

## DASY5 Validation Report for Head TSL

Date: 14.02.2018

Test Laboratory: SPEAG, Zurich, Switzerland

# DUT: Dipole D5GHzV2; Type: D5GHzV2; Serial: D5GHzV2 - SN:1212

Communication System: UID 0 - CW; Frequency: 5200 MHz, Frequency: 5300 MHz, Frequency: 5500 MHz, Frequency: 5600 MHz, Frequency: 5800 MHz Medium parameters used: f=5200 MHz;  $\sigma=4.53$  S/m;  $\epsilon_r=36.4;$   $\rho=1000$  kg/m³, Medium parameters used: f=5300 MHz;  $\sigma=4.64$  S/m;  $\epsilon_r=36.3;$   $\rho=1000$  kg/m³, Medium parameters used: f=5500 MHz;  $\sigma=4.84$  S/m;  $\epsilon_r=36;$   $\rho=1000$  kg/m³,

Medium parameters used: f = 5600 MHz;  $\sigma = 4.95$  S/m;  $\varepsilon_r = 35.8$ ;  $\rho = 1000$  kg/m<sup>3</sup>,

Medium parameters used: f = 5800 MHz;  $\sigma = 5.16$  S/m;  $\epsilon_r = 35.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

#### DASY52 Configuration:

- Probe: EX3DV4 SN3503; ConvF(5.75, 5.75, 5.75); Calibrated: 30.12.2017, ConvF(5.5, 5.5, 5.5);
   Calibrated: 30.12.2017, ConvF(5.2, 5.2, 5.2); Calibrated: 30.12.2017, ConvF(5.05, 5.05, 5.05);
   Calibrated: 30.12.2017, ConvF(4.96, 4.96, 4.96); Calibrated: 30.12.2017;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 26.10.2017
- Phantom: Flat Phantom 5.0 (front); Type: QD 000 P50 AA; Serial: 1001
- DASY52 52.10.0(1446); SEMCAD X 14.6.10(7417)

# Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5200 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 71.98 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 28.5 W/kg

SAR(1 g) = 7.95 W/kg; SAR(10 g) = 2.26 W/kg

Maximum value of SAR (measured) = 18.0 W/kg

# Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5300 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 72.21 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 29.9 W/kg

SAR(1 g) = 8.1 W/kg; SAR(10 g) = 2.31 W/kg

Maximum value of SAR (measured) = 18.8 W/kg

### Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5500 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 73.15 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 33.3 W/kg

SAR(1 g) = 8.53 W/kg; SAR(10 g) = 2.4 W/kg

Maximum value of SAR (measured) = 20.1 W/kg

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# Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5600 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 72.01 V/m; Power Drift = -0.05 dB

Peak SAR (extrapolated) = 32.2 W/kg

SAR(1 g) = 8.36 W/kg; SAR(10 g) = 2.38 W/kg

Maximum value of SAR (measured) = 20.0 W/kg

# Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5800 MHz/Zoom Scan,

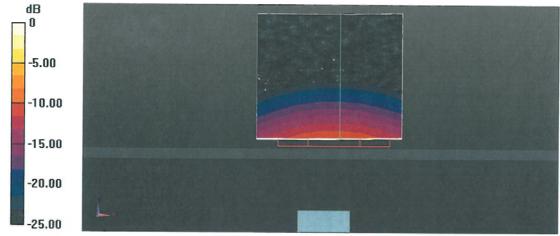
dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 70.08 V/m; Power Drift = -0.03 dB

Peak SAR (extrapolated) = 31.9 W/kg

SAR(1 g) = 7.95 W/kg; SAR(10 g) = 2.24 W/kg

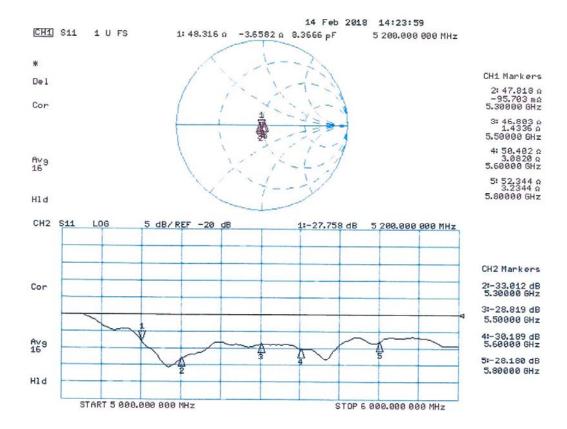
Maximum value of SAR (measured) = 19.4 W/kg



