

Estimating the Effect of a Mis-measured, Endogenous, Binary Regressor

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Additively Separable Model

$$y = m(T^*, \mathbf{x}) + \varepsilon$$

- ▶ y – Outcome of interest
- ▶ m – Known or unknown function
- ▶ T^* – Unobserved, endogenous binary regressor
- ▶ T – Observed, mis-measured binary surrogate for T^*
- ▶ \mathbf{x} – Exogenous covariates
- ▶ ε – Mean-zero error term

What is the Effect of T^* ?

Re-write the Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon$$

$$\beta(\mathbf{x}) = m(1, \mathbf{x}) - m(0, \mathbf{x})$$

$$c(\mathbf{x}) = m(0, \mathbf{x})$$

This Paper:

- ▶ Does a discrete instrument z (typically binary) identify $\beta(\mathbf{x})$?
- ▶ What assumptions are required for z and the surrogate T ?
- ▶ How to carry out inference for a mis-classified regressor?

Example: Job Training Partnership Act (JPTA)

Heckman et al. (2000, QJE)

Randomized offer of job training, but about 30% of those *not* offered also obtain training and about 40% of those offered training don't attend. Estimate causal effect of *training* rather than *offer* of training.

- ▶ y – Log wage
- ▶ T^* – True training attendance
- ▶ T – Self-reported training attendance
- ▶ x – Individual characteristics
- ▶ z – Offer of job training

Related Literature

Continuous Treatment

Lewbel (1997, 2012), Schennach (2004, 2007), Chen et al. (2005), Hu & Schennach (2008), Song (2015), Hu et al. (2015)...

Binary, Exogenous Treatment

Aigner (1973), Bollinger (1996), Kane et al. (1999), Black et al. (2000), Frazis & Loewenstein (2003), Mahajan (2006), Lewbel (2007), Hu (2008)

Binary, Endogenous Treatment

Mahajan (2006), Shiu (2015), Ura (2015), Denteh et al. (2016)

Baseline Assumptions – Maintained Throughout

Additively Separable Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon, \quad \mathbb{E}[\varepsilon] = 0$$

Valid & Relevant Instrument

$$\mathbb{E}[\varepsilon|\mathbf{x}, z] = 0, \quad \mathbb{E}[T^*|\mathbf{x}, z = k] \neq \mathbb{E}[T^*|\mathbf{x}, z = \ell]$$

Measurement Error Assumptions

- (i) $\mathbb{E}[\varepsilon|\mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon|\mathbf{x}, z, T^*]$
- (ii) $\alpha_0(\mathbf{x}) = \mathbb{P}(T = 1|T^* = 0, \mathbf{x}, z)$
- (iii) $\alpha_1(\mathbf{x}) = \mathbb{P}(T = 0|T^* = 1, \mathbf{x}, z)$
- (iv) T is (positively) correlated with T^*

Theorem: Baseline Assumptions Fail to Identify $\beta(\mathbf{x})$

Sketch for Simple Case: $\alpha_0 = 0$

$$0 \leq \alpha_1(\mathbf{x}) \leq \min_k \{1 - p_k(\mathbf{x})\}$$

$$[1 - p_k(\mathbf{x})] \mathbb{E}[y | T = 0, z_k, \mathbf{x}] =$$

$$p_k(\mathbf{x}) \mathbb{E}[y | T = 1, z_k, \mathbf{x}] = p_k(\mathbf{x}) \beta(\mathbf{x})$$

System of Equations given $E[\varepsilon|z] = 0$

Let $m_{tk}^* = \mathbb{E}[\varepsilon | T^* = t, z = k]$

$$(1 - p_k)\bar{y}_{0k} = \alpha_1(p_k - \alpha_0) \left(\frac{\beta}{1 - \alpha_0 - \alpha_1} \right) + (1 - \alpha_0)c - (p_k - \alpha_0)(c + m_{1k}^*)$$

$$p_k\bar{y}_{1k} = (1 - \alpha_1)(p_k - \alpha_0) \left(\frac{\beta}{1 - \alpha_0 - \alpha_1} \right) + \alpha_0 c + (p_k - \alpha_0)(c + m_{1k}^*)$$

Theorem

$2K$ equations in $K + 4$ unknowns, but β is unidentified from conditional means of y regardless of how many values, K , the instrument takes on.

Intuition

Using $E[\varepsilon|z] = 0$ to eliminate m_{0k}^* from the system “entangles” the equations such that each pair only provides one restriction.

Identification from Stronger Assumptions?

