

# Econ 722 – Advanced Econometrics IV

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# Lecture #1 – Decision Theory

Statistical Decision Theory

The James-Stein Estimator

# Decision Theoretic Preliminaries

Parameter  $\theta \in \Theta$

Unknown state of nature, from parameter space  $\Theta$

Observed Data

Observe  $X$  with distribution  $F_\theta$  from a sample space  $\mathcal{X}$

Estimator  $\hat{\theta}$

An estimator (aka a decision rule) is a function from  $\mathcal{X}$  to  $\Theta$

Loss Function  $L(\theta, \hat{\theta})$

A function from  $\Theta \times \Theta$  to  $\mathbb{R}$  that gives the cost we incur if we report  $\hat{\theta}$  when the true state of nature is  $\theta$ .

## Examples of Loss Functions

$$L(\theta, \hat{\theta}) = (\theta - \hat{\theta})^2$$

squared error loss

$$L(\theta, \hat{\theta}) = |\theta - \hat{\theta}|$$

absolute error loss

$$L(\theta, \hat{\theta}) = 0 \text{ if } \theta = \hat{\theta}, 1 \text{ otherwise}$$

zero-one loss

$$L(\theta, \hat{\theta}) = \int \log \left[ \frac{f(x|\theta)}{f(x|\hat{\theta})} \right] f(x|\theta) dx$$

Kullback–Leibler loss

## (Frequentist) Risk of an Estimator $\hat{\theta}$

$$R(\theta, \hat{\theta}) = \mathbb{E}_{\theta} [L(\theta, \hat{\theta})] = \int L(\theta, \hat{\theta}(x)) dF_{\theta}(x)$$

*The frequentist decision theorist seeks to evaluate, for each  $\theta$ , how much he would “expect” to lose if he used  $\hat{\theta}(X)$  repeatedly with varying  $X$  in the problem.*

*(Berger, 1985)*

### Example: Squared Error Loss

$$R(\theta, \hat{\theta}) = \mathbb{E}_{\theta} [(\theta - \hat{\theta})^2] = \text{MSE} = \text{Var}(\hat{\theta}) + \text{Bias}_{\theta}^2(\hat{\theta})$$

# Bayes Risk and Maximum Risk

## Comparing Risk

$R(\theta, \hat{\theta})$  is a *function* of  $\theta$  rather than a single number. We want an estimator with low risk, but how can we compare?

## Maximum Risk

$$\bar{R}(\hat{\theta}) = \sup_{\theta \in \Theta} R(\theta, \hat{\theta})$$

## Bayes Risk

$$r(\pi, \hat{\theta}) = \mathbb{E}_{\pi} \left[ R(\theta, \hat{\theta}) \right], \text{ where } \pi \text{ is a prior for } \theta$$

# Bayes and Minimax Rules

Minimize the Maximum or Bayes risk over all estimators  $\tilde{\theta}$

## Minimax Rule/Estimator

$\hat{\theta}$  is **minimax** if

$$\sup_{\theta \in \Theta} R(\theta, \hat{\theta}) = \inf_{\tilde{\theta}} \sup_{\theta \in \Theta} R(\theta, \tilde{\theta})$$

## Bayes Rule/Estimator

$\hat{\theta}$  is a **Bayes rule** with respect to prior  $\pi$  if

$$r(\pi, \hat{\theta}) = \inf_{\tilde{\theta}} r(\pi, \tilde{\theta})$$

## Recall: Bayes' Theorem and Marginal Likelihood

Let  $\pi$  be a prior for  $\theta$ . By Bayes' theorem, the **posterior**  $\pi(\theta|\mathbf{x})$  is

$$\pi(\theta|\mathbf{x}) = \frac{f(\mathbf{x}|\theta)\pi(\theta)}{m(\mathbf{x})}$$

where the **marginal likelihood**  $m(\mathbf{x})$  is given by

$$m(\mathbf{x}) = \int f(\mathbf{x}|\theta)\pi(\theta) d\theta$$



# Posterior Expected Loss

## Posterior Expected Loss

$$\rho(\pi(\theta|\mathbf{x}), \hat{\theta}) = \int L(\theta, \hat{\theta}) \pi(\theta|\mathbf{x}) d\theta$$

## Bayesian Decision Theory

Choose an estimator that minimizes posterior expected loss.

## Easier Calculation

Since  $m(\mathbf{x})$  does not depend on  $\theta$ , to minimize  $\rho(\pi(\theta|\mathbf{x}), \hat{\theta})$  it suffices to minimize  $\int L(\theta, \hat{\theta}) f(\mathbf{x}|\theta) \pi(\theta) d\theta$ .

## Question

Is there a relationship between Bayes risk,  $r(\pi, \hat{\theta}) \equiv \mathbb{E}_{\pi}[R(\theta, \hat{\theta})]$ , and posterior expected loss?

# Bayes Risk vs. Posterior Expected Loss

## Theorem

$$r(\pi, \hat{\theta}) = \int \rho(\pi(\theta|\mathbf{x}), \hat{\theta}(\mathbf{x})) m(\mathbf{x}) d\mathbf{x}$$

## Proof

$$\begin{aligned} r(\pi, \hat{\theta}) &= \int R(\theta, \hat{\theta}) \pi(\theta) d\theta = \int \left[ \int L(\theta, \hat{\theta}(\mathbf{x})) f(\mathbf{x}|\theta) d\mathbf{x} \right] \pi(\theta) d\theta \\ &= \int \int L(\theta, \hat{\theta}(\mathbf{x})) [f(\mathbf{x}|\theta) \pi(\theta)] d\mathbf{x} d\theta \\ &= \int \int L(\theta, \hat{\theta}(\mathbf{x})) [\pi(\theta|\mathbf{x}) m(\mathbf{x})] d\mathbf{x} d\theta \\ &= \int \left[ \int L(\theta, \hat{\theta}(\mathbf{x})) \pi(\theta|\mathbf{x}) d\theta \right] m(\mathbf{x}) d\mathbf{x} \\ &= \int \rho(\pi(\theta|\mathbf{x}), \hat{\theta}(\mathbf{x})) m(\mathbf{x}) d\mathbf{x} \end{aligned}$$

# Finding a Bayes Estimator

## Hard Problem

Find the **function**  $\hat{\theta}(\mathbf{x})$  that minimizes  $r(\pi, \hat{\theta})$ .

## Easy Problem

Find the **number**  $\hat{\theta}$  that minimizes  $\rho(\pi(\theta|\mathbf{x}), \hat{\theta})$

## Punchline

Since  $r(\pi, \hat{\theta}) = \int \rho(\pi(\theta|\mathbf{x}), \hat{\theta}(\mathbf{x})) m(\mathbf{x}) d\mathbf{x}$ , to minimize  $r(\pi, \hat{\theta})$  we can set  $\hat{\theta}(\mathbf{x})$  to be the value  $\hat{\theta}$  that minimizes  $\rho(\pi(\theta|\mathbf{x}), \hat{\theta})$ .

# Bayes Estimators for Common Loss Functions

## Zero-one Loss

For zero-one loss, the Bayes estimator is the posterior mode.

Absolute Error Loss:  $L(\theta, \hat{\theta}) = |\theta - \hat{\theta}|$

For absolute error loss, the Bayes estimator is the posterior median.

Squared Error Loss:  $L(\theta, \hat{\theta}) = (\theta - \hat{\theta})^2$

For squared error loss, the Bayes estimator is the posterior mean.

# Derivation of Bayes Estimator for Squared Error Loss

By definition,

$$\hat{\theta} \equiv \arg \min_{a \in \Theta} \int (\theta - a)^2 \pi(\theta | \mathbf{x}) d\theta$$

Differentiating with respect to  $a$ , we have

$$\begin{aligned} 2 \int (\theta - a) \pi(\theta | \mathbf{x}) d\theta &= 0 \\ \int \theta \pi(\theta | \mathbf{x}) d\theta &= a \end{aligned}$$

## Example: Bayes Estimator for a Normal Mean

Suppose  $X \sim N(\mu, 1)$  and  $\pi$  is a  $N(a, b^2)$  prior. Then,

$$\begin{aligned}\pi(\mu|x) &\propto f(x|\mu) \times \pi(\mu) \\ &\propto \exp \left\{ -\frac{1}{2} \left[ (x - \mu)^2 + \frac{1}{b^2} (\mu - a)^2 \right] \right\} \\ &\propto \exp \left\{ -\frac{1}{2} \left[ \left( 1 + \frac{1}{b^2} \right) \mu^2 - 2 \left( x + \frac{a}{b^2} \right) \mu \right] \right\} \\ &\propto \exp \left\{ -\frac{1}{2} \left( \frac{b^2 + 1}{b^2} \right) \left[ \mu - \left( \frac{b^2 x + a}{b^2 + 1} \right) \right]^2 \right\}\end{aligned}$$

So  $\pi(\mu|x)$  is  $N(m, \omega^2)$  with  $\omega^2 = \frac{b^2}{1+b^2}$  and  $m = \omega^2 x + (1 - \omega^2)a$ .

Hence the Bayes estimator for  $\mu$  under squared error loss is

$$\hat{\theta}(X) = \frac{b^2 X + a}{1 + b^2}$$

# Minimax Analysis

## Wasserman (2004)

*The advantage of using maximum risk, despite its problems, is that it does not require one to choose a prior.*

## Berger (1986)

*Perhaps the greatest use of the minimax principle is in situations for which no prior information is available . . . but two notes of caution should be sounded. First, the minimax principle can lead to bad decision rules. . . Second, the minimax approach can be devilishly hard to implement.*

# Methods for Finding a Minimax Estimator

1. Direct Calculation
2. Guess a “Least Favorable” Prior
3. Search for an “Equalizer Rule”

Method 1 rarely applicable so focus on 2 and 3...



# The Bayes Rule for a Least Favorable Prior is Minimax

## Theorem

Let  $\hat{\theta}$  be a Bayes rule with respect to  $\pi$  and suppose that for all  $\theta \in \Theta$  we have  $R(\theta, \hat{\theta}) \leq r(\pi, \hat{\theta})$ . Then  $\hat{\theta}$  is a **minimax estimator**, and  $\pi$  is called a **least favorable prior**.

