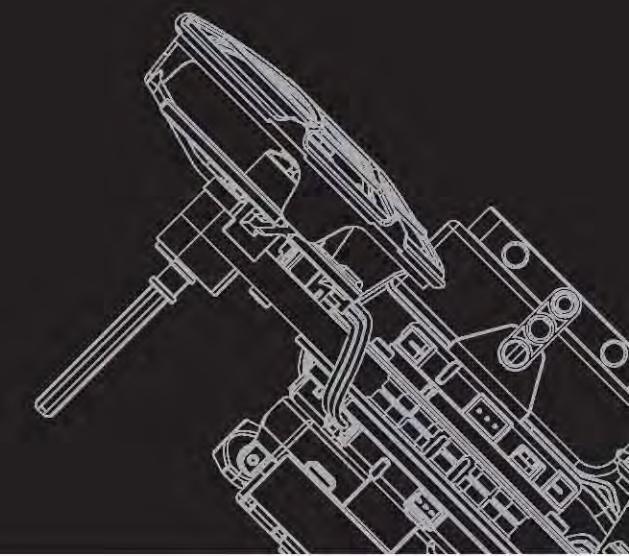


Makerfire

# GHOST II



Product Introduction



Makerfire Technology Co., Ltd.

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## Product Introduction

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# 1 product description



# STEAM Education



STEAM education is the new style teaching way which mixed with Science, Technology, Engineering, Art and Maths. It emphasizes on motivating students' imagination and creativity, also improving the ability of thinking, solving the problem and cooperation.

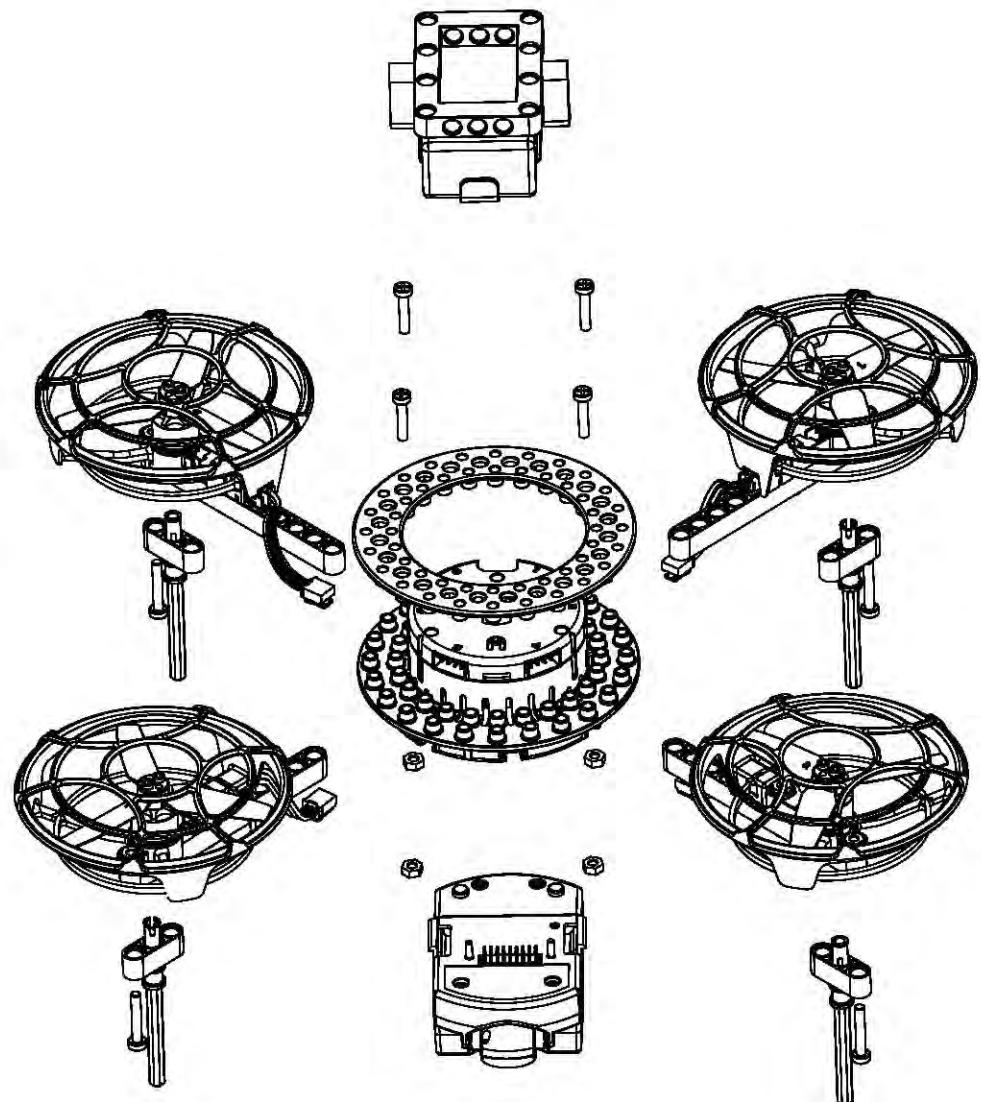
STEAM education is the quality-oriented education indeed, which was originated from United States and now spreads all over the world.

# Aerial drone- Ghost

Ghost is a STEAM Educational aerial drone kit, customized for 8-16 years old students and can enhance their creative thinking.

Ghost is compatible with LEGO machinery parts, and it is including the powerful brushless system and built-in ultrasound and Optical flow sensor.

Students can learn the drone structure, assemble Schematic, and get a deeper understanding about the aerial drone by the online/offline graphical programming.



# Flight Controller

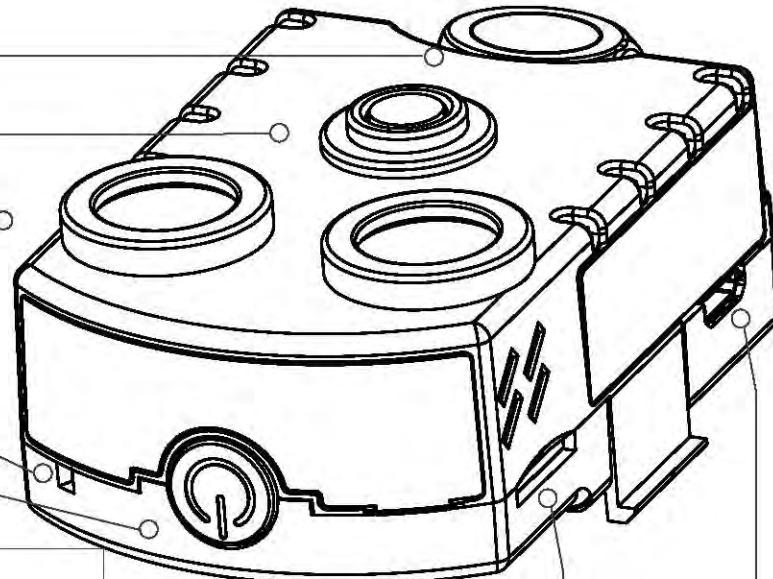
Camera

Optical Flow Sensor Module

Ultrasonic Module

Indicator Light

Power Switch



**Green Light solid:** Take off waiting (Attitude hold and fixed point function)

**Green Light flash slow:** One-key landing(Fixed point movement)

**Blue light flash:** Photography mode (It can be take photo anytime)

**Blue light flash fast:** SD card failure

**Blue light flash slow:** Record mode(video recording)

**Red light flash slow:** Fail to connect (fail to connected with remote control or APP, fail to binding, no signal)

**Red light flash fast:** Low voltage protection landing automatically/Low voltage

**Red light solid:** System crash/System major failure

**Red light and green light flash alternately:** Sensor abnormality (Calibration fail, Optical flow/Ultrasonic/ Barometer abnormal, etc.)

**Blue light and green light flash alternately:** Gyroscope on the calibration

**Red light and blue light flash alternately:** Special flight mode( switch to sport mode, 360°flip, spin, etc.)

**Failsafe:** When the remote control losts the signal or exits abnormally from the APP, Ghost will land automatically to the ground.

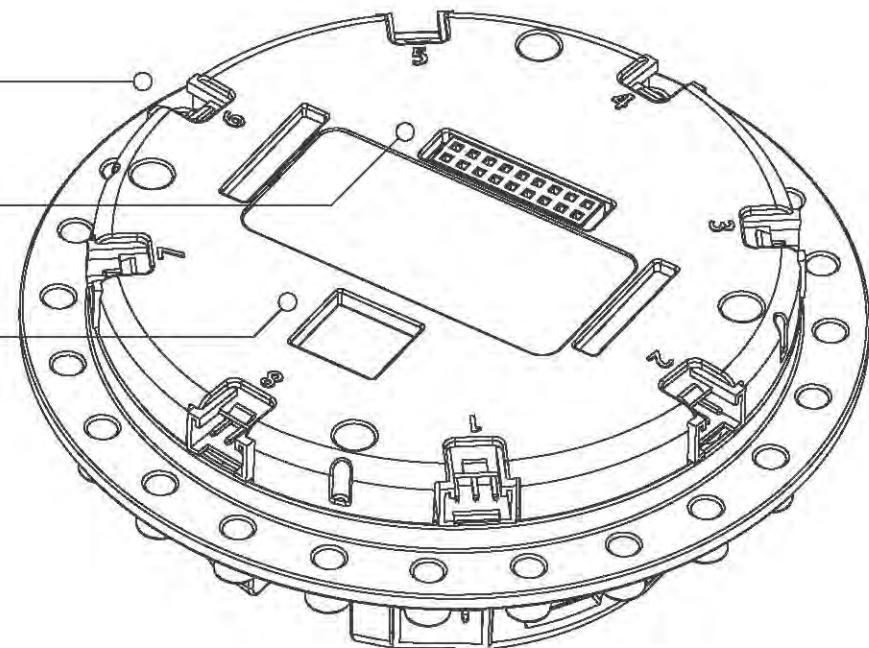
**Low voltage protection:** When the battery voltage is lower than 10.5V, Ghost will activate the low voltage protection system, land automatically, and buzzer keeps buzzing.

# Smart Driver

PWM driver interface (Brushless motor driver interface)

Communication interface

Heater

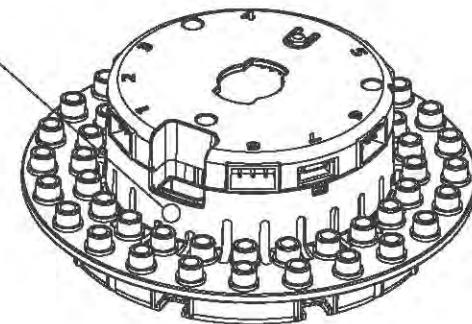


Smart driver can drive brushless motor and connect the hardware through the adapter cable and brushless power system;

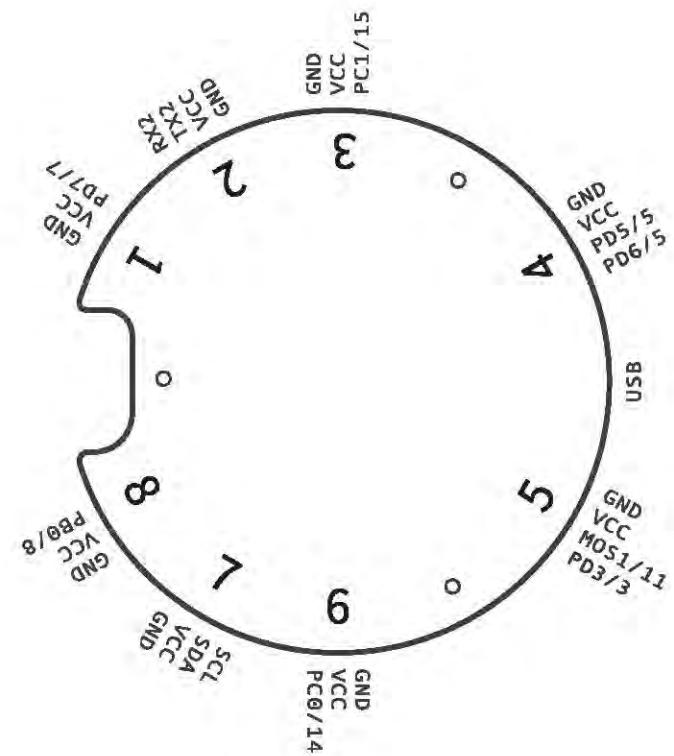
The 1-way maximal current is 12A and the maximal brushless motor drive is 8-way, the PWM driver interface can activate interface based on the customized mapping of Ghost in the Scratch.

