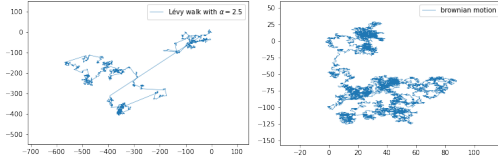


# Search via Parallel Lévy Walks on $\mathbb{Z}^2$

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## Lévy walk



**Lévy walk (informal):**

A Lévy walk is a random walk whose step-length density distribution is proportional to a power-law, namely, for each  $d \in \mathbb{R}^+$ ,  $f(d) \sim 1/d^\alpha$ , for some  $\alpha > 1$

**Note:** the speed of the walk is constant

## Movement model

Lévy walks are used to model movement patterns [Reynolds, Biology Open 2018]

Examples:

- T cells within the brain
- swarming bacteria
- midge swarms
- termite broods
- schools of fish
- Australian desert ants
- a variety of molluscs



Widely employed in the foraging theory

## Lévy walk optimality

[Viswanathan et al., Nature 1999]: the Lévy walk with  $\alpha = 2$  is optimal for foraging in  $\mathbb{R}^n$

[Guinard et Korman, Sciences Advances 2021]: the Lévy walk with  $\alpha = 2$  is optimal for finding targets of all shapes in  $\mathbb{T}^2$

## Lévy flight foraging hypothesis

Since Lévy flights/walks optimize random searches, biological organisms must have therefore evolved to exploit Lévy flights/walks [Viswanathan et al., Physics of Life Reviews 2008]

Seems there is a special exponent  $\alpha = 2$

We test this hypothesis by focusing on a distributed search problem:

- the ANTS (Ants Nearby Treasure Search) problem



Full version of the work available at: <https://arxiv.org/abs/2004.01562>



## The ANTS problem

Introduced by [Feinerman et al., PODC 2012]:

Setting:

- $k$  (mutually) independent agents start moving on  $\mathbb{Z}^2$  from the origin
- time is synchronous and marked by a global clock
- one special node  $\mathcal{P} \in \mathbb{Z}^2$ , the target, placed by an adversary at unknown (Manhattan) distance  $\ell$  from the origin

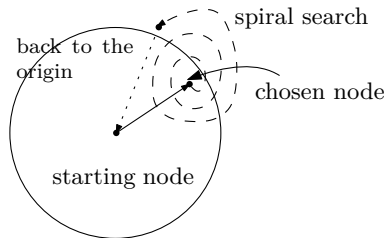
**Task:** find the target as fast as possible



**Lower bound:** for any  $k \geq 1$ , and for any search algorithm  $\mathcal{A}$ , the hitting time to find  $\mathcal{P}$  is  $\Omega(\ell^2/k + \ell)$  both with constant probability and in expectation

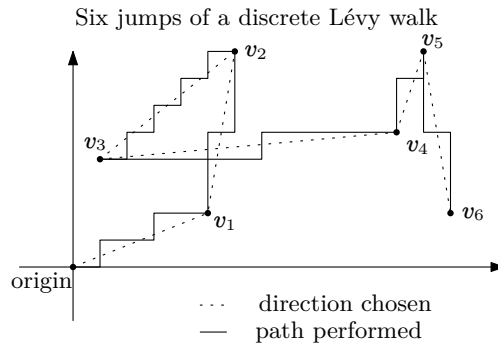
## Proposed solution

- no communication, no advice
- achieves expected hitting time  $\mathcal{O}((\ell^2/k + \ell) \log^{1+\epsilon} \ell)$
- not natural (simple, lightweight)



- fix a ball of some radius  $\ell_i$
- agents go to random nodes in the ball
- agents perform a spiral search of length  $d_i$  around the chosen nodes
- agents return to the source node
- increase  $\ell_i$  and  $d_i$ , and repeat (i)-(v)

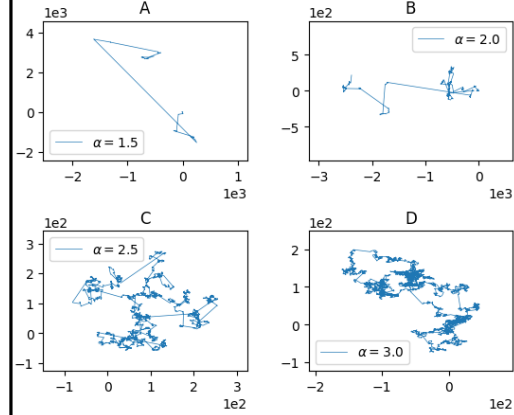
## Discrete Lévy walk



**Lévy walk:**  $\alpha > 1$ , the agent

- chooses a distance  $d \in \mathbb{N}$  as follows:  $d = 0$  w.p.  $1/2$ , and  $d \geq 1$  w.p.  $c_\alpha/d^\alpha$
- chooses a destination u.a.r. among those at distance  $d$
- walks along an approximating path for  $d$  steps, one edge at a time, crossing  $d$  nodes
- repeats the procedure

## $\alpha$ -Behavior of Lévy walks



- $1 < \alpha \leq 2$  ballistic diffusion (fig.s A and B)
- $2 < \alpha < 3$  super diffusion (fig. C)
- $3 \leq \alpha$  normal diffusion (fig. D)

## Input domain partition

Recall:  $\ell$  target distance,  $k$  number of agents

Three different possible settings:

- close target:  $\ell \leq k/\text{polylog}(k)$
- far target:  $k/\text{polylog}(k) \leq \ell \leq \exp(k^{\Theta(1)})$
- very far target:  $\exp(k^{\Theta(1)}) \leq \ell$

**Recall:** an event  $E$  depending on a parameter  $\ell$  holds with high probability in  $\ell$  if  $\mathbb{P}(E) \geq 1 - \ell^{-\Theta(1)}$

## Hitting time

**Close target**

ballistic walks: any  $\alpha$  in  $(1, 2]$

hitting time  $\mathcal{O}(\ell \text{polylog}(\ell))$  w.h.p.

**Very far target**

diffusive walks: any  $\alpha \geq 3$  (brownian-like)

the whalks eventually find the target w.p. 1

**Far target**

best strategy: ... it depends!

$\alpha^* = 3 - \log k / \log \ell$ : super-diffusive range

The following holds w.h.p. in  $\ell$

- if  $\alpha = \alpha^* + \mathcal{O}(\log \log \ell / \log \ell)$ , the hitting time is  $\mathcal{O}((\ell^2/k + \ell) \text{polylog}(\ell))$
- if  $\alpha = \alpha^* + \epsilon$ , the hitting time is  $\Omega((\ell^2/k + \ell) \ell^c)$ , for some constant  $c > 0$
- if  $\alpha = \alpha^* - \epsilon$  the hitting time is infinite

## Search algorithm

How can we find  $\alpha^*$ ? We don't have to!

**Algorithm:** each agent  $u$  samples u.a.r. a real number  $\alpha_u \in (2, 3)$ . Then, it performs a discrete Lévy walk with exponent  $\alpha_u$

If  $\ell \leq \exp(k^{\Theta(1)})$ , the hitting time is  $\mathcal{O}((\ell^2/k + \ell) \text{polylog}(\ell))$  w.h.p.

Natural, time-homogeneous, almost-optimal solution for the ANTS problem