--|--|--|--|
| | | Pitch alignment | | | | | |
| Roll alignment | Yaw alignment | Ideal | Acceptable for γ within ±5° (γ ≠ 0 may be used to prevent receiver saturation for highly-reflective objects) | | | | |
| | 90° | 90° | 90° | | | | |



Compounded roll and yaw cosine error Measured speed = (True object speed) \times cos (α) \times cos (β) Error angle α or β / degrees cos (α) or cos (β) Measurement error / % 1.000000 0 0.000 0.25 0.999990 -0.001 -0.004 0.50 0.999962 0.75 0.999914 -0.009 1.0 0.999848 -0.015 2.0 -0.061 0.999391 3.0 0.998630 -0.137 4.0 0.997564 -0.244 5.0 0.996195 -0.381

0.984808

10

-1.519

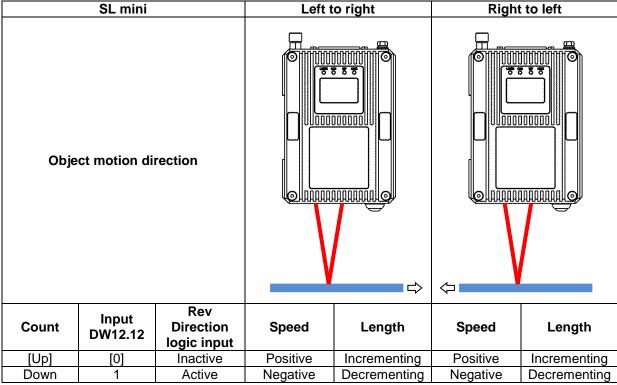
MEASUREMENT DIRECTION

SL MINI UNIDIRECTIONAL SPEED AND LENGTH GAUGE

The unidirectional SL mini speed and length gauge interprets motion in either direction as a positive speed and an increase in length, thus correct length accumulation requires that the object must only move in one direction (reverse motion will incorrectly cause the length to increment, not decrement).

Length measurements during line stoppage may exhibit a positive error due to microscopic vibration of the object; hence it is recommended that the "Length hold" function on the SL mini logic input is activated by the line controller when the line is stationary to temporarily suspend speed measurement and length accumulation.

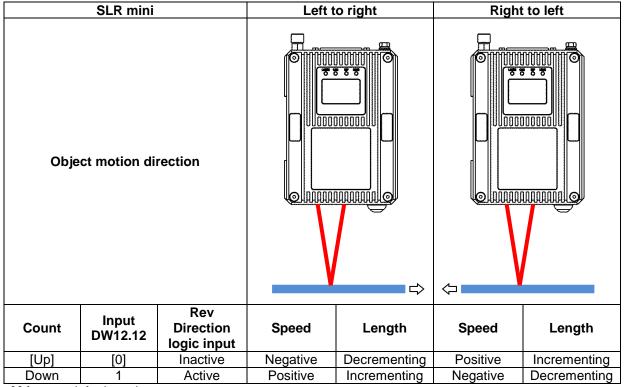
For production lines that require correct length accumulation during direction reversals or line stoppage (without using the "Length hold" function), it is recommended that the SLR mini is used.



^[] factory-default setting

SLR MINI BIDIRECTIONAL SPEED AND LENGTH GAUGE

The bidirectional SLR mini speed and length may be used for production lines that exhibit bidirectional motion and line stoppage.



^[] factory-default setting

Mechanical mounting

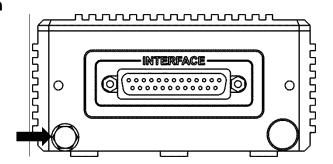
It is preferable for the gauge to be mounted in isolation from the machine or production line using a precision base plate fitted to a mounting arm (if this is not possible then the gauge must be mounted on rubber vibration isolation mounts). The mounting arm should be kept as short as possible to avoid vibration or twisting.

- Please see the dimensional drawings for mounting hole locations.
- Three M5 tapped holes are provided in the base of the gauge; select appropriate length screws which do not bottom out in these holes.

| Specification | Minimum | Typical | Maximum | Unit |
|---|---------|---------|---------|------|
| Mounting surface flatness (machined flat and even) | | | 0.15 | mm |
| M5 mounting hole depth (do not allow bolts to bottom out) | | | 6 | mm |
| M5 mounting bolt torque | | | 6 | Nm |

ELECTRICAL INSTALLATION

Earth connection



Connector type: M5 bolt

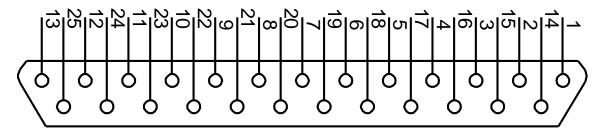
- An earth wire of at least 6mm² must be attached via a crimp on ring terminal to the dedicated M5 earth bolt on the case of the gauge.
- Do not rely on the mounting bolts to provide a reliable earth path.
- If a height stand is used then it must also be earthed via its own dedicated earth wire.
- All earth wires should be kept as short as possible.

Shielded Cables

- Use shielded cable for all signal connections.
- Ensure that all cable shields are correctly clamped and electrically connected to their connectors and metal connector shells at both ends.
- Ensure that the shields of cables connecting to the end user's equipment are clamped to earth at their destination.

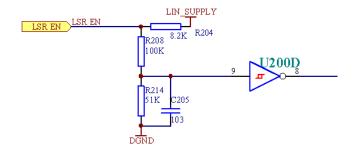
LASER ENABLE

- The laser enable input is provided for compliance with laser safety regulations.
- The laser diode in the gauge may be energised only if the "LSR_EN" pin (pin 14) is connected (via an external user-supplied switch contact) to any one of the "DGND" pins (pins 2, 15, 24).
- The gauge requires a few minutes for the laser temperature to stabilise and for valid measurement after "LSR_EN" is connected to "DGND". For this reason, it is recommended that the laser enable input is connected to a safety interlock that is active infrequently, such as a maintenance lock-out key switch.
- Safety interlocks that are frequently activated and require the gauge to immediately resume measurement upon deactivation (such as a machine guard door) should be connected to the shutter enable input ("SHUT_EN") described in the next section.



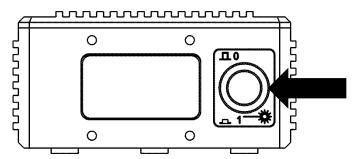
Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes | | |
|-------------------|---------------|-------------|-------------------------------------|------------------------|-------------------|--|
| Shield | S | Shield | Shield | Connect to cable and p | olug shields | |
| Power | 25 | +24V SUPPLY | +24V power supply | | | |
| supply and ground | 2 15 24 | DGND | Power supply and signal ground (0V) | | | |
| Laser | | | (0.7) | Connection | Laser diode state | |
| enable | 14 | LSR_EN | Laser enable | Open | Off (no emission) | |
| CHADIE | | | | Connected to DGND | On (emission) | |



SHUTTER CONTROL SWITCH, SHUTTER ENABLE INPUT AND SHUTTER STATE OUTPUT

The shutter control switch (located on the front of the gauge), the shutter enable input (SHUT_EN) and shutter status output (SHUT_ST) are provided for compliance with laser safety regulations.

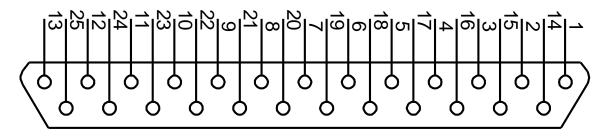


The SHUT_EN input and the shutter control switch operate in conjunction as follows:

| SHUT_EN input | Shutter control switch position | Shutter state | Laser output |
|-----------------|---------------------------------|---------------|--------------|
| Open | 0 | Closed | Blocked |
| Open | I | Closed | Blocked |
| Shorted to DGND | 0 | Closed | Blocked |
| Shorted to DGND | I | Open | Emitting |

- The shutter control switch and SHUT_EN input blocks laser beam emission without switching
 off the laser diode, thus no warm up time is required when the shutter is opened and the
 gauge may be used immediately for measurements.
- The SHUT_EN input is intended for connection to a safety interlock switch that may be frequently opened, such as on a machine guard or laser safety shield.
- The SHUT_ST output is electrically independent of the SHUT_EN input; the SHUT_ST signal
 is taken directly from an optical sensor in the path of the shutter, thus it indicates the shutter
 state even in the event of shutter actuator failure.

SHUT_EN input electrical specifications

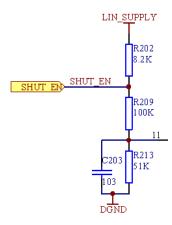


Connector type: DB25 female (socket)

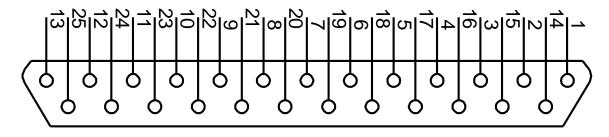
| Functional group | Pin | Designation | Description | Notes | | |
|------------------|-----|-------------|---------------|---|-------------|----------|
| Shield | S | Shield | Shield | Connect to cable and | connector s | hields |
| | 2 | | Power supply | | | |
| | 15 | DGND | and signal | | | |
| | 24 | | ground (0V) | | | |
| | | | | Connection | Shutter | Laser |
| Shutter | 13 | SHUT_EN | Shutter | Low state (logic 0) / connected to DGND | Open | Emitting |
| CONTROL | | | control input | High state (logic 1) / unconnected | Closed | Blocked |

- The SHUT_EN input is NOT isolated from earth.
- The input is internally pulled up to +15V via an 8.2kΩ resistor and will default to the high state if left unconnected.
- The input will source a minimum current of 3mA when externally pulled down to the low state.

| Specification | Minimum | Typical | Maximum | Units |
|------------------------------------|---------|---------|---------|-------|
| Low state (logic 0) input voltage | | | 3 | V |
| High state (logic 1) input voltage | 10.5 | | | V |
| Absolute input voltage | -30 | | 30 | V |
| Low state source current | 3 | | | mΑ |



SHUT_ST output electrical specifications

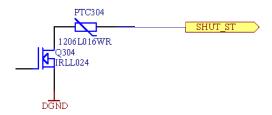


Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes | | |
|------------------|-----|-------------|-----------------------|----------------------|-------------|----------|
| Shield | S | Shield | Shield | Connect to cable and | connector s | hields |
| Power | 25 | +24V SUPPLY | +24V power supply | | | |
| supply and | 2 | | Power supply | | | |
| ground | 15 | DGND | and signal | | | |
| | 24 | | ground (0V) | | | |
| | | | | Signal | Shutter | Laser |
| Shutter control | 12 | SHUT_ST | Shutter status output | Pulled down to DGND | Open | Emitting |
| | | | | Floating | Closed | Blocked |

- The SHUT_ST output is NOT isolated from earth.
- The SHUT_ST output must NOT be used to directly drive high-current or inductive loads.
- It is recommended that the SHUT_ST output is used to drive an opto-isolated solid-state relay.

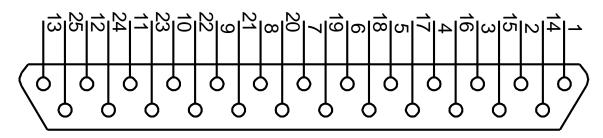
| Specification | Minimum | Typical | Maximum | Units |
|------------------------------|---------|---------|---------|-------|
| Logic output to DGND voltage | | | +25 | VDC |
| Current | | | 0.1 | Α |



POWER SUPPLY

| Specification | Minimum | Typical | Maximum | Units |
|-----------------------|---------|---------|---------|-------|
| Power supply voltage* | 15 | 24 | 28 | VDC |
| Power consumption | | | 15 | W |

^{*}If a long power supply cable with a significant voltage drop is used, then ensure that the voltage at the gauge connector does not fall below the minimum value.



Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes |
|------------------|-----|-------------|-------------------------------------|-------|
| Shield | S | Shield | Shield | |
| | 25 | +24V SUPPLY | +24V power supply | |
| Power | 2 | | Power supply and signal ground (0V) | |
| supply | 15 | DGND | | |
| | 24 | | | |

Powering on the gauge

The gauge has no power switch; as soon as power is applied it will power up and perform some self-tests. Measurement will begin after a warm-up period of a few minutes required for the temperature of internal components to stabilise.

Powering off the gauge

The gauge has no power switch; it may be powered off by switching off or disconnecting the power supply to the unit.

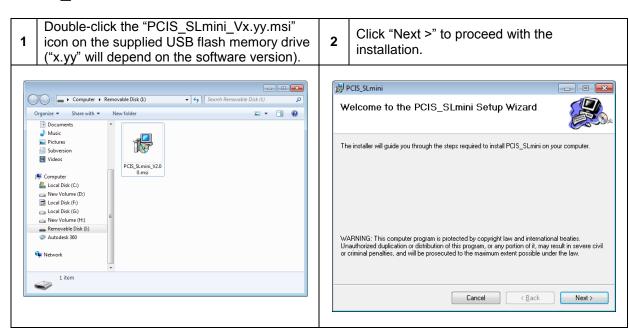
CONFIGURATION

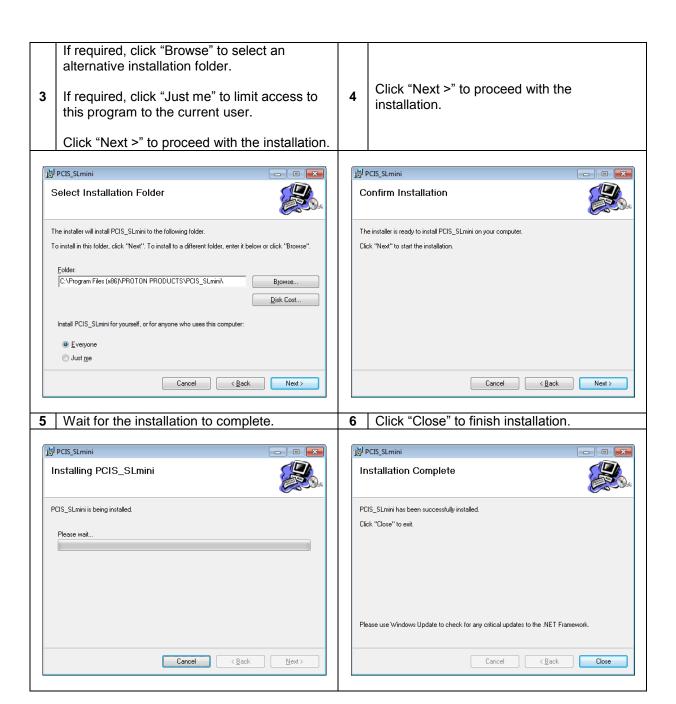
The SL mini and SLR mini series of speed and length gauges may be configured using a PC running the PCiS_SLmini software.

PCIS_SLMINI SOFTWARE PC SYSTEM REQUIREMENTS

| Minimum processor | Pentium 300 MHz CPU compatible or higher |
|------------------------------|--|
| Minimum RAM | 512 MB |
| Minimum free hard disk space | 100 MB |
| Display resolution | 1024 x 768 |
| Operating system | Microsoft Windows XP / Windows 7 / Windows 8 |
| | 100Base-TX Ethernet port or adapter card |
| Other requirements | RS-232 port or USB port and USB to RS-232 adaptor cable |
| | Keyboard and mouse (for configuration and software installation) |

PCIS_SLMINI SOFTWARE INSTALLATION





CONNECTION AND SOFTWARE START UP

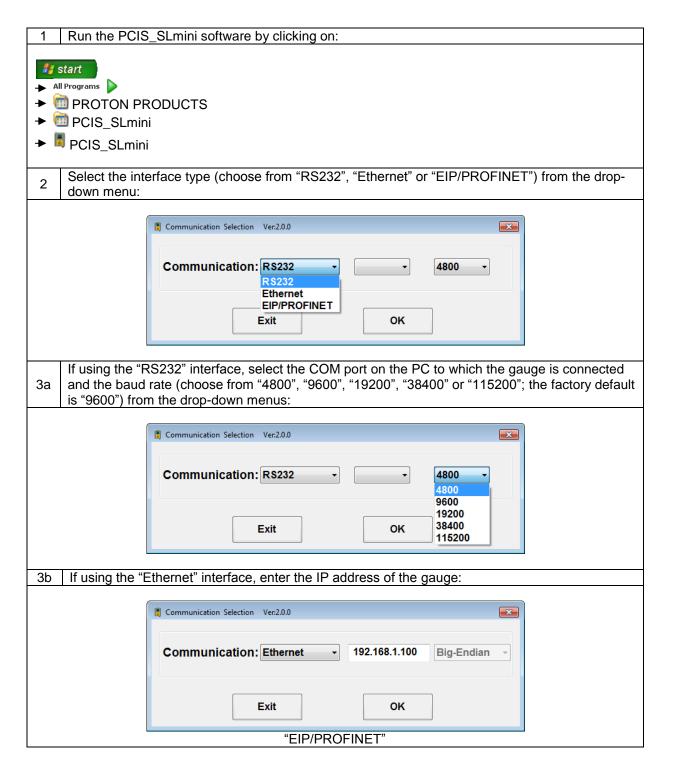
A PC running the PCiS_SLmini software may be connected to the gauge using any one of the following communications interfaces:

- RS-232 (fitted as standard on all gauges).
- Ethernet (only available if NO other optional communications interface has been installed).
- EtherNet/IP (only available if the gauge has been installed with the optional EtherNet/IP communications interface)
- PROFINET (only available if the gauge has been installed with the optional PROFINET communications interface)

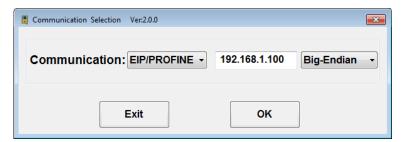
Note: For gauges communicating over either optional EtherNet/IP or PROFINET communications interfaces, only input and output parameters DW0 to DW31 are visible to the PCiS software.

The above communications interfaces may be directly accessed via the DB25 "INTERFACE" connector on the rear of the gauge or via a PSU-BOB mini connected to the "INTERFACE" port; for wiring information, please refer to the following sections in this manual:

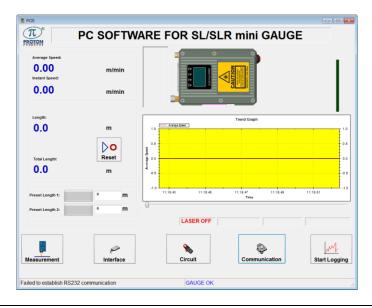
- RS-232 Communications
- Ethernet Communications
- EtherNet/IP or PROFINET Communications



3c If using the "EIP/PROFINET" interface, enter the IP address of the gauge and select "Big-Endian" or "Little-Endian" data format (the factory-default is "Big-Endian"):

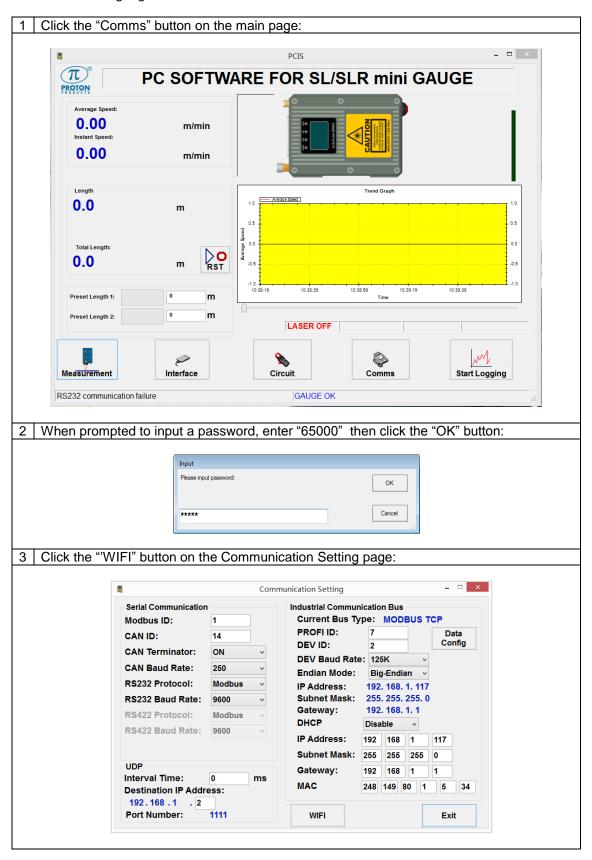


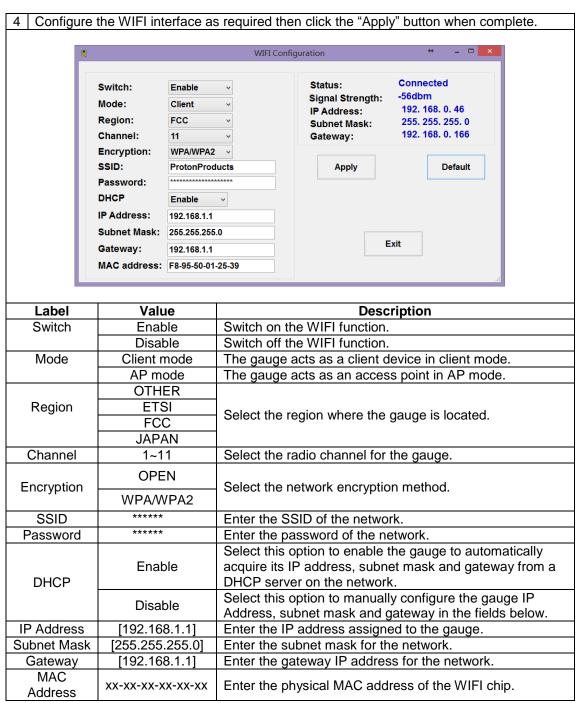
4 Click the "OK" button to proceed.