# Application Docking Station

Power interface



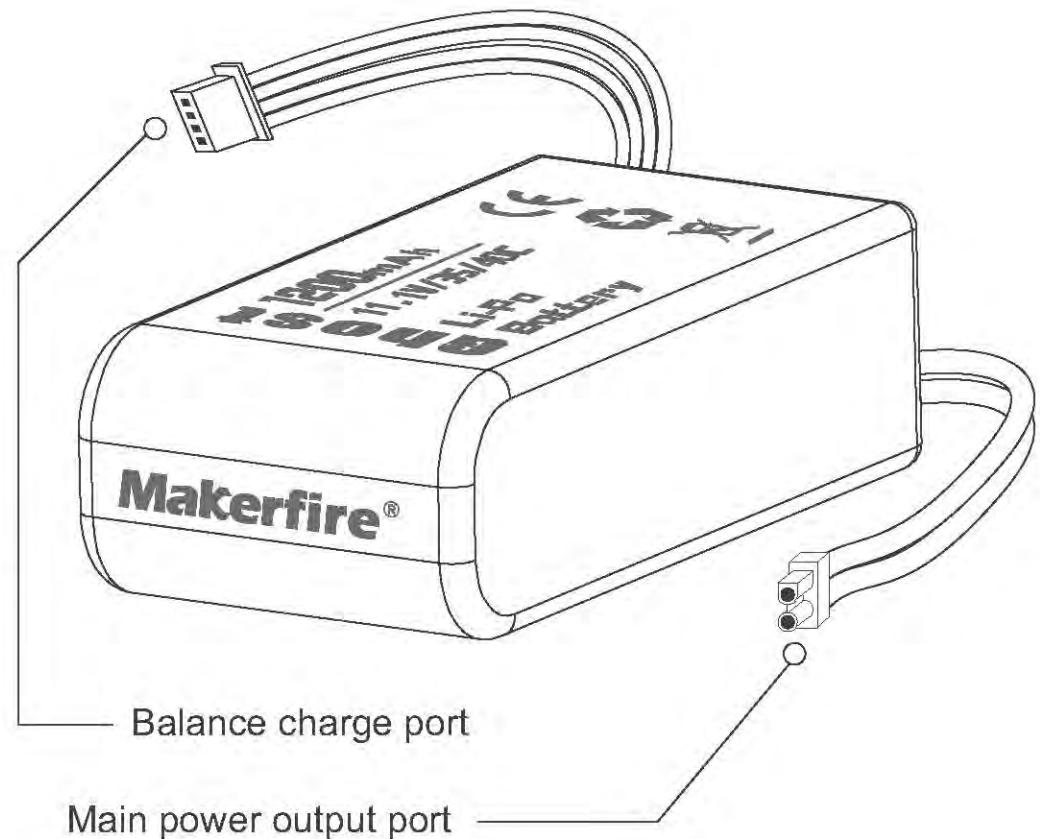
Expanding Interface Number	Type of the interface
No. 1 and No. 8	Digital IO port
No. 2	UART 2
No. 3 and No. 6	Analog IO port
No. 4 and No. 5	PWM output port
No. 7	IIC



# LiPo Battery Management

## Caution:

1. Do NOT insert the anode and Cathode of the battery directly into the battery socket.
2. Do NOT short the battery, it will cause serious damage to the battery.
3. Do NOT transport the battery with metal.
4. Do NOT throw, tread, strike and take the battery apart.
5. Do NOT solder the battery without any protection or use other sharp weapon to impale the battery.
6. Do NOT charge the battery without any monitor.

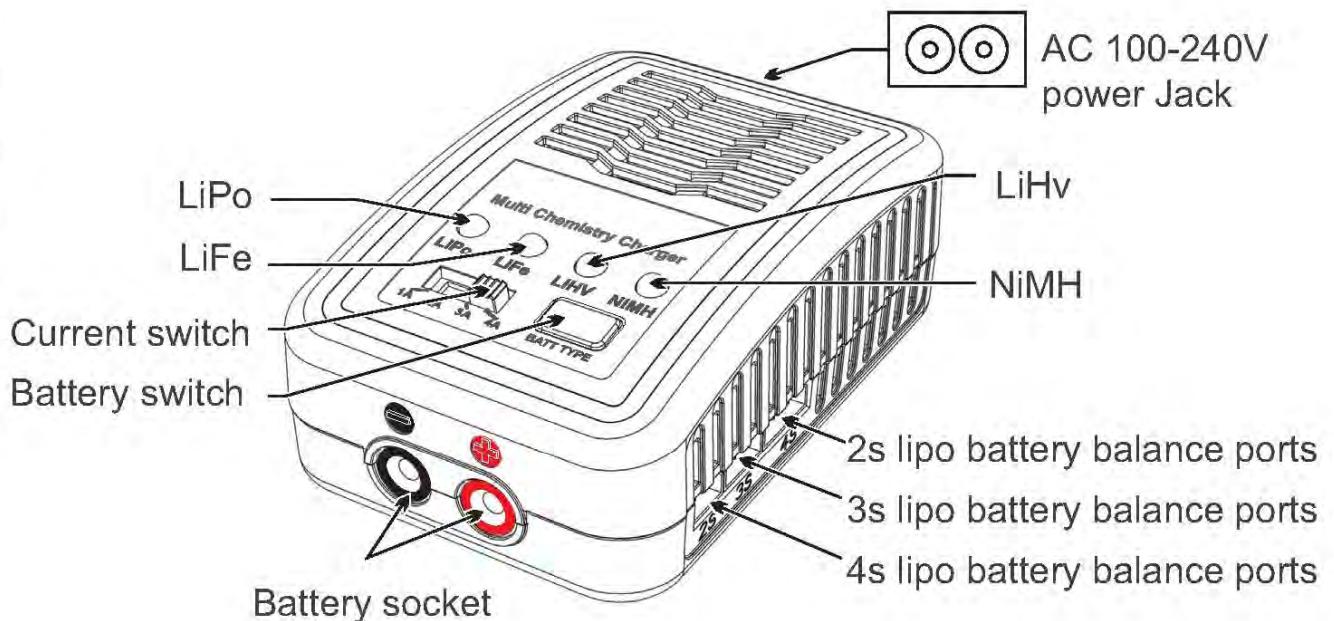


# Battery Charging Guide-The use of the charger

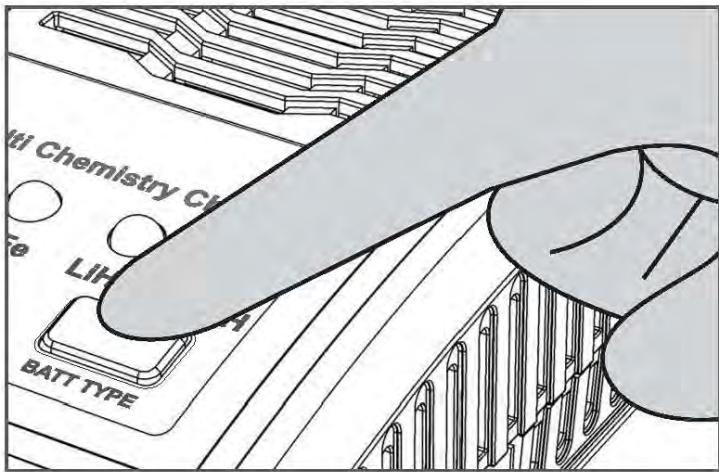
Battery configuration of Ghost: 3s LiPo Battery

## Indicator status description

Red light and green light flash alternately	Ready to charge (stand by)
Red light solid	Electricity<25%
Red light flash	Electricity 25%-50%
Yellow light flash	Electricity 50%-75%
Green light flash	Electricity 75%-99%
Green light solid	Fully charged

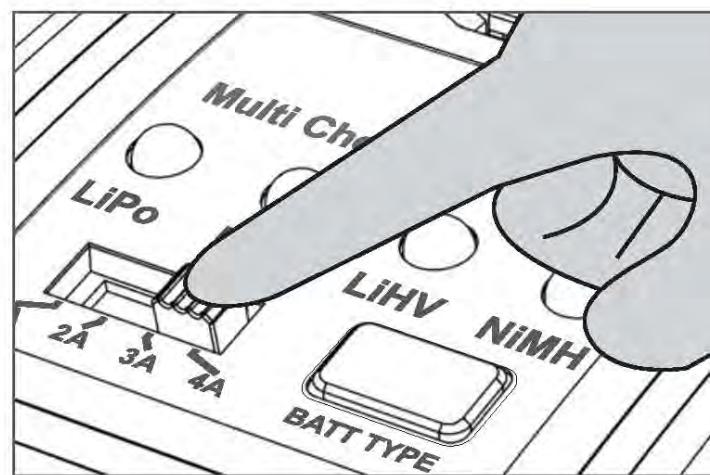


# Battery Charging Guide-The use of the charger



**Battery type switch**

Press the "BATT TYPE" to switch battery type cyclically. Set the LiPo mode when charging the Ghost battery.



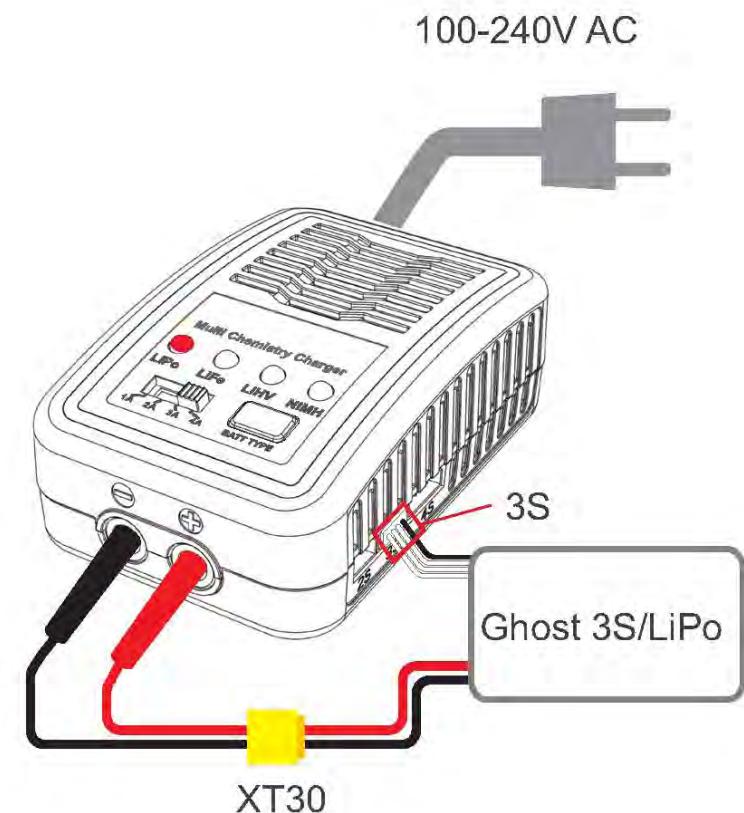
**Current switch**

Toggle the switch manually to switch 4-level charging current, the max current input is 4A.

# Battery Charging Guide-The use of the charger

Wire connection and charging settings:

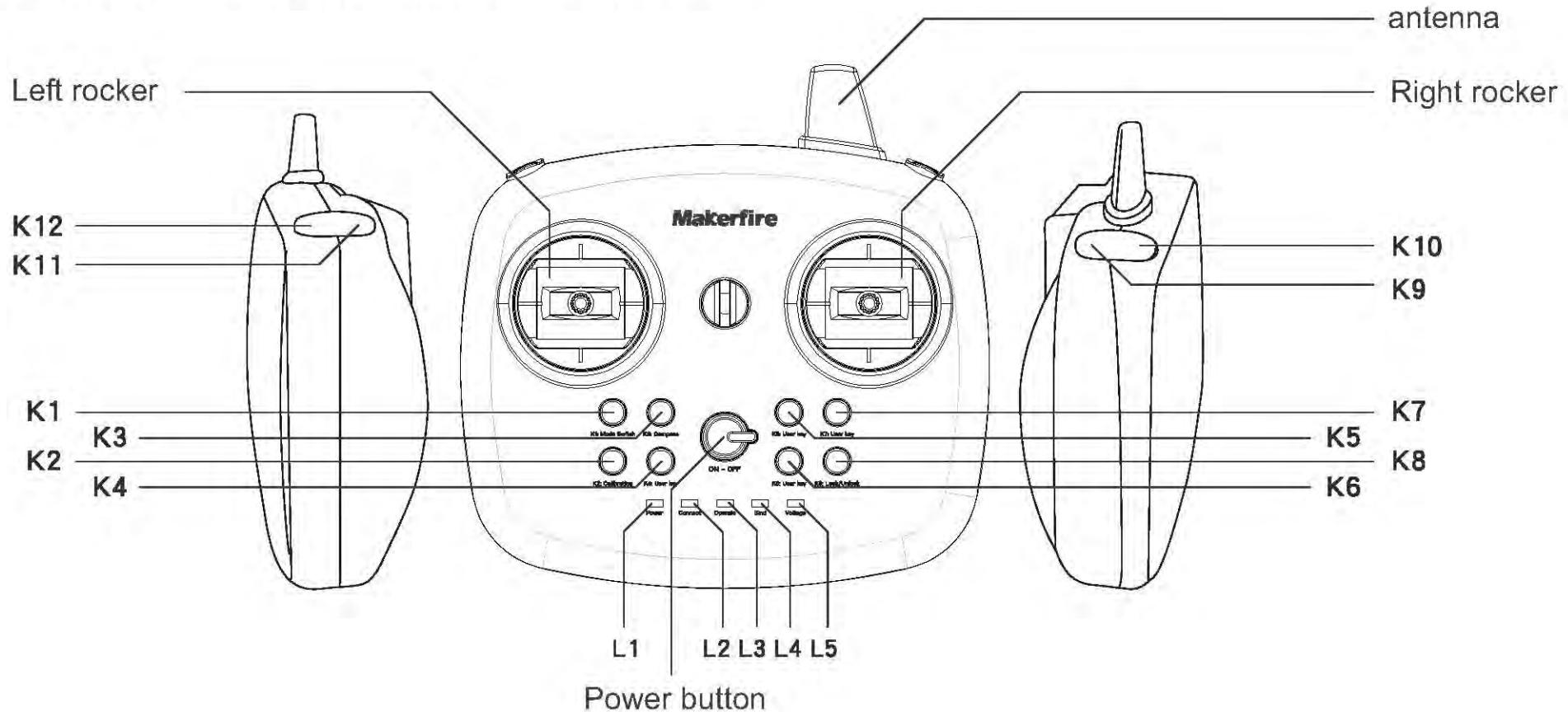
- 1) Insert the AC power cord into the charger and insert the plug as tight as possible to ensure a good connection
- 2) Set the charging type to LiPo mode
- 3) Set the charging current; Choose the current setting from 1-4A, we kindly recommend set it to 2A.
- 4) Insert the switch cable, the black one is anode, which corresponding to the black socket “-”; The red one is cathode, which orresponding to the red socket “+”; Please insert the plug as tight as possible to ensure a good connection.
- 5) Insert the white blance sprt into the “3s” port( it is in the middle), and 4 of the LED light should be all in flashing state.
- 6) Insert the dynamic electricity to the XT30 port and 4 of the LED will be change to “LiPo” lighting solid.



