

# Mis-Classified, Binary, Endogenous Regressors: Identification and Inference

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October 11th, 2018

## What is the effect of $T^*$ ?

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon$$

- ▶  $y$  – Outcome of interest
- ▶  $T^*$  – Unobserved, endogenous binary regressor
- ▶  $T$  – Observed, mis-measured binary surrogate for  $T^*$
- ▶  $\mathbf{x}$  – Exogenous covariates
- ▶  $z$  – Discrete (typically binary) instrumental variable

## Using a discrete IV to learn about $\beta(\mathbf{x})$

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon$$

### Contributions of This Paper

1. Show that only existing point identification result for mis-classified, endogenous  $T^*$  is incorrect.
2. Sharp identified set for  $\beta$  under standard assumptions.
3. Point identification of  $\beta$  under slightly stronger assumptions.
4. Describe problem of weak identification in mis-classification models, develop identification-robust inference for  $\beta$ .

# Example: Smoking and Birthweight (SNAP Trial)

Coleman et al. (N Engl J Med, 2012)

RCT with pregnant smokers in England: half given nicotine patches, the rest given placebo patches. Some given nicotine fail to quit; some given placebo quit.

- ▶  $y$  – Birthweight
- ▶  $T^*$  – True smoking behavior
- ▶  $T$  – Self-reported smoking behavior
- ▶  $x$  – Mother characteristics
- ▶  $z$  – Indicator of nicotine patch

# Baseline Assumptions I – Model & Instrument

## Additively Separable Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon, \quad \mathbb{E}[\varepsilon] = 0$$

## Valid & Relevant Instrument: $z \in \{0, 1\}$

- ▶  $\mathbb{P}(T^* = 1 | \mathbf{x}, z = 1) \neq \mathbb{P}(T^* = 1 | \mathbf{x}, z = 0)$
- ▶  $\mathbb{E}[\varepsilon | \mathbf{x}, z] = 0$
- ▶  $0 < \mathbb{P}(z = 1 | \mathbf{x}) < 1$

# Baseline Assumptions II – Measurement Error

## Notation

►  $\alpha_0(\mathbf{x}, z) \equiv \mathbb{P}(T = 1 | T^* = 0, \mathbf{x}, z)$

►  $\alpha_1(\mathbf{x}, z) \equiv \mathbb{P}(T = 0 | T^* = 1, \mathbf{x}, z)$

## Mis-classification unaffected by $z$

$$\alpha_0(\mathbf{x}, z) = \alpha_0(\mathbf{x}), \quad \alpha_1(\mathbf{x}, z) = \alpha_1(\mathbf{x})$$

## Extent of Mis-classification

$$\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) < 1 \quad (T \text{ is positively correlated with } T^*)$$

## Non-differential Mis-classification

$$\mathbb{E}[\varepsilon | \mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon | \mathbf{x}, z, T^*]$$

# Only Existing Result for Endogenous $T^*$ is Incorrect

Mahajan (2006; Ecta) A2

$$\mathbb{E}[\varepsilon|\mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon|\mathbf{x}, T^*] + \text{"Baseline"} \Rightarrow \beta(\mathbf{x}) \text{ identified.}$$

We Show:

Mahajan's assumptions imply that the instrument  $z$  is uncorrelated with  $T^*$  unless  $T^*$  is in fact *exogenous*.

# “Weak” Bounds

## First-Stage

$$p_k(\mathbf{x}) \equiv \mathbb{P}(T = 1 | \mathbf{x}, z = k)$$

## IV Estimand

$$\frac{\mathbb{E}[y | \mathbf{x}, z = 1] - \mathbb{E}[y | \mathbf{x}, z = 0]}{p_1(\mathbf{x}) - p_0(\mathbf{x})} = \frac{\beta(\mathbf{x})}{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})}$$

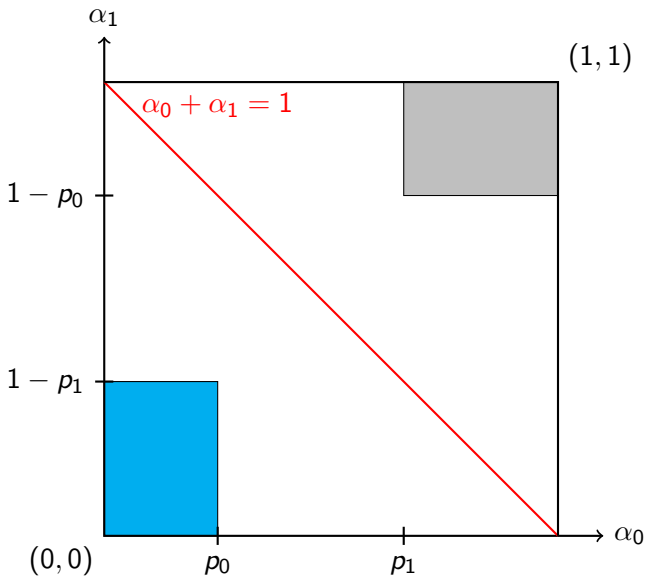
## Bounds for $(\alpha_0, \alpha_1)$

$$\alpha_0(\mathbf{x}) \leq \min_k \{p_k(\mathbf{x})\}, \quad \alpha_1(\mathbf{x}) \leq \min_k \{1 - p_k(\mathbf{x})\} \quad \text{▶ more}$$