WIFI CONFIGURATION

The WIFI function can be configured via the PCiS_SLmini software after a PC connection is established with the gauge.





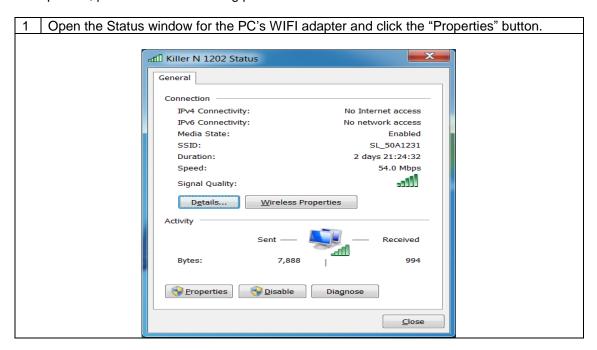
^{* []} indicates factory-default values.

Note: To restore the gauge to factory-default network settings, click the "Default" button. See the table above for the factory-default values.

The WIFI function can also be enabled or disabled manually using the physical hardware buttons on the gauge. To do this, first enter the WIFI interface configuration screen by long pressing [Li] (the pause button) while the gauge is powering on. Then press [Li] (the reset button) to enable or disable the WIFI function. Press the pause button to exit the WIFI interface configuration screen.



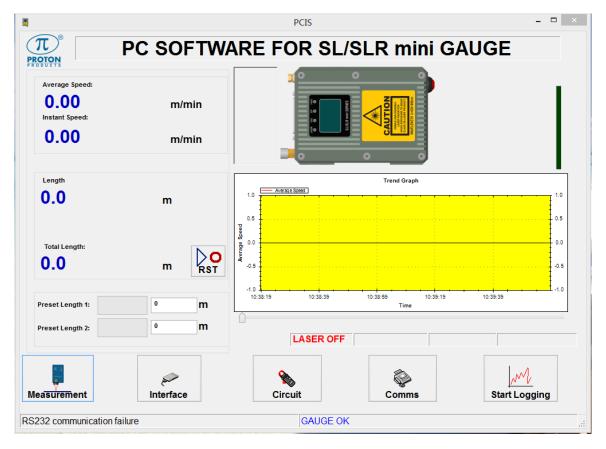
In the event of communication issues, it may be necessary to enable the Federal Information Processing Standards (FIPS) compliance on the PC connected with the gauge. To enable the FIPS compliance, please use the following procedure:



Click the Advanced settings button on the Security tab. SL_50A1231 Wireless Network Properties Connection Security WPA2-Personal Security type: Encryption type: Network security key Show characters A<u>d</u>vanced settings OK Cancel Check the tick box next to "Enable Federal Information Processing Standards (FIPS) 3 compliance for this network" then click the "OK" button. Advanced settings 802.11 settings Enable Eederal Information Processing Standards (FIPS) compliance for this network

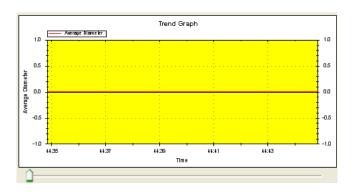
Cancel

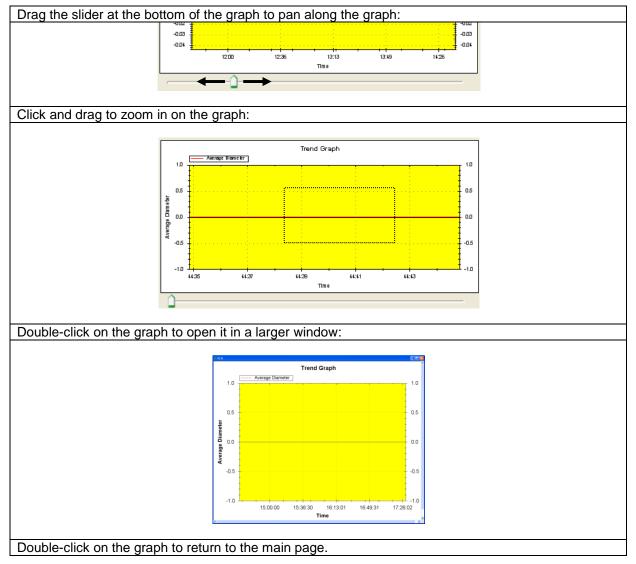
PCIS_SLMINI MAIN PAGE



| Label | Description | | |
|-----------------|--|---|--|
| Average Speed | Displays the time-averaged measured object speed. | | |
| Instant Speed | Displays the ins | tantaneous measured object speed. | |
| | | | |
| Length | Normal mode | Displays the measured length. | |
| Lengui | Batch mode | Displays the measured length of the current segment. | |
| Total Langth | Normal mode | Displays the measured length (identical to "Length" above). | |
| Total Length | Batch mode | Displays the total measured length of all segments. | |
| Reset | Click this button to reset the measured "Length" and "Total Length" to zero. | | |
| | | | |
| Preset Length 1 | Click to enter "Preset Length 1" at which the corresponding logic output is activated. | | |
| | The bar graph indicates the measured length relative to this preset. | | |
| Preset Length 2 | Click to enter "Preset Length 2" at which the corresponding logic output is activated. | | |
| | The bar graph indicates the measured length relative to this preset. | | |

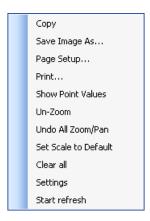
TREND GRAPH

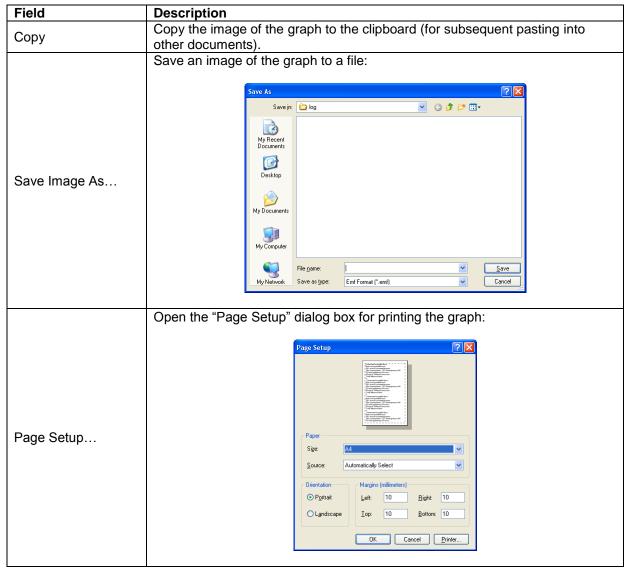


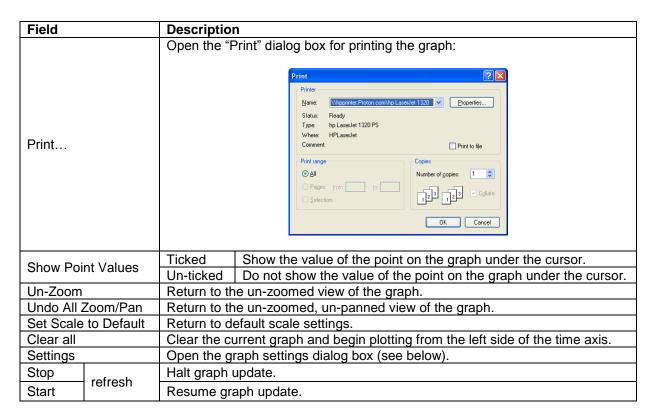


Context menu

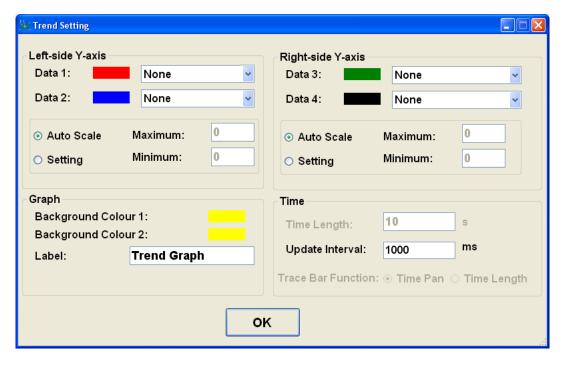
Right-click on the graph to open the context menu:





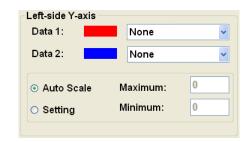


Settings



Click the "OK" button to return to the main page.

Left-side Y-axis



| Field | Description | |
|------------|---|--|
| Data 1 | Click on the drop down box to select the data plotted on this axis. | |
| Dala 1 | Click on the coloured box to select the line colour. | |
| Data 2 | Click on the drop down box to select the data plotted on this axis. | |
| Dala 2 | Click on the coloured box to select the line colour. | |
| Auto Scale | Click to allow the software to automatically set the minimum and maximum values for | |
| Auto Scale | this axis. | |
| Setting | Click to manually set "Maximum" and "Minimum" values for this axis. | |
| Maximum | Click to enter the maximum value for this axis. | |
| Minimum | Click to enter the minimum value for this axis. | |

Clicking on "Data" or colour boxes will open the colour selection dialog:



Right-side Y-axis



| Field | Description |
|------------|---|
| Data 3 | Click on the drop down box to select the data plotted on this axis. |
| Data 3 | Click on the coloured box to select the line colour. |
| Data 4 | Click on the drop down box to select the data plotted on this axis. |
| Dala 4 | Click on the coloured box to select the line colour. |
| Auto Scale | Click to allow the software to automatically set the minimum and maximum values for |
| Auto Scale | this axis. |
| Setting | Click to manually set "Maximum" and "Minimum" values for this axis. |
| Maximum | Click to enter the maximum value for this axis. |
| Minimum | Click to enter the minimum value for this axis. |

Clicking on "Data" or colour boxes will open the colour selection dialog:



Graph



| Field | Description |
|------------|--|
| Background | Click on the coloured box to select the top left corner background colour for the graph; |
| Colour 1 | this colour will be graded across the graph to "Background Colour 2". |
| Background | Click on the coloured box to select the bottom right corner background colour for the |
| Colour 2 | graph; this colour will be graded across the graph to "Background Colour 1". |
| Label | Click to enter a title for the graph. |

Clicking on "Background Colour" colour boxes will open the colour selection dialog:



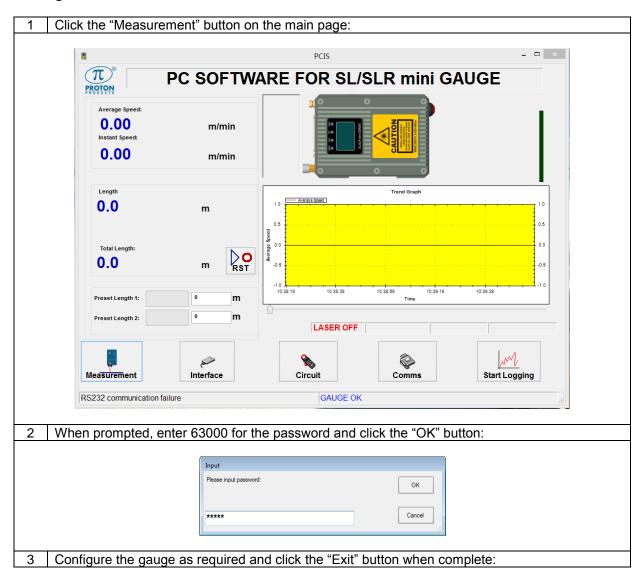
Time

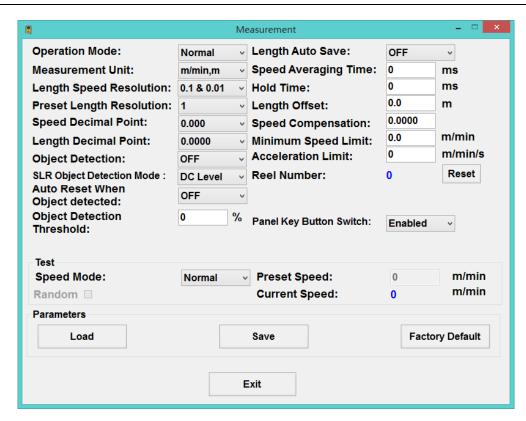


| Field | Description |
|----------|--|
| Update | Set the time interval at which data is updated on the graph; a shorter time interval will result |
| interval | in a more detailed graph, whilst a longer time interval is clearer at showing long-term trends. |

MEASUREMENT CONFIGURATION

Configuration via the PCiS_SLmini software:





| Label | Value* | Description | Input DW |
|-------------------------|------------------|---|-------------|
| Operation | [Normal] | See the section below to determine the appropriate | |
| Mode | Batch | operation mode. | 0.0 |
| | [Meter] | Select for length measurement in metres and speed | |
| | [] | measurement in meters per minute | |
| | Feet | Select for length measurement in feet and speed | 0.3-4 |
| Measurement | | measurement in feet per minute. | |
| Unit | Yards | Select for length measurement in yards and speed | |
| | | measurement in yards or feet per minute. | |
| | Inch | Select for length measurement in inch and speed | |
| | | measurement in feet per minute. | |
| | | Select to set the length resolution to 0.1 units and speed | |
| | 0.1 & 0.01 | resolution to 0.01 units/minute, where the units are | |
| | | metres, feet or yards depending on the "Measurement | |
| Length Speed | | Unit" setting. | 0.8 |
| Resolution | | Select to set the length resolution to 0.0001 units and | 0.0 |
| | [0.0001 & 0.001] | speed resolution to 0.001 units/minute, where the units | |
| | | are metres, feet or yards depending on the | |
| | | "Measurement Unit" setting. | |
| | 0 | | |
| Speed | 0.0 | Set the number of digits after the decimal point to be | _ |
| Decimal Point | 0.00 | displayed for the measured speed. | |
| | 0.000 | | |
| | 0 | | |
| Length Decimal Point | 0.0 | Sot the number of digite ofter the desimal point to be | |
| | 0.00 | Set the number of digits after the decimal point to be displayed for the measured length. | |
| | 0.000 | displayed for the measured length. | |
| | 0.0000 | | |
| Object | [OFF] | See the section below for information on "Object | |
| Detection ON | | Detection" mode. | 0.11 |

| Auto Reset | [OFF] | Accumulate the length measurement across all discrete objects. | 0.40 |
|---|--|--|------|
| When Object Detected | ON | Reset the length measurement on detection of the next discrete object. | 0.12 |
| Object Detection Threshold | 0 ~ [15] ~100% Set a DC level percentage threshold above which an object is considered as present. | | - |
| Longth Auto | [OFF] | The length measurement will be reset to zero when the gauge is powered-up. | |
| Length Auto Save | ON | The length measurement just prior to a power interruption is stored in non-volatile memory and will resume from this stored value on subsequent power-up. | 0.10 |
| Speed Averaging | 5 ~ [200] ~ | Set the time period (in milliseconds) over which the measured speed is averaged. | 2 |
| Time | 5000ms | A longer averaging period results in a more stable speed measurement (and pulse output rate) which is less sensitive to small and sudden speed changes. | |
| | 4 [400] | Set the time to hold the last speed measurement after speed signal loss. | |
| Hold Time | 1 ~ [100] ~ 5000ms | The "Hold Time" should be set to a sufficiently long period to cover any momentary speed signal dropouts due to surface irregularities on the measured object. | 3 |
| | 0000 | Set the length offset value. | |
| Length Offset | -3000.0 ~ 3000.0 m{ft}{yds}{inch} | For an object threaded through the production line, the unmeasured length located beyond the gauge may be entered here (as a positive value) to add to the measured length to yield the correct total length. | 14 |
| Speed Compensation | [1.0000] | Set a value other than the default value of 1.0000 to apply a compensation factor to the measured speed. | 38 |
| Minimum Speed Limit | [0] ~ 6553.5 m{ft}{yds}/min | Set the minimum speed at which the gauge is required to measure speed; for speeds below this value, the gauge will register a speed of zero. This value may be set to avoid drift in the measured length when the object is stationary due to measurement | 11 |
| Acceleration | 1 ~ [9999] | Not currently in use. | 39 |
| Limit | m{ft}{yds}/min/s | Displays the current reel number. | 33 |
| Reel Number | | The "Reel Number" may be incremented by activation of a logic input configured for the "End of Reel" function. | - |
| Panel Key | [Enabled] | When "Enable" is selected, the two buttons (Reset and Pause) located on the LCD display of the gauge will be active. | |
| Button Switch | Disabled | When "Disable" is selected, the two buttons (Reset and Pause) located on the LCD display of the gauge will be inactive to avoid wrong operations. | |
| | | Click to reset the "Reel Number" to zero. | |
| Reset | | The "Reel Number" may also be reset by activation for longer than 5 seconds of a logic input configured for the "Reset" function. | |
| The "Test" function simulates the measurement of a user set speed by the gauge even when there is no object being measured; pulse outputs will generate pulses corresponding to the "Preset Speed". | | | |

| Crood Mode | Normal | Select for normal operation. | |
|--------------------|---|--|----|
| Speed Mode | Simulation | Select for simulated measurement. | |
| Random | Unticked | The gauge will behave as if it is measuring the "Preset Speed". | |
| Kandom | Ticked | The gauge will behave as if it is measuring a randomly changing speed. | - |
| Preset Speed | 0 ~[100] ~6553.5 m{ft}{yds}/min | Set the required simulation speed measurement. | 45 |
| Current Speed | | This indicates the current simulated speed. | |
| | | | |
| Parameters | Parameters The "Parameters" section is for bulk saving and loading of parameters settings to and from a file. | | |
| Load | Load parameters from a file. | | - |
| Save | | Save current parameters to a file. | |
| Factory Default | | Restore parameters to their factory default values. | 40 |
| Exit | | Click to return to the main page. | - |

^{*} factory-default values are shown in enclosed in [].

Normal Operation Mode

In "Normal" operation mode, the user may set two length presets ("Preset Length 1" and "Preset Length 2").

Whenever the measured length **exceeds** any length preset, the corresponding logic output assigned to that length preset will be activated (pulled-low).

The logic output will be deactivated (floating) when:

- The measured length is reset to zero by:
 - Activating a logic input configured for the "Reset" function.
 - o Clicking the PCiS_SLmini software "Reset" button.
 - Writing logic 1 to input parameter DW0.1.
- The measured length falls below the length preset (applicable only to the SLR mini when the measured length is decrementing due to line direction reversal).

Batch Operation Mode

"Batch" operation mode is used when a continuous object is being measured for marking (e.g. by an inkjet printer) or cutting (e.g. by a guillotine) at regular intervals.

In "Batch" mode, the user may set a "Batch Length" and a "Batch Number".

As each "Batch length" segment of the object is measured, the corresponding logic output assigned to the "Batch Length" function will be *momentarily* activated (pulled-low; the activation time may be configured by the user).

When the total number of segments measured *equals or exceeds* the "Batch Number", then the corresponding logic output assigned to the "Batch Number" function, will be activated (pulled-low).

The real-time measured segment and total lengths may be viewed using the PCiS_SLmini software or read out of the gauge from output parameters DW6-7 and DW12-13 respectively. The current segment number may be read from output parameter DW10.

^{} indicates alternative units depending on the "Measurement Unit" setting.

| DW | Bit | Comments | Units | Range/Remark |
|----|-----|----------------|---|---------------|
| 6 | | Longth | Old format: 1=0.1m{ft}{yds}{inch} | ±200.000.0000 |
| 7 | | Length | New format: 1=0.0001m{ft}{yds}{inch} | ±200,000.0000 |
| 10 | | Batch number | 1=1 | |
| 12 | | Total length | 1=0.1m{ft}{yds}{inch} | ±200.000.0000 |
| 13 | | Total leligiti | 1=0. III(it)(yus)(iiicii) | ±200,000.0000 |

The "Batch Number" logic output will be deactivated (floating) when the measured length is reset to zero by:

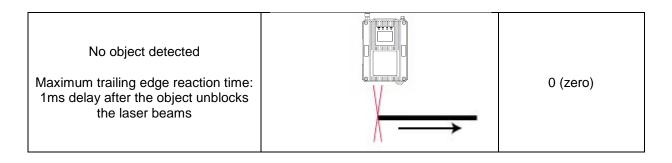
- Activating a logic input configured for the "Reset" function.
- Clicking the PCiS_SLmini software "Reset" button.
- Writing logic 1 to input parameter DW0.1.

Object Detection Mode

The "Object Detection" mode is used when measuring the speed and length of *discrete* objects (e.g. multiple separate parts on a conveyor belt). The "Object Detection" mode forces the speed reading to zero when no object is present.