## Caution:

- 1) Switch cable will takes the risk of short circuit, please disconnect the XT30 port before you take the battery.
- 2) The battery charge mode that you set must be matched with the battery types
- 3) Please keep the battery charger in ventilation place, do Not cover it by any flammable object(towel, clothes etc.)
- 4) Do NOT charge the battery without look after.

# Operation Guide-Radio Transmitter



Power switch button: turn on/ turn off

K1: Online mode/offline mode switch

K4: Speed switch

K8: Lock/unlock

K2: Gyroscope calibration

K5: Spin 360°

K10: Photographic mode

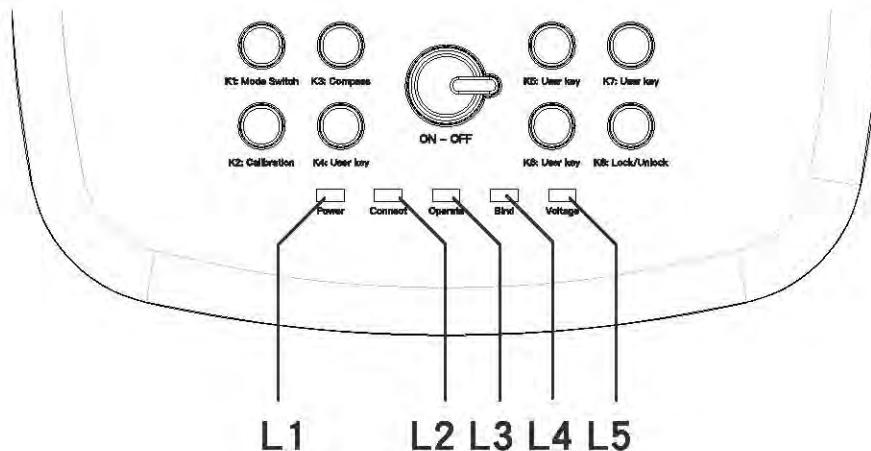
K3: Magnetometer calibration

K6: Bouncing mode

K12: Recording mode

Note: Radio transmitter distance is 100 meters, maximal flight height is 30 meters, please fly safely within the sight.

# Operation Guide-Radio Transmitter



## L1: Power Indicator

Light on: Power on  
Light off: Remote controller fail or battery overcharged

## L2: Connection status

Light off: Connect successfully  
Flash slow : Fail to connect

## L3: Operation mode

Light on: Online programming mode  
Light Off: Radio transmitter mode

## L4: Binding status

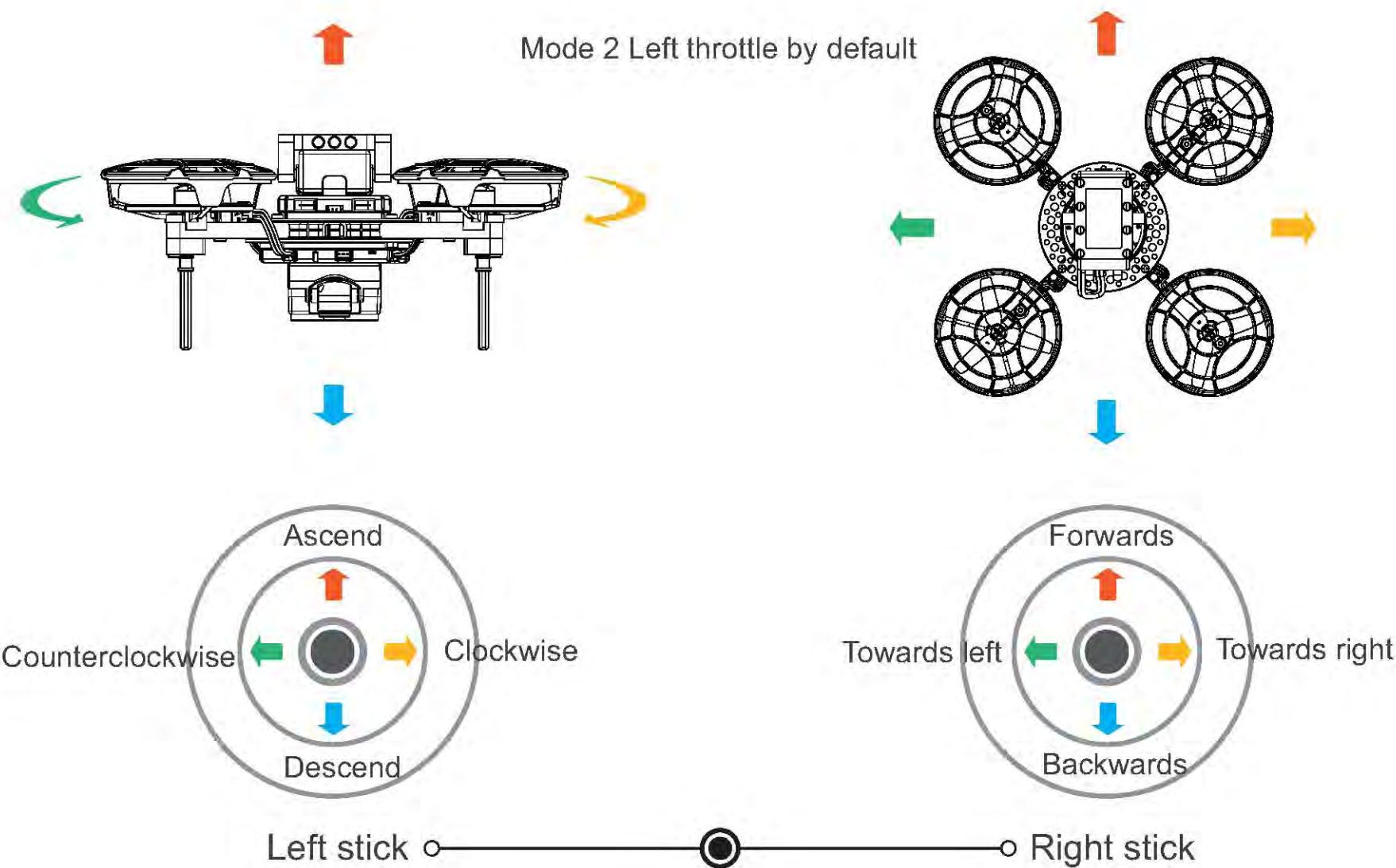
Flash fast : Binding status  
Light Off: Normal status

## L5: Voltage indicator

Flash fast: Low battery  
Flash slow: Low battery of the radio transmitter  
Light off: Fully charged

**Note:** L2 and L4 light flash fast shows the GHOST goes into binding process.

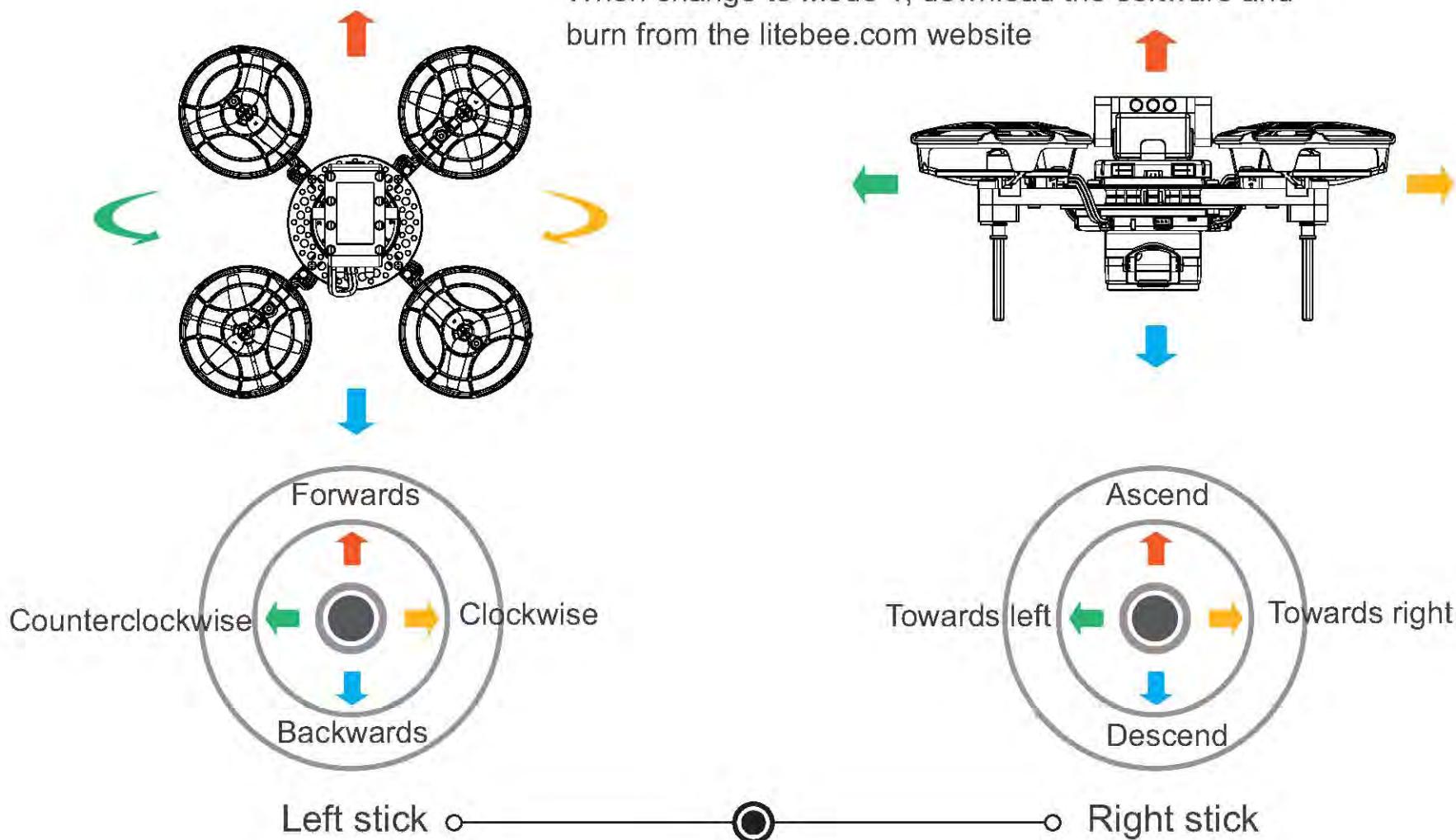
# Operation Guide-Radio transmitter



# Operation Guide-Radio transmitter

## Mode 1 Right throttle

When change to Mode 1, download the software and burn from the [litebee.com](http://litebee.com) website



# Operation guide-Fly with your phone

## Adriod

Search “LiteBee” on your App store to download the application

## IOS

Search “LiteBee” on your App store to download the application

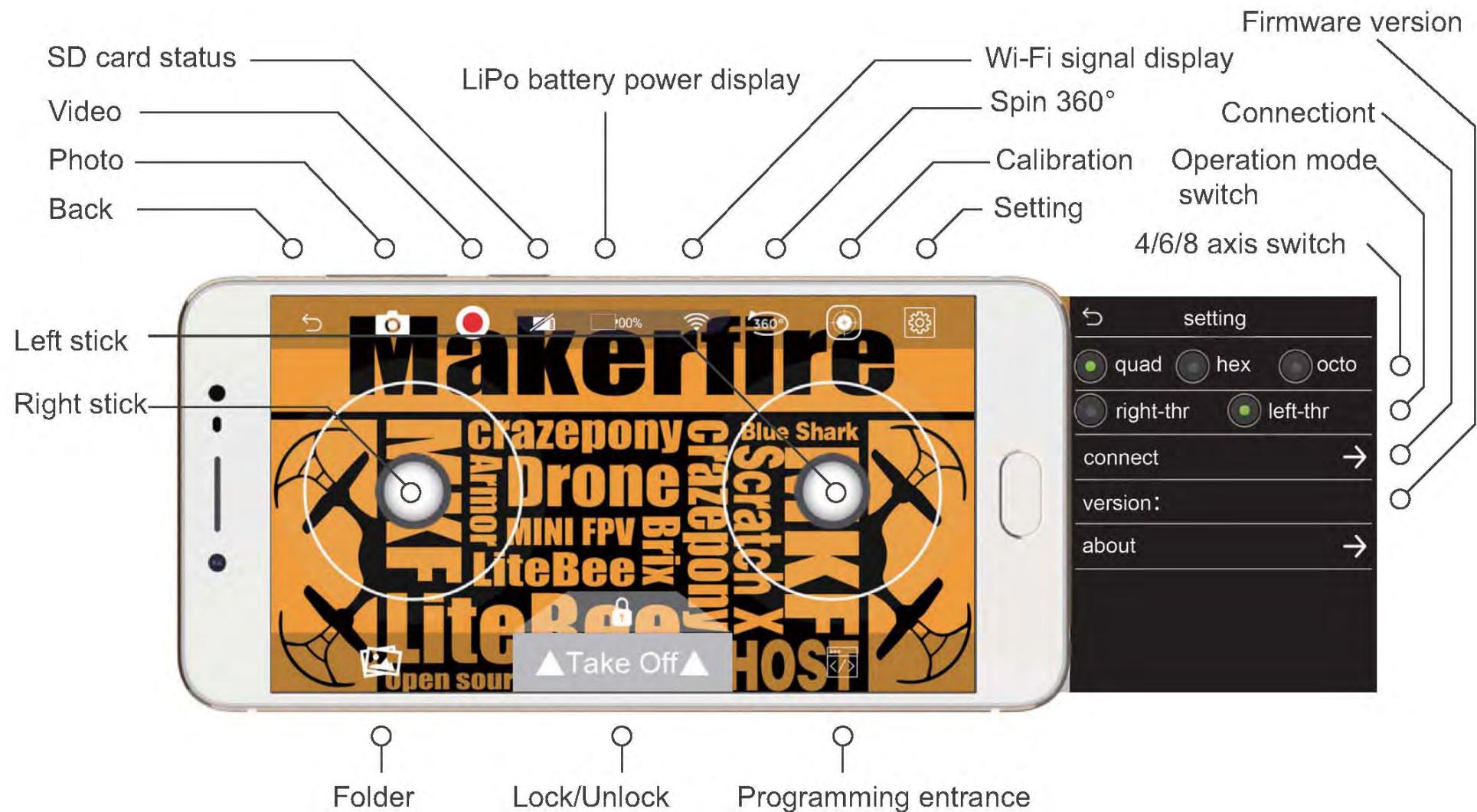
Open the application, click Ghost to get into the operation interface; based on Wi-Fi communication, palm device supports operation and image transmission; Connect Wi-Fi: “Ghost II\_XXXXXX”, password by default is “12345678”.



