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Appendix 4. Photographs

This appendix contains the following photographs:

Photo Reference Number	Title
PHT/72900JD03/001	Test configuration for the measurement of Specific Absorption Rate (SAR)
PHT/72900JD03/002	Front of EUT Facing Phantom With Wrist Strap
PHT/72900JD03/003	Rear of EUT Facing Phantom With Wrist Strap
PHT/72900JD03/004	Front of EUT Facing Phantom With Neck Strap
PHT/72900JD03/005	Rear of EUT Facing Phantom With Neck Strap
PHT/72900JD03/006	Touch Left With Neck Strap
PHT/72900JD03/007	Touch Left With Wrist Strap
PHT/72900JD03/008	Touch Right With Neck Strap
PHT/72900JD03/009	Touch Right With Wrist Strap
PHT/72900JD03/010	Front of EUT With Wrist Strap
PHT/72900JD03/011	Rear of EUT With Wrist Strap
PHT/72900JD03/012	Front of EUT With Neck Strap
PHT/72900JD03/013	Rear of EUT With Neck Strap
PHT/72900JD03/014	Internal View of EUT
PHT/72900JD03/015	1900MHz Body Fluid Level
PHT/72900JD03/016	1900MHz Head Fluid Level
PHT/72900JD03/017	900MHz Body Fluid Level
PHT/72900JD03/018	900MHz Head Fluid Level

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PHT/72900JD03/001: Test configuration for the measurement of Specific Absorption Rate (SAR)



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PHT/72900JD03/002: Front of EUT Facing Phantom With Wrist Strap



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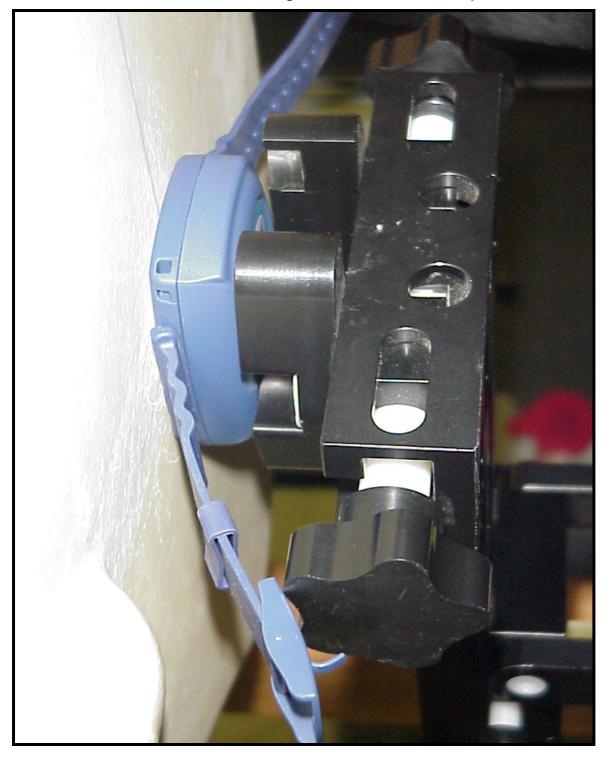
Issue Date: 14 February 2008

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PHT/72900JD03/003: Rear of EUT Facing Phantom With Wrist Strap



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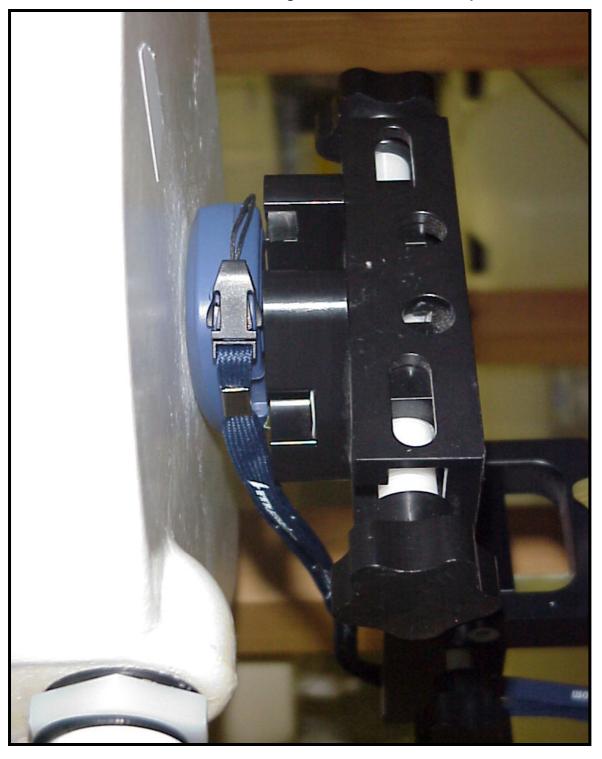
Issue Date: 14 February 2008

