# Joins $\rightarrow$ Aggregates $\rightarrow$ Optimization

https://fdbresearch.github.io



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#### Acknowledgements

Some work reported in this course has been done in the context of the FDB project, LogicBlox, and RelationalAI by

- Zavodný, Schleich, Kara, Nikolic, Zhang, Ciucanu, and Olteanu (Oxford)
- Abo Khamis and Ngo (RelationalAI), Nguyen (U. Michigan)

Some of the following slides are derived from presentations by

- Abo Khamis (optimization diagrams)
- Kara (covers, IVM<sup>e</sup>, and many graphics)
- Ngo (functional aggregate queries)
- Schleich (performance and quizzes)

Lastly, Kara and Schleich proofread the slides.

I would like to thank them for their support!

#### Goal of This Course

Introduction to a principled approach to in-database computation

This course starts where mainstream databases courses finish.

Part 1: Joins

#### Part 2: Aggregates

- ▶ Important functionality of DB query languages and essential for applications
- Natural generalization of aggregates over joins can express problems across Computer Science in, e.g., DB, logic, probabilistic graphical models [ANR16]
- ► Algorithm with lowest known computational complexity [BKOZ13,ANR16]
- Aggregates under data updates

[NO18,KNNOZ19]

■ Part 3: Optimization

# Outline of Part 2: Aggregates



FAQs: Functional Aggregate Queries

FAQ Computation

Counting Triangles under Updates

References

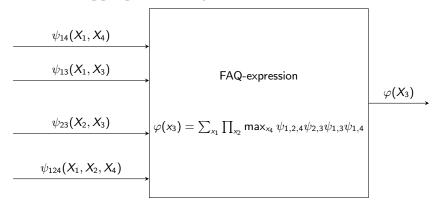
Quiz

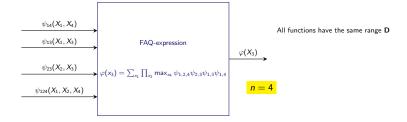
We use the following notation  $(i \in [n] = \{1, ..., n\})$ :

- $\blacksquare$   $X_i$  are variables,
- $\blacksquare$   $x_i$  are values in discrete domain  $Dom(X_i)$
- $\mathbf{x} = (x_1, \dots, x_n) \in \mathsf{Dom}(X_1) \times \dots \times \mathsf{Dom}(X_n)$
- For any  $S \subseteq [n]$ ,

$$\begin{array}{rcl} \mathbf{x}_{S} & = & (x_{i})_{i \in S} \in \prod_{i \in S} \mathsf{Dom}(X_{i}) \\ \\ \text{e.g. } \mathbf{x}_{\{2,5,8\}} & = & (x_{2},x_{5},x_{8}) \in \mathsf{Dom}(X_{2}) \times \mathsf{Dom}(X_{5}) \times \mathsf{Dom}(X_{8}) \end{array}$$

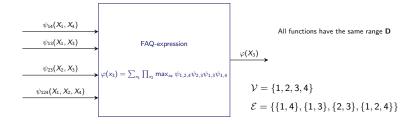
### Functional Aggregate Query: The Problem





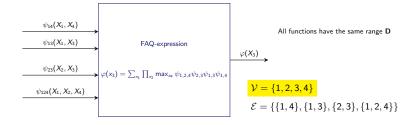
- $\blacksquare$  n variables  $X_1, \ldots, X_n$
- lacksquare a multi-hypergraph  $\mathcal{H}=(\mathcal{V},\mathcal{E})$ 
  - **Each** vertex is a variable (notation overload: V = [n])
  - ▶ To each hyperedge  $S \in \mathcal{E}$  there corresponds a factor  $\psi_S$

$$\psi_S:\prod_{i\in S}\mathsf{Dom}(X_i)\to \ \mathbf{D}$$



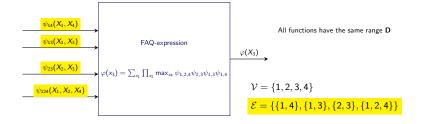
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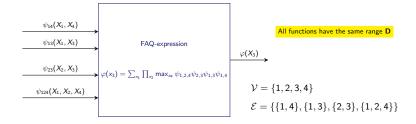
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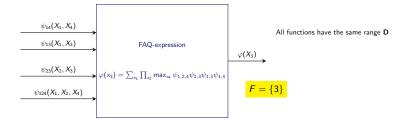
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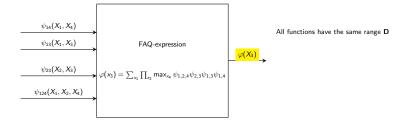
$$\psi_{\mathcal{S}}:\prod_{i\in\mathcal{S}}\mathsf{Dom}(X_i) orac{\mathbf{D}}{\uparrow}$$
 $\mathbf{R}_+,\ \{\mathsf{true},\mathsf{false}\},\ \{0,1\},\ 2^{\mathcal{U}},\ \mathsf{etc.}$ 



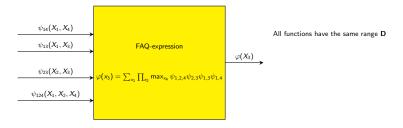
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■ a set  $F \subseteq \mathcal{V}$  of free variables (wlog,  $F = [f] = \{1, \dots, f\}$ )

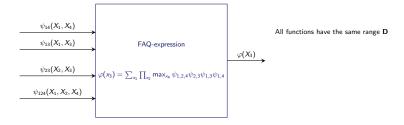


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- $\blacksquare \varphi$  defined by the *FAQ-expression*

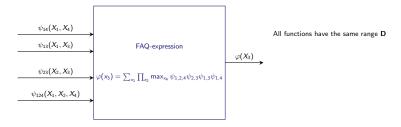
$$\varphi(\mathbf{x}_{[f]}) = \bigoplus_{x_{f+1} \in \mathsf{Dom}(X_{f+1})}^{(f+1)} \cdots \bigoplus_{x_{n-1} \in \mathsf{Dom}(X_{n-1})}^{(n-1)} \bigoplus_{x_n \in \mathsf{Dom}(X_n)}^{(n)} \bigotimes_{S \in \mathcal{E}} \psi_S(\mathbf{x}_S)$$



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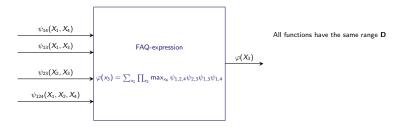
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  - ▶ Either  $(D, \bigoplus^{(i)}, \bigotimes)$  is a commutative semiring



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- For each  $\bigoplus^{(i)}$ 
  - ightharpoonup Either  $\left(\mathbf{D}, \bigoplus^{(i)}, \bigotimes\right)$  is a commutative semiring
  - ightharpoonup Or  $\bigoplus^{(i)} = \bigotimes$

### Commutative Semirings

- $(\mathbf{D},\oplus,\otimes)$  is a commutative semiring when
  - **■**  $(\mathbf{D}, \oplus)$  is a commutative monoid with identity element  $\mathbf{0}$ :
    - $(a \oplus b) \oplus c = a \oplus (b \oplus c)$
    - $ightharpoonup 0 \oplus a = a \oplus 0 = a$
    - ightharpoonup  $a \oplus b = b \oplus a$
  - **(D**, $\otimes$ ) is a commutative monoid with identity element 1:
    - $(a \otimes b) \otimes c = a \otimes (b \otimes c)$
    - $\blacktriangleright \ \mathbf{1} \otimes a = a \otimes \mathbf{1} = a$
    - ightharpoonup  $a \oplus b = b \oplus a$
  - Multiplication distributes over addition:
  - Multiplication by **0** annihilates **D**:

#### Commutative Semirings

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    - ightharpoonup  $a \oplus b = b \oplus a$
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  - Multiplication by 0 annihilates D:
    - $ightharpoonup 0 \otimes a = a \otimes 0 = 0$

Common examples (there are many more!)

