

# EZ-BLE<sup>TM</sup> PSoC<sup>®</sup> Module

### **General Description**

The Cypress CYBLE-014008-00 is a fully certified and qualified module supporting Bluetooth<sup>®</sup> Low Energy (BLE) wireless communication. The CYBLE-014008-00 is a turnkey solution and includes onboard crystal oscillators, trace antenna, passive components, and the Cypress PSoC<sup>®</sup> 4 BLE. Refer to the PSoC<sup>®</sup> 4 BLE datasheet for additional details on the capabilities of the PSoC<sup>®</sup> 4 BLE device used on this module.

The EZ-BLE<sup>TM</sup> PSoC<sup>®</sup> module is a scalable and reconfigurable platform architecture. It combines programmable and reconfigurable analog and digital blocks with flexible automatic routing. The CYBLE-014008-00 also includes digital programmable logic, high-performance analog-to-digital conversion (ADC), opamps with comparator mode, and standard communication and timing peripherals.

The CYBLE-014008-00 includes a royalty-free BLE stack compatible with Bluetooth 4.1 and provides up to 25 GPIOs in a small  $11 \times 11 \times 1.80$  mm package.

The CYBLE-014008-00 is a complete solution and an ideal fit for applications seeking a highly integrated BLE wireless solution.

#### **Module Description**

- Module size: 11.0 mm × 11.0 mm × 1.80 mm (with shield)
- Bluetooth 4.1 single-mode module
- Industrial temperature range: -40 °C to +85 °C
- 32-bit processor (0.9 DMIPS/MHz) with single-cycle 32-bit multiply, operating at up to 48 MHz
- 128-KB flash memory
- 16-KB SRAM memory
- Watchdog timer with dedicated internal low-speed oscillator (ILO)
- Two-pin SWD for programming
- Up to 25 GPIOs configurable as open drain high/low, pull-up/pull-down, HI-Z analog, HI-Z digial, or strong output
- Certified to FCC, CE, MIC, KC, and IC regulations
- Bluetooth SIG 4.1 qualified

#### **Power Consumption**

- TX output power: -18 dbm to +3 dbm
- Received signal strength indicator (RSSI) with 1-dB resolution
- TX current consumption of 15.6 mA (radio only, 0 dbm)
- RX current consumption of 16.4 mA (radio only)
- Low power mode support
  - □ Deep Sleep: 1.3 µA with watch crystal oscillator (WCO) on
  - ☐ Hibernate: 150 nA with SRAM retention
  - ☐ Stop: 60 nA with XRES wakeup

#### **Programmable Analog**

- Four opamps with reconfigurable high-drive external and high-bandwidth internal drive, comparator modes, and ADC input buffering capability; can operate in Deep-Sleep mode.
- 12-bit, 1-Msps SAR ADC with differential and single-ended modes; channel sequencer with signal averaging
- Two current DACs (IDACs) for general-purpose or capacitive sensing applications on any pin
- One low-power comparator that operate in Deep-Sleep mode

### **Programmable Digital**

- Four programmable logic blocks called universal digital blocks, (UDBs), each with eight macrocells and datapath
- Cypress-provided peripheral Component library, user-defined state machines, and Verilog input

#### **Capacitive Sensing**

- Cypress CapSense Sigma-Delta (CSD) provides best-in-class SNR (> 5:1) and liquid tolerance
- Cypress-supplied software component makes capacitive-sensing design easy
- Automatic hardware-tuning algorithm (SmartSense™)

#### **Segment LCD Drive**

- LCD drive supported on all GPIOs (common or segment)
- Operates in Deep-Sleep mode with four bits per pin memory

#### **Serial Communication**

■ Two independent runtime reconfigurable serial communication blocks (SCBs) with I<sup>2</sup>C, SPI, or UART functionality

#### **Timing and Pulse-Width Modulation**

- Four 16-bit timer, counter, pulse-width modulator (TCPWM) blocks
- Center-aligned, Edge, and Pseudo-random modes
- Comparator-based triggering of Kill signals for motor drive and other high-reliability digital logic applications

#### **Up to 25 Programmable GPIOs**

- Any GPIO pin can be CapSense, LCD, analog, or digital
- Two overvoltage-tolerant (OVT) pins; drive modes, strengths, and slew rates are programmable

Cypress Semiconductor Corporation

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#### Overview

### **Module Description**

The CYBLE-014008-00 module is a complete module designed to be soldered to the main host board.

#### Module Dimensions and Drawing

Cypress reserves the right to select components (including the appropriate BLE device) from various vendors to achieve the BLE module functionality. Such selections will guarantee that all height restrictions of the component area are maintained. Designs should be completed with the physical dimensions shown in the mechanical drawings in Figure 1. All dimensions are in millimeters (mm).

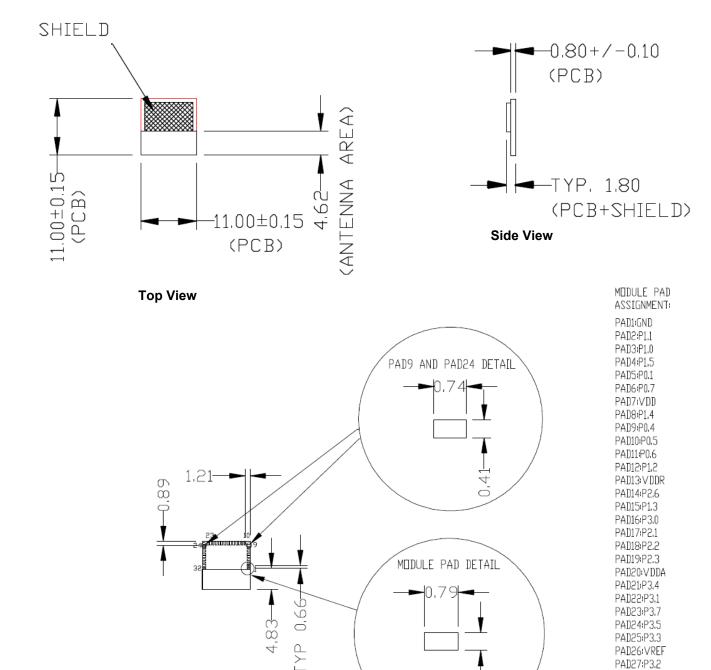
**Table 1. Module Design Dimensions** 

Dimension Item	Specification	
Module dimensions	Length (X)	11.00 ± 0.15 mm
Module difficulties	Width (Y)	11.00 ± 0.15 mm
Antenna location dimensions	Length (X)	11.00 ± 0.15 mm
Afficentia location difficulties	Width (Y)	4.62 ± 0.15 mm
PCB thickness	Height (H)	0.80 ± 0.10 mm
Shield height	Height (H)	1.00 ± 0.10 mm
Maximum component height	Height (H)	1.00 mm typical (shield)
Total module thickness (bottom of module to highest component)	Height (H)	1.80 mm typical

See Figure 1 on page 4 for the mechanical reference drawing for CYBLE-014008-00.



Figure 1. Module Mechanical Drawing



#### Note

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**Bottom View** 

PAD28:P3.6 PAD29:XRES

PAD30:P2.4 PAD31:P2.5 PAD32:GND

<sup>1.</sup> No metal should be located beneath or above the antenna area. Only bare PCB material should be located beneath the antenna area. For more information on recommended host PCB layout, see Figure 3 and Figure 4 on page 6.



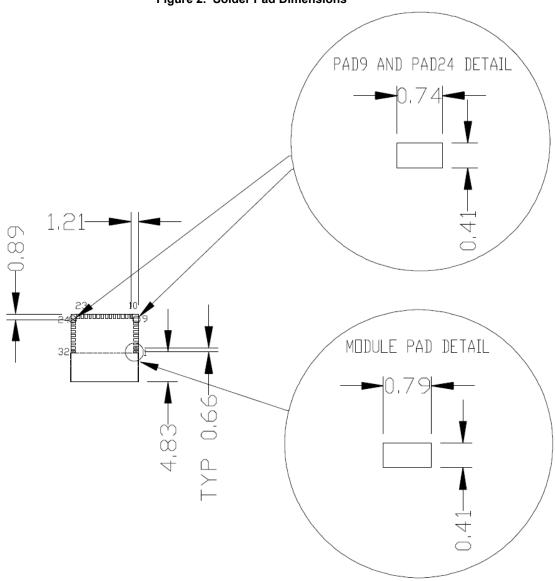
#### **Pad Connection Interface**

As shown in the bottom view of Figure 1 on page 4, the CYBLE-014008-00 connects to the host board via solder pads on the back of the module. Table 2 and Figure 2 detail the solder pad length, width, and pitch dimensions of the CYBLE-014008-00 module.

**Table 2. Solder Pad Connection Description** 

Name	Connections	Connection Type	Pad Length Dimension	Pad Width Dimension	Pad Pitch
SP	32	Solder Pads	Pad9/Pad24: 0.74 mm All Others: 0.79 mm	0.41 mm	0.66 mm

Figure 2. Solder Pad Dimensions





### **Recommended Host PCB Layout**

Figure 3 details the recommended PCB layout pattern for the host PCB. Dimensions are in mm.

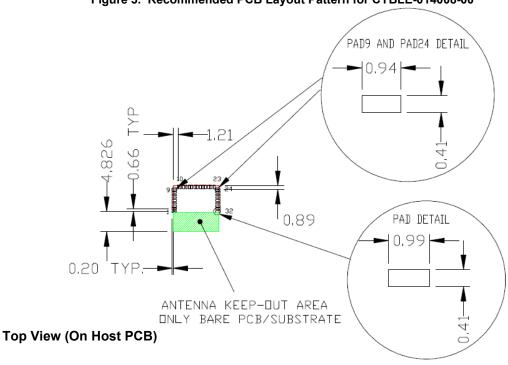
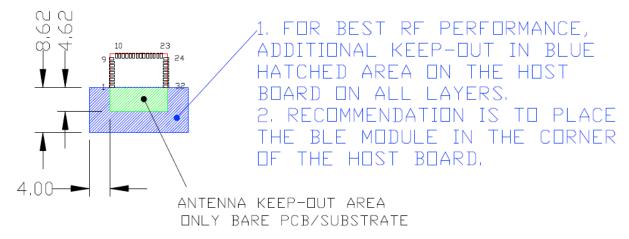


Figure 3. Recommended PCB Layout Pattern for CYBLE-014008-00

To maximize RF performance, the host layout should follow these recommendations:

- 1. The ideal placement of the Cypress BLE module is in a corner of the host board with the antenna located on the edge of the host board. This placement minimizes the additional recommended keep-out area stated in item 2.
- 2. It is recommended that the area around the Cypress BLE module trace antenna should contain an additional keep-out area, where no grounding or signal traces are contained. The keep-out area applies to all layers of the host board. The recommended dimensions of the host PCB keep-out area are shown in Figure 4 (dimensions are in mm).

Figure 4. Recommended Host PCB Keep-Out Area Around the CYBLE-014008-00 Trace Antenna



Host PCB Keep-Out Area Around Trace Antenna



Table 3 details the solder pad pitch (center-to-center) for each of the neighboring connections.

