# Estimating the Effect of a Mis-measured, Endogenous, Binary Regressor

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## Additively Separable Model

$$y = h(T^*, \mathbf{x}) + \varepsilon$$

- ▶ y − Outcome of interest
- ► *h* − Known or unknown function
- ▶ T\* Unobserved, endogenous binary regressor
- ► T Observed, mis-measured binary surrogate for T\*
- x Exogenous covariates
- $\triangleright$   $\varepsilon$  Mean-zero error term

### What is the Effect of $T^*$ ?

#### Re-write the Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon$$
$$\beta(\mathbf{x}) = h(1, \mathbf{x}) - h(0, \mathbf{x})$$
$$c(\mathbf{x}) = h(0, \mathbf{x})$$

### This Paper:

- ▶ Does a discrete instrument z (typically binary) identify  $\beta(x)$ ?
- ▶ What assumptions are required for z and the surrogate T?
- ▶ How to carry out inference for a mis-classified regressor?

## Example: Job Training Partnership Act (JPTA)

Heckman et al. (2000, QJE)

Randomized offer of job training, but about 30% of those *not* offered also obtain training and about 40% of those offered training don't attend. Estimate causal effect of *training* rather than *offer* of training.

- y − Log wage
- ▶ T\* True training attendence
- ➤ T Self-reported training attendance
- x Individual characteristics
- $\triangleright$  z Offer of job training

#### Related Literature

#### Continuous Treatment

Lewbel (1997, 2012), Schennach (2004, 2007), Chen et al. (2005), Hu & Schennach (2008), Song (2015), Hu et al. (2015)...

### Binary, Exogenous Treatment

Aigner (1973), Bollinger (1996), Kane et al. (1999), Black et al. (2000), Frazis & Loewenstein (2003), Mahajan (2006), Lewbel (2007), Hu (2008)

### Binary, Endogenous Treatment

Mahajan (2006), Shiu (2015), Ura (2015), Denteh et al. (2016)

## Baseline Assumptions – Maintained Throughout

### Additively Separable Model

$$y = c(\mathbf{x}) + \beta(\mathbf{x})T^* + \varepsilon, \quad \mathbb{E}[\varepsilon] = 0$$

#### Valid & Relevant Instrument

$$\mathbb{E}[\varepsilon|\mathbf{x},z] = 0, \quad \mathbb{E}\left[T^*|\mathbf{x},z=k\right] \neq \mathbb{E}\left[T^*|\mathbf{x},z=\ell\right]$$

### Measurement Error Assumptions

- (i)  $\mathbb{E}[\varepsilon|\mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon|\mathbf{x}, z, T^*]$
- (ii)  $\alpha_0(\mathbf{x}) = \mathbb{P}(T = 1 | T^* = 0, \mathbf{x}, z), \quad \alpha_1(\mathbf{x}) = \mathbb{P}(T = 0 | T^* = 1, \mathbf{x}, z)$
- (iii)  $\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) < 1$  (T is positively correlated with  $T^*$ )

#### **Theorem**

The baseline assumptions fail to identify  $\beta(\mathbf{x})$ , even if the instrument z takes on an arbitrarily large finite number of distinct values.

## Identification from Stronger Assumptions?

### Second Moment Assumption

- (i)  $\mathbb{E}[\varepsilon^2|\mathbf{x}, z, T^*, T] = \mathbb{E}[\varepsilon^2|\mathbf{x}, z, T^*]$
- (ii)  $\mathbb{E}[\varepsilon^2|\mathbf{x},z] = \mathbb{E}[\varepsilon^2|\mathbf{x}]$

### Third Moment Assumption

- (i)  $\mathbb{E}[\varepsilon^3|\mathbf{x},z,T^*,T] = \mathbb{E}[\varepsilon^3|\mathbf{x},z,T^*]$
- (ii)  $\mathbb{E}[\varepsilon^3|\mathbf{x},z] = \mathbb{E}[\varepsilon^3|\mathbf{x}]$

#### Sufficient Condition

- (i) T is conditionally independent of  $(\varepsilon, z)$  given  $(T^*, \mathbf{x})$
- (ii) z is conditionally independent of  $\varepsilon$  given **x**

## Identification Argument: Step I

### Reparameterization

$$\begin{aligned} &\theta_1(\mathbf{x}) = \beta(\mathbf{x})/\left[1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\right] \\ &\theta_2(\mathbf{x}) = \left[\theta_1(\mathbf{x})\right]^2 \left[1 + \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\right] \\ &\theta_3(\mathbf{x}) = \left[\theta_1(\mathbf{x})\right]^3 \left[\left\{1 - \alpha_0(\mathbf{x}) - \alpha_1(\mathbf{x})\right\}^2 + 6\alpha_0(\mathbf{x})\left\{1 - \alpha_1(\mathbf{x})\right\}\right] \end{aligned}$$

