Supplementary: Prototype-based Incremental Few-Shot Semantic Segmentation

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1 Implementation details

1.1 Training protocol

In this section, we provide additional details on the training protocol used in our experiments. Note that we adopt the same protocol for all the methods, to ensure a fair comparison.

When fine-tuning we follow [**G**], using SGD as optimizer with momentum 0.9, weight decay 10^{-4} and a polynomial learning rate policy, *i.e.* $Ir = Ir_{init}(1 - \frac{iter}{max_iter})^{0.9}$. During training, we apply the same data augmentation of [**G**], performing random scaling and horizontal flipping, with a crop-size of 512×512 . While the previous hyperparameters are shared across settings, we use a different learning rate and number of training iterations depending on the dataset, number of shots and learning steps. In particular, in the base step we train the network for 30 epochs on Pascal-VOC and 20 epochs on COCO using learning rate 10^{-2} and batch size 24. For the FSL step t, we set the batch size to $min(10, |\mathcal{D}_t|)$. In the FSL steps of VOC-SS, we train for 1000 iterations with learning rate 10^{-3} , and for 200 iterations per step for VOC-MS, with learning rate 10^{-4} . On COCO FSL steps we use a learning rate 10^{-3} , training the model for 2000 iterations on COCO-SS, and 100 iterations on every step of COCO-MS. These training hyperparameters are shared by all methods.

1.2 Adapting baselines to iFSS and hyperparameters choice

In this section, we describe how we adapt the baselines reported in the main paper to iFSS and the value of their hyperparameters. We set the hyperparameters specific of each approach in the VOC-SS and COCO-SS 1-shot settings, using the first split of each dataset (*i.e.* 5-0 for VOC, and 20-0 for COCO) and maintaining the same values across all other shots, splits and number of learning steps.

For Weight Imprinting (WI), we adapted the work of [1] from image classification. In particular, we replaced the image-level feature extractor of [1] with masked average pooling (MAP), as described in Sec. 4.1 of the paper. This method does not require additional hyperparameters, and we initialize the prototypes for new classes while keeping the prototypes of old ones unaltered.

split	classes
5-0	aeroplane, bicycle, bird, boat, bottle
5-1	bus, car, cat, chair, cow
5-2	table, dog, horse, motorbike, person
5-3	plant, sheep, sofa, train, tv-monitor
	Table 1: Pascal-VOC class split.

Similarly, for Dynamic Weight Imprinting [I] (DWI), we implemented the classifier using the same attention mechanism and weight generator of [I], but we replaced the class-specific image-level features with the ones extracted through MAP. DWI uses a second meta-learning training stage on the base classes to refine the weight generator. We performed this step for 1000 iterations, with learning rate 1.0 and batch size 8, aggregating the gradient of 2 training episodes, as in [I]. After the meta learning stage, the method includes new classes in the FSL steps by weight imprinting, that we implemented with MAP, as for WI.

Rethinking FSL [12] (RT), refines the model during the base step by using self-distillation and fine-tunes the classifier on the FSL step. In particular, after the base step a copy of the model is stored and provides the target of the self-distillation loss, to the current model. This training phase uses the same hyperparameters of the base one. We stopped after one additional training round because we did not see clear improvements using more rounds at the expense of a longer training time. For iFSS, we applied the self-distillation loss pixel-wise. For the FSL steps, we trained the classifier for new classes starting from random weights and freezing the rest of the network. We multiplied the learning rate by 10 w.r.t. the Sec 1.1 on the FSL step, since this improved the performance on both datasets.

Adaptive Masked Proxies [\square] (AMP) has been implemented following details in [\square] uses a standard linear classification layer and, an L2-normalized MAP features as classifier for the new classes. We adapted AMP to work on both old and new classes using all the available annotations in the FSL dataset. In particular, as proposed by [\square] for continuous segmentation, we update the classifier weights for all the old classes appearing in the new dataset by computing a moving average with update rate $\alpha = 0.25$.

For Semantic Projection Network $[\[mathbf{III}]\]$ (SPN) we follow the implementation provided by the authors, using the combination of word2vec $[\[mathbf{S}]\]$ and fastText $[\[mathbf{S}]\]$ as class embeddings, using them directly as classifier weights. The method has no specific hyperparameters and we adapt it to iFSS by not retaining the old datasets in the learning steps.

We implemented the three incremental learning methods, Learning without Forgetting $[\Box]$ (LwF), Incremental Learning Techniques $[\Box]$ (ILT), and Modeling the Background $[\Box]$ (MiB), following the code provided by $[\Box]$. As regularizer, LwF and ILT apply a standard cross-entropy loss using the old network predictions as target, and ILT imposes an additional L2 constraint on the output of the backbone (*i.e.* the Resnet-101). MiB uses the revised cross-entropy and distillation losses as well as the classifier weights initialization for new classes. The weight of the distillation losses is 100 for LwF, 100 on both the L2 and the cross-entropy for ILT, and 10 for MiB.

Finally, for our model we set λ to 10 for all settings. We recall that for all the baseline we report in the paper, we used the same training protocol and architectures of PIFS.