## Proof

Suppose that  $\hat{\theta}$  is not minimax. Then there exists another estimator  $\tilde{\theta}$  with  $\sup_{\theta \in \Theta} R(\theta, \tilde{\theta}) < \sup_{\theta \in \Theta} R(\theta, \hat{\theta})$ . But since

$$r(\pi, \tilde{\theta}) \equiv \mathbb{E}_{\pi} [R(\theta, \tilde{\theta})] \leq \mathbb{E}_{\pi} \left[ \sup_{\theta \in \Theta} R(\theta, \tilde{\theta}) \right] = \sup_{\theta \in \Theta} R(\theta, \tilde{\theta})$$

but this implies that  $\tilde{\theta}$  is *not* Bayes with respect to  $\pi$  since

$$r(\pi, \tilde{\theta}) \leq \sup_{\theta \in \Theta} R(\theta, \tilde{\theta}) < \sup_{\theta \in \Theta} R(\theta, \hat{\theta}) \leq r(\pi, \hat{\theta})$$

# Example of Least Favorable Prior

## Bounded Normal Mean

- ▶  $X \sim N(\theta, 1)$
- ▶ Squared error loss
- ▶  $\Theta = [-m, m]$  for  $0 < m < 1$

## Least Favorable Prior

$\pi(\theta) = 1/2$  for  $\theta \in \{-m, m\}$ , zero otherwise.

## Resulting Bayes Rule is Minimax

$$\hat{\theta}(X) = m \tanh(mX) = m \left[ \frac{\exp\{mX\} - \exp\{-mX\}}{\exp\{mX\} + \exp\{-mX\}} \right]$$

# Equalizer Rules

## Definition

An estimator  $\hat{\theta}$  is called an **equalizer rule** if its risk function is constant:  $R(\theta, \hat{\theta}) = C$  for some  $C$ .

## Theorem

If  $\hat{\theta}$  is an equalizer rule and is Bayes with respect to  $\pi$ , then  $\hat{\theta}$  is **minimax** and  $\pi$  is **least favorable**.

## Proof

$$r(\pi, \hat{\theta}) = \int R(\theta, \hat{\theta}) \pi(\theta) d\theta = \int C \pi(\theta) d\theta = C$$

Hence,  $R(\theta, \hat{\theta}) \leq r(\pi, \hat{\theta})$  for all  $\theta$  so we can apply the preceding theorem.

Example:  $X_1, \dots, X_n \sim \text{iid Bernoulli}(p)$

Under a  $\text{Beta}(\alpha, \beta)$  prior with  $\alpha = \beta = \sqrt{n}/2$ ,

$$\hat{p}(\mathbf{x}) = \frac{n\bar{X} + \sqrt{n}/2}{n + \sqrt{n}}$$

is the Bayesian posterior mean, hence the Bayes rule under squared error loss. The risk function of  $\hat{p}$  is,

$$R(p, \hat{p}) = \frac{n}{4(n + \sqrt{n})^2}$$

which is constant in  $p$ . Hence,  $\hat{p}$  is an equalizer rule, and by the preceding theorem is minimax.

# Problems with the Minimax Principle



In the left panel,  $\tilde{\theta}$  is preferred by the minimax principle; in the right panel  $\hat{\theta}$  is preferred. But the only difference between them is that the right panel adds an additional *fixed* loss of 1 for  $1 \leq \theta \leq 2$ .

## Problems with the Minimax Principle

Suppose that  $\Theta = \{\theta_1, \theta_2\}$ ,  $\mathcal{A} = \{a_1, a_2\}$  and the loss function is:

	$a_1$	$a_2$
$\theta_1$	10	10.01
$\theta_2$	8	-8

- ▶ Minimax principle: choose  $a_1$
- ▶ Bayes: Choose  $a_2$  unless  $\pi(\theta_1) > 0.9994$

Minimax ignores the fact that under  $\theta_1$  we can never do better than a loss of 10, and tries to prevent us from incurring a tiny additional loss of 0.01

# Dominance and Admissibility

## Dominance

$\hat{\theta}$  **dominates**  $\tilde{\theta}$  with respect to  $R$  if  $R(\theta, \hat{\theta}) \leq R(\theta, \tilde{\theta})$  for all  $\theta \in \Theta$  and the inequality is strict for at least one value of  $\theta$ .

## Admissibility

$\hat{\theta}$  is **admissible** if no other estimator dominates it.

## Inadmissibility

$\hat{\theta}$  is **inadmissible** if there is an estimator that dominates it.

## Example of an Admissible Estimator

Say we want to estimate  $\theta$  from  $X \sim N(\theta, 1)$  under squared error loss. Is the estimator  $\hat{\theta}(X) = 3$  admissible?

If not, then there is a  $\tilde{\theta}$  with  $R(\theta, \tilde{\theta}) \leq R(\theta, \hat{\theta})$  for all  $\theta$ . Hence:

$$R(3, \tilde{\theta}) \leq R(3, \hat{\theta}) = \left\{ \mathbb{E} [\hat{\theta} - 3] \right\}^2 + \text{Var}(\hat{\theta}) = 0$$

Since  $R$  cannot be negative for squared error loss,

$$0 = R(3, \tilde{\theta}) = \left\{ \mathbb{E} [\tilde{\theta} - 3] \right\}^2 + \text{Var}(\tilde{\theta})$$

Therefore  $\hat{\theta} = \tilde{\theta}$ , so  $\hat{\theta}$  is admissible, although very silly!



# Bayes Rules are Admissible

## Theorem A-1

Suppose that  $\Theta$  is a discrete set and  $\pi$  gives strictly positive probability to each element of  $\Theta$ . Then, if  $\hat{\theta}$  is a Bayes rule with respect to  $\pi$ , it is admissible.

## Theorem A-2

If a Bayes rule is unique, it is admissible.

## Theorem A-3

Suppose that  $R(\theta, \hat{\theta})$  is continuous in  $\theta$  for all  $\hat{\theta}$  and that  $\pi$  gives strictly positive probability to any open subset of  $\Theta$ . Then if  $\hat{\theta}$  is a Bayes rule with respect to  $\pi$ , it is admissible.

# Admissible Equalizer Rules are Minimax

## Theorem

Let  $\hat{\theta}$  be an equalizer rule. Then if  $\hat{\theta}$  is admissible, it is minimax.

## Proof

Since  $\hat{\theta}$  is an equalizer rule,  $R(\theta, \hat{\theta}) = C$ . Suppose that  $\hat{\theta}$  is not minimax. Then there is a  $\tilde{\theta}$  such that

$$\sup_{\theta \in \Theta} R(\theta, \tilde{\theta}) < \sup_{\theta \in \Theta} R(\theta, \hat{\theta}) = C$$

But for any  $\theta$ ,  $R(\theta, \tilde{\theta}) \leq \sup_{\theta \in \Theta} R(\theta, \tilde{\theta})$ . Thus we have shown that  $\tilde{\theta}$  dominates  $\hat{\theta}$ , so that  $\hat{\theta}$  cannot be admissible.

# Minimax Implies “Nearly” Admissible

## Strong Inadmissibility

We say that  $\hat{\theta}$  is **strongly inadmissible** if there exists an estimator  $\tilde{\theta}$  and an  $\varepsilon > 0$  such that  $R(\theta, \tilde{\theta}) < R(\theta, \hat{\theta}) - \varepsilon$  for all  $\theta$ .

## Theorem

If  $\hat{\theta}$  is minimax, then it is **not** strongly inadmissible.

## Example: Sample Mean, Unbounded Parameter Space

### Theorem

Suppose that  $X_1, \dots, X_n \sim N(\theta, 1)$  with  $\Theta = \mathbb{R}$ . Under squared error loss, one can show that  $\hat{\theta} = \bar{X}$  is admissible.

### Intuition

The proof is complicated, but effectively we view this estimator as a **limit** of a of Bayes estimator with prior  $N(a, b^2)$ , as  $b^2 \rightarrow \infty$ .

### Minimaxity

Since  $R(\theta, \bar{X}) = \text{Var}(\bar{X}) = 1/n$ , we see that  $\bar{X}$  is an equalizer rule. Since it is admissible, it is therefore minimax.

# Recall: Gauss-Markov Theorem

## Linear Regression Model

$$\mathbf{y} = X\beta + \epsilon, \quad \mathbb{E}[\epsilon|X] = \mathbf{0}$$

## Best Linear Unbiased Estimator

- ▶  $\text{Var}(\epsilon|X) = \sigma^2 I \Rightarrow$  then OLS has lowest variance among linear, unbiased estimators of  $\beta$ .
- ▶  $\text{Var}(\epsilon|X) \neq \sigma^2 I \Rightarrow$  then GLS gives a lower variance estimator.

What if we consider biased estimators and squared error loss?

# Multiple Normal Means: $X \sim N(\theta, I)$

## Goal

Estimate the  $p$ -vector  $\theta$  using  $X$  with  $L(\theta, \hat{\theta}) = \|\hat{\theta} - \theta\|^2$ .

## Maximum Likelihood Estimator $\hat{\theta}$

MLE = sample mean, but only one observation:  $\hat{\theta} = X$ .

## Risk of $\hat{\theta}$

$$(\hat{\theta} - \theta)' (\hat{\theta} - \theta) = (X - \theta)' (X - \theta) = \sum_{i=1}^p (X_i - \theta_i)^2 \sim \chi_p^2$$

Since  $\mathbb{E}[\chi_p^2] = p$ , we have  $R(\theta, \hat{\theta}) = p$ .

## Multiple Normal Means: $X \sim N(\theta, I)$

### James-Stein Estimator

$$\hat{\theta}^{JS} = \hat{\theta} \left( 1 - \frac{p-2}{\hat{\theta}'\hat{\theta}} \right) = X - \frac{(p-2)X}{X'X}$$

- ▶ Shrinks components of sample mean vector towards zero
- ▶ More elements in  $\theta \Rightarrow$  more shrinkage
- ▶ MLE close to zero ( $\hat{\theta}'\hat{\theta}$  small) gives more shrinkage

## MSE of James-Stein Estimator

$$\begin{aligned}R(\theta, \hat{\theta}^{JS}) &= \mathbb{E} \left[ (\hat{\theta}^{JS} - \theta)' (\hat{\theta}^{JS} - \theta) \right] \\&= \mathbb{E} \left[ \left\{ (X - \theta) - \frac{(p-2)X}{X'X} \right\}' \left\{ (X - \theta) - \frac{(p-2)X}{X'X} \right\} \right] \\&= \mathbb{E} [(X - \theta)' (X - \theta)] - 2(p-2) \mathbb{E} \left[ \frac{X'(X - \theta)}{X'X} \right] \\&\quad + (p-2)^2 \mathbb{E} \left[ \frac{1}{X'X} \right] \\&= p - 2(p-2) \mathbb{E} \left[ \frac{X'(X - \theta)}{X'X} \right] + (p-2)^2 \mathbb{E} \left[ \frac{1}{X'X} \right]\end{aligned}$$

Using fact that  $R(\theta, \hat{\theta}) = p$



# Simplifying the Second Term

## Writing Numerator as a Sum

$$\mathbb{E} \left[ \frac{X'(X - \theta)}{X'X} \right] = \mathbb{E} \left[ \frac{\sum_{i=1}^p X_i (X_i - \theta_i)}{X'X} \right] = \sum_{i=1}^p \mathbb{E} \left[ \frac{X_i (X_i - \theta_i)}{X'X} \right]$$