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PHT/72900JD03/004: Front of EUT Facing Phantom With Neck Strap



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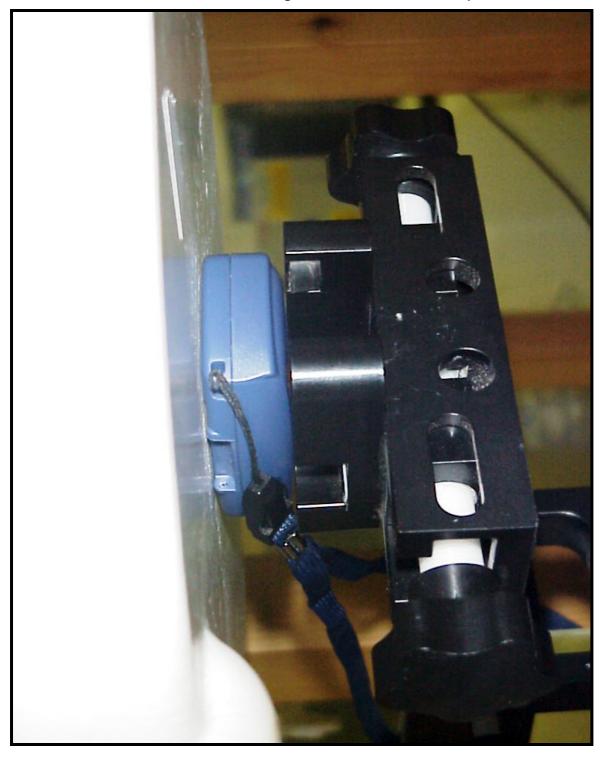
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PHT/72900JD03/005: Rear of EUT Facing Phantom With Neck Strap



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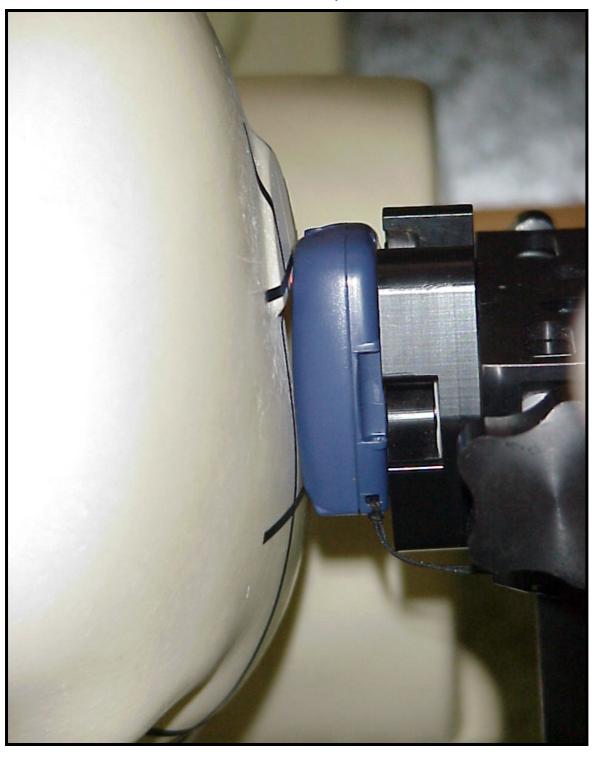
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PHT/72900JD03/006: Touch Left With Neck Strap



