# Stochastic Multistrain Dengue Modeling

Flavio Codeço Coelho

& Luiz Max de Carvalho

#### **Abstract**

We proposed and analize a full multistrain Stochastic model for studying Dengue Dynamics. The model is presented both as a Continuous-time markov process and as a set of It stochastic differential equations. Sugestions of how to explore the dynamics numerically is also provided, along with source code examples.

## Introduction

# Multi-strain dynamics

In this paper we propose a stochastic 4-serotype SIR model with cross-immunity to describe multi-strain Dengue dynamics. The model permits up to 4 dengue infections with reduced susceptibility after the first Dengue episode due to cross immunity. Immunity to each serotype is considered complete and permanent. Figure 1 depicts all 48 possible states and 64 state-transitions included in the model.

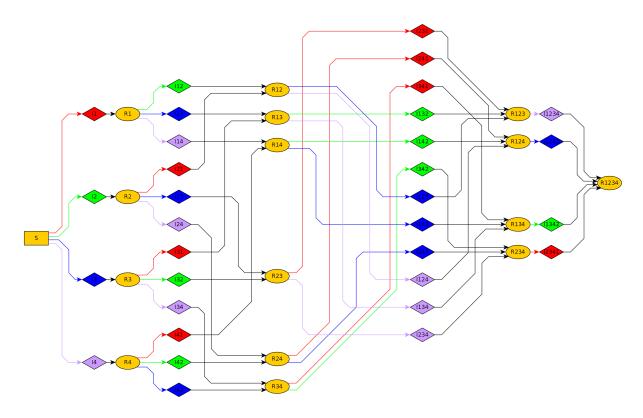


Figure 1: Block diagram detailing the stochastic model. Infected individuals with different Dengue viruses are represented by different colors. Infections are also represented by colored arrows matching the virus type.

### Deterministic Model

The derivation of the stochastic model is based on the deterministic ordinary differential equations below

$$\frac{dS}{dt} = -\beta S I_{*i} - \mu S + \mu N \tag{1}$$

$$\frac{dI_i}{dt} = \beta S I_{*i} - (\sigma + \mu) I_i \tag{2}$$

$$\frac{dI_{[i]j}}{dt} = \beta \delta R_i I_{*j} - (\sigma + \mu) I_{[i]j} \tag{3}$$

$$\frac{dI_{[ij]k}}{dt} = \beta \delta R_{ij} I_{*k} - (\sigma + \mu) I_{[ij]k} \tag{4}$$

$$\frac{dI_{[ijk]l}}{dt} = \beta \delta R_i j k I_{*l} - (\sigma + \mu) I_{[ijk]l}$$
(5)

$$\frac{dR_i}{dt} = \sigma I_i - \delta R_i (I_{*j} + I_{*k} + I_{*l}) - \mu R_i$$
 (6)

$$\begin{cases}
\frac{dS}{dt} = -\beta S I_{*i} - \mu S + \mu N & (1) \\
\frac{dI_i}{dt} = \beta S I_{*i} - (\sigma + \mu) I_i & (2) \\
\frac{dI_{[i]j}}{dt} = \beta \delta R_i I_{*j} - (\sigma + \mu) I_{[i]j} & (3) \\
\frac{dI_{[ij]k}}{dt} = \beta \delta R_i j I_{*k} - (\sigma + \mu) I_{[ij]k} & (4) \\
\frac{dI_{[ijk]l}}{dt} = \beta \delta R_i j k I_{*l} - (\sigma + \mu) I_{[ijk]l} & (5) \\
\frac{dR_i}{dt} = \sigma I_i - \delta R_i (I_{*j} + I_{*k} + I_{*l}) - \mu R_i & (6) \\
\frac{dR_{ij}}{dt} = \sigma I_{ij} - \delta R_{ij} (I_{*k} + I_{*l}) - \mu R_{ij} & (7) \\
\frac{dR_{ijk}}{dt} = \sigma I_{ijk} - \delta R_{ijk} I_{*l} - \mu R_{ijk} & (8) \\
\frac{dR_{ijkl}}{dt} = \sigma I_{ijkl} - \mu R_{ijkl} & (9)
\end{cases}$$

$$\frac{dR_{ijk}}{dt} = \sigma I_{ijk} - \delta R_{ijk} I_{*l} - \mu R_{ijk} \tag{8}$$

$$\frac{dR_{ijkl}}{dt} = \sigma I_{ijkl} - \mu R_{ijkl} \tag{9}$$

Table 1: State-transitions and probabilities:  $P(\Delta X(t)|X(t))$ . The transitions are summarized below. Fully expanded, the system contemplates 64 possible state transitions, as can be verified in figure 1. †: Non-zero elements of  $(\Delta X)_i$ .

i	Transition	Probability, $p_i$	State Change <sup>†</sup>	Description
14	$S \to I_i$	$\beta SI_{*i}\Delta t$	$\Delta S(t) = -1, \ \Delta I_i(t) = 1$	Primary infection
58	$I_i \to R_i$	$\sigma I_i \Delta t$	$\Delta I_i(t) = -1, \ \Delta R_i(t) = 1$	Primary recovery
920	$R_i \to I_{[i]j}$	$\beta \delta R_i I_{*j} \Delta t$	$\Delta R_i(t) = -1,  \Delta I_{[i]j}(t) = 1$	Secondary infection
2132	$I_{[i]j} \rightarrow R_{ij}$	$\sigma I_{[i]j} \Delta t$	$\Delta I_{[i]j}(t) = -1, \ \Delta R_{ij}(t) = 1$	Secondary recovery
3344	$R_{ij} \rightarrow I_{[ij]k}$	$\beta \delta R_{ij} I_{*k} \Delta t$	$\Delta R_{ij}(t) = -1,  \Delta I_{[ij]k}(t) = 1$	Tertiary infection
4556	$I_{[ij]k}  o R_{ijk}$	$\sigma I_{[ij]k} \Delta t$	$\Delta I_{[ij]k}(t) = -1,  \Delta R_{ijk}(t) = 1$	Tertiary recovery
5760	$R_{ijk} \rightarrow I_{[ijk]l}$	$\beta \delta R_{ijk} I_{*l} \Delta t$	$\Delta R_{ijk}(t) = -1,  \Delta I_{[ijk]l}(t) = 1$	Quaternary infection
6164	$I_{[ijk]l} \to R_{ijkl}$	$\sigma I_{[ijk]l}\Delta t$	$\Delta I_{[ijk]l}(t) = -1, \ \Delta R_{ijkl}(t) = 1$	Quaternary recovery
65	$\rightarrow S$	$\mid \mu N \Delta t \mid$	$\Delta S = 1$	Birth
66113	$All \rightarrow$	$\mu N \Delta t$	$\Delta S = \Delta I_* = \Delta R_* = -1$	Death
_114	No transition	$1-\sum_{i}p_{i}$	No change	

Where S are individuals susceptible to all 4 types of dengue,  $I_i$  infectious with Dengue type i,  $R_i$  individuals recovered from Dengue type i and  $N(t) = S(t) + I_*(t) + R_*(t)$  is the total population size at time t. Infectious individuals already on their secondary and later Dengue infections are represented by indices  $\{i, j, k, l\}$  which can take values in the close interval (1, 4). For example,  $I_{[23]1}$  is an individual which has had Dengues type 2 and 3 in the past – and therefore is immune to them – and is currently transmitting Dengue 1. The index outside the bracket denotes current infection. Recovered individuals indices denote their immunity, so for instance  $R_{123}$  is an individual which is immune to Dengue types 1, 2 and 3, but not to 4. Let  $I_{*i} = \sum I_{[...]i}$  with [...] representing exposure history of the infected individual which can vary from 0 to 3 in length. All individuals are born to the S state and birth and death rates are equal.