0 dB = 19.4 W/kg = 12.88 dBW/kg



# Impedance Measurement Plot for Head TSL





## DASY5 Validation Report for Body TSL

Date: 15.02.2018

Test Laboratory: SPEAG, Zurich, Switzerland

# DUT: Dipole D5GHzV2; Type: D5GHzV2; Serial: D5GHzV2 - SN:1212

Communication System: UID 0 - CW; Frequency: 5200 MHz, Frequency: 5300 MHz, Frequency: 5500 MHz, Frequency: 5600 MHz, Frequency: 5800 MHz Medium parameters used: f=5200 MHz;  $\sigma=5.41$  S/m;  $\epsilon_r=47.5;$   $\rho=1000$  kg/m $^3$ , Medium parameters used: f=5300 MHz;  $\sigma=5.54$  S/m;  $\epsilon_r=47.3;$   $\rho=1000$  kg/m $^3$ , Medium parameters used: f=5500 MHz;  $\sigma=5.8$  S/m;  $\epsilon_r=47;$   $\rho=1000$  kg/m $^3$ , Medium parameters used: f=5500 MHz;  $\sigma=5.8$  S/m;  $\epsilon_r=46.8;$   $\rho=1000$  kg/m $^3$ , Medium parameters used: f=5600 MHz;  $\sigma=5.95$  S/m;  $\epsilon_r=46.8;$   $\rho=1000$  kg/m $^3$ , Medium parameters used: f=5800 MHz;  $\sigma=6.23$  S/m;  $\epsilon_r=46.4;$   $\rho=1000$  kg/m $^3$  Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

#### DASY52 Configuration:

- Probe: EX3DV4 SN3503; ConvF(5.35, 5.35, 5.35); Calibrated: 30.12.2017, ConvF(5.15, 5.15, 5.15);
   Calibrated: 30.12.2017, ConvF(4.7, 4.7, 4.7); Calibrated: 30.12.2017, ConvF(4.65, 4.65, 4.65);
   Calibrated: 30.12.2017, ConvF(4.53, 4.53, 4.53); Calibrated: 30.12.2017;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 26.10.2017
- Phantom: Flat Phantom 5.0 (back); Type: QD 000 P50 AA; Serial: 1002
- DASY52 52.10.0(1446); SEMCAD X 14.6.10(7417)

## Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5200 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 64.59 V/m; Power Drift = -0.02 dB

Peak SAR (extrapolated) = 27.2 W/kg

SAR(1 g) = 7.31 W/kg; SAR(10 g) = 2.03 W/kg

Maximum value of SAR (measured) = 16.9 W/kg

### Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5300 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 64.99 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 29.6 W/kg

SAR(1 g) = 7.57 W/kg; SAR(10 g) = 2.11 W/kg

Maximum value of SAR (measured) = 17.7 W/kg

### Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5500 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 65.88 V/m; Power Drift = -0.07 dB

Peak SAR (extrapolated) = 33.3 W/kg

SAR(1 g) = 8.04 W/kg; SAR(10 g) = 2.22 W/kg

Maximum value of SAR (measured) = 19.3 W/kg

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# Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5600 MHz/Zoom Scan,

dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 64.59 V/m; Power Drift = -0.02 dB

Peak SAR (extrapolated) = 33.4 W/kg

SAR(1 g) = 7.94 W/kg; SAR(10 g) = 2.2 W/kg

Maximum value of SAR (measured) = 19.0 W/kg

# Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5800 MHz/Zoom Scan,

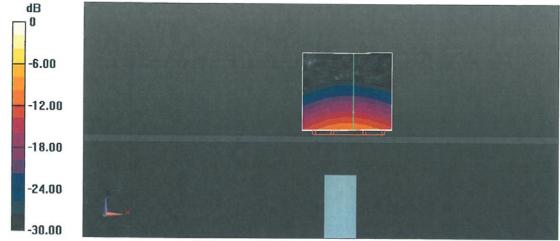
dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 63.42 V/m; Power Drift = -0.02 dB

