

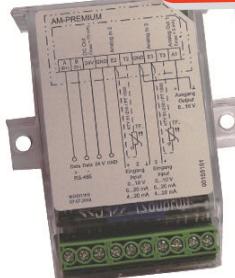
# AM-PREMIUM / AM-PREMIUM-W

Part.-No. 349046 / 349051

## Universal control module for ECblue fans

### Operating Instructions

**DRAFT**



Software version: D1727A / D2263A from version 4.00

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## 1 General notes

### 1.1 Structure of the operating instructions

These operating instructions are valid only in connection with the device's operating instructions into which this module is being integrated. The remarks concerning safety, installation and connection described in those operating instructions must be followed!  
Before installation and start up, read this manual carefully to ensure correct use!

### 1.2 Exclusion of liability

Concurrence between the data contained in these operating instructions and the described software has been examined. It is still possible that non-compliances exist. No guarantee is assumed for complete conformity. To allow for future developments given are subject to alteration. We do not accept any liability for possible errors or omissions in the information contained in data, illustrations or drawings provided.

Ziehl-Abegg AG is not liable for damage due to misuse, incorrect or improper use.

### 1.3 FCC / IC Statements (for AM-PREMIUM-W Modules only)

The FCC / IC warnings and statements are valid only for the AM-PREMIUM-W modules, because they have only installed the integrated submodule EM-W, that enhances the AM-PREMIUM module with the radio communication function to allow communication over radio frequencies with other Ziehl-Abegg devices (only).

Note: Only the submodule EM-W installed in the AM-PREMIUM-W module is tested for compliancy according to the relevant FCC and IC standards (for more information see installation instruction of EM-W).

#### FCC Compliance (US)

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Note: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

#### FCC Warning

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

## IC Compliance (Canada)

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

This Class A digital apparatus complies with Canadian ICES-003.

Cet appareil numérique de la classe A est conforme à la norme NMB-003 du Canada.

## 2 Safety instructions

- Mounting, electrical connection, and start-up operation may only be carried out by an electrical specialist in accordance with electrotechnical regulations (e.g. DIN EN 50110 or DIN EN 60204)!
- It is strictly forbidden for work to be carried out on any components while they are connected to live voltage. The open equipment is protected to IP00. It is possible to come into direct contact with dangerous voltages!

## 3 General description

### 3.1 Operational area

The add-on module can only be used together with compatible Ziehl-Abegg devices.

Note: The AM-PREMIUM-W module is strictly limited for the integration and usage in host devices (fans and converters) of Ziehl-Abegg AG.

### 3.2 Function

When the "AM-PREMIUM" is plugged in the controller in the fan is extended to become a full-grade multipurpose controller. The "Premium module" provides not only an integrated MODBUS interface, it also enables sensors to be connected straight to the fan.

The module also comes with one digital input and one analogue output.

With AM-PREMIUM-W it is possible to control additionally over radio link with the fan.

### 3.3 Transport

- The device is packed ex factory to suit the transport method previously agreed.
- Always use the original packaging materials when transporting the device.
- Avoid shocks and impacts to the device during the transport.
- During manual handling the human lifting and carrying restrictions must be observed and adhered to.

### 3.4 Storage

- The device must be stored in its original packaging in a dry and weather-proof room.
- Avoid exposure to extreme heat and cold.
- Avoid over-long storage periods (we recommend a maximum of one year).

### 3.5 Disposal / recycling

Disposal must be carried out professionally and environmentally friendly in accordance with the legal stipulations.

## 4 Mounting

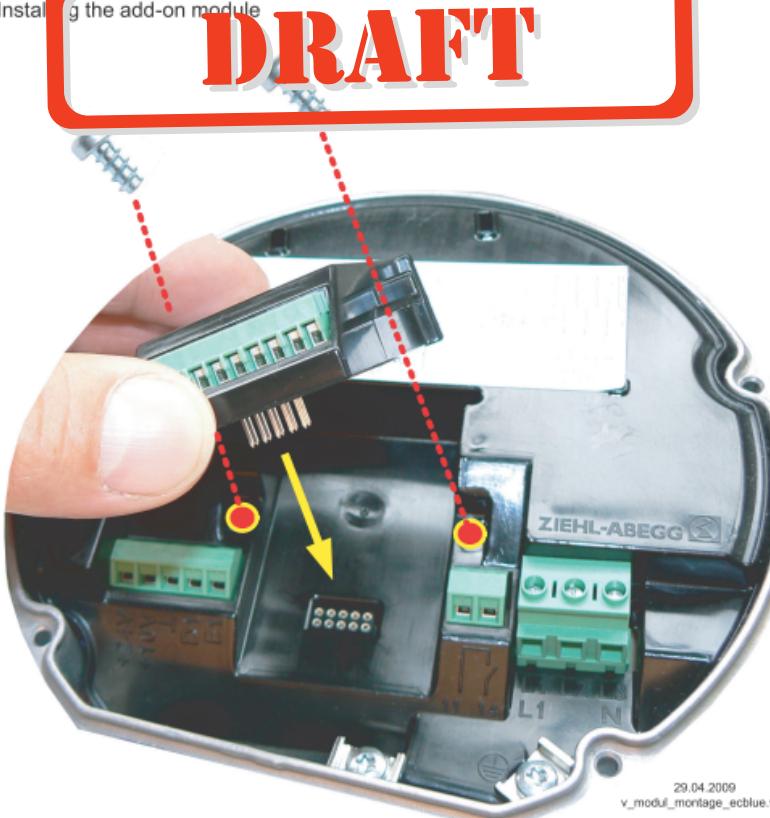
- Before installation remove the device from the packing and check for any possible shipping damage!
- For installation the cover of the controller housing must be removed. The module is then put into the intended slot of the ECblue fan. ([Assembly instructions / Operating Instructions for fan / Electrical Installation](#)).
- Install afterwards module with both enclosed screws in the controller housing (permissible tightening torque  $M_A = 1.3 \text{ Nm}$ ).
- When the AM-Premium-W module will be mounted in a fan or converter of Ziehl-Abegg AG, the FCC/IC label (EM-W inside) has to be stick on the housing of the converter



Danger due to electric current

Voltage supply for motor must be interrupted and secured against restoration!

Installing the add-on module



Sticking the FCC/IC label (EM-W inside) on the housing of the fan.



## 5 Electrical installation

### 5.1 Safety precautions



#### Danger due to electric current

- Work on electric components may only be carried out by trained electricians or by persons instructed in electricity under the supervision of an electrician in accordance with electrical engineering regulations.
- It is forbidden to carry out work on electrically live parts.

### 5.2 Signal connection or sensor connection to analog inputs (Analog In 2, Analog In 3)

The unit has two analog inputs: Analog In 2 [E2] and Analog In 3 [E3]

The connection is independent of the programmed operating mode and from the sensor signal employed.

- When connecting **passive** temperature sensors TF.. (KTY81-210) or PT1000 at terminals "E2 / T2" and/or "E3 / T3" must be paid attention to no polarity.  
For high input frequencies (e.g. 50 Hz) a **capacitor** must be connected directly to the sensor (1 nF parallel). With Ziehl-Abegg temperature sensors type TF.. (KTY81-210) the capacitor is integrated.
- When connecting **active** sensors to the terminals "E2 / GND" and/or "E3 / GND" attention must be paid to correct polarity. a 24 V DC power supply is integrated.
- For sensors in two-wire-technology (4 - 20 mA signal), the connection is made on the "E1 / 24 V" and/or "E3 / 24 V", "GND" terminal is omitted.



#### Attention!

Never apply line voltage to analog inputs!

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### 5.3 Output voltage 0 - 10 V (Analog Out)

The analog outputs 0 - 10 V can be allocated with various functions (☞ IO Setup: Analog output "A").

Connection to terminal "A" - "GND" = "Analog Out" ( $I_{max}$  10 mA).

It is not permissible to connect outputs of several devices to each other!

### 5.4 Voltage supply for external devices (+24V, GND)

There is an integrated power supply for external devices, e.g. a sensor. Terminal +24 V, output voltage tolerance +/- 20%. Max. load current 70 mA.

It is not permissible to connect outputs of several devices to each other!

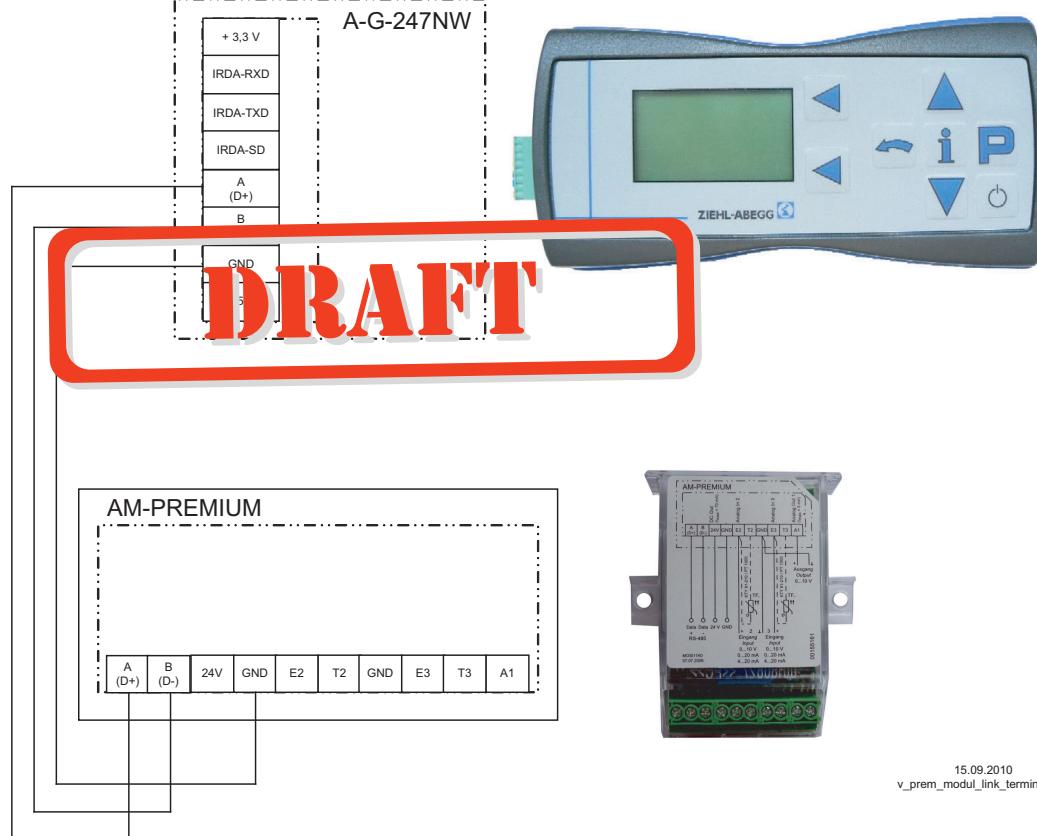
In case of overload or short circuit (24 V – GND), the external power supply is shut down (multi-fuse).

The device performs a "Reset" and continues operation.

## 5.5 Connection external terminal type A-G-247NW or AXG-1A(E)

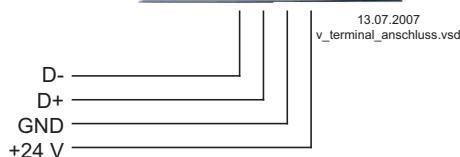
If necessary an external terminal can be connected. This can be e.g. necessary to adapt the pre-setting during start-up. For information about the current operating condition a terminal can be permanent attached.

- The connection is made via a 4-strand line at the terminals (D-, D+ and GND).
- e.g., telephone flex e.g. J-Y (St) Y 2x2x0.6 (or similar), maximum line length ca. 250 m.
- Signal "D+" and "D-" (RS 485)
- Type A-G-247NW, Part.-No. 380070, handheld terminal



The voltage supply of the terminal is made by the accumulators inserted there or the plug power supply unit.

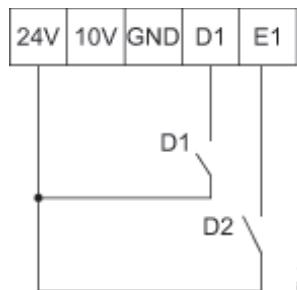
- Model AXG-1A, Part-No. 349034 for wall mounting
- Model AXG-1AE, Part-No. 349008 for panel mounting



Voltage supply: Terminal "24 V", "GND", ( $I_{max}$ , for terminal approx. 50 mA)

## 5.6 Digital inputs (D1, E1 = D2)

In the case of use of the module AM-PREMIUM two digital inputs can be programmed. When inserting the module the analog input "E1" becomes automatically to the second digital input "D2".



D1: contact at Terminals "D1" - "24 V"  
D2: contact at Terminals "E1" - "24 V"

Various functions can be allocated to the digital inputs "D1" and "D2" (☞ IO Setup: Functions summary of the digital inputs). Activation via floating contacts (a low voltage of ca. 24 V DC is connected).



**Attention**

Never apply line voltage to the inputs! It is not permissible to connect inputs of several devices to one another!

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## 5.7 Relay output (K1)

The relay output "K1" can have different functions assigned to it (☞ IO Setup: Function and inversion of relay output). Max. contact load ☞ ECblue: Technical data and connection diagram.

Connection of the floating contacts of relay "K1" to the terminals 11, 14.

factory setting [1K] = Operating indication (☞ IO Setup).

## 5.8 Communication

### 5.8.1 Networking via MODBUS-RTU

The device comes equipped with a RS-485 interface for networking via MODBUS. Connection at: "A (D+)", "B (D-)" and "GND".

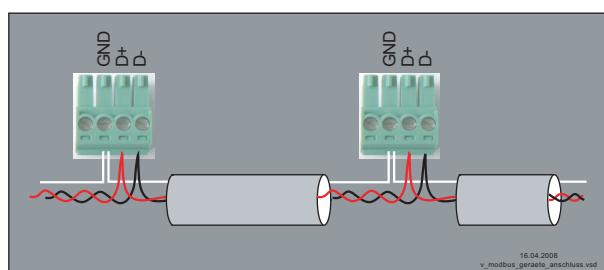
**A maximum of 64 members can be directly connected to one another, and another 63 members via a repeater.**

**The address must be set in the "IO Setup" menu.**

### 5.8.2 RS-485 - network design and interface parameter

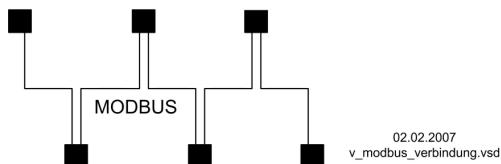
Please ensure the correct connection; i.e. "A (D+)" must always be connected to "A (D+)" of the next devices. The same applies to "B (D-)".

In addition, a "GND" connection must be established, as dissimilar potential (over 10 V!) will lead to the destruction of the RS-485 interface (e.g. lightning).



general example for MODBUS device connection

The data line must be connected from one device to the next. No other type of wiring is allowed!  
Always use only two wires of one lead (twisted pair) for the connection.



Examples for MODBUS connection

#### **Recommended wire types**

1. CAT5 / CAT7 cables
2. J-Y (St) 2x2x0.6 (telephone wire)
3. AWG22 (2x2 twisted pair)

When using telephone flex with four cable cores, we recommend the following allocation:  
"A (D+)" = red, "B (D-)" = black, "GND" = white



#### **Information**

- Pay attention to sufficient distance from powerlines and motor wires (min. 20 cm)
  - Do not use wire shielded
  - Except the data line ("D+"), ("D-") and "GND"- connection may no further cable cores of the data line be used.
  - Max. allowed wire length: 1000 m (CAT5E)
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#### **Default interface parameter**

Baudrate	=	19200
Bits	=	8
Parity	=	Even (None, exception of devices agriculture)
Stop bits	=	1
Handshake	=	none



#### **Information**

If any matters are unclear, please contact our V-STE support department for control systems - ventilation technology. The information sheet "Network structure of MODBUS" R-TIL08\_01 contains detailed information about "MODBUS".

### 5.8.3 AM-PREMIUM-W Wireless Communication

The type A-G-247NW hand-held terminal can communicate wireless with the type **AM-PREMIUM-W** communications module.

In a hard-wired system, wireless communication is primarily designed in order to have a second interface for communicating with the device (e.g., for configuration and diagnostics).

In the A-G-247NW, for wireless communication with an EC fan type **ECblue Basic** use the **[AM-PREMIUM-W]** menu item.

Wireless communication is also used by the MODBUS protocol, so it is necessary to assign an address. **Wireless** and **hard-wired communications use the same address**. The address can be hard-wire assigned via an RS-485.

**For pure, wireless communication, it is recommended to assign the address manually.**

- Switch on the device you want to re-address and establish a connection with address 247.
- In “IO Setup”, change the address and then switch this device off again.
- Apply the same procedure to the next device.

#### Radio control key (0 - 9999)

Different from RS-485 communication, wireless communication also has a radio control key (0 - 9999). This radio control key identifies the module and ensures that several networks can be operated in mutually overlapping radio ranges.

For that reason, every wireless MODBUS network should have its own radio control key if there is another wireless MODBUS network in the vicinity.

The factory setting is **[9999]**.

A radio control key with the value **[0]** switches off encoding.

The ECblue must be switched off to save the new radio control key.

The radio control key must be assigned in the same manner as the assignment of the MODBUS address. The radio control key can be found in the ECblue basic menu in the “IO Setup” menu item.

#### Technical data for wireless Communication:

Radio communication standard:	IEEE 802.15.4
Frequency:	2.4 GHz (not licensed wireless band, like WLAN, Bluethooth) 16 wireless channels, default wireless channel 0
Communications range:	Short-distance radio, within buildings max. 8 m typically 3 - 5m, free field to 25 m, generally strongly dependent on interferences
Type of communication:	Bi-directional, half duplex
Application protocol:	MODBUS-RTU (max. protocol length 125 Bytes and/or 50 register)
Coding:	Proprietary through 4-digit number
Network structure:	Point - to - point or point - to- mulit point - communication

### 5.9 Potential at control voltage connections

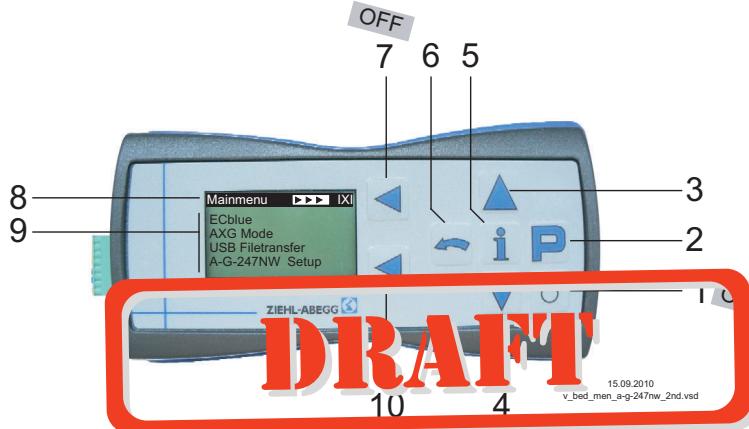
The control voltage connections (< 50 V) relate to the joint GND potential (Exception: Relay contacts are potential free). There is a potential separation between the control voltage connections and the protective earth. It must be ensured that the maximum external voltage at the control voltage connections cannot exceed 50V (between “GND” terminals and “PE” protective earth). If necessary, a connection to the protective earth potential can be established, install bridge between “GND” terminal and the “PE” connection (terminal for screening).