Second Moment Assumption

- (i) $\mathbb{E}[\varepsilon^2 | \mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon^2 | \mathbf{x}, z, T^*]$
- (ii) $\mathbb{E}[\varepsilon^2 | \mathbf{x}, z] = \mathbb{E}[\varepsilon^2 | \mathbf{x}]$

Third Moment Assumption

- (i) $\mathbb{E}[\varepsilon^3 | \mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon^3 | \mathbf{x}, z, T^*]$
- (ii) $\mathbb{E}[\varepsilon^3 | \mathbf{x}, z] = \mathbb{E}[\varepsilon^3 | \mathbf{x}]$

Sufficient Condition

- (i) T is conditionally independent of (ε, z) given (T^*, \mathbf{x})
- (ii) z is conditionally independent of ε given \mathbf{x}

Identification Argument: Step I

Reparameterization

$$\theta_1(\mathbf{x}) = \beta(\mathbf{x}) / [1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})]$$

$$\theta_2(\mathbf{x}) = [\theta_1(\mathbf{x})]^2 [1 + \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})]$$

$$\theta_3(\mathbf{x}) = [\theta_1(\mathbf{x})]^3 \left[\{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\}^2 + 6\alpha_0(\mathbf{x}) \{1 - \alpha_1(\mathbf{x})\} \right]$$

Theorem

Suppose that $\theta_1(\mathbf{x})$, $\theta_2(\mathbf{x})$ and $\theta_3(\mathbf{x})$ are identified. Then:

- ▶ $\theta_1(\mathbf{x}) \neq 0 \implies \beta(\mathbf{x}), \alpha_0(\mathbf{x})$ and $\alpha_1(\mathbf{x})$ are identified
- ▶ $\theta_1(\mathbf{x}) = 0 \implies \beta(\mathbf{x})$ is identified but $\alpha_0(\mathbf{x})$ and $\alpha_1(\mathbf{x})$ are not.

First Moment Condition

Assumptions

- ▶ $\mathbb{E}[\varepsilon|z] = 0$
- ▶ $\mathbb{E}[\varepsilon|T^*, T, z] = \mathbb{E}[\varepsilon|T^*, z]$
- ▶ $\alpha_0 = \mathbb{P}(T = 1|T^* = 0, z)$
- ▶ $\alpha_1 = \mathbb{P}(T = 0|T^* = 1, z)$

Moment Condition

$$\text{Cov}(y, z) - \left(\frac{\beta}{1 - \alpha_0 - \alpha_1} \right) \text{Cov}(T, z) = 0$$

MC # 1 identifies $\beta/(1 - \alpha_0 - \alpha_1)$

Second Moment Condition

Additional Assumptions

- ▶ $\mathbb{E}[\varepsilon^2|z] = \mathbb{E}[\varepsilon^2]$
- ▶ $\mathbb{E}[\varepsilon^2|T^*, T, z] = \mathbb{E}[\varepsilon^2|T^*, z]$

Moment Condition

$$\text{Cov}(y^2, z) - \frac{\beta}{1 - \alpha_0 - \alpha_1} \left\{ 2\text{Cov}(yT, z) - \beta\text{Cov}(T, z) \left(\frac{1 + \alpha_0 - \alpha_1}{1 - \alpha_0 - \alpha_1} \right) \right\} = 0$$

Given MC #1, MC #2 identifies $(\alpha_1 - \alpha_0)$

Third Moment Condition

Additional Assumptions

- ▶ $\mathbb{E}[\varepsilon^3|z] = \mathbb{E}[\varepsilon^3]$
- ▶ $\mathbb{E}[\varepsilon^3|T^*, T, z] = \mathbb{E}[\varepsilon^3|T^*, z]$

Moment Condition

$$\text{Cov}(y^3, z) - \left(\frac{\beta}{1 - \alpha_0 - \alpha_1} \right) \left\{ \beta^2 \left[1 + \frac{6\alpha_0(1 - \alpha_1)}{(1 - \alpha_0 - \alpha_1)^2} \right] \text{Cov}(T, z) \right. \\ \left. - 3\beta \left[\frac{1 - (\alpha_1 - \alpha_0)}{1 - \alpha_0 - \alpha_1} \right] \text{Cov}(yT, z) + 3\text{Cov}(y^2 T, z) \right\} = 0$$

Theorem

Model is identified if $\beta \neq 0$ and $\alpha_0 + \alpha_1 < 1$. If $\beta = 0$, reduced form identifies β . If $\alpha_0 + \alpha_1 > 1$, β is identified up to sign.

