

人工智能基础

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2024 年 2 月 21 日

Used Materials

Disclaimer: 本课件采用了 S. Russell and P. Norvig's Artificial Intelligence –A modern approach slides, 徐林莉老师课件和其他网络课程课件，也采用了 GitHub 中开源代码，以及部分网络博客内容

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Course overview

What is AI?

A brief history

The state of the art

《人工智能基础》

- ▶ 教材
 - ▶ Artificial Intelligence – A Modern Approach (3rd Edition)
S. Russell and P. Norvig
 - ▶ 人工智能——一种现代方法
- ▶ 参考书
 - ▶ 机器学习 周志华 (2016)
 - ▶ 动手学深度学习 (第二版)
- ▶ 课程考核
 - ▶ 学期总评 = 期末考试 (60%) + 书面作业 (15%) + 实验部分 (25%)
- ▶ 课程主页

<http://staff.ustc.edu.cn/~jianmin/2024/ai2024/>
- ▶ 课件下载
 - <http://staff.ustc.edu.cn/~jianmin/lecture/ai2024/lec1.pdf>
 - <http://staff.ustc.edu.cn/~jianmin/lecture/ai2024/lec2.pdf>

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课程内容

- ▶ 第一部分：人工智能概述 / Introduction and Agents (chapters 1, 2)
- ▶ 第二部分：问题求解 / Search (chapters 3 ~ 6)
 - ▶ Solving Problems by Searching, Informed Search, Constraint Satisfaction Problems (CSP), Game Planning
- ▶ 第三部分：知识、推理与规划 / Logic, Knowledge, Reasoning, and Planning (chapters 7 ~ 12)
 - ▶ Logical Agents, FOL and Inference in FOL, Planning and Knowledge Representation
- ▶ 第四部分：不确定知识与推理 / Uncertainty and Decision Making (chapters 13 ~ 17)
 - ▶ Uncertainty and Bayesian Networks, Decision Making (MDPs, POMDPs, and Stochastic Games)
- ▶ 第五部分：学习 / Learning (chapters 18 ~ 21)
 - ▶ Machine Learning, Deep Learning, Reinforcement Learning
- ▶ 第六部分：应用 / NLP, Perception, and Robotics (chapters 22 ~ 25)

课程内容

- ▶ 广义上“人工智能”包括很多经典工作，如搜索、知识表示与推理、规划、MDPs、贝叶斯网等。
- ▶ 由于近期深度学习的成功，现在提到“人工智能”很多人主要指机器学习，尤其是深度学习、大模型方面的工作。
- ▶ 《人工智能基础》这门课的定位是：
 - ▶ 面向计算机专业的同学，介绍 IT 工程师应该掌握的人工智能基础技术和知识，要求大家熟练掌握；
 - ▶ 同时，作为索引介绍人工智能的各方面工作，尤其是机器学习、神经网络、大模型等方面的新工作，仅要求了解。
- ▶ 上完这门课，期望大家了解人工智能的全貌，掌握人工智能的基础技术和知识，了解机器学习的一些工作。
 - ▶ 想系统入门深度学习，建议自学“动手学深度学习”，实际动手 coding，听李沐的在线课程：<https://zh.d2l.ai/>
 - ▶ 想入门以后再精深，建议选定 CV、NLP、多模态等某个具体领域，从综述开始系统阅读核心论文、持续学习该领域的最新工作，自己动手实现系统，同时培养科研能力和工程能力；
 - ▶ 想精深后再成为某方向专家，建议加入相关实验室，培养自己对该方向的洞见，开展前沿研究。

助教

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Different people think of AI differently

"[The automation of] activities that we associate with human thinking, activities such as decision-making, problem solving, learning ..." (Bellman, 1978)	"The study of mental faculties through the use of computational models" (Charniak+McDermott, 1985)
"The study of how to make computers do things at which, at the moment, people are better" (Rich+Knight, 1991)	"The branch of computer science that is concerned with the automation of intelligent behavior" (Luger+Stubblefield, 1993)

Views of AI fall into four categories:

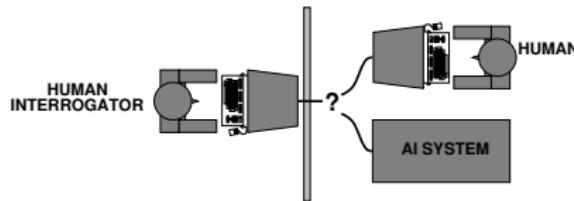
Thinking humanly	Thinking rationally
Acting humanly	Acting rationally

The textbook advocates “acting rationally (理性的)”

Acting humanly: The Turing Test 图灵测试

Turing (1950) "Computing machinery and intelligence":

- ▶ "Can machines think?" → "Can machines behave intelligently?"
- ▶ Operational test for intelligent behavior: the Imitation Game



- ▶ Predicted that by 2000, a machine might have a 30% chance of fooling a lay person for 5 minutes
- ▶ Anticipated all major arguments against AI in following 50 years
- ▶ Suggested major components of AI: knowledge (知识), reasoning (推理), language understanding (语言理解), learning (学习)

Problem: Turing test is not reproducible, constructive, or amenable to mathematical analysis

Thinking humanly: Cognitive Science (认知科学)

- ▶ 1960s “cognitive revolution”: information-processing psychology replaced prevailing orthodoxy of behaviorism
- ▶ Requires scientific theories of internal activities of the brain
 - ▶ What level of abstraction? “Knowledge” or “circuits”?
 - ▶ How to validate? Requires
 - ▶ Predicting and testing behavior of human subjects (top-down), or
 - ▶ Direct identification from neurological data (bottom-up)
- ▶ Both approaches (roughly, Cognitive Science and Cognitive Neuroscience) are now distinct from AI

Thinking rationally: Laws of Thought

- ▶ Normative (or prescriptive) rather than descriptive
- ▶ Aristotle (亚里士多德): what are correct arguments/thought processes?
- ▶ Several Greek schools developed various forms of logic:
notation and rules of derivation for thoughts; may or may not have proceeded to the idea of mechanization
- ▶ Direct line through mathematics and philosophy to modern AI
- ▶ Problems:
 - ▶ Not all intelligent behavior is mediated by logical deliberation
 - ▶ What is the purpose of thinking? What thoughts should I have?
 - ▶ Logical systems tend to do the wrong thing in the presence of uncertainty
 - ▶ 部分学者观点, 部分学者不同意

Acting rationally

- ▶ Rational behavior: doing the right thing
 - ▶ The right thing: that which is expected to maximize goal achievement, given the available information
 - ▶ Doesn't necessarily involve thinking—e.g., blinking reflex—but thinking should be in the service of rational action
 - ▶ Aristotle (Nicomachean Ethics, 亚里士多德所著《尼各马可伦理学》):

Every art and every inquiry, and similarly every action and pursuit, is thought to aim at some good

- ▶ Entirely dependent on goals!
- ▶ Irrational \neq insane, irrationality is sub-optimal action
- ▶ Rational \neq successful
- ▶ Our focus here:
 - ▶ Systems which make the best possible decisions given goals, evidence, and constraints
 - ▶ In the real world, usually lots of uncertainty
 - ▶ ... and lots of complexity
 - ▶ Usually, we're just approximating rationality

