

## MS Series Encoder Data Structure

The MS Series encoder is designed to securely register button presses or switch closures over a wireless link for remote control applications. It will turn eight parallel input lines into a secure, encoded serial bit stream output.

The MS Series algorithm is designed to create a data stream with a 50% duty cycle by using the same number of high bits and low bits. Two wait times reduce this duty cycle to just below 50%.

Logic State Description:

1 = HIGH

0 = LOW

Total bits, including start and stop bits = 80

Total 1's = 40

Total 0's = 40

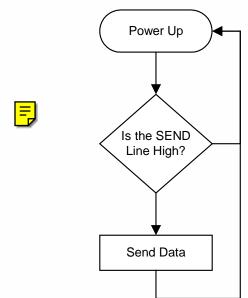
Value for each bit per baud rate:

2400bps = 417uS or 1.18% of duty cycle

9600bps = 104uS or 1.01% of duty cycle

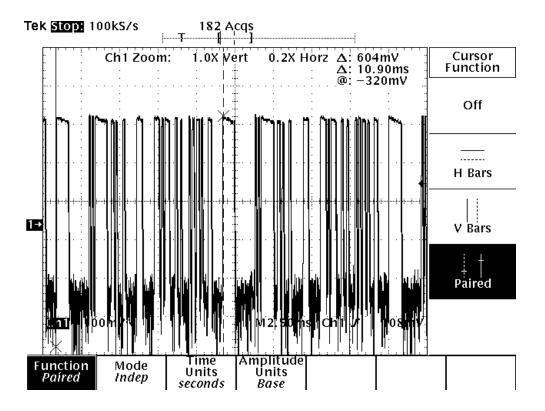
19200bps = 52uS or 0.85% of duty cycle

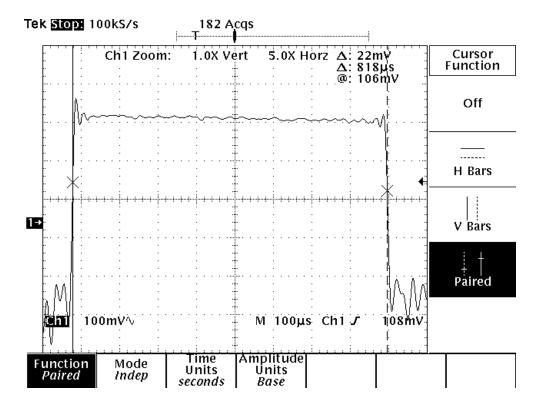
28800bps = 35uS or 0.74% of duty cycle

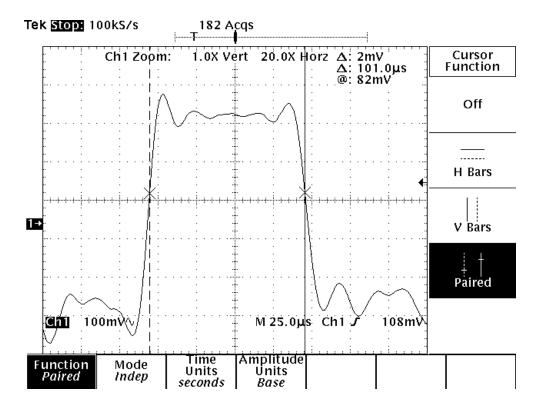


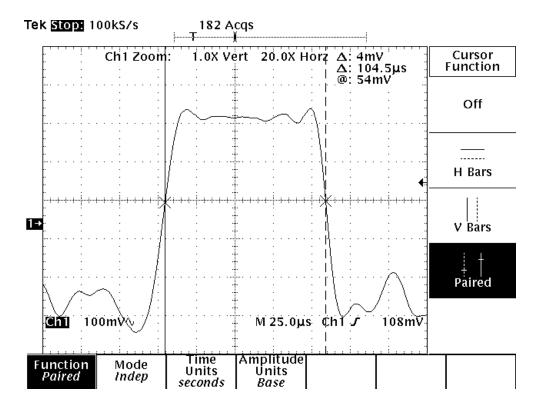
Wait Time	Process	ing Time	Wait Time	Wake	Noise Filter	Error Check	ADDR-H	ADDR-M	ADDR-L	Data Byte	Error Check	
680uS	11111111	00000000	465uS	1010	800uS	0 01101000 1	0 10101010 1	0 01010101 1	0 00000000 1	0 10000001 1	0 11101010 1	