Peak SAR (extrapolated) = 33.2 W/kg

SAR(1 g) = 7.62 W/kg; SAR(10 g) = 2.1 W/kg

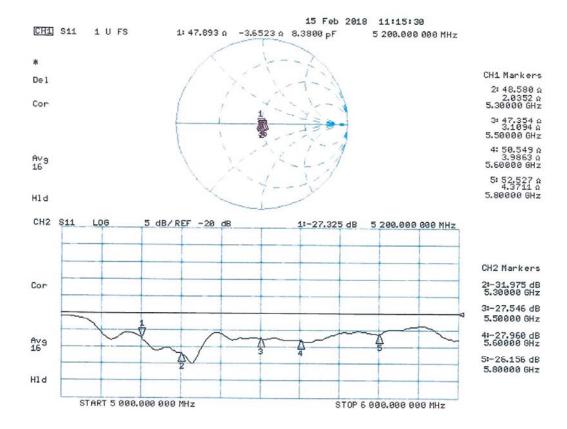
Maximum value of SAR (measured) = 18.7 W/kg



0 dB = 16.9 W/kg = 12.28 dBW/kg



# Impedance Measurement Plot for Body TSL





# **APPENDIX C. – SAR Tissue Specifications**



The brain and muscle mixtures consist of a viscous gel using hydrox-ethylcellulose (HEC) gelling agent and saline solution (see Table C.1). Preservation with a bactericide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The mixture characterizations used for the brain and muscle tissue simulating liquids are according to the data by C. Gabriel and G. Harts grove.



Figure C.1 Simulated Tissue

**Table C.1 Composition of the Tissue Equivalent Matter** 

Ingredients	Frequency (MHz)							
(% by weight)	835		1900		2450		5200 ~ 5800	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body
Water	40.19	50.75	55.24	70.23	71.88	73.40	65.52	80.00
Salt (NaCl)	1.480	0.940	0.310	0.290	0.160	0.060	-	-
Sugar	57.90	48.21	-	-	-	-	-	-
HEC	0.250	-	-	-	-	-	-	-
Bactericide	0.180	0.100	-	-	-	-	-	-
Triton X-100	-	-	-	-	19.97	-	17.24	-
DGBE	-	-	44.45	29.48	7.990	26.54	-	-
Diethylene glycol hexyl ether	-	-	-	-	-	-	17.24	-
Polysorbate (Tween) 80	-	-	-	-	-	-		20.00
Target for Dielectric Constant	41.5	55.2	40.0	53.3	39.2	52.7	-	-
Target for Conductivity (S/m)	0.90	0.97	1.40	1.52	1.80	1.95	-	-

Salt: 99 % Pure Sodium Chloride Sugar: 98 % Pure Sucrose

Water: De-ionized, 16M resistivity HEC: Hydroxyethyl Cellulose

DGBE: 99 % Di(ethylene glycol) butyl ether,[2-(2-butoxyethoxy) ethanol]

Triton X-100(ultra pure): Polyethylene glycol mono[4-(1,1,3,3-tetramethylbutyl)phenyl] ether



Table C.2 HSL/MSL750 (Head and Body liquids for 700 - 800 MHz)

Item	Head Tissue Simulation Liquids HSL750				
	Muscle (body) Tissue Simulation Liquids MSL750				
Type No	SL AAH 075, SL AAM 075				
Manufacturer	SPEAG				
The item is composed of the following ingredients:					
H <sup>2</sup> O	Water, 35 – 58%				
Sucrose	Sucrose, 40 – 60%				
NaCl	Sodium Chloride, 0 – 6%				
Hydroxyethyl-cellulose	Medium Viscosity (CAS# 9004-62-0), < 0.3%				
Preventol-D7	Preservative: aqueous preparation, (CAS# 55965-84-9), containing 5 chloro-2-methyl-3(2H)-isothiazolone and 2-methyyl-3(2H)-isothiazolone 0.1 – 0.6%				

# Table C.3 HSL/MSL1750 (Head and Body liquids for 1700 – 1800 MHz)

Item	Head Tissue Simulation Liquids HSL1750				
	Muscle (body) Tissue Simulation Liquids MSL1750				
Type No	SL AAH 175, SL AAM 175				
Manufacturer	SPEAG				
The item is composed of the following ingredients:					
H <sup>2</sup> O	Water, 52 – 75%				
C8H18O3	Diethylene glycol monobutyl ether (DGBE), 25 – 48%				
NaCl	Sodium Chloride, < 1.0%				

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# **APPENDIX D. - SAR SYSTEM VALIDATION**

### **SAR System Validation**

Per FCC KDB 865664 D02v01r02, SAR system validation status should be documented to confirm measurement accuracy. The SAR systems (including SAR probes, system components and software versions) used for this device were validated against its performance specifications prior to the SAR measurements. Reference dipoles were used with the required tissue- equivalent media for system validation, according to the procedures outlined in FCC KDB 865664 D01v01r04 and IEEE 1528-2013. Since SAR probe calibrations are frequency dependent, each probe calibration point was validated at a frequency within the valid frequency range of the probe calibration point, using the system that normally operates with the probe for routine SAR measurements and according to the required tissue-equivalent media.