## 6 Operating by terminal

### 6.1 Hand held terminal type A-G-247-NW for several members

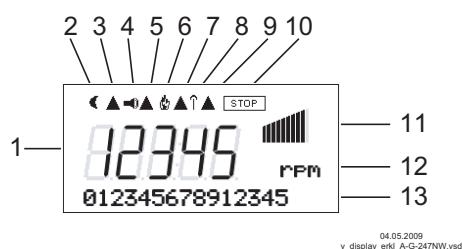
#### 6.1.1 Display and operating elements of the terminal

Hand held terminal type A-G-247NW



- 1 Switch on terminal
- 2 Program key and open menu
- 3 Menu selection, increase value
- 4 Menu selection, reduce value
- 5 From each menu (member) directly back to the display for "Speed"
- 6 Escape = exit menu for settings (user), cancel input
- 7 - Select type of user
  - back to selection of user (exit application)
  - Switch off terminal (keep key pressed for a few seconds)
- 8 "Main menu" = momentarily active menu level ([>>>] = batteries being charged, [=====] = full)
- 9 Selection option of the sub-menu (display in menu language English)
- 10 Key not assigned (soft key, program-dependent function)

#### Explanation of display (menu User)



1. Numeric display 5 digit
2. Moon-Symbol for set point 2
3. Current derating active
4. Alarm-symbol (list of fault indications)
5. Brake motor or motor heating active
6. Fire-Symbol (heating operation)
7. temperature management active (power reduction)
8. No connection to Modul (only AM-MODBUS)
9. not used
10. STOP-Symbol (enable)
11. Bargraph Fanlevel
12. Text line 3 figures (display unit, etc.)
13. Text line 16 figures (display text menu.)

### 6.1.2 Establish connection to member

1. Open drop-down menu **ECblue** with the **P** key.
2. Select type of user with the **▼ + ▲** keys and confirm with the **P** key.

#### Setting kind of member

Display		Explanation
Main menu IXI	P	
	ECblue Apps	<b>Setting kind of member</b>
	AM-MODBUS	ECblue fan with integrated communication module. Type AM-MODBUS, Part.-no. 349045 Communication via cable.
		ECblue fan with integrated communication module. Type AM-MODBUS-W, Part.-no. 349050 Communication wireless.
ECblue	AM-MODBUS-W	ECblue fan with integrated universal control module. Type AM-PREMIUM, Part.-no. 349046
	AM-PREMIUM	
	AM-PREMIUM-W	ECblue fan with integrated universal control module. Type AM-PREMIUM-W, Part.-no. 349051 Communication wireless.

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#### Confirm address

Netzwerkschlüssel	IXI	◀
9999		For communication wireless: Set network key and confirm with <b>P</b> -key.
Select device	IXI	◀
247		The device address (Device-ID) of the members is factory set to the highest available MODBUS address: 247 Set address with the <b>▼ + ▲</b> keys and confirm this with the <b>P</b> key to establish the first connection.
ZATerminal support		◀
ECblue-247	IXI	 <span>Successful connection!</span>
ECblue-246	IXI	 <span>No connection! Settings are not possible! In the display the two symbols for alarm and antenna appear (only for AM-MODBUS).  Cause: wrong address, no connection via wire and/or radio (only AM-MODBUS-W).</span>

## 6.2 Terminal type AXG-1A(E) for one member

With terminal type AXG-1A(E) connection only to one member possible.



- P Program key and open menu
- ▼ Menu selection, reduce value
- ▲ Menu selection, increase value
- ▼ + ▲ ESC-key combination, Escape = leave menu

explaining display terminal A-G-247NW

## 6.3 Menu operation

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**Display after turning on the mains voltage.**  
description for menu language English = "GB" (delivery status).  
Switch over between "Start" and \*Actual value with Escape [Esc].

Example for mode **1.01** (speed controller).

\*actual value depending device type:  
- "Speed" / rpm,- "Frequency" / Hz, - "Fanlevel" / %



**P↓↑ ESC**

By pushing the P key one reaches the menu item "START".



**▲▼**

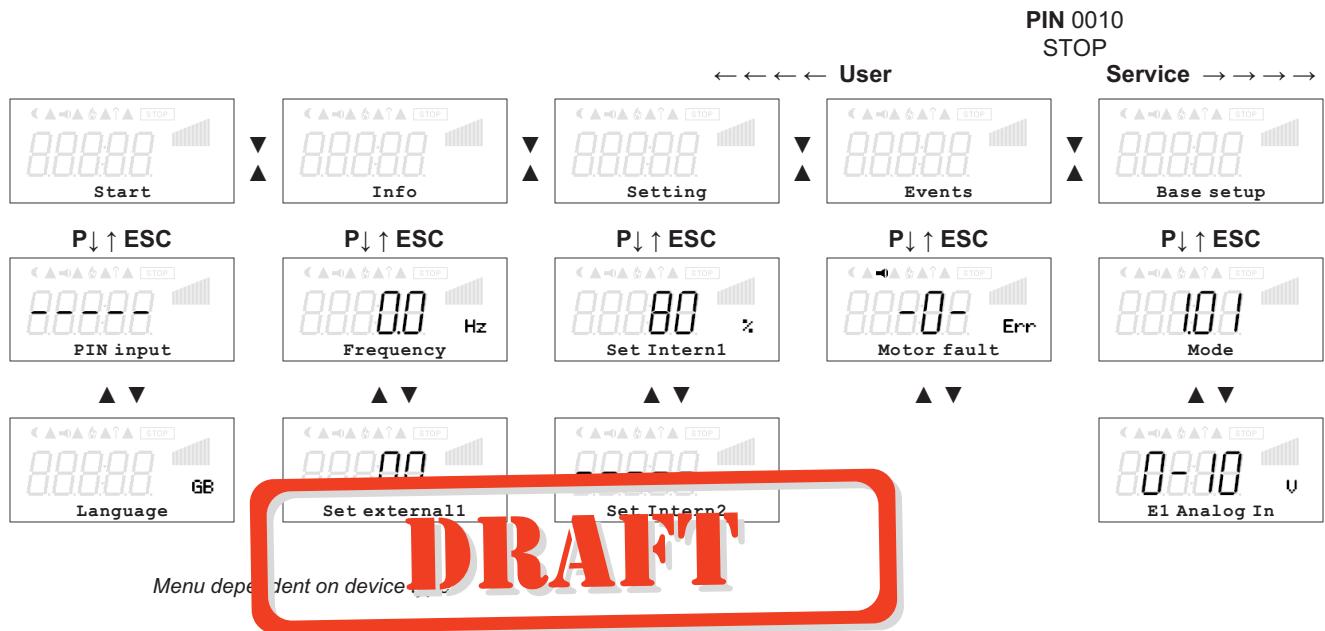
One moves up and down within the menu group using the arrow keys.



In the menu point "Language" display language can be selected.

One returns to the menu group "Start" using the ESC (▼ + ▲) shortcut keys.

## 6.4 Menu structure



Selection of the menu group (e.g. Base setup) to the right through the ▼-key, to the left through the ▲-key.

You can go to the menu items in the menu groups (e.g. mode of operation) by using the P key. Use the arrow keys to move up and down within the menu group.

The menu groups consist of one area for the user (user menu) and one area for installation (service). The service area can be protected against unauthorized access by using a PIN.

In order to simplify the initial start-up operation, the service level is enabled at first (i.e., not protected by the PIN 0010 (☞ see Controller Setup, PIN protection = OFF)). If PIN protection is activated (ON), the service menu remains enabled after input of PIN 0010 as long as one is pressing keys. If no keys are pressed for ca. 15 minutes, the PIN is automatically erased, i.e. the service level is blocked.

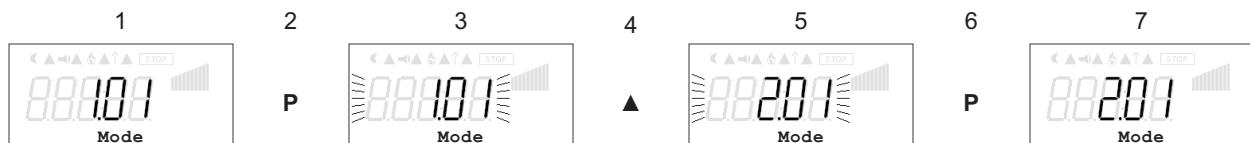
To make adjustments, press the P key after selecting the menu item. If the previously set value starts to flash it can be adjusted with the ▲ + ▼ keys and then saved with the P key. To exit the menu without making any changes, use the "Esc" short-key, i.e., the originally set values remain.



### Information

After installation of the device has been carried out, PIN protection should be activated (☞ Controller Setup)!

## 6.5 Example for programming mode 2.01 in “Base setup”



## 7 Base setup

### 7.1 Select operation mode



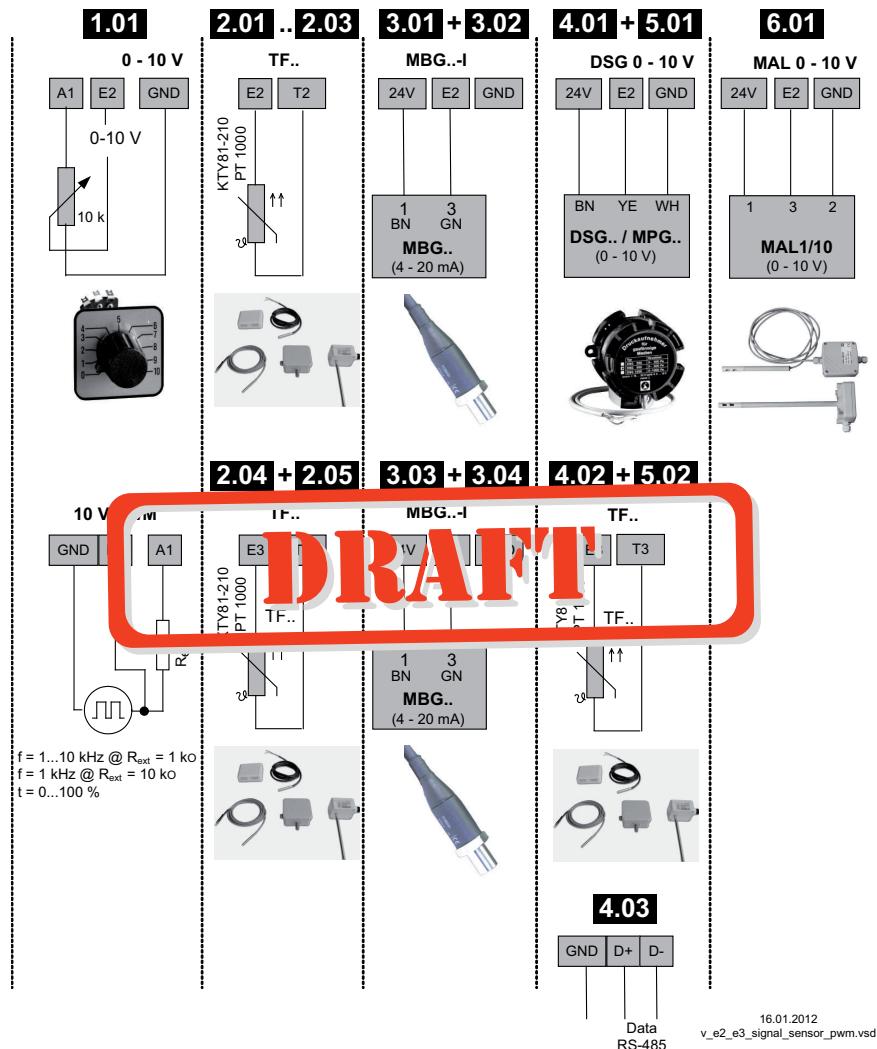
#### Information

Simple installation is possible through the selection of the preprogrammed mode of operation. This determines the basic function of the device; factory setting **1.01** = speed controller (activation via 0 - 10 V signal). The controller configuration is automatically carried out during selection of the application related mode of operation. The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted (☞ Controller Setup: "Controller Configuration").

The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value (modulation) is deduced from this.

Mode	Signal or Sensor <small>(input)</small>	Function
<b>1.01</b>	Signal 0 - 10 V	Speed control, two step operation (factory setting)
<b>2.01</b>	Sensor KTY81-210 / PT1000 (E2)	Temperature control airconditioning and refrigeration. (preset set-point 20.0 °C, - P-band 5.0 K)
<b>2.02</b>	Sensor KTY81-210 / PT1000 (E3)	Temperature control depending on outdoor temperature (preset set-point 5.0 °C, - P-band 20.0 K)
<b>2.03</b>	Sensor KTY81-210 / PT1000 (E2)	Temperature control with additional functions (shutter and heating)
<b>2.04</b>	1x Sensor KTY81-210 / PT1000 (E2) 1x Sensor KTY81-210 / PT1000 (E3)	Temperature control with two sensors, comparison or average
<b>2.05</b>	1x Sensor KTY81-210 / PT1000 (E2) 1x Sensor KTY81-210 / PT1000 (E3)	Temperature control with two sensors differential temperature
<b>3.01</b>	Sensor MBG.. (E2)	Pressure control condensers (refrigeration)
<b>3.02</b>	Sensor MBG..(E2)	Pressure control for condensers with input for refrigerant
<b>3.03</b>	1x Sensor MBG..(E2) 1x Sensor MBG..(E3)	Pressure control for two circuit condensers
<b>3.04</b>	1x Sensor MBG..(E2) 1x Sensor MBG..(E3)	Pressure control for two circuit condensers with input for refrigerant
<b>4.01</b>	Sensor DSG.. / MPG.. (E2)	Pressure control for ventilation systems
<b>4.02</b>	1x Sensor DSG.. / MPG.. (E2) 1x Sensor KTY81-210 / PT1000 (E3)	Pressure control depending on outdoor temperature
<b>4.03</b>	1x Sensor DSG.. / MPG.. (E2) 1x BUS RS 485	Pressure control depending on outdoor temperature, MODBUS for outdoor temperature and remote control by central operating device type AXE-200AX
<b>5.01</b>	Sensor DSG.. / MPG.. (E2)	Volume control (constant) for ventilation systems
<b>5.02</b>	1x Sensor DSG.. / MPG.. (E2) 1x Sensor KTY81-210 / PT1000 (E3)	Volume control with setpoint depending on outdoor temperature
<b>6.01</b>	Sensor MAL..(E2)	Air velocity control e.g. clean room

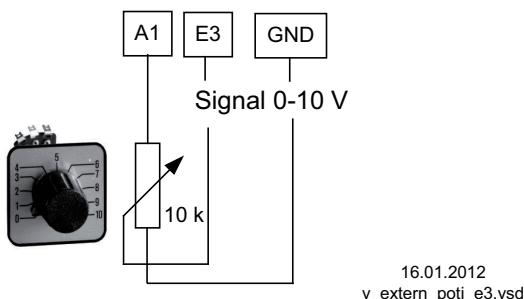
## Mode and Signal to E1, E3



## 7.2 External Setpoint / External speed setting in manual operation

External setpoint setting or external manual operation are possible using a 0 - 10 V (0 - 20 mA, 4 - 20 mA) signal at the "E3" and "GND" terminals. Configure "E3" in Base setup. For potentiometers, program Analog Out 1 (terminal "A1") to the function [1A] = "+10 V" (as factory setting IO Setup).

E3 Analog In = factory setting 0 - 10 V



**External Setpoint** via external signal instead of "Setpoint 1". The "external Setpoint" function must be activated in base setup [1E] for "E3 function". The active external Setpoint value is displayed in the "info" menu group.

**External speed setting** in manual operation. The "external manual operation" function must be activated in the basic settings [2E] for "E3 function". Switchover between settings on the device and external manual operation via the digital input ( IO Setup: "Control / manual operation" [7D]).

## 8 Start-up

### 8.1 Prerequisites for commissioning



#### Attention!

1. You must mount and connect the device in accordance with the operating instructions.
2. Double check that all connections are correct.
3. Make sure that no persons or objects are in the fan's hazardous area.

### 8.2 Procedure for commissioning

Sequence	Setting
1	If necessary, set the menu language in <b>Menu group "Start"</b> . (Factory setting Englisch: " <b>Language GB</b> ")
2	Set the operating mode in the <b>Base setup</b> menu group (factory settings <b>1.01 = speed controllers</b> ). <b>Attention!</b> When saving the operating mode, the respective preset factory operating-mode setting is loaded. That means, the settings you have made in <b>Mode Selection</b> are lost. An exception: the menu language setting remains preserved.
	<b>DRAFT</b>

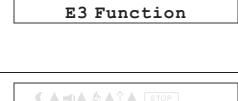
### 8.3 Menu Mode **1.01**

Start	Info	Setting	Events	Base setup	Controller Setup	IO Setup	Limits	Motor Setup	Diagnostic
---- PIN input	0 rpm Speed	200 rpm Set Intern1	-0- Factory sett.	1.01 Mode	OFF PIN Protection	[1A] A Function	OFF Level. Function	20 sec Rampup time	OTC 00012:56:-15
GB Lan- guage	0.0 A Motor cur- rent	----- Set Intern2	-1- Sensor 1	0 - 10 V E2 Analog In	OFF Set protec- tion	0.0 V A min.	----- Level min	20 sec Rampdown time	OTM 00010:56:-11
OFF Reset	0 rpm Set exter- nal1	0 rpm Min. Speed	-3- ext. Fault	OFF E3 Func- tion	OFF Save User Setup	10.0 V A max.	----- Level max.	OFF Suppres- sion1	585 V DC-Voltage
1.01 Mode		1800 rpm Max. Speed		----- E3 Analog In	----- Limit	OFF A Inverting	----- Level Delay	----- Range1 min.	244 V Line volt- age
4.00 ECblue Premium		ON Set exter- nal1			----- Group 2 ON value	OFF D1 Func- tion	OFF Lmt E2 Function	----- Range1 max.	29.5 °C Heatsink
1.01 Basic Ver- sion					----- nmin at Group2	----- D1 Invert- ing	----- Lmt E2 min	OFF Suppres- sion1	29.5 °C Capacitor

## 9 Programming

### 9.1 Speed controller 1.01

#### 9.1.1 Base setup 1.01

	<b>Base setup</b>
	<b>Mode</b> Factory setting Mode: <b>1.01</b>
	<b>E2 Analog In</b> Selection: 0 - 20 mA, 4 - 20 mA, Bus (Inverting  IO Setup)
	<b>E3 Function</b> <b>DRAFT</b> For operation with a second signal and switch over via floating contact set function for E3 to 1E (  IO Setup: function [4D]). For operation with a second signal and automatic control at the higher level. Set "E3" Function to [4E].
	<b>E3 Analog In</b> As long as no allocation has been carried out display:  Selection: 0 - 20 mA, 4 - 20 mA, Bus (Inverting  IO Setup) Factory setting: 0 - 10 V

