

# **DFS TEST REPORT**

**REPORT NO.:** RF980313L03-5

MODEL NO.: MC9598

**TESTED:** Mar. 13, 2009 **TESTED:** Mar. 27, 2009 **ISSUED:** Mar. 31, 2009

**APPLICANT:** Motorola, Inc.

**ADDRESS:** One Motorola Plaza, Holtsville, NY 11742-1300

USA

**ISSUED BY:** Bureau Veritas Consumer Products Services (H.K.)

Ltd., Taoyuan Branch

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**TEST LOCATION:** No. 19, Hwa Ya 2nd Rd, Wen Hwa Tsuen, Kwei

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# 1. LAB DECLARATION

**PRODUCT:** Mobile Computer

MODEL: MC9598 BRAND: Motorola

APPLICANT: Motorola, Inc.

**TESTED:** Mar. 27, 2009

**TEST SAMPLE:** ENGINEERING SAMPLE

STANDARDS: FCC Part 15, Subpart E (Section 15.407)

FCC 06-96

The above equipment (model: MC9598) has been tested by **Bureau Veritas Consumer Products Services (H.K.) Ltd., Taoyuan Branch**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

PREPARED BY:  $\ell \ell / \ell / \ell$  , DATE: Mar. 31, 2009

Peggy Chen / Specialist

TECHNICAL

ACCEPTANCE: Mar. 31, 2009

Responsible for RF Dylan Chiou / Senior Engineer

APPROVED BY: Jay Jag , DATE: Mar. 31, 2009

Gary Chang / Assistant Manager



# 2. EUT INFORMATION

# 2.1 OPERATING FREQUENCY BANDS AND MODE OF EUT

TABLE 1: OPERATING FREQUENCY BANDS AND MODE OF EUT

| OPERATIONAL MODE                                   | OPERATING FREQUENCY RANGE |              |  |  |
|--|---------------------------|--------------|--|--|
| OPERATIONAL MODE                                   | 5250~5350MHz              | 5470~5725MHz |  |  |
| Client without radar detection and ad hoc function | ✓                         | ✓            |  |  |

### 2.2 EUT SOFTWARE AND FIRMWARE VERSION

**TABLE 2: THE EUT SOFTWARE/FIRMWARE VERSION** 

| NO. | PRODUCT         | MODEL NO. | SOFTWARE/FIRMWARE VERSION        |
|-----|-----------------|-----------|----------------------------------|
| 1   | Mobile Computer | MC9598    | Driver:3.00.0.0.14, FW:3.0.0.0.3 |

Note: Windows Mobile 6.1

# 2.3 DESCRIPTION OF AVAILABLE ANTENNAS TO THE EUT

**TABLE 3: ANTENNA LIST** 

| ANT<br>NO. | ANTENNA TYPE | OPERATION FREQUENCY<br>RANGE | MAX. GAIN (dBi) |
|------------|--------------|------------------------------|-----------------|
| 1          | PIFA (Main)  | 5.0GHz                       | 3.52            |
| 2          | PIFA (Aux.)  | 5.0GHz                       | 4.00            |



### 2.4 EUT MAXIMUM AND MINIMUM CONDUCTED POWER

# TABLE 4: THE MEASURED CONDUCTED OUTPUT POWER

#### **IEEE 802.11a**

| ANT | FREQUENCY BAND | MAX. POWER           |                     | MIN. POWER           |                     |
|-----|----------------|----------------------|---------------------|----------------------|---------------------|
| NO. | (MHz)          | OUTPUT<br>POWER(dBm) | OUTPUT<br>POWER(mW) | OUTPUT<br>POWER(dBm) | OUTPUT<br>POWER(mW) |
| 1   | 5250~5350      | 10.59                | 11.455              | 5.91                 | 3.899               |
| 1   | 5470~5725      | 13.65                | 23.174              | 2.22                 | 1.660               |