IOS App requires IOS 9.0 or advanced version

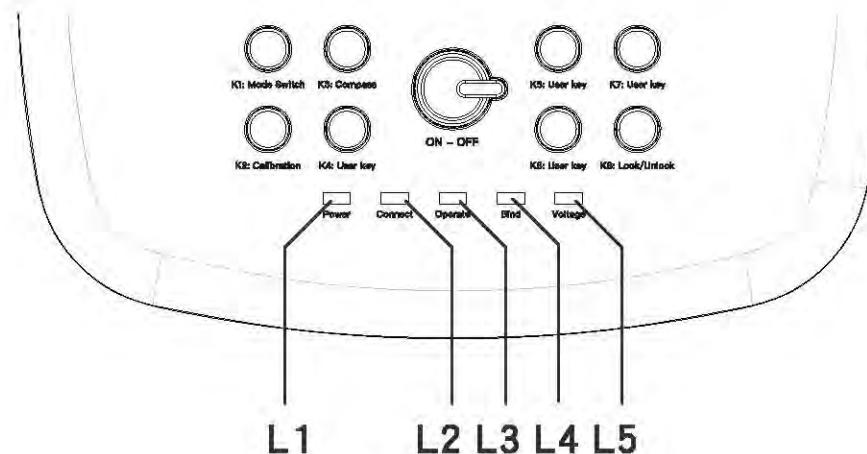
Android App requires Android 4.4 or advanced version

# Operation guide-Fly with your phone

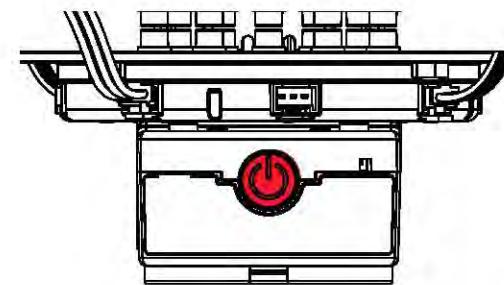


# Operation Guide-Binding

Note: Ghost needs to bind if first use

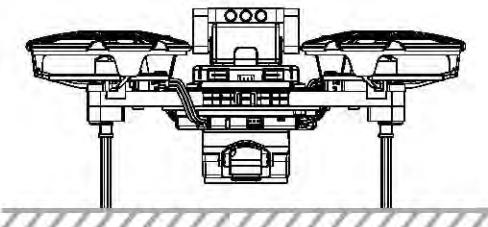


1. Turn on the radio transmitter(The Ghost is power off)
2. Push the right joystick to upper right 45° and press mode switch at the same time, then light L2 & L4 change to flash.



3. Turn on Ghost, then radio transmitter has "di" sound, the light L2 & L4 turn off and the light L1 flashes solid shows binding is successfully.

# Operation Guide-Lock&Unlock



1.Put Ghost in the horizontal position.



2. 1) Press the calibration button, Ghost will have a "di" sound and finish the calibration in 5 seconds.
- 2) Press the Unlock button, Ghost starts to take off.



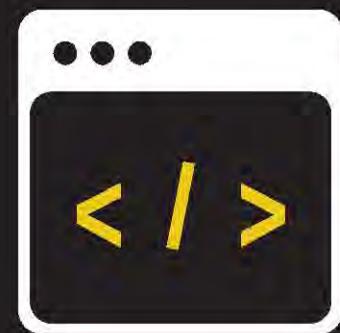
3. 1) Pull down the left joystick,when the Ghost lands to the ground, press the lock button.
- 2) Press one-key landing, Ghost will land vertically to the ground and lock automatically.

# Operation Guide-Precaution

- 1.Insure the correct installation before flying the Ghost.
- 2.Insure the battery is in fully charged, and the motor wires in correct connection.
- 3.Place the Ghost in the horizontal place.
- 4.Press the calibration button before flying, the buzzer has the“di” sound and blue and green light finish flash.
- 5.If replace the new battery when control with the phone, please restart the APP before flying again.

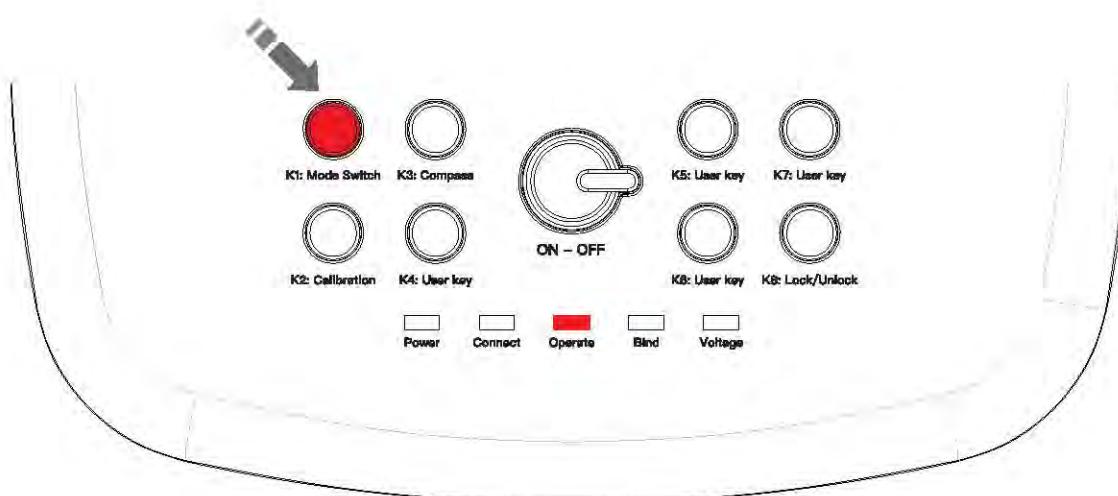


## Graphical programming



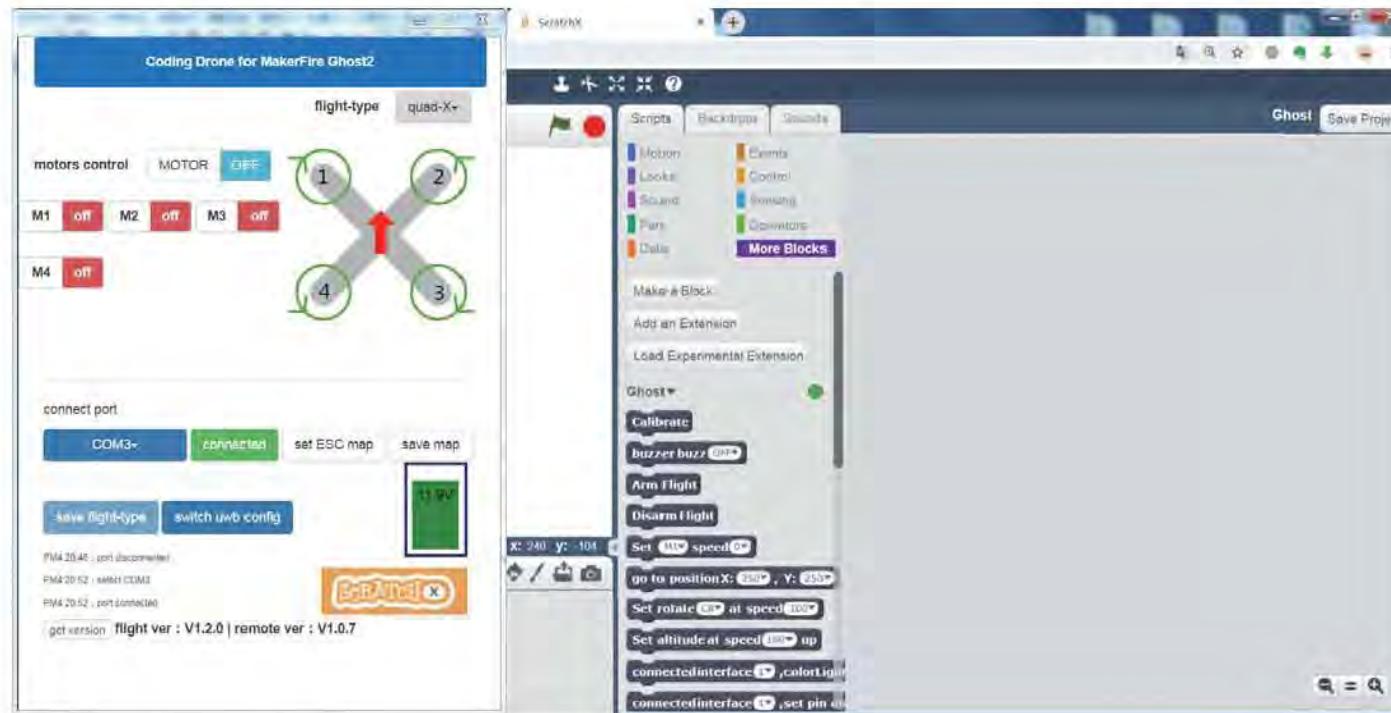
# Computer programming-connecting devices

- 1.Turn on Ghost and remote control, connect the remote control to the computer with a USB cable
- 2.Press the K1 button, Enter programming mode, Operate indicator stays lit.



# Computer programming-Software acquisition and installation

- 1.Go to <http://www.litebee.com>, download Ghost offline programming software (please download the software package that matches your computer's windows version)
- 2.Unpacking the package, install the driver, and install Google Chrome
- 3.Open the "Offline version - run Begin" folder, extract the file "Ghost\_bat", and double-click to open the file Begin, the following two pages appear



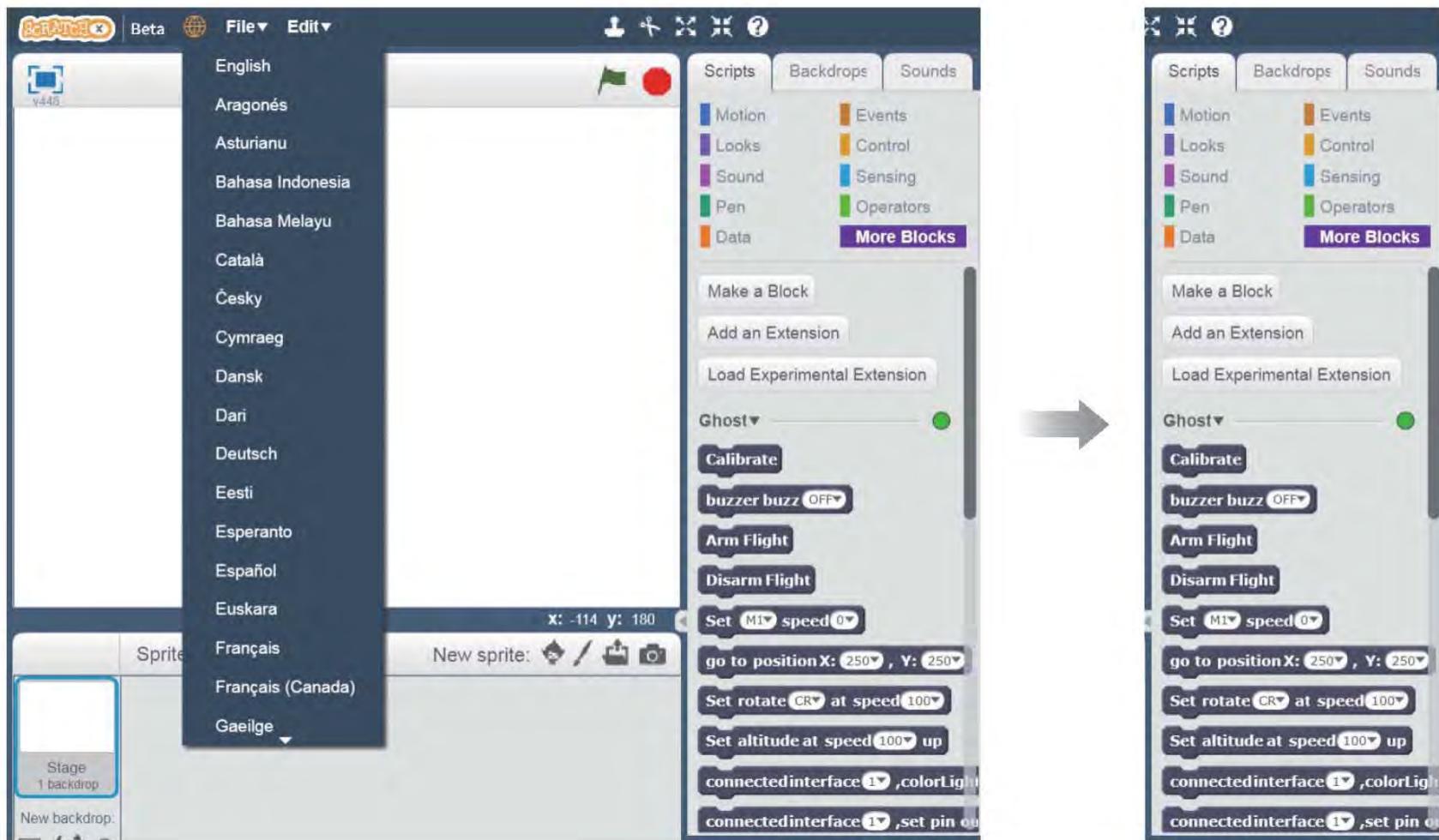
# Computer programming-Software acquisition and installation

4. On the connection page, choose the serial port COM3, click Connect
5. After connection succeed, please check if the installed flight programming can run. Click "Motor" in the control to display "Start"; then click "off" in "M1" to display "on". At this time, observe whether the blade rotates. If it rotated, the environment is set up successfully. Then click on "Scratch" in the lower right corner to enter the programming interface.