For  $i = 1, \dots, p$

$$\mathbb{E} \left[ \frac{X_i (X_i - \theta_i)}{X'X} \right] = \mathbb{E} \left[ \frac{X'X - 2X_i^2}{(X'X)^2} \right]$$

Not obvious: integration by parts, expectation as a  $p$ -fold integral,  $X \sim N(\theta, I)$

## Combining

$$\begin{aligned} \mathbb{E} \left[ \frac{X'(X - \theta)}{X'X} \right] &= \sum_{i=1}^p \mathbb{E} \left[ \frac{X'X - 2X_i^2}{(X'X)^2} \right] = p \mathbb{E} \left[ \frac{1}{X'X} \right] - 2 \mathbb{E} \left[ \frac{\sum_{i=1}^p X_i^2}{(X'X)^2} \right] \\ &= p \mathbb{E} \left[ \frac{1}{X'X} \right] - 2 \mathbb{E} \left[ \frac{X'X}{(X'X)^2} \right] = (p - 2) \mathbb{E} \left[ \frac{1}{X'X} \right] \end{aligned}$$

## The MLE is Inadmissible when $p \geq 3$

$$\begin{aligned} R\left(\theta, \hat{\theta}^{JS}\right) &= p - 2(p-2) \left\{ (p-2) \mathbb{E} \left[ \frac{1}{X'X} \right] \right\} + (p-2)^2 \mathbb{E} \left[ \frac{1}{X'X} \right] \\ &= p - (p-2)^2 \mathbb{E} \left[ \frac{1}{X'X} \right] \end{aligned}$$

- ▶  $\mathbb{E}[1/(X'X)]$  exists and is positive whenever  $p \geq 3$
- ▶  $(p-2)^2$  is always positive
- ▶ Hence, second term in the MSE expression is *negative*
- ▶ First term is MSE of the MLE

Therefore James-Stein strictly dominates MLE whenever  $p \geq 3$ !

## James-Stein More Generally

- ▶ Our example was specific, but the result is general:
  - ▶ MLE is inadmissible under quadratic loss in regression model with at least three regressors.
  - ▶ Note, however, that this is MSE for the *full parameter vector*
- ▶ James-Stein estimator is also inadmissible!
  - ▶ Dominated by “positive-part” James-Stein estimator:

$$\hat{\beta}^{JS} = \hat{\beta} \left[ 1 - \frac{(p-2)\hat{\sigma}^2}{\hat{\beta}'X'X\hat{\beta}} \right]_+$$

- ▶  $\hat{\beta}$  = OLS,  $(x)_+ = \max(x, 0)$ ,  $\hat{\sigma}^2$  = usual OLS-based estimator
- ▶ Stops us from shrinking *past* zero to get a negative estimate for an element of  $\beta$  with a small OLS estimate.
- ▶ Positive-part James-Stein isn't admissible either!

# Lecture #2 – Model Selection I

Kullback-Leibler Divergence

Bias of Maximized Sample Log-Likelihood

Review of Asymptotics for Mis-specified MLE

Deriving AIC and TIC

Corrected AIC ( $AIC_c$ )

Mallow's  $C_p$

# Kullback-Leibler (KL) Divergence

## Motivation

How well does a given density  $f(y)$  approximate an unknown true density  $g(y)$ ? Use this to select between parametric models.

## Definition

$$\text{KL}(g; f) = \underbrace{\mathbb{E}_G \left[ \log \left\{ \frac{g(Y)}{f(Y)} \right\} \right]}_{\text{True density on top}} = \underbrace{\mathbb{E}_G [\log g(Y)]}_{\substack{\text{Depends only on truth} \\ \text{Fixed across models}}} - \underbrace{\mathbb{E}_G [\log f(Y)]}_{\text{Expected log-likelihood}}$$

## Properties

- ▶ Not symmetric:  $\text{KL}(g; f) \neq \text{KL}(f; g)$
- ▶ By Jensen's Inequality:  $\text{KL}(g; f) \geq 0$  (strict iff  $g = f$  a.e.)
- ▶ Minimize KL  $\iff$  Maximize Expected log-likelihood

# KL Divergence and Mis-specified MLE

Pseudo-true Parameter Value  $\theta_0$

$$\hat{\theta}_{MLE} \xrightarrow{P} \theta_0 \equiv \arg \min_{\theta \in \Theta} \text{KL}(g; f_{\theta}) = \arg \max_{\theta \in \Theta} \mathbb{E}_G[\log f(Y|\theta)]$$

What if  $f_{\theta}$  is correctly specified?

If  $g = f_{\theta}$  for some  $\theta$  then  $\text{KL}(g; f_{\theta})$  is minimized at zero.

Goal: Compare Mis-specified Models

$$\mathbb{E}_G [\log f(Y|\theta_0)] \quad \text{versus} \quad \mathbb{E}_G [\log h(Y|\gamma_0)]$$

where  $\theta_0$  is the pseudo-true parameter value for  $f_{\theta}$  and  $\gamma_0$  is the pseudo-true parameter value for  $h_{\gamma}$ .

# How to Estimate Expected Log Likelihood?

For simplicity:  $Y_1, \dots, Y_n \sim \text{iid } g(y)$

## Unbiased but Infeasible

$$\mathbb{E}_G \left[ \frac{1}{T} \ell(\theta_0) \right] = \mathbb{E}_G \left[ \frac{1}{T} \sum_{t=1}^T \log f(Y_t | \theta_0) \right] = \mathbb{E}_G [\log f(Y | \theta_0)]$$

## Biased but Feasible

$T^{-1} \ell(\hat{\theta}_{MLE})$  is a **biased** estimator of  $\mathbb{E}_G[\log f(Y | \theta_0)]$ .

## Intuition for the Bias

$T^{-1} \ell(\hat{\theta}_{MLE}) > T^{-1} \ell(\theta_0)$  unless  $\hat{\theta}_{MLE} = \theta_0$ . Maximized sample log-like. is an **overly optimistic** estimator of expected log-like.

# What to do about this bias?

1. General-purpose asymptotic approximation of “degree of over-optimism” of maximized sample log-likelihood.
  - ▶ Takeuchi's Information Criterion (TIC)
  - ▶ Akaike's Information Criterion (AIC)
2. Problem-specific finite sample approach, assuming  $g \in f_\theta$ .
  - ▶ Corrected AIC ( $AIC_c$ ) of Hurvich and Tsai (1989)

## Tradeoffs

TIC is most general and makes weakest assumptions, but requires very large  $T$  to work well. AIC is a good approximation to TIC that requires less data. Both AIC and TIC perform poorly when  $T$  is small relative to the number of parameters, hence  $AIC_c$ .



# Recall: Asymptotics for Mis-specified ML Estimation

Model  $f(y|\theta)$ , pseudo-true parameter  $\theta_0$ . For simplicity  $Y_1, \dots, Y_T \sim \text{iid } g(y)$ .

## Fundamental Expansion

$$\sqrt{T}(\hat{\theta} - \theta_0) = J^{-1} \left( \sqrt{T} \bar{U}_T \right) + o_p(1)$$

$$J = -\mathbb{E}_G \left[ \frac{\partial \log f(Y|\theta_0)}{\partial \theta \partial \theta'} \right], \quad \bar{U}_T = \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(Y_t|\theta_0)}{\partial \theta}$$

## Central Limit Theorem

$$\sqrt{T} \bar{U}_T \rightarrow_d U \sim N_p(0, K), \quad K = \text{Var}_G \left[ \frac{\partial \log f(Y|\theta_0)}{\partial \theta} \right]$$

$$\sqrt{T}(\hat{\theta} - \theta_0) \rightarrow_d J^{-1} U \sim N_p(0, J^{-1} K J^{-1})$$

## Information Matrix Equality

If  $g = f_\theta$  for some  $\theta \in \Theta$  then  $K = J \implies \text{AVAR}(\hat{\theta}) = J^{-1}$

# Bias Relative to Infeasible Plug-in Estimator

## Definition of Bias Term $B$

$$B = \underbrace{\frac{1}{T} \ell(\hat{\theta})}_{\text{feasible over-optimistic}} - \underbrace{\int g(y) \log f(y|\hat{\theta}) dy}_{\text{uses data only once infeas. not over-optimistic}}$$

## Question to Answer

On average, over the sampling distribution of  $\hat{\theta}$ , how large is  $B$ ?

AIC and TIC construct an asymptotic approximation of  $\mathbb{E}[B]$ .

# Derivation of AIC/TIC

## Step 1: Taylor Expansion

$$B = \bar{Z}_T + (\hat{\theta} - \theta_0)' J(\hat{\theta} - \theta_0) + o_p(T^{-1})$$

$$\bar{Z}_T = \frac{1}{T} \sum_{t=1}^T \{\log f(Y_t|\theta_0) - \mathbb{E}_G[\log f(Y|\theta_0)]\}$$

## Step 2: $\mathbb{E}[\bar{Z}_T] = 0$

$$\mathbb{E}[B] \approx \mathbb{E} \left[ (\hat{\theta} - \theta_0)' J(\hat{\theta} - \theta_0) \right]$$

## Step 3: $\sqrt{T}(\hat{\theta} - \theta_0) \rightarrow_d J^{-1}U$

$$T(\hat{\theta} - \theta_0)' J(\hat{\theta} - \theta_0) \rightarrow_d U' J^{-1}U$$

## Derivation of AIC/TIC Continued...

Step 3:  $\sqrt{T}(\hat{\theta} - \theta_0) \rightarrow_d J^{-1}U$

$$T(\hat{\theta} - \theta_0)'J(\hat{\theta} - \theta_0) \rightarrow_d U'J^{-1}U$$

Step 4:  $U \sim N_p(0, K)$

$$\mathbb{E}[B] \approx \frac{1}{T}\mathbb{E}[U'J^{-1}U] = \frac{1}{T}\text{tr}\{J^{-1}K\}$$

Final Result:

$T^{-1}\text{tr}\{J^{-1}K\}$  is an asymp. unbiased estimator of the over-optimism of  $T^{-1}\ell(\hat{\theta})$  relative to  $\int g(y) \log f(y|\hat{\theta}) dy$ .

# TIC and AIC

## Takeuchi's Information Criterion

Multiply by  $2T$ , estimate  $J, K \Rightarrow \text{TIC} = 2 \left[ \ell(\hat{\theta}) - \text{tr} \left\{ \hat{J}^{-1} \hat{K} \right\} \right]$

## Akaike's Information Criterion

If  $g = f_{\theta}$  then  $J = K \Rightarrow \text{tr} \left\{ J^{-1} K \right\} = p \Rightarrow \text{AIC} = 2 \left[ \ell(\hat{\theta}) - p \right]$

## Contrasting AIC and TIC

Technically, AIC requires that all models under consideration are at least correctly specified while TIC doesn't. But  $J^{-1}K$  is hard to estimate, and if a model is badly mis-specified,  $\ell(\hat{\theta})$  dominates.

