CETECOM ICT Services GmbH

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Accredited testing laboratory

DAR registration number: DAT-P-176/94-D1

Test report no. : 2-4506-01-04/06
Type identification : Discus Dual Phone
Test specification : IEEE P1528/D1.2
FCC-ID : U2K151060001
IC-ID : 6930A-1510600

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Test report no.: 2-4506-01-04/06



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1 General Information

1.1 Notes

The test results of this test report relate exclusively to the test item specified in 1.5. The CETECOM ICT Services GmbH does not assume responsibility for any conclusions and generalisations drawn from the test results with regard to other specimens or samples of the type of the equipment represented by the test item. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of the CETECOM ICT Services GmbH.

1.1.1 Statement of Compliance

The SAR values found for the Discus Dual Phone **GSM/Wi-Fi Dual mode phone** are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C 95.1:1999, the NCRP Report Number 86 for uncontrolled environment, according to the Health Canada's Safety Code 6 and the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure.

For body worn operation, this phone has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal and that positions the handset a minimum of 15 mm from the body. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The measurement together with the test system set-up is described in chapter 2.3 of this test report. A detailed description of the equipment under test can be found in chapter 1.5.

Test engineer:

2007-02-09 Oleksandr Hnatovskiy

Date Name Signature

Technical responsibility for area of testing:

2007-02-09 Thomas Vogler

Date Name Signature

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Thomas Vogt

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1.2 Testing laboratory

CETECOM ICT Services GmbH Untertuerkheimer Straße 6-10, 66117 Saarbruecken

Germany

Telephone: + 49 681 598 - 0 Fax: + 49 681 598 - 8475

e-mail: <u>info@ict.cetecom.de</u>
Internet: <u>http://www.cetecom-ict.de</u>

State of accreditation: The Test laboratory (area of testing) is accredited according to DIN EN

ISO/IEC 17025. DAR registration number: DAT-P-176/94-D1

Test location, if different from CETECOM ICT Services GmbH

Name: --Street: --Town: --Country: --Phone: --Fax: ---

1.3 Details of applicant

Name: Pirelli Broadband Solutions S.p.A.

Street: Viale Sarca 336 Town: 20126 Milano

Country: Italy

Contact: Mr. Massimo Lo Iacono Telephone: +39 (0) 2 64 42 93 78

1.4 Application details

Date of receipt of application: 2006-12-06
Date of receipt of test item: 2006-12-12
Start/Date of test: 2006-12-12
End of test: 2007-02-07

Person(s) present during the test: ---

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1.5 Test item

Description of the test item: GSM/Wi-Fi Dual mode phone

Type identification:

FCC-ID:

U2K151060001

IC-ID:

6930A-1510600

Serial number:

0017C2EFBC45

Manufacturer:

Name: Pirelli Broadband Solutions S.p.A.

Street: Viale Sarca 336 Town: 20126 Milano

Country: Italy

| additional information on the DUT: | | | | | 1 | |
|--------------------------------------|---|-------------|--------|---------------|-----------|--|
| additional information on the DOT. | | | | | | |
| device type : | portable device | | | | | |
| IMEI No: | 3527890100590 |)9-7 | | | | |
| exposure category: | uncontrolled environment / general population | | | | | |
| test device production information | serial production unit | | | | | |
| 1 | | | | | | |
| device operating configurations: | | | | | | |
| operating mode(s) | GSM, DCS, PC | S, WLAN IEI | EE 80 | 02.11 b/g | | |
| modulation | GMSK, DSSS, | OFDM | | | | |
| GPRS mobile station class: | В | | | | | |
| GPRS multislot class: | voice mode : | | | | | |
| EGPRS multislot class | voice mode : | | | | | |
| maximum no. of timeslots in uplink : | | | | | | |
| operating frequency range(s) | PCS 1900 | IEEE 802.1 | 1 | DCS 1800 | GSM 900 | |
| | (tested) | b and g | | | | |
| | | (tested) | | | | |
| - transmitter frequency range : | 1850.2 MHz ~ | | | 1710 MHz ~ | 880 MHz ~ | |
| | 1909.8 MHz | 2462 MH | Z | 1785 MHz | 915 MHz | |
| - receiver frequency range : | 1930.2 MHz ~ | | | 1805 MHz ~ | 925 MHz ~ | |
| D 1 CCC 1 | 1989.8 MHz | 1 10/ | 1000 | 1880 MHz | 960 MHz | |
| Power class GSM: | 1, tested with po | | | | | |
| measured peak output power | 2450 band: 19. | | 8), 21 | 1.2 dBm (OFD) | M) | |
| (conducted): | 1900 band: 28.6 | | | | | |
| test channels (low – mid – high): | 1 (2450 MHz ba | / | | | | |
| 1 1 . | 661 (1900 MHz | z bana) | | | | |
| hardware version: | 715_02 | | | | | |
| software version : | 3.98 | | | | | |
| antenna type : | Integrated antenna | | | | | |
| accessories / | Headset with earphone / microphone | | | | | |
| body-worn configurations: | Rechargeable Li-ion battery 3.7V; 1050mAh | | | | | |
| battery options : | S/N: SYWDA6 | - |)./V; | 1030mAn | | |
| | S/N. SI WDA0 | 3/1/300 | | | | |

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1.6 Test specification(s)

Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01)

IEEE P1528/D1.2 (April 21, 2003)

RSS-102: Radio Frequency Exposure Compliance of Radiocommunication Apparatus (All Frequency Bands (Issue 2 of November 2005)

Canada's Safety Code 6: Limits of Human Exposure to Radiofrequency Electromagnetic Fields in the Frequency Range from 3 kHz to 300 GHz (99-EHD-237)

IEEE Std C95.3 – 1991, IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave.

IEEE Std C95.1 – 1999, IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz – 300 GHz.

1.6.1 RF exposure limits

| Human Exposure | Uncontrolled Environment General Population | Controlled Environment Occupational |
|--|--|--|
| Spatial Peak SAR* (Brain) | 1.60 mW/g | 8.00 mW/g |
| Spatial Average SAR** (Whole Body) | $0.08~\mathrm{mW/g}$ | 0.40 mW/g |
| Spatial Peak SAR*** (Hands/Feet/Ankle/Wrist) | 4.00 mW/g | 20.00 mW/g |

Table 1: RF exposure limits

The limit applied in this test report is shown in **bold** letters

Notes:

- * The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time
- ** The Spatial Average value of the SAR averaged over the whole body.
- *** The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

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2 Technical test

2.1 Summary of test results

| No deviations from the technical specification(s) were ascertained in the course of the tests performed. | \boxtimes |
|--|-------------|
| The deviations as specified in 2.5 were ascertained in the course of the tests performed. | |

2.2 Test environment

General Environment conditions in the test area are as follows:

Ambient temperature: $20^{\circ}\text{C} - 24^{\circ}\text{C}$ Tissue simulating liquid: $20^{\circ}\text{C} - 24^{\circ}\text{C}$ Humidity: 40% - 50%

Exact temperature values for each test are shown in the table(s) under 2.5. and/or on the measurement plots.

2.3 Measurement and test set-up

The measurement system is described in chapter 2.4.

The test setup for the system validation can be found in chapter 2.4.14.

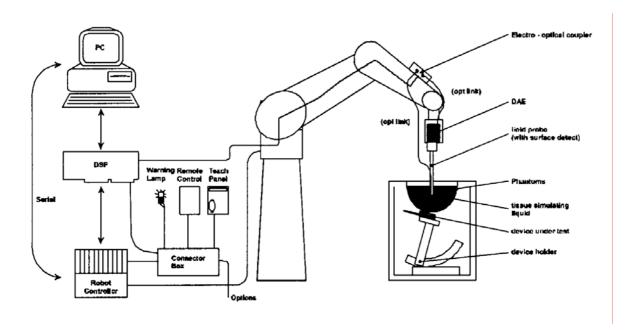
A description of positioning and test signal control can be found in chapter 2.5 together with the test results.

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2.4 Measurement system

2.4.1 System Description



The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- A unit to operate the optical surface detector which is connected to the EOC.
- The <u>Electro-Optical Coupler (EOC)</u> performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY4 measurement server.
- The DASY4 measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 2000
- DASY4 software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- System validation dipoles allowing to validate the proper functioning of the system.

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2.4.2 Test environment

The DASY4 measurement system is placed at the head end of a room with dimensions:

 $5 \times 2.5 \times 3 \text{ m}^3$, the SAM phantom is placed in a distance of 75 cm from the side walls and 1.1m from the rear wall. Above the test system a 1.5 x 1.5 m² array of pyramid absorbers is installed to reduce reflections from the ceiling.

Picture 1 of the photo documentation shows a complete view of the test environment.

The system allows the measurement of SAR values larger than 0.005 mW/g.