1.3 Dataset class splits

We split both Pascal-VOC and COCO in 4 folds, following previous works in semantic segmentation [1, 11, 12, 13, 13]. Table 1 reports the detailed class folds for Pascal-VOC,

split	classes
20-0	person, airplane, boat, parking meter, dog, ele-
	phant, backpack, suitcase, sports ball, skate-
	board, wine glass, spoon, sandwich, hot dog,
	chair, dining table, mouse, microwave, refrig-
	erator, scissors
20-1	bicycle, bus, traffic light, bench, horse, bear,
	umbrella, frisbee, kite, surfboard, cup, bowl,
	orange, pizza, couch, toilet, remote, oven,
	book, teddy bear
20-2	car, train, fire hydrant, bird, sheep, zebra,
	handbag, skis, baseball bat, tennis racket, fork,
	banana, broccoli, donut, potted plant, tv, key-
	board, toaster, clock, hair drier
20-3	motorcycle, truck, stop sign, cat, cow, giraffe,
	tie, snowboard, baseball glove, bottle, knife,
	apple, carrot, cake, bed, laptop, cell phone,
	sink, vase, toothbrush
	Table 2: COCO class split.

taken from $[\square]$, and Table 2 the ones for the COCO dataset, taken from $[\square]$.

2 Influence of old classes annotations in iFSS

The few-shot learning steps (FSL) in our benchmark consider a dataset with 1, 2, or 5 images for each new class, randomly sampled from the set of images containing at least one pixel of that class, but *without* imposing any constraint about the presence of old classes. However, differently from [II], the few-shot datasets provide annotation for all available pixels, both for new and old classes. In this section, we first analyze the frequency with which old classes appears in few-shot learning steps, showing that they co-occurs rarely with new classes. Then, we compare the results of the settings using (non-strict IL) and not using (strict IL) old classes annotations.

2.1 Frequency of old classes in few-shot learning datasets

Fig.1 reports the percentage of images per old class averaged on all folds of the 5-shot settings. From the figure, we note that old classes rarely co-occur when learning new classes: the median is 1.56% of images per old class on VOC and 2.1% on COCO. The only exception is the *person* class that frequently appears in the few-shot dataset: in 32% of images in VOC and in 52% in COCO. Moreover, we note that many classes never appear with new classes, both in VOC, such as classes 4 (*boat*) and 10 (*cow*), and in COCO, *e.g.* classes 22 (*bear*) and 23 (*zebra*).

2.2 Comparison between iFSS in strict and non-strict settings

Tab. 3 reports the comparison among the strict and non-strict setting of some indicative methods, FT, WI [[11]], SPN [[16]], MIB [[1]] and PIFS, evaluating the impact of the background shift on them. We also report PIFS*, which uses the revised classification loss proposed by MIB [[1]] to deal with the background shift. First, we note that WI obtains the same results in the two settings since it is not affected by the annotation on old classes and it



Figure 1: Percentage of images containing the old class in the 5-shot setting datasets. We note that class *person* has class-ID 15 on VOC and 1 on COCO. The red line represents the median over all classes.

		I			v	OC-SS					1			C	oco-ss				
			1-shot			2-shot			5-shot			1-shot			2-shot			5-shot	
Method	Strict	mIoU-B	mIoU-N	HM															
FT		58.2	9.7	16.6	59.1	19.6	29.5	55.8	29.5	38.6	41.2	4.1	7.5	41.5	7.3	12.4	41.6	12.3	19.0
FT	1	55.0	10.2	17.2	55.5	19.2	28.5	43.7	26.8	33.2	35.3	4.5	8.0	32.8	7.4	12.1	26.9	11.1	15.7
WI [Í	62.6	15.4	24.8	63.2	19.2	29.4	63.2	21.7	32.3	43.8	6.9	11.9	44.2	7.9	13.5	43.6	8.7	14.6
WI [🛄]	1	62.6	15.4	24.8	63.2	19.2	29.4	63.2	21.7	32.3	43.8	6.9	11.9	44.2	7.9	13.5	43.6	8.7	14.6
SPN [[59.8	16.3	25.6	60.7	26.3	36.7	58.3	33.4	42.4	43.5	6.7	11.7	43.7	10.2	16.5	43.7	15.6	22.9
SPN [1	56.3	16.4	25.4	57.0	25.3	35.1	48.6	30.2	37.3	38.1	7.0	11.8	37.0	10.4	16.3	33.2	15.1	20.8
MIB \llbracket		61.0	5.2	9.6	63.5	12.6	21.1	64.9	28.1	39.2	43.8	3.5	6.5	44.4	6.0	10.6	44.7	11.9	18.8
MIB 🔲	1	61.0	6.0	11.0	63.5	13.7	22.5	64.9	29.4	40.4	43.7	4.2	7.7	44.2	7.1	12.3	44.4	13.8	21.1
PIFS		60.8	18.5	28.4	60.5	26.3	36.7	60.0	33.2	42.8	40.8	8.2	13.6	40.9	11.1	17.5	42.8	15.7	23.0
PIFS	1	59.1	18.2	27.9	58.8	26.1	36.2	57.2	32.5	41.5	34.9	8.9	14.2	34.6	11.7	17.4	32.6	15.6	21.1
PIFS*	1	60.3	18.0	27.7	60.3	26.3	36.6	59.5	33.0	42.5	38.8	8.8	14.4	39.2	11.8	18.1	38.4	16.1	22.6

Table 3: Performance in strict and non-strict incremental learning on single-step settings. In bold-red the best method in strict-IL scenario. In bold-blue, the best method in non strict-IL. PIFS* uses the revised classification loss proposed by MIB [**D**].

only uses new classes' pixels for generating the classifier weights. Differently, FT and SPN, suffer the background shift, as indicated by the large decrease in mIoU-B on all setting. MIB, being designed to solve deal with the background shift, even improves its performance, obtaining similar results in mIoU-B and improving its performance on mIoU-N. Finally, we note that PIFS is robust to the background shift on VOC but it decrease in performance on mIoU-B on COCO. Moreover, it obtains outstanding performance on new classes, constantly outperforming the competitors on mIoU-N. Introducing the cross-entropy loss of MiB [II] in PIFS, it notably improves the results on old classes, alleviating the background shift. We remark that introducing the loss of [III] is straightforward, since the choice of classification loss is independent from the prototype-learning and the distillation loss of PIFS.

3 Additional results3.1 Detailed results step-by-step

We report the results for every incremental step on the VOC-MS and COCO-MS settings in Fig. 2. For every incremental step, we report the harmonic mean (HM) between the mIoU on base (C^0) and new ($C^t \setminus C^0$) classes.

From the results, we note that fine-tuning (orange), RT $[\Box]$ (green, circle), and incremental learning methods $[\Box, \Box, \Box]$ (blue) obtain the worst performance on all settings. We argue that this is due to: i) not exploiting prototype learning, failing to correctly initialize and represent the new classes, and ii) not dealing with the non-*i.i.d.* data, as demonstrated by the



Figure 2: iFSS results on the sequential addition of new class. Every column is a new step.

poor performances obtained on VOC when few images are provided (1- and 2-shot settings). On the other hand, methods that perform prototype learning, such as few-shot classification methods [1], [1]] (green) and AMP [1]] (yellow, square), show a better trade-off between learning and forgetting. In particular, WI [11] and DWI [12] achieve good performance on VOC, being close to PIFS (red) especially on the 1-shot setting. However, we note that on VOC 5-shot and COCO, PIFS obtains better performances since it fine-tunes the network on the few-shot data, obtaining a better representation while avoiding overfitting. AMP [13], differently, is outperformed by PIFS, remarking that it is essential to update the network representation and not only the prototypes during the FSL steps. Finally, SPN [16] (yellow, triangle) achieves good performance on the initial steps of COCO-MS 2- and 5-shot settings, even surpassing PIFS. However, after only one (5-shot) or two (2-shot) learning steps its performances degrade and it is surpassed by PIFS. This demonstrates that PIFS improves the representation for new class pixels while better dealing with forgetting and non-*i.i.d.* data, even without using external knowledge. Overall, PIFS is consistently the best on every dataset and shot.

3.2 Detailed results for each split

Due to space constraints, in the main paper we report the average results across the 4 splits of classes of each dataset. Here, we report the detailed results in all folds separately, measuring them as the mIoU on base (mIoU-B) and new (mIoU-N) classes, and their harmonic mean (HM).

Pascal VOC. We report the results for Pascal-VOC with only one few-shot learning step (VOC-SS) on Tab. 5 for 1-shot, on Tab. 6 for 2-shot, and on Tab. 7 for 5-shot. The results on each fold are consistent with their average. PIFS is effective on all the VOC folds, being always the best on 1-shot, and always the best or second best on 2-shot scenario, in terms of HM. Moreover, we note that SPN is the second best on both 2-shot and 5-shot scenarios, on all folds. On 5-shot scenario incremental learning methods become competitive to PIFS, being ILT the best on 5-0 (+1.7% HM w.r.t. PIFS) and LwF on 5-1 (+3.4% HM w.r.t. PIFS). However the improvement of these methods is not consistent in other folds (*e.g.* 5-3, where PIFS improves ILT of 5.1% in HM), obtaining an average performance lower than PIFS.

Tables 8, 9, and 10 report the results (averaged per FSL step) for the multi step scenario

(VOC-MS), for the 1, 2, and 5 shot respectively. We remark that this setting is particularly challenging since methods are provided only with 1, 2 or 5 images of the same class to train, resulting in very unbalanced and non-*i.i.d* set. In this setting, PIFS obtains the best results on 5-1, 5-2, and 5-3, in both 1, 2, and 5-shot setting, achieving the second best results on 5-0 on 2 and 5-shot. We note that methods obtaining excellent performance on VOC-SS struggle on this scenario. In particular, SPN performances are lower than PIFS of 15% HM on average, while incremental learning methods are not able to learn new classes properly, performing close to standard fine-tuning. On the other hand, DWI and WI are effective on this scenario, since they can integrate new classes without forgetting previous knowledge. DWI is the second best method on both 1, 2, and 5-shot, being the best on the 5-0 fold. However, PIFS still outperforms it by 0.5% HM on 1-shot, 2.1% HM on 2-shot, and 1.7% HM on 5-shot.

COCO. The results for COCO-SS are reported on tables 11 (1-shot), 12 (2-shot), and 13 (5-shots). From the tables we can see that PIFS is consistently best or second best on every shot and fold. It achieves nearly 1% HM more than the second best method in 1-shot (13.6% w.r.t. DWI 12.8%) and in 2-shot (17.5% w.r.t. SPN 16.5%). Differently, on 5-shot SPN achieves comparable performance to PIFS, *i.e.* 22.9% vs 23.0 HM. From the detailed results on the folds we can see that while SPN obtains better results on 20-0 and 20-1 (+1.0% HM and +0.3% HM respectively), PIFS outperforms it on 20-2 and 20-3 (+0.5% and +1.3% HM).