## Corrected AIC ( $AIC_c$ ) – Hurvich & Tsai (1989)

### Idea Behind $AIC_c$

Asymptotic approximation used for AIC/TIC works poorly if  $p$  is too large relative to  $T$ . Try exact, finite-sample approach instead.

Assumption: True DGP

$$\mathbf{y} = \mathbf{X}\beta_0 + \varepsilon, \quad \varepsilon \sim N(\mathbf{0}, \sigma_0^2 \mathbf{I}_T), \quad k \text{ Regressors}$$

Can Show That

$$KL(g, f) = \frac{T}{2} \left[ \frac{\sigma_0^2}{\sigma_1^2} - \log \left( \frac{\sigma_0^2}{\sigma_1^2} \right) - 1 \right] + \left( \frac{1}{2\sigma_1^2} \right) (\beta_0 - \beta_1)' \mathbf{X}' \mathbf{X} (\beta_0 - \beta_1)$$

Where  $f$  is a normal regression model with parameters  $(\beta_1, \sigma_1^2)$  that might not be the true parameters.

## But how can we use this?

$$KL(g, f) = \frac{T}{2} \left[ \frac{\sigma_0^2}{\sigma_1^2} - \log \left( \frac{\sigma_0^2}{\sigma_1^2} \right) - 1 \right] + \left( \frac{1}{2\sigma_1^2} \right) (\beta_0 - \beta_1)' \mathbf{X}' \mathbf{X} (\beta_0 - \beta_1)$$

1. Would need to know  $(\beta_1, \sigma_1^2)$  for **candidate model**.
  - ▶ Easy: just use MLE  $(\hat{\beta}_1, \hat{\sigma}_1^2)$
2. Would need to know  $(\beta_0, \sigma_0^2)$  for **true model**.
  - ▶ Very hard! The whole problem is that we don't know these!

### Hurvich & Tsai (1989) Assume:

- ▶ Every candidate model is **at least correctly specified**
- ▶ Implies any candidate estimator  $(\hat{\beta}, \hat{\sigma}^2)$  is consistent for truth.

## Deriving the Corrected AIC

Since  $(\hat{\beta}, \hat{\sigma}^2)$  are random, look at  $\mathbb{E}[\widehat{KL}]$ , where

$$\widehat{KL} = \frac{T}{2} \left[ \frac{\sigma_0^2}{\hat{\sigma}^2} - \log \left( \frac{\sigma_0^2}{\hat{\sigma}^2} \right) - 1 \right] + \left( \frac{1}{2\hat{\sigma}^2} \right) (\hat{\beta} - \beta_0)' \mathbf{X}' \mathbf{X} (\hat{\beta} - \beta_0)$$

Finite-sample theory for correctly spec. normal regression model:

$$\mathbb{E}[\widehat{KL}] = \frac{T}{2} \left\{ \frac{T+k}{T-k-2} - \log(\sigma_0^2) + \mathbb{E}[\log \hat{\sigma}^2] - 1 \right\}$$

Eliminate constants and scaling, unbiased estimator of  $\mathbb{E}[\log \hat{\sigma}^2]$ :

$$\text{AIC}_c = \log \hat{\sigma}^2 + \frac{T+k}{T-k-2}$$

a finite-sample unbiased estimator of KL for model comparison



## Motivation: Predict $\mathbf{y}$ from $\mathbf{x}$ via Linear Regression

$$\underset{(T \times 1)}{\mathbf{y}} = \underset{(T \times K)}{\mathbf{X}} \underset{(K \times 1)}{\boldsymbol{\beta}} + \boldsymbol{\epsilon}$$

$$\mathbb{E}[\boldsymbol{\epsilon}|\mathbf{X}] = 0, \quad \text{Var}(\boldsymbol{\epsilon}|\mathbf{X}) = \sigma^2 \mathbf{I}$$

- ▶ If  $\boldsymbol{\beta}$  were known, could never achieve lower MSE than by using all regressors to predict.
- ▶ But  $\boldsymbol{\beta}$  is unknown so we have to estimate it from data  $\Rightarrow$  bias-variance tradeoff.
- ▶ Could make sense to exclude regressors with small coefficients: add small bias but reduce variance.

# Operationalizing the Bias-Variance Tradeoff Idea

## Mallow's $C_p$

Approximate the predictive MSE of each model relative to the infeasible optimum in which  $\beta$  is known.

## Notation

- ▶ Model index  $m$  and regressor matrix  $\mathbf{X}_m$
- ▶ Corresponding OLS estimator  $\hat{\beta}_m$  padded out with zeros
- ▶  $\mathbf{X}\hat{\beta}_m = \mathbf{X}_{(-m)}\mathbf{0} + \mathbf{X}_m [(\mathbf{X}_m'\mathbf{X}_m)^{-1}\mathbf{X}_m'\mathbf{y}] = \mathbf{P}_m\mathbf{y}$

# In-sample versus Out-of-sample Prediction Error

Why not compare  $RSS(m)$ ?

In-sample prediction error:  $RSS(m) = (\mathbf{y} - \mathbf{X}\hat{\beta}_m)'(\mathbf{y} - \mathbf{X}\hat{\beta}_m)$

From your Problem Set

RSS cannot decrease even if we add irrelevant regressors. Thus in-sample prediction error is an **overly optimistic** estimate of out-of-sample prediction error.

Bias-Variance Tradeoff

Out-of-sample performance of full model (using all regressors) could be very poor if there is a lot of estimation uncertainty associated with regressors that aren't very predictive.

# Predictive MSE of $\mathbf{X}\hat{\boldsymbol{\beta}}_m$ relative to infeasible optimum $\mathbf{X}\boldsymbol{\beta}$

Step 1: Algebra

$$\begin{aligned}\mathbf{X}\hat{\boldsymbol{\beta}}_m - \mathbf{X}\boldsymbol{\beta} &= \mathbf{P}_m\mathbf{y} - \mathbf{X}\boldsymbol{\beta} = \mathbf{P}_m(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) - (\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta} \\ &= \mathbf{P}_m\boldsymbol{\epsilon} - (\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta}\end{aligned}$$

Step 2:  $\mathbf{P}_m$  and  $(\mathbf{I} - \mathbf{P}_m)$  are both symmetric and idempotent, and orthogonal to each other

$$\begin{aligned}\left\|\mathbf{X}\hat{\boldsymbol{\beta}}_m - \mathbf{X}\boldsymbol{\beta}\right\|^2 &= \{\mathbf{P}_m\boldsymbol{\epsilon} - (\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta}\}' \{\mathbf{P}_m\boldsymbol{\epsilon} + (\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta}\} \\ &= \boldsymbol{\epsilon}'\mathbf{P}_m'\mathbf{P}_m\boldsymbol{\epsilon} - \boldsymbol{\beta}'\mathbf{X}'(\mathbf{I} - \mathbf{P}_m)'\mathbf{P}_m\boldsymbol{\epsilon} - \boldsymbol{\epsilon}'\mathbf{P}_m'(\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta} \\ &\quad + \boldsymbol{\beta}'\mathbf{X}'(\mathbf{I} - \mathbf{P}_m)(\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta} \\ &= \boldsymbol{\epsilon}'\mathbf{P}_m\boldsymbol{\epsilon} + \boldsymbol{\beta}'\mathbf{X}'(\mathbf{I} - \mathbf{P}_m)\mathbf{X}\boldsymbol{\beta}\end{aligned}$$

## Predictive MSE of $\mathbf{X}\hat{\boldsymbol{\beta}}_m$ relative to infeasible optimum $\mathbf{X}\boldsymbol{\beta}$

Step 3: Expectation of Step 2 conditional on  $\mathbf{X}$

$$\begin{aligned}\text{MSE}(m|\mathbf{X}) &= \mathbb{E} \left[ (\mathbf{X}\hat{\boldsymbol{\beta}}_m - \mathbf{X}\boldsymbol{\beta})' (\mathbf{X}\hat{\boldsymbol{\beta}}_m - \mathbf{X}\boldsymbol{\beta}) | \mathbf{X} \right] \\ &= \mathbb{E} \left[ \boldsymbol{\epsilon}' \mathbf{P}_m \boldsymbol{\epsilon} | \mathbf{X} \right] + \mathbb{E} \left[ \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta} | \mathbf{X} \right] \\ &= \mathbb{E} \left[ \text{tr} \left\{ \boldsymbol{\epsilon}' \mathbf{P}_m \boldsymbol{\epsilon} \right\} | \mathbf{X} \right] + \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta} \\ &= \text{tr} \left\{ \mathbb{E} [\boldsymbol{\epsilon} \boldsymbol{\epsilon}' | \mathbf{X}] \mathbf{P}_m \right\} + \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta} \\ &= \text{tr} \left\{ \sigma^2 \mathbf{P}_m \right\} + \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta} \\ &= \sigma^2 k_m + \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta}\end{aligned}$$

where  $k_m$  denotes the number of regressors in  $\mathbf{X}_m$  and

$$\text{tr}(\mathbf{P}_m) = \text{tr} \left\{ \mathbf{X}_m (\mathbf{X}_m' \mathbf{X}_m)^{-1} \mathbf{X}_m' \right\} = \text{tr} \left\{ \mathbf{X}_m' \mathbf{X}_m (\mathbf{X}_m' \mathbf{X}_m)^{-1} \right\} = \text{tr}(\mathbf{I}_m)$$

Now we know the MSE of a given model...

$$\text{MSE}(m|\mathbf{X}) = \sigma^2 k_m + \beta' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \beta$$

### Bias-Variance Tradeoff

- ▶ Smaller Model  $\Rightarrow \sigma^2 k_m$  smaller: less estimation uncertainty.
- ▶ Bigger Model  $\Rightarrow \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} = \|(\mathbf{I} - \mathbf{P}_m) \mathbf{X}\|^2$  is in general smaller: less (squared) bias.

### Mallow's $C_p$

- ▶ Problem: MSE formula is infeasible since it involves  $\beta$  and  $\sigma^2$ .
- ▶ Solution: Mallow's  $C_p$  constructs an unbiased estimator.
- ▶ Idea: what about plugging in  $\hat{\beta}$  to estimate second term?

## What if we plug in $\hat{\beta}$ to estimate the second term?

For the missing algebra in Step 4, see the lecture notes.

### Notation

Let  $\hat{\beta}$  denote the full model estimator and  $\mathbf{P}$  be the corresponding projection matrix:  $\mathbf{X}\hat{\beta} = \mathbf{P}\mathbf{y}$ .