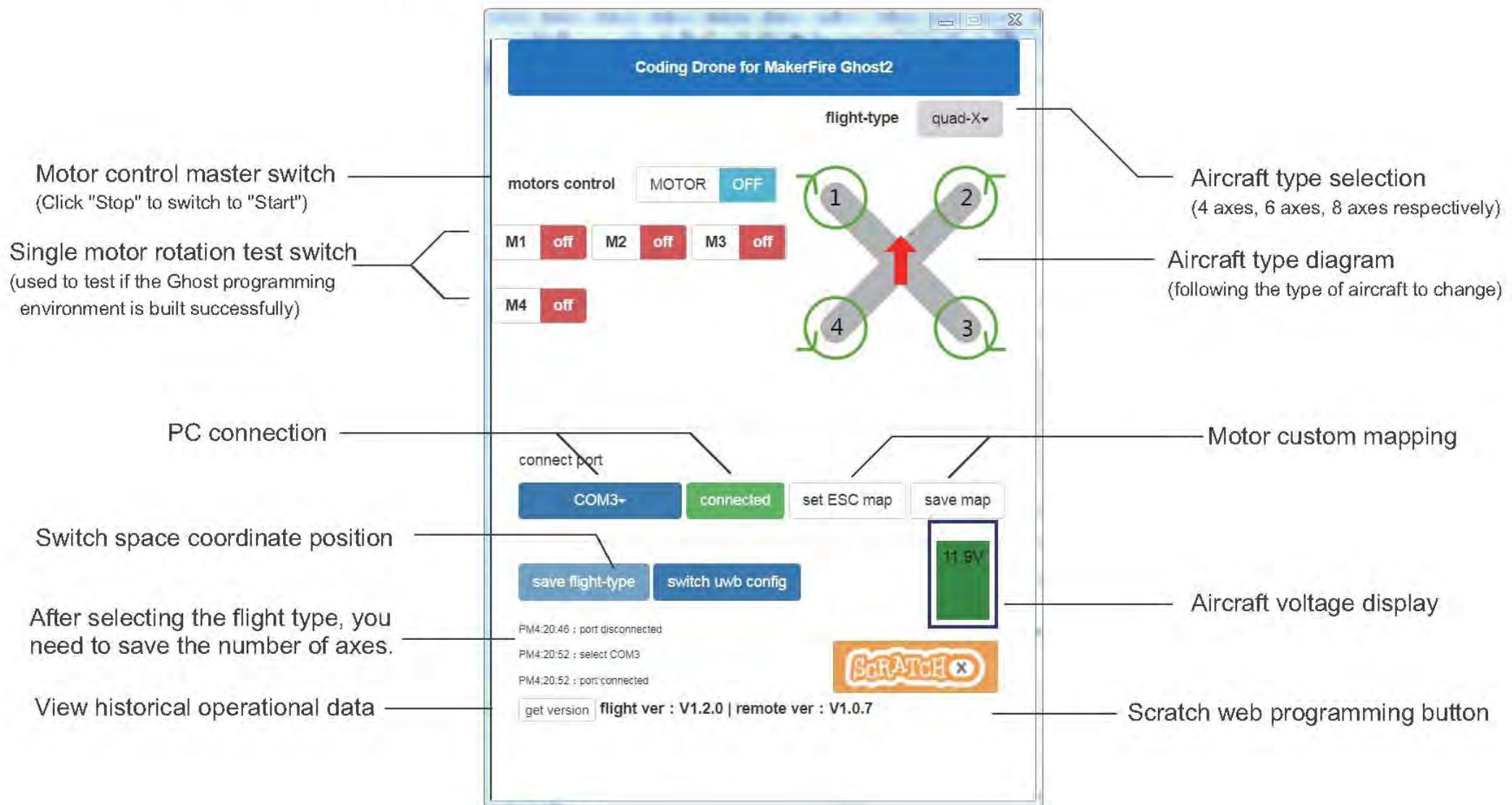


# Computer programming-Software acquisition and installation

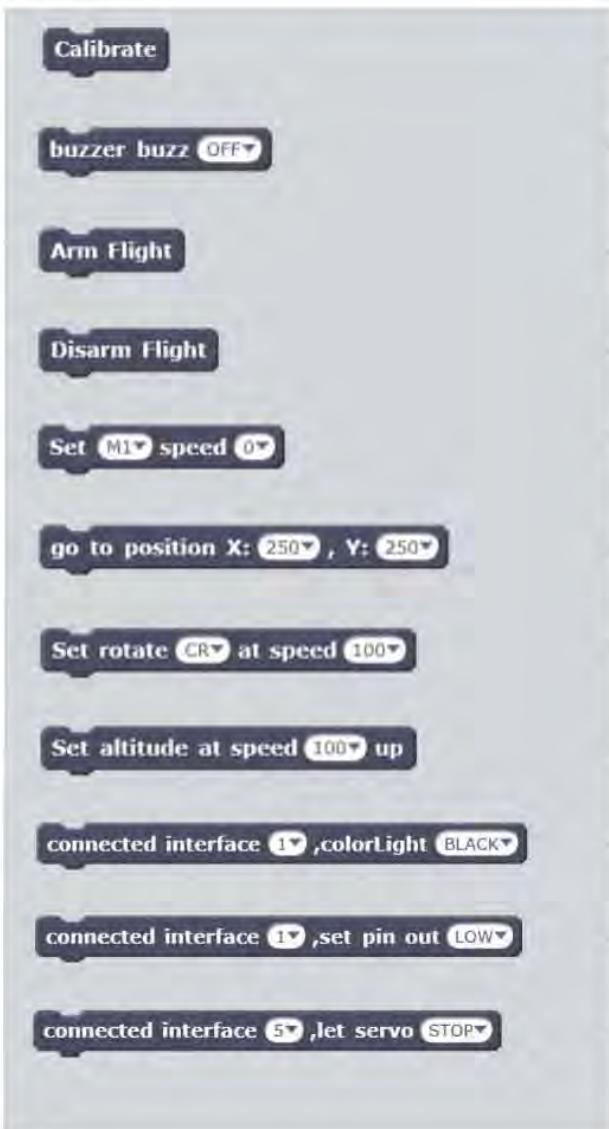
6. The initial programming language is English. You can query the fly instructions in “More blocks” to control Ghost.



# Computer programming-Software acquisition and installation



# Computer programming-Software acquisition and installation



- Calibrate the sensor of the aircraft
- Buzzer switch
- Take off
- Landing
- Set the motor speed
- Set the coordinates of the aircraft destination
- Set the aircraft to rotate clockwise/counterclockwise
- Set the aircraft to fly to the specified height
- Set the color of the expansion module
- Set the expansion interface signal output
- Set the servo connection interface



- Set start button
- Set the speed of flight in the specified direction
- End the specified direction flight command

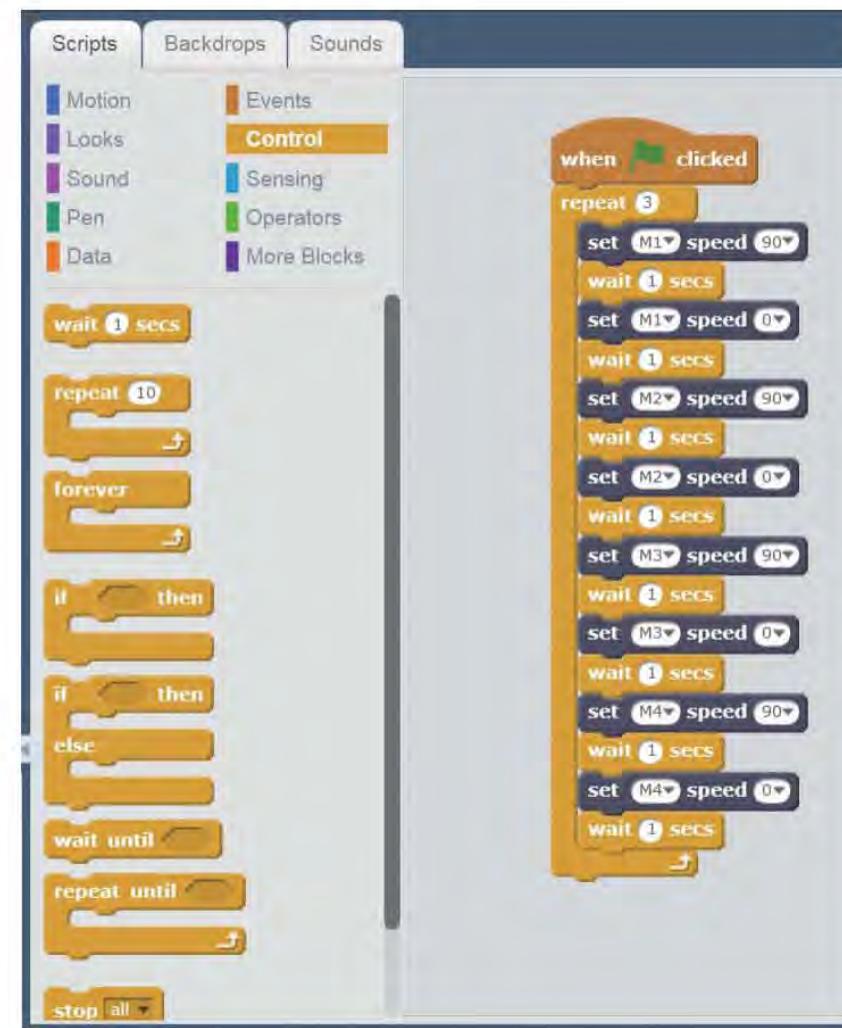
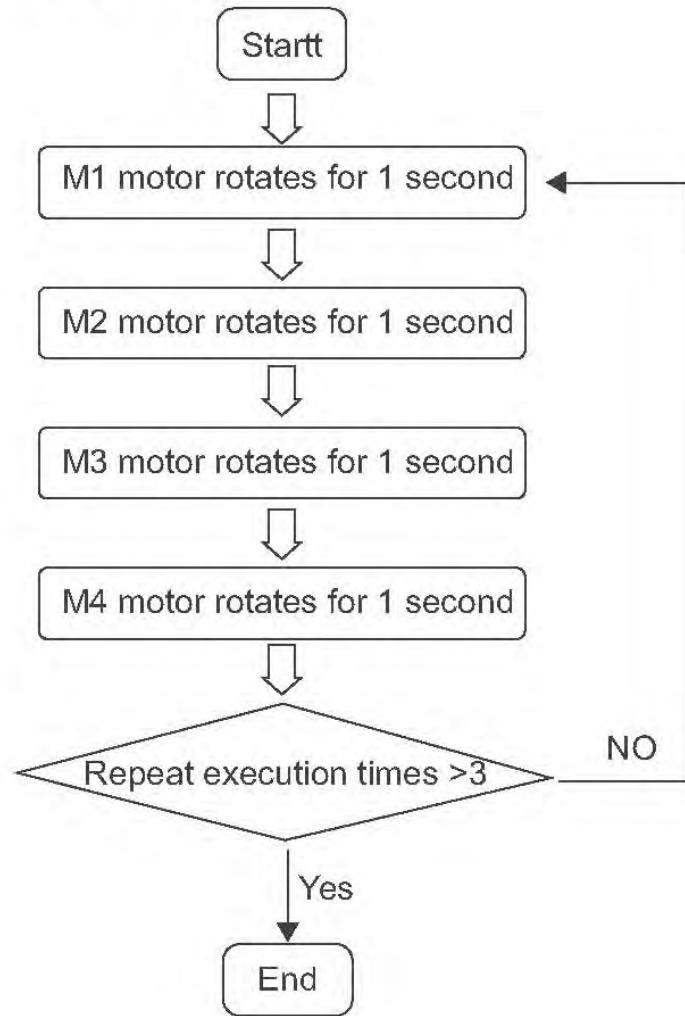


- Check the flight data after selection
- Spatial coordinate data
- Check the sensor data after selection

# Computer programming-Task-based routine one

Task: Scratch sets the motor. In the order of number 1-4, each motor rotates at an idle value of 90 for 1 second, end the task after 3 cycles.

