

# **SAR Test Report**

Report No.: AGC01662180605FH01

2ALNEWLDAE1 FCC ID

APPLICATION PURPOSE **Original Equipment** 

PRODUCT DESIGNATION Wireless Video Intercom - Master Station

**BRAND NAME** Aiphone

**MODEL NAME** WL-1ME.E1

CLIENT Aiphone Co.,Ltd

**DATE OF ISSUE** Aug. 03,2018

IEEE Std. 1528:2013

FCC 47CFR § 2.1093 STANDARD(S)

IEEE/ANSI C95.1:2005

REPORT VERSION

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## **Report Revise Record**

	Report Version	Revise Time	Issued Date	Valid Version	Notes
10	V1.0	ns Signaturion of C	Aug. 03,2018	Valid	Initial Release

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	Test Report		
Applicant Name	Aiphone Co.,Ltd		
Applicant Address	2-18, Jinno-cho, Atsuta-ku, Nagoya, Aichi, 456-8666, Japan		
Manufacturer Name	Shenzhen Guo Wei Electronics Co., Ltd		
Manufacturer Address	No.3038, Luosha Road, Luohu District, Shenzhen, Guangdong, China Wireless Video Intercom - Master Station		
Product Designation			
Brand Name	Aiphone		
Model Name	WL-1ME.E1		
Different Description	N/A		
EUT Voltage	DC2.4V		
Applicable Standard	IEEE Std. 1528:2013 FCC 47CFR § 2.1093 IEEE/ANSI C95.1:2005		
Test Date	July 21,2018		
Report Template	AGCRT-US-1.9G/SAR (2018-01-01)		

Note: The results of testing in this report apply to the product/system which was tested only.

	Thea 1tuang				
Tested By	T. T. D. T. T.	pod Co. Harce			
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#### 1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 1g-SAR(W/Kg)	SAR Test Limit
	Body SAR (with 0mm separation)	(W/Kg)
1.9GHz	0.206	1.6
SAR Test Result	PASS	FK bal Compile

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/Kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:2005 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04

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# 2. GENERAL INFORMATION

2.1. EUT Description

Z. I. EUT Description	
General Information	
Product Designation	Wireless Video Intercom - Master Station
Test Model	WL-1ME.E1
Hardware Version	REV.0.4
Software Version	V6703USD
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
Duty Cycle	9%(test mode)
1.9 GHz	
TX Frequency Range	1921.536~1928.448MHz
RX Frequency Range	1900: 1922.400-1929.312MHz
Type of modulation	DFSK
Peak Power	19.42dBm
Battery	Voltage and Capacitance: 2.4 V & 2000mAh

Note: The sample used for testing is end product.

Product	Туре	:ml 12 12 12 12 12 12 12 12 12 12 12 12 12
Product	□ Production unit	☐ Identical Prototype

#### 2.2. Test Procedure

	1	Setup the EUT and Install the test software in PC.	-1117	JE 300	The Company
	2	Turn on the power of all equipment.	The Compliance	The Compilar	(8) Antiestation of the state o
3 Make EUT in continuous emission test at fixed frequency through software control.				'O CO	

#### 2.3. Test Environment

Ambient conditions in the laboratory:

Items	Required	Actual	
Temperature (°C)	18-25	21±2	
Humidity (%RH)	30-70	55±2	

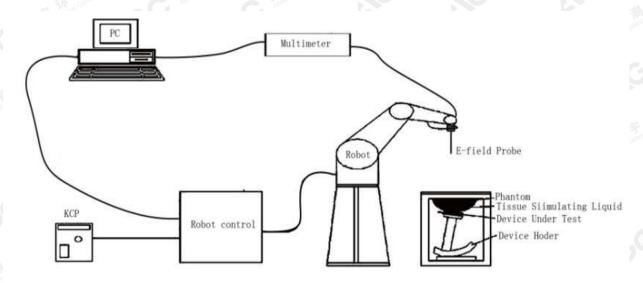
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#### 3. SAR MEASUREMENT SYSTEM

#### 3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- •The phantom, the device holder and other accessories according to the targeted measurement.

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#### 3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528 and relevant KDB files.) The calibration data are in Appendix D.

#### **Isotropic E-Field Probe Specification**

Model	SSE2
Manufacture	MVG
Identification No.	SN 08/16 EPGO282
Frequency	0.7GHz-6GHz Linearity:±0.06dB(700MHz-6GHz)
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.06dB
Dimensions	Overall length:330mm Length of individual dipoles:2mm Maximum external diameter:8mm Probe Tip external diameter:2.5mm Distance between dipoles/ probe extremity:1mm
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.

#### 3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

☐ High precision (repeatability 0.02 mm)

☐ High reliability (industrial design)

☐ Jerk-free straight movements

□ Low ELF interference (the closed metallic

construction shields against motor control fields)

□ 6-axis controller



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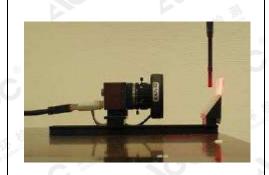
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## 3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link.