Boolean ({true, false}, 
$$\vee$$
,  $\wedge$ ) sum-product ( $\mathbb{R}$ ,  $+$ ,  $\times$ ) max-product ( $\mathbb{R}_+$ , max,  $\times$ ) set ( $2^U$ ,  $\cup$ ,  $\cap$ )

#### $SumProduct \subset FAQ$

#### Problem (SumProduct)

Given a commutative semiring  $(\mathbf{D}, \oplus, \otimes)$ , compute the function

$$\varphi(x_1,\ldots,x_f) = \bigoplus_{x_{f+1}} \bigoplus_{x_{f+2}} \cdots \bigoplus_{x_n} \bigotimes_{S \in \mathcal{E}} \psi_S(\mathbf{x}_S)$$

For  $\oplus = +$  and  $\otimes = *$ ,  $\varphi$  can be expressed in SQL as:

SELECT 
$$x_1, ..., x_f$$
, SUM( $R_1$ .val \* · · · \*  $R_n$ .val)  
FROM  $R_1$  NATURAL JOIN ...  $R_n$   
GROUP BY  $x_1, ..., x_f$ ;

where each function  $\psi_i$  over variables  $\mathbf{X}_S$  is encoded as a relation  $R_i$  over  $\mathbf{X}_S$  and an additional variable val to account for the values of  $\psi_i$ .

This formulation is equivalent to:

SumProduct

D99

Marginalize a Product Function

[AM00]

### Many examples for SumProduct

- $\blacksquare$  ({true, false},  $\lor$ ,  $\land$ )
  - Constraint satisfaction problems
  - Boolean conjunctive query evaluation
  - ► SAT
  - ▶ *k*-colorability
  - etc.
- $\blacksquare$   $(U, \cup, \cap)$ 
  - Conjunctive query evaluation
- **■** (ℝ, +, ×)
  - Permanent
  - ► DFT
  - Inference in probabilistic graphical models
  - ► #CSP
  - ► Matrix chain multiplication
  - Aggregates in DB
- **■** (**R**<sub>+</sub>, max, ×)
  - MAP queries in probabilistic graphical models

### SumProduct Example 1: Boolean Query Evaluation

#### **Boolean Conjunctive Queries:**

- Boolean query  $\Phi$  with set  $rels(\Phi)$  of relation symbols
- Each relation symbol  $R \in rels(\Phi)$  has variables vars(R)

$$\Phi = \exists X_1 \dots \exists X_n : \bigwedge_{R \in rels(\Phi)} R(vars(R))$$

#### FAQ encoding:

$$\phi = \bigvee_{\mathbf{x}} \bigwedge_{S \in \mathcal{E}} \psi_S(\mathbf{x}_S), \text{ where}$$

- ullet  $\phi$  has the hypergraph  $(\mathcal{V}, \mathcal{E})$  with
- $\mathbf{v} = \bigcup_{R \in rels(\Phi)} vars(R) \text{ and } \mathcal{E} = \{vars(R) \mid R \in rels(\Phi)\}$
- For each  $S \in \mathcal{E}$ , there is a factor  $\psi_S$  such that  $\psi_S(\mathbf{x}_S) = (\mathbf{x}_S \in R)$

### SumProduct Example 2: Matrix Chain Multiplication

Compute the product 
$$\mathbf{A} = \mathbf{A}_1 \cdots \mathbf{A}_n$$
 of  $n$  matrices

■ Each matrix  $\mathbf{A}_i$  is over field  $\mathbb{F}$  and has dimensions  $p_i \times p_{i+1}$ 

#### FAQ encoding:

- We use n+1 variables  $X_1, \ldots, X_{n+1}$  with domains  $\mathsf{Dom}(X_i) = [p_i]$
- **Each** matrix  $\mathbf{A}_i$  can be viewed as a function of two variables:

$$\psi_{i,i+1}: \mathsf{Dom}(X_i) \times \mathsf{Dom}(X_{i+1}) \to \mathbb{F}, \text{ where } \psi_{i,i+1}(x_i,x_{i+1}) = (\mathbf{A}_i)_{x_i x_{i+1}}$$

The problem is now to compute the FAQ expression

$$\phi(x_1, x_{n+1}) = \sum_{x_2 \in Dom(X_2)} \cdots \sum_{x_n \in Dom(X_n)} \prod_{i \in [n]} \psi_{i, i+1}(x_i, x_{i+1}).$$

### SumProduct Example 3: Queries in Graphical Models

- lacksquare Discrete undirected graphical model represented by a hypergraph  $(\mathcal{V},\mathcal{E})$
- $\mathcal{V} = \{X_1, \dots, X_n\}$  consists of n discrete random variables
- lacksquare There is a factor  $\psi_{\mathcal{S}}:\prod_{i\in\mathcal{S}}\mathsf{Dom}(X_i) o\mathbb{R}_+$  for each edge  $\mathcal{S}\in\mathcal{E}$

FAQ expression to compute the marginal Maximum A Posteriori estimates:

$$\phi(x_1,\ldots,x_f) = \max_{x_{f+1} \in \mathsf{Dom}(X_{f+1})} \cdots \max_{x_n \in \mathsf{Dom}(X_n)} \prod_{S \in \mathcal{E}} \psi_S(\mathbf{x}_S)$$

FAQ expression to compute the marginal distribution of variables  $X_1, \ldots, X_f$ :

$$\phi(x_1,\ldots,x_f) = \sum_{x_{f+1} \in \mathsf{Dom}(X_{f+1})} \cdots \sum_{x_n \in \mathsf{Dom}(X_n)} \prod_{S \in \mathcal{E}} \psi_S(\mathbf{x}_S)$$

For conditional distributions  $prob(\mathbf{X}_A \mid \mathbf{X}_B = \mathbf{x}_B)$ , we set  $\mathbf{X}_B$  to  $\mathbf{x}_B$ .

# Outline of Part 2: Aggregates



FAQs: Functional Aggregate Queries

#### FAQ Computation

Counting Triangles under Updates

References

Quiz

#### How to compute a SumProduct FAQ $\varphi$

- $\blacksquare$  Find a variable order for  $\varphi$
- $\blacksquare$  Compute  $\varphi$  by eliminating variables in the given order

This is a dynamic programming algorithm. Two flavours:

► FDB: Top-down with memoization (caching)

[BKOZ13]

We exemplify two variants:

- 1. Compute the factorized join and the aggregates in one pass over the factorization
- 2. Translate the factorized computation into relational queries
- InsideOut: Bottom-up with indicator projections

[ANR16]

■ The complexity is given by the width of the variable order:

Given a database of size N, an FAQ  $\varphi$ , a variable order for  $\varphi$  with width w,  $\varphi$  can be computed in time  $\mathcal{O}(N^w + |\mathsf{OUT}|)$ , where  $|\mathsf{OUT}|$  is the output size.

# Finding a Variable Order for a SumProduct FAQ $\varphi$

First attempt: Same variable order  $\Delta$  as for the join part of  $\varphi$ 

One wrinkle: What if not all variables are free?

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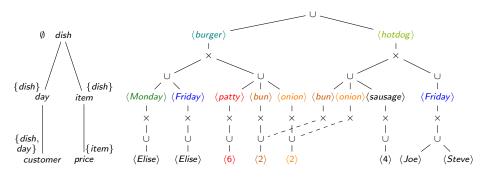
- The free variables sit above the bound variables in  $\Delta$ . [BKOZ13,OZ15]
- Equivalent constraint for hypertree decompositions: [ANR16]

Take a hypertree decomposition for the join part of  $\varphi$  such that the bags with the free variables form a connected subtree.

#### Implication on complexity:

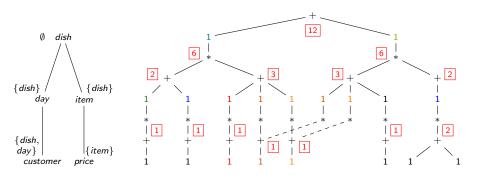
- The width for  $\varphi$  is at least the width for its join part  $\Rightarrow \varphi$  may be more expensive than its join part if it has free variables
- This new width is called the *FAQ-width* in the literature [ANR16]

# Computing COUNT over Factorized Join using FDB



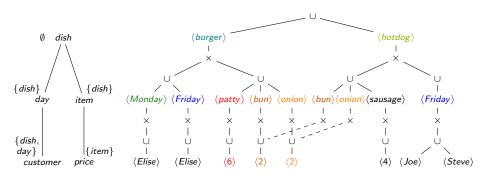
- $\varphi = \sum_{m} O(customer, day, dish) \cdot D(dish, item) \cdot I(item, price)$
- In SQL: SELECT COUNT(\*) FROM O NATURAL JOIN .. I;
- We change the semiring to  $(\mathbb{N}, +, *)$ :
  - ▶ values  $\mapsto$  1  $\cup \mapsto +$   $\times \mapsto *$

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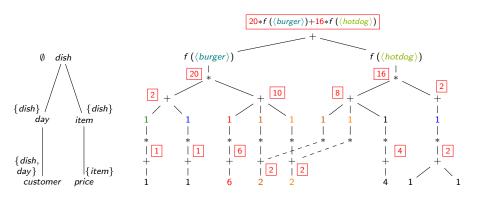
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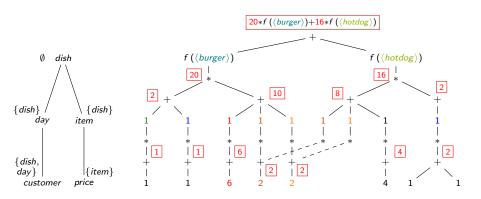
- $\varphi = \sum_{...} f(dish) \cdot price \cdot O(customer, day, dish) \cdot D(dish, item) \cdot I(item, price)$
- In SQL: SELECT SUM(f(dish) \* price) FROM O NATURAL JOIN .. I;
  - Assume there is a function f that turns dish into reals or indicator vectors.
  - ▶ All values except for dish & price  $\mapsto$  1,  $\cup \mapsto +$ ,  $\times \mapsto *$ .

