Sparse Temporal Spanners with Low Stretch

Davide Bilò, Gianlorenzo D'Angelo, Luciano Gualà, **Stefano Leucci**, and Mirko Rossi











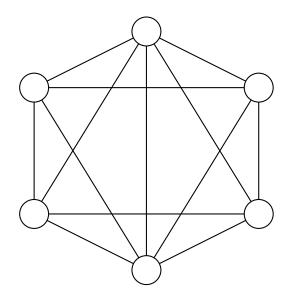




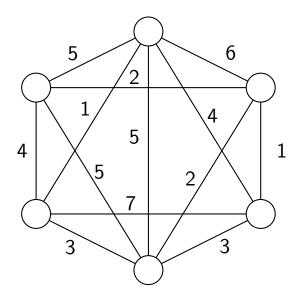




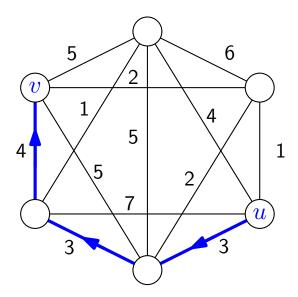




A temporal graph is a graph G=(V,E) in which each edge $e\in E$ has an associated **time-label** $\lambda(e)\in\mathbb{N}^+$

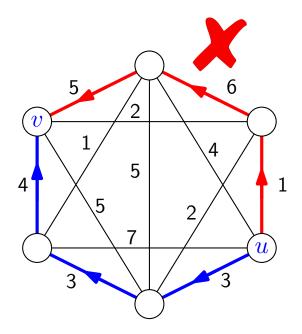


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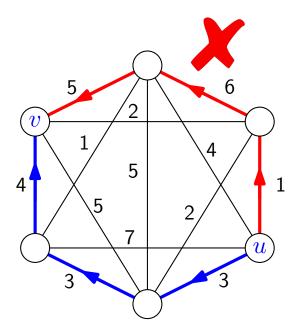
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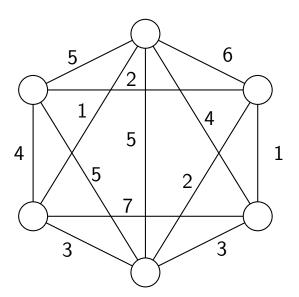
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A vertex u is **temporally connected** to a vertex v if there is a temporal path from u to v (not symmetric)

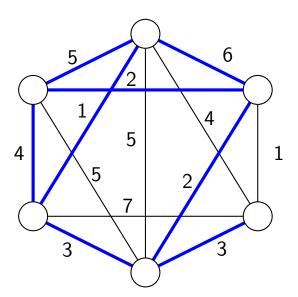
A **temporal spanner** of a temporal graph G is a subgraph H of G that preserves the temporal connectivity between all pairs of vertices

u is temporally connected to v in $G \iff u$ is temporally connected to v in H



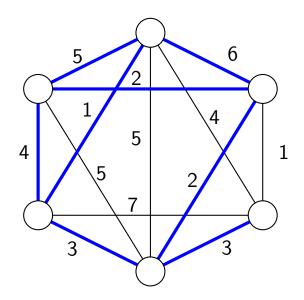
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The **size** of a temporal spanner is the number of its edges

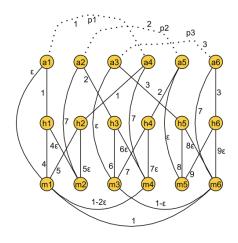
Kempe et al. [STOC 2000]: Are there sparse (small size) temporal spanners?

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No (on general input graphs).



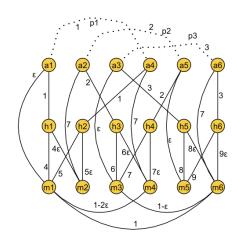
Lower Bound of $\Omega(n^2)$.

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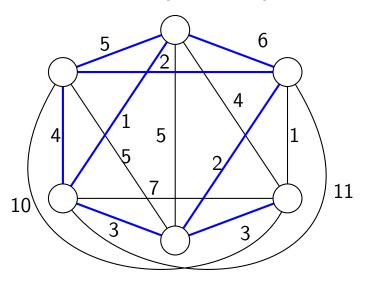


Lower Bound of $\Omega(n^2)$.



Casteigts et al. [ICALP 2019]:

Yes, on temporal cliques.



Upper Bound of $O(n \log n)$.

Kempe et al. [STOC 2000]: Are there sparse (small size) temporal spanners?



The temporal spanner of Casteigts et al. only preserves temporal reachability

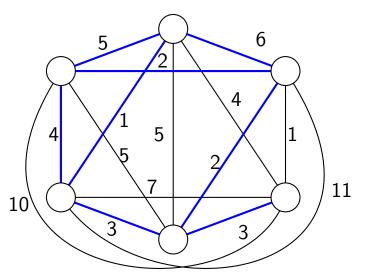
No guarantee on how "temporal distances" between vertices are affected

High "temporal stretch"



Casteigts et al. [ICALP 2019]:

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Upper Bound of $O(n \log n)$.

A temporal spanner with stretch α of a temporal graph G is a temporal spanner H of G such that, for every pair of vertices u,v:

$$\mathsf{dist}_H(u,v) \leq \alpha \cdot \mathsf{dist}_G(u,v)$$

 $\operatorname{dist}(u,v) = +\infty \text{ ff } u \text{ is not}$ temporally connected to v

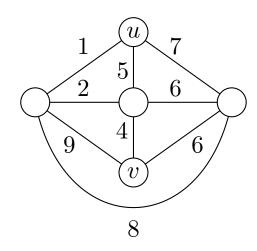
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How do we define **dist**?

Unlike static graphs, there are several natural notions of distance for temporal graphs:



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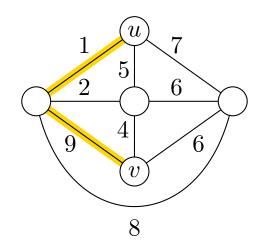
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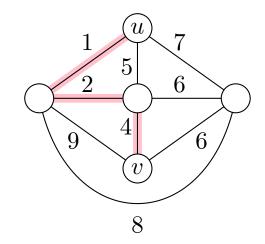
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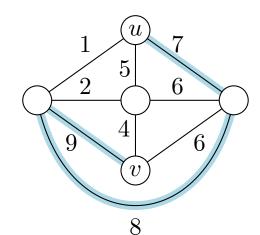
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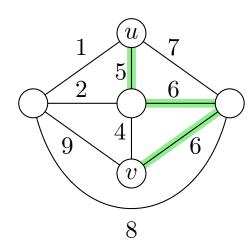
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- fastest travel time (time elapsed between the first and last edge in a temporal path from u to v)









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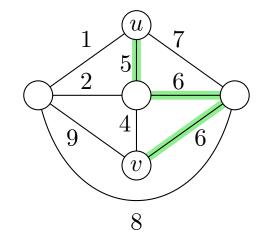
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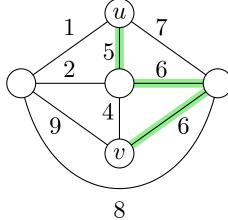
Our choice. Generalizes distance on static graphs.

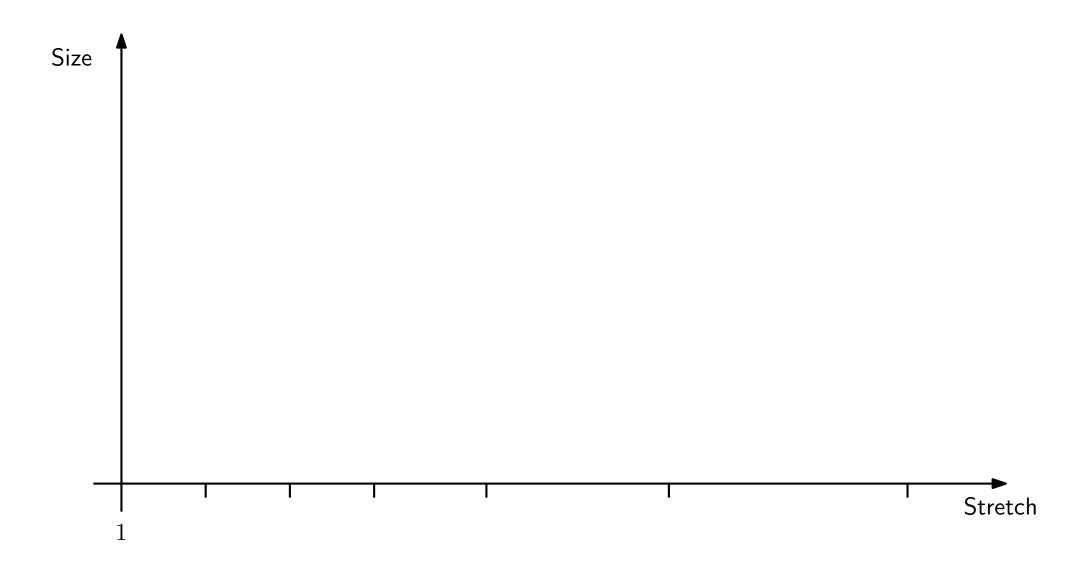
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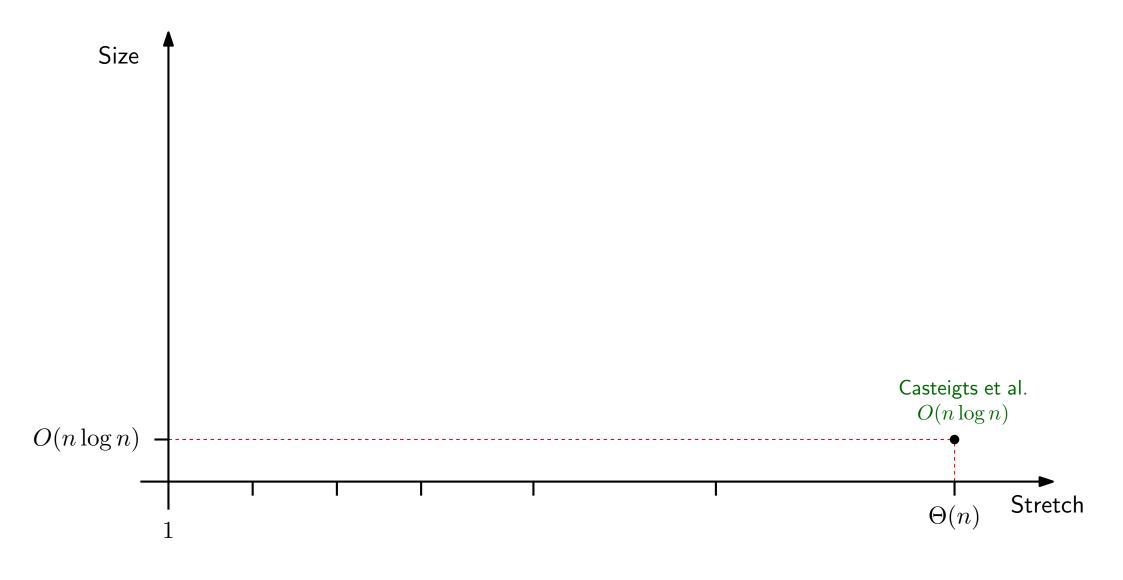