2.4.3 Probe description

Isotropic E-Field Probe ET3DV6 for Dosimetric Measurements

| Technical data accor | rding to manufacturer information |
|---------------------------|---|
| Construction | Symmetrical design with triangular core |
| | Built-in optical fiber for surface detection system |
| | Built-in shielding against static charges |
| | PEEK enclosure material (resistant to organic |
| | solvents, e.g., glycolether) |
| Calibration | In air from 10 MHz to 2.5 GHz |
| | In head tissue simulating liquid (HSL) at 900 (800- |
| | 1000) MHz and 1.8 GHz (1700-1910 MHz) |
| | (accuracy \pm 9.5%; k=2) Calibration for other liquids |
| | and frequencies upon request |
| Frequency | 10 MHz to 3 GHz (dosimetry); Linearity: ± 0.2 dB |
| | (30 MHz to 3 GHz) |
| Directivity | \pm 0.2 dB in HSL (rotation around probe axis) |
| | \pm 0.4 dB in HSL (rotation normal to probe axis) |
| Dynamic range | $5 \mu W/g \text{ to} > 100 \text{ mW/g}$; Linearity: $\pm 0.2 \text{ dB}$ |
| Optical Surface Detection | \pm 0.2 mm repeatability in air and clear liquids over |
| | diffuse reflecting surfaces (ET3DV6 only) |
| Dimensions | Overall length: 330 mm |
| | Tip length: 16 mm |
| | Body diameter: 12 mm |
| | Tip diameter: 6.8 mm |
| | Distance from probe tip to dipole centers: 2.7 mm |
| Application | General dosimetry up to 3 GHz |
| | Compliance tests of mobile phones |
| | Fast automatic scanning in arbitrary phantoms (ET3DV6) |

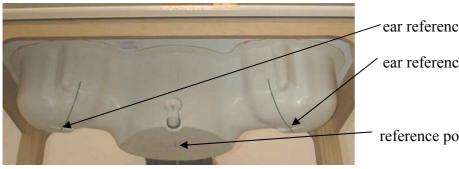
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2.4.4 Phantom description

The used SAM Phantom meets the requirements specified in Edition 01-01 of Supplement C to OET Bulletin 65 for Specific Absorption Rate (SAR) measurements.

The phantom consists of a fibreglass shell integrated in a wooden table. It allows left-hand and right-hand head as well as body-worn measurements with a maximum liquid depth of 18 cm in head position and 22 cm in planar position (body measurements). The thickness of the Phantom shell is 2 mm +/- 0.1 mm.



ear reference point right hand side

ear reference point left hand side

reference point flat position

2.4.5 Device holder description

The DASY4 device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.



Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values.

Therefore those devices are normally only tested at the flat part of the SAM.

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2.4.6 Scanning procedure

The DASY4 installation includes predefined files with recommended procedures for measurements and validation. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.

- The "reference" and "drift" measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT's output power and should vary max. +/- 5 %.
- The "surface check" measurement tests the optical surface detection system of the DASY4 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above \pm 0.1mm). To prevent wrong results tests are only executed when the liquid is free of air bubbles. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within \pm 30°.)
- The "area scan" measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strenth is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The standard scan uses large grid spacing for faster measurement. Standard grid spacing for head measurements is 15 mm in x- and y- dimension. If a finer resolution is needed, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation. Results of this coarse scan are shown in annex 2.
- A "7x7x7 zoom scan" measures the field in a volume around the 2D peak SAR value acquired in the previous "coarse" scan. This is a fine 7x7 grid where the robot additionally moves the probe in 7 steps along the z-axis away from the bottom of the Phantom. Grid spacing for the cube measurement is 5 mm in x and y-direction and 5 mm in z-direction. DASY4 is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in annex 2. Test results relevant for the specified standard (see chapter 1.6.) are shown in table form in chapter 2.5.
- A Z-axis scan measures the total SAR value at the x-and y-position of the maximum SAR value found during the cube 7x7x7 scan. The probe is moved away in z-direction from the bottom of the SAM phantom in 2mm steps. This measurement shows the continuity of the liquid and can depending in the field strength also show the liquid depth. A z-axis scan of the measurement with maximum SAR value is shown in annex 2.

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2.4.7 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of 7 x 7 x 7 points. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.
- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.
- All neighboring volumes are evaluated until no neighboring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

Advanced Extrapolation

DASY4 uses the advanced extrapolation option which is able to compansate boundary effects on E-field probes.

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2.4.8 Data Storage and Evaluation

Data Storage

The DASY4 software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

Device parameters:

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

| Probe para | meters: - S | ensitivity | Norm | $a_{i}, a_{i0}, a_{i1}, a_{i2}$ |
|------------|-------------|------------|------|---------------------------------|
|------------|-------------|------------|------|---------------------------------|

 $\begin{array}{lll} \text{- Conversion factor} & \text{ConvF}_i \\ \text{- Diode compression point} & \text{Dcpi} \\ \text{- Frequency} & \text{f} \end{array}$

- Crest factor cf

Media parameters: - Conductivity σ

- Density ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY4 components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.

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If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

with V_i = compensated signal of channel i (i = x, y, z) U_i = input signal of channel i (i = x, y, z)

cf = crest factor of exciting field (DASY parameter) dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $E_i = (V_i / Norm_i \cdot ConvF)^{1/2}$

H-field probes: $H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$

with V_i = compensated signal of channel i (i = x, y, z)

Norm_i = sensor sensitivity of channel i (i = x, y, z)

 $[mV/(V/m)^2]$ for E-field Probes

ConvF = sensitivity enhancement in solution

 a_{ij} = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

 E_i = electric field strength of channel i in V/m H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^2 + E_y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^2 \cdot \sigma) / (\rho \cdot 1000)$$

with SAR = local specific absorption rate in mW/g

 E_{tot} = total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m]

 ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{\text{pwe}} = E_{tot}^2 / 3770$$
 or $P_{\text{pwe}} = H_{tot}^2 \cdot 37.7$

with P_{nwe} = equivalent power density of a plane wave in mW/cm²

 E_{tot} = total electric field strength in V/m H_{tot} = total magnetic field strength in A/m

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2.4.9 Test equipment utilized

This table gives a complete overview of the SAR measurement equipment

Devices used during the test described in chapter 2.5. are marked \boxtimes

| | Manufacturer | Device | Туре | Serial number | Date of last calibration)* |
|-------------|------------------------------------|---|---------------------|---------------|-----------------------------|
| | Schmid & Partner Engineering AG | Dosimetric E-Field Probe | ET3DV6 | 1558 | August 30, 2006 |
| | Schmid & Partner Engineering AG | Dosimetric E-Field Probe | ET3DV6 | 1559 | January 19, 2006 |
| | Schmid & Partner Engineering AG | 900 MHz System Validation Dipole | D900V2 | 102 | August 18, 2006 |
| | Schmid & Partner Engineering AG | 1800 MHz System Validation Dipole | D1800V2 | 287 | August 22, 2006 |
| | Schmid & Partner Engineering AG | 1900 MHz System Validation Dipole | D1900V2 | 5d009 | August 16, 2006 |
| | Schmid & Partner Engineering AG | 2450 MHz System Validation Dipole | D2450V2 | 710 | August 21, 2006 |
| | Schmid & Partner Engineering AG | Data acquisition electronics | DAE3V1 | 413 | January 12, 2006 |
| | Schmid & Partner Engineering AG | Software | DASY 4 V4.5 | | N/A |
| | Schmid & Partner Engineering AG | Phantom | SAM | | N/A |
| | Rohde & Schwarz | Universal Radio Communication Tester | CMU 200 | 832221/0055 | January 12, 2006 |
| | Agilent | Network Analyser 300 kHz to 3 GHz | 8753C | 2936A00872 | July 15, 2004 |
| | Agilent | Dielectric Probe Kit | 85070C | US99360146 | N/A |
| | Agilent | Peak Power Analyzer | 8990A | 3128A00169 | August 23, 2005 |
| | Agilent | Peak Power Sensor | 84813A | 3125A00111 | August 25, 2005 |
| | Agilent | Signal Generator | 8665A | 2833A00112 | November 08, 2005 |
| | Amplifier Reasearch | Amplifier | 25S1G4 (25 Watt) | 20452 | N/A |
| \boxtimes | Agilent | Power Meter | 438A | 2804U01006 | February 4, 2006 |
| \boxtimes | Agilent | Power Meter Sensor | 8482A | 2703A03025 | February 4, 2006 |

^{)* :} Network analyzer probe calibration against air, destilled water and a 50 Ohm resistor performed before measuring liquid parameters.

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2.4.10 Tissue simulating liquids: dielectric properties

The following materials are used for producing the tissue-equivalent materials.

(liquids used for tests described in chapter 2.5. are marked with \boxtimes):

| Ingredients | Frequency (MHz) | | | | | | | |
|----------------|-----------------|-------|-------|-------------|--------|---------------|--|--|
| (% of weight) | | | | | | | | |
| frequency band | <u>450</u> | 835 | 900 | 1800 | ∑ 1900 | ≥ 2450 | | |
| Tissue Type | Head | Head | Head | Head | Head | Head | | |
| Water | 38.56 | 41.45 | 40.92 | 52.64 | 54.9 | 62.7 | | |
| Salt (NaCl) | 3.95 | 1.45 | 1.48 | 0.36 | 0.18 | 0.5 | | |
| Sugar | 56.32 | 56.0 | 56.5 | 0.0 | 0.0 | 0.0 | | |
| HEC | 0.98 | 1.0 | 1.0 | 0.0 | 0.0 | 0.0 | | |
| Bactericide | 0.19 | 0.1 | 0.1 | 0.0 | 0.0 | 0.0 | | |
| Triton X-100 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 36.8 | | |
| DGBE | 0.0 | 0.0 | 0.0 | 47.0 | 44.92 | 0.0 | | |

Table 2: Head tissue dielectric properties

| Ingredients (% of weight) | Frequency (MHz) | | | | | | | |
|---------------------------|-----------------|------|-------|----------|--------|---------------|--|--|
| frequency band | <u>450</u> | 835 | 900 | <u> </u> | X 1900 | ≥ 2450 | | |
| Tissue Type | Body | Body | Body | Body | Body | Body | | |
| Water | 51.16 | 52.4 | 56.0 | 69.91 | 69.91 | 73.2 | | |
| Salt (NaCl) | 1.49 | 1.40 | 0.76 | 0.13 | 0.13 | 0.04 | | |
| Sugar | 46.78 | 45.0 | 41.76 | 0.0 | 0.0 | 0.0 | | |
| HEC | 0.52 | 1.0 | 1.21 | 0.0 | 0.0 | 0.0 | | |
| Bactericide | 0.05 | 0.1 | 0.27 | 0.0 | 0.0 | 0.0 | | |
| Triton X-100 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | | |
| DGBE | 0.0 | 0.0 | 0.0 | 29.96 | 29.96 | 26.7 | | |