## Bounds for $\beta$

$\beta(\mathbf{x})$  is between IV and Reduced form; same sign as IV. ▶ more





# Restrictions from Non-differential Mis-classification?

(Suppress  $\mathbf{x}$  for simplicity)

## Notation

- ▶  $r_{tk} \equiv \mathbb{P}(T^* = 1 | T = t, z = k)$
- ▶  $z_k$  is shorthand for  $z = k$

## Iterated Expectations over $T^*$

$$\mathbb{E}(y | T = 0, z_k) = (1 - r_{0k})\mathbb{E}(y | T^* = 0, T = 0, z_k) + r_{0k}\mathbb{E}(y | T^* = 1, T = 0, z_k)$$

$$\mathbb{E}(y | T = 1, z_k) = (1 - r_{1k})\mathbb{E}(y | T^* = 0, T = 1, z_k) + r_{1k}\mathbb{E}(y | T^* = 1, T = 1, z_k)$$

# Restrictions from Non-differential Mis-classification?

(Suppress  $\mathbf{x}$  for simplicity)

## Notation

- ▶  $r_{tk} \equiv \mathbb{P}(T^* = 1 | T = t, z = k)$
- ▶  $z_k$  is shorthand for  $z = k$

## Adding Non-differential Assumption

$$\mathbb{E}(y | T = 0, z_k) = (1 - r_{0k})\mathbb{E}(y | T^* = 0, z_k) + r_{0k}\mathbb{E}(y | T^* = 1, z_k)$$

$$\mathbb{E}(y | T = 1, z_k) = (1 - r_{1k})\mathbb{E}(y | T^* = 0, z_k) + r_{1k}\mathbb{E}(y | T^* = 1, z_k)$$

2 equations in 2 unknowns $\Rightarrow$ solve for $\mathbb{E}(y   T^* = t^*, z = k)$ given $(r_{0k}, r_{1k})$ .
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# Restrictions from Non-differential Mis-classification?

## Mixture Representation

$$F_{tk} = (1 - r_{tk})F_{tk}^0 + r_{tk}F_{tk}^1$$

$$F_{tk} \equiv y | (T = t, z = k)$$

$$F_{tk}^{t^*} \equiv y | (T^* = t^*, T = t, z = k)$$

## Restrictions

- ▶  $\mathbb{E}(y | T^*, T, z) = \mathbb{E}(y | T^*, z)$  observable given  $(\alpha_0, \alpha_1)$
- ▶  $r_{tk}$  observable given  $(\alpha_0, \alpha_1)$

## Question

Given  $(\alpha_0, \alpha_1)$  can we always find  $(F_{tk}^0, F_{tk}^1)$  to satisfy the mixture model?

# Restrictions from Non-differential Mis-classification?

## Equivalent Problem

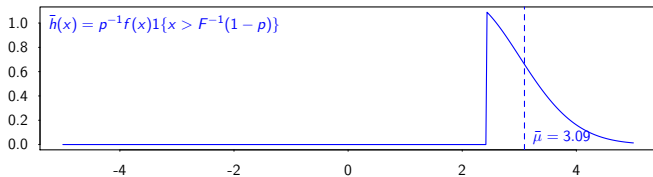
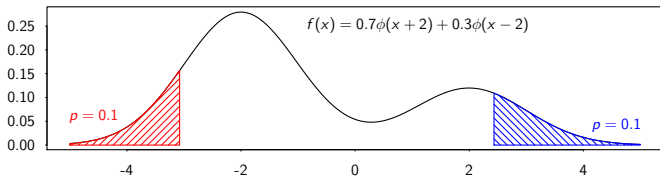
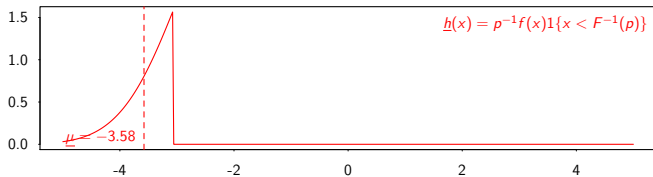
Given a specified CDF  $F$ , for what values of  $p$  and  $\mu$  do there exist valid CDFs  $(G, H)$  with  $F = (1 - p)G + pH$  and  $\mu = \text{mean}(H)$ ?

