
SAR Test Report

Report No.: AGC01570141106FH01

FCC ID : WRYHLT-5199U

APPLICATION PURPOSE : Original Equipment

Product Designation : Handheld Two Way Radio

Brand Name : Havoc

Model Name : HLT-5199U , HLT-A31 , HLT-A31U

Client : EKL Imports LLC

Date of Issue : Nov 12,2014

STANDARD(S) : IEEE Std. 1528:2003
47CFR § 2.1093
IEEE/ANSI C95.1

REPORT VERSION : V1.0

Attestation of Global Compliance(Shenzhen) Co., Ltd.

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Report Revise Record

| Report Version | Revise Time | Issued Date | Valid Version | Notes |
|----------------|-------------|-------------|---------------|-----------------|
| V1.0 | / | Nov 12,2014 | Valid | Original Report |

Test Report Certification

| | |
|------------------------|--|
| Applicant Name | EKL Imports LLC |
| Applicant Address | PO Box 1997 Gig Harbor WA 98335 USA |
| Manufacturer Name | Juston Electronic Equipment Co., Ltd. |
| Manufacturer Address | No.115-119,Yuantai 3 rd Road, Jiangnan Hi-tech Park, Licheng District, Quanzhou, China,362000 |
| Product Name | Handheld Two Way Radio |
| Brand Name | Havoc |
| Model Name | HLT-5199U , HLT-A31 , HLT-A31U |
| Difference Description | All the same, except for the model name. The test model is HLT-5199U |
| EUT Voltage | DC7.4V by battery |
| Applicable Standard | IEEE Std. 1528:2003 47CFR § 2.1093 IEEE/ANSI C95.1 |
| Test Date | Oct. 06,2014 |
| Performed Location | Attestation of Global Compliance (Shenzhen)Co., Ltd. 2F, Building 2, No.1-No.4, Chaxi Sanwei Technical Industrial Park, Gushu, Xixiang Street, Bao'an District, Shenzhen, China |
| Report Template | AGCRT-EC-PPT/SAR (2013-03-01) |

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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:
Highest Report tested & scaled SAR Summary (with 50% duty cycle)

| Exposure Position | Separation | Highest Tested 1g-SAR(W/Kg) | Highest Reported SAR(W/Kg) |
|-------------------|------------|-----------------------------|----------------------------|
| Face Up | 12.5 KHz | 3.915 | 4.383 |
| Back Touch | 12.5 KHz | 3.665 | 4.103 |

This device is compliance with Specific Absorption Rate (SAR) for Occupational / Controlled Exposure Environment limits (8.0W/Kg) specified in 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1, and had been tested in accordance with measurement methods and procedures specified in IEEE 1528-2003 and the following specific FCC Test Procedures:

KDB 447498 D01 General RF Exposure Guidance v05

KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r03

KDB 643646 D01 SAR Test for PTT Radios V01r01

2. GENERAL INFORMATION

2.1. EUT Description

| General Information | |
|--------------------------|----------------------------------|
| Product Name | Handheld Two Way Radio |
| Test Model | HLT-5199U |
| Hardware Version | N/A |
| Software Version | N/A |
| Exposure Category: | Occupational/Controlled Exposure |
| Device Category | FM UHF Portable Transceiver |
| Modulation Type | FM |
| TX Frequency Range | 400-470MHz |
| Rated Power | UHF:5Watt |
| Max. Average Power | UHF: 36.98dBm |
| Channel Spacing | 12.5 KHz |
| Antenna Type | External Antenna |
| Antenna Gain | 2.15dBi |
| Body-Worn Accessories: | Belt Clip with headset |
| Face-Head Accessories: | None |
| Battery Type (s) Tested: | DC 7.4V, 1600mAh (by battery) |

| | |
|---------|--|
| Product | Type |
| | <input checked="" type="checkbox"/> Production unit <input type="checkbox"/> Identical Prototype |

2.2. Test Procedure

| | |
|---|--|
| 1 | Setup the EUT for two typical configuration of hold to face and body worn individually |
| 2 | Power on the EUT and make it continuously transmitting on required operating channel |
| 3 | Make sure the EUT work normally during the test |

2.3. Test Environment

Ambient conditions in the laboratory:

| Items | Required | Actual |
|------------------|----------|--------|
| Temperature (°C) | 18-25 | 21 ± 2 |
| Humidity (%RH) | 30-70 | 56 |

3. SAR MEASUREMENT SYSTEM

3.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume (dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg)

SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \left. \frac{dT}{dt} \right|_{t=0}$$

Where

| | |
|-----------------------------|--|
| SAR | is the specific absorption rate in watts per kilogram; |
| E | is the r.m.s. value of the electric field strength in the tissue in volts per meter; |
| σ | is the conductivity of the tissue in siemens per metre; |
| ρ | is the density of the tissue in kilograms per cubic metre; |
| c_h | is the heat capacity of the tissue in joules per kilogram and Kelvin; |
| $\frac{dT}{dt} \quad t = 0$ | is the initial time derivative of temperature in the tissue in kelvins per second |

3.2. SAR Measurement Procedure

The EUT is set to transmit at the required power in line with product specification, at each frequency relating to the LOW, MID, and HIGH channel settings.

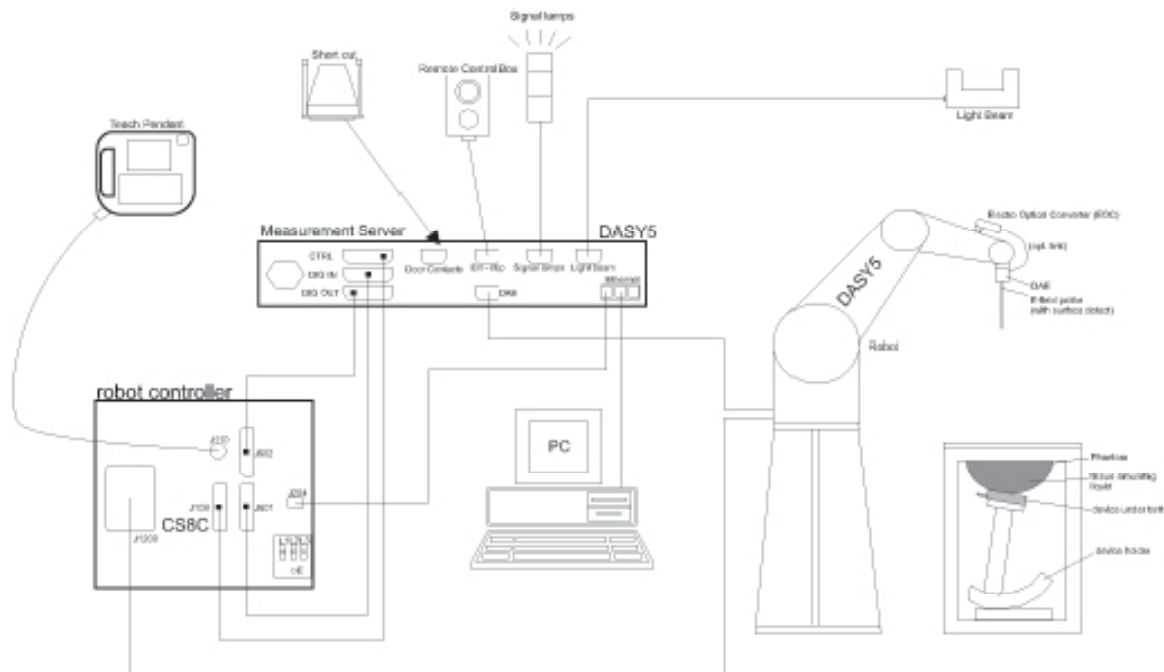
Pre-scans are made on the device to establish the location for the transmitting antenna, using a large area scan in either air or tissue simulation fluid.

The EUT is placed against the Flat Phantom where the maximum area scan dimensions are larger than the physical size of the resonating antenna. When the scan size is not large enough to cover the peak SAR distribution, it is modified by either extending the area scan size in both the X and Y directions, or the device is shifted within the predefined area.

The area scan is then run to establish the peak SAR location (interpolated resolution set at 1mm^2) which is then used to orient the center of the zoom scan. The zoom scan is then executed and the 1g and 10g averages are derived from the zoom scan volume (interpolated resolution set at 1mm^3).

When multiple peak SAR location were found during the same configuration or test mode, Zoom scan shall performed on each peak SAR location, only the peak point with maximum SAR value will be reported for the configuration or test mode.

3.3. DASY SAR System Description



DASY5 System Configurations

The DASY system for performing compliance tests consists of the following items:

- (1) A standard high precision 6-axis robot with controller, teach pendant and software.
- (2) A data acquisition electronics (DAE) which attached to the robot arm extension. The DAE consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit.
- The mechanical probe mounting device includes two different sensor systems frontal and side-ways probe contacts. They are used for mechanical surface detection and probe collision detection.
- (3) Mechanical surface detection uses the probe collision detector built into the DAE box. It is extremely accurate if the probe is normal to the surface
- (4) A Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- (5) A computer running WinXP .
- (6) DASY software.
- (7) Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- (8) Phantoms, device holders and other accessories according to the targeted measurement.

3.3.1. Applications

Predefined procedures and evaluations for automated compliance testing with all worldwide standards, e.g., IEEE 1528, Reference KDB files, and others.

3.3.2. Area Scans

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 10mm² step integral, with 1mm interpolation used to locate the peak SAR area used for zoom scan assessments. When an Area Scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE 1528-2003, Reference KDB files standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan).

3.3.3. Zoom Scan (Cube Scan Averaging)

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. A density of 1000 kg/m³ is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1 g cube is 10mm, with the side length of the 10 g cube 21,5mm. The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications utilize a physical step of 7x7x7 (5mmx5mmx5mm) providing a volume of 30mm in the X & Y axis, and 30mm in the Z axis.

3.3.4. Uncertainty of Inter-/Extrapolation and Averaging

In order to evaluate the uncertainty of the interpolation, extrapolation and averaged SAR calculation algorithms of the Post processor, DASY allows the generation of measurement grids which are artificially predefined by analytically based test functions. Therefore, the grids of area scans and zoom scans can be filled with uncertainty test data, according to the SAR benchmark functions of IEEE 1528. The three analytical functions shown in equations as below are used to describe the possible range of the expected SAR distributions for the tested handsets. The field gradients are covered by the spatially flat distribution f1, the spatially steep distribution f3 and f2 accounts for H-field cancellation on the phantom/tissue surface.

$$f_1(x, y, z) = A e^{-\frac{z}{2a}} \cos^2 \left(\frac{\pi}{2} \frac{\sqrt{x'^2 + y'^2}}{5a} \right)$$


$$f_2(x, y, z) = A e^{-\frac{z}{a}} \frac{a^2}{a^2 + x'^2} \left(3 - e^{-\frac{2z}{a}} \right) \cos^2 \left(\frac{\pi}{2} \frac{y'}{3a} \right)$$

$$f_3(x, y, z) = A \frac{a^2}{\frac{a^2}{4} + x'^2 + y'^2} \left(e^{-\frac{2z}{a}} + \frac{a^2}{2(a + 2z)^2} \right)$$

3.4. DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, Reference KDB files, etc.). The calibration data are in Appendix D.

3.5. Isotropic E-Field Probe Specification

| | | | |
|---------------|--|---|--|
| Model | ES3DV3 | | |
| Manufacture | SPEAG | | |
| frequency | 0.03GHz-3GHz Linearity:±0.2dB(30MHz-3GHz) |  | |
| Dynamic Range | 0.01W/Kg-100W/Kg Linearity:±0.2dB | | |
| Dimensions | Overall length:337mm Tip diameter:4mm Typical distance from probe tip to dipole centers:2mm | | |
| Application | High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%. | | |

3.6. Robot

The DASY system uses the high precision robots (DASY5:TX60) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from is used. The XL robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



3.7. Light Beam Unit

The light beam switch allows automatic “tooling” of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



3.8. Device Holder

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles.

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon=3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



3.9. Measurement Server

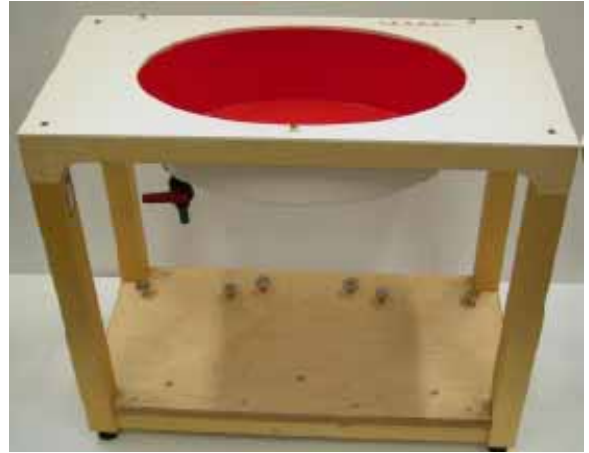
The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip-disk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DAYS I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



3.10. ELI4 Phantom

Flat phantom a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

4. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 4.2

4.1. The composition of the tissue simulating liquid

| Ingredient (% Weight) Tissue Type | 450 MHz Head | 450 MHz Body |
|--------------------------------------|--------------|--------------|
| Water | 48.9 | 51.16 |
| Salt (NaCl) | 1.7 | 1.49 |
| Sugar | 0.0 | 46.78 |
| HEC | 0.0 | 0.52 |
| Bactericide | 0.5 | 0.05 |
| Diacetin | 48.9 | 0.0 |

4.2. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY5 Dielectric Probe Kit and R&S Network Analyzer ZVL6 .

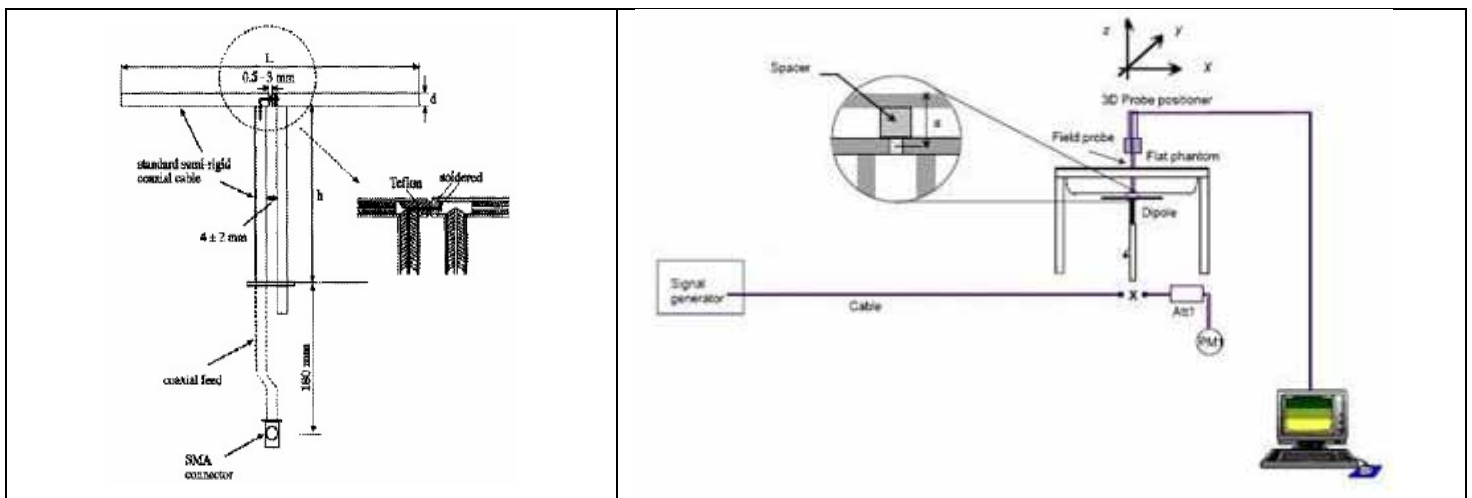
| Tissue Stimulant Measurement for 450MHz | | | | | | |
|---|------------------------------------|---------------------------------------|-----------------------------------|----------------------------------|------------------------|--------------|
| Frequency (MHz) | Dielectric Parameters (±5%) | | | | Tissue Temp [°C] | Test time |
| | head | | body | | | |
| | εr 43.50 41.325 to 45.675 | δ[s/m] 0.87 0.8265 to 0.9135 | εr 56.7 53.865 to 59.535 | δ[s/m] 0.94 0.893 to 0.987 | | |
| 400.025 | 43.15 | 0.87 | 56.52 | 0.93 | 21 | Oct. 06,2014 |
| 417.500 | 43.20 | 0.85 | 56.24 | 0.91 | 21 | Oct. 06,2014 |
| 435.000 | 42.11 | 0.89 | 56.13 | 0.95 | 21 | Oct. 06,2014 |
| 452.500 | 43.09 | 0.88 | 56.17 | 0.92 | 21 | Oct. 06,2014 |
| 469.975 | 43.28 | 0.86 | 55.78 | 0.96 | 21 | Oct. 06,2014 |

4.3. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in P1528.