GMM Estimator in Simple Special Case: $\alpha_0 = 0$

$$u(\boldsymbol{\theta}) = y - c - \frac{\beta}{1 - \alpha_1} T$$

$$v(\boldsymbol{\theta}) = y^2 - \sigma_{\varepsilon\varepsilon} - c^2 - \frac{\beta}{1 - \alpha_1} 2yT + \frac{\beta^2}{1 - \alpha_1}$$

$$\mathbb{E}[g_1(\mathbf{x}, \boldsymbol{\theta})] = \mathbb{E} \begin{bmatrix} u(\boldsymbol{\theta}) \\ v(\boldsymbol{\theta}) \end{bmatrix} = \mathbf{0}, \quad \mathbb{E}[g_2(\mathbf{x}, \boldsymbol{\theta})] = \mathbb{E} \begin{bmatrix} u(\boldsymbol{\theta})z \\ v(\boldsymbol{\theta})z \end{bmatrix} = \mathbf{0}$$

$$\beta = \frac{2\text{Cov}(yT, z)}{\text{Cov}(T, z)} - \frac{\text{Cov}(y^2, z)}{\text{Cov}(y, z)}$$

Simulation DGP: $y = \beta T^* + \varepsilon$

Errors

$(\varepsilon, \eta) \sim$ jointly normal, mean 0, variance 1, correlation 0.5.

First-Stage

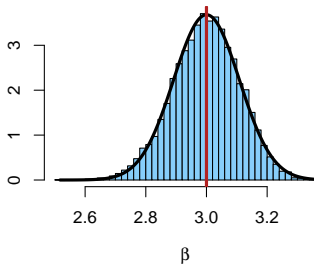
- ▶ Half of subjects have $z = 1$, the rest have $z = 0$.
- ▶ $T^* = \mathbf{1}\{\gamma_0 + \gamma_1 z + \eta > 0\}$
- ▶ $\delta = \mathbb{P}(T^* = 0|z = 1) = \mathbb{P}(T^* = 1|z = 0)$

Mis-classification

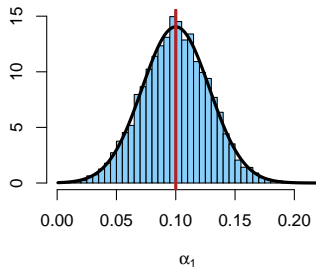
- ▶ Set $\alpha_0 = 0$
- ▶ $T|T^* = 1 \sim \text{Bernoulli}(1 - \alpha_1)$

$\beta = 3, \alpha_1 = 0.1, \delta = 0.15, n = 1000$

Bias = -0.002 , SD = 0.11

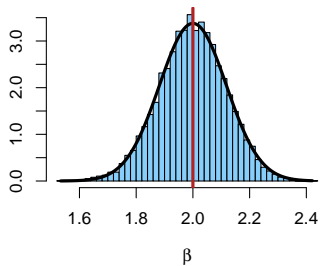


Bias = 0 , SD = 0.028

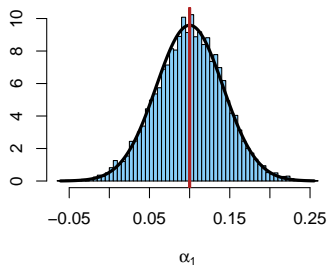


$\beta = 2, \alpha_1 = 0.1, \delta = 0.15, n = 1000$

Bias = -0.002 , SD = 0.118

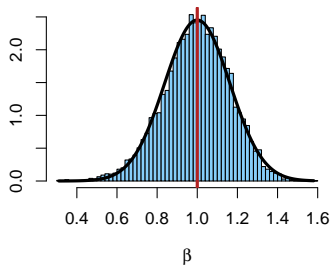


Bias = 0.001 , SD = 0.042

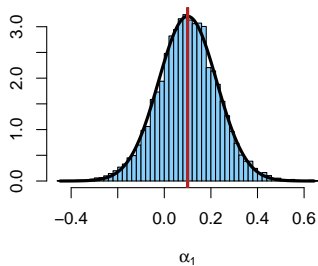


$\beta = 1, \alpha_1 = 0.1, \delta = 0.15, n = 1000$

Bias = -0.002 , SD = 0.165

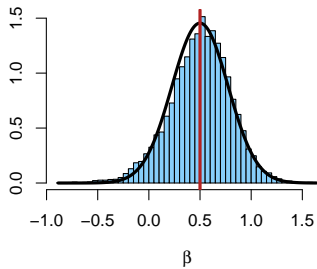


Bias = 0.001 , SD = 0.129

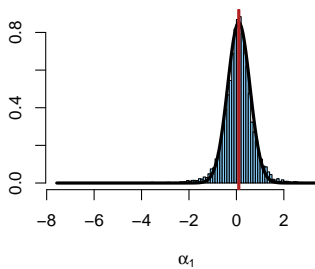


$\beta = 0.5, \alpha_1 = 0.1, \delta = 0.15, n = 1000$

Bias = 0.002 , SD = 0.297



Bias = -0.012 , SD = 0.616



Identification Failure when $\beta = 0$

Simple Special Case: $\alpha_0 = 0$

$$u(\theta) = y - c - \frac{\beta}{1 - \alpha_1} T$$

$$v(\theta) = y^2 - \sigma_{\varepsilon\varepsilon} - c^2 - \frac{\beta}{1 - \alpha_1} 2yT + \frac{\beta^2}{1 - \alpha_1}$$

$$\mathbb{E}[g_1(\mathbf{x}, \theta)] = \mathbb{E} \begin{bmatrix} u(\theta) \\ v(\theta) \end{bmatrix} = \mathbf{0}, \quad \mathbb{E}[g_2(\mathbf{x}, \theta)] = \mathbb{E} \begin{bmatrix} u(\theta)z \\ v(\theta)z \end{bmatrix} = \mathbf{0}$$