A tabulated summary of the system validation status including the validation date(s), measurement frequencies, SAR probes and tissue dielectric parameters has been included.

PERM. COND. **CW Validation** MOD. Validation SAR Frea. Probe Probe Date Probe CAL, Point Probe System [MHz] Type Probe Duty MOD. Type PAR (er)  $(\sigma)$ tivity Linearity Isortopy Factor D 750 2018.10.15 3933 EX3DV4 Head 42.212 0.887 **PASS** PASS PASS N/A N/A D 835 2018.12.10 EX3DV4 835 40.881 0.894 PASS PASS PASS N/A N/A N/A 7337 Head D 1800 2018.12.11 7337 EX3DV4 1800 Head 39.441 1.405 PASS PASS PASS N/A N/A D 1900 PASS 2018.10.18 7337 EX3DV4 1900 39.641 1.415 **PASS PASS** N/A N/A N/A Head D 2450 2018.05.10 3933 EX3DV4 2450 Head 38.885 1.851 PASS PASS PASS OFDM/TDD PASS PASS D 5200 2018.05.14 3933 EX3DV4 5200 Head 35.225 4.717 **PASS** PASS PASS OFDM N/A PASS D 5300 2018.05.15 3933 EX3DV4 5300 Head 34.997 4.822 PASS PASS PASS OFDM N/A PASS D 5500 2018.05.16 3933 EX3DV4 34.678 5.018 PASS PASS PASS OFDM N/A PASS 5500 Head D 5600 2018 05 17 3933 FX3DV4 5600 34 442 5 116 PASS PASS PASS OFDM N/A PASS Head D 5800 2018.05.18 3933 EX3DV4 5800 Head 34.412 5.316 PASS PASS PASS OFDM N/A PASS D 750 2018.10.15 3933 EX3DV4 750 Body 54.650 0.965 PASS PASS PASS N/A N/A N/A Body D 835 2018.10.16 3933 EX3DV4 835 54.597 0.975 PASS PASS PASS N/A N/A N/A D 835 2018.12.10 7337 EX3DV4 835 53.846 0.966 PASS PASS PASS N/A N/A N/A Body D 2018.10.17 3933 EX3DV4 1800 Body 52.381 1.553 PASS PASS PASS N/A D 1900 2018.10.18 3933 EX3DV4 1900 52.289 1.571 PASS PASS PASS N/A N/A N/A Body D 1900 2018 10 18 52 616 PASS 7337 FX3DV4 1900 Body 1.471 PASS PASS N/A N/A N/A D 2450 2018.05.10 EX3DV4 2450 51.770 2.015 PASS PASS PASS OFDM/TDD PASS 3933 Body PASS D 5200 2018.05.14 3933 EX3DV4 5200 Body 48.399 5.467 PASS PASS PASS OFDM PASS D 5300 2018.05.15 3933 EX3DV4 5300 48.089 5.446 PASS PASS PASS OFDM N/A PASS Body D 5500 2018.05.16 3933 EX3DV4 5500 47.642 5.716 PASS PASS PASS OFDM N/A PASS Body D 5600 2018.05.17 3933 EX3DV4 5600 47.304 5.789 PASS PASS PASS OFDM N/A PASS Body

**Table D.1 SAR System Validation Summary** 

NOTE: While the probes have been calibrated for both a CW and modulated signals, all measurements were performed using communication systems calibrated for CW signals only. Modulations in the table above represent test configurations for which the measurement system has been validated per FCC KDB Publication 865664 D01v01r04 for scenarios when CW probe calibrations are used with other signal types. SAR systems were validated for modulated signals with a periodic duty cycle, such as GMSK, or with a high peak to average ratio (>5 dB), such as OFDM according to KDB 865664.

