Estimating the Effect of a Mis-measured, Endogenous, Binary Regressor

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Additively Separable Model

$$y = m(T^*, \mathbf{x}) + \varepsilon$$

- ▶ y Outcome of interest
- ▶ m Known or unknown function
- ▶ T* Unobserved, endogenous binary regressor
- ► T Observed, mis-measured binary surrogate for T*
- x Exogenous covariates
- \triangleright ε Mean-zero error term

What is the Effect of T^* ?

Re-write the Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x}) T^* + \varepsilon$$
$$\beta(\mathbf{x}) = m(1, \mathbf{x}) - m(0, \mathbf{x})$$
$$c(\mathbf{x}) = m(0, \mathbf{x})$$

This Paper:

- ▶ Does a discrete instrument z (typically binary) identify $\beta(x)$?
- ▶ What assumptions are required for z and the surrogate T?
- ▶ How to carry out inference for a mis-classified regressor?

Example: Job Training Partnership Act (JPTA)

Heckman et al. (2000, QJE)

Randomized offer of job training, but about 30% of those *not* offered also obtain training and about 40% of those offered training don't attend. Estimate causal effect of *training* rather than *offer* of training.

- y − Log wage
- ▶ T* True training attendence
- ➤ T Self-reported training attendance
- x Individual characteristics
- \triangleright z Offer of job training

Related Literature

Continuous Treatment

Lewbel (1997, 2012), Schennach (2004, 2007), Chen et al. (2005), Hu & Schennach (2008), Song (2015), Hu et al. (2015)...

Binary, Exogenous Treatment

Aigner (1973), Bollinger (1996), Kane et al. (1999), Black et al. (2000), Frazis & Loewenstein (2003), Mahajan (2006), Lewbel (2007), Hu (2008)

Binary, Endogenous Treatment

Mahajan (2006), Shiu (2015), Ura (2015), Denteh et al. (2016)

Baseline Assumptions – Maintained Throughout

Additively Separable Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon, \quad \mathbb{E}[\varepsilon] = 0$$

Valid & Relevant Instrument

$$\mathbb{E}[\varepsilon | \mathbf{x}, z] = 0, \quad \mathbb{E}[T^* | \mathbf{x}, z = k] \neq \mathbb{E}[T^* | \mathbf{x}, z = \ell]$$

Measurement Error Assumptions

- (i) $\mathbb{E}[\varepsilon|\mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon|\mathbf{x}, z, T^*]$
- (ii) $\alpha_0(\mathbf{x}) = \mathbb{P}(T = 1 | T^* = 0, \mathbf{x}, z), \quad \alpha_1(\mathbf{x}) = \mathbb{P}(T = 0 | T^* = 1, \mathbf{x}, z)$
- (iii) $\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) < 1$ (T is positively correlated with T^*)

Theorem

The baseline assumptions fail to identify $\beta(\mathbf{x})$, even if the instrument z takes on an arbitrarily large finite number of distinct values.

Identification from Stronger Assumptions?

Second Moment Assumption

- (i) $\mathbb{E}[\varepsilon^2|\mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon^2|\mathbf{x}, z, T^*]$
- (ii) $\mathbb{E}[\varepsilon^2|\mathbf{x},z] = \mathbb{E}[\varepsilon^2|\mathbf{x}]$

Third Moment Assumption

- (i) $\mathbb{E}[\varepsilon^3|\mathbf{x},z,T^*,T] = \mathbb{E}[\varepsilon^3|\mathbf{x},z,T^*]$
- (ii) $\mathbb{E}[\varepsilon^3|\mathbf{x},z] = \mathbb{E}[\varepsilon^3|\mathbf{x}]$

Sufficient Condition

- (i) T is conditionally independent of (ε, z) given (T^*, \mathbf{x})
- (ii) z is conditionally independent of ε given **x**

Identification Argument: Step I

Reparameterization

$$\begin{aligned} &\theta_1(\mathbf{x}) = \beta(\mathbf{x})/\left[1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\right] \\ &\theta_2(\mathbf{x}) = \left[\theta_1(\mathbf{x})\right]^2 \left[1 + \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\right] \\ &\theta_3(\mathbf{x}) = \left[\theta_1(\mathbf{x})\right]^3 \left[\left\{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\right\}^2 + 6\alpha_0(\mathbf{x})\left\{1 - \alpha_1(\mathbf{x})\right\}\right] \end{aligned}$$

Theorem

If $\theta_1(\mathbf{x}), \theta_2(\mathbf{x})$ and $\theta_3(\mathbf{x})$ are identified and $\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) < 1$

- ▶ If $\theta_1(\mathbf{x}) \neq 0$, then $\beta(\mathbf{x}), \alpha_0(\mathbf{x})$ and $\alpha_1(\mathbf{x})$ are identified
- If $\theta_1(\mathbf{x}) = 0$ then $\beta(\mathbf{x})$ is identified

If $\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) \neq 1$, then $\beta(\mathbf{x})$ is identified up to sign.

Identification Argument: Step II

Notation

$$\pi(\mathbf{x}) = \mathsf{Cov}(T, z | \mathbf{x}), \quad \eta_j(\mathbf{x}) = \mathsf{Cov}(y^j, z | \mathbf{x}), \quad \tau_j(\mathbf{x}) = \mathsf{Cov}(Ty^j, z | \mathbf{x})$$

Theorem

Baseline plus 2nd and 3rd Moment Assumptions imply

$$\eta_1(\mathbf{x}) = \pi(\mathbf{x})\theta_1(\mathbf{x})
\eta_2(\mathbf{x}) = 2\tau_1(\mathbf{x})\theta_1(\mathbf{x}) - \pi(\mathbf{x})\theta_2(\mathbf{x})
\eta_3(\mathbf{x}) = 3\tau_2(\mathbf{x})\theta_1(\mathbf{x}) - 3\tau_1(\mathbf{x})\theta_2(\mathbf{x}) + \pi(\mathbf{x})\theta_3(\mathbf{x})$$

so $\theta_1(\mathbf{x}), \theta_2(\mathbf{x})$ and $\theta_3(\mathbf{x})$ are identified if $\pi(\mathbf{x}) \neq 0$.

Simple Special Case

Suppose $\alpha_0 = 0$ and No Covariates

$$\mathsf{Cov}(y,z) - \left(\frac{\beta}{1-\alpha_1}\right)\mathsf{Cov}(\mathcal{T},z) = 0$$

$$\mathsf{Cov}(y^2,z) - \frac{\beta}{1-\alpha_1}\left\{2\mathsf{Cov}(y\mathcal{T},z) - \beta\mathsf{Cov}(\mathcal{T},z)\right\} = 0$$

Closed-Form Solution for β

$$\beta = \frac{2\mathsf{Cov}(yT, z)}{\mathsf{Cov}(T, z)} - \frac{\mathsf{Cov}(y^2, z)}{\mathsf{Cov}(y, z)}$$

Unconditional Moment Equalities ($\alpha_0 = 0$, No Covariates)

$$\mathbf{u}_{i}(\boldsymbol{\kappa},\boldsymbol{\theta}) = \begin{bmatrix} y_{i} - \kappa_{1} - \theta_{1}T_{i} \\ y_{i}^{2} - \kappa_{2} - \theta_{1}2y_{i}T_{i} + \theta_{2}T_{i} \end{bmatrix}, \quad \mathbb{E}\begin{bmatrix} \mathbf{u}_{i}(\boldsymbol{\kappa},\boldsymbol{\theta}) \\ \mathbf{u}_{i}(\boldsymbol{\kappa},\boldsymbol{\theta})z_{i} \end{bmatrix} = \mathbf{0}$$

$$\theta_1 = \beta/(1 - \alpha_1)$$

$$\theta_2 = \beta^2/(1 - \alpha_1)$$

$$\kappa_1 = c$$

$$\kappa_2 = c^2 + \sigma_s^2$$

What happens if we try standard GMM inference?

Simulation DGP: $y = \beta T^* + \varepsilon$

Errors

 $(\varepsilon, \eta) \sim$ jointly normal, mean 0, variance 1, correlation 0.5.

First-Stage

- ▶ Half of individuals have z = 1, the rest have z = 0.
- ► $T^* = \mathbf{1} \{ \gamma_0 + \gamma_1 z + \eta > 0 \}$
- $\delta = \mathbb{P}(T^* = 0|z = 1) = \mathbb{P}(T^* = 1|z = 0) = 0.15$

Mis-classification

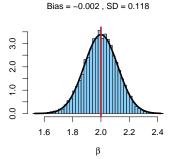
- ▶ Set $\alpha_0 = 0$
- $ightharpoonup T | T^* = 1 \sim \mathsf{Bernoulli}(1 \alpha_1)$

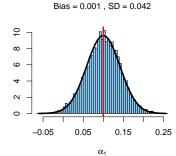
Coverage and Width of Nominal 95% GMM CIs

 $\alpha_1=$ 0.1, $\delta=$ 0.15, n= 1000, $\rho=$ 0.5, 5000 simulation replications

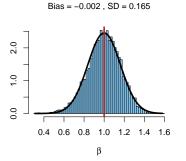
β	Coverage	Median Width
2.00	0.95	0.23
1.50	0.95	0.26
1.00	0.95	0.32
0.50	0.96	0.55
0.25	0.98	1.08
0.20	0.99	1.40
0.15	0.99	1.86
0.10	1.00	3.04
0.05	1.00	4.76
0.01	1.00	5.92

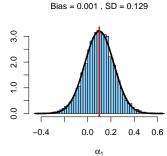
$$\beta = 2$$
, $\alpha_1 = 0.1$, $\delta = 0.15$, $n = 1000$



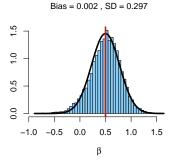


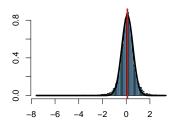
$$\beta = 1$$
, $\alpha_1 = 0.1$, $\delta = 0.15$, $n = 1000$





$$\beta = 0.5, \, \alpha_1 = 0.1, \, \delta = 0.15, \, n = 1000$$





Bias = -0.012, SD = 0.616

 α_1

Weak Identification Problem

Illustrated for $\alpha_0 = 0$ but holds generally

$$\mathbf{u}_{i}(\kappa,\theta) = \begin{bmatrix} y_{i} - \kappa_{1} - \theta_{1}T_{i} \\ y_{i}^{2} - \kappa_{2} - \theta_{1}2y_{i}T_{i} + \theta_{2}T_{i} \end{bmatrix}, \quad \mathbb{E}\begin{bmatrix} \mathbf{u}_{i}(\kappa,\theta) \\ \mathbf{u}_{i}(\kappa,\theta)z_{i} \end{bmatrix} = \mathbf{0}$$

$$\theta_1 = \beta/(1-\alpha_1), \quad \theta_2 = \beta^2/(1-\alpha_1)$$

- β small \Rightarrow moment equalities uninformative about α_1
- Same problem for other estimators from the literature but hasn't been pointed out.
- ▶ Identification robust inference: GMM Anderson-Rubin Test
- But we can do better...

Auxiliary Moment Inequalities

General Case $\alpha_0 \neq 0$

Law of Total Probability

$$\mathbb{P}(T^* = 1 | z = k) = \frac{\mathbb{P}(T = 1 | z = k) - \alpha_0}{1 - \alpha_0 - \alpha_1}, \quad \mathbb{P}(T^* = 0 | z = k) = \frac{\mathbb{P}(T = 0 | z = k) - \alpha_1}{1 - \alpha_0 - \alpha_1}$$

$$Cor(T, T^*) > 0$$

$$\iff \alpha_0 + \alpha_1 < 1 \iff 1 - \alpha_0 - \alpha_1 > 0$$

Implications

- $\qquad \qquad \alpha_0 < \min_k \mathbb{P}(T = 1|z = k), \quad \alpha_1 < \min_k \mathbb{P}(T = 0|z = k)$
- \blacktriangleright β is between β_{RF} and β_{IV}
- \triangleright β_{IV} inflated but has correct sign

Even Tighter Bounds for α_0, α_1 from Conditional Variances

Assume

$$\mathbb{E}[\varepsilon^2|T^*,T,z] = \mathbb{E}[\varepsilon^2|T^*,z]$$

Observables

$$\sigma_{tk}^2 = \mathsf{Var}(y|T=t, z=k)$$

Constrain Unobservables

$$s_{tk}^{*2} = Var(u|T^* = t, z_k) > 0$$

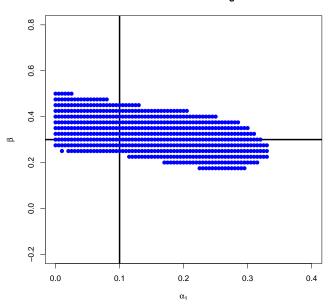
$$(p_k - \alpha_0) \left[(1 - \alpha_0) p_k \sigma_{1k}^2 - \alpha_0 (1 - p_k) \sigma_{0k}^2 \right] > \alpha_0 (1 - \alpha_0) p_k (1 - p_k) (\bar{y}_{1k} - \bar{y}_{0k})^2$$

$$(1 - p_k - \alpha_1) \left[(1 - \alpha_1) (1 - p_k) \sigma_{0k}^2 - \alpha_1 p_k \sigma_{1k}^2 \right] > \alpha_1 (1 - \alpha_1) p_k (1 - p_k) (\bar{y}_{1k} - \bar{y}_{0k})^2$$

Identification-Robust Joint Inference for $(\alpha_0, \alpha_1, \beta)$

- Auxiliary moment inequalities to bound (α_0, α_1)
- ▶ Joint CS for $(\alpha_0, \alpha_1, \beta)$ by inverting Anderson-Rubin Test
- ▶ Marginal inference for β by projection.
- Generalized Moment Selection (Andrews & Soares, 2010) for tighter confidence sets.
- Results are preliminary (not exploiting full set of inequalities) but this approach seems to work extremely well.

95% GMS Confidence Region



Conclusion

- ► Endogenous, mis-measured binary treatment.
- Important in applied work but no solution in the literature.
- lacktriangle Usual (1st moment) IV assumption fails to identify eta
- ▶ Higher moment / independence restrictions identify β
- Identification-Robust Inference incorportating additional inequality moment conditions.