### Crucial Fact

$\text{span}(\mathbf{X}_m)$  is a subspace of  $\text{span}(\mathbf{X})$ , so  $\mathbf{P}_m\mathbf{P} = \mathbf{P}\mathbf{P}_m = \mathbf{P}_m$ .

### Step 4: Algebra using the preceding fact

$$\mathbb{E} \left[ \hat{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \hat{\beta} | \mathbf{X} \right] = \dots = \beta' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \beta + \mathbb{E} \left[ \epsilon' (\mathbf{P} - \mathbf{P}_m) \epsilon | \mathbf{X} \right]$$

## Substituting $\hat{\beta}$ doesn't work...

Step 5: Use “Trace Trick” on second term from Step 4

$$\begin{aligned}\mathbb{E}[\epsilon'(\mathbf{P} - \mathbf{P}_m)\epsilon|\mathbf{X}] &= \mathbb{E}[\text{tr}\{\epsilon'(\mathbf{P} - \mathbf{P}_m)\epsilon\}|\mathbf{X}] \\&= \text{tr}\{\mathbb{E}[\epsilon\epsilon'|\mathbf{X}](\mathbf{P} - \mathbf{P}_m)\} \\&= \text{tr}\{\sigma^2(\mathbf{P} - \mathbf{P}_m)\} \\&= \sigma^2(\text{trace}\{\mathbf{P}\} - \text{trace}\{\mathbf{P}_m\}) \\&= \sigma^2(K - k_m)\end{aligned}$$

where  $K$  is the total number of regressors in  $\mathbf{X}$

### Bias of Plug-in Estimator

$$\mathbb{E}\left[\hat{\beta}'\mathbf{X}'(\mathbf{I} - \mathbf{P}_m)\mathbf{X}\hat{\beta}|\mathbf{X}\right] = \underbrace{\beta'\mathbf{X}'(\mathbf{I} - \mathbf{P}_m)\mathbf{X}\beta}_{\text{Truth}} + \underbrace{\sigma^2(K - k_m)}_{\text{Bias}}$$



## Putting Everything Together: Mallows's $C_p$

Want An Unbiased Estimator of This:

$$\text{MSE}(m|\mathbf{X}) = \sigma^2 k_m + \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta}$$

Previous Slide:

$$\mathbb{E} \left[ \hat{\boldsymbol{\beta}}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \hat{\boldsymbol{\beta}} | \mathbf{X} \right] = \boldsymbol{\beta}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \boldsymbol{\beta} + \sigma^2 (K - k_m)$$

End Result:

$$\begin{aligned} \text{MC}(m) &= \hat{\sigma}^2 k_m + \left[ \hat{\boldsymbol{\beta}}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \hat{\boldsymbol{\beta}} - \hat{\sigma}^2 (K - k_m) \right] \\ &= \hat{\boldsymbol{\beta}}' \mathbf{X}' (\mathbf{I} - \mathbf{P}_m) \mathbf{X} \hat{\boldsymbol{\beta}} + \hat{\sigma}^2 (2k_m - K) \end{aligned}$$

is an unbiased estimator of MSE, with  $\hat{\sigma}^2 = \mathbf{y}'(\mathbf{I} - \mathbf{P})\mathbf{y}/(T - K)$

## Why is this different from the textbook formula?

Just algebra, but tedious. . .

$$\begin{aligned}\text{MC}(m) - 2\hat{\sigma}^2 k_m &= \hat{\beta}' X' (\mathbf{I} - P_M) X \hat{\beta} - K \hat{\sigma}^2 \\ &\vdots \\ &= \mathbf{y}' (\mathbf{I} - P_M) \mathbf{y} - T \hat{\sigma}^2 \\ &= \text{RSS}(m) - T \hat{\sigma}^2\end{aligned}$$

Therefore:

$$\text{MC}(m) = \text{RSS}(m) + \hat{\sigma}^2(2k_m - T)$$

Divide Through by  $\hat{\sigma}^2$ :

$$C_p(m) = \frac{\text{RSS}(m)}{\hat{\sigma}^2} + 2k_m - T$$

Tells us how to adjust RSS for number of regressors. . .

# Lecture #3 – Model Selection II

Bayesian Model Comparison

Bayesian Information Criterion (BIC)

K-fold Cross-validation

Asymptotic Equivalence Between LOO-CV and TIC

# Bayesian Model Comparison: Marginal Likelihoods

## Bayes' Rule for Model $m \in \mathcal{M}$

$$\underbrace{\pi(\boldsymbol{\theta}|\mathbf{y}, m)}_{\text{Posterior}} \propto \underbrace{\pi(\boldsymbol{\theta}|m)}_{\text{Prior}} \underbrace{f(\mathbf{y}|\boldsymbol{\theta}, m)}_{\text{Likelihood}}$$
$$\underbrace{f(\mathbf{y}|m)}_{\text{Marginal Likelihood}} = \int_{\Theta} \pi(\boldsymbol{\theta}|m) f(\mathbf{y}|\boldsymbol{\theta}, m) \, d\boldsymbol{\theta}$$

## Posterior Model Probability for $m \in \mathcal{M}$

$$P(m|\mathbf{y}) = \frac{P(m)f(\mathbf{y}|m)}{f(\mathbf{y})} = \frac{\int_{\Theta} P(m)f(\mathbf{y}, \boldsymbol{\theta}|m) \, d\boldsymbol{\theta}}{f(\mathbf{y})} = \frac{P(m)}{f(\mathbf{y})} \int_{\Theta} \pi(\boldsymbol{\theta}|m)f(\mathbf{y}|\boldsymbol{\theta}, m) \, d\boldsymbol{\theta}$$

where  $P(m)$  is the **prior model probability** and  $f(\mathbf{y})$  is constant across models.

# Laplace (aka Saddlepoint) Approximation

Suppress model index  $m$  for simplicity.

General Case: for  $T$  large...

$$\int_{\Theta} g(\theta) \exp\{T \cdot h(\theta)\} d\theta \approx \left(\frac{2\pi}{T}\right)^{p/2} \exp\{T \cdot h(\theta_0)\} g(\theta_0) |H(\theta_0)|^{-1/2}$$

$$p = \dim(\theta), \quad \theta_0 = \arg \max_{\theta \in \Theta} h(\theta), \quad H(\theta_0) = -\frac{\partial^2 h(\theta)}{\partial \theta \partial \theta'} \Big|_{\theta=\theta_0}$$

Use to Approximate Marginal Likelihood

$$h(\theta) = \frac{\ell(\theta)}{T} = \frac{1}{T} \sum_{t=1}^T \log f(Y_t|\theta), \quad H(\theta) = J_T(\theta) = -\frac{1}{T} \sum_{t=1}^T \frac{\partial^2 \log f(Y_t|\theta)}{\partial \theta \partial \theta'}, \quad g(\theta) = \pi(\theta)$$

and substitute  $\hat{\theta}_{MLE}$  for  $\theta_0$

# Laplace Approximation to Marginal Likelihood

Suppress model index  $m$  for simplicity.

$$\int_{\Theta} \pi(\boldsymbol{\theta}) f(\mathbf{y}|\boldsymbol{\theta}) \, d\boldsymbol{\theta} \approx \left(\frac{2\pi}{T}\right)^{p/2} \exp\left\{\ell(\hat{\boldsymbol{\theta}}_{MLE})\right\} \pi(\hat{\boldsymbol{\theta}}_{MLE}) \left|J_T(\hat{\boldsymbol{\theta}}_{MLE})\right|^{-1/2}$$

$$\ell(\boldsymbol{\theta}) = \sum_{t=1}^T \log f(Y_t|\boldsymbol{\theta}), \quad H(\boldsymbol{\theta}) = J_T(\boldsymbol{\theta}) = -\frac{1}{T} \sum_{t=1}^T \frac{\partial^2 \log f(Y_t|\boldsymbol{\theta})}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}'}$$

# Bayesian Information Criterion

$$\int_{\Theta} \pi(\boldsymbol{\theta}) f(\mathbf{y}|\boldsymbol{\theta}) \, d\boldsymbol{\theta} \approx \left(\frac{2\pi}{T}\right)^{p/2} \exp\left\{\ell(\hat{\boldsymbol{\theta}}_{MLE})\right\} \pi(\hat{\boldsymbol{\theta}}_{MLE}) \left|J_T(\hat{\boldsymbol{\theta}}_{MLE})\right|^{-1/2}$$

Take Logs and Multiply by 2

$$2 \log f(\mathbf{y}|\boldsymbol{\theta}) \approx \underbrace{2\ell(\hat{\boldsymbol{\theta}}_{MLE})}_{O_p(T)} - \underbrace{p \log(T)}_{O(\log T)} + \underbrace{p \log(2\pi) + \log \pi(\hat{\boldsymbol{\theta}}) - \log |J_T(\hat{\boldsymbol{\theta}})|}_{O_p(1)}$$

The BIC

Assume uniform prior over **models** and ignore lower order terms:

$$\text{BIC}(m) = 2 \log f(\mathbf{y}|\hat{\boldsymbol{\theta}}, m) - p_m \log(T)$$

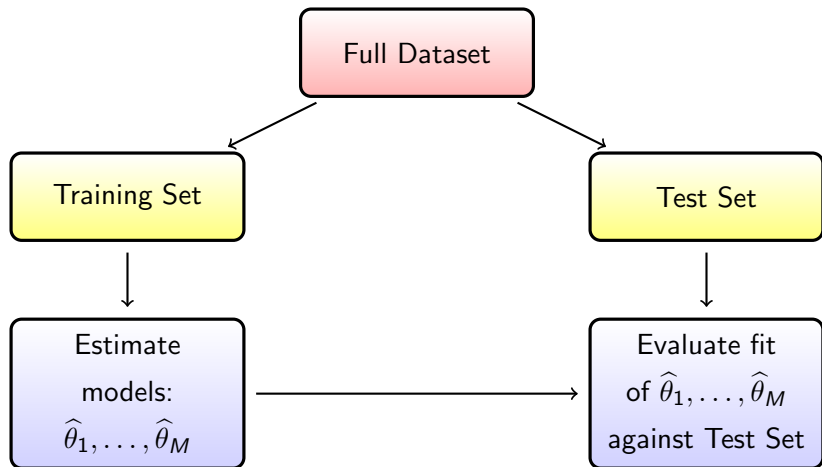
large-sample Frequentist approx. to Bayesian marginal likelihood

# Model Selection using a Hold-out Sample

- ▶ The real problem is **double** use of the data: first for estimation, then for model comparison.
  - ▶ Maximized sample log-likelihood is an overly optimistic estimate of expected log-likelihood and hence KL-divergence
  - ▶ In-sample squared prediction error is an overly optimistic estimator of out-of-sample squared prediction error
- ▶ AIC/TIC,  $AIC_c$ , BIC,  $C_p$  **penalize** sample log-likelihood or RSS to compensate.
- ▶ Another idea: **don't re-use the same data!**

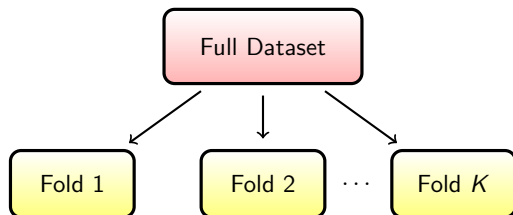


## Hold-out Sample: Partition the Full Dataset



Unfortunately this is extremely wasteful of data...