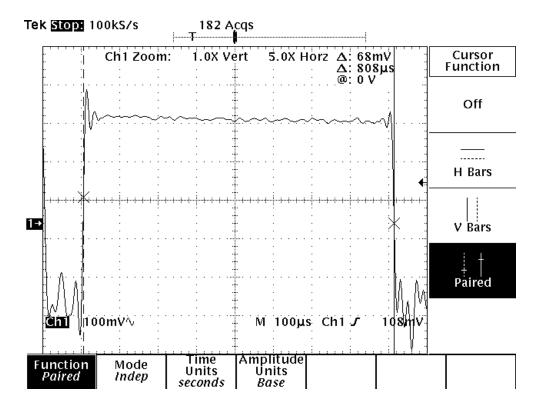
Duty Cycle = 
$$\frac{\text{Time High}}{\text{Total Time}}$$
  $\longrightarrow$   $\frac{40 \text{ bits} + 800 \text{uS}}{80 \text{ bits} + 680 \text{uS} + 465 \text{uS} + 800 \text{uS}}$   $\longrightarrow$   $\frac{(34*104 \text{uS}) + 800 \text{uS}}{(80*104 \text{uS}) + 1,945 \text{uS}}$  =  $\frac{4,336 \text{uS}}{10,265 \text{uS}}$  = 42.24%

