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1 //Sistemas Embebidos - Examen parcial 2
2 //Fernando Cossio Ramirez
3
4 #include <avr32/io.h>
5 #include "compiler.h"
6
7 #include <pm.h>
8 // From module: GPIO - General-Purpose Input/Output
9 #include <gpio.h>
10 // From module: Generic board support
11 #include <board.h>
12 // From module: INTC - Interrupt Controller
13 #include <intc.h>
14 // From module: Interrupt management - UC3 implementation
15 #include <interrupt.h>
16
17 #include <tc.h>
18
19 #include <spi.h>
20
21 #define PBA_HZ          FOSC0
22 #define BTN_UP          AVR32_PIN_PB22
23 #define BTN_DOWN        AVR32_PIN_PB23
24 #define BTN_RIGHT        AVR32_PIN_PB24
25 #define BTN_LEFT        AVR32_PIN_PB25
26 #define BTN_CENTER        AVR32_PIN_PB26
27 #define LED0            AVR32_PIN_PB27
28 #define LED1            AVR32_PIN_PB28
29 #define LED2            AVR32_PIN_PA05
30 #define LED3            AVR32_PIN_PA06
31
32 enum btn{NONE, UP, DOWN, LEFT, RIGHT, CENTER};
33 enum btn btn_pressed = NONE;
34 uint8_t state = 0;
35 uint8_t humidity = 0;
36 uint8_t temperature = 0; //0:NONE, 1:LOW, 2:HIGH
37 uint8_t timer_configured = 0;
38 __attribute__((__interrupt__));
39 void btn_interrupt_routine (void);
40 void leds(uint8_t value);
41 static void init_tc_output(volatile avr32_tc_t *tc, unsigned int channel);
42
43 void state1(void);
44 void state2(void);
45 void state3(void);
46
47
48 int main(void){
49
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50     pm_switch_to_osc0(&AVR32_PM, 16000000, 6);
51     board_init();
52
53     Disable_global_interrupt();
54     INTC_init_interrupts();
55     INTC_register_interrupt(&Botones, 70, 3);
56     INTC_register_interrupt(&Botones, 71, 3);
57
58     uint16_t button_ref [] = {BTN_UP,BTN_DOWN,BTN_RIGHT,BTN_LEFT,BTN_CENTER};
59     for(uint8_t i=0; i<5; i++){
60         gpio_enable_gpio_pin(button_ref[i]);
61         gpio_enable_pin_pull_up(button_ref[i]);
62         gpio_enable
63         _pin_interrupt(button_ref[i],GPIO_FALLING_EDGE);
64     }
65     Enable_global_interrupt();
66     init_tc_output(&AVR32_TC, 2); //Canal 2 como waveform
67     static const gpio_map_t TC_GPIO_MAP =
68     {
69         {86, 2} //GPIO 86, FN especial C, 2
70     };
71     gpio_enable_module(TC_GPIO_MAP, sizeof(TC_GPIO_MAP) / sizeof(TC_GPIO_MAP  ↗
72         [0]));//Activar Fn especial para TIOA2
73
74     /
75     *SPI*****
76     ***/
77     // SPI options.
78     //Mapa SPI
79     static const gpio_map_t SPI_GPIO_MAP = {
80         {AVR32_SPI0_SCK_0_0_PIN , AVR32_SPI0_SCK_0_0_FUNCTION }, // SCK: SPI  ↗
81         Clock.
82         {AVR32_SPI0_MISO_0_0_PIN, AVR32_SPI0_MISO_0_0_FUNCTION}, // MISO.
83         {AVR32_SPI0_MOSI_0_0_PIN, AVR32_SPI0_MOSI_0_0_FUNCTION}, // MOSI.