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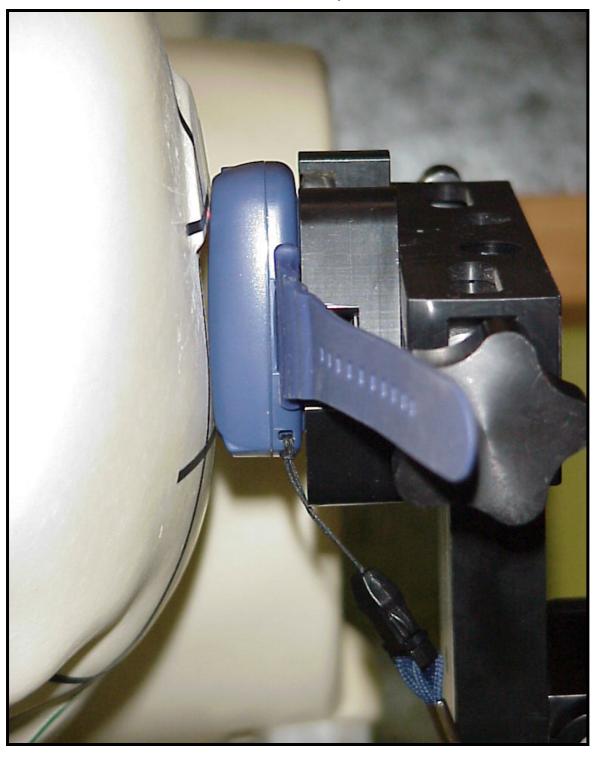
Issue Date: 14 February 2008

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PHT/72900JD03/007: Touch Left With Wrist Strap



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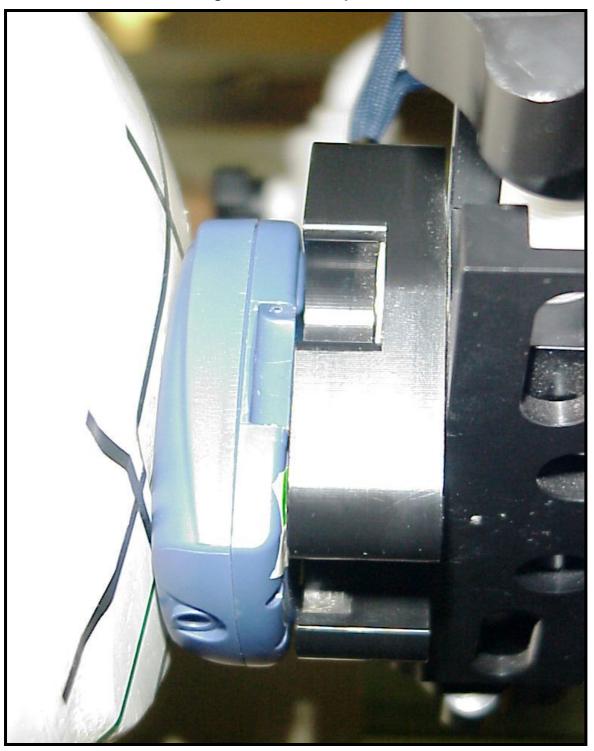
Issue Date: 14 February 2008

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PHT/72900JD03/008: Touch Right With Neck Strap



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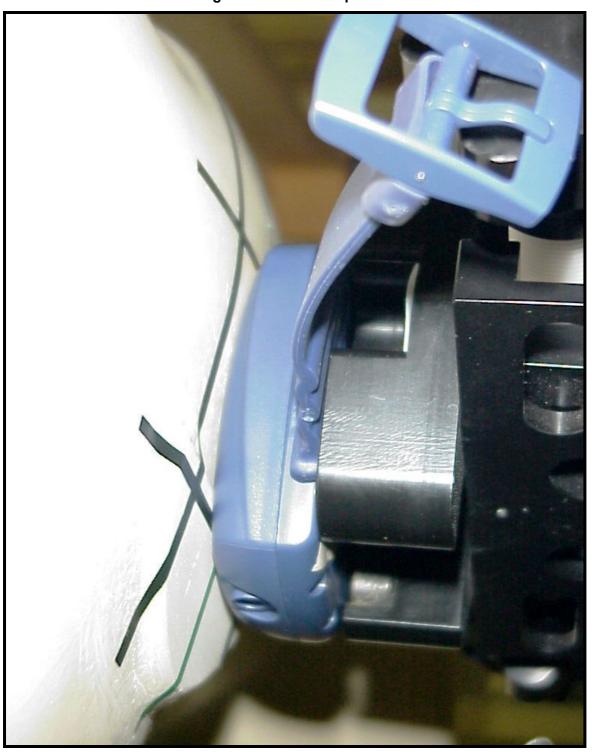
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PHT/72900JD03/009: Touch Right With Wrist Strap



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PHT/72900JD03/010: Front of EUT With Wrist Strap



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PHT/72900JD03/011: Rear of EUT With Wrist Strap



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PHT/72900JD03/012: Front of EUT With Neck Strap