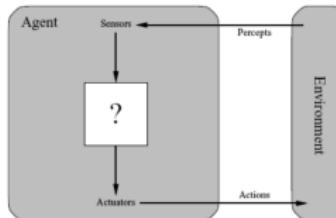
Rational agents

Maximize Your Expected Utility

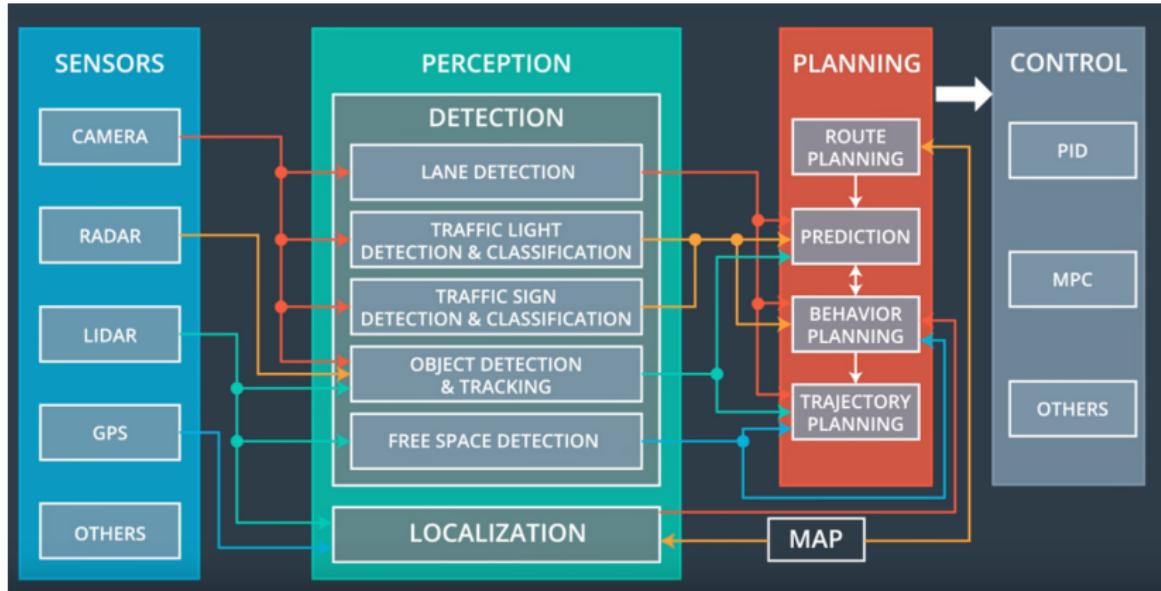
- ▶ An agent is an entity that perceives and acts
- ▶ This course is about designing rational agents
- ▶ Abstractly, an agent is a function from percept histories to actions:

$$f: \mathcal{P}^* \rightarrow \mathcal{A}$$

- ▶ For any given class of environments and tasks, we seek the agent (or class of agents) with the best performance
- ▶ Caveat: computational limitations make perfect rationality unachievable → design best program for given machine resources

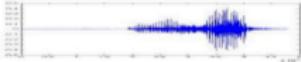


Self Driving Car Architecture



机器学习 ≈ 拟合一个函数

- Speech Recognition

$f($  $) = \text{“How are you”}$

- Image Recognition

$f($  $) = \text{“Cat”}$

- Playing Go

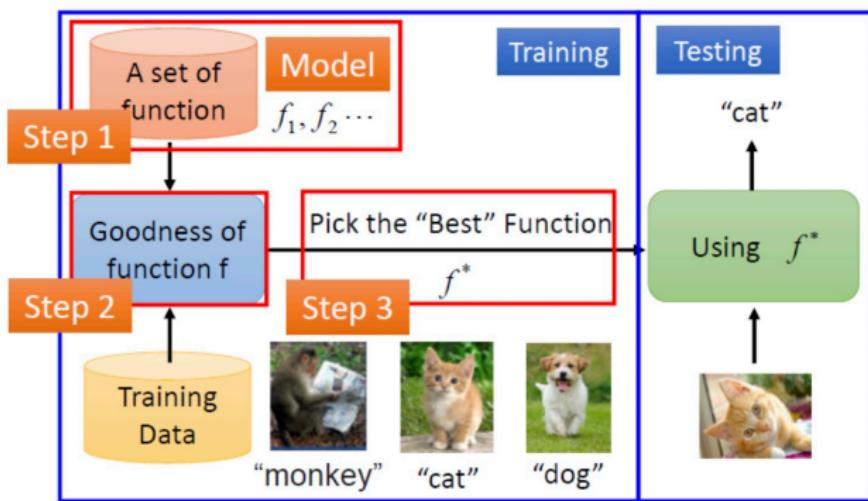
$f($  $) = \text{“5-5”}$ (next move)

- Dialogue System

$f($ “Hi” $) = \text{“Hello”}$
(what the user said) (system response)

学习 = 表示 + 评价 + 优化

- ▶ 表示 (Representation): 确定假设空间 (hypothesis space)
- ▶ 评价 (Evaluation): 评价函数 (目标函数、打分函数) 来判断优劣
- ▶ 优化 (Optimization): 需要一个搜索方法, 能够在假设空间中找到评价函数得分最高的函数



PAC Learning: 机器学习为什么可能?

- ▶ 泛化误差 (generalization error): 给定 $h \in \mathcal{H}$, $c \in \mathcal{C}$, 分布 \mathcal{D} , h 的泛化误差为

$$R(h) = P_{x \sim \mathcal{D}}[h(x) \neq c(x)]$$

- ▶ 经验误差 (empirical error): 给定样本集合 $S = (x_1, \dots, x_m)$

$$\hat{R}_S(h) = \frac{1}{m} \sum_{i=1}^m [h(x_i) \neq c(x_i)]$$

- ▶ 比较经验误差与泛化误差:
 - ▶ 经验误差是 h 在训练数据 S 上的平均误差
 - ▶ 泛化误差是 h 在分布 \mathcal{D} 上的期望误差
 - ▶ 两者存在联系, 因为 S 是根据 \mathcal{D} 独立同分布产生的

$$E_{S \sim \mathcal{D}^m}[\hat{R}_S(h)] = R(h)$$

PAC 学习理论

- ▶ PAC 学习理论考虑，能否从假设空间 \mathcal{H} 中学习一个好的假设 h
- ▶ “好的假设”需要满足两个条件 (PAC 辨识条件):
 - ▶ 近似正确 (Approximately Correct): 泛化误差 $R(h)$ 足够小
 - ▶ $R(h)$ 越小越好，最好泛化误差能能于 0，但一般是不可能的。那我们就把 $R(h)$ 限定在一个很小的数 ϵ 之内，即只要假设 h 满足 $R(h) \leq \epsilon$ ，我们就认为 h 是近似正确的
 - ▶ 可能正确 (Probably Correct): h 在很大概率上近似正确
 - ▶ 不指望选择的假设 h 百分之百是近似正确的，即 $R(h) \leq \epsilon$ ，只要很可能是近似正确的就可以，即我们给定一个值 δ ，假设 h 满足 $P(R(h) \leq \epsilon) \geq 1 - \delta$
- ▶ 同时学习所需的样本数量不能太大，样本数量是关于 $1/\epsilon$, $1/\delta$, 样本大小, $\text{size}(c)$ 的多项式函数

定义

A concept class \mathcal{C} is said to be *PAC-learnable* if there exists an algorithm \mathcal{A} and a polynomial function $poly(\cdot, \cdot, \cdot, \cdot)$ such that for any $\epsilon > 0$ and $\delta > 0$, for all distribution \mathcal{D} on \mathcal{X} (containing instances of length n) and for any target concept $c \in \mathcal{C}$, the following holds for any sample size $m \geq poly(1/\epsilon, 1/\delta, n, size(c))$:

$$P_{S \sim \mathcal{D}^m}[R(h_S) \leq \epsilon] \geq 1 - \delta$$

If \mathcal{A} further runs in $poly(1/\epsilon, 1/\delta, n, size(c))$, then \mathcal{C} is said to be *efficiently PAC-learable*. When such an algorithm \mathcal{A} exists, it is called a *PAC-learning algorithm* for \mathcal{C} .

