

Applicant:	Kyocera
FCC ID:	V65C5155
Report #:	CT-C5155-12A-0412-R0

EXHIBIT 12 APPENDIX A: HAC RF PROBE CALIBRATION CERTIFICATE

Total pages including cover page = 21

Calibration Laboratory of

Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland





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Swiss Calibration Service

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Client

Kyocera USA

Certificate No: ER3-2341_Jul11

Accreditation No.: SCS 108

CALIBRATION CERTIFICATE

Object

ER3DV6 - SN:2341

Calibration procedure(s)

QA CAL-02.v6, QA CAL-25.v4

Calibration procedure for E-field probes optimized for close near field

evaluations in air

Calibration date:

July 12, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	31-Mar-11 (No. 217-01372)	Apr-12
Power sensor E4412A	MY41498087	31-Mar-11 (No. 217-01372)	Apr-12
Reference 3 dB Attenuator	SN: S5054 (3c)	29-Mar-11 (No. 217-01369)	Apr-12
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-11 (No. 217-01367)	Apr-12
Reference 30 dB Attenuator	SN: S5129 (30b)	29-Mar-11 (No. 217-01370)	Apr-12
Reference Probe ER3DV6	SN: 2328	4-Oct-10 (No. ER3-2328_Oct10)	Oct-11
DAE4	SN: 789	6-Apr-11 (No. DAE4-789_Apr11)	Apr-12
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Calibrated by:

Deton Kastrati

Laboratory Technician

Approved by:

Katja Pokovic

Technical Manager

Issued: July 12, 2011

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Certificate No: ER3-2341_Jul11 Page 1 of 10

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Glossary:

NORMx,y,z

sensitivity in free space

DCP CF

diode compression point

crest factor (1/duty_cycle) of the RF signal modulation dependent linearization parameters

A, B, C

Polarization ()

φ rotation around probe axis

Polarization 9

9 rotation around an axis that is in the plane normal to probe axis (at measurement center).

i.e., 9 = 0 is normal to probe axis

Connector Angle

information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, " IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization 9 = 0 for XY sensors and 9 = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- NORM(f)x,y,z = NORMx,y,z * frequency response (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

Certificate No: ER3-2341 Jul11

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Probe ER3DV6

SN:2341

Manufactured: June 15, 2004

Calibrated:

July 12, 2011

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2341

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)	
Norm $(\mu V/(V/m)^2)$	orm (μV/(V/m) ²) 1.67		1.69	± 10.1 %	
DCP (mV) ^B	97.0	97.1	99.5		

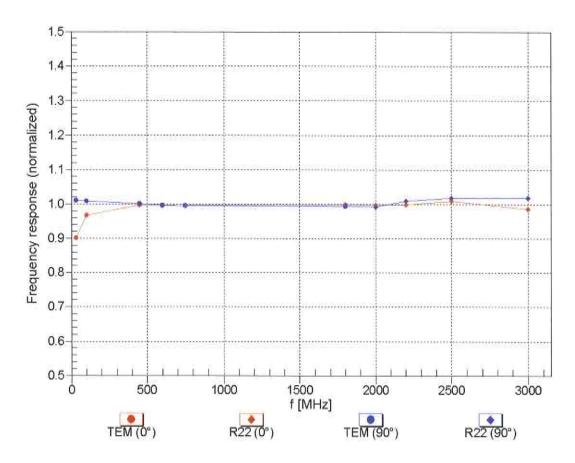
Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^E (k=2)
10000	CW 0.00 X	X	0.00	0.00	1.00	89.5	±2.5 %	
			Υ	0.00	0.00	1.00	116.2	
			Z	0.00	0.00	1.00	105.8	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

B Numerical linearization parameter: uncertainty not required.
E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the

Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)