#### 9.1.2 Setting for operation 1.01

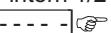
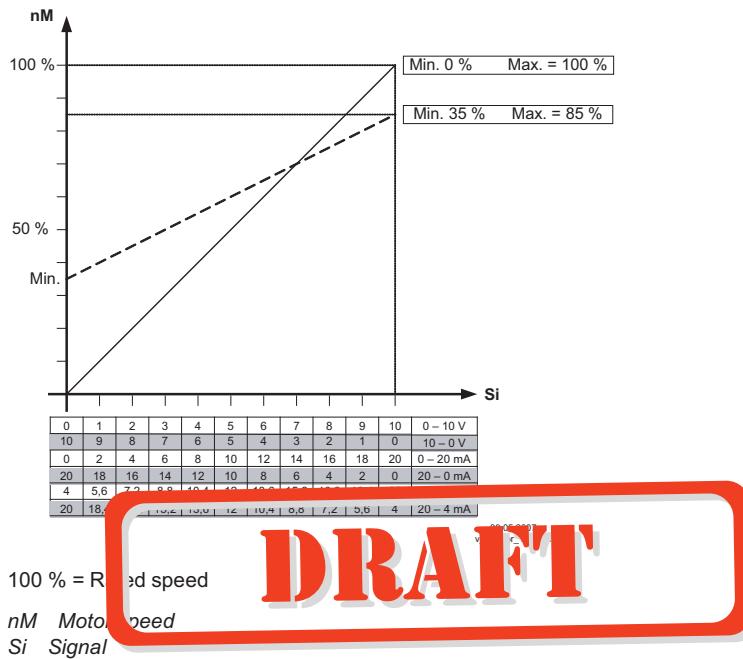
	<b>Setting</b>
	<b>Set Intern1</b> Setting range manual speed setting: 0 rpm... "Max. Speed" Factory setting: 200 rpm
	<b>Set Intern2</b> Setting "Set Intern 2" e.g. reduced value for night operation. Switch over intern 1/2 by external contact (as long as no allocation is carried out: Display:   IO Setup).
	<b>Min. Speed</b> Setting range: 0 rpm... "Max. Speed" Factory setting: 0 rpm
	<b>Max. Speed</b> Setting range: Rated speed...0 rpm (takes priority over setting "Min. Speed") Factory setting: Rated speed
	<b>Set external1</b> "ON" (factory setting) = speed setting by external Signal "OFF" = Setting "Set Intern1"

Diagram setting signal and output voltage (Idealized principle diagram)



## 9.2 Temperature control 2.01... 2.05

### 9.2.1 Basic setting 2.01... 2.05

	<b>Base setup</b>
	<b>Mode</b> Mode selection e.g. <b>2.01</b>
	<b>E2 Analog In</b> In all group 2 operating modes (2.01, 2.02, 2.03, ....) "E2 Analog In" factory set to "KTY" (sensors type TF..) at terminals "E2" and "T2" (measuring range: -50.0...+140 °C).
	<b>Alternative selection sensor</b> <ul style="list-style-type: none"> <li>PT1000 to Terminals "E2" and "T2" (Measuring range -50.0...+140 °C)</li> <li>MTG-120V active sensor with 0 - 10 V output at terminals "E2" and "GND" (measuring range: -10...+120 °C)</li> </ul> Alternative selection signal at terminals "E2" and "GND": 0 - 10 V, 0 - 20 mA, 4 - 20 mA. The sensor measurement range must be entered in order to display the actual value correctly. Example with a 0 - 10 V sensor and 0 - 100 °C measurement range: E2 Analog In = 0 - 10 V, E2 Min. = 0.0 °C, E2 Max. = 100.0 °C, E2 Decimally = 1, E2 Unit = °C
	<b>E2 Offset</b> Sensor calibration with calibrated comparison device

	<b>E3 Function</b> (only for special applications)

- Function **[1E]** = External Setpoint e.g. via external signal (0 - 10 V) instead of "Setpoint1"
  - For sensor type "E2 Analog In" = "KTY or PT1000": 0 - 10 V  $\triangleq$  -50.0...+140 °C.
  - For sensors with active signal: 0 - 10 V  $\triangleq$  0 - 100 % sensor measuring range.
- Function **[2E]** = External manual operation via external signal (0 - 10 V). Switch over between settings on the device and external manual operation via digital input ( $\Rightarrow$  IO Setup: function **[7D]**).
- Function **[7E]** Measurement value = Measurement value e.g. for limit indication, display in Info menu "E3 Actual".

#### Modes with two sensors

The function is automatically jointly programmed in operating modes using 2 sensors. The second analog input is thus allocated and additional function allocations are not possible.

- DRAFT**
- [1E]** E3 Function and **[4E]** preprogrammed = comparison value with control to higher value. Alternative: average of 2 measuring points for this must be pre-programmed on function **[3E]** preprogrammed sensor type "KTY".
  - [2E]** E3 Function and **[5E]** preprogrammed = regulation on difference temperature between sensor 1 and sensor 2. Preprogrammed sensor type "KTY".

#### 9.2.2 Settings for operation modes **2.01 ... 2.05**

**2.01** Temperature control simple

**2.02** Temperature control depending on outdoor temperature (Special function: Sensor connection at "E3", display and setting under "E2").

**2.03** Temperature control with pre-programmed additional functions (heating, shutter, temperature monitoring).

**2.04** Temperature control with 2 sensors

Comparison with control to higher value "E3 Function" set to comparison **[4E]**. Display during operation: "Control value"

Alternative: Average calculation of 2 measuring places "E3 Function" set to **[3E]**. Display during operation: "Average E2 / E3"

**2.05** Temperature control with 2 sensors, regulation on difference temperature.

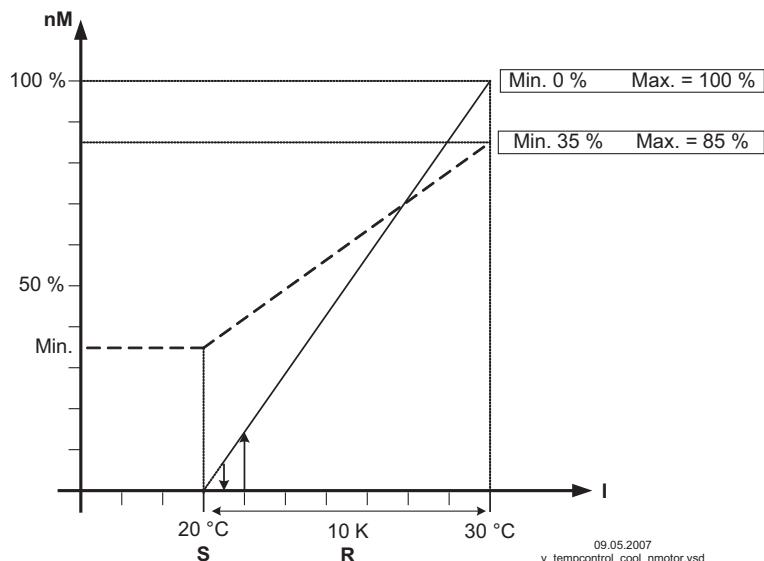
Display during operation: "Value of E2 - E3" in K, "E2" = reference temperature, "E3" causes positive (E3 < E2) or negative (E3 > E2) difference.

	<b>Setting</b>
	<b>Setpoint1</b> Setting range: with passive sensor type "KTY", "PT1000": -50.0...150.0 °C Factory setting: <b>2.01</b> , <b>2.03</b> , <b>2.04</b> : 20.0 °C at <b>2.02</b> : 5.0 °C at <b>2.05</b> : 0.0 °C Setting range: at active sensor type "MTG-120V": -10.0...+120.0 °C Factory setting: <b>2.01</b> - <b>2.05</b> : 55.0 °C
	<b>Setpoint2</b> Setting "Setpoint 2" e.g. reduced value for night operation. Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out: Display: <b>-----</b> $\Rightarrow$ IOSetup).

	<b>Pband</b> Narrow control range = Short control times Wide control range = Longer control times and more stable control  Passive sensor type "KTY", "PT1000" Setting range: 0 - 200.0 K (Kelvin) Factory setting: 5.0 K, (at 2.02): 20.0 K  active Sensor type "MTG-120V" Setting range: 0.0...+130.0 K Factory setting: 65.0 K
	<b>Min. Speed</b> Setting range: 0 rpm... "Max. Speed" Factory setting: 0 rpm
	<b>Max. Speed</b> Setting range: Rated speed...0 rpm (takes priority over setting "Min. Speed") Factory setting: Rated speed
	<b>Manual mode</b> Set parameters (Factory setting) "ON" = automatic control without function, speed setting in menu "Speed manual"
	<b>Speed Manual mode</b> Manual speed setting without influence by the external signal. Activation by menu "Manual mode" or external contact at digital input (IO Setup). Setting range: 0 rpm...Rated speed, Factory setting: 200 rpm For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

### 9.2.3 Functional diagrams temperature control

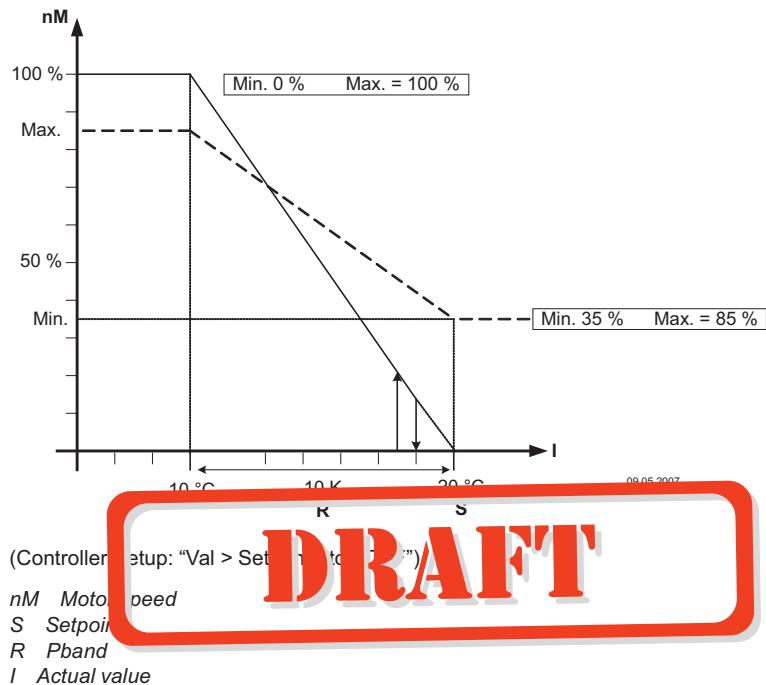
Example 1: Temperature control in factory setting "Cooling function" (Idealized principle diagram)



(Controller Setup: "Val > Set = n+" to "ON")

$nM$  Motor speed  
 $S$  Setpoint  
 $R$  Pband  
 $I$  Actual value

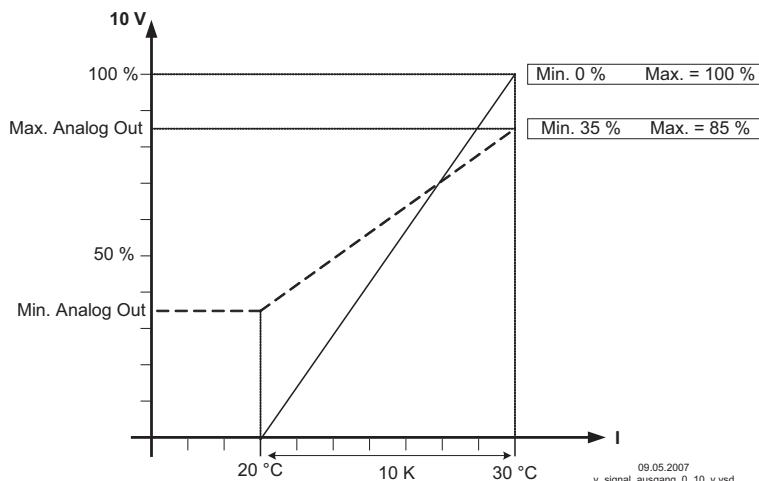
Example 2: Temperature control in “Heating function” (Idealized principle diagram)



#### 9.2.4 Additional for mode 2.03: Signal output 0 - 10 V

The 0 - 10 V output signal can, e.g., be used for triggering a shutter or heating.

	<b>Offset AnalogOut</b> The target value for this output is the target value (Setpoint) for the ventilation “offset” setting. Adjustment: range +/- 10 K relative to the active Setpoint. Example for triggering a shutter servomotor: At factory setting “0 K” = synchronous operation. The analog output is factory set to increasing activation during increasing temperature. Reprogramming to “Heating function”, i.e., increasing modulation during decreasing temperature is possible (IO Setup).
	<b>Pband AnalogOut</b> Pband AnalogOut = separately adjustable range of control (P-band) for 0 - 10 V output Setting range: 0...102.0 K Factory setting: 2.0 K
	<b>Min. AnalogOut</b> Min. AnalogOut = Minimal output voltage Setting range: 0...100 % = 0 - 10 V Factory setting: 0 %
	<b>Max. AnalogOut</b> Max. AnalogOut = Maximal output voltage, Setting range: 100...0 % = 10 - 0 V Factory setting: 0.0 K

**Example for signal out 0 - 10 V (IO Setup: "A function" = [6A])**

Example: Setpoint ventilation  $20^{\circ}\text{C}$  Setpoint  $+/- 1\text{K}$  Actual  $\text{I}$   
 S Setpoint Ventilation +/- 0 K  
 R Pband 0 K  
 I Actual value

**DRAFT**

**9.2.5 For mode 2.03: Relay output for Heating or Cooling**

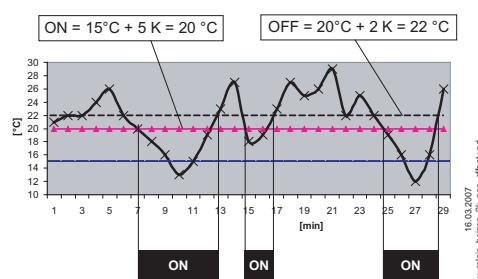
 	<b>OffsetDigitalOut</b> Offset Digital Out = Offset for relay output ("K1" has to be reprogrammed to function [9K]). The relay operating point deviates by the adjusted offset of the Setpoint of the ventilation. Setting range: -10.0...+10.0 K Factory setting: -1.0 K <ul style="list-style-type: none"> <li>“0.0 K” set, i.e. heating “ON” when: actual value = Setpoint</li> <li>During negative offset value heating “ON” when: actual value = Setpoint - offset</li> <li>During positive offset value heating “ON” when: actual value = Setpoint + offset</li> </ul> <b>Hyst.DigitalOut</b> Switching hysteresis of the relay Setting range: 0...10 K, Factory setting: 1.0 K (Kelvin)
---	---

**Temperature variation with setting [9K] for K1 function in IO Setup e. g. for controlling a Heating.**

If the ambient temperature is lower than the set operating point, the heating remains switched on. If the ambient temperature exceeds the set operating point of the heating by 2 K (Kelvin), the heating is switched off. i.e., the release point is situated at the hysteresis value over the operating point.

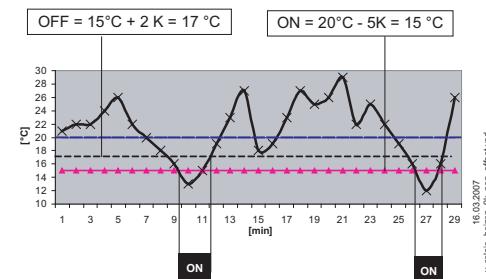
Example:

Setpoint  $15.0^{\circ}\text{C}$ , Offset  $+5.0\text{ K}$ , Hysteresis  $2.0\text{ K}$



Example:

Setpoint  $20.0^{\circ}\text{C}$ , Offset  $-5.0\text{ K}$ , Hysteresis  $2.0\text{ K}$



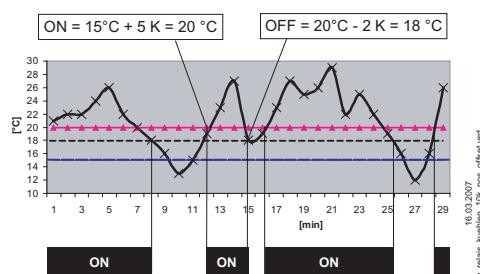
The activated heating is indicated over the fire symbol in the display.



**Temperature variation with setting **[10K]** for “K1” function in IO Setup e. g. for activation of the cooling.**

Example:

Setpoint 15.0 °C, Offset +5.0 K, Hysteresis 2.0 K



If the ambient temperature is higher than the set operating point, the cooling remains switched on. If the ambient temperature falls below the set operating point of the cooling by 2 K (Kelvin), it is switched off. I.e., the OFF point is situated at the hysteresis value under the ON point.

#### 9.2.6 For mode **2.03** Relay output for temperature monitoring

If the set value for the “minimum alarm” is not reached or the set value for the “maximum alarm” is exceeded, a message is generated with the alarm symbol in the display. In addition, „Lmt E1 min“ is displayed alternately with the actual value due to the minimum alarm and Lmt E1 max for the „Maximum alarm“. An external message follows via the factory-assigned “K1” relay. (IO Setup: K1 function = **[2K]**).

	<b>Alarm Minimum</b> Setting range: OFF / -26.9...75.0 °C Factory setting: 0.0 °C
	<b>Alarm Maximum</b> Setting range: OFF / -26.9...75.0 °C Factory setting: 40.0 °C

Example for display if falling below setting “Alarm Minimum” alternating to the actual value display.  
Relay “K1” disengages (if not inverted).

Example for display if exceeding setting “Alarm Maximum” alternating to the actual value display  
Relay “K1” disengages (if not inverted).

## 9.3 Pressure control for condensers refrigeration 3.01... 3.04

### 9.3.1 Base setup 3.01... 3.04

	<b>Base setup</b>
	<b>Mode</b> Mode selection e.g. 3.01
	<b>E2 Analog In</b> For all Modes in Group 3 (3.01, 3.02, 3.03, ...) “E2 Analog In” factory setting to “MBG-30I”. (measuring range 0..30 bar) proportional output 4 - 20 mA Selection sensor: MBG-30I, MBG-50I, DCE-25
<b>DRAFT</b>	
	<b>E2 Offset</b> Sensor calibration with calibrated comparison device
	<b>E2 Refrigerant</b> With 3.02 and 3.04 operating modes with input of the refrigerant, the device automatically calculates the corresponding temperature for the measured pressure. The settings for offset, target value and the controlling range are then carried out in °C or K. Calculation for relative pressure (differential measurement of pressure relative to ambient pressure). No further settings are necessary for pressure sensors model e.g. “MBG-30I” or “MBG-50I” (measurement range 0 - 30 bar or 0 - 50 bar). In the case of sensors with other measurement ranges, the “E2 Min. value” and the “E2 Max. Value”. Setting in “bar” although unit display is in “C”!
	<b>E3 Function</b> (only for special applications) <ul style="list-style-type: none"> <li>External setpoint = Function [1E] by external signal (0 - 10 V) instead of “Setpoint 1”. 0 - 10 V <math>\triangleq</math> 0 - 100 % sensor measuring range.</li> <li>External manual operation via external signal (0 - 10 V) = Function [2E] Switch over between settings on the device and external manual operation via digital input (☞ IO Setup: function [7D]).</li> <li>Measurement value = function [7E] e.g. for limit indication, display in Info menu “E3 Actual”.</li> </ul> <b>Modes 3.03 and 3.04 with two sensors</b> The function is automatically jointly programmed in operating modes using 2 sensors. The second analog input is thus allocated and additional function allocations are not possible. With 3.03 and 3.04 E3 Function at [4E] preprogrammed = comparison value with control to higher value (two circuit condensers).