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PHT/72900JD03/013: Rear of EUT With Neck Strap



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PHT/72900JD03/014: Internal View of EUT



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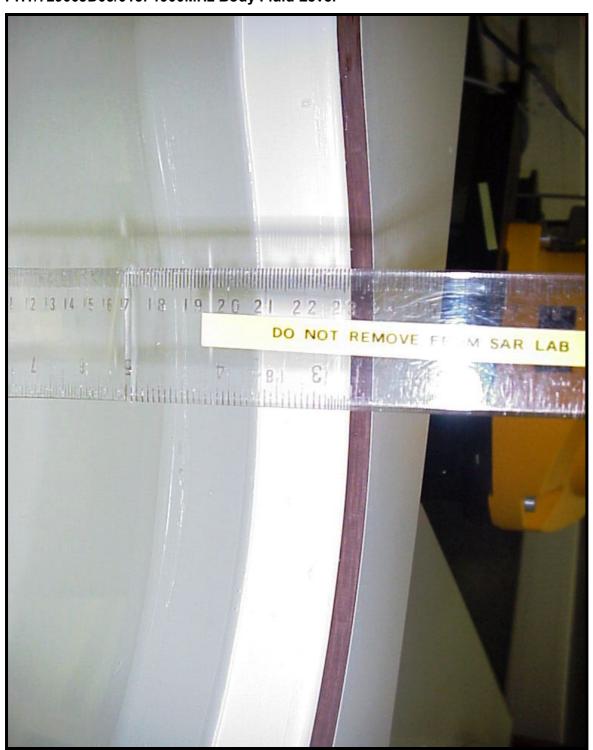
Issue Date: 14 February 2008

Test of: Aerotel Medical Systems (1998) Ltd.

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PHT/72900JD03/015: 1900MHz Body Fluid Level



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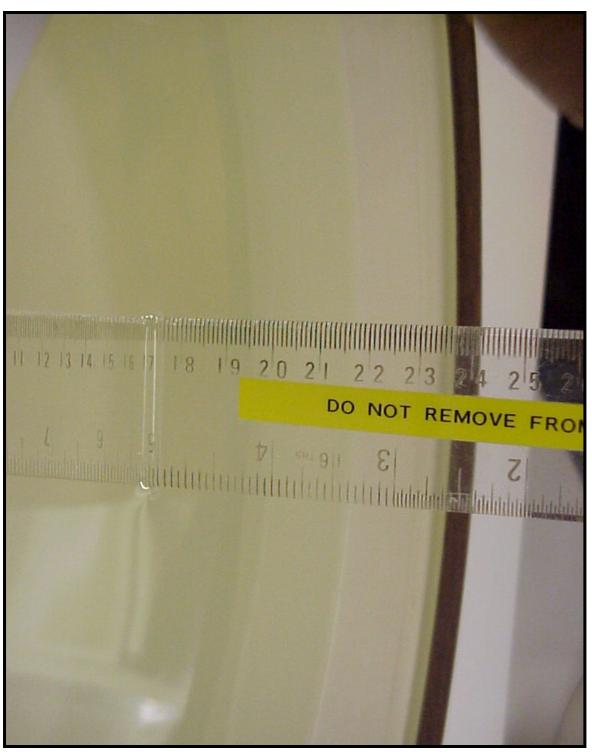
Issue Date: 14 February 2008

Test of: Aerotel Medical Systems (1998) Ltd.

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PHT/72900JD03/016: 1900MHz Head Fluid Level



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Test of: Aerotel Medical Systems (1998) Ltd.

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PHT/72900JD03/017: 900MHz Body Fluid Level



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PHT/72900JD03/018: Hz Head Fluid Level



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Appendix 5. Validation of System

Prior to the assessment, the system was verified in the flat region of the phantom.

A 900 MHz & 1900 MHz dipole were used. A forward power of 250 mW was applied to the dipole and the system was verified to a tolerance of $\pm 5\%$ for the 900 MHz & 1900 MHz dipole. The applicable verification (normalised to 1 Watt).