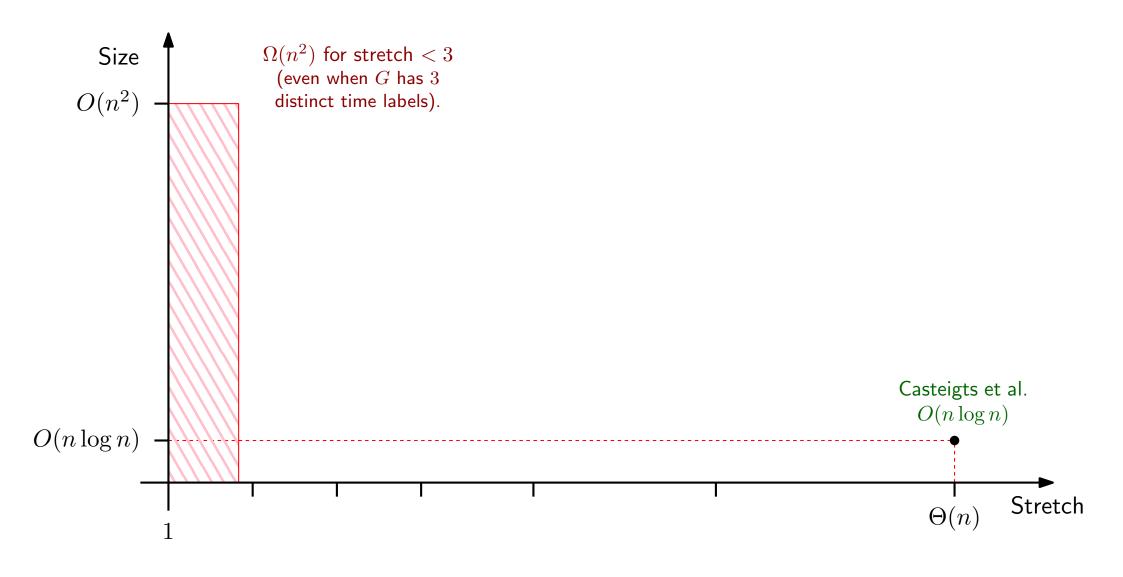


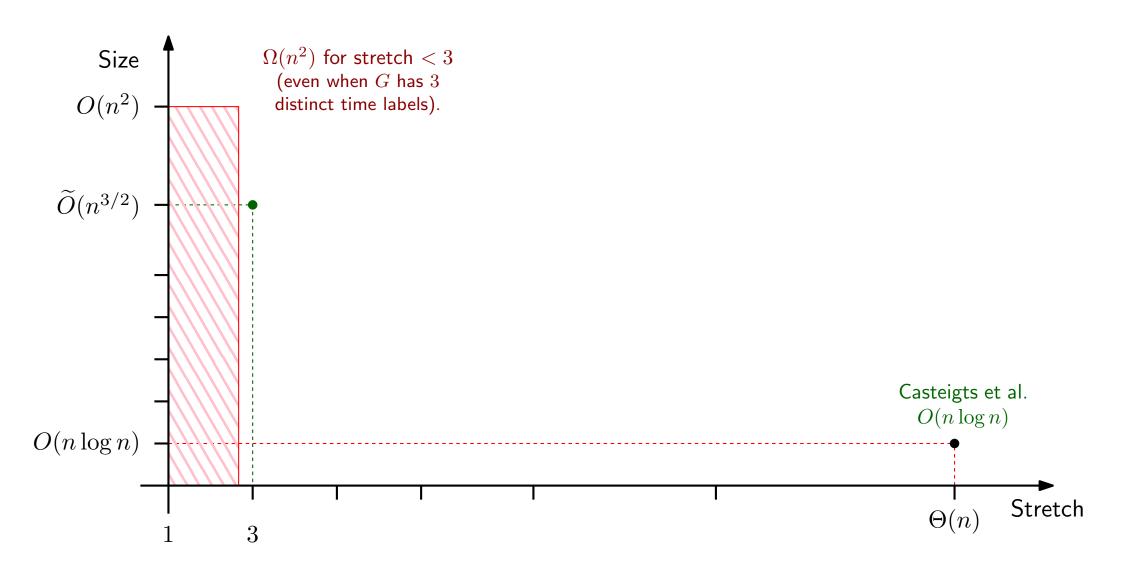


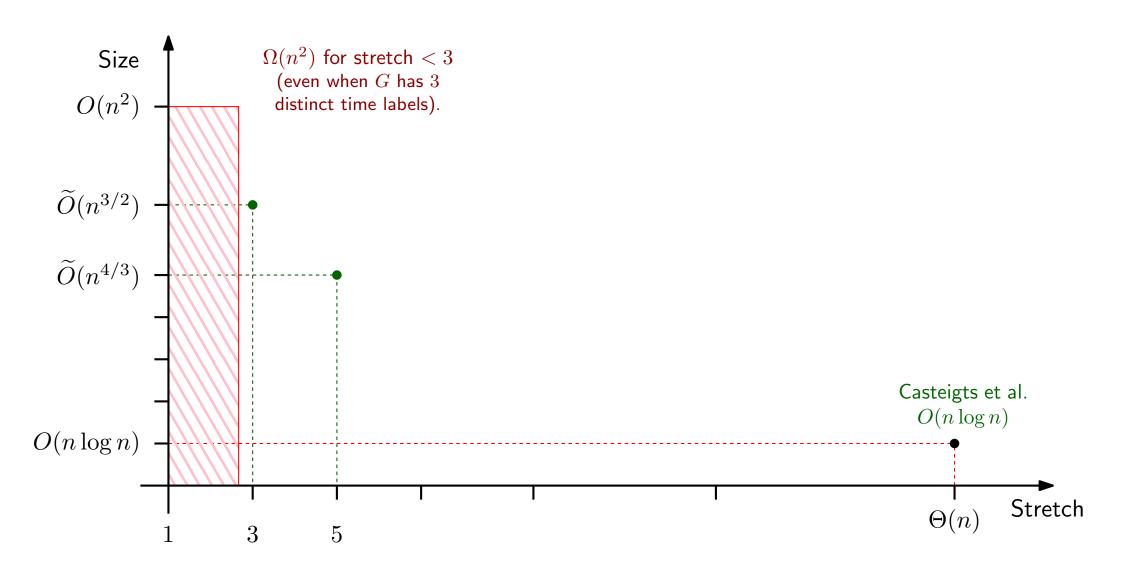


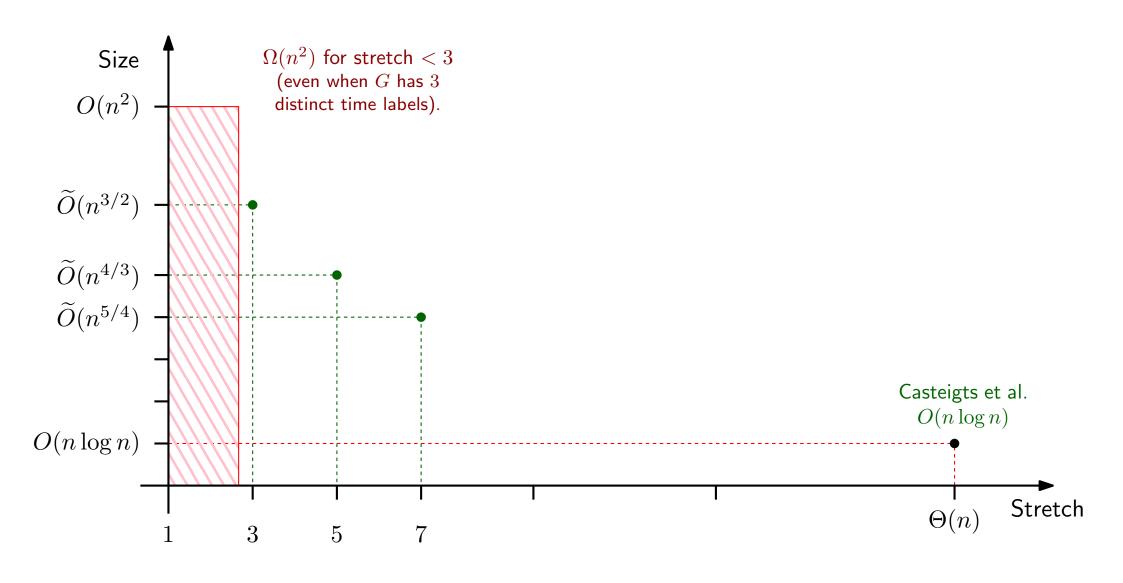


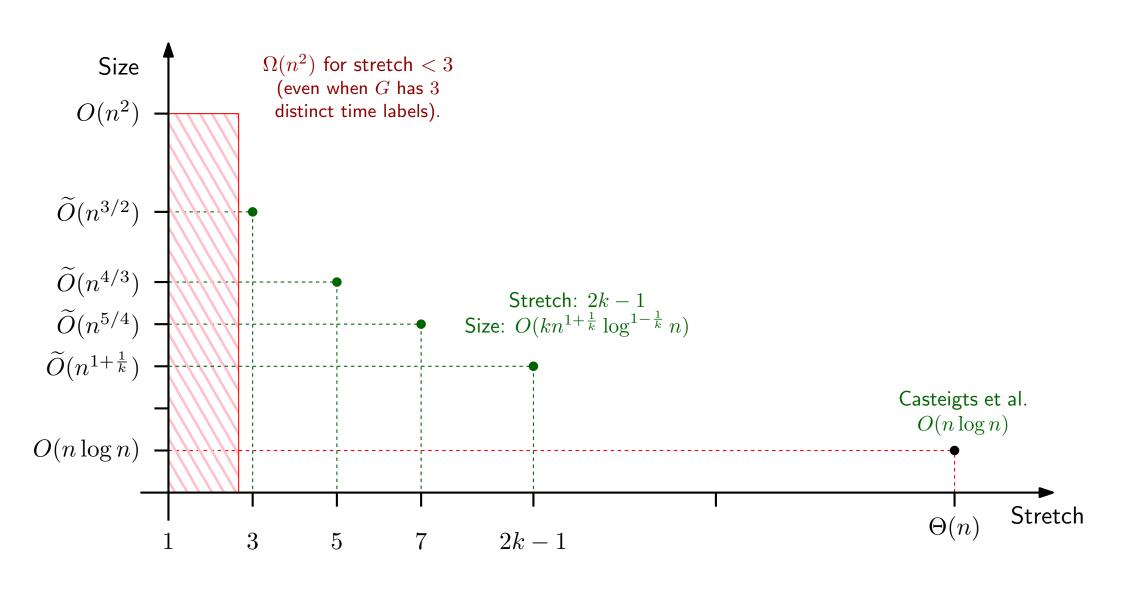


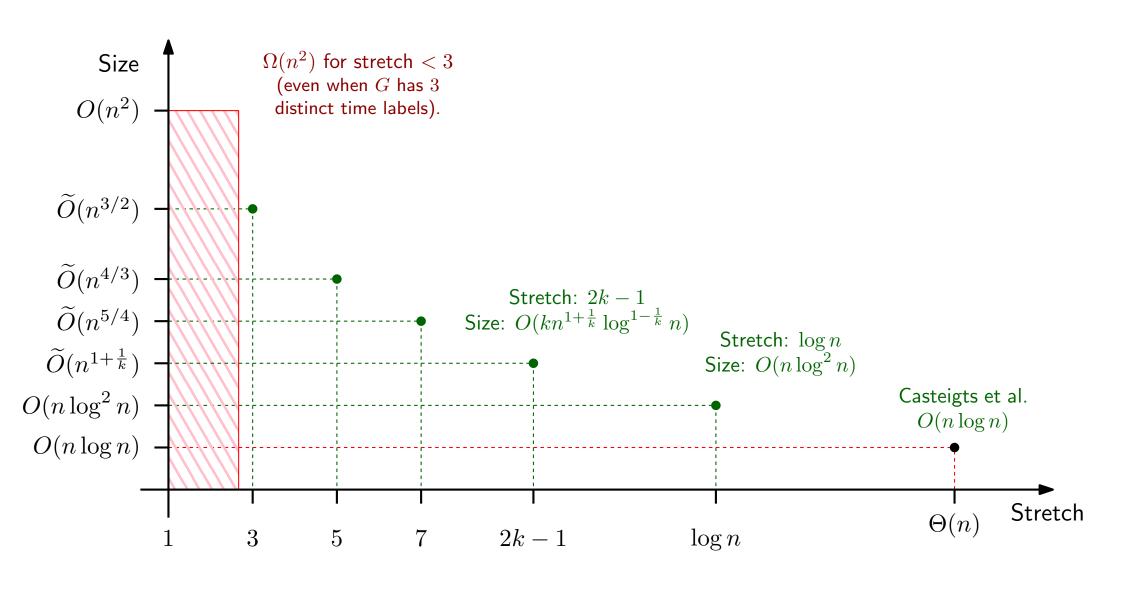


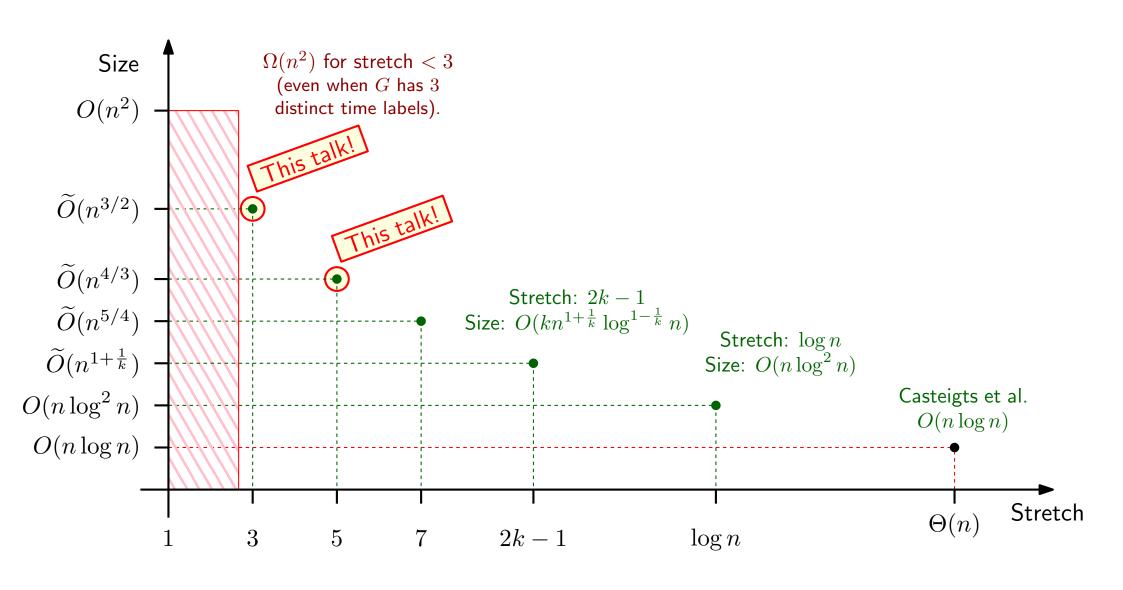












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- Stretch: $\alpha = 1 + \varepsilon$
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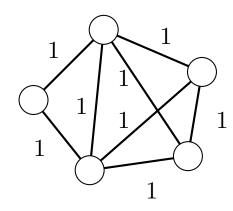
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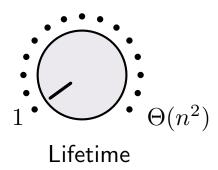
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Our Results: The Role of Lifetime

The **lifetime** L of a temporal graph is the number of its distinct time-labels W.l.o.g. the time-labels are in $1,\ldots,L$ Intuitively, the lifetime measures "how temporal" is the graph