During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

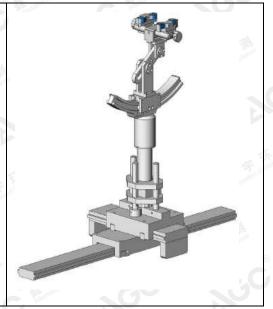


#### 3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity

 $\epsilon r = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



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#### 3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

□ Left head

☐ Right head

☐ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

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## 4. SAR MEASUREMENT PROCEDURE

#### 4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (p). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg) SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt} \Big|_{t=0}$$

Where

SAR is the specific absorption rate in watts per kilogram; is the r.m.s. value of the electric field strength in the tissue in volts per meter; is the conductivity of the tissue in siemens per metre;

is the density of the tissue in kilograms per cubic metre;

is the heat capacity of the tissue in joules per kilogram and Kelvin;

is the initial time derivative of temperature in the tissue in kelvins per second

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#### 4.2. SAR Measurement Procedure

#### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

#### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

≤3 GHz	> 3 GHz	
5 ± 1 mm	½·δ·ln(2) ± 0.5 mm	
30° ± 1°	20° ± 1°	
≤2 GHz: ≤15 mm 2 – 3 GHz: ≤12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm	
When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.		
	5 ± 1 mm  30° ± 1°  ≤2 GHz: ≤15 mm 2 - 3 GHz: ≤12 mm  When the x or y dimension o measurement plane orientation the measurement resolution r x or y dimension of the test d	

#### Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

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#### Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

				40.00
Maximum zoom scan s	n spatial resolution: Δx <sub>Zoom</sub> , Δy <sub>Zoom</sub>		$\leq$ 2 GHz: $\leq$ 8 mm 2 – 3 GHz: $\leq$ 5 mm <sup>*</sup>	3 – 4 GHz: ≤ 5 mm <sup>*</sup> 4 – 6 GHz: ≤ 4 mm <sup>*</sup>
uniform		grid: Δz <sub>Zoom</sub> (n)	≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
Maximum zoom scan spatial resolution, normal to phantom surface	$\begin{array}{c} \Delta z_{Z00m}(1)\text{: between} \\ 1^{\text{st}} \text{ two points closest} \\ \text{to phantom surface} \\ \\ \Delta z_{Z00m}(n > 1)\text{:} \\ \text{between subsequent} \\ \text{points} \end{array}$	1 <sup>st</sup> two points closest	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		≤ 1.5·Δz	Zoom(n-1)	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

#### Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

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When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



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# 4.3. RF Exposure Conditions

Test Configuration and setting:

The EUT is a wireless indoor monitor. For SAR testing, the device was controlled by software.

Antenna Location: (back view)



**EUT Bottom Edge (Edge 3)** 

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### 5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 4.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Polysorbate 20	DGBE	1,2 Propanediol	Triton X-100
1900 Body	70	1 ~	0.0	9 8	0.0	20

#### 5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency	h	ead	bo	ody
(MHz)	εr	σ (S/m)	εr	σ (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	1.01	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73

( $\epsilon r = relative permittivity$ ,  $\sigma = conductivity and <math>\rho = 1000 \text{ kg/m}3$ )

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#### 5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

***		Tissue Stimulant Me	easurement for 1900MHz			
	Fr.	Dielectric Par	ameters (±5%)	Tissue	testation	
	(MHz) εr53.30(50.635-55.965)		δ[s/m]1.52(1.444-1.596)	Temp [oC]	Test time	
Body	1900	53.34	1.51	-51	4	
	1921.536	52.04	1.55	01 F	July 24 2010	
	1924.992	51.85	1.56	21.5	July 21,2018	
	1928.448	51.56	1.57	non	5	

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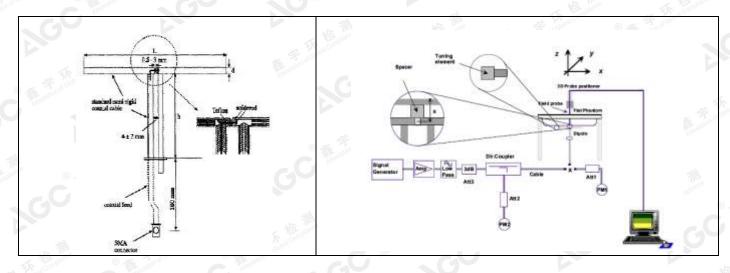
#### 6. SAR SYSTEM CHECK PROCEDURE

#### 6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.

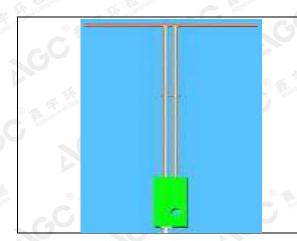


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# 6.2. SAR System Check 6.2.1. Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical Specifications for the dipoles.

Frequency	L (mm)	h (mm)	d (mm)		
1900MHz	68	39.5	3.6		

#### 6.2.2. System Check Result

System Per	formance	Check a	t 1900MHz for Bo	ody				
Validation K	(it: SN29/	15 DIP 00	8835-383&SN 29	15 DIP 1G900-3	<b>39</b>			
Frequency	ncy Value(W/Kg) (+ 10%) Value					sted (W/Kg)	Tissue Temp.	Test time
[MHz]	1g	10g	1g	10g	1g	10g	[°C]	Allesten
1900	39.38	20.86	35.442-43.318 18.774-22.946		41.02	20.57	21.5	July 21,2018

#### Note:

- (1) We use a CW signal of 18dBm for system check, and then all SAR value are normalized to 1W forward power. The result must be within  $\pm 10\%$  of target value.
- (2) Tested normalized SAR (W/kg) = Tested SAR (W/kg)  $\times$  [1000/ 10^1.8]

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#### 7. EUT TEST POSITION

This EUT was tested in Body back, Body front, Edge1, Edge2 and Edge4.