84         {AVR32_SPI0_NPCS_3_0_PIN, AVR32_SPI0_NPCS_3_0_FUNCTION} // NPCS: Chip  ↗
85         Select
86     };//Pines y funciones SPI
87     spi_options_t spiOptions = {
88         .reg          = 3, //CHIP SELECT 1
89         .baudrate     = 100000, //BAUDRATE: 100Kbps (sin modulacion)*
90         .bits         = 8, //Número de bits a transmitir: 8
91         .spck_delay   = 48, //Delay antes del SPCK (DLYBS = CLK*DLY = 12M*4u =  ↗
92         48)*
93         .trans_delay  = 0, //Delay entre transiciones consecutivas (DLYBCT = 0,  ↗
94         no se especifica un delay)*
95         .stay_act     = 0, //Deselección de periféricos (CSAAT = 0, se  ↗
96         desactiva en la ultima transferencia)*
97         .spi_mode     = 3, //Modo (CPOL y NCPHA): 0*
98         .modfdis      = 1, //Modo Fault Detection: 1 - Inhabilitado*

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91     }; //Estructura SPI
92
93     gpio_enable_module(SPI_GPIO_MAP,
94         sizeof(SPI_GPIO_MAP) / sizeof(SPI_GPIO_MAP[0]));
95     spi_initMaster(AVR32_SPI0_ADDRESS, &spiOptions);
96     // Set SPI selection mode: variable_ps, pcs_decode, delay.
97     spi_selectionMode(AVR32_SPI0_ADDRESS, 0, 0, 0); //PS, PCS_decode, DLYBCS
98     //PS = 0: fija
99     //PCS = 0: sin decodificación
100    //DLYBCS = DLY*CLK, no especificado
101
102    spi_selectChip(AVR32_SPI0_ADDRESS, 3);
103
104    // Enable SPI module.
105    spi_enable(AVR32_SPI0_ADDRESS);
106    spi_setupChipReg(AVR32_SPI0_ADDRESS, &spiOptions, PBA_HZ);
107    /
108    ****/
109    while (true)
110    {
111        switch (state) {
112            case 0:
113                //do nothing
114                break;
115            case 1: //programacion de humedad
116                state1();
117                break;
118            case 2: //programar temp
119                state2();
120                break;
121            case 3: //contador arriba y abajo
122                state3();
123                break;
124            case 4: //spi
125                state4();
126                break;
127        } //Fin switch
128    } //Fin While
129
130
131    void state1(void){//increment humidity
132        if(btn_pressed == UP){
133            humidity++;
134            if (humidity > 4) humidity = 1;
135            leds(0b1000>>(humidity-1));
136        }
137        else if(btn_pressed == CENTER){

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138     if(temperature)
139         state = 3;
140     else
141         state = 0;
142     timer_configured = 0;
143 }
144 else if (btn_pressed == RIGHT || btn_pressed == LEFT || btn_pressed == DOWN){
145     humidity = 0; //invalidar seleccion
146 }
147 btn_pressed = NONE;
148 }
149 void state2(void){
150     if(btn_pressed == LEFT){
151         temperature = 1;
152     }
153     else if(btn_pressed == RIGHT){
154         temperature = 2;
155     }
156     else if(btn_pressed == CENTER){
157         if(humidity)
158             state = 3; //pasar a generar PWM
159         else
160             state = 0;
161         timer_configured = 0;
162     }
163     else if (btn_pressed == UP || btn_pressed == DOWN){
164         temperature = 0;
165     }
166     btn_pressed = NONE;
167 }
168 void state3(void){
169     if (!timer_configured){
170         //fPBA=16MHz; fPBA/32=500kHz => TPBA=8e-6 seg
171         //Tpwm= 30ms => rc = Tpwm/TPBA = 3750
172         //20%(3750) = 750
173         //40%(3750) = 1500
174         //60%(3750) = 2250
175         //80%(3750) = 3000
176         //Tpwm= 70ms => rc = Tpwm/TPBA = 8750
177         //20%(8750) = 1750
178         //40%(8750) = 3500
179         //60%(8750) = 5250
180         //80%(8750) = 7000
181         gpio_set_gpio_pin(86); //Para iniciar PWM en 1
182         if(temperature == 1){
183             //period = 30 ms
184             tc_write_rc(&AVR32_TC0, 2, 3750);
185             tc_write_ra(&AVR32_TC0, 2, 750*humidity);
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186     }
187     else if(temperature ==2){
188         //period = 70ms
189         tc_write_rc(&AVR32_TC0, 2, 8750);
190         tc_write_ra(&AVR32_TC0, 2, 1750*humidity);
191     }
192     tc_start(&AVR32_TC0,2);
193     timer_configured = 1;
194 }
195
196 }
197 void state4(void){
198     if (humidity && temperature){
199         //send SPI
200         spi_write(AVR32_SPI0_ADDRESS, humidity);
201         spi_write(AVR32_SPI0_ADDRESS, temperature-1);
202         state = 0;
203     }
204 }
205
206 void leds(uint8_t value){
207     if ((value & 0b1000)>>3)gpio_clr_gpio_pin(LED0); else gpio_set_gpio_pin  ↗
208         (LED0);
209     if ((value & 0b0100)>>2)gpio_clr_gpio_pin(LED1); else gpio_set_gpio_pin  ↗
210         (LED1);
211     if ((value & 0b0010)>>1)gpio_clr_gpio_pin(LED2); else gpio_set_gpio_pin  ↗
212         (LED2);
213     if (value & 0b0001)gpio_clr_gpio_pin(LED3); else gpio_set_gpio_pin(LED3);
214 }//Fin Fn
215 void btn_interrupt_routine (void){
216     if (gpio_get_pin_interrupt_flag(BTN_UP)) {
217         btn_pressed=UP;
218         state=1;
219         gpio_clear_pin_interrupt_flag(BTN_UP);
220     }
221     if (gpio_get_pin_interrupt_flag(BTN_DOWN)){
222         btn_pressed=DOWN;
223         state=4;
224         gpio_clear_pin_interrupt_flag(BTN_DOWN);
225     }
226     if (gpio_get_pin_interrupt_flag(BTN_RIGHT)){
227         btn_pressed=RIGHT;
228         state=2;
229         gpio_clear_pin_interrupt_flag(BTN_RIGHT);
230     }
231     if (gpio_get_pin_interrupt_flag(BTN_LEFT)){
232         btn_pressed=LEFT;
233         state=2;
234         gpio_clear_pin_interrupt_flag(BTN_LEFT);
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232     }
233     if (gpio_get_pin_interrupt_flag(BTN_CENTER)){
234         gpio_clear_pin_interrupt_flag(BTN_CENTER);
235         btn_pressed=CENTER;
236     }
237     if (gpio_get_pin_interrupt_flag(BTN_CENTER)){
238         gpio_clear_pin_interrupt_flag(BTN_CENTER);
239     }
240 } //Fin Botones
241 static void init_tc_output(volatile avr32_tc_t *tc, unsigned int channel){
242     // Options for waveform generation.
243     tc_waveform_opt_t waveform_opt =
244     {
245         .channel = channel,                // Channel ↗
246         .selection.
247         .bswtrg = 0, //TC_EVT_EFFECT_NOOP,    // Software trigger ↗
248         .effect on TIOB.
249         .beevt = 0, //TC_EVT_EFFECT_NOOP,    // External event effect ↗
250         .on TIOB.
251         .bcpc = 0, //TC_EVT_EFFECT_NOOP,    // RC compare effect on ↗
252         .TIOB.
253         .bcpb = 0, //TC_EVT_EFFECT_NOOP,    // RB compare effect on ↗
254         .TIOB.
255         .aswtrg = 0, //TC_EVT_EFFECT_NOOP, // Trigger no cambia la salida
256         .aeevt = 0, //TC_EVT_EFFECT_NOOP, // Trigger no cambia la salida
257         .acpc = 1, //TC_EVT_EFFECT_SET,      // RC compare effect ↗
258         .on TIOA.
259         .acpa = 2, //TC_EVT_EFFECT_CLEAR,    // RA compare effect on ↗
260         .TIOA.
261         .wavsel = 2, //Simple pendiente, RC determina Periodo, RA Duty
262         .enetrg = 0, //No hay trigger por evento externo FALSE,
263         .eevt = 0, //No hay trigger por evento externo ↗
264         .TC_EXT_EVENT_SEL_TIOB_INPUT,
265         .eevtedg = 0, //No hay trigger por evento externo TC_SEL_NO_EDGE,
266         .cpcdis = FALSE, //Se va a generar mas de un periodo
267         .cpcstop = FALSE, //Se va a generar mas de un periodo
268         .burst = 0, //Sin Burst, TC_BURST_NOT_GATED
269         .clki = 0, //Reloj no invertido, TC_CLOCK_RISING_EDGE
270         .tcclks = 5, // fPBA/128, TC4, TC_CLOCK_SOURCE_TC4
271     };
272     // Initialize the timer/counter waveform.
273     tc_init_waveform(tc, &waveform_opt);
274 }

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