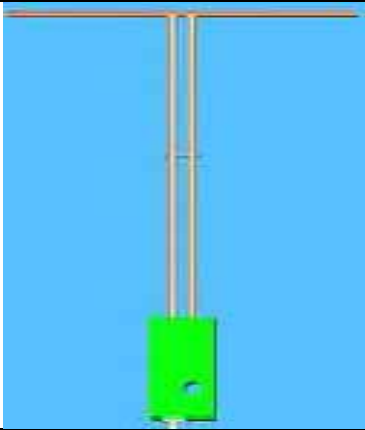
| Target Frequency (MHz) | head | | body | |
|---------------------------|--------------|----------------|--------------|----------------|
| | ϵ_r | σ (S/m) | ϵ_r | σ (S/m) |
| 150 | 52.3 | 0.76 | 61.9 | 0.80 |
| 300 | 45.3 | 0.87 | 58.2 | 0.92 |
| 450 | 43.5 | 0.87 | 56.7 | 0.94 |
| 835 | 41.5 | 0.90 | 55.2 | 0.97 |
| 900 | 41.5 | 0.97 | 55.0 | 1.05 |
| 915 | 41.5 | 0.98 | 55.0 | 1.06 |
| 1450 | 40.5 | 1.20 | 54.0 | 1.30 |
| 1610 | 40.3 | 1.29 | 53.8 | 1.40 |
| 1800 – 2000 | 40.0 | 1.40 | 53.3 | 1.52 |
| 2450 | 39.2 | 1.80 | 52.7 | 1.95 |
| 3000 | 38.5 | 2.40 | 51.6 | 2.73 |
| 5800 | 35.3 | 5.27 | 48.2 | 6.00 |

(ϵ_r = relative permittivity, σ = conductivity and ρ = 1000 kg/m³)



5.2. SAR System Validation

5.2.1. Validation Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of both IEEE and FCC Supplement C. the table below provides details for the mechanical and electrical Specifications for the dipoles.

| Frequency | L (mm) | h (mm) | d (mm) |
|-----------|--------|--------|--------|
| 450MHz | 290 | 166.7 | 6.35 |

5.2.2. Validation Result

| System Performance Check at 450MHz | | | | | | | | |
|---------------------------------------|-----------------------|------|------------------------------------|-------------|-----------------------|------|-------------------------|--------------|
| Validation Kit: SN 46/11DIP 0G450-184 | | | | | | | | |
| Frequency [MHz] | Target Value(W/Kg) | | Reference Result ($\pm 10\%$) | | Tested Value(W/Kg) | | Tissue Temp. [°C] | Test time |
| | 1g | 10g | 1g | 10g | 1g | 10g | | |
| 450 head | 4.91 | 3.13 | 4.419-5.401 | 2.817-3.443 | 4.70 | 3.12 | 21 | Oct. 06,2014 |
| 450 body | 5.07 | 3.25 | 4.563-5.577 | 2.925-3.575 | 4.66 | 3.22 | 21 | Oct. 06,2014 |

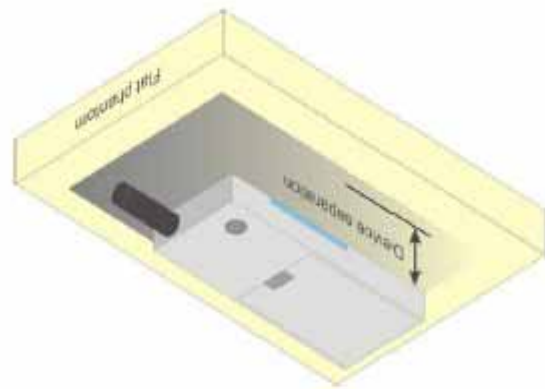
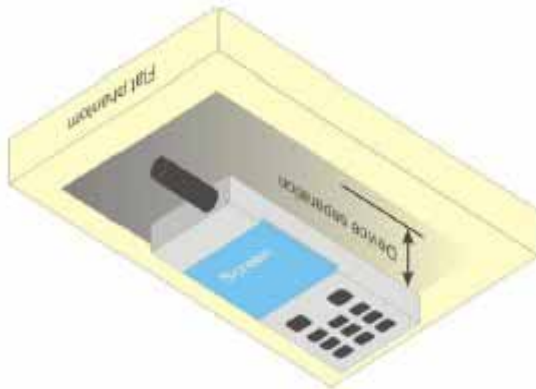
Note: The input power of system check is 27dBm.

6. EUT TEST POSITION

This EUT was tested in **Front Face and Rear Face**.

6.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **25mm** while used in front of face, and body back touch with belt clip.



7. SAR EXPOSURE LIMITS

SAR assessments have been made in line with the requirements of IEEE-1528, FCC Supplement C, and comply with ANSI/IEEE C95.1-1992 "Controlled Exposure Environment" limits. These limits apply to a location which is deemed as "Controlled Exposure Environment" which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for Occupational / Controlled Exposure Environment

| Type Exposure Limits | Occupational / Controlled Exposure Environment(W/Kg) |
|----------------------------------|--|
| Spatial Average SAR (whole body) | 8.0 |

8. TEST EQUIPMENT LIST

| Equipment description | Manufacturer/ Model | Identification No. | Current calibration date | Next calibration date |
|-------------------------------|------------------------|--------------------------|-----------------------------|--------------------------|
| Stäubli Robot | Stäubli-TX60 | F13/5Q2UD1/A/01 | N/A | N/A |
| TISSUE Probe | SATIMO | SN 45/11 OCPG45 | 11/14/2013 | 11/13/2015 |
| Robot Controller | Stäubli-CS8 | 139522 | N/A | N/A |
| E-Field Probe | ES3DV3 | SN:3337 | 09/05/2014 | 09/04/2015 |
| ELI4 Phantom | ELI V5.0 | 1210 | N/A | N/A |
| Device Holder | Speag-SD 000 H01 KA | SD 000 H01 KA | N/A | N/A |
| DAE4 | Speag-SD 000 D04 BM | 1398 | 10/10/2013 | 10/09/2014 |
| SAR Software | Speag-DASY5 | DASY52.8 | N/A | N/A |
| Liquid | SPEAG | - | N/A | N/A |
| Radio Communication Tester | R&S-CMU200 | 069Y7-158-13-712 | 02/17/2014 | 02/16/2015 |
| Dipole | SATIMO SID450 | SN46/11 DIP 0G450-184 | 11/14/2013 | 11/13/2016 |
| Signal Generator | Agilent-E4438C | MY44260051 | 02/23/2014 | 02/22/2015 |
| Power Sensor | NRP-Z23 | US38261498 | 02/17/2014 | 02/16/2015 |
| SPECTRUM ANALYZER | Agilent- E4440A | MY44303916 | 10/22/2013 | 10/21/2014 |
| Network Analyzer | Rhode & Schwarz ZVA | SN100132 | 02/17/2014 | 02/16/2015 |

Note: Per KDB 865664 Dipole SAR Validation Verification, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

9. MEASUREMENT UNCERTAINTY

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 12.1

| Uncertainty Distributions | Normal | Rectangular | Triangular | U-Shape |
|---------------------------|----------|--------------|--------------|--------------|
| Multi-plying Factor(a) | $1/k(b)$ | $1/\sqrt{3}$ | $1/\sqrt{6}$ | $1/\sqrt{2}$ |

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) k is the coverage factor

Table 13.1 Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.

| Measurement uncertainty for 30 MHz to 3GHz averaged over 1 gram / 10 gram. | | | | | | | |
|--|-------------------------|--------------------------|---------|---------|----------|---------------------------|----------------------------|
| Error Description | Uncertainty value(±10%) | Probability Distribution | Divisor | (Ci) 1g | (Ci) 10g | Standard Uncertainty (1g) | Standard Uncertainty (10g) |
| Measurement System | | | | | | | |
| Probe Calibration | 6.0 | Normal | 1 | 1 | 1 | ±6.0% | ±6.0% |
| Axial Isotropy | 4.7 | Rectangular | √3 | 0.7 | 0.7 | ±1.9% | ±1.9% |
| Hemispherical Isotropy | 9.6 | Rectangular | √3 | 0.7 | 0.7 | ±3.9% | ±3.9% |
| Linearity | 4.7 | Rectangular | √3 | 1 | 1 | ±2.7% | ±2.7% |
| Probe Modulation Response | 2.4 | Rectangular | √3 | 1 | 1 | ±1.4% | ±1.4% |
| System Detection Limits | 1.0 | Rectangular | √3 | 1 | 1 | ±0.6% | ±0.6% |
| Boundary Effects | 2.0 | Rectangular | √3 | 1 | 1 | ±1.2% | ±1.2% |
| Readout Electronics | 0.3 | Normal | √3 | 1 | 1 | ±0.3% | ±0.3% |
| Response Time | 0.8 | Rectangular | √3 | 1 | 1 | ±0.5% | ±0.5% |
| Integration Time | 2.6 | Rectangular | √3 | 1 | 1 | ±1.5% | ±1.5% |
| RF Ambient Noise | 3.0 | Rectangular | √3 | 1 | 1 | ±1.7% | ±1.7% |
| RF Ambient Reflection | 3.0 | Rectangular | √3 | 1 | 1 | ±1.7% | ±1.7% |
| Probe Positioner | 0.8 | Rectangular | √3 | 1 | 1 | ±0.5% | ±0.5% |
| Probe Positioning | 6.7 | Rectangular | √3 | 1 | 1 | ±3.9% | ±3.9% |
| Post-processing | 4.0 | Rectangular | √3 | 1 | 1 | ±2.3% | ±2.3% |
| Test Sample Related | | | | | | | |
| Device Positioning | 3.6 | Normal | 1 | 1 | 1 | ±3.6% | ±2.3% |
| Device Holder | 2.9 | Normal | 1 | 1 | 1 | ±2.9% | ±2.3% |
| Measurement SAR Drift | 5.0 | Rectangular | √3 | 1 | 1 | ±2.9% | ±2.3% |
| Power Scaling | 0.0 | Rectangular | √3 | 1 | 1 | ±0.0% | ±2.3% |
| Phantom and Setup | | | | | | | |
| Phantom Uncertainty | 4.0 | Rectangular | √3 | 1 | 1 | ±2.3% | ±2.3% |
| Liquid Conductivity(Meas.) | 2.5 | Normal | 1 | 0.78 | 0.71 | ±2.0% | ±2.0% |
| Liquid Conductivity(Target) | 5.0 | Rectangular | √3 | 0.64 | 0.43 | ±1.8% | ±1.8% |
| Liquid Permittivity(Meas.) | 2.5 | Normal | | 0.26 | 0.26 | ±0.7% | ±0.7% |
| Liquid Permittivity((Target) | 5.0 | Rectangular | √3 | 0.6 | 0.49 | ±1.7% | ±1.4% |
| Liquid Conductivity-temperature uncertainty | 1.7 | Rectangular | √3 | 0.78 | 0.71 | ±0.8% | ±0.7% |
| Liquid Permittivity-temperature uncertainty | 0.3 | Rectangular | √3 | 0.23 | 0.26 | ±0.0% | ±0.0% |
| Combined Standard Uncertainty | | | | | | ±12.2% | ±11.9% |
| Coverage Factor for 95% | | | | | | K=2 | |
| Expanded Uncertainty | | | | | | ±22.0% | ±21.5% |

10. CONDUCTED POWER MEASUREMENT

| Frequency (MHz) | Channel Spacing | Measured Conducted Output power | |
|--------------------|-----------------|---------------------------------|---------------------|
| | | Max. Peak Power (dBm) | Avg. Power (dBm) |
| 400.125 | 12.5KHz | 36.98 | 36.51 |
| 417.500 | | 36.75 | 36.45 |
| 435.000 | | 36.91 | 36.47 |
| 452.500 | | 36.59 | 36.25 |
| 469.975 | | 36.93 | 36.50 |

11. TEST RESULTS

11.1. SAR Test Results Summary

11.1.1. Test position and configuration

Head SAR was performed with the device configured in the positions according to KDB 643646 and Body SAR was performed with the device configured with all accessories close to the Flat Phantom.

11.1.2. Operation Mode

- Set the EUT to maximum output power level and transmit on lower, middle and top channel with 100% duty cycle individually during SAR measurement.
- Per KDB 447498D01 v05r02 Chapter 4.1 6) the number of channels to be assessed is 5.
- Per KDB 643646 D01, Passive body-worn and audio accessories generally do not apply to the head SAR of PTT radios. Head SAR is measured with the front surface of the radio positioned at 2.5 cm parallel to a flat phantom.

When testing antennas with the default battery:

- a. When the $SAR \leq 3.5$ W/kg, testing of all other required channels is not necessary for that antenna;
 - b. When the $SAR > 3.5$ W/kg and ≤ 4.0 W/kg, testing of the required immediately channel(s) is not necessary; testing of the other required channels may still be required.
 - c. When the $SAR > 4.0$ W/kg and ≤ 6.0 W/kg, SAR should be measured for that antenna on the all required channels;
 - d. When the highest measured SAR is ≤ 6.0 W/kg, PBA is not required
- Per KDB 643646 D01, Body SAR is measured with the radio placed in a body-worn accessory, positioned against a flat phantom, representative of the normal operating conditions expected by users and typically with a standard default audio accessory supplied with the radio.

When testing antennas with the default battery: the same test measurement with head part.