Finally, we report the results for COCO-MS on tables 14 (1-shot), 15 (2-shot), and 16 (5-shot). Also in this setting PIFS is always the best or second best method across all shots and folds. In particular, it is the best on 1-shot on every fold, outperforming the second best method (DWI) by 1.3% HM on average. On the 2-shot setting, PIFS is the best on 20-0 (+1.8% HM w.r.t. SPN) and 20-1 (+1.2% HM w.r.t. RT) folds, being second best on 20-2 (-1.2% HM w.r.t. SPN) and 20-3 (-0.8% HM w.r.t. SPN). Overall, PIFS outperforms the second best method, SPN, by 0.6% HM. In the 5-shot setting, the performance of PIFS and SPN are on par, achieving very similar results for both old and new classes. In particular, comparing them on the different folds, we see that they maintain very close performances, *i.e.* in terms of HM, 22.9% vs 23.3% on 20-0, 22.3% vs 21.5% on 20-1, 26.4% vs 26.5% on 20-2, 29.5% vs 29.4% on 20-3, respectively for PIFS and SPN.

3.3 Prototype learning offline performance

An open question from our results is whether prototype learning in the base step hampers the performance of the pretrained segmentation network. Ideally, we would like the model to retain the performance of a standard semantic segmentation model when trained offline, while keeping the advantage of prototype learning for the FSL steps.

In this section, we show that prototype learning performs on par to other learning techniques in a standard offline setting, *i.e.* when all the classes are learned in one step. To demonstrate this, in Tab. 4 we report the results for a linear classifier trained with crossentropy (std), SPN [IIG], and PIFS on the base step of COCO. From the results we can see that our model is competitive with both choices, achieving an average mIoU of 52.1% vs 53.0% of SPN and 52.9% of standard training. Note that while PIFS performs comparably to other approaches in the offline scenario, the improvement on the incremental few-shot learning settings is remarkable, as demonstrated in previous experiments.

3.4 Additional qualitative results

Due to space constraints, in the paper we report only the qualitative results for VOC-SS 1shot. Here, we expand the analysis by reporting the results for other scenarios, *i.e.* COCO-SS

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Method	Mean	20-0	20-1	20-2	20-3
std	52.9	49.8	52.6	55.1	54.2
SPN [53.0	49.5	53.2	54.7	54.6
PIFS	52.1	47.9	51.6	54.4	54.3

Table 4: mIoU on base classes, before the few-shot steps, comparing the Prototype Learning (PIFS) with a standard classifier (std) and SPN [II] on the COCO dataset.

			Mean			5-0			5-1			5-2			5-3	
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	58.3	9.7	16.7	61.9	3.2	6.1	55.2	16.3	25.2	53.6	13.1	21.1	62.4	6.3	11.5
r \	WI [62.7	15.5	24.8	66.5	10.5	18.1	58.9	21.9	31.9	58.6	15.3	24.2	66.7	14.2	23.5
ŝ	DWI [64.3	15.4	24.8	67.3	10.3	17.9	59.9	23.3	<u>33.5</u>	60.0	16.0	25.3	69.9	11.8	20.2
щ	RT [💶]	59.1	12.1	20.1	62.7	3.8	7.1	54.5	18.7	27.9	56.3	14.6	23.2	63.1	11.4	19.3
S	AMP 🗖	57.5	16.7	25.8	61.7	12.0	20.1	49.8	22.9	31.4	54.8	15.3	23.9	63.5	16.5	26.1
F	SPN [59.8	16.3	25.6	64.1	9.0	15.8	56.2	23.9	<u>33.5</u>	56.2	19.3	28.7	62.7	13.1	21.7
_	LwF [61.5	10.7	18.2	63.7	2.8	5.3	59.0	19.3	29.0	59.1	14.1	22.8	64.0	6.6	11.9
Ц	ILT 🔲	64.3	13.6	22.5	67.1	5.9	10.8	60.5	19.3	29.2	61.2	18.9	28.9	68.4	10.3	18.0
	MiB 🔲	61.0	5.2	9.7	64.6	3.1	6.0	56.9	7.6	13.4	57.3	6.3	11.4	65.4	3.9	7.4
	PIFS	60.9	18.6	28.4	64.4	12.7	21.2	54.3	25.1	34.3	57.1	20.3	29.9	67.6	16.2	26.1

Table 5: iFSS: VOC-SS 1-shot.

1-shot, COCO-SS 2-shot and VOC-SS 2-shot.

Fig. 3 shows some qualitative results for different methods on COCO-SS 1-shot. From the figure, we can see how PIFS better discriminates the new class w.r.t. other approaches. Overall, we see that WI and DWI tend to assign pixels to new classes even when they are outside the class of interest (*e.g. dog* second row, *wc*, fourth row), while ILT and SPN may either ignore pixels of new classes (*e.g. surfboard* third row) or assign them to old ones (*e.g. elephant* first row). On the other hand, PIFS correctly segments both old and new classes, even in images with clutter (*e.g. surfboard* third row), multiple instances (*e.g. sheep* last row) and complex boundaries (*e.g. dog* second row).

In Fig. 4 and Fig. 5 we show results for the VOC-SS and COCO-SS 2-shot settings. Similarly to VOC-SS 1-shot and COCO-SS 1-shot, non-finetuned methods (WI, DWI) may not discriminate new classes, when they are similar to base ones, making incoherent predictions. Examples are cow and bus (first and second rows of Fig. 4) mistakenly segmented as horse (purple) and train (light-green) respectively, and giraffe (fifth row of Fig. 5) segmented as zebra (blue). SPN and ILT may not properly learn to segment new classes when trained with few complex examples. For instance, both methods fail to segment motorcycle (third row Fig. 4) and sofa (Fig. 5, fourth row), where training images are either small and in cluttered environments (e.g. motorcycle) or mixed with other classes (e.g. dogs in sofa). In contrast, PIFS precisely segments new classes, discriminating them from old ones. For instance, our model correctly segments the multiple instances of *motorcycle* and *sheep* (last row) in Fig. 4, while separating pixels of cat and dog from the new class sofa in Fig. 5. Interestingly, PIFS can correctly discriminate almost all pixels of the new classes (e.g. cow, second row of Fig. 4, bear and sandwich in Fig. 5 second and third rows), despite their similarities (e.g. cow with horse) or large difference (e.g. bear) with old ones, or the presence of multiple other classes (e.g. sandwich).