### 2.5 EUT MAXIMUM AND MINIMUM E.I.R.P. POWER

### TABLE 5: THE E.I.R.P OUTPUT POWER LIST

#### IEEE 802.11a

| ANT | FREQUENCY BAND | Y BAND MAX. POWER    |                     | MIN. P               | OWER                |
|-----|----------------|----------------------|---------------------|----------------------|---------------------|
| NO. | (MHz)          | OUTPUT<br>POWER(dBm) | OUTPUT<br>POWER(mW) | OUTPUT<br>POWER(dBm) | OUTPUT<br>POWER(mW) |
| 1   | 5250~5350      | 14.59                | 28.774              | 9.91                 | 9.795               |
| 1   | 5470~5725      | 17.65                | 58.210              | 6.22                 | 4.188               |

# 2.6 STATEMENT OF MAUNFACTURER

Manufacturer statement confirming that information regarding the parameters of the detected Radar Waveforms is not available to the end user. **And the device doesn't have Ad Hoc mode on DFS frequency band.** 



# 3. U-NII DFS RULE REQUIREMENTS

## 3.1 WORKING MODES AND REQUIRED TEST ITEMS

The manufacturer shall state whether the UUT is capable of operating as a Master and/or a Client. If the UUT is capable of operating in more than one operating mode then each operating mode shall be tested separately. See tables 1 and 2 for the applicability of DFS requirements for each of the operational modes.

TABLE 6: APPLICABILITY OF DFS REQUIREMENTS PRIOR TO USE A CHANNEL

|                                 | OPERATIONAL MODE |                                      |                                   |  |  |
|---------------------------------|------------------|--------------------------------------|-----------------------------------|--|--|
| REQUIREMENT                     | MASTER           | CLIENT WITHOUT<br>RADAR<br>DETECTION | CLIENT WITH<br>RADAR<br>DETECTION |  |  |
| Non-Occupancy Period            | ✓                | Not required                         | ✓                                 |  |  |
| DFS Detection Threshold         | ✓                | Not required                         | ✓                                 |  |  |
| Channel Availability Check Time | ✓                | Not required                         | Not required                      |  |  |
| Uniform Spreading               | ✓                | Not required                         | Not required                      |  |  |
| U-NII Detection Bandwidth       | ✓                | Not required                         | ✓                                 |  |  |

TABLE 7: APPLICABILITY OF DFS REQUIREMENTS DURING NORMAL OPERATION

|                                   | OPERATIONAL MODE |                                      |                                   |  |  |
|-----------------------------------|------------------|--------------------------------------|-----------------------------------|--|--|
| REQUIREMENT                       | MASTER           | CLIENT WITHOUT<br>RADAR<br>DETECTION | CLIENT WITH<br>RADAR<br>DETECTION |  |  |
| DFS Detection Threshold           | ✓                | Not required                         | ✓                                 |  |  |
| Channel Closing Transmission Time | ✓                | ✓                                    | ✓                                 |  |  |
| Channel Move Time                 | ✓                | ✓                                    | <b>√</b>                          |  |  |
| U-NII Detection Bandwidth         | ✓                | Not required                         | ✓                                 |  |  |



### 3.2 TEST LIMITS AND RADAR SIGNAL PARAMETERS

#### **DETECTION THRESHOLD VALUES**

# TABLE 8: DFS DETECTION THRESHOLDS FOR MASTER DEVICES AND CLIENT DEVICES WITH RADAR DETECTION

| MAXIMUM TRANSMIT POWER | VALUE (SEE Note 1 and 2) |
|------------------------|--------------------------|
| ≥ 200 milliwatt        | -64 dBm                  |
| < 200 milliwatt        | -62 dBm                  |

**Note 1:** This is the level at the input of the receiver assuming a 0 dBi receive antenna.

**Note 2:** Throughout these test procedures an additional 1 dB has been added to the amplitude of the test transmission waveforms to account for variations in measurement equipment. This will ensure that the test signal is at or above the detection threshold level to trigger a DFS response.