### Stochastic Model

Let's now assume that S(t),  $I_*(t)$  and  $R_*(t)$  are random variables representing the state of a stochastic process. The possible state-transitions and their probabilities are listed in table 1.

The stochastic model can be described as a continuous time Markov jump process. Let

$$\overrightarrow{X}(t) = [S(t), I_1(t), I_2(t), \dots, R_{1234}(t)]$$

be the state of the system at the time t.  $\sum X(t) = N, \forall t$  with N being the population size. The system is written as a forward Kolmogorov differential equation, which in matrix form looks like

$$\frac{dp_i(t)}{dt} = Qp_i(t) \tag{10}$$

Where  $p_i(t)$  is the vector of transition probabilities (given in table 1) and Q is the generator matrix, whose non-zero values are also given in table 1 (in the state change column). The full formula and matrices are ommitted due to their large sizes.

### **Expected Change and Covariance Matrix**

It is useful to calculate the expected change and the covariance matrix for the changes  $\Delta X = [\Delta S, \Delta I_1, \Delta I_2, \Delta I_3, \Delta I_4, \Delta R_1, \Delta R_2, \Delta R_3, \Delta R_4, \Delta I_{12}, \Delta I_{13}, \Delta I_{12}, \Delta I_{13}, \Delta I_{14}, \Delta I_{21}, \Delta I_{23}, \Delta I_{24}, \Delta I_{31}, \Delta I_{32}, \Delta I_{34}, \Delta I_{41}, \Delta I_{42}, \Delta I_{43}, \Delta R_{12}, \Delta R_{13}, \Delta R_{14}, \Delta R_{23}, \Delta R_{24}, \Delta R_{34}, \Delta I_{231}, \Delta I_{241}, \Delta I_{341}, \Delta I_{132}, \Delta I_{142}, \Delta I_{342}, \Delta I_{123}, \Delta I_{123}, \Delta I_{124}, \Delta I_{134}, \Delta I_{234}, \Delta I_{1234}, \Delta I_{1234}, \Delta I_{1234}, \Delta I_{1342}, \Delta I_{2341}, \Delta R_{1234}]^T.$ 

Thus from the probabilities of table 1,

$$E(\Delta X) = \sum_{i=1}^{114} p_i(\Delta X)_i = \begin{pmatrix} -\beta SI_{*1} + \mu N - \mu S \\ \vdots \\ \beta SI_{*4} + \mu N - \mu S \\ \beta SI_{*1} - \sigma I_1 - \mu I_1 \\ \vdots \\ \beta SI_{*4} - \sigma I_4 - \mu I_4 \\ \sigma I_1 - \beta \delta R_1 I_{*j} - \mu R_1 \\ \vdots \\ \sigma I_4 - \beta \delta R_4 I_{*j} - \mu R_4 \\ \beta \delta R_i I_{[i]j} - \sigma I_{[i]j} - \mu I_{[i]j} \\ \sigma I_{[i]j} - \beta \delta R_{ij} I_{*k} - \mu R_{ij} \\ \beta \delta R_{ij} I_{*k} - \sigma I_{[ij]k} - \mu I_{[ij]k} \\ \sigma I_{[ij]k} - \beta \delta R_{ijk} I_{*l} - \mu R_{ijk} \\ \beta \delta R_{ijk} I_{*l} - \sigma I_{[ijk]l} - \mu I_{[ijk]l} \\ \sigma I_{[ijk]l} - \mu R_{1234} \end{pmatrix}$$

$$(11)$$

The expected change,  $E(\Delta X)$ , is a 48 × 1 vector. The covariance matrix is a 48 × 48 matrix,  $\Sigma(\Delta X) = \sum_{i=1}^{114} p_i(\Delta X)_i(\Delta X)_i^T$