Table 3: Body tissue dielectric properties

Salt: 99+% Pure Sodium Chloride Sugar: 98+% Pure Sucrose Water: De-ionized, $16M\Omega$ + resistivity HEC: Hydroxyethyl Cellulose

DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]

Triton X-100(ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

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2.4.11 Tissue simulating liquids: parameters

| Used Target Frequency | 8 | | | Measured Date | |
|--------------------------|--------------|--------------|--------------|------------------|------------|
| [MHz] | Permittivity | Conductivity | Permittivity | Conductivity | Date |
| | | [S/m] | _ | [S/m] | |
| 1900 | 40.0 | 1.40 | 39.3 | 1.37 | 2006-12-12 |
| 2450 | 39.0 | 1.84 | 37.9 | 1.86 | 2006-02-07 |

Table 4: Parameter of the head tissue simulating liquid

| Used Target | Target | | Meas | Measured | | |
|--------------------|--------------|--------------|-----------------------------|--------------|------------|------|
| Frequency | Body Tissue | | nency Body Tissue Body Tiss | | Tissue | Date |
| [MHz] | Permittivity | Conductivity | Permittivity | Conductivity | | |
| | - | [S/m] | _ | [S/m] | | |
| 1900 | 53.3 | 1.52 | 52.9 | 1.52 | 2006-12-12 | |
| 2450 | 52.7 | 1.95 | 52.3 | 2.04 | 2006-02-07 | |

Table 5: Parameter of the body tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 21.1°C.

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2.4.12 Measurement uncertainty evaluation for SAR test

The overall combined measurement uncertainty of the measurement system is \pm 10,3% (K=1). The expanded uncertainty (k=2) is assessed to be \pm 20.6%

This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

| Error Sources | Uncertainty Value | Probability Distribution | Divi- sor | c _i | c _i 10g | Standard Uncertainty 1g | Standard Uncertainty 10g | v _i ² or v _{eff} |
|----------------------------------|----------------------|-----------------------------|--------------|----------------|-----------------------|-------------------------------|--------------------------------|--|
| Measurement System | | | | | | | | |
| Probe calibration | ± 4.8% | Normal | 1 | 1 | 1 | ± 4.8% | ± 4.8% | ∞ |
| Axial isotropy | ± 4.7% | Rectangular | √3 | 0.7 | 0.7 | ± 1.9% | ± 1.9% | ∞ |
| Hemispherical isotropy | ± 9.6% | Rectangular | √3 | 0.7 | 0.7 | ± 3.9% | ± 3.9% | ∞ |
| Spatial resolution | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| Boundary effects | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | 8 |
| Probe linearity | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | 8 |
| System detection limits | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Readout electronics | ± 1.0% | Normal | 1 | 1 | 1 | ± 1.0% | ± 1.0% | ∞ |
| Response time | ± 0.8% | Rectangular | √3 | 1 | 1 | ± 0.5% | ± 0.5% | ∞ |
| Integration time | ± 2.6% | Rectangular | √3 | 1 | 1 | ± 1.5% | ± 1.5% | ∞ |
| RF ambient conditions | ± 3.0% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Probe positioner | ± 0.4% | Rectangular | √3 | 1 | 1 | ± 0.2% | ± 0.2% | 8 |
| Probe positioning | ± 2.9% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | 8 |
| Max. SAR evaluation | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | 8 |
| Test Sample Related | | | | | | | | |
| Device positioning | ± 2.9% | Normal | 1 | 1 | 1 | ± 2.9% | ± 2.9% | 145 |
| Device holder uncertainty | ± 3.6% | Normal | 1 | 1 | 1 | ± 3.6% | ± 3.6% | 5 |
| Power drift | ± 5.0% | Rectangular | √3 | 1 | 1 | ± 2.9% | ± 2.9% | 8 |
| Phantom and Set-up | | | | | | | | |
| Phantom uncertainty | ± 4.0% | Rectangular | √3 | 1 | 1 | ± 2.3% | ± 2.3% | ∞ |
| Liquid conductivity (target) | ± 5.0% | Rectangular | √3 | 0.64 | 0.43 | ± 1.8% | ± 1.2% | ∞ |
| Liquid conductivity (meas.) | ± 2.5% | Normal | 1 | 0.64 | 0.43 | ± 1.6% | ± 1.1% | ∞ |
| Liquid permittivity (target) | ± 5.0% | Rectangular | √3 | 0.6 | 0.49 | ± 1.7% | ± 1.4% | 8 |
| Liquid permittivity (meas.) | ± 2.5% | Normal | 1 | 0.6 | 0.49 | ± 1.5% | ± 1.2% | 8 |
| Combined Uncertainty | | | | | | ± 10.3% | ± 10.0% | 330 |
| Expanded Std. Uncertainty | | | | | | ± 20.6% | ± 20.1% | |

Table 6: Measurement uncertainties

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2.4.13 Measurement uncertainty evaluation for system validation

The overall combined measurement uncertainty of the measurement system is \pm 8.4% (K=1).

The expanded uncertainty (k=2) is assessed to be \pm 16.8%

This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

| Error Sources | Uncertainty Value | Probability Distribution | Divi- sor | c _i | c _i 10g | Standard Uncertainty 1g | Standard Uncertainty 10g | v _i ² or v _{eff} |
|----------------------------------|----------------------|-----------------------------|--------------|----------------|-----------------------|-------------------------------|--------------------------------|---|
| Measurement System | | | | | | | | |
| Probe calibration | ± 4.8% | Normal | 1 | 1 | 1 | ± 4.8% | ± 4.8% | ∞ |
| Axial isotropy | ± 4.7% | Rectangular | √3 | 0.7 | 0.7 | ± 1.9% | ± 1.9% | ∞ |
| Hemispherical isotropy | ± 0.0% | Rectangular | $\sqrt{3}$ | 0.7 | 0.7 | ± 0.0% | ± 3.9% | ∞ |
| Boundary effects | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Probe linearity | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| System detection limits | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Readout electronics | ± 1.0% | Normal | 1 | 1 | 1 | ± 1.0% | ± 1.0% | ∞ |
| Response time | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| Integration time | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| RF ambient conditions | ± 3.0% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Probe positioner | ± 0.4% | Rectangular | √3 | 1 | 1 | ± 0.2% | ± 0.2% | ∞ |
| Probe positioning | ± 2.9% | Rectangular | $\sqrt{3}$ | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Max. SAR evaluation | ± 1.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Test Sample Related | | | | | | | | |
| Dipole axis to liquid distance | ± 2.0% | Normal | 1 | 1 | 1 | ± 1.2% | ± 1.2% | ∞ |
| Power drift | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| Phantom and Set-up | | | | | | | | |
| Phantom uncertainty | ± 4.0% | Rectangular | √3 | 1 | 1 | ± 2.3% | ± 2.3% | ∞ |
| Liquid conductivity (target) | ± 5.0% | Rectangular | √3 | 0.64 | 0.43 | ± 1.8% | ± 1.2% | ∞ |
| Liquid conductivity (meas.) | ± 2.5% | Normal | 1 | 0.64 | 0.43 | ± 1.6% | ± 1.1% | ∞ |
| Liquid permittivity (target) | ± 5.0% | Rectangular | $\sqrt{3}$ | 0.6 | 0.49 | ± 1.7% | ± 1.4% | ∞ |
| Liquid permittivity (meas.) | ± 2.5% | Normal | 1 | 0.6 | 0.49 | ± 1.5% | ± 1.2% | ∞ |
| Combined Uncertainty | | | | | | ± 8.4% | ± 8.1% | |
| Expanded Std. Uncertainty | | | | | _ | ± 16.8% | ± 16.2% | |

Table 7: Measurement uncertainties

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2.4.14 System validation

The system validation is performed for verifying the accuracy of the complete measurement system and performance of the software. The system validation is performed with tissue equivalent material according to IEEE P1528 (described above). The following table shows validation results for all frequency bands and tissue liquids used during the tests of the test item described in chapter 1.5. (graphic plot(s) see annex 1).

| Validation Kit | Frequency | Target Peak SAR (1000 mW) (+/- 10%) | Target SAR _{1g} (1000 mW) (+/- 10%) | Measured Peak SAR | Measured SAR _{1g} | Measured date |
|-----------------------|------------------|--|--|----------------------|-------------------------------|------------------|
| D1900V2 S/N: 5d009 | 1900 MHz head | 64.8 mW/g | 38.4 mW/g | 67.8 mW/g | 38.6 mW/g | 2006-12-12 |
| D1900V2 S/N: 5d009 | 1900 MHz body | 68.4 mW/g | 38.9 mW/g | 64.7 mW/g | 38.4 mW/g | 2006-12-12 |
| D2450V2 S/N: 710 | 2450 MHz head | 120.0 mW/g | 56.0 mW/g | 131.7 mW/g | 60.4 mW/g | 2007-02-07 |
| D2450V2 S/N: 710 | 2450 MHz body | 114.0 mW/g | 53.4 mW/g | 124.5 mW/g | 57.2 mW/g | 2006-02-07 |

Table 8: Results system validation

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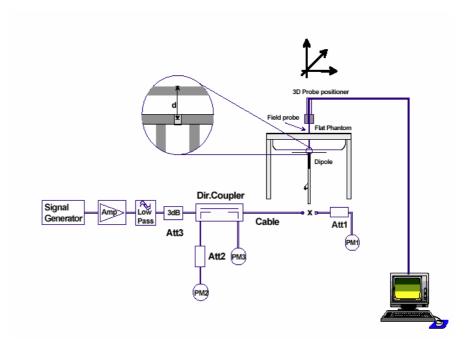


2.4.15 Validation procedure

The validation is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 1000 mW. To adjust this power a power meter is used. The power sensor is connected to the cable before the validation to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).