An object is determined as present if the detected DC level (in percent) exceeds the "Object Detection Threshold"; the factory default value for this threshold is 15% and it may be adjusted on the "Measurement" page of the PCiS_SLmini software in the event of incorrect object detection behaviour.

| Status | | Speed measurement |
|---|--|-------------------|
| No object detected | | 0 (zero) |
| Object detected Maximum leading edge reaction time: 1ms delay after the object blocks the laser beams) | | Line speed |
| Object detected | | Line speed |



The "Object Detection" mode may be configured to automatically reset the measured length when a new object is detected:

| Auto Reset When Object Detected* | Length measurement behaviour |
|-------------------------------------|--|
| [OFF] | The gauge measures the total length accumulated across multiple discrete objects. |
| ON | The gauge measures the length of each individual discrete object; detection of the next object resets the length measurement to zero so that only the length of the next object is measured. |

^{* []} indicates the factory-default setting.

"Hold Time" behaviour in "Object Detection" mode

In "Object Detection" mode, the "Hold Time" only applies when an object is detected.

If an object is detected, but the speed signal is momentarily lost (possibly due to a surface defect on the object), then the gauge will hold the last speed measurement for the "Hold Time" period and accumulate length accordingly during this period.

The "Hold Time" should be set to a sufficiently long period to cover any momentary speed signal dropouts due to surface irregularities on the measured object.

When an object is not detected, the gauge will NOT hold the last speed measurement (or accumulate length).

STANDARD COMMUNICATIONS INTERFACES

CAN-BUS COMMUNICATIONS

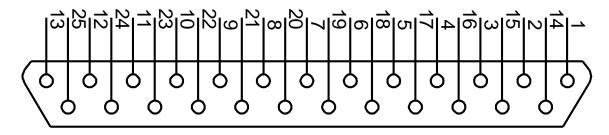
This CAN-bus interface is fitted as standard. It operates independently of the other communications interfaces and may be accessed at the same time as them.

The CAN-bus interface uses a proprietary Proton Products protocol. It is exclusively used to communicate between the unit and other Proton Products modules. The unit automatically detects connection to other modules and configures the bus appropriately; it is not normally necessary to manually configure this interface.

The CAN-bus interface is not intended for use with an external CAN-bus network.

CAN-bus interface

The CAN-bus interface may be accessed through the following pins:



Connector type: DB25 female (socket)

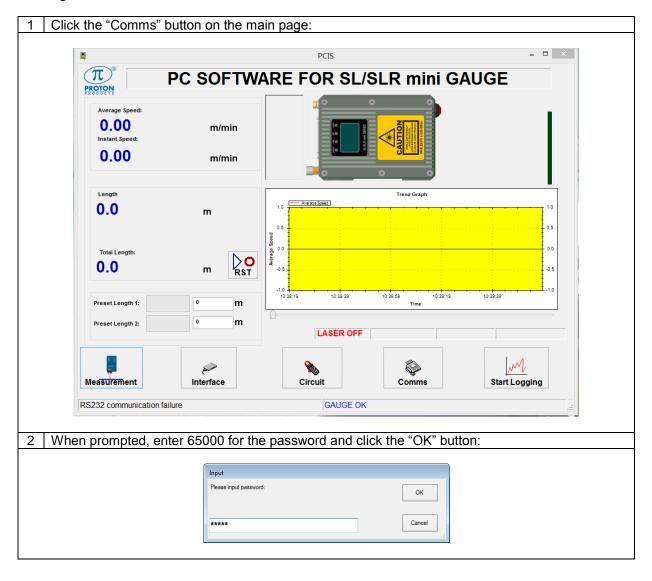
| Functional group | Pin | Designation | Description | Notes |
|------------------|-----|-------------|-------------------------------------|--|
| Shield | S | Shield | Shield | Ensure that the cable shield is connected to the plug shield connection. |
| | 25 | +24V SUPPLY | +24V power supply | |
| Power | 2 | | Dower aupply and | |
| supply | 15 | DGND | Power supply and signal ground (0V) | |
| | 24 | | signal ground (0v) | |
| CANbus | 8 | CAN H | CANbus high | |
| | 9 | CAN L | CANbus low | |

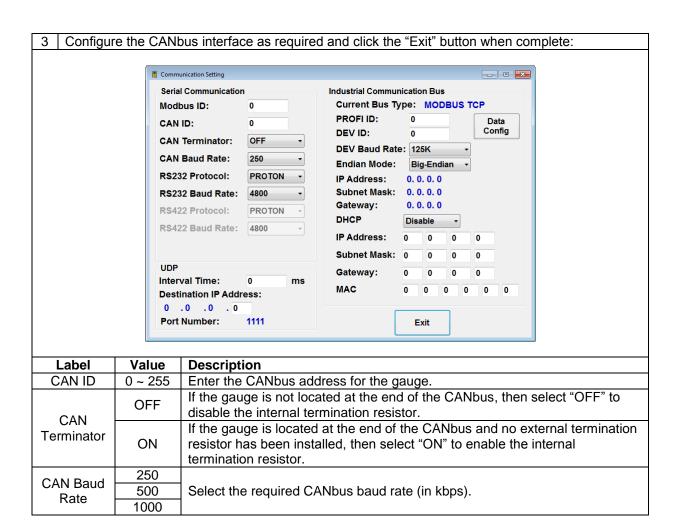
CAN-bus LED indicator

| CAN | | LED status | Indication |
|------------------------|--|----------------|---------------------|
| CAIN | | Flashing green | Online |
| CAN-bus communications | | Flashing red | Communication error |
| | | Extinguished | No communication |

CAN-bus configuration

Configuration via the PCiS_SLmini software:





Configuration via input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|----------------|------|---------------------------------------|---------|
| 21 | | CAN address | 1=1 | 0~255 | 14 |
| 22 | | CAN baud rate | | 0=250 1=500 2=1000 other=500 | 2 |
| 36 | | CAN terminator | 1=1 | 0=Off 1=On | 0 |

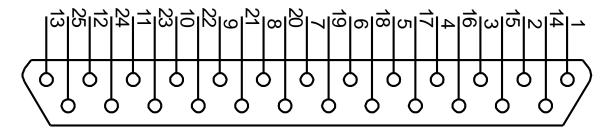
RS-232 COMMUNICATIONS

This RS-232 interface is fitted as standard. It operates independently of the other communications interfaces and may be accessed at the same time as them.

If the RS-232 interface "Mode" is set to "ZM400 Printer", then a Zebra ZM400 printer may be connected to the port to print reel report tickets when triggered by the "End of Reel" logic input.

RS-232 interface

The RS-232 interface may be accessed through the following pins:



Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes | PC DB9 serial port pin |
|-------------------------|---------------|-------------|---|--|------------------------|
| Shield | S | Shield | Shield | Connect to cable and connector shields | Shield |
| Power supply and ground | 2 15 24 | DGND | Power supply and signal ground (0V) | | 5 |
| RS-232 | 16 | RXD | RS-232 receive | | 3 |
| RS-232 | 17 | TXD | RS-232 transmit | | 2 |

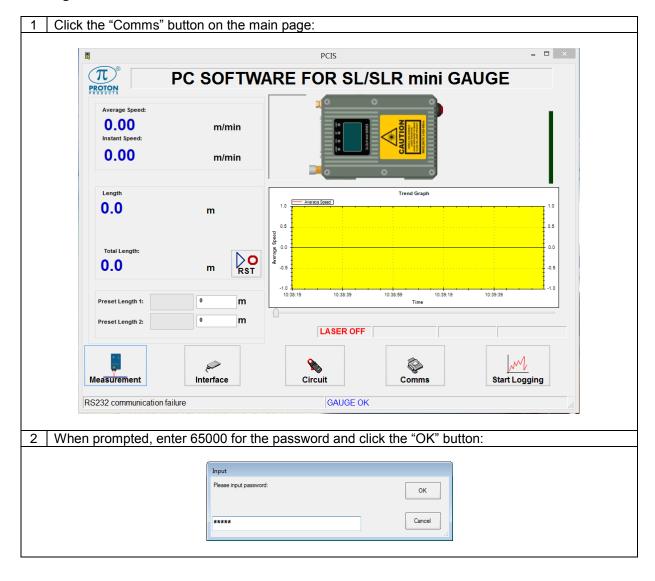
The above table also shows the configuration of a cable for connection to a personal computer (PC) type DB9 serial port.

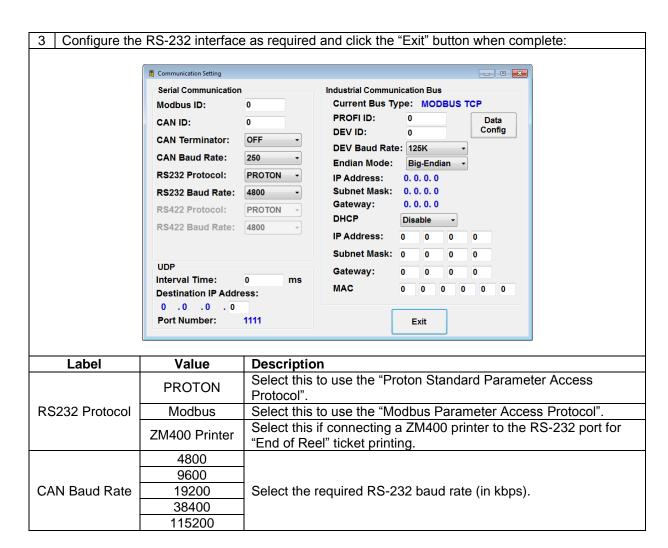
The maximum baud rate depends on the cable capacitance and length. For low-cost overall shielded cable with total capacitance of shield to core-plus-core to core of 300pF per metre, the maximum recommended baud rates are as follows:

| Cable lengt | h range / m | Maximum Baud rate / s |
|-------------|-------------|-----------------------|
| 0 | 3 | 115200 |
| 3 | 10 | 38400 |
| 10 | 20 | 19200 |
| 20 | 40 | 9600 |
| 40 | 80 | 4800 |

RS-232 Communications configuration

Configuration via the PCiS_SLmini software:





Configuration via input parameters:

This interface may be configured by writing to the following input parameters:

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|-----------------|------|---|---------|
| 23 | | RS232 baud rate | | 0=4800 1=9600 2=19200 3=38400 4=115200 | 1 |
| 24 | | RS232 mode | | 0=Proton protocol 1=Modbus protocol 2=ZM400 Printer | 1 |

RS-232 Printing

If the RS-232 interface "Mode" is set to "ZM400 Printer" (input parameter DW24 set to "2), then a Zebra ZM400 printer may be connected to the port to print End of Reel report tickets when triggered by the "End of Reel" logic input (see the "Logic Inputs" section for connection and configuration information).

Ensure that the RS-232 baud rate (input parameter DW23) is configured to the same value as set on the printer (9600 by default).

Zebra ZM400 Cable

The gauge may either be directly connected to the printer via the DB25F "INTERFACE" port or via the DB9F RS-232 port on an optional PSU-BOB mini:

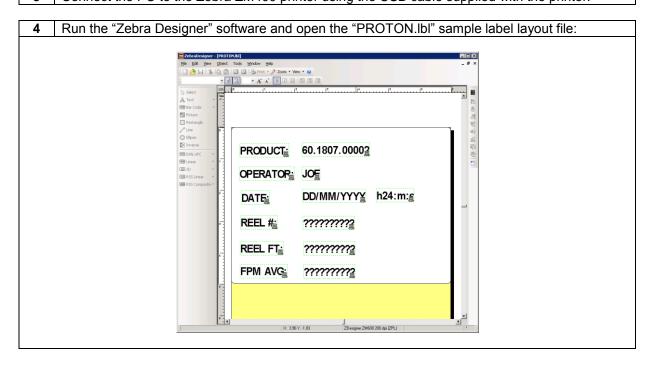
| SL / SLR mini INTERF | ACE port | Zebra ZM400 RS-232 port | | |
|------------------------|-----------|--------------------------------|-------------|--|
| Required cable connect | or: DB25M | Required cable connector: DB9M | | |
| Designation | Pin | Pin | Designation | |
| Shield | Shield | Shield | Shield | |
| | 2 | | | |
| DGND | 15 | 5 | DGND | |
| | 24 | 1 | | |
| RXD | 16 | 3 | TXD | |
| TXD | 17 | 2 | RXD | |

| PSU-BOB mini RS- | 232 port | Zebra | ZM400 RS-232 port |
|-----------------------|-----------|--------------------------------|-------------------|
| Required cable connec | tor: DB9M | Required cable connector: DB9M | |
| Designation | Pin | Pin | Designation |
| Shield | Shield | Shield | Shield |
| DGND | 5 | 5 | DGND |
| RXD | 2 | 3 | TXD |
| TXD | 3 | 2 | RXD |

Zebra ZM400 Printer Configuration

The Zebra ZM400 printer must be configured with the layout of the End of Reel report ticket using the following procedure:

- 1 Install the "Zebra Designer" software onto a suitable PC.
- Install the Zebra printer drivers onto the PC (the drivers are supplied on a CD-ROM with the Zebra ZM400 printer and may also be downloaded from www.zebra.com).
- 3 Connect the PC to the Zebra ZM400 printer using the USB cable supplied with the printer.



The gauge will send 3 strings in the following sequence to the Zebra ZM400 printer:

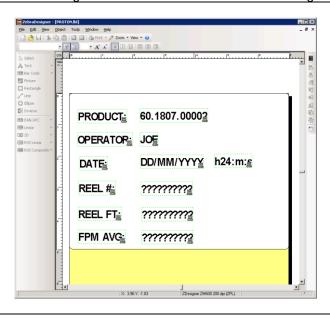
String no.1: Reel number

• String no.2: Length

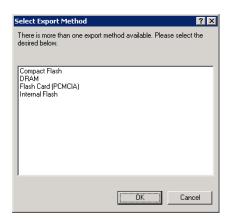
5

String no.3: Average speed

The label layout must be designed to accommodate the above 3 strings in sequence:



6 Export the "PROTON.Ibl" file to the Zebra ZM400 printer by clicking "File → Export to Printer" in the "Zebra Designer" software and then selecting "Internal Flash" and clicking the "OK" button:



7 The Zebra ZM400 printer may be triggered to print a ticket by activating the "End of Reel" logic input on the SL / SLR mini gauge.

Proton standard RS232 parameter access protocol

This uses a protocol to access individual parameters or blocks of parameters and is typically used in a production line environment where the gauge is connected to a PLC or similar device.

Notes

- The parameters are split into 'Input' and 'Output' groups, the 'Input' parameters can be both read and written, and the 'Output' parameters can only be read
- The parameter number is the same as the word address used for Profibus data; refer to the 'PROFIBUS Master to Gauge and RS232 Input Parameter List' for the parameter numbers
- For 'Input' data: when a word is defined as bits then four hexadecimal characters are required to form the bits 15~0; when a word is defined as a data value then only sufficient characters to define the value in decimal format, with the decimal point where appropriate, are needed; where the data is of double word length then only the first word address is used
- For 'Output' data: when a word is defined as bits then four hexadecimal characters will be sent; when a word is defined as a data value it is converted to a decimal number with the decimal point but without leading zeros; where a double word is used then only the first word address is used to request the data, the data in both words is automatically converted to a single value
- If a PC keyboard is being used to enter the codes then the 'carriage return' plus 'line feed' are replaced by the Enter key

SET THE VALUE OF AN 'INPUT' PARAMETER

Write Format:

& Input Parameter number Space Value without decimal point [0.5m = 50] Carriage return Line feed

REQUEST VALUE ONCE FOR ONE OR A RANGE OF 'INPUT' PARAMETERS

Request Format 1: (e.g.: ?2 'ENTER')

?

Input Parameter number

Carriage return

Line feed

Request Format 2: (e.g.: ?2 2 'ENTER')

?

Input Parameter number

Space

Length of string

Carriage return

Line feed

REQUEST CONTINUOUSLY REPEATING VALUES FOR ONE OR A RANGE OF 'OUTPUT' PARAMETERS

The repartition rate is the maximum possible and only limited by the data length and baud rate. The parameters must be consecutive when requesting multiple parameters.

Request Format 1:

#

Parameter number Carriage return Line feed

Request Format 2:

#

First parameter number

Space

Number of parameters

Carriage return

Line feed

Reply Format 1:

Parameter value Carriage return Line feed

Reply Format 2:

First output parameter value

Carriage return Line feed

Second output parameter value

Carriage return Line feed

Third output parameter and so on, until the end of the range.

REQUEST VALUE ONCE FOR ONE OR A RANGE OF 'OUTPUT' PARAMETERS

The request and reply format is identical to the # format given below except that # is replaced by ~.

Modbus parameter access protocol

This protocol provides access to individual parameters or blocks of parameters and is typically used in a production environment where the Proton Products instrument is connected to a computer, Modbus connected PLC or similar device.

The parameters consist of 16-bit words (DW) and are divided into input and output groups:

- Input parameters may be read from and written to and are used to configure the instrument.
- Output parameters are read only and provide access to instrument status and measurement data.

| 1 word (DW) consists of 2 bytes | | | | |
|--|--|--|--|--|
| 1 byte consists of 8 bits | | | | |
| 4 bits are expressed by 1 hexadecimal digit (0-9, A-F) | | | | |

Proton Products instruments use the following Modbus format:

| Modbus format | RTU (Remote Terminal Unit) | |
|---------------|-------------------------------|--|
| Error check | CRC (Cyclic Redundancy Check) | |

The Modbus RTU frame format is as follows:

| | Modbus RTU frame format | | | | | |
|----------|-------------------------|---|---|--|--|--|
| Name | Length | Function | | | | |
| Start | > 3.5 characters | >3.5 characters of silence | | | | |
| Address | 1-byte | Slave (instrument) Modbus address | * | | | |
| Function | 1-byte | Modbus function code determines read or write operation | * | | | |
| Data | Multiple bytes | Length and data dependent on function | * | | | |
| CRC | 2-bytes | Cyclic Redundancy Check for errors (not required for Modbus TCP) ⁺ | | | | |
| End | > 3.5 characters | >3.5 characters of silence | | | | |

^{*}Please refer to Modbus Protocol Standards documentation for the CRC error check field calculation. For Modbus protocol communications over TCP/IP networks via the Ethernet port (also known as **Modbus TCP**), the CRC error check field is not required as error checking is handled by the TCP/IP protocol.

For brevity, only the fields marked * are shown in the subsequent examples.

Proton Products instruments support the following Modbus functions:

| | M | odbus function | |
|------|-----|---------------------------|---|
| Code | | Name | Instrument operation |
| Dec | Hex | Name | |
| 03 | 03 | Read Holding Registers | Read data from a block of consecutive input parameters. |
| 06 | 06 | Preset Single Register | Write data to a single input parameter. |
| 10 | 16 | Preset Multiple Registers | Write data to a block of consecutive input parameters. |
| 04 | 04 | Read Input Registers | Read data from a block of consecutive output parameters. |

For Modbus protocol communications via the RS-232 serial port, the RS-232 data format is:

| Number of data bits | Parity | Number of stop bits | Flow control | Default baud rate |
|---------------------|--------|---------------------|--------------|-------------------|
| 8 | None | 1 | None | 9600 bit / s |

Read data from a block of consecutive input parameters

Use Modbus function "03" (Read Holding Registers) to read from a block of consecutive input parameters.

| Modbus query format | Hex | |
|--|--------------|----|
| Slave Modbus address (Gauge Modbus address) | 01 | |
| Modbus function code | 03 | |
| Starting address (Starting input parameter | High byte | 00 |
| address) | Low byte | 08 |
| Number of points | High byte | 00 |
| (Input parameter word count) | Low byte | 04 |

| Modbus response forma | Hex | | |
|---|----------------------|----|--|
| Slave Modbus address (Gauge Modbus address | 01 | | |
| Modbus function code | Modbus function code | | |
| Byte count N = (2 × Number of points | s) | 08 | |
| Data word 0 | 01 | | |
| (corresponds to input DW8) | Low byte | F4 | |
| Data word 1 | High byte | 01 | |
| (corresponds to input DW9) | Low byte | F4 | |
| High Data word 2 byte | | 01 | |
| (corresponds to input DW10) | Low byte | F4 | |
| Data word [(N/2) – 1] = 3 | High byte | 01 | |
| (corresponds to input DW11) | Low byte | F4 | |

The response contains the input parameter values requested in the query; its length is dependent on the number of input parameters requested.

Write data to a single input parameter

Use Modbus function "06" (Preset Single Register) to read from a block of consecutive input parameters.

| Modbus query format | Hex | |
|--|--------------|----|
| Slave Modbus address (Gauge Modbus address) | 01 | |
| Modbus function code | 06 | |
| Register address | High byte | 00 |
| (Input parameter address) | Low byte | 06 |
| Preset data | High byte | 03 |
| (Input parameter value) | E8 | |

| Modbus response forma | Hex | |
|---|--------------|----|
| Slave Modbus address (Gauge Modbus address | 01 | |
| Modbus function code | 06 | |
| Register address | High byte | 00 |
| (Input parameter address) | Low byte | 06 |
| Preset data | 03 | |
| (Input parameter value) | Low byte | E8 |

The response is an echo of the query.