霍夫丁不等式 (Hoeffding's Inequality)

定理 (Hoeffding's Inequality)

Let X_1, \dots, X_m be i.i.d. random variable in $[0, 1]$, for any $\epsilon > 0$

$$P\left(\left|\frac{1}{m} \sum_{i=1}^m X_i - \frac{1}{m} \sum_{i=1}^m E(X_i)\right| \geq \epsilon\right) \leq 2e^{-2m\epsilon^2}.$$

- ▶ 该定理给出了位于区间 $[0,1]$ 的两两随机变量其期望与均值之间满足的关系，在任意分布 \mathcal{D} 下
- ▶ 由泛化误差 $R(h)$ 与经验误差 $\hat{R}_S(h)$ 的定义易知 $E(\hat{R}_S(h)) = R(h)$ ，由此得到

$$P_{S \sim \mathcal{D}^m} \left[\left| \hat{R}_S(h) - R(h) \right| \geq \epsilon \right] \leq 2e^{-2m\epsilon^2}$$

- ▶ 令 $\delta = 2e^{-2m\epsilon^2}$ ，则 Fix a hypothesis $h: \mathcal{X} \rightarrow \{0, 1\}$. Then, for any $\delta > 0$, the following inequality holds with probability at least $1 - \delta$:

$$R(h) \leq \hat{R}_S(h) + \sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

奥卡姆剃刀原则

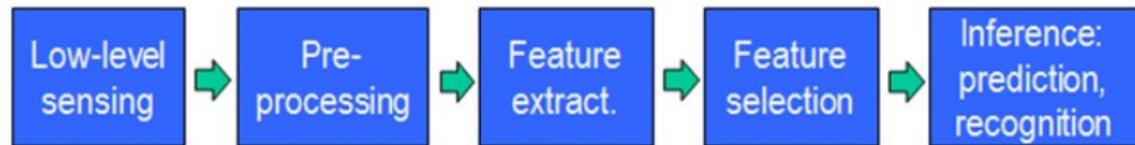
- ▶ Thus, for a finite hypothesis set \mathcal{H} ,

$$R(h) \leq \hat{R}_S(h) + O\left(\sqrt{\frac{\log_2 |\mathcal{H}|}{m}}\right)$$

- ▶ For a fixed $|\mathcal{H}|$, to attain the same guarantee as in the consistent case, a quadratically larger labeled sample is needed
- ▶ This can also be viewed as an instance of the so-called **Occam's Razor principle**
 - ▶ Plurality should not be posited without necessity, also rephrased as, the simplest explanation is best.

机器学习

目前机器学习解决问题的思路



中间的三部分，概括起来就是特征表达。良好的特征表达，对最终算法的准确性起了非常关键的作用，而且系统主要的计算和测试工作都耗在这一大部分。但这块实际上一般都是人工完成的。
靠人工提取特征

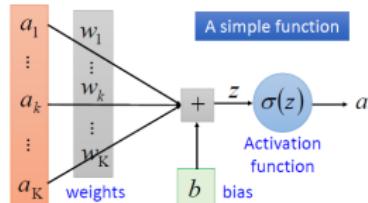


手工选取特征不太好，那么能不能自动地学习一些特征呢？能！
Deep Learning (Unsupervised Feature Learning)

深度神经网络

Neuron

$$z = a_1 w_1 + \dots + a_k w_k + \dots + a_K w_K + b$$

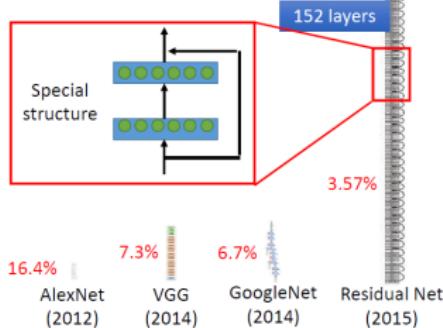


A simple function

Activation
function

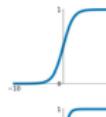
bias

Deep = Many hidden layers



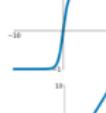
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



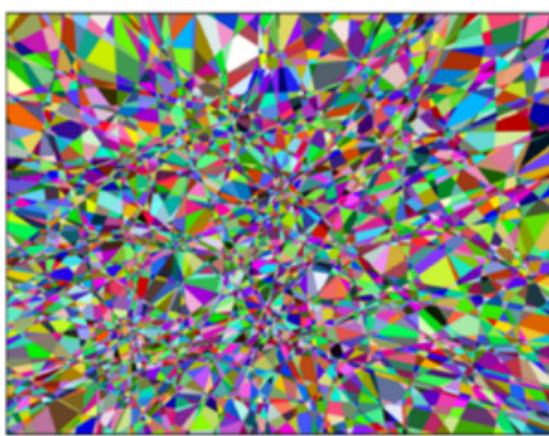
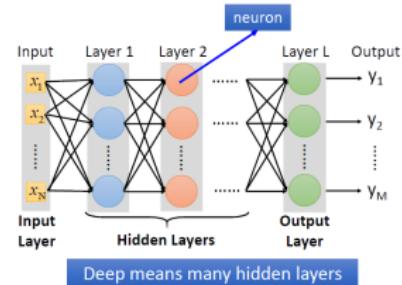
tanh

$$\tanh(x)$$



ReLU

$$\max(0, x)$$



深度学习基本方法

- 为了让 $f(w, x)$ 接近D， 我们定义了损失函数

$$L(w) = \sum_{d_i \in D} f(w, x_i) - y_i$$

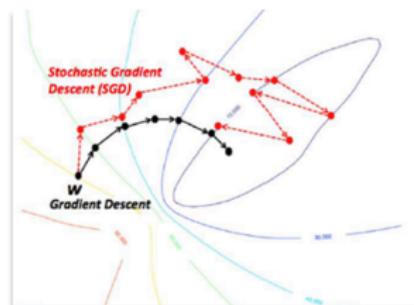
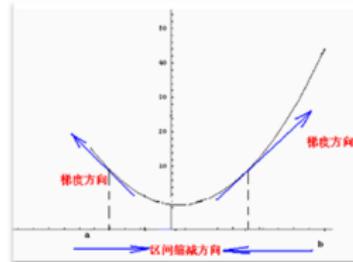
$$w = \operatorname{argmin}_w L(w)$$