#### 7.4. Test Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to 0mm.

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#### 8. SAR EXPOSURE LIMITS

SAR assessments have been made in line with the requirements of IEEE-1528, and comply with ANSI/IEEE C95.1-2005 "Uncontrolled Environments" limits. These limits apply to a location which is deemed as "Uncontrolled Environment" which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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# 9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2F., Bldg.2, No.1-4, Chaxi Sanwei Technical Industrial Park, Gushu, Xixiang, Bao'an District B112-B113, Shenzhen 518012
NVLAP Lab Code	600153-0
Designation Number	CN5028
Test Firm Registration Number	682566
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by National Voluntary Laboratory Accreditation program, NVLAP Code 600153-0

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## **10. TEST EQUIPMENT LIST**

description Model		Identification No.	Current calibration date	Next calibration date	
		SN 08/16 EPGO282	Aug. 08,2017	Aug. 07,2018	
Phantom	SATIMO	SN_4511_SAM90	Validated. No cal required.	Validated. No ca required.	
Liquid	SATIMO	环境测量	Validated. No cal required.	Validated. No ca required.	
Dipole	SATIMO SID1900	SN 29/15 DIP 1G900-389	July 05,2016	July 04,2019	
Signal Generator	Agilent-E4438C	US41461365	Mar. 01,2018	Feb. 28,2019	
Vector Analyzer	Agilent / E4440A	US41421290	Mar. 01,2018	Feb. 28,2019	
Network Analyzer	Rhode & Schwarz ZVL6	SN100132	Mar. 01,2018	Feb. 28,2019	
Attenuator	Warison /WATT-6SR1211	N/A	N/A	N/A	
Attenuator	Mini-circuits / VAT-10+	N/A	N/A	N/A	
Amplifier	EM30180	SN060552	Mar. 01,2018	Feb. 28,2019	
Directional Werlatone/ Couple C6026-10		SN99482	June 12,2018	June 11,2019	
Power Sensor	ower Sensor NRP-Z21 1137.		Oct. 12,2017	Oct. 11,2018	
Power Sensor	NRP-Z23	US38261498	Mar. 01,2018	Feb. 28,2019	
Power Viewer	iewer R&S V2.3.1.0		N/A	N/A	

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

- 1. There is no physical damage on the dipole;
- 2. System validation with specific dipole is within 10% of calibrated value;
- 3. Return-loss is within 20% of calibrated measurement;
- 4. Impedance is within  $5\Omega$  of calibrated measurement.

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#### 11. MEASUREMENT UNCERTAINTY

Measur	ement un	certainty fo	r Dipole	averaged o	over 1 gran	n / 10 gran	1.		
a a	b	C ® Mar	# d	e f(d,k)	Cf To	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System		1 (= 70)	:111		all	- 11/1	(=70)	(±70)	Ompliance
Probe calibration	E.2.1	5.831	N	1 派 恒	1	15/ William	5.83	5.83	00
Axial Isotropy	E.2.2	0.695	R ®	√3	√0.5	√0.5	0.28	0.28	00
Hemispherical Isotropy	E.2.2	1.045	R	√3	√0.5	√0.5	0.43	0.43	8
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	00
Linearity	E.2.4	0.685	R	√3	E 15/h Company	1 5	0.40	0.40	00
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	Alles allo	0.58	0.58	00
(C) # 1000 (C) # 1000 (C)	E2.5	3.0	R	√3	1	1	1.73	1.73	00
Modulation response						etilita -		1421 1000	
Readout Electronics	E.2.6	0.021	N	1	1	EK KEL phance	0.021	0.021	00
Response Time	E.2.7	0	R	√3 	1 (8)	1	O Maria de la lorr	0	00
Integration Time	E.2.8	1.4	R	√3 -	1	1	0.81	0.81	00
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	œ
RF ambient conditions-reflections	E.6.1	3.0	R	√3	1	1 🦪	1.73	1.73	8
Probe positioner mechanical tolerance	E.6.2	1.4	R	$\sqrt{3}$	1	Attestation of	0.81	0.81	oo
Probe positioning with respect to phantom shell	E.6.3	1.4	R	√3	1	1	0.81	0.81	8
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	1	1 <b>11</b> 1	1.33	1.33	80
Test sample Related	THE ST.	_	The shot all	omplie.	A of Glopal Co.		(B) Allestation of	C	Altest
Test sample positioning	E.4.2	2.6	N	1	1	1	2.6	2.6	o
Device holder uncertainty	E.4.1	3	N	1	1	1	3	3	X
Output power variation—SAR drift measurement	E.2.9	5	R	√3	<u>all</u> 1	1,5	2.89	2.89	ox
SAR scaling	E.6.5	5	R	$\sqrt{3}$	1_	1 1 al Comalii	2.89	2.89	~
Phantom and tissue parameters	14	\$A Committee	® #	station of Glov	All'	astalion Ol			U
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	$\sqrt{3}$	1	1	2.31	2.31	α
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	IN 1 King	0.84	1.90	1.60	O
Liquid conductivity measurement	E.3.3	4	od Comp	1 38 Auto	0.78	0.71	3.12	2.84	N
Liquid permittivity measurement	E.3.3	5	N	3 1	0.23	0.26	1.15	1.30	N
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	o
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	O
Combined Standard Uncertainty	_ F 30	(B) (S) (S) (S) (S) (S) (S) (S) (S) (S) (S	RSS	500	C Atte	~ (4	9.79	9.59	
Expanded Uncertainty (95% Confidence interval)	Attestation !	C,C	K=2	10			19.58	19.18	×17.