#### Selection of the refrigerants:

R12	R13	R13b1	R22	R23	R32	R114	R134a	R142B
R227	R401	R401A	R401B	R402	R402A	R402B	R404A	R407A
R407B	R407C	R410A	R500	R502	R503	R507	R717	

### 9.3.2 Setting for operation modes **3.01... 3.02**

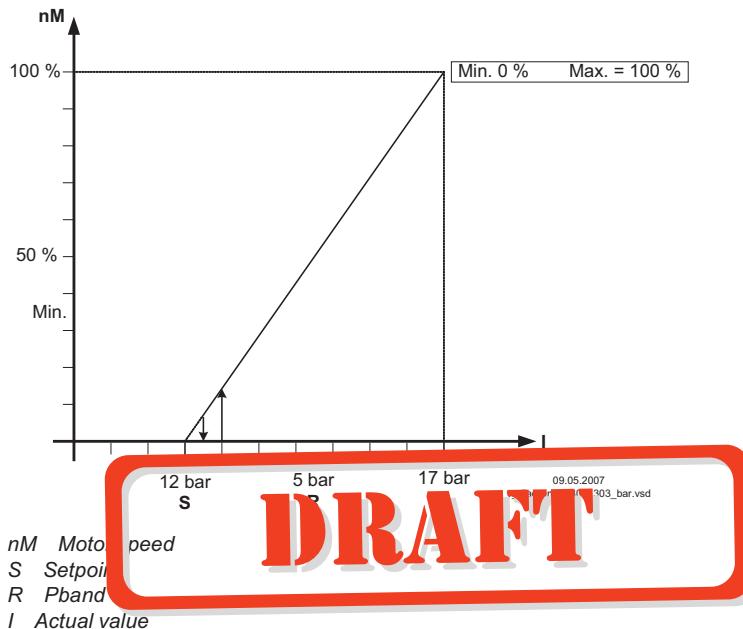
**3.01** Pressure control condensers, setting Setpoint in bar

**3.02** Pressure control for condensers with input for refrigerant, Setpoint in °C

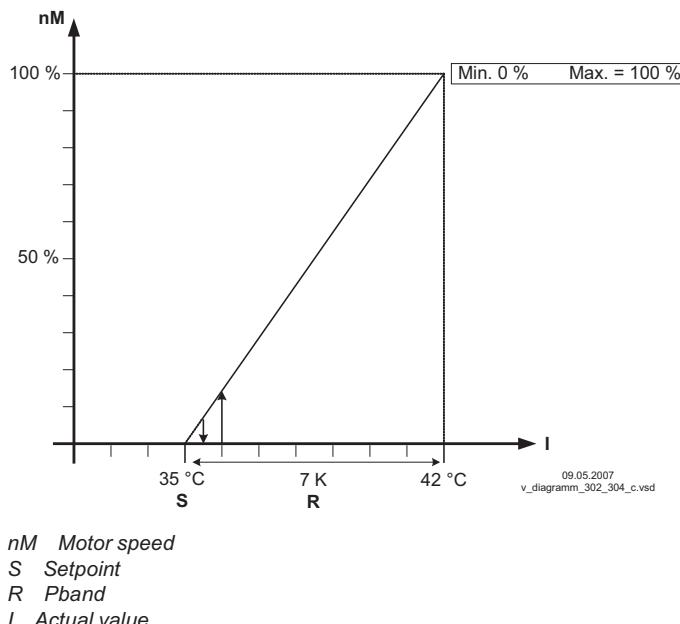
	<b>Setting</b>
	<b>Setpoint1</b> <b>3.01</b> Setting range: in measuring range of sensor, factory setting: 12.0 bar <b>3.02</b> Setting range: dependent on the selected refrigerant, factory setting: 35.0 °C
	<b>DRAFT</b> Setpoint 2 = Setpoint 1 - 10%. Reduced value for night operation. Switch over Setpoint 1/2 by external contact as long as no allocation is carried out:
	<b>Pband</b> Narrow control range = Short control times Wide control range = Longer control times and more stable control <b>3.01</b> Setting range: in measuring range of sensor, factory setting: 5.0 bar <b>3.02</b> Setting range: dependent on the selected refrigerant and in measuring range of sensor, factory setting 7.0 K
	<b>Min. Speed</b> Setting range: 0 rpm... "Max. Speed" Factory setting: 0 rpm
	<b>Max. Speed</b> Setting range: Rated speed...0 rpm (takes priority over setting "Min. Speed") Factory setting: Rated speed
	<b>Manual mode</b> "OFF" = automatic control as function of the set parameters (Factory setting) "ON" = automatic control without function, speed setting in menu "Speed manual"
	<b>Speed Manual mode</b> Manual speed setting without influence by the external signal. Activation by menu "Manual mode" or external contact at digital input (☞ IO Setup). Setting range: 0 rpm...Rated speed, Factory setting: 200 rpm For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

### 9.3.3 Functional diagrams pressure control condensers

Functional diagram for Mode **3.01** and **3.03** (Idealized principle diagram)



Functional diagram for Mode **3.02** and **3.04** (Idealized principle diagram)



#### Information

The factory default presets must be adapted to match the system conditions by a competent person.

## 9.4 Pressure control airconditioning **4.01... 4.03**

### 9.4.1 Base setup **4.01... 4.03**

	<b>Base setup</b>
	<b>Mode</b> Mode selection e.g. <b>4.01</b>
	<b>E2 Analog In</b> In all group 2 operating modes 4 ( <b>4.01, 4.02, 4.03</b> , ....) "E2 Analog In" factory setting "DSG200". Selection sensor type: "DSG 50", "DSG100*", "DSG200", "DSG300"*, "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000" (! no standard type). The type of the connected external analog sensor defines further settings are necessary. Select with 2 - 10 V sensor and 0 - 400 Pa measurement range (proportional output signal). E2 Actual = 000.000 Pa, E2 Setpoint = 000.000 Pa, Max. = 400 Pa, E2 Dezimal = 1, E2 Einheit = Pa
	<b>E2 Offset</b> Sensor calibration with calibrated comparison device
	<b>E3 Function</b> (only for special applications) <ul style="list-style-type: none"> <li>External setpoint = Function <b>[1E]</b> by external signal (0 - 10 V) instead of "Setpoint 1". 0 - 10 V <math>\triangleq</math> 0 - 100 % sensor measuring range.</li> <li>External manual operation via external signal (0 - 10 V) = Function <b>[2E]</b> Switch over between settings on the device and external manual operation via digital input (IO Setup: function <b>[7D]</b>).</li> <li>Measurement value = function <b>[7E]</b> e.g. for limit indication, display in Info menu "E3 Actual".</li> </ul> <b>Modes 4.02 and 4.03 with two sensors</b> The function is automatically jointly programmed in operating modes using 2 sensors. The second analog input is thus allocated and additional function allocations are not possible. For <b>4.02</b> E3 Function at <b>[6E]</b> preprogrammed = sensor for setpoint lowering. Preprogrammed sensor type "KTY" For <b>4.03</b> <b>[E3]</b> Function at <b>[6E]</b> preprogrammed = sensor for setpoint lowering. - preprogrammed sensor type "BUS" - measuring range -35.0...+65.0 °C In "IO Setup": For enable "ON" / "OFF" via Bus: - D1 function = <b>[1D]</b> - D1 Busmode = "ON" For switch over setpoint 1 / 2 via Bus: - D2 function = <b>[5D]</b> , - D2 Busmode = "ON"

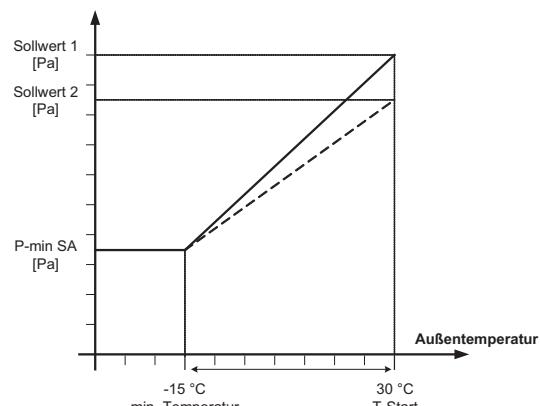
### 9.4.2 Setting for operation modes 4.01... 4.03

- **4.01** pressure control, setpoint in Pa
- **4.02** and **4.03** Pressure control for ventilation systems setpoint depending on outdoor temperature

	<b>Setting</b>
	<b>Setpoint1</b> Setting range: in measuring range of sensor Factory setting: 100 Pa
	<b>Setpoint2</b> Setting "Setpoint 2" e.g. reduced value for night operation. Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out: Display → IO Setup → Setpoint 1/2)
	<b>Pband</b> Short control times Long control times Setting range: in measuring range of sensor Factory setting: 100 Pa
	<b>Min. Speed</b> Setting range: 0 rpm... "Max. Speed" Factory setting: 0 rpm
	<b>Max. Speed</b> Setting range: Rated speed...0 rpm (takes priority over setting "Min. Speed") Factory setting: Rated speed
	<b>Manual mode</b> "OFF" = automatic control as function of the set parameters (Factory setting) "ON" = automatic control without function, speed setting in menu "Speed manual"
	<b>Speed Manual mode</b> Manual speed setting without influence by the external signal. Activation by menu "Manual mode" or external contact at digital input (IO Setup). Setting range: 0 rpm...Rated speed, Factory setting: 200 rpm For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

**Additional menu item for mode 4.02 and 4.03 with outside-temperature dependent target-setpoint.**

#### Outside-temperature dependent target-setpoint



An outside temperature compensation can be activated (sensor connection "E2" = "Analog In 2") when being operated as a pressure regulation device.

An optimal building climate, e.g., can be achieved through this. Through this function, the set and active "Setpoint 1" or "Setpoint 2" is automatically changed proportional to the measured outside temperature (☞ Info: "Setpoint control").

S1 Setpoint 1  
 S2 Setpoint 2  
 P-Min SA Minimum pressure  
 T-min Minimum temperature  
 T-Start Setpoint reducing will start below this outside temperature  
 AT Outdoor air temperature

**DRAFT**



#### T-Band SA

Temperature range in which the setpoint change continuously with outside temperature



#### T-Start SA

Setpoint reducing will start below this outside temperature



#### P-Min SA

Minimum pressure for very low outside temperature

## 9.5 Volume control [5.01... 5.02]

### 9.5.1 Basic setting [5.01] and [5.02]

	<b>Base setup</b>
	<b>Mode</b> Mode selection e.g. <b>5.01</b>
	<b>E2 Analog In</b> In all group operating modes 5 ( <b>5.01</b> and <b>5.02</b> ) "E2 Analog In" factory setting "DSG200". Selection sensor measuring range: "DSG 50", * "DSG100", "DSG200", * "DSG300", "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000" (no standard type).
 <b>DRAFT</b>	Setting "K factor" depending on the fan (outlet duct). setting range: 0...7.000 Factory setting: 7.00
	<b>E2 Offset</b> Sensor calibration with calibrated comparison device
	<b>E3 Function</b> (only for special applications) <ul style="list-style-type: none"> <li>External setpoint = Function <b>[1E]</b> by external signal (0 - 10 V) instead of "Setpoint 1". 0 - 10 V <math>\triangleq</math> 0 - 100 % setting range</li> <li>External manual operation via external signal (0 - 10 V) = Function <b>[2E]</b> Switch over between settings on the device and external manual operation via digital input (IO Setup: function <b>[7D]</b>).</li> <li>Measurement value = function <b>[7E]</b> e.g. for limit indication, display in Info menu "E2 Actual"</li> </ul> <b>Modes 5.02 with two sensors</b> Modes with two sensors The function is automatically jointly programmed in operating modes using 2 sensors. The second analog input is thus allocated and additional function allocations are not possible. For <b>5.02</b> E3 Function at <b>[6E]</b> preprogrammed = sensor for setpoint lowering. Pre-programmed sensor type "KTY".

### 9.5.2 Setting for operation modes [5.01... 5.02]

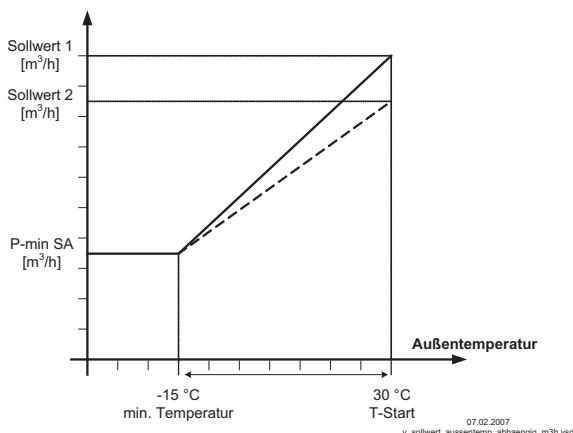
- 5.01** Volume control, Setpoint in  $\text{m}^3/\text{h}$
- 5.02** Volume control for ventilation systems setpoint depending on outdoor temperature.

	<b>Setting</b>
	<b>Setpoint1</b> Setpoint in $\text{m}^3/\text{h}$ ( $\text{m}^3/\text{s}$ ) Setting range: depending on measuring range of sensor and "K factor" Factory setting: $530 \text{ m}^3/\text{h}$
	<b>Setpoint2</b> Setting "Setpoint 2" e.g. reduced value for night operation. Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out: Display: <b>-----</b> IO Setup).

	<b>Pband</b> Narrow control range = Short control times Wide control range = Longer control times and more stable control Setting range: depending on measuring range of sensor and "K factor" Factory setting: 530 m³/h
	<b>Min. Speed</b> Setting range: 0 rpm... "Max. Speed" Factory setting: 0 rpm
	<b>Max. Speed</b> Setting range: Rated speed...0 rpm (takes priority over setting "Min. Speed") Factory setting: Rated speed
	<b>Manual mode</b> "OFF" = automatic control as function of the set parameters (Factory setting) "ON" = automatic control without function, speed setting in menu "Speed manual"
	<b>Speed manual mode</b> Regulation is deactivated starting with the influence by the external signal. Activation by menu "Manual mode" or external contact at digital input (☞ IO Setup). Setting range: 0...200 rpm Factory setting: 200 rpm  For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

**Additional menu item for mode 5.02 with outside-temperature dependent target-setpoint**

Outside-temperature dependent target-setpoint



An outside temperature compensation can be activated (sensor connection "E2" to "Analog In 2") when being operated as a air volume regulation device.

An optimal building climate, e.g., can be achieved through this. Through this function, the set and active Setpoint 1/2 is automatically changed proportional to the measured outside temperature (☞ Info: "Setpoint control").

S1 Setpoint1

S2 Setpoint2

P-Min SA Minimum air volume

T-min Minimum temperature

T-Start Setpoint reducing will start below this outside temperature

AT Outdoor temperature

	<b>T-Band SA</b> Temperature range in which the setpoint change continuously with outside temperature
	<b>T-Start SA</b> Setpoint reducing will start below this outside temperature
	<b>P-Min SA</b> Minimum pressure for very low outside temperature

## 9.6 Air velocity control 6.01

### 9.6.1 Base setup 6.01

	<b>Base setup</b>
	<b>Mode</b> Mode selection <b>6.01</b>
	<b>E2 Analog In</b> For mode <b>6.01</b> "E2 Analog In" factory setting to "MAL1" Selection sensor measuring range: MAL1, MAL10 Alternative selection signal: 0 - 10 V, 0 - 20 mA, 4 - 20 mA. The sensor measurement range must be converted in order to display the actual value correctly. Example with a 0 - 10 V sensor and 0 - 5 m/s measurement range (proportional output signal) 2 mV/V → 100 %, E2 in. = 0.0 m/s, E2 Max. = 5.0 m/s, E2 Decimals = 1, E2 Unit = m/s
	Calibration with calibrated comparison device
	<b>E3 Function</b> (only for special applications) <ul style="list-style-type: none"> <li>External setpoint = Function <b>1E</b> by external signal (0 - 10 V) instead of "Setpoint 1". 0 - 10 V <math>\triangleq</math> 0 - 100 % setting range</li> <li>External manual operation via external signal (0 - 10 V) = Function <b>2E</b> Switch over between settings on the device and external manual operation via digital input (☞ IO Setup: function <b>7D</b>).</li> <li>Measurement value = function <b>7E</b> e.g. for limit indication, display in Info menu "E3 Actual."</li> </ul>

### 9.6.2 Settings for operation modes [6.01]

	<b>Setting</b>
	<b>Setpoint1</b> Setting range: in measuring range of sensor Factory setting: 0.50 m/s
	<b>Setpoint2</b> Setting "Setpoint 2" e.g. reduced value for night operation. Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out: Display:  IOSetup).
	<b>Pband</b> Narrow control range = Short control times Wide control range = Longer control times and more stable control Setting range: in measuring range of sensor Factory setting: 0.50 m/s
	<b>Min. Speed</b> Setting range: 0 rpm ... "Max. Speed" Factory setting: 0 rpm
	<b>Max. Speed</b> Setting range: Rated speed...0 rpm (takes priority over setting "Min. Speed") Factory setting: Rated speed
	<b>Manual mode</b> "OFF" = automatic control as function of the set parameters (Factory setting) "ON" = automatic control without function, speed setting in menu "Speed manual"
	<b>Speed Manual mode</b> Manual speed setting without influence by the external signal. Activation by menu "Manual mode" or external contact at digital input (  IO Setup). Setting range: 0...100 %, Factory setting: 100 % For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

## 9.7 Menu group Start

	<b>Start</b>
	<b>PIN input</b> The service menu for the installation can be protected against unintentional changes by a pin code. With further pin codes putting back to pre-setting is possible. <b>PIN 0010</b> Opening “service menu”, if PIN-protection activated Menu (☞menu structure). <b>PIN 1234</b> Opening “setting”. if “set protection” = “ON” (☞ Controller Setup). <b>PIN 9090</b>
	<b>DRAFT</b> PIN 9090 This menu is set up (depends function “Save user setup” = “ON” ☞ Controller Setup). PIN 9090 DRAFT
	Exception, the following parameters are not set back: Min. Speed, Max. Speed, all settings in Motor Setup.
	<b>Language</b> Menu language by the factory set to English. In this menu different national languages can be selected (GB = English, D = German ...).
	<b>Reset</b> Complete re-start of the device.
	<b>Mode</b> Query of the operating mode (e.g. <b>1.01</b> for speed controller).
	<b>ECblue Premium</b> Software version Modul.
	<b>Basic Version</b> software version motorcontroller.
	Individual unit number.

## 9.8 Menu group Info

	<b>Menu group Info</b>
<b>Info for mode speed controller 1.01</b>	
	Speed
	Display of motor current, different from the input current (metering precision approx. +/-10%)
	<p>The menu shows the active target value for the actuation of the power component under consideration of the settings "Min. speed" and "Max. speed".</p> <p>0 - 10 V, 0 - 10 mA, 0 - 20 mA, 20 - 4 mA</p> <p>The device operates at:</p> <p>Signal to "E2" / "GND"</p>
	Set "external1"
	Set "External2"
	Set "Intern1"
	Set "Intern2"
<b>Info for mode controller 2.01 ... 6.01</b>	
	Current actual value measured on the sensor 1. Depending sensor-type in: mbr, m <sup>3</sup> /s, m/s, Pa, %, bar, m <sup>3</sup> /h, °C, V, mA, etc.
	For operation with two sensors display for "2 actual". If function not active, display [-----]
	Display of the active target value at which the device operates. "Setpoint1" Menu "Setting" "Setpoint2" Menu "Setting" "Ext. Setpoint" = setting by external signal 0 - 10 V. With activated manual mode the display constantly changes between actual value and value for manual mode.
	Speed
	Motor current (deviating to input current)
	Momentarily status for minimum speed cut off "ON" = switch off, if Setpoint (+/- "Min. speed cut off") is reached. "OFF" = no switch off that means operation with minimum rate of air.