- 通常我们可以通过“梯度下降”的方法来求解w

$$w_{new} = w_{old} - \eta \frac{\partial L}{\partial w}$$

学习率 损失函数对参数的梯度

这种算法是机器学习（也是深度学习）的基础



计算图

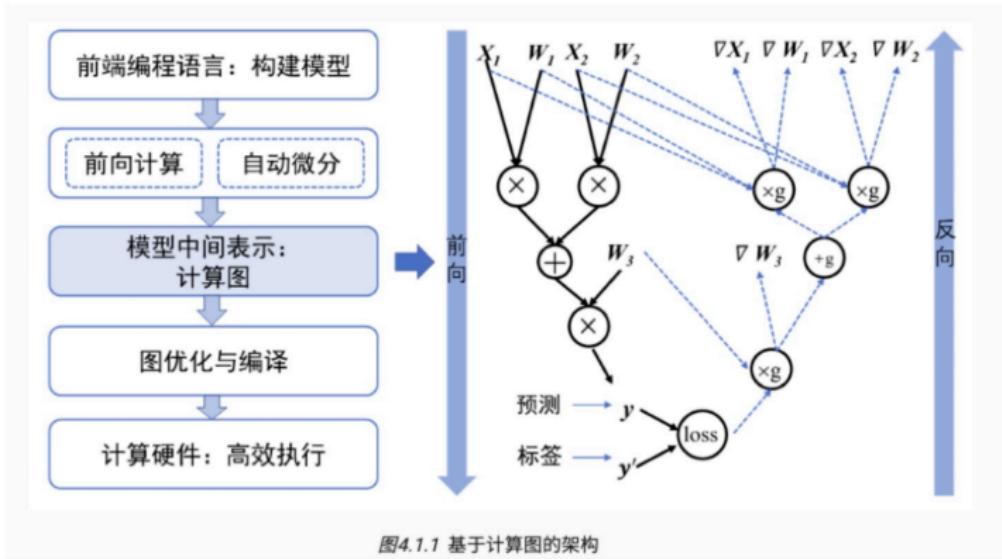
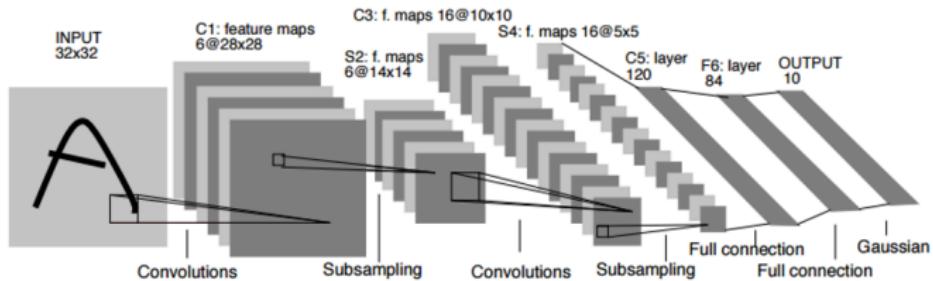


图4.1.1 基于计算图的架构

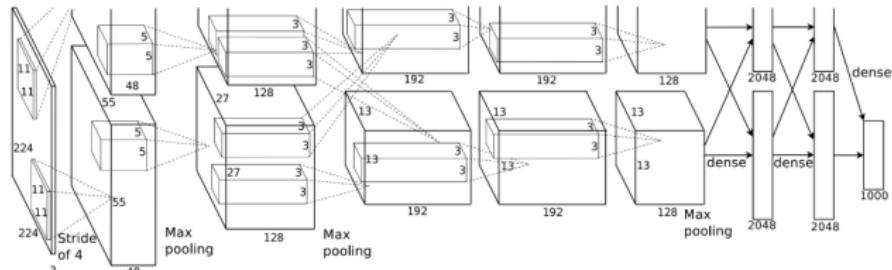
自动微分：将计算机程序中的运算操作分解为一个有限的基本操作集合，且集合中基本操作的求导规则均为已知，在完成每一个基本操作的求导后，使用链式法则将结果组合得到整体程序的求导结果。

卷积神经网络 (CNN)

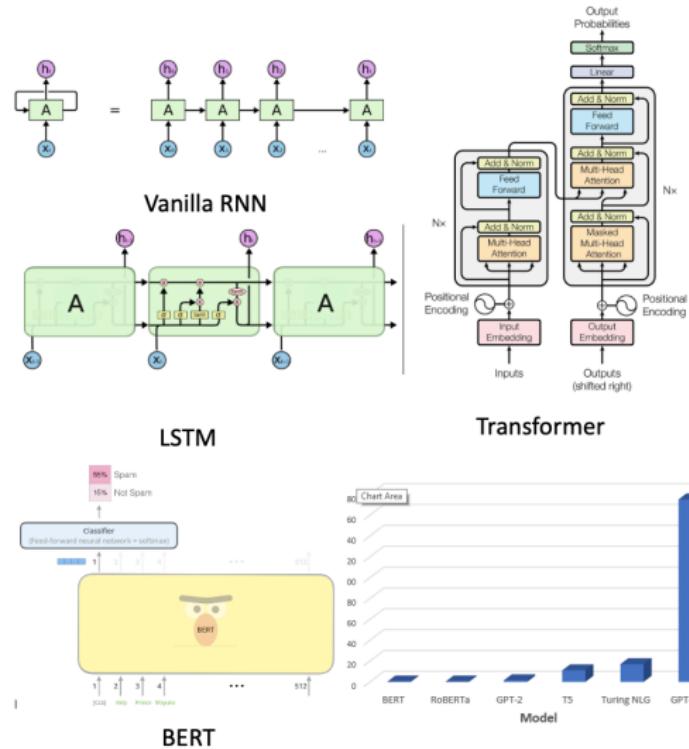
LeCun et al.
1989-1998
LeNet



Krizhevsky,
Sutskever,
Hinton 2012
ImageNet



BERT and GPT-3



Zero-shot

The model predicts the answer given only a natural language description of the task. No gradient updates are performed.



One-shot

In addition to the task description, the model sees a single example of the task. No gradient updates are performed.



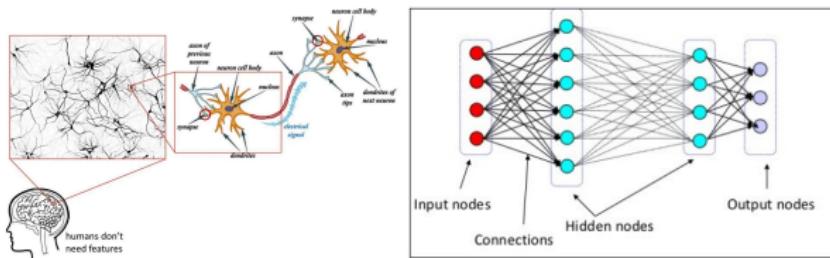
Few-shot

In addition to the task description, the model sees a few examples of the task. No gradient updates are performed.

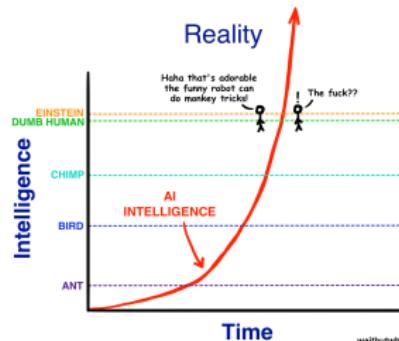
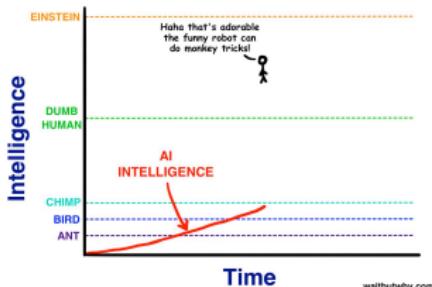


GPT-3

How to fly? How to be intelligent?



Our Distorted View of Intelligence



“New” Novum Organum (“新” 新工具)

- ▶ 自然科学是怎样可能的？
 - ▶ 英国经验主义（如，休谟）：没有真理，只是经验的归纳整理，compact 的表示
 - ▶ 大陆理性主义（如，莱布尼茨）：类似几何原本，从几条简单公设出发形式化推理构建完整理论
 - ▶ 哥德尔不完备性定理：任何足够复杂的公理系统不能既可靠又完备；在可靠系统中，一定存在真命题没法被证明
 - ▶ 不同的公理系统（理论），彼此不能证伪
 - ▶ 康德、黑格尔：人通过先验概念理解世界，不是世界一定是这样，而是我们只能理解由公理系统所描述的世界
 - ▶ 培根《新工具》(“Novum Organum”)：公理系统 + 科学实验
- ▶ “新” 新工具：神经网络，端到端学习
 - ▶ Universal approximation：任何连续函数都可以被前馈神经网络以无限小的误差近似
 - ▶ Turing completeness：任何图灵机都可以被循环神经网络进行模拟

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AI prehistory

Philosophy	logic, methods of reasoning mind as physical system
Mathematics	foundations of learning, language, rationality formal representation and proof algorithms computation, (un)decidability, (in)tractability probability
Psychology	adaptation phenomena of perception and motor control experimental techniques (psychophysics, etc.)
Linguistics	knowledge representation grammar
Neuroscience	physical substrate for mental activity
Control theory	homeostatic systems, stability simple optimal agent designs

AI history

- ▶ The gestation of AI 孕育期 (—1956)
- ▶ Reasoning methods 注重推理时期 (1956-1975)
- ▶ Knowledge-based system 知识运用时期 (1976- 1988)
- ▶ Integration 集成运用 (1989- present)

The Gestation of AI

- ▶ 古希腊 Aristotle (亚里士多德 BC 384-322), 给出形式逻辑的基本规律 Syllogism (三段论)
- ▶ 英国 Bacon (培根 1561-1626), 系统地给出 Induction (归纳法)
- ▶ 德国 Leibnitz (莱布尼茨 1646-1716) 提出 Symbolic Logic (符号逻辑)
- ▶ 英国 Boole (布尔 1815-1864) 提出 Boolean Algebra (布尔代数) 系统, 实现了思维符号化和数学化
- ▶ 1936 英国 Turing (图灵, 1912-1954): 理想计算机模型 Turing Machine (图灵机)
- ▶ 1946 美国 Mauchly (莫克利), Eckert (埃克特): ENIAC
- ▶ 1948 美国 Shannon (香农): Information Theory (信息论)
- ▶ 1950 Turing Test 图灵测试

The Birth of AI (1956)

- ▶ John McCarthy organized a two-month workshop at Dartmouth (达特茅斯会议) in the summer of 1956, ten young men were there:
McCarthy, Minsky, Rochester, Shannon, Moore, Samuel, Selfridge, Solomonoff, Simon, Newell
- ▶ They introduced all the major figures to each other and agreed to adopt the name of **Artificial Intelligence** for the field.

Abridged history of AI

- 1943 McCulloch & Pitts: Boolean circuit model of brain
- 1950 Turing's "Computing Machinery and Intelligence"
- 1952–69 Look, Ma, no hands!
- 1950s Early AI programs, including Samuel's checkers program, Newell & Simon's Logic Theorist, Gelernter's Geometry Engine
- 1956 Dartmouth meeting: "Artificial Intelligence" adopted
- 1965 Robinson's complete algorithm for logical reasoning
- 1966–73 AI discovers computational complexity
Neural network research almost disappears
- 1969–79 Early development of knowledge-based systems
- 1980–88 Expert systems industry booms
- 1988–93 Expert systems industry busts: "AI Winter"
- 1985–95 Neural networks return to popularity
- 1987– AI becomes a science
- 1995– The emergence of intelligent agents
- 2001– The availability of very large data sets
- 2010– Deep learning

AI Today

- ▶ Mostly about engineering domain-specific solutions rather than creating general theories
- ▶ We don't know how to do most of intelligent things, but the rest can be solved pretty well
- ▶ A set of “tools” for representing information and using them to solve specific tasks
 - ▶ Neural networks, hidden Markov models, Bayesian networks, heuristic search, logic, ...
- ▶ There's no magic in AI. It's all about **representation**, **optimization**, **probability**, and **algorithms**

Table of Contents

Course overview

What is AI?

A brief history

The state of the art

Well-known AI applications

- ▶ Expert systems (organic chemistry, medicine, geology, configuring computers)
- ▶ Speech recognition
- ▶ Handwriting recognition
- ▶ Game playing (chess, checkers, now Go)
- ▶ Robots (automated cars, ping pong player, Honda robot)
- ▶ Automated theorem proving
- ▶ Web search engines
- ▶ Natural language understanding (machine translation, Google)
- ▶ Logistics scheduling (military — people, cargo, vehicles)
- ▶ Cruise missiles
- ▶ Microsoft Answer Wizard

The state of the art

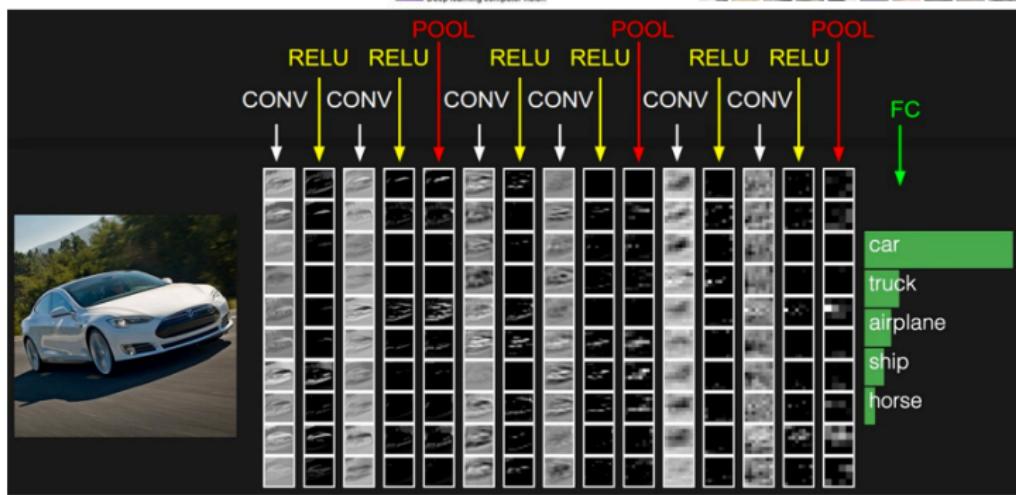
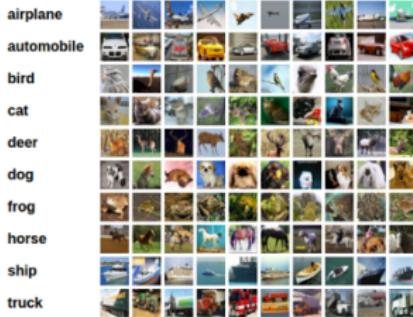
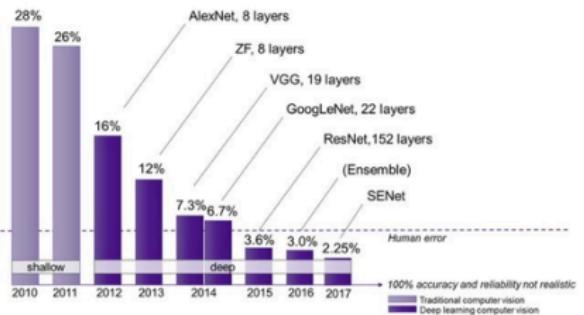
- ▶ Google language translation services
- ▶ Google automatic news aggregation and summarization
- ▶ Nuance voice recognition (behind Apple's Siri)
- ▶ Face detection and face recognition systems
- ▶ Apple Siri question-answering system
- ▶ IBM Watson question-answering system
- ▶ IBM Deep Blue chess playing program
- ▶ Deepmind AlphaGo
- ▶ Microsoft Photosynth
- ▶ Google Goggles
- ▶ Driverless cars
- ▶ OpenAI ChatGPT
- ▶ Robotics
- ▶ OpenAI Sora

Question Answering

Feb 2011, Watson (沃森) beat human on the quiz show Jeopardy!. And received the first prize of \$1 million.