11.1.3. Test Result

| SAR MEASUREMENT | | | | | | | | | |
|---|---------|------------------|-----------------------|------------------------------------|-----------------------------------|--------------------------|--------------------------|-------------------|------------|
| Ambient Temperature (°C) : 21 ±2 | | | | | Relative Humidity (%): 55 | | | | |
| Liquid Temperature (°C) : 21 ±2 | | | | | Depth of Liquid (cm):>15 | | | | |
| Product: Handheld Two Way Radio | | | | | | | | | |
| Test Mode: Hold to Face with 2.5 cm separation & body back touch with clip and accessories (UHF) | | | | | | | | | |
| Position | Mode | Separation (KHz) | Power Drift (<±0.2db) | SAR 1g with 100% duty Cycle (W/kg) | SAR 1g with 50% duty cycle (W/Kg) | Max. Turn-up Power (dBm) | Meas. output Power (dBm) | Scaled SAR (W/Kg) | Limit W/kg |
| Face Up | 400.125 | 12.5 | -0.12 | 7.83 | 3.915 | 37 | 36.51 | 4.383 | 8.0 |
| Face Up | 417.500 | 12.5 | -0.02 | 4.40 | 2.20 | 37 | 36.45 | 2.497 | 8.0 |
| Face Up | 435.000 | 12.5 | -0.03 | 4.89 | 2.445 | 37 | 36.47 | 2.762 | 8.0 |
| Face Up | 452.500 | 12.5 | 0.18 | 5.42 | 2.71 | 37 | 36.25 | 3.220 | 8.0 |
| Face Up | 469.975 | 12.5 | -0.16 | 7.64 | 3.82 | 37 | 36.50 | 4.286 | 8.0 |
| Back Touch | 400.125 | 12.5 | 0.01 | 7.33 | 3.665 | 37 | 36.51 | 4.103 | 8.0 |
| Back Touch | 417.500 | 12.5 | 0.05 | 5.13 | 2.565 | 37 | 36.45 | 2.911 | 8.0 |
| Back Touch | 435.000 | 12.5 | -0.09 | 6.33 | 3.165 | 37 | 36.47 | 3.576 | 8.0 |
| Back Touch | 452.500 | 12.5 | 0.16 | 5.67 | 2.835 | 37 | 36.25 | 3.369 | 8.0 |
| Back Touch | 469.975 | 12.5 | -0.17 | 6.71 | 3.355 | 37 | 36.50 | 3.764 | 8.0 |
| Note: 1 During the test, EUT power is 5 W with 100% duty cycle; 2. There is just default battery and antenna in this project; 3 According to KDB 643646 D01, when testing antennas with the default battery: a. When the SAR≤ 3.5 W/kg, testing of all other required channels is not necessary for that antenna; b. When the SAR > 3.5 W/kg and ≤ 4.0 W/kg, testing of the required immediately channel(s) is not necessary; testing of the other required channels may still be required. c. When the SAR > 4.0 W/kg and ≤ 6.0 W/kg, SAR should be measured for that antenna on the all required channels; d. When the highest scaled SAR is ≤ 6.0 W/kg, PBA is not required | | | | | | | | | |

| Repeated SAR | | | | | | | | |
|---|-----------------|-------------------|-----------------------|---|--|--|---|------------|
| Ambient Temperature (°C) : 21 ±2 | | | | | Relative Humidity (%): 55 | | | |
| Liquid Temperature (°C) : 21 ±2 | | | | | Depth of Liquid (cm):>15 | | | |
| Product: Handheld Two Way Radio | | | | | | | | |
| Test Mode: Hold to Face with 2.5 cm separation(UHF) | | | | | | | | |
| Position | Frequency (MHz) | Separati on (KHz) | Power Drift (<±0.2db) | Once SAR 1g with 100% duty cycle (W/kg) | Once SAR 1g with 50% duty cycle (W/Kg) | Twice SAR 1g with 100% duty cycle (W/kg) | Twice SAR 1g with 50% duty cycle (W/kg) | Limit W/kg |
| Face Up | 400.125 | 12.5 | -0.01 | 7.81 | 3.91 | -- | -- | 8.0 |

APPENDIX A. SAR SYSTEM VALIDATION DATA

Test Laboratory: AGC Lab
System Check Head 450MHz

Test date: Oct. 06,2014

DUT: Dipole 450 MHz Type: SID 450

Communication System: CW; Communication System Band: CW; Duty Cycle: 1:1;
Frequency: 435MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma = 0.89 \text{ mho/m}$; $\epsilon_r = 42.11$; $\rho = 1000 \text{ kg/m}^3$;
Phantom Type: Elliptical Phantom; Input Power=27 dBm
Ambient temperature (): 21.0, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

450-HSL-18dBm/27dBm 2/Area Scan (11x33x1): Measurement grid: $dx=10\text{mm}$, $dy=10\text{mm}$

Maximum value of SAR (measured) = 2.67 W/kg

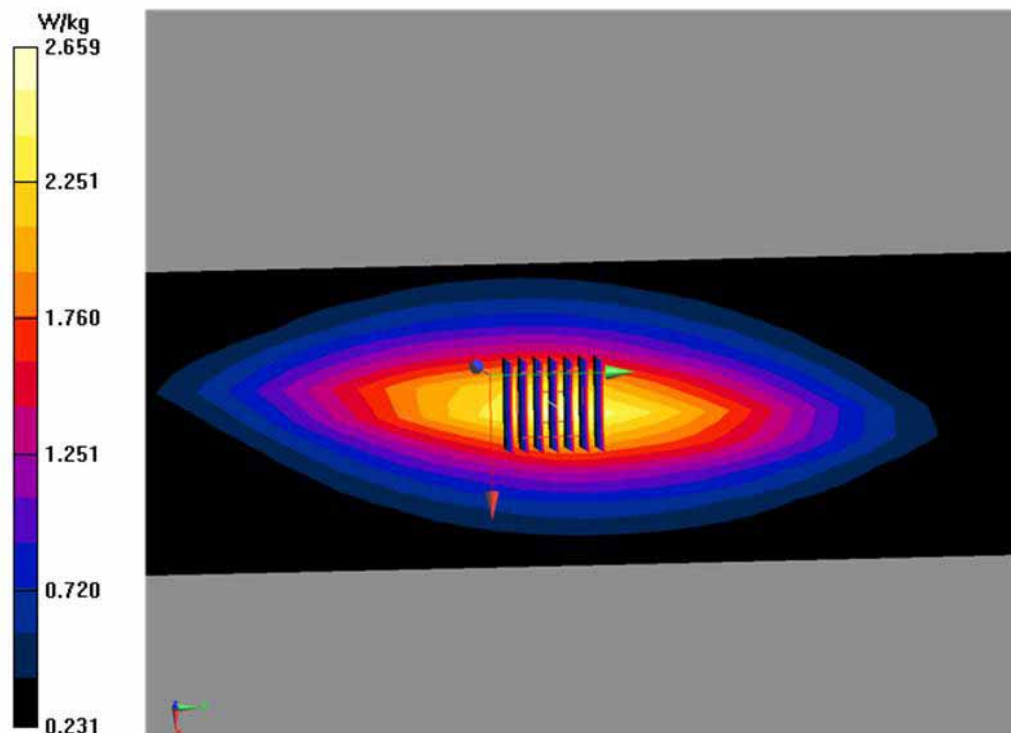
450-HSL-18dBm/27dBm 2/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 58.262 V/m; Power Drift = 0.01 dB

Peak SAR (extrapolated) = 3.65 W/kg

SAR(1 g) = 2.35 W/kg; SAR(10 g) = 1.56 W/kg

Maximum value of SAR (measured) = 2.72 W/kg



Test Laboratory: AGC Lab
System Check Body 450MHz

Test date: Oct. 06,2014

DUT: Dipole 450 MHz Type: SID 450

Communication System: CW; Communication System Band: CW; Duty Cycle: 1:1;
Frequency: 450MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma=0.95\text{ mho/m}$; $\epsilon_r=56.13$; $\rho = 1000\text{ kg/m}^3$;
Phantom Type: Elliptical Phantom; Input Power=27 dBm
Ambient temperature (): 21.0, Liquid temperature (): 21.0

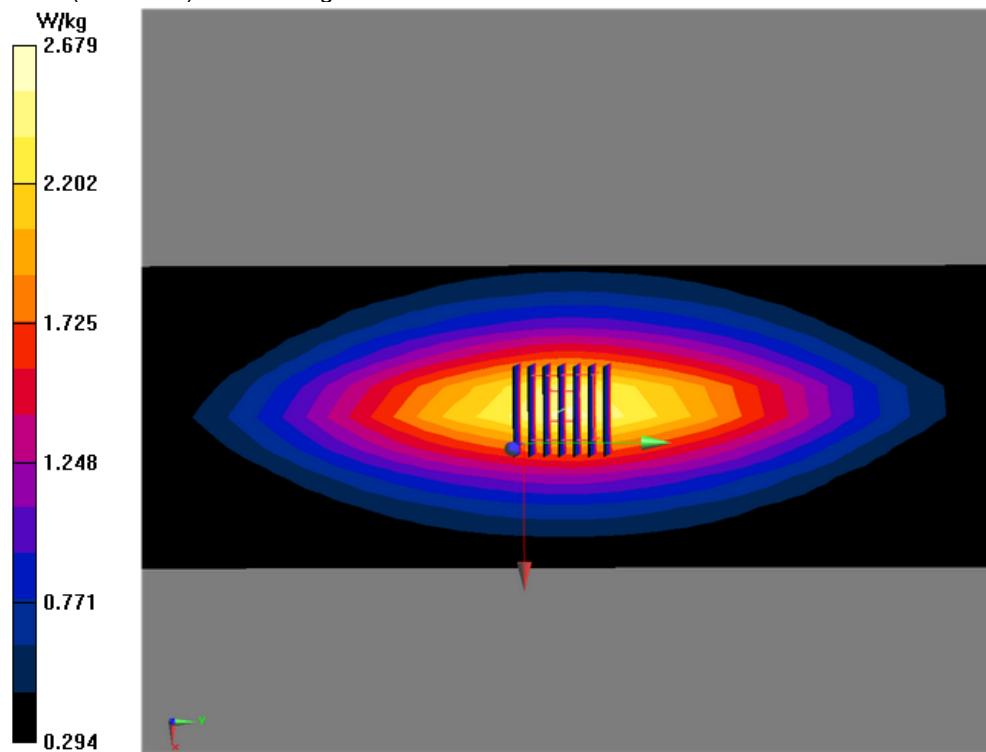
DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(7.08,7.08,7.08); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

Configuration/System Check 450MHz Body/Area Scan (11×33×1): Measurement grid: $dx=10.000\text{mm}$, $dy=10.000\text{mm}$,
Maximum value of SAR (measured)=2.61 W/Kg

Configuration/System Check 900MHz Body/Zoom Scan (7×7×7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy = 5\text{mm}$, $dz=5\text{mm}$,
Reference Value=56.950 V/m; Power Drift=0.12 dB
Peak SAR (extrapolated) =3.48 W/kg

SAR (1g) =2.33 W/Kg; SAR (10g) =1.61 W/Kg
Maximum value of SAR (measured)=2.679 W/Kg



APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab

Date: Oct. 06,2014

CW450 channel 1-face up 2.5cm (12.5 KHz)

DUT: Handheld Two Way Radio; Type: HLT-5199U

Communication System: CW; Communication System Band: CW 450MHz; Duty Cycle: 1:1;

Frequency: 400.125 MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma = 0.87\text{ mho/m}$; $\epsilon_r = 43.15$; $\rho = 1000\text{ kg/m}^3$;

Phantom Type: Elliptical Phantom

Ambient temperature (): 21.5, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FRONT/1/Area Scan (8x12x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Maximum value of SAR (measured) = 8.73 W/kg

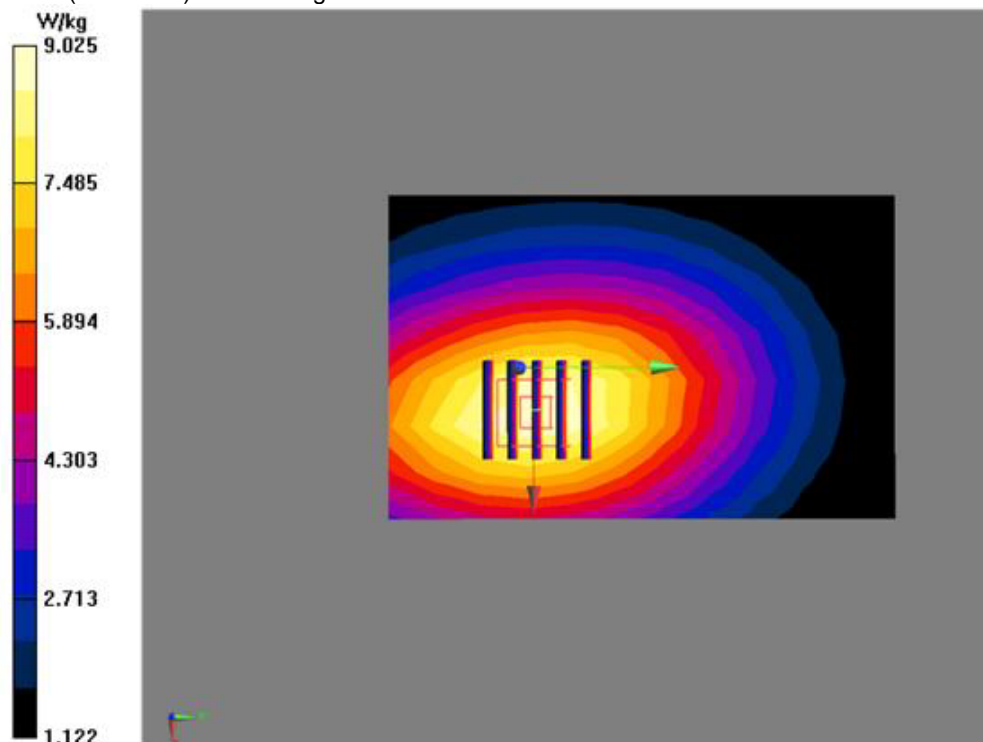
FRONT/1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$

Reference Value = 98.256 V/m; Power Drift = -0.12 dB

Peak SAR (extrapolated) = 10.4 W/kg

SAR(1 g) = 7.83 W/kg; SAR(10 g) = 5.79 W/kg

Maximum value of SAR (measured) = 9.03 W/kg



Test Laboratory: AGC Lab
CW450 channel 2-face up 2.5cm (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

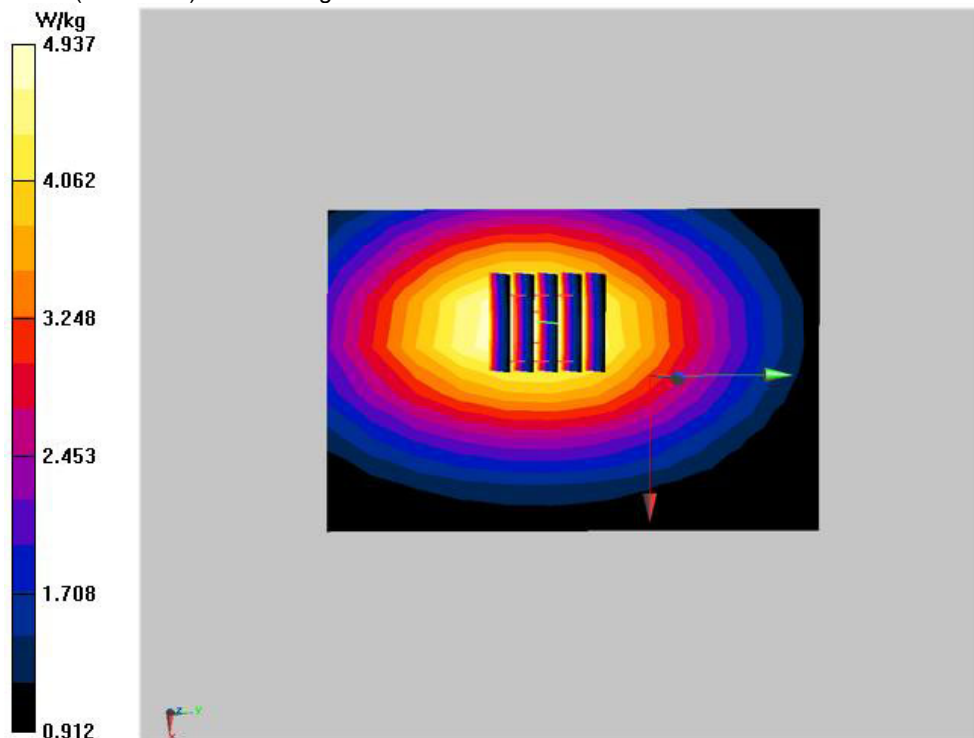
Communication System: CW; Communication System Band: CW 450MHz; Duty Cycle: 1:1;
Frequency: 417.500 MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma = 0.85 \text{ mho/m}$; $\epsilon_r = 43.20$; $\rho = 1000 \text{ kg/m}^3$;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FRONT/2/Area Scan (8x12x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$
Maximum value of SAR (measured) = 4.90 W/kg