- ▶ β small \Rightarrow moment equalities uninformative about α_1
- ▶ $(c, \sigma_{\varepsilon\varepsilon})$ are identified at any hypothesized pair (α_1, β)

Auxiliary Moment Inequalities

General Case $\alpha_0 \neq 0$

$$\alpha_0(z) = \alpha_0, \quad \alpha_1(z) = \alpha_1$$

$$\implies p_k^* = \frac{p_k - \alpha_0}{1 - \alpha_0 - \alpha_1}, \quad 1 - p_k^* = \frac{1 - p_k - \alpha_1}{1 - \alpha_0 - \alpha_1}$$

$$\alpha_0 + \alpha_1 < 1 \iff \text{Cor}(T, T^*) > 0 \iff (1 - \alpha_0 - \alpha_1) > 0$$

Implications

- ▶ $\alpha_0 < \min_k \{p_k\}$, $\alpha_1 < \min_k \{1 - p_k\}$
- ▶ β is between β_{RF} and β_{IV}
- ▶ β_{IV} *inflated* but has correct sign

Even Tighter Bounds for α_0, α_1 from Conditional Variances

Assume

$$\mathbb{E}[\varepsilon^2 | T^*, T, z] = \mathbb{E}[\varepsilon^2 | T^*, z]$$

Observables

$$\sigma_{tk}^2 = \text{Var}(y | T = t, z = k)$$

Constrain Unobservables

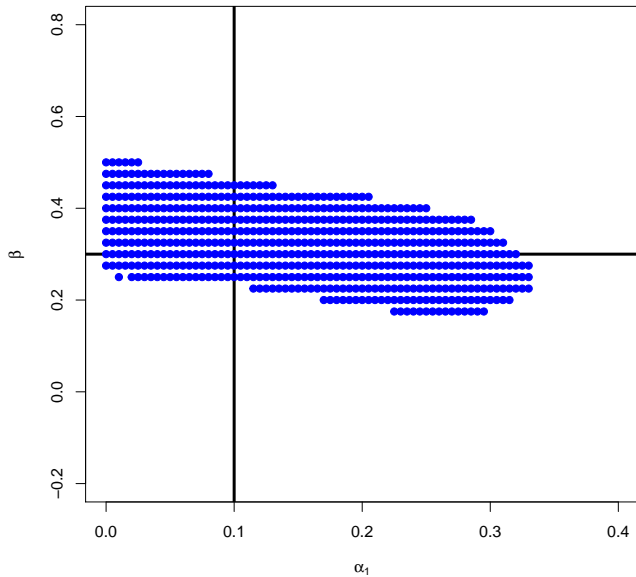
$$s_{tk}^{*2} = \text{Var}(u | T^* = t, z_k) > 0$$

$$\begin{aligned} (p_k - \alpha_0) \left[(1 - \alpha_0) p_k \sigma_{1k}^2 - \alpha_0 (1 - p_k) \sigma_{0k}^2 \right] &> \alpha_0 (1 - \alpha_0) p_k (1 - p_k) (\bar{y}_{1k} - \bar{y}_{0k})^2 \\ (1 - p_k - \alpha_1) \left[(1 - \alpha_1) (1 - p_k) \sigma_{0k}^2 - \alpha_1 p_k \sigma_{1k}^2 \right] &> \alpha_1 (1 - \alpha_1) p_k (1 - p_k) (\bar{y}_{1k} - \bar{y}_{0k})^2 \end{aligned}$$

Identification-Robust Joint Inference for $(\alpha_0, \alpha_1, \beta)$

- ▶ Auxiliary moment inequalities to bound (α_0, α_1)
- ▶ Joint CS for $(\alpha_0, \alpha_1, \beta)$ by inverting Anderson-Rubin Test
- ▶ Marginal inference for β by projection.
- ▶ Generalized Moment Selection (Andrews & Soares, 2010) for tighter confidence sets.
- ▶ Results are preliminary (not exploiting full set of inequalities) but this approach seems to work extremely well.

95% GMS Confidence Region



Conclusion

- ▶ Endogenous, mis-measured binary treatment.
- ▶ Important in applied work but no solution in the literature.
- ▶ Usual (1st moment) IV assumption fails to identify β
- ▶ Higher moment / independence restrictions identify β
- ▶ Identification-Robust Inference incorporating additional inequality moment conditions.