Validation results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.





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2.5 Test results (Head and Body SAR)

| The table contains the measured SAR values averaged over a mass of 1 g | | | | | | |
|--|------------|--------------------|---------------------|----------|--------------------|--|
| Channel / frequency | Position | Left hand position | Right hand position | Limit | Liquid temperature | |
| 661 / 1880.0 MHz | cheek | 0.210 W/kg | 0.304 W/kg | 1.6 W/kg | 20.1/20.2 °C | |
| 661 / 1880.0 MHz | tilted 15° | 0.185 W/kg | 0.228 W/kg | 1.6 W/kg | 20.1/20.1 °C | |
| 512 / 1850.2 MHz | cheek | not necessary | not necessary | 1.6 W/kg | °C | |
| 810 / 1909.8 MHz | cheek | not necessary | not necessary | 1.6 W/kg | °C | |

Table 9: Test results (Head SAR 1900 MHz)

Note: The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least 3.0 dB lower than the SAR limit (< 0.8 W/kg), testing at the high and low channels is optional.

| The table contains the measured SAR values averaged over a mass of 1 g | | | | | |
|--|----------|-------------------|----------|--------------------|--|
| Channel / frequency | Position | Body worn | Limit | Liquid temperature | |
| 661 / 1880.0 MHz | front | 0.117 W/kg | 1.6 W/kg | 20.0 °C | |
| 661 / 1880.0 MHz | rear | 0.534 W/kg | 1.6 W/kg | 20.1 °C | |
| 512 / 1850.2 MHz | rear | not necessary | 1.6 W/kg | | |
| 810 / 1909.8 MHz | rear | not necessary | 1.6 W/kg | | |

Table 10: Test results (Body SAR 1900 MHz)

Note: The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least $3.0~\mathrm{dB}$ lower than the SAR limit ($< 0.8~\mathrm{W/kg}$), testing at the high and low channels is optional.

Tests in body position were performed with 15 mm air gap between DUT and SAM to simulate the use of a non-metallic belt-clip or holster.

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| The table contains the measured SAR values averaged over a mass of 1 g | | | | | | |
|--|------------|--------------------|---------------------|----------|--------------------|--|
| Channel / frequency | Position | Left hand position | Right hand position | Limit | Liquid temperature | |
| 6 / 2437 MHz | cheek | 0.006 W/kg | 0.004 W/kg | 1.6 W/kg | 20.9/21.2 °C | |
| 6 / 2437 MHz | tilted 15° | 0.004 W/kg | 0.003 W/kg | 1.6 W/kg | 21.0/21.1 °C | |
| 1 / 2412 MHz | cheek | not necessary | not necessary | 1.6 W/kg | °C | |
| 11 / 2462 MHz | cheek | not necessary | not necessary | 1.6 W/kg | °C | |

Table 11: Test results (Head SAR 2450 MHz)

Note: The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least 3.0 dB lower than the SAR limit (< 0.8 W/kg), testing at the high and low channels is optional.

| The table contains the measured SAR values averaged over a mass of 1 g | | | | | |
|--|----------|---------------|----------|--------------------|--|
| Channel / frequency | Position | Body worn | Limit | Liquid temperature | |
| 6 / 2437 MHz | front | 0.0003 W/kg | 1.6 W/kg | 21.4°C | |
| 6 / 2437 MHz | rear | 0.002 W/kg | 1.6 W/kg | 21.5°C | |
| 1 / 2412 MHz | rear | not necessary | 1.6 W/kg | | |
| 11 / 2462 MHz | rear | not necessary | 1.6 W/kg | | |

Table 12: Test results (Body SAR 2450 MHz)

Note: The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least 3.0 dB lower than the SAR limit (< 0.8 W/kg), testing at the high and low channels is optional.

Tests in body position were performed with 15 mm air gap between DUT and SAM to simulate the use of a non-metallic belt-clip or holster.

2.5.1 General description of test procedures

In GSM mode the DUT is tested using a CMU 200 communications tester as controller unit to set test channels and maximum output power to the DUT, as well as for measuring the conducted peak power.

Test positions as described in the tables above are in accordance with the specified test standard.

Tests in body position are performed with the maximum number of timeslots in uplink.

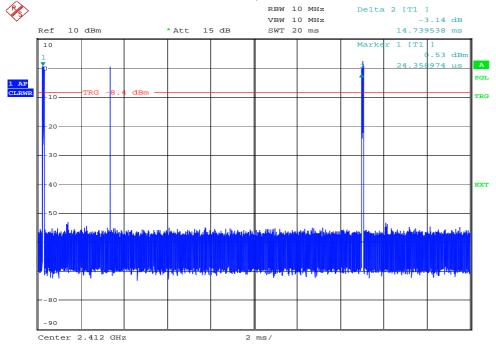
Tests in head position are performed in voice mode with 1 timeslot unless GPRS/EGPRS function allows parallel voice and data traffic on 2 or more timeslots (see chapter 1.5 for details).

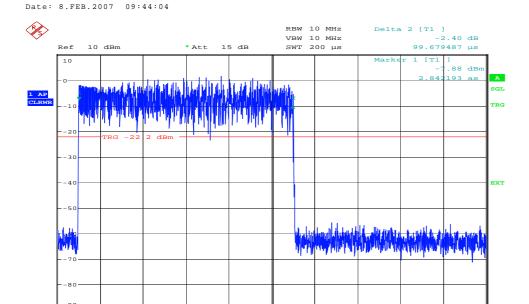
Conducted output power was measured using an integrated RF connector and attached RF cable.

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In WLAN mode the device was tested after setting up a standard voice call in 802.11b mode (DSSS) as a special test mode for higher duty cycles was not available. The shape of the signal was as follows (plots created with Rohde & Schwarz FSU50):





Date: 8.FEB.2007 09:46:23

Center 2.412 GHz

Speech data packets of 0.1 ms at a pulse length of 14 ms (duty cycle about 1: 140) result in an average output power < 1 mW causing SAR values close to noise level of the measurement system.

The test was performed on channel 1 (highest conducted output power in 802.11b mode).

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2.6 Test results (conducted power measurement)

For the measurements a Rohde & Schwarz Radio Communication Tester CMU 200 was used. WLAN mode was tested with a Rohde & Schwarz FSU50 (see Part 15.247 test report). The output power was measured using an integrated RF connector and attached RF cable. The conducted output power was measured before and after each SAR measurement. The resulting power values were within a 0.2 dB tolerance of the values shown below.

| PCS 1900 | | | | |
|-----------|------------|--|--|--|
| Channel | peak power | | | |
| 661 | 28.6 dBm | | | |
| WLAN 2450 | | | | |
| Channel | peak power | | | |
| 1 (DSSS) | 19.1 dBm | | | |
| 1 (OFDM) | 21.2 dBm | | | |

Table 13: Test results conducted peak power measurement

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Annex 1 System performance verification

Date/Time: 2006-12-12 10:13:58Date/Time: 2006-12-12 10:18:00

SystemPerformanceCheck-D1900 head 2006-12-12

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 5d009

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL1900 Medium parameters used (interpolated): f = 1900 MHz; $\sigma = 1.37 \text{ mho/m}$; $\varepsilon_r = 39.3$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.86, 4.86, 4.86); Calibrated: 2006-08-30

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn413; Calibrated: 2006-01-12

- Phantom: SAM 12; Type: SAM; Serial: 1043

- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 47.5 mW/g

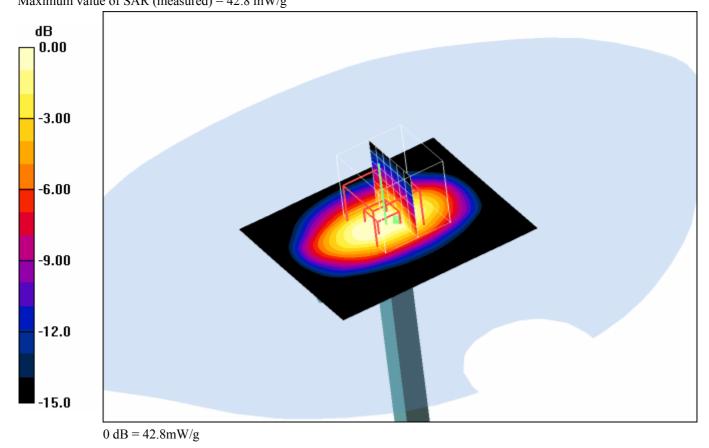
d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 181.5 V/m; Power Drift = 0.014 dB

Peak SAR (extrapolated) = 67.8 W/kg

SAR(1 g) = 38.6 mW/g; SAR(10 g) = 20.2 mW/gMaximum value of SAR (measured) = 42.8 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 20.4°C; liquid temperature: 20.0°C

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Date/Time: 2006-12-12 12:36:57Date/Time: 2006-12-12 12:40:59

SystemPerformanceCheck-D1900 body 2006-12-12

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 5d009

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: M1900 Medium parameters used (interpolated): f = 1900 MHz; $\sigma = 1.52 \text{ mho/m}$; $\epsilon_r = 52.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.44, 4.44, 4.44); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 47.5 mW/g