References

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			Mean	- 1		5-0			5-1			5-2			5-3	
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	59.1	19.7	29.5	61.7	12.6	20.9	57.5	31.0	40.3	54.8	20.2	29.5	62.5	15.0	24.2
r \	WI [🛄]	63.3	19.2	29.5	67.1	13.1	21.9	59.0	28.2	38.2	59.3	18.1	27.7	67.7	17.5	27.8
ŝ	DWI 🚺	64.8	19.8	30.4	68.2	15.1	24.7	60.4	30.9	40.9	60.4	17.2	26.8	70.1	16.2	26.3
щ	RT [🗖]	60.9	21.6	31.9	65.3	10.4	18.0	54.4	34.6	42.3	59.2	24.3	34.5	64.7	17.0	27.0
S	AMP 🗳	54.4	18.8	27.9	59.7	12.5	20.7	44.5	28.4	34.7	53.4	17.2	26.0	59.8	17.0	26.5
Ľ	SPN [🖽]	60.8	26.3	36.7	65.5	18.8	29.2	57.1	37.4	45.2	57.8	25.6	35.5	62.7	23.4	<u>34.1</u>
	LwF 🖪	63.6	18.9	29.2	65.2	10.8	18.6	61.8	31.3	41.6	60.9	21.0	31.3	66.5	12.6	21.2
Ц	ILT [64.2	23.1	34.0	68.4	16.1	26.1	58.3	33.7	42.7	61.1	25.6	36.1	68.9	17.1	27.4
	MiB 🔲	63.5	12.7	21.1	66.6	12.3	20.7	60.1	18.3	28.0	59.7	11.2	18.8	67.7	9.0	15.8
	PIFS	60.5	26.4	36.8	64.0	18.9	<u>29.1</u>	53.9	36.6	<u>43.6</u>	58.2	26.5	36.4	65.9	23.6	34.7

Table 6: iFSS: VOC-SS 2-shot.

			Mean			5-0			5-1			5-2			5-3	
	Method	mIoU-B	mIoU-N	HM												
_	FT	55.8	29.6	38.7	58.4	22.8	32.8	52.3	42.7	47.0	50.6	29.7	37.5	62.0	23.0	33.6
-	WI [🛄]	63.3	21.7	32.3	67.5	16.3	26.3	58.7	30.8	40.4	59.4	21.3	31.4	67.5	18.4	28.9
ŝ	DWI 🖪	64.9	23.5	34.5	68.8	20.7	31.8	60.8	34.7	44.2	60.9	20.6	30.7	69.1	17.9	28.5
щ	RT [💶]	60.4	27.5	37.8	65.6	19.1	29.6	55.8	38.8	45.8	55.1	29.3	38.3	65.0	22.9	33.9
s	AMP 🗖	51.9	18.9	27.7	58.5	12.9	21.2	38.5	26.5	31.4	51.9	20.4	29.3	58.5	15.8	24.8
H	SPN [58.4	33.4	<u>42.5</u>	63.3	28.2	<u>39.0</u>	53.4	43.7	<u>48.1</u>	54.5	33.5	41.5	62.3	28.2	<u>38.8</u>
	LwF [59.7	30.9	40.8	62.8	23.9	34.6	57.1	44.0	49.7	55.9	31.6	40.3	63.0	24.4	35.2
Ц	ILT [61.4	32.0	42.1	67.2	27.8	39.4	54.2	40.4	46.3	57.1	33.8	<u>42.4</u>	67.0	26.1	37.5
	MiB 🔳	65.0	28.1	39.3	68.0	24.8	36.4	62.1	35.2	44.9	60.6	27.1	37.4	69.1	25.4	37.2
_	PIFS	60.0	33.3	42.8	64.3	26.7	37.7	53.3	41.0	46.3	57.4	33.8	42.5	65.2	31.6	42.6

Table 7: iFSS: VOC-SS 5-shot.

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	I		Mean	1		5-0			5-1			5-2			5-3	
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	47.2	3.9	7.2	46.8	2.0	3.8	42.0	8.0	13.4	47.3	3.5	6.5	52.7	2.1	4.0
r.\	WI [66.6	16.1	25.9	68.8	14.9	24.5	63.5	24.4	35.3	63.3	14.3	23.4	70.9	10.6	18.5
ŝ	DWI 🖪	67.2	16.3	26.2	69.0	15.7	25.6	63.6	25.8	<u>36.7</u>	64.1	13.6	22.5	71.9	10.0	17.6
щ	RT [💶]	49.2	5.8	10.4	45.4	2.2	4.2	41.5	12.4	19.1	46.7	4.8	8.6	53.3	4.5	8.2
ŝ	AMP 🗳	58.6	14.5	23.2	61.6	12.1	20.2	54.5	22.8	32.1	56.1	11.8	19.5	62.4	11.3	19.1
Ę	SPN [49.8	8.1	13.9	48.7	3.6	6.6	44.0	13.7	20.9	51.4	8.7	14.9	55.0	6.5	11.7
	LwF 🖪	42.1	3.3	6.2	42.1	1.8	3.4	37.9	6.8	11.5	41.4	2.5	4.7	47.1	2.2	4.3
Ц	ILT 🔲	43.7	3.3	6.1	42.3	1.7	3.3	41.0	6.1	10.6	41.9	3.5	6.4	49.6	1.8	3.4
	MiB 🔲	43.9	2.6	4.9	41.0	1.0	2.0	40.2	5.8	10.2	43.4	2.4	4.5	51.0	1.1	2.2
	PIFS	64.1	16.9	26.7	67.6	13.3	22.3	58.0	27.1	36.9	61.0	15.6	24.9	69.8	11.5	19.8