# Computing SUM over Factorized Join using FDB



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# Computing SUM over Factorized Join using FDB



If f turns dish into indicator vectors:

- $\varphi(dish) = \sum_{...} price \cdot O(customer, day, dish) \cdot D(dish, item) \cdot I(item, price)$
- In SQL: SELECT dish, SUM(price) FROM O NATURAL JOIN..I GROUP BY dish;

#### To Compute or Not To Compute the Factorized Join

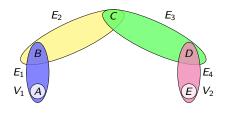
Aggregates can be computed without materializing the factorized join  $[ \hbox{OZ15,OS16,ANNOS18a+b} ]$ 

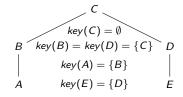
- The factorized join becomes the *trace* of the aggregate computation
- This is called factorized aggregate computation

# Example of Factorized Computation via Query Rewriting

The 4-path count query  $Q_4$  on a graph with 4 copies of the edge relation E:

$$Q_4() = \sum_{a,b,c,d,e} \underbrace{V_1(a) \cdot E_1(a,b) \cdot E_2(b,c) \cdot E_3(c,d) \cdot E_4(d,e) \cdot V_2(e)}_{J(a,b,c,d,e)}$$

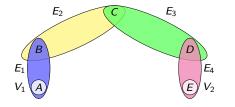


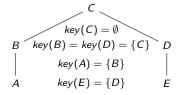


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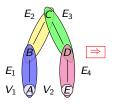


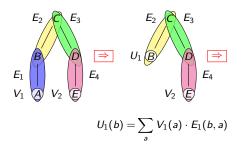
Sizes for listing/factorized representations of the result of the join J of  $Q_4$ 

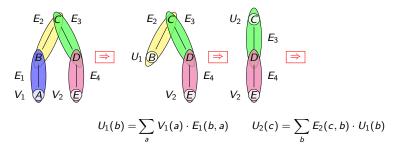
- $\rho^*(J) = 3 \Rightarrow$  listing representation has size  $O(|E|^3)$ .
- $fhtw(J) = 1 \Rightarrow$  factorization with caching has size O(|E|).

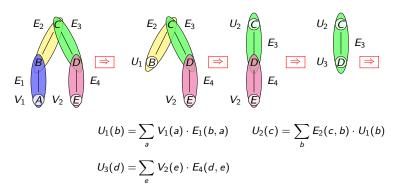
We would like to compute  $Q_4$ :

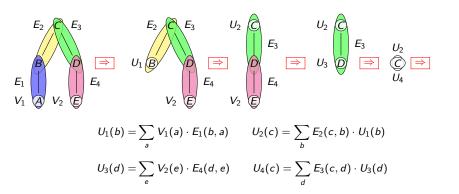
- in O(|E|) time (no free variables, so use best variable order)
- $\blacksquare$  using optimized queries that are derived from the variable order of  $Q_4$
- without materializing the factorized join J

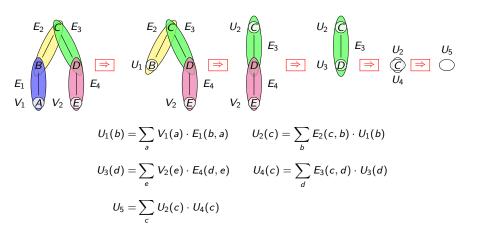


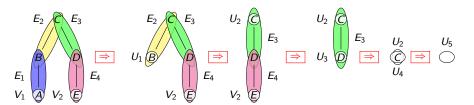








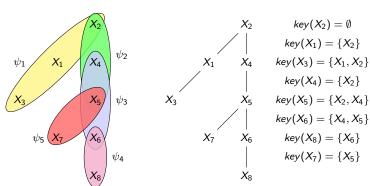




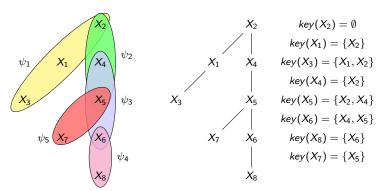
This computation strategy corresponds to the following query rewriting:

$$\begin{split} &\sum_{a,b,c,d,e} V_1(a) \cdot E_1(b,a) \cdot E_2(c,b) \cdot E_3(c,d) \cdot E_4(d,e) \cdot V_2(e) = \\ &\sum_{c} \Bigl( \sum_b E_2(c,b) \cdot \bigl( \sum_a V_1(a) \cdot E_1(b,a) \bigr) \Bigr) \cdot \Bigl( \sum_d E_3(c,d) \cdot \bigl( \sum_e E_4(d,e) \cdot V_2(e) \bigr) \Bigr) \end{split}$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_3, x_5, x_6, x_7, x_8} \psi_1(x_1, x_2, x_3) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7)$$



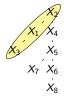
$$\varphi(x_1, x_2, x_4) = \sum_{x_3, x_5, x_6, x_7, x_8} \psi_1(x_1, x_2, x_3) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7)$$



- $\rho^*(\varphi) = 4$ ,  $s(\varphi) = 2$ ,  $fhtw(\varphi) = 1$ . The above variable order  $\Delta$  has the free variables  $x_1, x_2, x_4$  on top of the others and  $fhtw(\Delta) = 1$ .
- The query result has size: O(N) when factorized;  $O(N^2)$  when listed

$$X_{1}$$
 $X_{1}$ 
 $X_{4}$ 
 $X_{3}$ 
 $X_{5}$ 
 $X_{7}$ 
 $X_{6}$ 
 $X_{8}$ 

$$\varphi(x_1, x_2, x_4) = \sum_{\substack{x_3, x_5, x_6, x_7, x_8}} \psi_1(x_1, x_2, x_3) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7)$$



$$\begin{split} \varphi(x_1, x_2, x_4) &= \sum_{x_3, x_5, x_6, x_7, x_8} \psi_1(x_1, x_2, x_3) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7) \\ \varphi(x_1, x_2, x_4) &= \sum_{x_5, x_6, x_7, x_8} \left( \sum_{\underline{x_3}} \psi_1(x_1, x_2, x_3) \right) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7) \\ &\qquad \qquad \psi_6(x_1, x_2) \end{split}$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{3}, x_{5}, x_{6}, x_{7}, x_{8} \\ \psi_{1}(x_{1}, x_{2}, x_{3}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})}$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{6}, x_{7}, x_{8} \\ \psi_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})}$$

$$\tilde{O}(N)$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{3}, x_{5}, x_{6}, x_{7}, x_{8} \\ x_{5}, x_{6}, x_{7}, x_{8}}} \psi_{1}(x_{1}, x_{2}, x_{3}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{5}, x_{6}, x_{7}, x_{8} \\ x_{5}, x_{6}, x_{7}}} \psi_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\widetilde{O}(N)$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{5}, x_{6}, x_{7} \\ x_{5}, x_{6}, x_{7}}} \psi_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \left(\sum_{\substack{x_{8} \\ x_{8}, x_{6}, x_{7}}} \psi_{4}(x_{6}, x_{8})\right) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{3}, x_{5}, x_{6}, x_{7}, x_{8} \\ y_{6}(x_{1}, x_{2}, x_{3}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})}$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{5}, x_{7}, x_{7}, x_{8} \\ y_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})}$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{(x_1, x_2, x_4)} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_5(x_5, x_7)$$

$$\widetilde{O}(N)$$

$$\begin{split} \varphi(x_1, x_2, x_4) &= \sum_{x_3, x_5, x_6, x_7, x_8} \psi_1(x_1, x_2, x_3) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7) \\ \varphi(x_1, x_2, x_4) &= \sum_{x_5, x_6, x_7, x_8} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7) \\ \varphi(x_1, x_2, x_4) &= \sum_{x_5, x_6, x_7} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_5(x_5, x_7) \\ \varphi(x_1, x_2, x_4) &= \sum_{x_5, x_6} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \left(\sum_{x_7} \psi_5(x_5, x_7)\right) \\ \varphi(x_1, x_2, x_4) &= \sum_{x_5, x_6} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \left(\sum_{x_7} \psi_5(x_5, x_7)\right) \end{split}$$