#### **TABLE 9: DFS RESPONSE REQUIREMENT VALUES**

| PARAMETER                         | VALUE   |
|-----------------------------------|---|
| Non-occupancy period              | Minimum 30 minutes  |
| Channel Availability Check Time   | 60 seconds  |
| Channel Move Time                 | 10 seconds  |
|                                   | See Note 1.   |
| Channel Closing Transmission Time | 200 milliseconds + an aggregate of 60                     |
|                                   | milliseconds over remaining 10 second period.             |
|                                   | See Notes 1 and 2.  |
| U-NII Detection Bandwidth         | Minimum 80% of the UNII 99% transmission power bandwidth. |
|                                   | See Note 3.   |

**Note 1:** The instant that the Channel Move Time and the Channel Closing Transmission Time begins is as follows:

- For the Short Pulse Radar Test Signals this instant is the end of the Burst.
- For the Frequency Hopping radar Test Signal, this instant is the end of the last radar Burst generated.
- For the Long Pulse Radar Test Signal this instant is the end of the 12 second period defining the Radar Waveform.

**Note 2:** The Channel Closing Transmission Time is comprised of 200 milliseconds starting at the beginning of the Channel Move Time plus any additional intermittent control signals required to facilitate a Channel move (an aggregate of 60 milliseconds) during the remainder of the 10 second period. The aggregate duration of control signals will not count quiet periods in between transmissions.

**Note 3:** During the U-NII Detection Bandwidth detection test, radar type 1 is used and for each frequency step the minimum percentage of detection is 90 percent. Measurements are performed with no data traffic.



# PARAMETERS OF DFS TEST SIGNALS

Step intervals of 0.1 microsecond for Pulse Width, 1 microsecond for PRI, 1 MHz for chirp width and 1 for the number of pulses will be utilized for the random determination of specific test waveforms.

**TABLE 10: SHORT PULSE RADAR TEST WAVEFORMS** 

| RADAR TYPE | PULSE<br>WIDTH<br>(µsec) | PRI (μsec) | NUMBER OF<br>PULSES | MINIMUM<br>PERCENTAGE<br>OF<br>SUCCESSFUL<br>DETECTION | MINIMUM<br>NUMBER OF<br>TRIALS |
|------------|--------------------------|------------|---------------------|--|--------------------------------|
| 1          | 1                        | 1428       | 18                  | 60%  | 30                             |
| 2          | 1-5                      | 150-230    | 23-29               | 60%  | 30                             |
| 3          | 6-10                     | 200-500    | 16-18               | 60%  | 30                             |
| 4          | 11-20                    | 200-500    | 12-16               | 60%  | 30                             |
|            | Aggregate (Ra            | 80%        | 120                 |  |                                |

**TABLE 11: LONG PULSE RADAR TEST WAVEFORM** 

| RADAR<br>TYPE | PULSE<br>WIDTH<br>(µsec) | CHIRP<br>WIDTH<br>(MHz) | PRI<br>(µsec) | NUMBER<br>OF PULSES<br>PER BURST | NUMBER<br>OF BURSTS | MINIMUM<br>PERCENTAGE OF<br>SUCCESSFUL<br>DETECTION | MINIMUM<br>NUMBER OF<br>TRIALS |
|---------------|--------------------------|-------------------------|---------------|----------------------------------|---------------------|---|--------------------------------|
| 5             | 50-100                   | 5-20                    | 1000-2000     | 1-3                              | 8-20                | 80%   | 30                             |

### TABLE 12: FREQUENCY HOPPING RADAR TEST WAVEFORM

| RADAR<br>TYPE | PULSE<br>WIDTH<br>(µsec) | PRI<br>(µsec) | PULSES<br>PER HOP | HOPPING<br>RATE<br>(kHz) | HOPPING<br>SEQUENCE<br>LENGTH<br>(msec) | MINIMUM<br>PERCENTAGE OF<br>SUCCESSFUL<br>DETECTION | MINIMUM<br>NUMBER OF<br>TRIALS |
|---------------|--------------------------|---------------|-------------------|--------------------------|---|---|--------------------------------|
| 6             | 1                        | 333           | 9                 | 0.333                    | 300                                     | 70%   | 30                             |



# 4. TEST & SUPPORT EQUIPMENT LIST

### 4.1 TEST INSTRUMENTS

TABLE 1: TEST INSTRUMENTS LIST.

| DESCRIPTION & MANUFACTURER | MODEL NO. | BRAND     | DATE OF CALIBRATION | DUE DATE OF CALIBRATION |
|----------------------------|-----------|-----------|---------------------|-------------------------|
| R&S Spectrum analyzer      | FSP40     | R&S       | Jul. 04, 2008       | Jul. 03, 2009           |
| Signal generator           | 8645A     | Agilent   | Jun. 10, 2008       | Jun. 09, 2009           |
| Oscilloscope               | TDS 5104  | Tektronix | Sep. 01, 2008       | Aug. 31, 2009           |