Table 8: iFSS: VOC-MS 1-shot.

		Mean				5-0			5-1			5-2			5-3	
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	53.5	4.4	8.1	54.5	2.3	4.5	51.2	8.9	15.2	51.5	4.3	7.9	56.9	2.2	4.3
r \	WI [66.6	19.8	30.5	69.1	17.1	27.4	63.7	31.9	42.5	63.5	16.7	26.5	70.3	13.5	22.7
SC	DWI 🗳	67.5	21.6	<u>32.7</u>	69.7	21.3	32.6	63.9	35.4	<u>45.6</u>	64.3	15.8	25.4	72.0	14.0	<u>23.5</u>
щ	RT [💶]	36.0	4.9	8.6	43.8	3.1	5.8	23.0	7.2	11.0	28.3	5.3	9.0	40.7	4.7	8.5
S	AMP 🗖	58.4	16.3	25.5	62.3	12.3	20.6	54.0	27.2	36.1	55.9	14.7	23.3	61.5	10.8	18.4
FS	SPN [🛄]	56.4	10.4	17.6	58.3	5.8	10.6	54.0	18.2	27.2	55.6	10.4	17.5	57.8	7.3	13.0
	LwF 🖪	51.6	3.9	7.3	50.7	1.9	3.7	49.4	8.6	14.7	50.4	3.4	6.3	55.9	1.7	3.4
Н	ILT 🔲	52.2	4.4	8.1	50.7	2.0	3.9	51.6	9.7	16.3	49.9	4.0	7.4	56.8	1.7	3.4
	MiB 🔲	51.9	2.1	4.0	52.7	1.7	3.4	47.9	3.4	6.4	50.6	2.5	4.7	56.4	0.8	1.5
	PIFS	65.2	23.7	34.8	68.0	17.7	28.1	61.3	40.4	48.7	62.5	21.8	32.4	69.2	15.0	24.7

Table 9: iFSS: VOC-MS 2-shot.

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			Mean			5-0			5-1			5-2			5-3	
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	58.7	7.7	13.6	59.9	5.1	9.5	57.0	14.8	23.5	55.9	7.1	12.5	62.5	3.7	7.0
<i>r</i> \	WI [🛄]	66.6	21.9	33.0	69.6	20.4	31.5	63.4	32.9	43.3	63.4	20.1	30.6	69.9	14.3	23.8
ŝ	DWI 🚺	67.6	25.4	<u>36.9</u>	70.3	27.9	39.9	64.1	38.0	<u>47.7</u>	64.5	19.6	30.1	71.5	16.0	26.1
щ	RT [🗖]	45.1	10.0	16.4	52.5	7.3	12.7	35.4	16.7	22.7	39.4	9.3	15.0	53.1	6.9	12.2
S	AMP 🖪	57.1	17.2	26.4	62.5	13.5	22.2	50.1	25.3	33.7	55.1	18.7	28.0	60.8	11.2	18.9
F	SPN [61.6	16.3	25.8	62.3	10.4	17.9	59.5	27.6	37.7	60.3	14.7	23.7	64.2	12.3	20.6
_	LwF 🖸	59.8	7.5	13.4	60.7	5.2	9.6	57.8	14.6	23.3	57.4	6.8	12.2	63.3	3.5	6.6
Ц	ILT 🔲	59.0	7.9	13.9	59.9	5.4	9.8	57.0	15.0	23.8	56.0	7.1	12.6	62.9	4.0	7.6
	MiB 🔲	60.9	5.8	10.5	61.0	4.8	8.9	58.4	9.6	16.5	59.5	5.9	10.8	64.9	2.7	5.2
	PIFS	64.5	27.5	38.6	67.4	23.8	<u>35.2</u>	60.4	41.6	49.3	61.6	25.4	35.9	68.6	19.0	29.8

Table 10: iFSS: VOC-MS 5-shot.