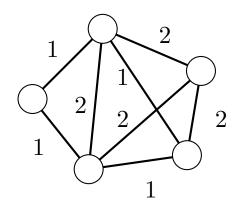


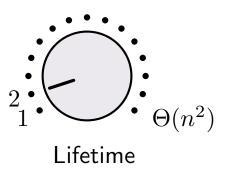


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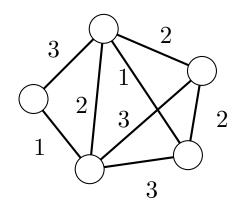
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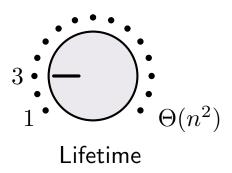




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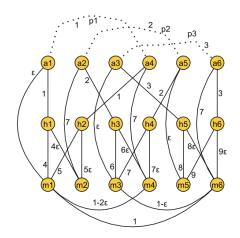


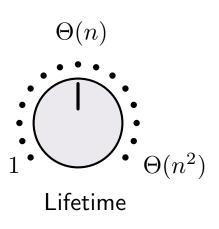
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- For $L=\Theta(n)$ the lower bound of $\Omega(n^2)$ on temporal connectivity applies Axiotis and Fotakis [ICALP 2016]

On temporal cliques:

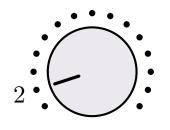
Lifetime

$$\alpha = 2$$

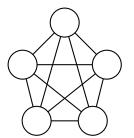
$$\alpha = 3$$

$$L=2$$

 $O(n \log n)$



Lifetime



On temporal cliques:

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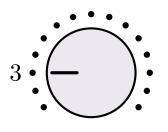
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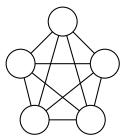
$$O(n \log n)$$

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$$\Omega(n^2)$$



Lifetime



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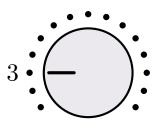
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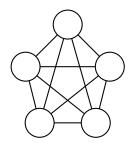
$$O(n \log n)$$

$$\Omega(n^2)$$

$$O(n \log n)$$



Lifetime



On temporal cliques:

L

Lifetime	Stretch			
	$\alpha = 2$	$\alpha = 3$	L	
L=2	$O(n \log n)$			
L=3	$\Omega(n^2)$	$O(n \log n)$		
L		$O(2^L \cdot n \log n)$	Lifetime	

 $O(2^L \cdot n \log n)$

On temporal cliques:

Lifetime

Stretch

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$$\alpha = 3$$

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$$O(n \log n)$$

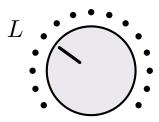
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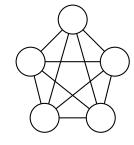
 $\Omega(n^2)$

 $O(n \log n)$

 $O(2^L \cdot n \log n)$



Lifetime

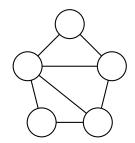


On general temporal graphs:

$$\alpha$$
-spanner of size $f(n)$ for static graphs



temporal spanner of size $O(L \cdot f(n))$ for temporal graphs with lifetime ${\cal L}$



On temporal cliques:

Lifetime

Stretch

$$\alpha = 2$$

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$$L=2$$

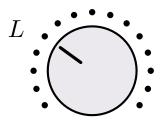
$$O(n \log n)$$

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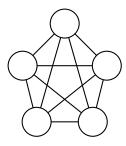
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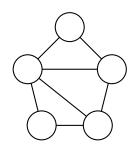


On general temporal graphs:

 α -spanner of size f(n) for static graphs



temporal spanner of size $O(L \cdot f(n))$ for temporal graphs with lifetime L



Consequence: any temporal graph with lifetime L=o(n) admits a temporal spanner with stretch $\log n$ and subquadratic size.

On temporal cliques:

Lifetime

$$\alpha = 2$$

$$\alpha = 3$$

$$L=2$$

$$O(n \log n)$$

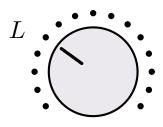
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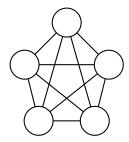
$$\Omega(n^2)$$

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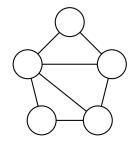


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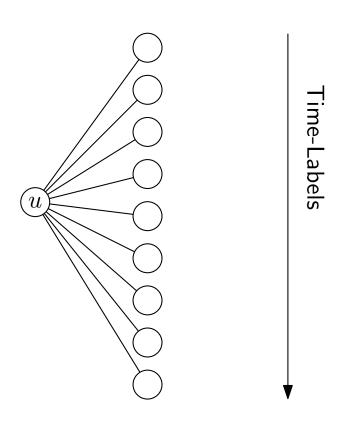
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VS

Lower bound of $\Omega(n^2)$ for $L = \Theta(n)$, regardless of stretch.

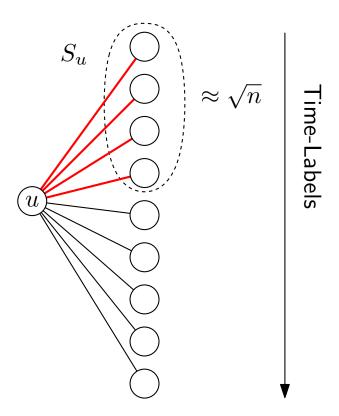
Our Temporal 3-Spanner of Size $\widetilde{O}(n\sqrt{n})$ (for temporal cliques)

For every $u \in V$:



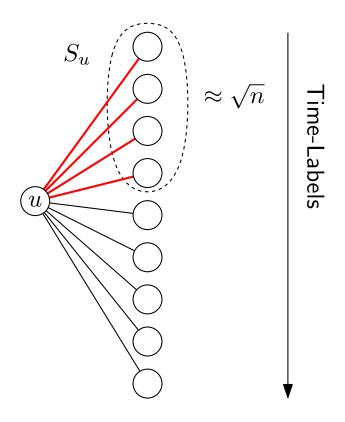
For every $u \in V$:

 $S_u = \text{set of neighbors } v \text{ of } u \text{ such that } (u, v) \text{ is one the } \approx \sqrt{n} \text{ edges incident to } u \text{ with the smallest label}$



For every $u \in V$:

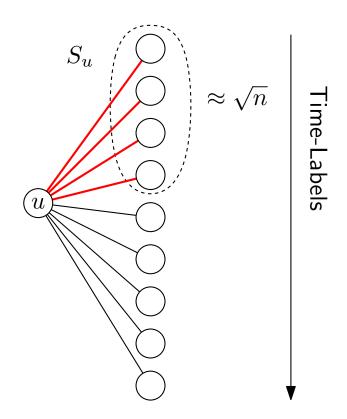
 $S_u = \text{set of neighbors } v \text{ of } u \text{ such that } (u, v) \text{ is one the } \approx \sqrt{n} \text{ edges incident to } u \text{ with the smallest label}$



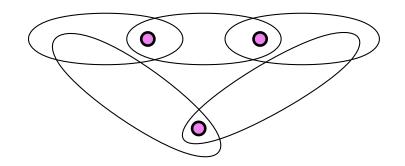
 $\# red edges = O(n\sqrt{n})$

For every $u \in V$:

 $S_u = \text{set of neighbors } v \text{ of } u \text{ such that } (u,v) \text{ is one the } \approx \sqrt{n} \text{ edges incident to } u \text{ with the smallest label}$



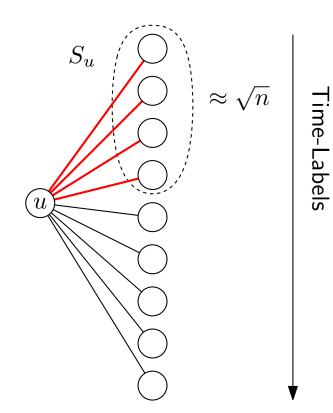
Compute a hitting set R of the collection $C = \{S_u \mid u \in V\}$



 $\#\mathrm{red}$ edges $=O(n\sqrt{n})$

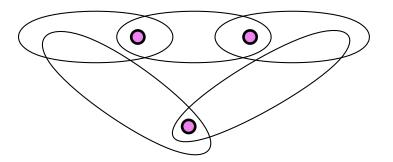
For every $u \in V$:

 $S_u = \text{set of neighbors } v \text{ of } u \text{ such that } (u,v) \text{ is one the } \approx \sqrt{n} \text{ edges incident to } u \text{ with the smallest label}$



 $\# red edges = O(n\sqrt{n})$

Compute a hitting set R of the collection $C = \{S_u \mid u \in V\}$



Lemma: If every set S_u has size at least k, an hitting set of \mathcal{C} of size $\widetilde{O}(n/k)$ can be found in polynomial time.

$$|R| = \widetilde{O}(\frac{n}{\sqrt{n}}) = \widetilde{O}(\sqrt{n})$$

Cluster the vertices around R:

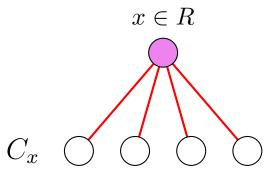
• Each vertex $x \in R$ is a center





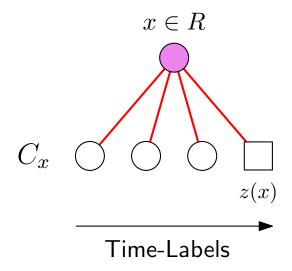
Cluster the vertices around R:

- Each vertex $x \in R$ is a center
- Arbitrarily assign each vertex u to a neighboring center $x \in S_u$
- Each center x, along with the set C_x of its assigned nodes, forms a **cluster**



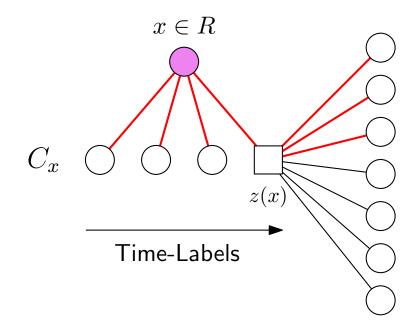
Cluster the vertices around R:

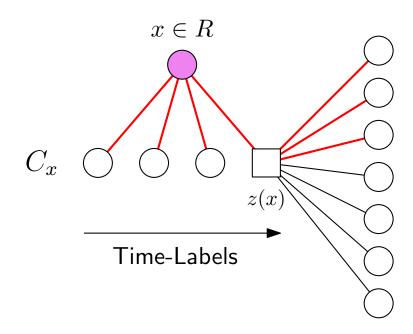
- Each vertex $x \in R$ is a center
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- For each center x, choose a **special** vertex $z(x) \in C_x$ that maximizes the time-label of (x, z(x))



Cluster the vertices around R:

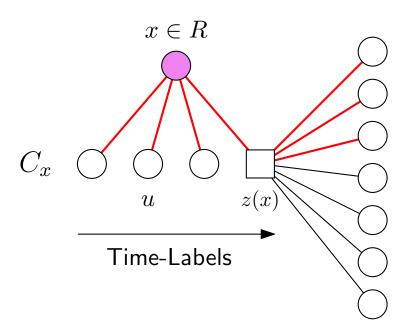
- Each vertex $x \in R$ is a center
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 $H=\operatorname{all}\operatorname{red}\operatorname{edges}$

Consider two vertices u,v and focus on the cluster of u with center \boldsymbol{x}

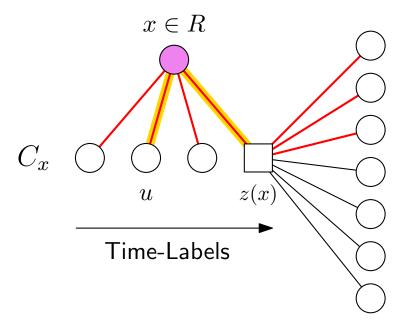


 $H=\operatorname{all}\operatorname{red}\operatorname{edges}$

Consider two vertices u,v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

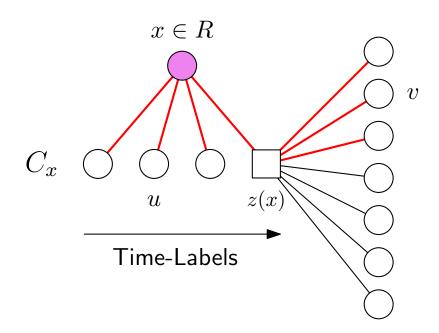


Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

• There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$



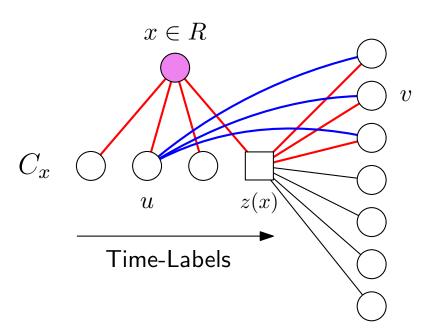
Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

• There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

• Add all blue edges between u and $S_{z(x)}$



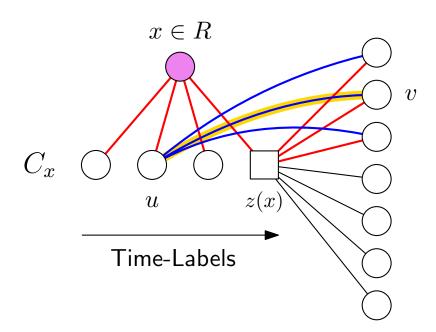
Consider two vertices u,v and focus on the cluster of u with center x

Case 1: v = z(x)

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Case 2: $v \in S_{z(x)}$

- ullet Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v



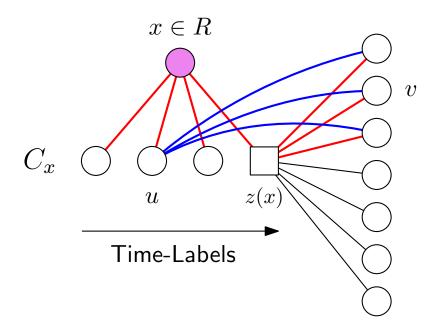
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- Add all blue edges between u and $S_{z(x)}$
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 $H = \mathsf{all} \ \mathsf{red} \ \mathsf{edges} \ \cup \ \mathsf{all} \ \mathsf{blue} \ \mathsf{edges}$