# 4.2 DESCRIPTION OF SUPPORT UNITS

**TABLE 2: SUPPORT UNIT INFORMATION.** 

| NO. | PRODUCT                    | BRAND | MODEL NO.    | FCC ID    |
|-----|----------------------------|-------|--------------|-----------|
| 1   | 802.11a/b/g/n Access Point | Cisco | AIR-AP1252AG | LDK102061 |

**NOTE:** This device was functioned as a ⊠Master □Slave device during the DFS test.

TABLE 3: SOFTWARE/FIRMWARE INFORMATION.

| NO. | PRODUCT                    | MODEL NO.         | SOFTWARE/FIRMWARE<br>VERSION |  |
|-----|----------------------------|-------------------|------------------------------|--|
| 1.  | 802.11a/b/g/n Access Point | AIR-AP1252AG-A-K9 | 12.4(10b)JA1                 |  |

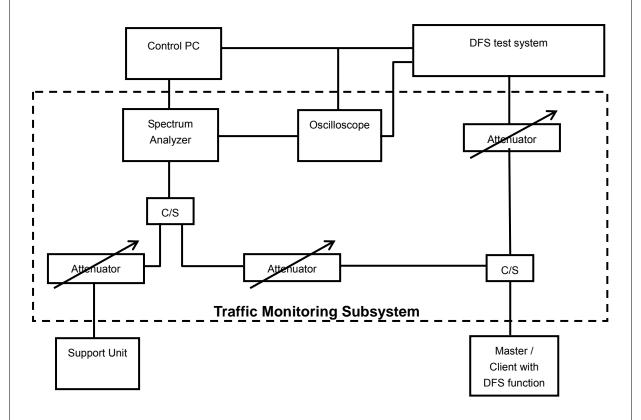


# 5. TEST PROCEDURE

## 5.1 BVADT DFS MEASUREMENT SYSTEM:

A complete BVADT DFS Measurement System consists of two subsystems: (1) the Radar Signal Generating Subsystem and (2) the Traffic Monitoring Subsystem. The control PC is necessary for generating the Radar waveforms in Table 6, 7 and 8. The traffic monitoring subsystem is specified to the type of unit under test (UUT).

# CONDUCTED SETUP CONFIGURATION OF ADT DFS MEASUREMENT SYSTEM



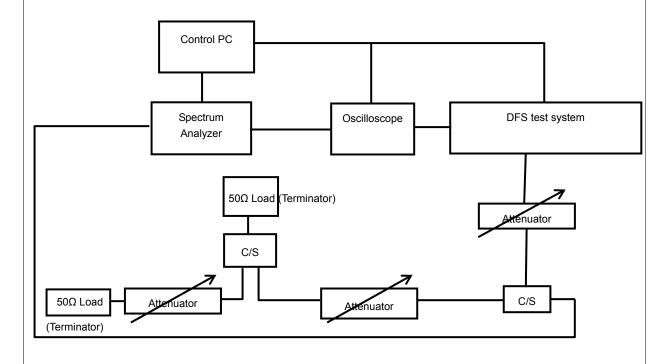
The test transmission will always be from the Master Device to the Client Device. While the Client device is set up to associate with the Master device and play the MPEG file (6  $\frac{1}{2}$  Magic Hours) from Master device, the designated MPEG test file and instructions are located at: http://ntiacsd.ntia.doc.gov/dfs/.



### 5.2 CALIBRATION OF DFS DETECTION THRESHOLD LEVEL:

The measured channel is 5500 MHz. The radar signal was injected into the antenna port of AP (master) or Client Device with Radar Detection, measured the channel closing transmission time and channel move time. The Master antenna gain is 3 dBi and required detection threshold is -59 dBm (= -62 +3)dBm. The calibrated conducted detection threshold level is set to -59 dBm. The tested level is lower than required level hence it provides margin to the limit.

