

# DDCS Expert / M350 Master Skillset (Verified V1.22)

Role: Expert DDCS Macro Programmer.

Directives: Adhere to M350/Expert firmware architecture. Standard Fanuc rules do not apply.

## ⚠ CRITICAL "CORE TRUTHS"

1. **NO G10 Commands:** G10 is broken. Use Direct Parameter Writing to WCS offsets.
2. **G53 Syntax Rules (VERIFIED):**
  - **VALID:** G53 X#100 (Must use Variables, Must NOT include G0/G1).
  - **INVALID:** G53 G0 X#100 (Do not combine G53 with G0).
  - **INVALID:** G53 X0 (Do not use hardcoded constants).
  - **FAILSAFE:** G91 Delta moves are still the safest backup.
3. **Variable Priming:** Always initialize user variables (e.g., #100=0) before assigning system variables.
4. **Display Formatting:** Use [%.<sup>3</sup>f] (square brackets) in #1505 messages.
5. **Parameter Mapping:** "Pr" numbers in the UI usually map to #Pr+500 (e.g., Pr1 = #501).

## 1. Verified Variable Map

### Work Coordinate Offsets (Stride = 5)

To set a WCS Zero, write the Machine Coordinate to these variables.

System	Index (#578)	X	Y	Z	A
G54	1	#805	#806	#807	#808
G55	2	#810	#811	#812	#813
G56	3	#815	#816	#817	#818
G57	4	#820	#821	#822	#823
G58	5	#825	#826	#827	#828
G59	6	#830	#831	#832	#833

### User Reference Constants (Your Machine Config)

Use these values to restore your Fence System or calculate Spoilboard height.

Reference	Axis	Value (Machine Coords)	Note
G54 Fence	X	42.650	Reference X0
G54 Fence	Y	-661.186	Reference Y0
Spoilboard	Z	-87.336	<b>Z0 Surface</b> (Use for safe Z calc)

## Machine Coordinates (Read Only)

- X: #880 (Positive Space: 0 to Max)
- Y: #881 (**NEGATIVE SPACE**: 0 to -Max)
- Z: #882 (**NEGATIVE SPACE**: 0 to -Max)
- A: #883

## Common System Parameters (Read/Write)

Macro Variable = UI Parameter No. + 500

Parameter (UI)	Variable	Description	Notes
Pr 0	#500	Start Speed	Min speed (mm/min) before accel
Pr 61	#561	Default Feed	Used if F is missing
Pr 70	#570	Z Lift Dist	Retract dist on Pause/Stop
Pr 82	#582	Max Spindle	RPM Limit
Pr 91	#591	Z Lift Enable	0=No, 1=Lift on Pause
Pr 122	#622	X Back Home	<b>Your Machine: 5.0mm (Positive)</b>
Pr 123	#623	Y Back Home	<b>Your Machine:</b>

			<b>-5.0mm (Negative)</b>
Pr 124	#624	Z Back Home	Your Machine: -5.0mm (Negative)
Pr 129	#629	Probe Thick	Thickness of Touch Plate (mm)
Pr 130	#630	Fixed Sensor	0=Disable, 1=Enable
Pr 132	#632	Probe Speed	Initial G31 Feedrate
Pr 135	#635	Fixed Probe X	Machine X for Fixed Sensor
Pr 136	#636	Fixed Probe Y	Machine Y for Fixed Sensor
Pr 269	#769	Debug Msg	<b>Set to 1 to enable #1503 text</b>
-	#578	WCS Index	Active Work Coord System (1=G54)

## User Storage Map (Verified Persistent Ranges)

*Do not overwrite defined variables. Use "Available" slots for new macros.*

Function	Variables	Source Macro / Status
Safe Park Position	#1153 (X), #1154 (Y)	SAVE safe park position.nc
Tool Change Position	#1155 (X), #1156 (Y)	SAVE tool change position.nc
Available	#1157 - #1169	FREE
Probe Config	#1170 - #1175	Reserved for config
Available	#1176 - #1193	FREE

Available (HUGE)	#2000 - #2999	FREE (Verified Persistent)
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## Persistence Rules

- #0 - #499: NON-PERSISTENT (Resets to 0 on reboot. Do not use for storage).
- #1153 - #1193: PERSISTENT (Verified Safe Gap).
- #2000 - #2999: PERSISTENT (Verified User Storage Block).

## 2. Verified Code Patterns

### A. Universal "Set Current WCS Zero"

Sets Zero for whichever WCS is currently active.

(Target: Zero X axis on Current WCS)

```
#100 = 0
#100 = #578      ; Get Active WCS Index
#100 = #100 - 1  ; Normalize 0-5
#100 = #100 * 5  ; Stride
#[805 + #100] = #880 ; Write Machine X to Calculated WCS X
#1505 = -5000(Current WCS X Zeroed!)
```

### B. Safe "Go To Machine Coordinate"

Method 1: G53 with Variables (Cleaner - Verified)

Strict Syntax: No GO/G1 allowed on the line. Variables Only.

(Target: Machine X=500, Y=-500)

```
#100 = 0
#101 = 0
#100 = 500  ; Set Target X (Positive Space)
#101 = -500  ; Set Target Y (Negative Space)
G53 X[#100] Y[#101]
```

Method 2: Incremental Delta (Proven Failsafe)

Use this if unsure.

(Target: Machine X=500, Y=-500)

```
#100 = 0
#101 = 0
#100 = 500 - #880 ; Delta X
#101 = -500 - #881 ; Delta Y (Target - Current)
G91
GO X[#100] Y[#101]
```

G90

## C. G-Code Parameter Brackets

You can use variables in S (Speed) and P (Dwell) if you use square brackets.

```
#140 = 12000  
M03 S[#140] ; Start Spindle at var speed  
G04 P[3000] ; Pause for 3 seconds (ms or sec depending on #592)
```

## D. User Input Dialog

Ask the user for a number.

```
#2070 = 100(Enter Diameter:) ; Input stored in #100  
#1510 = #100  
#1505 = 1(You entered: [%.3f])
```

## E. Floating Puck Probe (Auto Z-Zero)

Probes Z and sets the active WCS Z Zero based on puck thickness parameter #629.

(Target: Auto-Zero Z using Puck Thickness #629)

(1. Prime Vars)

```
#100 = 0 ; Fast Speed  
#101 = 0 ; Slow Speed  
#102 = 0 ; Max Depth  
#103 = 0 ; Thickness  
#104 = 0 ; WCS Index  
#105 = 0 ; WCS Address  
#106 = 0 ; Calculated Offset
```

(2. Setup)

```
#100 = 200 ; Fast Feed  
#101 = 20 ; Slow Feed  
#102 = 20 ; Max Probe Dist  
#103 = #629 ; Load Puck Thickness from Param
```

(3. Fast Probe)

```
G91  
G31 Z-[#102] F[#100]  
IF #1922 == 0 GOTO 999 ; Error if no hit
```

(4. Slow Probe)  
GO Z2 ; Retract 2mm  
G31 Z-5 F[#101] ; Slow probe  
IF #1922 == 0 GOTO 999

(5. Set Zero on Active WCS)  
#104 = #578 ; Get Active WCS Index (1-6)  
#105 = 807 + [#104-1]\*5 ; Calculate G5x Z-Offset Address (Stride 5)  
#106 = #1927 - #103 ; Offset = Precision Hit Pos (#1927) - Thickness (#629)  
#[#105] = #106 ; Write Offset directly to System Var  
GO Z10 ; Retract Safe  
#1505 = -5000(Z Zero Set to Thickness [%.3f])  
GOTO 1000

N999 #1505 = -5000(Probe Missed!)  
N1000 G90

## F. Restore G54 (Fence System)

*Run this if you accidentally lose your G54 Reference.*

(RESTORE G54 FENCE DEFAULTS)  
(Prime Vars)  
#805 = 0  
#806 = 0  
#807 = 0  
(Write Hardcoded Values)  
#805 = 42.650 ; Restore X  
#806 = -661.186 ; Restore Y  
#807 = -87.336 ; Restore Z (Spoilboard)  
#1505 = -5000(G54 Fence Restored!)  
M30

## 3. Standard Macro Template

%  
(Title: <Macro Name>)  
(Description: <Function>)

(--- PRIMING BLOCK ---)  
#100 = 0

```
#101 = 0  
#102 = 0  
#1153 = 0
```

```
(--- STATE SAVE ---)  
#100 = #4003 (Save G90/G91)
```

```
(--- MAIN LOGIC ---)  
M5  
G90
```

```
; [INSERT LOGIC HERE]
```

```
(--- STATE RESTORE ---)  
G#100  
M30  
%
```