#### **Theorem**

If  $\theta_1(\mathbf{x}), \theta_2(\mathbf{x})$  and  $\theta_3(\mathbf{x})$  are identified and  $\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) < 1$ 

- ▶ If  $\theta_1(\mathbf{x}) \neq 0$ , then  $\beta(\mathbf{x}), \alpha_0(\mathbf{x})$  and  $\alpha_1(\mathbf{x})$  are identified
- If  $\theta_1(\mathbf{x}) = 0$  then  $\beta(\mathbf{x})$  is identified

If  $\alpha_0(\mathbf{x}) + \alpha_1(\mathbf{x}) \neq 1$ , then  $\beta(\mathbf{x})$  is identified up to sign.

## Identification Argument: Step II

#### Notation

$$\pi(\mathbf{x}) = \mathsf{Cov}(T, z | \mathbf{x}), \quad \eta_j(\mathbf{x}) = \mathsf{Cov}(y^j, z | \mathbf{x}), \quad \tau_j(\mathbf{x}) = \mathsf{Cov}(Ty^j, z | \mathbf{x})$$

#### **Theorem**

Baseline plus 2nd and 3rd Moment Assumptions imply

$$\eta_1(\mathbf{x}) = \pi(\mathbf{x})\theta_1(\mathbf{x}) 
\eta_2(\mathbf{x}) = 2\tau_1(\mathbf{x})\theta_1(\mathbf{x}) - \pi(\mathbf{x})\theta_2(\mathbf{x}) 
\eta_3(\mathbf{x}) = 3\tau_2(\mathbf{x})\theta_1(\mathbf{x}) - 3\tau_1(\mathbf{x})\theta_2(\mathbf{x}) + \pi(\mathbf{x})\theta_3(\mathbf{x})$$

so  $\theta_1(\mathbf{x}), \theta_2(\mathbf{x})$  and  $\theta_3(\mathbf{x})$  are identified if  $\pi(\mathbf{x}) \neq 0$ .

## Simple Special Case

Suppose  $\alpha_0 = 0$  and No Covariates

$$\mathsf{Cov}(y,z) - \left(\frac{\beta}{1-\alpha_1}\right)\mathsf{Cov}(T,z) = 0$$
 
$$\mathsf{Cov}(y^2,z) - \frac{\beta}{1-\alpha_1}\left\{2\mathsf{Cov}(yT,z) - \beta\mathsf{Cov}(T,z)\right\} = 0$$

Closed-Form Solution for  $\beta$ 

$$\beta = \frac{2\mathsf{Cov}(yT, z)}{\mathsf{Cov}(T, z)} - \frac{\mathsf{Cov}(y^2, z)}{\mathsf{Cov}(y, z)}$$

# Unconditional Moment Equalities ( $\alpha_0 = 0$ , No Covariates)

$$\mathbf{u}_{i}(\boldsymbol{\kappa},\boldsymbol{\theta}) = \begin{bmatrix} y_{i} - \kappa_{1} - \theta_{1}T_{i} \\ y_{i}^{2} - \kappa_{2} - \theta_{1}2y_{i}T_{i} + \theta_{2}T_{i} \end{bmatrix}, \quad \mathbb{E}\begin{bmatrix} \mathbf{u}_{i}(\boldsymbol{\kappa},\boldsymbol{\theta}) \\ \mathbf{u}_{i}(\boldsymbol{\kappa},\boldsymbol{\theta})z_{i} \end{bmatrix} = \mathbf{0}$$

$$\theta_1 = \beta/(1 - \alpha_1)$$

$$\theta_2 = \beta^2/(1 - \alpha_1)$$

$$\kappa_1 = c$$

$$\kappa_2 = c^2 + \sigma_s^2$$

What happens if we try standard GMM inference?

## Simulation DGP: $y = \beta T^* + \varepsilon$

#### **Errors**

 $(\varepsilon, \eta) \sim$  jointly normal, mean 0, variance 1, correlation 0.5.

### First-Stage

- ▶ Half of individuals have z = 1, the rest have z = 0.
- ►  $T^* = \mathbf{1} \{ \gamma_0 + \gamma_1 z + \eta > 0 \}$
- $\delta = \mathbb{P}(T^* = 0|z = 1) = \mathbb{P}(T^* = 1|z = 0) = 0.15$

#### Mis-classification

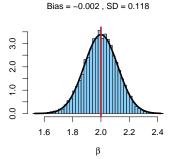
- ▶ Set  $\alpha_0 = 0$
- $ightharpoonup T | T^* = 1 \sim \mathsf{Bernoulli}(1 \alpha_1)$

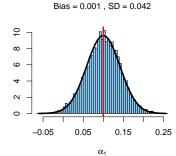
## Coverage and Width of Nominal 95% GMM CIs

 $\alpha_1=$  0.1,  $\delta=$  0.15, n= 1000,  $\rho=$  0.5, 5000 simulation replications

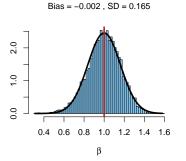
β	Coverage	Median Width
2.00	0.95	0.23
1.50	0.95	0.26
1.00	0.95	0.32
0.50	0.96	0.55
0.25	0.98	1.08
0.20	0.99	1.40
0.15	0.99	1.86
0.10	1.00	3.04
0.05	1.00	4.76
0.01	1.00	5.92

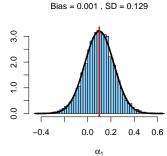
$$\beta = 2$$
,  $\alpha_1 = 0.1$ ,  $\delta = 0.15$ ,  $n = 1000$ 



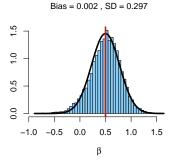


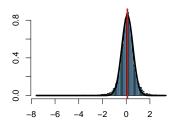
$$\beta = 1$$
,  $\alpha_1 = 0.1$ ,  $\delta = 0.15$ ,  $n = 1000$ 





$$\beta = 0.5, \, \alpha_1 = 0.1, \, \delta = 0.15, \, n = 1000$$





Bias = -0.012, SD = 0.616

 $\alpha_1$ 

### Weak Identification Problem

Illustrated for  $\alpha_0 = 0$  but holds generally

$$\mathbf{u}_{i}(\kappa,\theta) = \begin{bmatrix} y_{i} - \kappa_{1} - \theta_{1}T_{i} \\ y_{i}^{2} - \kappa_{2} - \theta_{1}2y_{i}T_{i} + \theta_{2}T_{i} \end{bmatrix}, \quad \mathbb{E}\begin{bmatrix} \mathbf{u}_{i}(\kappa,\theta) \\ \mathbf{u}_{i}(\kappa,\theta)z_{i} \end{bmatrix} = \mathbf{0}$$

$$\theta_1 = \beta/(1-\alpha_1), \quad \theta_2 = \beta^2/(1-\alpha_1)$$

- $\beta$  small  $\Rightarrow$  moment equalities uninformative about  $\alpha_1$
- Same problem for other estimators from the literature but hasn't been pointed out.
- ▶ Identification robust inference: GMM Anderson-Rubin statistic
- But we can do better...

## "Weak" Bounds for $\alpha_0, \alpha_1$

General Case  $\alpha_0 \neq 0$ 

Law of Total Probability

$$p_k^* = \frac{p_k - \alpha_0}{1 - \alpha_0 - \alpha_1}, \quad 1 - p_k^* = \frac{1 - p_k - \alpha_1}{1 - \alpha_0 - \alpha_1}$$
where  $p_k = \mathbb{P}(T = 1|z = k), \quad p_k^* = \mathbb{P}(T^* = 1|z = k)$ 

$$\operatorname{Cor}(T, T^*) > 0$$

$$\iff \alpha_0 + \alpha_1 < 1 \iff 1 - \alpha_0 - \alpha_1 > 0$$

### **Implications**

- $\blacktriangleright$   $\beta$  is between  $\beta_{RF}$  and  $\beta_{IV}$
- $ightharpoonup eta_{IV}$  inflated but has correct sign

## Second Moment Bounds for $\alpha_0, \alpha_1$

#### Observables

$$\sigma_{tk}^2 = \mathsf{Var}(y|T=t,z_k), \quad \mu_{tk} = \mathbb{E}[y|T=t,z_k], \quad p_k = \mathbb{P}(T=1|z_k)$$

#### Constraint on Unobservables

$$\operatorname{Var}(arepsilon | T^* = t, z_k) > 0$$

### Equivalent To

$$(p_k - \alpha_0) \left[ \left( \frac{1 - \alpha_0}{1 - p_k} \right) \sigma_{1k}^2 - \left( \frac{\alpha_0}{p_k} \right) \sigma_{0k}^2 \right] > \alpha_0 (1 - \alpha_0) (\mu_{1k} - \mu_{0k})^2$$

$$(1 - p_k - \alpha_1) \left[ \left( \frac{1 - \alpha_1}{p_k} \right) \sigma_{0k}^2 - \left( \frac{\alpha_1}{1 - p_k} \right) \sigma_{1k}^2 \right] > \alpha_1 (1 - \alpha_1) (\mu_{1k} - \mu_{0k})^2$$