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		700		e e	- 2	m / 10 gran	h.	i e	. 5
a	b	C	d	f(d,k)	©f	g e	cxf/e	c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System								1	
Probe calibration drift	E.2.1.3	0.5	N	1	1	1 1	0.50	0.50	00
Axial Isotropy	E.2.2	0.695	R	√3	0	0	0.00	0.00	00
Hemispherical Isotropy	E.2.2	1.045	R	√3	0	0	0.00	0.00	00
Boundary effect	E.2.3	1.0	R	√3	0	0	0.00	0.00	00
Linearity	E.2.4	0.685	R	$\sqrt{3}$	0	0	0.00	0.00	00
System detection limits	E.2.4	1.0	R	√3	0	0	0.00	0.00	00
Modulation response	E2.5	3.0	R	√3	0	0	0.00	0.00	00
Readout Electronics	E.2.6	0.021	N	1	0	0	0.00	0.00	00
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	00
Integration Time	E.2.8	1.4	R	√3	© 0	0	0.00	0.00	00
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	00
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	00
Probe positioner mechanical tolerance	E.6.2	1.4	₩ R	√3	The 1	1# T	0.81	0.81	00
Probe positioning with respect to phantom shell	E.6.3	1.4	R 👩	√3	1	1	0.81	0.81	00
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	0	0	0.00	0.00	00
System check source (dipole)			~ 核	-lini	<b>长</b>	pliance	0 # F 10	(B)	- The state of the
Deviation of experimental dipoles	E.6.4	2	N	1 🛭 🧸	atation of Tiobal	1	2	2	00
Input power and SAR drift measurement	8,6.6.4	5	R	$\sqrt{3}$	1	1	2.89	2.89	00
Dipole axis to liquid distance	8,E.6.6	2	R	$\sqrt{3}$	1	1	1.15	1.15	00
Phantom and tissue parameters		litte:		不怕	mpliance	The Compile	ince (6)	The station of Gio	
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	√3	18 %	alation of 1	2.31	2.31	00
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	9 1	0.84	1.90	1.60	00
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5	₩ N°	1 4	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	oc
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	oc
Combined Standard Uncertainty		lin;	RSS	Mar All	1/2	FA Global Company	5.564	5.205	. (
Expanded Uncertainty (95% Confidence interval)	云河	Oal Compliance	K=2	pal Compile	Altestati		11.128	10.410	

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System Va	alidation u	ıncertainty	for Dipo	le average	ed over 1 gr	am / 10 gra	am.		
a	b	C	d	e f(d,k)	®f #	g g	h cxf/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (±%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System			Tre-		•				III;
Probe calibration	E.2.1	5.831	-MN	1	1	1 7	5.83	5.83	00
Axial Isotropy	E.2.2	0.695	R	√3	o <sup>b</sup> 1	F That Complian	0.40	0.40	00
Hemispherical Isotropy	E.2.2	1.045	R	√3	0	0	0.00	0.00	00
Boundary effect	E.2.3	1.0	R	√3	1	1	0.58	0.58	00
Linearity	E.2.4	0.685	R	$\sqrt{3}$	1, 7	, 1	0.40	0.40	00
System detection limits	E.2.4	1.0	R	√3	1 Con 1	e 1 F	0.58	0.58	00
Modulation response	E2.5	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	00
Readout Electronics	E.2.6	0.021	N	1	1	1 ,	0.021	0.021	00
Response Time	E.2.7	0.0	R	$\sqrt{3}$	0	10 marce	0.00	0.00	00
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	of Clops Cours	0.00	0.00	00
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	C 1	10	1.73	1.73	00
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	00
Probe positioner mechanical tolerance	E.6.2	1.4	<sub>sh</sub> R	√3	<b>#</b> 1	1,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	0.81	0.81	00
Probe positioning with respect to phantom shell	E.6.3	1.4	R	√3	1	A 1 stallon	0.81	0.81	00
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	1	1	1.33	1.33	8
System check source (dipole)			***	TIII)	~ 恒	lisuce Jins	学 玩	ibal Compile	A. 13
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	K Nonda	1 @ 🧣	F 10 100	1	5.00	5.00	00
Input power and SAR drift measurement	8,6.6.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	00
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	00
Phantom and tissue parameters		litte:		一枪	-Min	A Kinglis	® ®	Tation of Globa	
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4.0	R	√3	19 🐔	Jalion of Globba	2.31	2.31	8
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	51	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4.0	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	5.0	N	1 4	0.23	0.26	1.15	1.30	М
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	00
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	8
Combined Standard Uncertainty		litte	RSS		2	The Compile	9.718	9.517	
Expanded Uncertainty (95% Confidence interval)	II.	bal Compliance	K=2	Pal Combilar.	® Allestation	01	19.437	19.035	