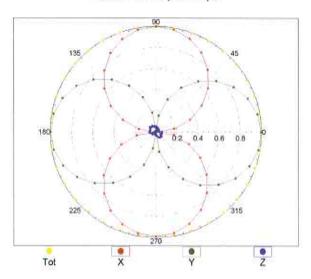


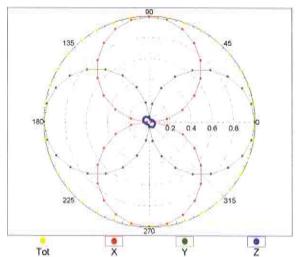
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$

f=600 MHz,TEM,0°

f=2500 MHz,R22,0°

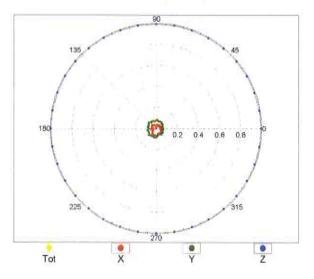


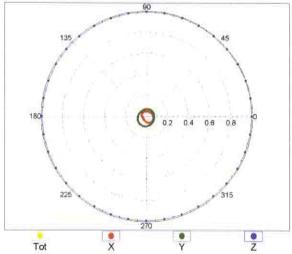


Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$

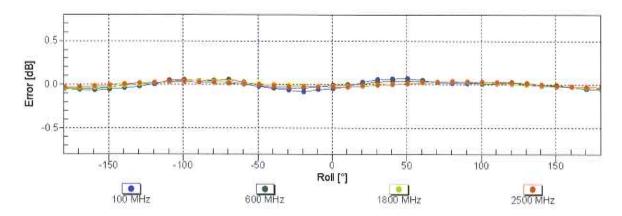
f=600 MHz,TEM,90°

f=2500 MHz,R22,90°



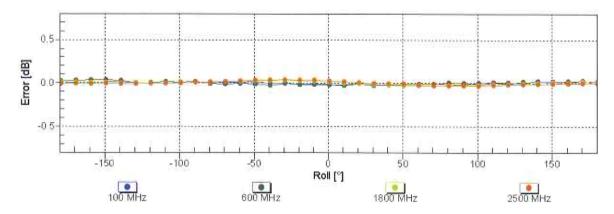


Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



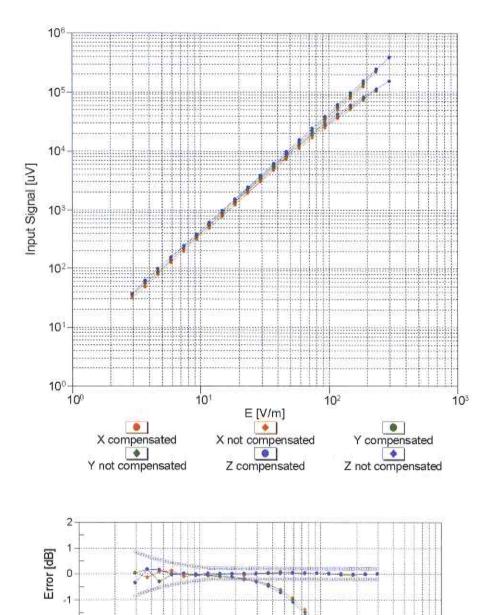
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Dynamic Range f(E-field) (TEM cell, f = 900 MHz)



100 101 102 103

E [V/m]

X compensated X not compensated Y compensated

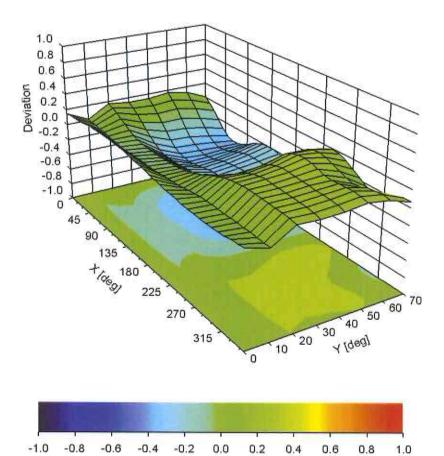
Y not compensated Z compensated Z not compensated

Uncertainty of Linearity Assessment: ± 0.6% (k=2)

-2

Deviation from Isotropy in Air

Error (ϕ, ϑ) , f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2341

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-59.2
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Client