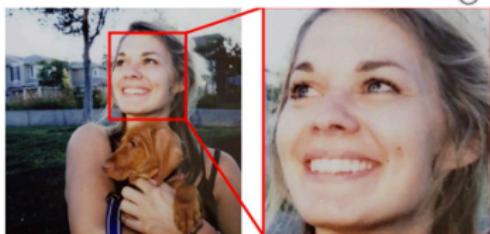
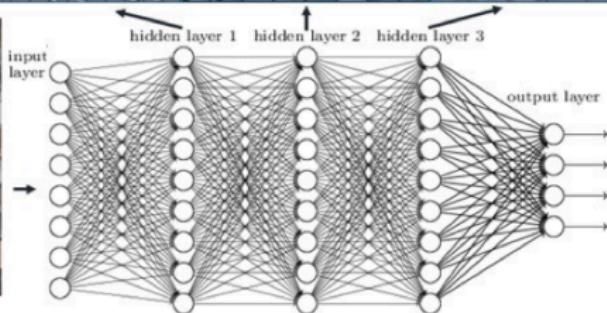


Visual Recognition



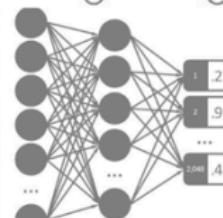
Face Detection

Deep neural networks learn hierarchical feature representations



Detect face (Face++)

Crop and resize
(224 x 224 pixels)



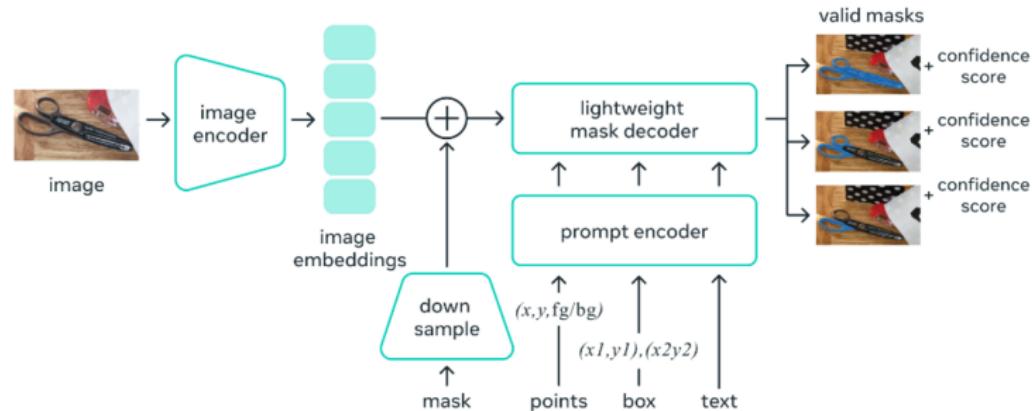
Extract 2,048 face
descriptors (VGGFace2)

Cross-validated
Logistic Regression
(or other similarity
measure)
 $P_{\text{liberal}} = 38\%$

Compare with liberal
and conservative faces

Meta AI: Segment Anything Model (SAM)

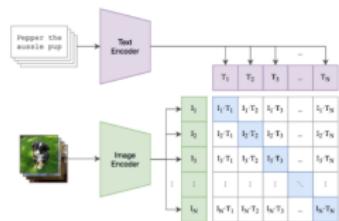
- ▶ SAM: an AI model that can "cut out" any object, in any image, with a single click



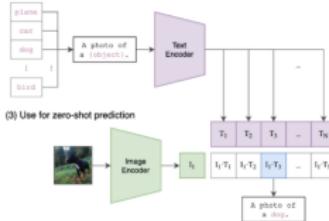
OpenAI: CLIP

► CLIP: Connecting text and images

(1) Contrastive pre-training



(2) Create dataset classifier from label text

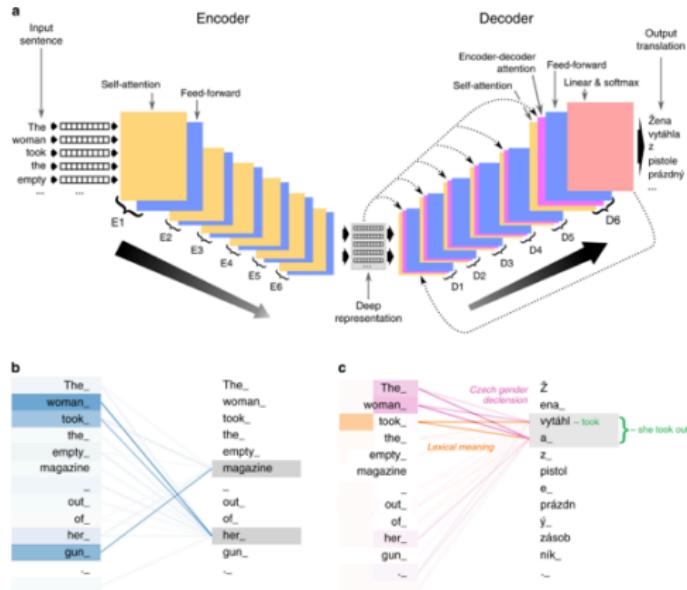
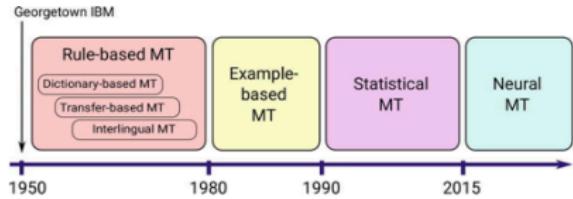


(3) Use for zero-shot prediction

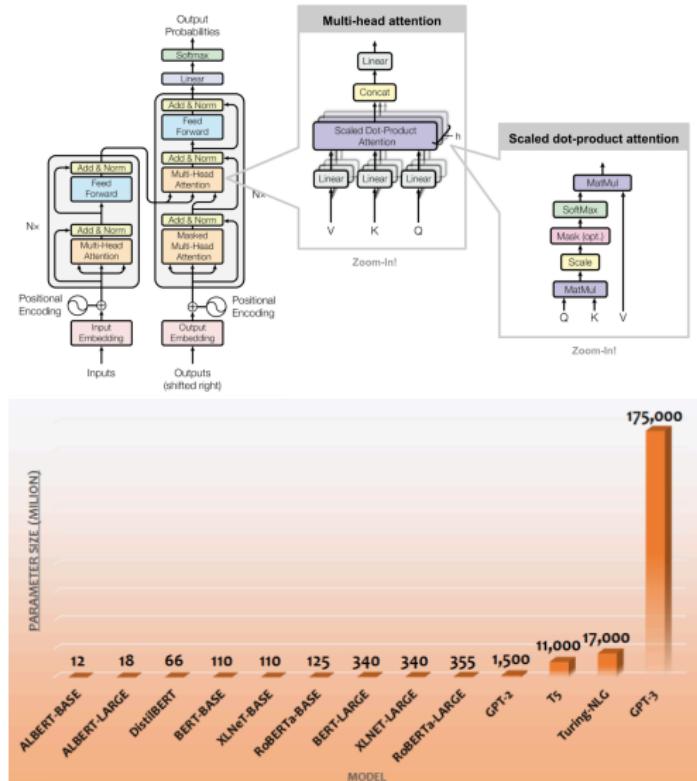


Figure 1. Summary of our approach. While standard image models jointly train an image feature extractor and a linear classifier to predict some label, CLIP jointly trains an image encoder and a text encoder to predict the correct pairings of a batch of (image, text) training examples. At test time the learned text encoder synthesizes a zero-shot linear classifier by embedding the names or descriptions of the target dataset's classes.