**Table 3. Module Solder Pad Connection Dimensions** 

Pad X	Pad Y	Pad Pitch (Pad X - Pad Y)	Comments
Bottom Right Corner	1	4.83 mm	Distance from bottom right corner to Pad 1 center
1	2	0.66 mm	Distance from Pad 1 center to Pad 2 center
2	3	0.66 mm	Distance from Pad 2 center to Pad 3 center
3	4	0.66 mm	Distance from Pad 3 center to Pad 4 center
4	5	0.66 mm	Distance from Pad 4 center to Pad 5 center
5	6	0.66 mm	Distance from Pad 5 center to Pad 6 center
6	7	0.66 mm	Distance from Pad 6 center to Pad 7 center
7	8	0.66 mm	Distance from Pad 7 center to Pad 8 center
8	9	0.66 mm	Distance from Pad 8 center to Pad 9 center
Top Right Corner	10	1.21 mm	Distance from Pad 9 center to Pad 10 center
10	11	0.66 mm	Distance from Pad 10 center to Pad 11 center
11	12	0.66 mm	Distance from Pad 11 center to Pad 12 center
12	13	0.66 mm	Distance from Pad 12 center to Pad 13 center
13	14	0.66 mm	Distance from Pad 13 center to Pad 14 center
14	15	0.66 mm	Distance from Pad 14 center to Pad 15 center
15	16	0.66 mm	Distance from Pad 15 center to Pad 16 center
16	17	0.66 mm	Distance from Pad 16 center to Pad 17 center
17	18	0.66 mm	Distance from Pad 17 center to Pad 18 center
18	19	0.66 mm	Distance from Pad 18 center to Pad 19 center
19	20	0.66 mm	Distance from Pad 19 center to Pad 20 center
20	21	0.66 mm	Distance from Pad 20 center to Pad 21 center
21	22	0.66 mm	Distance from Pad 21 center to Pad 22 center
22	23	0.66 mm	Distance from Pad 22 center to Pad 23 center
Top Left Corner	24	0.89 mm	Distance from Top Left Corner to Pad 24 center
24	25	0.66 mm	Distance from Pad 24 center to Pad 25 center
25	26	0.66 mm	Distance from Pad 25 center to Pad 26 center
26	27	0.66 mm	Distance from Pad 26 center to Pad 27 center
27	28	0.66 mm	Distance from Pad 27 center to Pad 28 center
28	29	0.66 mm	Distance from Pad 28 center to Pad 29 center
29	30	0.66 mm	Distance from Pad 29 center to Pad 30 center
30	31	0.66 mm	Distance from Pad 30 center to Pad 31 center
31	32	0.66 mm	Distance from Pad 31 center to Pad 32 center
32	Bottom Left Corner	4.83 mm	Distance from Pad 32 center to Bottom Left Corner





Table 4 and Table 5 detail the solder pad connection definitions and available functions for each connection pad. Table 4 lists the solder pads on CYBLE-014008-00, the BLE device port-pin, and denotes whether the digital function shown is available for each solder pad. Table 5 denotes whether the analog function shown is available for each solder pad. Each connection is configurable for a single option shown with a  $\checkmark$ .

Table 4. Digital Peripheral Capabilities

Pad Number	Device Port Pin	UART	SPI	I <sup>2</sup> C	TCPWM <sup>[2]</sup>	Cap- Sense	WCO Out	ECO OUT	LCD	SWD	GPIO
1	GND <sup>[3]</sup>	Ground Connection									
2	P1.1		✓(SCB1_SS1)		✓(TCPWM0)	<b>✓</b>			<b>/</b>		/
3	P1.0				✓(TCPWM0)	<b>√</b>			<b>/</b>		<b>-</b>
4	P1.5	✓(SCB0_TX)		✓(SCB0_SCL)		/			<b>/</b>		
5	P0.1	✓(SCB1_TX)	. – .	✓(SCB1_SCL)	✓(TCPWM0)	<b>/</b>			<b>/</b>		
6	P0.7	✓(SCB0_CTS)	✓(SCB0_SCLK)		✓(TCPWM2)	<b>/</b>			/	(SWDCLK)	<b>√</b>
7	VDD			Digital Pow	er Supply Input	(1.71 to 5.5	iV)		•		
8	P1.4	✓(SCB0_RX)	√(SCB0_MOSI)		✓(TCPWM2)	<b>✓</b>			<b>/</b>		<b>✓</b>
9	P0.4	✓(SCB0_RX)	✓(SCB0_MOSI)	✓(SCB0_SDA)	<b>√</b> (TCPWM1)	<b>/</b>		<b>✓</b>	<b>✓</b>		<b></b>
10	P0.5	✓(SCB0_TX)	√(SCB0_MISO)	✓(SCB0_SCL)	<b>√</b> (TCPWM1)	<b>✓</b>			<b>/</b>		<b>✓</b>
11	P0.6	✓(SCB0_RTS)	✓(SCB0_SS0)		✓(TCPWM2)	1			1	(SWDIO)	✓
12	P1.2		✓(SCB1_SS2)		✓(TCPWM1)	<b>✓</b>			/		/
13	$V_{\mathrm{DDR}}$			Radio P	ower Supply (1.9	9V to 5.5V)					
14	P2.6					<b>✓</b>			<b>/</b>		/
15	P1.3		✓(SCB1_SS3)		✓(TCPWM1)	<b>/</b>			<b>/</b>		/
16	P3.0	✓(SCB0_RX)		✓(SCB0_SDA)	<b>√</b> (TCPWM0)	<b>✓</b>			<b>/</b>		<b>✓</b>
17	P2.1		✓(SCB0_SS2)			<b>✓</b>			<b>/</b>		<b>✓</b>
18	P2.2		✓(SCB0_SS3)			<b>✓</b>			<b>/</b>		<b>✓</b>
19	P2.3					<b>✓</b>	<b>/</b>		<b>/</b>		<b>\</b>
20	VDDA			Analog Pov	ver Supply Input	(1.71 to 5.5	5V)		•		
21	P3.4	✓(SCB1_RX)		✓(SCB1_SDA)	✓(TCPWM2)	<b>/</b>			<b>✓</b>		<b></b>
22	P3.1	✓(SCB0_TX)		✓(SCB0_SCL)	<b>√</b> (TCPWM0)	<b>✓</b>			<b>/</b>		<b>✓</b>
23	P3.7	✓(SCB1_CTS)			<b>√</b> (TCPWM3)	<b>✓</b>	<b>/</b>		<b>✓</b>		<b>✓</b>
24	P3.5	✓(SCB1_TX)		✓(SCB1_SCL)	✓(TCPWM2)	<b>✓</b>			<b>/</b>		<b>✓</b>
25	P3.3	✓(SCB0_CTS)			<b>√</b> (TCPWM1)	<b>✓</b>			<b>/</b>		<b>✓</b>
26	VREF			Re	ference Voltage	Input			•		
27	P3.2	✓(SCB0_RTS)			<b>√</b> (TCPWM1)	<b>✓</b>			<b>/</b>		/
28	P3.6	√(SCB1_RTS)			✓(TCPWM3)	<b>√</b>			/		<b>✓</b>
29	XRES			External Re	set Hardware Co	onnection Ir	put		•		
30	P2.4					<b>✓</b>			<b>/</b>		<b>✓</b>
31	P2.5					<b>√</b>			<b>/</b>		<b>✓</b>
32	GND				Ground Connect	ion			•		

- Notes
  2. TCPWM stands for timer, counter, and PWM. If supported, the pad can be configured to any of these peripheral functions.
  3. The main board needs to connect both GND connections (Pad 1 and Pad 32) on the module to the common ground of the system.



Table 5. Analog Peripheral Capabilities

Pad Number	Device Port Pin	SARMUX	ОРАМР	LPCOMP
1	GND <sup>[3]</sup>		Ground Connection	
2	P1.1		✓(CTBm1_OA0_INN)	
3	P1.0		✓(CTBm1_OA0_INP)	
4	P1.5		✓(CTBm1_OA1_INP)	
5	P0.1			✓(COMP0_INN)
6	P0.7			
7	VDD		Digital Power Supply Input (1.71 t	o 5.5V)
8	P1.4		✓(CTBm1_OA1_INN)	
9	P0.4			✓(COMP1_INP)
10	P0.5			✓(COMP1_INN)
11	P0.6			
12	P1.2		✓(CTBm1_OA0_OUT)	
13	$V_{DDR}$		Radio Power Supply (1.9V to 5	5.5V)
14	P2.6		✓(CTBm1_OA0_INP)	
15	P1.3		✓(CTBm1_OA1_OUT)	
16	P3.0	<b>√</b>		
17	P2.1		✓(CTBm1_OA0_INN)	
18	P2.2		✓(CTBm1_OA0_OUT)	
19	P2.3		✓(CTBm1_OA1_OUT)	
20	VDDA		Analog Power Supply Input (1.71 t	to 5.5V)
21	P3.4	<b>✓</b>		
22	P3.1	<b>√</b>		
23	P3.7	<b>√</b>		
24	P3.5	<b>√</b>		
25	P3.3	<b>√</b>		
26	VREF		Reference Voltage Input (Option	onal)
27	P3.2	<b>√</b>		
28	P3.6	<b>√</b>		
29	XRES		External Reset Hardware Connecti	ion Input
30	P2.4		✓(CTBm1_OA1_INN)	
31	P2.5		✓(CTBm1_OA1_INP)	
32	GND		Ground Connection	



### **Power Supply Connections and Recommended External Components**

#### **Power Connections**

The CYBLE-014008-00 contains three power supply connections, VDD, VDDA, and VDDR. The VDD and VDDA connections supply power for the digital and analog device operation respectively. VDDR supplies power for the device radio.

VDD and VDDA accept a supply range of 1.71 V to 5.5 V. VDDR accepts a supply range of 1.9 V to 5.5 V. These specifications can be found in Table 10. The maximum power supply ripple for both power connections on the module is 100 mV, as shown in Table 8.

The power supply ramp rate of VDD and VDDA must be equal to or greater than that of VDDR when the radio is used.

#### **Connection Options**

Two connection options are available for any application:

- Single supply: Connect VDD, VDDA, and VDDR to the same supply.
- Independent supply: Power VDD, VDDA, and VDDR separately.

#### **External Component Recommendation**

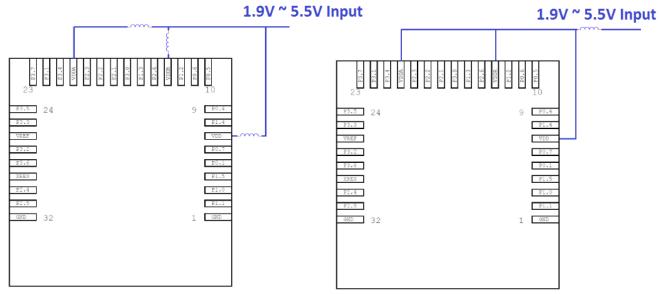
In either connection scenario, it is recommended to place an external ferrite bead between the supply and the module connection. The ferrite bead should be positioned as close as possible to the module pin connection.

Figure 5 details the recommended host schematic options for a single supply scenario. The use of one or two ferrite beads will depend on the specific application and configuration of the CYBLE-014008-00.

Figure 6 details the recommended host schematic for an independent supply scenario.

The recommended ferrite bead value is 330  $\Omega$ , 100 MHz. (Murata BLM21PG331SN1D).

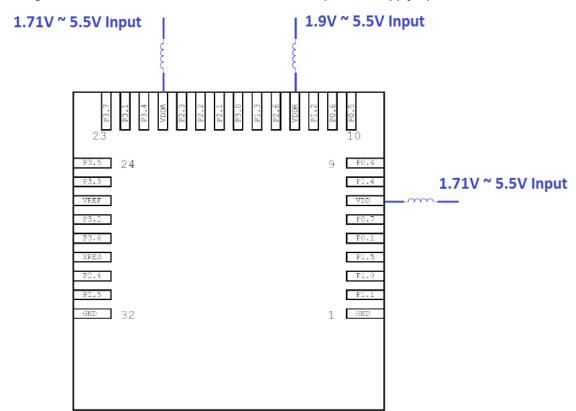




**Single Ferrite Bead Option** 



Figure 6. Recommended Host Schematic for an Independent Supply Option





The CYBLE-014008-00 schematic is shown in Figure 7.