46.946

6.089

PASS

PASS

PASS

OFDM

N/A

PASS

2018.05.18

3933

EX3DV4

5800

D

5800

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# **APPENDIX E. – Description of Test Equipment**

### **E.1 SAR Measurement Setup**

Measurements are performed using the DASY5 automated dosimetric assessment system. The DASY5 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, desktop computer, near-field probe, probe alignment sensor, and the generic twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Fig. E.1.1).

A cell controller system contains the power supply, robot controller each pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the Intel Core i7-3770 3.40 GHz desktop computer with Windows 7 system and SAR Measurement Software DASY5,A/D interface card, monitor, mouse, and keyboard. The Staubli Robotis connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

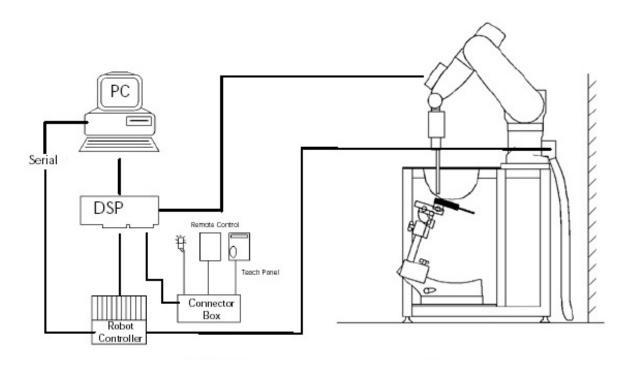


Figure E.1.1 SAR Measurement System Setup

The DAE4 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail.

### **E.2 Probe Specification**

Calibration In air from 10 MHz to 6 GHz

In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1750 MHz, 1900 MHz, 2450 MHz, 2600 MHz,

5200 MHz, 5300 MHz, 5500 MHz, 5600 MHz, 5800 MHz /

750 MHz, 835 MHz, 900 MHz, 1750 MHz, 1900 MHz, 2300 MHz, 2450 MHz, 2600 MHz, 3500 MHz, 3700 MHz, 5200 MHz, 5300 MHz, 5500 MHz, 5600 MHz, 5800 MHz

Frequency 10 MHz to 6 GHz

**Linearity** ± 0.2 dB(30 MHz to 6 GHz)

**Dynamic** 10  $\mu$ W/g to > 100 mW/g

Range Linearity: ±0.2dB

**Dimensions** Overall length: 337 mm

**Tip length** 9 mm

Body diameter 10 mm

Tip diameter 2.5 mm

Distance from probe tip to sensor center 1.0 mm

**Application** SAR Dosimetry Testing

Compliance tests of mobile phones

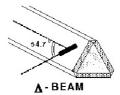


Figure E.2.1 Triangular Probe Configurations



Figure E.2.2 Probe Thick-Film Technique



**DAE System** 

The SAR measurements were conducted with the dosimetric probe EX3DV4 designed in the classical triangular configuration(see E.2.1) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multitier line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped at reaching the maximum.

#### E.3 E-Probe Calibration Process

#### **Dosimetric Assessment Procedure**

Each probe is calibrated according to a dosimetric assessment procedure with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure and found to be better than +/-0.25dB. The sensitivity parameters (Norm X, Norm Y, Norm Z), the diode compression parameter (DCP) and the conversion factor (Conv F) of the probe is tested.

### Free Space Assessment

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 1 GHz, and in a waveguide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity at the proper orientation with the field. The probe is then rotated 360 degrees.

#### **Temperature Assessment \***

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium, correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent the remits or based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

$$SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$$

simulated tissue conductivity,

Tissue density (1.25 g/cm<sup>3</sup> for brain tissue)

where: where:

 $\Delta t$  = exposure time (30 seconds),

C = heat capacity of tissue (brain or muscle),

 $\Delta T$  = temperature increase due to RF exposure.

SAR is proportional to  $\Delta T \, / \, \Delta t$ , the initial rate of tissue heating, before thermal diffusion takes place. Now it's possible to quantify the electric field in the simulated tissue by equating the thermally derived SAR to the E- field;