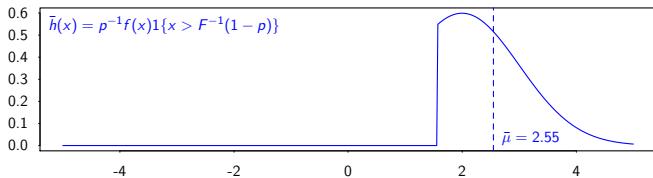
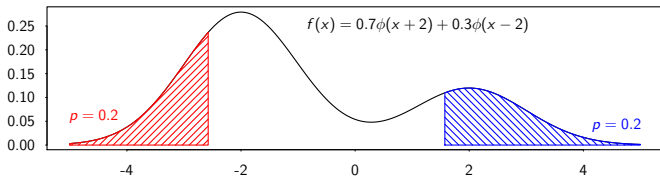
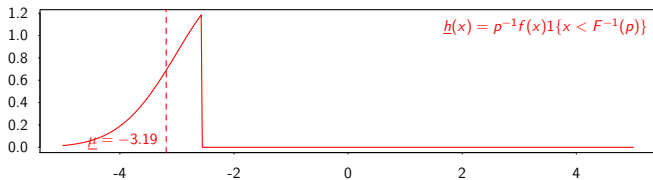
## Necessary and Sufficient Condition if $F$ is Continuous

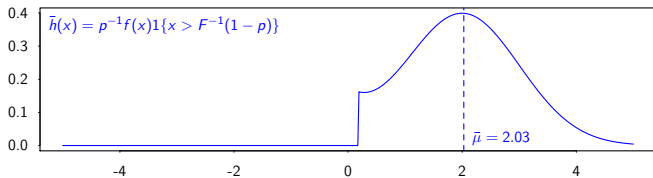
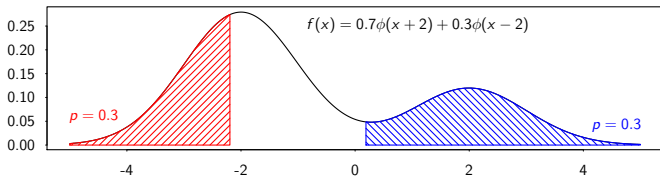
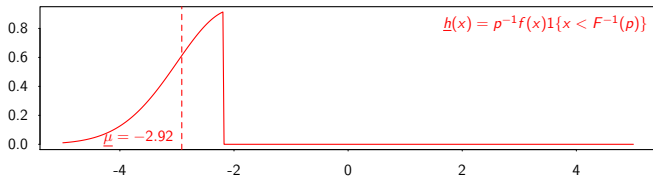
$$\underline{\mu}(F, p) \leq \mu \leq \bar{\mu}(F, p)$$

$$\underline{\mu}(F, p) \equiv \int_{-\infty}^{\infty} x \left[ p^{-1} f(x) \mathbf{1}\{x < F^{-1}(p)\} \right] dx = \int_{-\infty}^{\infty} x \underline{h}(x) dx$$

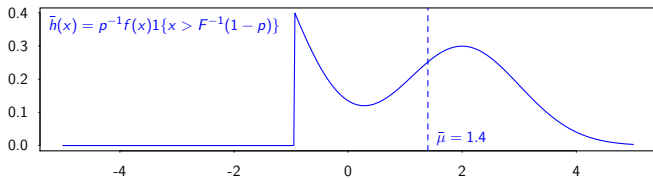
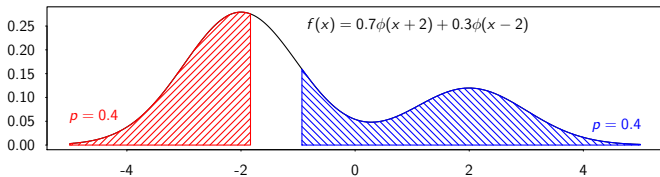
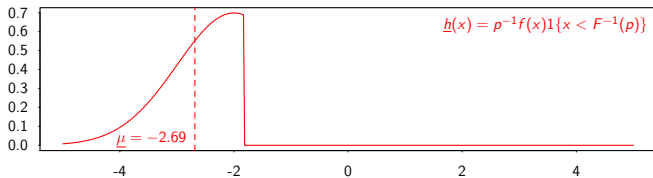
$$\bar{\mu}(F, p) \equiv \int_{-\infty}^{\infty} x \left[ p^{-1} f(x) \mathbf{1}\{x > F^{-1}(1 - p)\} \right] dx = \int_{-\infty}^{\infty} x \bar{h}(x) dx$$

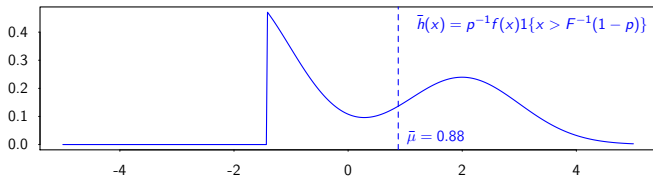
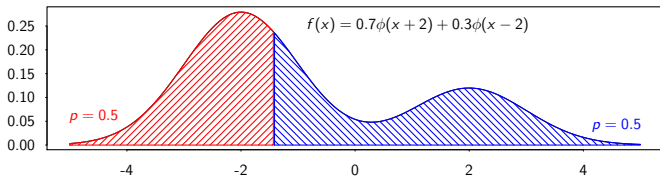
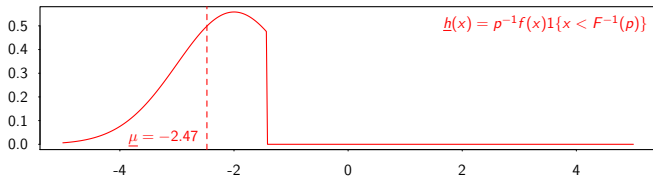