Figure 7. CYBLE-014008-00 Schematic Diagram P0.1 P3.0 24MHz O P0.4 O P3.1 O P0.5 O P3.2 VDDR O P0.6 P3.3 P0.7 P3.4 No Load P1.0 P3.5 L1 1.0nH,0201 L2 1.5nH,0201 O P1.1 O P3.6 A2 A3 A4 A5 A6 A7 A8 A9 P1.2 O P3.7 O VDD O P1.3 O VREF P1.4 VCCD VDD F1 F2 F3 F4 F5 F6 O P1.5 P2.3 VSSA3 P2.7 P3.4 P3.5 P3.6 XTAL32I-P6.1 XTAL32O-P6.0 B4 B5 B6 P2.1 O P2.2 P2.4 NC4 P1.2 P1.5 P1.6 P1.6 P5.4 VSSD3 O P2.5 32.768KHz P2.6 O XRES -OVDD \_\_OVDDR P4.0 C16 2.2nF,0201 CMOD C14 0.1uF,0201 C3 0.1uF,0201 P4.1 C17 10nF,0201 CTANK \_\_OVDDA C13 0.1uF,0201 VREF 0 C7 1.0uF,0201 C4 1.0uF,0201 VCCD O C10 1.0uF,0201 C12 0.1uF,0201 C5 1.0uF,0201 C9 0.1uF,0201 P3.5 24 9 P0.4 C6 0.1uF,0201 P3.3 P1.4 VREF VDD C8 1.0uF,0201 P3.2 P3.6 XRES P1.5 P2.4 P1.0 P2.5 P1.1 GND 32 1 GND



### **Critical Components List**

Table 6 details the critical components used in the CYBLE-014008-00 module.

#### **Table 6. Critical Component List**

Component	Reference Designator	Description
Silicon	U1	68-pin WLCSP Programmable System-on-Chip (PSoC) with BLE
Crystal	Y1	24.000 MHz, 10PF
Crystal	Y2	32.768 kHz, 12.5PF

### **Antenna Design**

Table 7 details antenna used on the CYBLE-014008-00 module. The Cypress module performance improves many of these characteristics. For more information, see Table 9.

**Table 7. Trace Antenna Specifications** 

Item	Description
Frequency Range	2400 – 2500 MHz
Peak Gain	0.5 dBi typical
Average Gain	-0.5 dBi typical
Return Loss	10 dB minimum



### **Electrical Specification**

Table 8 details the absolute maximum electrical characteristics for the Cypress BLE module.

Table 8. CYBLE-014008-00 Absolute Maximum Ratings

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
V <sub>DDD_ABS</sub>	$V_{DD}$ , $V_{DDA}$ or $V_{DDR}$ supply relative to $V_{SS}$ ( $V_{SSD}$ = $V_{SSA}$ )	-0.5	ı	6	>	Absolute maximum
V <sub>CCD_ABS</sub>	Direct digital core voltage input relative to V <sub>SSD</sub>	-0.5	_	1.95	٧	Absolute maximum
V <sub>DDD_RIPPLE</sub>	Maximum power supply ripple for $V_{DD}$ , $V_{DDA}$ and $V_{DDR}$ input voltage	-	-	100	mV	3.0V supply Ripple frequency of 100 kHz to 750 kHz
V <sub>GPIO_ABS</sub>	GPIO voltage	-0.5	-	VDD +0.5	V	Absolute maximum
I <sub>GPIO_ABS</sub>	Maximum current per GPIO	-25	_	25	mA	Absolute maximum
I <sub>GPIO_injection</sub>	GPIO injection current: Maximum for $V_{IH} > V_{DD}$ and minimum for $V_{IL} < V_{SS}$	-0.5	_	0.5	mA	Absolute maximum current injected per pin
LU	Pin current for latch up	-200		200	mA	-

Table 9 details the RF characteristics for the Cypress BLE module.

Table 9. CYBLE-014008-00 RF Performance Characteristics

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
RF <sub>O</sub>	RF output power on ANT	-18	0	3	dBm	Configurable via register settings
RX <sub>S</sub>	RF receive sensitivity on ANT	_	<b>–</b> 91	-	dBm	Guaranteed by design simulation; High Gain Mode
F <sub>R</sub>	Module frequency range	2400	_	2480	MHz	-
G <sub>P</sub>	Peak gain	_	0.5	_	dBi	_
G <sub>Avg</sub>	Average gain	_	-0.5	_	dBi	_
RL	Return loss	_	-10	_	dB	_

Table 10 through Table 50 list the module level electrical characteristics for the CYBLE-014008-00. All specifications are valid for -40 °C  $\leq$  TA  $\leq$  85 °C and TJ  $\leq$  100 °C, except where noted. Specifications are valid for 1.71 V to 5.5 V, except where noted.

Table 10. CYBLE-014008-00 DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
V <sub>DD1</sub>	Power supply input voltage (V <sub>DD</sub> = V <sub>DDA</sub> = V <sub>DDR</sub> )	1.71	-	5.5	V	With regulator enabled
$V_{\mathrm{DD2}}$	Power supply input voltage unregulated (V <sub>DD</sub> = V <sub>DDA</sub> = V <sub>DDR</sub> )	1.71	1.8	1.89	V	Internally unregulated supply
V <sub>DDR1</sub>	Radio supply voltage (radio on)	1.9	_	5.5	V	_
V <sub>DDR2</sub>	Radio supply voltage (radio off)	1.71	_	5.5	V	_
Active Mode,	V <sub>DD</sub> = 1.71 V to 5.5 V					
I <sub>DD3</sub>	Execute from flash; CPU at 3 MHz	_	1.7	-	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD4</sub>	Execute from flash; CPU at 3 MHz	_	_	_	mA	T = -40 °C to 85 °C
I <sub>DD5</sub>	Execute from flash; CPU at 6 MHz	_	2.5	-	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD6</sub>	Execute from flash; CPU at 6 MHz	_	_	_	mA	T = -40 °C to 85 °C
I <sub>DD7</sub>	Execute from flash; CPU at 12 MHz	_	4	-	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V



Table 10. CYBLE-014008-00 DC Specifications (continued)

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>DD8</sub>	Execute from flash; CPU at 12 MHz	-	_	-	mA	T = -40 °C to 85 °C
I <sub>DD9</sub>	Execute from flash; CPU at 24 MHz	-	7.1	_	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD10</sub>	Execute from flash; CPU at 24 MHz	-	_	_	mA	T = -40 °C to 85 °C
I <sub>DD11</sub>	Execute from flash; CPU at 48 MHz	-	13.4	_	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD12</sub>	Execute from flash; CPU at 48 MHz	_	_	_	mA	T = -40 °C to 85 °C
Sleep Mode, \	V <sub>DD</sub> = 1.71 to 5.5 V	•				
I <sub>DD13</sub>	IMO on	_	_	-	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V, SYSCLK = 3 MHz
Sleep Mode, \	V <sub>DD</sub> and V <sub>DDR</sub> = 1.9 to 5.5 V				•	
I <sub>DD14</sub>	ECO on	_	_	_	mA	T = 25 °C, V <sub>DD</sub> = 3.3 V, SYSCLK = 3 MHz
Deep-Sleep M	lode, V <sub>DD</sub> = 1.71 to 3.6 V					
I <sub>DD15</sub>	WDT with WCO on	_	1.3	1	μA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD16</sub>	WDT with WCO on	_	_	1	μA	T = -40 °C to 85 °C
I <sub>DD17</sub>	WDT with WCO on	_	_	-	μA	T = 25 °C, V <sub>DD</sub> = 5 V
I <sub>DD18</sub>	WDT with WCO on	_	_	-	μA	T = -40 °C to 85 °C
Deep-Sleep N	lode, V <sub>DD</sub> = 1.71 to 1.89 V (Regulator Bypassed	<del>i)</del>				
I <sub>DD19</sub>	WDT with WCO on	_	_	_	μA	T = 25 °C
I <sub>DD20</sub>	WDT with WCO on	_	_	-	μA	T = -40 °C to 85 °C
Hibernate Mo	de, V <sub>DD</sub> = 1.71 to 3.6 V					
I <sub>DD27</sub>	GPIO and reset active	_	150	-	nA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD28</sub>	GPIO and reset active	_	_	ı	nA	T = -40 °C to 85 °C
Hibernate Mo	de, V <sub>DD</sub> = 3.6 to 5.5 V					
I <sub>DD29</sub>	GPIO and reset active	_	1	1	nA	T = 25 °C, V <sub>DD</sub> = 5 V
I <sub>DD30</sub>	GPIO and reset active	_	_	1	nA	T = -40 °C to 85 °C
Stop Mode, V	<sub>DD</sub> = 1.71 to 3.6 V					
I <sub>DD33</sub>	Stop-mode current (V <sub>DD</sub> )	_	20	-	nA	T = 25 °C, V <sub>DD</sub> = 3.3 V
I <sub>DD34</sub>	Stop-mode current (V <sub>DDR</sub> )	_	40		nA	T = 25 °C, V <sub>DDR</sub> = 3.3 V
I <sub>DD35</sub>	Stop-mode current (V <sub>DD</sub> )	_	_	_	nA	T = -40 °C to 85 °C
I <sub>DD36</sub>	Stop-mode current (V <sub>DDR</sub> )	_	-	_	nA	T = -40 °C to 85 °C, V <sub>DDR</sub> = 1.9 V to 3.6 V
Stop Mode, V	<sub>DD</sub> = 3.6 to 5.5 V				•	•
I <sub>DD37</sub>	Stop-mode current (V <sub>DD</sub> )	_	_	-	nA	T = 25 °C, V <sub>DD</sub> = 5 V
I <sub>DD38</sub>	Stop-mode current (V <sub>DDR</sub> )	_	_	-	nA	T = 25 °C, V <sub>DDR</sub> = 5 V
I <sub>DD39</sub>	Stop-mode current (V <sub>DD</sub> )	_	_	_	nA	T = -40 °C to 85 °C
I <sub>DD40</sub>	Stop-mode current (V <sub>DDR</sub> )	-	_	_	nA	T = -40 °C to 85 °C



Table 11. AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
F <sub>CPU</sub>	CPU frequency	DC	_	48	MHz	$1.71 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}$
T <sub>SLEEP</sub>	Wakeup from Sleep mode	-	0	-	μs	Guaranteed by characterization
T <sub>DEEPSLEEP</sub>	Wakeup from Deep-Sleep mode	-	_	25	μs	24-MHz IMO. Guaranteed by characterization
T <sub>HIBERNATE</sub>	Wakeup from Hibernate mode	_	_	800	μs	Guaranteed by characterization
T <sub>STOP</sub>	Wakeup from Stop mode	1	_	2	ms	XRES wakeup