FRONT/2/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$
Reference Value = 78.152 V/m; Power Drift = -0.02 dB
Peak SAR (extrapolated) = 6.21 W/kg
SAR(1 g) = 4.40 W/kg; SAR(10 g) = 3.21 W/kg
Maximum value of SAR (measured) = 4.94 W/kg



Test Laboratory: AGC Lab
CW450 channel 3- face up 2.5cm (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

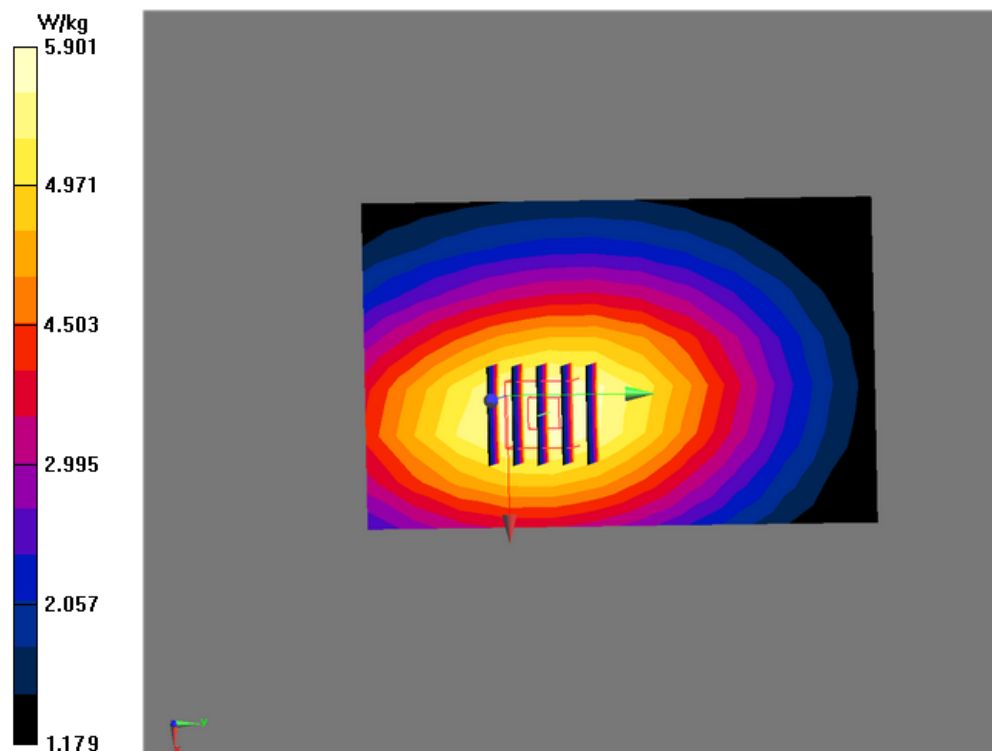
Communication System: CW; Communication System Band: CW 450MHz; Duty Cycle: 1:1;
Frequency:435.000 MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma=0.89\text{ mho/m}$; $\epsilon_r=42.11$; $\rho= 1000\text{ kg/m}^3$;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FRONT/3/Area Scan (8x12x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$
Maximum value of SAR (measured) = 5.97 W/kg

FRONT/3/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$
Reference Value = 83.265 V/m; Power Drift = -0.13 dB
Peak SAR (extrapolated) = 7.09 W/kg
SAR(1 g) = 5.28 W/kg; SAR(10 g) = 3.97 W/kg
Maximum value of SAR (measured) = 5.90 W/kg



Test Laboratory: AGC Lab
CW450 channel 4- face up 2.5cm (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

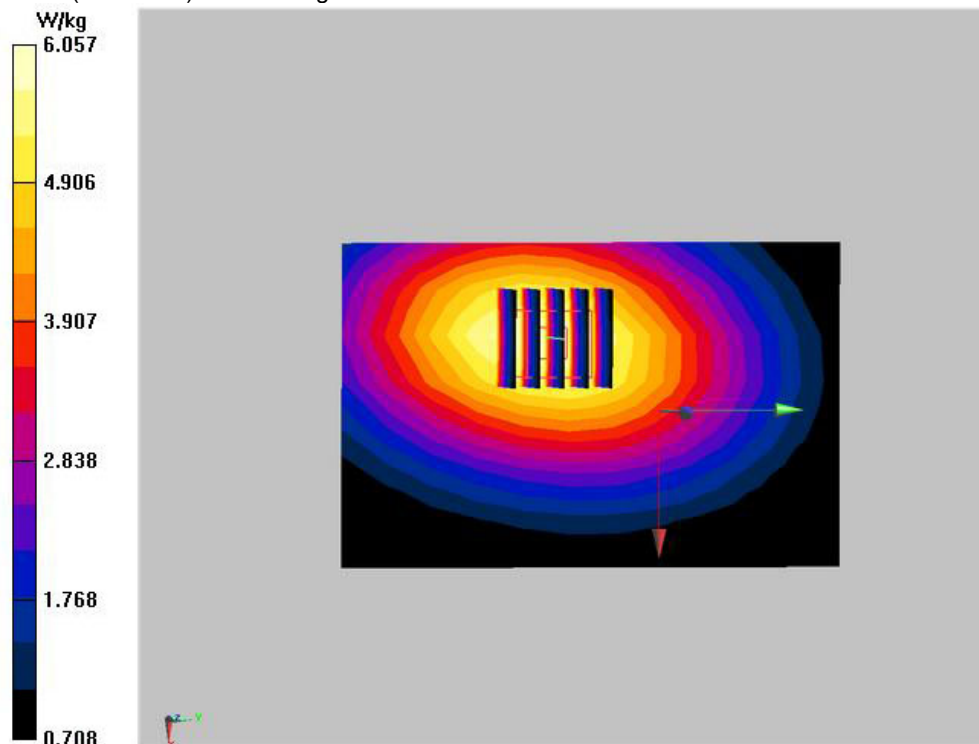
Communication System: CW; Communication System Band: CW 450MHz; Duty Cycle: 1:1;
Frequency:452.500 MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma=0.88\text{ mho/m}$; $\epsilon_r=43.09$; $\rho= 1000\text{ kg/m}^3$;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FRONT 4/Area Scan (8x14x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$
Maximum value of SAR (measured) = 5.98 W/kg

FRONT 4/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$
Reference Value = 86.977V/m; Power Drift = 0.18 dB
Peak SAR (extrapolated) = 7.42 W/kg
SAR(1 g) = 5.42 W/kg; SAR(10 g) = 4.03 W/kg
Maximum value of SAR (measured) = 6.06 W/kg



Test Laboratory: AGC Lab
CW450 channel 5- face up 2.5cm (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

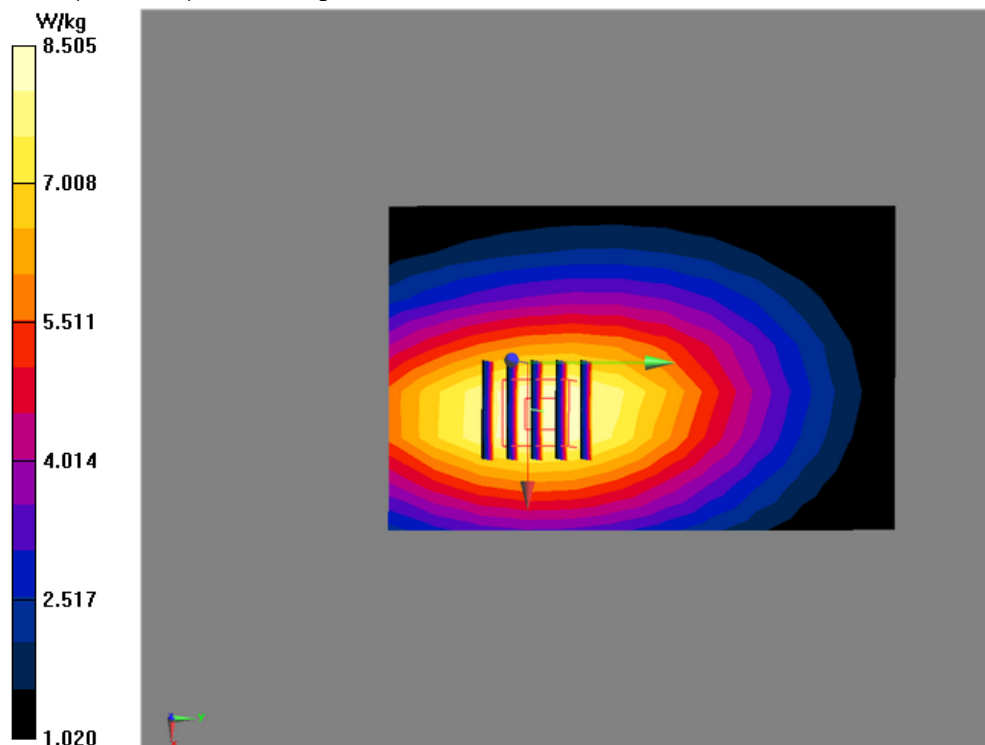
Communication System: CW; Communication System Band: CW 450MHz; Duty Cycle: 1:1;
Frequency: 469.975MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma = 0.86 \text{ mho/m}$; $\epsilon_r = 43.28$; $\rho = 1000 \text{ kg/m}^3$;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FRONT/5/Area Scan (8x12x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$
Maximum value of SAR (measured) = 8.34 W/kg

FRONT/5/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$
Reference Value = 98.198 V/m; Power Drift = -0.16 dB
Peak SAR (extrapolated) = 10.3 W/kg
SAR(1 g) = 7.64 W/kg; SAR(10 g) = 5.66 W/kg
Maximum value of SAR (measured) = 8.51 W/kg



Test Laboratory: AGC Lab
CW450 channel 1 -Body -Touch (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

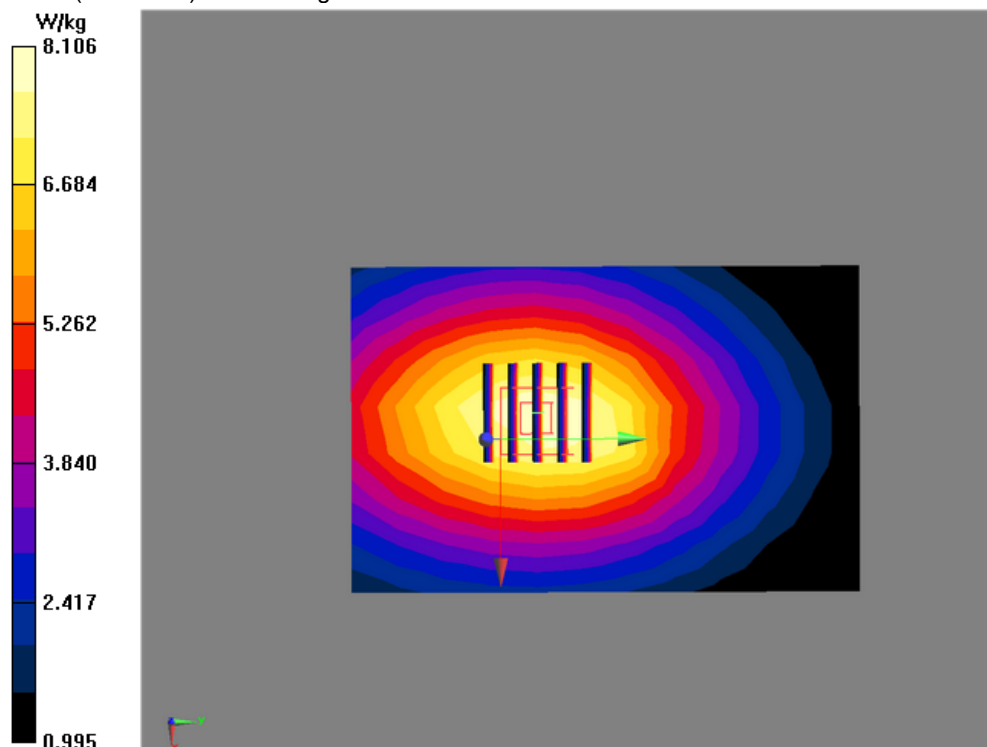
Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1;
Frequency:400.125MHz; Medium parameters used: $f = 450$ MHz; $\sigma=0.93$ mho/m; $\epsilon_r =56.52$; $\rho= 1000$ kg/m³ ;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature(): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(7.08,7.08,7.08); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BACK/1/Area Scan (8x12x1): Measurement grid: $dx=15$ mm, $dy=15$ mm
Maximum value of SAR (measured) = 8.09 W/kg

BACK/1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8$ mm, $dy=8$ mm, $dz=5$ mm
Reference Value = 99.887 V/m; Power Drift = 0.01 dB
Peak SAR (extrapolated) = 9.57 W/kg
SAR(1 g) = 7.33 W/kg; SAR(10 g) = 5.46 W/kg
Maximum value of SAR (measured) = 8.11 W/kg



Test Laboratory: AGC Lab
CW450 channel 2 -Body -Touch (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