## K-fold Cross-Validation: “Pseudo-out-of-sample”



### Step 1

Randomly partition full dataset into  $K$  folds of approx. equal size.

### Step 2

Treat  $k^{\text{th}}$  fold as a hold-out sample and estimate model using all observations **except** those in fold  $k$ : yielding estimator  $\hat{\theta}(-k)$ .

# $K$ -fold Cross-Validation: “Pseudo-out-of-sample”

## Step 2

Treat  $k^{\text{th}}$  fold as a hold-out sample and estimate model using all observations **except** those in fold  $k$ : yielding estimator  $\hat{\theta}(-k)$ .

## Step 3

Repeat Step 2 for each  $k = 1, \dots, K$ .

## Step 4

For each  $t$  calculate the prediction  $\hat{y}_t^{-k(t)}$  of  $y_t$  based on  $\hat{\theta}(-k(t))$ , the estimator that excluded observation  $t$ .

## $K$ -fold Cross-Validation: “Pseudo-out-of-sample”

### Step 4

For each  $t$  calculate the prediction  $\hat{y}_t^{-k(t)}$  of  $y_t$  based on  $\hat{\theta}(-k(t))$ , the estimator that excluded observation  $t$ .

### Step 5

Define  $CV_K = \frac{1}{T} \sum_{t=1}^T L(y_t, \hat{y}_t^{-k(t)})$  where  $L$  is a loss function.

### Step 5

Repeat for each model & choose  $m$  to minimize  $CV_K(m)$ .

CV uses each observation for parameter estimation and model evaluation but never at the same time!

# Cross-Validation (CV): Some Details

## Which Loss Function?

- ▶ For regression squared error loss makes sense
- ▶ For classification (discrete prediction) could use zero-one loss.
- ▶ Can also use log-likelihood/KL-divergence as a loss function. . .

## How Many Folds?

- ▶ One extreme:  $K = 2$ . Closest to Training/Test idea.
- ▶ Other extreme:  $K = T$  **Leave-one-out** CV (LOO-CV).
- ▶ Computationally expensive model  $\Rightarrow$  may prefer fewer folds.
- ▶ If your model is a linear smoother there's a computational trick that makes LOO-CV extremely fast. (Problem Set)
- ▶ Asymptotic properties are related to  $K$  . . .

# Relationship between LOO-CV and TIC

## Theorem

LOO-CV using KL-divergence as the loss function is asymptotically equivalent to TIC but doesn't require us to estimate the Hessian and variance of the score.

# Large-sample Equivalence of LOO-CV and TIC

## Notation and Assumptions

For simplicity let  $Y_1, \dots, Y_T \sim \text{iid}$ . Let  $\hat{\theta}_{(t)}$  be the maximum likelihood estimator based on all observations **except**  $t$  and  $\hat{\theta}$  be the full-sample estimator.

## Log-likelihood as “Loss”

$CV_1 = \frac{1}{T} \sum_{t=1}^T \log f(y_t | \hat{\theta}_{(t)})$  but since min. KL = max. log-like.  
we choose the model with **highest**  $CV_1(m)$ .

# Overview of the Proof

First-Order Taylor Expansion of  $\log f(y_t|\hat{\theta}_{(t)})$  around  $\hat{\theta}$ :

$$\begin{aligned} CV_1 &= \frac{1}{T} \sum_{t=1}^T \log f(y_t|\hat{\theta}_{(t)}) \\ &= \frac{1}{T} \sum_{t=1}^T \left[ \log f(y_t|\hat{\theta}) + \frac{\partial \log f(y_t|\hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) \right] + o_p(1) \\ &= \frac{\ell(\hat{\theta})}{T} + \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t|\hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) + o_p(1) \end{aligned}$$

Why isn't the first-order term zero in this case?



# Important Side Point

## Definition of ML Estimator

$$\frac{\partial \ell(\hat{\theta})}{\partial \theta'} = \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} = 0$$

## In Contrast

$$\begin{aligned} \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) &= \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} \hat{\theta}_{(t)} \right] - \hat{\theta} \left[ \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} \right] \\ &= \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} \hat{\theta}_{(t)} \neq 0 \end{aligned}$$

# Overview of Proof

From expansion two slides back, we simply need to show that:

$$\frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) = -\frac{1}{T} \text{tr}(\hat{J}^{-1} \hat{K}) + o_p(1)$$

$$\hat{K} = \frac{1}{T} \sum_{t=1}^T \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right) \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right)'$$

$$\hat{J} = -\frac{1}{T} \sum_{t=1}^T \frac{\partial^2 \log f(y_t | \hat{\theta})}{\partial \theta \partial \theta'}$$

## Overview of Proof

By the definition of  $\hat{K}$  and the properties of the trace operator:

$$\begin{aligned} -\frac{1}{T} \text{tr} \left\{ \hat{J}^{-1} \hat{K} \right\} &= -\frac{1}{T} \text{tr} \left\{ \hat{J}^{-1} \left[ \frac{1}{T} \sum_{t=1}^T \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right) \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right)' \right] \right\} \\ &= \left[ \frac{1}{T} \sum_{t=1}^T \text{tr} \left\{ -\frac{\hat{J}^{-1}}{T} \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right) \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right)' \right\} \right] \\ &= \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} \left( -\frac{1}{T} \hat{J}^{-1} \right) \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \end{aligned}$$

So it suffices to show that

$$\left( \hat{\theta}_{(t)} - \hat{\theta} \right) = -\frac{1}{T} \hat{J}^{-1} \left[ \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right] + o_p(1)$$

# Remaining Steps in the Proof

## Step 1

Let  $\hat{G}$  denote the empirical CDF based on  $y_1, \dots, y_T$ . Then:

$$\left(\hat{\theta}_{(t)} - \hat{\theta}\right) = -\frac{1}{T} \text{infl}(\hat{G}, y_t) + o_p(1)$$

## Step 2

For ML estimation:  $\text{infl}(G, y) = J^{-1} \frac{\partial}{\partial \theta} \log f(y|\theta_0)$ .

## Step 3

Evaluating Step 2 at  $\hat{G}$  and substituting into Step 2

$$\left(\hat{\theta}_{(t)} - \hat{\theta}\right) = -\frac{1}{T} \hat{J}^{-1} \left[ \frac{\partial \log f(y_t|\hat{\theta})}{\partial \theta} \right] + o_p(1)$$

# What is an Influence Function?

## Statistical Functional

$\mathbb{T} = \mathbb{T}(G)$  maps a CDF  $G$  to  $\mathbb{R}^p$ .

## Example: ML Estimation

$$\theta_0 = \mathbb{T}(G) = \arg \min_{\theta \in \Theta} E_G \left[ \log \left\{ \frac{g(Y)}{f(Y|\theta)} \right\} \right]$$

## Influence Function

Let  $\delta_y$  be a **point mass** at  $y$ :  $\delta_y(y) = 1$ ,  $\delta_y(y') = 0$  for  $y' \neq y$ .

Influence function = functional derivative: how does a small change in  $G$  affect  $\mathbb{T}$ ?

$$\text{infl}(G, y) = \lim_{\epsilon \rightarrow 0} \frac{\mathbb{T}[(1 - \epsilon) G + \epsilon \delta_y] - \mathbb{T}(G)}{\epsilon}$$

# Intuition for Step 1

Empirical CDF  $\hat{G}$

$$\hat{G}(a) = \frac{1}{T} \sum_{t=1}^T \mathbf{1}\{y_t \leq a\} = \frac{1}{T} \sum_{t=1}^T \delta_{y_t}(a)$$

Relation to “LOO” Empirical CDF  $\hat{G}_{(t)}$

$$\hat{G} = \left(1 - \frac{1}{T}\right) \hat{G}_{(t)} + \frac{\delta_{y_t}}{T}$$

Applying  $\mathbb{T}$  to both sides...

$$\mathbb{T}(\hat{G}) = \mathbb{T}\left(\left(1 - 1/T\right)\hat{G}_{(t)} + \delta_{y_t}/T\right)$$

## Intuition for Step 1 Continued...

Some algebra, followed by taking  $\varepsilon = 1/T$  to zero gives:

$$\mathbb{T}(\hat{G}) = \mathbb{T}\left((1 - 1/T)\hat{G}_{(t)} + \delta_{y_t}/T\right)$$

$$\mathbb{T}(\hat{G}) - \mathbb{T}(\hat{G}_{(t)}) = \mathbb{T}\left((1 - 1/T)\hat{G}_{(t)} + \delta_{y_t}/T\right) - \mathbb{T}(\hat{G}_{(t)})$$

$$\mathbb{T}(\hat{G}) - \mathbb{T}(\hat{G}_{(t)}) = \frac{1}{T} \left[ \frac{\mathbb{T}\left((1 - 1/T)\hat{G}_{(t)} + \delta_{y_t}/T\right) - \mathbb{T}(\hat{G}_{(t)})}{1/T} \right]$$

$$\mathbb{T}(\hat{G}) - \mathbb{T}(\hat{G}_{(t)}) = \frac{1}{T} \text{infl}\left(\hat{G}_{(t)}, y_t\right) + o_p(1)$$

$$\hat{\theta} - \hat{\theta}_{(t)} = \frac{1}{T} \text{infl}\left(\hat{G}, y_t\right) + o_p(1)$$

Last step: difference between having  $\hat{G}$  vs.  $\hat{G}_{(t)}$  in infl is negligible

# Derivation of Influence Function for MLE

I'll do this on the blackboard if we have time. . .



# Lecture #4 – Asymptotic Properties

Overview

Weak Consistency

Consistency

Efficiency

AIC versus BIC in a Simple Example

# Overview

## Asymptotic Properties

What happens as the sample size increases?

## Consistency

Choose “best” model with probability approaching 1 in the limit.

## Efficiency

Post-model selection estimator with low risk.

## Some References

Sin and White (1992, 1996), Pötscher (1991), Leeb & Pötscher (2005), Yang (2005) and Yang (2007).

# Penalizing the Likelihood

Examples we've seen:

$$TIC = 2\ell_T(\hat{\theta}) - \text{trace} \left\{ \hat{J}^{-1} \hat{K} \right\}$$

$$AIC = 2\ell_T(\hat{\theta}) - 2 \text{ length}(\theta)$$

$$BIC = 2\ell_T(\hat{\theta}) - \log(T) \text{ length}(\theta)$$

Generic penalty  $c_{T,k}$

$$IC(M_k) = 2 \sum_{t=1}^T \log f_{k,t}(Y_t | \hat{\theta}_k) - c_{T,k}$$

How does choice of  $c_{T,k}$  affect behavior of the criterion?