### **GPIO**

### Table 12. GPIO DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
	Input voltage HIGH threshold	0.7 × V <sub>DD</sub>	-	_	V	CMOS input
V <sub>IH</sub> <sup>[4]</sup>	LVTTL input, V <sub>DD</sub> < 2.7 V	0.7 × V <sub>DD</sub>	_	_	V	-
	LVTTL input, V <sub>DD</sub> ≥ 2.7 V	2.0	-	_	V	-
	Input voltage LOW threshold	_	_	$0.3 \times V_{DD}$	V	CMOS input
$V_{IL}$	LVTTL input, V <sub>DD</sub> < 2.7 V	_	_	0.3× V <sub>DD</sub>	V	-
	LVTTL input, V <sub>DD</sub> ≥ 2.7 V	_	-	0.8	V	-
V	Output voltage HIGH level	V <sub>DD</sub> -0.6	-	-	V	I <sub>OH</sub> = 4 mA at 3.3-V V <sub>DD</sub>
V <sub>OH</sub>	Output voltage HIGH level	V <sub>DD</sub> -0.5	_	_	V	I <sub>OH</sub> = 1 mA at 1.8-V V <sub>DD</sub>
	Output voltage LOW level	_	-	0.6	V	$I_{OL}$ = 8 mA at 3.3-V $V_{DD}$
V <sub>OL</sub>	Output voltage LOW level	_	-	0.6	V	$I_{OL}$ = 4 mA at 1.8-V $V_{DD}$
	Output voltage LOW level	_	_	0.4	V	$I_{OL}$ = 3 mA at 3.3-V $V_{DD}$
R <sub>PULLUP</sub>	Pull-up resistor	3.5	5.6	8.5	kΩ	-
R <sub>PULLDOWN</sub>	Pull-down resistor	3.5	5.6	8.5	kΩ	-
I <sub>IL</sub>	Input leakage current (absolute value)	_	_	2	nA	25 °C, V <sub>DD</sub> = 3.3 V
I <sub>IL_CTBM</sub>	Input leakage on CTBm input pins	_	-	4	nA	-
C <sub>IN</sub>	Input capacitance	_	_	7	pF	-
V <sub>HYSTTL</sub>	Input hysteresis LVTTL	25	40	_	mV	V <sub>DD</sub> > 2.7 V
V <sub>HYSCMOS</sub>	Input hysteresis CMOS	0.05 × V <sub>DD</sub>	-	-	1	-
I <sub>DIODE</sub>	Current through protection diode to V <sub>DD</sub> /V <sub>SS</sub>	_	_	100	μΑ	-
I <sub>TOT_GPIO</sub>	Maximum total source or sink chip current	-	_	200	mA	-

#### Note

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<sup>4.</sup> V<sub>IH</sub> must not exceed V<sub>DD</sub> + 0.2 V.



Table 13. GPIO AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>RISEF</sub>	Rise time in Fast-Strong mode	2	_	12	ns	$3.3\text{-V V}_{DDD}$ , $C_{LOAD} = 25 \text{ pF}$
T <sub>FALLF</sub>	Fall time in Fast-Strong mode	2	_	12	ns	$3.3\text{-V V}_{DDD}$ , $C_{LOAD} = 25 \text{ pF}$
T <sub>RISES</sub>	Rise time in Slow-Strong mode	10	_	60	ns	$3.3\text{-V V}_{DDD}$ , $C_{LOAD} = 25 \text{ pF}$
T <sub>FALLS</sub>	Fall time in Slow-Strong mode	10	_	60	ns	$3.3\text{-V V}_{DDD}$ , $C_{LOAD} = 25 \text{ pF}$
F <sub>GPIOUT1</sub>	GPIO Fout; $3.3 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}$ Fast-Strong mode	_	_	33	MHz	90/10%, 25 pF load, 60/40 duty cycle
F <sub>GPIOUT2</sub>	GPIO Fout; 1.7 V≤ V <sub>DD</sub> ≤ 3.3 V Fast-Strong mode	_	_	16.7	MHz	90/10%, 25 pF load, 60/40 duty cycle
F <sub>GPIOUT3</sub>	GPIO Fout; $3.3 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}$ Slow-Strong mode	_	_	7	MHz	90/10%, 25 pF load, 60/40 duty cycle
F <sub>GPIOUT4</sub>	GPIO Fout; 1.7 $V \le V_{DD} \le 3.3 V$ Slow-Strong mode	_	_	3.5	MHz	90/10%, 25 pF load, 60/40 duty cycle
F <sub>GPIOIN</sub>	GPIO input operating frequency 1.71 V $\leq$ V <sub>DD</sub> $\leq$ 5.5 V	_	_	48	MHz	90/10% V <sub>IO</sub>

### **XRES**

Table 14. XRES DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
V <sub>IH</sub>	Input voltage HIGH threshold	$0.7 \times V_{DDD}$	_	_	V	CMOS input
V <sub>IL</sub>	Input voltage LOW threshold	-	_	$0.3 \times V_{DDD}$	V	CMOS input
R <sub>PULLUP</sub>	Pull-up resistor	3.5	5.6	8.5	kΩ	-
C <sub>IN</sub>	Input capacitance	-	3	_	pF	-
V <sub>HYSXRES</sub>	Input voltage hysteresis	-	100	_	mV	-
I <sub>DIODE</sub>	Current through protection diode to V <sub>DD</sub> /V <sub>SS</sub>	_	-	100	μΑ	-

Table 15. XRES AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>RESETWIDTH</sub>	Reset pulse width	1	ı	ı	μs	1

### **Analog Peripherals**

Opamp

**Table 16. Opamp Specifications** 

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions		
I <sub>DD</sub> (Opamp Block	Current. V <sub>DD</sub> = 1.8 V. No Load)							
I <sub>DD_HI</sub>	Power = high	-	1000	1300	μA			
I <sub>DD_MED</sub>	Power = medium	-	500	_	μA			
I <sub>DD_LOW</sub>	Power = low	-	250	350	μA			
GBW (Load = 20	pF, 0.1 mA. V <sub>DDA</sub> = 2.7 V)							
GBW_HI	Power = high	6	-	-	MHz			
GBW_MED	Power = medium	4	_	-	MHz			
GBW_LO	Power = low	_	1	-	MHz			
$I_{OUT\_MAX}$ ( $V_{DDA} \ge$	I <sub>OUT_MAX</sub> (V <sub>DDA</sub> ≥ 2.7 V, 500 mV from Rail)							



Table 16. Opamp Specifications (continued)

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
I <sub>OUT_MAX_HI</sub>	Power = high	10	_	-	mA	
I <sub>OUT_MAX_MID</sub>	Power = medium	10	-	_	mA	
I <sub>OUT_MAX_LO</sub>	Power = low	-	5	-	mA	
I <sub>OUT</sub> (V <sub>DDA</sub> = 1.71	V, 500 mV from Rail)		•			
I <sub>OUT_MAX_HI</sub>	Power = high	4	_	-	mA	
I <sub>OUT_MAX_MID</sub>	Power = medium	4	-	_	mA	
I <sub>OUT_MAX_LO</sub>	Power = low	-	2	_	mA	
V <sub>IN</sub>	Charge pump on, V <sub>DDA</sub> ≥ 2.7 V	-0.05	_	V <sub>DDA</sub> – 0.2	V	
V <sub>CM</sub>	Charge pump on, V <sub>DDA</sub> ≥ 2.7 V	-0.05	_	V <sub>DDA</sub> – 0.2	V	
$V_{OUT}$ ( $V_{DDA} \ge 2.7$	V)			•	l	
V <sub>OUT 1</sub>	Power = high, I <sub>LOAD</sub> =10 mA	0.5	_	V <sub>DDA</sub> – 0.5	V	
V <sub>OUT_2</sub>	Power = high, I <sub>LOAD</sub> =1 mA	0.2	_	V <sub>DDA</sub> – 0.2	V	
V <sub>OUT_3</sub>	Power = medium, I <sub>LOAD</sub> =1 mA	0.2	_	V <sub>DDA</sub> – 0.2	V	
V <sub>OUT_4</sub>	Power = low, I <sub>LOAD</sub> =0.1 mA	0.2	_	V <sub>DDA</sub> – 0.2	V	
V <sub>OS_TR</sub>	Offset voltage, trimmed	1	±0.5	1	mV	High mode
V <sub>OS_TR</sub>	Offset voltage, trimmed	_	±1	_	mV	Medium mode
V <sub>OS_TR</sub>	Offset voltage, trimmed	-	±2	_	mV	Low mode
V <sub>OS_DR_TR</sub>	Offset voltage drift, trimmed	-10	±3	10	μV/C	High mode
V <sub>OS_DR_TR</sub>	Offset voltage drift, trimmed	_	±10	-	μV/C	Medium mode
V <sub>OS_DR_TR</sub>	Offset voltage drift, trimmed	_	±10	-	μV/C	Low mode
CMRR	DC	65	70	_	dB	V <sub>DDD</sub> = 3.6 V, High-power mode
PSRR	At 1 kHz, 100-mV ripple	70	85	_	dB	V <sub>DDD</sub> = 3.6 V
Noise		•	•	•		
V <sub>N1</sub>	Input referred, 1 Hz–1 GHz, power = high	_	94	_	μVrms	
V <sub>N2</sub>	Input referred, 1 kHz, power = high	_	72	_	nV/rtHz	
V <sub>N3</sub>	Input referred, 10 kHz, power = high	_	28	-	nV/rtHz	
$V_{N4}$	Input referred, 100 kHz, power = high	_	15	_	nV/rtHz	
C <sub>LOAD</sub>	Stable up to maximum load. Performance specs at 50 pF	_	_	125	pF	
Slew_rate	Cload = 50 pF, Power = High, V <sub>DDA</sub> ≥ 2.7 V	6	_	_	V/µsec	
T_op_wake	From disable to enable, no external RC dominating	_	300	_	µsec	
Comp_mode (Co	omparator Mode; 50-mV Drive, T <sub>RISE</sub> = T <sub>FAL</sub>	(Approx.)	)	I.		
T <sub>PD1</sub>	Response time; power = high		150	_	nsec	
T <sub>PD2</sub>	Response time; power = medium	_	400	_	nsec	
T <sub>PD3</sub>	Response time; power = low	_	2000	_	nsec	
Vhyst_op	Hysteresis	_	10	_	mV	
	e (Deep-Sleep mode operation is only guar	anteed for	V <sub>DDA</sub> > :	2.5 V)	l	
GBW_DS	Gain bandwidth product	_	50		kHz	
IDD_DS	Current	_	15	_	μA	
Vos_DS	Offset voltage	_	5	_	mV	
_	1 -	l	1	1	i .	