Date: 22/01/2008

Validation Dipole and Serial Number: D900V2 SN:124

Simulant	Frequency (MHz)	Room Temperature	Liquid Temperature	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)							
				ε _r	41.50	39.74	-0.04	5.00							
Head	900	22.0 °C	22 0 0€	22 N °C 22 N °C	22.0 °C	22 0 ℃	22.0 °C	22 0 °C	22 0 °C	22 0 °C	σ	0.97	0.94	-0.03	5.00
71cdd 300 22.0 C	22.0 0	1g SAR	10.60	10.24	-3.40	5.00									
		10g SAR	6.84	6.56	-4.09	5.00									

Date: 22/01/2008

Validation Dipole and Serial Number: D900V2 SN:185

Simulant	Frequency (MHz)	Room Temperature	Liquid Temperature	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)				
				ε _r	55.00	52.71	-0.04	5.00				
Body	900	22.0 °C	22.0 °C	22.0 °C 22.0 °C	22.0 °C	22 N °C	22 0 ℃	σ	1.05	1.02	-0.03	5.00
Body	300					1g SAR	10.50	10.44	-0.57	5.00		
				10g SAR	6.88	6.76	-1.74	5.00				

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Date: 21/01/2008

Validation Dipole and Serial Number: D1900V2:SN:540

Simulant	Frequency (MHz)	Room Temperature	Liquid Temperature	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)				
				ε _r	41.06	40.00	2.65	5.00				
Head	1900	22 0 0€	22 0 0€	22.0 °C	22.0.90	22 0 0€	22.0 °C	σ	1.46	1.40	4.36	5.00
1900 22.0 C	22.0 0	1g SAR	36.10	37.28	3.27	5.00						
				10g SAR	19.30	18.68	-3.21	5.00				

Date: 21/01/2008

Validation Dipole and Serial Number:D1900V2:SN:540

Simulant	Frequency (MHz)	Room Temperature	Liquid Temperature	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)				
				ε _r	53.30	51.70	-0.03	5.00				
Body	1900	22 N ºC	22 0 ⁰€	22.0 °C	22.0 °C	22.0 °C	22.0 °C	σ	1.52	1.57	0.03	5.00
Body	1300	22.0 0	22.0	22.0 0				1g SAR	38.00	39.40	3.68	5.00
				10g SAR	20.70	20.24	-2.22	5.00				

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Appendix 6. Simulated Tissues

The body mixture consists of water and glycol. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient	Frequency
	1800/1900 MHz Body
De-Ionised Water	69.79%
Diglycol Butyl Ether (DGBE)	30.00%
Salt	0.20%

Ingredient	Frequency
	1800/1900 MHz Head
De-Ionised Water	55.41%
Diglycol Butyl Ether (DGBE)	44.51%
Salt	0.08%

Ingredient	Frequency
	835/850/900 MHz Body
De-Ionised Water	50.75%
Sugar	48.21%
Salt	0.94%
Kathon	0.10%

Ingredient	Frequency		
	835/850/900 MHz Head		
Propanediol	64.81%		
De-Ionised Water	34.40%		
Salt	0.79%		

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Appendix 7. DASY4 System Details

A.7.1. DASY4 SAR Measurement System

RFI Global Services Ltd, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching mulitplexer, a fast 16-bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

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A.7.2. DASY4 SAR System Specifications

Robot System

Positioner:	Stäubli Unimation Corp. Robot Model: RX90L
Repeatability:	0.025 mm
No. of Axis:	6
Serial Number:	F00/SD89A1/A/01
Reach:	1185 mm
Payload:	3.5 kg
Control Unit:	CS7
Programming Language:	V+

Data Acquisition Electronic (DAE) System

Serial Number:	DAE3 SN:394
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Cell Controller

PC:	Dell Precision 340
Operating System:	Windows 2000
Data Card:	DASY4 Measurement Server
Serial Number:	1080

Data Converter

Features:	Signal Amplifier, multiplexer, A/D converted and control logic.
Software:	DASY4 Software
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock.

PC Interface Card

24 bit (64 MHz) DSP for real time processing Link to DAE3 16 nit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.
to reset an est emergency step estipation reset.

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DASY4 SAR System Specifications (Continued)

E-Field Probe

Model:	ET3DV6
Serial No:	1528
Construction:	Triangular core fibre optic detection system
Frequency:	10 MHz to 3 GHz
Linearity:	±0.2 dB (30 MHz to 3 GHz)
Probe Length (mm):	337
Probe Diameter (mm):	12
Tip Length (mm):	10
Tip Diameter (mm):	6.8
Sensor X Offset (mm):	2.7
Sensor Y Offset (mm):	2.7
Sensor Z Offset (mm):	2.7

Phantom

Phantom:	SAM Phantom
Shell Material:	Fibreglass
Thickness:	2.0 ±0.1 mm