## 9.9 Controller Setup



### Controller Setup

#### 9.9.1 PIN protection activate, PIN 0010



The adjustments for the installation in the service level can be protected against unintentional modifications. To do this, activate the “PIN protection” = “ON”. In order to simplify the initial start-up operation, the service level in the factory setting is free = “OFF” i.e. accessible without **PIN 0010**.



#### Information

After installation of the device has been completed, “PIN Protection” should be activated = “ON”

**DRAFT**

#### 9.9.2 PIN protection activate, PIN 1234



The “Settings” menu for the user’s basic settings (Setpoint, default value, min, max ..) are freely accessible when using the factory settings (i.e. without “PIN”). If necessary, these can also be protected against unauthorized modifications by using a “**PIN 1234**”. For this, the settings protection must be programmed to “ON”. The settings menu is then no longer visible without inputting a PIN!

Function only in combination with activated PIN-Protection!

#### 9.9.3 Save user settings restore with PIN 9090



The individually made device configurations (User Settings) can be saved and, with the corresponding PIN input (9091), can be reestablished. By entering **PIN 9090** the individually made device configurations can be reestablished ( Start - PIN Input).



#### Information

By entering “**PIN 9095**” in the “PIN” menu in the “start” menu-group, the device is entirely reset to the pre-delivery condition.

Any changes that have been made to the settings are thus lost!

#### 9.9.4 Sensor Alarm ON / OFF

Function only in controller mode (**2.01**)!

For “E2 Analog In” and if activated for sensor 2 “E3 Analog In”.

In case of an interruption or short-circuit in the sensor conductor, or in case of measured values that lie outside of the device’s measurement range, a time-delayed fault indication takes place.



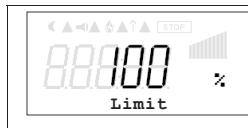
With “Alarm Sensors” = “OFF” (factory setting). Indicated sensor disturbances are displayed as “Message” alternating to the actual value and stored in the menu of “Events”.



With “AlarmSensors” = “ON” are indicated sensor disturbances as “Alarm” alternating to the actual value and stored in the menu of “Events”. Indication via relays is possible ( IO Setup / function relay outputs).



### 9.9.5 Limit

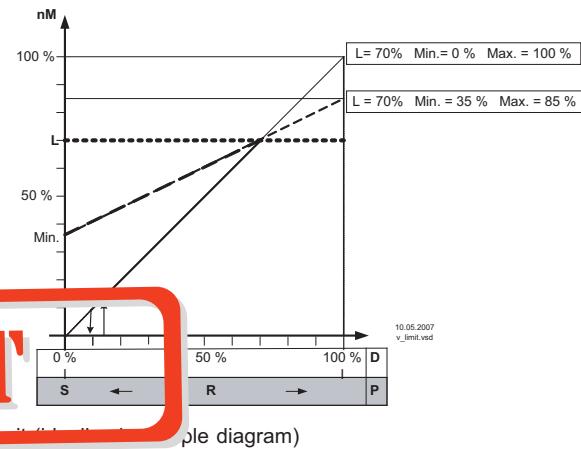


After allocation of a digital input (→ IO Setup) an adjustable limitation of the modulation can be activated via a digital input ("D1", "D2", ..). As long as no allocation has been carried out "IO Setup". Display: [ - - - ]

"Limit value" = max. possible modulation (e.g. speed reduction during night operation by time switch).

Setting range: "Limit" = "n-max" up to "n-min". Factory setting: 100 %  $\triangleq$  max. modulation, i.e. no limit.

Setting depending on device tie in: % or rpm.



*nM* Motor speed  
*L* Limit  
*S* Setpoint  
*R* Pband  
*D* Speed controller: setting signal  
*P* P-controller: control deviation

### 9.9.6 Minimum speed cut off



This function is primarily significant for installation of the device as a pure P Controller in refrigeration and air-conditioning technology.

For operation mode speed controller **1.01** without function!

**MSCO = OFF** (factory setting)

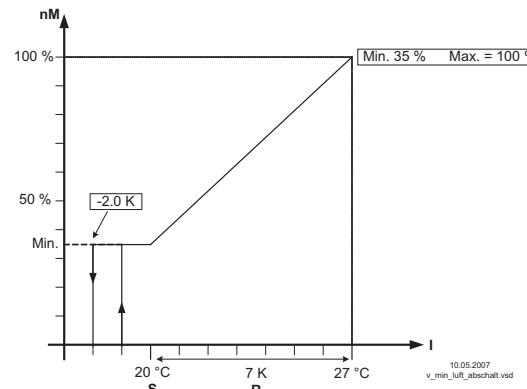
If no "Min. speed" is adjusted, the fan stops with reaching the desired value.

If "Min. speed" is adjusted (e.g. 20%), then no disconnection of the fan takes place. I.e., always a minimum ventilation is ensured (fan does not go under setting "Min. speed").

**MSCO. e.g. -2.0 K**

It takes place a disconnection from setting "Min. speed" to "0", if the given difference is reached related to the desired value.

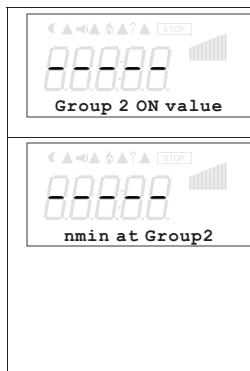
At a plus value (+) before reaching the desired value  
 At a minus value (-) after falling below the desired value.



Minimum speed cut off (idealized principle diagram)

*nM* Motor speed  
*S* Setpoint  
*R* Pband  
*I* Actual value

### 9.9.7 Second Group

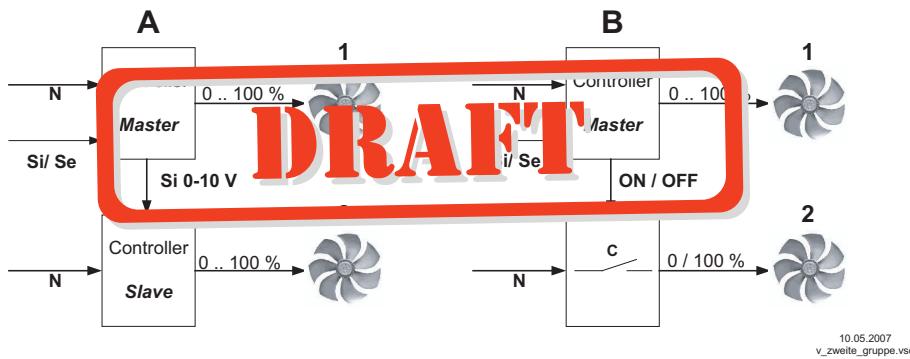


#### Second group "indirectly controlled" (picture A)

Analog output "AnalogOut 1" in IO Setup function [5A] = group control is programmed. This output is employed as the default signal for a speed controller. If the default signal or the regulation deviation exceeds the group 2 switch-on point, group 1 is reduced to "n-min group 2". Starting here, both groups run parallel at maximum power.

#### Second group "100 % energized" (picture B)

Relay output (K1 or K2) in IO Setup function [8K] = group control is programmed. A contactor is triggered via this relay contact, which directly switches the fans of the second group to mains voltage. If the default signal or the regulation deviation exceeds the "Group 2 ON value" switch-on point, the relay for the second group switches on and the speed of the first group is lowered to an adjustable minimum value. After that, the speed of the first group increases back up to maximum.



N Line  
Si Signal  
Se Sensor  
C Contactor

10.05.2007  
v\_zweite\_gruppe.vsd

### 9.9.8 Reverse action of the control function



#### For the effect of the regulation there are two functions:

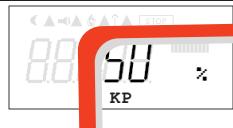
- **ON** for "Val > Set = n+"  $\triangleq$  increasing Fanlevel for increasing actual value over Setpoint.
- **OFF** for "Val > Set = n+"  $\triangleq$  increasing Fanlevel for decreasing actual value below Setpoint.

For special applications an external switch over of the control function is possible (☞ IO Setup).

Factory setting depending on selected mode		Example for temperature control (Idealized principle diagram)
Mode	Controller function	
<b>1.01</b>	non	
<b>2.01...</b>	ON	
<b>3.01...</b>	ON	
<b>4.01...</b>	OFF	
<b>5.01...</b>	OFF	
<b>6.01...</b>	OFF	<p>nM Motor speed R Pband S Setpoint I Actual value OFF for Val &gt; Set = n+ = heating function ON for Val &gt; Set = n+ = cooling function</p>

### 9.9.9 Controller configuration

The “controller configuration” is automatically carried out during selection of the application related mode of operation (Base setup). The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted (☞ Menu group “setting”).

	<p>The type of control determines the method with which the controlled value behaves in case of a difference between the target and current values. For this, the control technology has standard algorithms, which consist of a combination of three methods:</p> <p><b>Selection P, PID:</b></p> <ul style="list-style-type: none"> <li>• <b>P</b> control (Proportional component, proportion of the absolute deviation)</li> <li>• <b>I</b> control (Integral component, proportion of the sum of all deviations)</li> <li>• <b>D</b> control (Differential component, proportion of the last difference)</li> </ul>
	<p>With pure P controllers (controller type <b>P</b>), the following described settings do not have any function. If needed, the most suitable combination for the respective control system can be determined from these proportions.</p>
	<p><b>P-component = reaction time</b> Setting range: 0 - 200 % smaller = more slowly bigger = faster</p>
	<p><b>I-component = accuracy, correction time</b> Setting range: 0 - 200 % bigger = faster smaller = more slowly</p>
	<p><b>D-component</b> More “D-component” causes more stability by a clean actual value signal with shorter correction times By a actual value signal with a superposition should be done to attitude without “D-component” → 0 % Setting range: 0 - 200 % value smaller = less “D-component” value higher = more “D-component”</p>
	<p><b>Integration time = correction time</b> Setting range: 0 - 200 % smaller = faster bigger = more slowly</p>

### 9.9.10 Data on the total control deviation

The total control deviation is comprised of the sum of the control deviations for performance quantities and work quantities combined and refers to the specified areas.

In direct reference to the acquired input and controlled variables, the maximum deviation to the target value is < ± 5 %. By activating the menu-assisted adjustment, the total control deviation can be reduced to a value of < ± 1 %.

For indirect reference of the acquired input value to the controlled variable, i.e., two physical variables still need to be converted, the deviation can be reduced to < ± 5 % through adjustment.

In the case of an internal default value through the integrated or external terminal, the control deviation remains at < ± 0.5%.

### 9.9.11 LED Mode

	For motor sizes “D” and “G” there is a status LED in the cover of the controller housing.
<b>ON</b>	Status LED in ECblue active i.e. operating conditions are indicated by flash code (factory setting).
<b>OFF</b>	Status LED not active, i.e. always OFF.

## 9.10 IO Setup

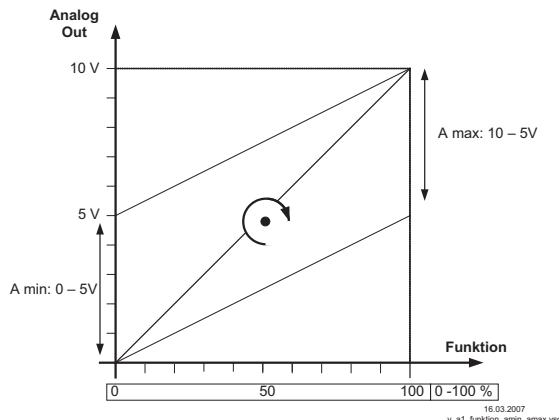


### 9.10.1 Analog-Output "A"

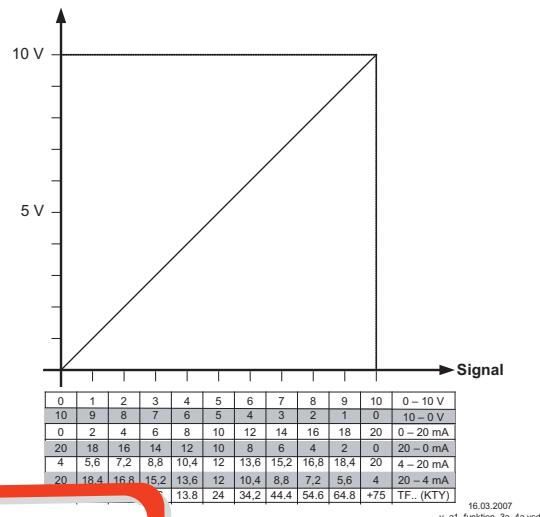
	The analog outputs 0 - 10 V can be allocated with various functions. Terminals "A" - "GND" = Analog Out ( $I_{max}$ 10 mA)
	With the attitudes "A min" and "A max" the characteristic of the output voltage can be adapted. Setting range: "A min." = 0 - 5 V, "A max." = 10 - 5 V Factory setting: A min. = 0 V, A max. = 10 V
	With the attitudes "A Inverting" the output voltage can inverted. Factory setting: "A Inverting" = "OFF"

Function	Description
OFF	without function
1A	Constant voltage +10 V (factory setting)
2A	Proportional the internal control of modulation with consideration "Min. speed" and "Max. speed" setting. <ul style="list-style-type: none"> <li>• for enable "OFF" it goes back to 0 V</li> <li>• for motor fault the output signal remains for a slave controller ("Master-Slave" combination).</li> </ul>
3A	proportional input "E2"
4A	proportional input "E3"
5A	Group control (Controller Setup - second group)
6A	Control output 2 increasing modulation at actual value > Set = cooling (only mode <b>2.03</b> temperature controller with additional functions).
7A	Control output 2 increasing modulation at actual value < Set (Heating) only mode <b>2.03</b> temperature controller with additional functions).
9A	Output speed ratio: actual speed / rated speed (for 10 V actual speed = rated speed)

## A1 Function "A min." and "A max."



## A1 Function [3A] / [4A]

**DRAFT**

## 9.10.2 Digital Inputs "D1", "D2" (E1)

## 9.10.2.1 Menu overview

	The digital inputs Digital In 1 (D1) and Digital In 2 (D2) can be allocated with various functions. Activation via floating contacts (a low voltage of approx. 24 V DC is connected).
	Inverting "D1" and "D2" possible
	With networking the digital inputs can be replaced by control over bus. With mode of operation <b>4.03</b> pre-setting of "D1" and "D2" is <b>[ON]</b> .



**Attention!**  
**Never apply line voltage to the digital input!**

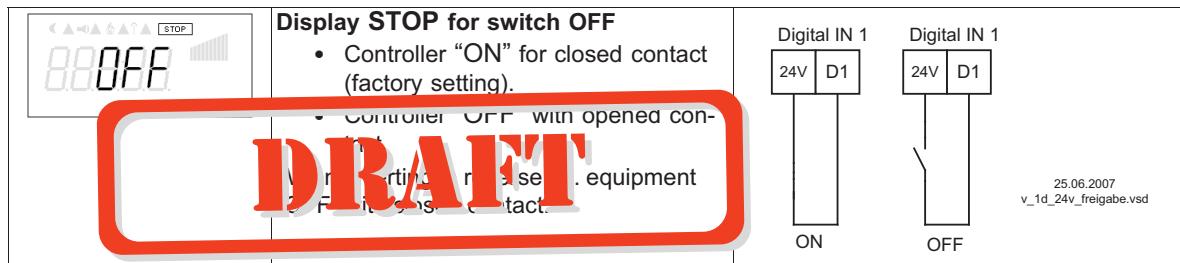
Function	Description
<b>OFF</b>	No function
<b>1D</b>	Enable (remote control) "ON" / "OFF"
<b>2D</b>	External error
<b>3D</b>	"Limit" ON / OFF
<b>4D</b>	Switch over "E1" / "E3"
	<b>For mode speed controller 1.01</b>
<b>5D</b>	Switch over "Setpoint Intern1" / "Setpoint Intern2"
<b>6D</b>	Switch over "Intern" / "Extern"
	<b>For modes as controller higher 2.01</b>
<b>5D</b>	Switch over "Setpoint1" / "Setpoint2"
<b>6D</b>	Switch over "Intern" / "Extern"
<b>7D</b>	Switch over "automatic control" / "Speed manual"
<b>8D</b>	Switch over control function (e.g. "heating" / "cooling")

<b>10D</b>	"Reset"
<b>11D</b>	Setting Max. Speed "ON" / "OFF"
<b>13D</b>	Switch over direction of rotation "right" / "left"
<b>14D</b>	"Freeze function" = maintain momentary modulation value

### 9.10.2.2 Enable ON/OFF function **[1D]**

Remote ON/OFF (electronic disconnection) and Reset after a motor malfunction via floating contact. The power section is electronically disconnected. Operation of the device is still possible after pressing the "ESC" hotkey combination in switched-off condition. Signal- in and outputs remain active.

- A programmed alarm relay (factory set "K1 function" = **[2K]**) does not report the switch-off.
- A programmed operation indicator relay (**[1K]**) reports the switch-off.



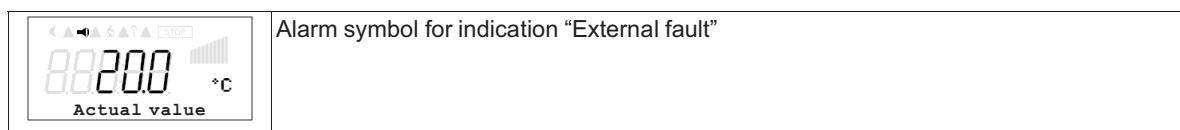
**Attention!**

**No disconnection (isolation) when turned off, in accordance with VBG4 §6!**

### 9.10.2.3 External fault Function **[2D]**

Connecting an external alarm indication (via floating contact). The device continues to work unchanged during an external indication to the digital input; the alarm symbol appears in the display. This indication can be issued via the relay contacts (K1) (☞IO Setup function K1).

- Indication during closed contact (factory setting): "D1 Inverting" = "OFF"
- Indication during opened contact: "D1 Inverting" = "ON"

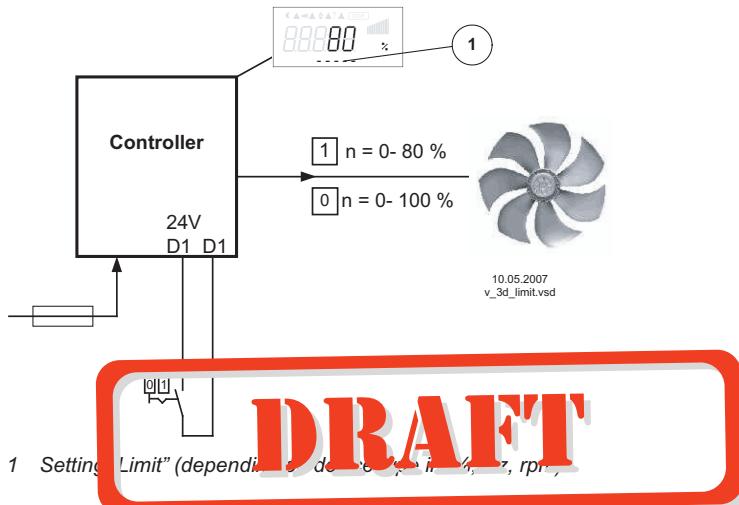


#### 9.10.2.4 Limit ON / OFF, Function [3D]

The value for "Limit" adjusted in the Controller Setup, is activated over a digital input.