Write data to a block of consecutive input parameters

Use Modbus function "16 (10 Hex)" (Preset Multiple Registers) to write to a block of consecutive input parameters.

| Modbus query format | Hex | | |
|--|--------------|----|--|
| Slave Modbus address (Gauge Modbus address) | 01 | | |
| Modbus function code | | 10 | |
| Starting address (Starting input parameter | | | |
| address) | Low byte | 01 | |
| Number of registers | 00 | | |
| (Input parameter word count) | Low byte | 03 | |
| Byte count $N = (2 \times Number of register)$ | 06 | | |
| Data word 0 | High byte | 1F | |
| (corresponds to input DW1) | Low byte | 40 | |
| Data word 1 | High byte | 1F | |
| (corresponds to input DW2) | Low byte | 40 | |
| Data word $[(N/2) - 1] = 2$ High byte | | 1F | |
| (corresponds to input DW3) | Low byte | 40 | |

| Modbus response forma | Hex | |
|---|--------------|----|
| Slave Modbus address (Gauge Modbus address) | 01 | |
| Modbus function code | 10 | |
| Starting address | High byte | 00 |
| (Starting input parameter address) | Low byte | 01 |
| Number of registers | High byte | 00 |
| (Input parameter word count) | Low byte | 03 |

The response contains the starting input parameter address and the count of input parameter words written.

Read data from a block of consecutive output parameters

Use Modbus function "04" (Read Input Registers) to write to a block of consecutive input parameters.

| Modbus query format | Hex | |
|--|--------------|----|
| Slave Modbus address (Gauge Modbus address) | 01 | |
| Modbus function code | 04 | |
| Starting address (Starting output parameter | High byte | 00 |
| address) | Low byte | 02 |
| Number of points | High byte | 00 |
| (Output parameter word count) | Low byte | 03 |

| Modbus response forma | Hex | |
|---|--------------|----|
| Slave Modbus address (Gauge Modbus address | 01 | |
| Modbus function code | 04 | |
| Byte count $N = (2 \times Number of points)$ | 06 | |
| Data word 0 | 07 | |
| (corresponds to output DW2) | Low byte | D0 |
| Data word 1 | High byte | 05 |
| (corresponds to output DW3) | Low byte | DC |
| Data word 2 | High byte | 09 |
| [(N/2) – 1] (corresponds to output DW4) | Low byte | C4 |

The response contains the output parameter values requested in the query; its length is dependent on the number of output parameters requested.

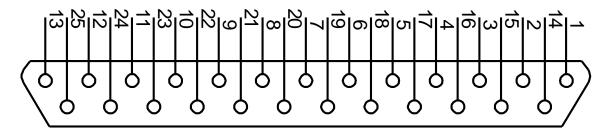
ETHERNET COMMUNICATIONS

This Ethernet interface is fitted as standard. It operates independently of the other communications interfaces and may be accessed at the same time as them.

If an optional industrial bus interface (Ethernet/IP, PROFIBUS or DeviceNET) has been installed in the gauge, then the Ethernet interface is substituted by the industrial bus interface.

Ethernet interface

The Ethernet interface may be accessed through the following pins:



Connector type: DB25 female (socket)

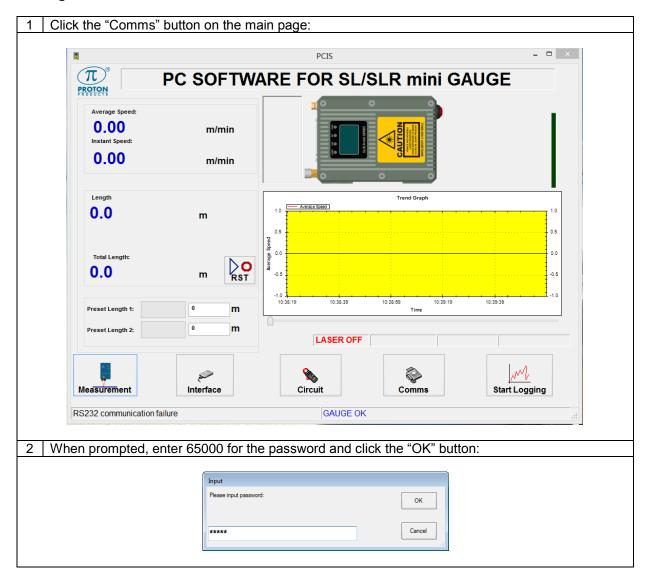
| Functional group | Pin | Designation | Description | Notes |
|------------------|-----|-------------|-------------|-----------------------------------|
| Shield | S | Shield | Shield | Connect to cable and plug shields |
| | 22 | IBUS1 | TX+ | |
| Ethernet | 10 | IBUS2 | TX- | |
| Ethernet | 23 | IBUS3 | RX+ | |
| | 11 | IBUS4 | RX- | |

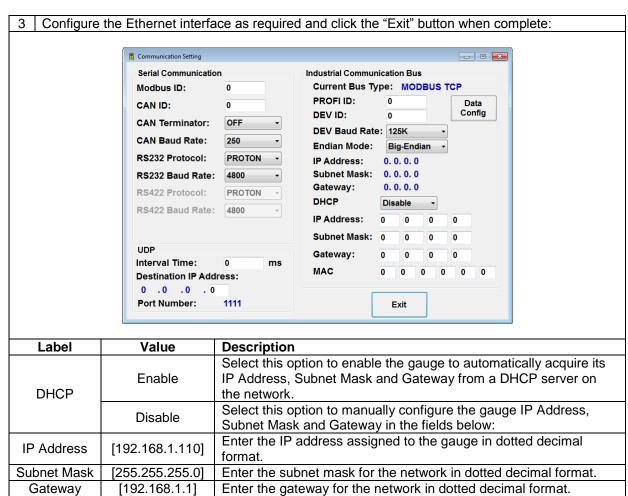
Ethernet LED indicator

| EIP | | LED status | Indication |
|-------------------------|--|------------------|--------------------------|
| | | Continuous green | Online and connected |
| Ethernet communications | | Flashing green | Online but not connected |
| | | Continuous red | Critical link failure |
| | | Flashing red | Connection timeout |

Ethernet configuration

Configuration via the PCiS_SLmini software:





^{* []} indicates factory-default values.

Configuration via input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters

| | par parameters | | | | | |
|----|----------------|-------------------|--------------------|-------------------------------------|-----------------|--|
| DW | Bit | Comment | Unit | Range/Remark | Default | |
| 27 | | Modbus address | 1=1 | 0~255 | 1 | |
| 28 | | EtherNet protocol | | 0=Modbus protocol 1=EIP protocol | 0 | |
| 29 | | DHCP | | 0=Disabled 1=Enabled | 0 | |
| 30 | | IP address | V V V V | | C0A8016E | |
| 31 | | ir address | IP address x.x.x.x | | (192.168.1.110) | |
| 32 | | Subnet mask | V V V V | | FFFF0000 | |
| 33 | | Subflet fliask | X.X.X.X | | (255.255.255.0) | |
| 34 | | Gateway | | | C0A80001 | |
| 35 | | Galeway | X.X.X.X | | (192.168.1.1) | |

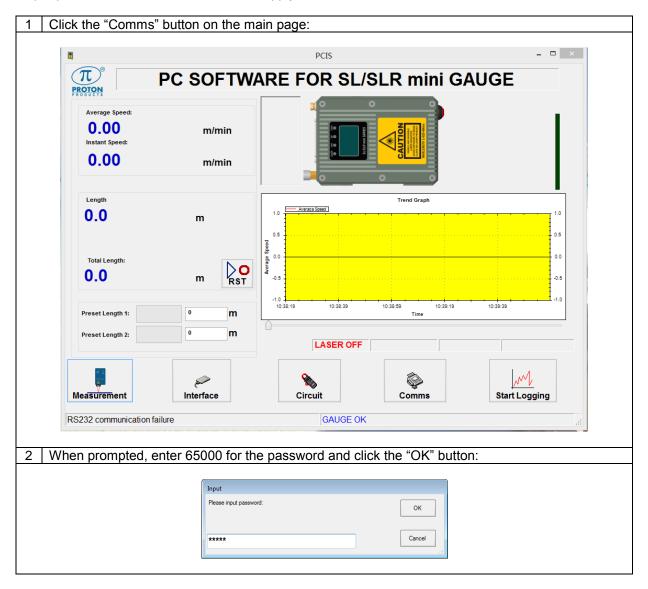
Input Parameter Write Disable

The gauge may be configured to write-disable specific input parameters when a page of input parameters is written via the optional DeviceNET, PROFIBUS, PROFINET or EtherNet/IP communications interface.

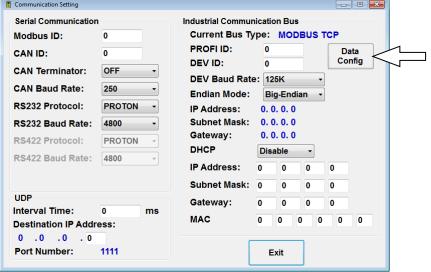
Input parameters may be write-disabled for the following purposes:

- **To simplify setup**: all unused input parameters may be write-disabled to simplify the composition of the written data page.
- To avoid unintended modification of specific parameters: input parameters which must NOT be changed via the optional communication interface (e.g. input parameters which determine the operating mode of the gauge) may be write-disabled.

Input parameter write-disable does NOT apply to the CANbus, RS-232 or Ethernet interfaces.



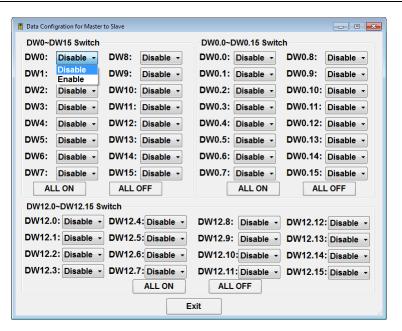
3 Click the "Data Config" button to access the "Data Configuration for Master to Slave" page:



4 When prompted, enter 65065 for the password and click the "OK" button:



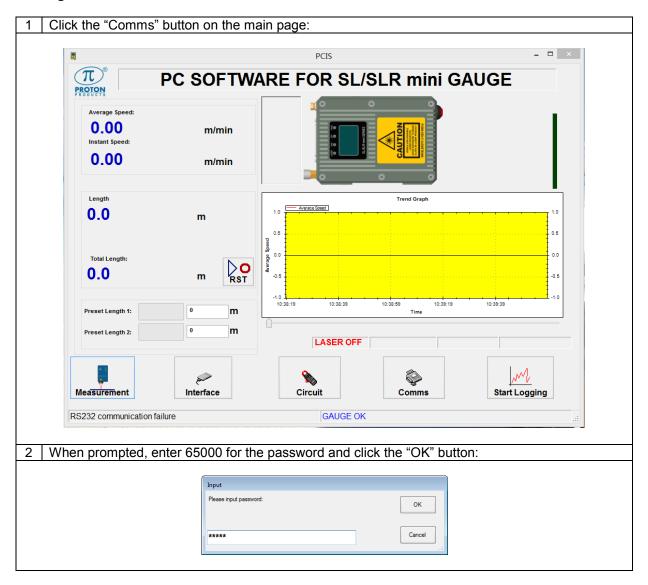
Enable or disable writing of input parameter DW words or bits via the optional DeviceNET, PROFIBUS, PROFINET or EtherNet/IP communications interfaces:

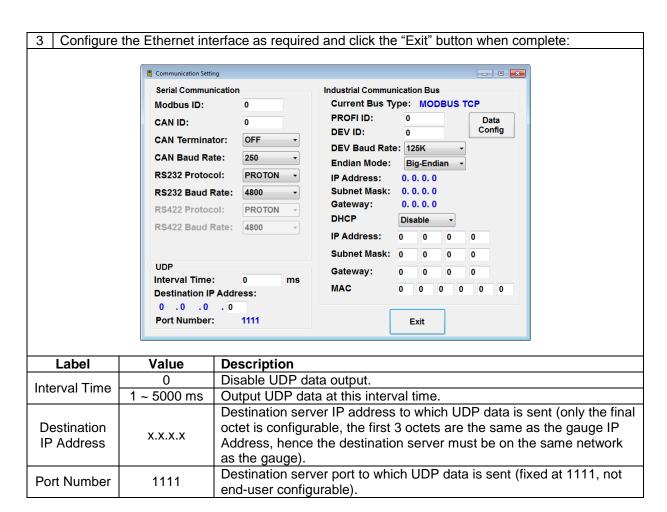


| Label | Description |
|---------|--|
| Enable | Select to <i>enable</i> writing of the specific input parameter DW word or bit. |
| Disable | Select to <i>disable</i> writing of the specific input parameter DW word or bit. |
| ALL ON | Click to enable writing of all associated input parameter DW words. |
| ALL OFF | Click to <i>disable</i> writing of <i>all</i> associated input parameter DW words. |
| Exit | Click to exit this page and return to the "Communication Setting" page. |

UDP Protocol

The gauge may be configured to continuously send data by UDP-protocol (at a user-configured rate) to a server on the same network.





Configuration via input parameters:

The UDP data output function may be configured by writing to the following input parameters:

Input parameters

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|---------------------------|---------|--------------------------------|---------------|
| 30 | | IP address | x.x.x.x | | C0A80001 |
| 31 | | ir address | X.X.X.X | | (192.168.0.1) |
| 41 | | UDP data output interval | 1=1ms | 1~5000 | 0 |
| 71 | | time | 1=11118 | 0=Disable UDP output | U |
| 48 | | UDP destination IP | | Note: the UDP destination port | 2 |
| 40 | | address (last octet only) | | number is fixed at 1111 | 2 |

OPTIONAL COMMUNICATIONS INTERFACES

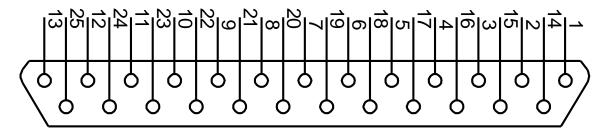
PROFIBUS COMMUNICATIONS

The PROFIBUS interface is an optional extra that must be ordered for installation during manufacture; it cannot be retrofitted to the gauge.

This communications interface operates independently of the other communications interfaces and may be used at the same time as them.

PROFIBUS interface

The PROFIBUS interface may be accessed through the following pins:



Connector type: DB25 female (socket)

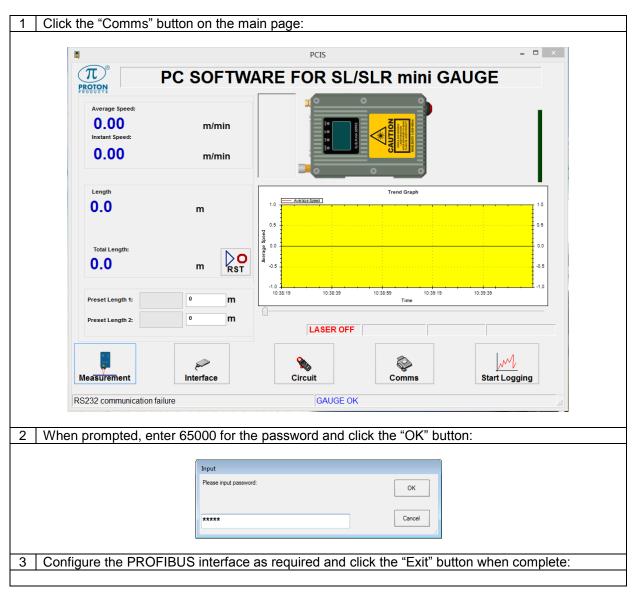
| Functional group | Pin | Designation | Description | Notes |
|-------------------------------|-----|-------------|-------------|-----------------------------------|
| Shield | S | Shield | Shield | Connect to cable and plug shields |
| PROFIBUS Industrial bus | 22 | IBUS1 | +5V | |
| | 10 | IBUS2 | GND | |
| | 23 | IBUS3 | A | |
| | 11 | IBUS4 | В | |

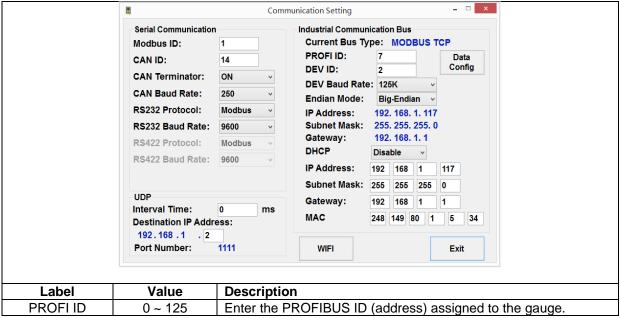
PROFIBUS LED indicator

| i-BUS | | LED status | Indication |
|-------------------------|--|------------------|---------------------|
| 1-003 | | Continuous green | Online |
| PROFIBUS communications | | Continuous red | Communication error |
| | | Extinguished | No communication |

PROFIBUS configuration

The gauge head is configured as a PROFIBUS slave.





Configuration via input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters:

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|------------------|------|--------------|---------|
| 20 | | Profibus address | 1=1 | 0~125 | 7 |

ETHERNET / IP OR PROFINET COMMUNICATIONS

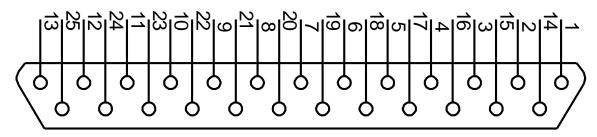
The EtherNet / IP or PROFINET interface is an optional extra that must be ordered for installation during manufacture; it cannot be retrofitted to the gauge.

The Ethernet/IP interface is compatible with PLCs fitted with an Ethernet/IP interface that supports the CIP (Common Industrial Protocol).

This communications interface operates independently of the other communications interfaces and may be used at the same time as them.

EtherNet / IP or PROFINET interface

The EtherNet / IP or PROFINET interface may be accessed through the following pins:



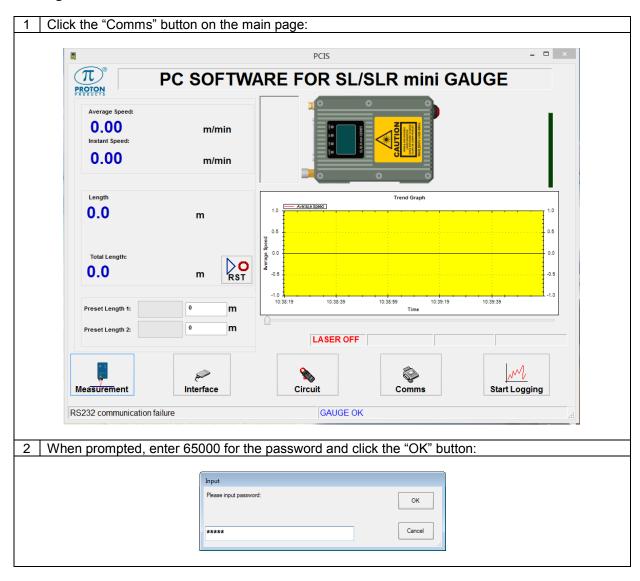
Connector type: DB25 female (socket)

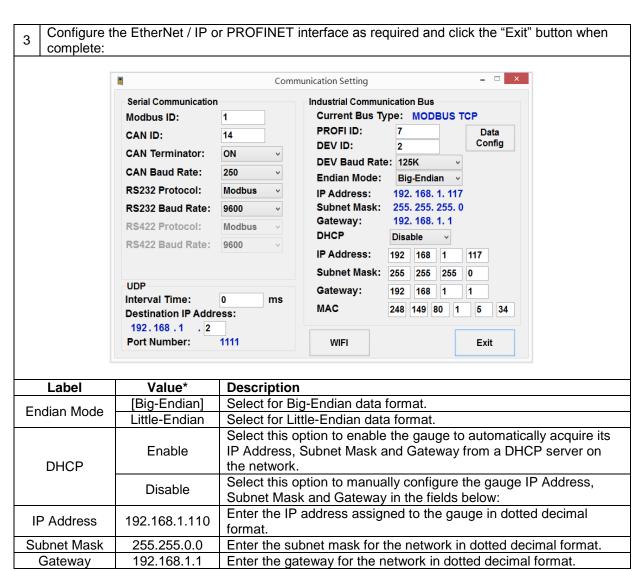
| Functional group | Pin | Designation | Description | Notes |
|--|-----|-------------|-------------|-----------------------------------|
| Shield | S | Shield | Shield | Connect to cable and plug shields |
| Ethernet/IP or PROFINET Industrial bus | 22 | IBUS1 | TX+ | |
| | 10 | IBUS2 | TX- | |
| | 23 | IBUS3 | RX+ | |
| | 11 | IBUS4 | RX- | |

EtherNet / IP or PROFINET LED indicator

| i-BUS | | LED status | Indication |
|--------------------|---------|------------------|---------------------|
| 1-003 | | Continuous green | Online |
| EtherNet / IP or P | ROFINET | Continuous red | Communication error |
| communications | | Extinguished | No communication |

EtherNet / IP or PROFINET configuration





^{* []} indicates factory-default value.

Configuration via input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|---------------------|---------|---------------------------------|-----------------|
| 29 | | DHCP | | 0=Disabled 1=Enabled | 0 |
| 30 | | IP address | V V V V | | C0A8016E |
| 31 | | ir address | X.X.X.X | | (192.168.1.110) |
| 32 | | Subnet mask | t mook | | FFFF0000 |
| 33 | | Subnet mask x.x.x.x | X.X.X.X | | (255.255.0.0) |
| 34 | | Gateway | V V V V | | C0A80001 |
| 35 | | Galeway | X.X.X.X | | (192.168.1.1) |
| 49 | | Endianess | | 1=Little endian 0=Big endian | 0 |

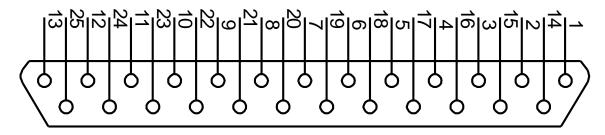
DEVICENET COMMUNICATIONS

The DeviceNet interface is an optional extra that must be ordered for installation during manufacture; it cannot be retrofitted to the gauge.