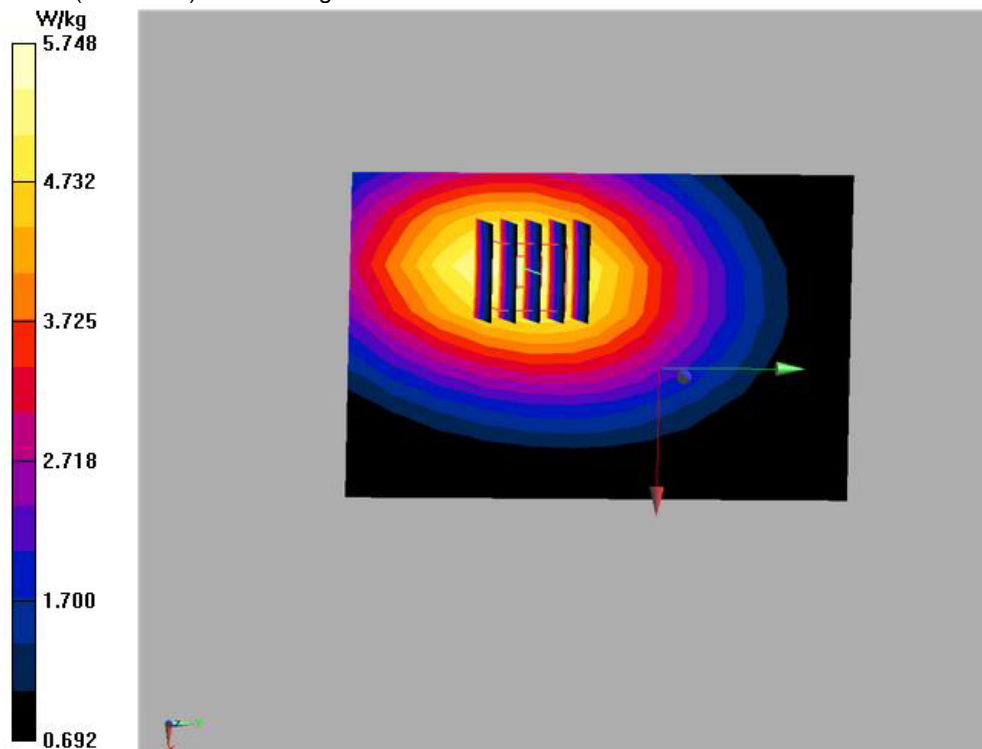
Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1;
Frequency:417.500MHz; Medium parameters used: $f = 450$ MHz; $\sigma=0.91$ mho/m; $\epsilon_r=56.24$; $\rho= 1000$ kg/m³ ;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature(): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(7.08,7.08,7.08); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BACK/ 2/Area Scan (8x14x1): Measurement grid: $dx=15$ mm, $dy=15$ mm
Maximum value of SAR (measured) = 5.65 W/kg

BACK /2/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8$ mm, $dy=8$ mm, $dz=5$ mm
Reference Value = 85.751V/m; Power Drift = 0.05 dB
Peak SAR (extrapolated) = 7.00 W/kg
SAR(1 g) = 5.13 W/kg; SAR(10 g) = 3.78 W/kg
Maximum value of SAR (measured) = 5.75 W/kg



Test Laboratory: AGC Lab
CW450 channel 3 -Body –Touch (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

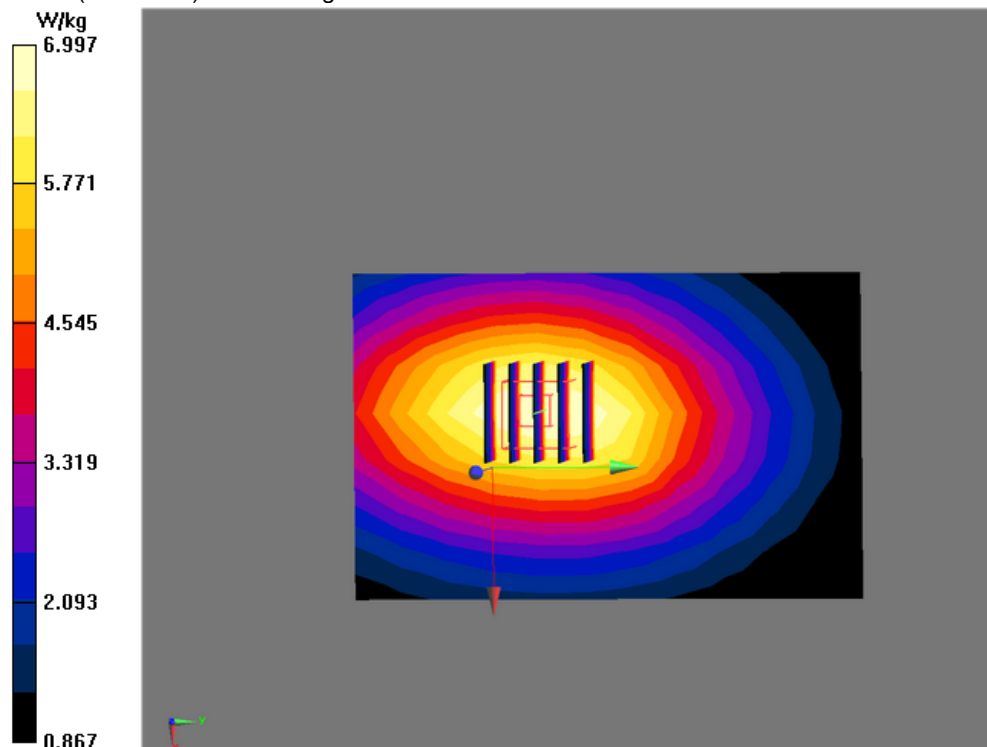
Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1;
Frequency:435.000 MHz; Medium parameters used: $f = 450$ MHz; $\sigma=0.95$ mho/m; $\epsilon_r=56.13$; $\rho= 1000$ kg/m³ ;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature(): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(7.08,7.08,7.08); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD; ;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BACK/3/Area Scan (8x12x1): Measurement grid: $dx=15$ mm, $dy=15$ mm
Maximum value of SAR (measured) = 7.17 W/kg

BACK/3/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8$ mm, $dy=8$ mm, $dz=5$ mm
Reference Value = 92.787 V/m; Power Drift = -0.09 dB
Peak SAR (extrapolated) = 8.28 W/kg
SAR(1 g) = 6.33 W/kg; SAR(10 g) = 4.73 W/kg
Maximum value of SAR (measured) = 7.00 W/kg



Test Laboratory: AGC Lab
CW450 channel 4 -Body –Touch (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

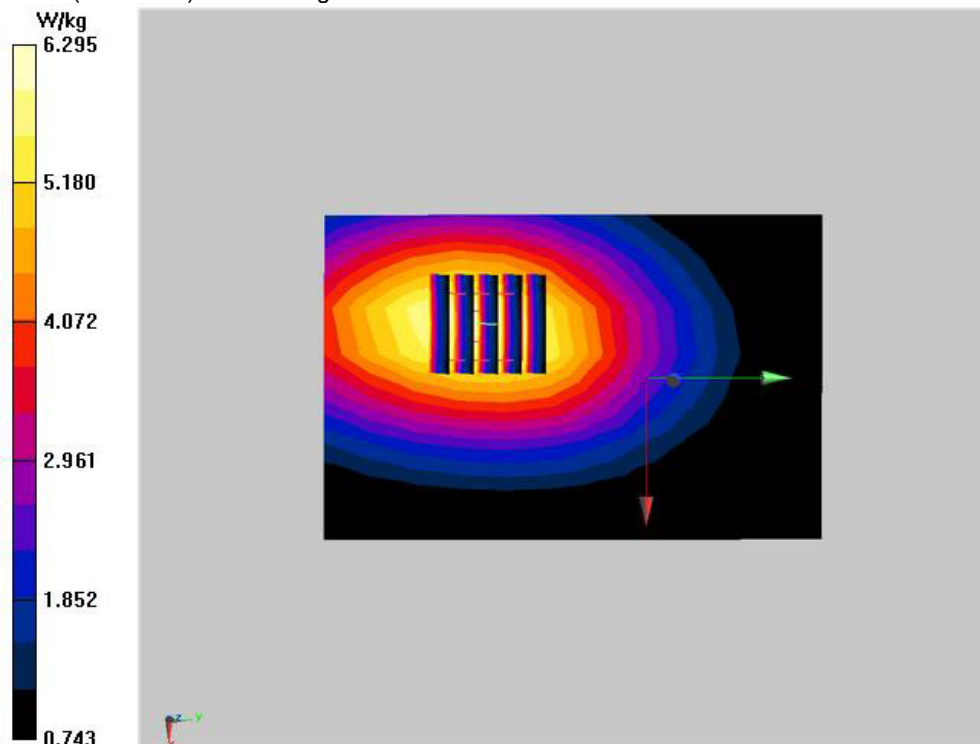
Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1;
Frequency:452.500 MHz; Medium parameters used: $f = 450$ MHz; $\sigma=0.92$ mho/m; $\epsilon_r=56.17$; $\rho= 1000$ kg/m³ ;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature(): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(7.08,7.08,7.08); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD; ;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BACK /4/Area Scan (8x14x1): Measurement grid: $dx=15$ mm, $dy=15$ mm
Maximum value of SAR (measured) = 6.44 W/kg

BACK /4/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8$ mm, $dy=8$ mm, $dz=5$ mm
Reference Value = 86.029 V/m; Power Drift = 0.14 dB
Peak SAR (extrapolated) = 7.71 W/kg
SAR(1 g) = 5.67 W/kg; SAR(10 g) = 4.24 W/kg
Maximum value of SAR (measured) = 6.30 W/kg



Test Laboratory: AGC Lab
CW450 channel 5 -Body –Touch (12.5 KHz)
DUT: Handheld Two Way Radio; Type: HLT-5199U

Date: Oct. 06,2014

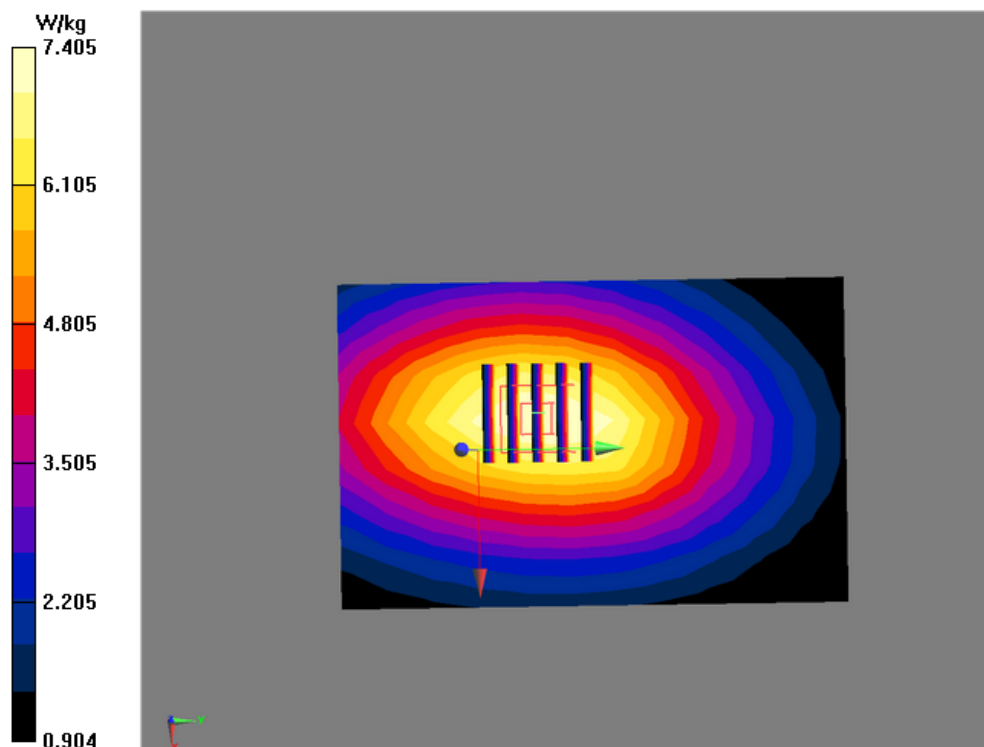
Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1;
Frequency: 469.975MHz; Medium parameters used: $f = 450$ MHz; $\sigma = 0.96$ mho/m; $\epsilon_r = 55.78$; $\rho = 1000$ kg/m³ ;
Phantom Type: Elliptical Phantom
Ambient temperature (): 21.5, Liquid temperature(): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(7.08,7.08,7.08); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BACK/5/Area Scan (8x12x1): Measurement grid: $dx=15$ mm, $dy=15$ mm
Maximum value of SAR (measured) = 7.50 W/kg

BACK/5/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8$ mm, $dy=8$ mm, $dz=5$ mm
Reference Value = 94.379 V/m; Power Drift = -0.17 dB
Peak SAR (extrapolated) = 8.83 W/kg
SAR(1 g) = 6.71 W/kg; SAR(10 g) = 5.06 W/kg
Maximum value of SAR (measured) = 7.41 W/kg



Repeated SAR

Test Laboratory: AGC Lab

Date: Oct. 06,2014

CW450Low-face up 2.5cm (12.5 KHz)

DUT: Handheld Two Way Radio; Type: HLT-5199U

Communication System: CW; Communication System Band: CW 450MHz; Duty Cycle: 1:1;

Frequency: 400.125 MHz; Medium parameters used: $f = 450\text{MHz}$; $\sigma = 0.87 \text{ mho/m}$; $\epsilon_r = 43.15$; $\rho = 1000 \text{ kg/m}^3$;

Phantom Type: Elliptical Phantom

Ambient temperature (): 21.5, Liquid temperature (): 21.0

DASY Configuration:

- Probe: ES3DV3-SN:3337; ConvF(6.71,6.71,6.71); Calibrated: 09/05/2014;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0$,
- Electronics: DAE4 Sn1398; Calibrated: 10/10/2013
- Phantom: ELI4 (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FRONT/1/Area Scan (8x12x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Maximum value of SAR (measured) = 8.39 W/kg

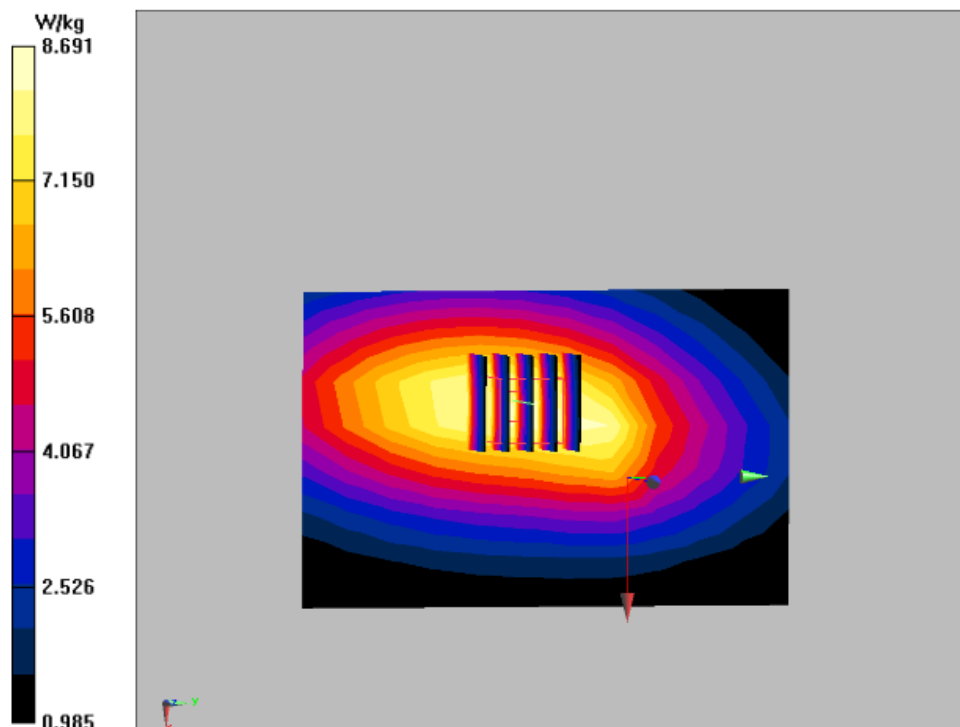
FRONT/1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$

Reference Value = 90.045 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 10.47 W/kg

SAR(1 g) = 7.81 W/kg; SAR(10 g) = 5.80 W/kg

Maximum value of SAR (measured) = 8.69 W/kg



APPENDIX C. TEST SETUP PHOTOGRAPHS & EUT PHOTOGRAPHS

Test Setup Photographs

Face Up with 25mm Separation Distance.