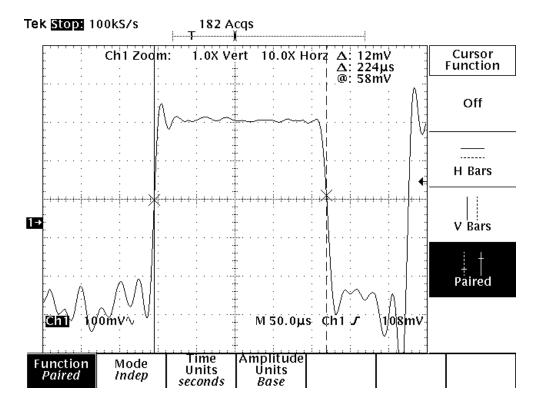


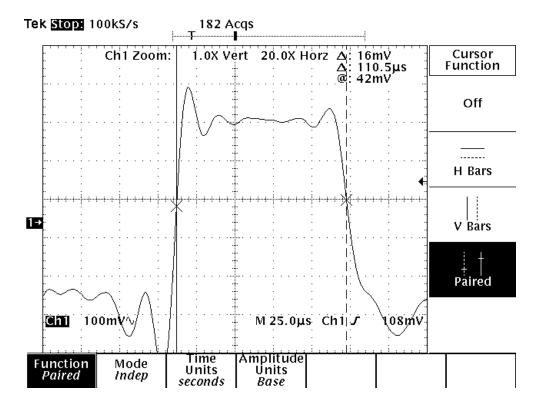


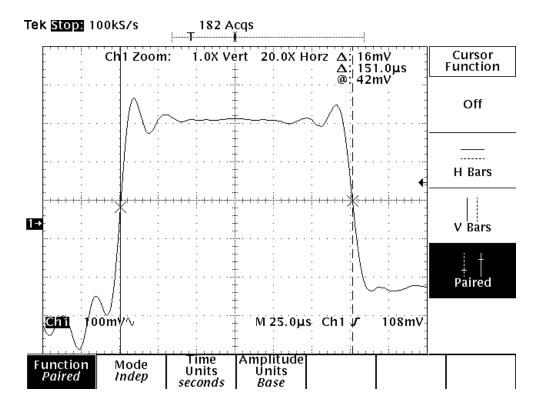


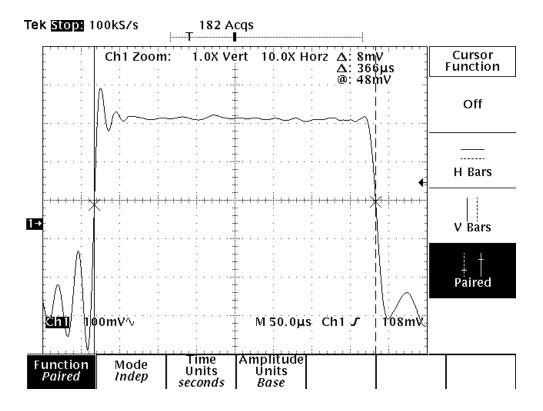


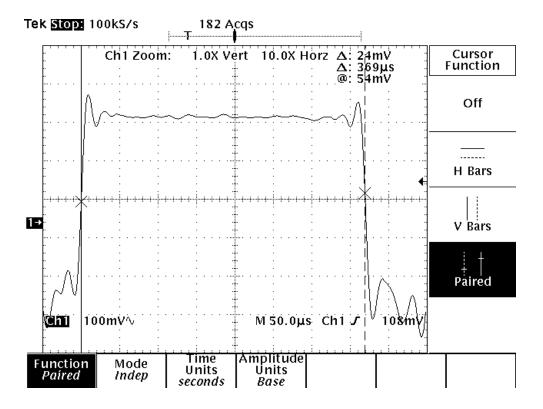


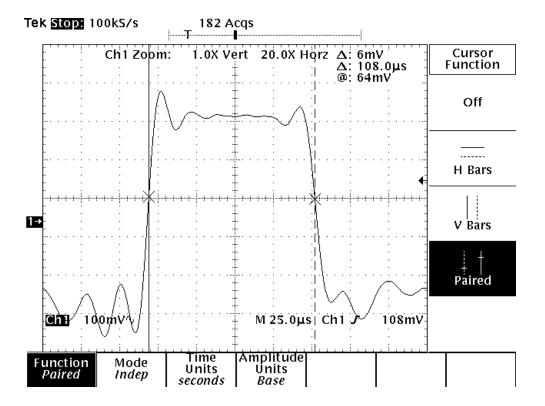


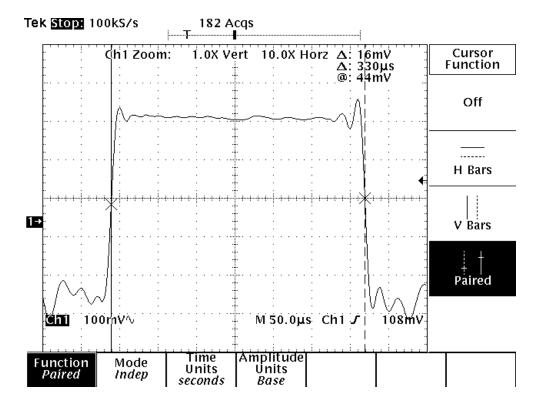


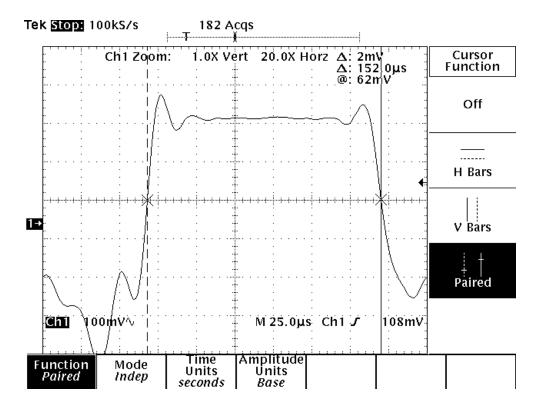


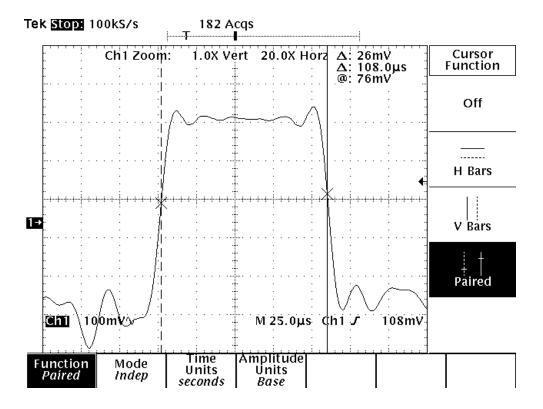


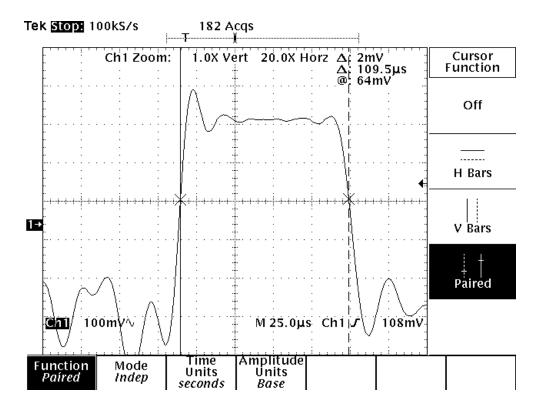