This communications interface operates independently of the other communications interfaces and may be used at the same time as them.

DeviceNet interface

The DeviceNet interface may be accessed through the following pins:



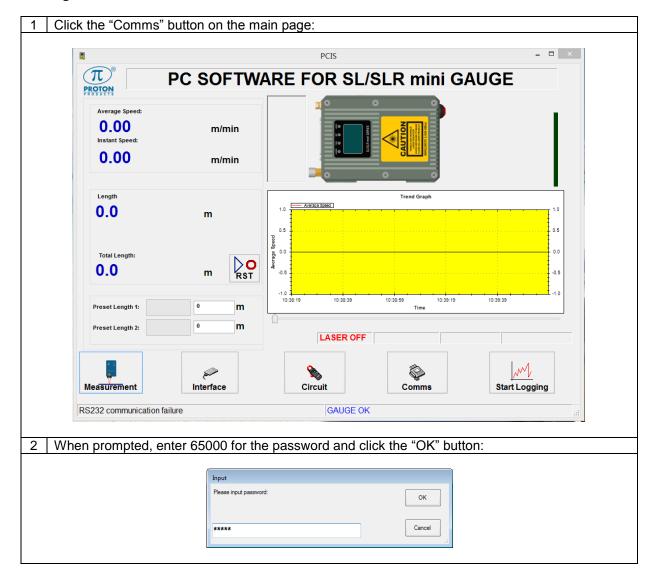
Connector type: DB25 female (socket)

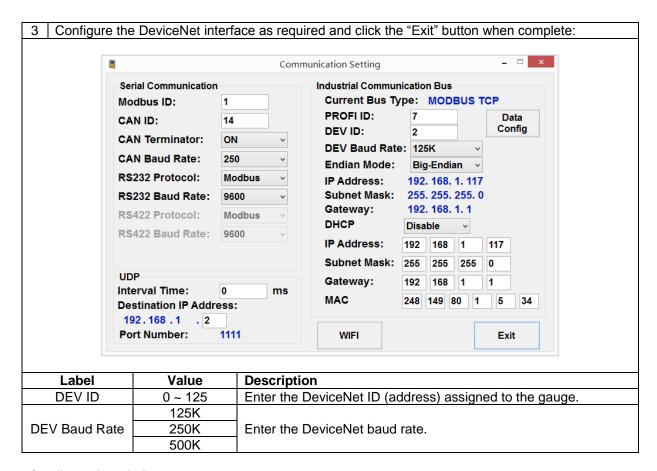
| Functional group | Pin | Designation | Description | Notes | DeviceNet wire colour |
|----------------------|-----|-------------|-------------|-----------------------------------|-----------------------|
| Shield | S | Shield | Shield | Connect to cable and plug shields | Bare wire |
| DovisoNET | 22 | IBUS1 | V+ | | Red |
| DeviceNET Industrial | 10 | IBUS2 | V- | | Black |
| | 23 | IBUS3 | CANH | | White |
| bus | 11 | IBUS4 | CANL | | Blue |

DeviceNet LED indicator

| i-BUS | | LED status | Indication |
|--------------------------|--|------------------|---------------------|
| 1-003 | | Continuous green | Online |
| DeviceNet communications | | Continuous red | Communication error |
| | | Extinguished | No communication |

DeviceNet configuration





Configuration via input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters:

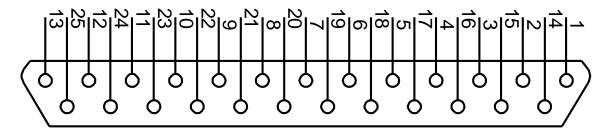
| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|---------------------|------|----------------------------|---------|
| 46 | | DeviceNet address | | 0~63 | 7 |
| 47 | | DeviceNet baud rate | | 0=125K 1=250K 2=500K | |

STANDARD ELECTRICAL INTERFACES

LOGIC INPUTS

Logic inputs connection

Two logic inputs are fitted as standard and may be accessed through the following pins:



Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes |
|------------------|-----|-------------|-------------------------------------|---------------------------------------|
| Shield | S | Shield | Shield | Connect to cable and plug shields |
| Power | 2 | | Dower aupply and | |
| supply and | 15 | DGND | Power supply and signal ground (0V) | |
| ground | 24 | | signal ground (0V) | |
| Logio | 3 | LIN1 | Logic input 1 | Low state (logic 0) voltage < +3V |
| Logic inputs | 4 | LIN2 | Logic input 2 | High state (logic 1) voltage > +10.5V |
| Πραιδ | 5 | LIN3 | Logic input 3 | Maximum input voltage ±30V |

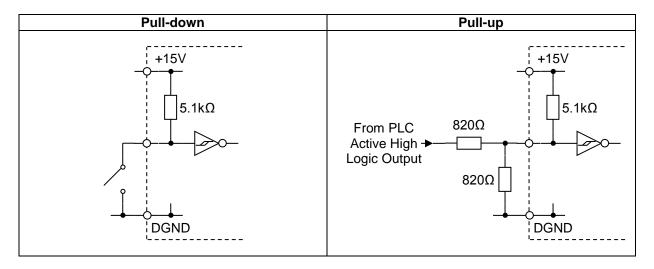
Logic inputs electrical specification

- Logic inputs are NOT isolated from earth.
- Inputs are internally pulled up to +15V via 8.2kΩ resistors; unconnected inputs default to the high state.
- Inputs will source a minimum current of 3mA when externally pulled down to the low state.

| Specification | Minimum | Typical | Maximum | Units |
|------------------------------------|---------|---------|---------|-------|
| Low state (logic 0) input voltage | | | 3 | V |
| High state (logic 1) input voltage | 10.5 | | | V |
| Absolute input voltage | -30 | | 30 | V |
| Low state source current | 3 | | | mA |

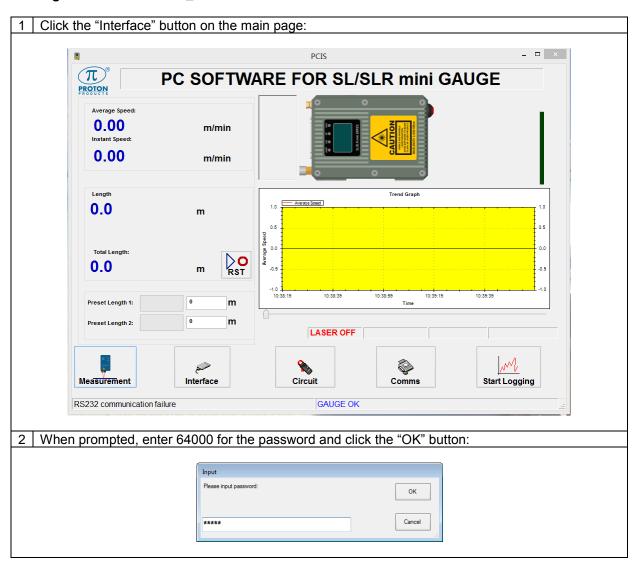
Logic inputs can be connected to different types of signal sources as follows:

| Signal source | Connection method | | | |
|---|--|--|--|--|
| Mechanical or solid state relay contact | Connect between logic input and DGND. | | | |
| Pull-down | Connect the pull-down signal to the logic input and ground to DGND. | | | |
| Pull-up | Connect an 820Ω resistor between the logic input and DGND to pull the input down to 2.5V. Connect the pull-up signal source to the logic input and ground to DGND. For 24V signals (such as from a PLC), the power dissipation in the 820Ω resistor can be reduced by connecting another 820Ω in series between the pull-up signal source and logic input. | | | |



Logic inputs configuration

Each individual logic input can be independently configured for both active state polarity and function.



Configure the logic input interface as required and click the "Exit" button when complete:



| Label | Value* | Description | Input DW |
|---------------|------------------|--|-------------|
| Format | New | Select "New" (factory-default setting) to configure the logic inputs as below. | 12.15 |
| | Old | Select "Old" for backward compatibility with Proton Products | |
| Logic Input 1 | | | |
| | Rev Direction | Activate to reverse the length counting direction. For SL gauges, when this input is activated (for example by a direction wheel) the gauge will decrement length. • See the "Measurement Direction" section for information on how this logic input affects length accumulation. | |
| Function | Length Hold | Activate to hold the length measurement by forcing the speed measurement to zero. The lengths read from output parameters DW6-7 and DW12-13 will be held at their values at the instant of activation. The speeds read from output parameters DW2-3 and DW4-5 will be forced to zero. The frequency of the pulse outputs is also forced to zero. | 12 |
| | Display Hold | Activate to hold the <i>displayed</i> speed and length measurements at the instant of activation for ease of reading. The gauge internally continues to measure speed and length and the display will revert to these live values when this logic input returns to inactive. The lengths read from output parameters DW6-7 and DW12-13 and speeds read from output parameters DW2-3 and DW4-5 will continue to update even with "Display Hold" active. The pulse outputs are NOT affected by this function and will continue to correspond to the object speed. | |

| | Speed Hold | Activate to hold the speed measurement at its value at the instant of activation. The length reading will accumulate at the held speed (including lengths read from output parameters DW6-7 and DW12-13). The speeds read from output parameters DW2-3 and DW4-5 will be held at their values at the instant of activation. The frequency of the pulse outputs is held at the corresponding speed value. | | | |
|---------------|----------------|---|-------|--|--|
| | Reset | Activate momentarily to reset the length to zero. Activate for longer than 5 seconds to also reset the "Reel Number" to zero. | | | |
| | End of Reel | Activate to increment the "Reel Number" and trigger printing of the End of Reel report on a Zebra ZM400 printer attached to the RS-232 port. | | | |
| Delevity | Active Low | Pulling the logic input low (logic 0) activates the configured function. | | | |
| Polarity | Active High | Pulling the logic input high (logic 1) activates the configured function. | | | |
| Logic Input 2 | | | • | | |
| Function | | As per "Logic Input 1" above. | 12 | | |
| Polarity | | As per "Logic Input 1" above. | 12 | | |
| Logic Input 3 | | | | | |
| Function | | As per "Logic Input 1" above. | 12 | | |
| Polarity | | As per "Logic Input 1" above. | 12 | | |
| | | | | | |
| | | Select this for normal length accumulation. | | | |
| | [Up/Normal] | SL mini Object motion increments length. | | | |
| | | SLR mini Standard direction increments length. | | | |
| Direction | | Select this for reverse length accumulation. | | | |
| Setting | Down/Invert | SL mini Object motion decrements the length. | | | |
| | | SLR mini Standard direction decrements length. | 12.12 | | |
| | | the logic inputs are configured for the "Rev Direction" | 12.12 | | |
| | | this "Directing Setting" is overridden by the logic input and | | | |
| | has no effect. | | | | |
| Laser Switch | [ON] | Select to switch on the laser diode. | 13 | | |
| Laser Switch | OFF | Select to switch off the laser diode. | 13 | | |

^{*} factory-default values are shown in enclosed in [].

Configuration by input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters

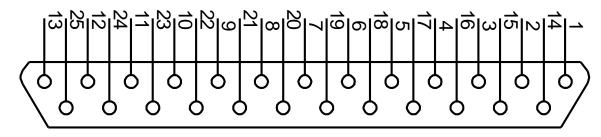
| DW | Bit | Comment | Unit | Range/Remark | Default | | |
|----|----------|--|---------------------------------------|---|---------|--|--|
| | | Logic input (old format: co | mpatible with old SL gauge;DW12.15=0) | | | | |
| | 0 | | | 0=Direction | | | |
| | 1 | Logic input 1 function | | 1=Length hold 2=Display hold 3=Speed hold | 1 | | |
| | 2 | Direction setting (available only when no logic input for direction) | | 0=Count up 1=Count down | 0 | | |
| 12 | 12 3 | Logic input 1 polarity | | 0=Active low 1=Active high | 0 | | |
| | 4~7 | Not used | | | 0 | | |
| | 8 | Logic input 2 function | | 0=Reset input 1=Length hold | 0 | | |
| | 10 | Logic input 2 polarity | | 0=Active low 1=Active high | 0 | | |
| | 11 12 | Logic input 3 function | | 0=Direction 1=Length hold | 1 | | |

| DW | Bit | Comment | Unit | Range/Remark | Default | |
|----|-----|------------------------------|--------------|---------------------------|---------|--|
| | | | | 2=Display hold | | |
| | 13 | | | 3=Speed hold | | |
| | | | | 4=Reset | | |
| | 14 | Logic input 3 polarity | | 0=Active low | 0 | |
| | 14 | Logic input 3 polarity | | 1=Active high | 0 | |
| | 15 | Must be 0 | | 0=Old format logic inputs | 0 | |
| | | Logic input(new format;DW12. | 15=1) | | | |
| | 0 | | - | 0=direction (count down) | | |
| | 1 | 1 | | 1=Length hold | | |
| | 2 | Lania inmut 4 function | | 2=Display hold | | |
| | | Logic input 1 function | | 3=Speed hold | 0 | |
| | | | | 4=Reset | | |
| | | | | 5=End of Reel | | |
| | 3 | 1 1 1 1 1 1 1 | 0=Active low | | | |
| | 3 | | | 1=Active high | 0 | |
| | 4 | | | 0=direction (count down) | | |
| | 5 | - | | 1=Length hold | | |
| | 6 | 1, | | 2=Display hold | | |
| | | Logic input 2 function | | 3=Speed hold | 1 | |
| | | | | 4=Reset | | |
| | | | | 5=End of Reel | | |
| 12 | 7 | La via invad O valantus | 0=Active low | 0 | | |
| | 7 | Logic input 2 polarity | | 1=Active high | 0 | |
| | 8 | | | 0=direction (count down) | | |
| | 9 | | | 1=Length hold | | |
| | | Lania innut 2 function | | 2=Display hold | 4 | |
| | | Logic input 3 function | | 3=Speed hold | 4 | |
| | 10 | | | 4=Reset | | |
| | | | | 5=End of Reel | | |
| | 4.4 | Logic input 2 polority | | 0=Active low | 0 | |
| | 11 | Logic input 3 polarity | | 1=Active high | 0 | |
| | | Direction setting (available | | | | |
| | 12 | only when no logic input | | 0=Count up | 0 | |
| | | for direction) | | 1=Count down | | |
| | 13~ | Not used | | | | |
| | 14 | Not used | | | | |
| | 15 | Must be 1 | | 1=New format logic inputs | | |

LOGIC OUTPUTS

Logic outputs connection

Two outputs are fitted as standard and may be accessed through the following pins:



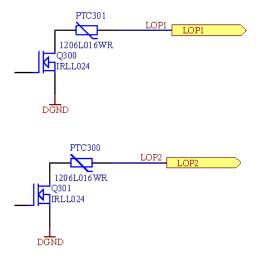
Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes | |
|-------------------------|---------------|-------------|-------------------------------------|-----------------------------|-------------------------------------|
| Shield | S | Shield | Shield | Connect to | cable and plug shields |
| Power supply and ground | 2 15 24 | DGND | Power supply and signal ground (0V) | Floating (ina | active) or pull-down to ve) |
| Logic | 6 | LOP1 | Logic output 1 | State Inactive Active | Output Floating Pulled down to DGND |
| outputs | 7 | LOP2 | Logic output 2 | State Inactive Active | Output Floating Pulled down to DGND |

Logic outputs electrical specifications

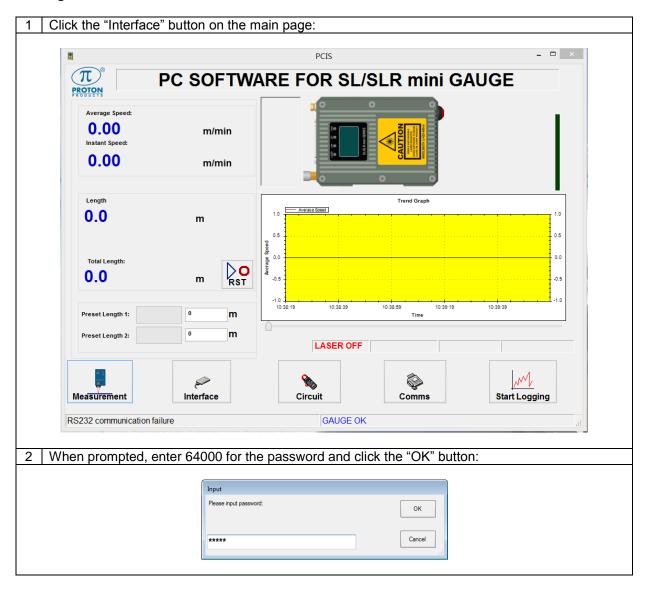
- The logic outputs must NOT be used to directly drive high-current or inductive loads.
- It is recommended that the logic outputs are used to drive opto-isolated solid-state relays.

| Specification | Minimum | Typical | Maximum | Units |
|------------------------------|---------|---------|---------|-------|
| Logic output to DGND voltage | | | +25 | VDC |
| Current | | | 0.1 | Α |

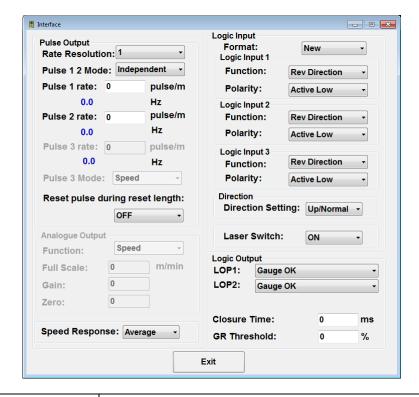


Logic outputs configuration

Each individual logic output can be independently configured to pull-down to DGND upon any one of the following conditions:







| Label | Value* | Description | | | | |
|-----------------|---|---|---|----|--|--|
| | Select the condition to pull-down the logic output: | | | | | |
| | Gauge OK | There are | There are no errors in the operation of the gauge. | | | |
| | Gauge Measuring Speed | The gauge is measuring speed. | | | | |
| | Preset Length 1 | Normal mode | The measured length exceeds "Preset Length 1". | | | |
| LOP1 | / Batch Length | Batch mode | The measured length equals the "Batch Length" (the logic output is pulled down momentarily for the duration of the "Closure Time" setting below). | | | |
| LOFT | Preset Length 2 | Normal mode | The measured length exceeds "Preset Length 2". | 16 | | |
| | / Batch Number | Batch | The number of measured batch lengths is equal | | | |
| | | mode | to or greater than the "Batch Number". | | | |
| | Good Reading | The "Good Readings" percentage exceeds the "GR Threshold" set below. | | | | |
| | Object Detected | An object | has been detected by the gauge. | | | |
| | | The gauge temperature has exceeded its safe operating limit | | | | |
| | Gauge Too Hot | of 45°C (this output may be used to activate external cooling systems). | | | | |
| LOP2 | As per LOP1 | As per LOP1 | | | | |
| Closure | 10 ~ [500] ~ | Set the minimum pull-down time (in milliseconds) for any | | | | |
| Time | 5000 ms | logic outputs configured for the "Batch Length" function. | | | | |
| GR Threshold | 0 ~ [60] ~ 100 % | percentag | Set the threshold above which the "Good Readings" percentage will trigger pull-down of any logic output configured to the "Good Reading" condition. | | | |

^{*} factory-default values are shown in enclosed in [].