## Weak Consistency: Suppose $M_{k_0}$ Uniquely Minimizes KL

### Assumption

$$\liminf_{T \rightarrow \infty} \left( \min_{k \neq k_0} \frac{1}{T} \sum_{t=1}^T \{KL(g; f_{k,t}) - KL(g; f_{k_0,t})\} \right) > 0$$

### Consequences

- ▶ Any criterion with  $c_{T,k} > 0$  and  $c_{T,k} = o_p(T)$  is weakly consistent: **selects  $M_{k_0}$  wpa 1 in the limit.**
- ▶ Weak consistency still holds if  $c_{T,k}$  is zero for one of the models, so long as it is strictly positive for all the others.

## Both AIC and BIC are Weakly Consistent

Both satisfy  $T^{-1}c_{T,k} \xrightarrow{P} 0$ .

BIC Penalty:  $c_{T,k} = \log(T) \times \text{length}(\theta_k)$

AIC Penalty:  $c_{T,k} = 2 \times \text{length}(\theta_k)$

# Consistency: No Unique KL-minimizer

## Example

If the truth is an AR(5) model then AR(6), AR(7), AR(8), etc. models **all have zero KL-divergence**.

## Principle of Parsimony

Among the KL-minimizers, choose the **simplest model**, i.e. the one with the fewest parameters.

## Notation

$\mathcal{J}$  = be the set of all models that attain minimum KL-divergence

$\mathcal{J}_0$  = subset with the minimum number of parameters.

# Sufficient Conditions for Consistency

Consistency: Select Model from  $\mathcal{J}_0$  wpa 1

$$\lim_{T \rightarrow \infty} \mathbb{P} \left\{ \min_{\ell \in \mathcal{J} \setminus \mathcal{J}_0} [IC(M_{j_0}) - IC(M_\ell)] > 0 \right\} = 1$$

## Sufficient Conditions

(i) For all  $k \neq \ell \in \mathcal{J}$

$$\sum_{t=1}^T [\log f_{k,t}(Y_t | \theta_k^*) - \log f_{\ell,t}(Y_t | \theta_\ell^*)] = O_p(1)$$

where  $\theta_k^*$  and  $\theta_\ell^*$  are the KL minimizing parameter values.

(ii) For all  $j_0 \in \mathcal{J}_0$  and  $\ell \in (\mathcal{J} \setminus \mathcal{J}_0)$

$$P(c_{T,\ell} - c_{T,j_0} \rightarrow \infty) = 1$$

## BIC is Consistent; AIC and TIC Are Not

- ▶ AIC and TIC *cannot* satisfy (ii) since  $(c_{T,\ell} - c_{T,j_0})$  *does not depend on sample size*.
- ▶ It turns out that AIC and TIC are *not* consistent.
- ▶ BIC is consistent:

$$c_{T,\ell} - c_{T,j_0} = \log(T) \{ \text{length}(\theta_\ell) - \text{length}(\theta_{j_0}) \}$$

- ▶ Term in braces is *positive* since  $\ell \in \mathcal{J} \setminus \mathcal{J}_0$ , i.e.  $\ell$  is not as parsimonious as  $j_0$
- ▶  $\log(T) \rightarrow \infty$ , so BIC always selects a model in  $\mathcal{J}_0$  in the limit.



# Efficiency: Risk Properties of Post-selection Estimator

## Setup

- ▶ Models  $M_0$  and  $M_1$ ; corresponding estimators  $\hat{\theta}_{0,T}$  and  $\hat{\theta}_{1,T}$
- ▶ Model Selection: If  $\hat{M} = 0$  choose  $M_0$ ; if  $\hat{M} = 1$  choose  $M_1$ .

## Post-selection Estimator

$$\hat{\theta}_{\hat{M},T} \equiv \mathbf{1}_{\{\hat{M}=0\}}\hat{\theta}_{0,T} + \mathbf{1}_{\{\hat{M}=1\}}\hat{\theta}_{1,T}$$

## Two Sources of Randomness

Variability in  $\hat{\theta}_{\hat{M},T}$  arises both from  $(\hat{\theta}_{0,T}, \hat{\theta}_{1,T})$  and from  $\hat{M}$ .

## Question

How does the risk of  $\hat{\theta}_{\hat{M},T}$  compare to that of other estimators?

# Efficiency: Risk Properties of Post-selection Estimator

## Pointwise-risk Adaptivity

$\hat{\theta}_{\hat{M},T}$  is **pointwise-risk adaptive** if for any fixed  $\theta \in \Theta$ ,

$$\frac{R(\theta, \hat{\theta}_{\hat{M},T})}{\min \left\{ R(\theta, \hat{\theta}_{0,T}), R(\theta, \hat{\theta}_{1,T}) \right\}} \rightarrow 1, \quad \text{as } T \rightarrow \infty$$

## Minimax-rate Adaptivity

$\hat{\theta}_{\hat{M},T}$  is **minimax-rate adaptive** if

$$\sup_T \left[ \frac{\sup_{\theta \in \Theta} R(\theta, \hat{\theta}_{\hat{M},T})}{\inf_{\tilde{\theta}_T} \sup_{\theta \in \Theta} R(\theta, \tilde{\theta}_T)} \right] < \infty$$

# The Strengths of AIC and BIC Cannot be Shared

## Theorem

No model post-model selection estimator can be both pointwise-risk adaptive and minimax-rate adaptive.

## AIC vs. BIC

- ▶ BIC is pointwise-risk adaptive but AIC is not. (This is effectively identical to consistency.)
- ▶ AIC is minimax-rate adaptive, but BIC is not.
- ▶ Further Reading: Yang (2005), Yang (2007)

# Consistency and Efficiency in a Simple Example

## Information Criteria

Consider criteria of the form  $IC_m = 2\ell(\theta) - d_T \times \text{length}(\theta)$ .

## True DGP

$Y_1, \dots, Y_T \sim \text{iid } N(\mu, 1)$

## Candidate Models

$M_0$  assumes  $\mu = 0$ ,  $M_1$  does not restrict  $\mu$ . Only one parameter:

$$IC_0 = 2 \max_{\mu} \{\ell(\mu) : M_0\}$$

$$IC_1 = 2 \max_{\mu} \{\ell(\mu) : M_1\} - d_T$$

# Log-Likelihood Function

Since  $\sum_{t=1}^T (Y_t - \mu)^2 = T(\bar{Y} - \mu)^2 + T\hat{\sigma}^2$ ,

$$\begin{aligned}\ell_T(\mu) &= \sum_{t=1}^T \log \left( \frac{1}{2\pi} \exp \left\{ -\frac{1}{2} (Y_t - \mu)^2 \right\} \right) \\ &= -\frac{T}{2} \log(2\pi) - \frac{1}{2} \sum_{t=1}^T (Y_t - \mu)^2 \\ &= -\frac{T}{2} \log(2\pi) - \frac{T}{2} \hat{\sigma}^2 - \frac{T}{2} (\bar{Y} - \mu)^2 \\ &= \text{Constant} - \frac{T}{2} (\bar{Y} - \mu)^2\end{aligned}$$

Side Calculation:  $\sum_{t=1}^T (Y_t - \mu)^2 = T(\bar{Y} - \mu)^2 + T\hat{\sigma}^2$

$$\begin{aligned} T\hat{\sigma}^2 &= \sum_{t=1}^T (Y_t - \bar{Y})^2 = \sum_{t=1}^T (Y_t - \mu + \mu - \bar{Y})^2 = \sum_{t=1}^T [(Y_t - \mu) - (\bar{Y} - \mu)]^2 \\ &= \sum_{t=1}^T (Y_t - \mu)^2 - \sum_{t=1}^T 2(Y_t - \mu)(\bar{Y} - \mu) + \sum_{t=1}^T (\bar{Y} - \mu)^2 \\ &= \left[ \sum_{t=1}^T (Y_t - \mu)^2 \right] - 2(\bar{Y} - \mu) \left( \sum_{t=1}^T Y_t - \sum_{t=1}^T \mu \right) + T(\bar{Y} - \mu)^2 \\ &= \left[ \sum_{t=1}^T (Y_t - \mu)^2 \right] - 2(\bar{Y} - \mu)(T\bar{Y} - T\mu) + T(\bar{Y} - \mu)^2 \\ &= \left[ \sum_{t=1}^T (Y_t - \mu)^2 \right] - 2T(\bar{Y} - \mu)^2 + T(\bar{Y} - \mu)^2 \\ &= \left[ \sum_{t=1}^T (Y_t - \mu)^2 \right] - T(\bar{Y} - \mu)^2 \end{aligned}$$

# The Selected Model $\hat{M}$

## Information Criteria

$M_0$  sets  $\mu = 0$  while  $M_1$  uses the MLE  $\bar{Y}$ , so we have

$$IC_0 = 2 \max_{\mu} \{\ell(\mu) : M_0\} = 2 \times \text{Constant} - T\bar{Y}^2$$

$$IC_1 = 2 \max_{\mu} \{\ell(\mu) : M_1\} - d_T = 2 \times \text{Constant} - d_T$$

## Difference of Criteria

$$IC_1 - IC_0 = T\bar{Y}^2 - d_T$$

## Selected Model

$$\hat{M} = \begin{cases} M_1, & |\sqrt{T}\bar{Y}| \geq \sqrt{d_T} \\ M_0, & |\sqrt{T}\bar{Y}| < \sqrt{d_T} \end{cases}$$

## Case I: $\mu \neq 0$

Apply theory from earlier in lecture...

### KL-Divergence of $M_1$

$M_1$  is the true DGP with minimized KL-divergence equal to zero.

### KL-Divergence of $M_0$

- ▶ Truth:  $g(y) = (2\pi)^{-1/2} \exp \{-(y - \mu)^2/2\}$
- ▶  $M_0$ :  $f(y) = (2\pi)^{-1/2} \exp \{-y^2/2\}$
- ▶ Hence:  $\log g(y) - \log f(y) = -\frac{1}{2}(y - \mu)^2 + \frac{1}{2}y^2 = \mu(y - \frac{\mu}{2})$

$$\begin{aligned} \text{KL}(g; M_0) &= \int_{\mathbb{R}} \mu(y - \mu/2)(2\pi)^{-1/2} \exp \{(y - \mu)^2/2\} dy \\ &= \mu(\mu - \mu/2) = \mu^2/2 \end{aligned}$$



## Verifying Weak Consistency: $\mu \neq 0$

### Condition on KL-Divergence

$$\liminf_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \{KL(g; M_0) - KL(g; M_1)\} = \liminf_{n \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \left( \frac{\mu^2}{2} - 0 \right) > 0$$

### Condition on Penalty

- ▶ Need  $c_{T,k} = o_p(T)$ , i.e.  $c_{T,k}/T \xrightarrow{P} 0$ .
- ▶ Both AIC and BIC satisfy this
- ▶ If  $\mu \neq 0$ , both AIC and BIC select  $M_1$  wpa 1 as  $T \rightarrow \infty$ .