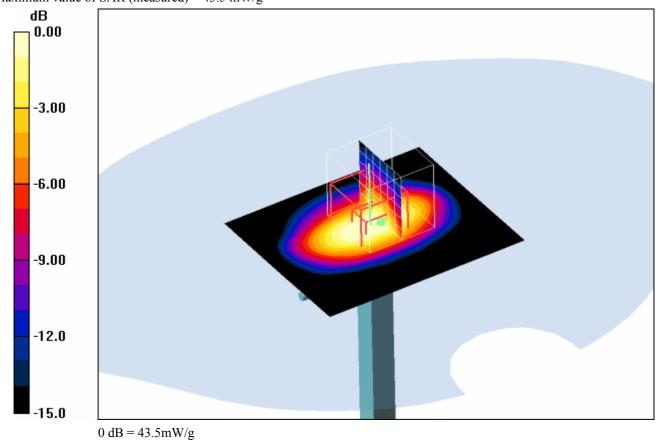
d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 170.9 V/m; Power Drift = 0.050 dB

Peak SAR (extrapolated) = 64.7 W/kg

SAR(1 g) = 38.4 mW/g; SAR(10 g) = 20.4 mW/gMaximum value of SAR (measured) = 43.5 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 20.7°C; liquid temperature: 20.0°C

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Date/Time: 2007-02-07 15:00:02Date/Time: 2007-02-07 15:04:08

SystemPerformanceCheck-D2450 head 2007-02-07

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 710

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL2450 Medium parameters used: f = 2450 MHz; $\sigma = 1.86 \text{ mho/m}$; $\varepsilon_r = 37.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.32, 4.32, 4.32); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 81.0 mW/g

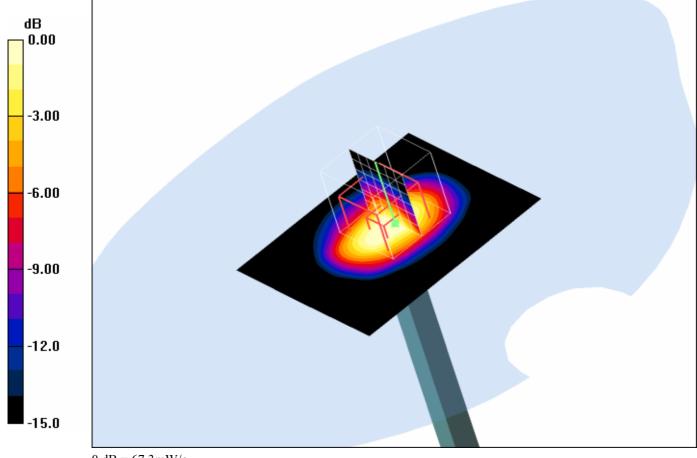
d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 187.3 V/m; Power Drift = 0.047 dB

Peak SAR (extrapolated) = 131.7 W/kg

SAR(1 g) = 60.4 mW/g; SAR(10 g) = 28 mW/gMaximum value of SAR (measured) = 67.3 mW/g



0 dB = 67.3 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.8°C; liquid temperature: 21.0°C

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Date/Time: 2007-02-08 09:33:05Date/Time: 2007-02-08 09:37:05

SystemPerformanceCheck-D2450 body 2007-02-08

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 710

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: M2450 Medium parameters used: f = 2450 MHz; $\sigma = 2.04$ mho/m; $\varepsilon_r = 52.3$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.06, 4.06, 4.06); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 71.5 mW/g

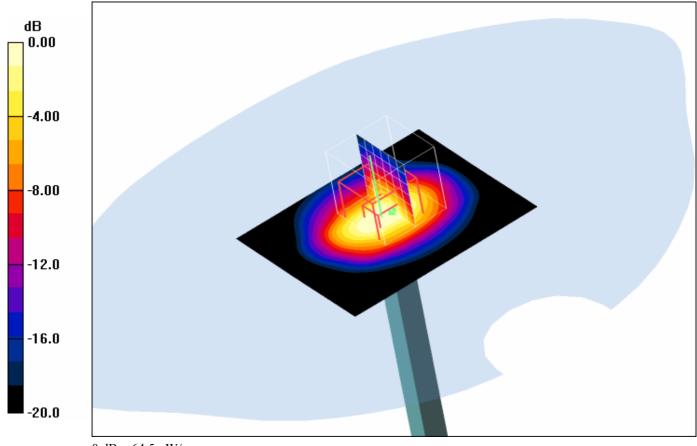
d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 168.6 V/m; Power Drift = 0.082 dB

Peak SAR (extrapolated) = 124.5 W/kg

SAR(1 g) = 57.2 mW/g; SAR(10 g) = 26.3 mW/gMaximum value of SAR (measured) = 64.5 mW/g



0 dB = 64.5 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.6°C; liquid temperature: 21.4°C

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Annex 2 Measurement results (printout from DASY TM)

Remark: results of conducted power measurements: see chapter 2.5/2.6 (if applicable)

Annex 2.1 GSM 1900 head

Date/Time: 2006-12-12 10:46:38Date/Time: 2006-12-12 10:53:02

P1528_OET65-LeftHandSide-GSM1900

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: PCS 1900; Frequency: 1880 MHz; Duty Cycle: 1:8

Medium: HSL1900 Medium parameters used: f = 1880 MHz; $\sigma = 1.37$ mho/m; $\varepsilon_r = 39.3$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.86, 4.86, 4.86); Calibrated: 2006-08-30

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn413; Calibrated: 2006-01-12

- Phantom: SAM 12; Type: SAM; Serial: 1043

- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.230 mW/g

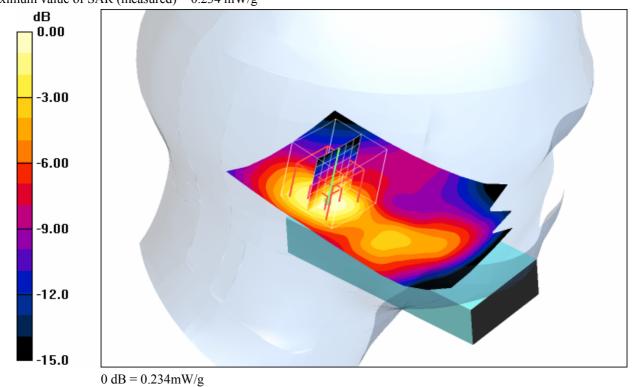
Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 7.60 V/m; Power Drift = -0.136 dB

Peak SAR (extrapolated) = 0.339 W/kg

SAR(1 g) = 0.210 mW/g; SAR(10 g) = 0.113 mW/gMaximum value of SAR (measured) = 0.234 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 20.6° C; liquid temperature: 20.1° C

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Date/Time: 2006-12-12 11:09:28Date/Time: 2006-12-12 11:16:06

P1528 OET65-LeftHandSide-GSM1900

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: PCS 1900; Frequency: 1880 MHz; Duty Cycle: 1:8

Medium: HSL1900 Medium parameters used: f = 1880 MHz; $\sigma = 1.37$ mho/m; $\varepsilon_r = 39.3$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.86, 4.86, 4.86); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.208 mW/g

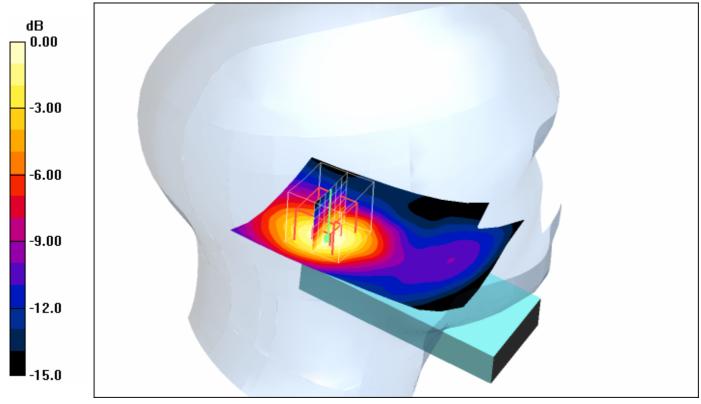
Tilt position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 12.1 V/m; Power Drift = -0.020 dB

Peak SAR (extrapolated) = 0.296 W/kg

SAR(1 g) = 0.185 mW/g; SAR(10 g) = 0.101 mW/gMaximum value of SAR (measured) = 0.207 mW/g



0 dB = 0.207 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 20.7°C; liquid temperature: 20.1°C

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Date/Time: 2006-12-12 11:53:41Date/Time: 2006-12-12 12:00:00

P1528_OET65-RightHandSide-GSM1900

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: PCS 1900; Frequency: 1880 MHz; Duty Cycle: 1:8

Medium: HSL1900 Medium parameters used: f = 1880 MHz; $\sigma = 1.37 \text{ mho/m}$; $\varepsilon_r = 39.3$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.86, 4.86, 4.86); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.328 mW/g

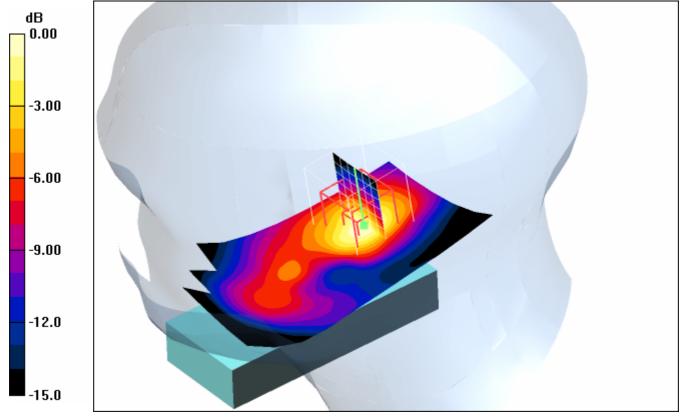
Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 11.1 V/m; Power Drift = -0.022 dB