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# 12. CONDUCTED POWER MEASUREMENT

1.9GHz

Mode	Channel	Frequency (MHz)	Maximum Peak Power (dBm)
Global (Global	CH0	1921.536	19.42
1900MHz	CH4	1924.992	19.36
C all	CH9	1928.448	19.30

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#### 13. TEST RESULTS

# 13.1. SAR Test Results Summary 13.1.1. Test position and configuration

- 1. The EUT is a wireless indoor monitor;
- 2. Lab use the body liquid with a separation of 0mm at flat phantom to test;
- 4. For SAR testing, the device was controlled by software to test at reference fixed frequency points.

#### 13.1.2. Operation Mode

- 1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
- 2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥0.8W/Kg, testing for repeated SAR measurement is required, that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
  - (1) When the original highest measured SAR is  $\geq$ 0.8W/Kg, repeat that measurement once.
  - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥1.45 W/Kg.
  - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20.
- Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
  - Maximum Scaling SAR =tested SAR (Max.)  $\times$  [maximum turn-up power (mw)/ maximum measurement output power(mw)]

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#### 13.1.3. Test Result

SAR MEASUREMENT		
Depth of Liquid (cm):>15	Relative Humidity (%): 50.6	
Product: Wireless Video Intercom - Master S	Station	

Test Model:WL-1ME.E1

Position	Ch.	Fr. (MHz)	Power Drift (<±5%)	SAR (1g) (W/kg)	Max. Tune -up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
Body Back	0	1921.536	-0.13	0.178	20.00	19.36	0.206	1.6
Body Front	0	1921.536	-0.02	0.118	20.00	19.36	0.137	1.6
Edge1	0	1921.536	0.15	0.178	20.00	19.36	0.206	1.6
Edge2	<i>₃</i> 0	1921.536	-0.26	0.156	20.00	19.36	0.181	1.6
Edge4	Compliance 0	1921.536	0.03	0.111	20.00	19.36	0.129	1.6

#### Note:

• When the 1-g Reported SAR is ≤ 0.8 W/kg, testing for low and high channel is optional. Refer to KDB 447498.

•The test separation is 0mm of all above table.

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#### APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab Date: July 21,2018

System Check Body 1900MHz

DUT: Dipole 1900 MHz; Type: SID 1900

Communication System: CW; Communication System Band: D1900 (1900.0 MHz); Duty Cycle:1:1; Conv.F=2.39 Frequency: 1900 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.51$  mho/m;  $\epsilon r = 53.34$ ;  $\rho = 1000$  kg/m³;

Phantom section: Flat Section; Input Power=18dBm

Ambient temperature (°C):21.8, Liquid temperature (°C): 21.5

#### **SATIMO Configuration:**

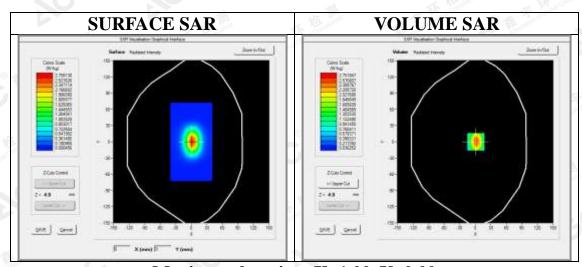
Probe: SSE2; Calibrated: Aug. 08,2017; Serial No.: SN 08/16 EPGO282

Sensor-Surface: 4mm (Mechanical Surface Detection)

Phantom: SAM twin phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/System Check 1900MHz Body/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/System Check 1900MHz Body/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm



Maximum location: X=1.00, Y=0.00 SAR Peak: 4.42 W/kg

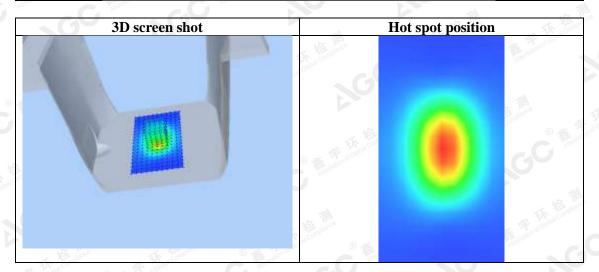
31111	8
SAR 10g (W/Kg)	1.297986
SAR 1g (W/Kg)	2.588076

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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	4.4246	2.7518	1.4753	0.8251	0.4630	0.2640	0.1518
Ton of Colon Complain	4.42 - 4.00 -	$\bigvee$					
P. Residen	SAR (W/kg)	$\mathbb{H}$					
Compliance	SAR (V						
5C ****	1.00-					<b>A</b>	
The State of The S	0.09 – \ 0.	0 2.5 5.0 7.51	0.0 15.0	20.0 25.0 Z (mm)	30.0 35.	0 40.0	