Configuration by input parameters: This interface may be configured by writing to the following input parameters:

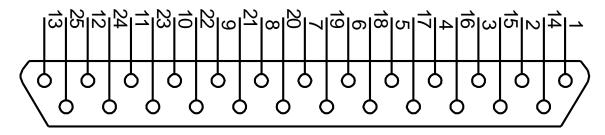
Input parameters

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|------|-----------------------------|--------|--|---------|
| 4 | | Batch mode LOP closure time | 1=10ms | 1~500 (10ms~5s) | 50 |
| | | Logic output function | | | |
| | 0~3 | LOP1 function | | 0=Gauge OK | 0 |
| | 4~7 | LOP2 function | | 1=Gauge measuring speed | 2 |
| 16 | 8~15 | Not used | | 2=Preset length 1 / Batch length 3=Preset length 2 / Batch number 4=Good reading 5=Object detected 6=Gauge too hot | 3 |
| 18 | | Good Reading threshold | 1=1% | - | 60% |

PULSE OUTPUTS

Pulse outputs connection

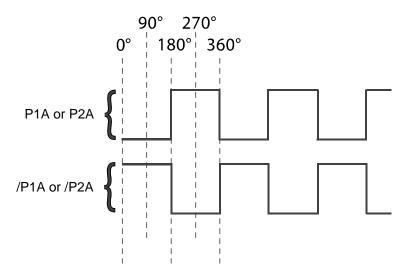
Four pulse outputs are fitted as standard and may be accessed through the following pins:



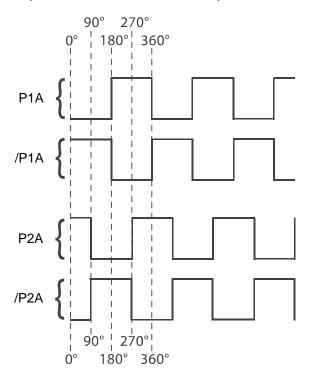
Connector type: DB25 female (socket)

| Functional group | Pin | Designation | Description | Notes |
|----------------------|-----|-------------|------------------------------------|---|
| Pulse | 1 | POUT +V | Pulse output external power supply | If no external power supply is connected, then the pulse outputs default to the internal +5V supply. Maximum voltage: +24V |
| outputs | 18 | P1A | Pulse output 1 | RS-422 compliant differential pair pulse |
| • | 19 | /P1A | Inverted pulse output 1 | output 1. |
| | 20 | P2A | Pulse output 2 | RS-422 compliant differential pair pulse |
| | 21 | /P2A | Inverted pulse output 2 | output 2. |
| Power | 25 | +24V | Power supply | For 24V pulse outputs, connect this pin to POUT +V. |
| supply and ground | 2 | DGND | Power supply and | Cround reference for D1A /D1A D2A |
| | 15 | DGND | signal ground | Ground reference for P1A, /P1A, P2A and /P2A. |
| | 24 | DGND | reference | anu/FZA. |
| Shield | S | Shield | Shield | Connect to cable and plug shields |

- RS-422 compliant differential pair (normal and inverse) outputs are provided for pulse outputs
 "Pulse output 1(P1A, /P1A)" and "Pulse output 2 (P2A, /P2A)"; each pulse output can thus be
 connected to both single-ended and differential interfaces.
- "Pulse output 1(P1A, /P1A)" and "Pulse output 2 (P2A, /P2A)" default to a 0 to +5V signal range; if a higher output voltage is required, then an external voltage source up to +24VDC may be connected across POUT +V and DGND to define the required voltage.
- "Pulse output 1" and "Pulse output 2" may be user-configured for either independent or quadrature operation.
- In independent mode, "Pulse output 1" and "Pulse output 2" run independently and may be configured with different pulse rates:



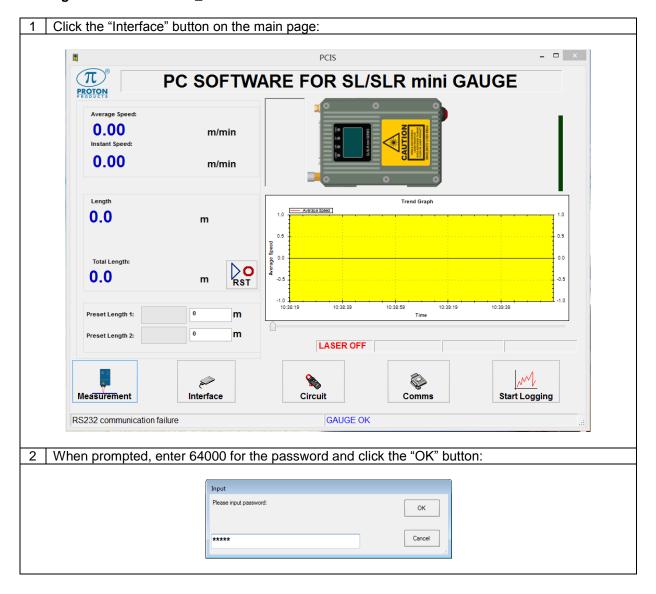
• In quadrature mode, "Pulse output 1" and "Pulse output 2" run at the same pulse rate (set as the "Pulse 1 rate") with a 90° phase shift between the two outputs:



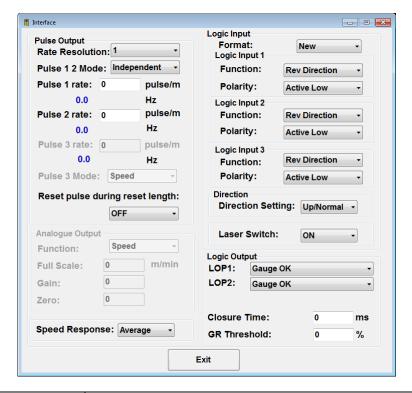
Pulse outputs electrical specifications

| Specification | Minimum | Typical | Maximum | Units |
|--|---------|---------|---------|-------|
| Pulse output external power supply (POUT +V) | +5 | | +25 | VDC |
| Pulse output frequency | | | 2* | MHz |

^{*} reduced with increasing cable length in accordance with RS-422 standards.



3 Configure the pulse output interface as required and click the "Exit" button when complete:



| Label | Value* | Description |
|-----------------|--------------------------|---|
| | 1000 | |
| | 100 | |
| Pulse | 10 | Set the required pulse output resolution in pulses/ unit, where the unit |
| Resolution | [1] | is the "Measurement unit" (metres, feet, inch or yards) set on the |
| Resolution | 0.1 | "Measurement" page. |
| | 0.01 | |
| | 0.001 | |
| Pulse 1 2 | [Independent] | Select "Independent" mode to configure "Pulse output 1" and "Pulse output 2" with separate and independent pulse rates. |
| Mode | Quadrature | Select "Quadrature" mode to couple together "Pulse output 1" and "Pulse output 2" as a quadrature pair, with pulse rate set under "Pulse 1 rate". |
| Pulse 1 rate | 1 ~ [1000] ~ 65535 | Set the required pulse rate for "Pulse output 1" in pulses/unit, where the unit is the "Measurement unit" (metres, feet, inch or yards) set on the "Measurement" page. Note: If the "Pulse Resolution" setting above is not suitable for the pulse rate entered here, then the pulse rate will be automatically rounded up or down. When "Pulse 1 2 Mode" is set to "Quadrature", this parameter sets the |
| | | rate for the quadrature pulse output across both "Pulse output 1" and "Pulse output 2". |
| | | 1 |

| Pulse 2 rate | 1 ~ [1000] ~ 65535 | Set the required pulse rate for "Pulse output 2" in pulses/ unit, where the unit is the "Measurement unit" (metres, feet, inch or yards) set on the "Measurement" page. Note: If the "Pulse Resolution" setting above is not suitable for the pulse rate entered here, then the pulse rate will be automatically rounded up or down. This field is disabled when "Pulse 1 2 Mode" is set to "Quadrature". |
|---|--------------------------|---|
| | | |
| Reset pulse during reset length | [OFF] | Select for pulse outputs to continue following the measured speed during a length reset. |
| | ON | Select to reset pulse outputs when the length is reset. |

^{*} factory-default values are shown in enclosed in [].

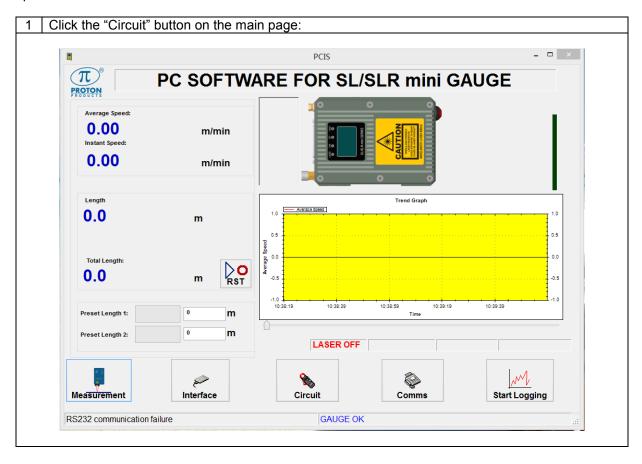
Configuration by input parameters:

This interface may be configured by writing to the following input parameters:

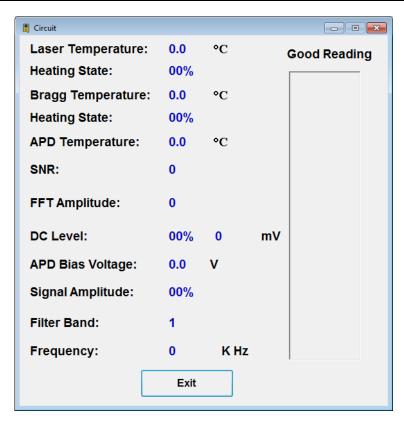
| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|---------------------------------|----------------------------|---|---------|
| | | System Function | | | |
| 0 | 9 | Pulse output 1 mode | | 0=Normal 1=Quadrature | 0 |
| 7 | | Pulse output 1 rate | 1=1/10DW17pulse/m{ft}{yds} | 1~65535 | 1000 |
| 8 | | Pulse output 2 rate | 1=1/10DW17pulse/m{ft}{yds} | 1~65535 | 1000 |
| 17 | | Pulse output rate resolution | 1=1 | 3=1000 2=100 1=10 0=1 -1=0.1 -2=0.01 -3=0.001 | 0 |
| 19 | | Pulse reset during reset length | | 0=Off 1=On | 0 |

Circuit Information and Gauge Performance Indicators

The "Circuit" page of the PCiS_SLmini displays various performance indicators and gauge circuit parameters.



The "Circuit" page displays parameters which may be useful during gauge alignment or for Proton Products authorized service personnel; when contacting Proton Products for technical assistance, please have the information displayed on the "Circuit" page available for our service personnel to better diagnose any problems.

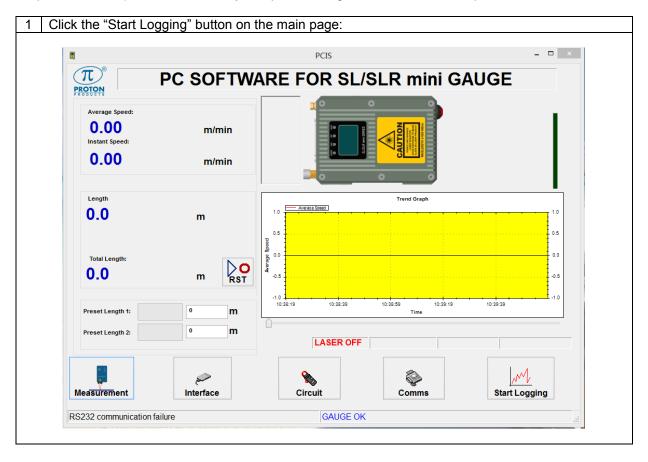


| Label | Description | Min | Тур | Max | Units |
|-----------------|---|-----|-----|-----|-------|
| Good Reading | The gauge attempts to sample the speed of the object several thousand times per second; the "Good Reading" rate represents the proportion of samples that have yielded a valid speed reading. Higher "Good Reading" rates result in better length accuracy, especially over shorter object lengths. If the surface of the object is irregular then different areas may yield different "Good Reading" rates. For smooth surfaces a "Good Reading" rate above 50% will produce speed and length readings of reliably high accuracy. In short-length measurement applications (such as inkjet-marking or cutting, with lengths in the range of a few metres), a "Good Reading" rate of above 80% is recommended to maintain good length accuracy. | | | | 14 |
| | Long length (> 5 m) accuracy | 50 | 70 | 100 | % |
| | Short length (0 ~ 5 m) accuracy | 80 | 90 | 100 | % |

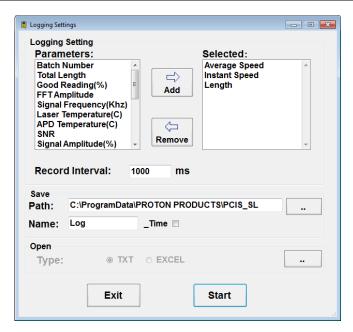
| | This parameter is highly-dependent on object material, object distance to the centre of the depth-of-field and object speed. | | | | |
|----------------------|---|-----|-----|----|-----------|
| SNR | For example, a metal or matt-plastic surface moving at 100 m/minute may return a SNR > 1000, but the SNR for a translucent plastic object may be much lower. | 200 | 500 | | - |
| | The signal-to-noise ratio must exceed 80 for a | | | | |
| | consistent and reliable speed reading. | | | | |
| | The DC level depends on the amount of light received from the object and must be between 10% and 90% for correct operation; it is held at around 30% by an automatic gain controller (AGC). | | | | |
| DC Level | The AGC may be saturated by highly reflective (e.g. flat, metallic) surfaces resulting in the DC level exceeding 100%; in this case tilt the gauge (pitch, angle $\gamma \neq 0$) to reduce the received light and bring the DC level below 90%. | 10 | 30 | 90 | % |
| | Very narrow or low-reflectivity objects might not reflect sufficient light for the DC level to reach 10%; maximise the signal by locating the object as close to the stand-off distance (i.e. centre of the depth-of-field). | | | | |
| | Highly-reflective, uneven or fast-moving objects may result in saturation and clipping of the received oscillating light signal. Signal amplitudes below 80% will not incur saturation, whilst an Automatic Gain Controller | | | | |
| Signal Amplitude | (AGC) will accommodate signal amplitude between 80 and 99%. Signal amplitudes above 99% will still yield measurements but at a substantially degraded Good Reading rate. | | | 80 | % |
| | Maintain the signal amplitude at below 80% by tilting the gauge (pitch, angle $\gamma \neq 0$) to reduce the received light. | | | | |
| Laser Temperature | | | | | °C |
| Heating | | | | | 0/ |
| State | | | | | % |
| Bragg Temperature | | | | | °C |
| Heating | | | | | 0,1 |
| State | | | | | % |
| APD | For use by Proton Products authorized service | | | | °C |
| Temperature FFT | personnel only. | | | | - |
| Amplitude | | | | | |
| DC Level (mV) | | | | | mV |
| APD Bias | | | | | V |
| Voltage | | | | | |
| Filter Band | | | | | - /U= |
| Frequency | | | |] | kHz |

DATA LOGGING

The data logging function logs measurement data at regular time intervals to a .csv (comma separated values) text file which may be opened using MS Excel and other spreadsheet software.

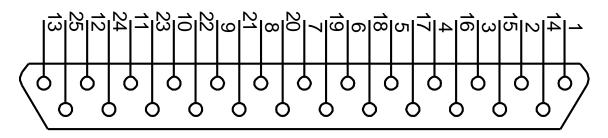


2 Select the required parameters to log to file, the logging time interval, file name and start/stop logging:



| Label | Description | on | | | |
|-----------------|--|---|--|--|--|
| Parameters | This displays the parameters that are available for logging; click to highlight a parameter in this list and then click the "Add" button to move the highlighted parameter to the "Selected" list. | | | | |
| Selected | This displays the parameters selected for logging; click to highlight a parameter in this list and then click the "Remove" button to move the highlighted parameter back to the "Parameter" list. | | | | |
| Add | Click this button to move a highlighted parameter from the "Parameters" list to the "Selected" list. | | | | |
| Remove | Click this button to move a highlighted parameter from the "Selected" list to the "Parameters" list. | | | | |
| Record Interval | Enter the interval time (in milliseconds) at which data is written to the log file. | | | | |
| Path | Click the "" button to edit the path to the log file. | | | | |
| Name | Click to ec | lit the name of the log file. | | | |
| Time | Ticked | Append the start time to the name of the log file. | | | |
| _Time | Unticked | Do not append the start time to the name of the log file. | | | |
| Start | Click to commence data logging. | | | | |
| Stop | Click to stop data logging. | | | | |
| Exit | Click to close this dialog box and return the main page. | | | | |

CONNECTOR PIN OUTS



Connector type: DB25 female (socket)

| Functional | Pin | Designation | Description | Notes |
|------------|-----|-------------|-------------------------|--|
| group | | _ | - | Notes |
| Logic | 3 | LIN1 | Logic input 1 | Low < +3V; High > +10.5V; Max ±30V |
| inputs | 4 | LIN2 | Logic input 2 | User configurable function. |
| прис | 5 | LIN3 | Logic input 3 | Osci comigurable function. |
| Logic | 6 | LOP1 | Logic output 1 | Floating or pull-down; user configurable |
| outputs | 7 | LOP2 | Logic output 2 | function. |
| CANbus | 8 | CAN H | CANbus high | For connection to Proton Products |
| CAMBUS | 9 | CAN L | CANbus low | accessories. |
| | 12 | SHUT ST | Shutter status | Pulled down to DGND when the shutter |
| | 12 | 31101_31 | Shutter status | is open. |
| Laser | 13 | /SHUT_EN | Shutter control | Pull down to DGND to open the laser |
| safety | 13 | /SHUT_EN | Shatter control | shutter. |
| | 14 | /LSR EN | Laser enable | Pull down to DGND to enable the laser |
| | 14 | /LOK_EIN | Laser enable | diode. |
| RS-232 | 16 | RXD | RS-232 receive | |
| NO-232 | 17 | TXD | RS-232 transmit | |
| | | | Pulse output external | If no external power supply is |
| | 1 | POUT +V | power supply | connected, then the pulse outputs |
| Pulse | | | | default to the internal +5V supply. |
| outputs | 18 | P1A | Pulse output 1 | RS-422 compliant differential pair |
| Outputs | 19 | /P1A | Inverted pulse output 1 | outputs. Pulse outputs 1 and 2 may be |
| | 20 | P2A | Pulse output 2 | user-configured for independent or |
| | 21 | /P2A | Inverted pulse output 2 | quadrature operation. |
| | 25 | +24V | Power supply | Operating voltage: 15 to 28VDC |
| | 20 | | 1 Ower Supply | Power consumption: 15W |
| | 2 | DGND | Power supply and | |
| | 15 | DGND | signal ground | |
| | 24 | DGND | reference | |
| Shield | S | Shield | Shield | Connect to cable and plug shields |

| Functional | | | Industrial bus option | | | |
|------------|-----|-------------|-------------------------|----------|-----------|--|
| group | Pin | Designation | Ethernet EtherNet/IP | PROFIBUS | DeviceNET | |
| | 22 | IBUS1 | TX+ | +5V | V+ | |
| Industrial | 10 | IBUS2 | TX- | GND | V- | |
| bus | 23 | IBUS3 | RX+ | Α | CANH | |
| | 11 | IBUS4 | RX- | В | CANI | |

OPTIONAL PSU-BOB MINI

The Proton Products PSU-BOB mini (Power Supply Unit-Break Out Box-mini) is an optional accessory for the SL mini / SLR mini series of laser speed and length gauges which provides the following functions:

- Universal AC to DC power supply
- DB9 connectors for CANbus, RS-232 and optional PROFIBUS / DeviceNET communications interfaces
- RJ45 socket for Ethernet MODBUS or optional Ethernet/IP communications interface
- Laser enable key switch
- Screw terminals for logic inputs, logic outputs, pulse outputs and laser safety connections







The SL mini / SLR mini gauge may be connected to the PSU-BOB mini using one of the following optional DB25-to-DB25 cables:

| Length / m | Part name | Proton part no |
|------------|----------------|----------------|
| 3 | SLMKII-BOB-003 | 00043MC021 |
| 5 | SLMKII-BOB-005 | 00041CT005 |
| 10 | SLMKII-BOB-010 | 00041CT010 |
| 20 | SLMKII-BOB-020 | 00041CT020 |
| 30 | SLMKII-BOB-030 | 00041CT030 |

CAN

Connector type: DB9 male (plug)

| Pin | Designation | Comment |
|-----|-------------|---|
| 2 | CANL | |
| 3 | GND | Ground reference (isolated from earth / shield). |
| 5 | Shield | Ensure that the cable shield is connected to this via the plug shield connection. |
| 7 | CANH | |
| 9 | +24V | +24VDC power input (the gauge may be powered via this pin). |
| S | Shield | Ensure that the cable shield is connected to the plug shield connection. |

RS232

Connector type: DB9 female (socket)

| Pin | Designation | Comment | PC DB9 serial port pin |
|-----|-------------|--|------------------------|
| 2 | TXD1 | | 2 |
| 3 | RXD1 | | 3 |
| 5 | GND_R | Ground reference is not isolated from earth. | 5 |

| Pin | Designation | Comment | PC DB9 serial port pin |
|-----|-------------|---|------------------------|
| 7 | CTS1 | | Not used |
| 8 | RTS1 | | Not used |
| S | Shield | Ensure that the cable shield is connected to this via the plug shield connection. | Shield |

The above table also shows the configuration of a cable for connection to a personal computer (PC) type DB9 serial port.

I-BUS

Connector type: DB9 female (socket)

| PROFIBUS | | | |
|----------|----------|---|--|
| Pin | Function | Comments | |
| 3 | В | | |
| 5 | GND | | |
| 6 | +5V | | |
| 8 | Α | | |
| S | Shield | Ensure that the cable shield is connected to this via the plug shield connection. | |

| DeviceNet | | | |
|-----------|----------|-------------|---|
| Pin | Function | Wire colour | Comment |
| 3 | CANL | Blue | |
| 5 | V- | Black | |
| 6 | V+ | Red | |
| 8 | CANH | White | |
| S | Shield | | Ensure that the cable shield is connected to this via the plug shield connection. |

| Ethernet / EtherNet/IP / PROFINET | | | |
|-----------------------------------|----------|---|--|
| Pin | Function | Comments | |
| 1 | LAN TX- | | |
| 2 | LAN TX+ | | |
| 7 | LAN RX- | | |
| 9 | LAN RX+ | | |
| S | Shield | Ensure that the cable shield is connected to this via the plug shield connection. | |

Note: for Ethernet, EtherNet/IP and PROFINET communications interfaces, the i-BUS DB9 socket and RJ45 socket are wired in parallel; either one or the other connector may be used depending on the available cable plug type.