Body Back Touch with all accessories

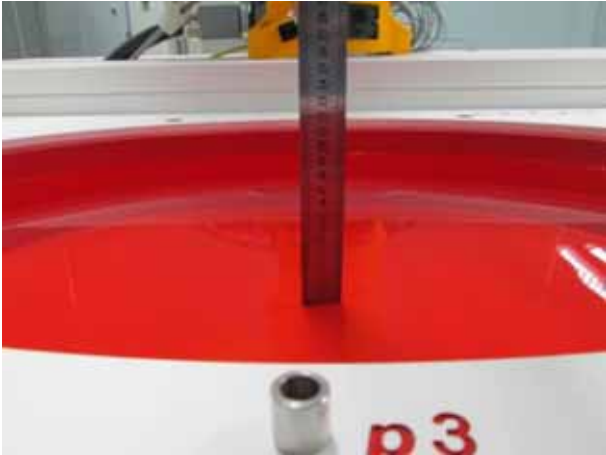





Note : The headset is just for testing. This tested and electrically similar headsets may be used.

DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note : The position used in the measurement were according to IEEE 1528-2003

| 450MHz Head | 450MHz Body |
|---|--|
|  |  |

EUT PHOTOGRAPHS

TOTAL VIEW OF EUT



TOP VIEW OF EUT



BOTTOM VIEW OF EUT



FRONT VIEW OF EUT



BACK VIEW OF EUT



LEFT VIEW OF EUT



RIGHT VIEW OF EUT



OPEN VIEW-1 OF EUT



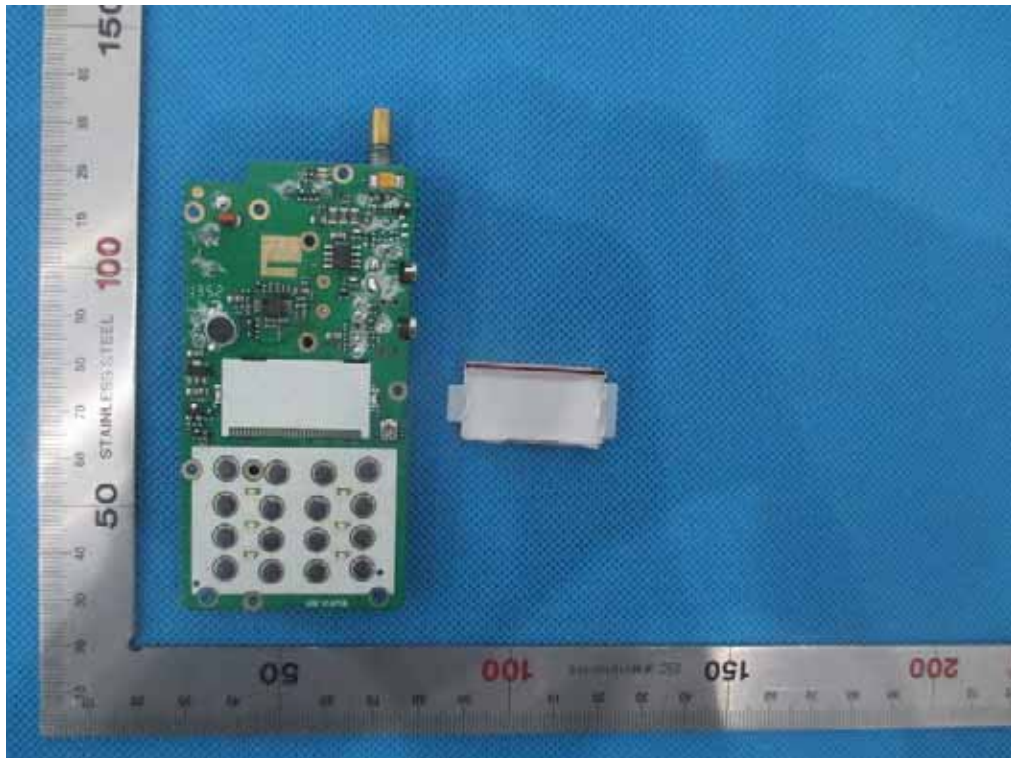
OPEN VIEW-2 OF EUT



INTERNAL VIEW-1 OF EUT



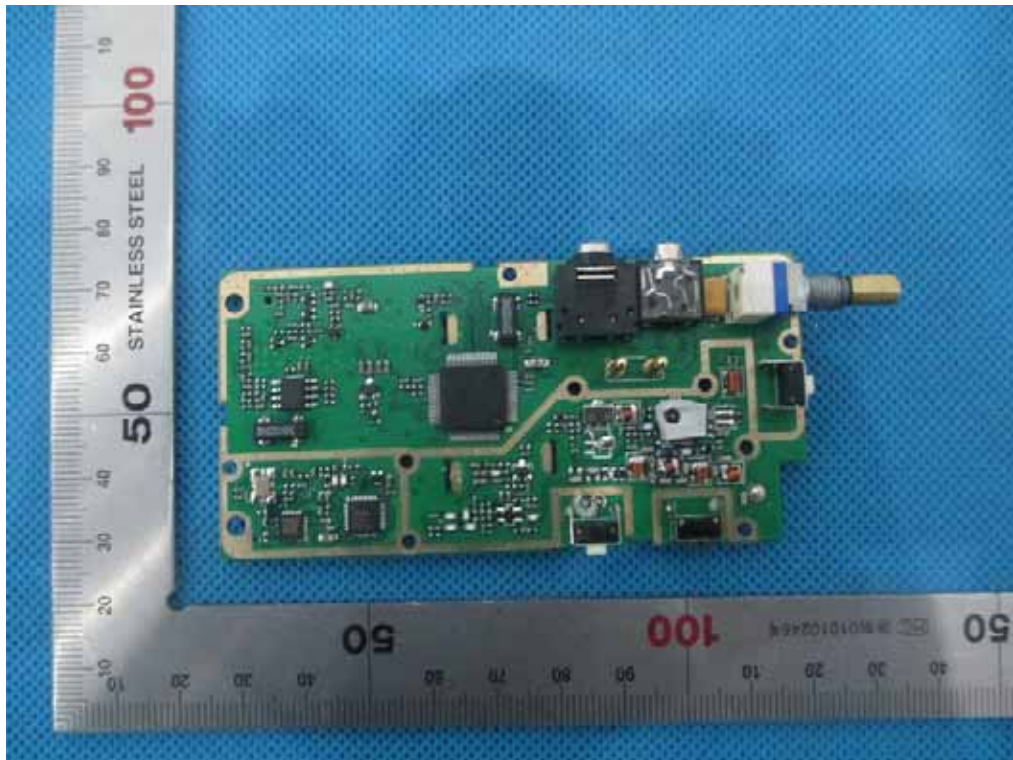
INTERNAL VIEW-2 OF EUT



INTERNAL VIEW-3 OF EUT



INTERNAL VIEW-4 OF EUT



APPENDIX D. PROBE CALIBRATION DATA

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Accreditation No.: **SCS 108**

Client **AGC-CERT (Auden)**

Certificate No: **ES3-3337_Sep14**

CALIBRATION CERTIFICATE

Object **ES3DV3 - SN:3337**

Calibration procedure(s) **QA CAL-01.v9, QA CAL-12.v9, QA CAL-23.v5, QA CAL-25.v6
Calibration procedure for dosimetric E-field probes**

Calibration date **September 5, 2014**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility; environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID | Cal Date (Certificate No.) | Scheduled Calibration |
|----------------------------|-----------------|-----------------------------------|------------------------|
| Power meter E4419B | GB41293874 | 03-Apr-14 (No. 217-01911) | Apr-15 |
| Power sensor E4412A | MY41498087 | 03-Apr-14 (No. 217-01911) | Apr-15 |
| Reference 3 dB Attenuator | SN: S5054 (3c) | 03-Apr-14 (No. 217-01915) | Apr-15 |
| Reference 20 dB Attenuator | SN: S5277 (20x) | 03-Apr-14 (No. 217-01919) | Apr-15 |
| Reference 30 dB Attenuator | SN: S5129 (30b) | 03-Apr-14 (No. 217-01920) | Apr-15 |
| Reference Probe ES3DV2 | SN: 3013 | 30-Dec-13 (No. ES3-3013, Dec13) | Dec-14 |
| DAE4 | SN: 660 | 13-Dec-13 (No. DAE4-660, Dec13) | Dec-14 |
| Secondary Standards | ID | Check Date (in house) | Scheduled Check |
| RF generator HP 8648C | US3642U01700 | 4-Aug-99 (in house check Apr-13) | In house check: Apr-16 |
| Network Analyzer HP 8753E | US37390585 | 16-Oct-01 (in house check Oct-13) | In house check: Oct-14 |

| | Name | Function | Signature |
|---|----------------|-----------------------|-----------|
| Calibrated by: | Jeton Kastrati | Laboratory Technician | |
| Approved by: | Katja Pokovic | Technical Manager | |
| Issued: September 6, 2014 | | | |
| This calibration certificate shall not be reproduced except in full without written approval of the laboratory. | | | |

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

| | |
|-----------------------|---|
| TSL | tissue simulating liquid |
| NORM _{x,y,z} | sensitivity in free space |
| ConvF | sensitivity in TSL / NORM _{x,y,z} |
| DCP | diode compression point |
| CF | crest factor (1/duty_cycle) of the RF signal |
| A, B, C, D | modulation dependent linearization parameters |
| Polarization ϕ | ϕ rotation around probe axis |
| Polarization θ | θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\theta = 0$ is normal to probe axis |
| Connector Angle | information used in DASY system to align probe sensor X to the robot coordinate system |

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\theta = 0$ ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not affect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; D_{x,y,z}; VR_{x,y,z}**: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).

ES3DV3 – SN:3337

September 5, 2014

Probe ES3DV3

SN:3337

| | |
|---------------|-------------------|
| Manufactured: | January 24, 2012 |
| Repaired: | August 25, 2014 |
| Calibrated: | September 5, 2014 |

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

ES3DV3- SN:3337

September 5, 2014

DASY/EASY - Parameters of Probe: ES3DV3 - SN:3337

Basic Calibration Parameters

| | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|---|----------|----------|----------|---------------|
| Norm ($\mu\text{V}/(\text{V}/\text{m})^2$) ^A | 1.11 | 0.97 | 1.00 | $\pm 10.1 \%$ |
| DCP (mV) ^B | 104.8 | 103.8 | 103.8 | |

Modulation Calibration Parameters

| UID | Communication System Name | | A dB | B dB $\sqrt{\mu\text{V}}$ | C | D dB | VR mV | Unc ^C (k=2) |
|-----|---------------------------|---|---------|------------------------------|-----|---------|----------|---------------------------|
| 0 | CW | X | 0.0 | 0.0 | 1.0 | 0.00 | 168.6 | $\pm 3.8 \%$ |
| | | Y | 0.0 | 0.0 | 1.0 | | 183.6 | |
| | | Z | 0.0 | 0.0 | 1.0 | | 184.7 | |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of NormX,Y,Z do not affect the E^2 -field uncertainty inside TSL (see Pages 5 and 6).

^B Numerical linearization parameter; uncertainty not required.

^C Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

ES3DV3- SN:3337

September 5, 2014

DASY/EASY - Parameters of Probe: ES3DV3 - SN:3337

Calibration Parameter Determined in Head Tissue Simulating Media

| f (MHz) ^c | Relative Permittivity ^f | Conductivity (S/m) ^f | ConvF X | ConvF Y | ConvF Z | Alpha ^g | Depth (mm) ^g | Unct. (k=2) |
|----------------------|------------------------------------|---------------------------------|---------|---------|---------|--------------------|-------------------------|-------------|
| 150 | 52.3 | 0.76 | 7.56 | 7.56 | 7.56 | 0.07 | 1.20 | ± 13.3 % |
| 450 | 43.5 | 0.87 | 6.71 | 6.71 | 6.71 | 0.21 | 1.90 | ± 13.3 % |

^c Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^f At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^g Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

ES3DV3- SN:3337

September 5, 2014

DASY/EASY - Parameters of Probe: ES3DV3 - SN:3337

Calibration Parameter Determined in Body Tissue Simulating Media

| f (MHz) ^c | Relative Permittivity ^f | Conductivity (S/m) ^f | ConvF X | ConvF Y | ConvF Z | Alpha ^g | Depth ^g (mm) | Unct. (k=2) |
|----------------------|------------------------------------|---------------------------------|---------|---------|---------|--------------------|-------------------------|-------------|
| 150 | 61.9 | 0.80 | 7.17 | 7.17 | 7.17 | 0.07 | 1.20 | ± 13.3 % |
| 450 | 56.7 | 0.94 | 7.08 | 7.08 | 7.08 | 0.12 | 1.50 | ± 13.3 % |

^c Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

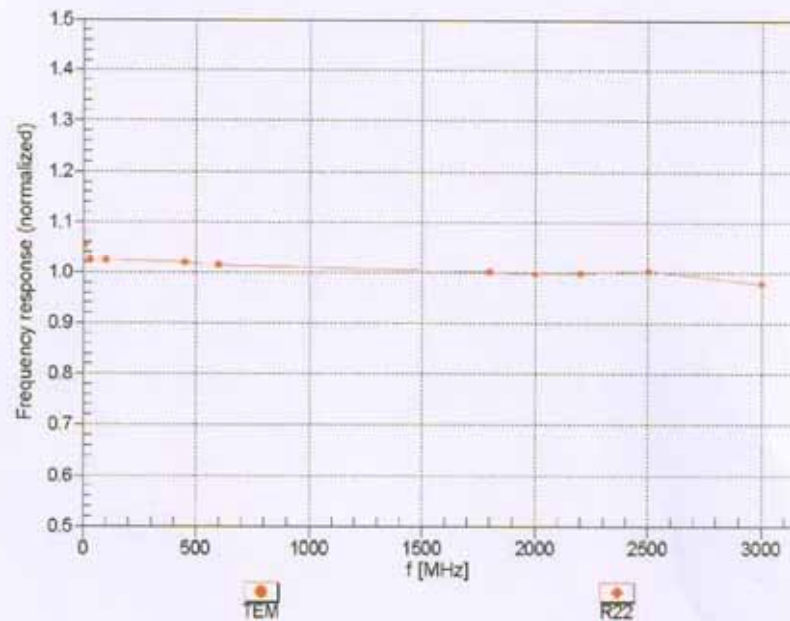
^f At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^g Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

ES3DV3- SN:3337

September 5, 2014

Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



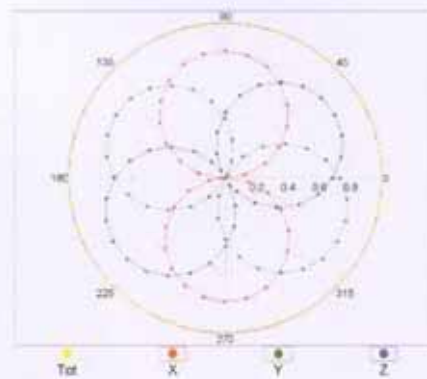
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

