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Appendix 5. System Check

Prior to the assessment, the system was verified in the flat region of the phantom. 900 MHz and 2450 MHz dipoles were used. A forward power of 250 mW was applied to the dipole and the system was verified to a tolerance of $\pm 5\%$ for both the dipole.

The applicable verification normalised to 1 Watt.

System Check 850/900 Body

Date: 31/05/2012 Validation Dipole and Serial Number: D900V2; SN: 124								
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	900	24.0 °C	22.5 °C	ε _r	55.00	55.51	0.92	5.00
				σ	1.05	1.01	-3.60	5.00
				1g SAR	11.10	11.28	1.62	5.00
				10g SAR	7.14	7.36	3.08	5.00

System Check 2450 Body

Date: 31/05/2012 Validation Dipole and Serial Number: D2450V2; SN: 725								
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body		24.0 °C	23.0 °C	ε _r	52.70	50.68	-3.83	5.00
	2450			σ	1.95	2.02	3.73	5.00
				1g SAR	51.90	50.80	-2.12	5.00
				10g SAR	24.10	23.08	-4.23	5.00

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Appendix 6. Simulated Tissues

The body mixture consists of water, Polysorbate 20 and salt. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient	Frequency		
	835/850/900 MHz Body		
De-Ionized Water	71.30		
Polysorbate 20 (Tween 20)	28.00		
Salt	0.70		

Ingredient	Frequency		
	2450 MHz Body		
De-Ionized Water	71.70		
Polysorbate 20 (Tween 20)	28.00		
Salt	0.30		

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Appendix 7. DASY4 System Details

A.7.1. DASY4 SAR Measurement System

RFI Global Services Ltd, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching mulitplexer, a fast 16bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

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A.7.2. DASY4 SAR System Specifications				
Robot System				
Positioner:	Stäubli Unimation Corp. Robot Model: RX90L			
Repeatability:	0.025 mm			
No. of Axis:	6			
Serial Number:	F00/SD89A1/A/01			
Reach:	1185 mm			
Payload:	3.5 kg			
Control Unit:	CS7			
Programming Language:	V+			
Data Acquisition Electronic (DAE) System				
Serial Number:	DAE3 SN:394			
PC Controller				
PC:	Dell Precision 340			
Operating System:	Windows 2000			
Data Card:	DASY4 Measurement Server			
Serial Number:	1080			
Data Converter				
Features:	Signal Amplifier, multiplexer, A/D converted and control logic.			
Software:	DASY4 Software			
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock.			
PC Interface Card				
Function:	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 nit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.			

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DASY4 SAR System Specifications (Continued)				
E-Field Probe				
Model:	EX3DV4			
Serial No:	3814			
Construction:	Triangular core			
Frequency:	10 MHz to >6 GHz			
Linearity:	±0.2 dB (30 MHz to 6 GHz)			
Probe Length (mm):	330			
Probe Diameter (mm):	12			
Tip Length (mm):	20			
Tip Diameter (mm):	2.5			
Sensor X Offset (mm):	1			
Sensor Y Offset (mm):	1			
Sensor Z Offset (mm):	1			
Phantom				
Phantom:	SAM Phantom			
Shell Material:	Fibreglass			
Thickness:	2.0 ±0.1 mm			

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