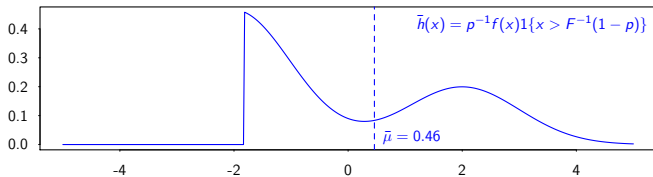
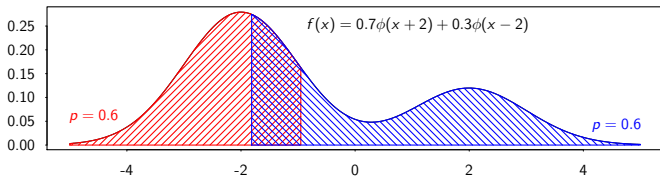
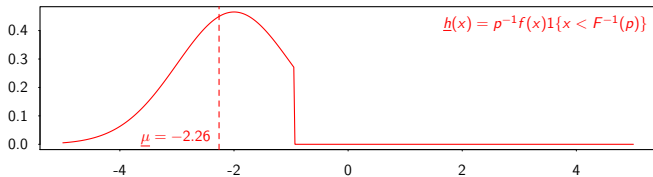


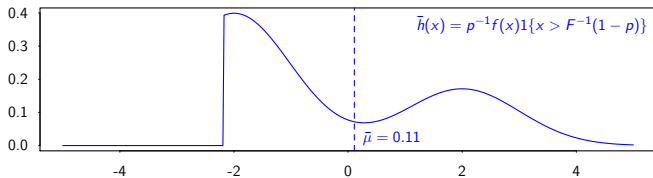
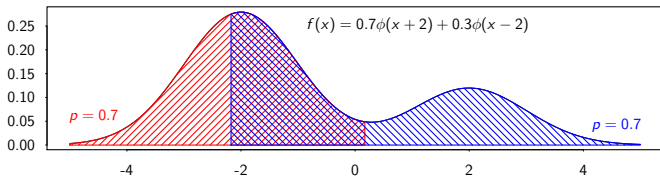
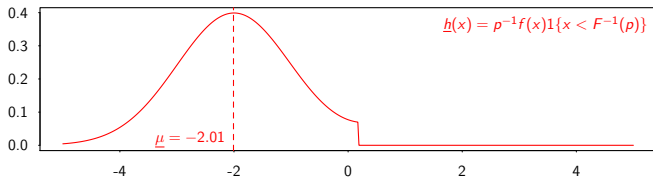


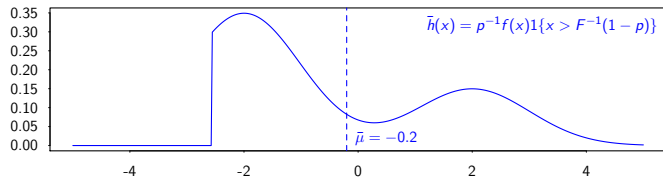
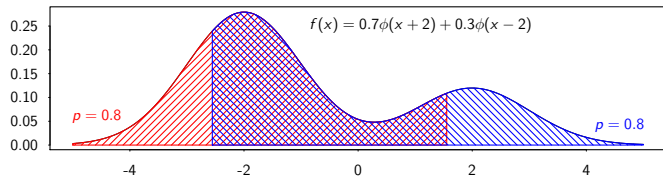
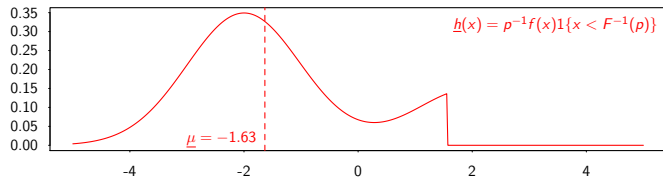