### Table 16. Opamp Specifications (continued)

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
Vos_dr_DS	Offset voltage drift	-	20	_	μV/°C	
Vout_DS	Output voltage	0.2	_	V <sub>DD</sub> -0.2	V	
Vcm_DS	Common mode voltage	0.2	_	V <sub>DD</sub> –1.8	V	

### **Table 17. Comparator DC Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
V <sub>OFFSET1</sub>	Input offset voltage, Factory trim	_	_	±10	mV	
V <sub>OFFSET2</sub>	Input offset voltage, Custom trim	_	_	±6	mV	
V <sub>OFFSET3</sub>	Input offset voltage, ultra-low-power mode	-	±12	-	mV	
V <sub>HYST</sub>	Hysteresis when enabled	-	10	35	mV	
V <sub>ICM1</sub>	Input common mode voltage in normal mode	0	_	V <sub>DDD</sub> -0.1	V	Modes 1 and 2
V <sub>ICM2</sub>	Input common mode voltage in low-power mode	0	-	$V_{DDD}$	V	
V <sub>ICM3</sub>	Input common mode voltage in ultra low-power mode	0	-	V <sub>DDD</sub> –1.15	V	
CMRR	Common mode rejection ratio	50	_	-	dB	$V_{DDD} \ge 2.7 \text{ V}$
CMRR	Common mode rejection ratio	42	_	_	dB	$V_{DDD} \le 2.7 \text{ V}$
I <sub>CMP1</sub>	Block current, normal mode	-	_	400	μA	
I <sub>CMP2</sub>	Block current, low-power mode	-	_	100	μA	
I <sub>CMP3</sub>	Block current in ultra-low-power mode	-	6	_	μA	
Z <sub>CMP</sub>	DC input impedance of comparator	35	-	_	ΜΩ	

### Table 18. Comparator AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
T <sub>RESP1</sub>	Response time, normal mode, 50-mV overdrive	-	38	-	ns	50-mV overdrive
T <sub>RESP2</sub>	Response time, low-power mode, 50-mV overdrive	_	70	_	ns	50-mV overdrive
T <sub>RESP3</sub>	Response time, ultra-low-power mode, 50-mV overdrive	_	2.3	_	μs	200-mV overdrive

Temperature Sensor

### **Table 19. Temperature Sensor Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>SENSACC</sub>	Temperature-sensor accuracy	<b>-</b> 5	±1	5	°C	–40 to +85 °C

#### SAR ADC

### Table 20. SAR ADC DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
A_RES	Resolution	_	-	12	bits	

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### Table 20. SAR ADC DC Specifications

A_CHNIS_S	Number of channels - single-ended	_	_	8		8 full-speed
A-CHNKS_D	Number of channels - differential	_	_	4		Diff inputs use neighboring I/O
A-MONO	Monotonicity	_	_	-		Yes
A_GAINERR	Gain error	_	-	±0.1	%	With external reference
A_OFFSET	Input offset voltage	_	_	2	mV	Measured with 1-V V <sub>REF</sub>
A_ISAR	Current consumption	_	_	1	mA	
A_VINS	Input voltage range - single-ended	$V_{SS}$	_	$V_{DDA}$	V	
A_VIND	Input voltage range - differential	$V_{SS}$	_	$V_{DDA}$	V	
A_INRES	Input resistance	_	_	2.2	kΩ	
A_INCAP	Input capacitance	_	_	10	pF	
VREFSAR	Trimmed internal reference to SAR	<b>–</b> 1	_	1	%	Percentage of Vbg (1.024 V)

### Table 21. SAR ADC AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
A_PSRR	Power-supply rejection ratio	70	_	_	dB	Measured at 1-V reference
A_CMRR	Common-mode rejection ratio	66	_	_	dB	
A_SAMP			806 Ksps for More Part Numbers devices			
Fsarintref	SAR operating speed without external ref. bypass	_	_	100	Ksps	12-bit resolution
A_SNR	Signal-to-noise ratio (SNR)	65	_	-	dB	F <sub>IN</sub> = 10 kHz
A_BW	Input bandwidth without aliasing	_	_	A_SAMP/2	kHz	
A_INL	Integral nonlinearity. V <sub>DD</sub> = 1.71 V to 5.5 V, 1 Msps	-1.7	_	2	LSB	$V_{REF} = 1 \text{ V to } V_{DD}$
A_INL	Integral nonlinearity. V <sub>DDD</sub> = 1.71 V to 3.6 V, 1 Msps	-1.5	_	1.7	LSB	$V_{REF}$ = 1.71 V to $V_{DD}$
A_INL	Integral nonlinearity. V <sub>DD</sub> = 1.71 V to 5.5 V, 500 Ksps	-1.5	_	1.7	LSB	V <sub>REF</sub> = 1 V to V <sub>DD</sub>
A_dnl	Differential nonlinearity. V <sub>DD</sub> = 1.71 V to 5.5 V, 1 Msps	<b>–</b> 1	_	2.2	LSB	V <sub>REF</sub> = 1 V to V <sub>DD</sub>
A_DNL	Differential nonlinearity. V <sub>DD</sub> = 1.71 V to 3.6 V, 1 Msps	<b>–</b> 1	_	2	LSB	$V_{REF}$ = 1.71 V to $V_{DD}$
A_DNL	Differential nonlinearity. V <sub>DD</sub> = 1.71 V to 5.5 V, 500 Ksps	<b>–</b> 1	_	2.2	LSB	V <sub>REF</sub> = 1 V to V <sub>DD</sub>
A_THD	Total harmonic distortion	1	_	-65	dB	F <sub>IN</sub> = 10 kHz

#### CSD

### **CSD Block Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
$V_{CSD}$	Voltage range of operation	1.71	ı	5.5	V	



### **CSD Block Specifications** (continued)

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
IDAC1	DNL for 8-bit resolution	-1	_	1	LSB	
IDAC1	INL for 8-bit resolution	-3	_	3	LSB	
IDAC2	DNL for 7-bit resolution	-1	_	1	LSB	
IDAC2	INL for 7-bit resolution	-3	_	3	LSB	
SNR	Ratio of counts of finger to noise	5	_	_	Ratio	Capacitance range of 9 pF to 35 pF, 0.1-pF sensitivity. Radio is not operating during the scan
I <sub>DAC1_CRT1</sub>	Output current of IDAC1 (8 bits) in High range	_	612	_	μA	
I <sub>DAC1_CRT2</sub>	Output current of IDAC1 (8 bits) in Low range	_	306	_	μA	
I <sub>DAC2_CRT1</sub>	Output current of IDAC2 (7 bits) in High range	_	305	_	μA	
I <sub>DAC2_CRT2</sub>	Output current of IDAC2 (7 bits) in Low range	_	153	_	μA	

### **Digital Peripherals**

Timer

### **Table 22. Timer DC Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>TIM1</sub>	Block current consumption at 3 MHz	_	_	42	μA	16-bit timer
I <sub>TIM2</sub>	Block current consumption at 12 MHz	_	_	130	μA	16-bit timer
I <sub>TIM3</sub>	Block current consumption at 48 MHz	_	_	535	μA	16-bit timer

### **Table 23. Timer AC Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>TIMFREQ</sub>	Operating frequency	F <sub>CLK</sub>	-	48	MHz	
T <sub>CAPWINT</sub>	Capture pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>CAPWEXT</sub>	Capture pulse width (external)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>TIMRES</sub>	Timer resolution	T <sub>CLK</sub>	_	_	ns	
T <sub>TENWIDINT</sub>	Enable pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>TENWIDEXT</sub>	Enable pulse width (external)	2 × T <sub>CLK</sub>	-	_	ns	
T <sub>TIMRESWINT</sub>	Reset pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>TIMRESEXT</sub>	Reset pulse width (external)	2 × T <sub>CLK</sub>	_	_	ns	

### Counter

### **Table 24. Counter DC Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>CTR1</sub>	Block current consumption at 3 MHz	-	-	42	μA	16-bit counter
I <sub>CTR2</sub>	Block current consumption at 12 MHz	_	_	130	μA	16-bit counter
I <sub>CTR3</sub>	Block current consumption at 48 MHz	_	_	535	μA	16-bit counter



**Table 25. Counter AC Specifications** 

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>CTRFREQ</sub>	Operating frequency	F <sub>CLK</sub>	_	48	MHz	
T <sub>CTRPWINT</sub>	Capture pulse width (internal)	2 × T <sub>CLK</sub>	_	-	ns	
T <sub>CTRPWEXT</sub>	Capture pulse width (external)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>CTRES</sub>	Counter Resolution	T <sub>CLK</sub>	_	_	ns	
T <sub>CENWIDINT</sub>	Enable pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>CENWIDEXT</sub>	Enable pulse width (external)	2 × T <sub>CLK</sub>	_	-	ns	
T <sub>CTRRESWINT</sub>	Reset pulse width (internal)	2 × T <sub>CLK</sub>	_	-	ns	
T <sub>CTRRESWEXT</sub>	Reset pulse width (external)	2 × T <sub>CLK</sub>	_	-	ns	

### Pulse Width Modulation (PWM)

### Table 26. PWM DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>PWM1</sub>	Block current consumption at 3 MHz	_	-	42	μΑ	16-bit PWM
I <sub>PWM2</sub>	Block current consumption at 12 MHz	_	_	130	μΑ	16-bit PWM
I <sub>PWM3</sub>	Block current consumption at 48 MHz	_	_	535	μA	16-bit PWM

### Table 27. PWM AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>PWMFREQ</sub>	Operating frequency	F <sub>CLK</sub>	-	48	MHz	
T <sub>PWMPWINT</sub>	Pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>PWMEXT</sub>	Pulse width (external)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>PWMKILLINT</sub>	Kill pulse width (internal)	2 × T <sub>CLK</sub>	-	_	ns	
T <sub>PWMKILLEXT</sub>	Kill pulse width (external)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>PWMEINT</sub>	Enable pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>PWMENEXT</sub>	Enable pulse width (external)	2 × T <sub>CLK</sub>	1	_	ns	
T <sub>PWMRESWINT</sub>	Reset pulse width (internal)	2 × T <sub>CLK</sub>	_	_	ns	
T <sub>PWMRESWEXT</sub>	Reset pulse width (external)	2 × T <sub>CLK</sub>	_	_	ns	

#### LCD Direct Drive

### Table 28. LCD Direct Drive DC Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID228	I <sub>LCDLOW</sub>	Operating current in low-power mode	-	17.5	_	μA	16 × 4 small segment display at 50 Hz
SID229	C <sub>LCDCAP</sub>	LCD capacitance per segment/common driver	_	500	5000	pF	
SID230	LCD <sub>OFFSET</sub>	Long-term segment offset	_	20	_	mV	
SID231	I <sub>LCDOP1</sub>	LCD system operating current V <sub>BIAS</sub> = 5 V	_	2	-	mA	32 × 4 segments. 50 Hz at 25 °C
SID232	I <sub>LCDOP2</sub>	LCD system operating current V <sub>BIAS</sub> = 3.3 V	ı	2	_	mA	32 × 4 segments 50 Hz at 25 °C

### Table 29. LCD Direct Drive AC Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID233	F <sub>LCD</sub>	LCD frame rate	10	50	150	Hz	



### **Serial Communication**

### Table 30. Fixed I<sup>2</sup>C DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>I2C1</sub>	Block current consumption at 100 kHz	-	_	50	μΑ	-
I <sub>I2C2</sub>	Block current consumption at 400 kHz	-	_	155	μΑ	-
I <sub>I2C3</sub>	Block current consumption at 1 Mbps	_	_	390	μA	-
I <sub>I2C4</sub>	I <sup>2</sup> C enabled in Deep-Sleep mode	=	_	1.4	μΑ	-

### Table 31. Fixed I<sup>2</sup>C AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
F <sub>I2C1</sub>	Bit rate	_	-	400	kHz	

### Table 32. Fixed UART DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>UART1</sub>	Block current consumption at 100 kbps	-	-	55	μA	-
I <sub>UART2</sub>	Block current consumption at 1000 kbps	_	-	312	μA	_

### Table 33. Fixed UART AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
F <sub>UART</sub>	Bit rate	_	-	1	Mbps	_

### Table 34. Fixed SPI DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>SPI1</sub>	Block current consumption at 1 Mbps	_	_	360	μΑ	_
I <sub>SPI2</sub>	Block current consumption at 4 Mbps	_	-	560	μA	_
I <sub>SPI3</sub>	Block current consumption at 8 Mbps	_	-	600	μA	-

#### Table 35. Fixed SPI AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
F <sub>SPI</sub>	SPI operating frequency (master; 6x over sampling)	1	1	8	MHz	_