ES3DV3- SN:3337

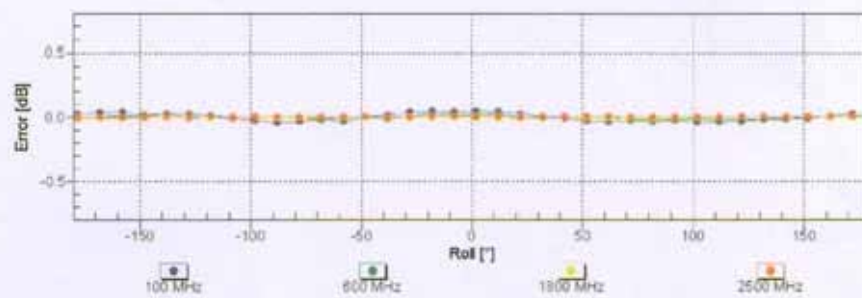
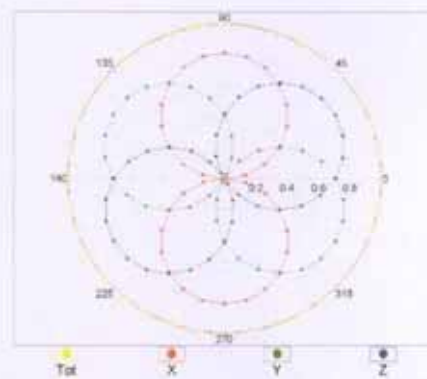
September 5, 2014

Receiving Pattern (ϕ), $\theta = 0^\circ$

f=600 MHz,TEM



f=1800 MHz,R22

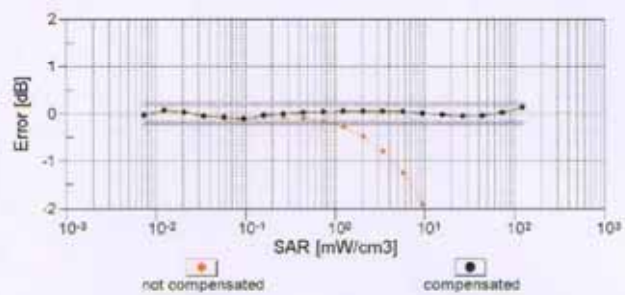
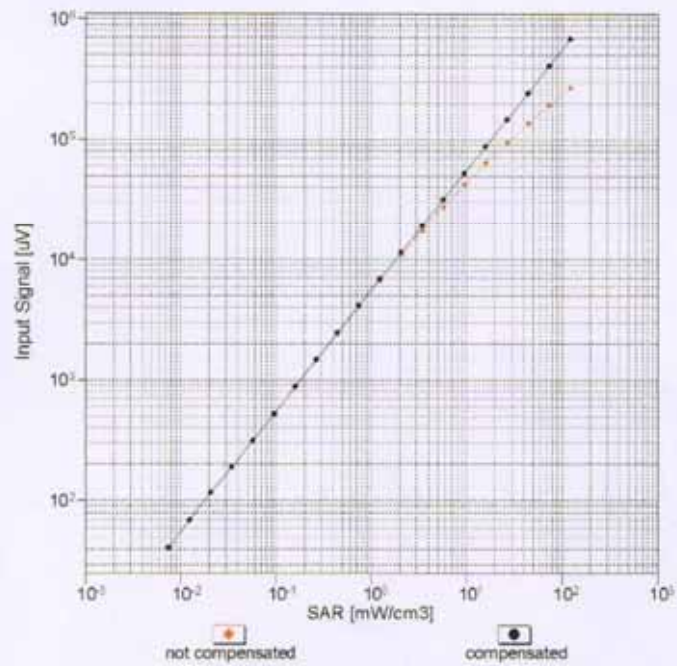


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

ES3DV3- SN:3337

September 5, 2014

Dynamic Range $f(\text{SAR}_{\text{head}})$ (TEM cell , $f_{\text{eval}} = 1900 \text{ MHz}$)

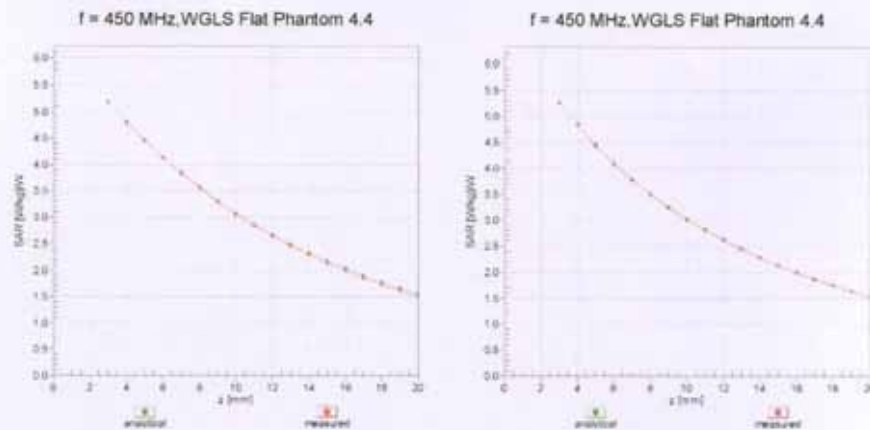


Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

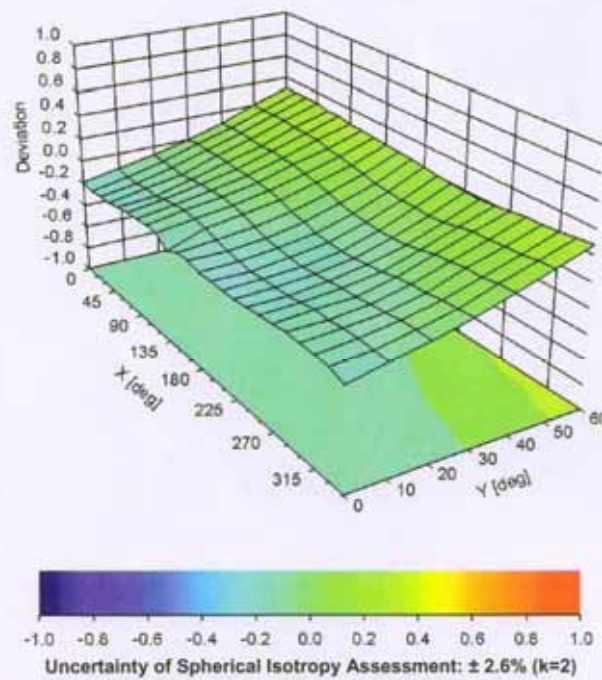
ES3DV3- SN:3337

September 5, 2014

Conversion Factor Assessment



Deviation from Isotropy in Liquid Error (ϕ, θ), $f = 900 \text{ MHz}$



ES3DV3- SN:3337

September 5, 2014

DASY/EASY - Parameters of Probe: ES3DV3 - SN:3337

Other Probe Parameters

| | |
|---|------------|
| Sensor Arrangement | Triangular |
| Connector Angle (°) | -8.1 |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disabled |
| Probe Overall Length | 337 mm |
| Probe Body Diameter | 10 mm |
| Tip Length | 10 mm |
| Tip Diameter | 4 mm |
| Probe Tip to Sensor X Calibration Point | 2 mm |
| Probe Tip to Sensor Y Calibration Point | 2 mm |
| Probe Tip to Sensor Z Calibration Point | 2 mm |
| Recommended Measurement Distance from Surface | 2 mm |

APPENDIX E. DAE CALIBRATION DATA

Calibration Laboratory of
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Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: SCS 108

Client AGC-CERT (Auden)

Certificate No: DAE4-1398_Oct13

CALIBRATION CERTIFICATE

Object DAE4 - SD 000 D04 BM - SN: 1398

Calibration procedure(s) QA CAL-06.v26
Calibration procedure for the data acquisition electronics (DAE)

Calibration date: October 10, 2013

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID # | Cal Date (Certificate No.) | Scheduled Calibration |
|-------------------------------|--------------------|----------------------------|------------------------|
| Keithley Multimeter Type 2001 | SN: 0810276 | 01-Oct-13 (No:13976) | Oct-14 |
| Secondary Standards | ID # | Check Date (in house) | Scheduled Check |
| Auto DAE Calibration Unit | SE UWS 053 AA 1001 | 07-Jan-13 (in house check) | In house check: Jan-14 |
| Calibrator Box V2.1 | SE UMS 006 AA 1002 | 07-Jan-13 (in house check) | In house check: Jan-14 |

| | | | |
|----------------|-------------------|--------------------------|---------------|
| Calibrated by: | Name R.Mayoraz | Function Technician | Signature |
| Approved by: | Fin Bomholt | Deputy Technical Manager | |

Issued: October 10, 2013

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Accreditation No.: **SCS 108**

Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- **DC Voltage Measurement:** Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- **Connector angle:** The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - **DC Voltage Measurement Linearity:** Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - **Common mode sensitivity:** Influence of a positive or negative common mode voltage on the differential measurement.
 - **Channel separation:** Influence of a voltage on the neighbor channels not subject to an input voltage.
 - **AD Converter Values with inputs shorted:** Values on the internal AD converter corresponding to zero input voltage
 - **Input Offset Measurement:** Output voltage and statistical results over a large number of zero voltage measurements.
 - **Input Offset Current:** Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - **Input resistance:** Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - **Low Battery Alarm Voltage:** Typical value for information. Below this voltage, a battery alarm signal is generated.
 - **Power consumption:** Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| Calibration Factors | X | Y | Z |
|---------------------|---------------------------|---------------------------|---------------------------|
| High Range | 404.147 \pm 0.02% (k=2) | 404.125 \pm 0.02% (k=2) | 403.593 \pm 0.02% (k=2) |
| Low Range | 3.97351 \pm 1.50% (k=2) | 3.99134 \pm 1.50% (k=2) | 3.96993 \pm 1.50% (k=2) |

Connector Angle

| | |
|---|-------------------------------------|
| Connector Angle to be used in DASY system | 195.0 $^{\circ}$ \pm 1 $^{\circ}$ |
|---|-------------------------------------|

Appendix

1. DC Voltage Linearity

| High Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|---------------------------|------------------------------|-----------|
| Channel X + Input | 199993.80 | -0.96 | -0.00 |
| Channel X + Input | 20001.48 | 0.96 | 0.00 |
| Channel X - Input | -19998.33 | 1.89 | -0.01 |
| Channel Y + Input | 199993.57 | -0.93 | -0.00 |
| Channel Y + Input | 19999.87 | -0.65 | -0.00 |
| Channel Y - Input | -20000.78 | -0.61 | 0.00 |
| Channel Z + Input | 199994.78 | 0.34 | 0.00 |
| Channel Z + Input | 19999.79 | -0.74 | -0.00 |
| Channel Z - Input | -20001.29 | -1.06 | 0.01 |

| Low Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|---------------------------|------------------------------|-----------|
| Channel X + Input | 2000.47 | -0.40 | -0.02 |
| Channel X + Input | 201.47 | 0.11 | 0.05 |
| Channel X - Input | -198.29 | 0.26 | -0.13 |
| Channel Y + Input | 2001.20 | 0.29 | 0.01 |
| Channel Y + Input | 200.83 | -0.60 | -0.30 |
| Channel Y - Input | -198.98 | -0.44 | 0.22 |
| Channel Z + Input | 2001.13 | 0.29 | 0.01 |
| Channel Z + Input | 200.34 | -1.05 | -0.52 |
| Channel Z - Input | -199.72 | -1.09 | 0.55 |

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Common mode Input Voltage (mV) | High Range Average Reading (μV) | Low Range Average Reading (μV) |
|-----------|--------------------------------|--|---|
| Channel X | 200 | -13.30 | -14.96 |
| | - 200 | 15.96 | 14.26 |
| Channel Y | 200 | 8.58 | 8.53 |
| | - 200 | -10.64 | -10.82 |
| Channel Z | 200 | 7.29 | 7.35 |
| | - 200 | -9.79 | -10.00 |

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Input Voltage (mV) | Channel X (μV) | Channel Y (μV) | Channel Z (μV) |
|-----------|--------------------|-----------------------------|-----------------------------|-----------------------------|
| Channel X | 200 | - | -2.79 | -1.69 |
| Channel Y | 200 | 4.12 | - | -2.08 |
| Channel Z | 200 | 9.54 | 2.38 | - |

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | High Range (LSB) | Low Range (LSB) |
|-----------|------------------|-----------------|
| Channel X | 15962 | 16491 |
| Channel Y | 15951 | 16621 |
| Channel Z | 15854 | 15212 |

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

| | Average (μ V) | min. Offset (μ V) | max. Offset (μ V) | Std. Deviation (μ V) |
|-----------|--------------------|------------------------|------------------------|---------------------------|
| Channel X | -0.35 | -1.45 | 0.36 | 0.33 |
| Channel Y | -1.44 | -2.26 | -0.41 | 0.33 |
| Channel Z | -2.29 | -3.89 | -0.99 | 0.46 |

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

| | Zeroing (kOhm) | Measuring (MOhm) |
|-----------|----------------|------------------|
| Channel X | 200 | 200 |
| Channel Y | 200 | 200 |
| Channel Z | 200 | 200 |

8. Low Battery Alarm Voltage (Typical values for information)

| Typical values | Alarm Level (VDC) |
|----------------|-------------------|
| Supply (+ Vcc) | +7.9 |
| Supply (- Vcc) | -7.6 |

9. Power Consumption (Typical values for information)

| Typical values | Switched off (mA) | Stand by (mA) | Transmitting (mA) |
|----------------|-------------------|---------------|-------------------|
| Supply (+ Vcc) | +0.01 | +6 | +14 |
| Supply (- Vcc) | -0.01 | -8 | -9 |

APPENDIX F DIPOLE CALIBRATION DATA



SAR Reference Dipole Calibration Report

Ref: ACR.318.4.13.SATU.A

ATTESTATION OF GLOBAL COMPLIANCE CO. LTD.

1&2F, NO.2 BUILDING, HUAFENG NO.1 INDUSTRIAL
PARK, GUSHU COMMUNITY XIXIANG STREET
BAOAN DISTRICT, SHENZHEN, P.R. CHINA
SATIMO COMOSAR REFERENCE DIPOLE

FREQUENCY: 450 MHZ

SERIAL NO.: SN 46/11 DIP 0G450-184

Calibrated at SATIMO US
2105 Barrett Park Dr. - Kennesaw, GA 30144



11/14/13

Summary:

This document presents the method and results from an accredited SAR reference dipole calibration performed in SATIMO USA using the COMOSAR test bench. All calibration results are traceable to national metrology institutions.



SAR REFERENCE DIPOLE CALIBRATION REPORT

Ref: ACR 318.4.13.SATU.A

| | <i>Name</i> | <i>Function</i> | <i>Date</i> | <i>Signature</i> |
|----------------------|---------------|-----------------|-------------|----------------------|
| <i>Prepared by :</i> | Jérôme LUC | Product Manager | 11/14/2013 | <i>JL</i> |
| <i>Checked by :</i> | Jérôme LUC | Product Manager | 11/14/2013 | <i>JL</i> |
| <i>Approved by :</i> | Kim RUTKOWSKI | Quality Manager | 11/14/2013 | <i>Kim Rutkowski</i> |

| | |
|-----------------------|--|
| | <i>Customer Name</i> |
| <i>Distribution :</i> | ATTESTATION OF GLOBAL COMPLIANCE CO. LTD. |

| <i>Issue</i> | <i>Date</i> | <i>Modifications</i> |
|--------------|-------------|----------------------|
| A | 11/14/2013 | Initial release |
| | | |
| | | |
| | | |



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1 INTRODUCTION

This document contains a summary of the requirements set forth by the IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards for reference dipoles used for SAR measurement system validations and the measurements that were performed to verify that the product complies with the fore mentioned standards.

