

# TEST REPORT

## 1. Applicant

**Name** : APROTECH CO.,LTD.  
**Address** : 201-23, Anyang-Dong, Manan-Gu, Anyang-Si, Gyeonggi-Do,  
430-817, Korea

## 2. Products

**Name** : Digital Enhanced Cordless Telephone (Punkt)  
**Model** : DP01H  
**Manufacturer** : APROTECH CO.,LTD.

## 3. Test Standard

: FCC 47 CFR § 2.1093

## 4. Test Method

: IEEE 1528, OET Bulletin 65, Supplement C(July 2001)

## 5. Test Result

: Positive

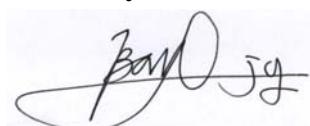
## 6. Date of Application

: August 22, 2011

## 7. Date of Issue

: September 19, 2011

### Tested by



Jong-Gon Ban

Telecommunication Center  
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### Approved by



Jeong-Min Kim

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Manager

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## 1. EQUIPMENT UNDER TEST

### 1.1 Applicant (Client)

Name	APROTECH CO.,LTD.
Address	201-23, Anyang-dong, Manan-gu, Anyang-Si, Gyeonggi-do, 430-817, Korea
Contact Person	JH Yang
Telephone No.	82 31 478 2687
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E-mail address	jhyang@aprotech.net
Manufacturer	APROTECH CO.,LTD.
Manufacturer Address	201-23, Anyang-dong, Manan-gu, Anyang-Si, Gyeonggi-do, 430-817, Korea

### 1.2 Description of Device

Name	Digital Enhanced Cordless Telephone (Punkt)
Model Name	DP01H
FCC ID	ZY2DP01H
Type of Modulation	UPCS (GFSK)
Maximum Conducted Power	19.13dBm
Tx Frequency Range	1921.536 MHz ~ 1928.448 MHz
Number of Channels	5
Duty Cycle	1:12
Antenna Type	Internal Antenna
Serial No.	Prototype
FCC Classification	Part 15 Unlicensed PCS portable Tx held to ear (PUE)
Hardware Version	Rev 1.1
Software Version	A030
<b>Maximum 1g Head SAR</b>	<b>0.054 mW/g</b>

## 2. INTRODUCTION

The FCC has adopted the guidelines for evaluating the environmental effects of radio frequency(RF) radiation in ET Docket 93-62 on Aug. 6, 1996 to protect the public and workers from the potential hazards of RF emission due to FCC-regulated portable devices.[1]

The safety limits used for the environmental evaluation measurements are based on the criteria published by American National Standards Institute (ANSI) for localized specific absorption rate (SAR) in IEEE/ANSI C95.1-1992 Standard for safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz. (c) 1992 by the Institute of Electrical and Electronics Engineers, Inc., New York, New York 10017.[2] The measurement procedure described in IEEE/ANSI C95.3-1992 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave[3] is used for guidance in measuring SAR due to the RF radiation exposure from the Equipment Under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the National Council on Radiation Protection and Measurements(NCRP) in Biological Effects and Exposure Criteria for Radiofrequency Electromagnetic Fields “NCRP Report No. 86 (c) NCRP, 1986, Bethesda, MD 20814.[4] SAR is a measure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

### 2.1 SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy ( $dU$ ) absorbed by (dissipated in) an incremental mass ( $dm$ ) contained in a volume element ( $dV$ ) of a given density( $p$ ). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body. (see Figure.1)

$$SAR = \frac{d}{dt} \left( \frac{dU}{dm} \right) = \frac{d}{dt} \left( \frac{dU}{pdv} \right)$$

**Figure 1. SAR Mathematical Equation**

SAR is expressed in units of Watts per Kilogram (W/kg).

$$SAR = \sigma E^2 / p$$

Where :

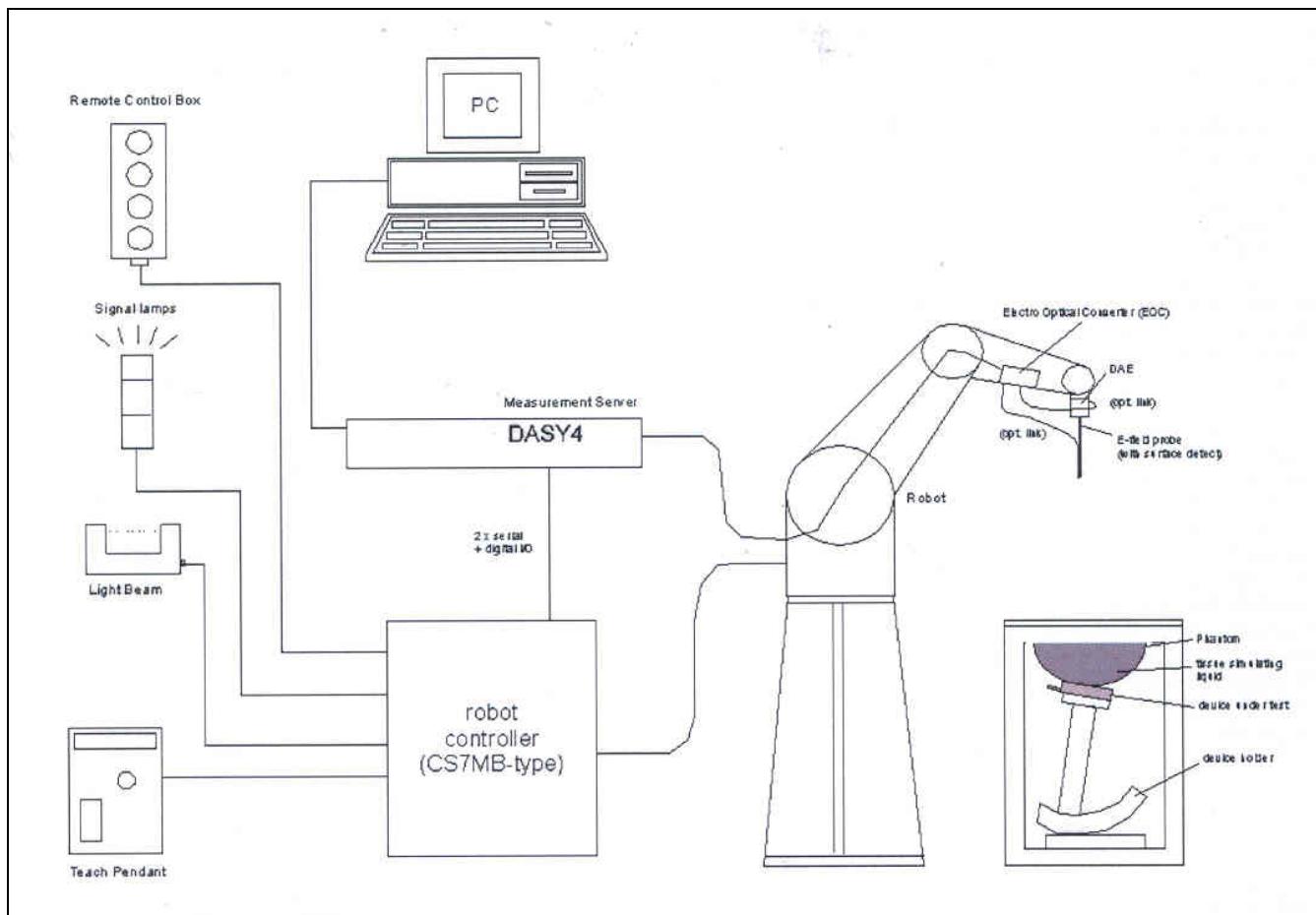
- $\sigma$  = conductivity of the tissue-simulant material (S/m)
- $p$  = mass density of the tissue-simulant material (kg/m<sup>3</sup>)
- $E$  = Total RMS electric field strength (V/m)

Note: The primary factors that control rate or energy absorption were found to be the wavelength of the incident field in realtions to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflectinf surfaces, and whether conductive contact is made by the organism with a ground plane.[4]

### **3. DESCRIPTION OF SAR MEASUREMENT SYSTEM**

#### **3.1 SAR Measurement System**

These measurements are performed using the DASY4 automated dosimetric assessment system. It is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, measurement server, Measurement computer, near-field probe, probe alignment sensor, and the SAM twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Fig.2).



**Figure 2. SAR Measurement System**

The DAE4 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in [5].

### 3.2 E-Field Probe Type and Performance

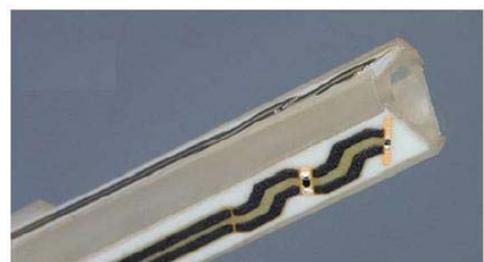
The SAR measurements were conducted with the dosimetric probe ET3DV6, (see Figure 4) designed in the classical triangular configuration [5] and optimised for dosimetric evaluation. The probe has been constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical mortifier line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches a maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2<sup>nd</sup> order fitting. The approach is stopped at reaching the maximum.



**Figure 3. Probe and DAE**

#### Probe Specifications

Construction	Symmetrical design with triangular core Built-in optical fiber for surface detection System Built-in shielding against static charges
Calibration	In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 450 MHz, 900 MHz and 1.8 GHz (accuracy 8%)
Frequency	10 MHz to > 6 GHz; Linearity: 0.2 dB (30 MHz to 3 GHz)
Directivity	0.2 dB in brain tissue (rotation around probe axis) 0.4 dB in brain tissue (rotation normal probe axis)
Dynamic Range Linearity	5 uW/g to > 100 mW/g; 0.2 dB
Surface Detection	0.2 mm repeatability in air and clear liquids Over diffuse reflecting surfaces.
Dimensions	Overall length: 330 mm Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application	General dissymmetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms



**Figure 4. ET3DV6 E-Field Probe**

### 3.3 Probe Calibration Process

#### Dosimetric Assessment Procedure

Each probe is calibrated according to a dosimetric assessment procedure described [6] with an accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [7] and found to be better than +/- 0.25dB. The sensitivity parameters (NornX, NornY, NornZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe is tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1 GHz, and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$\text{SAR} = C \frac{\Delta T}{\Delta t}$$

where:

$\Delta t$  = exposure time (30 seconds),

C = heat capacity of tissue (brain or muscle),

$\Delta T$  = temperature increase due to RF exposure.

SAR is proportional to  $\Delta T / \Delta t$ , the initial rate of tissue heating, before thermal diffusion takes place. Now it's possible to quantify the electric field in the simulated tissue by equating the thermally derived SAR to the E-field;

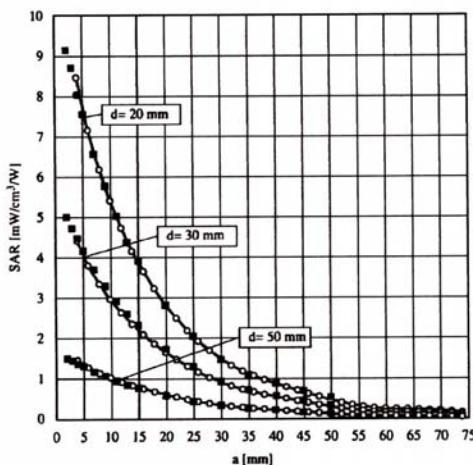


Figure B.1. E-Field and Temperature measurements at 900MHz[5]

$$\text{SAR} = \frac{|E|^2 \cdot \sigma}{\rho}$$

where:

$\sigma$  = simulated tissue conductivity,

$\rho$  = Tissue density (1.25 g/cm³ for brain tissue)

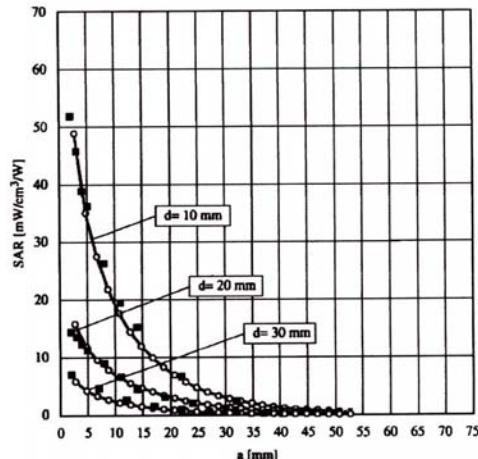


Figure B.2. E -field and temperature measurements at 1.8GHz[5]

### 3.4 Data Acquisition Electronics

The data acquisition electronics (DAE4) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. The input impedance of the DAE4 box is 200 Mohm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB. Transmission to the PC-card is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe-mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

### 3.5 Phantom Properties



The SAM Phantom is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users [9][10]. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot.