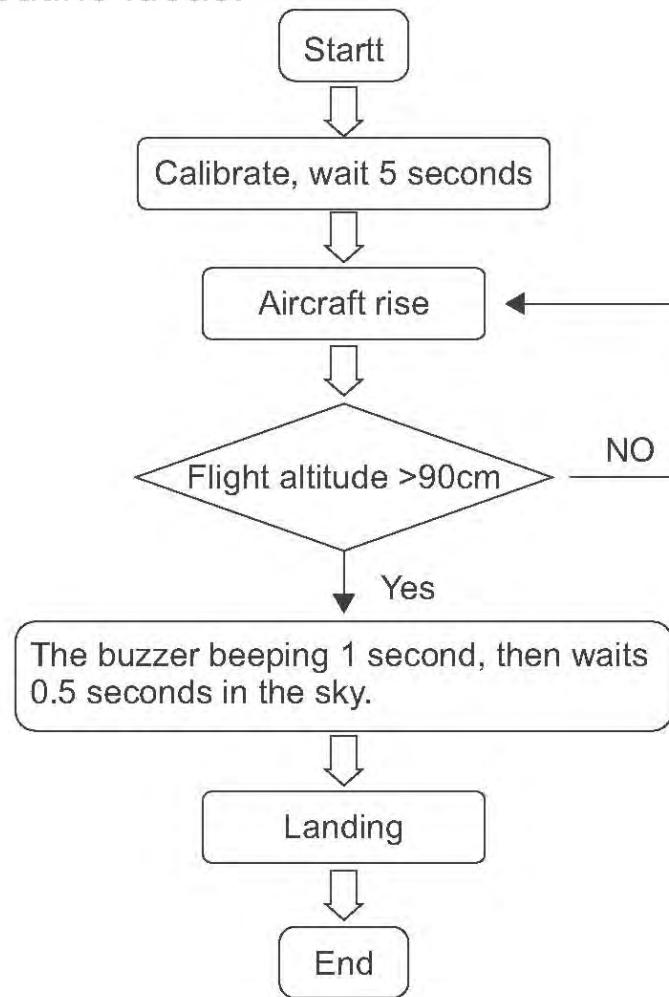
Routine idea:



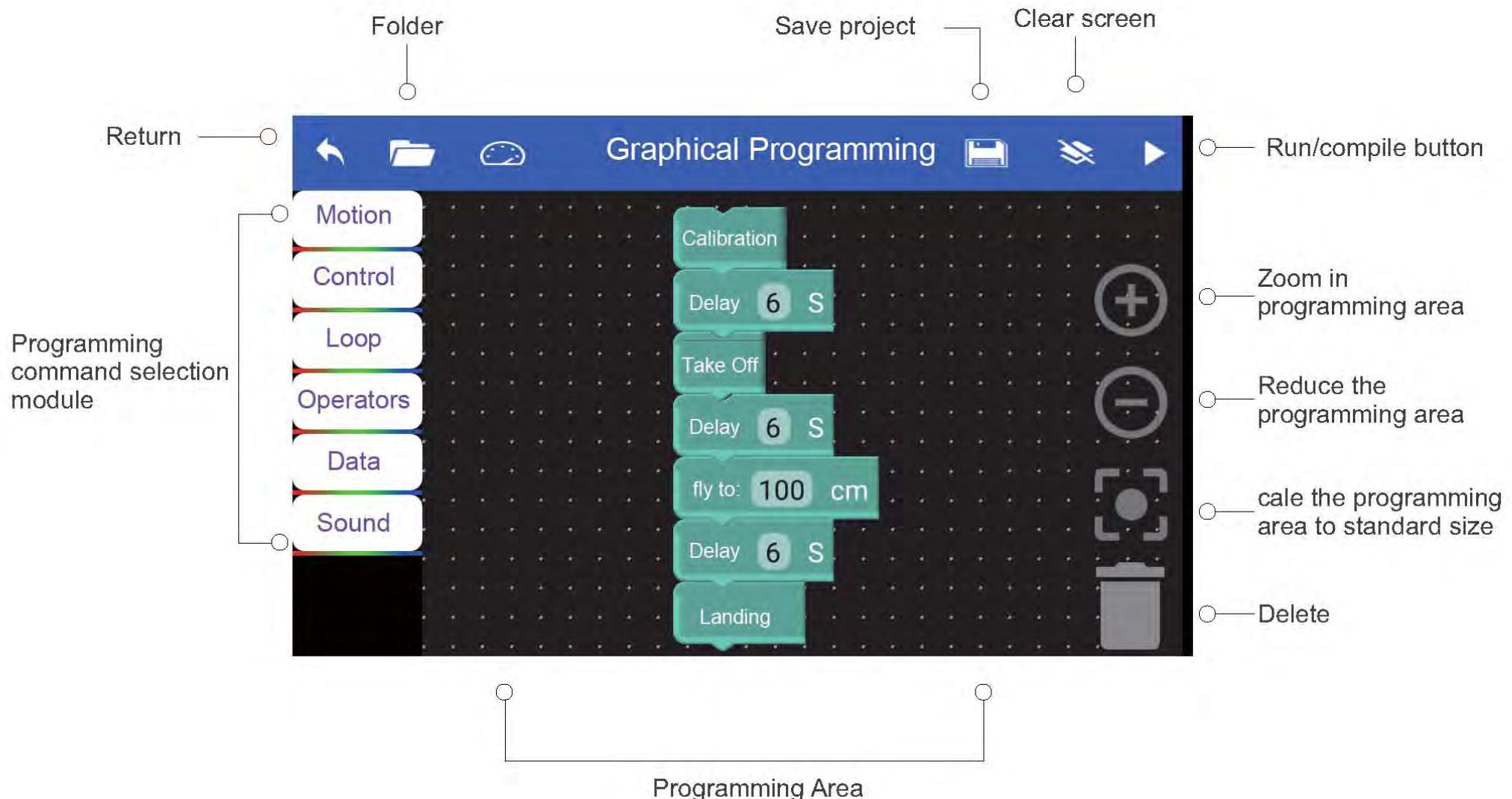
# Computer programming-Task-based routine two

Task: Scratch programming control Ghost, calibration, wait 5 seconds, take off, fly Ghost to 100cm height, set buzzer beep when the flight altitude is higher than 90cm, buzzer beeping 1 second, wait 0.5 seconds in the sky, turn off the buzzer and land.

Routine ideas:



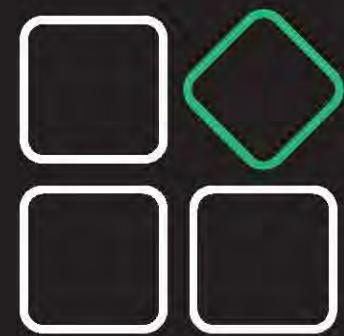
# Graphical programming-Android programming interface





# 3 Application development

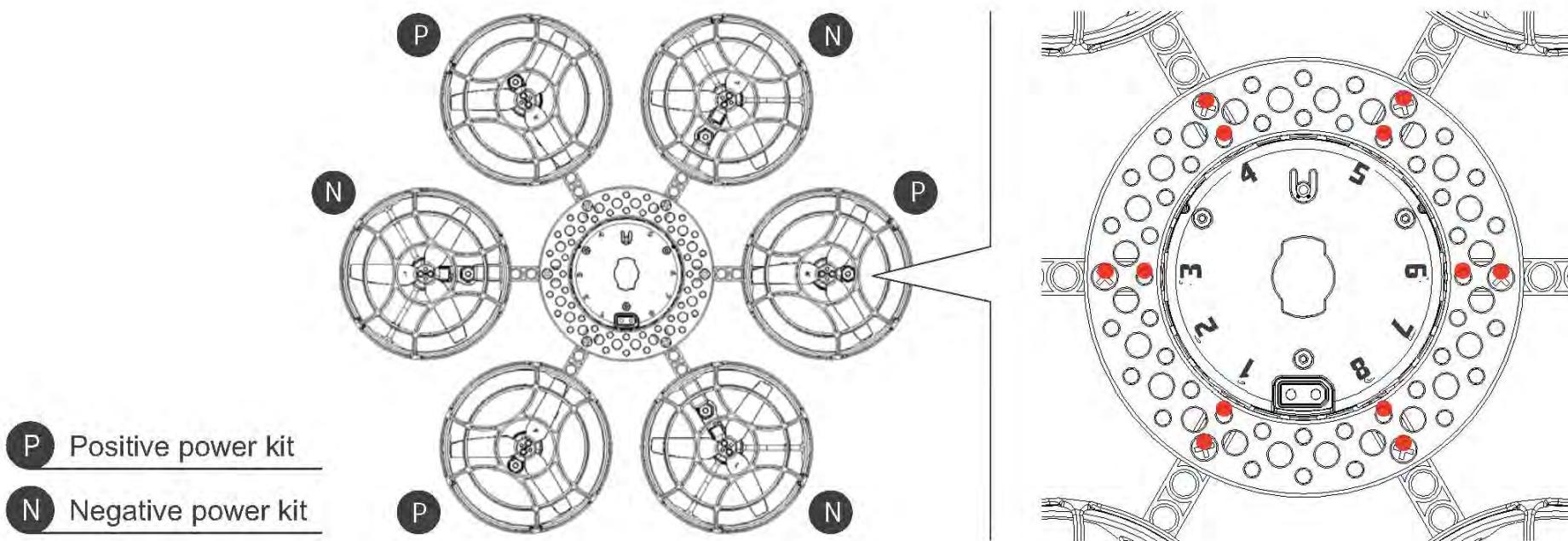
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# Six-axis / Eight-axis expansion-six-axis installation

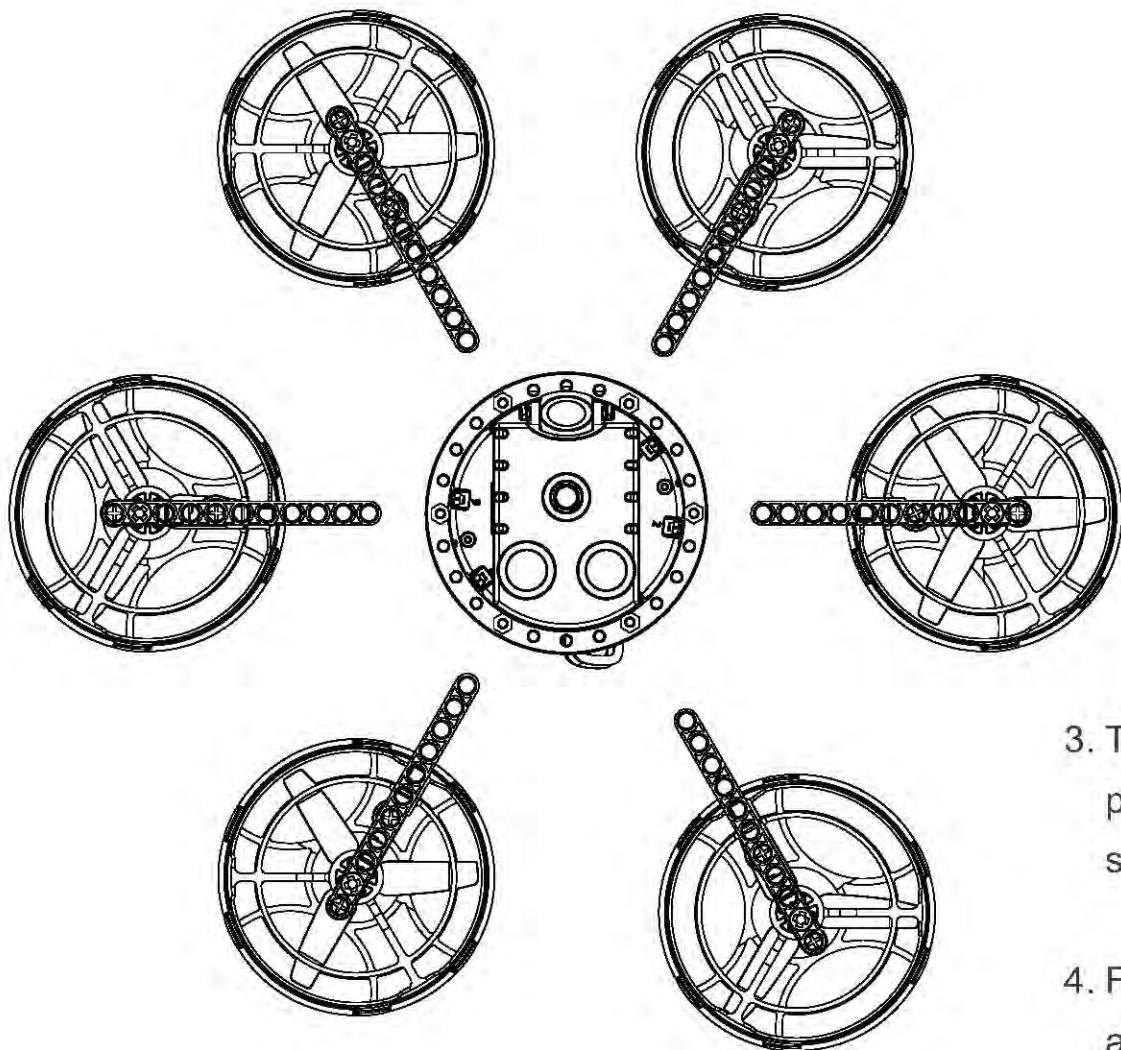
1. Before assembling the six-axis, in addition to the original accessories, additional preparation is required:

Positive power kit\*1 and negative power kit\*1, Clockwise power kit\*1, Counterclockwise power kit\*1, Power cable\*2, eleven-hole structural rod\*2, 1\*5 cross shaft\*2, Long pin with bushing\*2, Screw nuts\*6, Screws (M3\*15)\*2, Screws (M3\*20)\*4, three-hole structural rod\*2



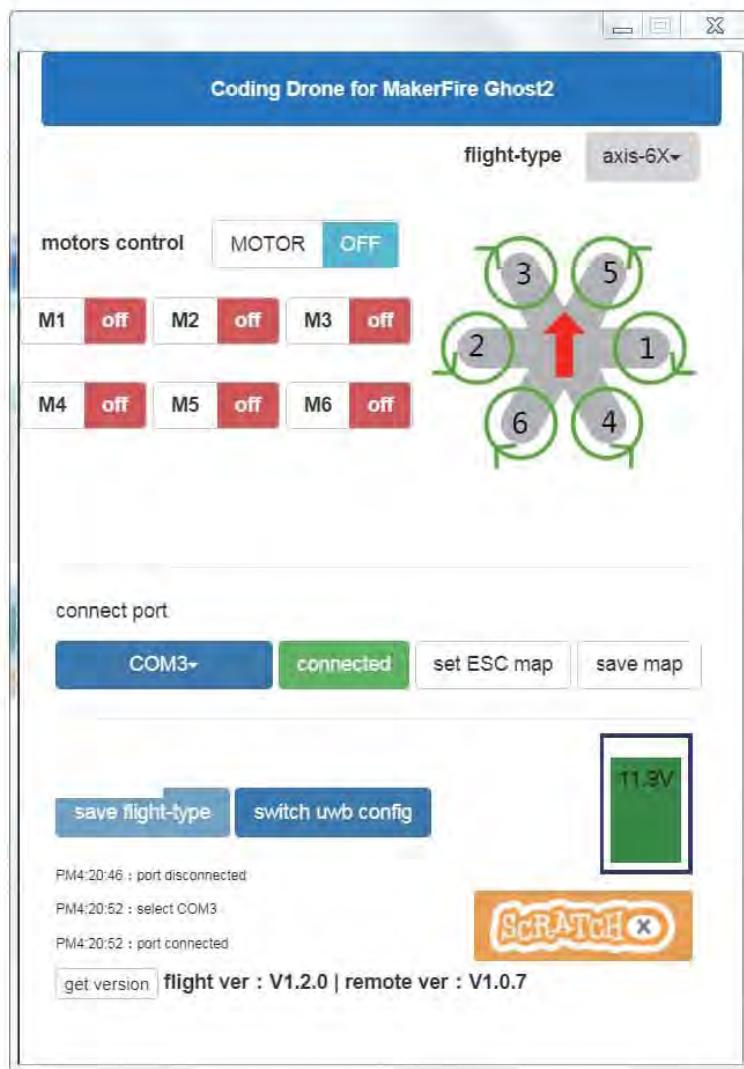
2. Install the power kit in the position shown above, according to the installation method of the assembly manual.

# Six-axis / Eight-axis expansion-six-axis installation



3. Turn the aircraft upside down, and connect the power cables to the corresponding sockets as shown in the figure above.
4. Finally, install other accessories as shown in the assembly manual.

# Six-axis / Eight-axis expansion-six-axis installation

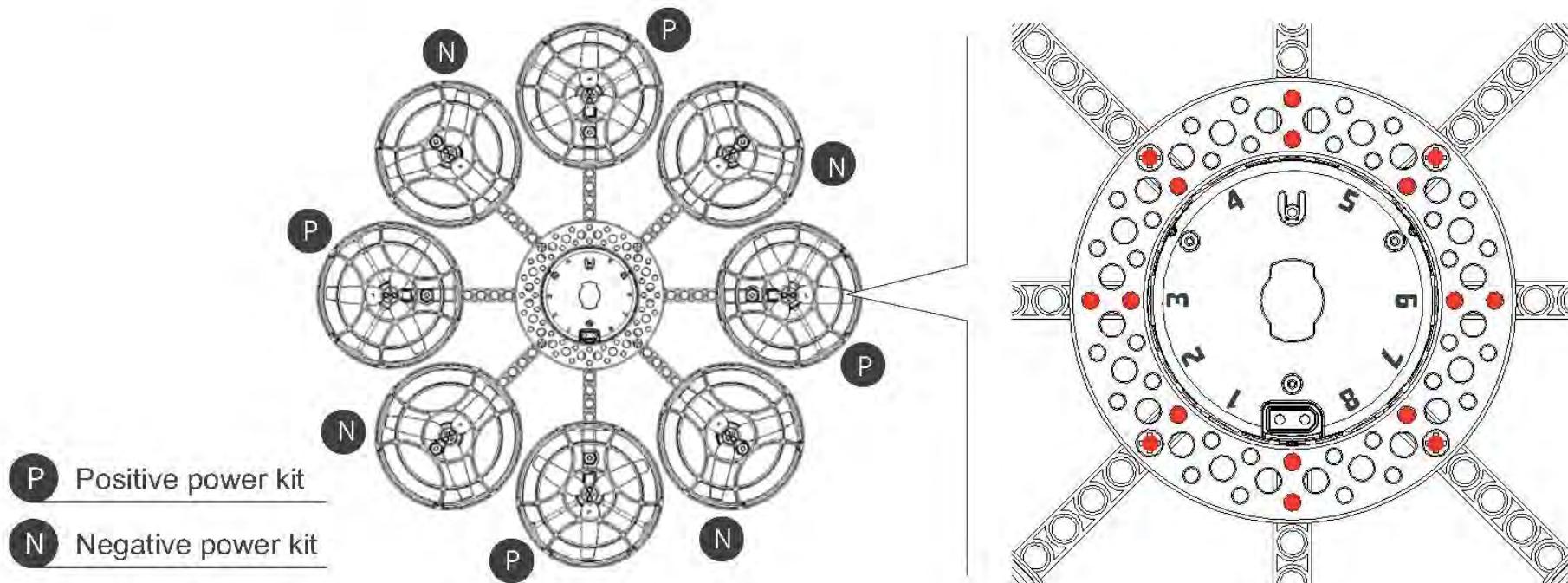


5. Open the Google App plugin - Ghost, open the remote control and connect to the computer  
(note: the remote control is in online mode)
6. Click "Select Serial Port". After connecting, the port will automatically detect the current axis type of the aircraft. Please set the aircraft type to "6-axis X" in the upper right corner. Finally, click "Axis save" button to save.
7. Rebinding the Ghost with remote control, then the aircraft can be operated to fly.

# Six-axis / Eight-axis expansion-eight-axis installation

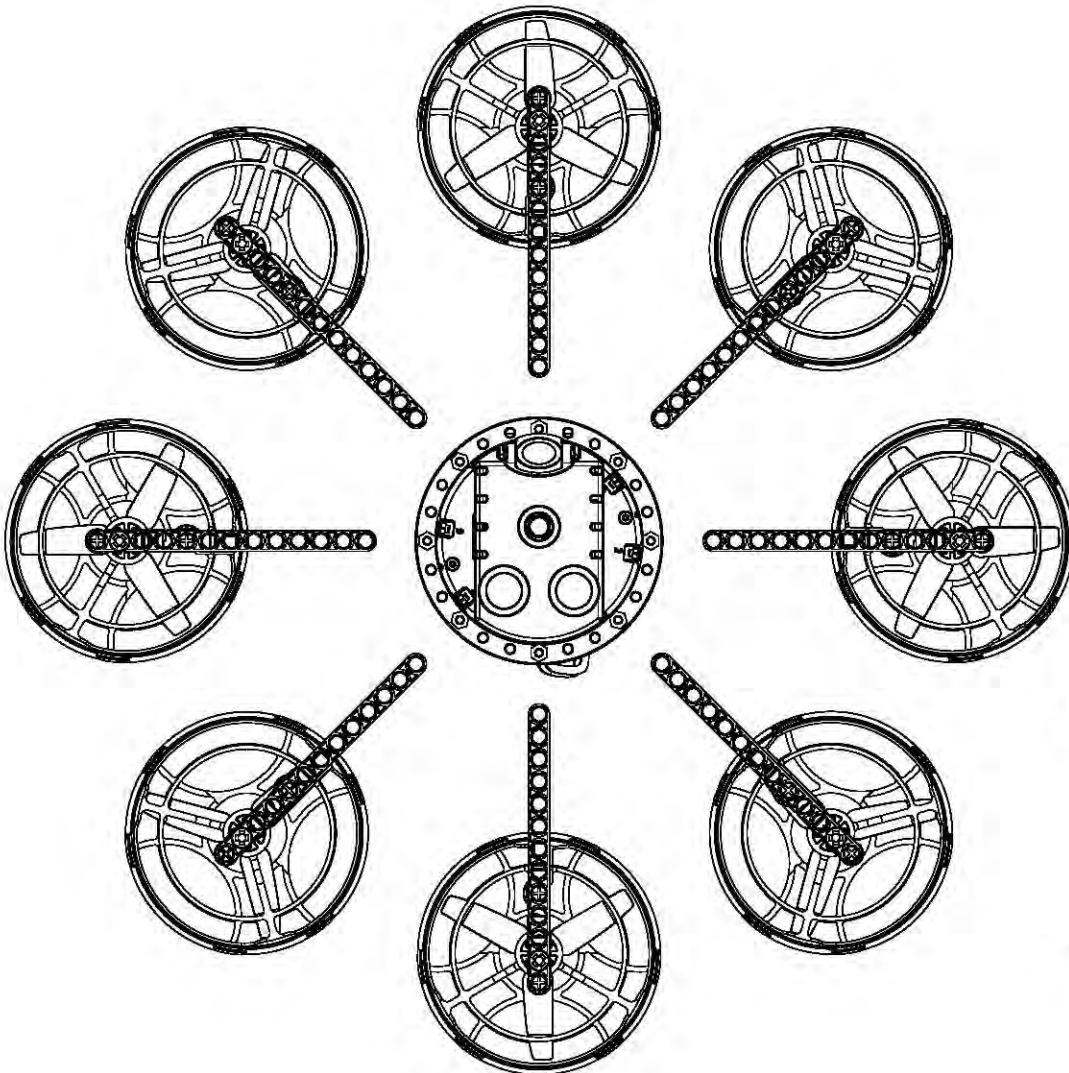
1. Before assembling the eight-axis, in addition to the original accessories, additional preparation is required:

Positive power kit\*2 and negative power kit\*2,Clockwise power kit\*2,Counterclockwise power kit\*2, Power cable\*4, Thirteen-hole structural rod\*8, 1\*5 cross shaft\*4, Long pin with bushing\*4, Screw nuts\*12, Screws (M3\*15)\*4, Screws (M3\*20)\*8, Three-hole structural rod\*4



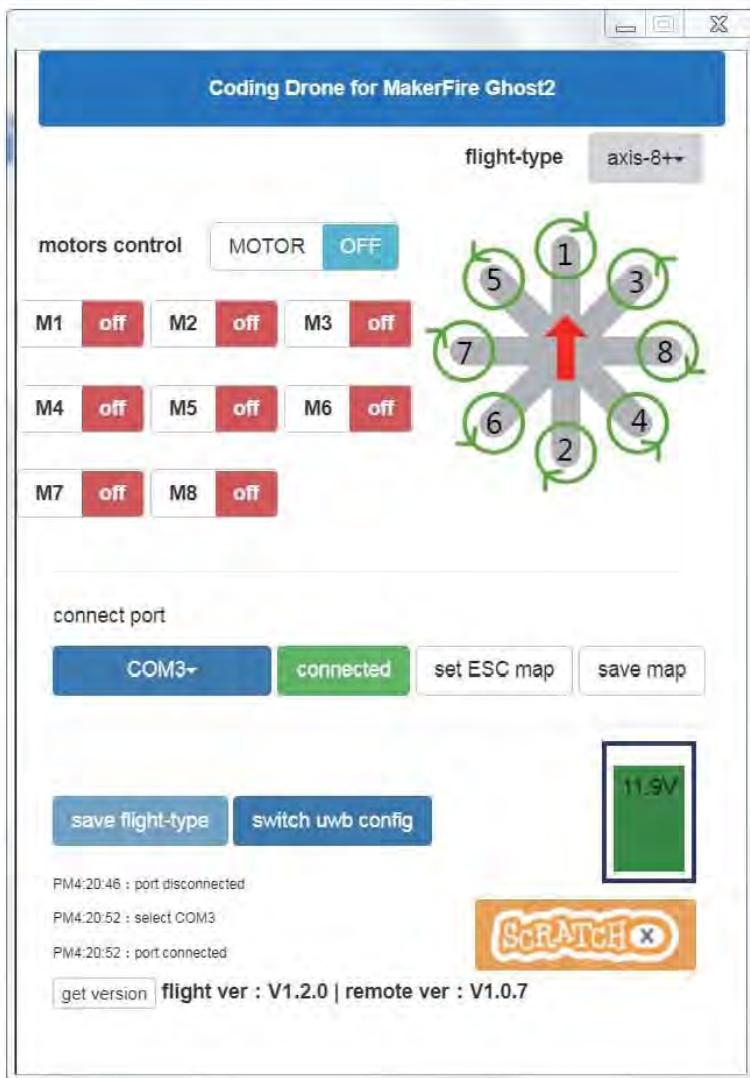
2. Install the power kit in the position shown above, according to the installation method of the assembly manual.