Machine Translation



Language Models



Zero-shot

The model predicts the answer given only a natural language description of the task. No gradient updates are performed.

- 1 Translate English to French: task description
- 2 cheese => prompt

One-shot

In addition to the task description, the model sees a single example of the task. No gradient updates are performed.

- 1 Translate English to French: task description
- 2 sea otter => loutre de mer example
- 3 cheese => prompt

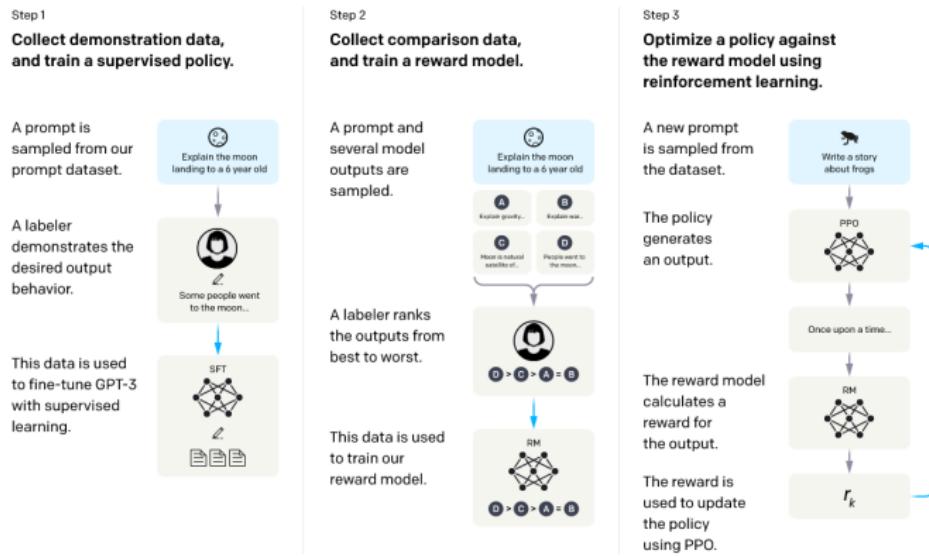
Few-shot

In addition to the task description, the model sees a few examples of the task. No gradient updates are performed.

- 1 Translate English to French: task description
- 2 sea otter => loutre de mer examples
- 3 peppermint => menthe poivrée examples
- 4 plush girafe => girafe peluche examples
- 5 cheese => prompt

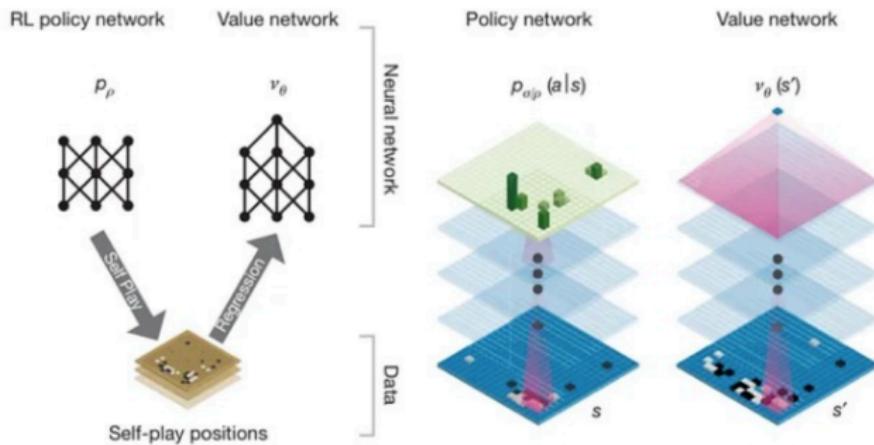
OpenAI: ChatGPT

- ▶ ChatGPT: an artificial intelligence chatbot developed by OpenAI and launched in November 2022
 - ▶ GPT-3: Large language model with 175 billion parameters
 - ▶ ChatGPT was fine-tuned on top of GPT-3.5 using supervised learning and reinforcement learning



DeepMind: AlphaGo

- ▶ AlphaGo 以 4: 1 的战绩击败李世石，机器第一次在围棋领域战胜人类顶尖高手
- ▶ AlphaGo Zero 从 0 学起，在不到 3 天的时间内以 100:0 完虐 AlphaGo



Games



■ RoboCup 2D 仿真平台 (算法测试平台)

多智能体协作、对抗研究的标准平台



■ DeepMind 星际争霸2

■ 网易 “易水寒”



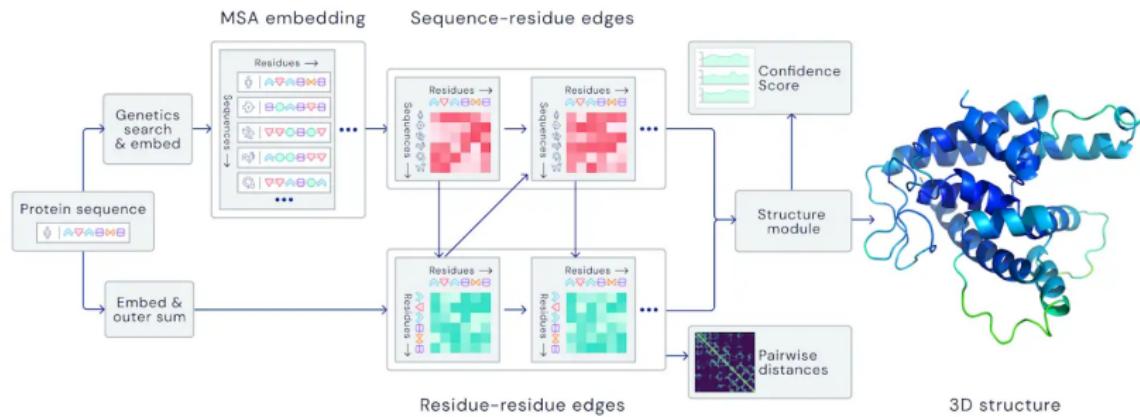
On cast of type **Area** we also observe absolute positive health over last 12 frames (reflecting or reflected by hero projectiles) to impact the target unit, and representation general pattern: increasing first since last attack, number of deaths and swing on phasing an ability.