Peak SAR (extrapolated) = 0.538 W/kg

SAR(1 g) = 0.304 mW/g; SAR(10 g) = 0.155 mW/g Maximum value of SAR (measured) = 0.342 mW/g



0 dB = 0.342 mW/g

Additional information:

As of 2007-02-09

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 20.9°C; liquid temperature: 20.2°C

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Date/Time: 2006-12-12 11:32:55Date/Time: 2006-12-12 11:39:22

P1528_OET65-RightHandSide-GSM1900

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: PCS 1900; Frequency: 1880 MHz; Duty Cycle: 1:8

Medium: HSL1900 Medium parameters used: f = 1880 MHz; $\sigma = 1.37 \text{ mho/m}$; $\varepsilon_r = 39.3$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.86, 4.86, 4.86); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.252 mW/g

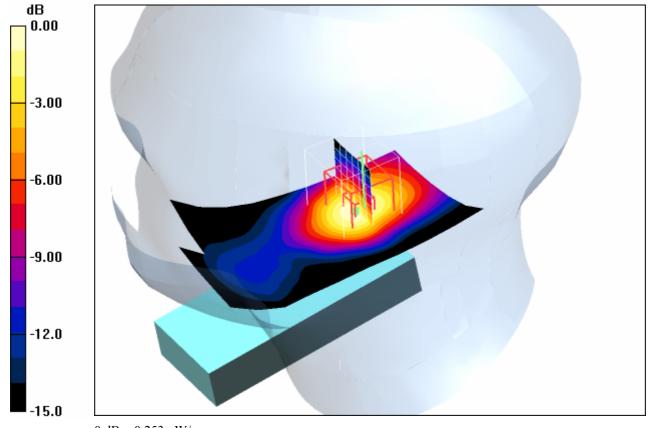
Tilt position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 11.7 V/m; Power Drift = -0.042 dB

Peak SAR (extrapolated) = 0.380 W/kg

SAR(1 g) = 0.228 mW/g; SAR(10 g) = 0.123 mW/gMaximum value of SAR (measured) = 0.253 mW/g



0~dB=0.253mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 20.8°C; liquid temperature: 20.1°C

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Annex 2.2 GSM 1900 body

Date/Time: 2006-12-12 13:04:53Date/Time: 2006-12-12 13:11:08

P1528 OET65-Body-GSM1900 GPRS class 10

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: PCS 1900 GPRS class 10; Frequency: 1880 MHz; Duty Cycle: 1:4

Medium: M1900 Medium parameters used: f = 1880 MHz; $\sigma = 1.52$ mho/m; $\varepsilon_r = 52.9$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.44, 4.44, 4.44); Calibrated: 2006-08-30

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn413; Calibrated: 2006-01-12

- Phantom: SAM 12; Type: SAM; Serial: 1043

- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Front position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

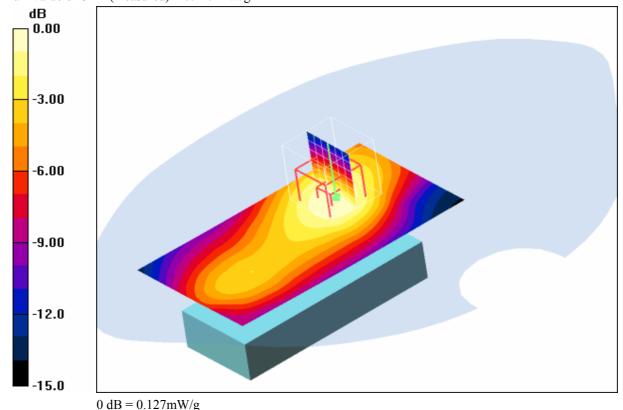
Maximum value of SAR (interpolated) = 0.128 mW/g

Front position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 7.19 V/m; Power Drift = 0.013 dB

Peak SAR (extrapolated) = 0.182 W/kg

SAR(1 g) = 0.117 mW/g; SAR(10 g) = 0.072 mW/g Maximum value of SAR (measured) = 0.127 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : 15 mm ambient temperature: 20.7° C; liquid temperature: 20.0° C

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Date/Time: 2006-12-12 13:27:31Date/Time: 2006-12-12 13:33:33

P1528_OET65-Body-GSM1900 GPRS class 10

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: PCS 1900 GPRS class 10; Frequency: 1880 MHz; Duty Cycle: 1:4

Medium: M1900 Medium parameters used: f = 1880 MHz; $\sigma = 1.52 \text{ mho/m}$; $\varepsilon_r = 52.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.44, 4.44, 4.44); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Rear position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.585 mW/g

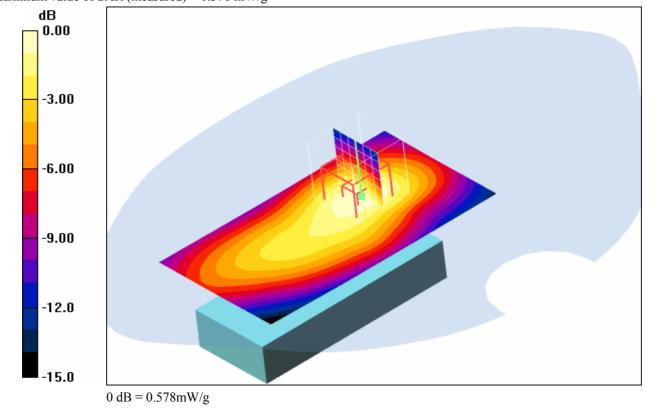
Rear position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 18.4 V/m; Power Drift = -0.00 dB

Peak SAR (extrapolated) = 0.810 W/kg

SAR(1 g) = 0.534 mW/g; SAR(10 g) = 0.330 mW/gMaximum value of SAR (measured) = 0.578 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : 15 mm ambient temperature: 20.8°C; liquid temperature: 20.1°C

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Annex 2.3 WLAN 2450 MHz head

Date/Time: 2007-02-07 15:21:26Date/Time: 2007-02-07 15:28:39

P1528 OET65 EN50361-LeftHandSide-WLAN

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: WLAN 2450 US; Frequency: 2412 MHz; Duty Cycle: 1:140

Medium: HSL2450 Medium parameters used (interpolated): f = 2412 MHz; $\sigma = 1.86$ mho/m; $\varepsilon_r = 37.9$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.32, 4.32, 4.32); Calibrated: 2006-08-30

- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Low/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.01 mW/g

Touch position - Low/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

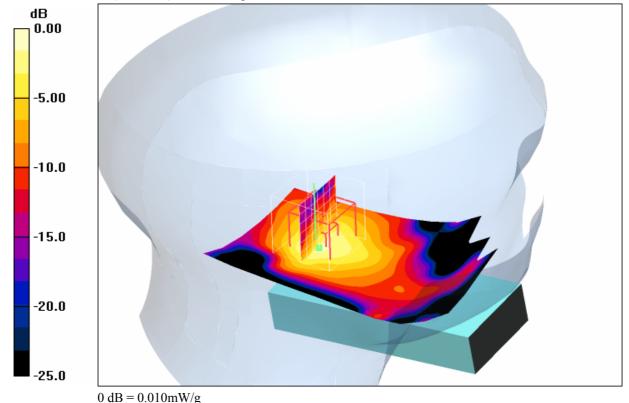
dz=5mm

Reference Value = 1.74 V/m; Power Drift = -0.211 dB

Peak SAR (extrapolated) = 0.010 W/kg

SAR(1 g) = 0.00588 mW/g; SAR(10 g) = 0.00289 mW/g

Maximum value of SAR (measured) = 0.01 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) :

ambient temperature: 22.9°C; liquid temperature: 20.9°C

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Date/Time: 2007-02-07 15:45:54Date/Time: 2007-02-07 15:53:10

P1528 OET65 EN50361-LeftHandSide-WLAN

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: WLAN 2450 US; Frequency: 2412 MHz; Duty Cycle: 1:140

Medium: HSL2450 Medium parameters used (interpolated): f = 2412 MHz; $\sigma = 1.86$ mho/m; $\varepsilon_r = 37.9$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.32, 4.32, 4.32); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Low/Area Scan (51x101x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.00 mW/g

Tilt position - Low/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

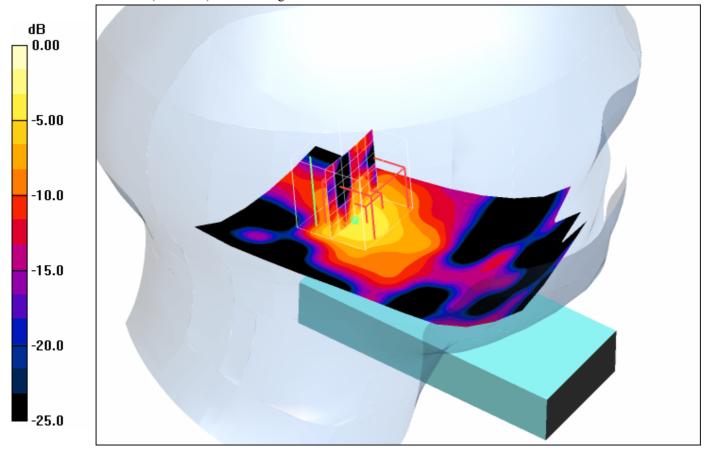
dz=5mm

Reference Value = 1.47 V/m; Power Drift = -0.060 dB

Peak SAR (extrapolated) = 0.016 W/kg

SAR(1 g) = 0.00394 mW/g; SAR(10 g) = 0.00167 mW/g

Maximum value of SAR (measured) = 0.01 mW/g



0 dB = 0.010 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 23.0°C; liquid temperature: 21.0°C