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### APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab Date: July 21,2018

1.9GHz Low-Body-Back

DUT: Wireless Video Intercom - Master Station; Type: WL-1ME.E1

Communication System: 1.9GHz; Communication System Band: 1900; Duty Cycle: 9%; Conv.F=2.39;

Frequency: 1921.536 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.56$  mho/m;  $\epsilon r = 51.85$ ;  $\rho = 1000$  kg/m<sup>3</sup>;

Phantom section: Flat Section

Ambient temperature ( $^{\circ}$ C): 21.8, Liquid temperature ( $^{\circ}$ C): 21.5

SATIMO Configuration:

Probe: SSE2; Calibrated: Aug. 08,2017; Serial No.: SN 08/16 EPGO282

Sensor-Surface: 4mm (Mechanical Surface Detection)

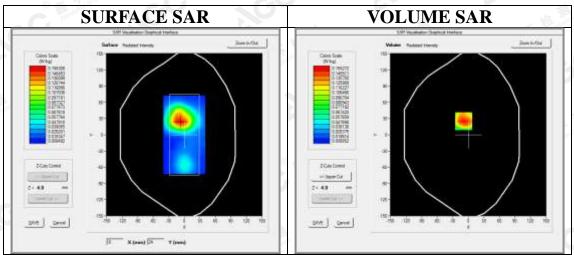
Phantom: SAM twin phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/1.9GHz Low-Body-Back/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1.9GHz Low-Body-Back/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

Area Scan	surf_sam_plan.txt, h= 5.00 mm				
ZoomScan	5x5x7,dx=8mm dy=8mm dz=5mm,Complete  Validation plane  Body Back				
Phantom					
Device Position					
Band	1.9GHz				
Channels	Low The state of t				
Signal	Crest factor: 11.11				



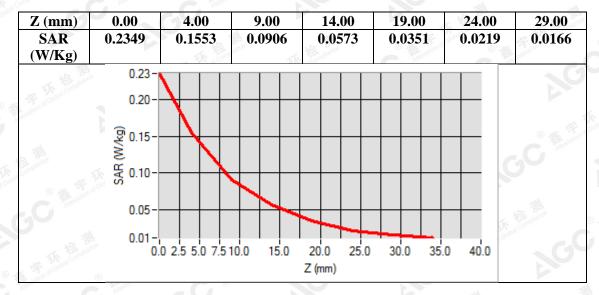
Maximum location: X=-9.00, Y=25.00 SAR Peak: 0.24 W/kg

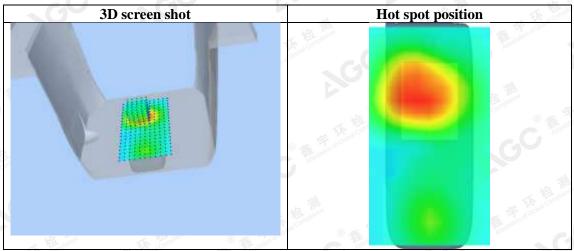
SAR 10g (W/Kg)	0.095637				
SAR 1g (W/Kg)	0.177594				

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Test Laboratory: AGC Lab Date: July 21,2018

1.9GHz Low-Body-Front

DUT: Wireless Video Intercom - Master Station; Type: WL-1ME.E1

Communication System: 1.9GHz; Communication System Band: 1900; Duty Cycle: 9%; Conv.F=2.39;

Frequency: 1921.536 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.56 \text{ mho/m}$ ;  $\epsilon = 51.85$ ;  $\rho = 1000 \text{ kg/m}^3$ ;

Phantom section: Flat Section

Ambient temperature (°C): 21.8, Liquid temperature (°C): 21.5

**SATIMO Configuration:** 

Probe: SSE2; Calibrated: Aug. 08,2017; Serial No.: SN 08/16 EPGO282

Sensor-Surface: 4mm (Mechanical Surface Detection)

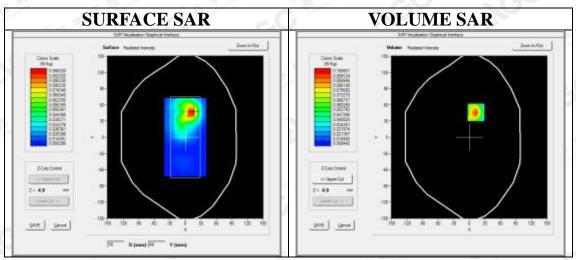
Phantom: SAM twin phantom

Measurement SW: OpenSAR V4 02 35

Configuration/1.9GHz Low-Body-Front/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1.9GHz Low-Body-Front/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

Area Scan	surf_sam_plan.txt, h= 5.00 mm		
ZoomScan	5x5x7,dx=8mm dy=8mm dz=5mm,Complete		
Phantom	Validation plane		
Device Position	Body Front		
Band	1.9GHz		
Channels	Low 2 March 2		
Signal	Crest factor: 11.11		



Maximum location: X=13.00, Y=46.00

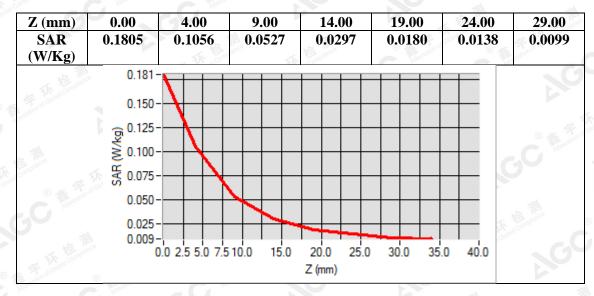
SAR Peak: 0.18 W/kg

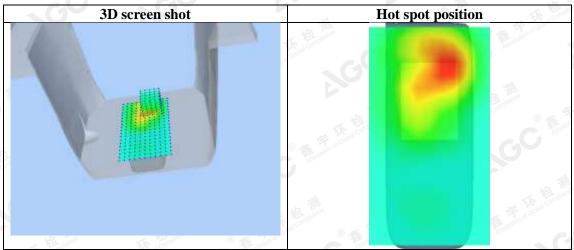
SAR 10g (W/Kg)	0.056471
SAR 1g (W/Kg)	0.117943

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Test Laboratory: AGC Lab

1.9GHz Low-Edge1

DUT: Wireless Video Intercom - Master Station; Type: WL-1ME.E1

Communication System: 1.9GHz; Communication System Band: 1900; Duty Cycle: 9%; Conv.F=2.39;

Frequency: 1921.536 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.56 \text{ mho/m}$ ; r = 51.85;  $\rho = 1000 \text{ kg/m}^3$ ;

Phantom section: Flat Section

Ambient temperature (°C): 21.8, Liquid temperature (°C): 21.5

**SATIMO Configuration:** 

Probe: SSE2; Calibrated: Aug. 08,2017; Serial No.: SN 08/16 EPGO282

Sensor-Surface: 4mm (Mechanical Surface Detection)

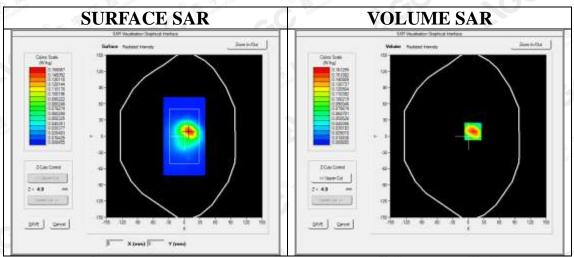
Phantom: SAM twin phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/1.9GHz Low-Edge1/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1.9GHz Low-Edge1/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

Area Scan	surf_sam_plan.txt, h= 5.00 mm			
ZoomScan	5x5x7,dx=8mm dy=8mm dz=5mm,Complete			
Phantom	Validation plane			
Device Position	Edge1			
Band	1.9GHz			
Channels	Low Low			
Signal	Crest factor: 11.11			



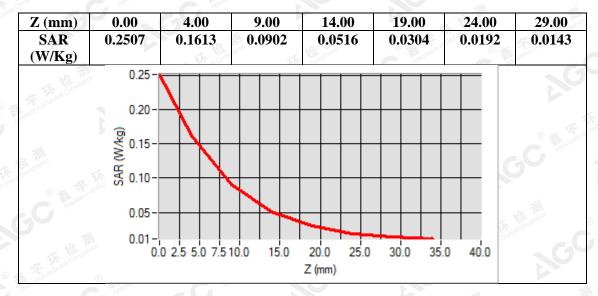
Maximum location: X=9.00, Y=9.00 SAR Peak: 0.26 W/kg

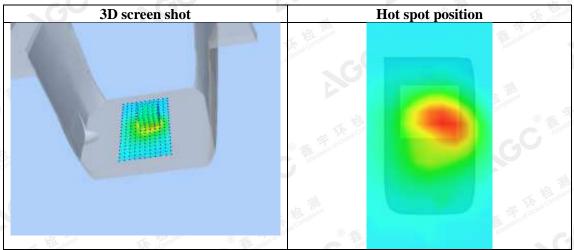
<b>SAR 10g (W/Kg)</b>	0.087645
SAR 1g (W/Kg)	0.178198

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Test Laboratory: AGC Lab

1.9GHz Low-Edge2

DUT: Wireless Video Intercom - Master Station; Type: WL-1ME.E1

Communication System: 1.9GHz; Communication System Band: 1900; Duty Cycle: 9%; Conv.F=2.39;

Frequency: 1921.536 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.56 \text{ mho/m}$ ;  $\epsilon = 51.85$ ;  $\rho = 1000 \text{ kg/m}^3$ ;

Phantom section: Flat Section

Ambient temperature (°C): 21.8, Liquid temperature (°C): 21.5

**SATIMO Configuration:** 

Probe: SSE2; Calibrated: Aug. 08,2017; Serial No.: SN 08/16 EPGO282

Sensor-Surface: 4mm (Mechanical Surface Detection)

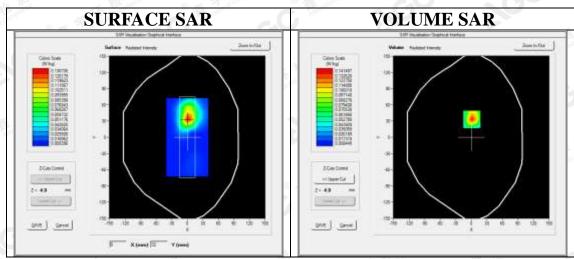
Phantom: SAM twin phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/1.9GHz Low-Edge2/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1.9GHz Low-Edge2/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