■ 网易 “潮人篮球”

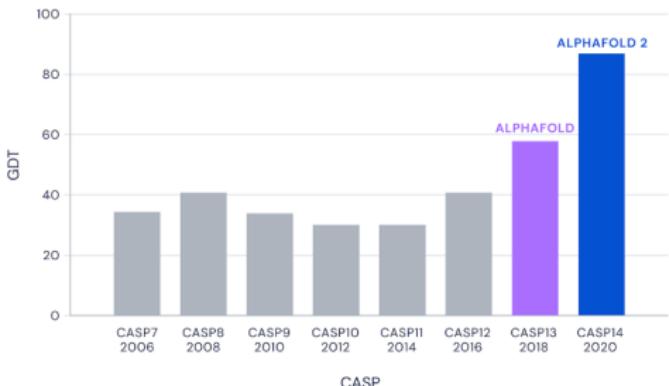


■ OpenAI Dota 2

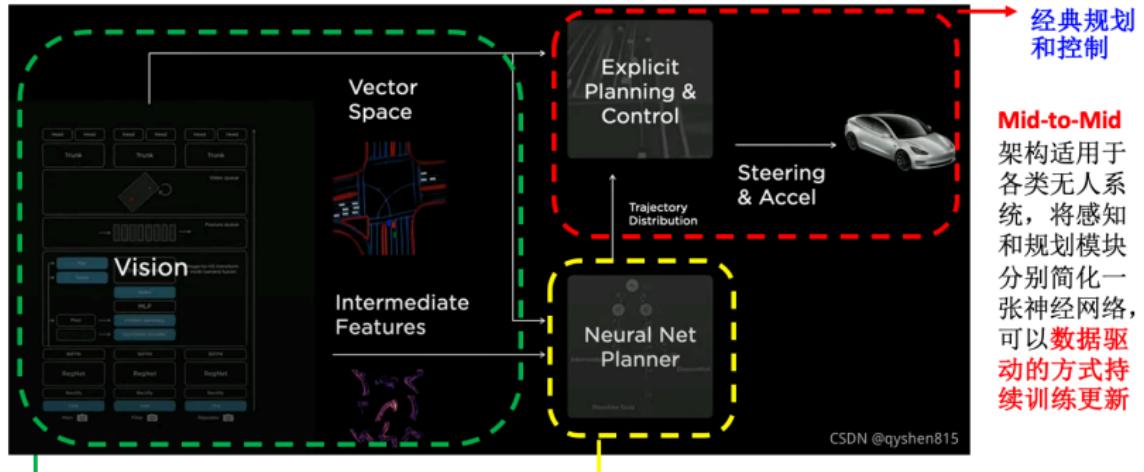
DeepMind: AlphaFold 2



Median Free-Modelling Accuracy



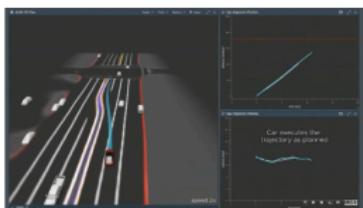
Tesla: Self-driving cars



感知一张网：输入传感器信息，训练网络输出BEV下的数字化世界模型

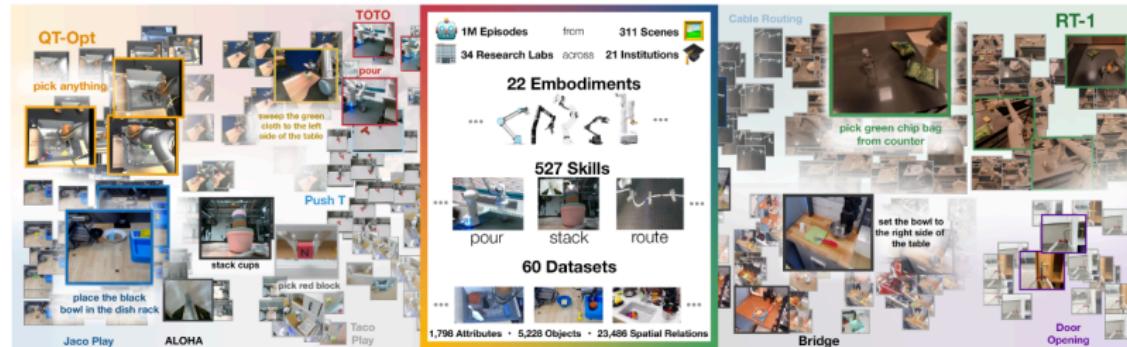


规划一张网：输入数字化世界模型，训练网络输出可行驶轨迹分布



Open X-Embodiment: 机器人界的 Image-Net 时刻

Open X-Embodiment: Robotic Learning Datasets and RT-X Models



提供了轨迹数据集和预训练模型：

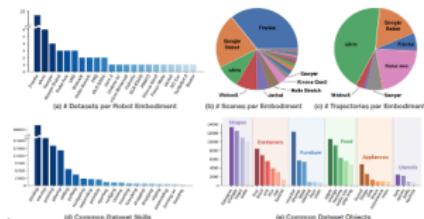
- **Open X-Embodiment Dataset:** robot learning dataset with *1M+ robot trajectories* from *22 robot embodiments*.
- **Pre-Trained Checkpoints:** a selection of RT-X model checkpoints ready for inference and finetuning.

数据集：

- 将不同已有数据集**统一化**
- 输入：规范相机视角，图片形式
- 输出：归一化的7维动作，能适应不同的动作形式：
[绝对值，相对值，速度]

模型：

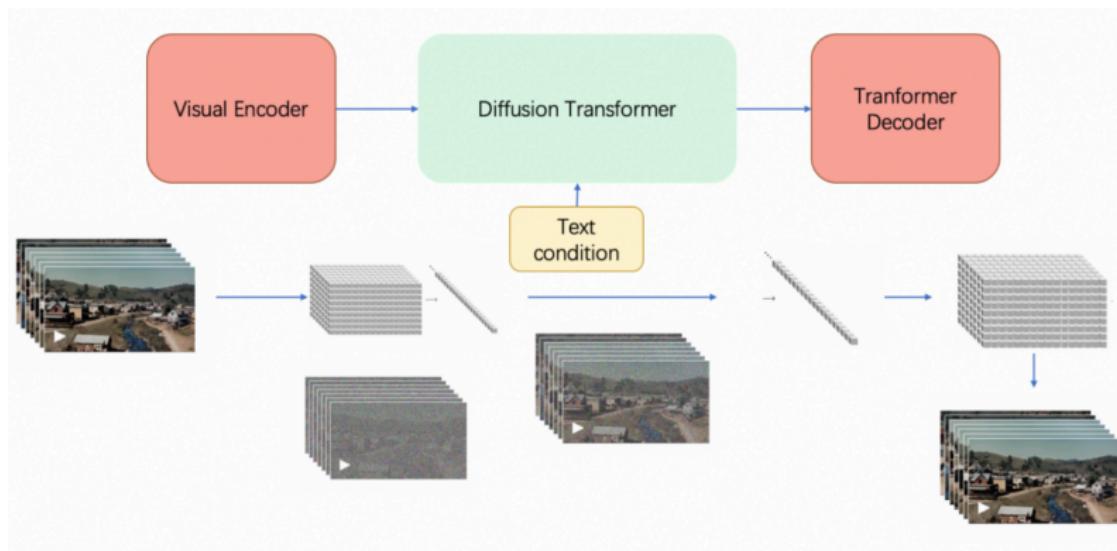
- RT-1-X 开源
- 输入：RGB图像 + 任务文本描述
- 输出：不同形式的7维动作



通过庞大的开源数据集，训练具身智能大模型，创造一个泛化能力极强的机器人

OpenAI: Sora

- ▶ Sora: an AI model that can create realistic and imaginative scenes from text instructions.



Summary

- ▶ Applications of AI:
 - ▶ high-impact (affect billions of people)
 - ▶ diverse (language, vision, robotics)
- ▶ Challenges: really hard...
 - ▶ computation complexity
 - ▶ information complexity
- ▶ Paradigm: modeling + algorithms