Consider two vertices u, v and focus on the cluster of u with center x

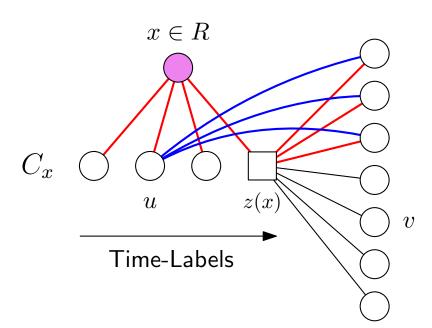
Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

- ullet Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$



 $H = \text{all red edges} \cup \text{all blue edges}$

Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

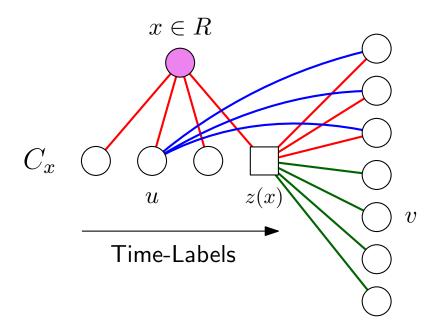
ullet There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

- Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

ullet Add all green edges between z(x) and V



H= all red edges \cup all blue edges

Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

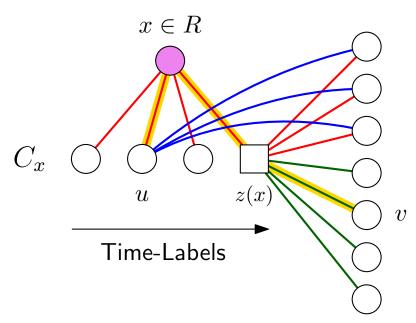
Case 2: $v \in S_{z(x)}$

- Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

H= all red edges \cup all blue edges



Consider two vertices u, v and focus on the cluster of u with center x

Case 1:
$$v = z(x)$$

ullet There is a red path of length ≤ 2 between u and v

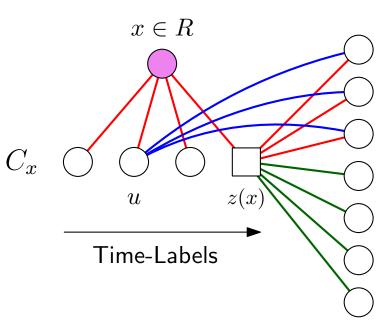
Case 2: $v \in S_{z(x)}$

- Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

H= all red edges \cup all blue edges \cup all green edges



Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

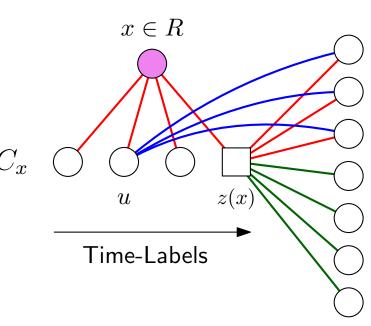
Case 2: $v \in S_{z(x)}$

- ullet Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

 $H=\operatorname{all}\operatorname{red}\operatorname{edges}\ \cup\operatorname{all}\operatorname{blue}\operatorname{edges}\ \cup\operatorname{all}\operatorname{green}\operatorname{edges}$



Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

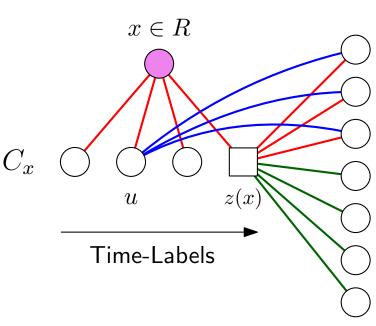
Case 2: $v \in S_{z(x)}$

- ullet Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

H= all red edges $\ \cup$ all blue edges $\ \cup$ all green edges $O(n\sqrt{n})$



Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

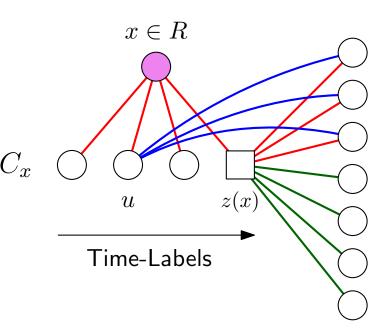
- ullet Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

 $H={
m all}\ {
m red}\ {
m edges}\ \cup\ {
m all}\ {
m blue}\ {
m edges}\ \cup\ {
m all}\ {
m green}\ {
m edges}$

$$O(n\sqrt{n}) + n \cdot O(\sqrt{n})$$



Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

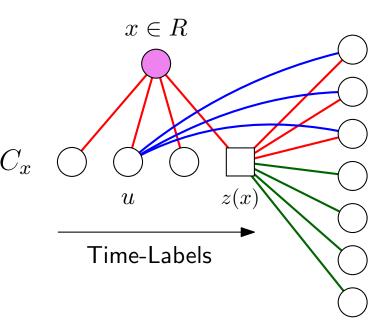
- ullet Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

 $H={
m all} \ {
m red} \ {
m edges} \ \ \cup \ {
m all} \ {
m blue} \ {
m edges} \ \ \cup \ {
m all} \ {
m green} \ {
m edges}$

$$O(n\sqrt{n}) + n \cdot O(\sqrt{n}) + |R| \cdot O(n)$$



Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

ullet There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

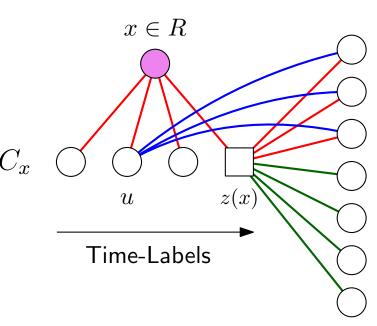
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m all} \ {
m red} \ {
m edges} \ \ \cup \ {
m all} \ {
m blue} \ {
m edges} \ \ \cup \ {
m all} \ {
m green} \ {
m edges}$

$$O(n\sqrt{n})$$
 + $n \cdot O(\sqrt{n})$ + $\widetilde{O}(\sqrt{n}) \cdot O(n)$



Consider two vertices u, v and focus on the cluster of u with center x

Case 1: v = z(x)

• There is a red path of length ≤ 2 between u and v

Case 2: $v \in S_{z(x)}$

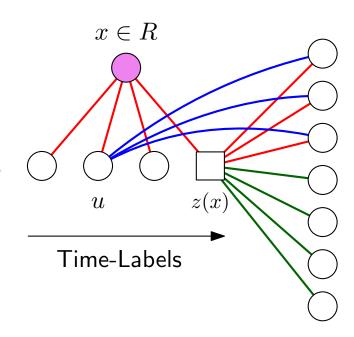
- Add all blue edges between u and $S_{z(x)}$
- ullet There is a blue edge between u and v

Case 3: $v \neq z$ and $v \notin S_{z(x)}$

- ullet Add all green edges between z(x) and V
- ullet There is a red and green path of length 3 between u and v

 $H={
m all}\ {
m red}\ {
m edges}\ \cup\ {
m all}\ {
m blue}\ {
m edges}\ \cup\ {
m all}\ {
m green}\ {
m edges}$

$$O(n\sqrt{n})$$
 + $n \cdot O(\sqrt{n})$ + $\widetilde{O}(\sqrt{n}) \cdot O(n)$

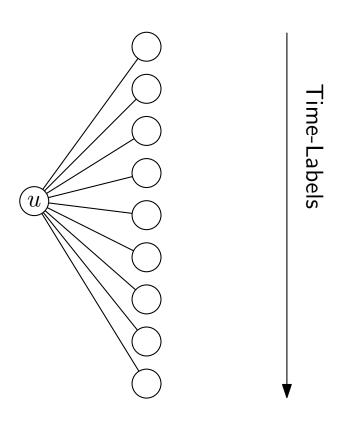


Size?

H is a temporal spanner with stretch 3 and size $\widetilde{O}(n^{3/2})$

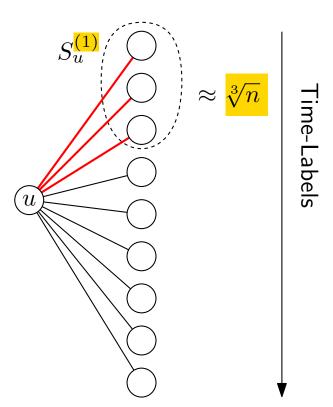
Our Temporal 5-Spanner of Size $\widetilde{O}(n\sqrt[3]{n})$ (for temporal cliques)

For every $u \in V$:



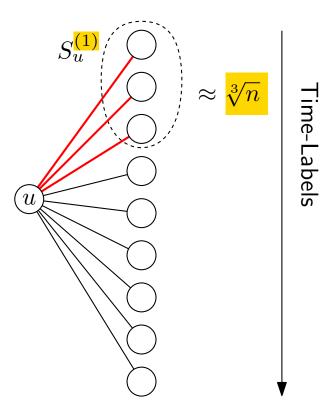
For every $u \in V$:

 $S_u^{(1)}$ = set of neighbors v of u such that (u,v) is one the $\approx \sqrt[3]{n}$ edges incident to u with the smallest label



For every $u \in V$:

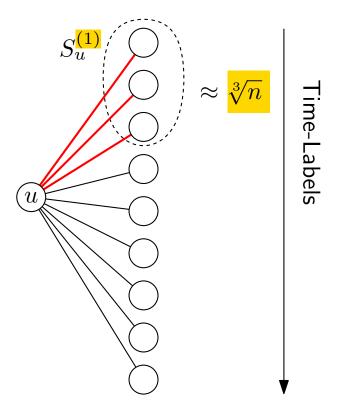
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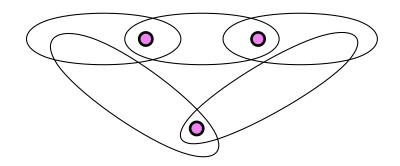
 $\# red edges = O(n\sqrt[3]{n})$

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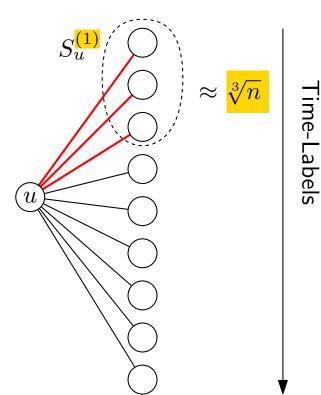
Compute a hitting set $R^{(1)}$ of the collection $\mathcal{C} = \{S_u^{(1)} \mid u \in V\}$



 $\# red edges = O(n\sqrt[3]{n})$

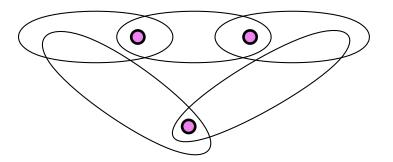
For every $u \in V$:

 $S_u^{(1)}$ = set of neighbors v of u such that (u,v) is one the $\approx \sqrt[3]{n}$ edges incident to u with the smallest label



 $\# \text{red edges} = O(n \sqrt[3]{n})$

Compute a hitting set $R^{(1)}$ of the collection $\mathcal{C} = \{S_u^{(1)} \mid u \in V\}$

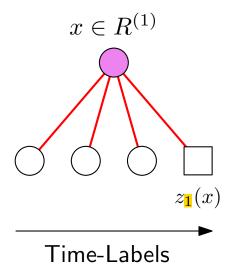


Lemma: If every set S_u has size at least k, an hitting set of \mathcal{C} of size $\widetilde{O}(n/k)$ can be found in polynomial time.

$$|R^{(1)}| = \widetilde{O}(\frac{n}{\sqrt[3]{n}}) = \widetilde{O}(\frac{n^{2/3}}{})$$

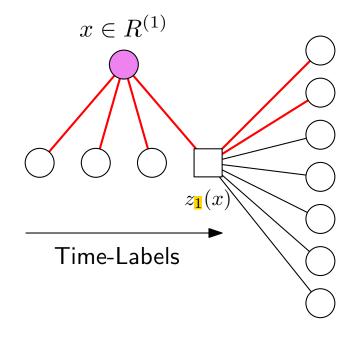
Cluster the vertices in V vertices around $R^{(1)}$:

- For each center $x \in R^{(1)}$, choose a **special vertex** $z_{\mathbf{l}}(x)$ that is assigned to x and maximizes the time-label of $(x, z_1(x))$
- $Z = \{z_1(x) \mid x \in R^{(1)}\}$



Cluster the vertices in V vertices around $R^{(1)}$:

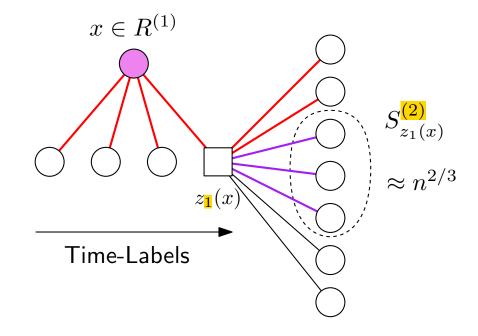
- For each center $x \in R^{(1)}$, choose a **special vertex** $z_{\mathbf{l}}(x)$ that is assigned to x and maximizes the time-label of $(x, z_1(x))$
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Cluster the vertices in V vertices around $R^{(1)}$:

- For each center $x \in R^{(1)}$, choose a **special vertex** $z_{\mathbf{l}}(x)$ that is assigned to x and maximizes the time-label of $(x, z_1(x))$
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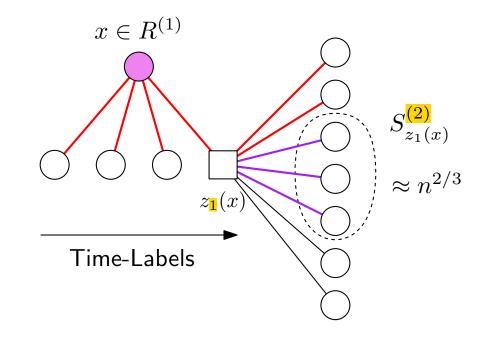
 $S_z^{(2)} =$ set of neighbors v of z such that (u,v) is one the $\approx n^{2/3}$ edges between z and $V \setminus S_z^{(1)}$ with the smallest label



Cluster the vertices in V vertices around $R^{(1)}$:

- For each center $x \in R^{(1)}$, choose a **special vertex** $z_{\mathbf{1}}(x)$ that is assigned to x and maximizes the time-label of $(x, z_1(x))$
- $Z = \{z_1(x) \mid x \in R^{(1)}\}$

 $S_z^{(2)} =$ set of neighbors v of z such that (u,v) is one the $\approx n^{2/3}$ edges between z and $V \setminus S_z^{(1)}$ with the smallest label

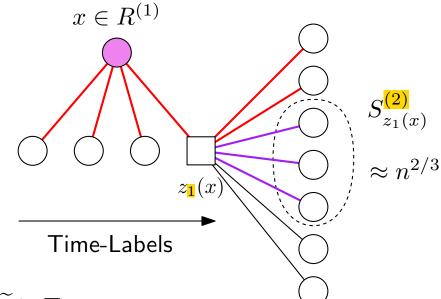


$$\# \mathrm{purple} \ \mathrm{edges} = \widetilde{O}(n^{2/3}) \cdot O(n^{2/3}) = \widetilde{O}(n\sqrt[3]{n})$$

Cluster the vertices in V vertices around $R^{(1)}$:

- For each center $x \in R^{(1)}$, choose a **special vertex** $z_{\mathbf{I}}(x)$ that is assigned to x and maximizes the time-label of $(x, z_1(x))$
- $Z = \{z_1(x) \mid x \in R^{(1)}\}$

 $S_z^{(2)} =$ set of neighbors v of z such that (u,v) is one the $\approx n^{2/3}$ edges between z and $V \setminus S_z^{(1)}$ with the smallest label



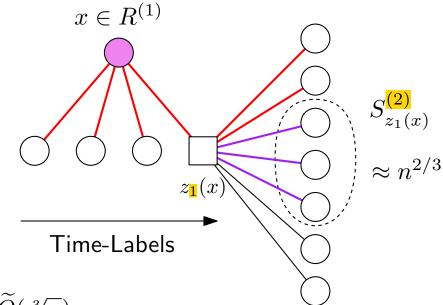
Compute a hitting set $R^{(2)}$ of $\{S_z^{(2)} \mid z \in Z\}$ of size $\widetilde{O}(\sqrt[3]{n})$

$$\# \mathrm{purple} \ \mathrm{edges} = \widetilde{O}(n^{2/3}) \cdot O(n^{2/3}) = \widetilde{O}(n\sqrt[3]{n})$$

Cluster the vertices in V vertices around $R^{(1)}$:

- For each center $x \in R^{(1)}$, choose a special vertex $z_{\mathbf{l}}(x)$ that is assigned to x and maximizes the time-label of $(x, z_1(x))$
- $Z = \{z_1(x) \mid x \in R^{(1)}\}$

 $S_z^{(2)} {=} \operatorname{set}$ of neighbors v of z such that (u,v) is one the $\approx n^{2/3}$ edges between z and $V \setminus S_z^{(1)}$ with the smallest label



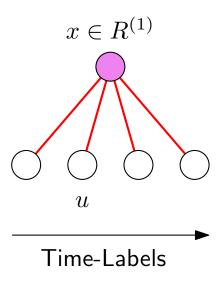
Compute a hitting set $R^{(2)}$ of $\{S_z^{(2)} \mid z \in Z\}$ of size $\widetilde{O}(\sqrt[3]{n})$

Cluster the vertices in Z around $R^{(2)}$:

• For each center $y \in R^{(2)}$, choose a **2nd-level special vertex** $z_2(y)$ that is assigned to y and maximizes the time-label of $(x, z_2(y))$

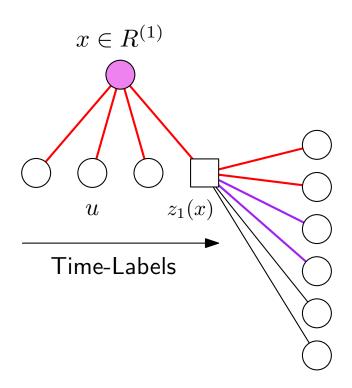
$$\# \text{purple edges} = \widetilde{O}(n^{2/3}) \cdot O(n^{2/3}) = \widetilde{O}(n\sqrt[3]{n})$$

For every $u \in V$:



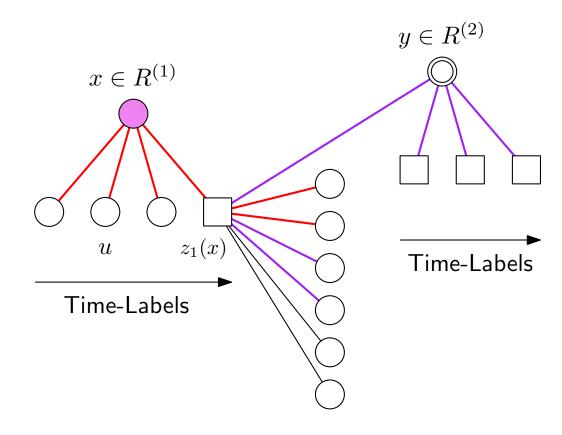
 $H = \mathsf{all} \ \mathsf{red} \ \mathsf{edges} \ \cup \ \mathsf{all} \ \mathsf{purple} \ \mathsf{edges}$

For every $u \in V$:



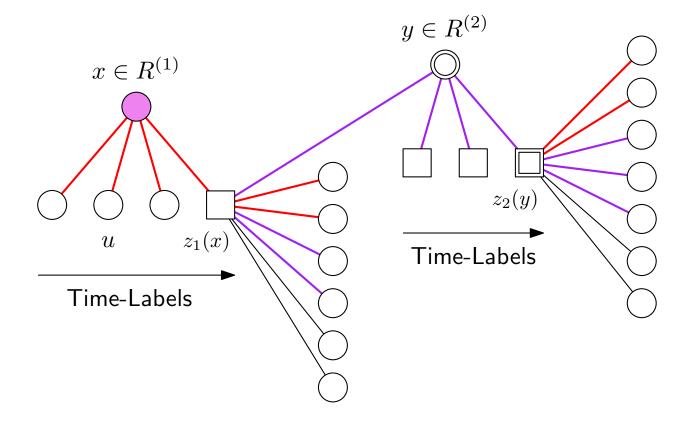
 $H = \mathsf{all} \ \mathsf{red} \ \mathsf{edges} \ \cup \ \mathsf{all} \ \mathsf{purple} \ \mathsf{edges}$

For every $u \in V$:



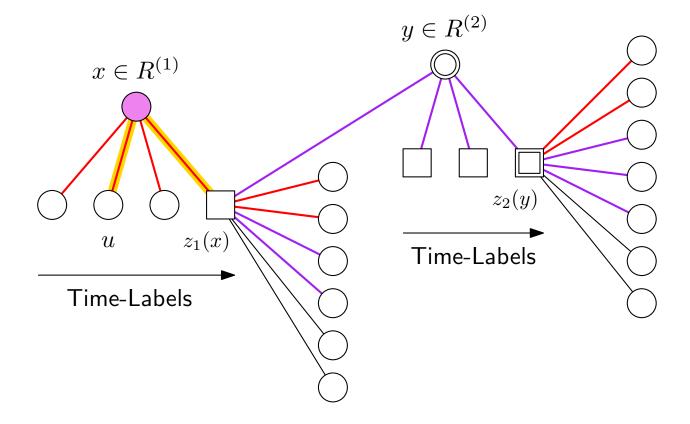
For every $u \in V$:

Case 1: $v = z_1(x)$ or $v = z_2(y)$



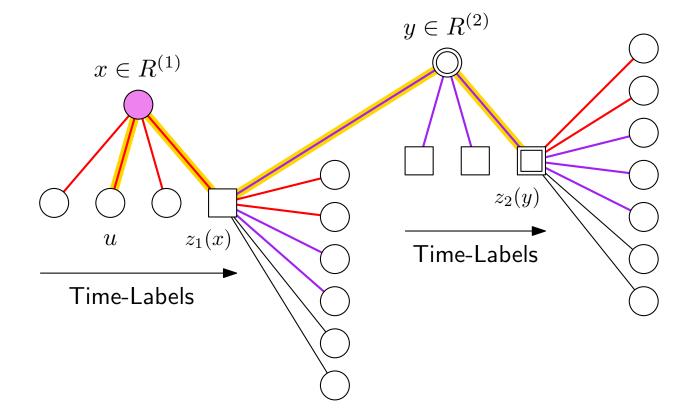
For every $u \in V$:

Case 1: $v = z_1(x)$ or $v = z_2(y)$



For every $u \in V$:

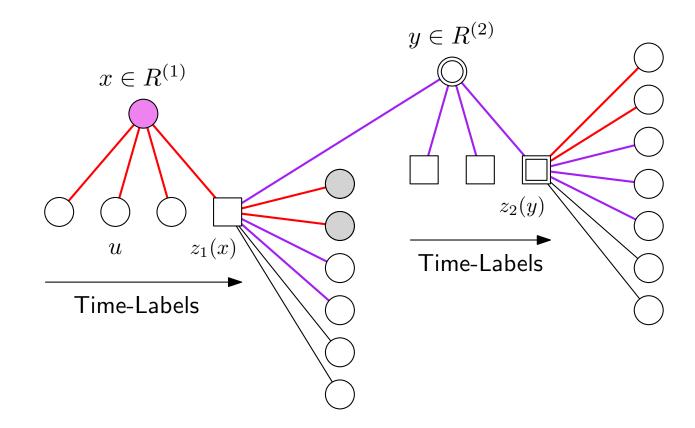
Case 1: $v = z_1(x)$ or $v = z_2(y)$



For every $u \in V$:

Case 1: $v = z_1(x)$ or $v = z_2(y)$

Case 2a: $v \in S_{z_1(x)}^{(1)}$



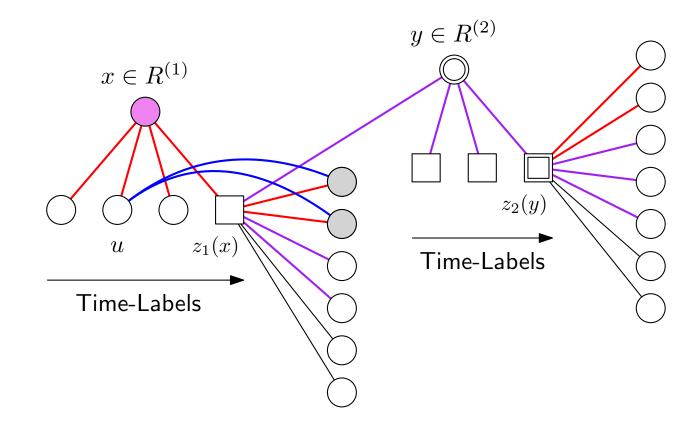
 $H = \mathsf{all} \ \mathsf{red} \ \mathsf{edges} \ \cup \ \mathsf{all} \ \mathsf{purple} \ \mathsf{edges}$

For every $u \in V$:

Case 1: $v = z_1(x)$ or $v = z_2(y)$

Case 2a: $v \in S_{z_1(x)}^{(1)}$

• Add all blue edges between u and $S_{z_1(x)}^{(1)}$



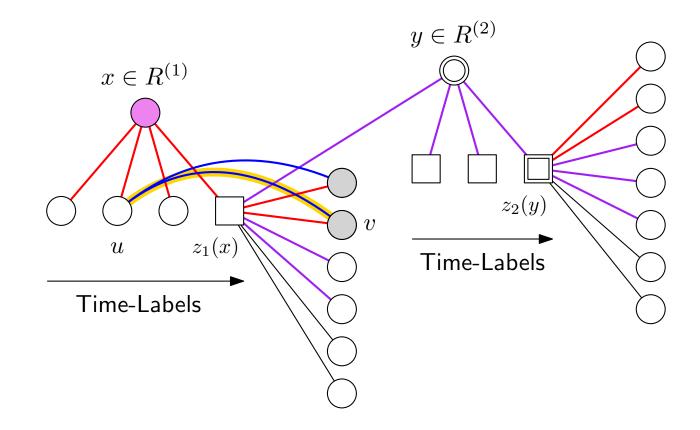
H= all red edges \cup all purple edges \cup all blue edges

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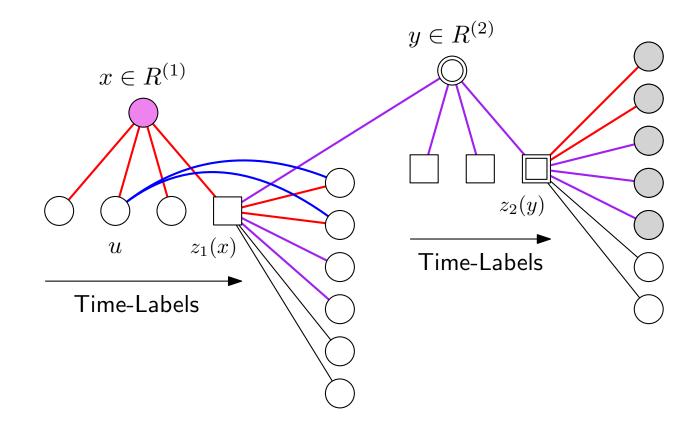
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H= all red edges \cup all purple edges \cup all blue edges