## Bounds can be very informative in practice. . .

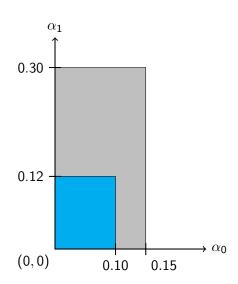
Figure based on data from Burde & Linden (2013)

"Weak" Bounds

$$\beta \in [0.65 \times \beta_{IV}, \ \beta_{IV}]$$

Add 2nd Moments

$$\beta \in [0.78 \times \beta_{IV}, \ \beta_{IV}]$$



## Adding Auxiliary Moment Inequalities

- ▶ Bounds for  $(\alpha_0, \alpha_1)$  immune to weak identification problem: remain informative if  $\beta$  is small or zero.
- 2nd moment bounds strictly tighter, but still need weak bounds to determine which root of quadratic is extraneous.
- ▶ Since  $\beta = 1/(1 \alpha_0 \alpha_1)$  is identified by TSLS, get meaningful restrictions on  $\beta$ .
- Inference using Generalized Moment Selection (Andrews & Soares, 2010)

## Inference With Moment Equalities and Inequalities

#### Moment Conditions

$$\mathbb{E}\left[m_j(\mathbf{w}_i, \theta_0)\right] = 0, \quad j = 1, \dots, p$$

$$\mathbb{E}\left[m_j(\mathbf{w}_i, \theta_0)\right] \ge 0, \quad j = p + 1, \dots, p + v$$

#### Test Statistic

$$T_n(\theta) = \sum_{j=1}^{p} \left[ \frac{\sqrt{n} \ \bar{m}_{n,j}(\theta)}{\widehat{\sigma}_{n,j}(\theta)} \right]_{-}^{2} + \sum_{j=p+1}^{p+\nu} \left[ \frac{\sqrt{n} \ \bar{m}_{n,j}(\theta)}{\widehat{\sigma}_{n,j}(\theta)} \right]^{2}$$

$$\begin{split} [x]_- &= \min \left\{ x, 0 \right\} \\ \bar{m}_{n,j}(\theta) &= n^{-1} \sum_{i=1}^n m_j(\mathbf{w}_i, \theta) \\ \widehat{\sigma}_{n,j}^2(\theta) &= \text{consistent est. of AVAR} \left[ \sqrt{n} \; \bar{m}_{n,j}(\theta) \right] \end{split}$$

### Inference via Generalized Moment Selection

Andrews & Soares (2010)

### Moment Selection Step

If 
$$\frac{\sqrt{n}\,\bar{m}_{n,j}(\theta_0)}{\widehat{\sigma}_{n,j}(\theta_0)}>\sqrt{\ln n}$$
 then drop inequality  $j$ 

#### Critical Value

- lacksquare  $\sqrt{n}\,ar{m}_n( heta_0) o_d$  normal limit with covariance matrix  $\Sigma( heta_0)$
- Use this to bootstrap the limit distribution of the test statistic.

#### Theoretical Guarantees

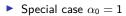
Uniformly valid test of  $H_0$ :  $\theta = \theta_0$  that is *not* asymptotically conservative.

## Confidence Regions

- ▶ Invert test of  $\theta = \theta_0$  to form confidence region
- lacktriangle Preliminary estimation of strongly identified parameters  $(\kappa)$
- Yields *joint* inference for  $(\alpha_0, \alpha_0, \beta)$
- ▶ Projection to get inference for  $\beta$ , but can be conservative

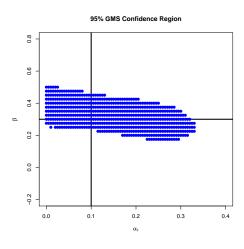
## Simple Example: n = 1000

#### Simulation DGP from earlier in talk



$$\beta = 0.25, \, \alpha_1 = 0.1$$

- ▶ Reduced Form  $\approx 0.18$
- ▶ Wald  $\approx 0.28$
- Only "weak" bounds
- Naive GMM Median Width  $\approx 1.1!$



### Additional Simulations: Size of GMS Test

Same DGP as earlier in the talk except  $\alpha_0$  is not zero, and use full set of inequalities. . .

### Conclusion

- ► Endogenous, mis-measured binary treatment.
- Important in applied work but no solution in the literature.
- Usual (1st moment) IV assumption fails to identify  $\beta$
- ▶ Higher moment / independence restrictions identify  $\beta$
- Identification-Robust Inference incorportating additional inequality moment conditions.