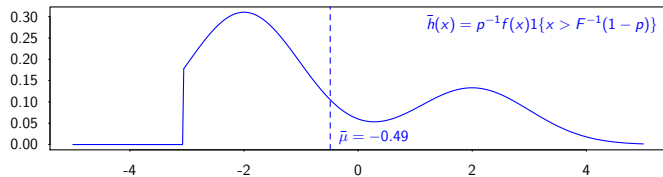
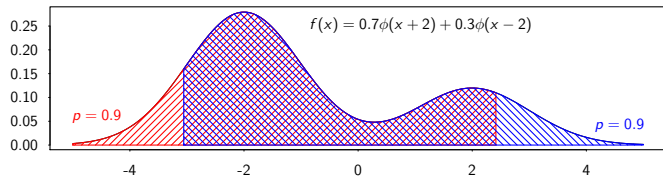
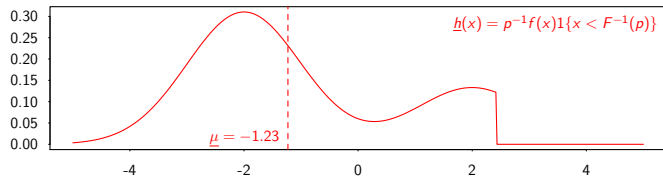


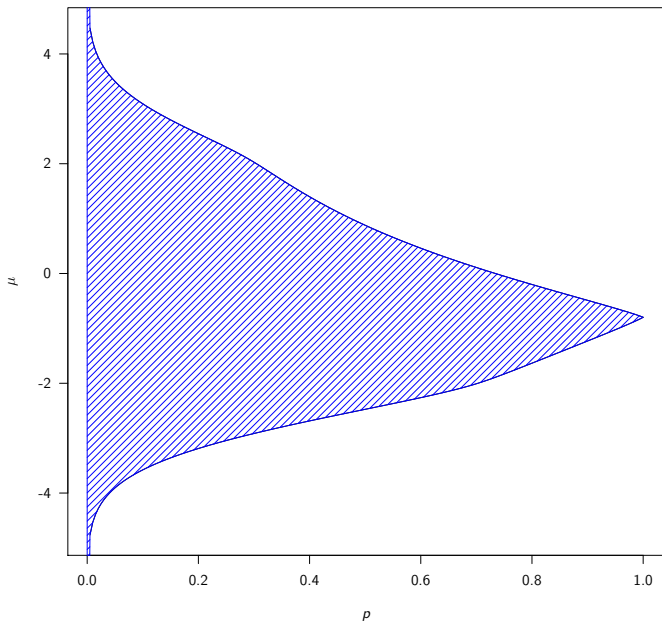












# Sharp Identified Set under Baseline Assumptions

## Theorem

- (i) If  $\mathbb{E}[y|\mathbf{x}, T = 0, z = k] \neq \mathbb{E}[y|\mathbf{x}, T = 1, z = k]$  for some  $k$ , non-differential assump. strictly improves upon weak bounds.
- (ii) Under the baseline assumptions,  $\beta$  is not point identified, regardless of how many (discrete) values  $z$  takes on.

## Corollary

Bounds for  $\alpha_0, \alpha_1$ , and  $\beta$  remain valid in a LATE model. They may not be sharp, however, sharp, since they do not incorporate the testable implications of the LATE assumptions.



# Point Identification: 1st Ingredient

## Reparameterization

$$\theta_1(\mathbf{x}) = \beta(\mathbf{x}) / [1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})]$$

$$\theta_2(\mathbf{x}) = [\theta_1(\mathbf{x})]^2 [1 + \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})]$$

$$\theta_3(\mathbf{x}) = [\theta_1(\mathbf{x})]^3 \left[ \{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\}^2 + 6\alpha_0(\mathbf{x}) \{1 - \alpha_1(\mathbf{x})\} \right]$$

## Lemma

Baseline Assumptions  $\implies \text{Cov}(y, z|\mathbf{x}) = \theta_1(\mathbf{x})\text{Cov}(z, T|\mathbf{x})$ .

## Point Identification: 2nd Ingredient

### Assumption (II)

$$\mathbb{E}[\varepsilon^2|\mathbf{x}, z] = \mathbb{E}[\varepsilon^2|\mathbf{x}]$$

### Lemma

(Baseline) + (II)  $\implies$

$$\text{Cov}(y^2, z|\mathbf{x}) = 2\text{Cov}(yT, z|\mathbf{x})\theta_1(\mathbf{x}) - \text{Cov}(T, z|\mathbf{x})\theta_2(\mathbf{x})$$

### Corollary

(Baseline) + (II) +  $[\beta(\mathbf{x}) \neq 0] \implies [\alpha_1(\mathbf{x}) - \alpha_0(\mathbf{x})]$  is identified.

# Point Identification: 3rd Ingredient

## Assumption (III)

$$(i) \quad \mathbb{E}[\varepsilon^2 | \mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon^2 | \mathbf{x}, z, T^*]$$

$$(ii) \quad \mathbb{E}[\varepsilon^3 | \mathbf{x}, z] = \mathbb{E}[\varepsilon^3 | \mathbf{x}]$$

## Lemma

(Baseline) + (II) + (III)  $\implies$

$$\text{Cov}(y^3, z | \mathbf{x}) = 3\text{Cov}(y^2 T, z | \mathbf{x})\theta_1(\mathbf{x}) - 3\text{Cov}(yT, z | \mathbf{x})\theta_2(\mathbf{x}) + \text{Cov}(T, z | \mathbf{x})\theta_3(\mathbf{x})$$

# Point Identification Result

## Theorem

(Baseline) + (II) + (III)  $\implies \beta(\mathbf{x})$  is point identified. If  $\beta(\mathbf{x}) \neq 0$ , then  $\alpha_0(\mathbf{x})$  and  $\alpha_1(\mathbf{x})$  are likewise point identified.