# CONDUCTED SETUP CONFIGURATION OF CALIBRATION OF DFS DETECTION THRESHOLD LEVEL



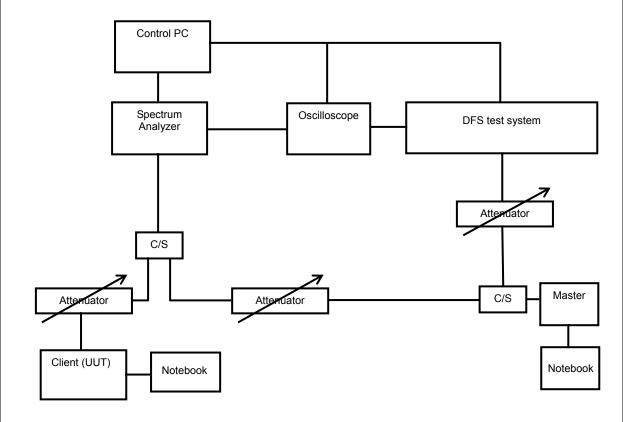


# 5.3 DEVIATION FROM TEST STANDARD

No deviation.

# 5.4 CONDUCTED TEST SETUP CONFIGURATION

# 5.4.1 CLIENT WITHOUT RADAR DETECTION MODE



The UUT is a U-NII Device operating in Client mode without radar detection. The radar test signals are injected into the Master Device.



# 6. TEST RESULTS

# 6.1 SUMMARY OF TEST RESULTS

| CLAUSE | TEST PARAMETER                    | REMARKS        | PASS/FAIL |
|--------|-----------------------------------|----------------|-----------|
| 15.407 | DFS Detection Threshold           | Not Applicable | NA        |
| 15.407 | Channel Availability Check Time   | Not Applicable | NA        |
| 15.407 | Channel Move Time                 | Applicable     | Pass      |
| 15.407 | Channel Closing Transmission Time | Applicable     | Pass      |
| 15.407 | Non- Occupancy Period             | Applicable     | Pass      |
| 15.407 | Uniform Spreading                 | Not Applicable | NA        |
| 15.407 | U-NII Detection Bandwidth         | Not Applicable | NA        |
| 15.407 | Non-associated test               | Not Applicable | NA        |



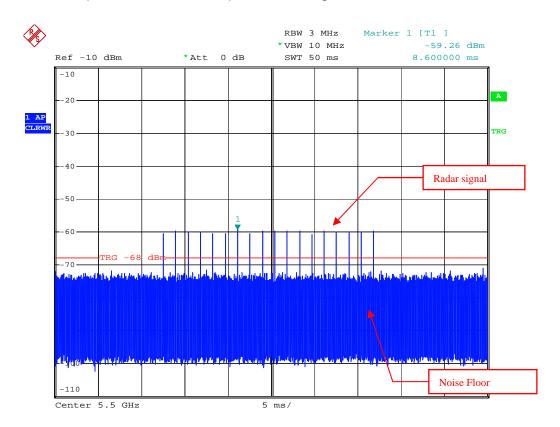
### 6.2 DETELED TEST RESULTS

# 6.2.1 TEST MODE: DEVICE OPERATING IN CLIENT WITHOUT RADAR DETECTION MODE.

Client with injection at the Master. (The radar test signals are injected into the Master Device)

### 6.2.1.1 DFS DETECTION THRESHOLD

For a detection threshold level of –62dBm and the Master antenna gain is 3 dBi. The Required detection threshold is -59 dBm (= -62 + 3)dBm. The tested level is lower than required level hence it provides margin to the limit.



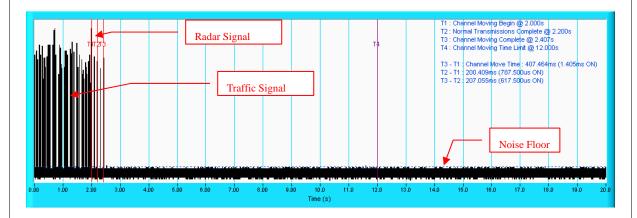
Radar Signal 1



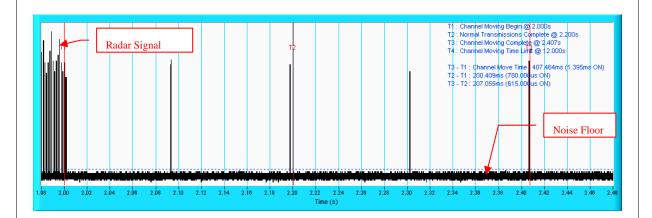
### 6.2.1.2 CHANNEL CLOSING TRANSMISSION AND CHANNEL MOVE TIME