 $\psi_8(x_5)$ 

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{x_{3}, x_{5}, x_{6}, x_{7}, x_{8}} \psi_{1}(x_{1}, x_{2}, x_{3}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{x_{5}, x_{6}, x_{7}, x_{8}} \psi_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\tilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_6, x_7, y_7} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_5(x_5, x_7)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_1, x_2} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_8(x_5)$$

$$\widetilde{O}(N)$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{3}, x_{5}, x_{6}, x_{7}, x_{8} \\ x_{5}, x_{6}, x_{7}, x_{8} \\ x_{6}, x_{7}, x_{8} \\ x_{6}, x_{7}, x_{8} \\ x_{7}, x_{8}, x_{8}, x_{8}, x_{9}, x_{9}, x_{9} \\ \varphi(x_{1}, x_{2}, x_{4}) = \sum_{\substack{x_{5}, x_{6}, x_{7}, x_{8} \\ x_{5}, x_{6}, x_{7} \\ x_{7}, x_{8} \\ x_{9}, x_$$

 $\psi_{\mathbf{Q}}(x_{\mathbf{A}}, x_{\mathbf{5}})$ 

$$\varphi(x_1, x_2, x_4) = \sum_{x_3, x_5, x_6, x_7, x_8} \psi_1(x_1, x_2, x_3) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_3, x_4, x_5, x_6} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_4(x_6, x_8) \cdot \psi_5(x_5, x_7)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_6, x_6, x_7} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_5(x_5, x_7)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_6, x_6} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_8(x_5)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_1} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_9(x_4, x_5) \cdot \psi_8(x_5)$$

$$\widetilde{O}(N)$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{x_{3}, x_{5}, x_{6}, x_{7}, x_{8}} \psi_{1}(x_{1}, x_{2}, x_{3}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{x_{3}, x_{5}, x_{6}, x_{7}, x_{8}} \psi_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\tilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_1, x_2, x_3} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_5(x_5, x_7)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_1, x_2} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_8(x_5)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_9(x_4, x_5) \cdot \psi_8(x_5)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \psi_6(x_1, x_2) \cdot \left( \sum_{x_5} \psi_2(x_2, x_4, x_5) \cdot \psi_9(x_4, x_5) \cdot \psi_8(x_5) \right)$$

 $\psi_{10}(x_2,x_4)$ 

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{x_{3}, x_{5}, x_{6}, x_{7}, x_{8}} \psi_{1}(x_{1}, x_{2}, x_{3}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\varphi(x_{1}, x_{2}, x_{4}) = \sum_{x_{3}, x_{5}, x_{6}, x_{7}, x_{8}} \psi_{6}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{4}, x_{5}) \cdot \psi_{3}(x_{4}, x_{5}, x_{6}) \cdot \psi_{4}(x_{6}, x_{8}) \cdot \psi_{5}(x_{5}, x_{7})$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_1, x_2, x_3} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_5(x_5, x_7)$$

$$\widetilde{O}(N)$$

$$\varphi(x_1, x_2, x_4) = \sum_{x_1, x_2} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_3(x_4, x_5, x_6) \cdot \psi_7(x_6) \cdot \psi_8(x_5)$$

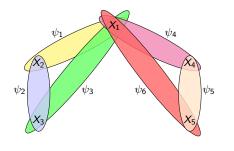
$$\widetilde{O}(N)$$

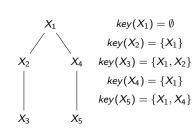
$$\varphi(x_1, x_2, x_4) = \sum_{w} \psi_6(x_1, x_2) \cdot \psi_2(x_2, x_4, x_5) \cdot \psi_9(x_4, x_5) \cdot \psi_8(x_5)$$

$$\widetilde{O}(N)$$

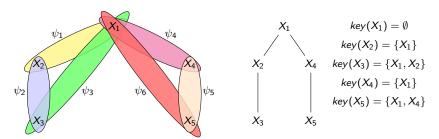
$$\varphi(x_1, x_2, x_4) = \psi_6(x_1, x_2) \cdot \psi_{10}(x_2, x_4)$$
 $\tilde{O}(N)$ 

$$\varphi(x_1) = \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1)$$

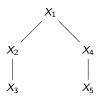




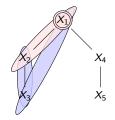
$$\varphi(x_1) = \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1)$$



- $\rho^*(\varphi) = 2.5$ ,  $s(\varphi) = 1.5$ ,  $fhtw(\varphi) = 1.5$ . The above variable order  $\Delta$  has the free variable  $x_1$  on top of the others and  $fhtw(\Delta) = 1.5$ .
- The (unary) query result has size O(N) when factorized or listed.



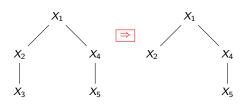
$$\varphi(x_1) = \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1)$$



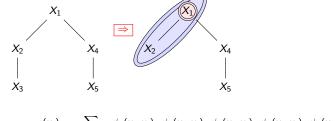
$$\begin{split} \varphi(x_1) &= \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \left( \sum_{x_3} \psi_1'(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4'(x_1) \cdot \psi_6'(x_1) \right) \cdot \psi_7(x_1, x_2) \\ & \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \end{split}$$

 $\psi_1'$  is an indicator projection of  $\psi_1$  (similarly,  $\psi_4'$  and  $\psi_6'$ ):

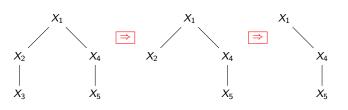
- It has the same support as  $\psi_1$ , i.e., same tuples  $(x_1, x_2)$
- $\psi_1'(x_1, x_2) = 1$  even in case  $\psi_1(x_1, x_2) \neq 1$  and  $\psi_1(x_1, x_2) \neq 0$



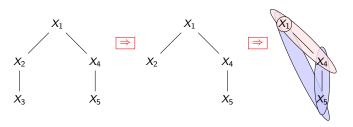
$$\begin{split} \varphi(x_1) &= \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum_{x_2, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_7(x_1, x_2) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \widetilde{O}(N^{1.5}) &= 0 \end{split}$$



The indicator projections  $\psi_4'$  and  $\psi_6'$  are redundant here, as they were already used for computing  $\phi_7$ .



$$\begin{split} \varphi(x_1) &= \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum_{x_2, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_7(x_1, x_2) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum \psi_3(x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ &\tilde{O}(N) \end{split}$$



$$\varphi(x_{1}) = \sum_{x_{2}, x_{3}, x_{4}, x_{5}} \psi_{1}(x_{1}, x_{2}) \cdot \psi_{2}(x_{2}, x_{3}) \cdot \psi_{3}(x_{3}, x_{1}) \cdot \psi_{4}(x_{1}, x_{4}) \cdot \psi_{5}(x_{4}, x_{5}) \cdot \psi_{6}(x_{5}, x_{1})$$

$$\varphi(x_{1}) = \sum_{x_{2}, x_{4}, x_{5}} \psi_{1}(x_{1}, x_{2}) \cdot \psi_{7}(x_{1}, x_{2}) \cdot \psi_{4}(x_{1}, x_{4}) \cdot \psi_{5}(x_{4}, x_{5}) \cdot \psi_{6}(x_{5}, x_{1})$$

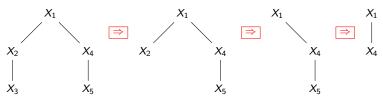
$$\tilde{O}(N^{1.5})$$

$$\varphi(x_{1}) = \sum_{x_{4}, x_{5}} \psi_{8}(x_{1}) \cdot \psi_{4}(x_{1}, x_{4}) \cdot \psi_{5}(x_{4}, x_{5}) \cdot \psi_{6}(x_{5}, x_{1})$$