## Sufficient for (II) and (III)

- (a)  $T$  is conditionally independent of  $(\varepsilon, z)$  given  $(T^*, \mathbf{x})$
- (b)  $z$  is conditionally independent of  $\varepsilon$  given  $\mathbf{x}$

# Inference for a Mis-classified Regressor

## Challenges

- ▶ Weak Identification:  $\beta$  small  $\Rightarrow$  moment equalities uninformative about  $(\alpha_0, \alpha_1)$  [▶ more](#)
- ▶  $(\alpha_0, \alpha_1)$  could be on the boundary of the parameter space
- ▶ Also true of existing estimators that assume  $T^*$  exogenous

## Our Approach

- ▶ Sharp identified set yields *inequality* moment restrictions that remain informative even if  $\beta \approx 0$ . [▶ more](#)
- ▶ Identification-robust inference with equality and inequality MCs.

# Inference with Moment Equalities and Inequalities

## Moment Conditions

$$\mathbb{E}[m_j(\mathbf{w}_i, \vartheta_0)] \geq 0, \quad j = 1, \dots, J$$

$$\mathbb{E}[m_j(\mathbf{w}_i, \vartheta_0)] = 0, \quad j = J+1, \dots, J+K$$

## Test Statistic

$$T_n(\vartheta) = \sum_{j=1}^J \left[ \frac{\sqrt{n} \bar{m}_{n,j}(\vartheta)}{\hat{\sigma}_{n,j}(\vartheta)} \right]_-^2 + \sum_{j=J+1}^{J+K} \left[ \frac{\sqrt{n} \bar{m}_{n,j}(\vartheta)}{\hat{\sigma}_{n,j}(\vartheta)} \right]^2$$

## Critical Value

- ▶  $\sqrt{n} \bar{\mathbf{m}}_n(\vartheta_0) \rightarrow_d$  normal limit with covariance matrix  $\Sigma(\vartheta_0)$
- ▶ Use this to bootstrap the limit dist. of  $T_n(\vartheta)$  under  $H_0: \vartheta = \vartheta_0$

# Generalized Moment Selection

Andrews & Soares (2010)

- ▶ Inequalities that don't bind reduce power of test, so eliminate those that are “far from binding” before calculating critical value:

$$\text{Drop inequality } j \text{ if } \frac{\sqrt{n} \bar{m}_{n,j}(\vartheta_0)}{\hat{\sigma}_{n,j}(\vartheta_0)} > \sqrt{\log n}$$

- ▶ Uniformly valid test of  $H_0: \vartheta = \vartheta_0$  even if  $\vartheta_0$  is not point identified.
- ▶ Not asymptotically conservative.

## Problem

*Joint test* for the whole parameter vector but we're only interested in  $\beta$ .  
Projection is conservative and computationally intensive.

# Our Solution: Bonferroni-Based Inference

## Special Structure

- ▶  $\beta$  only enters MCs through  $\theta_1 = \beta/(1 - \alpha_0 - \alpha_1)$
- ▶ Strong instrument  $\Rightarrow$  inference for  $\theta_1$  is standard.
- ▶ Nuisance pars  $\gamma$  strongly identified under null for  $(\alpha_0, \alpha_1)$

## Procedure

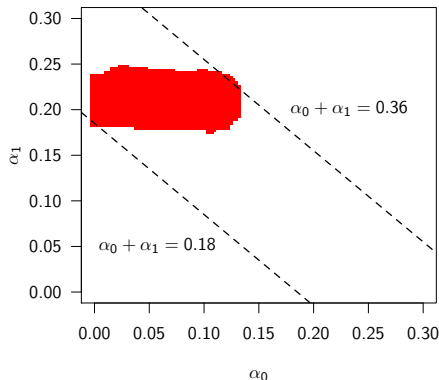
1. Concentrate out  $(\theta_1, \gamma) \Rightarrow$  joint GMS test for  $(\alpha_0, \alpha_1)$
2. Invert test  $\Rightarrow (1 - \delta_1) \times 100\%$  confidence set for  $(\alpha_0, \alpha_1)$
3. Project  $\Rightarrow$  CI for  $(1 - \alpha_0 - \alpha_1)$
4. Construct standard  $(1 - \delta_2) \times 100\%$  IV CI for  $\theta_1$
5. Bonferroni  $\Rightarrow (1 - \delta_1 - \delta_2) \times 100\%$  CI for  $\beta$



# Example

(sim data:  $\beta = 1, \alpha_0 = 0.1, \alpha_1 = 0.2, n = 5000$ )

## 97.5% GMS Confidence Region for $(\alpha_0, \alpha_1)$ Our Procedure



1. 97.5% GMS CI for  $(\alpha_0, \alpha_1)$  at left
2.  $\geq$  97.5% Projection CI for  $(1 - \alpha_0 - \alpha_1)$   
 $(1 - 0.36, 1 - 0.18) = (0.64, 0.82)$
3. 97.5% CI for  $\theta_1 = (1.20, 1.47)$
4.  $\geq$  95% CI for  $\beta$ :  
 $(0.64 \times 1.20, 0.82 \times 1.47) = (0.77, 1.21)$

## Comparisons

- ▶  $(0.88, 1.04)$  95% CI for IV using  $T^*$
- ▶  $(1.22, 1.45)$  95% CI for IV using  $T$

# Conclusion

## This Paper

- ▶ Partial and point identification results for effect of binary, endogenous regressor using a valid instrument.
- ▶ Identification-robust inference in models with mis-classification

## Related Work

- ▶ Relaxing Instrument Validity: “A Framework for Eliticing, Incorporating, and Disciplining Identification Beliefs in Linear Models” (with Camilo Garcia-Jimeno)
- ▶ Relaxing Non-differential Measurement Error: “Estimating the Returns to Lying” (with Arthur Lewbel)

# Simple Bounds for Mis-classification from First-stage

Unobserved	Observed
$p_k^*(\mathbf{x}) \equiv \mathbb{P}(T^* = 1   \mathbf{x}, z = k)$	$p_k(\mathbf{x}) \equiv \mathbb{P}(T = 1   \mathbf{x}, z = k)$

## Relationship

$$p_k^*(\mathbf{x}) = \frac{p_k(\mathbf{x}) - \alpha_0(\mathbf{x})}{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})}, \quad k = 0, 1$$

$z$  does not affect  $(\alpha_0, \alpha_1)$ ; denominator  $\neq 0$

## Bounds for Mis-classification

$$\alpha_0(\mathbf{x}) \leq p_k(\mathbf{x}) \leq 1 - \alpha_1(\mathbf{x}), \quad k = 0, 1$$

$$\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) < 1$$

# What does IV estimate under mis-classification?

Unobserved

$$\beta(\mathbf{x}) = \frac{\mathbb{E}[y|\mathbf{x}, z = 1] - \mathbb{E}[y|\mathbf{x}, z = 0]}{p_1^*(\mathbf{x}) - p_0^*(\mathbf{x})}$$

Wald (Observed)

$$\frac{\mathbb{E}[y|\mathbf{x}, z = 1] - \mathbb{E}[y|\mathbf{x}, z = 0]}{p_1(\mathbf{x}) - p_0(\mathbf{x})} = \beta(\mathbf{x}) \left[ \frac{p_1^*(\mathbf{x}) - p_0^*(\mathbf{x})}{p_1(\mathbf{x}) - p_0(\mathbf{x})} \right] = \frac{\beta(\mathbf{x})}{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})}$$

$$p_1^*(\mathbf{x}) - p_0^*(\mathbf{x}) = \frac{p_1(\mathbf{x}) - \alpha_0(\mathbf{x})}{1 - \alpha_0 - \alpha_1(\mathbf{x})} - \frac{p_0(\mathbf{x}) - \alpha_0(\mathbf{x})}{1 - \alpha_0 - \alpha_1(\mathbf{x})} = \frac{p_1(\mathbf{x}) - p_0(\mathbf{x})}{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})}$$

## Partial Identification Bounds for $\beta(\mathbf{x})$

$$\beta(\mathbf{x}) = [1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})] \left[ \frac{\mathbb{E}[y|\mathbf{x}, z = 1] - \mathbb{E}[y|\mathbf{x}, z = 0]}{p_1(\mathbf{x}) - p_0(\mathbf{x})} \right]$$

$$0 \leq \alpha_0 \leq \min_k \{p_k(\mathbf{x})\}, \quad 0 \leq \alpha_1 \leq \min_k \{1 - p_k(\mathbf{x})\}$$

### No Mis-classification

$$\alpha_0(\mathbf{x}) = \alpha_1(\mathbf{x}) = 0 \implies \beta(\mathbf{x}) = \text{Wald}$$

### Maximum Mis-classification

$$\alpha_0(\mathbf{x}) = p_{\min}(\mathbf{x}), \quad \alpha_1(\mathbf{x}) = 1 - p_{\max}(\mathbf{x})$$

$$\implies 1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x}) = p_{\max}(\mathbf{x}) - p_{\min}(\mathbf{x}) = |p_1(\mathbf{x}) - p_0(\mathbf{x})|$$

$$\implies \beta(\mathbf{x}) = \text{sign}\{p_1(\mathbf{x}) - p_0(\mathbf{x})\} \times (\text{Reduced Form})$$