Kyocera USA

Certificate No: H3-6029 Jul11

Accreditation No.: SCS 108

CALIBRATION CERTIFICATE

Object

H3DV5 - SN:6029

Calibration procedure(s)

QA CAL-03.v6, QA CAL-25.v4

Calibration procedure for H-field probes optimized for close near field

evaluations in air

Calibration date:

July 20, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	31-Mar-11 (No. 217-01372)	Apr-12
Power sensor E4412A	MY41498087	31-Mar-11 (No. 217-01372)	Apr-12
Reference 3 dB Attenuator	SN: S5054 (3c)	29-Mar-11 (No. 217-01369)	Apr-12
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-11 (No. 217-01367)	Apr-12
Reference 30 dB Attenuator	SN: S5129 (30b)	29-Mar-11 (No. 217-01370)	Apr-12
Reference Probe H3DV6	SN: 6182	23-Jun-11 (No. H3-6182_Jun11)	Jun-12
DAE4	SN: 789	6-Apr-11 (No. DAE4-789_Apr11)	Apr-12
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Name Function Signature
Calibrated by: Katja Pokovic Technical Manager

Approved by:

Niels Kuster Quality Manager

Issued: July 20, 2011

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Glossary:

NORMx,y,z

sensitivity in free space

DCP CF diode compression point

A. B. C

crest factor (1/duty_cycle) of the RF signal modulation dependent linearization parameters

A, B, C Polarization φ

φ rotation around probe axis

Polarization 9

9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

Connector Angle

information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

 a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ = 0 for XY sensors and θ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- X,Y,Z(f)_a0a1a2= X,Y,Z_a0a1a2* frequency_response (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of
 power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the
 maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the X_a0a1a2 (no uncertainty required).

Certificate No: H3-6029_Jul11 Page 2 of 10

Probe H3DV5

SN:6029

Manufactured: May 5, 1998 Calibrated:

July 20, 2011

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

DASY/EASY - Parameters of Probe: H3DV5 - SN:6029

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(A/m / \sqrt{(mV)})$	a0	2.80E-003	2.84E-003	2.89E-003	± 5.1 %
Norm $(A/m / \sqrt{(mV)})$	a1	-8.85E-005	-2.00E-004	1.00E-004	± 5.1 %
Norm $(A/m / \sqrt{(mV)})$	a2	-2.32E-005	1.74E-006	9.61E-005	± 5.1 %
DCP (mV) ^B		92.8	88.4	91.9	

Modulation Calibration Parameters

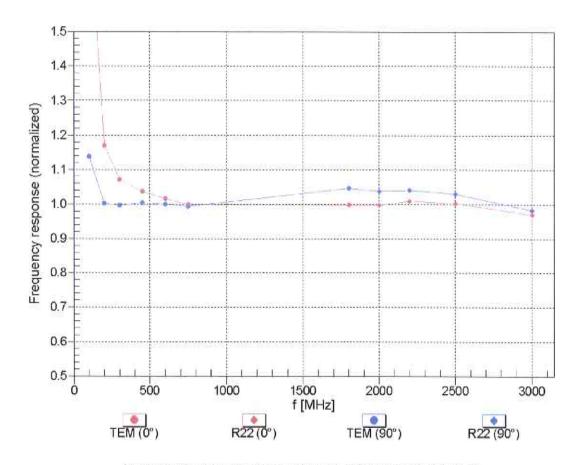
UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^E (k=2)
10000	CW 0.00 X	Х	0.00	0.00	1.00	93.3	±2.7 %	
			Y	0.00	0.00	1.00	94.6	
			Z	0.00	0.00	1.00	92.5	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the max, deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

Frequency Response of H-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)

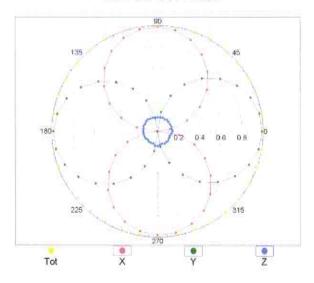


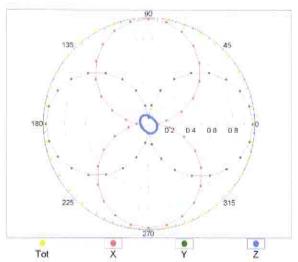
Uncertainty of Frequency Response of H-field: ± 6.3% (k=2)

Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$

f=600 MHz,TEM,0°

f=1800 MHz,R22,0°

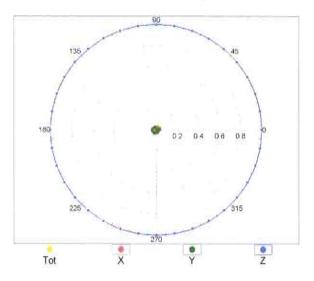


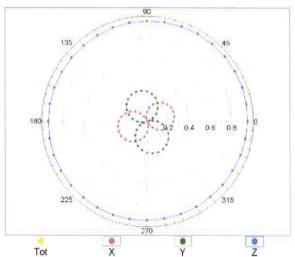


Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$

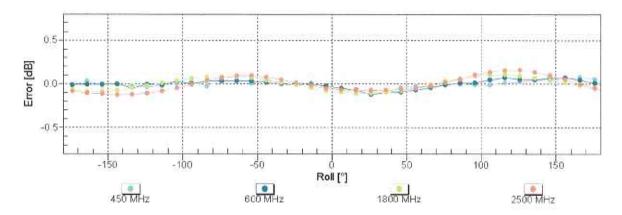
f=600 MHz,TEM,90°

f=1800 MHz,R22,90°



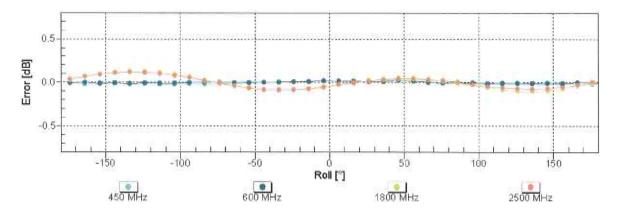


Receiving Pattern (ϕ), θ = 0°



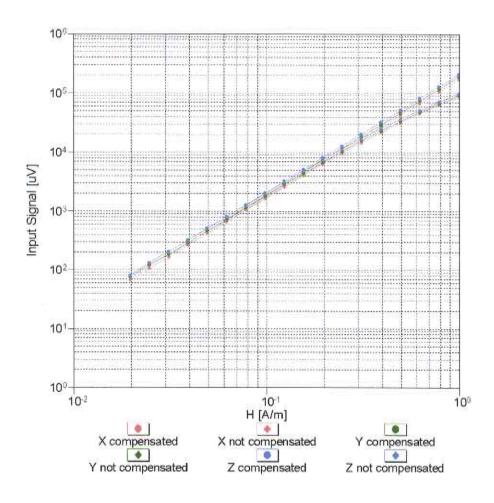
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

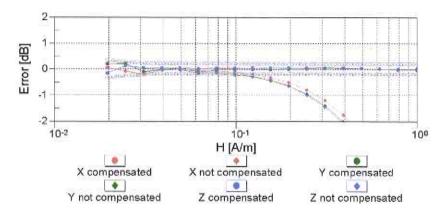
Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Dynamic Range f(H-field) (TEM cell, f = 900 MHz)

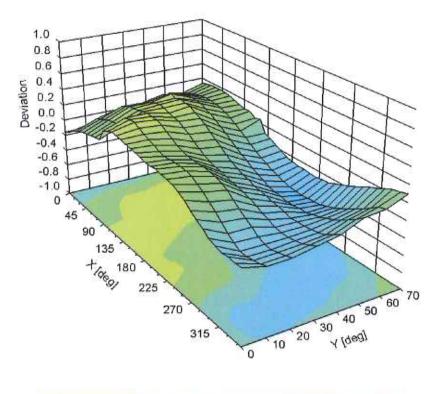


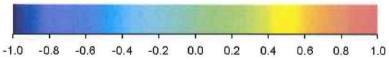


Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Deviation from Isotropy in Air

Error (φ, θ), f = 900 MHz





Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

DASY/EASY - Parameters of Probe: H3DV5 - SN:6029

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	166
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm