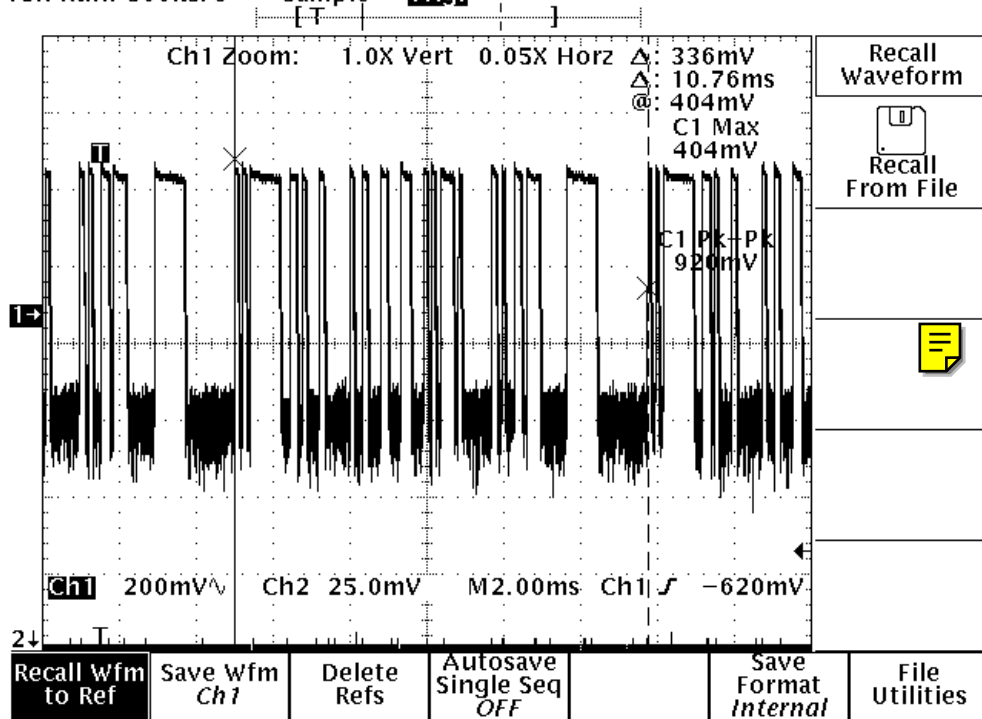
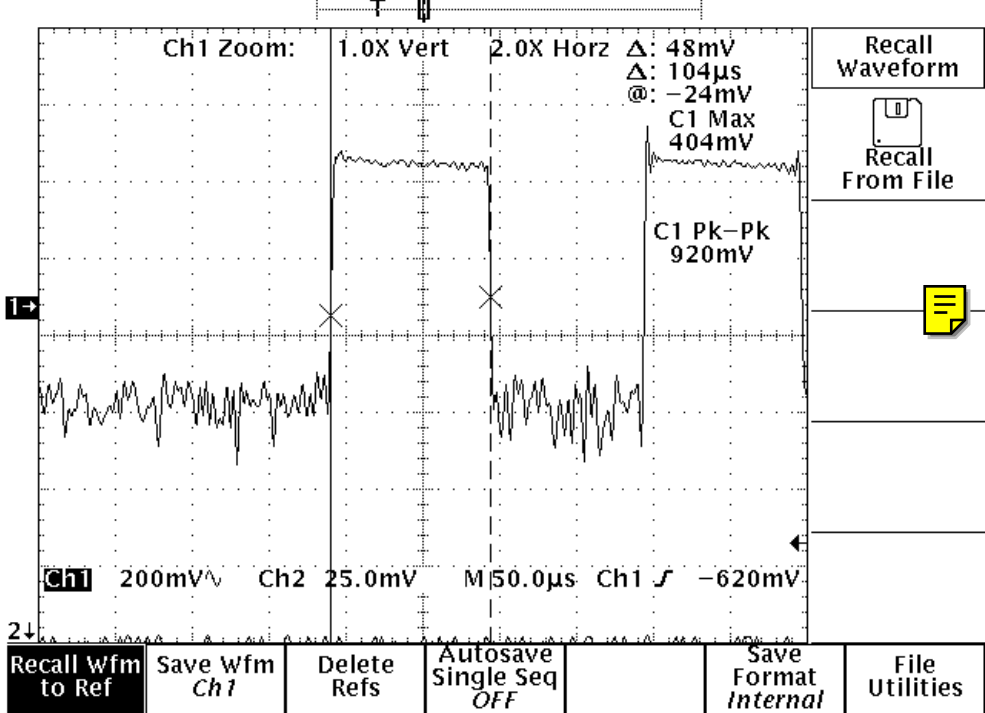


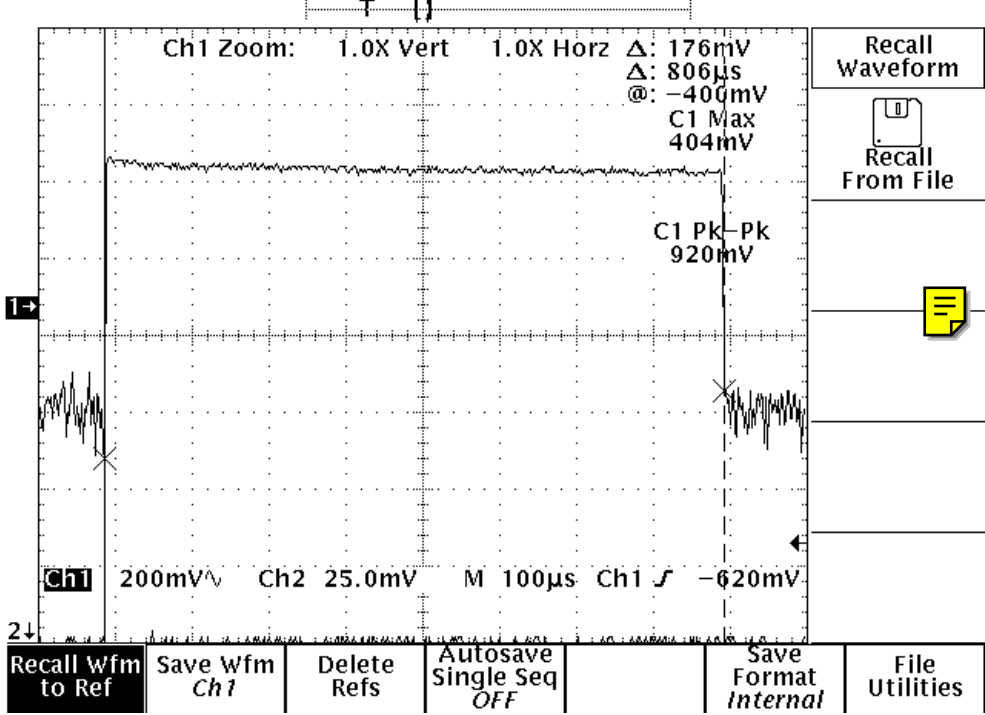
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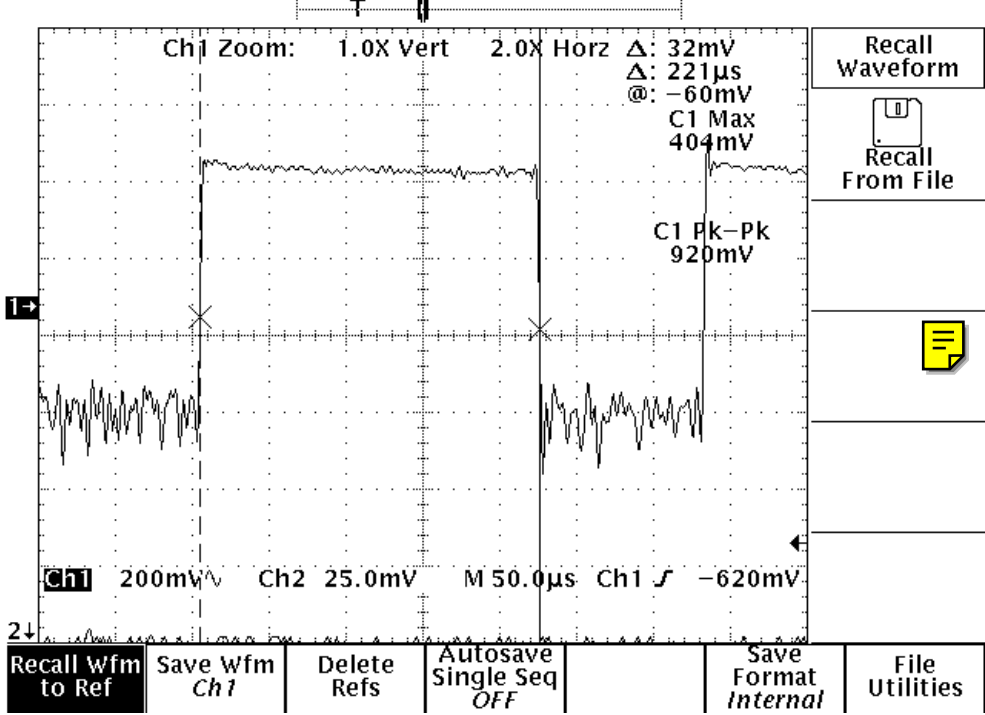


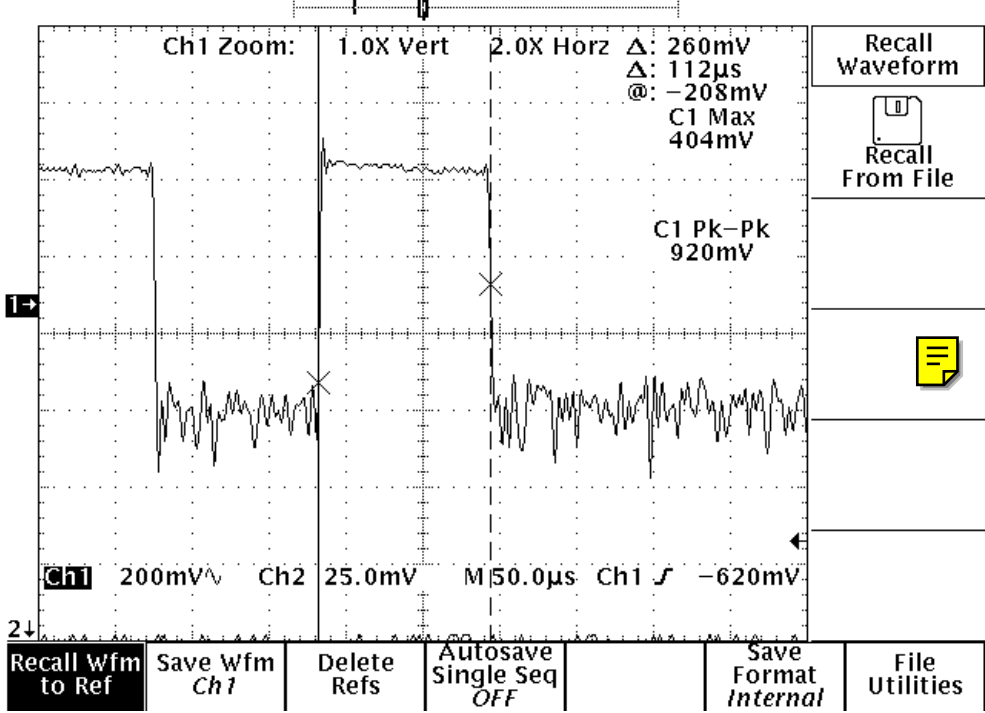


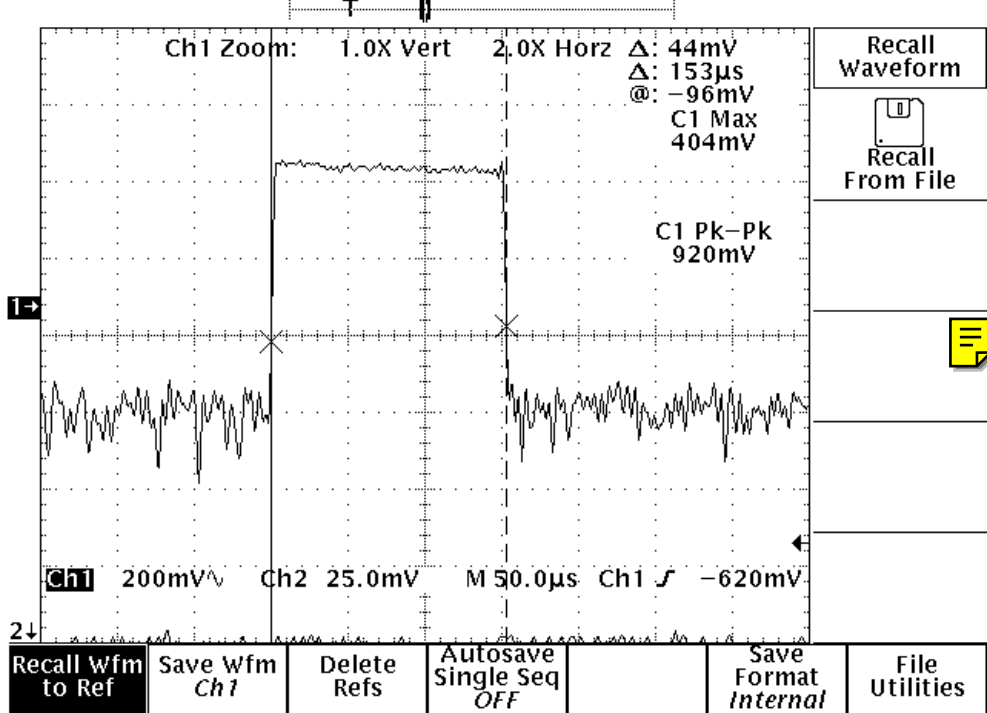
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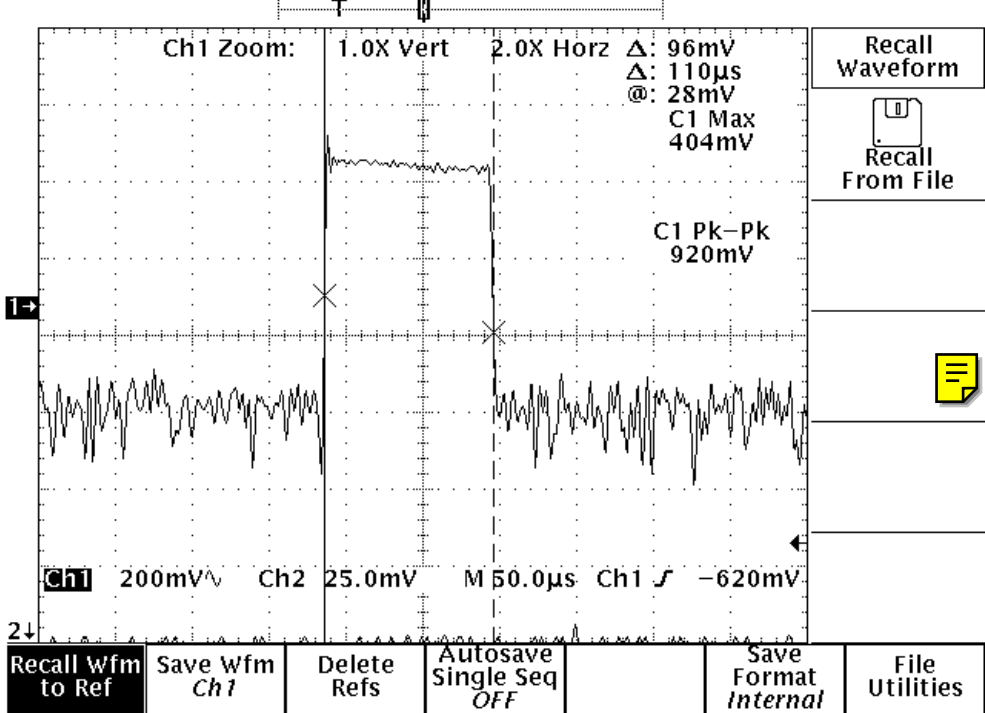


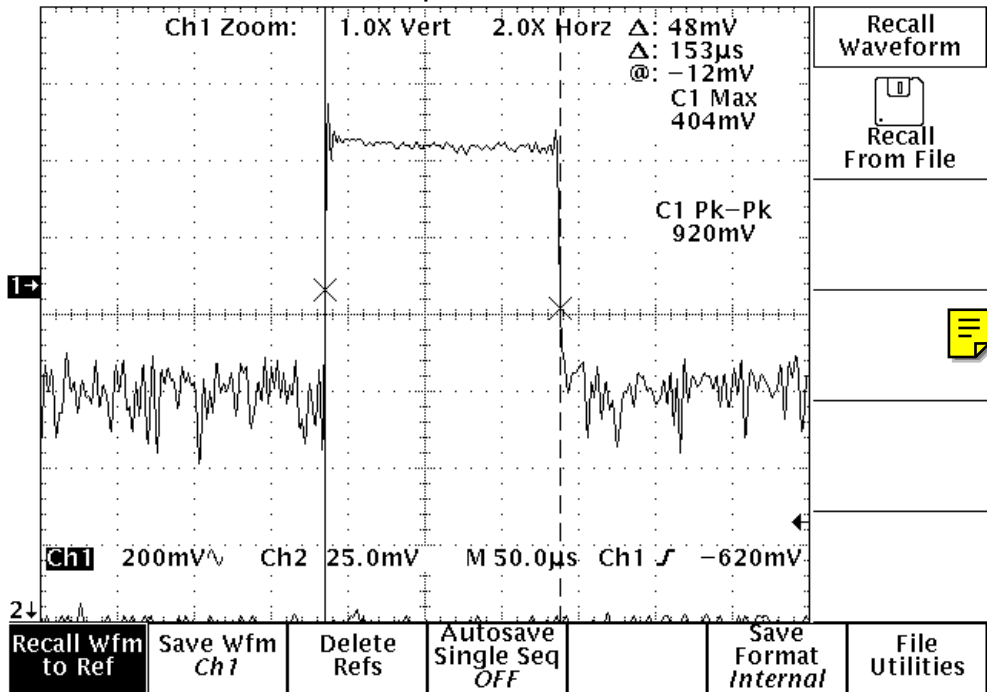


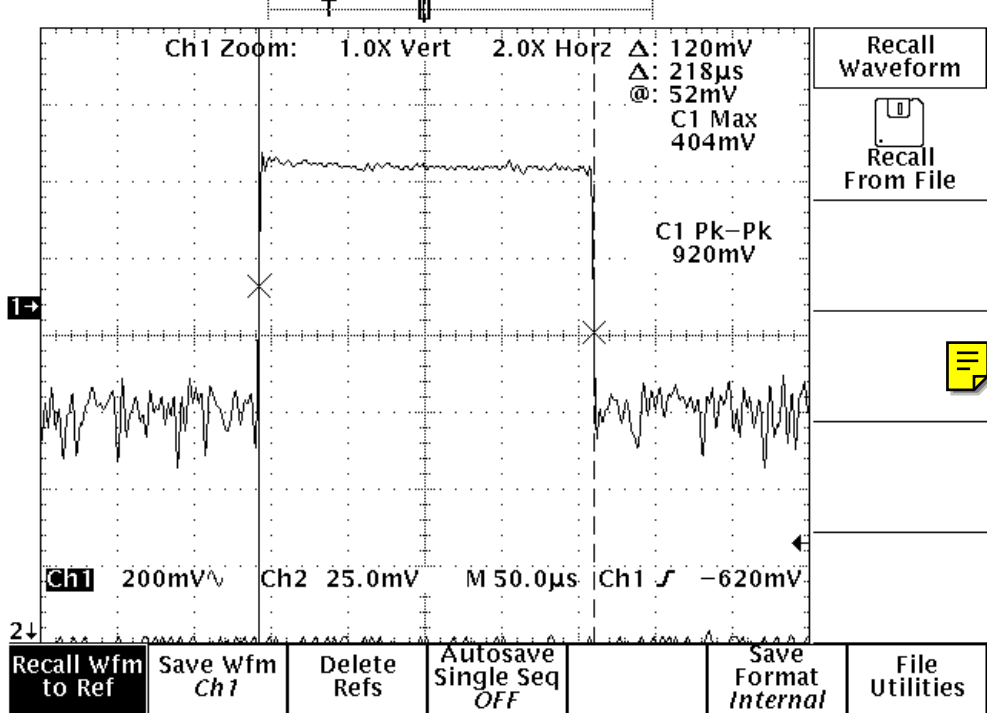


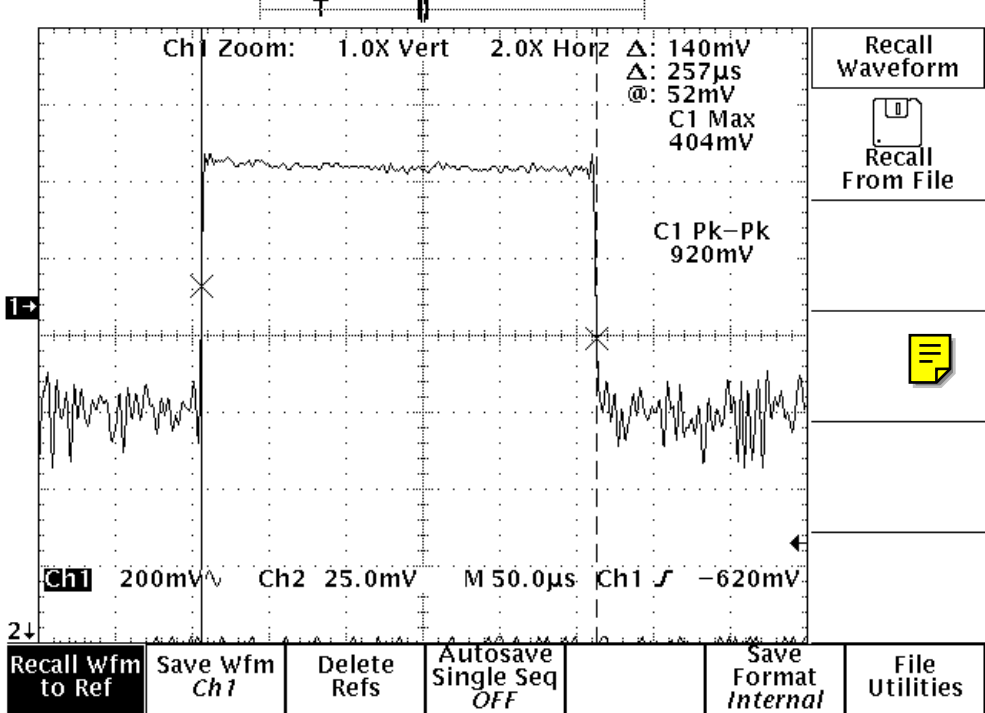


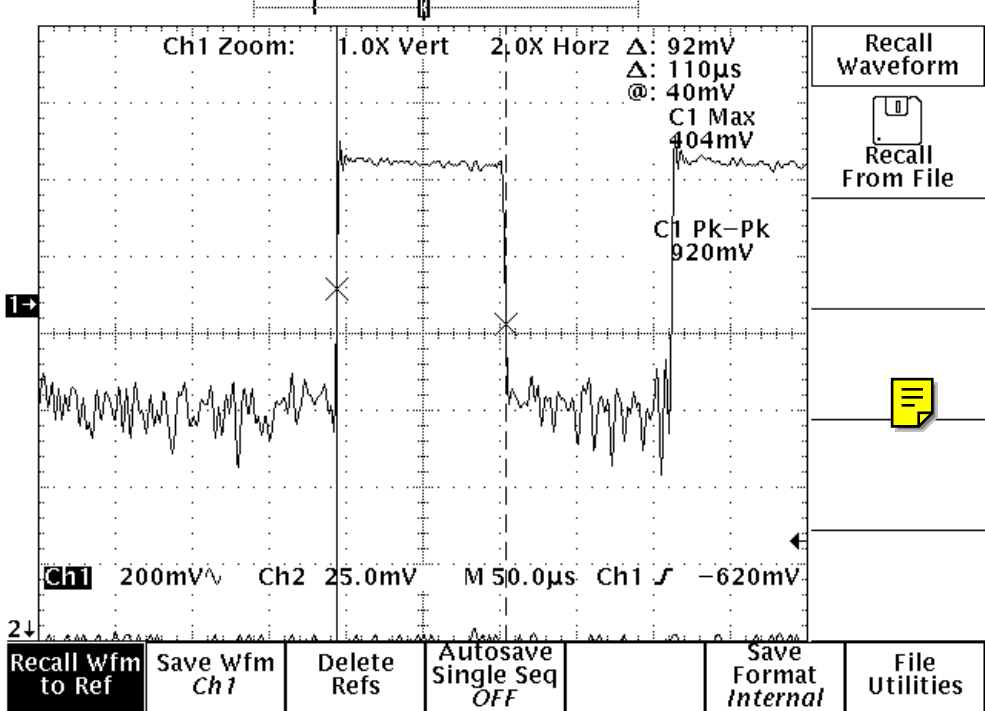




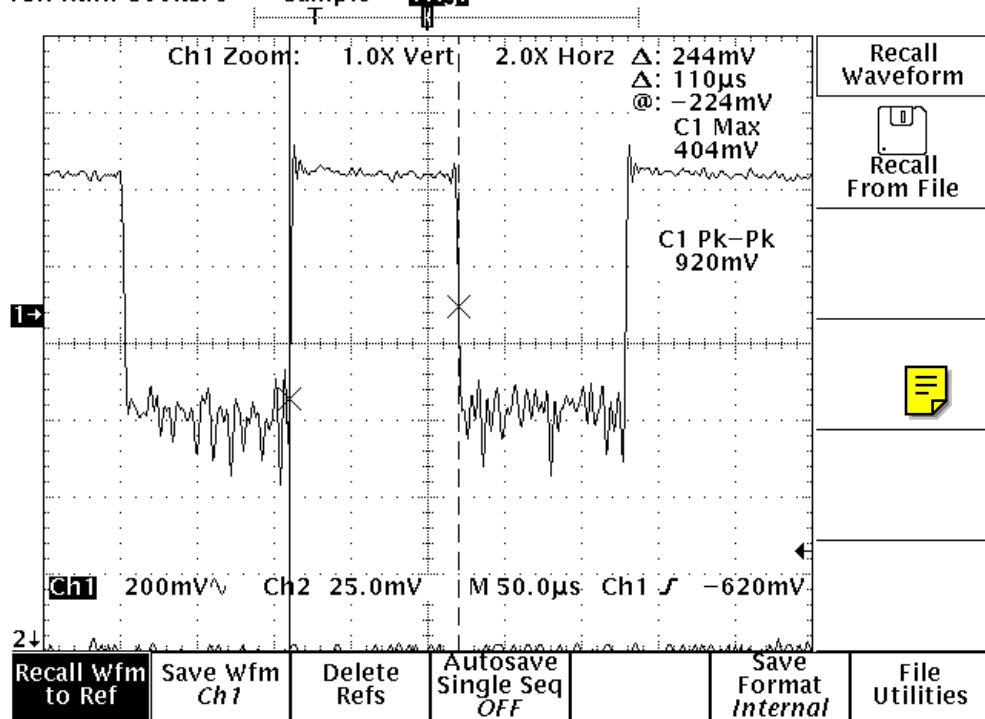


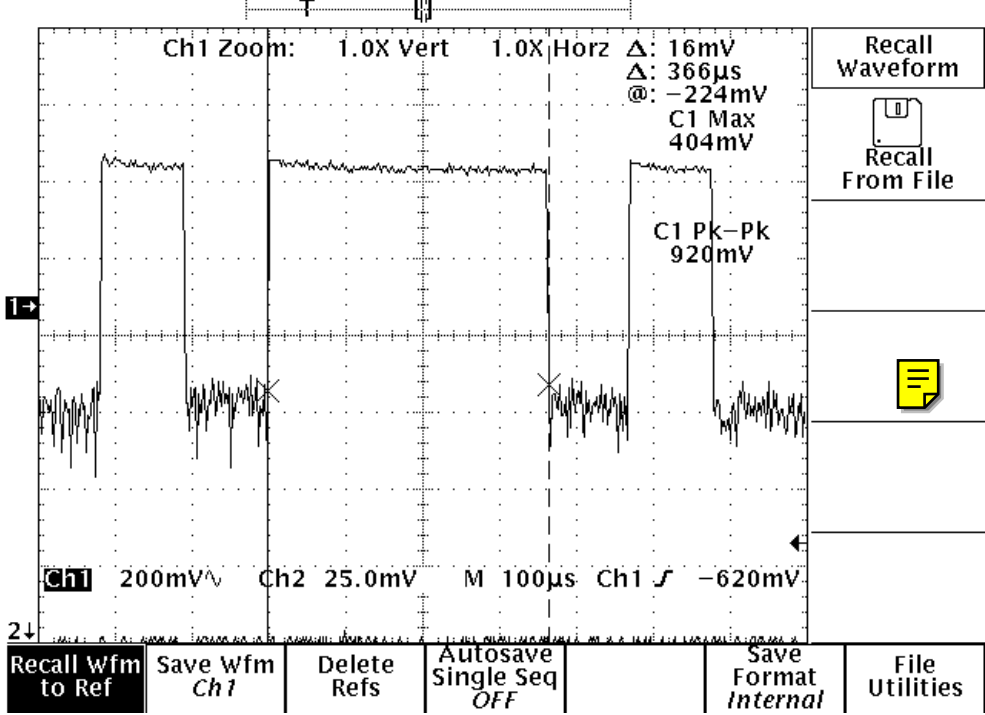


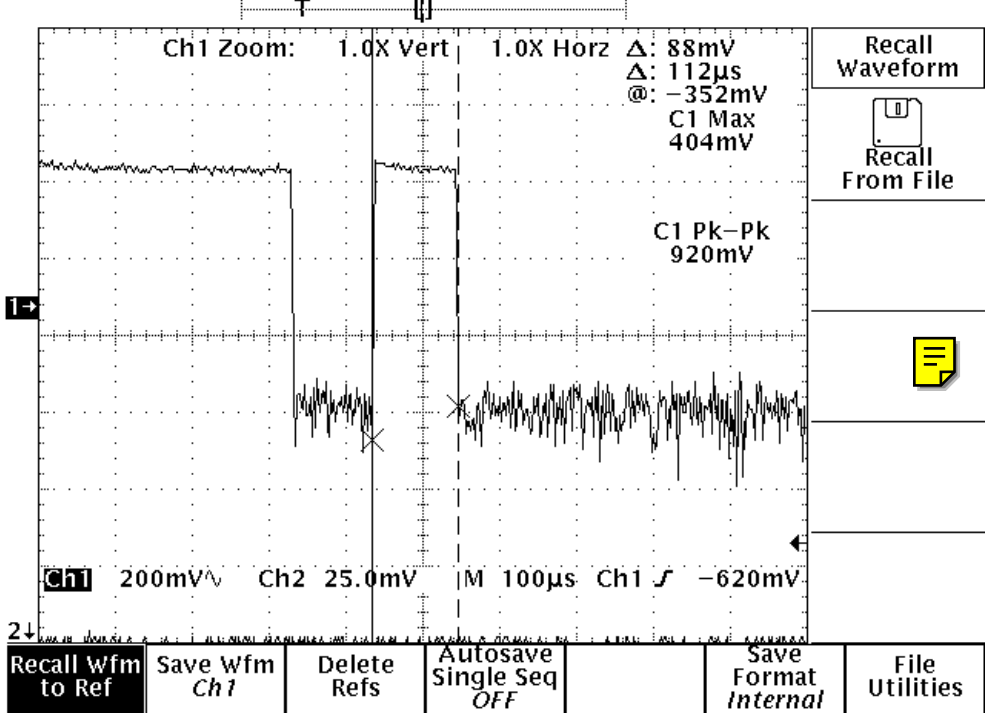




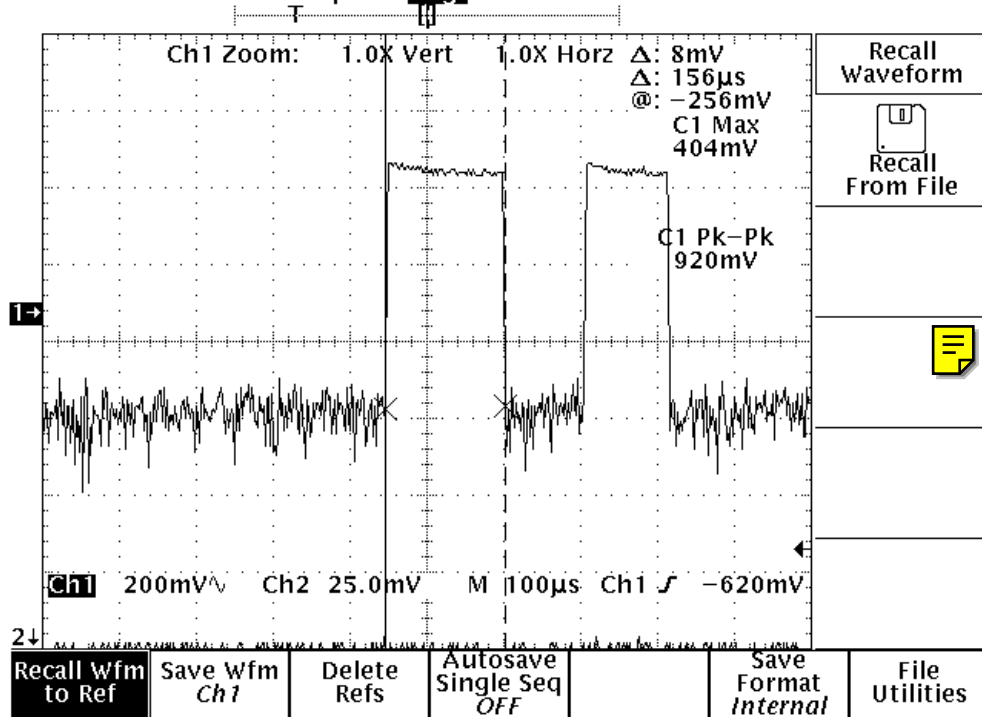
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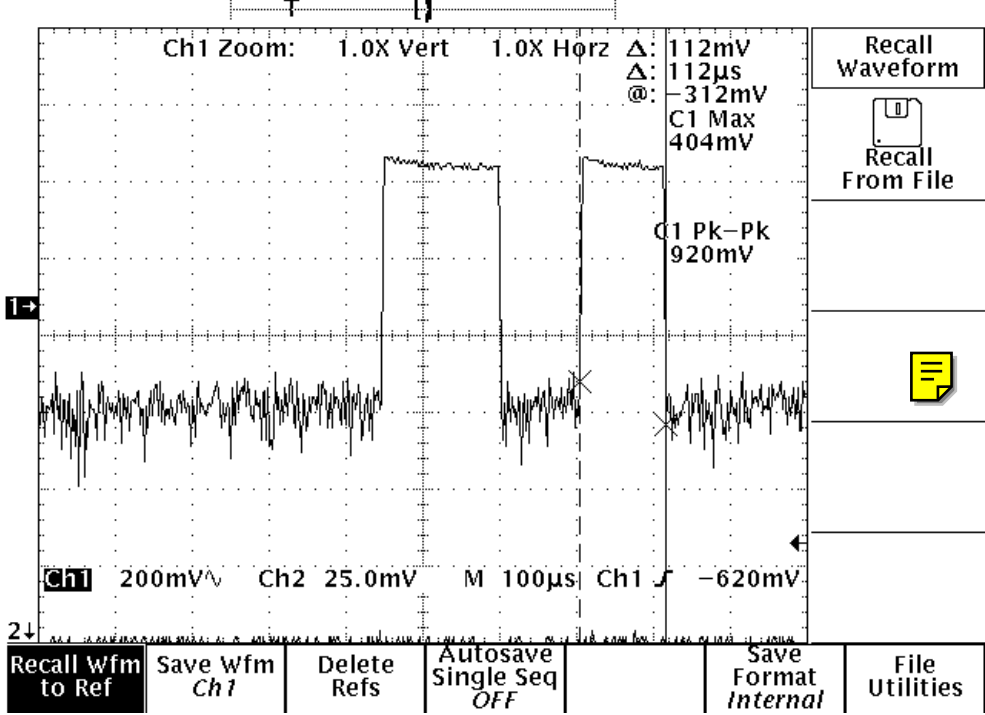


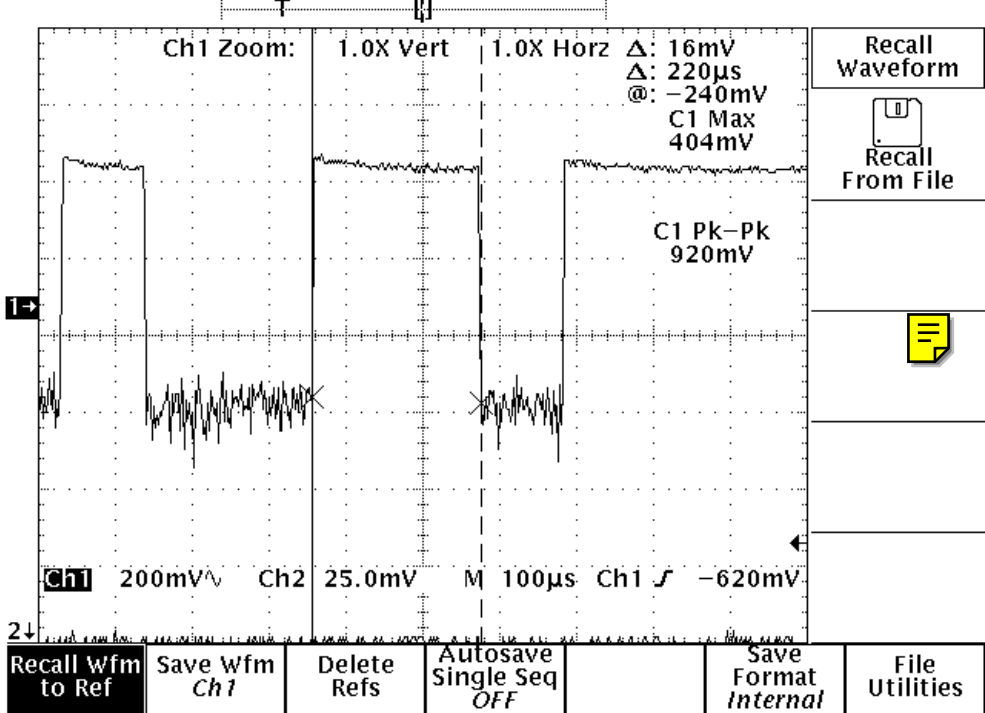




Trig?

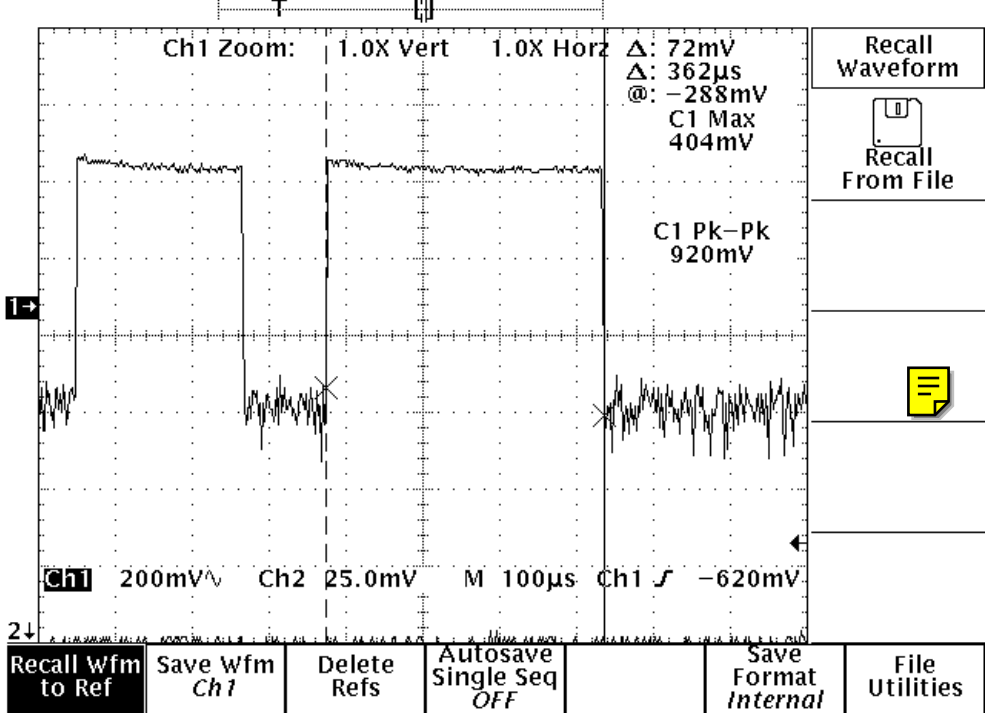


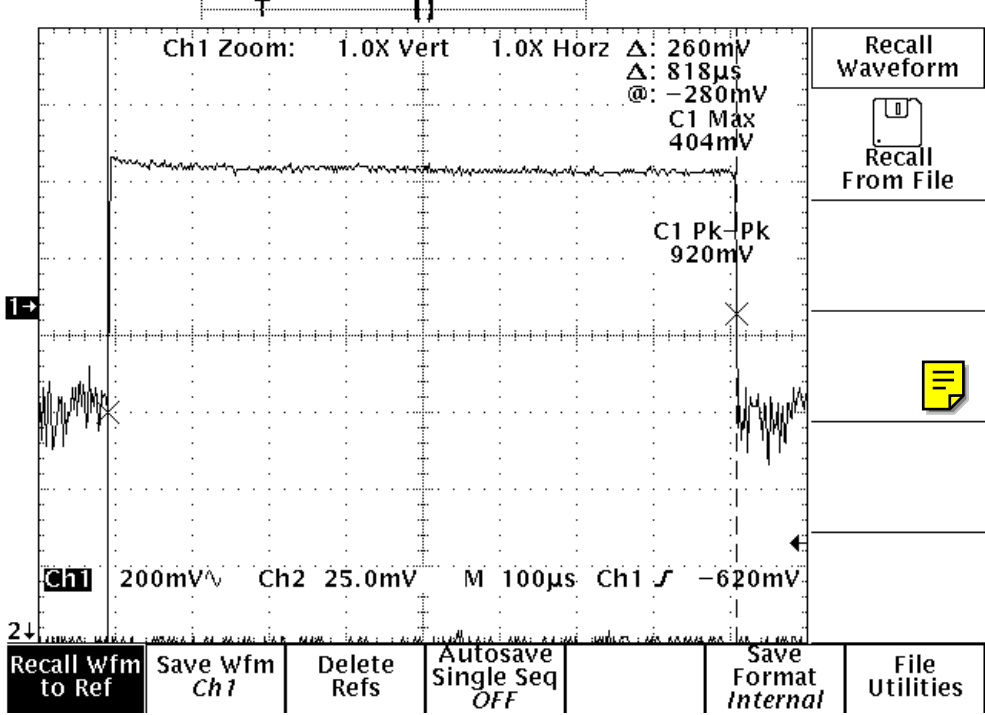




Recall Waveform

Recall From File





Pulse Number	time of pulse (uS)
1	104
2	104
3	806
4	221
5	112
6	153
7	110
8	153
9	218
10	257
11	110
12	110
13	366
14	112
15	156
16	112
17	220
18	362
19	818
Total:	4604

Total Duty Cycle = 4.604 mS / 10.76 mS = 42.79%

MS Series Encoder Data Structure

The MS Series encoder is designed to securely register button presses or switch closures over a wireless link for remote control applications. It will turn eight parallel input lines into a secure, encoded serial bit stream output.

The MS Series algorithm is designed to create a data stream with 5 High Data Bits at 9600bps.

Logic State Description:

1 = HIGH
0 = LOW



Total bits, including start and stop bits = 80

Total 1's = 40

Total 0's = 40

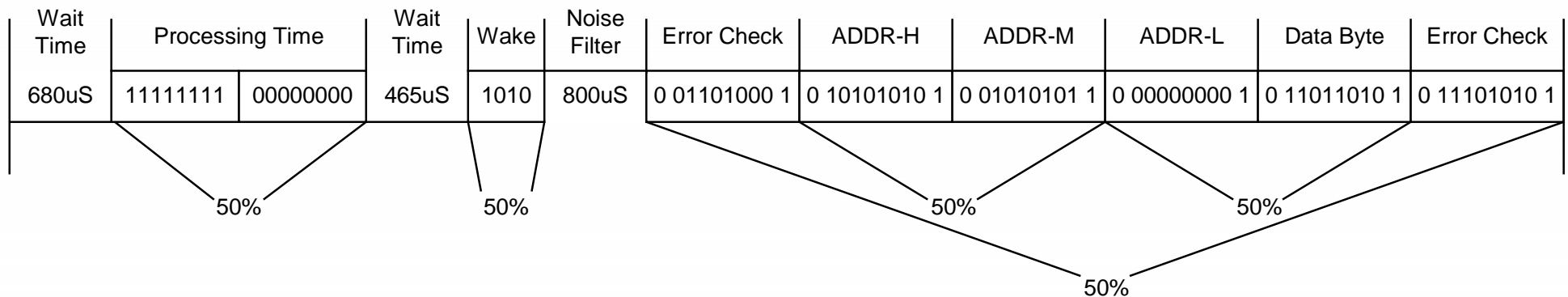
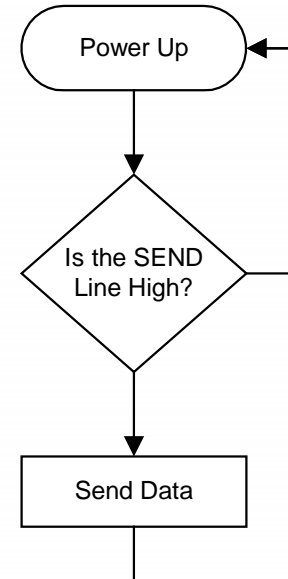
Value for each bit per baud rate:

2400bps = 417uS or 1.18% of duty cycle

9600bps = 104uS or 1.01% of duty cycle

19200bps = 52uS or 0.85% of duty cycle

28800bps = 35uS or 0.74% of duty cycle



$$\begin{aligned}
 \text{Duty Cycle} &= \frac{\text{Time High}}{\text{Total Time}} \longrightarrow \frac{37 \text{ bits} + 800\text{uS}}{80 \text{ bits} + 680\text{uS} + 465\text{uS} + 800\text{uS}} \longrightarrow \frac{(37 \times 104\text{uS}) + 800\text{uS}}{(80 \times 104\text{uS}) + 1,945\text{uS}} = \frac{4,648\text{uS}}{10,265\text{uS}} = 45.28\%
 \end{aligned}$$