# Just-Identified System of Moment Equalities

Suppress dependence on  $\mathbf{x} \dots$

$$\mathbb{E} \left[ \{ \boldsymbol{\Psi}(\boldsymbol{\theta}) \mathbf{w}_i - \boldsymbol{\kappa} \} \otimes \begin{pmatrix} 1 \\ z \end{pmatrix} \right] = \mathbf{0}$$

$$\boldsymbol{\Psi}(\boldsymbol{\theta}) \equiv \begin{bmatrix} -\theta_1 & 1 & 0 & 0 & 0 & 0 \\ \theta_2 & 0 & -2\theta_1 & 1 & 0 & 0 \\ -\theta_3 & 0 & 3\theta_2 & 0 & -3\theta_1 & 1 \end{bmatrix}$$

$$\mathbf{w}_i = (T_i, y_i, y_i T_i, y_i^2, y_i^2 T_i, y_i^3)' \quad \theta_1 = \beta / (1 - \alpha_0 - \alpha_1)$$

$$\boldsymbol{\kappa} = (\kappa_1, \kappa_2, \kappa_3)' \quad \theta_2 = \theta_1^2 (1 + \alpha_0 - \alpha_1)$$

$$\theta_3 = \theta_1^3 [(1 - \alpha_0 - \alpha_1)^2 + 6\alpha_0(1 - \alpha_1)]$$

## Moment Inequalities I – First-stage Probabilities

$\alpha_0 \leq p_k \leq 1 - \alpha_1$  becomes  $\mathbb{E}[m(\mathbf{w}_i, \boldsymbol{\vartheta})] \geq \mathbf{0}$  for all  $k$  where

$$m(\mathbf{w}_i, \boldsymbol{\vartheta}) \equiv \begin{bmatrix} \mathbf{1}(z_i = k)(T - \alpha_0) \\ \mathbf{1}(z_i = k)(1 - T_i - \alpha_1) \end{bmatrix}$$

## Moment Inequalities II – Non-differential Assumption

For all  $k$ , we have  $\mathbb{E}[m(\mathbf{w}_i, \vartheta, \mathbf{q}_k)] \geq 0$  where

$$m(\mathbf{w}_i, \vartheta, \mathbf{q}_k) \equiv \begin{bmatrix} y_i \mathbf{1}(z_i = k) \left\{ (T_i - \alpha_0) - \mathbf{1}(y_i \leq \underline{q}_{0k})(1 - T_i) \left( \frac{1 - \alpha_0 - \alpha_1}{\alpha_1} \right) \right\} \\ - y_i \mathbf{1}(z_i = k) \left\{ (T_i - \alpha_0) - \mathbf{1}(y_i > \bar{q}_{0k})(1 - T_i) \left( \frac{1 - \alpha_0 - \alpha_1}{\alpha_1} \right) \right\} \\ y_i \mathbf{1}(z_i = k) \left\{ (T_i - \alpha_0) - \mathbf{1}(y_i \leq \underline{q}_{1k}) T_i \left( \frac{1 - \alpha_0 - \alpha_1}{1 - \alpha_1} \right) \right\} \\ - y_i \mathbf{1}(z_i = k) \left\{ (T_i - \alpha_0) - \mathbf{1}(y_i > \bar{q}_{1k}) T_i \left( \frac{1 - \alpha_0 - \alpha_1}{1 - \alpha_1} \right) \right\} \end{bmatrix}$$

and  $\mathbf{q}_k \equiv (\underline{q}_{0k}, \bar{q}_{0k}, \underline{q}_{1k}, \bar{q}_{1k})'$  defined by  $\mathbb{E}[h(\mathbf{w}_i, \vartheta, \mathbf{q}_k)] = 0$  with

$$h(\mathbf{w}_i, \vartheta, \mathbf{q}_k) = \begin{bmatrix} \mathbf{1}(y_i \leq \underline{q}_{0k}) \mathbf{1}(z_i = k)(1 - T_i) - \left( \frac{\alpha_1}{1 - \alpha_0 - \alpha_1} \right) \mathbf{1}(z_i = k)(T_i - \alpha_0) \\ \mathbf{1}(y_i \leq \bar{q}_{0k}) \mathbf{1}(z_i = k)(1 - T_i) - \left( \frac{1 - \alpha_0}{1 - \alpha_0 - \alpha_1} \right) \mathbf{1}(z_i = k)(1 - T_i - \alpha_1) \\ \mathbf{1}(y_i \leq \underline{q}_{1k}) \mathbf{1}(z_i = k) T_i - \left( \frac{1 - \alpha_1}{1 - \alpha_0 - \alpha_1} \right) \mathbf{1}(z_i = k)(T_i - \alpha_0) \\ \mathbf{1}(y_i \leq \bar{q}_{1k}) \mathbf{1}(z_i = k) T_i - \left( \frac{\alpha_0}{1 - \alpha_0 - \alpha_1} \right) \mathbf{1}(z_i = k)(1 - T_i - \alpha_1) \end{bmatrix}$$