### Table 36. Fixed SPI Master Mode AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
$T_{DMO}$	MOSI valid after SCLK driving edge	_	_	18	ns	_
T <sub>DSI</sub>	MISO valid before SCLK capturing edge Full clock, late MISO sampling used	20	-	-	ns	Full clock, late MISO sampling
T <sub>HMO</sub>	Previous MOSI data hold time	0	_	-	ns	Referred to Slave capturing edge

### Table 37. Fixed SPI Slave Mode AC Specifications

Parameter	Description	Min	Тур	Max	Units
T <sub>DMI</sub>	MOSI valid before SCLK capturing edge	40	_	_	ns
T <sub>DSO</sub>	MISO valid after SCLK driving edge	-	_	42 + 3 × T <sub>CPU</sub>	ns
T <sub>DSO_ext</sub>	MISO Valid after SCLK driving edge in external clock mode. V <sub>DD</sub> < 3.0 V	-	_	50	ns
T <sub>HSO</sub>	Previous MISO data hold time	0	_	_	ns
T <sub>SSELSCK</sub>	SSEL valid to first SCK valid edge	100	_	_	ns



#### Memory

#### Table 38. Flash DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
$V_{PE}$	Erase and program voltage	1.71	_	5.5	V	-
T <sub>WS48</sub>	Number of Wait states at 32–48 MHz	2	_	_		CPU execution from flash
T <sub>WS32</sub>	Number of Wait states at 16–32 MHz	1	_	_		CPU execution from flash
T <sub>WS16</sub>	Number of Wait states for 0–16 MHz	0	_	-		CPU execution from flash

### Table 39. Flash AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>ROWWRITE</sub> <sup>[5]</sup>	Row (block) write time (erase and program)	_	_	20	ms	Row (block) = 128 bytes
T <sub>ROWERASE</sub> <sup>[5]</sup>	Row erase time	_	_	13	ms	_
T <sub>ROWPROGRAM</sub> <sup>[5]</sup>	Row program time after erase	_	_	7	ms	_
	Bulk erase time (128 KB)	_	_	35	ms	_
T <sub>DEVPROG</sub> <sup>[5]</sup>	Total device program time	_	_	25	seconds	_
F <sub>END</sub>	Flash endurance	100 K	_	_	cycles	_
F <sub>RET</sub>	Flash retention. T <sub>A</sub> ≤ 55 °C, 100 K P/E cycles	20	_	_	years	_
F <sub>RET2</sub>	Flash retention. T <sub>A</sub> ≤ 85 °C, 10 K P/E cycles	10	_	_	years	_

### **System Resources**

Power-on-Reset (POR)

#### Table 40. POR DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
V <sub>RISEIPOR</sub>	Rising trip voltage	0.80	_	1.45	V	_
V <sub>FALLIPOR</sub>	Falling trip voltage	0.75	_	1.40	V	_
V <sub>IPORHYST</sub>	Hysteresis	15	_	200	mV	_

#### Table 41. POR AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>PPOR_TR</sub>	Precision power-on reset (PPOR) response time in Active and Sleep modes	_	_	1	μs	-

#### Table 42. Brown-Out Detect

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
V <sub>FALLPPOR</sub>	BOD trip voltage in Active and Sleep modes	1.64	_	_	V	-
V <sub>FALLDPSLP</sub>	BOD trip voltage in Deep Sleep	1.4	_	_	V	-

#### Table 43. Hibernate Reset

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
$V_{HBRTRIP}$	BOD trip voltage in Hibernate	1.1	_	_	V	-

#### Note

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It can take as much as 20 ms to write to flash. During this time, the device should not be reset, or flash operations will be interrupted and cannot be relied on to have completed. Reset sources include the XRES pin, software resets, CPU lockup states and privilege violations, improper power supply levels, and watchdogs. Make certain that these are not inadvertently activated.



Voltage Monitors (LVD)

### Table 44. Voltage Monitor DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
V <sub>LVI1</sub>	LVI_A/D_SEL[3:0] = 0000b	1.71	1.75	1.79	V	-
V <sub>LVI2</sub>	LVI_A/D_SEL[3:0] = 0001b	1.76	1.80	1.85	V	-
V <sub>LVI3</sub>	LVI_A/D_SEL[3:0] = 0010b	1.85	1.90	1.95	V	_
$V_{LVI4}$	LVI_A/D_SEL[3:0] = 0011b	1.95	2.00	2.05	V	_
V <sub>LVI5</sub>	LVI_A/D_SEL[3:0] = 0100b	2.05	2.10	2.15	V	_
V <sub>LVI6</sub>	LVI_A/D_SEL[3:0] = 0101b	2.15	2.20	2.26	V	_
V <sub>LVI7</sub>	LVI_A/D_SEL[3:0] = 0110b	2.24	2.30	2.36	V	-
V <sub>LVI8</sub>	LVI_A/D_SEL[3:0] = 0111b	2.34	2.40	2.46	V	_
V <sub>LVI9</sub>	LVI_A/D_SEL[3:0] = 1000b	2.44	2.50	2.56	V	_
V <sub>LVI10</sub>	LVI_A/D_SEL[3:0] = 1001b	2.54	2.60	2.67	V	_
V <sub>LVI11</sub>	LVI_A/D_SEL[3:0] = 1010b	2.63	2.70	2.77	V	-
V <sub>LVI12</sub>	LVI_A/D_SEL[3:0] = 1011b	2.73	2.80	2.87	V	-
V <sub>LVI13</sub>	LVI_A/D_SEL[3:0] = 1100b	2.83	2.90	2.97	V	_
V <sub>LVI14</sub>	LVI_A/D_SEL[3:0] = 1101b	2.93	3.00	3.08	V	_
V <sub>LVI15</sub>	LVI_A/D_SEL[3:0] = 1110b	3.12	3.20	3.28	V	-
V <sub>LVI16</sub>	LVI_A/D_SEL[3:0] = 1111b	4.39	4.50	4.61	V	_
LVI_IDD	Block current	_	_	100	μA	_

### **Table 45. Voltage Monitor AC Specifications**

	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
$T_M$	IONTRIP	Voltage monitor trip time	-	_	1	μs	-

#### SWD Interface

#### **Table 46. SWD Interface Specifications**

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
F_SWDCLK1	$3.3 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}$	-	_	14	MHz	SWDCLK ≤ 1/3 CPU clock frequency
F_SWDCLK2	1.71 V ≤ V <sub>DD</sub> ≤ 3.3 V	_	_	7	MHz	SWDCLK ≤ 1/3 CPU clock frequency
T_SWDI_SETUP	T = 1/f SWDCLK	0.25 × T	_	_	ns	-
T_SWDI_HOLD	T = 1/f SWDCLK	0.25 × T	_	_	ns	-
T_SWDO_VALID	T = 1/f SWDCLK	_	_	0.5 × T	ns	-
T_SWDO_HOLD	T = 1/f SWDCLK	1	-	-	ns	-



#### Internal Main Oscillator

### Table 47. IMO DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>IMO1</sub>	IMO operating current at 48 MHz	_	_	1000	μΑ	-
I <sub>IMO2</sub>	IMO operating current at 24 MHz	_	_	325	μΑ	-
I <sub>IMO3</sub>	IMO operating current at 12 MHz	_	_	225	μΑ	-
I <sub>IMO4</sub>	IMO operating current at 6 MHz	_	_	180	μΑ	-
I <sub>IMO5</sub>	IMO operating current at 3 MHz	_	_	150	μΑ	_

### Table 48. IMO AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
F <sub>IMOTOL3</sub>	Frequency variation from 3 to 48 MHz	_	_	±2	%	With API-called calibration
F <sub>IMOTOL3</sub>	IMO startup time	_	12	-	μs	_

### Internal Low-Speed Oscillator

### Table 49. ILO DC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
I <sub>ILO2</sub>	ILO operating current at 32 kHz	_	0.3	1.05	μΑ	_

### Table 50. ILO AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
T <sub>STARTILO1</sub>	ILO startup time	_	-	2	ms	-
F <sub>ILOTRIM1</sub>	32-kHz trimmed frequency	15	32	50	kHz	-

### Table 51. ECO Trim Value Specification

Parameter	Description	Value	Details/Conditions
ECO <sub>TRIM</sub>	24-MHz trim value (firmware configuration)	1 110010101013444	Optimum trim value that needs to be loaded to register CY_SYS_XTAL_BLERD_BB_XO_CAPTRIM_REG

### Table 52. UDB AC Specifications

Parameter	Description	Min	Тур	Max	Units	Details/Conditions
Data Path perform	nance				•	
F <sub>MAX-TIMER</sub>	Max frequency of 16-bit timer in a UDB pair	_	_	48	MHz	
F <sub>MAX-ADDER</sub>	Max frequency of 16-bit adder in a UDB pair	-	-	48	MHz	
F <sub>MAX_CRC</sub>	Max frequency of 16-bit CRC/PRS in a UDB pair	_	-	48	MHz	
PLD Performance	in UDB					
F <sub>MAX_PLD</sub>	Max frequency of 2-pass PLD function in a UDB pair	-	-	48	MHz	
Clock to Output P	erformance					
T <sub>CLK_OUT_UDB1</sub>	Prop. delay for clock in to data out at 25 °C, Typical	_	15	_	ns	
T <sub>CLK_OUT_UDB2</sub>	Prop. delay for clock in to data out, Worst case	-	25	-	ns	



Table 53. BLE Subsystem

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
RF Receiver Spec	ification					
RXS, IDLE	RX sensitivity with idle transmitter	_	-89	_	dBm	
	RX sensitivity with idle transmitter excluding Balun loss	_	<b>–</b> 91	-	dBm	Guaranteed by design simulation
RXS, DIRTY	RX sensitivity with dirty transmitter	_	-87	-70	dBm	RF-PHY Specification (RCV-LE/CA/01/C)
RXS, HIGHGAIN	RX sensitivity in high-gain mode with idle transmitter	ı	<b>–</b> 91	_	dBm	
PRXMAX	Maximum input power	<b>–10</b>	-1	_	dBm	RF-PHY Specification (RCV-LE/CA/06/C)
CI1	Cochannel interference, Wanted signal at –67 dBm and Interferer at FRX	_	9	21	dB	RF-PHY Specification (RCV-LE/CA/03/C)
CI2	Adjacent channel interference Wanted signal at –67 dBm and Interferer at FRX ±1 MHz	_	3	15	dB	RF-PHY Specification (RCV-LE/CA/03/C)
Cl3	Adjacent channel interference Wanted signal at –67 dBm and Interferer at FRX ±2 MHz	-	-29	_	dB	RF-PHY Specification (RCV-LE/CA/03/C)
Cl4	Adjacent channel interference Wanted signal at –67 dBm and Interferer at ≥FRX ±3 MHz	-	-39	-	dB	RF-PHY Specification (RCV-LE/CA/03/C)
CI5	Adjacent channel interference Wanted Signal at –67 dBm and Interferer at Image frequency (F <sub>IMAGE</sub> )	-	-20	-	dB	RF-PHY Specification (RCV-LE/CA/03/C)
CI3	Adjacent channel interference Wanted signal at –67 dBm and Interferer at Image frequency (F <sub>IMAGE</sub> ± 1 MHz)	-	-30	_	dB	RF-PHY Specification (RCV-LE/CA/03/C)
OBB1	Out-of-band blocking, Wanted signal at –67 dBm and Interferer at F = 30–2000 MHz	-30	-27	_	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
OBB2	Out-of-band blocking, Wanted signal at –67 dBm and Interferer at F = 2003–2399 MHz	<b>–35</b>	-27	_	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
OBB3	Out-of-band blocking, Wanted signal at –67 dBm and Interferer at F = 2484–2997 MHz	<b>–</b> 35	-27	_	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
OBB4	Out-of-band blocking, Wanted signal a –67 dBm and Interferer at F = 3000–12750 MHz	-30	-27	_	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
IMD	Intermodulation performance Wanted signal at –64 dBm and 1-Mbps BLE, third, fourth, and fifth offset channel	<b>–</b> 50	_	_	dBm	RF-PHY Specification (RCV-LE/CA/05/C)
RXSE1	Receiver spurious emission 30 MHz to 1.0 GHz	-	-	-57	dBm	100-kHz measurement bandwidth ETSI EN300 328 V1.8.1