Contact e.g. at digital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

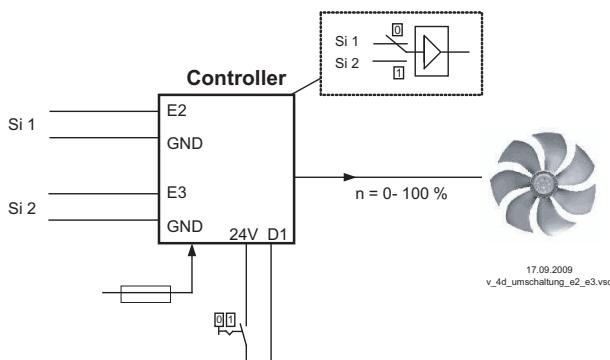
For "D1" Inverting "OFF", limitation active at closed contact.



#### 9.10.2.5 Switch over input signal "E2" / "E3", Function [4D]

Switch over between Input signal 1 (Analog In 1 terminal "E2") and input signal 2 (Analog In 3 terminal "E3").

Contact at digital input e.g. "Digital In 1"= terminals "D1" - "24 V"



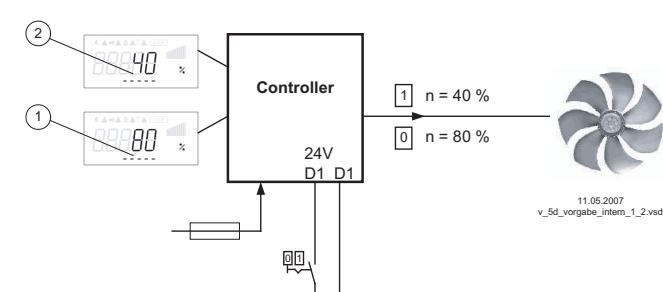
For mode speed controller (1.01) Base setup for "E3 Analog In": **[1E]** necessary.

For modes controller (higher 2.01 ..) Base setup for "E3 Analog In": **[7E]** necessary (as far as otherwise does not occupy).

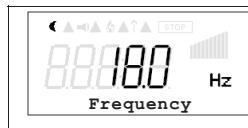
#### 9.10.2.6 Set 1/2 or Setpoint 1/2, Function [5D]

Switch over between "Set Intern1" and "Set Intern2" (for speed controller 1.01)

Contact e.g. at digital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").



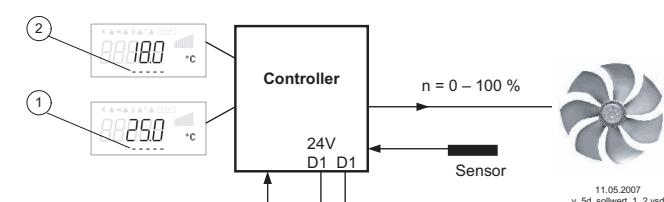
- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Set Intern2" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Intern2" at opened contact.



Operation with “Set Intern2” is signalized by the moon symbol for reduced operation.  
“Set extern1” under “settings” must be programmed to “OFF”.

### Switch over between “Setpoint1” and “Setpoint2” (for modes as controller higher 2.01)

Contact e.g. at digital input “Digital In 1” (depending on device type at terminals “D1” - “D1” or “D1” - “24 V”).



- “D1 Inverting” = “OFF”: “Setpoint1” = 18 °C at opened contact / “Setpoint2” = 25 °C at closed contact.
- “D1 Inverting” = “ON”: “Setpoint1” = 18 °C at closed contact / “Setpoint2” = 25 °C at opened contact.

1 Setting Setpoint1  
2 Setting Setpoint2

**DRAFT**

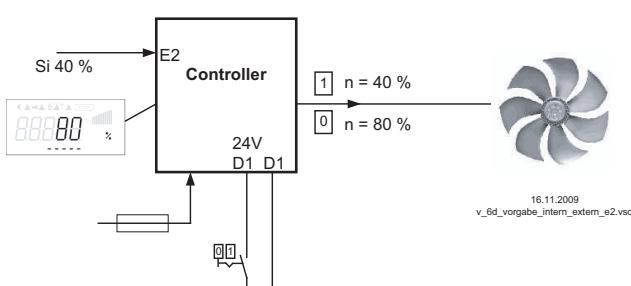


Operation with “Set Intern2” is signalized by the moon symbol for reduced operation.

### 9.10.2.7 Intern / Extern Function [6D]

**Switch over between Set Intern and Set Extern** (for mode speed controller 1.01). “Set extern1” under settings must be programmed to “OFF”.

Contact e.g. at digital input “Digital In 1” (depending on device type at terminals “D1” - “D1” or “D1” - “24 V”).



Si Signal

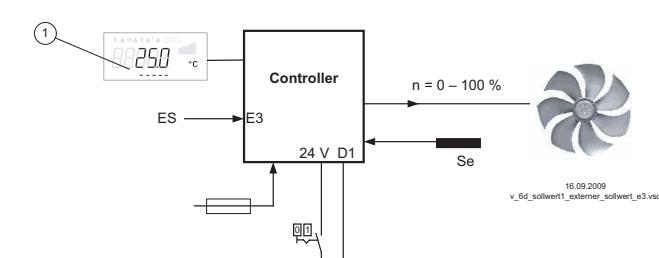
1 Setting “Set Intern1” (depending on device type in: %, Hz, rpm)

- “D1 Inverting” = “OFF”: “Set Intern1” at opened contact / “Setting Extern” at closed contact.
- “D1 Inverting” = “ON”: “Set Intern1” at closed contact / “Set Extern” at opened contact.

### “Setpoint1” / “external Setpoint” (modes 2.01)

Under Base setup “E3 function” programmed to function **[1E]** for “external setpoint” .

Contact at digital input e. g. “Digital In 1” = “D1” - “24 V”



1 Setting “Setpoint1”

ES External Setpoint e.g. 5 V  $\triangleq$  23.8°C

Se Sensor

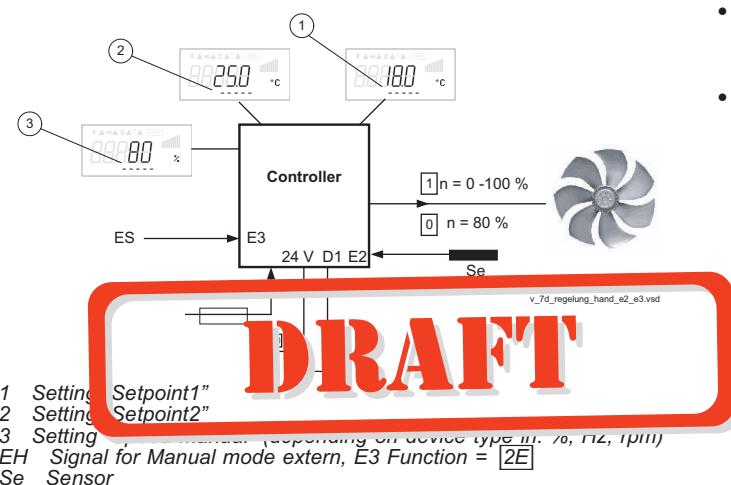
- “D1 Inverting” = “ON”: Setting at the unit at opened contact / Signal Extern at closed contact
- “D1 Inverting” = “OFF”: Setting at the unit at closed contact / Signal Extern at opened contact

### 9.10.2.8 Automatic control / speed manual, Function [7D] (mode 2.01)

Switch over between automatic control to set target value (depending on the activation: "Setpoint1", "Setpoint2") and the default for "manual operation" set at the device.

If for Analog In 2 "E3 function" is programmed to [2E] switch over between "Setpoint1" or "Setpoint2" and external manual operation. With activated manual mode the display constantly changes between "actual value" and value for "manual mode".

Contact at digital input e.g. "Digital In 1"



- "D1 Inverting" = "OFF" Automatic control at opened contact / manual operation at closed contact.
- "D1 Inverting" = "ON": Automatic control at closed contact / manual operation at opened contact.

### 9.10.2.9 Reverse action of control function (2.01), Function [8D]

Switchover between: Increasing modulation during increasing actual-value and increasing modulation during sinking actual-value.

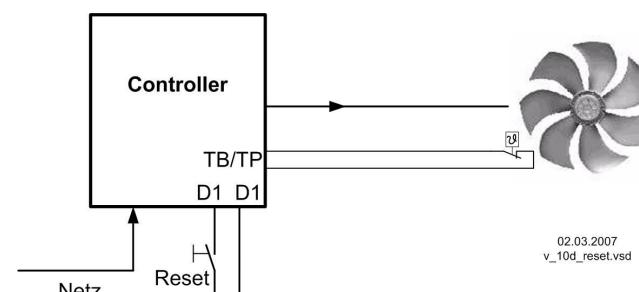
The factory presets for the "Control function" are dependent on the selected mode of operation (Controller Setup - reverse operation of the control function).

When switching over via a digital input, the device works with the opposite function than the one set there!



### 9.10.2.10 Reset, Function [10D]

Complete re-start of the device.



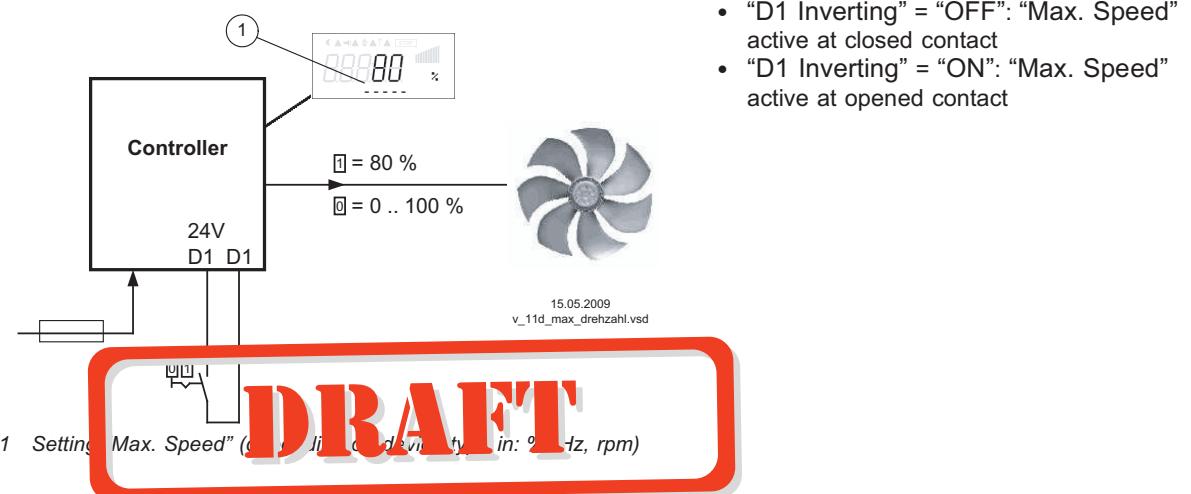
Contact at digital input e.g. "Digital In 1"

- For "D1 Inverting" = "OFF" both terminals "D1"- "24 V" in normal operation interrupted. Reset after fault by short close.(For "Inverting" = "ON" reverse function).

### 9.10.2.11 Setting Max. Speed ON / OFF function [11D]

The value for "Max Speed" adjusted in menu "Settings", is activated over a digital input. I.e. the unit works independently of the controller function firm with this value.

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").



### 9.10.2.12 Direction of rotation, Function [13D]

Switch over "clockwise" rotation and "counterclockwise" rotation. When switching over via a digital input, the device works with the opposite function than the one set in motorsetup.



#### Information

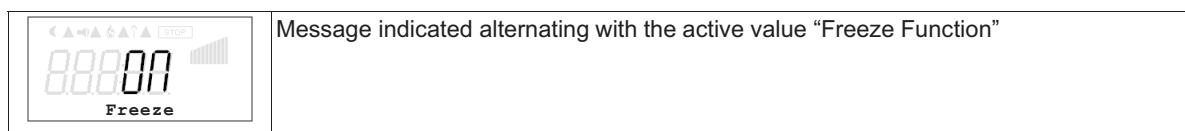
If the rotary direction is reversed with an available modulation, it is initially reduced to "0" (disconnected) and subsequently increased back to the default value.

**Contact e.g. by digital input "Digital In 1" for factory setting "clockwise rotation."**

- "D1 Invertierung" = "OFF": "Clockwise" at opened contact / "Counterclockwise" at closed contact.
- "D1 Invertierung" = "ON": "Counterclockwise" at opened contact / "Clockwise" at closed contact.

### 9.10.2.13 "Freeze function" = maintain momentary modulation value, Function [14D]

The device continues to work so long independently of the controller function with the momentary value of the modulation and / or speed as activated over the digital input.



Contact at digital input e.g. "Digital In 1"

"D1 Inverting" = "OFF": "Freeze function" at closed contact activ

"D1 Inverting" = "ON": "Freeze function" at opened contact activ

### 9.10.3 Configuration of analog inputs “E1” and “E3”

#### 9.10.3.1 Signal adaption E2 and E3

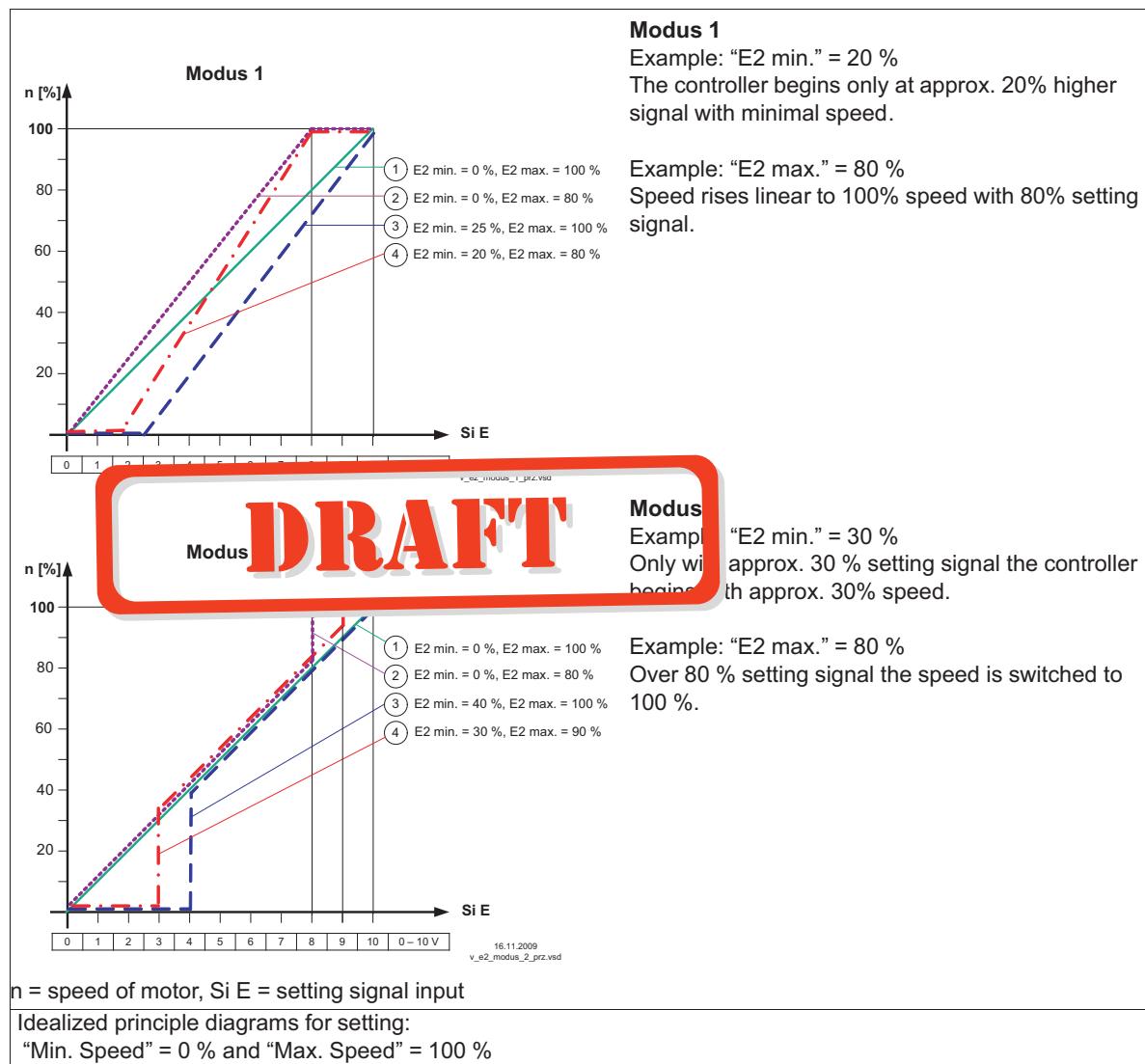
If required, an adaptation of the specification signal / speed characteristic curve is possible



##### Information

These settings are mostly practical for the operating mode **1.01** with rotational speed specification over an external signal. In operating modes (as of 2.01) this setting is not suited for influencing the regulation process.

	<b>E2 Mode</b> <input type="checkbox"/> 0 = E2 min. / E2 max. without function (factory setting) <input checked="" type="checkbox"/> 1 = Offset / turn <input type="checkbox"/> 2 = signal range
	<b>E2 min.</b> Setting range: 0 - 100 % Factory setting: 0 %
 <b>DRAFT</b>	<b>E2 max.</b> Setting range: 0 - 100 % Factory setting: 100 %
	<b>E3 Mode</b> <input type="checkbox"/> 0 = E2 min. / E2 max. without function (factory setting) <input checked="" type="checkbox"/> 1 = Offset / turn <input type="checkbox"/> 2 = signal range
	<b>E3 min.</b> Setting range: 0 - 100 % Factory setting: 0 %
	<b>E3 max.</b> Setting range: 0 - 100 % Factory setting: 100 %

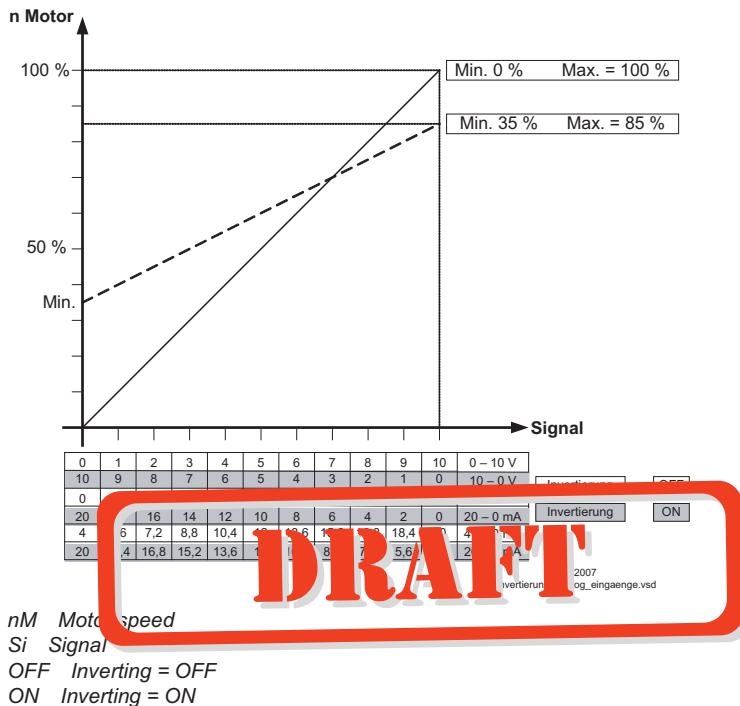
**Example for Mode “1.01” with speed setting signal 0 - 10 V****9.10.3.2 Inverting analog inputs “E2” / “E3”**

After programming the signal or sensor type, an inversion of the inputs can be carried out.