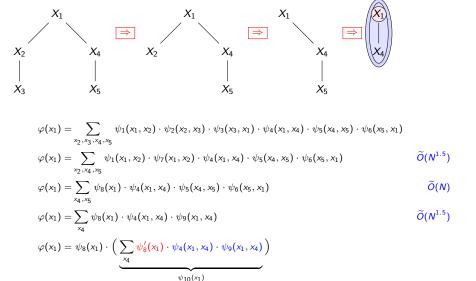
$$\tilde{O}(N)$$

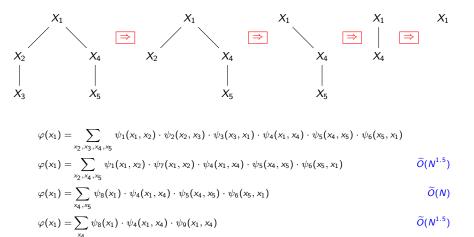
$$\varphi(x_{1}) = \sum_{x_{4}} \psi_{8}(x_{1}) \cdot \psi_{4}(x_{1}, x_{4}) \cdot \left(\sum_{x_{5}} \psi_{8}'(x_{1}) \cdot \psi_{4}'(x_{1}, x_{4}) \cdot \psi_{5}(x_{4}, x_{5}) \cdot \psi_{6}(x_{5}, x_{1})\right)$$

$$\psi_{9}(x_{1}, x_{4})$$



$$\begin{split} \varphi(x_1) &= \sum_{x_2, x_3, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_2(x_2, x_3) \cdot \psi_3(x_3, x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum_{x_2, x_4, x_5} \psi_1(x_1, x_2) \cdot \psi_7(x_1, x_2) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum_{x_4, x_5} \psi_8(x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_5(x_4, x_5) \cdot \psi_6(x_5, x_1) \\ \varphi(x_1) &= \sum_{x_4} \psi_8(x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_9(x_1, x_4) \\ \varphi(x_1) &= \sum_{x_4} \psi_8(x_1) \cdot \psi_4(x_1, x_4) \cdot \psi_9(x_1, x_4) \\ \tilde{O}(N^{1.5}) \end{split}$$





 $\varphi(x_1) = \psi_8(x_1) \cdot \psi_{10}(x_1)$ 

 $\widetilde{O}(N)$ 

#### Is Factorized Aggregate Computation Practical?

#### A glimpse at performance experiments

#### [ANNOS18b]

Retailer dataset (records)	excerpt (17M)	full (86M)	
PostgreSQL computing the join	50.63 sec	216.56 sec	
Aggregates for a linear regression model			
FDB computing join+aggregates	25.51 sec	380.31 sec	
Number of aggregates (scalar+group-by)	595+2,418	595+145k	
Aggregates for a polynomial regression model			
FDB computing join+aggregates	132.43 sec	1,819.80 sec	
Number of aggregates (scalar+group-by)	158k+742k	158k+37M	

#### In this experiment:

- FDB only used one core of a commodity machine
- For both PostgreSQL and FDB, the dataset was entirely in memory
- The aggregates represent gradients (or parts thereof) used for learning degree 1 and 2 polynomial regression models

# Outline of Part 2: Aggregates



FAQs: Functional Aggregate Queries

FAQ Computation

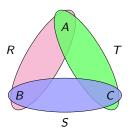
Counting Triangles under Updates

References

Quiz

#### Problem Setting

Maintain the triangle count Q under single-tuple updates to R, S, and T!



Q counts the number of tuples in the join of R, S, and T.

$$Q = \sum_{a,b,c} R(a,b) \cdot S(b,c) \cdot T(c,a)$$

#### Updates to the Triangle Count

R	<u> </u>	T
A B	ВС	C A
$\begin{vmatrix} a_1 & b_1 & 2 \\ a_2 & b_1 & 3 \end{vmatrix}$	$b_1 c_1 \mid 2$	$c_1 a_1 \mid 1$
$a_2 b_1 \mid 3$	$b_1 c_2 \mid 1$	$c_2 a_1 3$
		$c_2 a_2 3$

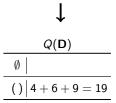
R	<i>S</i>	T
A B	ВС	C A
$\begin{vmatrix} a_1 & b_1 & 2 \\ a_2 & b_1 & 3 \end{vmatrix}$	$\begin{array}{c cccc} b_1 & c_1 & 2 \\ b_1 & c_2 & 1 \end{array}$	c <sub>1</sub> a <sub>1</sub> 1
$a_2 b_1 \mid 3$	$b_1 c_2 \mid 1$	$c_2 a_1 3$
		$c_2 a_2 3$

$R \cdot S \cdot T$				
ABC				
$a_1$ $b_1$ $c_2$	$2 \cdot 2 \cdot 1 = 4$			

R	S	<i>T</i>	$R \cdot S \cdot T$
A B	ВС	C A	A B C
$\begin{vmatrix} a_1 & b_1 & 2 \\ a_2 & b_1 & 3 \end{vmatrix}$	$\begin{array}{c cc} b_1 c_1 & 2 \\ b_1 c_2 & 1 \end{array}$	$ \begin{array}{c cccc} c_1 & a_1 & 1 \\ c_2 & a_1 & 3 \\ c_2 & a_2 & 3 \end{array} $	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

<i>S</i>	T
ВС	C A
$b_1 c_1 \mid 2$	$c_1 a_1 \begin{vmatrix} 1 \\ c_2 a_1 \end{vmatrix} 3$
$b_1 c_2 \mid 1$	$c_2 a_1 3$
	$c_2 a_2 3$

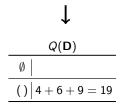
$R \cdot S \cdot T$		
A B C		
$a_1$ $b_1$ $c_2$	$\begin{vmatrix} 2 \cdot 2 \cdot 1 = 4 \\ 2 \cdot 1 \cdot 3 = 6 \\ 3 \cdot 1 \cdot 3 = 9 \end{vmatrix}$	
$a_1$ $b_1$ $c_2$	$2 \cdot 1 \cdot 3 = 6$	
$a_2$ $b_1$ $c_3$	$3 \cdot 1 \cdot 3 = 9$	



R		S		T	
A B		ВС		C A	
$a_1 b_1$ $a_2 b_1$	2	$b_1 c_1$ $b_1 c_2$	2	c <sub>1</sub> a <sub>1</sub> c <sub>2</sub> a <sub>1</sub>	1
$a_2 b_1$	3	$b_1 c_2$	1	$c_2 a_1$	3
				<i>c</i> <sub>2</sub> <i>a</i> <sub>2</sub>	3

$R \cdot S \cdot T$		
A B C		
$a_1$ $b_1$ $c_2$	$\begin{vmatrix} 2 \cdot 2 \cdot 1 = 4 \\ 2 \cdot 1 \cdot 3 = 6 \\ 3 \cdot 1 \cdot 3 = 9 \end{vmatrix}$	
$a_1$ $b_1$ $c_2$	$2 \cdot 1 \cdot 3 = 6$	
$a_2$ $b_1$ $c_3$	$3 \cdot 1 \cdot 3 = 9$	

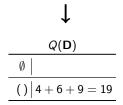




R		S		T	
A B		ВС		C A	
a <sub>1</sub> b <sub>1</sub> a <sub>2</sub> b <sub>1</sub>	2	$b_1 c_1$ $b_1 c_2$	2	c <sub>1</sub> a <sub>1</sub>	1
$a_2 b_1$	3	$b_1 c_2$	1	$c_1 a_1$ $c_2 a_1$	3
				c <sub>2</sub> a <sub>2</sub>	3

$R \cdot S \cdot T$		
A B C		
$a_1$ $b_1$ $c_2$	$\begin{vmatrix} 2 \cdot 2 \cdot 1 = 4 \\ 2 \cdot 1 \cdot 3 = 6 \\ 3 \cdot 1 \cdot 3 = 9 \end{vmatrix}$	
$a_1$ $b_1$ $c_2$	$2 \cdot 1 \cdot 3 = 6$	
a <sub>2</sub> b <sub>1</sub> c <sub>3</sub>	$3 \cdot 1 \cdot 3 = 9$	

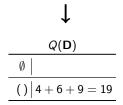




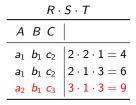
R		S		T	
A B		ВС		C A	
$a_1 b_1$ $a_2 b_1$	2	$b_1 c_1$ $b_1 c_2$	2	c <sub>1</sub> a <sub>1</sub>	1
$a_2$ $b_1$	1	$b_1 c_2$	1	$c_1 a_1$ $c_2 a_1$	3
				c <sub>2</sub> a <sub>2</sub>	3