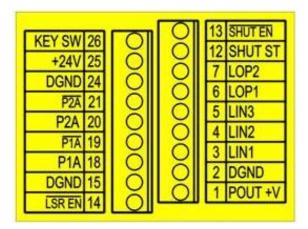
RJ45 SOCKET

Connector type: RJ45 8P8C female (socket)

| Ethernet / EtherNet/IP / PROFINET | | | |
|-----------------------------------|----------|---|--|
| Pin | Function | Comments | |
| 1 | LAN TX+ | | |
| 2 | LAN TX- | | |
| 3 | LAN RX+ | | |
| 6 | LAN RX- | | |
| S | Shield | Ensure that the cable shield is connected to this via the plug shield connection. | |

Note: for Ethernet, EtherNet/IP and PROFINET communications interfaces, the i-BUS DB9 socket and RJ45 socket are wired in parallel; either one or the other connector may be used depending on the available cable plug type.

SCREW TERMINALS



Connector type: Screw terminals

| Functional group | Screw terminal* | Designation | Description | Notes |
|------------------|-----------------|-------------|------------------------------------|--|
| Logio | 3 | LIN1 | Logic input 1 | Low < +3V; High > +10.5V; Max |
| Logic | 4 | LIN2 | Logic input 2 | ±30V |
| inputs | 5 | LIN3 | Logic input 3 | User configurable function. |
| Logic | 6 | LOP1 | Logic output 1 | Floating or pull-down; user |
| outputs | 7 | LOP2 | Logic output 2 | configurable function. |
| CANbus | 8 | CAN H | CANbus high | For connection to Proton |
| CAMBUS | 9 | CAN L | CANbus low | Products accessories. |
| | 12 | SHUT_ST | Shutter status | Pulled down to DGND when the shutter is open. |
| Laser safety | 13 | /SHUT_EN | Shutter control | Pull down to DGND to open the laser shutter. |
| | 14 | /LSR_EN | Laser enable | Pull down to DGND to enable the laser diode. |
| RS-232 | 16 | RXD | RS-232 receive | |
| RS-232 | 17 | TXD | RS-232 transmit | |
| Dule | 1 | POUT +V | Pulse output external power supply | If no external power supply is connected, then the pulse outputs default to the internal +5V supply. |
| Pulse | 18 | P1A | Pulse output 1 | RS-422 compliant differential pair |
| outputs | 19 | /P1A | Inverted pulse output 1 | outputs. Pulse outputs 1 and 2 |
| | 20 | P2A | Pulse output 2 | may be user-configured for |
| | 21 | /P2A | Inverted pulse output 2 | independent or quadrature operation. |
| | 25 | +24V | Power supply | Operating voltage: 15 to 28VDC Power consumption: 15W |
| | 2 | DGND | Power supply and | |
| | 15 | DGND | signal ground | |
| | 24 | DGND | reference | |
| Shield | S | Shield | Shield | Connect to cable and plug shields |
| Key-switch | 26 | KEY SW | Laser enable key- switch | This terminal is connected via the key-switch to DGND. A removable jumper connects this terminal to the /LSR_EN (14) terminal. |

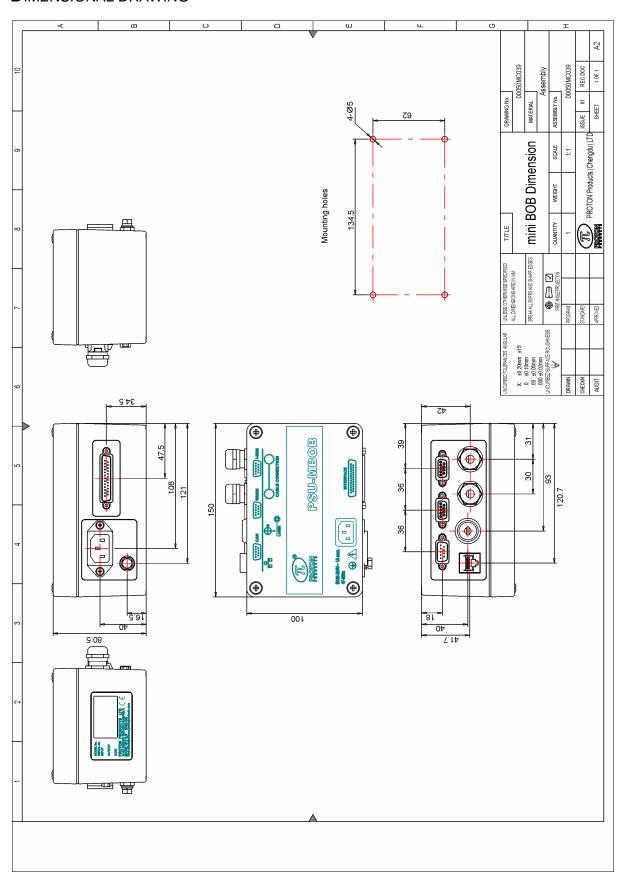
^{*} screw terminal numbering corresponds to the pin numbering for the DB25 INTERFACE connector on the gauge.

KEY SWITCH

The key switch is provided for compliance with laser safety regulations.

- When the key switch is in the open-circuited ("O") the laser diode in the gauge is DISABLED for laser emission.
- When the key switch is in the short-circuited ("I") the laser diode in the gauge is ENABLED for laser emission.
- After the key switch is set to the enabled ("I") position, a warm up period is required to for the laser diode to stabilise before measurements may be taken. The key-switch is intended for intermittent use such as locking out the laser at the end-of-shift or during line maintenance.
- A removable shorting-link connects the LSR_EN pin via the key-switch to DGND; removal of
 this shorting link disables the key-switch and permits an external, user-supplied interlock
 switch to be wired in place of the key-switch.

DIMENSIONAL DRAWING



INPUT PARAMETERS

1 DW word = 2 bytes

| 20 | | | | |
|----|--|--|--|--|
| | | | | |

| | word = 2 | | 11.2 | | | 2013.08.26 |
|--------------------|----------|---|----------------------------|--------|--|------------|
| DW | Bit | Comment | Unit | | Range/Remark | Default |
| 0 | | System Function | | | 0-Normal mada | |
| | 0 | Measurement mode | | | 0=Normal mode 1=Batch mode | 0 |
| | | | | | 0=Reset length to zero | |
| | 1 | Length reset | | | 1=Accumulate length | 1 |
| | | Batch length reset | | | | |
| | 2 | (available in batch mode | | | 0=Reset length to zero 1=Accumulate length | 1 |
| | | only) | | | - | |
| | 3 | | | | 0=metres | |
| | 4 | Measurement unit | | | 1=feet | 0 |
| | 4 | | | | 2=yards 3=other unit(set on PCIS) | |
| | | Speed signal output | | | 0=Averaged | |
| | 5 | response | | | 1=Instantaneous | 1 |
| | 6 | Pulse output 3 mode | | | 0=Speed | 0 |
| | U | Fulse output 3 mode | | | 1=Length | U |
| | 7 | Analogue output source | | | 0=Speed | 0 |
| | - | · | | | 1=Good Readings | - |
| | 8 | Length / speed | | | 0=Length 0.1 / speed 0.01 1=Length 0.0001 / Speed | 1 |
| | 0 | resolution | | | 0.001 | ' |
| | _ | Dula a sutment 4 manda | | | 0=Normal | 0 |
| | 9 | Pulse output 1 mode | | | 1=Quadrature | 0 |
| | 10 | Automatic save length | | | 0=Invalid | 0 |
| | | function | | | 1=Valid | Ů |
| | 11 | Object detection switch | | | 0=Off 1=On | 0 |
| | | Auto reset when object | | | 0=Off | |
| | 12 | detected | | | 1=On | 0 |
| | | | | | 0=Normal | |
| | 13 | Reset reel number | | | 1=Reset reel number to | 0 |
| | | | | | zero | |
| | 14~15 | Not used | | | | 0 |
| 1 | | Preset 1 and 2 decimal point position | | | -3~3 | 0 |
| 2 | | Averaging time | 1=5ms | | 1~1000 (5~5000ms) | 200 |
| | | No speed signal hold | | | • | |
| 3 | | time | 1=1ms | | 1~5000 (1ms~5s) | 100 |
| 4 | | Batch mode LOP | 1=10ms | | 1~500 (10ms~5s) | 50 |
| | | closure time | 1-101110 | | 1 000 (101110 00) | 00 |
| 5 | | Preset length 1 or Preset batch length | 1=1/10DW1m{ft}{yds{inch | า}} | 0~65535 | 1000 |
| | | Preset length 2 or | 1=1/10DW1m{ft}{yds}{inc | .hl | | |
| 6 | | Preset batch number | 1=1/105W militryyddymio | ,,,, | 0~65535 | 2000 |
| 7 | | Pulse output 1 rate | 1=1/10DW17pulse/m{ft}{y | yds} | 1~65535 | 1000 |
| 8 | | Pulse output 2 rate | 1=1/10DW17pulse/m{ft}{y | yds} | 1~65535 | 1000 |
| 9 | | Pulse output 3 rate | 1=1/10DW17pulse/m{ft}{y | | 1~65535 | 1000 |
| 10 | | Analogue output full | 1=1m/min{ft/min} | | 100~9999 | 3000 |
| 11 | | scale Minimum speed limit | 1=0.1m/min{ft/min} | | 0~65535 (0~6553.5) | 0 |
| - ' ' - | | | compatible with old SL ga | allue. | | l o |
| | 0 | ogio input (oid ioiniat. | Jonipations with old SE go | | irection | |
| | | Lania innut 4 for all an | | | ength hold | |
| | 1 | Logic input 1 function | | | isplay hold | 1 |
| | | | | 3=S | peed hold | |
| | | Direction setting | | 0=C | ount up | |
| | 2 | (available only when no | | | ount down | 0 |
| | | logic input for direction) | | 0-4 | ctive low | |
| 12 | 3 | Logic input 1 polarity | | | ctive low | 0 |
| | 4~7 | Not used | | | · • | 0 |
| | 8 | Logic input 2 function | | 0=R | eset input | 0 |
| | 9 | Logic input 2 function | | | ength hold | U |
| | 10 | Logic input 2 polarity | | | ctive low | 0 |
| | | - 3 - 1/20 = F 2/2007 | | | ctive high | |
| | 11 12 | Logic input 3 function | | | irection ength hold | 1 |
| | 13 | Logic input a function | | | isplay hold | [' |
| | | L | 1 | | -1 -7 | j |

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|---------------|---|-----------------------|--|---------|
| | | | | 3=Speed hold | |
| | | | | 4=Reset 0=Active low | |
| | 14 | Logic input 3 polarity | | 1=Active low | 0 |
| | 15 | Must be 0 | | 0=Old format logic inputs | 0 |
| | | Logic input(new format; | DW12.15=1) | | |
| | 0 | | | 0=Direction (count down) 1=Length hold | |
| | 1 | | | 2=Display hold | |
| | | Logic input 1 function | | 3=Speed hold | 0 |
| | 2 | | | 4=Reset total length | |
| | | | | 5= End of Reel / Reset batch length | |
| | 3 | Logic input 1 polority | | 0=Active low | 0 |
| | _ | Logic input 1 polarity | | 1=Active high | U |
| | <u>4</u> 5 | | | 0=Direction (count down) 1=Length hold | |
| | 3 | | | 2=Display hold | |
| | | Logic input 2 function | | 3=Speed hold | 1 |
| | 6 | | | 4= Reset total length | |
| 12 | | | | 5=End of Reel / Reset batch length | |
| '- | 7 | Logic input 2 polarity | | 0=Active low | 0 |
| | | Logic input 2 polarity | | 1=Active high | · · |
| | <u>8</u> 9 | - | | 0=Direction (count down) 1=Length hold | |
| | 3 | 1 | | 2=Display hold | |
| | | Logic input 3 function | | 3=Speed hold | 4 |
| | 10 | | | 4= Reset total length 5= End of Reel / Reset batch | |
| | | | | length | |
| | 11 | Logic input 3 polarity | | 0=Active low | 0 |
| | 11 | | | 1=Active high | U |
| | 12 | Direction setting (available only when no | | 0=Count up | 0 |
| | 12 | logic input for direction) | | 1=Count down | |
| | 13~14 | Not used | | | |
| | 15 | Must be 1 | | 1=New format logic inputs 0=Laser on | |
| 13 | | Laser switch | | 1=Laser off | 0 |
| 14 | | Length offset | 1=0.1m{ft}{yds}{inch} | -3000.0~3000.0m{ft}{yds} | 0 |
| 15 | | Pulse output 3 preset | 1=0.001m{ft}{yds} | | 1000 |
| | | length Logic output function | (70) | | |
| | 0~3 | LOP1 function | | 0=Gauge OK | 0 |
| | 4~7 | LOP2 function | | 1=Gauge measuring speed | 2 |
| | | | | 2=Preset length 1 / Batch length | |
| | | | | 3=Preset length 2 / Batch number | |
| | | | | 4=Good reading | |
| | 8~11 | LOP3 function | | 5=Object detected | 3 |
| 16 | | | | 6=Gauge too hot 13=User 1 | |
| 10 | | | | 14=User 2 | |
| | | | | 15=User 3 | |
| | | | | 0=OPEN | |
| | 13 | User I/P 1 | | 1=CLOSE | |
| | 14 | User I/P 2 | | 0=OPEN | |
| | 17 | 00011/1 2 | | 1=CLOSE | |
| | 15 | User I/P 3 | | 0=OPEN 1=CLOSE | |
| | | | | 3=1000 | |
| | | | | 2=100 | |
| 17 | | Pulse output rate | 1=1 | 1=10 0=1 | 0 |
| 17 | | resolution | 1=1 | 0=1 -1=0.1 | 3 |
| | | | | -2=0.01 | |
| 40 | | Cood Deadles discussion | 4 40/ | -3=0.001 | 600/ |
| 18 | | Good Reading threshold Pulse reset during reset | 1=1% | 0=Off | 60% |
| 19 | | length | | 1=On | 0 |
| 1 | | | | | |

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----------|--|---------------------------|---------------------|--------------------------------------|-----------------|
| 21 | | CAN address | 1=1 | 0~255 | 14 |
| | | | | 0=250 | |
| 00 | | CANID | | 1=500 | |
| 22 | | CAN baud rate | | 2=1000 | 2 |
| | | | | other=500 | |
| | | | | 0=4800 | |
| | | | | 1=9600 | |
| 23 | | RS232 baud rate | | 2=19200 | 1 |
| | | | | 3=38400 | |
| | | | | 4=115200 | |
| 0.4 | | DC000 d- | | 0=Proton protocol | _ |
| 24 | | RS232 mode | | 1=Modbus protocol 2=ZM400 Printer | 1 |
| | | | | 0=Proton protocol | |
| | | | | 1=Modbus protocol | |
| 25 | | RS422/RS485 mode | | 2=SSI speed protocol | 1 |
| | | | | 3=SSI length protocol | |
| | | | | 0=4800 | |
| | | | | 1=9600 | |
| | | | | 2=19200 | |
| -00 | | D0 400/D0 405 I | | 3=38400 | |
| 26 | | RS422/RS485 baud rate | | 4=115200 | 1 |
| | | | | 5=250K | |
| | | | | 6=500K | |
| | | | | 7=1M | |
| 27 | | Modbus address | 1=1 | 0~255 | 1 |
| 28 | | EtherNet protocol | | 0=Modbus protocol | 0 |
| 20 | | Ethernet protocol | | 1=EIP protocol | U |
| 29 | | DHCP | | 0=Disabled | 0 |
| | | 2 | | 1=Enabled | |
| 30 | | IP address | x.x.x.x | | C0A8016E |
| 31 | | | | | (192.168.1.110) |
| 32 | | Subnet mask | x.x.x.x | | FFFF0000 |
| 33 | | | | | (255.255.0.0) |
| 34 35 | | Gateway | x.x.x.x | | C0A80001 |
| 33 | | - | | 0=Off | (192.168.1.1) |
| 36 | | CAN terminator | 1=1 | 1=On | 0 |
| | | | | 1-011 | |
| 37 | | | | | |
| | | Speed compensation | | | 1,000 |
| 38 | | coefficient | 1=0.0001 | | 10000 |
| 39 | | Acceleration limit | 1=1m{ft}{yd}/min/s | 1~9999 | 9999 |
| 40 | | Reset parameters to | | 63000=factory default | |
| 40 | | factory defaults | | other=invalid | |
| 41 | | UDP data output interval | 1=1ms | 1~5000 | 0 |
| | | time | | 0=Disable UDP output | |
| 42 | | Analogue O/P gain | 1=0.0001 | | 9999 |
| 43 | <u> </u> | Analogue O/P zero | 1=0.0001 | | 0 |
| 44 | | Speed simulation | | 0=Normal | 0 |
| | | • | 4.04.000.100 | 1=Simulation | |
| 45 | | Simulation speed | 1=0.1m{ft}{yds}/min | 0~6553.5 | 100 |
| 46 | | DeviceNet address | | 0~63 | 7 |
| 4- | | Design No. 1 | | 0=125K | |
| 47 | | DeviceNet baud rate | | 1=250K | |
| - | | LIDD doction (Co. 1D | | 2=500K | |
| 48 | | UDP destination IP | | Note: the UDP destination port | 2 |
| | + | address (last octet only) | | number is fixed at 1111 | |
| 49 | | Endianess | | 1=Little endian | 0 |
| <u> </u> | <u> </u> | 1 | l | 0=Big endian | 1 |

OUTPUT PARAMETERS

1 DW word = 2 bytes

2013.08.26

| | | I = 2 bytes | | 2013.08.26 |
|----|-----|--------------------------------------|---|----------------------------|
| DW | Bit | Comments | Units | Range/Remark |
| | 0 | Mode | | 0=Normal |
| | U | Wode | | 1=Batch |
| | | | | 0=Length 0.1 / speed 0.01 |
| | 1 | Length / speed resolution | | 1=Length 0.0001 / speed |
| | | | | 0.001 |
| | 2 | Not used | | |
| | 3 | Measured length >= Preset1 | | 1=>Preset |
| | 4 | Measured length >= Preset2 | | 1=>Preset |
| | 5 | Length reset | | 0=Reset |
| | 6 | | | 0=Metres |
| | 7 | Measurement unit | | 1=Feet 2=Yards |
| | , | | | 3=other unit (set on PCIS) |
| 0 | | | | 0=Averaged |
| | 8 | Speed signal output response | | 1=Instantaneous |
| | 9 | | | |
| | 10 | Lagaratatus | | 1=Laser on |
| | 10 | Laser status | | 0=Laser off |
| | 11 | Gauge OK | | 1=Gauge OK |
| | 12 | Speed reading validity | | 1=Valid |
| | 12 | Opeca reading validity | | 0=Invalid |
| | 13 | Object detected | | 1=Object detected |
| | | | | 0=No object |
| | 14 | Good reading status | | 1=Lower than threshold |
| | 15 | Not used | | 0=OK |
| | 15 | | | 1=Error |
| | 0 | Gauge OK | | 0=OK |
| | | | | 1=Too high |
| | 1 | Laser temperature too high | | 0=OK |
| | _ | 1 1 | | 1=Too low |
| | 2 | Laser temperature too low | | 0=OK |
| | 3 | APD temperature too high | | 1=Too high |
| | 3 | Al Ditemperature too nigh | | 0=OK |
| 1 | 4 | APD temperature too low | | 1=Too low |
| | - | | | 0=OK |
| | 5 | APD DC level | | 1=Too high 0=OK |
| | | | | 1=Too hot |
| | 6 | Gauge too hot | | 0=OK |
| | 7 | Not used | | 0 0.1 |
| | 8 | Not used | | |
| | | | | |
| 2 | | A | | ±10~999999 |
| 3 | | Average speed | Old format: 1=0.01m/min {ft/min} {yds/min} | (0.10~9999.99) |
| 4 | | Instant speed | New format: 1=0.001m/min{ft/min}{yds/min} | ±10~999999 |
| 5 | | · | | (0.10~9999.99) |
| 6 | | Total length / Batch length (when in | Old format: 1=0.1m{ft}{yds}{inch} | ±200,000.0000 |
| 7 | | batch mode) | New format: 1=0.0001m{ft}{yds}{inch} | , |
| | | Logic input | | |
| | 0 | Not used | | 0-Count up |
| | 1 | Direction | | 0=Count up 1=Count down |
| | 2 | | | 0=Direction |
| | | 1, | | 1=Length hold |
| | 3 | Logic input 1 function | | 2=Display hold |
| | | | | 3=Speed hold |
| 8 | 4 | Logic input 1 state | | 1=Active |
| " | 5~7 | | | |
| | 8 | Logic input 2 function | | 0=Reset input |
| | 9 | • • | | 1=Length hold |
| | 10 | Logic input 2 state | | 1=Active |
| | 11 | Direction | | 0=Count up |
| | 12 | Length hold | | 1=Count down 1=Hold |
| | 13 | Display hold | + | 1=Hold |
| | 14 | Speed hold | | 1=Hold |
| | | 1 | 1 | |

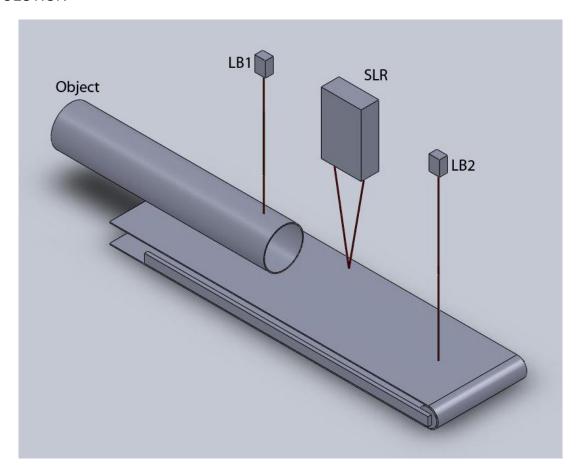
| DW | Bit | Comments | Units | Range/Remark |
|----------|-----|-------------------------------|-----------------------|--|
| | 15 | Length reset | | 1=Reset |
| 9 | | Not used | | |
| 10 | | Batch number | 1=1 | |
| 11 | | Not used | | SNR |
| 12 | | Total length | 1=0.1m{ft}{yds}{inch} | ±200,000.0000 |
| 13 | | Total leligiti | | |
| 14 | | Good readings percentage | 1=1% | 0~100 |
| 15 | | Not used | | Signal amplitude |
| 16 | | Not used | | |
| 17 | | Not used | | |
| 18 | | Not used | | |
| 19 | | Not used | | |
| 20 | | i-BUS communications bus type | | 0=Modbus_TCP 1=PROFIBUS 2=DeviceNET 3=Ethernet/IP 4=PROFINET |
| 21 | | DHCP | | 0=Enable 1=Disable |
| 22 23 | | IP address | x.x.x.x | |
| 24 | | Subnet mask | x.x.x.x | |
| 25 | | Capital mank | AAAAA | |
| 26 | | Gateway | x.x.x.x | |
| 27 | | • | | |
| 28 | | Not used | | |
| 29 | | Not used | | |

APPENDIX 1: HIGH ACCURACY LENGTH MEASUREMENT OF DISCRETE OBJECTS APPLICATION NOTE

PROBLEM

Length measurement of discrete objects moving on a production line may incur errors due to the tracking delay / hold time of the SL / SLR / SL mini / SLR mini gauge as individual objects enter and leave the gauge measurement spot.