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Date/Time: 2007-02-07 16:40:26Date/Time: 2007-02-07 16:46:54

P1528 OET65 EN50361-RightHandSide-WLAN

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: WLAN 2450 US; Frequency: 2412 MHz; Duty Cycle: 1:140

Medium: HSL2450 Medium parameters used (interpolated): f = 2412 MHz; $\sigma = 1.86$ mho/m; $\varepsilon_r = 37.9$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.32, 4.32, 4.32); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Low/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.00 mW/g

Touch position - Low/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

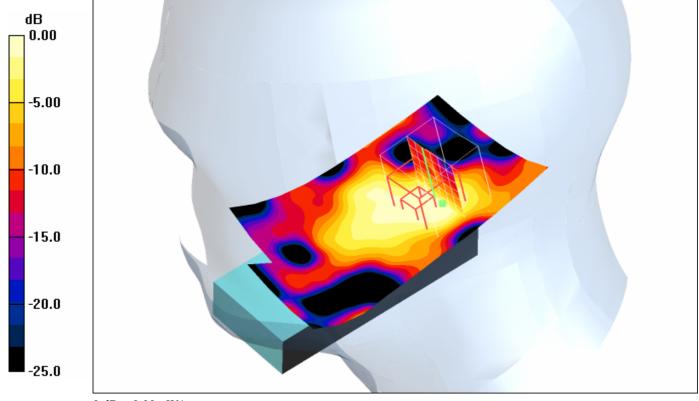
dz=5mm

Reference Value = 1.19 V/m; Power Drift = -0.029 dB

Peak SAR (extrapolated) = 0.012 W/kg

SAR(1 g) = 0.00412 mW/g; SAR(10 g) = 0.00196 mW/g

Maximum value of SAR (measured) = 0.00 mW/g



0 dB = 0.00 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.8°C; liquid temperature: 21.2°C

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Date/Time: 2007-02-07 16:07:48Date/Time: 2007-02-07 16:14:17

P1528_OET65_EN50361-RightHandSide-WLAN

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: WLAN 2450 US; Frequency: 2412 MHz; Duty Cycle: 1:140

Medium: HSL2450 Medium parameters used (interpolated): f = 2412 MHz; $\sigma = 1.86$ mho/m; $\varepsilon_r = 37.9$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.32, 4.32, 4.32); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Low/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.00 mW/g

Tilt position - Low/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

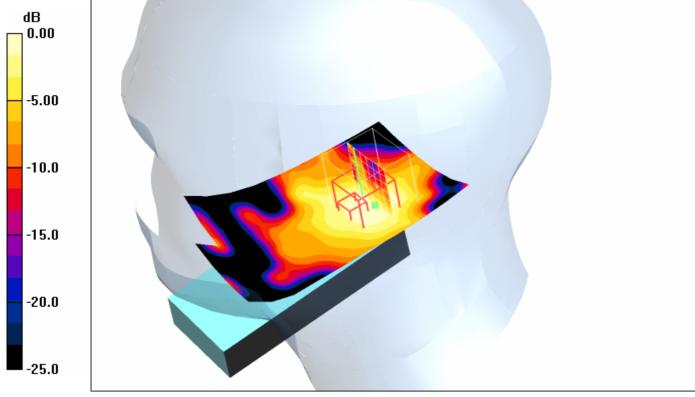
dz=5mm

Reference Value = 1.10 V/m; Power Drift = -0.025 dB

Peak SAR (extrapolated) = 0.016 W/kg

SAR(1 g) = 0.00283 mW/g; SAR(10 g) = 0.000914 mW/g

Maximum value of SAR (measured) = 0.00 mW/g



0 dB = 0.00 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.9°C; liquid temperature: 21.1°C

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Annex 2.4 WLAN 2450 MHz body

Date/Time: 2007-02-08 10:10:11Date/Time: 2007-02-08 10:18:13

P1528 OET65 EN50392-Body-WLAN2450

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: WLAN 2450 US; Frequency: 2412 MHz; Duty Cycle: 1:140

Medium: M2450 Medium parameters used (interpolated): f = 2412 MHz; $\sigma = 2.04$ mho/m; $\varepsilon_r = 52.3$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.06, 4.06, 4.06); Calibrated: 2006-08-30

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn413; Calibrated: 2007-01-18

- Phantom: SAM 12: Type: SAM: Serial: 1043

- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Front position - Low/Area Scan (61x101x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.00 mW/g

Front position - Low/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

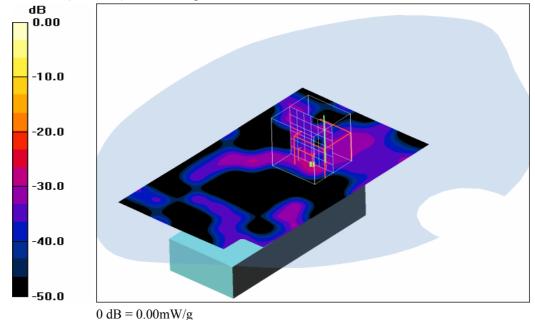
dz=5mm

Reference Value = 0.520 V/m; Power Drift = -0.143 dB

Peak SAR (extrapolated) = 0.00 W/kg

SAR(1 g) = 0.000284 mW/g; SAR(10 g) = 7.17e-005 mW/g

Maximum value of SAR (measured) = 0.00 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions): 15 mm

ambient temperature: 22.6°C; liquid temperature: 21.4°C

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Date/Time: 2007-02-08 11:08:38Date/Time: 2007-02-08 11:16:21

P1528_OET65_EN50392-Body-WLAN2450

DUT: Pirelli; Type: DP-L 10; Serial: 352789010059097

Communication System: WLAN 2450 US; Frequency: 2412 MHz; Duty Cycle: 1:140

Medium: M2450 Medium parameters used (interpolated): f = 2412 MHz; $\sigma = 2.04$ mho/m; $\varepsilon_r = 52.3$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.06, 4.06, 4.06); Calibrated: 2006-08-30
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2007-01-18
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Rear position - Low/Area Scan (61x101x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.00 mW/g

Rear position - Low 2/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

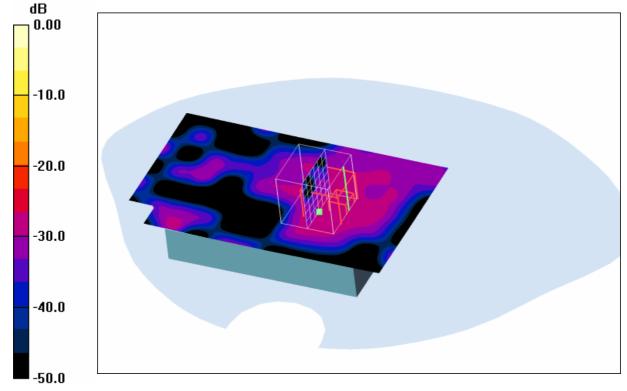
dz=5mm

Reference Value = 1.04 V/m; Power Drift = -0.164 dB

Peak SAR (extrapolated) = 0.01 W/kg

SAR(1 g) = 0.00198 mW/g; SAR(10 g) = 0.000765 mW/g

Maximum value of SAR (measured) = 0.00 mW/g



0 dB = 0.00 mW/g

Additional information:

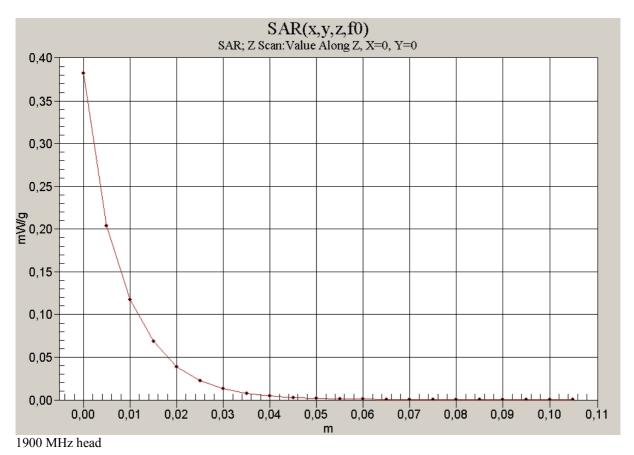
position or distance of DUT to SAM (if not standard head positions) : $15\ mm$

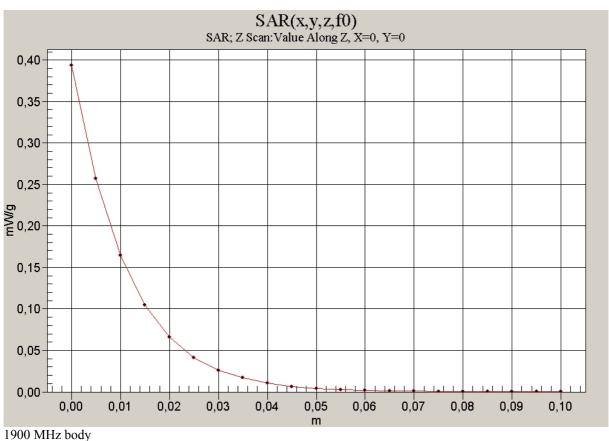
ambient temperature: 22.7°C; liquid temperature: 21.5°C