		Mean mIoU-B mIoU-N HM				20-0			20-1			20-2			20-3	
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	41.2	4.1	7.5	36.2	2.0	3.8	40.6	4.9	8.7	45.0	3.7	6.8	43.1	5.8	10.3
<i>r</i>)	WI [43.8	6.9	11.9	41.0	4.8	8.6	42.8	7.8	13.2	46.4	6.8	11.8	45.1	8.1	13.8
ŝ	DWI 🖪	44.5	7.5	12.8	39.8	5.0	<u>8.9</u>	44.4	8.2	<u>13.9</u>	47.2	6.8	11.9	46.6	9.9	16.4
щ	RT [💶]	46.2	5.8	10.2	39.4	3.4	6.2	46.5	6.1	10.8	50.4	5.3	9.6	48.4	8.2	14.1
Ś	AMP 🗳	37.5	7.4	12.4	33.4	4.8	8.4	37.4	8.4	13.8	39.9	8.7	14.2	39.1	7.8	13.0
Ł	SPN 🖽	43.5	6.7	11.7	39.2	4.6	8.2	43.7	6.4	11.1	46.8	7.1	12.3	44.3	8.9	14.8
	LwF 🖪	43.9	3.8	7.0	37.8	1.8	3.4	43.7	4.3	7.9	47.9	3.7	6.8	46.1	5.4	9.6
Ц	ILT [46.2	4.4	8.0	40.7	2.4	4.5	46.0	4.4	8.1	50.3	4.7	8.6	47.8	6.0	10.6
	MiB 🔲	43.8	3.5	6.5	37.5	2.1	4.0	44.1	3.6	6.6	47.6	3.9	7.1	46.0	4.4	8.1
	PIFS	40.8	8.2	13.6	38.6	5.4	9.5	39.7	8.6	14.2	43.5	7.7	13.1	41.4	10.9	17.2

Table 11: iFSS: COCO-SS 1-shot.

			Mean			20-0			20-1			20-2			20-3	
_	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM									
_	FT	41.5	7.3	12.4	37.4	4.2	7.6	40.3	9.0	14.7	45.4	7.7	13.2	43.1	8.4	14.0
-	WI [🛄]	44.2	7.9	13.5	41.8	5.2	9.2	43.3	9.8	16.0	46.8	7.6	13.1	44.7	9.2	15.3
ŝ	DWI 🖪	45.0	9.4	15.6	40.4	6.1	10.6	45.2	10.7	17.4	47.4	9.1	15.3	46.9	11.8	18.8
щ	RT [🗳]	46.7	8.8	14.8	40.6	5.5	9.7	46.8	10.5	17.2	50.8	8.1	14.0	48.5	11.1	18.1
S	AMP 🗖	35.7	8.8	14.2	30.9	5.8	9.8	36.2	10.5	16.3	38.4	9.2	14.8	37.3	9.9	15.6
Ľ.	SPN 🗖	43.7	10.2	<u>16.5</u>	40.0	6.7	<u>11.5</u>	43.3	11.5	<u>18.1</u>	47.0	10.7	<u>17.5</u>	44.6	11.9	18.7
	LwF 🖪	44.3	7.1	12.3	39.2	4.5	8.0	43.8	8.7	14.5	48.1	7.3	12.7	46.0	8.0	13.6
Ц	ILT 🔲	46.3	6.5	11.5	40.5	4.5	8.1	46.3	7.1	12.3	50.4	6.7	11.8	48.1	7.9	13.5
	MiB 🔲	44.4	6.0	10.6	38.2	4.2	7.6	44.5	7.1	12.3	48.6	6.5	11.4	46.3	6.1	10.8
	PIFS	40.9	11.1	17.5	38.6	6.8	11.6	39.4	13.1	19.7	43.5	11.4	18.1	42.2	13.1	20.0

Table 12: iFSS: COCO-SS 2-shot.

			Mean			20-0			20-1			20-2			20-3	
	Method	mIoU-B	mIoU-N	HM												
	FT	41.6	12.3	19.0	37.3	7.6	12.6	40.9	15.0	22.0	45.3	13.7	21.0	43.0	12.9	19.8
-	WI [🛄]	43.6	8.7	14.6	41.7	6.0	10.5	42.8	10.7	17.1	45.7	8.6	14.4	44.4	9.7	15.9
SC	DWI 🗳	44.9	12.1	19.1	40.5	8.2	13.6	45.3	14.4	21.9	47.0	12.2	19.4	46.7	13.7	21.2
щ	RT [🗖]	46.9	13.7	21.2	41.1	9.5	15.4	46.4	15.9	23.7	50.7	13.8	21.6	49.1	15.7	23.8
S	AMP 🗳	34.6	11.0	16.7	31.2	7.2	11.6	34.8	14.5	20.4	36.9	10.9	16.8	35.6	11.5	17.4
H	SPN [🖽]	43.7	15.6	22.9	40.1	11.5	17.9	42.9	17.7	25.1	46.4	16.4	24.2	45.4	16.6	24.4
	LwF 🖪	44.6	12.9	20.1	39.6	8.0	13.3	43.7	15.9	23.3	48.6	14.1	21.9	46.4	13.8	21.2
Ц	ILT 🔲	47.0	11.0	17.8	41.9	7.1	12.2	47.0	13.9	21.5	50.4	11.2	18.3	48.6	11.8	19.0
	MiB 🔲	44.7	11.9	18.8	38.2	8.1	13.4	44.9	13.9	21.2	49.0	13.4	21.0	46.7	12.2	19.3
	PIFS	42.8	15.7	23.0	40.6	10.7	16.9	41.5	17.7	24.8	45.3	16.9	24.7	43.9	17.5	25.0

Table 13: iFSS: COCO-SS 5-shot.

	ļ	Mean			20-0			20-1				20-2		20-3		
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	38.5	4.8	8.6	33.3	3.8	6.8	39.8	3.6	6.6	40.3	4.1	7.5	40.5	7.8	13.1
FSC	WI [🛄]	46.3	8.3	14.0	42.6	5.6	9.9	45.9	9.1	15.2	48.9	8.1	13.8	47.9	10.3	17.0
	DWI 🖪	46.2	9.2	<u>15.3</u>	41.0	5.7	9.9	46.5	9.7	16.0	48.8	8.6	14.7	48.6	12.7	<u>20.1</u>
	RT [🗳]	38.4	5.2	9.1	34.4	2.5	4.6	42.2	5.7	10.1	45.1	6.0	10.6	31.8	6.4	10.7
Ś	AMP [36.6	7.9	13.1	34.0	6.7	11.2	36.7	8.0	13.2	38.5	8.2	13.6	37.2	8.8	14.2
FS	SPN [40.3	8.7	14.3	37.1	7.5	12.4	41.1	7.0	11.9	42.3	8.2	13.7	40.6	12.2	18.8
Ц	LwF 🖪	41.0	4.1	7.4	35.5	3.3	6.0	42.4	2.7	5.2	42.9	3.8	6.9	43.1	6.6	11.4
	ILT 🔲	43.7	6.2	10.8	38.5	4.8	8.5	45.0	4.8	8.7	45.8	5.2	9.4	45.5	10.0	16.4
	MiB 🔲	40.4	3.1	5.8	32.8	1.2	2.4	41.5	2.3	4.4	43.9	3.9	7.1	43.4	5.0	9.0
	PIFS	40.4	10.4	16.6	37.0	8.3	13.6	40.5	10.0	16.0	42.0	9.1	15.0	42.3	14.3	21.4

Table 14: iFSS: COCO-MS 1-shot.

		Mean			20-0			20-1				20-2		20-3		
	Method	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM	mIoU-B	mIoU-N	HM
	FT	40.3	6.8	11.7	36.4	5.5	9.5	40.4	5.1	9.0	42.5	6.0	10.6	41.8	10.8	17.1
FSC	WI [46.5	9.3	15.4	43.2	5.8	10.3	46.1	10.0	16.4	49.1	9.5	15.9	47.5	11.7	18.8
	DWI [46.5	11.4	18.3	35.8	7.1	11.8	39.4	9.3	15.0	41.2	9.4	15.4	43.1	7.8	13.3
	RT [💶]	43.8	10.1	16.4	38.6	5.6	9.8	44.3	11.3	18.0	47.0	8.7	14.6	45.2	14.7	22.2
ŝ	AMP 🗖	36.0	9.2	14.6	33.2	7.9	12.8	36.7	8.9	14.3	37.9	8.7	14.2	36.4	11.2	17.2
FS	SPN [41.7	12.5	19.2	38.4	8.8	<u>14.3</u>	41.9	10.1	16.3	44.0	13.6	20.8	42.5	17.3	24.6
	LwF 🖪	42.7	6.5	11.3	38.1	6.3	10.9	43.3	4.9	8.8	44.6	5.6	9.9	44.7	9.4	15.5
Ц	ILT [47.1	10.0	16.5	46.5	7.1	12.3	48.5	8.0	13.7	47.7	13.2	20.7	45.7	11.9	18.8
	MiB 🔲	42.7	5.2	9.3	36.9	3.4	6.3	43.6	4.0	7.3	45.6	5.9	10.4	44.8	7.5	12.8
	PIFS	40.1	13.1	19.8	37.2	10.3	16.1	39.9	12.7	19.2	42.4	12.7	<u>19.6</u>	41.0	16.8	23.8

Table 15: iFSS: COCO-MS 2-shot.

			Mean			20-0			20-1			20-2			20-3	
	Method	mIoU-B	mIoU-N	HM												
	FT	39.5	11.5	17.8	36.1	11.1	17.0	38.4	9.3	15.0	42.0	10.6	16.9	41.5	14.8	21.8
r >	WI [46.3	10.3	16.8	43.4	7.3	12.4	45.7	11.1	17.8	48.7	10.5	17.2	47.4	12.3	19.5
S	DWI 🔲	46.6	14.5	22.1	35.8	7.1	11.8	39.4	9.3	15.0	41.2	9.4	15.4	43.1	7.8	13.3
щ	RT [🗖]	44.1	16.0	23.5	39.8	11.8	18.3	44.1	16.2	23.7	47.0	15.7	23.6	45.4	20.2	28.0
\sim	AMP 🖪	33.2	11.0	16.5	30.8	9.3	14.2	33.5	11.6	17.3	34.5	10.2	15.8	34.0	12.9	18.7
FS	SPN [41.4	18.2	25.3	37.9	16.8	23.3	41.0	14.6	21.5	44.0	19.0	26.5	42.8	22.4	<u>29.4</u>
	LwF 🖪	42.3	12.6	19.4	38.7	12.3	18.6	41.6	10.6	16.9	44.7	11.5	18.2	44.4	16.1	23.6
Н	ILT [45.3	15.3	22.8	41.1	14.5	21.4	45.3	13.7	21.0	47.8	14.1	21.8	47.1	18.8	26.9
	MiB 🔲	43.8	11.5	18.2	38.3	10.1	16.0	44.4	9.4	15.6	46.4	11.4	18.4	46.2	14.8	22.4
	PIFS	41.1	18.3	25.3	38.2	16.3	22.9	39.7	15.5	22.3	43.7	18.9	26.4	42.7	22.6	29.5

Table 16: iFSS: COCO-MS 5-shot.



Train

TestWIDWIILTSPNPIFSFigure 3: Qualitative results on the COCO-SS 1-shot setting.

GT



Test WI DWI ILT SPN **PIFS** Figure 4: Qualitative results on the VOC-SS 2-shot setting.



 Test
 WI
 DWI
 ILT
 SPN
 PIF

 Figure 5: Qualitative results on the COCO-SS 2-shot setting.