For every $u \in V$:

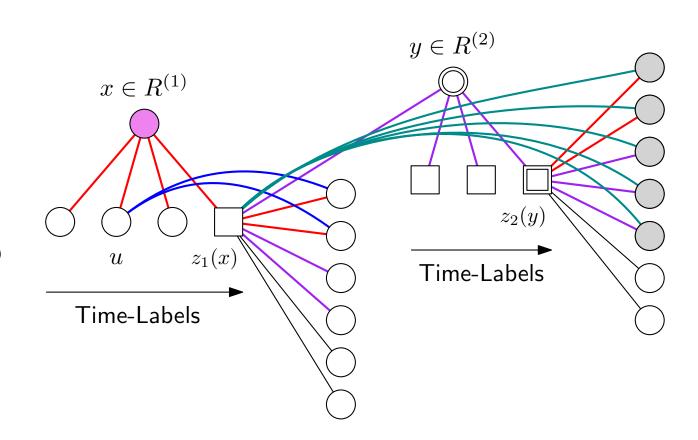
Case 1:
$$v = z_1(x)$$
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Case 2a:
$$v \in S_{z_1(x)}^{(1)}$$

• Add all blue edges between u and $S_{z_1(x)}^{(1)}$

Case 2b:
$$v \in S_{z_2(y)}^{(1)}$$
 or $v \in S_{z_2(y)}^{(2)}$

• Add all teal edges between $z_1(x)$ and $S_{z_2(y)}^{(1)} \cup S_{z_2(y)}^{(2)}$



H= all red edges \cup all purple edges \cup all blue edges \cup all teal edges

For every $u \in V$:

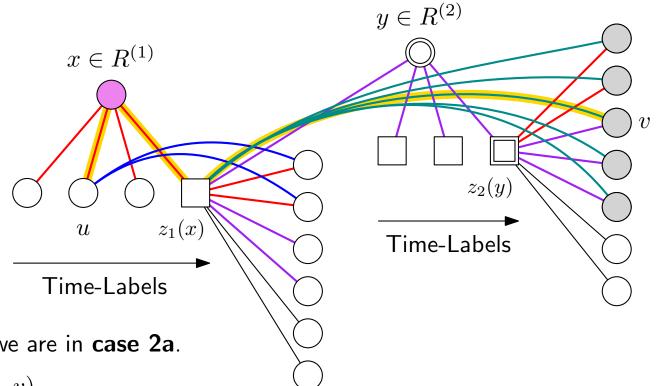
Case 1:
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Case 2a:
$$v \in S_{z_1(x)}^{(1)}$$

• Add all blue edges between u and $S_{z_1(x)}^{(1)}$

Case 2b:
$$v \in S_{z_2(y)}^{(1)}$$
 or $v \in S_{z_2(y)}^{(2)}$

- Add all teal edges between $z_1(x)$ and $S_{z_2(y)}^{(1)} \cup S_{z_2(y)}^{(2)}$
- If $(z_1(x), v)$ is a red edge of z_1 we are in case 2a.
- Otherwise $\lambda(x, z_1(x)) \leq \lambda(z_1(x), v)$



H= all red edges \cup all purple edges \cup all blue edges \cup all teal edges

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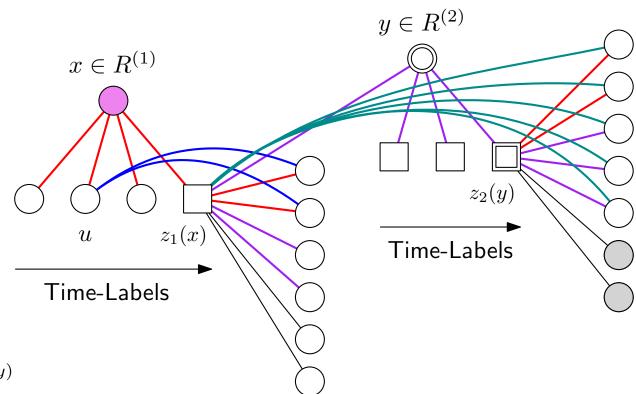
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Case 2b:
$$v \in S^{(1)}_{z_2(y)}$$
 or $v \in S^{(2)}_{z_2(y)}$

• Add all teal edges between $z_1(x)$ and $S_{z_2(y)}^{(1)} \cup S_{z_2(y)}^{(2)}$

Case 3:
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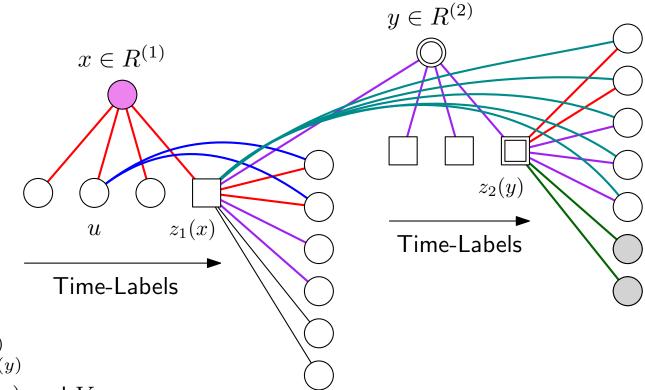
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Case 2b:
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∪ all green edges

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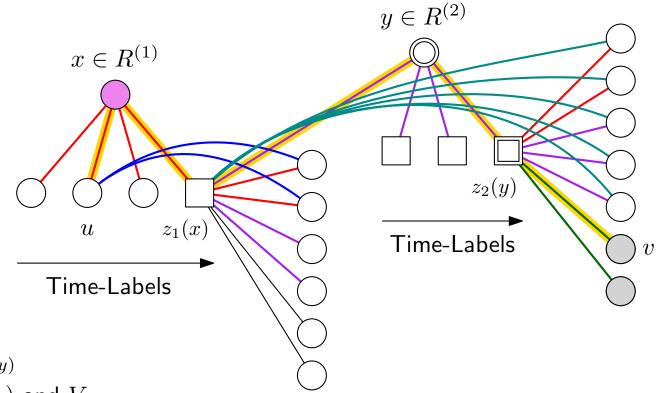
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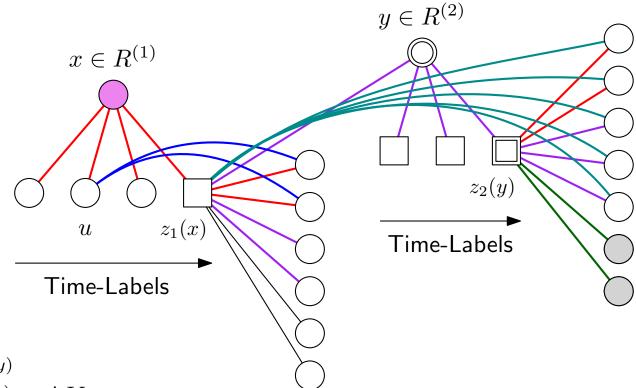
 $\bullet \ \, \text{Add all blue edges between} \\ u \ \, \text{and} \ \, S_{z_1(x)}^{(1)}$

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Size?

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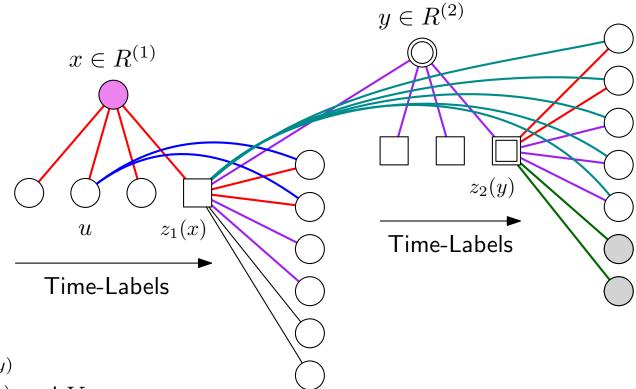
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Size?

$$H=$$
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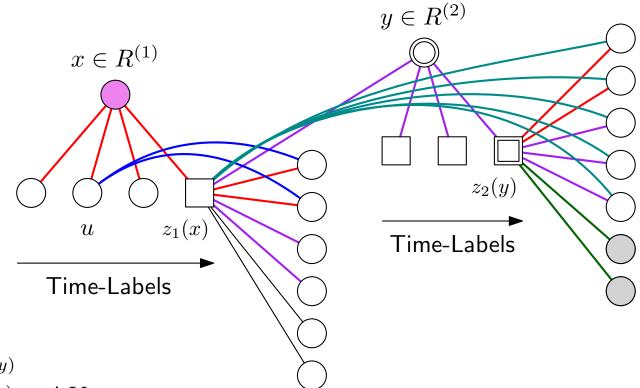
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∪ all green edges

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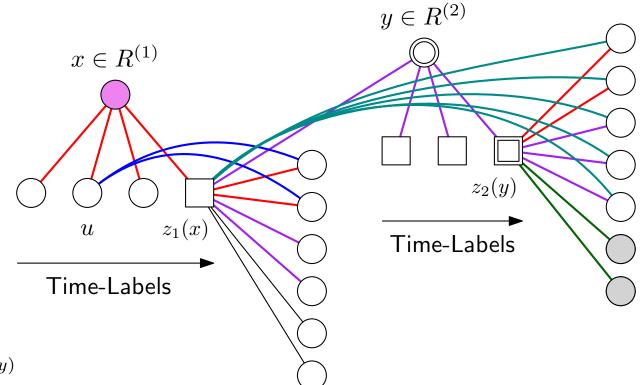
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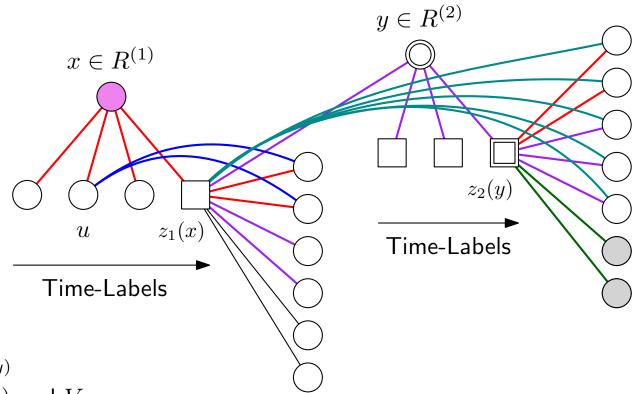
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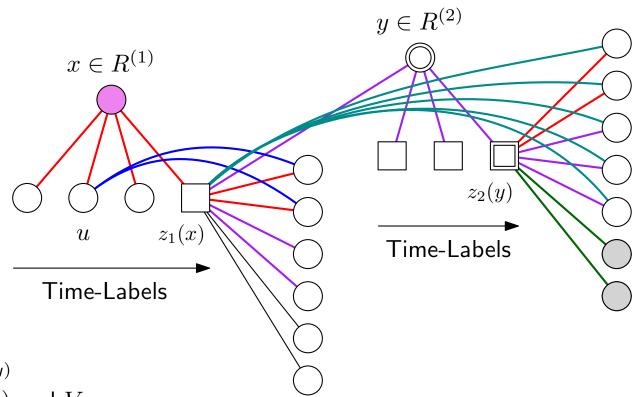
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$$O(n\sqrt[3]{n}) \quad + \quad O(n\sqrt[3]{n}) \quad + \quad n \cdot O(\sqrt[3]{n}) \quad + \quad \widetilde{O}(n^{2/3}) \cdot O(n^{2/3}) \, + \quad |R^{(2)}| \cdot O(n)$$

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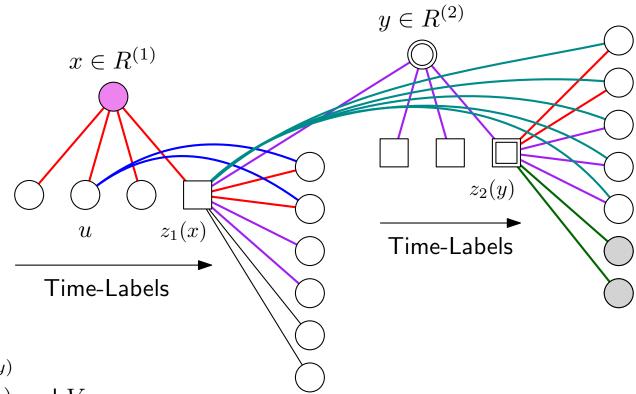
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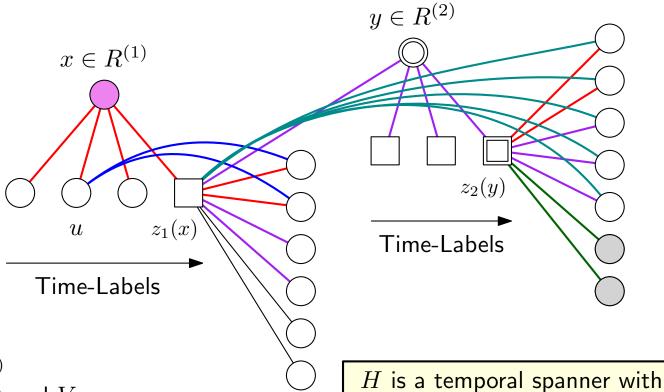
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stretch 5 and size $\widetilde{O}(n^{4/3})$