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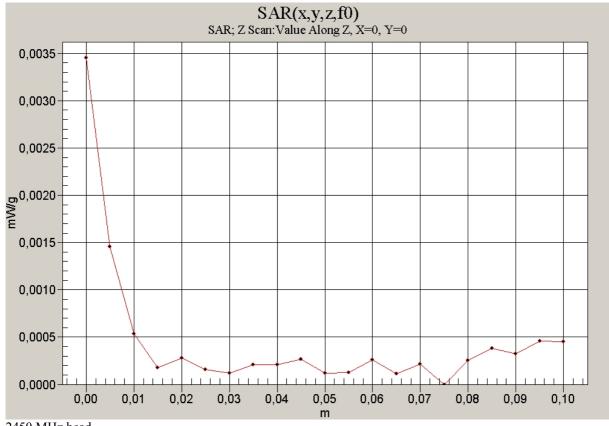
Annex 2.5 Z-Axis scan



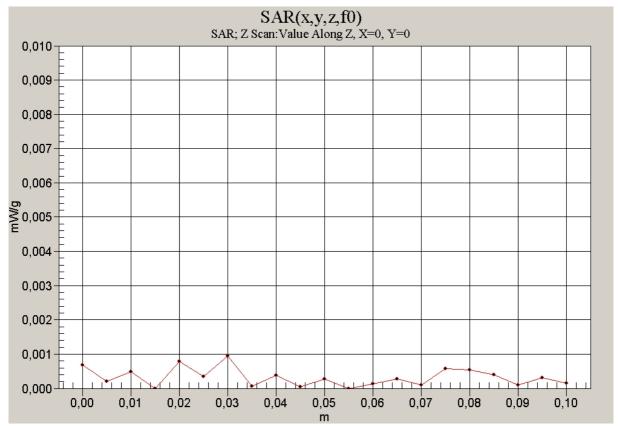


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2450 MHz body

Note: WLAN mode at 15 mm distance causes SAR values close to noise level.

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Annex 3 Photo documentation

Measurement System DASY 4



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Photo 1: DUT - front view



Photo 2: DUT - side view



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Photo 3: DUT - rear view



Photo 4: DUT - rear view (open)



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Photo 5: DUT - rear view (open) without battery



Photo 6: DUT - label



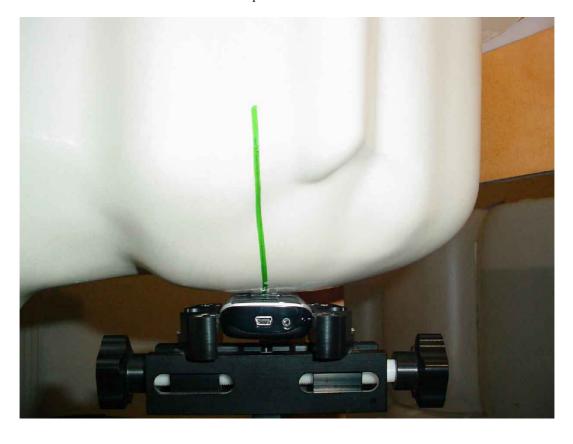
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Photo 7: DUT - battery



Photo 8: test position left hand touched



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Photo 9: test position left hand touched



Photo 10: test position left hand touched



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Photo 11: test position left hand tilted 15°

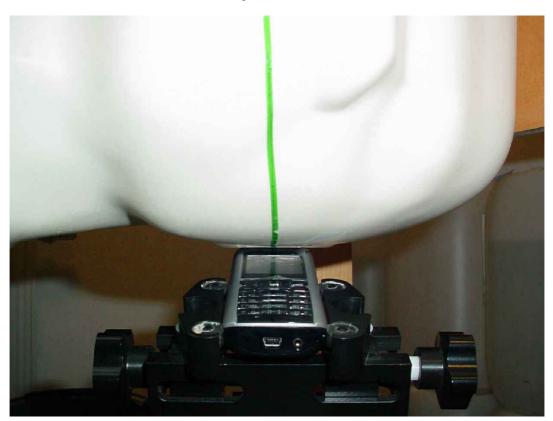
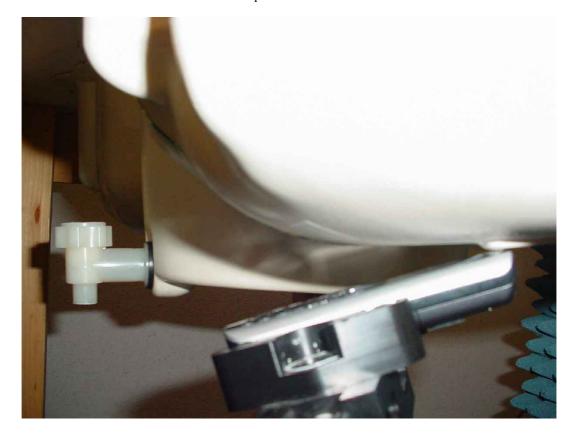


Photo 12: test position left hand tilted 15°



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Photo 13: test position right hand touched

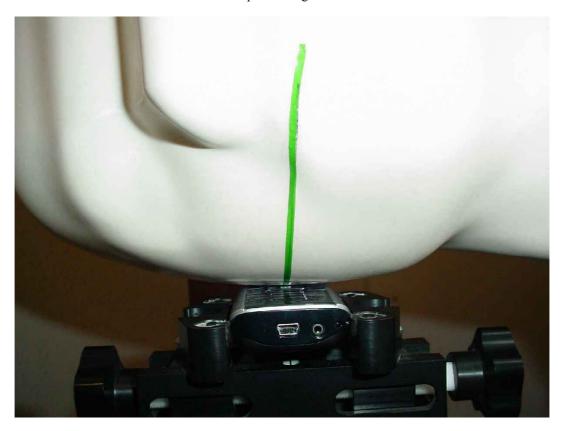


Photo 14: test position right hand touched



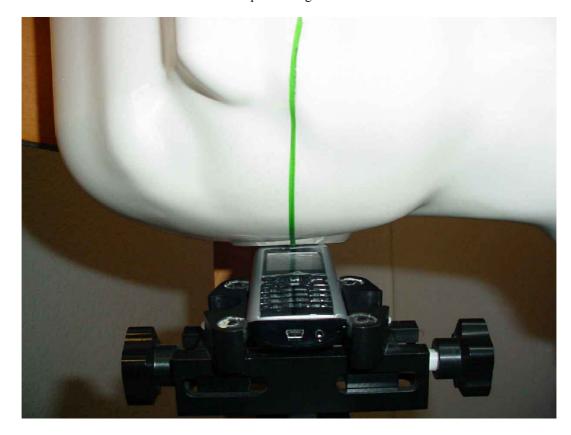
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Photo 15: test position right hand touched



Photo 16: test position right hand tilted 15°



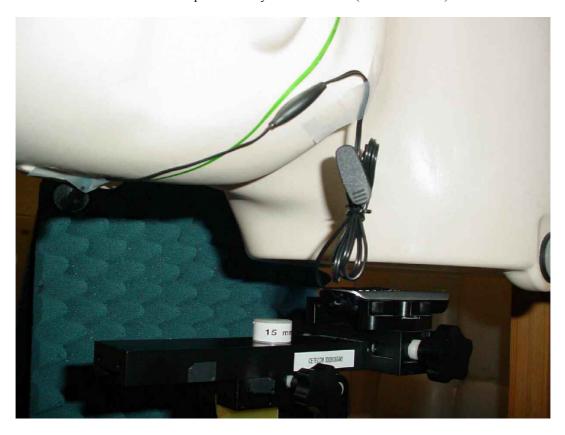
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Photo 17: test position right hand tilted 15°



Photo 18: test position body worn front side (15 mm distance)



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Photo 19: test position body worn front side (15 mm distance)



Photo 20: test position body worn rear side (15 mm distance)



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Photo 21: test position body worn rear side (15 mm distance)



Photo 22: liquid depth 1900 MHz head simulating liquid



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Photo 23: liquid depth 1900 MHz body simulating liquid



Photo 24: liquid depth 2450 MHz head simulating liquid



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Photo 25: liquid depth 2450 MHz body simulating liquid



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Annex 4 RF Technical Brief Cover Sheet acc. to RSS-102

| 1. COMPANY NUMBER: 6930A |
|---|
| 2. MODEL NUMBER: 1510600 |
| 3. MANUFACTURER: Pirelli Broadband Solutions S.p.A. |
| 4. TYPE OF EVALUATION: |
| (a) SAR Evaluation: Device used in the Vicinity of the Human Head |
| Multiple transmitters: Yes □ No □ |
| Evaluated against exposure limits: General Public Use □ Controlled Use □ Duty cycle used in evaluation: 12.5 % Standard used for evaluation: RSS-102 Issue 2 (2005-11) |
| • SAR value: 0.304 W/kg. Measured ⊠□ Computed □ Calculated □ |
| (b) SAR Evaluation: Body-worn Device |
| • Multiple transmitters: Yes □ No ⊠□ |
| • Evaluated against exposure limits: General Public Use □ Controlled Use □ • Duty cycle used in evaluation: 25 % • Standard used for evaluation: RSS-102 Issue 2 (2005-11) |
| • SAR value: 0.534 W/kg. Measured ⊠ Computed □ Calculated □ |
| Annex 4.1 Declaration of RF Exposure Compliance |
| ATTESTATION: I attest that the information provided in Annex 4 is correct; that a Technical Brief was prepared and the information it contains is correct; that the device evaluation was performed of supervised by me; that applicable measurement methods and evaluation methodologies have been followed and that the device meets the SAR and/or RF exposure limits of RSS-102. |
| Signature: Date: 2007-02-09 |
| |

NAME: Thomas Vogler

TITLE: Dipl.-Ing. (FH)

COMPANY: CETECOM ICT Services GmbH

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CETECOM ICT Services GmbH

Test report no.: 2-4506-01-04/06



Annex 5 Calibration parameters

Calibration parameters are described in the additional document:

Appendix to test report no. 2-4506-01-04/06' Calibration data, Phantom certificate and detail information of the DASY4 System

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