# Six-axis / Eight-axis expansion-eight-axis installation



3. Turn the aircraft upside down, and connect the power cables to the corresponding sockets as shown in the figure above.
4. Finally, install other accessories as shown in the assembly manual.

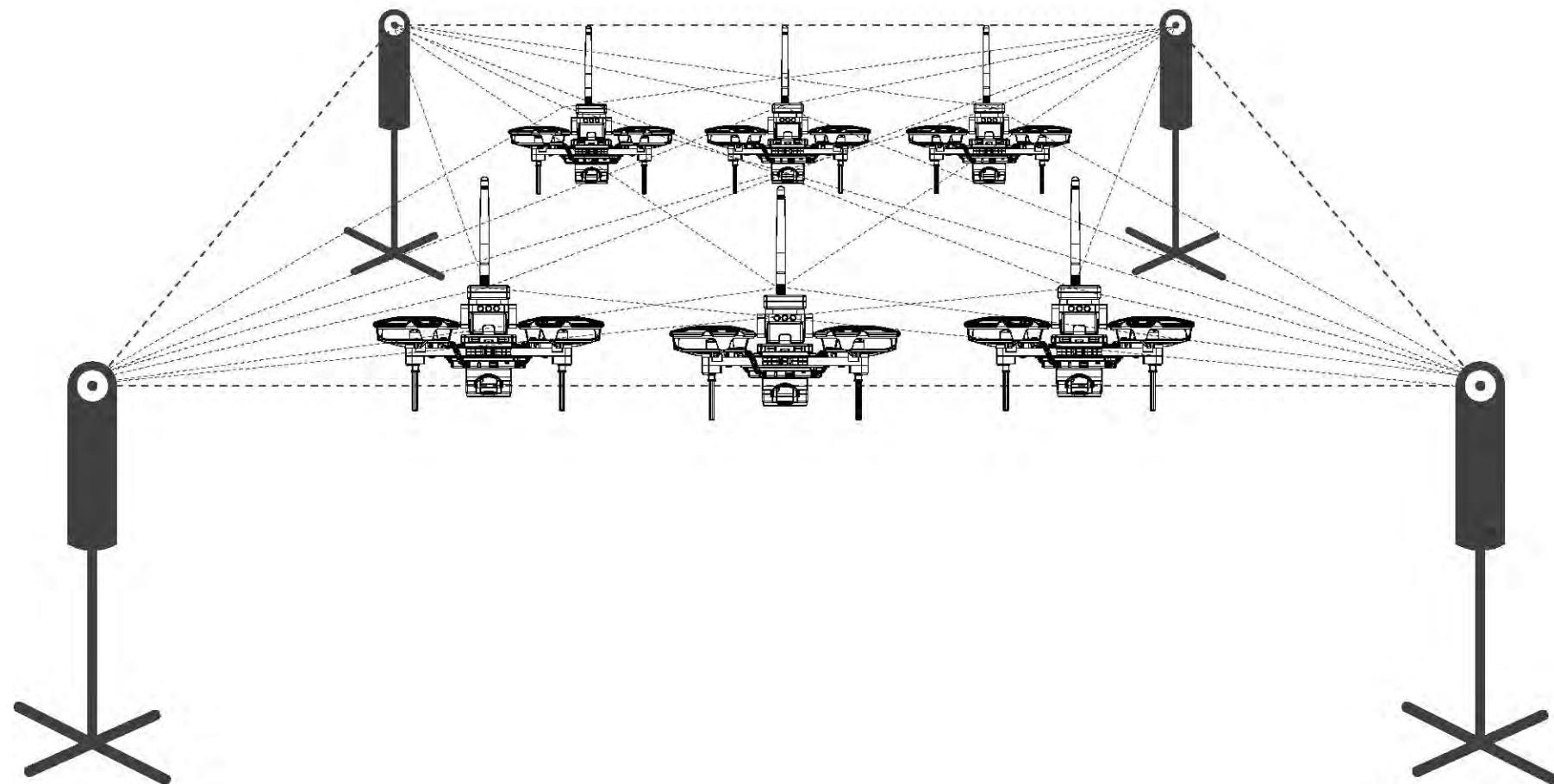
# Six-axis / Eight-axis expansion-eight-axis installation



5. Open the Google App plugin - Ghost, open the remote control and connect to the computer.  
(note: the remote control is in online mode)
6. Click "Select Serial Port". After connecting, the port will automatically detect the current axis type of the aircraft. Please set the aircraft type to "8-axis +" in the upper right corner. Finally, click "Axis save" button to save.
7. Rebinding the Ghost with remote, then the aircraft can be operated to fly.

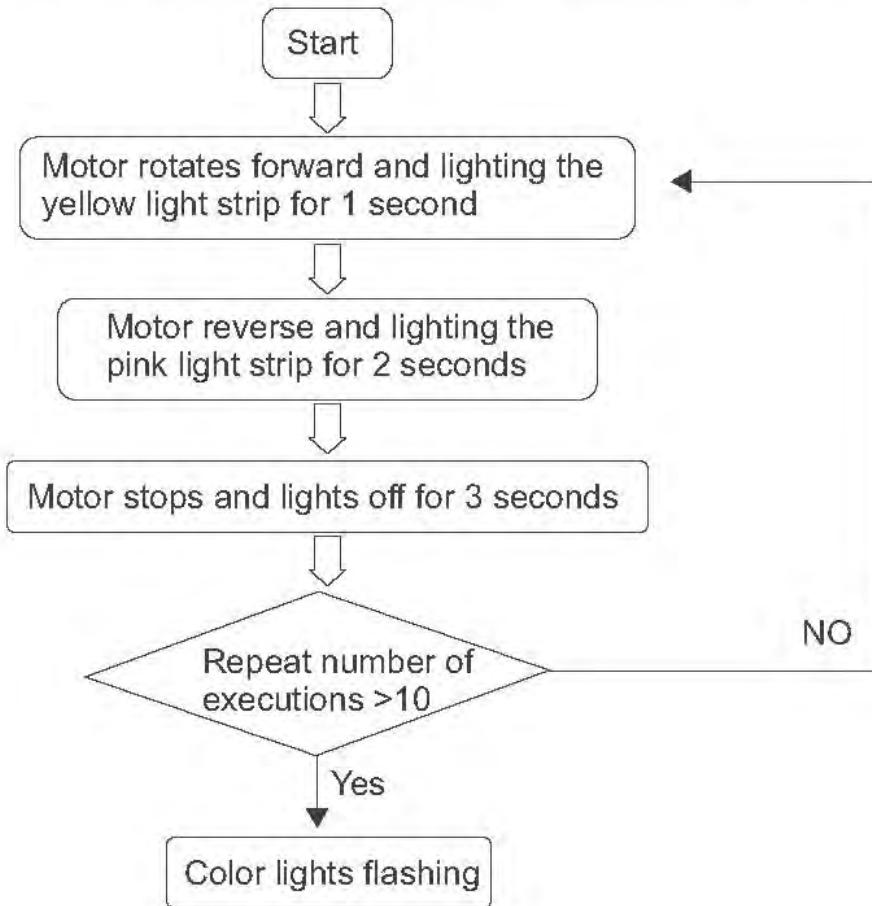
# Indoor 3D positioning solution

By using a space coordinate positioning system to build a 3D space in an indoor environment, so that each Ghost can get accurate 3D coordinate data. It can be used for indoor programming flight shows or multi-level task programming.



# Application docking station instance

Application docking station access to programmable lights and DC motors. Scratch programming controls the motor to rotate forward and lighting the yellow light strip for 1 second; then control the motor reverse and lighting the pink light strip for 2 seconds to execute 10 times in a loop. At the end, flash white light (each 0.4 seconds) to remind.



```
when green flag clicked
repeat (10)
    connect interface 1, set color YELLOW
    connect interface 6, set servo CR
    wait 1 secs
    connect interface 1, set color PINK
    connect interface 6, set servo CCR
    wait 2 secs
    connect interface 1, set color BLACK
    connect interface 6, set servo STOP
    wait 3 secs
end
forever
    connect interface 1, set color BLACK
    wait 1 secs
    connect interface 1, set color WHITE
    wait 1 secs
```

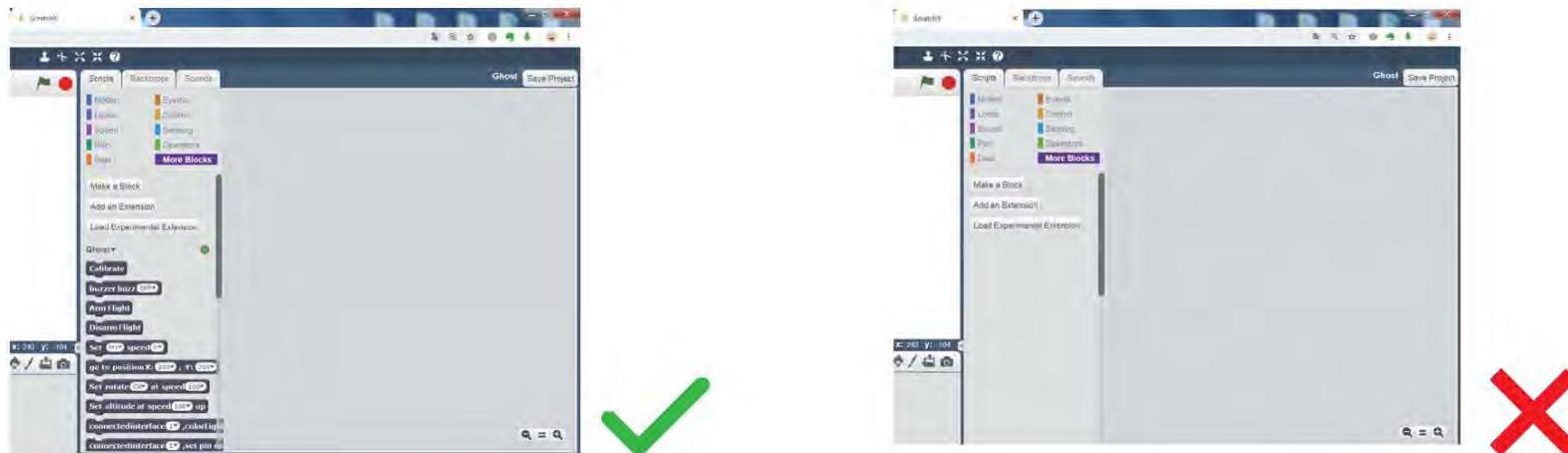
The Scratch script begins with a 'when green flag clicked' hat block. It then enters a 'repeat (10)' control loop. Inside the loop, it performs the following sequence: connects interface 1 and sets color to yellow, connects interface 6 and sets servo to CR, waits 1 second, connects interface 1 and sets color to pink, connects interface 6 and sets servo to CCR, waits 2 seconds, connects interface 1 and sets color to black, connects interface 6 and sets servo to stop, and waits 3 seconds. After the repeat loop, it enters a 'forever' control loop. Inside the forever loop, it connects interface 1 and sets color to black, waits 1 second, connects interface 1 and sets color to white, and waits 1 second.

# 4 Frequently asked questions



# Other aspects

- If the programming interface cannot be displayed completely when open Scratch interface, please use Google Chrome to open it.



- If the PC can't read serial port when the remote control is connected to it, please right-click Computer to open the device manager on your computer to check if there is a driver not installed prompt (with a yellow exclamation mark, as shown below). If so, please download the PC2102 driver from LiteBee's official website or use the Driver Wizard to detect and install.



# Other aspects

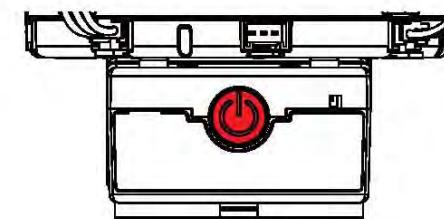
- The battery balance connector can be connected to the charger for charging, but be sure not to access to the application docking station.



- If the remote control fails to connect to the flight controller when updating the remote control or flight controller firmware, rebinding method as follows:



- Turn on the remote control (Ghost needs to be turned off)
- Press the right joy stick to the upper right corner for 45 degrees, and press the mode switch at the same time. Then the remote control L2 and L4 lights will flash.



- Turn on the aircraft, the buzzer will sound and the flight controller status indicator will be on. It means binding successful.

# Disclaimer statement

This product is a multi-rotor aircraft. We recommend for children over 8 years of age. Children under the age of 8 are required to be accompanied by adults. Please be careful when handling this product in the presence of children.

Please read this document carefully before using this product. This statement has important guidance for your safe use of this product and your legal rights. This product provides an easy flight experience when the power supply is working properly and the components are not damaged. Be sure to know your legal rights, responsibilities, and safety instructions before using this product, and also clear about that use this product may bring property damage, safety accidents and personal safety hazards. By using this product, you are deemed to have read, recognized and accepted all terms and conditions of this statement. The user is committed to being responsible for his non-compliant operations and the consequences thereof; the user undertakes to use the product solely for legitimate purposes and agrees to these terms and any relevant policies or guidelines that may be developed by us. We are not liable for any direct or indirect personal injury or property damage caused by failure to use this product in accordance with the safety guidelines.

# Air Robot LiteBee Series



LiteBee Brix  
DIY building block drone



LiteBee  
Graphical programming drone



LiteBee Pro  
Graphical Programming Drone Pro

# FCC Warning

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Aerial drone:

The antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter. This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. End user must follow the specific operating instructions for satisfying RF exposure compliance. This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

Controller:

The device has been evaluated to meet general RF exposure requirement. The device can be used in portable exposure condition without restriction.



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