SOLUTION

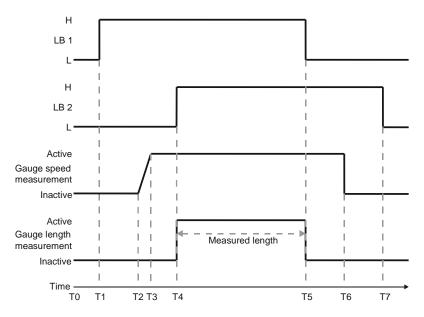


Use two accurately spaced light barriers connected to the logic inputs of the gauge to trigger length measurement only after the object is in position for accurate speed measurement by the gauge.

One light barrier (LB1) is installed upstream of the gauge and one light barrier (LB2) is installed downstream of the gauge. "L" is the accurately measured distance between LB1 and LB2.

The gauge is configured to measure length only when **both** LB1 **and** LB2 are interrupted by the object. The gauge thus measures the length of the object minus a section corresponding to the distance between LB1 and LB2:

Object length = L + (gauge measured length)



| Time | Object status | LB1 | LB1 | SL / SLR status |
|----------------|-----------------------------|---------|---------|--|
| T ₀ | Clear of LB1, LB2, SL / SLR | Clear | Clear | No object |
| T ₁ | Leading edge interrupts LB1 | Blocked | Clear | No object |
| T ₂ | Leading edge enters gauge | Blocked | Clear | Object detected but speed |
| | measurement spot | | | measurement not yet valid |
| T ₃ | - | Blocked | Clear | Speed measurement valid (but not displayed/output in "Length hold" mode) |
| T_4 | Leading edge interrupts LB2 | Blocked | Blocked | Length measurement starts |
| T ₅ | Trailing edge clears LB1 | Clear | Blocked | Length measurement ends |
| T ₆ | Trailing edge clears gauge | Clear | Blocked | Speed measurement ends |
| | measurement spot | | | |
| T ₇ | Trailing edge clears LB2 | Clear | Clear | No object |

The distance between the gauge gauge and LB2 must be large enough to allow the gauge sufficient time to generate valid speed measurements before the object reaches LB2 and triggers length measurement. Distance "L" between LB1 and LB2 must also be less than the minimum object length.

IMPLEMENTATION

Light barriers LB1 and LB2 can be connected to any 2 of the 3 logic inputs provided on the gauge. The behaviour of the gauge can be configured to trigger length measurement only when *both* LB1 and LB2 are blocked.

Both logic inputs should be configured to "Length hold" mode. An *active* logic input in "Length hold" mode will cause the gauge to freeze length readings and force the displayed speed to zero (however, internally the gauge will continue to accurately measure speed if an object is present). Hence each logic input should be configured to be *active* when its corresponding light barrier is *clear*.

A "Length offset" corresponding to the distance "L" between the two light barriers can also be programmed in to gauge. The gauge will then automatically add this "Length offset" to its length measurement display and output.

The length measurement generated by the gauge will be ready to read by other production control equipment when the output of LB1 transitions from blocked-to-clear (the object's trailing edge passes through LB1). A momentary pulse may be sent to the third logic input on the gauge to reset the length measurement once it has been read out by other production control equipment.

Connections to the SL / SLR / SL mini / SLR mini gauge

SL / SLR / SL mini / SLR mini gauges provide three user configurable logic inputs to connect to light barriers LB1 and LB2 and also to a reset pulse input from other production control equipment for resetting the length measurement. Access to these inputs is either via:

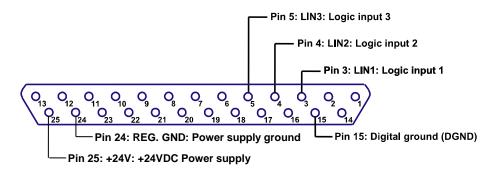
- 1. The DB25 INTERFACE socket on the gauge.
- 2. The screw terminal board in an optional PSU-BOB-SL combination power supply and breakout box (for SL and SLR gauges) or a PSU-BOB-SL-mini (for SL mini and SLR mini gauges).

| Pin / Screw | Designation | Designation full name | Suggested application |
|-------------|-------------|-----------------------|--|
| 3 | LIN 1 | Logic input 1 | LB1 – Length hold mode |
| 4 | LIN 2 | Logic input 2 | LB2 – Length hold mode |
| 5 | LIN 3 | Logic input 3 | Reset length measurement pulse (no shorter than 1ms in duration) |
| 15 | DGND | Digital ground | Ground reference for LB1 and LB2 |

Power for +24VDC light barriers may be derived from the +24VDC power rail of the gauge:

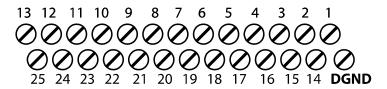
| Pin / Screw | Designation | Designation name | Suggeste | ed application |
|-------------|-------------|-------------------|---|---|
| 24 | REG. GND | Power rail ground | SL / SLR | User must externally connect this pin to DGND (pin 15) if used to power +24VDC light barriers |
| | | | SL mini / SLR mini | Already internally connected inside the SL mini / SLR mini to DGND (pin 15). |
| 25 | +24V | +24VDC power rail | May be used to power +24VDC light barriers. | |

DB25 INTERFACE Socket Logic Input Pin Designations



Connector type: DB25 Female Socket

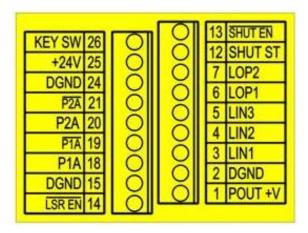
PSU-BOB-SL Screw Terminal Designations (for SL and SLR gauges only):



PSU-BOB-SL screw terminal numbers correspond directly to DB25 interface socket pin numbers.

In addition to screw terminal 15, an additional Digital Ground (DGND) terminal is provided on the PSU-BOB-SL screw terminal board.

PSU-BOB-SL-mini Screw Terminal Designations (for SL mini and SLR mini gauges only):



Connector type: Screw terminals

| Functional group | Screw terminal | Designation | Description | Notes |
|------------------|-------------------|-------------|------------------|---|
| Logio | 3 | LIN1 | Logic input 1 | Low < +3V; High > +10.5V; Max |
| Logic inputs | 4 | LIN2 | Logic input 2 | ±30V |
| | 5 | LIN3 | Logic input 3 | User configurable function. |
| | 25 | +24V | Power supply | Operating voltage: 15 to 28VDC Power consumption: 15W |
| | 2 | DGND | Power supply and | |
| | 15 | DGND | signal ground | |
| | 24 | DGND | reference | |

PSU-BOB-SL-mini screw terminal numbers correspond directly to DB25 interface socket pin numbers.

Logic input electrical characteristics

- Logic inputs are referenced to pin 15 (DGND). Pin 15 is internally connected to the enclosure earth so all voltages are also referenced to earth.
- A low state (logic 0) is defined as a voltage below +3V.
- A high state (logic 1) is defined as a voltage above +10.5V.
- The safe input voltage range is -30V to +30V.
- All inputs are internally pulled up via a 5.1kΩ resistor to an internal +15V source, thus inputs left open circuit default to the high state.
- The logic input requires a current of 3mA to pull it down to the low state.

Connection to the logic input depends on the signal source as follows:

- Solid state or mechanical relay contact: connect between pin 15 (DGND) and logic input pin.
- Pull-down: Connect ground to pin 15 (DGND) and signal to the logic input pin.
- Pull-up: Connect an $820k\Omega$ resistor from the logic input pin to pin 15 (DGND); this will pull down the input to 2.5V when the pull-up is switched off. Connect ground to pin 15 (DGND) and signal to the logic input pin. If the signal is 24V, then power loss in the resistor across the input can be reduced by adding an $820k\Omega$ resistor in series with the signal.

Gauge software configuration

The behaviour of the gauge can be configured via RS232, the optional AiG2 display unit or optional PCIS software. The following three configuration settings need to be adjusted:

- 1. Configure both light barrier logic input functions to "Length hold" mode.
- 2. Configure both light barrier logic input active states to **active** when the light barriers are **clear** (**no object**):

| LB1, LB2 output when clear (no object) | "Length hold" logic input active state |
|--|--|
| Low (pull down) | Active low |
| High (pull up) | Active high |

- 3. Configure reset logic input function to "Reset length" mode.
- 4. Configure reset logic input active state to active high or active low as required.
- 5. Configure "Length offset" to distance "L" between LB1 and LB2.

SL / SLR gauge configuration using the optional AiG2 display unit:

Navigate to the "Interface" menu and then navigate to the following submenus:

Logic input function:

Select "Length hold" for each light barrier logic input. Select "Reset length" for the reset pulse logic input.

Logic input active state:

Select "Active high" or "Active low" for each logic input.

• Navigate to the "Measurement" menu and then navigate to the following submenu:

Length offset:

Set a positive value corresponding to distance "L".

Note: If the default resolution of 1=0.1 m (or ft or yds or inch) of the "Length Offset" parameter is too large, then an enhanced resolution "Length Offset" of 1=0.001 m (or ft or yds or inch) can be factoryenabled in the SL / SLR gauge.

SL / SLR gauge configuration via RS232:

The following input parameters can be programmed via RS232 (and other optionally installed interfaces) on the SL / SLR gauge. For further information regarding the data format for programming parameters, please consult the SL / SLR gauge instruction manual.

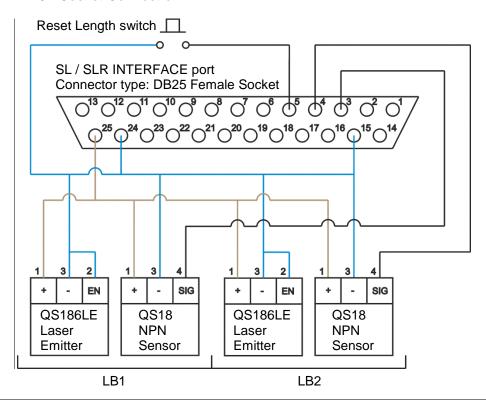
| DW | Data bit | Comments | Value |
|----|-------------|--|--|
| | 0 | | |
| | 1 | Logic input 1 function Logic input 1 polarity | 1= Length hold 4= Reset length [if signal held for 5s, resets reel number] |
| | 2 | | 1 - 13000 longar [ii dignar nota tor co, 1000 to 1001 hambor] |
| | 3 | | 0 = active low (pulled down) 1 = active high (pulled up) |
| | 4 | | 4 1 4 1 |
| | 5 | | 1 = Length hold 4= Reset length [if signal held for 5s, resets reel number] |
| 12 | 12 6 | | 4- Neset length [ii signal field for est, resets reel flamber] |
| | 7 | Logic input 2 polarity | 0 = active low (pulled down) 1 = active high (pulled up) |
| | 8 | | 4 1 4 1 |
| | 9 | Logic input 3 function | 1 = Length hold 4= Reset length [if signal held for 5s, resets reel number] |
| | | | - reset longer [ii signal note to oo, resets red namber] |
| | 11 | Logic input 3 polarity | 0 = active low (pulled down) 1 = active high (pulled up) |

| DW | / Comments Unit | | Range | Value |
|----|-----------------|-----------------------|-------------------------------|---------------------|
| 14 | Length offset | 1=0.1m{ft}{yds}{inch} | 3000.0~3000.0m{ft}{yds}{inch} | Set to distance "L" |

Note: If the default resolution of 1=0.1 m{ft}{yds}{inch}of the "Length Offset" (DW14) parameter is too large, then an enhanced resolution "Length Offset" of 1=0.001 m{ft}{yds}{inch} can be factory-enabled in the SL / SLR gauge.

EXAMPLE IMPLEMENTATION USING BANNER QS18 LASER EMITTERS AND QS186LE NPN SENSORS

DB25 INTERFACE Socket Connection



| QS186LE Laser Emitter / QS18 NPN Sensor wiring colour code | | | | | |
|--|-------|-------|------|-------|--|
| Pin 1 2 3 4 | | | | | |
| Colour | Brown | White | Blue | Black | |

When no object is present, laser light from the QS186LE laser emitter illuminates the QS18 NPN sensor and its SIG output is pulled low; hence the SL / SLR gauge "Length hold" function must be set to "active low".

SL / SLR gauge configuration using the optional AiG2 display unit:

• Navigate to the "Interface" menu and then navigate to the following submenus:

Logic input function:

Select "Length hold" for logic inputs 1 and 2. Select "Reset length" for logic input 3.

Logic input active state:

Select "Active low" for logic inputs 1, 2 and 3.

• Navigate to the "Measurement" menu and then navigate to the following submenu:

Length offset:

Set a positive value corresponding to distance "L".

SL / SLR gauge configuration via RS232:

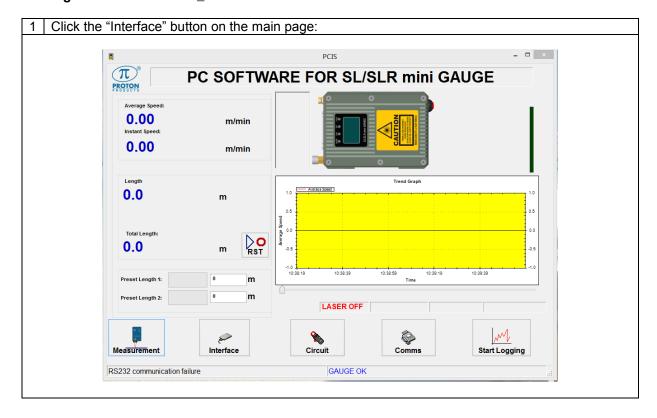
The following input parameters can be programmed via RS232 (and other optionally installed interfaces) on the SL / SLR gauge. For further information regarding the data format for programming parameters, please consult the SL / SLR gauge instruction manual.

| DW | Data bit | Comments | Value | | |
|--|-------------|------------------------|---|--|--|
| | 0 | | | | |
| | 1 | Logic input 1 function | 1= Length hold | | |
| | 2 | | | | |
| | 3 | Logic input 1 polarity | 0 = active low (pulled down) | | |
| | 4 | | 1 = Length hold | | |
| 12 | 5 | Logic input 2 function | | | |
| 12 | 6 | | | | |
| | 7 | Logic input 2 polarity | 0 = active low (pulled down) | | |
| | 8 | | 4= Reset length [if signal held for 5s, resets reel number] | | |
| | 9 | Logic input 3 function | | | |
| | 10 | | | | |
| 11 Logic input 3 polarity 0 = active low (pull-down) | | | 0 = active low (pull-down) | | |

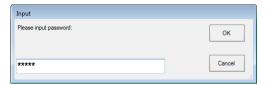
| DW | Comments | Unit | Range | Value |
|----|---------------|-----------------------|-------------------------------|---------------------|
| 14 | Length offset | 1=0.1m{ft}{yds}{inch} | 3000.0~3000.0m{ft}{yds}{inch} | Set to distance "L" |

SL mini / SLR mini configuration

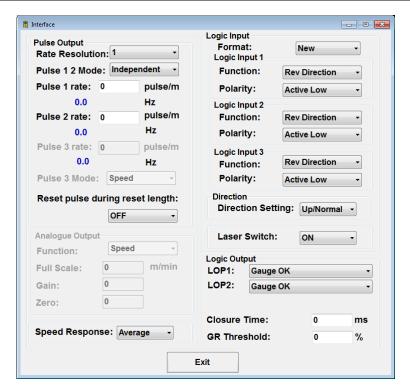
Configuration via the PCiS_SLmini software:



2 When prompted, enter 64000 for the password and click the "OK" button:

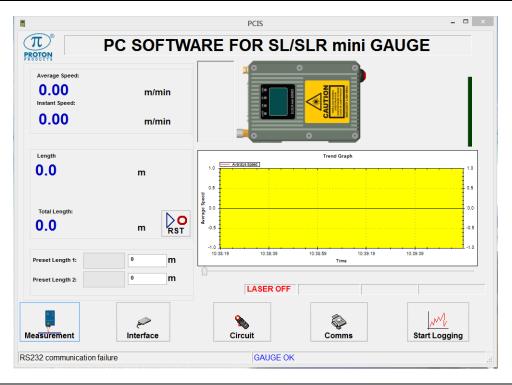


3 Configure the logic input interfaces as follows and then click the "Exit" button:



| Label | Value | Description | Input DW |
|---------------|-------------|-------------|-------------|
| Format | New | | 12.15 |
| Logic Input 1 | | | |
| Function | Length Hold | | 12 |
| Polarity | Active Low | | 12 |
| Logic Input 2 | | | |
| Function | Length Hold | | 12 |
| Polarity | Active Low | | 12 |
| Logic Input 3 | | | |
| Function | Reset | | 12 |
| Polarity | Active Low | | 12 |

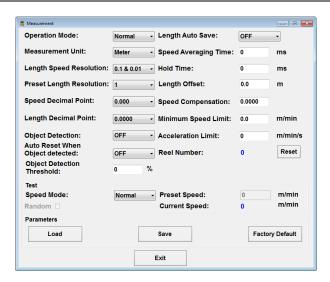
4 Click the "Measurement" button on the main page:



5 When prompted, enter 63000 for the password and click the "OK" button:



6 Configure the "Length Offset" to the distance between the light barriers and then click the "Exit" button:



| Label | Value* | Description | Input DW |
|---------------|---|---------------------------------------|-------------|
| Length Offset | -3000.0 ~ 3000.0 m{ft}{yds}{inch} | Set the required length offset value. | 14 |

Configuration by input parameters:

This interface may be configured by writing to the following input parameters:

Input parameters

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----------|--|-----------|----------------------------|---------|
| | | Logic input(new format;DW | /12.15=1) | | |
| | 0 | | | | |
| | 1 | Logic input 1 function | | 1=Length hold | 0 |
| | 2 | | | | |
| | 3 | Logic input 1 polarity | | 0=Active low | 0 |
| | 4 | | | | |
| | 5 | Logic input 2 function | | 1=Length hold | 1 |
| | 6 | | | | |
| | 7 | Logic input 2 polarity | | 0=Active low | 0 |
| 12 | 8 | | | | |
| | 9 | Logic input 3 function | | 4=Reset | 4 |
| | 10 | | | | |
| | 11 | Logic input 3 polarity | | 0=Active low | 0 |
| | 12 | Direction setting (available only when no logic input for direction) | | 0=Count up 1=Count down | 0 |
| | 13~ 14 | Not used | | | |
| | 15 | Must be 1 | · | 1=New format logic inputs | |

| DW | Bit | Comment | Unit | Range/Remark | Default |
|----|-----|---------------|-----------------------|--------------------------------|---------|
| 14 | | Length offset | 1=0.1m{ft}{yds}{inch} | -3000.0~3000.0m{ft}{yds}{inch} | 0 |

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

The users manual or instruction manual for an intentional or unintentional radiator shall caution the user that changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment. In cases where the manual is provided only in a form other than paper, such as on a computer disk or over the Internet, the information required by this section may be included in the manual in that alternative form, provided the user can reasonably be expected to have the capability to access information in that form.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

Radiation Exposure Statement

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with minimum distance 20cm between the radiator & your body.

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