Area Scan	surf_sam_plan.txt, h= 5.00 mm			
ZoomScan	5x5x7,dx=8mm dy=8mm dz=5mm,Complete			
Phantom	Validation plane			
Device Position	Edge2			
Band	1.9GHz			
Channels	Low 2			
Signal	Crest factor: 11.11			



Maximum location: X=1.00, Y=33.00 SAR Peak: 0.23 W/kg

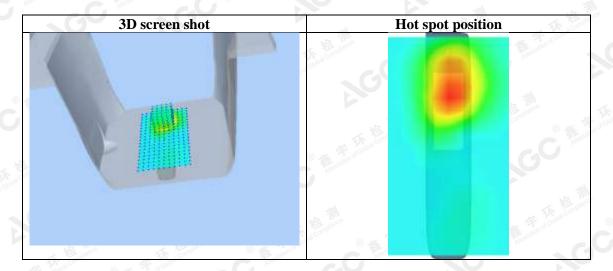
SAR 10g (W/Kg) 0.074625 SAR 1g (W/Kg) 0.155809

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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	0.2280	0.1415	0.0771	0.0419	0.0265	0.0175	0.0123
KE THE	0.23-	<u> </u>					
F of Global Confe	0.20-	$\overline{}$					
		<b>\</b>					
	© 0.15- W						
	√ SAR (0.10-						
	S. A.						
	0.05-		$\wedge$				
	0.01			<b></b>		The same of the sa	
TK KELDING	0.01 – 0.	0 2.5 5.0 7.5	10.0 15.0	20.0 25.0	30.0 35.	0 40.0	
F Thot Global Co.				Z (mm)			



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Test Laboratory: AGC Lab

1.9GHz Low-Edge4

DUT: Wireless Video Intercom - Master Station; Type: WL-1ME.E1

Communication System: 1.9GHz; Communication System Band: 1900; Duty Cycle: 9%; Conv.F=2.39;

Frequency: 1921.536 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.56 \text{ mho/m}$ ;  $\epsilon r = 51.85$ ;  $\rho = 1000 \text{ kg/m}^3$ ;

Phantom section: Flat Section

Ambient temperature (°C): 21.8, Liquid temperature (°C): 21.5

**SATIMO Configuration:** 

Probe: SSE2; Calibrated: Aug. 08,2017; Serial No.: SN 08/16 EPGO282

Sensor-Surface: 4mm (Mechanical Surface Detection)

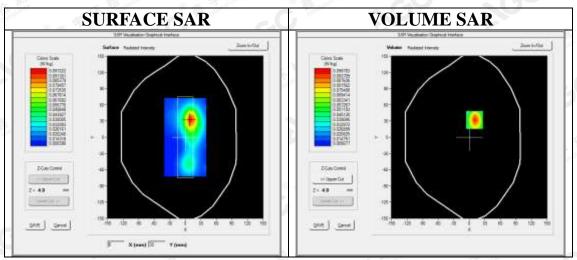
Phantom: SAM twin phantom

Measurement SW: OpenSAR V4 02 35

Configuration/1.9GHz Low-Edge4/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1.9GHz Low-Edge4/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

Area Scan	surf_sam_plan.txt, h= 5.00 mm
ZoomScan	5x5x7,dx=8mm dy=8mm dz=5mm,Complete
Phantom	Validation plane
Device Position	Edge4
Band	1.9GHz
Channels	Low 2
Signal	Crest factor: 11.11



Maximum location: X=10.00, Y=32.00

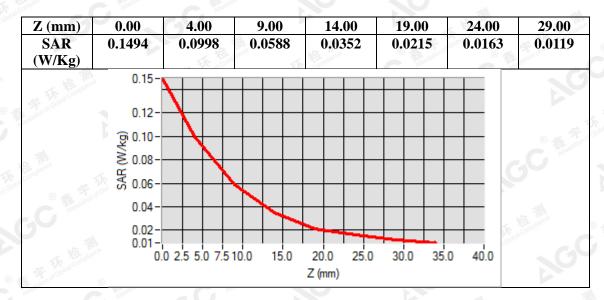
SAR Peak: 0.15 W/kg

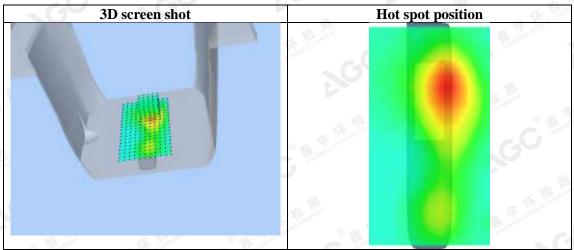
<b>SAR 10g (W/Kg)</b>	0.058055
SAR 1g (W/Kg)	0.110710

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## **APPENDIX C. TEST SETUP PHOTOGRAPHS**

Refer to Attached files.

#### APPENDIX D. CALIBRATION DATA

Refer to Attached files.

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