Factory setting for Inverting inputs = “OFF” (if input activated) (signal: 0 - 10 V, 0 - 20 mA, 4 - 20 mA).  
For activation using inverted default signals or sensors with inverted output signals proportional to the measurement range, switch inverting to “ON” (Signal: 10 - 0 V, 20 - 0 mA, 20 - 4 mA).

Example: mode **1.01** speed controller, setting by external signal

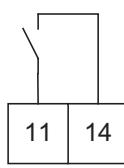


#### 9.10.4 Function and inverting for relay outputs “K1”

	Various functions can be allocated to the relay outputs “K1”. This is preset at the factory for fault indication.
	The relay inversion “K1” is set at the factory to “OFF” (when a function is programming). Switch to “ON” for inversion (switch-time response depends on the allocated function). Fundamentally, the relay can only become operative if the electronic's voltage supply is functioning. At least 2 current phases must be present!

Function	Description
<b>OFF</b>	No function Relays remain always de-energized
<b>1K</b>	Operating indication. Operation without fault, reports enable “OFF”
<b>2K</b>	Fault indication (factory setting for “K1”, non inverting). Energized for operation without fault, for enable “OFF” not energized. De-energized at line, motor and controller fault, Sensor fault dependent on programming, external fault at digital input.
<b>3K</b>	External fault separate with message at digital input (factory setting if terminals bridged)
<b>4K</b>	Limit modulation Over or falling below limits for modulation
<b>5K</b>	Limit “E2” When over or falling below limits for input signal “E2”
<b>6K</b>	Limit “E3” When over or falling below limits for input signal “E3”
<b>For modes as controller higher 2.01</b>	
<b>7K</b>	Setpoint Offset Deviation between actual value and setpoint to high
<b>8K</b>	Switching on second group
<b>For modes as temperature controller with additional functions 2.03</b>	

<b>9K</b>	Heating function Switch ON point: temperature = Setpoint +/- Offset Switch OFF point: Temperature around hysteresis over switch ON point
<b>10K</b>	Cooling function Switch ON point: temperature = Setpoint +/- Offset Switch OFF point: Temperature around hysteresis below switch ON point



**K1**  
1 = energized, terminals 11 - 14 bridged  
0 = de-energized 11 - 14 not bridged

17.09.2009  
v\_relays\_k1\_11\_14.vsd

K1

Function		Status controller		K1	
				1 = energized 0 = de-energized	
				Inverting	
OFF	ON				
<b>1K</b>	Operation without fault, line supply okay			1	0
<b>2K</b>	Fault with indication by relay			0	1
<b>3K</b>	Ext. Fault at digital input for external fault			1	0
<b>4K</b>	Over or falling below limits for modulation			1	0
<b>5K</b>	over or falling below limits for input signal "E2"			1	0
<b>6K</b>	over or falling below limits for input signal "E3"			1	0
<b>7K</b>	setpoint deviation to high			1	0

### 9.10.5 Networking via MODBUS

It is possible to network several devices with each other. The device uses the MODBUS-RTU as the protocol for the RS-485 interface.

The device address (Device-ID) is factory set to the highest available MODBUS address: 247. This address is reserved for operation with an external terminal model AXG.. and should not be occupied with anything else.

	<b>Bus Address</b> The addresses of the individual units must be continuously numbered beginning with "1". No address may be allocated twice. MODBUS address adjustable from 1-247. Address 247 = preprogrammed for an external terminal.
	<b>Addressing</b> Switch addressing to "ON" before setting "address".

### Reading and writing parameters

The device supports reading and writing processes for MODBUS Holding Registers. The start address is 0; the number of registers depends on the device. If the allowable start address or number is exceeded, the device answers with an exception code. The description of the register is device dependent and can be requested from service for the device/version concerned.

### 9.11 Limits

	<b>Menu group Limits</b>
--	--------------------------

### 9.11.1 Limit indication depending on modulation

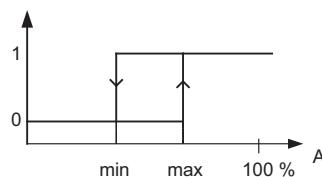
	Following functions can be allocated to the limit indication
OFF	without function
1L	Indication with the centralized fault of a programmed relay (IO allocation Function [2K]). Warning symbol in display, "AL" code in events memory.
2L	Is merely displayed in the events menu as message "msg".
In the IO setup, a separate relay can be allocated independent of these settings.	
	If the modulation exceeds the set "Level max" value, this is reported until the set value "Level min" has been undercut. The indication is delayed by the time set in "Display delay".
	The relay "Level 1 Delay" is switched if the modulation exceeds "Level max." up to indication by relay and alarm symbol. Switching range = 1 sec. (factory setting: 2 sec.)

DRAFT

#### Example indication by relay "K1":

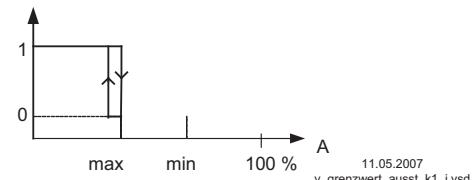
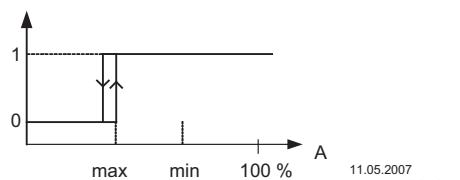
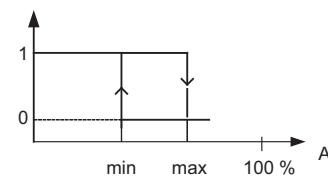
##### not inverted

IO Setup: K1 Function = 4K  
IO Setup: K1 Inverting = OFF



##### Inverting

IO Setup: K1 Function = 4K  
IO Setup: K1 Inverting = OFF

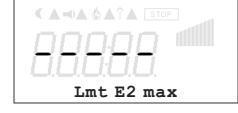


A Modulation

If "Level min." is higher than "Level max.", the "Level max." switching point is without hysteresis.

### 9.11.2 Limit indication depending on setting or sensor signal

	Following functions can be allocated to the limit indication
OFF	without function
1L	Indication with the centralized fault of a programmed relay (IO allocation Function [2K]). Warning symbol in display, "AL" code in events memory.
2L	Is merely displayed in the events menu as message "msg".
In the IO setup, a separate relay can be allocated independent of these settings.	

 	<p>Both values for E2 ("E2 min" and "E2 max") can be set independent of each other and act on a relay together if correspondingly programmed. If a function is activated or if a relay is allocated, both settings ("min" and "max") are initially at "OFF". Work can be carried out with one as well as with both limit indicators.</p> <p>The same setting applies to "E3 Min." and "E3 Max.", described below for "E2".</p> <p><b>Undercutting the signal ("E2 min").</b></p> <p>If the signal undercutts the set value "E2 min", this is reported until the set value (plus adjustable hysteresis) has been exceeded once again.</p> <p><b>Exceeding the signal ("E2 max").</b></p> <p>If the signal exceeds the set value "E2 max", this is reported until the set value (minus hysteresis) has been undercut once again.</p>
	<p><b>E2 Hysteresis</b></p> <p>Hysteresis adjustment in the unit of measure of the programmed input signal.</p>
	<p><b>E2 Delay</b></p> <p>Time delay adjustment "E2 Delay" for limit indication by relay and alarm symbol.</p> <p>Setting range: 0 - 120 sec</p>

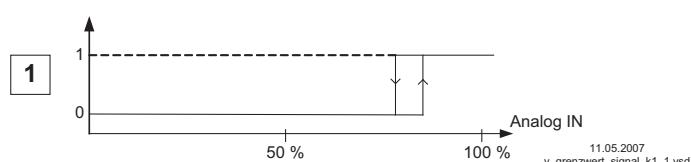
DRAFT



#### Information

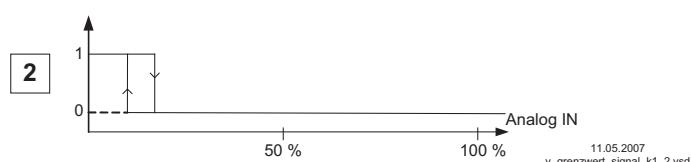
Always adjust the value for the maximum input signal higher than the value for the minimum input signal!  
E2 Max. > E2 Min.

#### Example for a limit indication of default signal or sensor signal to "Analog In 1"



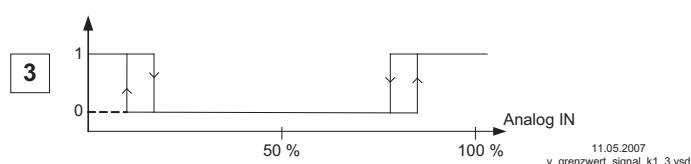
**Settings:**

- E2 Max.: 80 %
- E2 Min.: OFF
- switching hysteresis 5 % (from 100 %)



**Settings:**

- E2 Min.: 20 %
- E2 Max.: OFF
- switching hysteresis 5 % (from 100 %)



**Settings:**

- E2 Min.: 20 %
- E2 Max.: 80 %
- switching hysteresis 5 % (from 100 %)

Terminal "E2" and "GND" alarm via relay "K1" (non-inverted) IO Setup → K1 function: **[5 K]** = limit indicators

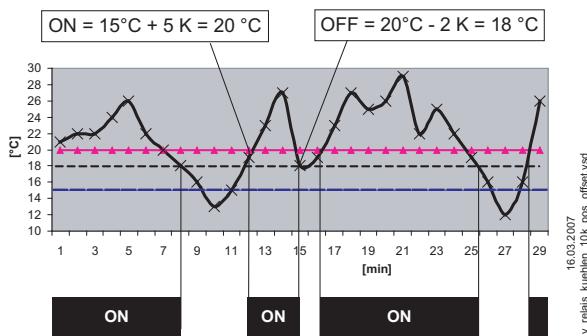
### 9.11.3 Limit indication depending on (offset) to Setpoint

In operating modes as a controller (via 2.01), two limit indicators can be carried out based on the set target value (Setpoint) and measured actual value (on E2).

	<p>Following functions can be allocated to the limit indication</p> <table border="1"> <tr> <td>OFF</td><td>without function</td></tr> <tr> <td>1L</td><td>Indication with the centralized fault of a programmed relay (IO allocation function 2K) warning symbol in display, "AL" code in events memory.</td></tr> <tr> <td>2L</td><td>Is merely displayed in the events menu as message "msg".</td></tr> </table> <p>In the IO setup, a separate relay can be allocated independent of these settings.</p>	OFF	without function	1L	Indication with the centralized fault of a programmed relay (IO allocation function 2K) warning symbol in display, "AL" code in events memory.	2L	Is merely displayed in the events menu as message "msg".
OFF	without function						
1L	Indication with the centralized fault of a programmed relay (IO allocation function 2K) warning symbol in display, "AL" code in events memory.						
2L	Is merely displayed in the events menu as message "msg".						
	<p><b>Offset 1, Offset 2</b></p> <p>Both values for Offset 1 and Offset 2 can be set independent of each other and act on a relay together if correspondingly programmed. If a function is activated or if a relay is allocated both settings (Offset 1 and Offset 2) are initially at "OFF".</p> <p>Work can be carried out with one as well as with both limit indicators.</p>						
	<p>"Offset 2" for alarm in case of an exceeding of the max. deviation between actual and target</p> <p>Switch ON point: actual value = Setpoint +/- offset</p> <p>Switch OFF point: Actual value by hysteresis under the switch-on point</p> <p><b>DRAFT</b></p>						
	<p><b>Offset Hysteresis</b></p> <p>Hysteresis switch-on point: In temperature regulation + / - 10 K, otherwise sensors 10 % of measurement range</p>						
	<p><b>Offset Delay</b></p> <p>Time delay until indication through relay and alarm symbol.</p> <p>Setting range: 0 - 120 sec.</p> <p>Factory setting: 2 sec.</p>						

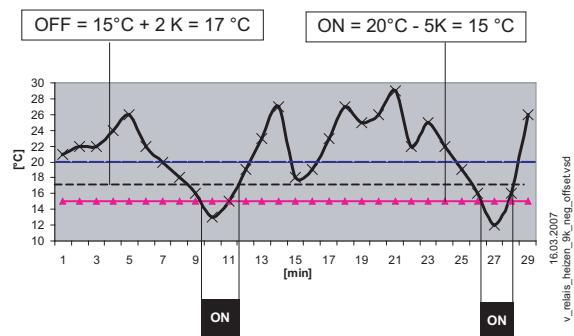
Example for temperature regulation; for other modes of operation settings in corresponding sensor unit.

#### Offset 1 for alarm during exceeding



Example: Setpoint 15.0 °C, Offset +5.0 K, Hysteresis 2.0 K

#### Offset 2 for alarm during undercutting



Example: Setpoint 15.0 °C, Offset -5.0 K, Hysteresis 2.0 K

## 9.12 Motor Setup



Menu group Motorsetup

### 9.12.1 Setting for Rampup time and Rampdown time

By separate menus for Rampup time and Rampdown time an adjustment is possible to individual system conditions.

This function is switched behind the actual controller function.

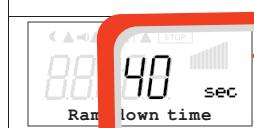


#### Rampup time

Time setting in which the automatic controller output from 0 % to 100 % rises.

Setting range: 2...250 sec.

Factory setting depending on motor

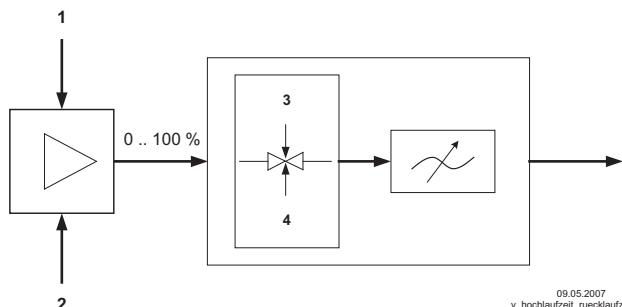


#### Rampdown time

The setting in this menu the automatic controller output from 100 % to 0 % reduces.

Setting range: 2...250 sec.

Factory setting depending on motor



1 external Signal

2 Setting

3 Rampup time

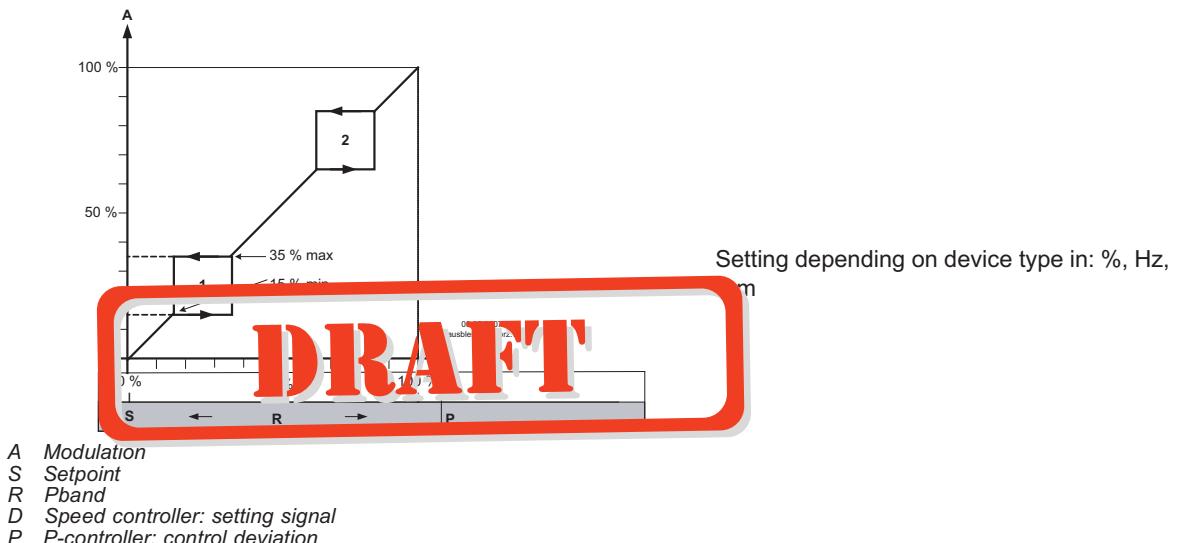
4 Rampdown time

### 9.12.2 Suppression of speeds

Suppression of up to three speed ranges.

Under certain circumstances, it is possible to prevent disturbing noises that can arise at certain speeds due to resonances.

#### Example for suppression of 2 ranges (Idealized principle diagram)



	→ Factory setting no suppression active = "OFF"	→	
	→ Setting for "Range1 min."	→	
	→ Setting for "Range1 max."	→	
	→ Identical procedures for Suppression2 and Suppression3, as far as desired	→	etc.