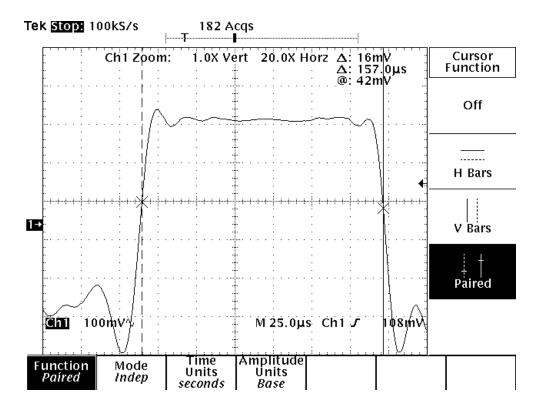


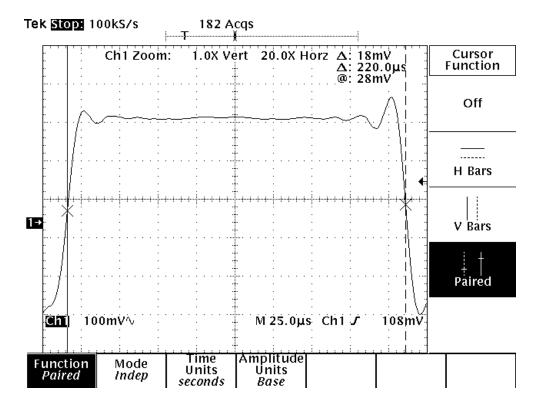


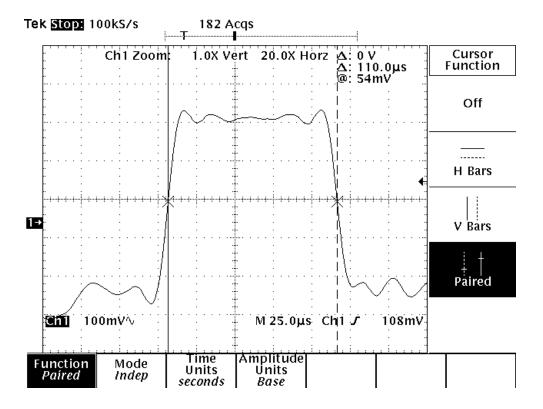


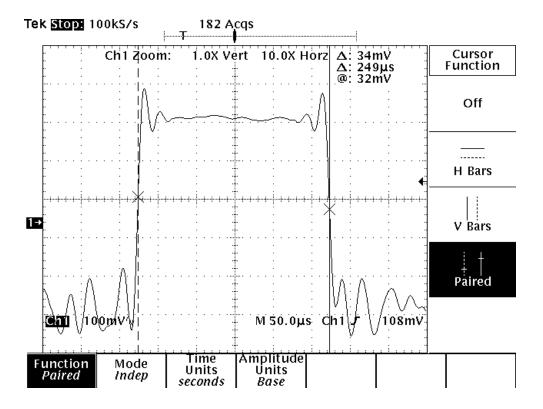












Pulse Number	Length of pulse (uS)
1	818
2	101
3	104.5
4	808
5	224
6	110.5
7	151
8	366
9	369
10	108
11	330
12	152
13	108
14	109.5
15	157
16	220
17	110
18	249
Total on-time	4595.5 uS

4595.5 uS S / 10900 uS = 42.16 %