$R \cdot S \cdot T$		
A B C		
$a_1$ $b_1$ $c_2$	$\begin{vmatrix} 2 \cdot 2 \cdot 1 = 4 \\ 2 \cdot 1 \cdot 3 = 6 \\ 3 \cdot 1 \cdot 3 = 9 \end{vmatrix}$	
$a_1$ $b_1$ $c_2$	$2 \cdot 1 \cdot 3 = 6$	
$a_2$ $b_1$ $c_3$	$3 \cdot 1 \cdot 3 = 9$	

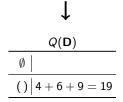




R	S	<i>T</i>
A B	ВС	C A
$\begin{vmatrix} a_1 & b_1 & 2 \\ a_2 & b_1 & 1 \end{vmatrix}$	$b_1 c_1 \mid 2$	$c_1 a_1 \begin{vmatrix} 1 \\ c_2 a_1 \end{vmatrix} 3$
$a_2 b_1 \mid 1$	$b_1 c_2 \mid 1$	$c_2 a_1 3$
		$c_2 a_2 3$



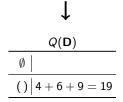




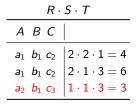
R		S		<i>T</i>	
A B		ВС		C A	
a <sub>1</sub> b <sub>1</sub> a <sub>2</sub> b <sub>1</sub>	2	$b_1 c_1$ $b_1 c_2$	2	c <sub>1</sub> a <sub>1</sub>	1
$a_2 b_1$	1	$b_1 c_2$	1	$c_1 a_1$ $c_2 a_1$	3
				$c_2 a_2$	3

$R \cdot S \cdot T$		
A B C		
$a_1$ $b_1$ $c_2$	$\begin{vmatrix} 2 \cdot 2 \cdot 1 = 4 \\ 2 \cdot 1 \cdot 3 = 6 \\ 1 \cdot 1 \cdot 3 = 3 \end{vmatrix}$	
$a_1$ $b_1$ $c_2$	$2 \cdot 1 \cdot 3 = 6$	
$a_2$ $b_1$ $c_3$	$1 \cdot 1 \cdot 3 = 3$	

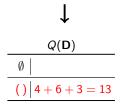




R		T
A B	ВС	C A
$\begin{vmatrix} a_1 & b_1 & 2 \\ a_2 & b_1 & 1 \end{vmatrix}$	$b_1 c_1 \mid 2$	$c_1 a_1 \begin{vmatrix} 1 \\ c_2 a_1 \end{vmatrix} 3$
$a_2 b_1 \mid 1$	$b_1 c_2   1$	$c_2 a_1 3$
		$c_2 a_2 3$







## Data Updates need the Additive Inverse

Data updates can be inserts (tuples with positive multiplicity) and deletes (tuples with negative multiplicity):

Semirings are enough if we only want inserts or no updates

Recall that FAQs use commutative semirings  $(\mathbf{D}, \oplus, \otimes)$ :

- **■** ( $\mathbf{D}$ ,  $\oplus$ ) is a commutative monoid with identity element  $\mathbf{0}$ :
  - $(a \oplus b) \oplus c = a \oplus (b \oplus c)$
  - $ightharpoonup 0 \oplus a = a \oplus 0 = a$
  - ightharpoonup  $a \oplus b = b \oplus a$
- $lackbox{(D,}\otimes)$  is a commutative monoid with identity element 1:
  - $(a \otimes b) \otimes c = a \otimes (b \otimes c)$
  - $\blacktriangleright \ \mathbf{1} \otimes \mathbf{a} = \mathbf{a} \otimes \mathbf{1} = \mathbf{a}$
  - $\triangleright$   $a \oplus b = b \oplus a$
- Multiplication distributes over addition:
  - $ightharpoonup a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c)$
- Multiplication by **0** annihilates **D**:
  - $ightharpoonup 0 \otimes a = a \otimes 0 = 0$

# From Semirings to Rings

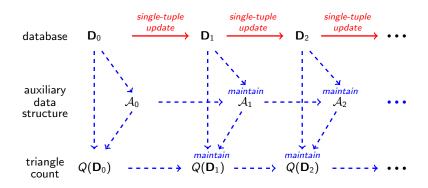
We need a commutative ring  $(\mathbf{D}, \oplus, \otimes)$  if we want to support deletes as well:

- **■**  $(\mathbf{D}, \oplus)$  is an abelian group with identity element  $\mathbf{0}$ :
  - $(a \oplus b) \oplus c = a \oplus (b \oplus c)$
  - $ightharpoonup 0 \oplus a = a \oplus 0 = a$
  - $\triangleright$   $a \oplus b = b \oplus a$
  - $ightharpoonup \exists -a \in D : a \oplus (-a) = (-a) \oplus a = 0$
- **■**  $(\mathbf{D}, \otimes)$  is a commutative monoid with identity element 1:
  - $(a \otimes b) \otimes c = a \otimes (b \otimes c)$
  - $ightharpoonup 1 \otimes a = a \otimes 1 = a$
  - ightharpoonup  $a \oplus b = b \oplus a$
- Multiplication distributes over addition:
  - $ightharpoonup a \otimes (b \oplus c) = (a \otimes b) \oplus (a \otimes c)$
- Multiplication by **0** annihilates **D**:
  - $ightharpoonup 0 \otimes a = a \otimes 0 = 0$

Examples:  $\mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}, \mathbb{R}^n$ , polynomial ring.

We used the ring  $(\mathbb{Z}, +, *)$  in our previous example.

### The Maintenance Problem



Given a current database  ${\bf D}$  and a single-tuple update, what are the time and space complexities for maintaining  $Q({\bf D})$ ?

## Much Ado about Triangles

### The Triangle Query Served as Milestone in Many Fields

- Worst-case optimal join algorithms [Algorithmica 1997, SIGMOD R. 2013]
- Parallel query evaluation [Found. & Trends DB 2018]
- Randomized approximation in static settings [FOCS 2015]
- Randomized approximation in data streams
  [SODA 2002, COCOON 2005, PODS 2006, PODS 2016, Theor. Comput. Sci. 2017]

### Investigation of Answering Queries under Updates

- Theoretical developments [PODS 2017, ICDT 2018]
- Systems developments [F. & T. DB 2012, VLDB J. 2014, SIGMOD 2017, 2018]
- Lower bounds [STOC 2015, ICM 2018]

### Naïve Maintenance

### "Compute from scratch!"

$$\sum_{a,b,c} \left[ \underbrace{R(a,b) + \delta R(a',b')}_{newR} \right] \cdot S(b,c) \cdot T(c,a)$$

$$= \sum_{a,b,c} \underbrace{newR(a,b) \cdot S(b,c) \cdot T(c,a)}$$

### Maintenance Complexity

- lacktriangle Time:  $\mathcal{O}(|\mathbf{D}|^{1.5})$  using worst-case optimal join algorithms
- Space:  $\mathcal{O}(|\mathbf{D}|)$  to store input relations

#### "Compute the difference!"

$$\sum_{a,b,c} \left[ R(a,b) + \delta R(a',b') \right] \cdot S(b,c) \cdot T(c,a)$$

$$=$$

$$\sum_{a,b,c} R(a,b) \cdot S(b,c) \cdot T(c,a)$$

$$+$$

$$\delta R(a',b') \cdot \sum_{c} S(b',c) \cdot T(c,a')$$

#### Maintenance Complexity

- Time:  $\mathcal{O}(|\mathbf{D}|)$  to intersect *C*-values from *S* and *T*
- Space:  $\mathcal{O}(|\mathbf{D}|)$  to store input relations

"Compute the difference by using pre-materialized views!"

Pre-materialize 
$$V_{ST}(b,a) = \sum_{c} S(b,c) \cdot T(c,a)!$$

$$\sum_{a,b,c} \left[ R(a,b) + \frac{\delta R(a',b')}{\delta} \right] \cdot S(b,c) \cdot T(c,a)$$

$$= \sum_{a,b,c} R(a,b) \cdot S(b,c) \cdot T(c,a)$$

$$+ \frac{\delta R(a',b') \cdot V_{ST}(b',a')}{\delta}$$

### Maintenance Complexity

- Time for updates to R:  $\mathcal{O}(1)$  to look up in  $V_{ST}$
- Time for updates to S and T:  $\mathcal{O}(|\mathbf{D}|)$  to maintain  $V_{ST}$
- Space:  $\mathcal{O}(|\mathbf{D}|^2)$  to store input relations and  $V_{ST}$

# Closing the Complexity Gap

Complexity bounds for the maintenance of the triangle count

### Known Upper Bound

Maintenance Time:  $\mathcal{O}(|\mathbf{D}|)$ 

Space:  $\mathcal{O}(|\mathbf{D}|)$ 

#### Lower Bound

Amortized maintenance time: not  $\mathcal{O}(|\mathbf{D}|^{0.5-\gamma})$  for any  $\gamma > 0$  (under reasonable complexity theoretic assumptions)

# Closing the Complexity Gap

Complexity bounds for the maintenance of the triangle count

### Known Upper Bound

Maintenance Time:  $\mathcal{O}(|\mathbf{D}|)$ 

Space:  $\mathcal{O}(|\mathbf{D}|)$ 

Can the triangle count be maintained in sublinear time?