Table 53. BLE Subsystem (continued)

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
RXSE2	Receiver spurious emission 1.0 GHz to 12.75 GHz	-	-	-47	dBm	1-MHz measurement bandwidth ETSI EN300 328 V1.8.1
RF Transmitter Sp	pecifications				•	•
TXP, ACC	RF power accuracy	_	±1	_	dB	
TXP, RANGE	RF power control range	-	20	_	dB	
TXP, 0dBm	Output power, 0-dB Gain setting (PA7)	_	0	_	dBm	
TXP, MAX	Output power, maximum power setting (PA10)	-	3	_	dBm	
TXP, MIN	Output power, minimum power setting (PA1)	-	-18	-	dBm	
F2AVG	Average frequency deviation for 10101010 pattern	185	-	-	kHz	RF-PHY Specification (TRM-LE/CA/05/C)
F1AVG	Average frequency deviation for 11110000 pattern	225	250	275	kHz	RF-PHY Specification (TRM-LE/CA/05/C)
EO	Eye opening = ∆F2AVG/∆F1AVG	8.0	_	_		RF-PHY Specification (TRM-LE/CA/05/C)
FTX, ACC	Frequency accuracy	-150	-	150	kHz	RF-PHY Specification (TRM-LE/CA/06/C)
FTX, MAXDR	Maximum frequency drift	-50	_	50	kHz	RF-PHY Specification (TRM-LE/CA/06/C)
FTX, INITDR	Initial frequency drift	-20	-	20	kHz	RF-PHY Specification (TRM-LE/CA/06/C)
FTX, DR	Maximum drift rate	-20	-	20	kHz/ 50 µs	RF-PHY Specification (TRM-LE/CA/06/C)
IBSE1	In-band spurious emission at 2-MHz offset	_	-	-20	dBm	RF-PHY Specification (TRM-LE/CA/03/C)
IBSE2	In-band spurious emission at ≥3-MHz offset	_	-	-30	dBm	RF-PHY Specification (TRM-LE/CA/03/C)
TXSE1	Transmitter spurious emissions (average), <1.0 GHz	_	-	-55.5	dBm	FCC-15.247
TXSE2	Transmitter spurious emissions (average), >1.0 GHz	_	-	-41.5	dBm	FCC-15.247
RF Current Specif	fications					•
IRX	Receive current in normal mode	-	18.7	_	mA	
IRX_RF	Radio receive current in normal mode	_	16.4	_	mA	Measured at V <sub>DDR</sub>
IRX, HIGHGAIN	Receive current in high-gain mode	_	21.5	_	mA	
ITX, 3dBm	TX current at 3-dBm setting (PA10)	_	20	_	mA	
ITX, 0dBm	TX current at 0-dBm setting (PA7)	_	16.5	-	mA	
ITX_RF, 0dBm	Radio TX current at 0 dBm setting (PA7)	_	15.6	-	mA	Measured at V <sub>DDR</sub>
ITX_RF, 0dBm	Radio TX current at 0 dBm excluding Balun loss	-	14.2	_	mA	Guaranteed by design simulation
ITX,-3dBm	TX current at –3-dBm setting (PA4)	_	15.5	-	mA	
ITX,-6dBm	TX current at –6-dBm setting (PA3)	-	14.5	_	mA	



Table 53. BLE Subsystem (continued)

Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
ITX,-12dBm	TX current at –12-dBm setting (PA2)	-	13.2	-	mA	
ITX,-18dBm	TX current at –18-dBm setting (PA1)	-	12.5	_	mA	
lavg_1sec, 0dBm	Average current at 1-second BLE connection interval	_	17.1	-	μА	TXP: 0 dBm; ±20-ppm master and slave clock accuracy. For empty PDU exchange
lavg_4sec, 0dBm	Average current at 4-second BLE connection interval	_	6.1	-	μА	TXP: 0 dBm; ±20-ppm master and slave clock accuracy. For empty PDU exchange
General RF Specifi	cations					
FREQ	RF operating frequency	2400	-	2482	MHz	
CHBW	Channel spacing	-	2	_	MHz	
DR	On-air data rate	-	1000	_	kbps	
IDLE2TX	BLE.IDLE to BLE. TX transition time	-	120	140	μs	
IDLE2RX	BLE.IDLE to BLE. RX transition time	-	75	120	μs	
RSSI Specifications						
RSSI, ACC	RSSI accuracy	_	±5	-	dB	
RSSI, RES	RSSI resolution	_	1	-	dB	
RSSI, PER	RSSI sample period	-	6	_	μs	



### **Environmental Specifications**

#### **Environmental Compliance**

This Cypress BLE module is built in compliance with the Restriction of Hazardous Substances (RoHS) and Halogen Free (HF) directives. The Cypress module and components used to produce this module are RoHS and HF compliant.

#### RF Certification

The CYBLE-014008-00 module is certified under the following RF certification standards:

■ FCC ID: WAP4008

■ CE

■ IC: 7922A-4008■ MIC (Japan)

■ KC: MSIP-CRM-Cyp-4008

#### **Environmental Conditions**

Table 54 describes the operating and storage conditions for the Cypress BLE module.

Table 54. Environmental Conditions for CYBLE-014008-00

Description	Minimum Specification	Maximum Specification			
Operating temperature	-40 °C	85 °C			
Operating humidity (relative, non-condensation)	5%	85%			
Thermal ramp rate	-	3 °C/minute			
Storage temperature	−40 °C	85 °C			
Storage temperature and humidity	-	85 ° C at 85%			
ESD: Module integrated into system Components <sup>[6]</sup>	-	15 kV Air 2.2 kV Contact			

#### **ESD and EMI Protection**

Exposed components require special attention to ESD and electromagnetic interference (EMI).

A grounded conductive layer inside the device enclosure is suggested for EMI and ESD performance. Any openings in the enclosure near the module should be surrounded by a grounded conductive layer to provide ESD protection and a low-impedance path to ground.

Device Handling: Proper ESD protocol must be followed in manufacturing to ensure component reliability.

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Note

<sup>6.</sup> This does not apply to the RF pins (ANT, XTALI, and XTALO). RF pins (ANT, XTALI, and XTALO) are tested for 500-V HBM.



### **Regulatory Information**

#### **FCC**

#### FCC NOTICE:

The device CYBLE-014008-00 complies with Part 15 of the FCC Rules. The device meets the requirements for modular transmitter approval as detailed in FCC public Notice DA00-1407. Transmitter Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) This device must accept any interference received, including interference that may cause undesired operation.

#### CAUTION:

The FCC requires the user to be notified that any changes or modifications made to this device that are not expressly approved by Cypress Semiconductor may void the user's authority to operate the equipment.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates and can radiate radio frequency energy and, if not installed and used in accordance with the instructions,ê may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help

#### LABELING REQUIREMENTS:

The Original Equipment Manufacturer (OEM) must ensure that FCC labelling requirements are met. This includes a clearly visible label on the outside of the OEM enclosure specifying the appropriate Cypress Semiconductor FCC identifier for this product as well as the FCC Notice above. The FCC identifier is FCC ID: WAP4008.

In any case the end product must be labeled exterior with "Contains FCC ID: WAP4008"

#### ANTENNA WARNING:

This device is tested with a standard SMA connector and with the antennas listed in Table 7 on page 13. When integrated in the OEMs product, these fixed antennas require installation preventing end-users from replacing them with non-approved antennas. Any antenna not in the following table must be tested to comply with FCC Section 15.203 for unique antenna connectors and Section 15.247 for emissions.

#### RF EXPOSURE:

To comply with FCC RF Exposure requirements, the Original Equipment Manufacturer (OEM) must ensure to install the approved antenna in the previous.

The preceding statement must be included as a CAUTION statement in manuals, for products operating with the approved antennas in Table 7 on page 13, to alert users on FCC RF Exposure compliance. Any notification to the end user of installation or removal instructions about the integrated radio module is not allowed.

The radiated output power of CYBLE-014008-00 is far below the FCC radio frequency exposure limits. Nevertheless, use CYBLE-014008-00 in such a manner that minimizes the potential for human contact during normal operation.

End users may not be provided with the module installation instructions. OEM integrators and end users must be provided with transmitter operating conditions for satisfying RF exposure compliance.



#### Industry Canada (IC) Certification

CYBLE-014008-00 is licensed to meet the regulatory requirements of Industry Canada (IC),

License: IC: 7922A-4008

Manufacturers of mobile, fixed or portable devices incorporating this module are advised to clarify any regulatory questions and ensure compliance for SAR and/or RF exposure limits. Users can obtain Canadian information on RF exposure and compliance from www.ic.gc.ca.

This device has been designed to operate with the antennas listed in Table 7 on page 13, having a maximum gain of 0.5 dBi. Antennas not included in this list or having a gain greater than 0.5 dBi are strictly prohibited for use with this device. The required antenna impedance is 50 ohms. The antenna used for this transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

#### IC NOTICE:

The device CYBLE-014008-00 complies with Canada RSS-GEN Rules. The device meets the requirements for modular transmitter approval as detailed in RSS-GEN. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) This device must accept any interference received, including interference that may cause undesired operation.

#### IC RADIATION EXPOSURE STATEMENT FOR CANADA

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

#### LABELING REQUIREMENTS:

The Original Equipment Manufacturer (OEM) must ensure that IC labelling requirements are met. This includes a clearly visible label on the outside of the OEM enclosure specifying the appropriate Cypress Semiconductor IC identifier for this product as well as the IC Notice above. The IC identifier is 7922A-4008. In any case, the end product must be labeled in its exterior with "Contains IC: 7922A-4008".

#### **European R&TTE Declaration of Conformity**

Hereby, Cypress Semiconductor declares that the Bluetooth module CYBLE-014008-00 complies with the essential requirements and other relevant provisions of Directive 1999/5/EC. As a result of the conformity assessment procedure described in Annex III of the Directive 1999/5/EC, the end-customer equipment should be labeled as follows:



All versions of the CYBLE-014008-00 in the specified reference design can be used in the following countries: Austria, Belgium, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Poland, Portugal, Slovakia, Slovenia, Spain, Sweden, The Netherlands, the United Kingdom, Switzerland, and Norway.

Document Number: 002-00023 Rev. \*C



#### **MIC Japan**

CYBLE-014008-00 is certified as a module with type certification number **TBD**. End products that integrate CYBLE-014008-00 do not need additional MIC Japan certification for the end product.

End product can display the certification label of the embedded module.

Model Name: EZ-BLE PSoC Module

Part Number: CYBLE-014008-00

Manufactured by Cypress Semiconductor.





TBD

#### **KC Korea**

CYBLE-014008-00 is certified for use in Korea with certificate number MSIP-CRM-Cyp-4008.