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Our Single-Source Temporal Spanner (for general graphs)

For a given source s. we will build a **single-source** temporal spanner with an additional guarantee:

- Let dist $^{\leq \tau}(s,v)$ be the length of the shortest temporal path from s to v with arrival time $\leq \tau$.
- ullet For every arrival time au and every vertex v

$$\mathsf{dist}_{H}^{\leqslant \tau}(s, v) \le \alpha \cdot \mathsf{dist}_{G}^{\leqslant \tau}(s, v) \qquad \forall v$$

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General result:

Stretch:
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 Size: $O\left(\frac{n\log^4 n}{\log(1+\epsilon)}\right)$

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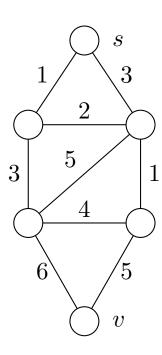
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To get stretch
$$(1+\delta)$$
 choose $\varepsilon=\delta/3$

$$(1+\delta/3)^2 \le (1+\delta)$$
 for $\delta \le 3$

Consider a fixed source s:

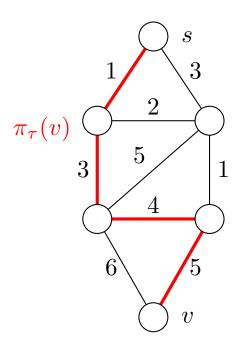
A au-restricted temporal path from s to v is a temporal path from s to v with arrival time at most au



Consider a fixed source s:

A $\tau\text{-restricted}$ temporal path from s to v is a temporal path from s to v with arrival time at most τ

Let $\pi_{\tau}(v)$ be a **shortest** τ -restricted temporal path from s to v in G



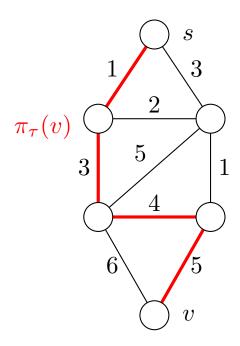
$$\mathsf{dist}_G^{\leqslant 5}(s,v) = 4$$

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Can be found in polynomial-time Wu et al. [VLDB 2014]



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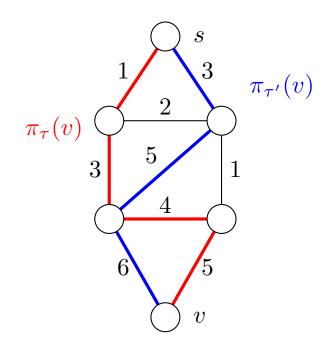
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Observation: If $\tau < \tau'$ then $|\pi_{\tau}(v)| \geq |\pi_{\tau'}(v)|$



$$\operatorname{dist}_G^{\leqslant 5}(s,v) = 4 \quad > \quad \operatorname{dist}_G^{\leqslant 6}(s,v) = 3$$

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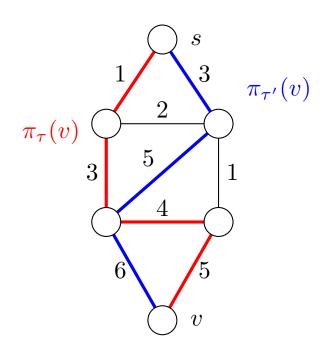
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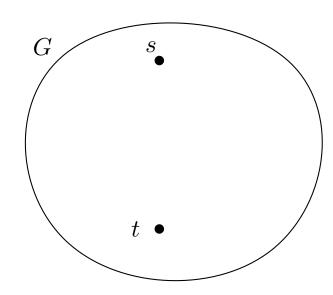
For each $v \in V$ we build a set Π_v of paths from s to v such that, for every τ there is some path $\pi \in \Pi_v$ that satisfies:

$$|\pi| \le (1+\epsilon) \cdot \mathsf{dist}_G^{\leqslant \tau}(s,v)$$

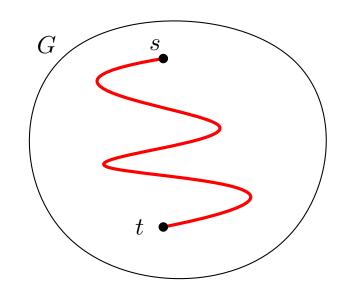


$$\operatorname{dist}_G^{\leqslant 5}(s,v) = 4 \quad > \quad \operatorname{dist}_G^{\leqslant 6}(s,v) = 3$$

$$\begin{split} D &= +\infty \\ \text{For } \tau &= 1, 2, \dots, L : \\ \text{If } D &> (1+\varepsilon) \cdot \mathsf{dist}_G^{\leq \tau}(s,v) \text{:} \\ \Pi_v &\leftarrow \Pi_v \cup \{\pi_\tau(v)\} \\ D &= |\pi_\tau(v)| \end{split}$$

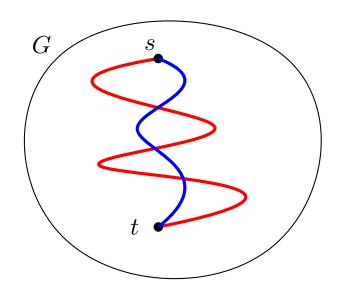


$$D=+\infty$$
 For $au=1,2,\ldots,L$: If $D>(1+arepsilon)\cdot {\sf dist}_G^{\leq au}(s,v)$: $\Pi_v\leftarrow \Pi_v\cup\{\pi_{ au}(v)\}$ $D=|\pi_{ au}(v)|$



After the first path is added to Π_v , $D \leq n$

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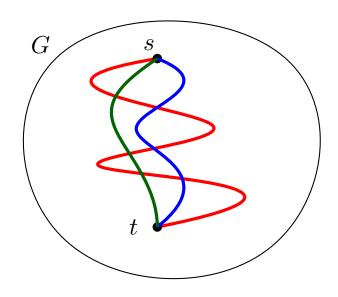


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Each subsequent path added decreases D by a factor of at least $(1+\varepsilon)$

$$D = +\infty$$
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$$\Pi_v \leftarrow \Pi_v \cup \{\pi_\tau(v)\}$$

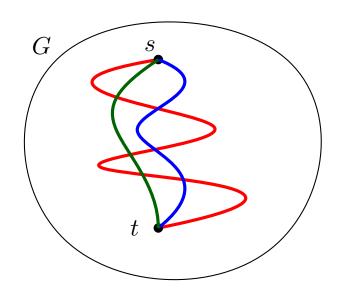
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 For $au=1,2,\ldots,L$: If $D>(1+arepsilon)\cdot {\sf dist}_G^{\leq au}(s,v)$: $\Pi_v\leftarrow \Pi_v\cup\{\pi_ au(v)\}$ $D=|\pi_ au(v)|$



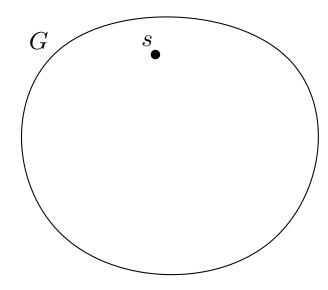
After the first path is added to Π_v , $D \leq n$

Each subsequent path added decreases D by a factor of at least $(1+\varepsilon)$

$$\implies |\Pi_v| = O\left(\frac{\log n}{\log(1+\epsilon)}\right)$$

A path is **long** if it has length at least \sqrt{n}

A vertex x hits a long path π if it is one of the last \sqrt{n} vertices of π

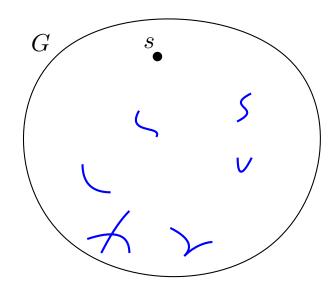


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The spanner H contains:

 \bullet The last \sqrt{n} edges of each path in $\bigcup_{v \in V} \Pi_v$

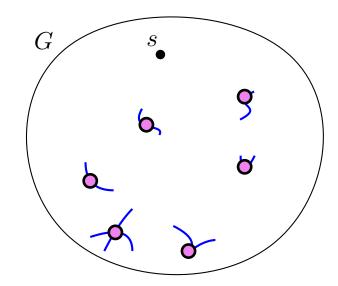


A path is **long** if it has length at least \sqrt{n}

A vertex x hits a long path π if it is one of the last \sqrt{n} vertices of π Choose a set R of $\widetilde{O}(\sqrt{n})$ vertices that hits all long paths in $\cup_v \Pi_v$

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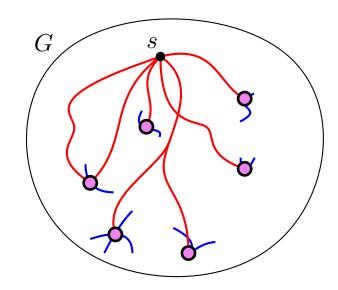


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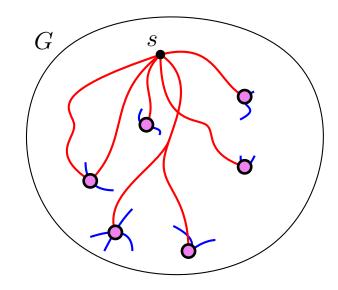
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Size

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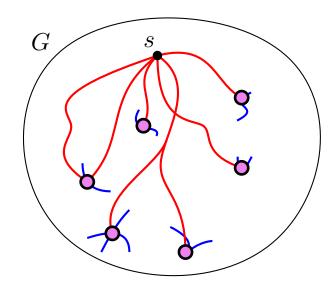
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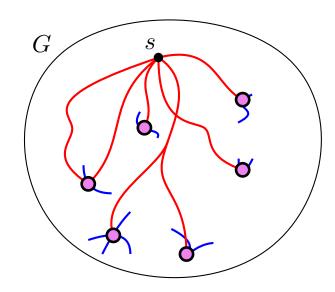
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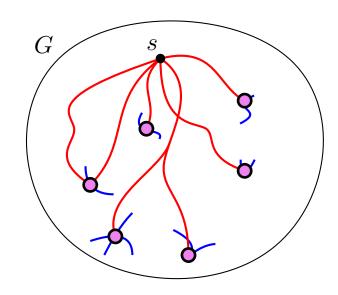
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Stretch factor?

arrival time $\leq \lambda(e)$



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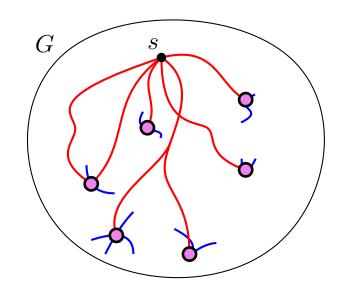
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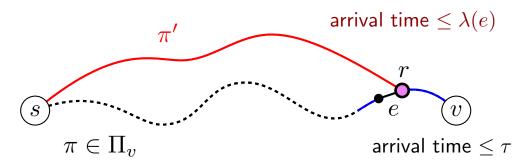
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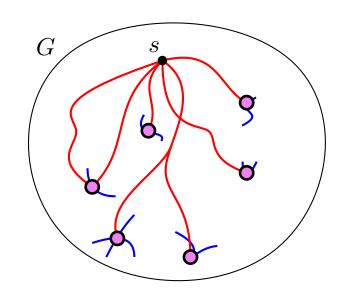
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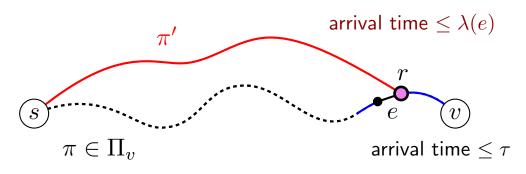
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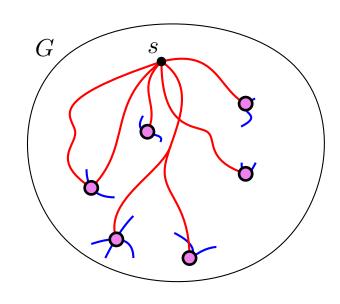
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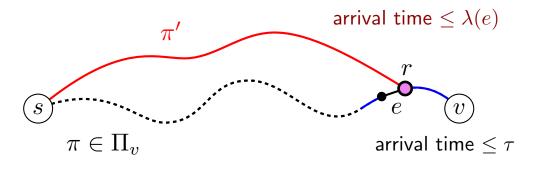
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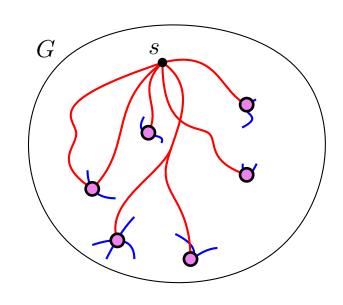
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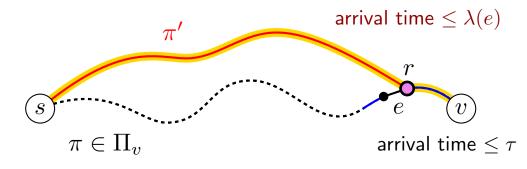
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arrival time
$$\leq \lambda(e)$$

$$|\pi'| \leq (1+\varepsilon) \cdot \operatorname{dist}_{G}^{\leq \lambda(e)}(s,r) \leq (1+\varepsilon) \cdot |\pi[s:r]|$$