**Figure 5. SAM twin phantom**

Phantom Properties	Requirement for specific EUT	Measured
Depth of Phantom	> 150 mm	200 mm
Width of flat section	> 10 cm (Twice EUT Width)	20 cm
Length of flat section	> 26 cm (Twice EUT Length)	30 cm
Thickness of flat section	2 mm ± 0.2 mm	2.08 ~ 2.20 mm

**Table 1. Flat Section Properties of SAM Twin Phantom**

### 3.6 Device Holder for DASY4

In combination with the SAM Phantom V4.0, the Mounting Device(POM) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeatable positioned according to the FCC CENELEC specifications. The device holder can be locked at different phantom locations(left head, right head, flat phantom).

Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations [10]. To produce the Worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.



**Figure 4. Device Holder**

### 3.7 Brain & Muscle Simulating Mixture Characteristic

The brain and muscle mixtures consist of a viscous gel using hydroxethylcellulose (HEC) gelling agent and saline solution (see Table 2). Preservation with bacteriocide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The mixture characterizations used for the brain and muscle tissue simulating liquids are according to the data by C. Gabriel and G. Hartsgrove [11].

Ingredients	1900MHz Brain
Water	55.24%
Sugar	-
Salt	0.31%
DGBE	44.45%
Bacteriocide	-
HEC	-

Table 2. Composition of Tissue Equivalent Matter

### 4. System Verification

#### 4.1 Tissue Verification

The dielectric parameters of the brain and muscle simulating liquid were measured prior to SAR assessment using the HP85070D dielectric probe kit and Agilent 8753D Network Analyzer. The actual dielectric parameters are shown in the following table.

Freq. [MHz]	Liquid	Date	Liquid Temp [°C]	parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
1900	Head	Sept. 16 <sup>th</sup> 2011	22.0	ε <sub>r</sub>	40.0	39.2	-2.0	± 5
				σ	1.40	1.42	+1.4	± 5

Table 3. Measured Simulating Liquid Dielectric Values

The humidity and dielectric/ambient temperatures are recorded during the assessment of the tissue material dielectric parameters. The difference between the ambient temperature of the liquid during the dielectric measurement and the temperature during tests was less than |2|°C.

## 4.2 System Validation



**Figure 5. Validation setup**

Prior to the SAR assessment, the system validation kit was used to verify that the DASY4 was operating within its specifications. The validation dipoles are highly symmetric and matched at the centre frequency for the specified liquid and distance to the phantom. The accurate distance between the liquid surface and the dipole centre is achieved with a distance holder that snaps onto the dipole.

System validation is performed by feeding a known power level into a reference dipole, set at a known distance from the phantom. The measured SAR is compared to the theoretically derived level.

The reference SAR values are derived using a reference dipole and flat phantom suitable. The forward power into the reference dipole for each SAR validation was adjusted to 250 mW.

These reference SAR values are obtained from the IEEE Std. 1528 and are normalized to 1 W. The measured 1g(10g) SAR should be within 10 % of the expected target reference values shown in table 4 below.

System Validation Kit	Date	Tissue	Liquid Temp.(°C)	Ambient Temp.( °C)	Targeted SAR <sub>1g</sub> (mW/g)	Measured SAR 1 g (mW/g)	Deviation (%)
D1900V2 S/N:5d038	Sept. 16 <sup>th</sup> 2011	1900MHz Brain	22.0	21.0	39.7	40.0	+ 0.76

**Table 4 : Deviation from Reference Validation Values**

During the SAR measurement process the liquid depth was maintained to a level of a least 15 tolerance of  $\pm 0.2\text{cm}$ .

The following photo shows the depth of the liquid depth of the liquid maintained during the testing.



**Figure 6. Liquid Depth**

## **5. SAR MEASUREMENT PROCEDURE USING DASY4**

The SAR evaluation was performed with the SPEAG DASY4 system. A summary of the procedure follows ;

- a) A measurement of the SAR value at a fixed location is used as a reference value for assessing the power drop of the EUT. The SAR at this point is measured at the start of the test and then again at the end of the test.
- b) The SAR distribution at the exposed side of the phantom is measured at a distance of 3.9 mm from the inner surface of the shell. The area covers the entire dimension of the EUT and the horizontal grid spacing is 15 mm x 15 mm( or 20mm x 20mm). The actual Area Scan has dimensions surrounding the test device. Based on this data, the area of the maximum absorption is determined by Spline interpolation.
- c) Around this point, a volume is assessed by measuring 5 x 5 x 7 (7 x 7 x 7) points. On the basis of this data set, the spatial peak SAR value is evaluated with the following procedure ;
  - (i) The data at the surface are extrapolated, since the centre of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2 mm. The extrapolation is based on a least square algorithm[13]. A polynomial of the fourth order is calculated through the points in z-axes. This polynomial is then used to evaluate the points between the surface and the probe tip.
  - (ii) The maximum interpolated value is searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g and 10 g) are computed using the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the “Not a knot”- condition (in x, y and z-direction)[13][14]. The volume is integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) are interpolated to calculate the averages.
  - (iii) All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.
  - (iv) The SAR value at the same location as in Step (a) is again measured (If the value changed by more than 5%, the evaluation is repeatd.)

## **6. MEASUREMENT UNCERTAINTY**

The uncertainty analysis is based on the template listed in the IEEE Std 1528-2003 for both EUT SAR tests and Validation uncertainty. The measurement uncertainty of a specific device is evaluated independently and the total uncertainty for both evaluations (95 % confidence level) must be less than 25 %.

a	b	c	d	e= f(d,k)	f	g	h=cxf/e	i=cxg/e	k
Uncertainty Component	Sec.	Tol. (%)	Prob. Dist.	Div.	Ci (1 g)	Ci (10 g)	1 g Ui (± %)	10 g Ui (± %)	vi
<b>Measurement System</b>									
Probe Calibration (k=1)	E.2.1	5.9	N	1	1	1	5.9	5.9	∞
Axial Isotropy	E.2.2	4.7	R	√ 3	0.7	0.7	1.9	1.9	∞
Hemispherical Isotropy	E.2.2	9.6	R	√ 3	0.7	0.7	3.9	3.9	∞
Boundary Effect	E.2.3	1.0	R	√ 3	1	1	0.6	0.6	∞
Linearity	E.2.4	4.7	R	√ 3	1	1	2.7	2.7	∞
System Detection Limits	E.2.5	1.0	R	√ 3	1	1	0.6	0.6	∞
Readout Electronics	E.2.6	0.3	N	1	1	1	0.3	0.3	∞
Response Time	E.2.7	0.8	R	√ 3	1	1	0.5	0.5	∞
Integration Time	E.2.8	2.6	R	√ 3	1	1	1.5	1.5	∞
RF Ambient Noise	E.6.1	3.0	R	√ 3	1	1	1.7	1.7	∞
RF Ambient Refections	E.6.1	3.0	R	√ 3	1	1	1.7	1.7	∞
Probe Positioner	E.6.2	0.4	R	√ 3	1	1	0.2	0.2	∞
Probe Positioning with respect to Phantom Shell	E.6.3	2.9	R	√ 3	1	1	1.7	1.7	∞
Algorithms for Max. SAR Evaluation	E.5	1.0	R	√ 3	1	1	0.6	0.6	∞
<b>Test Sample Related</b>									
Test Sample Positioning	E.4.2	2.9	N	1	1	1	2.9	2.9	145
Device Holder Uncertainty	E.4.1	3.6	N	1	1	1	3.6	3.6	5
Output Power Variation — SAR Drift Measurement	6.6.2	5.0	R	√ 3	1	1	2.9	2.9	∞
<b>Phantom and Tissue Parameters</b>									
Phantom Uncertainty (shape and thickness tolerances)	E.3.1	4.0	R	√ 3	1	1	2.3	2.3	∞
Liquid Conductivity — Deviation from target values	E.3.2	5.0	R	√ 3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity — Measurement uncertainty	E.3.3	2.5	N	1	0.64	0.43	1.6	1.1	∞
Liquid Permititvity — Deviation from target values	E.3.2	5.0	R	√ 3	0.6	0.49	1.7	1.4	∞
Liquid Pemiittivity — Measurement uncertainty	E.3.3	2.5	N	1	0.6	0.49	1.5	1.2	∞
Cornbined standard Uncertainty			RSS				± 10.9	± 10.7	387
Expanded Uncertainty (95% CONFIDENCE LEVEL)			K=2				± 21.9	± 21.4	

**Table 5. EUT SAR Test - Uncertainty Budget for DASY4 Version V4.6 Build 19**

Estimated total measurement uncertainty for the DASY4 measurement system was ± 10.9 %. The extended uncertainty (K=2) was assessed to be ± 21.9 % based on 95 % confidence level. The uncertainty is not added to the measurement result.

## 7. Description of Test Position

SAR measurements were performed in the “cheek” and “tilted” positions on left and right sides of the phantom. Both were measured in the head section of the SAM Twin Phantom. For the “Belt” position , it was measured in the flat section of the SAM Twin Phantom .

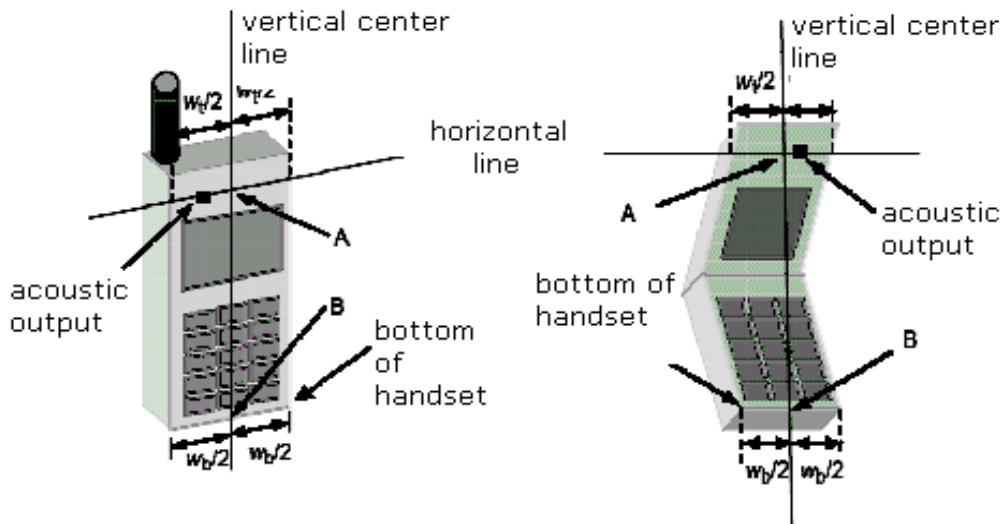
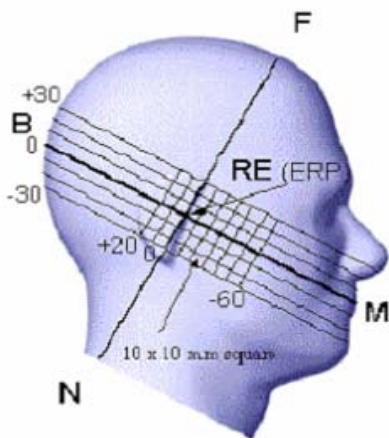


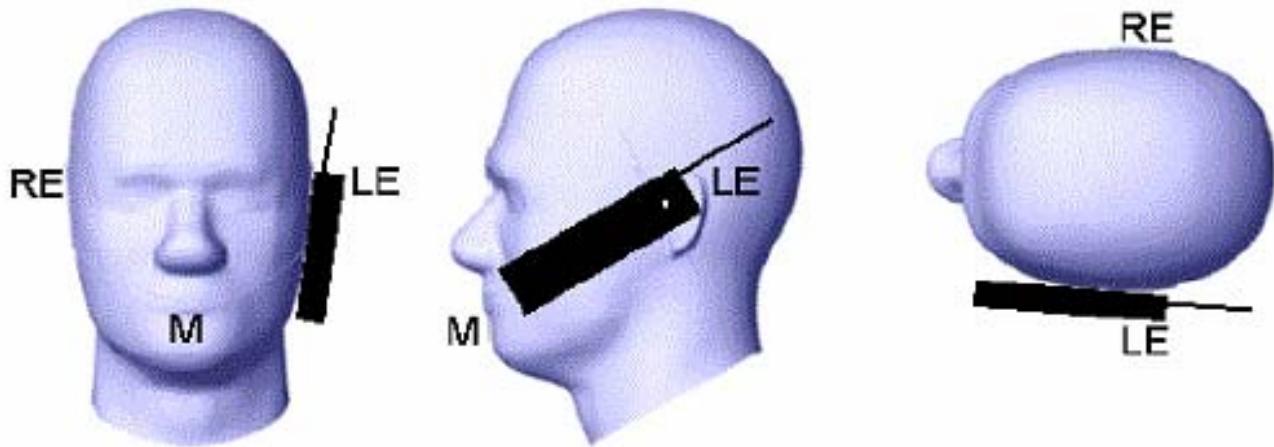
Figure 7. Handset vertical and horizontal reference line

### 7.1 Cheek Position

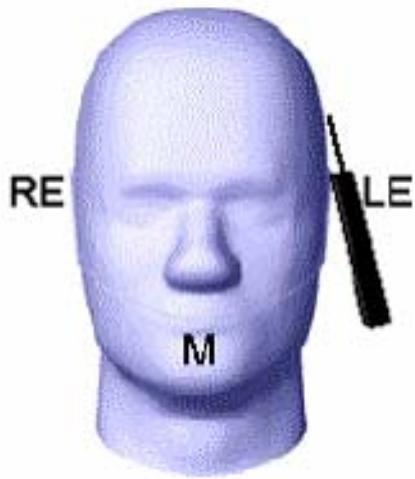


The device was positioned with the vertical center line of the body of the device and the horizontal line crossing the center (see Figure 7) of the ear piece in a plane parallel to the sagittal plane of the phantom(see Figure 8). While maintaining the device in this plane, it was aligned the vertical center line with the reference plane containing the three ear and mouth reference points(M, RE and LE) and aligned the center of the ear piece with the line RE-LE. Then device was translated towards the phantom with the ear piece aligned with the line LE-RE until it touched the ear. While maintaining the device in the reference plane and maintaining the device contact with the ear, the bottom of the device was moved until any point on the front side is in contact with the cheek of the phantom.(see Figure 9)

Figure 8. Side view of SAM phantom



**Figure 9. Cheek/Touch Position**



**Figure 10. Ear /Tilt Position**



**Figure 11. Belt Position set up without holster**

## 7.2 Tilt Position

The device was positioned in the “Cheek” position. While maintaining the device in the reference plane described above cheek position and pivoting against the ear, device was moved outward away from the mouth by an angle of 15 degrees. (see Figure 10)

## 7.3 Body Holster/Belt-Clip Position

Body-worn operating configurations are tested without the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration. A device with a headset output is tested with a headset connected to the device.

Accessories for Body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are tested

with the device with each accessory. If multiple accessories share an identical metallic component(i.e. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.

Body-worn accessories may not always be supplied or available as options for some devices intended to be authorized for body-worn use. In this case, a test configuration with a separation distance between the back of the device and the flat phantom is used. Test position spacing was documented.

Transmitters that are designed to operate in front of a person's face, as the push-to-talk configurations, are test for SAR compliance with the front of the device positioned to face the flat phantom in brain fluid. For devices that are carried next to the body such as a shoulder, waist or chest-worn transmitters, SAR compliance is tested with the accessories, including headsets and microphones, attached to the device and positioned against a flat phantom in a normal use configuration.

In this test case, the UPCS phone is not used in the Belt position. So only the head SAR is measured and reported.

## **8. FCC RF Exposure Limits**

HUMAN EXPOSURE	UNCONTROLLED ENVIRONMENT General Population (W/Kg) or (mW/g)	CONTROLLED ENVIRONMENT Occupational (W/Kg) or (mW/g)
<b>SPATIAL PEAK SAR (Brain)</b>	1.60	8.00
<b>SPATIAL AVERAGE SAR (Whole Body)</b>	0.08	0.40
<b>SPATIAL PEAK SAR (Hand / Feet / Ankle / Wrist)</b>	4.00	20.00

**Table. 8 Safety Limits for Partial Body Exposure**

NOTE 1 : **Whole-Body SAR** is averaged over the entire body, **partial-body SAR** is averaged over any 1gram of tissue defined as a tissue volume in the shape of a cube. **SAR for hands, wrists, feet and ankles** is averaged over any 10 grams of tissue defined as a tissue volume in the shape of cube

NOTE 2 : At frequencies above 6.0 GHz, SAR limits are not applicable and MPE limits for power density should be applied at 5 cm or more from the transmitting device.

NOTE 3 : The time averaging criteria for field strength and power density do not apply to general population SAR limit of 47 CFR § 2.1093.

## 9. SAR MEASUREMENT RESULTS

### 1) UP-CS Head SAR Measurement Result

- Date of Test: Sept. 16<sup>th</sup>, 2011
- Mixture Type: 1900MHz HEAD
- Ambient Temperature (C): 21.0
- Dielectric Constant: 39.2
- Liquid Temperature (C) : 22.0
- Humidity (%): 47
- Conductivity: 1.42

Mode	Antenna Position	Head Position	Device Position	Frequency		Power		SAR 1g (W/kg)
				MHz	CH	Ref. [V/m]	Drift [dB]	
UP-CS	Internal Ant.	LEFT	Cheek /Touch	1921.536	1	4.80	-0.005	0.051
				1924.992	3	4.93	-0.107	<b>0.054</b>
		LEFT	Ear/Tilt	1924.992	3	4.77	0.042	0.051
	Internal Ant.	RIGHT	Cheek /Touch	1924.992	3	4.68	-0.020	0.039
		RIGHT	Ear/Tilt	1924.992	3	4.56	-0.094	0.029

#### NOTES:

1. The test data reported are the worst-case SAR value with the position set in a typical configuration
2. All modes of operation were investigated and the worst-case are reported.
3. Battery: Standard Batteries are used and fully charged for all readings.
4. Power Measured: Power reference Values are recorded at the beginning and end of each measurement.
5. Test Signal Call mode: Base Station Simulator (CMD60)
6. Justification for reduced test configurations: per FCC/OET Supplement C (July,2001), if the SAR measured at the middle channel for each test configuration (Left, right, cheek/touch, tilt/ear, extended and retracted) is at least 3.0 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s).
7. Depth of simulation Tissue is 15.0 cm ± 0.2 cm

## **10. CONCLUSION**

The SAR evaluation indicates that DP01H complies with the RF radiation exposure limits of the FCC. These measurements were taken to simulate the RF effects of RF exposure under worst-case conditions. Precise laboratory measures were taken to assure repeatability of the tests. The results and statements relate only to the item(s) tested.

## 11. EQUIPMENT LIST AND CALIBRATION DETAILS

Equipment Type	Manufacturer	Model Number	Serial Number	Calibration Due	Used For this Test?
Robot - Six Axes	Staubli	RX60	N/A	N/A	Yes
Robot Remote Control	SPEAG	CS7MB	F03/5U96A1 /C/01	N/A	Yes
SAM Twin Phantom	SPEAG	TP1276	QD000P40CA	N/A	Yes
Flat Phantom V4.4	SPEAG	QD000P44BA, BB	1001, higher	N/A	No
Data Acquisition Electronics	SPEAG	DAE4	559	2012.05.23	Yes
Probe E-Field	SPEAG	ES3DV3	3020	2012.07.22	Yes
Antenna Dipole 835 MHz	SPEAG	D835V2	481	2013.03.15	No
Antenna Dipole 900 MHz	SPEAG	D900V2	194	2011.11.23	No
Antenna Dipole 1800 MHz	SPEAG	D1800V2	2d066	2013.04.18	No
Antenna Dipole 1900 MHz	SPEAG	D1900V2	5d038	2012.11.25	Yes
Antenna Dipole 1950 MHz	SPEAG	D1950V2	1027	2012.04.20	No
Antenna Dipole 2450 MHz	SPEAG	D2450V2	746	2012.04.19	No
High power RF Amplifier	EMPOWER	2057-BBS3Q5KCK	1002D/C0321	2012.02.07	Yes
Digital Communication Tester	R&S	CMD60	842989/006	2012.02.07	Yes
Signal Generator	Agilent	8648C	3629U00868	2012.02.07	Yes
RF Power Meter Dual	Hewlett Packard	E4419A	GB37170495	2012.02.08	Yes
RF Power Sensor 0.01 - 18 GHz	Hewlett Packard	8481A	US37299851	2012.02.15	Yes
RF Power Sensor 0.01 - 18 GHz	Hewlett Packard	8481A	3318A92872	2012.02.15	Yes
S-Parameter Network Analyzer	Agilent	8753D	3410A07251	2012.03.07	Yes
Dual Directional Coupler	Hewlett Packard	778D	1144AO4576	2012.02.10	Yes
Directional Coupler	Agilent	773D	MY28390213	2012.02.10	No
Bluetooth Test Set	Anritsu	MT8852B	6K00006994	2012.01.28	No

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## Appendix A. SAR PLOTS

Test Laboratory: KTL

**1900MHz Validation – D1900V2; SN:5d038**

\*Test Date : 16<sup>th</sup> /September/2011

**Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL1900 Medium parameters used:  $f = 1900 \text{ MHz}$ ;  $\sigma = 1.42 \text{ mho/m}$ ;  $\epsilon_r = 39.2$ ;  $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (61x71x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 12.3 mW/g

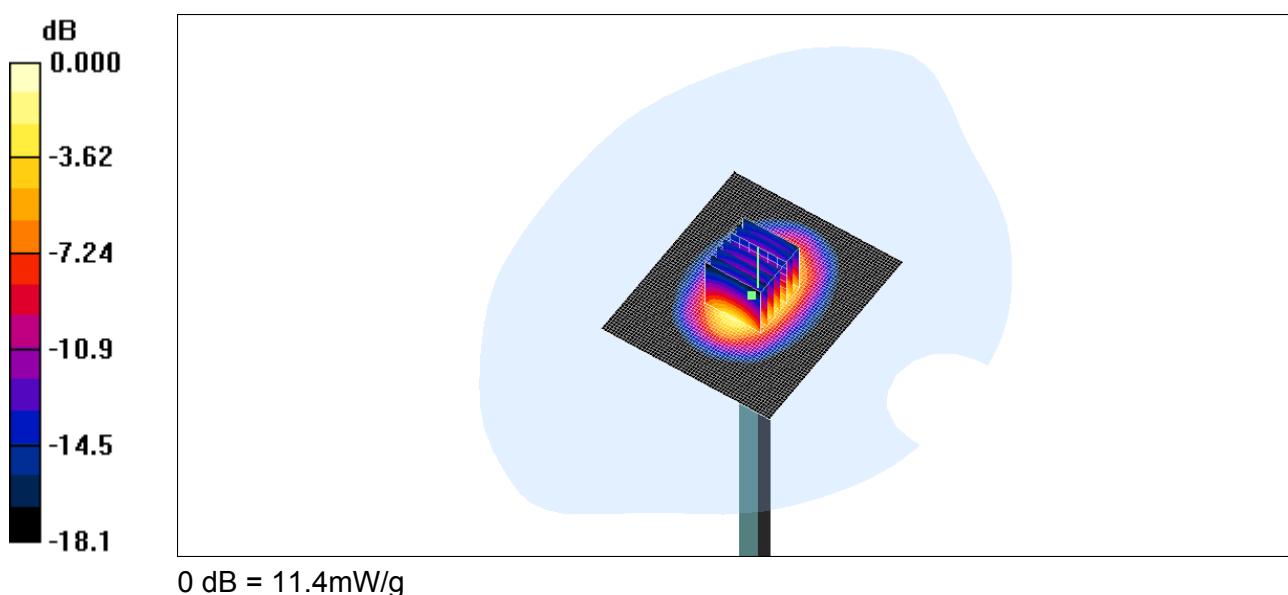
**Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 90.9 V/m; Power Drift = 0.012 dB

Peak SAR (extrapolated) = 18.9 W/kg

**SAR(1 g) = 10.0 mW/g; SAR(10 g) = 5.15 mW/g**

Maximum value of SAR (measured) = 11.4 mW/g



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Test Laboratory: KTL

**DP01H UPCS LEFT CHEEK TOUCH 3CH**

\*Test Date : 16<sup>th</sup> /September/2011

**Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: UPCS1900; Frequency: 1924.99 MHz; Duty Cycle: 1:12

Medium: HSL1900 Medium parameters used:  $f = 1924.99 \text{ MHz}$ ;  $\sigma = 1.45 \text{ mho/m}$ ;  $\epsilon_r = 38.8$ ;  $\rho = 1000 \text{ kg/m}^3$

Phantom section: Left Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (41x91x1):** Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.062 mW/g

**Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm

Maximum value of SAR (interpolated) = 0.008 mW/g

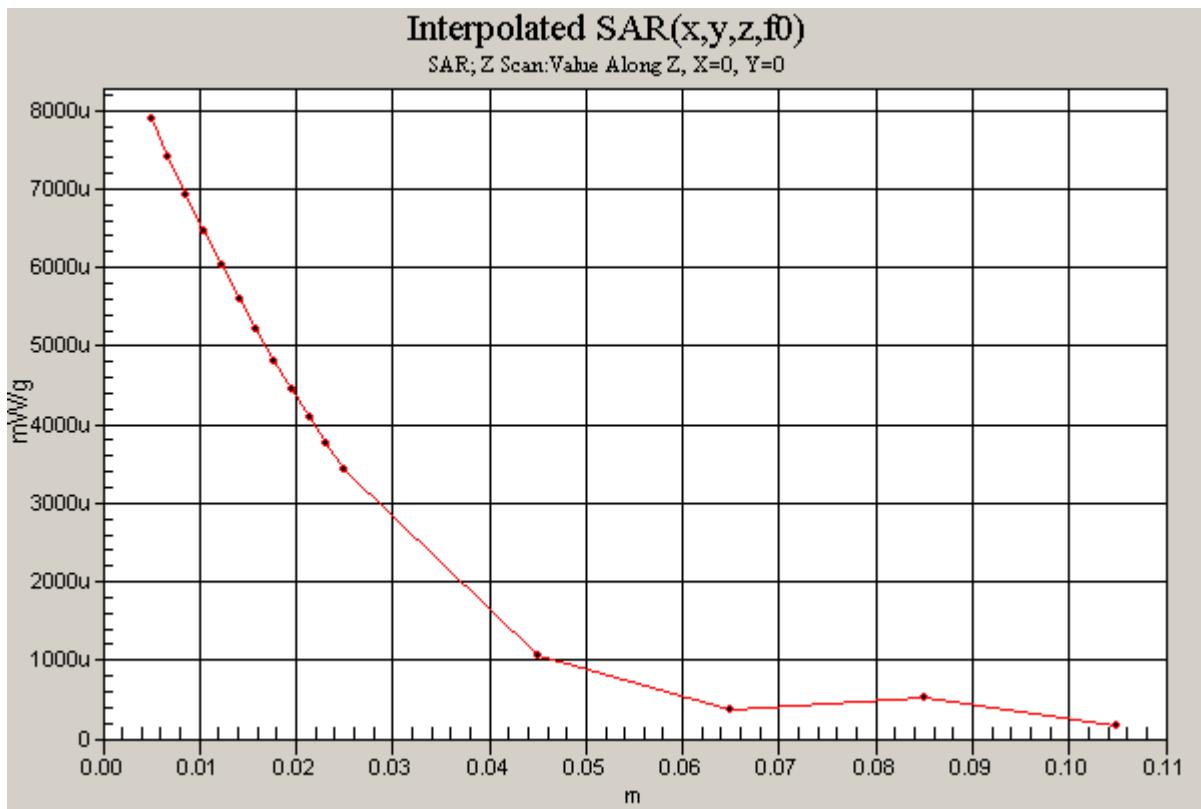
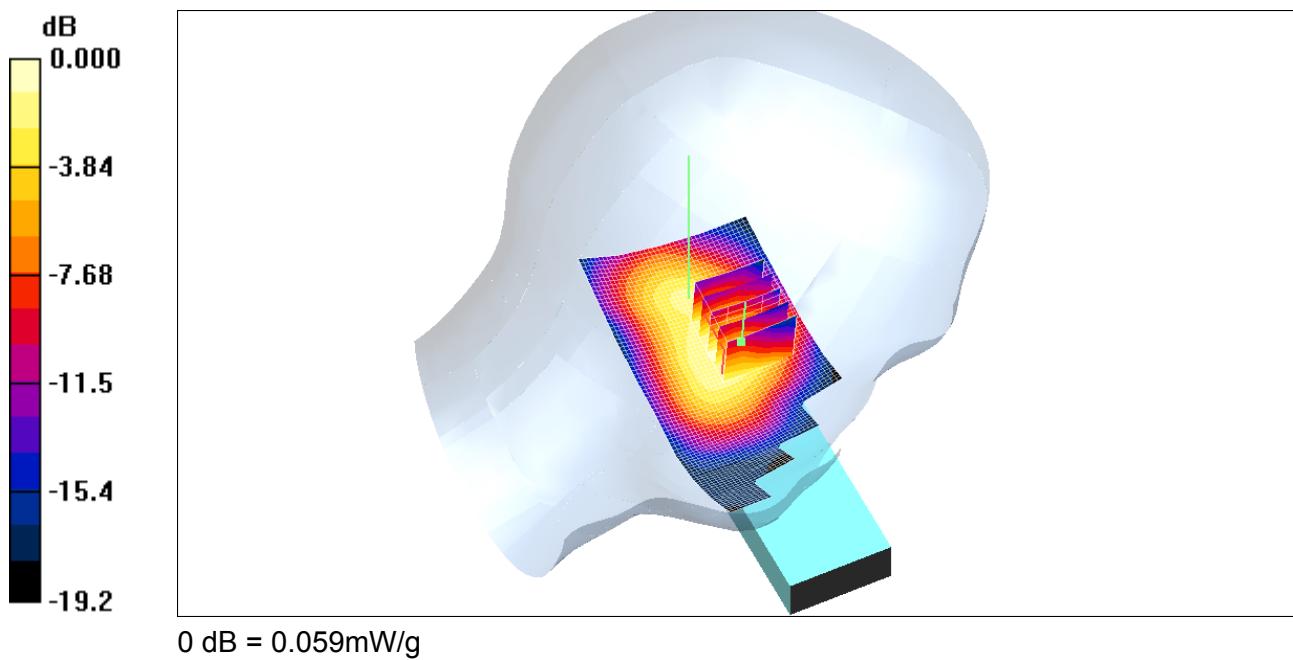
**Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.93 V/m; Power Drift = -0.107 dB

Peak SAR (extrapolated) = 0.083 W/kg

**SAR(1 g) = 0.054 mW/g; SAR(10 g) = 0.033 mW/g**

Maximum value of SAR (measured) = 0.059 mW/g



Test Laboratory: KTL

**DP01H UPCS LEFT EAR TILT 3CH****\*Test Date : 16<sup>th</sup> /September/2011****Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: UPCS1900; Frequency: 1924.99 MHz; Duty Cycle: 1:12

Medium: HSL1900 Medium parameters used:  $f = 1924.99$  MHz;  $\sigma = 1.45$  mho/m;  $\epsilon_r = 38.8$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Left Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (41x91x1):** Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.040 mW/g

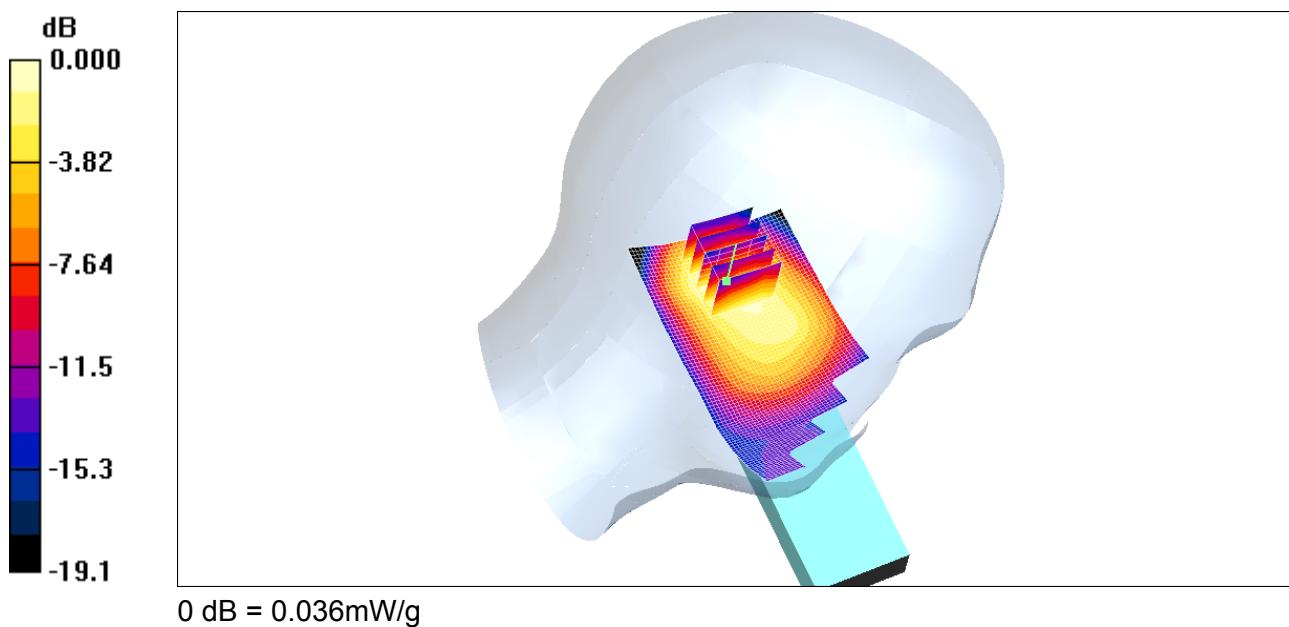
**Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.77 V/m; Power Drift = 0.031 dB

Peak SAR (extrapolated) = 0.055 W/kg

**SAR(1 g) = 0.033 mW/g; SAR(10 g) = 0.019 mW/g**

Maximum value of SAR (measured) = 0.036 mW/g



Test Laboratory: KTL

### DP01H UPCS RIGHT CHEEK TOUCH 3CH

\*Test Date : 16<sup>th</sup> /September/2011

**Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: UPCS1900; Frequency: 1924.99 MHz; Duty Cycle: 1:12

Medium: HSL1900 Medium parameters used:  $f = 1924.99$  MHz;  $\sigma = 1.45$  mho/m;  $\epsilon_r = 38.8$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Right Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (41x91x1):** Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.043 mW/g

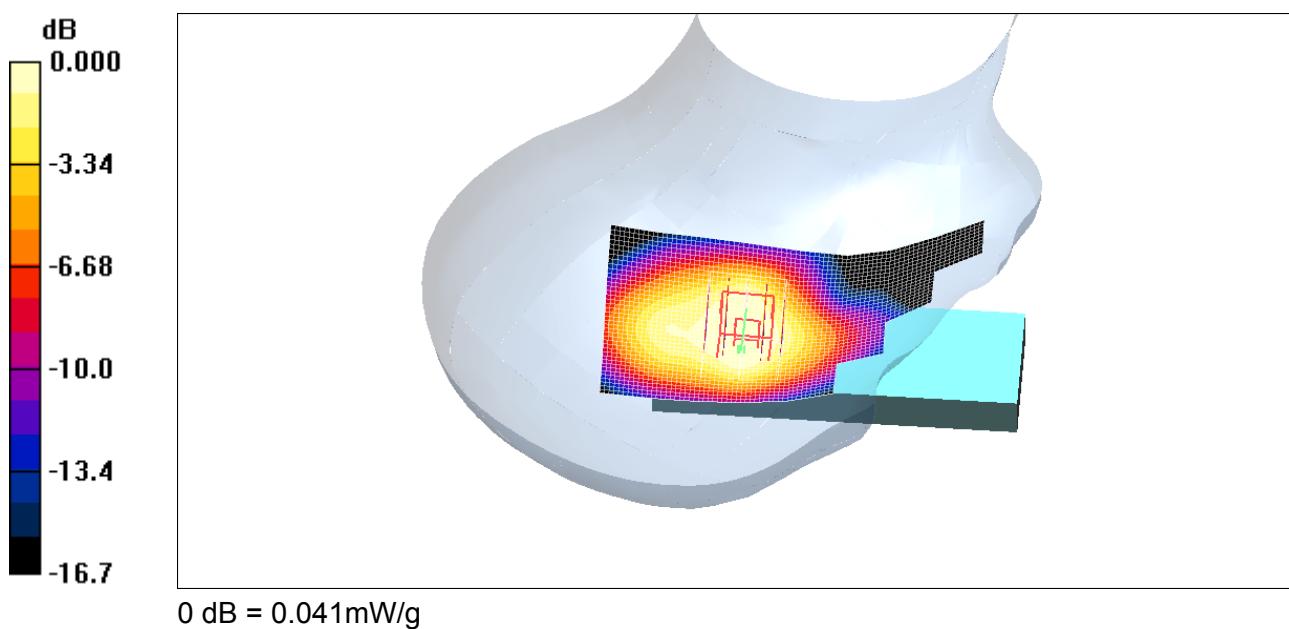
**Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.68 V/m; Power Drift = -0.020 dB

Peak SAR (extrapolated) = 0.056 W/kg

**SAR(1 g) = 0.039 mW/g; SAR(10 g) = 0.026 mW/g**

Maximum value of SAR (measured) = 0.041 mW/g



Test Laboratory: KTL

**DP01H UPCS RIGHT EAR TILT 3CH****\*Test Date : 16<sup>th</sup> /September/2011****Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: UPCS1900; Frequency: 1924.99 MHz; Duty Cycle: 1:12

Medium: HSL1900 Medium parameters used:  $f = 1924.99 \text{ MHz}$ ;  $\sigma = 1.45 \text{ mho/m}$ ;  $\epsilon_r = 38.8$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Right Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (41x91x1):** Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.037 mW/g

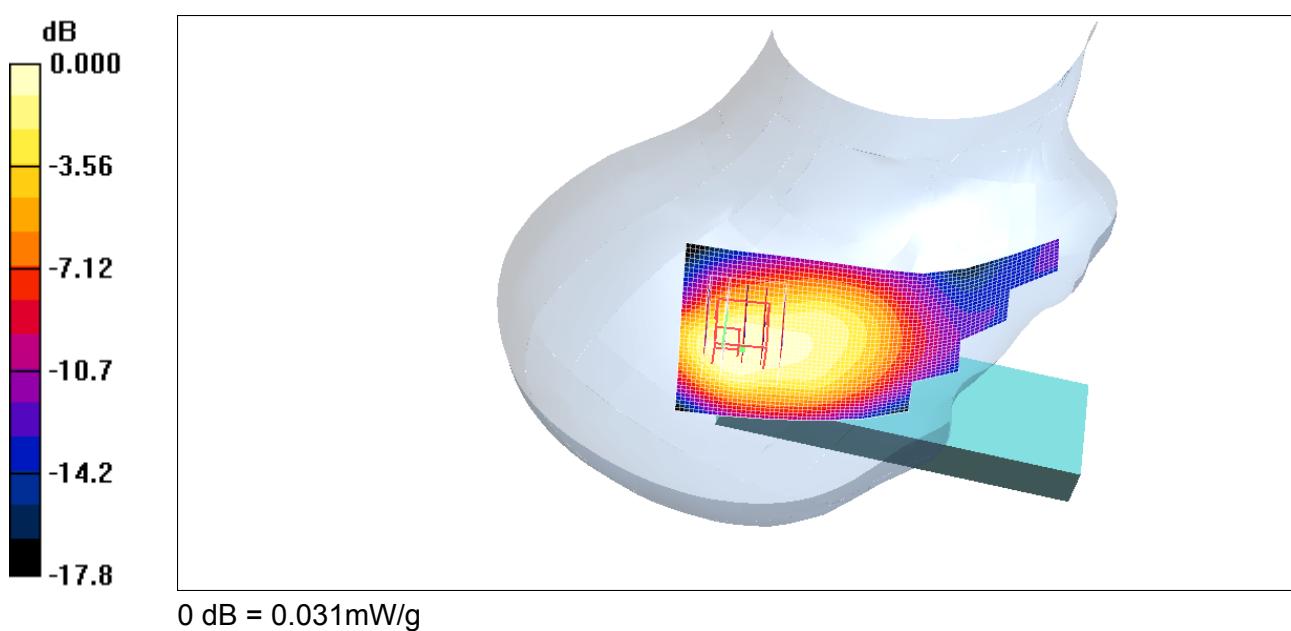
**Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.56 V/m; Power Drift = -0.094 dB

Peak SAR (extrapolated) = 0.050 W/kg

**SAR(1 g) = 0.029 mW/g; SAR(10 g) = 0.018 mW/g**

Maximum value of SAR (measured) = 0.031 mW/g



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Test Laboratory: KTL

**DP01H UPCS LEFT CHEEK TOUCH 1CH**

\*Test Date : 16<sup>th</sup> /September/2011

**Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: UPCS1900; Frequency: 1921.36 MHz; Duty Cycle: 1:12

Medium: HSL1900 Medium parameters used:  $f = 1921.36 \text{ MHz}$ ;  $\sigma = 1.44 \text{ mho/m}$ ;  $\epsilon_r = 38.8$ ;  $\rho = 1000 \text{ kg/m}^3$

Phantom section: Left Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (41x91x1):** Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.059 mW/g

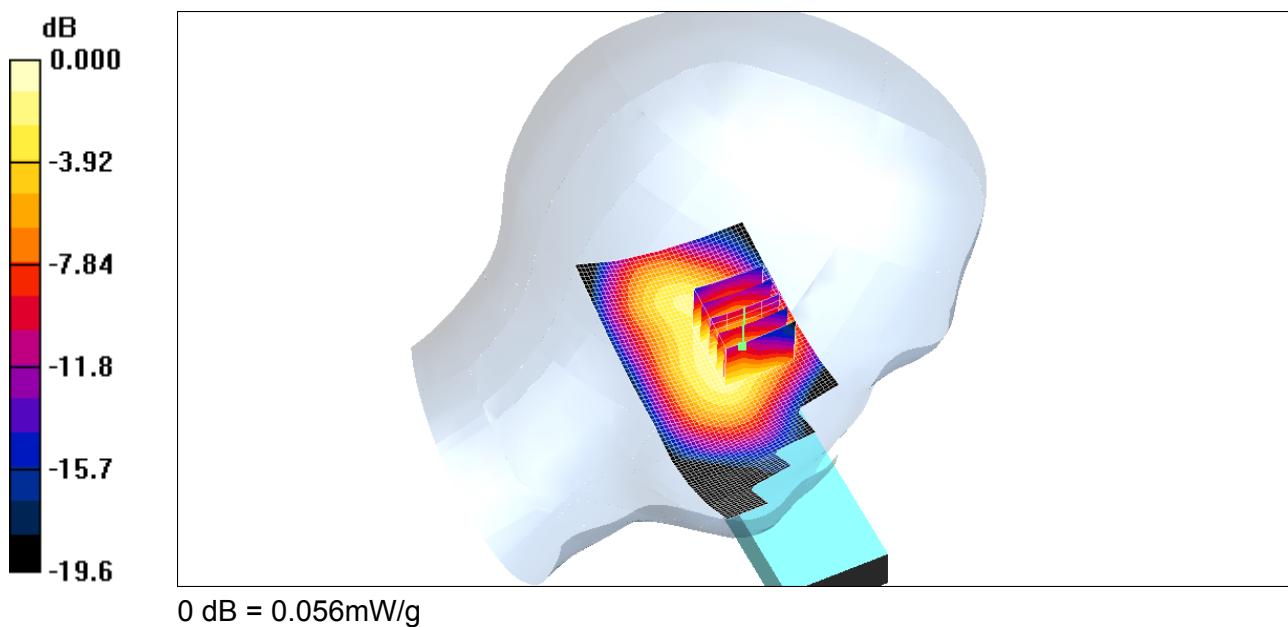
**Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.80 V/m; Power Drift = -0.005 dB

Peak SAR (extrapolated) = 0.077 W/kg

**SAR(1 g) = 0.051 mW/g; SAR(10 g) = 0.031 mW/g**

Maximum value of SAR (measured) = 0.056 mW/g



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Test Laboratory: KTL

**DP01H UPCS LEFT CHEEK TOUCH 5CH**

\*Test Date : 16<sup>th</sup> /September/2011

**Measured Liquid Temperature(°C) : 22.0, Ambient Temperature(°C) : 21.0**

Communication System: UPCS1900; Frequency: 1928.45 MHz; Duty Cycle: 1:12

Medium: HSL1900 Medium parameters used:  $f = 1928.45$  MHz;  $\sigma = 1.45$  mho/m;  $\epsilon_r = 38.7$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Left Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV3 - SN3020; ConvF(4.9, 4.9, 4.9); Calibrated: 2011-07-22
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn559; Calibrated: 2011-05-23
- Phantom: SAM Twin Phantom\_1800MHz; Type: SAM; Serial: TP-1433
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Area Scan (41x91x1):** Measurement grid: dx=20mm, dy=20mm

Maximum value of SAR (interpolated) = 0.057 mW/g

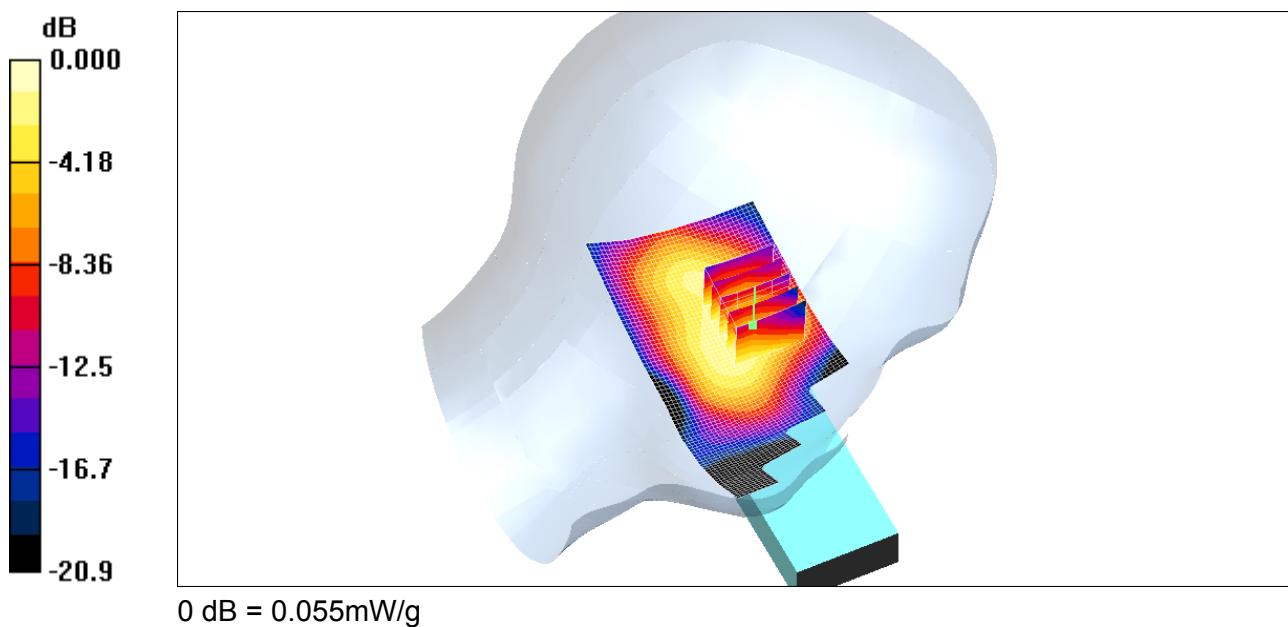
**Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 4.72 V/m; Power Drift = 0.042 dB

Peak SAR (extrapolated) = 0.077 W/kg

**SAR(1 g) = 0.051 mW/g; SAR(10 g) = 0.031 mW/g**

Maximum value of SAR (measured) = 0.055 mW/g





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## Appendix B. Calibration Data Sheets

E-Field Probe 3020  
Dipole Antenna D1900V2 5d038



Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA  
 Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **KTL (Dymstec)**

Certificate No: **ES3-3020\_Jul11**

## CALIBRATION CERTIFICATE

Object **ES3DV2 - SN:3020**

Calibration procedure(s) **QA CAL-01.v8, QA CAL-23.v4, QA CAL-25.v4**  
 Calibration procedure for dosimetric E-field probes

Calibration date: **July 22, 2011**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature ( $22 \pm 3$ )°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	31-Mar-11 (No. 217-01372)	Apr-12
Power sensor E4412A	MY41498087	31-Mar-11 (No. 217-01372)	Apr-12
Reference 3 dB Attenuator	SN: S5054 (3c)	29-Mar-11 (No. 217-01369)	Apr-12
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-11 (No. 217-01367)	Apr-12
Reference 30 dB Attenuator	SN: S5129 (30b)	29-Mar-11 (No. 217-01370)	Apr-12
Reference Probe ES3DV2	SN: 3013	29-Dec-10 (No. ES3-3013_Dec10)	Dec-11
DAE4	SN: 654	3-May-11 (No. DAE4-654_May11)	May-12
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Calibrated by:	Name <b>Claudio Leubler</b>	Function <b>Laboratory Technician</b>	Signature 
Approved by:	Name <b>Katja Pokovic</b>	Function <b>Technical Manager</b>	Signature 

Issued: July 26, 2011

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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Accreditation No.: **SCS 108**

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 Multilateral Agreement for the recognition of calibration certificates

### Glossary:

TSL	tissue simulating liquid
NORM <sub>x,y,z</sub>	sensitivity in free space
ConvF	sensitivity in TSL / NORM <sub>x,y,z</sub>
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization $\phi$	$\phi$ rotation around probe axis
Polarization $\theta$	$\theta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\theta = 0$ is normal to probe axis

### Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

### Methods Applied and Interpretation of Parameters:

- $NORM_{x,y,z}$ : Assessed for E-field polarization  $\theta = 0$  ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide).  $NORM_{x,y,z}$  are only intermediate values, i.e., the uncertainties of  $NORM_{x,y,z}$  does not affect the E<sup>2</sup>-field uncertainty inside TSL (see below ConvF).
- $NORM(f)x,y,z = NORM_{x,y,z} * frequency\_response$  (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- $DCPx,y,z$ : DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- $PAR$ : PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- $Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z$ : A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters*: Assessed in flat phantom using E-field (or Temperature Transfer Standard for  $f \leq 800$  MHz) and inside waveguide using analytical field distributions based on power measurements for  $f > 800$  MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to  $NORM_{x,y,z} * ConvF$  whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from  $\pm 50$  MHz to  $\pm 100$  MHz.
- Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

# Probe ES3DV2

**SN:3020**

Manufactured: December 5, 2002  
Calibrated: July 22, 2011

**Calibrated for DASY/EASY Systems**  
(Note: non-compatible with DASY2 system!)

## DASY/EASY - Parameters of Probe: ES3DV2 - SN:3020

### Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ( $\mu\text{V}/(\text{V}/\text{m})^2$ ) <sup>A</sup>	1.10	0.98	1.02	$\pm 10.1 \%$
DCP (mV) <sup>B</sup>	102.5	102.6	102.8	

### Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc <sup>E</sup> (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	104.5	$\pm 3.0 \%$
			Y	0.00	0.00	1.00	130.9	
			Z	0.00	0.00	1.00	132.6	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

<sup>E</sup> Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

## DASY/EASY - Parameters of Probe: ES3DV2 - SN:3020

### Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
835	41.5	0.90	6.20	6.20	6.20	0.61	1.19	± 12.0 %
1750	40.1	1.37	5.10	5.10	5.10	0.42	1.51	± 12.0 %
1900	40.0	1.40	4.90	4.90	4.90	0.46	1.39	± 12.0 %
2450	39.2	1.80	4.16	4.16	4.16	0.40	1.53	± 12.0 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

## DASY/EASY - Parameters of Probe: ES3DV2- SN:3020

### Calibration Parameter Determined in Body Tissue Simulating Media

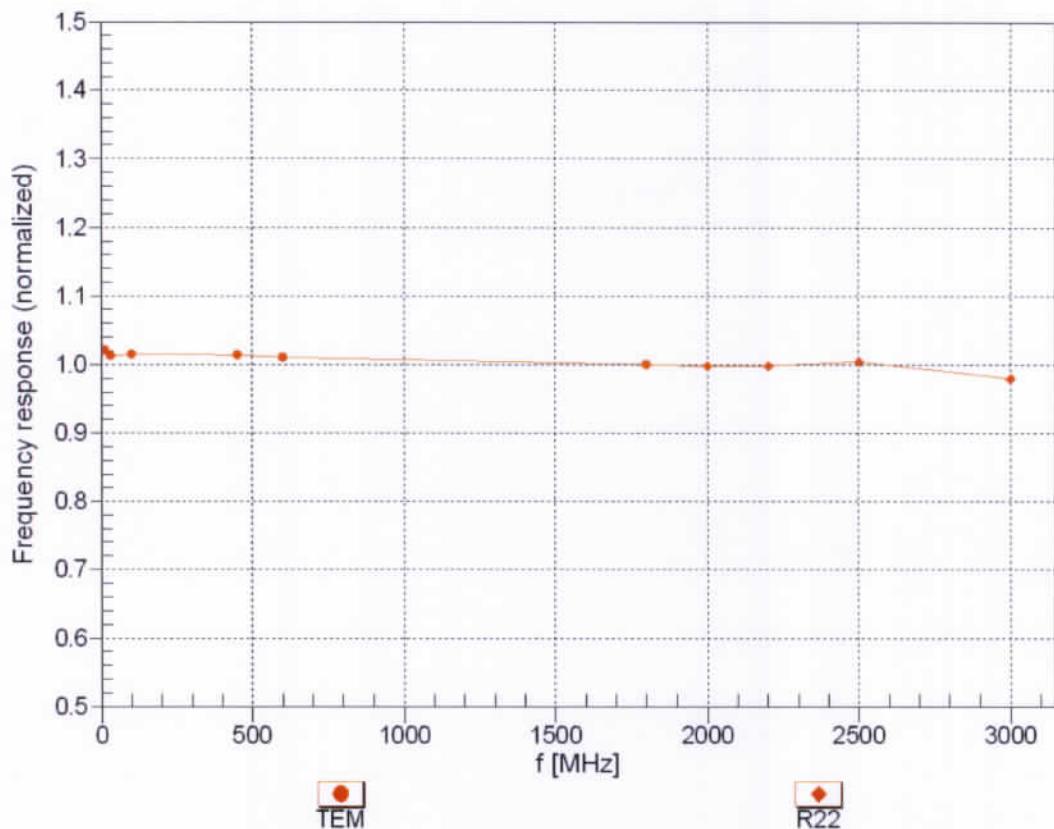
f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
835	55.2	0.97	6.26	6.26	6.26	0.73	1.10	± 12.0 %
1900	53.3	1.52	4.36	4.36	4.36	0.37	1.81	± 12.0 %
2450	52.7	1.95	3.85	3.85	3.85	0.39	1.38	± 12.0 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

## Frequency Response of E-Field

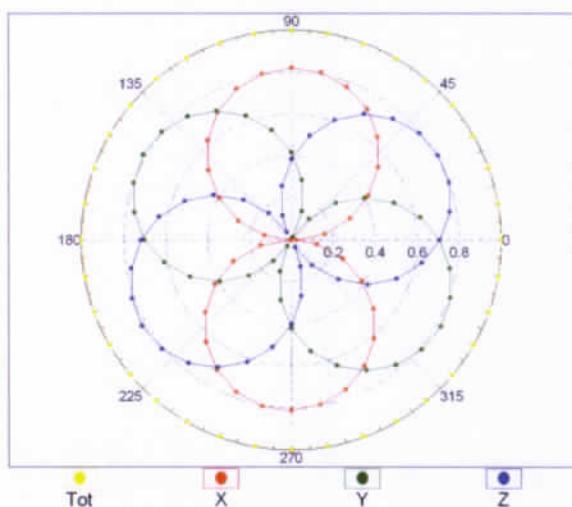
(TEM-Cell:ifi110 EXX, Waveguide: R22)



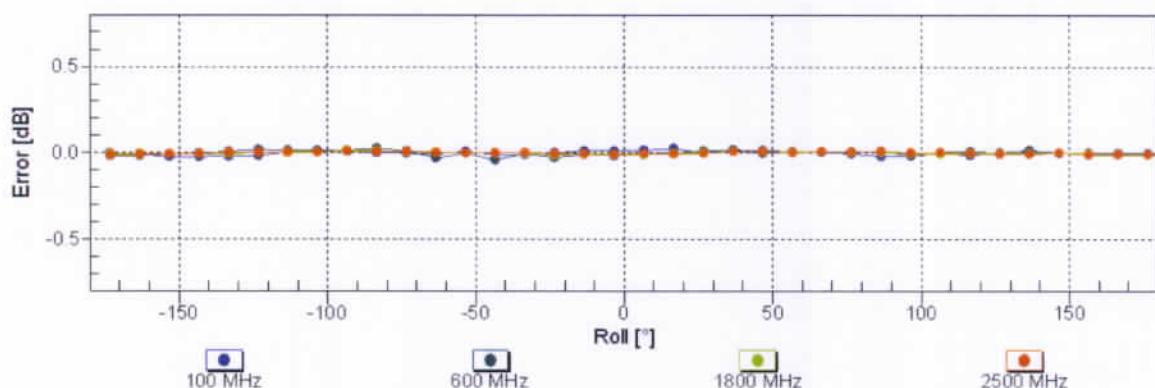
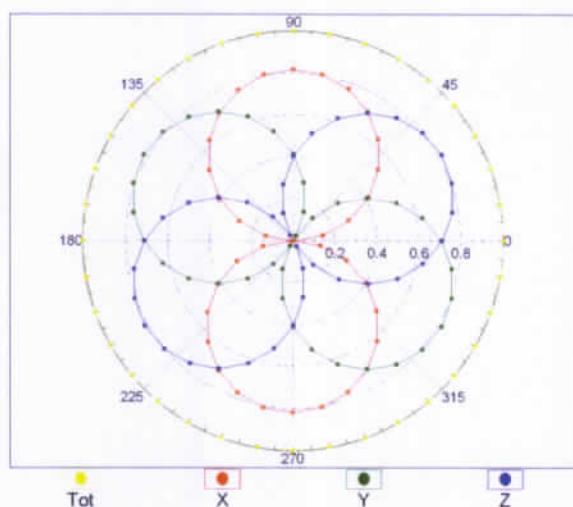
Uncertainty of Frequency Response of E-field:  $\pm 6.3\% \text{ (k=2)}$

## Receiving Pattern ( $\phi$ ), $\theta = 0^\circ$

f=600 MHz,TEM



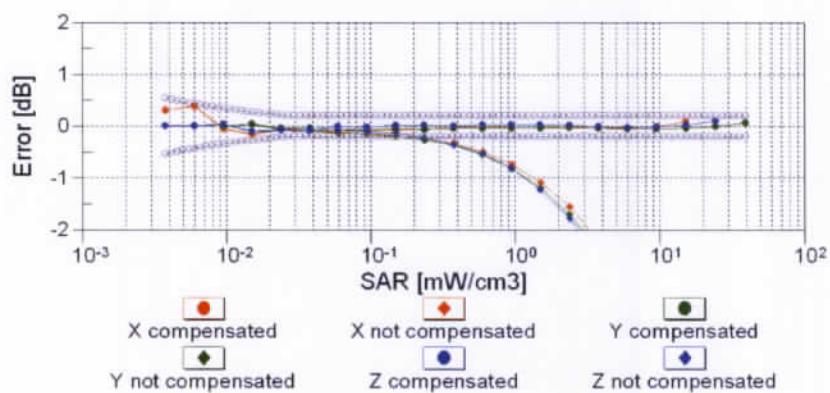
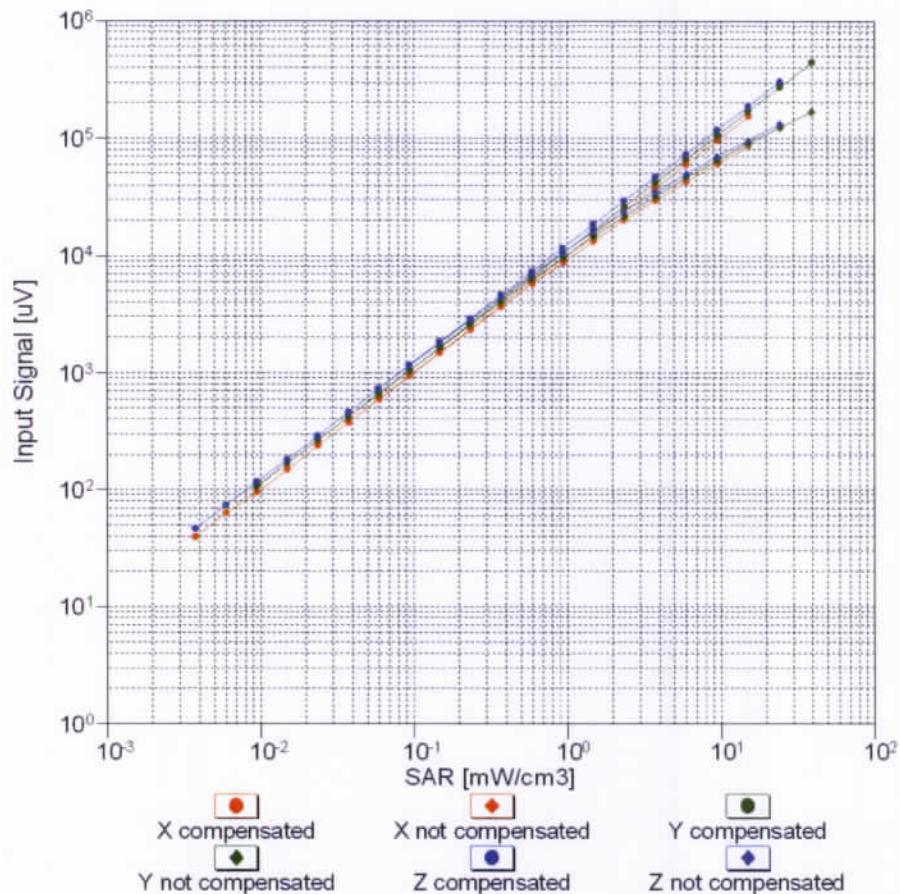
f=1800 MHz,R22



Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  (k=2)

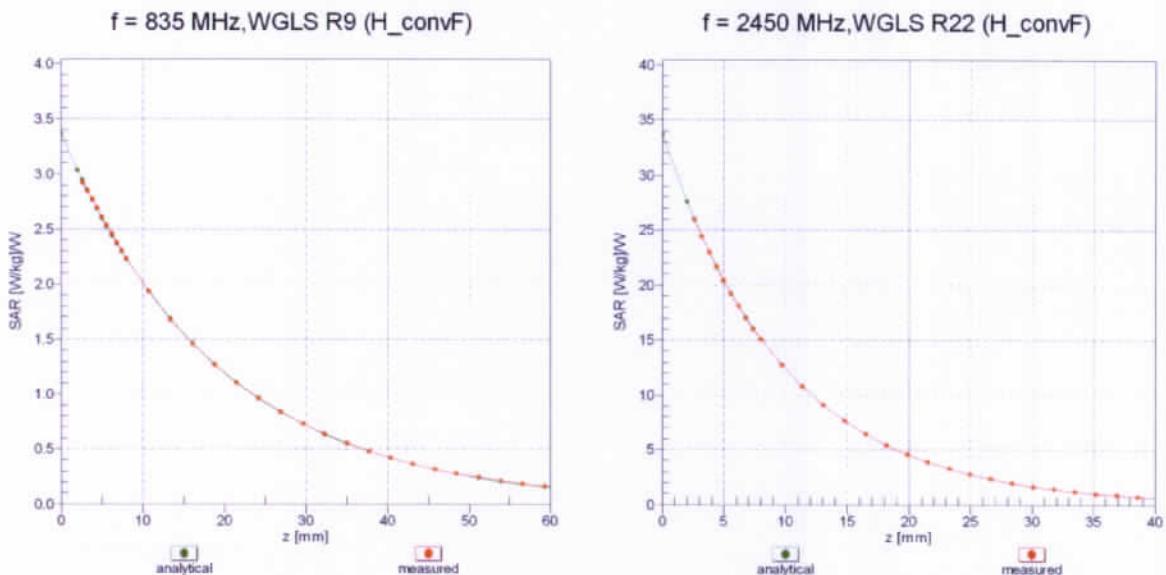
## Dynamic Range f(SAR<sub>head</sub>)

(TEM cell , f = 900 MHz)

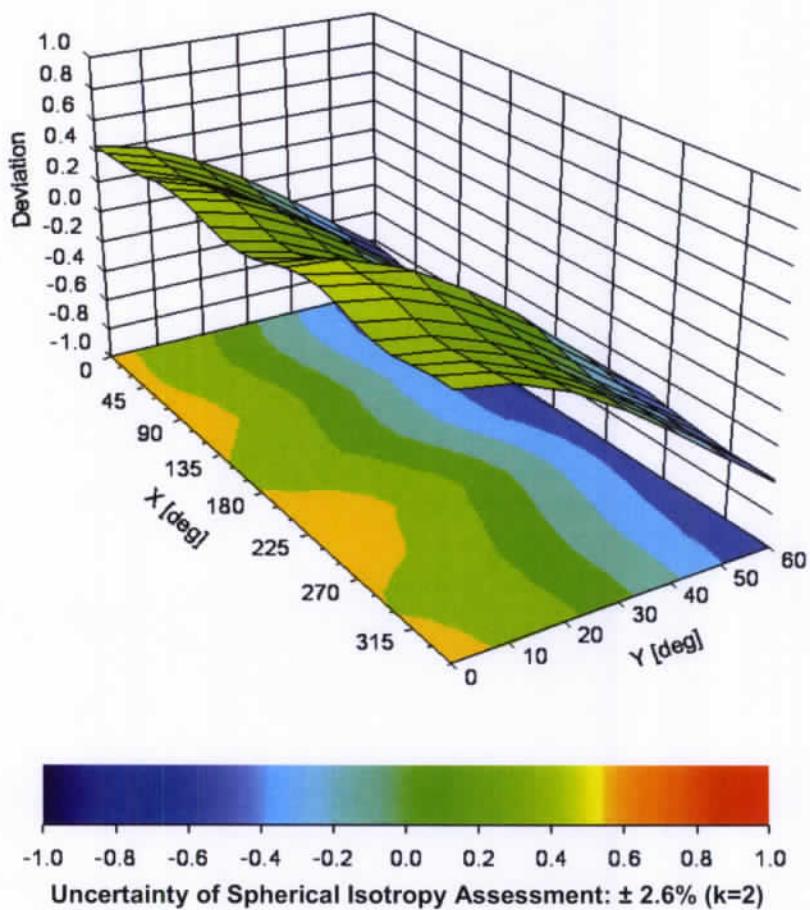


**Uncertainty of Linearity Assessment:  $\pm 0.6\%$  ( $k=2$ )**

## Conversion Factor Assessment



## Deviation from Isotropy in Liquid Error ( $\phi, \theta$ ), $f = 900 \text{ MHz}$



## DASY/EASY - Parameters of Probe: ES3DV2 - SN:3020

### Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	Not applicable
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	4 mm
Probe Tip to Sensor X Calibration Point	2 mm
Probe Tip to Sensor Y Calibration Point	2 mm
Probe Tip to Sensor Z Calibration Point	2 mm
Recommended Measurement Distance from Surface	3 mm



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The Swiss Accreditation Service is one of the signatories to the EA  
 Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **KTL (Dymstec)**

Certificate No: **D1900V2-5d038\_Nov10**

## CALIBRATION CERTIFICATE

Object **D1900V2 - SN: 5d038**

Calibration procedure(s) **QA CAL-05.v7**  
 Calibration procedure for dipole validation kits

Calibration date: **November 25, 2010**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature ( $22 \pm 3$ )°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	06-Oct-10 (No. 217-01266)	Oct-11
Power sensor HP 8481A	US37292783	06-Oct-10 (No. 217-01266)	Oct-11
Reference 20 dB Attenuator	SN: 5086 (20g)	30-Mar-10 (No. 217-01158)	Mar-11
Type-N mismatch combination	SN: 5047.2 / 06327	30-Mar-10 (No. 217-01162)	Mar-11
Reference Probe ES3DV3	SN: 3205	30-Apr-10 (No. ES3-3205_Apr10)	Apr-11
DAE4	SN: 601	10-Jun-10 (No. DAE4-601_Jun10)	Jun-11
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (in house check Oct-09)	In house check: Oct-11
RF generator R&S SMT-06	100005	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Calibrated by: Name **Jeton Kastrati** Function **Laboratory Technician**

Approved by: Name **Katja Pokovic** Function **Technical Manager**

Issued: November 26, 2010

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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Multilateral Agreement for the recognition of calibration certificates

### Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

### Additional Documentation:

- d) DASY4/5 System Handbook

### Methods Applied and Interpretation of Parameters:

- *Measurement Conditions:* Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- *Antenna Parameters with TSL:* The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- *Feed Point Impedance and Return Loss:* These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- *SAR measured:* SAR measured at the stated antenna input power.
- *SAR normalized:* SAR as measured, normalized to an input power of 1 W at the antenna connector.
- *SAR for nominal TSL parameters:* The measured TSL parameters are used to calculate the nominal SAR result.

## Measurement Conditions

DASY system configuration, as far as not given on page 1.

<b>DASY Version</b>	DASY5	V52.2
<b>Extrapolation</b>	Advanced Extrapolation	
<b>Phantom</b>	Modular Flat Phantom V5.0	
<b>Distance Dipole Center - TSL</b>	10 mm	with Spacer
<b>Zoom Scan Resolution</b>	dx, dy, dz = 5 mm	
<b>Frequency</b>	1900 MHz ± 1 MHz	

## Head TSL parameters

The following parameters and calculations were applied.

	<b>Temperature</b>	<b>Permittivity</b>	<b>Conductivity</b>
<b>Nominal Head TSL parameters</b>	22.0 °C	40.0	1.40 mho/m
<b>Measured Head TSL parameters</b>	(22.0 ± 0.2) °C	39.3 ± 6 %	1.40 mho/m ± 6 %
<b>Head TSL temperature during test</b>	(21.5 ± 0.2) °C	----	----

## SAR result with Head TSL

<b>SAR averaged over 1 cm<sup>3</sup> (1 g) of Head TSL</b>	<b>Condition</b>	
SAR measured	250 mW input power	10.2 mW / g
SAR normalized	normalized to 1W	40.8 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	<b>40.7 mW /g ± 17.0 % (k=2)</b>

<b>SAR averaged over 10 cm<sup>3</sup> (10 g) of Head TSL</b>	<b>condition</b>	
SAR measured	250 mW input power	5.27 mW / g
SAR normalized	normalized to 1W	21.1 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	<b>21.0 mW /g ± 16.5 % (k=2)</b>

## Appendix

### Antenna Parameters with Head TSL

Impedance, transformed to feed point	52.9 $\Omega$ + 6.2 $j\Omega$
Return Loss	- 23.5 dB

### General Antenna Parameters and Design

Electrical Delay (one direction)	1.199 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

### Additional EUT Data

Manufactured by	SPEAG
Manufactured on	July 04, 2003

# DASY5 Validation Report for Head TSL

Date/Time: 25.11.2010 12:50:06

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d038**

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL U12 BB

Medium parameters used:  $f = 1900 \text{ MHz}$ ;  $\sigma = 1.4 \text{ mho/m}$ ;  $\epsilon_r = 39.4$ ;  $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: ES3DV3 - SN3205; ConvF(5.09, 5.09, 5.09); Calibrated: 30.04.2010
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 10.06.2010
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- Measurement SW: DASY52, V52.2 Build 0, Version 52.2.0 (163)
- Postprocessing SW: SEMCAD X, V14.2 Build 2, Version 14.2.2 (1685)

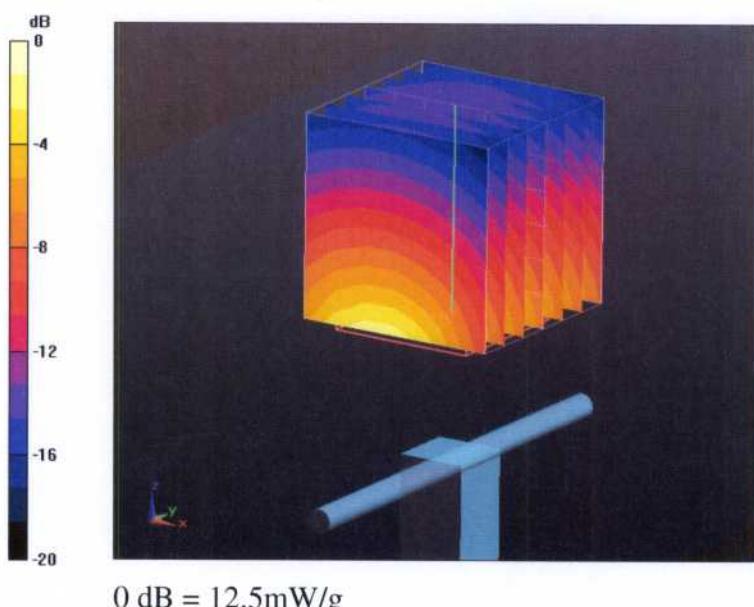
**Pin=250 mW /d=10mm, dist=3.0mm (ES-Probe)/Zoom Scan (7x7x7) /Cube 0:** Measurement grid:  $dx=5\text{mm}$ ,  $dy=5\text{mm}$ ,  $dz=5\text{mm}$

Reference Value = 97.6 V/m; Power Drift = 0.052 dB

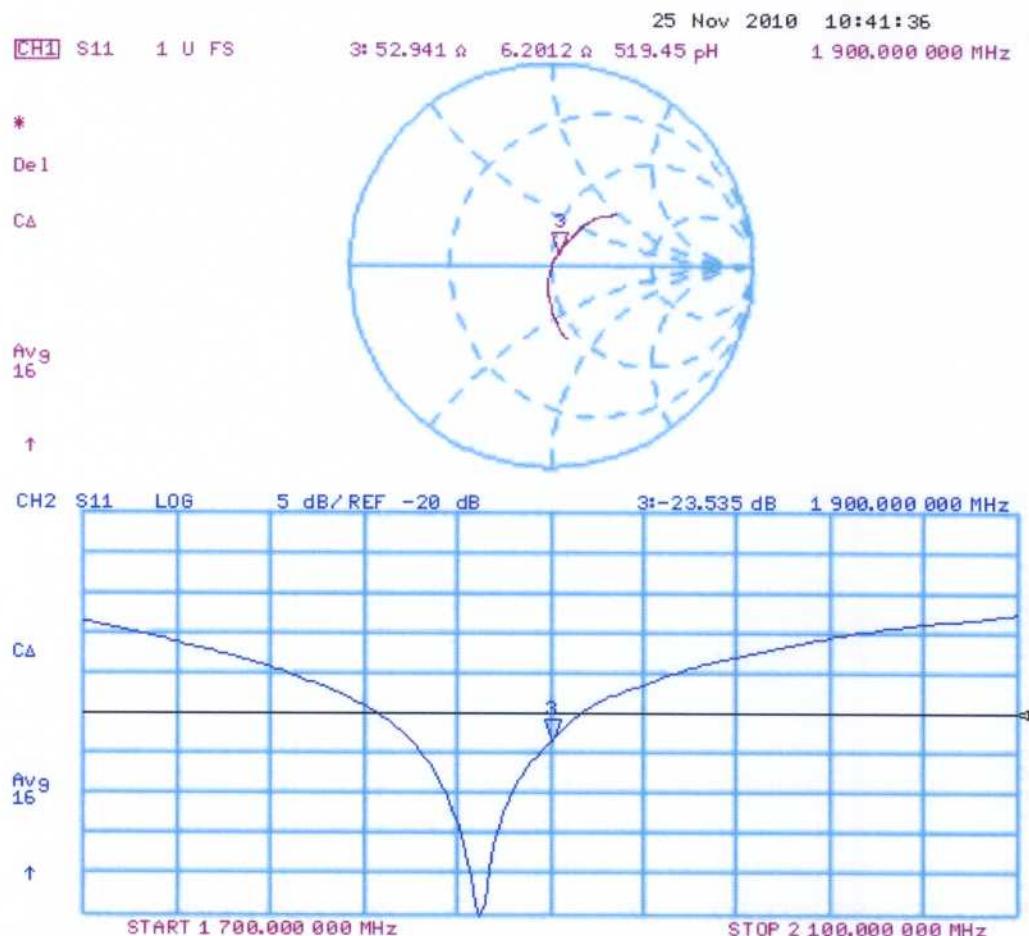
Peak SAR (extrapolated) = 18.8 W/kg

**SAR(1 g) = 10.2 mW/g; SAR(10 g) = 5.27 mW/g**

Maximum value of SAR (measured) = 12.5 mW/g



## Impedance Measurement Plot for Head TSL



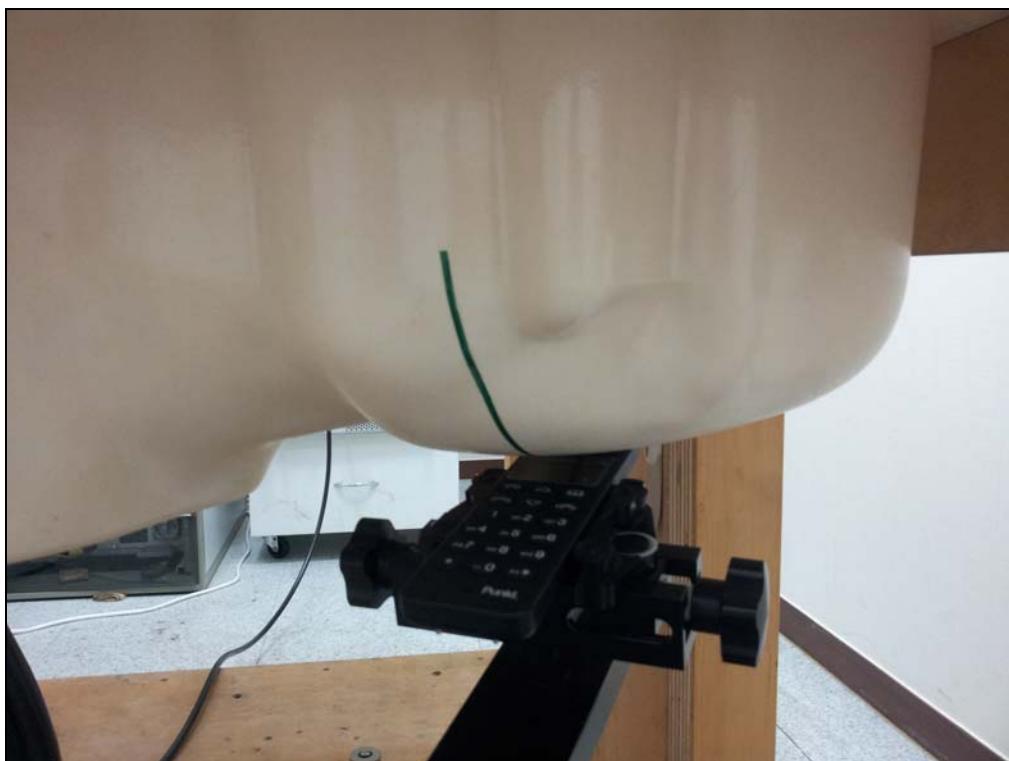
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## Appendix C. SAR measurement setup photos

## HEAD SAR Configuration



<Left Cheek Touch>



<Left Ear Tilt>



&lt;Right Cheek Touch&gt;



&lt;Right Ear Tilt&gt;