#### **RADAR SIGNAL 1**

#### 802.11A



**NOTE:** T1 denotes the start of Channel Move Time upon the end of the last Radar burst. T2 denotes the data transmission time of 200ms from T1. T3 denotes the end of Channel Move Time.T4 denotes the 10 second from T1 to observe the aggregate duration of transmissions.



**NOTE:** An expanded plot for the device vacates the channel in the required 500ms.

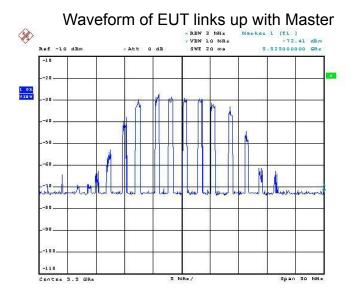


# 6.2.1.3 NON-OCCUPANCY PERIOD

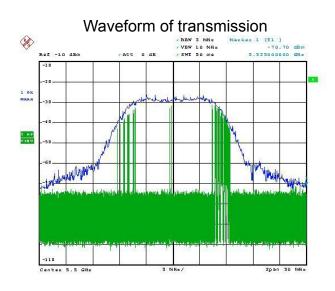
### **Associate test:**

During the 30 minutes observation time, UUT did not make any transmissions on a channel after a radar signal was detected on that channel by either the Channel Availability Check or the In-Service Monitoring.

1) EUT links up with Master at 5500MHz.

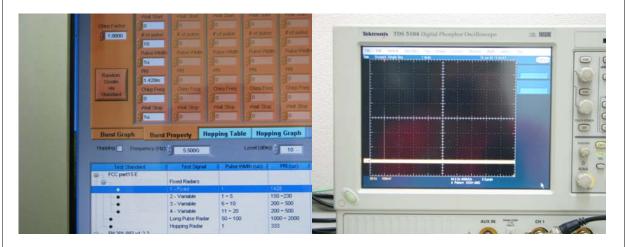


# 2) EUT plays test movie from Master.



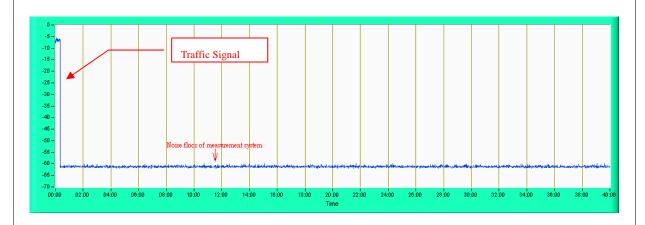


3) Radar 1 is used for DFS testing



4) 5500MHz has been monitored in 30 minutes period. In this period, no any transmission occur.

Plot of 30minutes period



Note: Test setup are shown on TSup\_UZ7MC9598.pdf



## 7. TESTING LABORATORIES INFORMATION

We, Bureau Veritas Consumer Products Services (H.K.) Ltd., Taoyuan Branch, were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved by the following approval agencies according to ISO/IEC 17025.

USA FCC, NVLAP
Germany TUV Rheinland

Japan VCCI Norway NEMKO

Canada INDUSTRY CANADA, CSA

**R.O.C.** TAF, BSMI, NCC

**Netherlands** Telefication

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<u>www.adt.com.tw/index.5/phtml</u>. If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab:Hsin Chu EMC/RF Lab:Tel: 886-2-26052180Tel: 886-3-5935343Fax: 886-2-26051924Fax: 886-3-5935342

## Hwa Ya EMC/RF/Safety Telecom Lab:

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The address and road map of all our labs can be found in our web site also.



**APPENDIX A - MODIFICATIONS RECORDERS FOR** 8. **ENGINEERING CHANGES TO THE EUT BY THE LAB** No any modifications are made to the EUT by the lab during the test. ---END---