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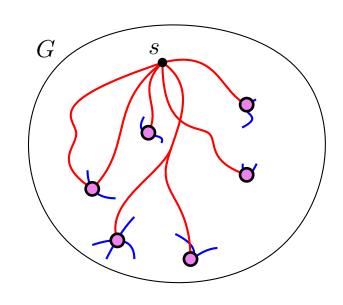
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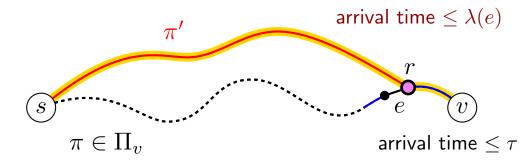
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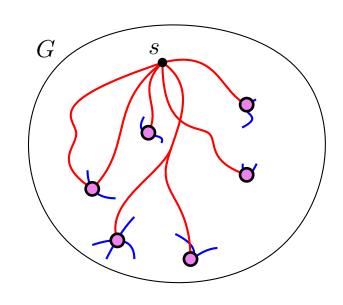
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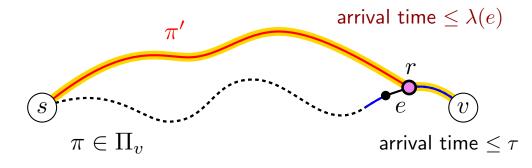
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$$\begin{aligned} & |\pi'| \leq (1+\varepsilon) \cdot \mathsf{dist}_G^{\leq \lambda(e)}(s,r) \leq (1+\varepsilon) \cdot |\pi[s:r]| \\ & |\pi'| \leq (1+\varepsilon) \cdot \mathsf{dist}_G^{\leq \lambda(e)}(s,r) \leq (1+\varepsilon) \cdot |\pi[s:r]| \\ & |\pi[s:r]| + |\pi[r:v]| \\ & \leq (1+\varepsilon)|\pi| \\ & |\pi[s:r]| + |\pi[r:v]| \\ & \leq (1+\varepsilon)|\pi| \end{aligned}$$

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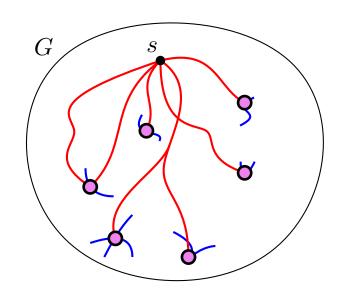
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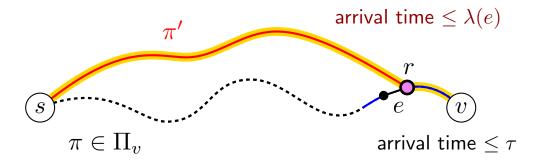
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Stretch factor?



H is a single-source temporal spanner with stretch $(1+\varepsilon)^2$ and size $\widetilde{O}(n^{3/2})$

Better Size-Stretch trade-offs

Temporal 3-Spanner on Cliques

 $\widetilde{O}(n)$

VS.

$$\Omega(n^{1+\varepsilon})$$
 for some $\varepsilon>0$

Better Size-Stretch trade-offs

Temporal 3-Spanner on Cliques



Beyond Temporal Cliques

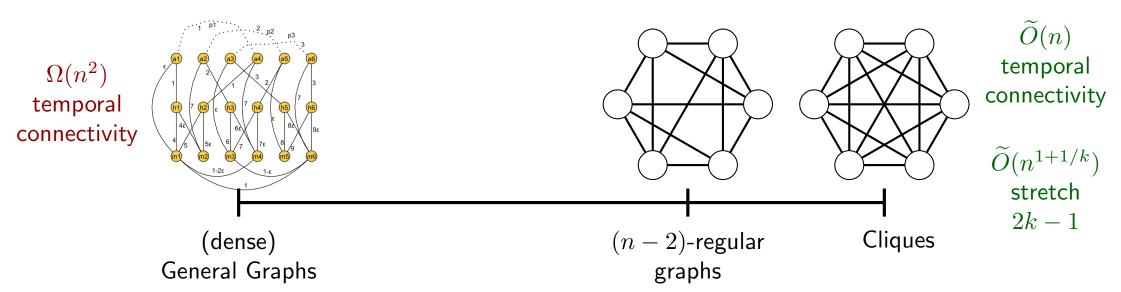


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Beyond Temporal Cliques

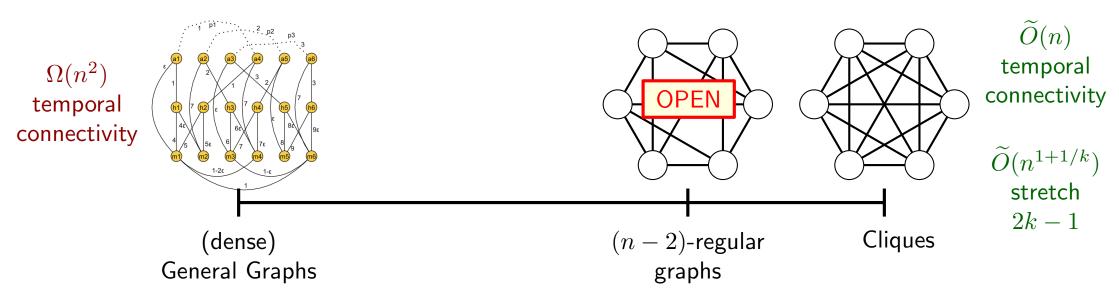


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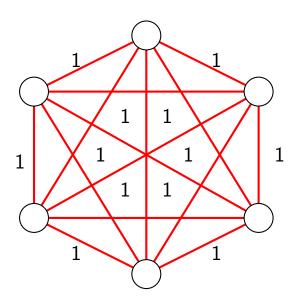


Variants and Extensions

Strict Paths

A **temporal path** from u to v is a path from u to v in which the traversed edges have non-decreasing time-labels

increasing

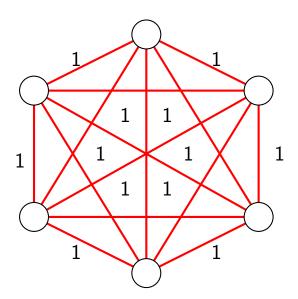


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Trivial Lower-bound of $\Omega(n^2)$ on cliques



Strict Paths

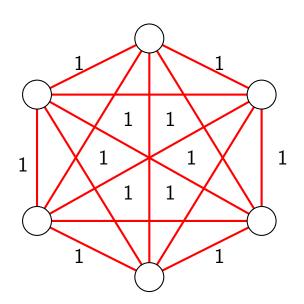
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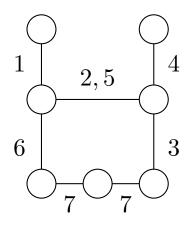
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Multiple Time-Labels

Edges can have more than one time label and a path can use **any** of them





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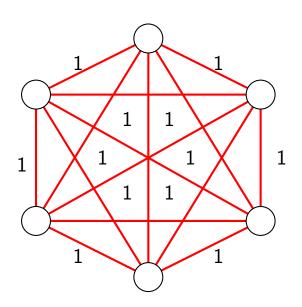
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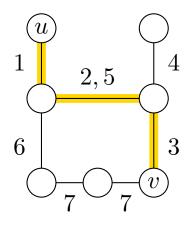
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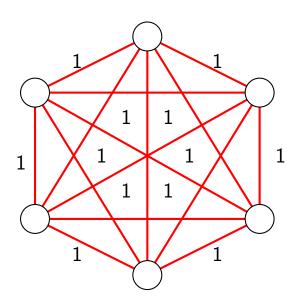
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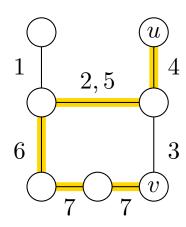
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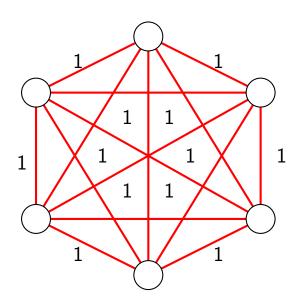
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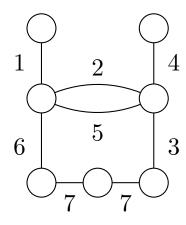
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Can be simulated with parallel edges





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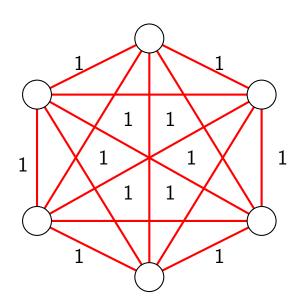
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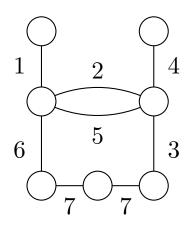
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The results in this talk also hold for temporal graphs with multiple time-labels



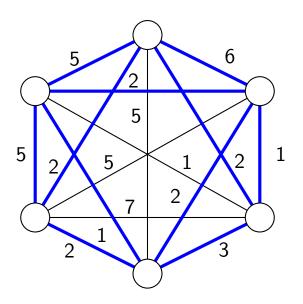


Edge Failures

A temporal f-edge fault-tolerant spanner with stretch α of G is a subgraph H such that, for every set $F \subseteq E(G)$ of at most f edges:

$$\mathsf{dist}_{H-F}^{\leqslant \tau}(u,v) \leq \alpha \cdot \mathsf{dist}_{G-F}^{\leqslant \tau}(u,v) \qquad \forall u,v$$

H remains a temporal spanner with stretch α even when up to f edges fail.

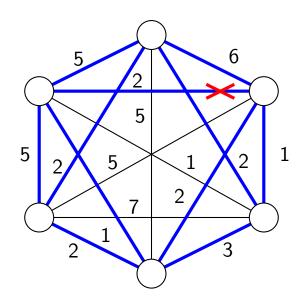


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	1-EFT clique single-pair single-source all-pairs			1-EFT single-pair single-source		2-EFT clique single-pair single-source		2-EFT single-pair	3-EFT clique single-pair
temporal spanner	+	O(n)		O(n)	$\Omega(n^2)$	O(n)	$\Omega(n^2)$	$\Omega(n^2)$	→
$\begin{array}{c} \text{temporal} \\ (1+\varepsilon)\text{-spanner} \end{array}$	A			$O\left(\frac{n\log^4 n}{\log(1+\varepsilon)}\right)$	V	$O\left(\frac{n\log^4 n}{\log(1+\varepsilon)}\right)$	V	V	†
temporal 1-spanner	O(n)	$\Omega(n^2)$	-	$\Omega(n^2)$	\	$\Omega(n^2)$	•	V	•

= sparse (almost linear)

= dense (quadratic)

[ALGOSENSORS 2022]

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temporal spanner	+	O(n)	OPEN	O(n)	$\Omega(n^2)$	O(n)	$\Omega(n^2)$	$\Omega(n^2)$ =	→
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temporal 1-spanner	O(n)	$\Omega(n^2)$ -	→	$\Omega(n^2)$	+	$\Omega(n^2)$	•	•	+

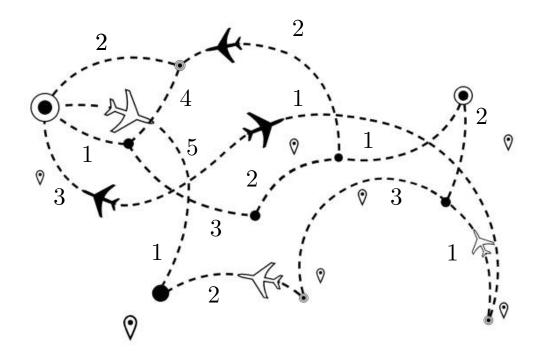
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[ALGOSENSORS 2022]

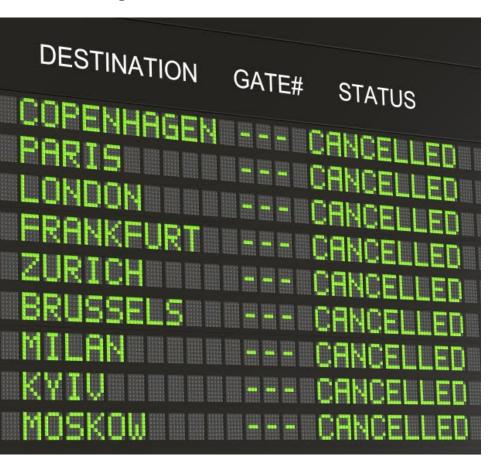
Blackout Failures

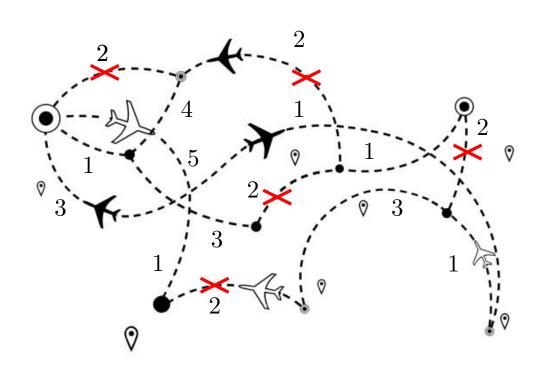
All edges with the same time-label fail simultaneously



Blackout Failures

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Blackout Failures

All edges with the same time-label fail simultaneously

	t	1-blackout emporal clique		1-blackout	2-blackout t. clique	2-blackout	3-blackout t. clique
	single pair	single source	all pairs	single pair	single pair	single pair	single pair
Reachability	↑	$\Omega(rac{n^2}{\log^2 n})$	$\Omega(n^2)$	O(n)	*	$\Omega(rac{n^2}{\log^2 n})$	
$(1+\varepsilon)$ -apx distances	↑	\	\	$O(rac{n\log^4 n}{\log(1+arepsilon)})$	†	\	\
exact distances	O(n)	$\Omega(n^2)$	\	$\Omega(rac{n^2}{\log^2 n})$	-	\	\

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[ALGOSENSORS 2022]

Thank you!