#### Lower Bound

Amortized maintenance time: not  $\mathcal{O}(|\mathbf{D}|^{0.5-\gamma})$  for any  $\gamma > 0$  (under reasonable complexity theoretic assumptions)

# Closing the Complexity Gap

Complexity bounds for the maintenance of the triangle count

### Known Upper Bound

Maintenance Time:  $\mathcal{O}(|\mathbf{D}|)$ 

Space:  $\mathcal{O}(|\mathbf{D}|)$ 

Yes!

Can the triangle count be maintained in sublinear time?

 $IVM^{\varepsilon}$  [KNNOZ19]

Amortized maintenance time:

 $\mathcal{O}(|\mathbf{D}|^{0.5})$ 

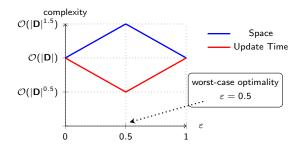
This is worst-case optimal!

#### Lower Bound

Amortized maintenance time: not  $\mathcal{O}(|\mathbf{D}|^{0.5-\gamma})$  for any  $\gamma > 0$ (under reasonable complexity theoretic assumptions)

Given  $\varepsilon \in [0,1]$  and a database **D**, IVM<sup> $\varepsilon$ </sup> maintains the triangle count with

- $\mathcal{O}(|\mathbf{D}|^{\max\{\varepsilon,1-\varepsilon\}})$  amortized update time
- $\mathbb{D}(|\mathbf{D}|^{1+\min\{\varepsilon,1-\varepsilon\}})$  space
- $\mathcal{O}(|\mathbf{D}|^{3/2})$  preprocessing time
- $\mathcal{O}(1)$  answer time.



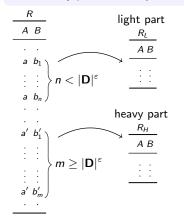
Known maintenance approaches are recovered by IVM $^{\varepsilon}$ .

### Main Ideas in IVM $^{\varepsilon}$

- Compute the difference like in classical IVM!
- Materialize views like in Factorized IVM!
- New ingredient: Use adaptive processing based on data skew!
  - $\implies$  Treat *heavy* values differently from *light* values!

#### Partition R into

- a light part
  - $R_L = \{t \in R \mid |\sigma_{A=t.A}| < |\mathbf{D}|^{\varepsilon}\},$
- $\blacksquare$  a heavy part  $R_H = R \backslash R_L!$

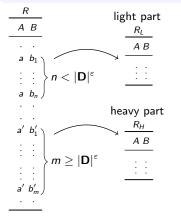


#### Partition R into

a light part

$$R_L = \{t \in R \mid |\sigma_{A=t.A}| < |\mathbf{D}|^{\varepsilon}\},$$

 $\blacksquare$  a heavy part  $R_H = R \backslash R_L!$ 



#### **Derived Bounds**

■ for all *A*-values *a*:

$$|\sigma_{A=a}R_L|<|\mathbf{D}|^{arepsilon}$$

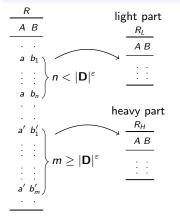
 $|\pi_A R_H| \le |\mathbf{D}|^{1-\varepsilon}$ 

#### Partition R into

a light part

$$R_L = \{t \in R \mid |\sigma_{A=t.A}| < |\mathbf{D}|^{\varepsilon}\},$$

 $\blacksquare$  a heavy part  $R_H = R \backslash R_L!$ 



#### **Derived Bounds**

for all A-values a:

$$|\sigma_{A=a}R_L|<|\mathbf{D}|^{arepsilon}$$

 $|\pi_A R_H| \leq |\mathbf{D}|^{1-\varepsilon}$ 

### Likewise, partition

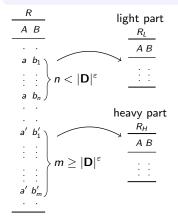
- $S = S_L \cup S_H$  based on B, and
- $T = T_L \cup T_H$  based on C!

#### Partition R into

a light part

$$R_L = \{t \in R \mid |\sigma_{A=t.A}| < |\mathbf{D}|^{\varepsilon}\},$$

 $\blacksquare$  a heavy part  $R_H = R \backslash R_L!$ 



#### Derived Bounds

- for all *A*-values *a*:  $|\sigma_{A=a}R_L| < |\mathbf{D}|^{\varepsilon}$
- $|\pi_A R_H| \leq |\mathbf{D}|^{1-\varepsilon}$

### Likewise, partition

- $S = S_L \cup S_H$  based on B, and
- $T = T_L \cup T_H$  based on C!

Q is the sum of skew-aware views  $R_U(a,b)\cdot S_V(b,c)\cdot T_W(c,a)$  with  $U,V,W\in\{L,H\}.$ 

Skew-aware View	Evaluation from left to right	Time
$\frac{\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_L(c,a)}{\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_L(c,a)}$	$\delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_L(c,a')$	$\mathcal{O}( D ^{arepsilon})$

Skew-aware View	Evaluation from left to right	Time
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_L(c,a)$	$\delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_L(c,a')$	$\mathcal{O}( D ^{arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_H(b,c) \cdot T_H(c,a)$	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_H(b',c)$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$

Skew-aware View	Evaluation from left to right	Time
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_L(c,a)$	$\delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_L(c,a')$	$\mathcal{O}( \mathbf{D} ^{arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_H(b,c) \cdot T_H(c,a)$	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_H(b',c)$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$
	$\delta R_*(a',b') \cdot \sum_{c} S_L(b',c) \cdot T_H(c,a')$	$\mathcal{O}( D ^{arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_H(c,a)$	or	
2,2,2	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_L(b',c)$	$\mathcal{O}( D ^{1-arepsilon})$

Skew-aware View	Evaluation from left to right	Time
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_L(c,a)$	$\delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_L(c,a')$	$\mathcal{O}( \mathbf{D} ^{arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_H(b,c) \cdot T_H(c,a)$	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_H(b',c)$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$
	$\delta R_*(a',b') \cdot \sum_{c} S_L(b',c) \cdot T_H(c,a')$	$\mathcal{O}( \mathbf{D} ^{\varepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_H(c,a)$	or	
<i>a,u,</i> c	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_L(b',c)$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_H(b,c) \cdot T_L(c,a)$	$\delta R_*(a',b') \cdot V_{ST}(b',a')$	$\mathcal{O}(1)$

Given an update  $\delta R_*(a',b')$ , compute the difference for each skew-aware view using different strategies:

Skew-aware View	Evaluation from left to right	Time
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_L(c,a)$	$\delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_L(c,a')$	$\mathcal{O}( \mathbf{D} ^{arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_H(b,c) \cdot T_H(c,a)$	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_H(b',c)$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$
	$\delta R_*(a',b') \cdot \sum_{c} S_L(b',c) \cdot T_H(c,a')$	$\mathcal{O}( \mathbf{D} ^{arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_L(b,c) \cdot T_H(c,a)$	or	
<i>a, u,</i> t	$\delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_L(b',c)$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$
$\sum_{a,b,c} R_*(a,b) \cdot S_H(b,c) \cdot T_L(c,a)$	$\delta R_*(a',b') \cdot V_{ST}(b',a')$	$\mathcal{O}(1)$

Overall update time:  $\mathcal{O}(|\mathbf{D}|^{\max\{\varepsilon,1-\varepsilon\}})$ 

## Materialized Auxiliary Views

$$V_{RS}(a,c) = \sum_{b} R_{H}(a,b) \cdot S_{L}(b,c)$$
$$V_{ST}(b,a) = \sum_{c} S_{H}(b,c) \cdot T_{L}(c,a)$$
$$V_{TR}(c,b) = \sum_{a} T_{H}(c,a) \cdot R_{L}(a,b)$$

lacksquare Maintenance of  $V_{RS}(a,c) = \sum\limits_b R_H(a,b) \cdot S_L(b,c)$ 

Update	Evaluation from left to right	Time
$\delta R_H(a',b')$	$\delta R_H(a',b') \cdot S_L(b',c)$	$\mathcal{O}( D ^{arepsilon})$
$\delta \mathcal{S}_L(b',c')$	$\delta S_L(b',c') \cdot R_H(a,b')$	$\mathcal{O}( D ^{1-arepsilon})$