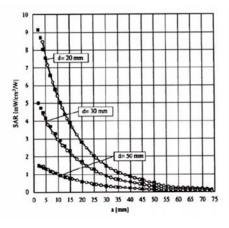


Figure E.3.1 E-Field and Temperature Measurements at 900MHz

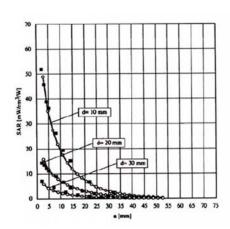


Figure E.3.2 E-Field and Temperature Measurements at 1800MHz



### E.4 Data Extrapolation

The DASY5 software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given like below;

with 
$$V_i = \text{compensated signal of channel i}$$
  $(i=x,y,z)$ 

$$U_i = \text{input signal of channel i}$$
  $(i=x,y,z)$ 

$$U_i = \text{input signal of channel i}$$
  $(i=x,y,z)$ 

$$Cf = \text{crest factor of exciting field}$$
  $(DASY parameter)$ 

$$dcp_i = \text{diode compression point}$$
  $(DASY parameter)$ 

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: with 
$$V_i$$
 = compensated signal of channel i (i = x,y,z)  
Norm<sub>i</sub> = sensor sensitivity of channel i (i = x,y,z)  
 $\mu V/(V/m)^2$  for E-field probes  
ConvF = sensitivity of enhancement in solution  
 $E_i$  = electric field strength of channel i in V/m

The RSS value of the field components gives the total field strength (Hermetian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$
 with SAR = local specific absorption rate in W/g = total field strength in V/m = conductivity in [mho/m] or [Siemens/m]  $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{prox} = \frac{E_{tot}^2}{3770}$$
 with  $P_{pwe} = \text{equivalent power density of a plane wave in W/cm}^2$  = total electric field strength in V/m

#### **E.5 SAM Twin Phantom**

The SAM Twin Phantom V5.0 is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid.

Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. (see Fig. E.5.1)



Figure E.5.1 SAM Twin Phantom

## **SAM Twin Phantom Specification:**

Construction The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin

(SAM) phantom defined in IEEE 1528 and IEC 62209-1. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by teaching

three points with the robot.

Twin SAM V5.0 has the same shell geometry and is manufactured from the same material

as Twin SAM V4.0, but has reinforced top structure.

**Shell Thickness**  $2 \pm 0.2 \text{ mm}$ 

Filling Volume Approx. 25 liters

Dimensions Length: 1000 mm

Width: 500 mm

Height: adjustable feet

### Specific Anthropomorphic Mannequin (SAM) Specifications:

The phantom for handset SAR assessment testing is a low-loss dielectric shell, with shape and dimensions derived from the anthropometric data of the 90th percentile adult male head dimensions as tabulated by the US Army. The SAM Twin Phantom shell is bisected along the mid-sagittal plane into right and left halves (see Fig. E.5.2). The perimeter sidewalls of each phantom halves are extended to allow filling with liquid to a depth that is sufficient to minimized reflections from the upper surface. The liquid depth is maintained at a minimum depth of 15cm to minimize reflections from the upper surface.



Figure E.5.2 Sam Twin Phantom shell



#### **E.6 Device Holder for Transmitters**

In combination with the Twin SAM Phantom V4.0/V4.0c, V5.0 or ELI4, the Mounting Device enables the rotation of the mounted transmitter device in spherical coordinates. Rotation point is the ear opening point. Transmitter devices can be easily and accurately positioned according to IEC, IEEE, FCC or other specifications. The device holder can be locked for positioning at different phantom sections (left head, right head, flat).

Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.



Figure E.6.1 Mounting Device



# **E.7 Automated Test System Specifications**

## **Positioner**

Robot Stäubli Unimation Corp. Robot Model: TX90XL

Repeatability 0.02 mm

No. of axis 6

# **Data Acquisition Electronic (DAE) System**

Cell Controller

**Processor** Intel Core i7-3770

Clock Speed 3.40 GHz

Operating System Windows 7 Professional DASY5 PC-Board

**Data Converter** 

Features Signal, multiplexer, A/D converter. & control logic

Software DASY5

**Connecting Lines** Optical downlink for data and status info

Optical uplink for commands and clock

**PC Interface Card** 

**Function** 24 bit (64 MHz) DSP for real time processing

Link to DAE 4

16 bit A/D converter for surface detection system

serial link to robot

direct emergency stop output for robot

**E-Field Probes** 

ModelEX3DV4 S/N: 7337 / EX3DV4 S/N: 3933ConstructionTriangular core fiber optic detection system

Frequency 10 MHz to 6 GHz

**Linearity**  $\pm$  0.2 dB (30 MHz to 6 GHz)

**Phantom** 

**Phantom** SAM Twin Phantom (V5.0)

Shell Material Composite
Thickness 2.0 ± 0.2 mm



Figure E.7.1 DASY5 Test System