한국 인증 세부정보:



- 1. 제품명(모델명): 특정소출력무선기기(무선데이터통신시스템용 무선기기), CYBLE-014008-00
- 2. 인증 번호: MSIP-CRM-Cyp-4008
- 3. 라이선스 소유자: Cypress Semiconductor Corporation
- 4. 제조일자: 2015.10
- 5. 제조업체/국가명: Cypress Semiconductor Corporation/ 중국

해당 무선설비는 전파혼신 가능성이 있으므로 인명안전과 관련된 서비스는 할 수 없습니다.



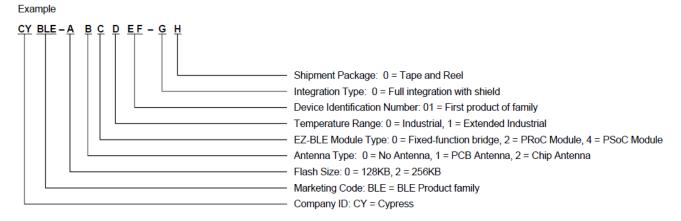
### **Ordering Information**

The CYBLE-014008-00 part number and features are listed in the following table.

		Features													
MPN	Max CPU Speed (MHz)	Flash (KB)	SRAM (KB)	UDB	Opamp (CTBm)	CapSense	Direct LCD Drive	12-bit SAR ADC	LP Comparators	TCPWM Blocks	SCB Blocks	PWMs (using UDBs)	I2S (using UDB)	GPIO	Package
CYBLE-014008-00	48	128	16	4	4	1	1	1 Msps	1	4	2	4	1	25	32-SMT

### **Part Numbering Convention**

The part numbers are of the form CYBLE-ABCDEF-GH where the fields are defined as follows.



For additional information and a complete list of Cypress Semiconductor BLE products, contact your local Cypress sales representative. To locate the nearest Cypress office, visit our website.

U.S. Cypress Headquarters Address	198 Champion Court, San Jose, CA 95134				
U.S. Cypress Headquarter Contact Info	(408) 943-2600				
Cypress website address	http://www.cypress.com				



### **Acronyms**

Table 55. Acronyms Used in this Document

Acronym	Description
ABUS	analog local bus
ADC	analog-to-digital converter
AG	analog global
AHB	AMBA (advanced microcontroller bus archi-
АПБ	tecture) high-performance bus, an ARM data transfer bus
ALU	arithmetic logic unit
AMUXBUS	analog multiplexer bus
API	application programming interface
APSR	application program status register
ARM <sup>®</sup>	advanced RISC machine, a CPU architecture
ATM	automatic thump mode
BLE	Bluetooth Low Energy
Bluetooth SIG	Bluetooth Special Interest Group
BW	bandwidth
CAN	Controller Area Network, a communications protocol
CE	European Conformity
CSA	Canadian Standards Association
CMRR	common-mode rejection ratio
CPU	central processing unit
CRC	cyclic redundancy check, an error-checking protocol
DAC	digital-to-analog converter, see also IDAC, VDAC
DFB	digital filter block
DIO	digital input/output, GPIO with only digital capabilities, no analog. See GPIO.
DMIPS	Dhrystone million instructions per second
DMA	direct memory access, see also TD
DNL	differential nonlinearity, see also INL
DNU	do not use
DR	port write data registers
DSI	digital system interconnect
DWT	data watchpoint and trace
ECC	error correcting code
ECO	external crystal oscillator
EEPROM	electrically erasable programmable read-only memory
EMI	electromagnetic interference

 Table 55. Acronyms Used in this Document (continued)

Acronym	Description
EMIF	external memory interface
EOC	end of conversion
EOF	end of frame
EPSR	execution program status register
ESD	electrostatic discharge
ETM	embedded trace macrocell
FCC	Federal Communications Commission
FET	field-effect transistor
FIR	finite impulse response, see also IIR
FPB	flash patch and breakpoint
FS	full-speed
GPIO	general-purpose input/output, applies to a PSoC pin
HCI	host controller interface
HVI	high-voltage interrupt, see also LVI, LVD
IC	integrated circuit
IDAC	current DAC, see also DAC, VDAC
IDE	integrated development environment
I <sup>2</sup> C, or IIC	Inter-Integrated Circuit, a communications protocol
IC	Industry Canada
IIR	infinite impulse response, see also FIR
ILO	internal low-speed oscillator, see also IMO
IMO	internal main oscillator, see also ILO
INL	integral nonlinearity, see also DNL
I/O	input/output, see also GPIO, DIO, SIO, USBIO
IPOR	initial power-on reset
IPSR	interrupt program status register
IRQ	interrupt request
ITM	instrumentation trace macrocell
KC	Korea Certification
LCD	liquid crystal display
LIN	Local Interconnect Network, a communications protocol.
LR	link register
LUT	lookup table
LVD	low-voltage detect, see also LVI
LVI	low-voltage interrupt, see also HVI
LVTTL	low-voltage transistor-transistor logic



Table 55. Acronyms Used in this Document (continued)

Acronym	Description
MAC	multiply-accumulate
MCU	microcontroller unit
MIC	Ministry of Internal Affairs and Communications (Japan)
MISO	master-in slave-out
NC	no connect
NMI	nonmaskable interrupt
NRZ	non-return-to-zero
NVIC	nested vectored interrupt controller
NVL	nonvolatile latch, see also WOL
Opamp	operational amplifier
PAL	programmable array logic, see also PLD
PC	program counter
PCB	printed circuit board
PGA	programmable gain amplifier
PHUB	peripheral hub
PHY	physical layer
PICU	port interrupt control unit
PLA	programmable logic array
PLD	programmable logic device, see also PAL
PLL	phase-locked loop
PMDD	package material declaration data sheet
POR	power-on reset
PRES	precise power-on reset
PRS	pseudo random sequence
PS	port read data register
PSoC <sup>®</sup>	Programmable System-on-Chip™
PSRR	power supply rejection ratio
PWM	pulse-width modulator
QDID	qualification design ID
RAM	random-access memory
RISC	reduced-instruction-set computing
RMS	root-mean-square
RTC	real-time clock
RTL	register transfer language
RTR	remote transmission request
RX	receive
SAR	successive approximation register
SC/CT	switched capacitor/continuous time
SCL	I <sup>2</sup> C serial clock

Table 55. Acronyms Used in this Document (continued)

Acronym	Description
SDA	I <sup>2</sup> C serial data
S/H	sample and hold
SINAD	signal to noise and distortion ratio
SIO	special input/output, GPIO with advanced features. See GPIO.
SMT	surface-mount technology; a method for producing electronic circuitry in which the components are placed directly onto the surface of PCBs
SOC	start of conversion
SOF	start of frame
SPI	Serial Peripheral Interface, a communications protocol
SR	slew rate
SRAM	static random access memory
SRES	software reset
STN	super twisted nematic
SWD	serial wire debug, a test protocol
SWV	single-wire viewer
TD	transaction descriptor, see also DMA
THD	total harmonic distortion
TIA	transimpedance amplifier
TN	twisted nematic
TRM	technical reference manual
TTL	transistor-transistor logic
TUV	Germany: Technischer Überwachungs-Verein (Technical Inspection Association)
TX	transmit
UART	Universal Asynchronous Transmitter Receiver, a communications protocol
UDB	universal digital block
USB	Universal Serial Bus
USBIO	USB input/output, PSoC pins used to connect to a USB port
VDAC	voltage DAC, see also DAC, IDAC
WDT	watchdog timer
WOL	write once latch, see also NVL
WRES	watchdog timer reset
XRES	external reset I/O pin
XTAL	crystal



## **Document Conventions**

### **Units of Measure**

### Table 56. Units of Measure

Symbol	Unit of Measure				
°C	degrees Celsius				
dB	decibel				
dBm	decibel-milliwatts				
fF	femtofarads				
Hz	hertz				
KB	1024 bytes				
kbps	kilobits per second				
Khr	kilohour				
kHz	kilohertz				
kΩ	kilo ohm				
ksps	kilosamples per second				
LSB	least significant bit				
Mbps	megabits per second				
MHz	megahertz				
ΜΩ	mega-ohm				
Msps	megasamples per second				
μΑ	microampere				
μF	microfarad				
μΗ	microhenry				
μs	microsecond				
μV	microvolt				
μW	microwatt				
mA	milliampere				
ms	millisecond				
mV	millivolt				
nA	nanoampere				
ns	nanosecond				
nV	nanovolt				
Ω	ohm				
pF	picofarad				
ppm	parts per million				
ps	picosecond				
s	second				
sps	samples per second				
sqrtHz	square root of hertz				
V	volt				



### **Errata**

This section describes the errata for the CYBLE-014008-00 module. Details include errata trigger conditions, scope of impact, and available workarounds. Contact your local Cypress Sales Representative if you have questions.

#### **Errata Summary**

- 1. CapSense is not enabled in PSoC Creator.
  - **PROBLEM DEFINITION**

CapSense Support for CYBLE-014008-00 is not enabled in PSoC Creator 3.3.

**■ PARAMETERS AFFECTED** 

None

**■ TRIGGER CONDITIONS** 

Applications that need CapSense functionality will not be able to enable it with PSoC Creator 3.3.

■ SCOPE OF IMPACT

None

**■ WORKAROUND** 

No work around with PSoC Creator 3.3.

**■ FIX STATUS** 

This issue will be fixed in November, 2015 on a future PSoC Creator release.

**■ CHANGES** 

None



## **Document History Page**

Documen Documen	t Title: CYE	BLE-014008- 002-00023	-00 EZ-BLE <sup>™</sup>	PSoC <sup>®</sup> Module
Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	4895738	DSO	8/26/2015	Preliminary datasheet for CYBLE-014008-00 module.
*A	4910660	DSO	9/07/2015	Modify reference of VDD/VDDA minimum voltage from 1.8V to 1.71V. Update Table 2 on page 5 Connections number from 21 to 32. Remove Footnotes 4, 5, and 6 on Page 8. Update Table 5 on page 9 to remove LPCOMP capabilities from Pads 2, 3, 4, 14, 30, and 31. Update Table 5 on page 9 to specify Vref (Pad 26) as Optional. Update Figure 5 on page 10 to swap diagram descriptions. Update Table 11 on page 16 T <sub>Hibernate</sub> from 2 ms to 800 μs. Update Table 53 on page 27 - changed power consumption lavg_1sec from 18.5 mA to 17.1 mA. Update Table 53 on page 27 - changed power consumption lavg_4sec from 6.25 mA to 6.1 mA.
*B	4944131	DSO	09/25/2015	Update Table 3 on page 7 to correct a typo in seventh row - changed "Distance from top right corner to Pad 6 center" to ""Distance from Pad 5 center to Pad 6 center". Corrected Footnotes 3 to specify ground connection as Pad 1 and Pad 32. Added $V_{DDA}$ to $V_{DDD\_RIPPLE}$ specification description Table 8 on page 14. Update Table 10 on page 14, parameters $V_{DD1}$ and $V_{DD2}$ to specify that $V_{DD} = V_{DDA} = V_{DDR}$ Removed Table 14 (OVT GPIO DC Specifications) and Table 15 (OVT GPIO AC Specifications). Added regulatory certification country in RF Certification on page 30 Added Errata section on page 38.
*C		DSO	10/29/2015	Update General Description to add reference link to PSoC® 4 BLE datasheet. Update Regulatory Information section to include final FCC, IC, and KC certification identification numbers. Update Industry Canada (IC) Certification on page 32 to add IC Radiation Exposure Statement for Canada (English and French language) per Industry Canada Requirements.



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