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$\delta S_L(b',c')$	$\delta S_L(b',c') \cdot R_H(a,b')$	$\mathcal{O}( \mathbf{D} ^{1-arepsilon})$

■ Size of  $V_{RS}(a,c) = \sum_{c} R_{H}(a,b) \cdot S_{L}(b,c)$ 

$$\begin{array}{lcl} |V_{RS}(a,c)| & \leq & |R_H| \cdot \max_b \{|S_L(b,c)|\} & = & \mathcal{O}(|\mathbf{D}|^{1+\varepsilon}) \\ |V_{RS}(a,c)| & \leq & |S_L| \cdot \max_b \{|R_H(a,b)|\} & = & \mathcal{O}(|\mathbf{D}|^{1+(1-\varepsilon)}) \end{array}$$

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$\delta R_H(a',b')$	$\delta R_H(a',b') \cdot S_L(b',c)$	$\mathcal{O}( D ^{arepsilon})$
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lacksquare Overall: Update Time  $\mathcal{O}(|\mathbf{D}|^{\max\{\varepsilon,1-\varepsilon\}})$  and Space  $\mathcal{O}(|\mathbf{D}|^{1+\min\{\varepsilon,1-\varepsilon\}})$ 

## Rebalancing Partitions

#### Full details available in the paper

[KNNOZ19]

- Updates can change the frequencies of values and the heavy/light threshold!
- This may require rebalancing of partitions:
  - ⇒ Minor rebalancing: Transfer tuples from one to the other part of the same relation!
  - ⇒ Major rebalancing: Recompute partitions and views from scratch!
- Both forms of rebalancing require superlinear time.
- The rebalancing times amortize over sequences of updates.

## Lower Bound for Maintaining the Triangle Count

■ The lower bound already holds for the Boolean Triangle Detection Problem, which is a special case of the Triangle Count.

For any  $\gamma>$  0, there is no algorithm that incrementally maintains the Triangle Detection Problem with

amortized update time answer time 
$$\mathcal{O}(|\mathbf{D}|^{\frac{1}{2}-\gamma}) \qquad \qquad \mathcal{O}(|\mathbf{D}|^{1-\gamma})$$

unless the Online Vector-Matrix-Vector Multiplication (OuMv) Conjecture fails.

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unless the Online Vector-Matrix-Vector Multiplication (OuMv) Conjecture fails.

#### The OuMy Problem

Input: An  $n \times n$  Boolean matrix **M** and n pairs  $(\mathbf{u}_1, \mathbf{v}_1), \dots, (\mathbf{u}_n, \mathbf{v}_n)$  of Boolean column-vectors of size n arriving one after the other.

Goal: After seeing each pair  $(\mathbf{u}_r, \mathbf{v}_r)$ , output  $\mathbf{u}_r^T \mathbf{M} \mathbf{v}_r$ 

#### The OuMv Conjecture

HKNS15

For any  $\gamma>0$ , there is no algorithm that solves the OuMv Problem in time  $\mathcal{O}(n^{3-\gamma})$ .

 $\blacksquare$  Assume there is an algorithm  ${\mathcal A}$  maintaining Triangle Detection with

amortized update time answer time 
$$\mathcal{O}(|\mathbf{D}|^{\frac{1}{2}-\gamma}) \qquad \qquad \mathcal{O}(|\mathbf{D}|^{1-\gamma})$$

for some  $\gamma > 0$ .

■ Goal: Design an algorithm  $\mathcal{B}$  using algorithm  $\mathcal{A}$  as oracle that solves OuMv in subcubic time.  $\Longrightarrow$  Contradicts the OuMv Conjecture!

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■ Goal: Design an algorithm  $\mathcal B$  using algorithm  $\mathcal A$  as oracle that solves OuMv in subcubic time.  $\Longrightarrow$  Contradicts the OuMv Conjecture!

### Algorithm $\mathcal{B}$

- Use relation S to encode the matrix M.
- In each round  $r \in [n]$ :
  - ▶ Use relations R and T to encode  $\mathbf{u}_r$  and  $\mathbf{v}_r$ , respectively, such that

$$\mathbf{u}_r^T \mathbf{M} \mathbf{v}_r = 1$$
 if and only if  $R \bowtie S \bowtie T \neq \emptyset$ 

▶ Check whether  $R \bowtie S \bowtie T$  contains a triangle.

Algorithm  ${\cal B}$  in more detail:

(1) Insert at most  $n^2$  tuples into S such that  $S(B,C)=\{(i,j)\mid \mathbf{M}(i,j)=1\}$ 

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### Time analysis:

■ The database size is  $\mathcal{O}(n^2)$ .

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- Time for each round in (2):  $\mathcal{O}(\underbrace{4n}_{\text{\#updates}} \cdot \underbrace{(n^2)^{\frac{1}{2}-\gamma}}_{\text{update time}} + \underbrace{(n^2)^{1-\gamma}}_{\text{answer time}}) = \mathcal{O}(n^{2-2\gamma})$

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- Time for *n* rounds in (2):  $\mathcal{O}(n \cdot n^{2-2\gamma}) = \mathcal{O}(n^{3-2\gamma})$

### Algorithm $\mathcal{B}$ in more detail:

- (1) Insert at most  $n^2$  tuples into S such that  $S(B,C)=\{(i,j)\mid \mathbf{M}(i,j)=1\}$
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- Time for *n* rounds in (2):  $\mathcal{O}(n \cdot n^{2-2\gamma}) = \mathcal{O}(n^{3-2\gamma})$
- Overall time: subcubic!  $\mathcal{O}(n^{3-2\gamma})$

### Notes on the OuMv Conjecture

The hardness of many dynamic problems is based on Online Matrix-vector multiplication problem (OMv)

OuMv is at least as hard as OMv

Examples: [HKNS15]

- source-target reachability
- source-target shortest path (in unweighted graphs)
- transitive closure

# Outline of Part 2: Aggregates



FAQs: Functional Aggregate Queries

FAQ Computation

Counting Triangles under Updates

#### References

Quiz

### References

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# Outline of Part 2: Aggregates



FAQs: Functional Aggregate Queries

FAQ Computation

Counting Triangles under Updates

References

Quiz

# QUIZ on Aggregates (1/3)

For each of of the following functional aggregate queries:

- 1. Give a hypertree decomposition and variable order.
- If you were to compute it as stated below (with all sums done after the products), what would be its time complexity? (Assume all functions have the same size.)
- 3. Is there an equivalent rewriting of  $\varphi$  that would allow for quadratic or even linear time complexity?

The *n*-hop query:

$$\varphi(x_1, x_{n+1}) = \sum_{x_2, \dots, x_n} \psi_1(X_1, X_2) \cdot \psi_2(X_2, X_3) \cdot \psi_3(X_3, X_4) \cdot \dots \cdot \psi_n(X_n, X_{n+1}).$$

# QUIZ on Aggregates (2/3)

For each of of the following functional aggregate queries:

- 1. Give a hypertree decomposition and variable order.
- If you were to compute it as stated below (with all sums done after the products), what would be its time complexity? Assume all functions have the same size.
- 3. Is there an equivalent rewriting of  $\varphi$  that would allow for quadratic or even linear time complexity?

### Query:

$$\varphi = \sum_{a} \sum_{b} \sum_{c} \sum_{f} \sum_{d} \sum_{e} \psi_1(a,b) \cdot \psi_2(a,c) \cdot \psi_3(c,d) \cdot \psi_4(b,c,e) \cdot \psi_5(e,f).$$

# QUIZ on Aggregates (3/3)

Give the update time and necessary space for the maintenance of the following FAQs as a function of the database size and the heavy/light threshold parameter  $\epsilon \in [0,1]$ :

$$\varphi_1 = \sum_{a,b,c,d} R(a,b) \cdot S(b,c) \cdot T(c,d)$$

$$\varphi_2 = \sum_{a,b,c,d} R(a,b) \cdot S(b,c) \cdot T(b,d)$$

$$\varphi_3 = \sum_{a,b,c,d} R(a,b) \cdot S(b,c) \cdot T(c,d) \cdot W(d,a)$$