## Case II: $\mu = 0$

What's different?

- ▶ Both  $M_1$  and  $M_0$  are true and minimize KL divergence at zero.
- ▶ **Consistency** says choose most parsimonious true model:  $M_0$

Verifying Conditions for Consistency

- ▶  $N(0, 1)$  model nested inside  $N(\mu, 1)$  model
- ▶ Truth is  $N(0, 1)$  so LR-stat is asymptotically  $\chi^2(1) = O_p(1)$ .
- ▶ For penalty term, need  $\mathbb{P}(c_{T,k} - c_{T,0}) \rightarrow \infty$
- ▶ BIC satisfies this but AIC doesn't.

# Finite-Sample Selection Probabilities: AIC

AIC Sets  $d_T = 2$

$$\hat{M}_{AIC} = \begin{cases} M_1, & |\sqrt{T}\bar{Y}| \geq \sqrt{2} \\ M_0, & |\sqrt{T}\bar{Y}| < \sqrt{2} \end{cases}$$

$$\begin{aligned} P(\hat{M}_{AIC} = M_1) &= P(|\sqrt{T}\bar{Y}| \geq \sqrt{2}) \\ &= P(|\sqrt{T}\mu + Z| \geq \sqrt{2}) \\ &= P(\sqrt{T}\mu + Z \leq -\sqrt{2}) + [1 - P(\sqrt{T}\mu + Z \leq \sqrt{2})] \\ &= \Phi(-\sqrt{2} - \sqrt{T}\mu) + [1 - \Phi(\sqrt{2} - \sqrt{T}\mu)] \end{aligned}$$

where  $Z \sim N(0, 1)$  since  $\bar{Y} \sim N(\mu, 1/T)$  because  $\text{Var}(Y_t) = 1$ .

# Finite-Sample Selection Probabilities: BIC

BIC sets  $d_T = \log(T)$

$$\hat{M}_{BIC} = \begin{cases} M_1, & |\sqrt{T}\bar{Y}| \geq \sqrt{\log(T)} \\ M_0, & |\sqrt{T}\bar{Y}| < \sqrt{\log(T)} \end{cases}$$

Same steps as for the AIC except with  $\sqrt{\log(T)}$  in the place of  $\sqrt{2}$ :

$$\begin{aligned} P(\hat{M}_{BIC} = M_1) &= P(|\sqrt{T}\bar{Y}| \geq \sqrt{\log(T)}) \\ &= \Phi(-\sqrt{\log(T)} - \sqrt{T}\mu) + [1 - \Phi(\sqrt{\log(T)} - \sqrt{T}\mu)] \end{aligned}$$

Interactive Demo: AIC vs BIC

[https://fditraglia.shinyapps.io/CH\\_Figure\\_4\\_1/](https://fditraglia.shinyapps.io/CH_Figure_4_1/)

# Probability of Over-fitting

- ▶ If  $\mu = 0$  both models are true but  $M_0$  is more parsimonious.
- ▶ Probability of over-fitting ( $Z$  denotes standard normal):

$$\begin{aligned}P(\hat{M} = M_1) &= P(|\sqrt{T}\bar{Y}| \geq \sqrt{d_T}) = P(|Z| \geq \sqrt{d_T}) \\&= P(Z^2 \geq d_T) = P(\chi_1^2 \geq d_T)\end{aligned}$$

- ▶ AIC:  $d_T = 2$  and  $P(\chi_1^2 \geq 2) \approx 0.157$ .
- ▶ BIC:  $d_T = \log(T)$  and  $P(\chi_1^2 \geq \log T) \rightarrow 0$  as  $T \rightarrow \infty$ .

AIC has  $\approx 16\%$  prob. of over-fitting; BIC does not over-fit in the limit.

# Risk of the Post-Selection Estimator

## The Post-Selection Estimator

$$\hat{\mu} = \begin{cases} \bar{Y}, & |\sqrt{T}\bar{Y}| \geq \sqrt{d_T} \\ 0, & |\sqrt{T}\bar{Y}| < \sqrt{d_T} \end{cases}$$

## Recall from above

Recall from above that  $\sqrt{T}\bar{Y} = \sqrt{T}\mu + Z$  where  $Z \sim N(0, 1)$

## Risk Function

MSE risk times  $T$  to get risk relative to minimax rate:  $1/T$ .

$$R(\mu, \hat{\mu}) = T \cdot \mathbb{E} \left[ (\hat{\mu} - \mu)^2 \right] = \mathbb{E} \left[ \left( \sqrt{T}\hat{\mu} - \sqrt{T}\mu \right)^2 \right]$$

# Simplifying the Risk Function

$\sqrt{T}\bar{Y} = \sqrt{T}\mu + Z$  where  $Z \sim N(0, 1)$

Let  $X = \mathbf{1}\{A\}$  where  $A = \left\{|\sqrt{T}\mu + Z| \geq \sqrt{d_T}\right\}$

$$\begin{aligned}R(\mu, \hat{\mu}) &= \mathbb{E} \left[ \left( \sqrt{T}\hat{\mu} - \sqrt{T}\mu \right)^2 \right] \\&= \mathbb{E} \left\{ \left[ \left( \sqrt{T}\mu + Z \right) X - \sqrt{T}\mu \right]^2 \right\} \\&= \mathbb{P}(A) \mathbb{E} \left\{ \left[ \left( \sqrt{T}\mu + Z \right) - \sqrt{T}\mu \right]^2 \middle| X = 1 \right\} + [1 - \mathbb{P}(A)] \left( \sqrt{T}\mu \right)^2 \\&= \mathbb{P}(A) \mathbb{E} \left[ Z^2 | X = 1 \right] + [1 - \mathbb{P}(A)] T\mu^2\end{aligned}$$

So we need to calculate  $\mathbb{P}(A) \mathbb{E}[Z^2 | X = 1]$  and  $\mathbb{P}(A)$ .

## Calculating $\mathbb{P}(A)$

Define  $a = (-\sqrt{d_T} - \sqrt{T}\mu)$  and  $b = (\sqrt{d_T} - \sqrt{T}\mu)$

$$\begin{aligned}\mathbb{P}(A) &= \mathbb{P}\left(|\sqrt{T}\mu + Z| \geq \sqrt{d_T}\right) \\&= \mathbb{P}\left(\sqrt{T}\mu + Z \geq \sqrt{d_T}\right) + \mathbb{P}\left(\sqrt{T}\mu + Z \leq -\sqrt{d_T}\right) \\&= \mathbb{P}(Z \geq b) + \mathbb{P}(Z \leq a) \\&= 1 - \Phi(b) + \Phi(a)\end{aligned}$$

And hence:

$$1 - \mathbb{P}(A) = \Phi(b) - \Phi(a)$$



## Calculating $\mathbb{P}(A) \mathbb{E}[Z^2|X = 1]$ – Step 1

### Conditional Density of $Z|X = 1$

$$f(z|x = 1) = \frac{\mathbf{1}(A)\varphi(z)}{\mathbb{P}(A)} \quad \text{where } \varphi \text{ is the } N(0, 1) \text{ density}$$

Therefore:

$$\begin{aligned}\mathbb{P}(A) \mathbb{E}[Z^2|X = 1] &= \mathbb{P}(A) \int_{\mathbb{R}} z^2 \left[ \frac{\mathbf{1}(A)\varphi(z)}{\mathbb{P}(A)} \right] dz \\ &= \int_{-\infty}^a z^2 \varphi(z) dz + \int_b^{\infty} z^2 \varphi(z) dz\end{aligned}$$

## Calculating $\mathbb{P}(A) \mathbb{E}[Z^2|X = 1]$ – Step 2

Unconditional Expectation:  $\mathbb{E}[Z^2]$

$$1 = \mathbb{E}[Z^2] = \int_{-\infty}^a z^2 \varphi(z) \, dz + \int_a^b z^2 \varphi(z) \, dz + \int_b^{\infty} z^2 \varphi(z) \, dz$$

Therefore:

$$\begin{aligned} \mathbb{P}(A) \mathbb{E}[Z^2|X = 1] &= \int_{-\infty}^a z^2 \varphi(z) \, dz + \int_b^{\infty} z^2 \varphi(z) \, dz \\ &= 1 - \int_a^b z^2 \varphi(z) \, dz \end{aligned}$$

## Calculating $\mathbb{P}(A) \mathbb{E}[Z^2|X = 1]$ – Step 3

### Integration By Parts

Take  $u = -z$  and  $dv = -z \exp\{-z^2/2\}$  since

$$\frac{d}{dz} (\exp\{-z^2/2\}) = -z \exp\{-z^2/2\}$$

Thus,  $v = \exp\{-z^2/2\}$ ,  $du = -1$  and

$$\begin{aligned} \int_a^b z^2 \phi(z) dz &= (2\pi)^{-1/2} \int_a^b z^2 \exp\{-z^2/2\} dz \\ &= (2\pi)^{-1/2} \left[ -z \exp\{-z^2/2\} \Big|_a^b + \int_a^b \exp\left\{-\frac{z^2}{2}\right\} dz \right] \\ &= a\phi(a) - b\phi(b) + \Phi(b) - \Phi(a) \end{aligned}$$

# The Simplified MSE Risk Function

$$\begin{aligned}R(\mu, \hat{\mu}) &= 1 - [a\phi(a) - b\phi(b) + \Phi(b) - \Phi(a)] + T\mu^2 [\Phi(b) - \Phi(a)] \\ &= 1 + [b\phi(b) - a\phi(a)] + (T\mu^2 - 1) [\Phi(b) - \Phi(a)]\end{aligned}$$

where

$$a = -\sqrt{d_T} - \sqrt{T}\mu$$

$$b = \sqrt{d_T} - \sqrt{T}\mu$$

[https://fditraglia.shinyapps.io/CH\\_Figure\\_4\\_2/](https://fditraglia.shinyapps.io/CH_Figure_4_2/)

## Punchline: Risk of the Post-Selection Estimator

Need to add explanation of the pointwise adaptivity and the minimax adaptivity vis-a-vis the preceding example. Easy for the minimax, since we can just read it off of the interactive figure. Harder for the pointwise, although it's easy for AIC since we know that it can't consistently select  $M_0$  when  $\mu$  is indeed zero, so it can't achieve the pointwise risk lower bound here. Need to explain about BIC. Also explain about consistency and unbounded minimax risk.