## 10 Menu tables

### 10.1 Menus of operating modes

Mode	1.01	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting
Parameter	Factory setting									
<b>Start</b>										
PIN input	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Language	GB	GB	GB	GB	GB	GB	GB	GB	GB	
Reset	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Mode	1.01	2.01 2.03	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	
ECblue Premium	4.00	4.00	4.00	4.00	4.00	4.00	4.00	4.00	4.00	
Basic Version	10.01	10.01	10.01	10.01	10.01	10.01	10.01	10.01	10.01	
SN:	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	1727393- 6FF33	
<b>Info</b>										
Actual value E2-E3				-2.4 °C						
Control value (only 2.04, 3.03, 3.04)		30.0 °C				12.0 bar 22.6 °C				
E2 Actual		30.0 °C	30.0 °C	30.0 °C	10.0 bar 9.5 °C	10.0 bar 9.5 °C	88.7 Pa	712 m³/h	0.45 m/s	
E3 Actual (only 2.04, 2.05, 3.03, 3.04, 4.02, 4.03, 5.02)		30.0 °C		30.0 °C		10.0 bar 9.5 °C	21.0 °C	21.0 °C		
Setpoint1		20.0 °C	5.0 °C	0.0 °C	12.0 bar 35.0°C	12.0 bar 35.0°C	100 Pa	530 m³/h	0.50 m/s	
Setpoint control (only 4.02, 4.03, 5.02)							100 Pa	530 m³/h		
Speed	0 rpm	0 rpm	0 rpm	0 rpm	0 rpm	0 rpm	0 rpm	0 rpm	0 rpm	
Motor current	0.0 A	0.0 A	0.0 A	0.0 A	0.0 A	0.0 A	0.0 A	0.0 A	0.0 A	
Set external1	0 rpm									
Msc0		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
<b>Setting</b>										
Set Intern1	200 rpm									
Set Intern2	-----									
Setpoint1		20.0 °C	5.0 °C	0.0 °C	12.0 bar 35.0°C	12.0 bar 35.0°C	100 Pa	530 m³/h	0.50 m/s	
Setpoint2	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Pband		5.0 K	20.0 K	5.0 K	5.0 bar 7.0 °C	5.0 bar 7.0 °C	100 Pa	530 m³/h	0.50 m/s	
Min. Speed *	0 rpm	0 rpm	0 rpm	0 rpm	0 %	0 %	0 rpm	0 rpm	0 rpm	
Max. Speed *	1800 rpm	1800 rpm	1800 rpm	1800 rpm	1800 rpm	1800 rpm	1800 rpm	1800 rpm	1800 rpm	
Set external1	ON									
Manual mode		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Speed man.		200 rpm	200 rpm	200 rpm	200 rpm	200 rpm	200 rpm	200 rpm	200 rpm	

Mode	<b>1.01</b>	<b>2.01</b> <b>2.03</b> <b>2.04</b>	<b>2.02</b>	<b>2.05</b>	<b>3.01</b> <b>3.02</b>	<b>3.03</b> <b>3.04</b>	<b>4.01</b> <b>4.02</b> <b>4.03</b>	<b>5.01</b> <b>5.02</b>	<b>6.01</b>	User Setting
Parameter	Factory setting									
Offset AnalogOut		2.03 = 0.0 K								
Pband AnalogOut		2.03 = 2.0 K								
Min. AnalogOut		2.03 = 0 %								
Max. AnalogOut		2.03 = 100 %								
OffsetDigitalOut		2.03 = -1.0 K								
Hyst.DigitalOut		2.03 = 1.0 K								
Alarm Minimum		2.03 = 0.0 °C								
Alarm Maximum		2.03 = 40.0 °C								
T-Band SA							4.02 + 4.03 = 30.0 K	5.02 = 30.0 K		
T-Start SA							4.02 + 4.03 = 15.0 °C	5.02 = 15.0 °C		
P-Min SA							4.02 + 4.03 = 70.0 Pa	5.02 = 70.0 m³/h		
<b>Events</b>										
<b>Base setup</b>										
Mode	<b>1.01</b>	<b>2.01</b> <b>2.03</b> <b>2.04</b>	<b>2.02</b>	<b>2.05</b>	<b>3.01</b> <b>3.02</b>	<b>3.03</b> <b>3.04</b>	<b>4.01</b> <b>4.02</b> <b>4.03</b>	<b>5.01</b> <b>5.02</b>	<b>6.01</b>	
E2 Analog In	0 - 10 V	KTY	KTY	KTY	0-30 MBG	0-30 MBG	DSG200	DSG200	0-1 MAL	
E2 Refrigerant (only 3.02 and 3.04)					R503	R503				
E2 K-Factor								75		
E2 Min.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
E2 Max.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
E2 Decimals	-----	-----	-----	-----	-----	-----	-----	-----	-----	
E2 Unit	-----	-----	-----	-----	-----	-----	-----	-----	-----	
E2 Offset		0.0 K	0.0 K	0.0 K	0.0 bar 0.0 K	0.0 bar 0.0 K	0.0 Pa	0.0 Pa	0.0 m/s	
E3 Function	OFF	OFF 2.04 = 4E	OFF	5E	OFF	4E	4.02 + 4.03 = 6E	5.02 = 6E	OFF	
E3 Analog In	-----	-----			-----	0-30 MBG	4.02 = TF 4.03 = Bus	5.02 = TF	OFF	
E3 Refrigerant (only 3.04)		-----				R503				
E3 K-Factor								75		

Mode	<b>1.01</b>	<b>2.01</b> <b>2.03</b> <b>2.04</b>	<b>2.02</b>	<b>2.05</b>	<b>3.01</b> <b>3.02</b>	<b>3.03</b> <b>3.04</b>	<b>4.01</b> <b>4.02</b> <b>4.03</b>	<b>5.01</b> <b>5.02</b>	<b>6.01</b>	User Setting
Parameter	Factory setting									
E3 Min.		-----			-----	-----	4.03 = - 35.0 °C	-----	-----	
E3 Max.		-----			-----	-----	4.03 = 65.0 °C	-----	-----	
E3 Decimals		-----			-----	-----	-----	-----	-----	
E3 Unit		-----			-----	-----	4.03 = °C	-----	-----	
E3 Offset		-----			-----	0.0 bar 0.0 K	4.02 + 4.03 = 0.0 K	5.02 = 0.0 K	-----	
<b>Controller Setup</b>										
PIN Protection	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Set protection	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Save User Setup	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Alarm sensors		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Limit	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Min. speed cut off		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Group 2 ON value	-----	-----	-----	-----	-----	-----	-----	-----	-----	
nmin at Group2	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Val > Set=n+		ON	ON	ON	ON	ON	OFF	OFF	OFF	
Type of control		P	P	P	P	P	Pid	Pid	Pid	
KP		50 %	50 %	50 %	50 %	50 %	50 %	50 %	50 %	
KI		50 %	50 %	50 %	50 %	50 %	50 %	50 %	50 %	
KD		50 %	50 %	50 %	50 %	50 %	50 %	50 %	50 %	
TI		0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	
LED Mode	ON	ON	ON	ON	ON	ON	ON	ON	ON	
<b>IO Setup</b>										
A Function	1A	1A (2.03 = 6A)	1A	1A	1A	1A	1A	1A	1A	
A min.	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	
A max.	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	
A Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
D1 Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF 4.03 = 1D	OFF	OFF	
D1 Inverting	-----	-----	-----	-----	-----	-----	----- 4.03 = OFF	-----	-----	
D1 Busmode	-----	-----	-----	-----	-----	-----	----- 4.03 = ON	-----	-----	
D2 Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF 4.03 = 5D	OFF	OFF	
D2 Inverting	-----	-----	-----	-----	-----	-----	----- 4.03 = OFF	-----	-----	
D2 Busmode	-----	-----	-----	-----	-----	-----	----- 4.03 = ON	-----	-----	

Mode	<b>1.01</b>	<b>2.01</b> <b>2.03</b> <b>2.04</b>	<b>2.02</b>	<b>2.05</b>	<b>3.01</b> <b>3.02</b>	<b>3.03</b> <b>3.04</b>	<b>4.01</b> <b>4.02</b> <b>4.03</b>	<b>5.01</b> <b>5.02</b>	<b>6.01</b>	User Setting
Parameter	Factory setting									
E2 Mode	0	0	0	0	0	0	0	0	0	
E2 min.	0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	
E2 max.	100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	
E2 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
E3 Mode	0	0	0	0	0	0	0	0	0	
E3 min.	0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	
E3 max.	100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	
E3 Inverting	-----	-----	-----	-----	-----	-----	-----	-----	-----	
K1 Function	1K	1K (2.03 = 2K)	1K	1K	1K	1K	1K	1K	1K	
K1 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Bus Address	2	247	247	247	247	247	247	247	247	
Addressing	C/F	OFF	OFF	C/F	C/F	OFF	OFF	OFF	OFF	
<b>DRAFT</b>										
Level Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Level min.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Level max.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Level Delay	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Lmt E2 Function	OFF	OFF (2.03 = 1L)	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Lmt E2 min.	-----	2.03 = 0.0 °C	-----	-----	-----	-----	-----	-----	-----	
Lmt E2 max.	-----	2.03 = 40.0 °C	-----	-----	-----	-----	-----	-----	-----	
Lmt E2 Hyst.	-----	2.03 = 1.0 K	-----	-----	-----	-----	-----	-----	-----	
Lmt E2 Del.	-----	2.03 = 2 sec.	-----	-----	-----	-----	-----	-----	-----	
Lmt E3 Function	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Lmt E3 min.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Lmt E3 max.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
GW E3 Hysteresis	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Lmt E3 Del.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Offset Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Offset 1	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Offset 2	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Offset Hyst.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Offset Del.	-----	-----	-----	-----	-----	-----	-----	-----	-----	
<b>Motor Setup</b>										
Rampup time*	10 sec	10 sec	10 sec	10 sec	10 sec	10 sec	10 sec	10 sec	10 sec	
Rampdown time*	2 sec	2 sec	2 sec	2 sec	2 sec	2 sec	2 sec	2 sec	2 sec	
Suppression1 *	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Range1 min. *	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Range1 max. *	-----	-----	-----	-----	-----	-----	-----	-----	-----	

Mode	<b>1.01</b>	<b>2.01</b> <b>2.03</b> <b>2.04</b>	<b>2.02</b>	<b>2.05</b>	<b>3.01</b> <b>3.02</b>	<b>3.03</b> <b>3.04</b>	<b>4.01</b> <b>4.02</b> <b>4.03</b>	<b>5.01</b> <b>5.02</b>	<b>6.01</b>	User Setting
Parameter	Factory setting									
Suppression2 *	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Range2 min. *	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Range2 max. *	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Suppression3 *	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Range3 min. *	-----	-----	-----	-----	-----	-----	-----	-----	-----	
Range3 max. *	-----	-----	-----	-----	-----	-----	-----	-----	-----	
<b>Diagnostic</b>										
OTC	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	
OTM	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	000056:- 46:13	
DC-Voltage	415 V	415 V	415 V	415 V	415 V	415 V	415 V	415 V	415 V	
Line voltage	240 V	240 V	240 V	240 V	240 V	240 V	240 V	240 V	240 V	
Heatsink	28.8 °C	28.8 °C	28.8 °C	28.8 °C	28.8 °C	28.8 °C	28.8 °C	28.8 °C	28.8 °C	
Capacitor	29.5	29.5	29.5	29.5	29.5	29.5	29.5	29.5	29.5	
E2-KTY	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	
E2-Current	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	
E2-Voltage	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	
E3-KTY	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	
E3-Current	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	9.0 mA	
E3-Voltage	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	4.0 V	
D1	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
D2	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
K1	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
* Factory setting depending on motor, changed settings are not put back on activation of factory setting!										

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## 10.2 Possible allocation of the IOs, PINs

### Analog output A

Function	Description Function A
<b>OFF</b>	without function
<b>1A</b>	Constant voltage +10 V
<b>2A</b>	proportional level control
<b>3A</b>	proportional input E2
<b>4A</b>	proportional input E3
<b>5A</b>	Group control
<b>6A</b>	only 2.03 Cooling function
<b>7A</b>	only 2.03 Heating function
<b>9A</b>	proportionally to speed

**Digital inputs D1 + D2**

<b>Function</b>	<b>Description Function D1 + D2</b>
<b>OFF</b>	No function
<b>1D</b>	Enable (remote control) "ON" / "OFF"
<b>2D</b>	External error
<b>3D</b>	"Limit" ON / OFF
<b>4D</b>	Switch over "E1" / "E3"
	<b>For mode speed controller 1.01</b>
<b>5D</b>	Switch over "Setpoint Intern1" / "Setpoint Intern2"
<b>6D</b>	Switch over "Intern" / "Extern"
	<b>For modes as controller from 2.01</b>
<b>5D</b>	Switch over "Setpoint1" / "Setpoint2"
<b>6D</b>	Switch over Intern / Extern
<b>7D</b>	Switch over automatic / manual controlled manual
<b>8D</b>	Switch over function (e.g. heating" / "cooling")
<b>10D</b>	Reset
<b>11D</b>	Setting Max. Speed "ON" / "OFF"
<b>13D</b>	Switch over direction of rotation "right" / "left"
<b>14D</b>	"Freeze function" = maintain momentary modulation value

**Analog input E2 / E3 (IO Setup)**

<b>Mode</b>	<b>Description E2 Modus</b>
<b>0</b>	E2 min. / E2 max. without function (factory setting)
<b>1</b>	Offset / turn
<b>2</b>	Signal range

**Analog input E3 (Base setup)**

<b>Function</b>	<b>Description Function E3</b>
<b>OFF</b>	No function
<b>1E</b>	external Setpoint
<b>2E</b>	external Manual mode (from <b>2.01</b> )
<b>3E</b>	Sensor average to E2 (from <b>2.01</b> )
<b>4E</b>	Sensor comparison to E2
<b>5E</b>	Sensor difference to E2 (from <b>2.01</b> )
<b>6E</b>	Sensor for Setpoint (from <b>2.01</b> )
<b>7E</b>	Measurement value (from <b>2.01</b> )

**Digital output K1**

<b>Function</b>	<b>Description Function K1 (not inverted)</b>
<b>OFF</b>	No function Relay remains always, i.e. de-energized
<b>1K</b>	Operating indication Operation without fault, reports enable "OFF"
<b>2K</b>	Fault indication Energized for operation without fault, for enable "OFF" not energized. De-energized at line, motor and controller fault, Sensor fault dependent on programming, external fault at digital input.
<b>3K</b>	External fault separate with message at digital input (factory setting if terminals bridged)
<b>4K</b>	Limit modulation Over or falling below limits for modulation
<b>5K</b>	Limit "E2" When over or falling below limits for input signal "E2"
<b>6</b>	Limit "E3" When over or falling below limits for input signal "E3"
<b>7</b>	Setpoint Offset Deviation between actual value and setpoint to high
<b>8K</b>	Group control Switching on fans depending on modulation
	<b>For modes as temperature controller with additional functions <b>2.03</b></b>
<b>9K</b>	Heating function Switch ON point: temperature = Setpoint +/- Offset Switch OFF point: Temperature around hysteresis over switch ON point
<b>10K</b>	Cooling function Switch ON point: temperature = Setpoint +/- Offset Switch OFF point: Temperature around hysteresis below switch ON point

**DRAFT****Limits GW E2, GW E3**

<b>Function</b>	<b>Description Function GW E2, GW E3</b>
<b>OFF</b>	without function
<b>1L</b>	Indication with the centralized fault of a programmed relay (IO allocation Function <b>[2K]</b> ). Warning symbol in display, "AL" code in events memory.
<b>2L</b>	Is merely displayed in the events menu as message "msg".

**PINs**

<b>PIN</b>	<b>Function</b>
<b>PIN 0010</b>	Opening service menu, if PIN-protection activated
<b>PIN 1234</b>	Opening "setting". if "set protection" = "ON" ( Controller Setup)
<b>PIN 9090</b>	Restore user setting
<b>PIN 9091</b>	Save user setting (corresponds function "Save user setup" = "ON"  Controller Setup)
<b>PIN 9095</b>	Restore factory setting = delivery status

## 11 Diagnostics menu

	The diagnostics menu supplies information about the momentary operating condition of the device.
	<b>O = Operation, T = Time, C = Controller</b> The time counting runs, as soon as mains voltage is connected (without fault). If events step on (Motor fault, External Error, etc.), the period of operation is stored at this time (☞ Events).
	<b>O = Operation, T = Time, M = Motor</b> The time counting runs as soon as a modulation of the controller is present
	<b>For 1 ~ types</b> ZK voltage constant at approx. 400 V The PFC (Power Factor Controller) makes it mostly independent of the mains voltage.
	<b>For 3 ~ types</b> In intermediate circuit voltage without load is the peak value of the input voltage. With three-phase supply network with 400 V an intermediate circuit voltage of ca. 565 V results. This voltage is also displayed here.
	Line voltage
	Display of DC-Choke or Capacitor temperature. In case of temperature increase above predetermined threshold value (from 90 °C) the output power will be automatic reduced.
	Display of DCLink Elco temperature. During impermissibly high levels (from 75 °C on), the output power is automatically reduced. At 90 °C switch off.
	Signal height at analog input E2 (Analog In 2)
	Signal height at analog input E3 (Analog In 3)

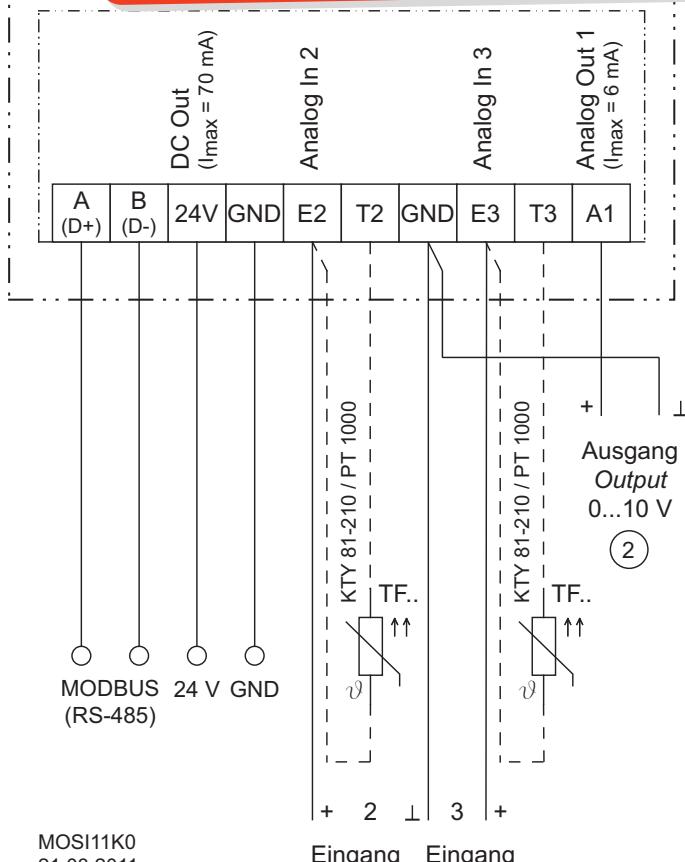
	Status digital input 1 (Digital In 1) OFF = terminals D1 - 24 V bridged ↔ ON = terminals D1 - 24 V not bridged
	Status digital input 2 (Digital In 2) OFF = terminals E1 - D24 bridged ↔ ON = terminals D2 (E2) - 24 V not bridged
	OFF = relay K1 de-energized: terminals 11 - 14 not bridged ON = relay K1 energized: terminals 11 - 14 bridged

## 12 Enclosure

### 12.1 Connection diagram

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AM-PREMIUM



MOSI11K0  
21.03.2011

(1)

Ausgang Output 0...10 V

(2)

Further connections ↗ connection diagram in operating instructions ECblue Basic

## 12.2 Index

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### 12.3 Manufacturer reference

Our products are manufactured in accordance with the relevant international regulations. If you have any questions concerning the use of our products or plan special uses, please contact:

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**Heinz-Ziehl-Straße**  
**74653 Künzelsau**  
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**Telefax: +49 (0) 7940 16-504**  
**[info@ziehl-abegg.de](mailto:info@ziehl-abegg.de)**  
**<http://www.ziehl-abegg.de>**

### 12.4 Service information

If you have any technical questions while commissioning or regarding malfunctions, please contact our V-STE support department for control systems - ventilation technology.

Our worldwide contacts are available in our subsidiaries for deliveries outside of Germany. [www.ziehl-abegg.com](http://www.ziehl-abegg.com)

If you make returns for inspections or repairs, we need certain information in order to facilitate focused troubleshooting and fault diagnosis. Please attach your repair tickets for this. It is provided to you after you have consulted our support department.

In addition, you can download it from our homepage. Document type: Repair ticket - Ventilation Technology - Topic: Control Engineering - Document type: General documents.

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