2 DEVICE UNDER TEST

| Device Under Test | |
|--------------------------------|----------------------------------|
| Device Type | COMOSAR 450 MHz REFERENCE DIPOLE |
| Manufacturer | Satimo |
| Model | SID450 |
| Serial Number | SN 46/11 DIP 0G450-184 |
| Product Condition (new / used) | Used |

A yearly calibration interval is recommended.

3 PRODUCT DESCRIPTION

3.1 GENERAL INFORMATION

Satimo's COMOSAR Validation Dipoles are built in accordance to the IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards. The product is designed for use with the COMOSAR test bench only.



Figure 1 – Satimo COMOSAR Validation Dipole



4 MEASUREMENT METHOD

The IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards provide requirements for reference dipoles used for system validation measurements. The following measurements were performed to verify that the product complies with the fore mentioned standards.

4.1 RETURN LOSS REQUIREMENTS

The dipole used for SAR system validation measurements and checks must have a return loss of -20 dB or better. The return loss measurement shall be performed against a liquid filled flat phantom, with the phantom constructed as outlined in the fore mentioned standards.

4.2 MECHANICAL REQUIREMENTS

The IEEE Std. 1528 and CEI/IEC 62209 standards specify the mechanical components and dimensions of the validation dipoles, with the dimensions frequency and phantom shell thickness dependent. The COMOSAR test bench employs a 2 mm phantom shell thickness therefore the dipoles sold for use with the COMOSAR test bench comply with the requirements set forth for a 2 mm phantom shell thickness.

5 MEASUREMENT UNCERTAINTY

All uncertainties listed below represent an expanded uncertainty expressed at approximately the 95% confidence level using a coverage factor of $k=2$, traceable to the Internationally Accepted Guides to Measurement Uncertainty.

5.1 RETURN LOSS

The following uncertainties apply to the return loss measurement:

| Frequency band | Expanded Uncertainty on Return Loss |
|----------------|-------------------------------------|
| 400-6000MHz | 0.1 dB |

5.2 DIMENSION MEASUREMENT

The following uncertainties apply to the dimension measurements:

| Length (mm) | Expanded Uncertainty on Length |
|-------------|--------------------------------|
| 3 - 300 | 0.05 mm |

5.3 VALIDATION MEASUREMENT

The guidelines outlined in the IEEE 1528, OET 65 Bulletin C, CENELEC EN50361 and CEI/IEC 62209 standards were followed to generate the measurement uncertainty for validation measurements.

| Scan Volume | Expanded Uncertainty |
|-------------|----------------------|
| 1 g | 20.3 % |
| 10 g | 20.1 % |

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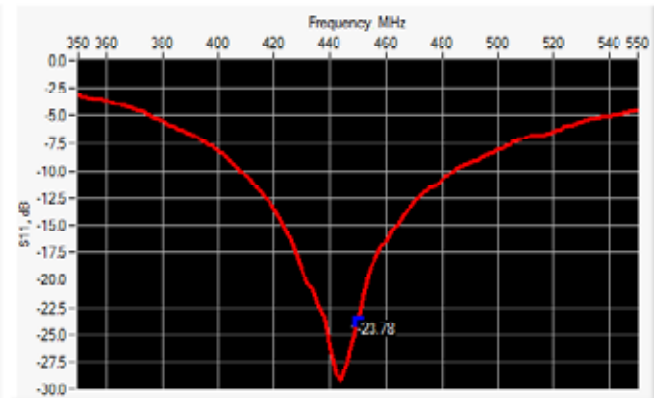


SAR REFERENCE DIPOLE CALIBRATION REPORT

Ref: ACR318.4.13 SATU.A

6 CALIBRATION MEASUREMENT RESULTS

6.1 RETURN LOSS AND IMPEDANCE



| Frequency (MHz) | Return Loss (dB) | Requirement (dB) | Impedance |
|-----------------|------------------|------------------|-----------------------------|
| 450 | -23.78 | -20 | $54.9 \Omega + 5.1 j\Omega$ |

6.2 MECHANICAL DIMENSIONS

| Frequency MHz | l mm | | h mm | | d mm | |
|---------------|-----------------|----------|-----------------|----------|----------------|----------|
| | required | measured | required | measured | required | measured |
| 300 | $420.0 \pm 1\%$ | | $250.0 \pm 1\%$ | | $6.35 \pm 1\%$ | |
| 450 | $290.0 \pm 1\%$ | PASS | $166.7 \pm 1\%$ | PASS | $6.35 \pm 1\%$ | PASS |
| 750 | $176.0 \pm 1\%$ | | $100.0 \pm 1\%$ | | $6.35 \pm 1\%$ | |
| 835 | $167.0 \pm 1\%$ | | $89.8 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 900 | $149.0 \pm 1\%$ | | $83.3 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1450 | $89.1 \pm 1\%$ | | $51.7 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1500 | $80.5 \pm 1\%$ | | $50.0 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1640 | $79.0 \pm 1\%$ | | $45.7 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1750 | $75.2 \pm 1\%$ | | $42.9 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1800 | $72.0 \pm 1\%$ | | $41.7 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1900 | $68.0 \pm 1\%$ | | $39.5 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 1950 | $66.3 \pm 1\%$ | | $38.5 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 2000 | $64.5 \pm 1\%$ | | $37.5 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 2100 | $61.0 \pm 1\%$ | | $35.7 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 2300 | $55.5 \pm 1\%$ | | $32.6 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 2450 | $51.5 \pm 1\%$ | | $30.4 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 2600 | $48.5 \pm 1\%$ | | $28.9 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 3000 | $41.5 \pm 1\%$ | | $25.0 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 3500 | $37.0 \pm 1\%$ | | $26.4 \pm 1\%$ | | $3.6 \pm 1\%$ | |
| 3700 | $34.7 \pm 1\%$ | | $26.4 \pm 1\%$ | | $3.6 \pm 1\%$ | |

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7 VALIDATION MEASUREMENT

The IEEE Std. 1528, OET 65 Bulletin C and CEI/IEC 62209 standards state that the system validation measurements must be performed using a reference dipole meeting the fore mentioned return loss and mechanical dimension requirements. The validation measurement must be performed against a liquid filled flat phantom, with the phantom constructed as outlined in the fore mentioned standards. Per the standards, the dipole shall be positioned below the bottom of the phantom, with the dipole length centered and parallel to the longest dimension of the flat phantom, with the top surface of the dipole at the described distance from the bottom surface of the phantom.

7.1 MEASUREMENT CONDITION

| | |
|---|---|
| Software | OPENSAR V4 |
| Phantom | SN 20/09 SAM71 |
| Probe | SN 18/11 EPG122 |
| Liquid | Head Liquid Values: ϵ_p : 42.5 σ : 0.06 |
| Distance between dipole center and liquid | 5.0 mm |
| Area scan resolution | $dx=8mm/dy=8mm$ |
| Zoom Scan Resolution | $dx=8mm/dy=8mm/dz=5mm$ |
| Frequency | 450 MHz |
| Input power | 20 dBm |
| Liquid Temperature | 21 °C |
| Lab Temperature | 21 °C |
| Lab Humidity | 45 % |

7.2 HEAD LIQUID MEASUREMENT

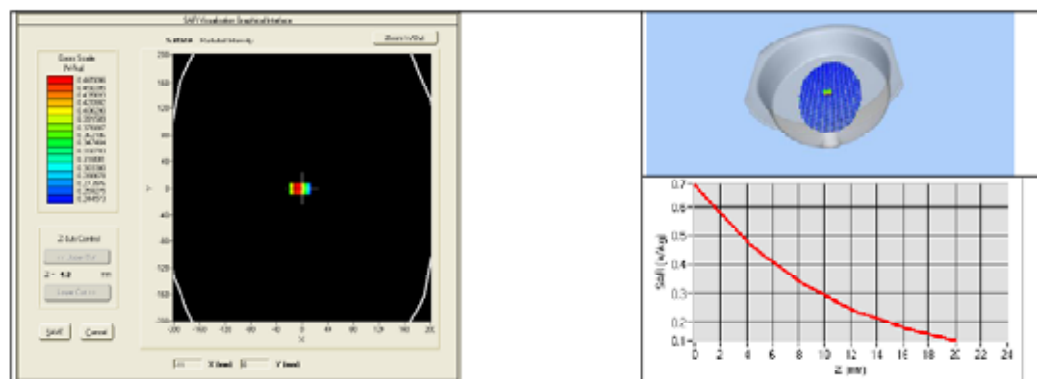
| Frequency MHz | Relative permittivity (ϵ_r) | | Conductivity (σ) S/m | |
|------------------|--|----------|-------------------------------|----------|
| | required | measured | required | measured |
| 300 | 45.3 \pm 5 % | | 0.87 \pm 5 % | |
| 450 | 43.5 \pm 5 % | PASS | 0.87 \pm 5 % | PASS |
| 750 | 41.9 \pm 5 % | | 0.89 \pm 5 % | |
| 835 | 41.5 \pm 5 % | | 0.90 \pm 5 % | |
| 900 | 41.5 \pm 5 % | | 0.97 \pm 5 % | |
| 1450 | 40.5 \pm 5 % | | 1.20 \pm 5 % | |
| 1500 | 40.4 \pm 5 % | | 1.23 \pm 5 % | |
| 1640 | 40.2 \pm 5 % | | 1.31 \pm 5 % | |
| 1750 | 40.1 \pm 5 % | | 1.37 \pm 5 % | |
| 1800 | 40.0 \pm 5 % | | 1.40 \pm 5 % | |
| 1900 | 40.0 \pm 5 % | | 1.40 \pm 5 % | |
| 1950 | 40.0 \pm 5 % | | 1.40 \pm 5 % | |
| 2000 | 40.0 \pm 5 % | | 1.40 \pm 5 % | |
| 2100 | 39.8 \pm 5 % | | 1.49 \pm 5 % | |
| 2300 | 39.5 \pm 5 % | | 1.67 \pm 5 % | |
| 2450 | 39.2 \pm 5 % | | 1.80 \pm 5 % | |
| 2600 | 39.0 \pm 5 % | | 1.96 \pm 5 % | |
| 3000 | 38.5 \pm 5 % | | 2.40 \pm 5 % | |
| 3500 | 37.9 \pm 5 % | | 2.91 \pm 5 % | |



7.3 MEASUREMENT RESULT

The IEEE Std. 1528 and CEITEC 62209 standards state that the system validation measurements should produce the SAR values shown below (for phantom thickness of 2 mm), within the uncertainty for the system validation. All SAR values are normalized to 1 W forward power. In bracket, the measured SAR is given with the used input power.

| Frequency MHz | 1 g SAR (W/kg/W) | | 10 g SAR (W/kg/W) | |
|------------------|------------------|-------------|-------------------|-------------|
| | required | measured | required | measured |
| 300 | 2.05 | | 1.94 | |
| 450 | 4.58 | 4.91 (0.49) | 3.06 | 3.13 (0.31) |
| 750 | 8.49 | | 5.55 | |
| 895 | 9.56 | | 6.22 | |
| 900 | 10.9 | | 6.99 | |
| 1450 | 29 | | 16 | |
| 1500 | 30.5 | | 16.8 | |
| 1640 | 34.2 | | 18.4 | |
| 1750 | 36.4 | | 19.3 | |
| 1800 | 38.4 | | 20.1 | |
| 1900 | 39.7 | | 20.5 | |
| 1950 | 40.5 | | 20.9 | |
| 2000 | 41.1 | | 21.1 | |
| 2100 | 43.6 | | 21.9 | |
| 2300 | 48.7 | | 23.3 | |
| 2450 | 52.4 | | 24 | |
| 2600 | 55.3 | | 24.6 | |
| 3000 | 63.9 | | 25.7 | |
| 3500 | 67.1 | | 25 | |





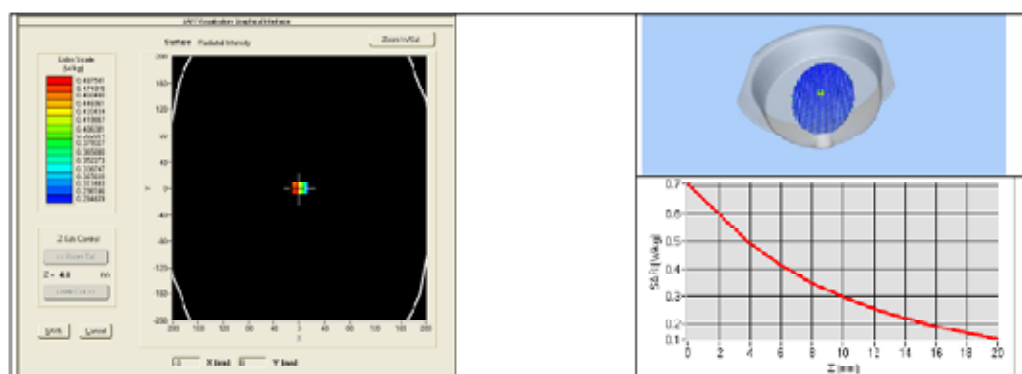
SAR REFERENCE DIPOLE CALIBRATION REPORT

Ref: ACR.318.4.13.SATU.A

7.4 BODY MEASUREMENT RESULT

| | |
|---|--|
| Software | OPENSAR V4 |
| Phantom | SN 20/09 SAM71 |
| Probe | SN : 8/11 EPG122 |
| Liquid | Body Liquid Values: $\epsilon_s' : 57.6$ $\sigma : 0.98$ |
| Distance between dipole center and liquid | 15.0 mm |
| Area scan resolution | $dx=8mm/dy=8mm$ |
| Zoon Scan Resolution | $dx=8mm/dy=8mm/dz=5mm$ |
| Frequency | 450 MHz |
| Input power | 20 dBm |
| Liquid Temperature | 21 °C |
| Lab Temperature | 21 °C |
| Lab Humidity | 45 % |

| Frequency MHz | 1 g SAR (W/kg/W) | 10 g SAR (W/kg/W) |
|------------------|------------------|-------------------|
| | measured | measured |
| 450 | 5.07 (0.51) | 3.25 (0.37) |





8 LIST OF EQUIPMENT

| Equipment Summary Sheet | | | | |
|---------------------------------|----------------------|--------------------|---|---|
| Equipment Description | Manufacturer / Model | Identification No. | Current Calibration Date | Next Calibration Date |
| SAM Phantom | Satimo | SN-20/09-SAM71 | Validated. No cal required. | Validated. No cal required. |
| COMOSAR Test Bench | Version 3 | NA | Validated. No cal required. | Validated. No cal required. |
| Network Analyzer | Rhode & Schwarz ZVA | SN10C132 | 02/2013 | 02/2016 |
| Calipers | Carrera | CALIPER-01 | 12/2010 | 12/2013 |
| Reference Probe | Satimo | EPG122 SN 18/11 | Characterized prior to test. No cal required. | Characterized prior to test. No cal required. |
| Multimeter | Keithley 2000 | 1188656 | 11/2010 | 11/2013 |
| Signal Generator | Agilent E4438C | MY49070581 | 12/2010 | 12/2013 |
| Amplifier | Aethercomm | SN 040 | Characterized prior to test. No cal required. | Characterized prior to test. No cal required. |
| Power Meter | HP E4418A | US382E1498 | 11/2010 | 11/2013 |
| Power Sensor | HP ECP-E26A | US37181460 | 11/2010 | 11/2013 |
| Directional Coupler | Narda 4216 20 | 01386 | Characterized prior to test. No cal required. | Characterized prior to test. No cal required. |
| Temperature and Humidity Sensor | Control Company | 11-881-9 | 3/2012 | 3/2014 |